

1. (35 points) An open-loop transfer function is given by,

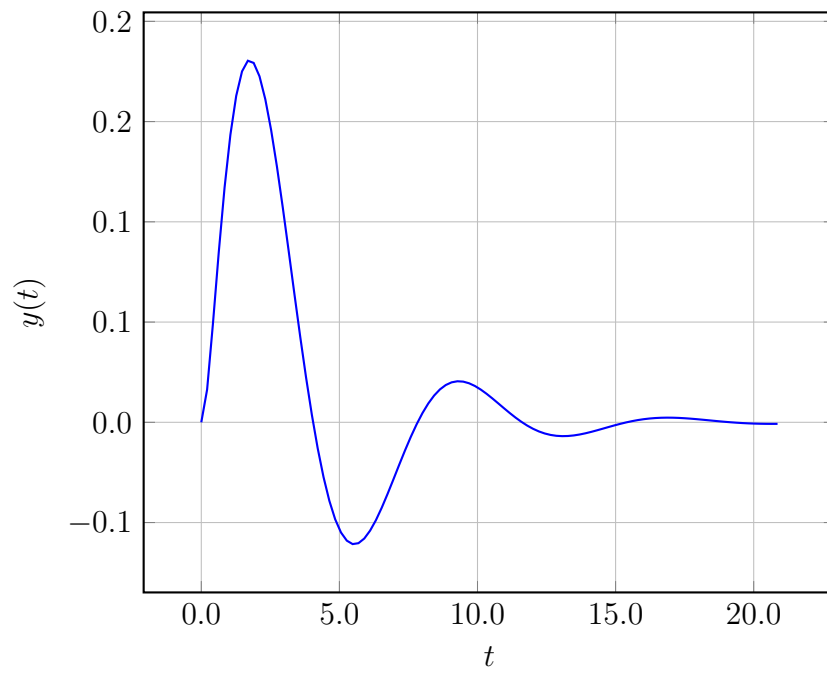
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.37878s + 7.37878}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

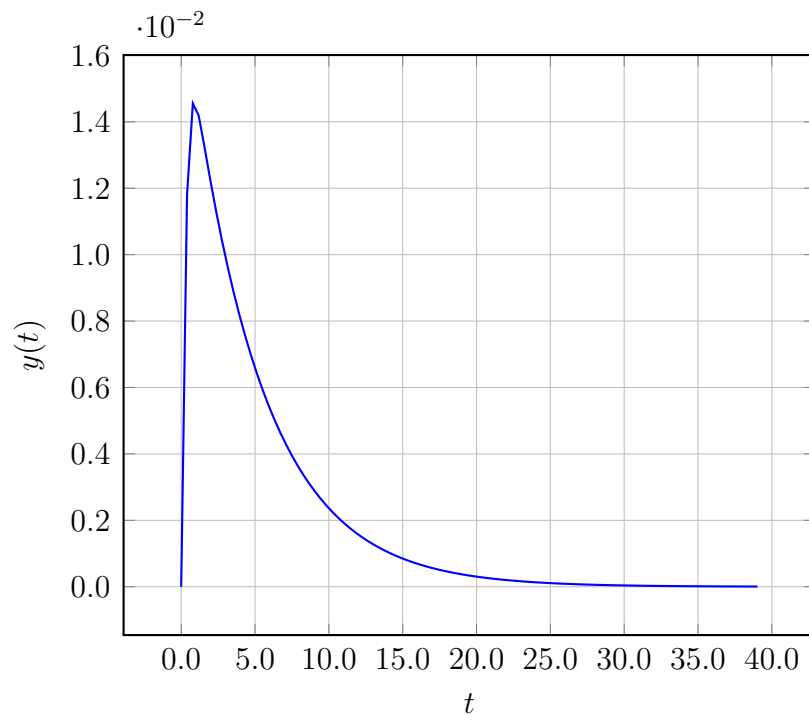
- A. $F(s) = 2.77272 + \frac{1.75757}{s}$
- B. $F(s) = -8.48486 + \frac{1.75757}{s}$
- C. $F(s) = -3.25757 + \frac{0.87878}{s}$
- D. $F(s) = 2.01514 + \frac{3.25757}{s}$
- E. $F(s) = -7.72728 + \frac{3.25757}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

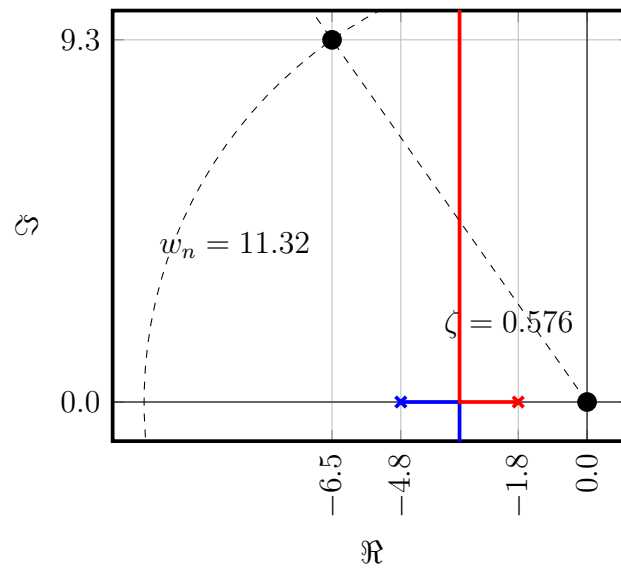
A.



B.

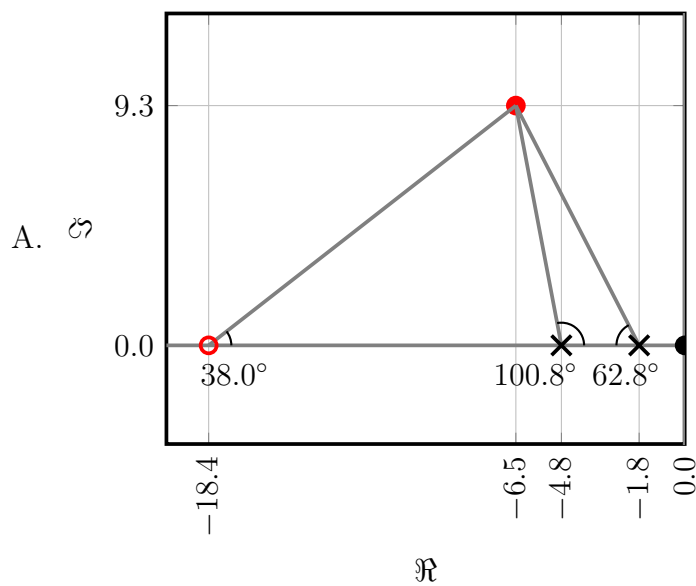


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

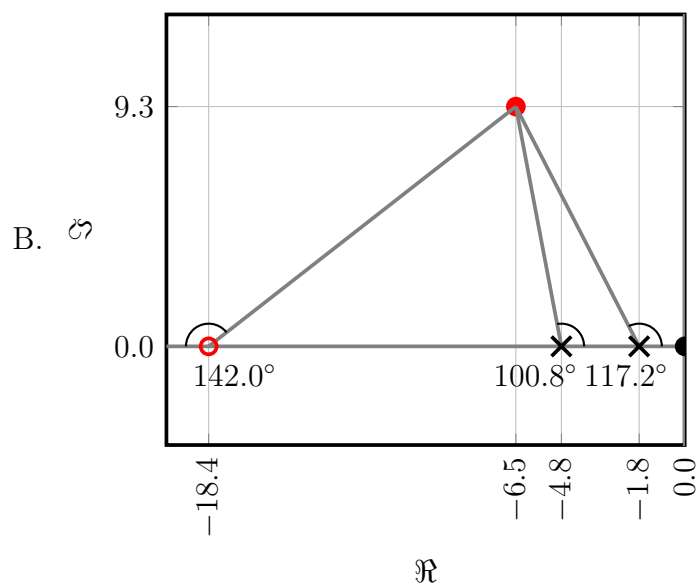


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

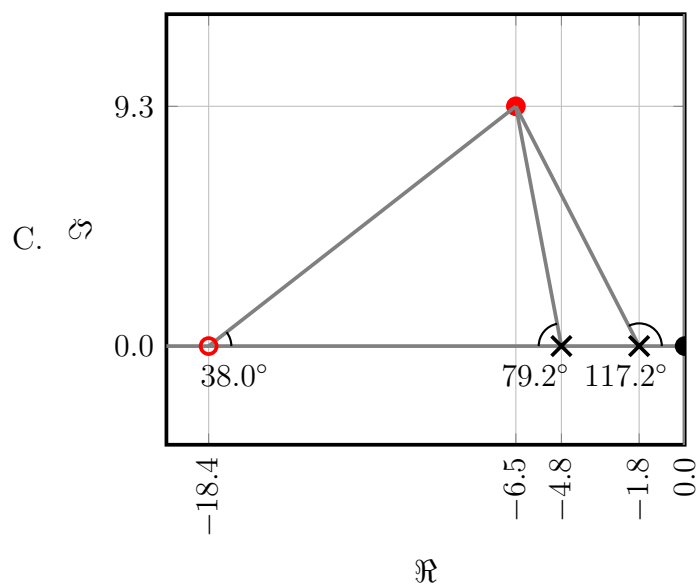
$$\sum \theta = 62.8^\circ + 100.8^\circ + 38.0^\circ = 201.5^\circ$$



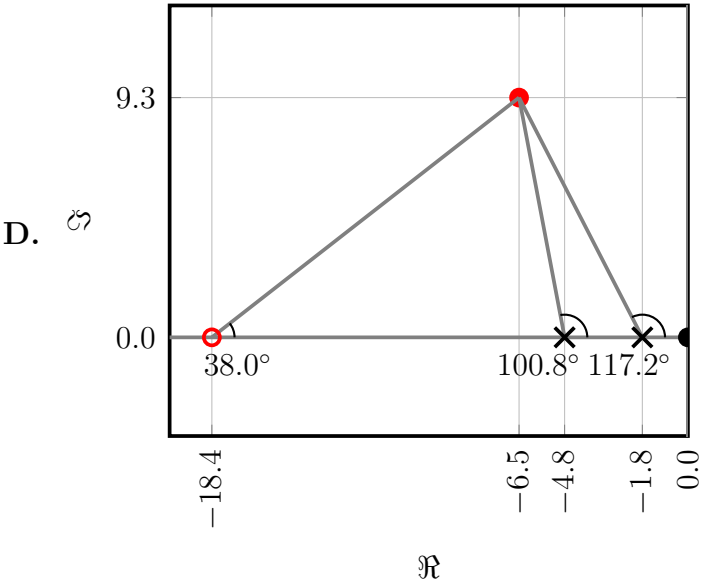
$$\sum \theta = 117.2^\circ + 100.8^\circ + 142.0^\circ = 360.0^\circ$$



$$\sum \theta = 117.2^\circ + 79.2^\circ + 38.0^\circ = 234.4^\circ$$



$$\sum \theta = 117.2^{\circ} + 100.8^{\circ} - 38.0^{\circ} = 180.0^{\circ}$$



Q	A
1	C
2	B
3	D