

1. (35 points) An open-loop transfer function is given by,

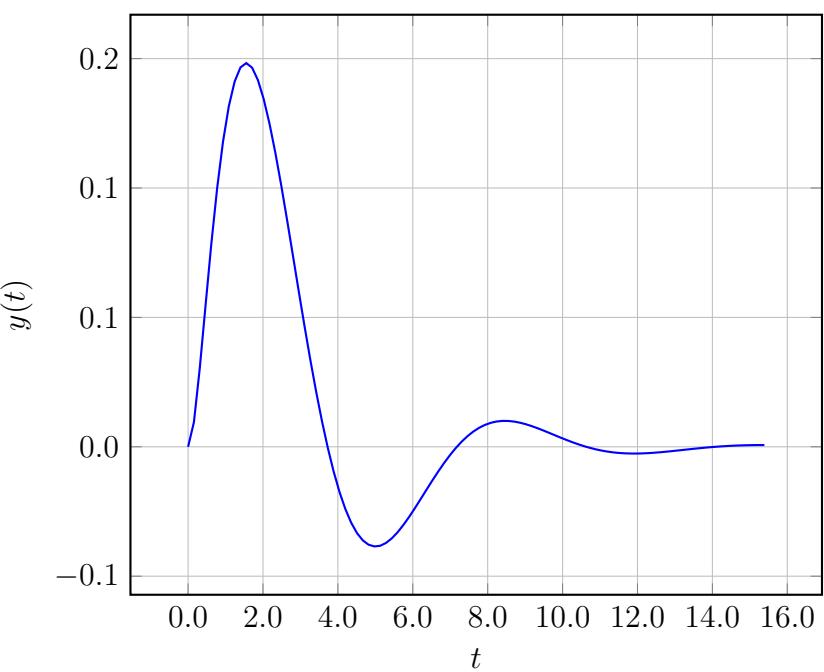
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.4899s + 7.4899}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

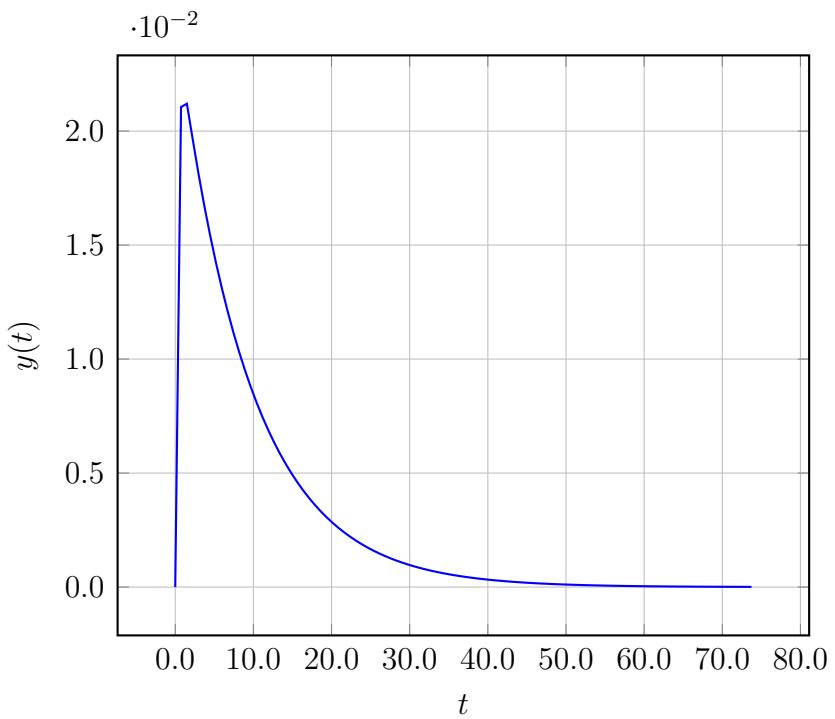
- A. $F(s) = -7.06061 + \frac{3.4798}{s}$
- B. $F(s) = -3.4798 + \frac{0.9899}{s}$
- C. $F(s) = -8.0404 + \frac{1.9798}{s}$
- D. $F(s) = 2.4596 + \frac{3.4798}{s}$
- E. $F(s) = 3.43939 + \frac{1.9798}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

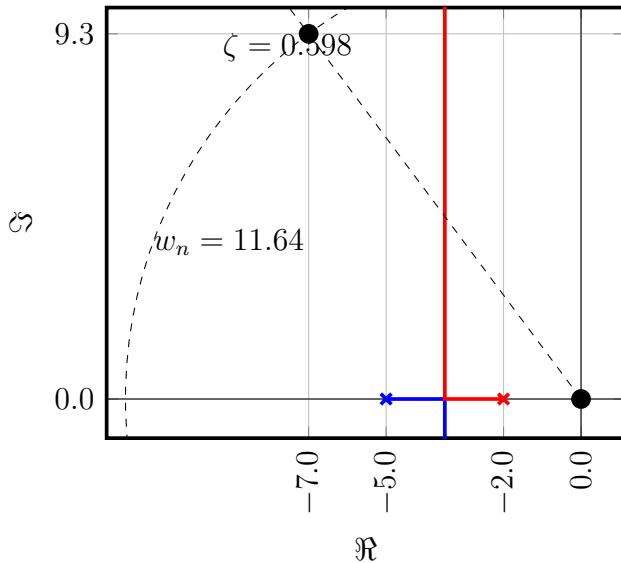
A.



B.

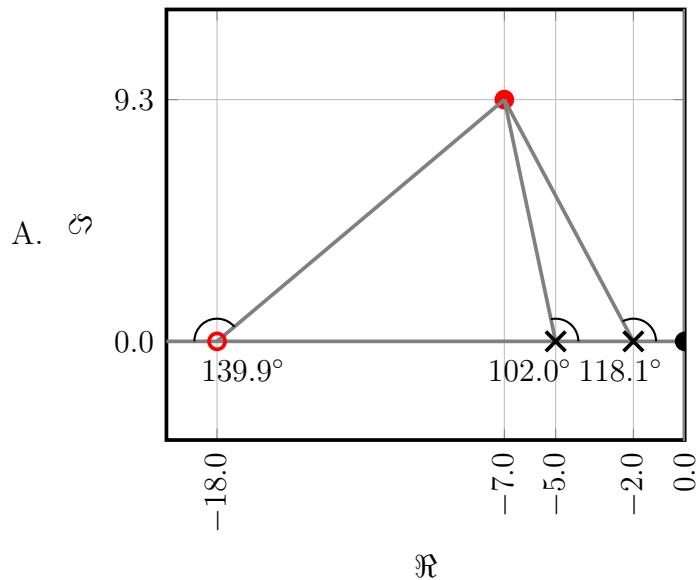


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

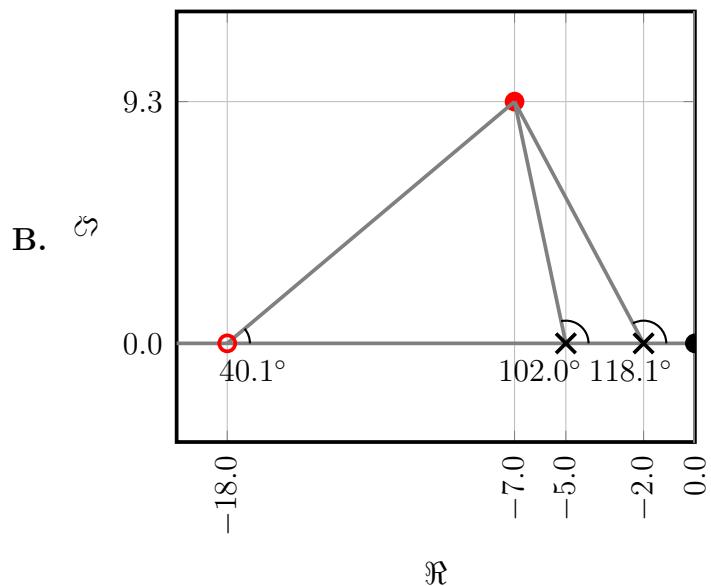


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

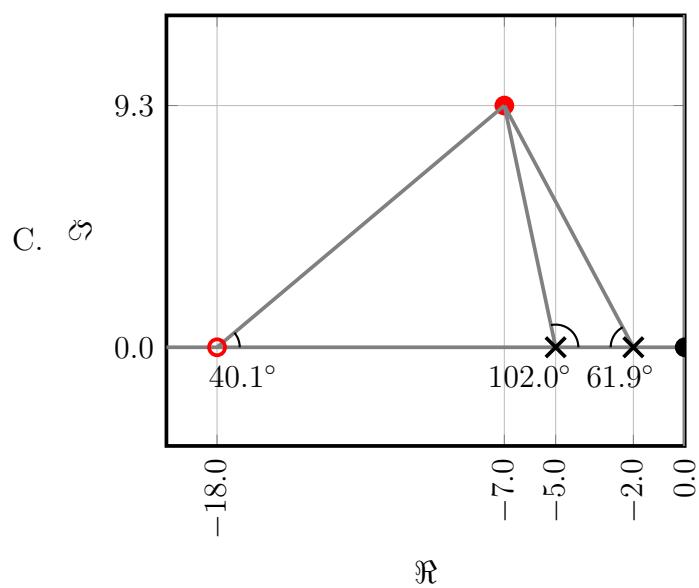
$$\sum \theta = 118.1^\circ + 102.0^\circ + 139.9^\circ = 360.0^\circ$$



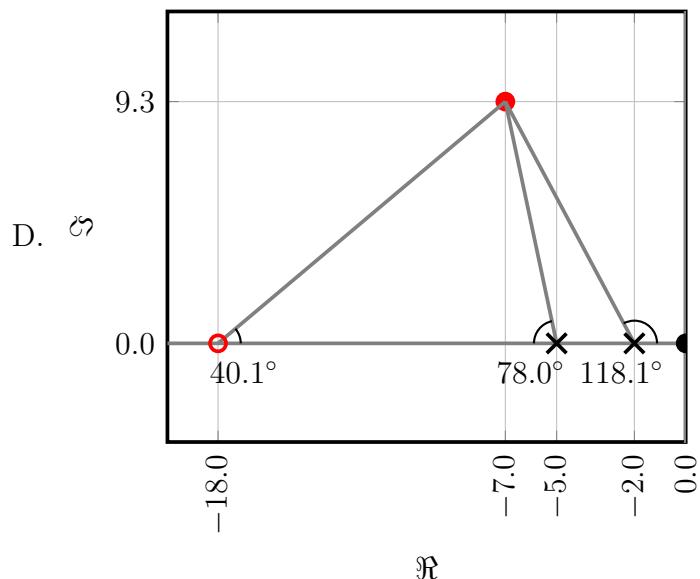
$$\sum \theta = 118.1^\circ + 102.0^\circ - 40.1^\circ = 180.0^\circ$$



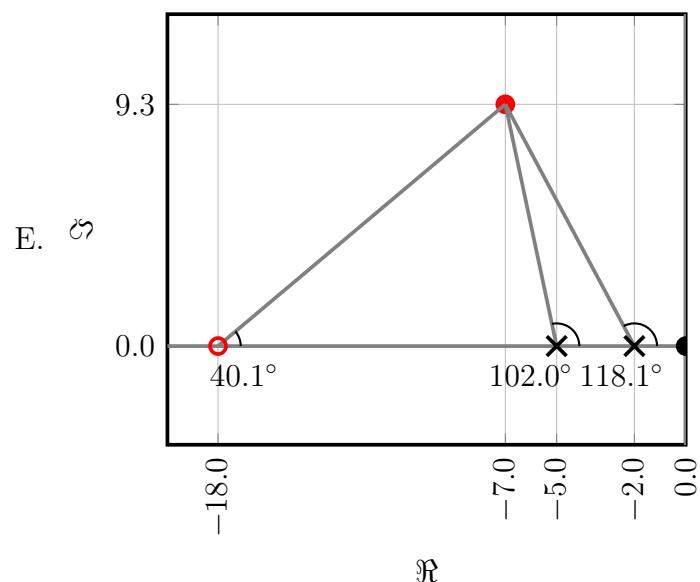
$$\sum \theta = 61.9^\circ + 102.0^\circ + 40.1^\circ = 204.0^\circ$$



$$\sum \theta = 118.1^\circ + 78.0^\circ + 40.1^\circ = 236.2^\circ$$



$$\sum \theta = 118.1^\circ + 102.0^\circ + 40.1^\circ = 260.2^\circ$$



Q	A
1	B
2	B
3	B