

1. (35 points) An open-loop transfer function is given by,

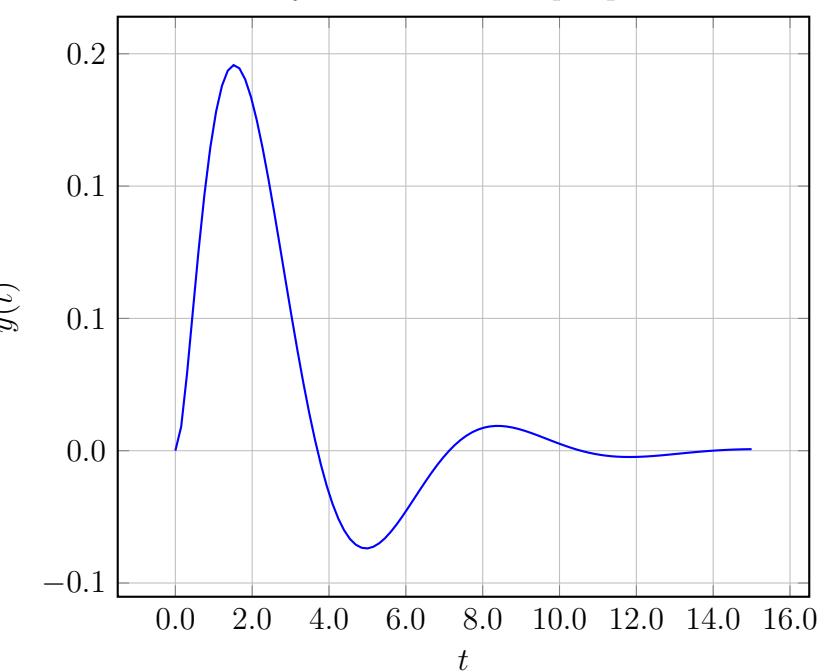
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.5s + 7.5}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

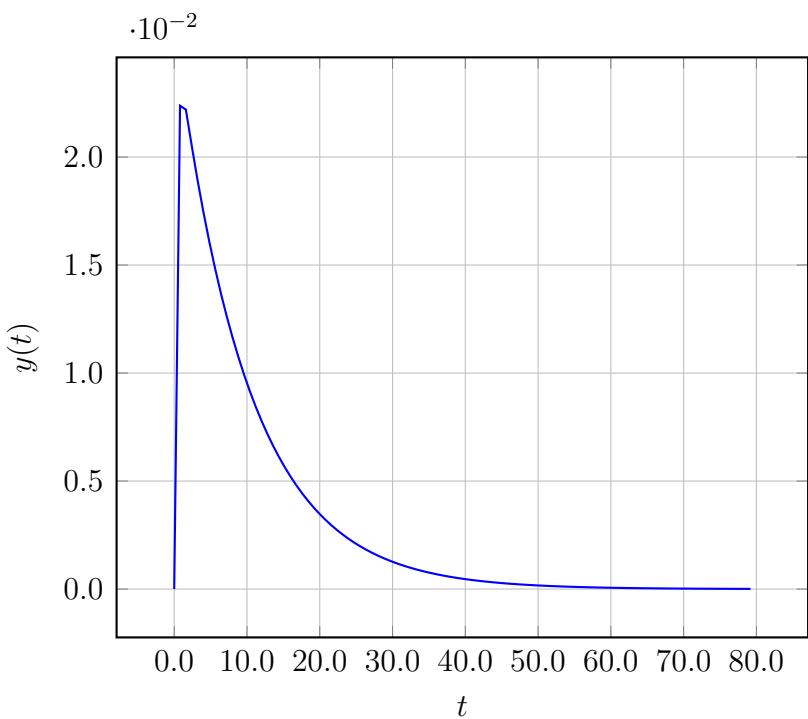
- A.  $F(s) = -3.5 + \frac{1.0}{s}$
- B.  $F(s) = 2.5 + \frac{3.5}{s}$
- C.  $F(s) = 3.5 + \frac{2.0}{s}$
- D.  $F(s) = -8.0 + \frac{2.0}{s}$
- E.  $F(s) = -7.0 + \frac{3.5}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

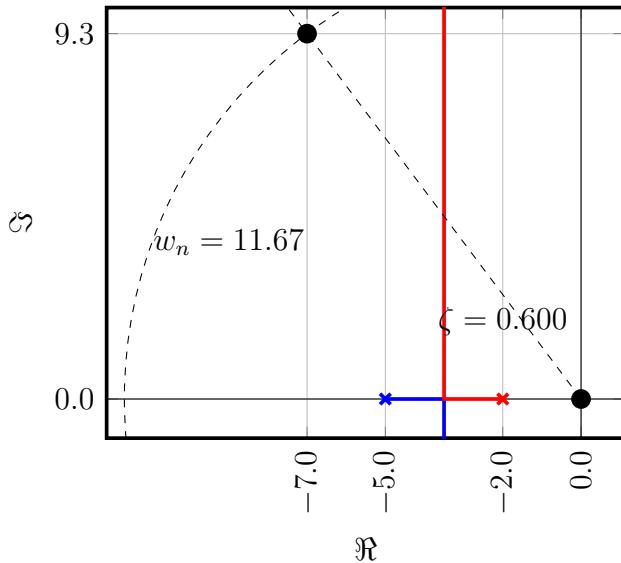
A.



B.

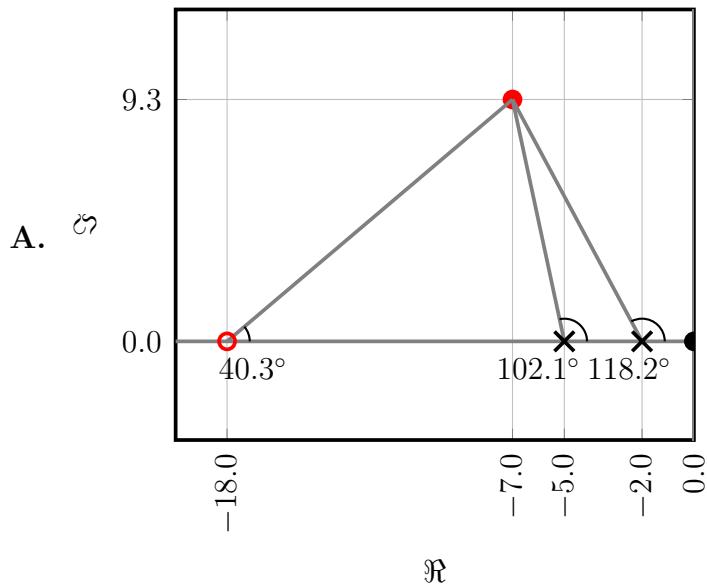


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

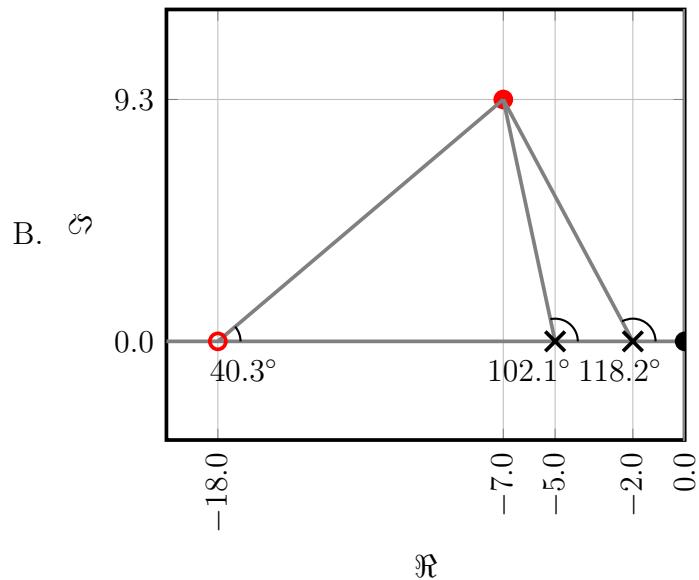


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

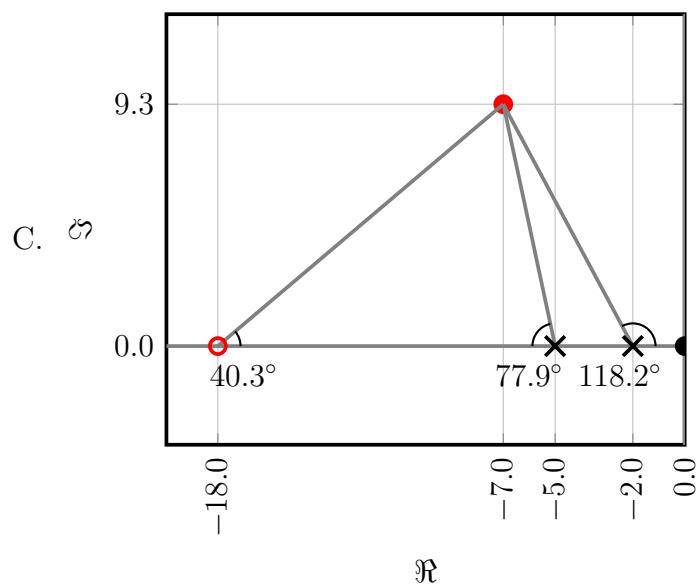
$$\sum \theta = 118.2^\circ + 102.1^\circ - 40.3^\circ = 180.0^\circ$$



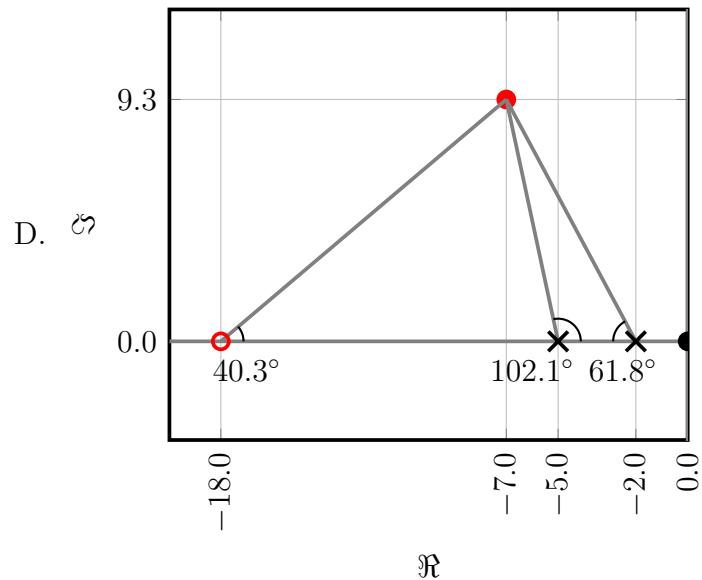
$$\sum \theta = 118.2^\circ + 102.1^\circ + 40.3^\circ = 260.5^\circ$$



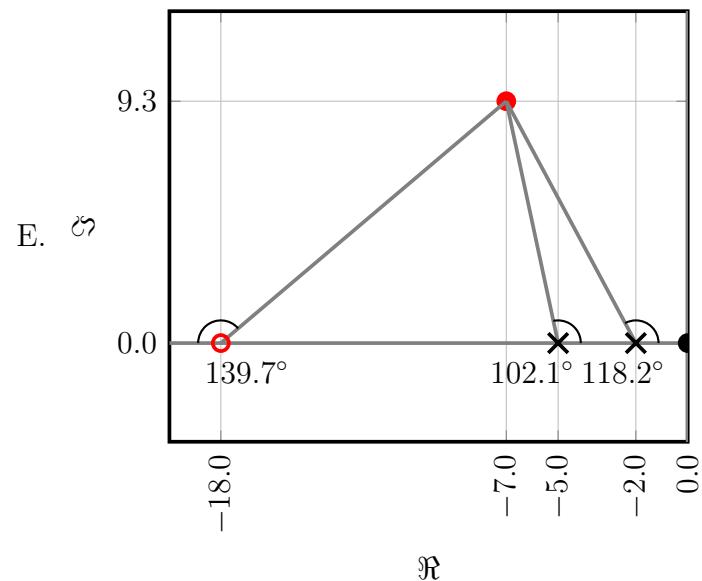
$$\sum \theta = 118.2^\circ + 77.9^\circ + 40.3^\circ = 236.4^\circ$$



$$\sum \theta = 61.8^\circ + 102.1^\circ + 40.3^\circ = 204.2^\circ$$



$$\sum \theta = 118.2^\circ + 102.1^\circ + 139.7^\circ = 360.0^\circ$$



Q	A
1	A
2	B
3	A