



NİĞDE ÖMER HALİSDEMİR ÜNİVERSİTESİ

TBMYO

MEKATRONİK / ELEKTRİK VE OTOMASYON

BİLGİSAYAR DESTEKLİ KONTROL SİSTEMLERİ

ÖDEV 0

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C: > Users > kacga > OneDrive > Masaüstü > alperen1.py

```
import control as ctrl
import numpy as np
import matplotlib.pyplot as plt
# Transfer fonksiyonu tanımla
num=[5]#Pay
den=[1,0.05] #Payda
G_s=ctrl.tf(num,den)
print(G_s)

# ZOH yontemiyle z-duzlemine donustur
T=0.1 #Ornekleme suresi
G_z=ctrl.c2d (G_s, T, method='zoh')

print ("G(z)",G_z)

# Surekli zaman basamak yaniti
t_s, y_s=ctrl.step_response(G_s)
plt.figure(1)
plt.plot(t_s, y_s, label='G(s)-Surekli Zaman')
#Ayrik zaman basamak yaniti
t_z, y_z=ctrl.step_response(G_z)
plt.figure(2)
plt.stem(t_z,y_z,label='G(z)-Ayrik zaman',use_line_collection=True)

import numpy as np
import matplotlib.pyplot as plt
# Sürekli zaman (G(s))
t_s = np.linspace(0, 10, 100)
y_s = 100 * (1 - np.exp(-0.05 * t_s))
# Grafikleri çizdir
plt.figure(1)
plt.plot(t_s,y_s,label='G(s)')
plt.stem(t_z,y_z,label='G(z)',use_line_collection=True)
plt.xlabel('Zaman')
plt.ylabel('Cikis')
plt.legend()
plt.show()
```

