

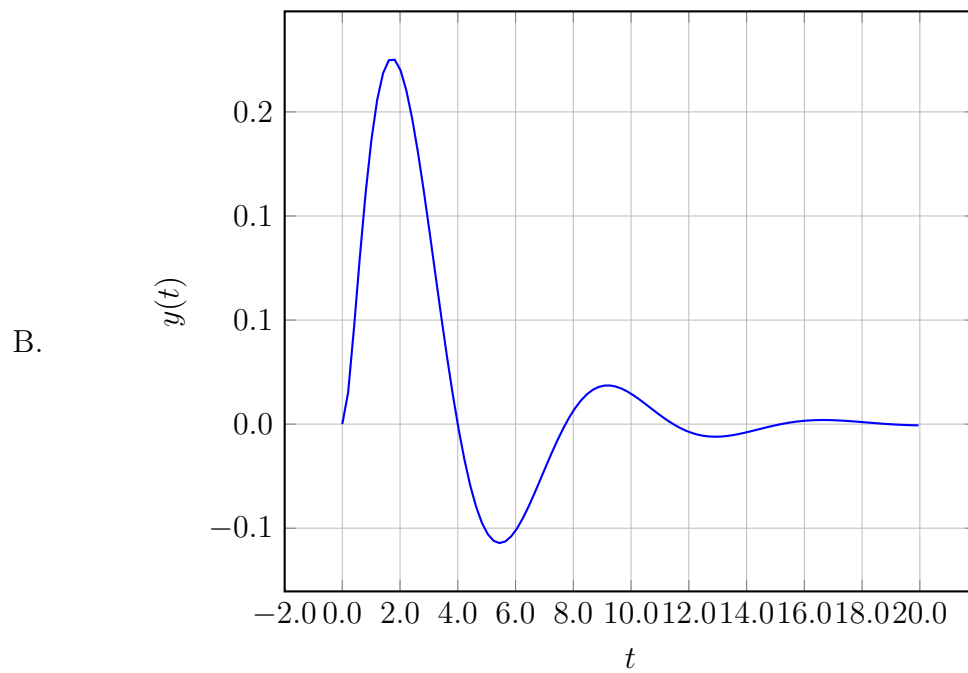
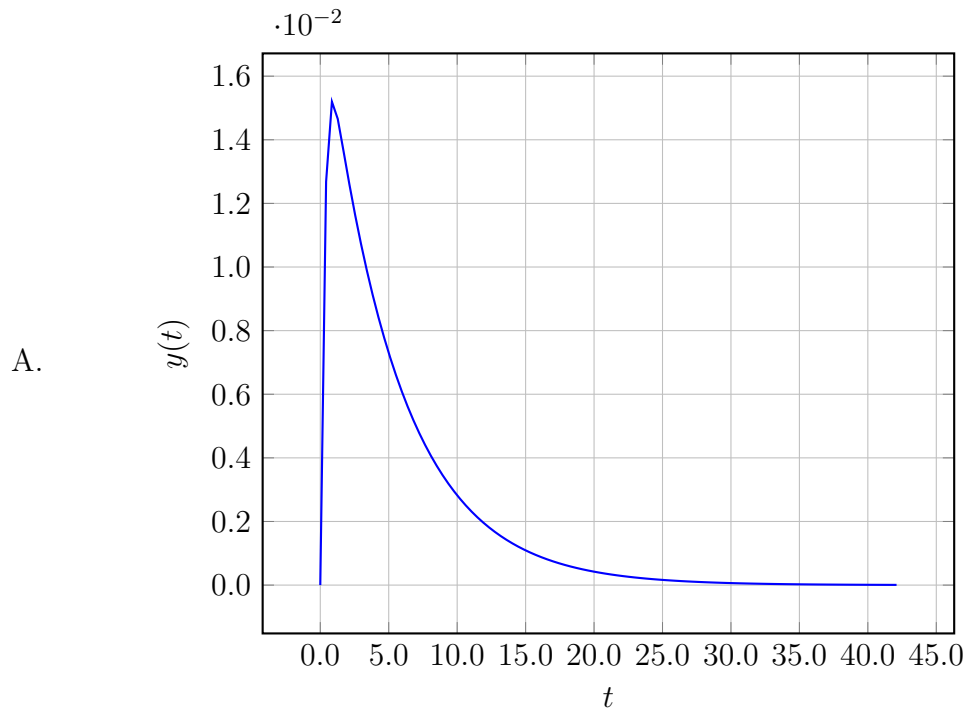
1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.39394s + 7.39394}$$

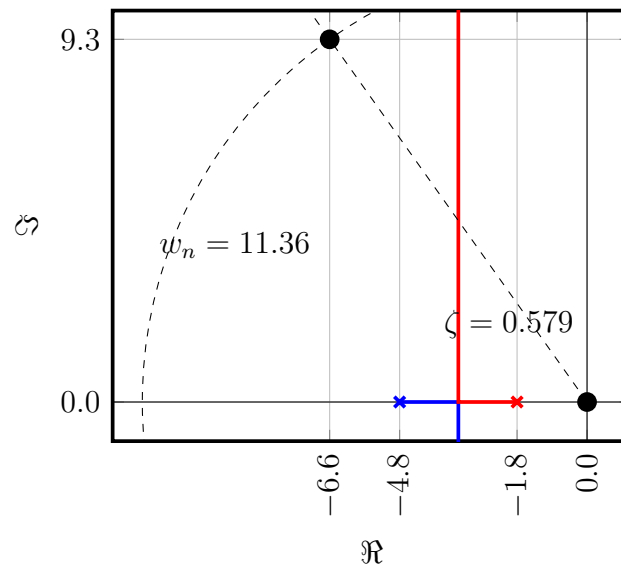
Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

- A. $F(s) = 2.07574 + \frac{3.28787}{s}$
- B. $F(s) = 2.86363 + \frac{1.78787}{s}$
- C. $F(s) = -7.63637 + \frac{3.28787}{s}$
- D. $F(s) = -3.28787 + \frac{0.89394}{s}$
- E. $F(s) = -8.42426 + \frac{1.78787}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

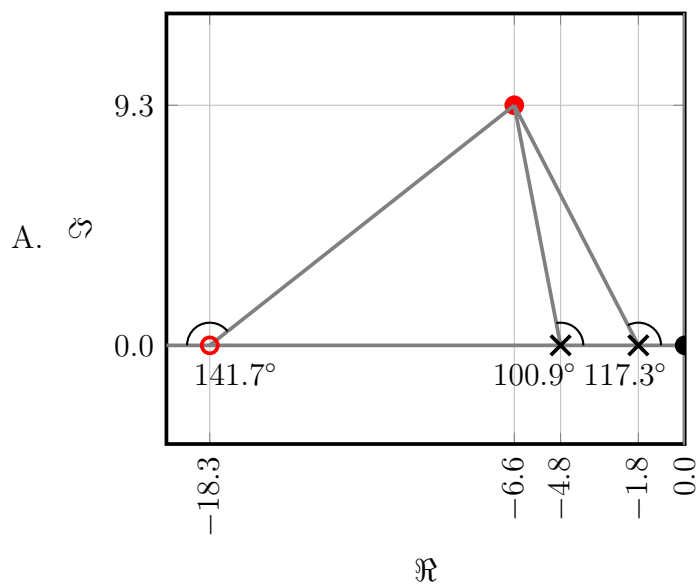


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

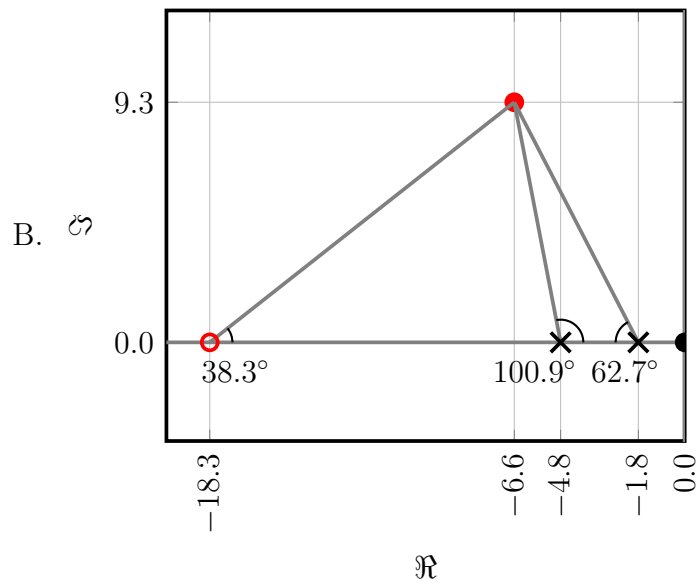


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

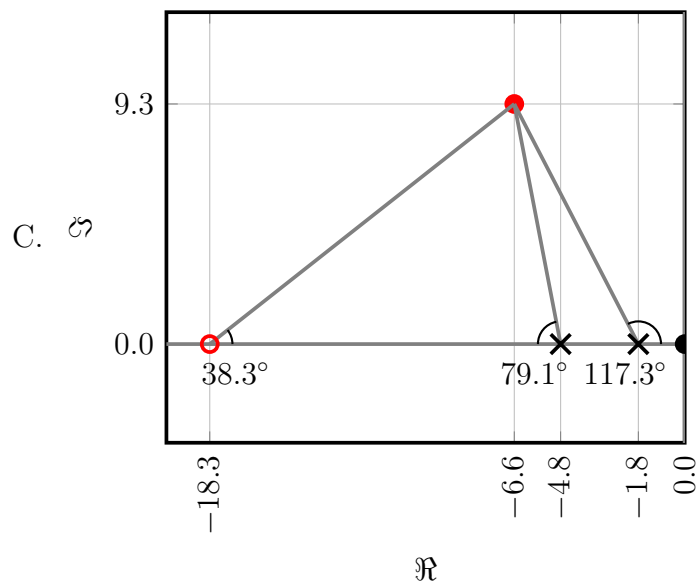
$$\sum \theta = 117.3^\circ + 100.9^\circ + 141.7^\circ =$$



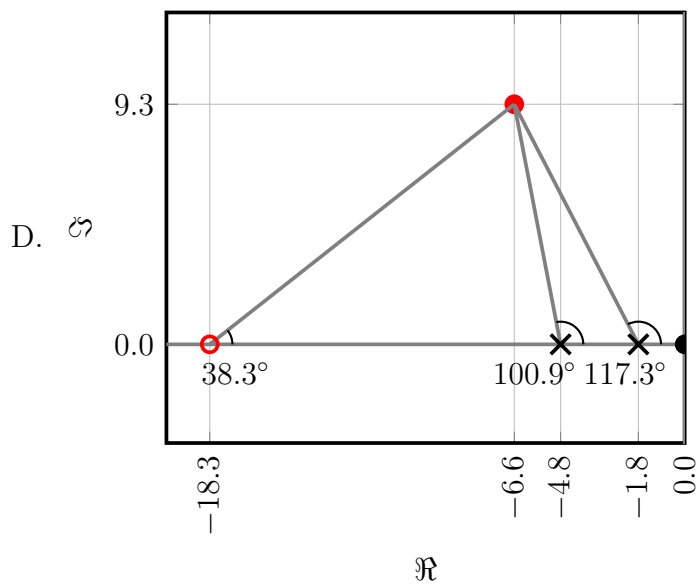
$$\sum \theta = 62.7^\circ + 100.9^\circ + 38.3^\circ =$$



$$\sum \theta = 117.3^\circ + 79.1^\circ + 38.3^\circ =$$



$$\sum \theta = 117.3^\circ + 100.9^\circ + 38.3^\circ =$$



$$\sum \theta = 117.3^\circ + 100.9^\circ - 38.3^\circ =$$

