

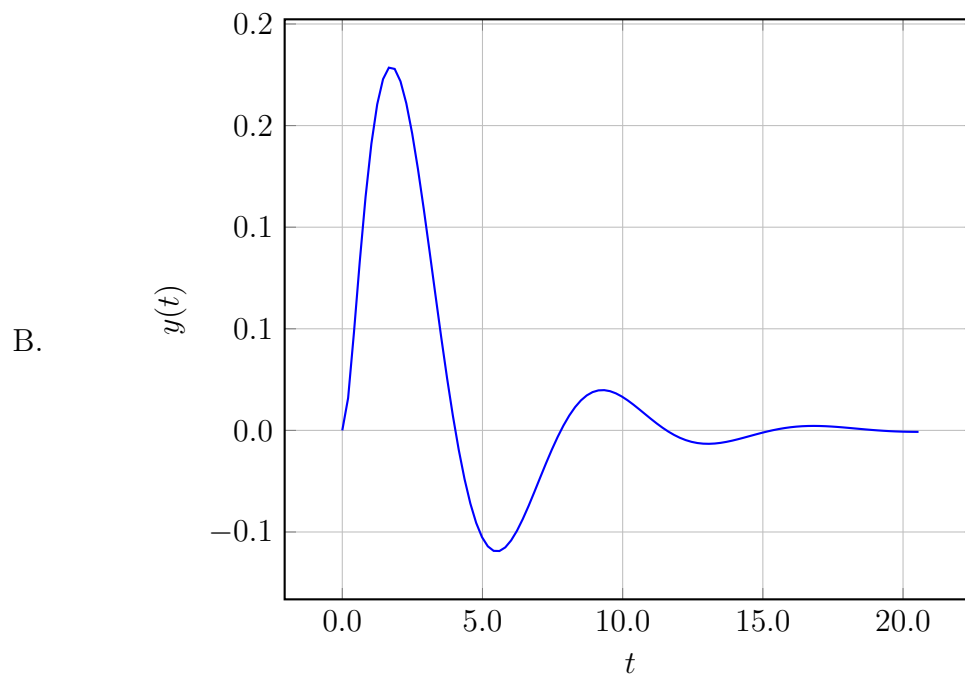
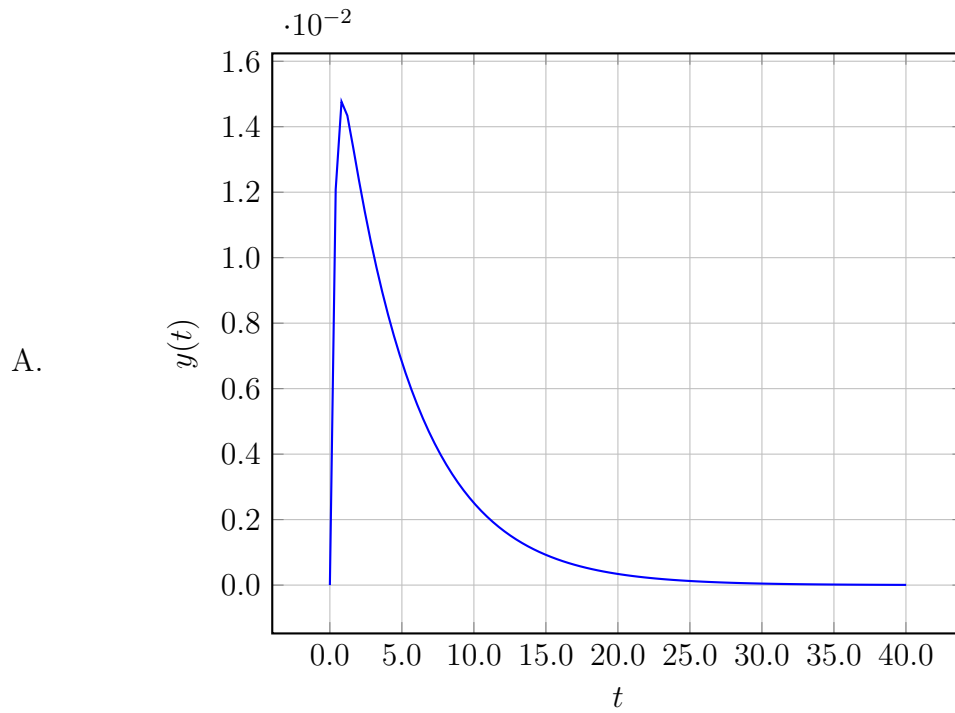
1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.38383s + 7.38383}$$

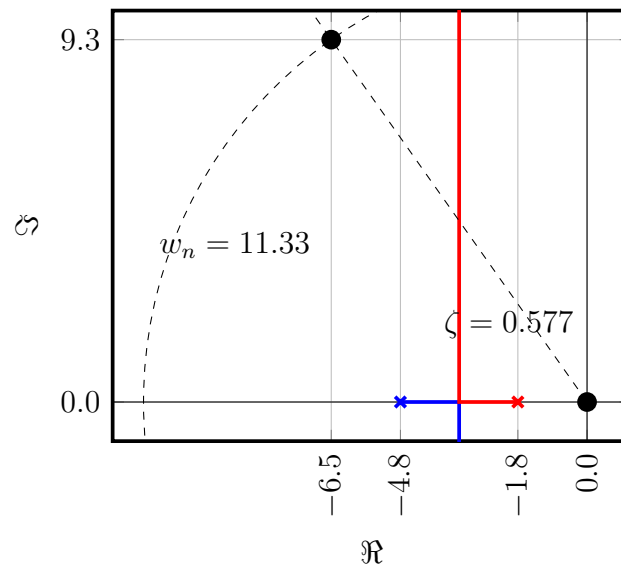
Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

- A.  $F(s) = -8.46466 + \frac{1.76767}{s}$
- B.  $F(s) = -3.26767 + \frac{0.88383}{s}$
- C.  $F(s) = -7.69698 + \frac{3.26767}{s}$
- D.  $F(s) = 2.80302 + \frac{1.76767}{s}$
- E.  $F(s) = 2.03534 + \frac{3.26767}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

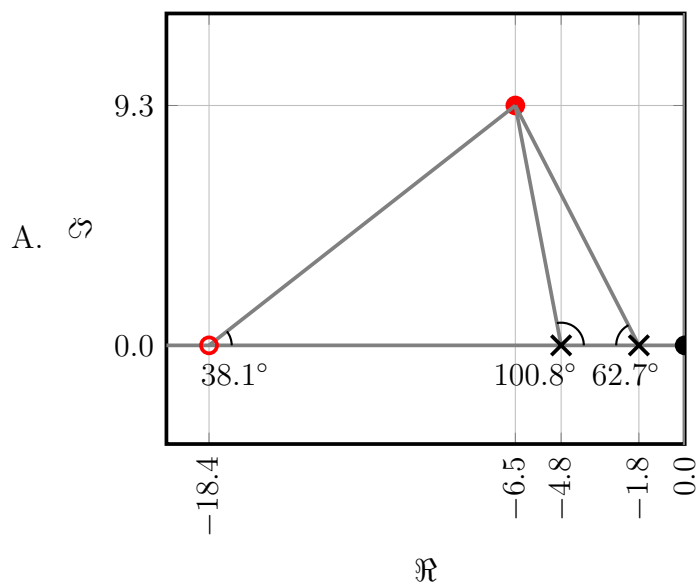


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

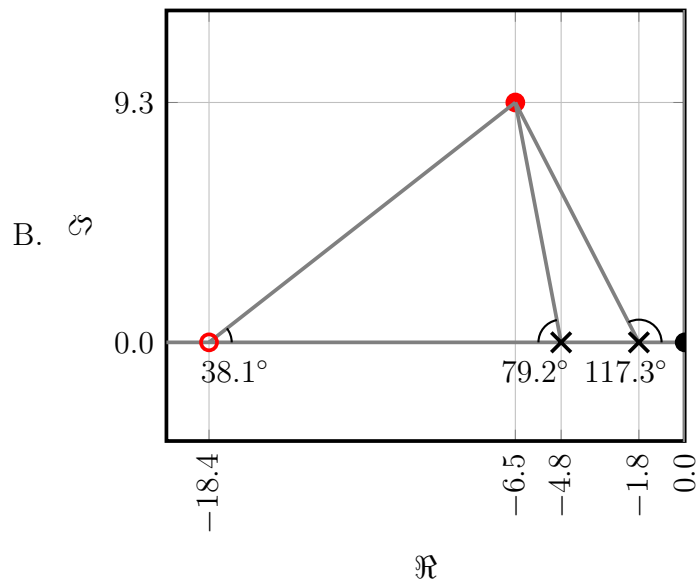


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

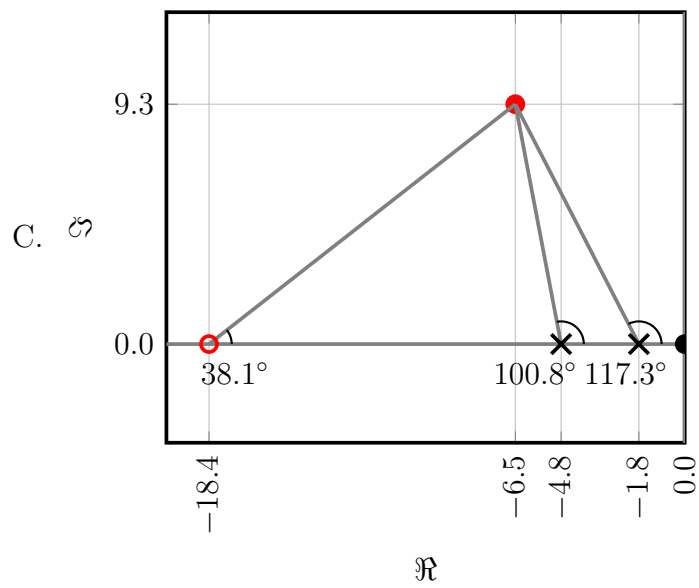
$$\sum \theta = 62.7^\circ + 100.8^\circ + 38.1^\circ =$$



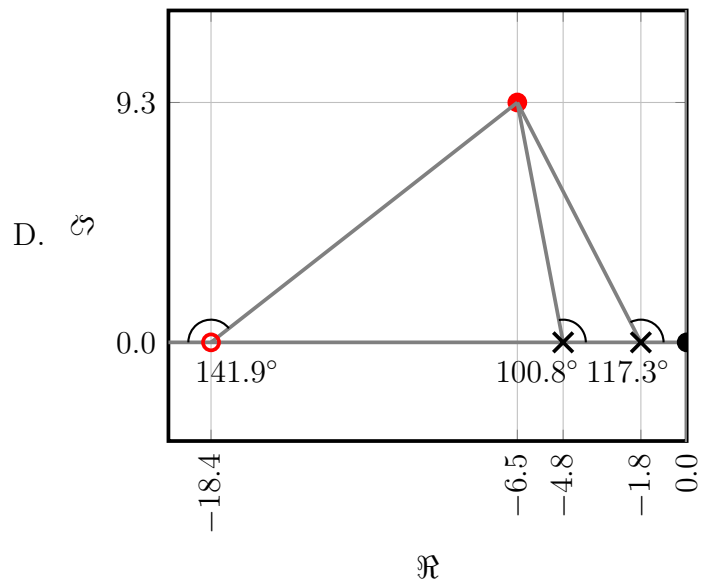
$$\sum \theta = 117.3^\circ + 79.2^\circ + 38.1^\circ =$$



$$\sum \theta = 117.3^\circ + 100.8^\circ - 38.1^\circ =$$



$$\sum \theta = 117.3^\circ + 100.8^\circ + 141.9^\circ =$$



$$\sum \theta = 117.3^\circ + 100.8^\circ + 38.1^\circ =$$

