

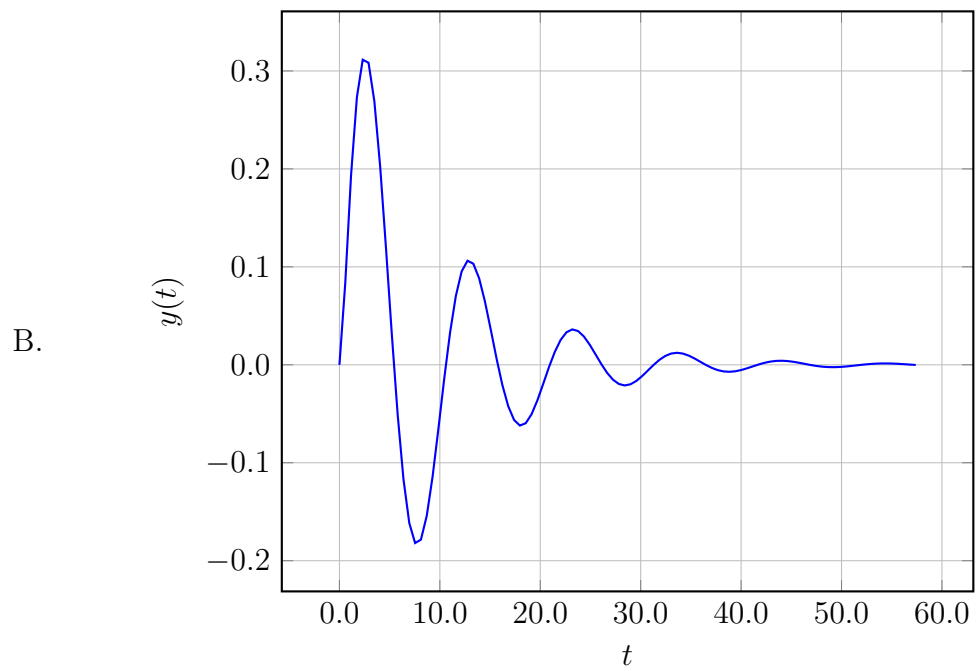
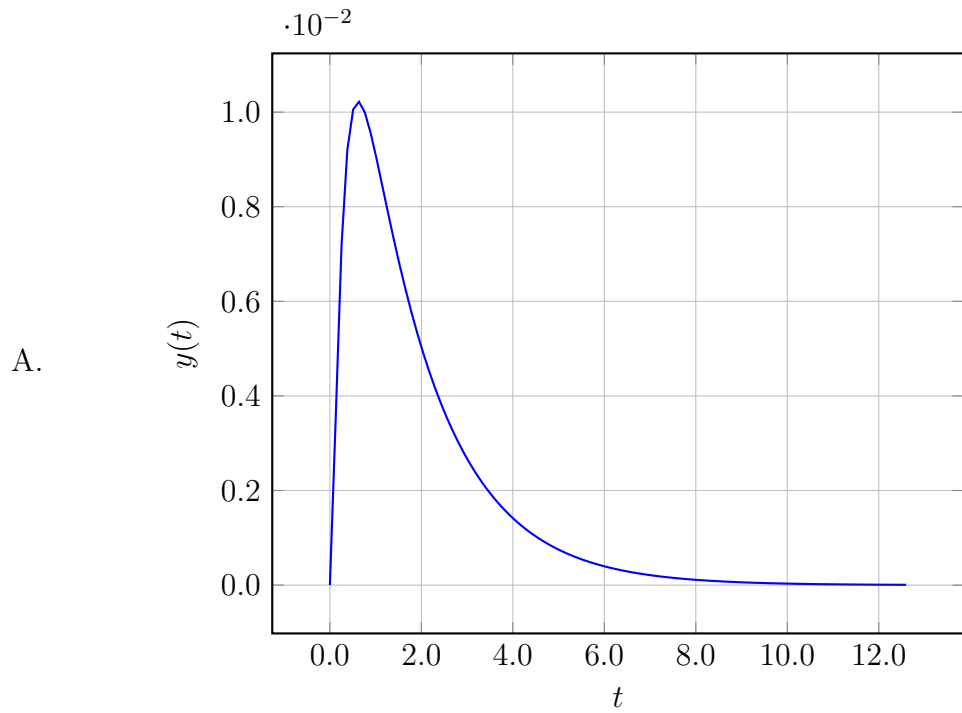
1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.11615s + 7.11615}$$

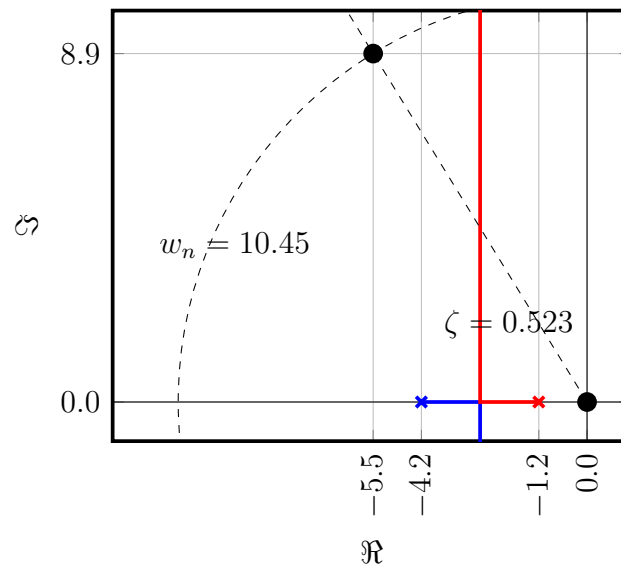
Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

- A. $F(s) = 0.96465 + \frac{2.73232}{s}$
- B. $F(s) = 1.19696 + \frac{1.23232}{s}$
- C. $F(s) = -2.73232 + \frac{0.61615}{s}$
- D. $F(s) = -9.30304 + \frac{2.73232}{s}$
- E. $F(s) = -9.53535 + \frac{1.23232}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

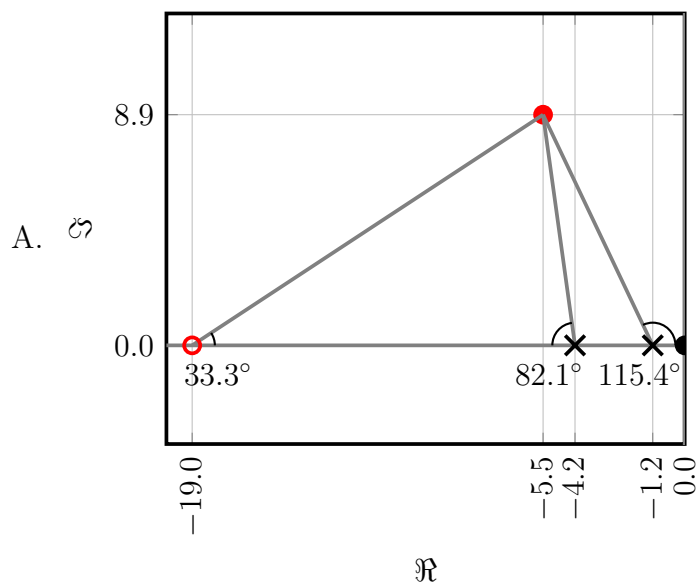


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

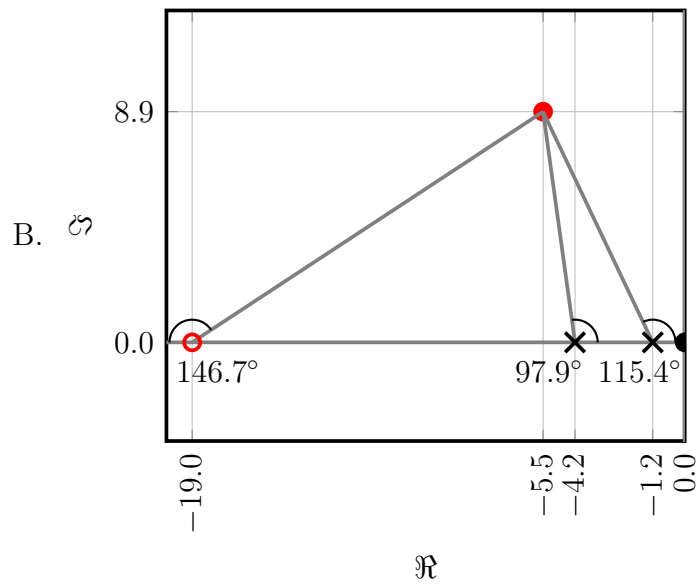


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

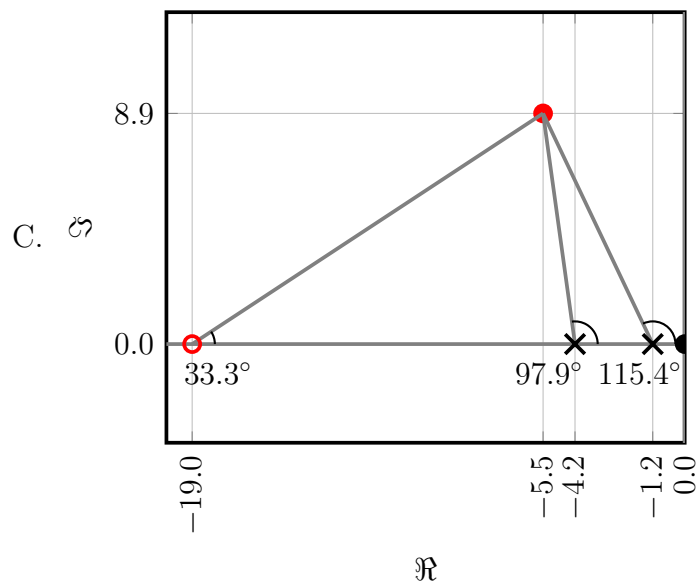
$$\sum \theta = 115.4^\circ + 82.1^\circ + 33.3^\circ =$$



$$\sum \theta = 115.4^\circ + 97.9^\circ + 146.7^\circ =$$

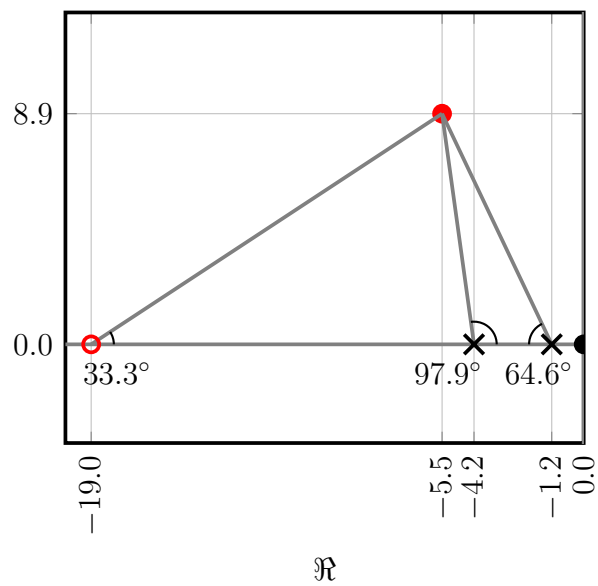


$$\sum \theta = 115.4^\circ + 97.9^\circ - 33.3^\circ =$$



$$\sum \theta = 64.6^\circ + 97.9^\circ + 33.3^\circ =$$

D. \mathcal{O}



$$\sum \theta = 115.4^\circ + 97.9^\circ + 33.3^\circ =$$

E. \mathcal{O}

