

1. (35 points) An open-loop transfer function is given by,

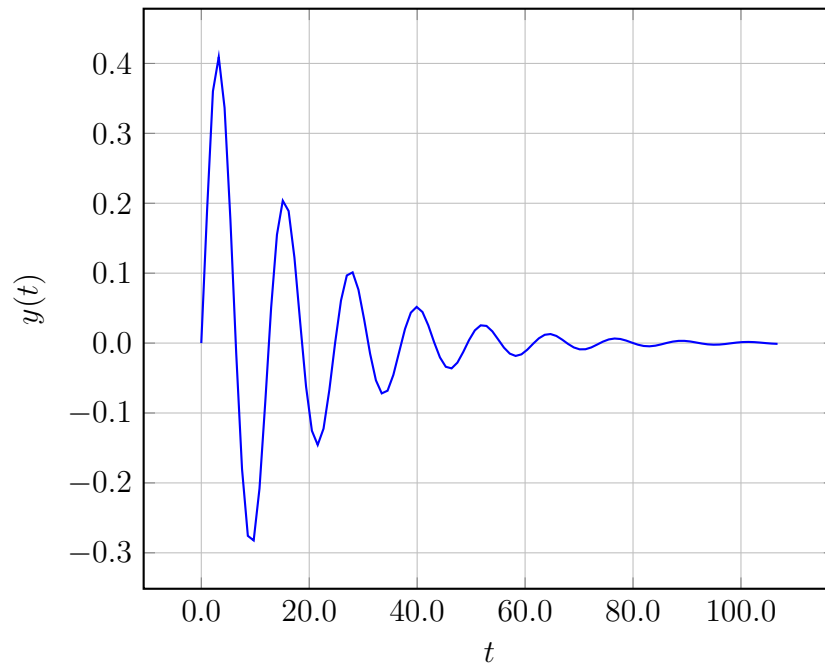
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.01514s + 7.01514}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

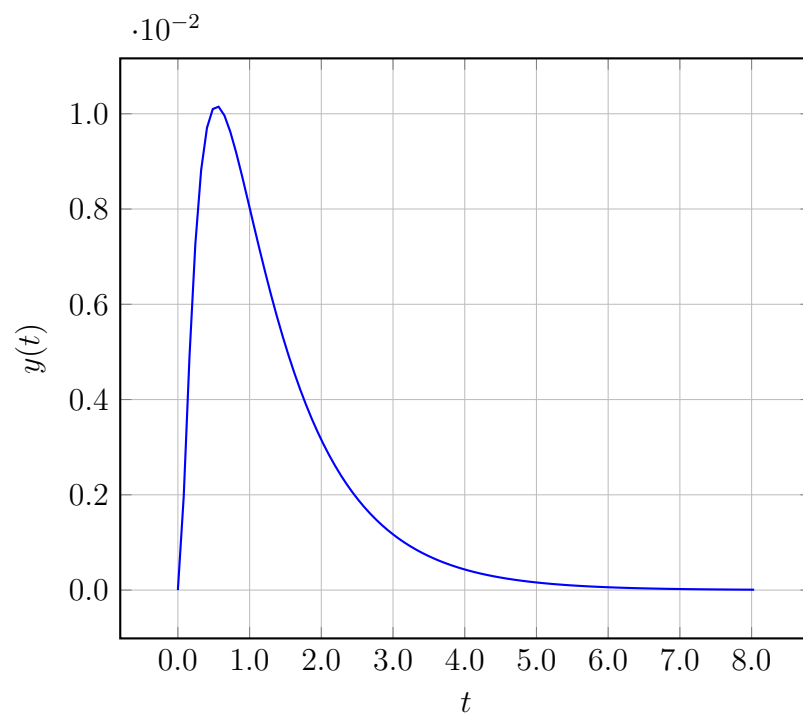
- A.  $F(s) = 0.5606 + \frac{2.53029}{s}$
- B.  $F(s) = -9.9091 + \frac{2.53029}{s}$
- C.  $F(s) = -2.53029 + \frac{0.51514}{s}$
- D.  $F(s) = -9.9394 + \frac{1.03029}{s}$
- E.  $F(s) = 0.5909 + \frac{1.03029}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

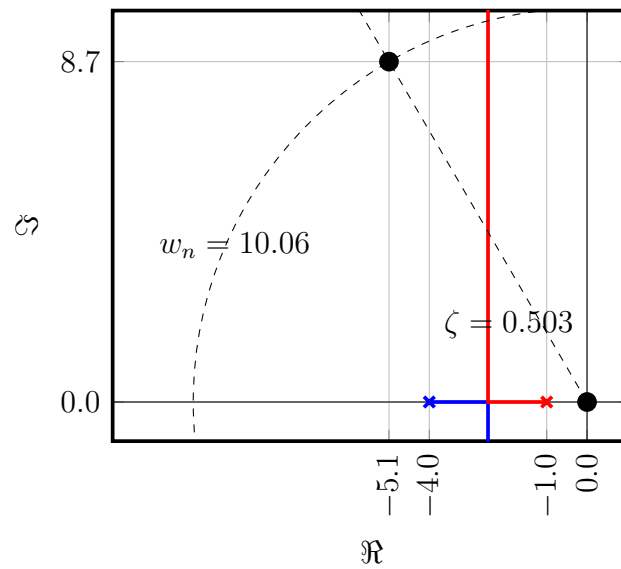
A.



B.

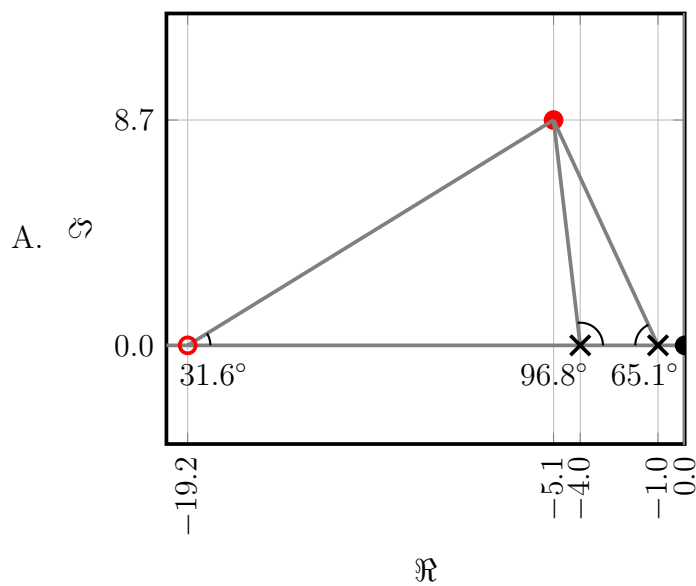


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

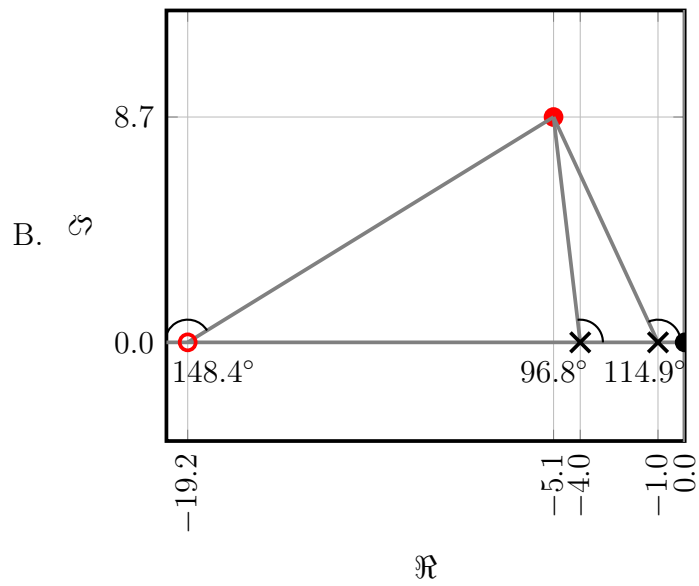


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

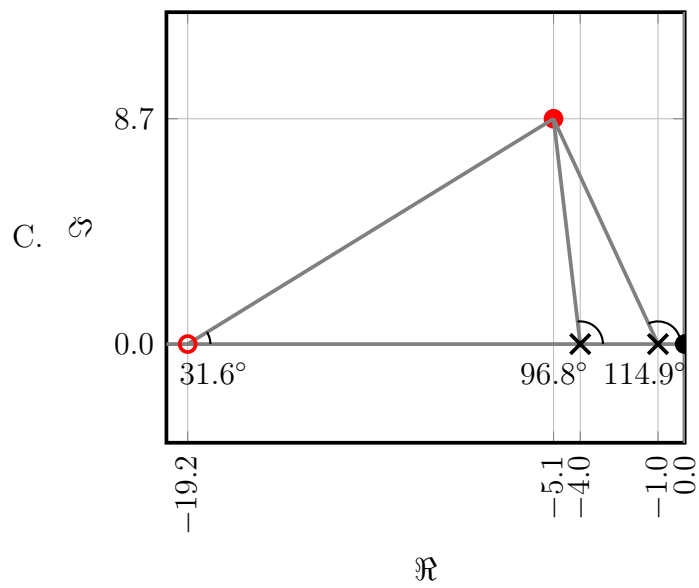
$$\sum \theta = 65.1^\circ + 96.8^\circ + 31.6^\circ =$$



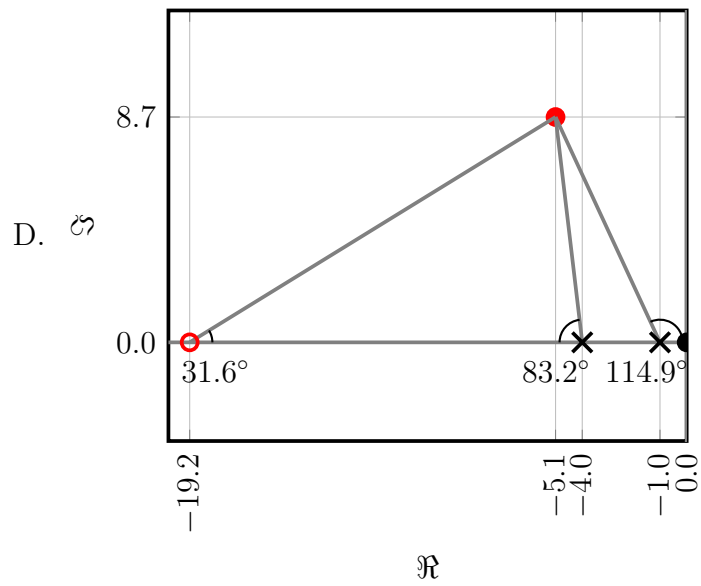
$$\sum \theta = 114.9^\circ + 96.8^\circ + 148.4^\circ =$$



$$\sum \theta = 114.9^\circ + 96.8^\circ + 31.6^\circ =$$



$$\sum \theta = 114.9^\circ + 83.2^\circ + 31.6^\circ =$$



$$\sum \theta = 114.9^\circ + 96.8^\circ - 31.6^\circ =$$

