

1. (35 points) An open-loop transfer function is given by,

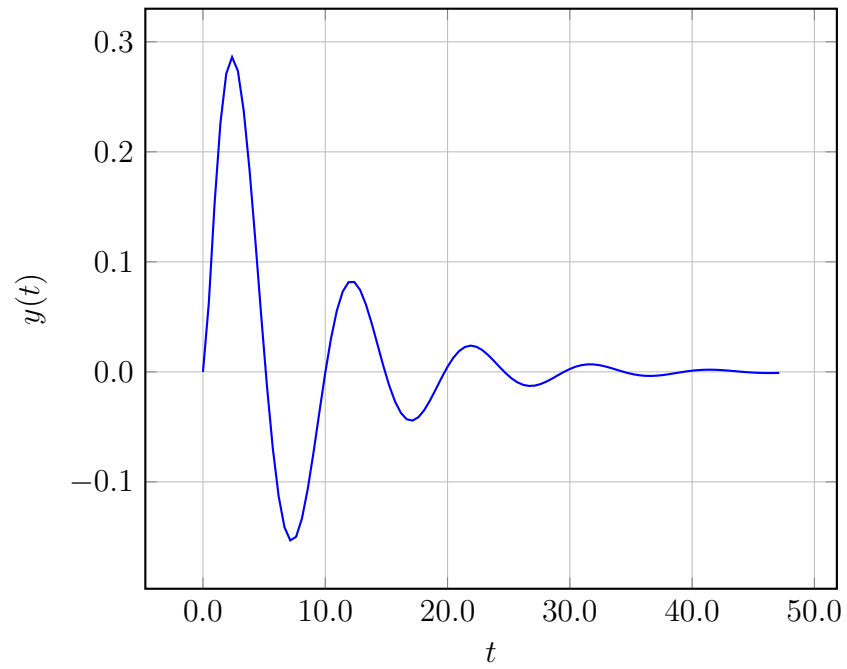
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.15656s + 7.15656}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

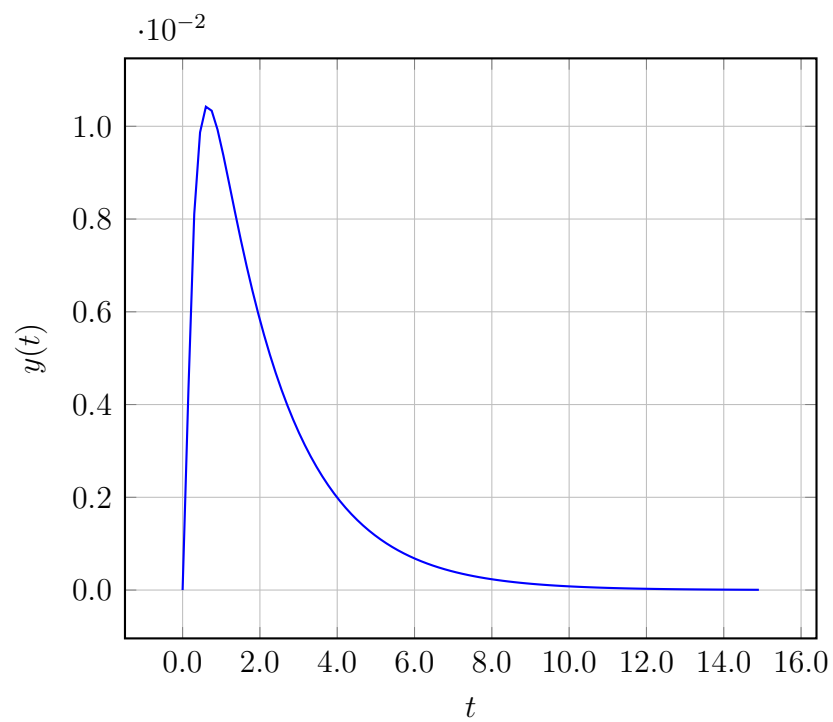
- A. $F(s) = -9.37375 + \frac{1.31313}{s}$
- B. $F(s) = 1.43939 + \frac{1.31313}{s}$
- C. $F(s) = -2.81313 + \frac{0.65656}{s}$
- D. $F(s) = -9.06061 + \frac{2.81313}{s}$
- E. $F(s) = 1.12625 + \frac{2.81313}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

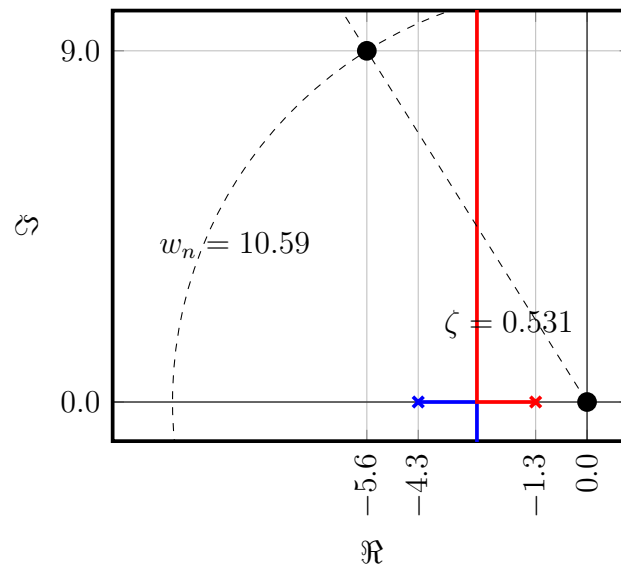
A.



B.

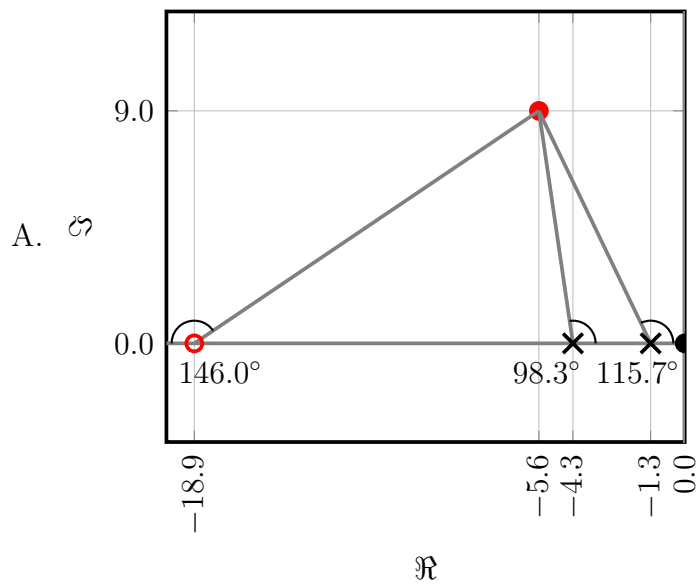


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

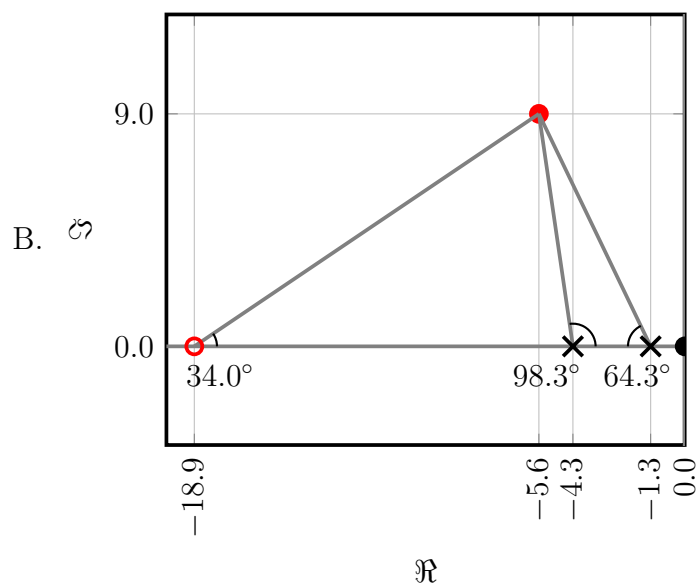


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

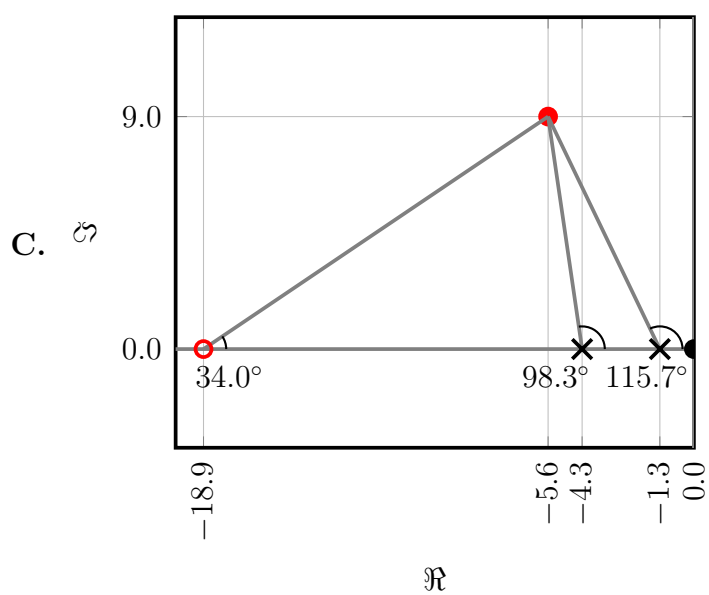
$$\sum \theta = 115.7^\circ + 98.3^\circ + 146.0^\circ = 360.0^\circ$$



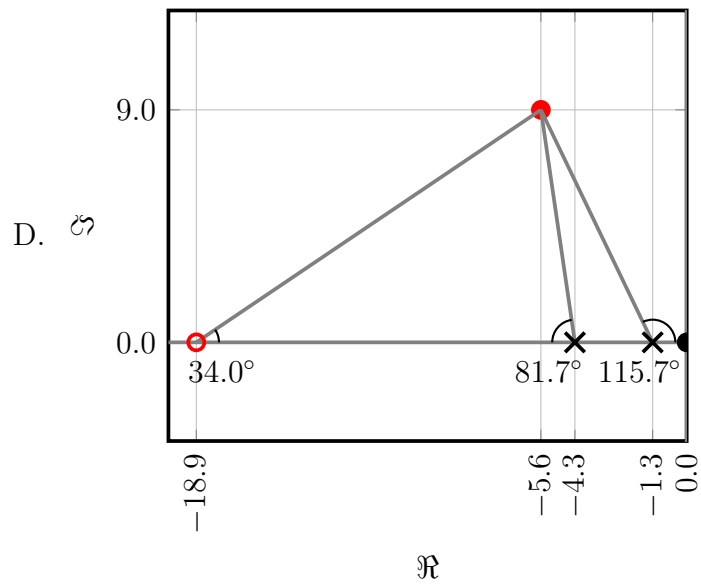
$$\sum \theta = 64.3^\circ + 98.3^\circ + 34.0^\circ = 196.7^\circ$$



$$\sum \theta = 115.7^\circ + 98.3^\circ - 34.0^\circ = 180.0^\circ$$



$$\sum \theta = 115.7^{\circ} + 81.7^{\circ} + 34.0^{\circ} = 231.4^{\circ}$$



Q	A
1	C
2	B
3	C