

1. (35 points) An open-loop transfer function is given by,

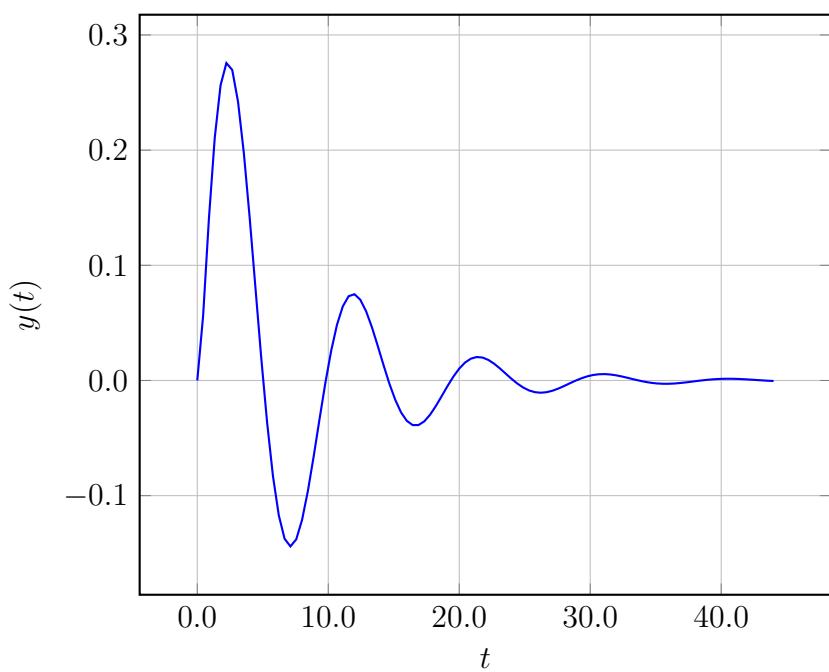
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.1717s + 7.1717}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

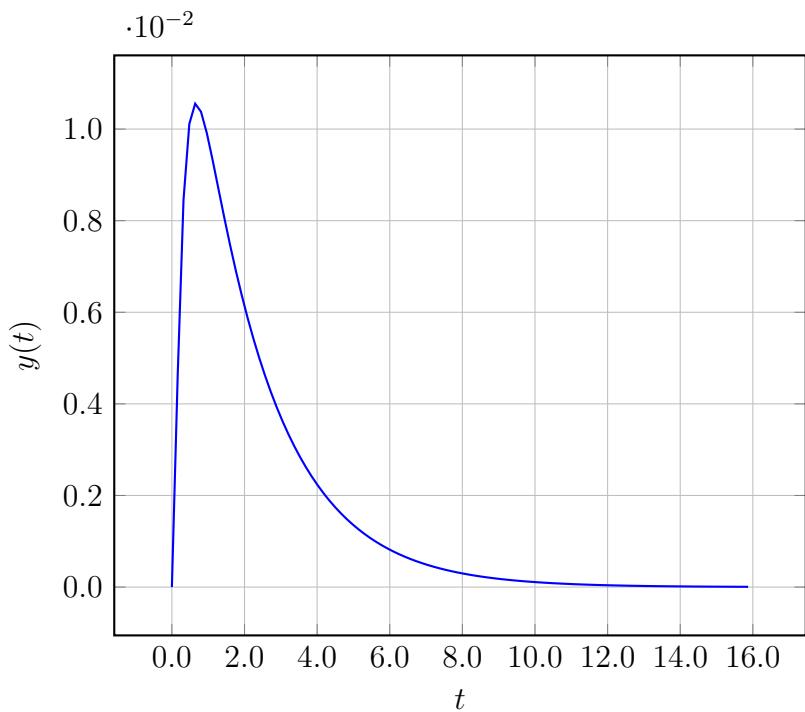
- A. $F(s) = -2.84343 + \frac{0.6717}{s}$
- B. $F(s) = 1.18686 + \frac{2.84343}{s}$
- C. $F(s) = -8.96971 + \frac{2.84343}{s}$
- D. $F(s) = 1.53029 + \frac{1.34343}{s}$
- E. $F(s) = -9.31314 + \frac{1.34343}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

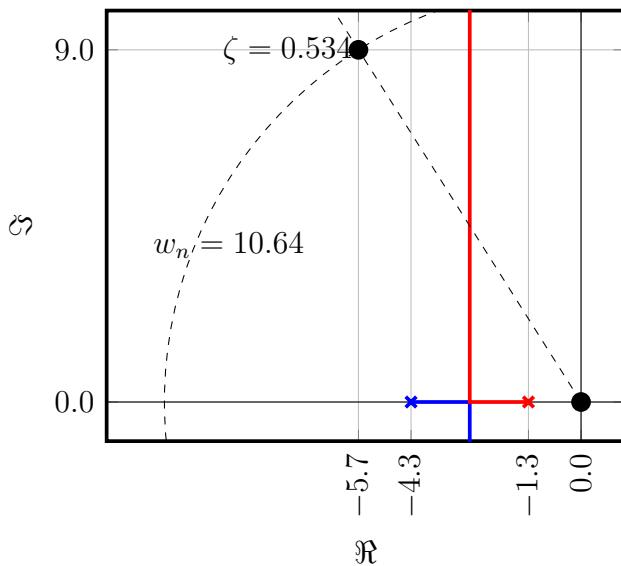
A.



B.

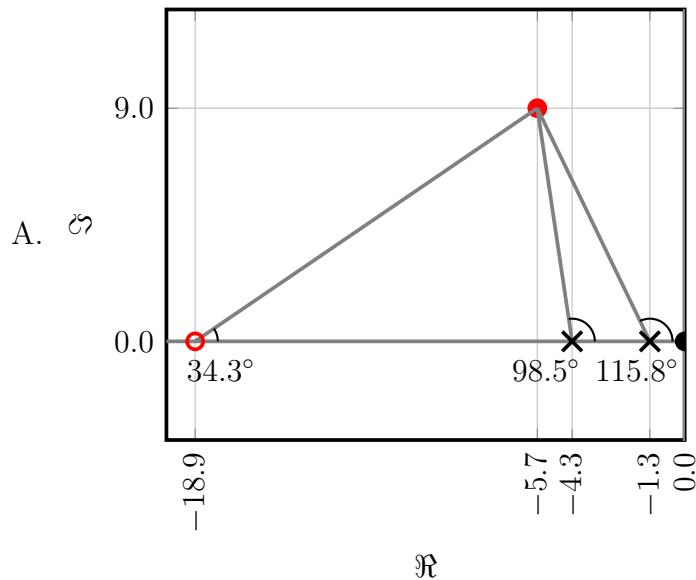


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

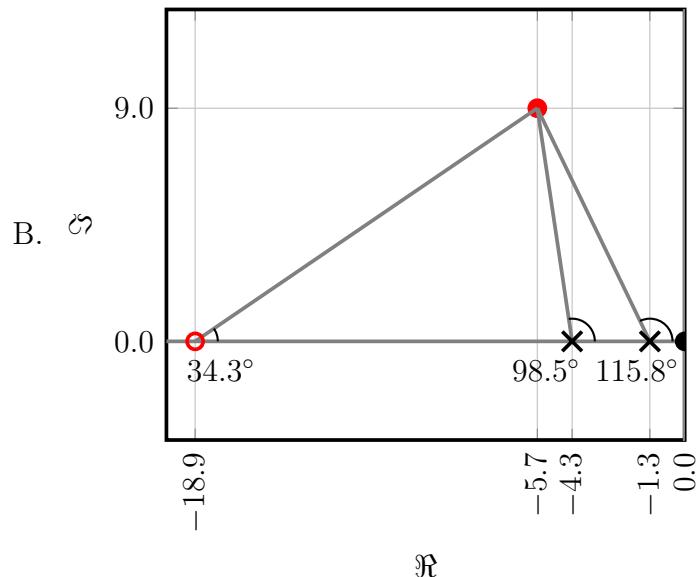


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

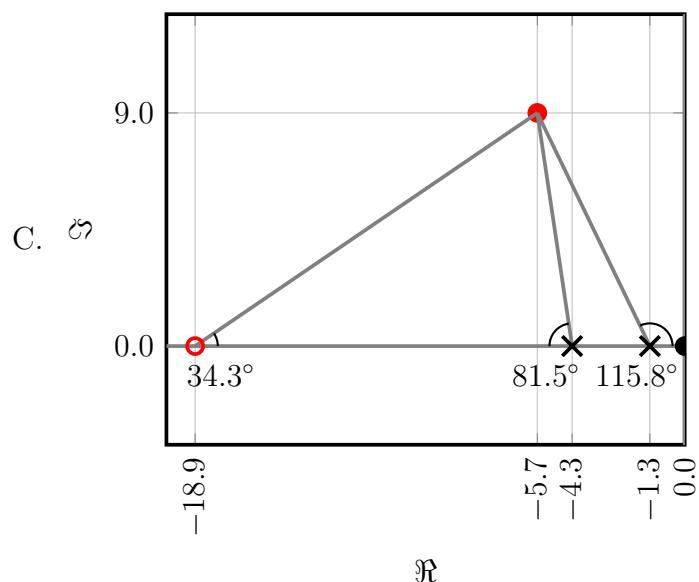
$$\sum \theta = 115.8^\circ + 98.5^\circ + 34.3^\circ =$$



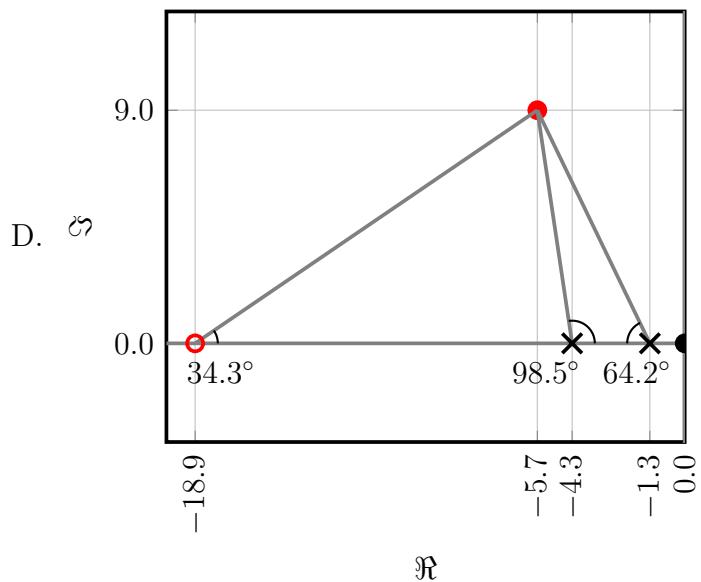
$$\sum \theta = 115.8^\circ + 98.5^\circ - 34.3^\circ =$$



$$\sum \theta = 115.8^\circ + 81.5^\circ + 34.3^\circ =$$



$$\sum \theta = 64.2^\circ + 98.5^\circ + 34.3^\circ =$$



$$\sum \theta = 115.8^\circ + 98.5^\circ + 145.7^\circ =$$

