

Let the following system be given,

$$\dot{x} = Ax + B_w(\alpha C + \beta C^\perp), y = Cx + (\alpha C + \beta C^\perp)$$

The classical Luenberger observer is given by,

$$\dot{\hat{x}} = A\hat{x} + L(y - \hat{y}), \hat{y} = C\hat{x}$$

Using the projection

$$\Pi = I - \frac{CC^T}{C^TC}$$

the GI-Luenberger observer can be defined as,

$$\dot{\hat{x}} = A\hat{x} + L(y - \hat{y}) + B_w\Pi y, \hat{y} = C\hat{x} + \Pi y$$

which is in explicit form,

$$\dot{\hat{x}} = A\hat{x} + L(y - \hat{y}) + B_w\beta C^\perp, \hat{y} = C\hat{x} + \beta C^\perp$$

where $\Pi C = 0$, $\Pi C^\perp = C^\perp$ and $C^TC^\perp = 0$. The error dynamics of the classical Luenberger observer is obtained as,

$$\begin{aligned} \dot{e} &= Ax + \alpha B_w C + \beta B_w C^\perp - A\hat{x} - L(Cx + \alpha C + \beta C^\perp - C\hat{x}) \\ \dot{e} &= (A - LC)e + \alpha(B_w C - LC) + \beta(B_w C^\perp - LC^\perp) \\ \dot{e} &= (A - LC)e + \alpha(B_w - L)C + \beta(B_w - L)C^\perp \end{aligned}$$

where the GI-Luenberger observer is obtained as,

$$\begin{aligned} \dot{e} &= Ax + \alpha B_w C + \beta B_w C^\perp - A\hat{x} - L(Cx + \alpha C + \beta C^\perp - C\hat{x} - \Pi y) - B_w \Pi y \\ \dot{e} &= Ax + \alpha B_w C + \beta B_w C^\perp - A\hat{x} - L(Cx + \alpha C + \beta C^\perp - C\hat{x} - \beta C^\perp) - B_w \beta C^\perp \\ \dot{e} &= (A - LC)e + \alpha(B_w - L)C \end{aligned}$$

From the error dynamics of GI-Luenberger observer stating,

$$||B_w - L|| = 0$$

the ideal case is obtained as

$$B_w = L$$

for complete invariance respect to α , but practically the following \mathcal{H}_∞ problem is more applicable,

$$\begin{aligned} & \min_L \gamma \text{ s.t.} \\ & P \succ 0 \\ & \begin{bmatrix} (A - LC)^T P + P(A - LC) & P(B_w - L) \\ P(B_w - L)^T & -\gamma I \end{bmatrix} \prec 0 \end{aligned}$$

which results in the following LMI problem,

$$\begin{aligned} & \min_L \rho \text{ s.t.} \\ & P \succ 0 \\ & \begin{bmatrix} A^T P + PA - YC - C^T Y^T & PB_w - Y \\ (PB_w)^T - Y^T & -\rho I \end{bmatrix} \prec 0 \\ & L = P^{-1}Y, \gamma = \sqrt{\rho} \end{aligned}$$