1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.31313s + 7.31313}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

A. $F(s) = -8.12122 + \frac{3.12625}{s}$

B. $F(s) = 2.37878 + \frac{1.62625}{s}$

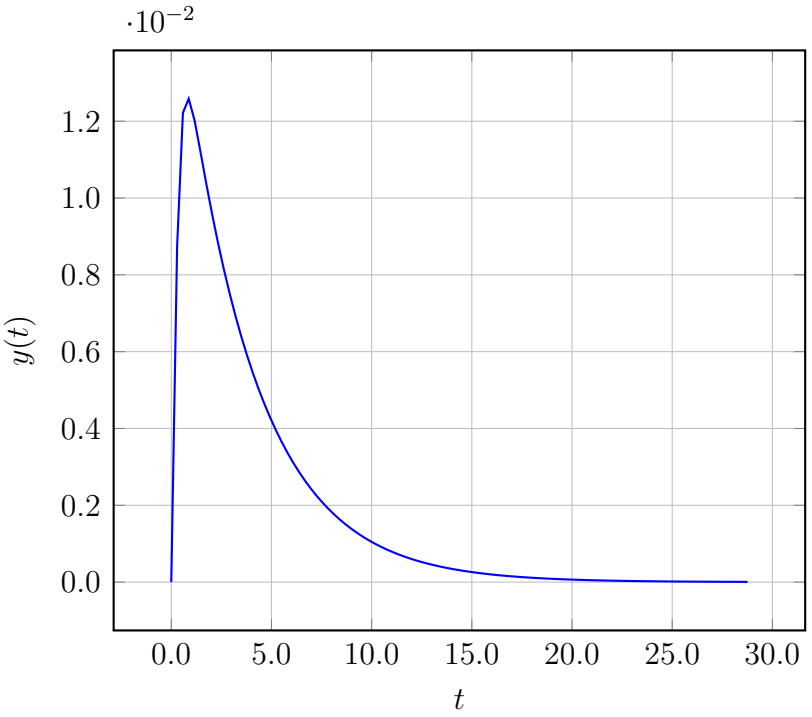
C. $F(s) = -8.74748 + \frac{1.62625}{s}$

D. $F(s) = -3.12625 + \frac{0.81313}{s}$

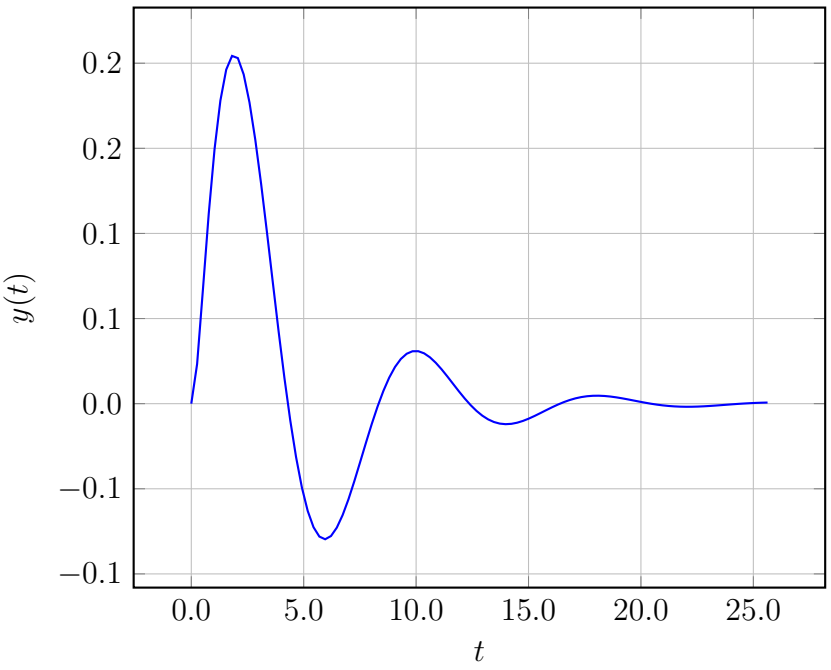
E. $F(s) = 1.75252 + \frac{3.12625}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

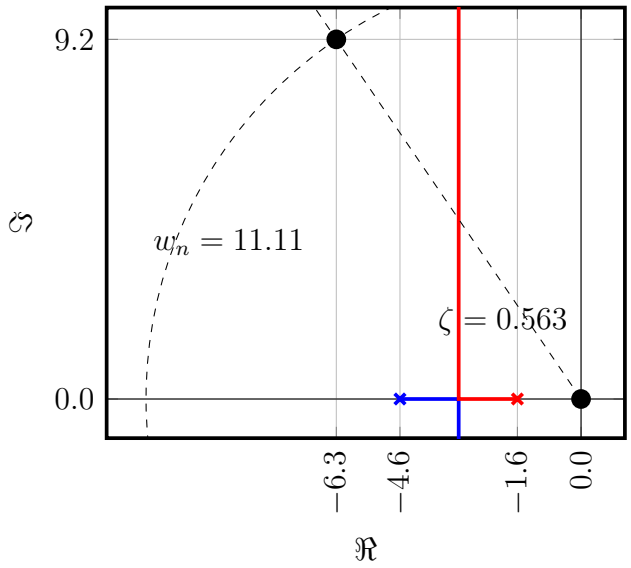
A.



B.



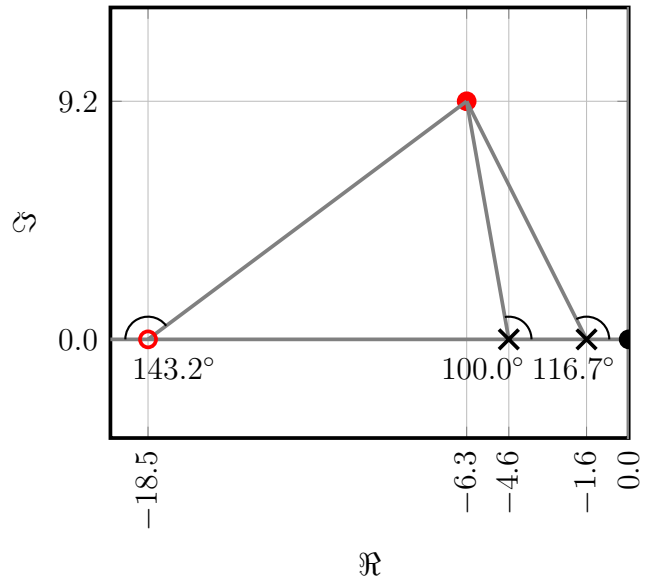
3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.



A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

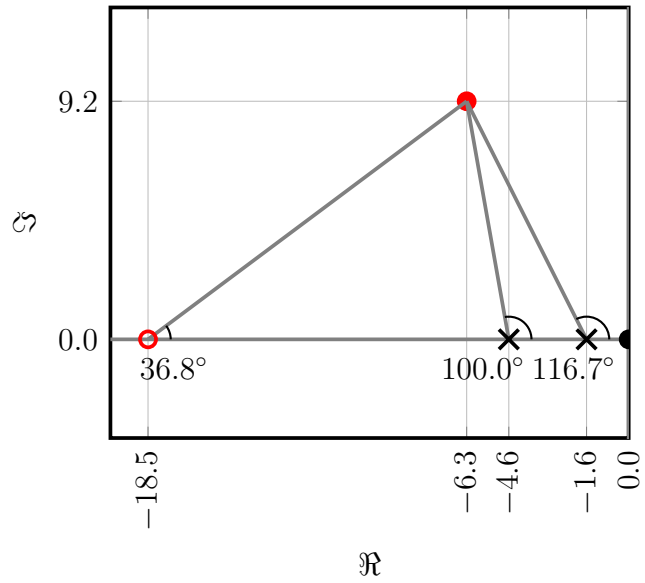
$$\sum \theta = 116.7^\circ + 100.0^\circ + 143.2^\circ = 360.0^\circ$$

A.



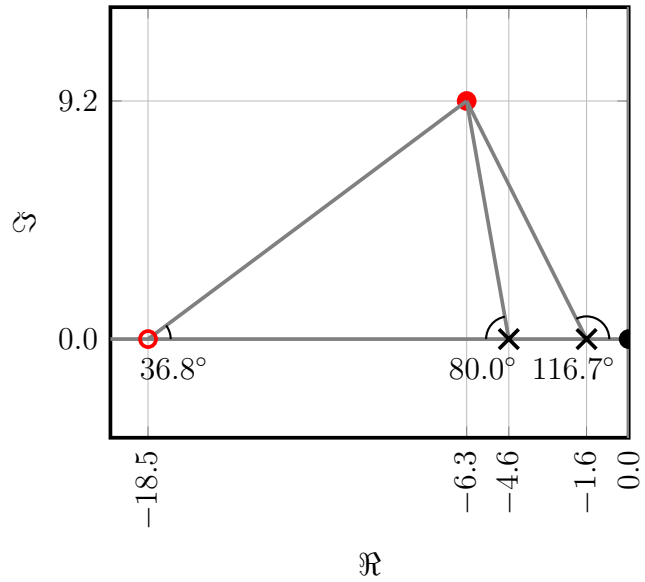
$$\sum \theta = 116.7^\circ + 100.0^\circ + 36.8^\circ = 253.5^\circ$$

B.



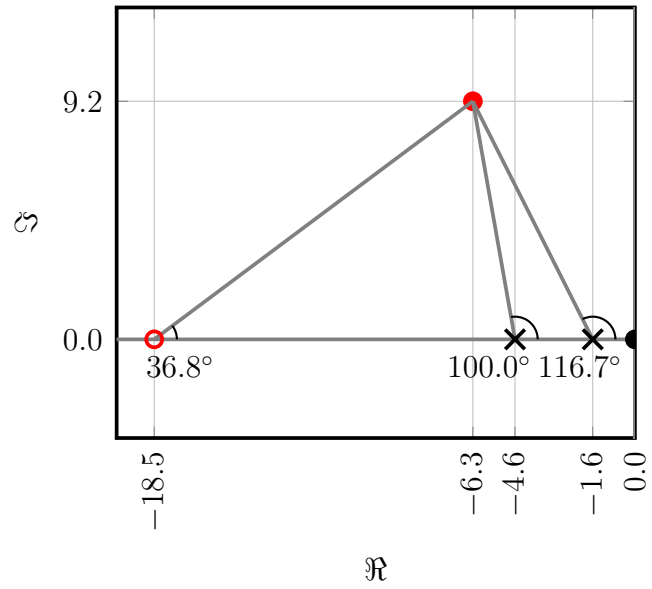
$$\sum \theta = 116.7^\circ + 80.0^\circ + 36.8^\circ = 233.5^\circ$$

C.



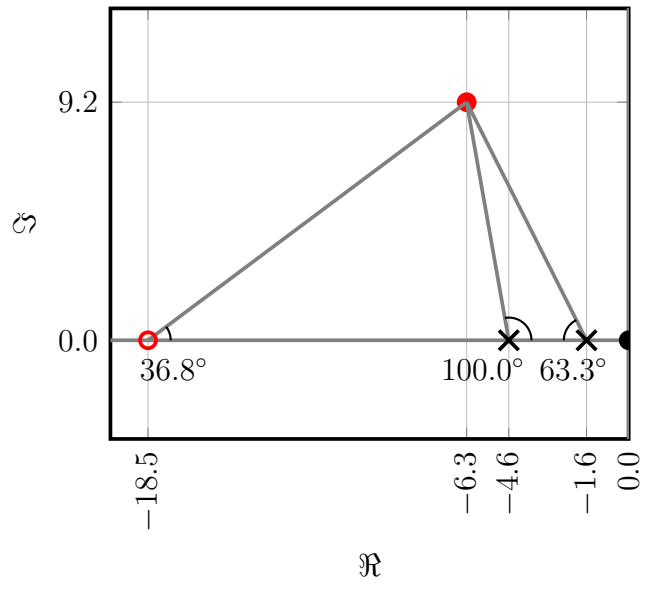
$$\sum \theta = 116.7^\circ + 100.0^\circ - 36.8^\circ = 180.0^\circ$$

D.



$$\sum \theta = 63.3^\circ + 100.0^\circ + 36.8^\circ = 200.1^\circ$$

E.



Q	A
1	D
2	A
3	D