

1. (35 points) An open-loop transfer function is given by,

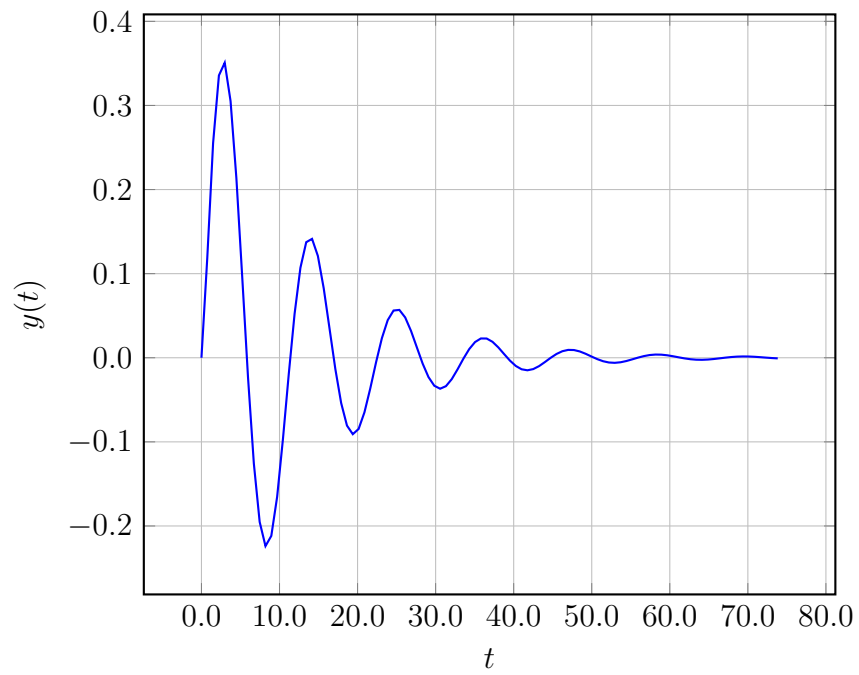
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.0707s + 7.0707}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

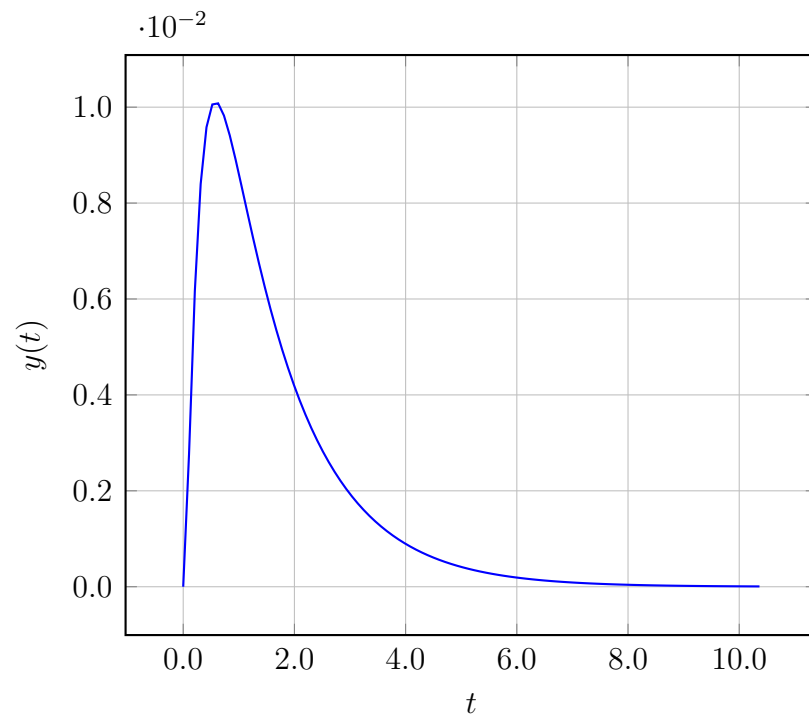
- A. $F(s) = -2.6414 + \frac{0.5707}{s}$
- B. $F(s) = -9.57576 + \frac{2.6414}{s}$
- C. $F(s) = -9.71718 + \frac{1.1414}{s}$
- D. $F(s) = 0.92424 + \frac{1.1414}{s}$
- E. $F(s) = 0.78282 + \frac{2.6414}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

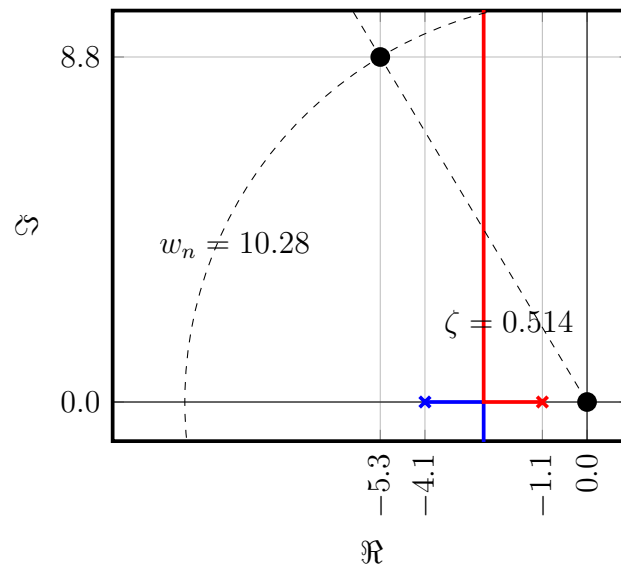
A.



B.

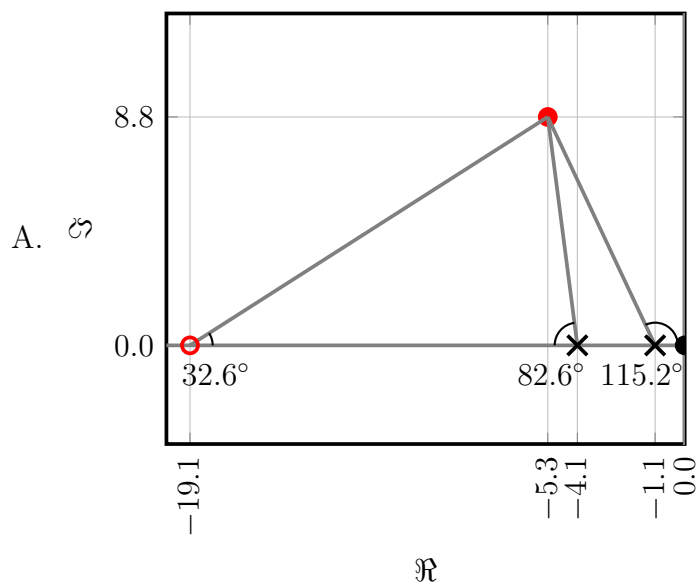


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

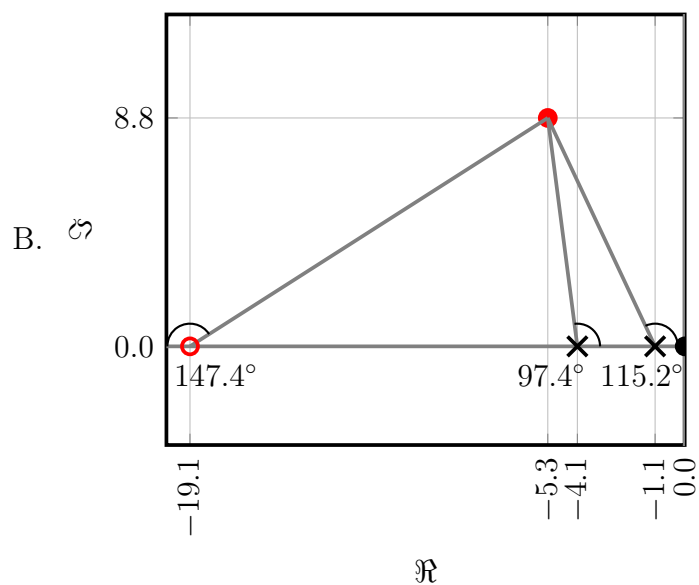


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

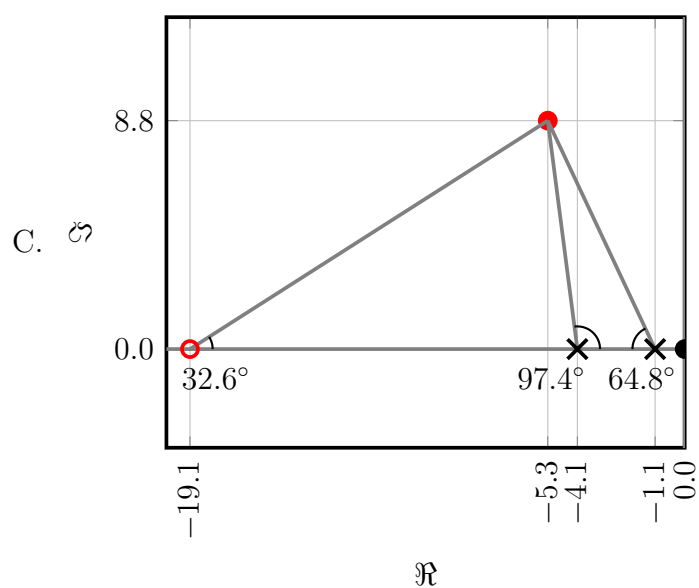
$$\sum \theta = 115.2^\circ + 82.6^\circ + 32.6^\circ = 230.3^\circ$$



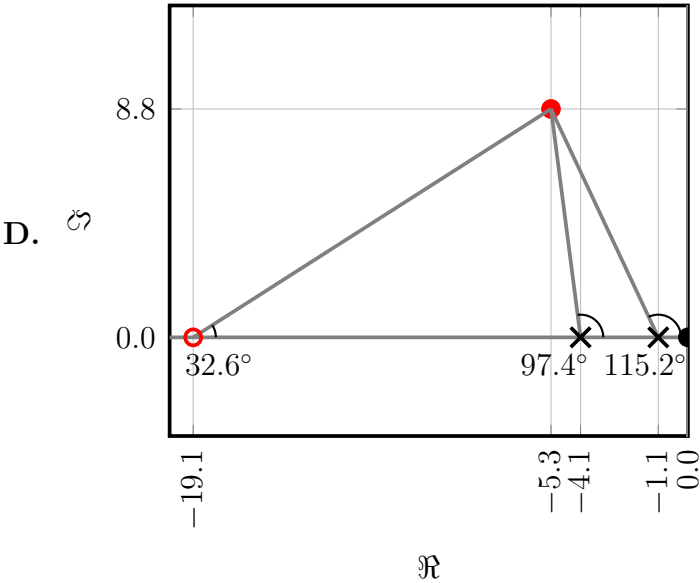
$$\sum \theta = 115.2^\circ + 97.4^\circ + 147.4^\circ = 360.0^\circ$$



$$\sum \theta = 64.8^\circ + 97.4^\circ + 32.6^\circ = 194.8^\circ$$



$$\sum \theta = 115.2^{\circ} + 97.4^{\circ} - 32.6^{\circ} = 180.0^{\circ}$$



Q	A
1	A
2	B
3	D