

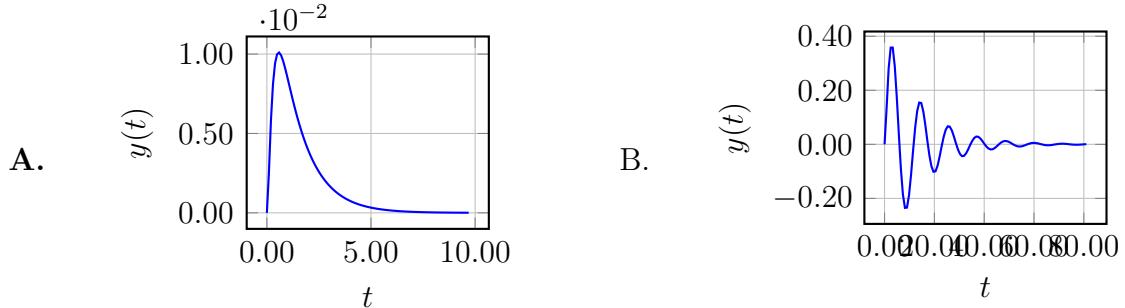
1. (35 points) An open-loop transfer function is given as,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.05554s + 7.05554}$$

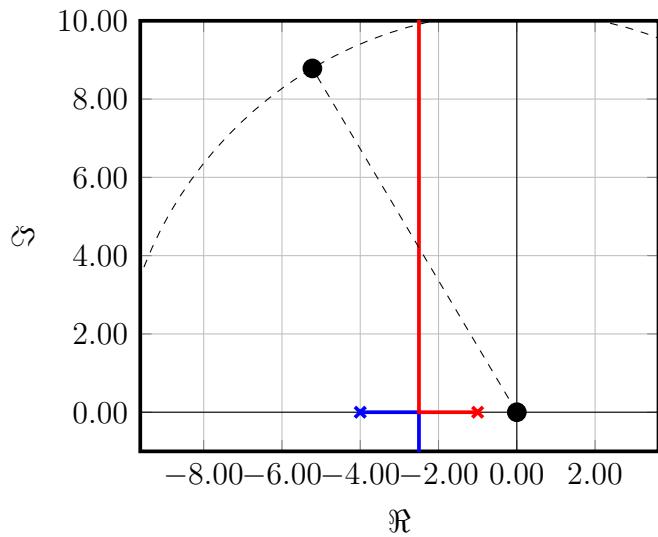
which of the following PI-controllers stabilizes the system in a closed-loop unit feedback structure?

- A. $F(s) = -9.77779 + \frac{1.1111}{s}$
- B. $F(s) = -2.6111 + \frac{0.55554}{s}$
- C. $F(s) = 0.83333 + \frac{1.1111}{s}$
- D. $F(s) = 0.72221 + \frac{2.6111}{s}$
- E. $F(s) = -9.66667 + \frac{2.6111}{s}$

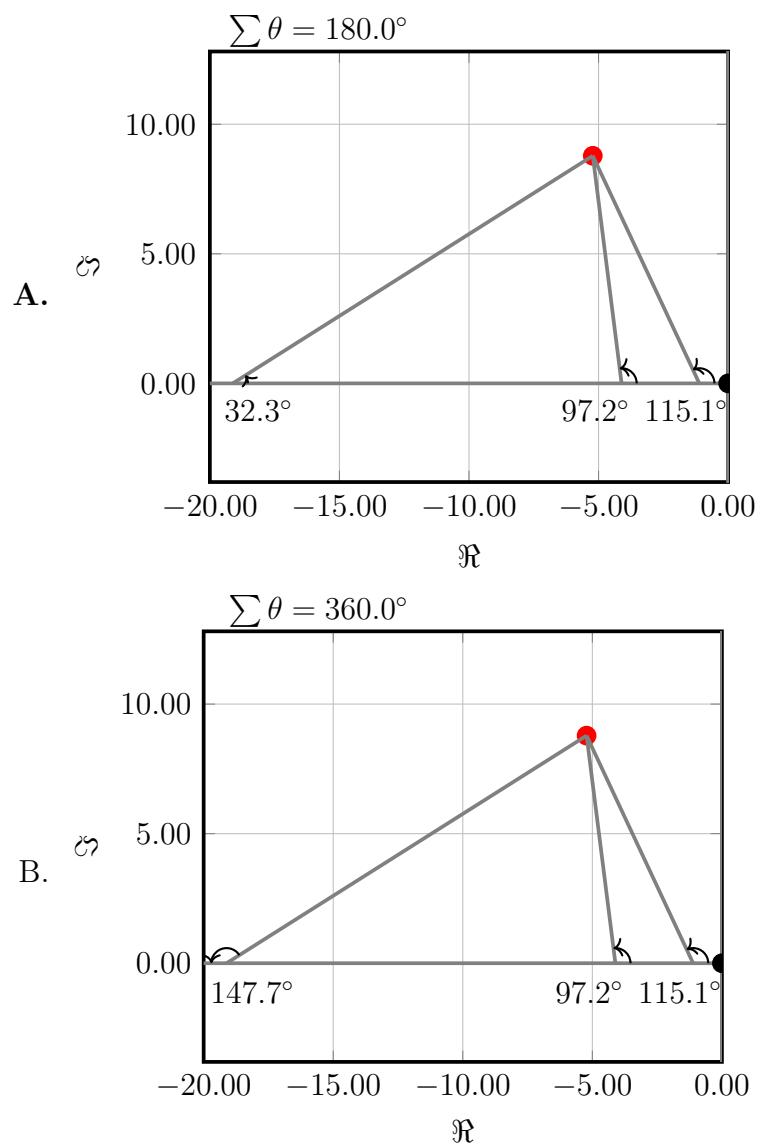
2. (35 points) Which of the following does not overshoot?



3. (30 points) Time-domain criteria is give as settling time $t_s = 1 s$ and overshoot $os = 10\%$. The root-locus plot for the P-type controller design is depicted below.



Upgrading the controller to a PD-type controller which of the following angle conditions need to be used?



Q	A
1	B
2	A
3	A