

1. (35 points) An open-loop transfer function is given by,

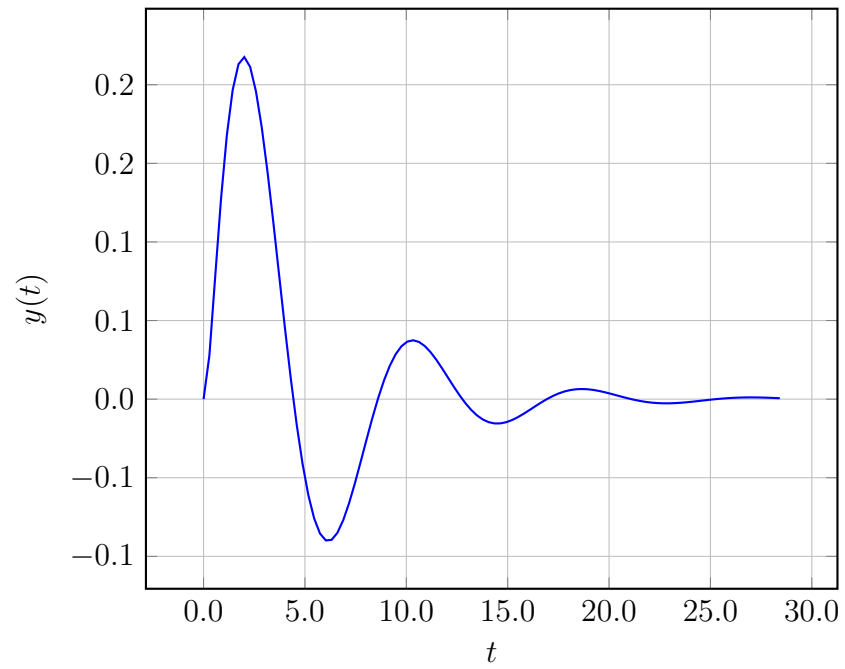
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.28282s + 7.28282}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

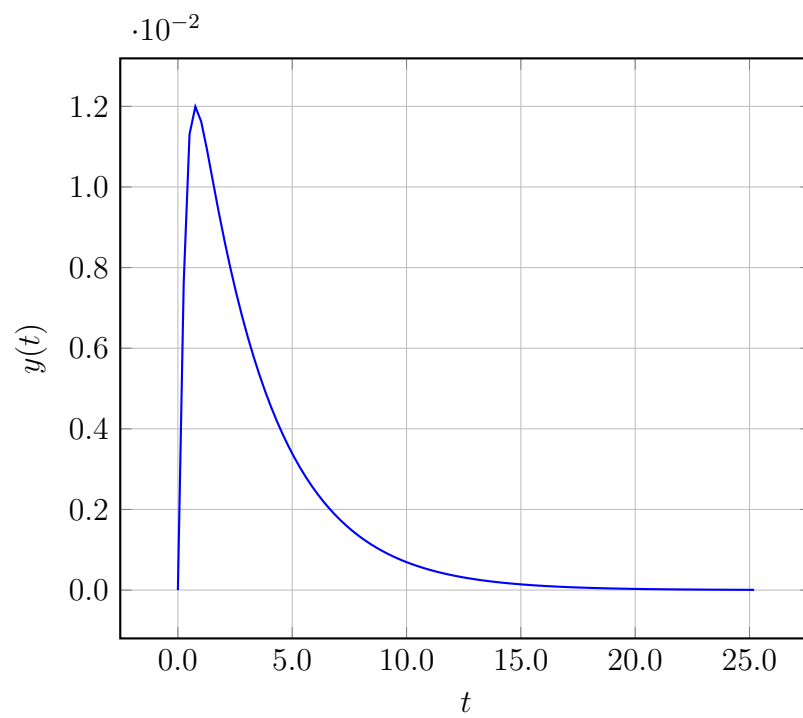
- A.  $F(s) = -8.8687 + \frac{1.56564}{s}$
- B.  $F(s) = 1.6313 + \frac{3.06564}{s}$
- C.  $F(s) = -8.30304 + \frac{3.06564}{s}$
- D.  $F(s) = -3.06564 + \frac{0.78282}{s}$
- E.  $F(s) = 2.19696 + \frac{1.56564}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

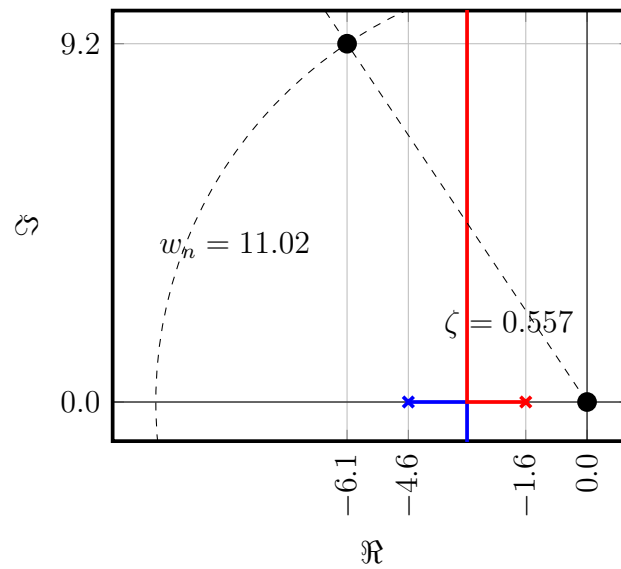
A.



B.

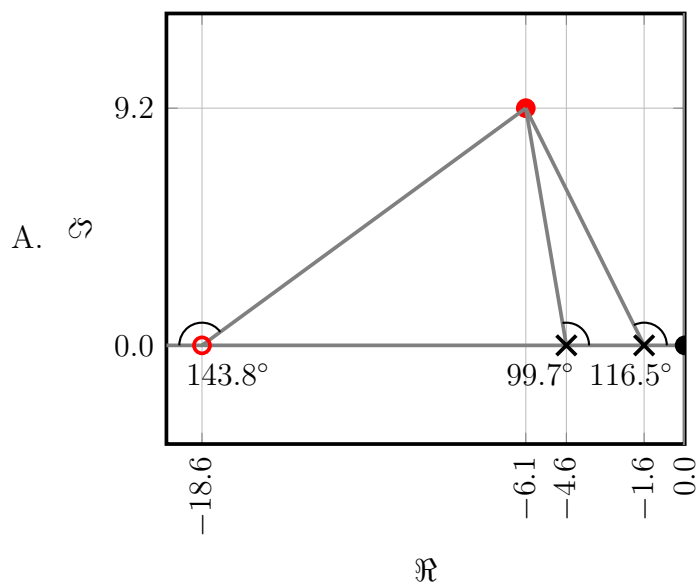


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

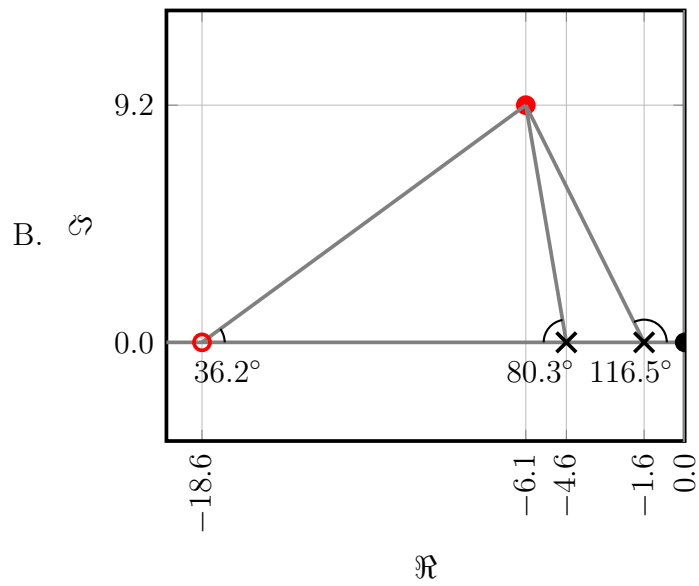


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

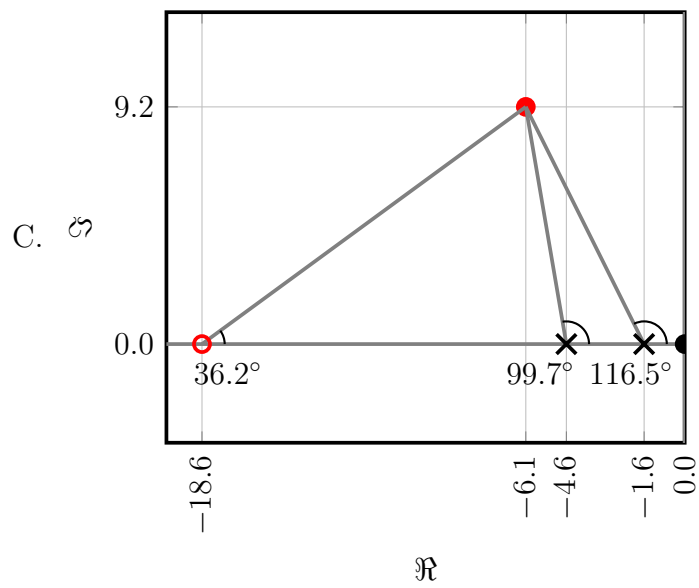
$$\sum \theta = 116.5^\circ + 99.7^\circ + 143.8^\circ =$$



$$\sum \theta = 116.5^\circ + 80.3^\circ + 36.2^\circ =$$

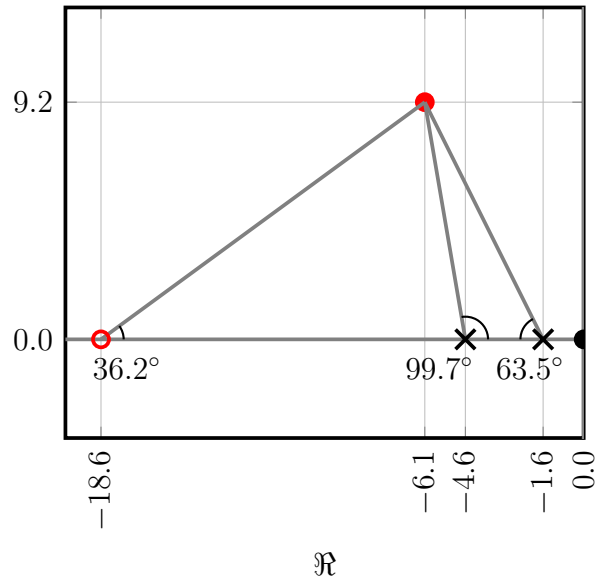


$$\sum \theta = 116.5^\circ + 99.7^\circ - 36.2^\circ =$$



$$\sum \theta = 63.5^\circ + 99.7^\circ + 36.2^\circ =$$

D.  $\Im$



$$\sum \theta = 116.5^\circ + 99.7^\circ + 36.2^\circ =$$

E.  $\Im$

