1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.25757s + 7.25757}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

A. $F(s) = -8.96971 + \frac{1.51514}{s}$

B. $F(s) = 1.53029 + \frac{3.01514}{s}$

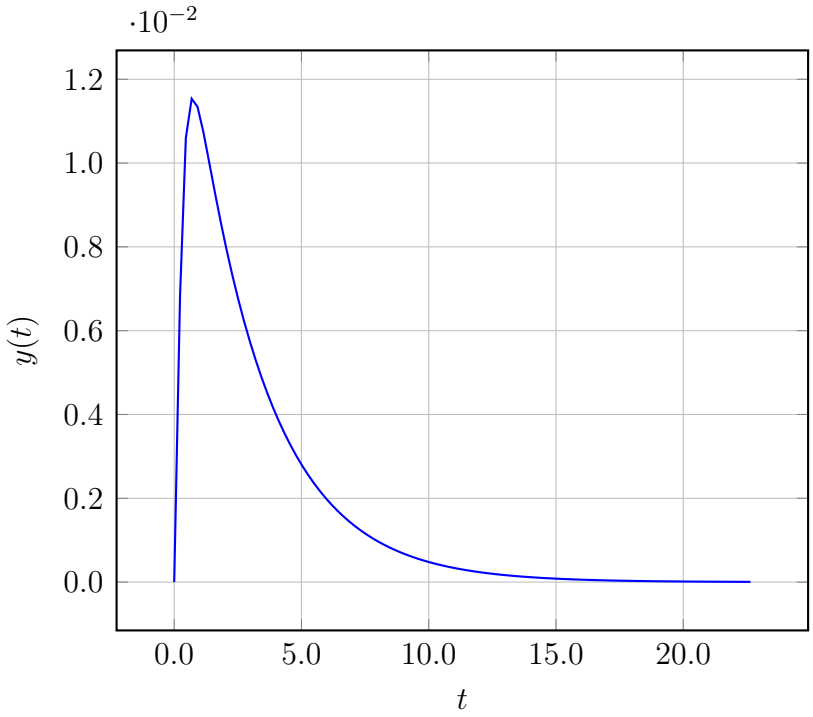
C. $F(s) = -3.01514 + \frac{0.75757}{s}$

D. $F(s) = -8.45456 + \frac{3.01514}{s}$

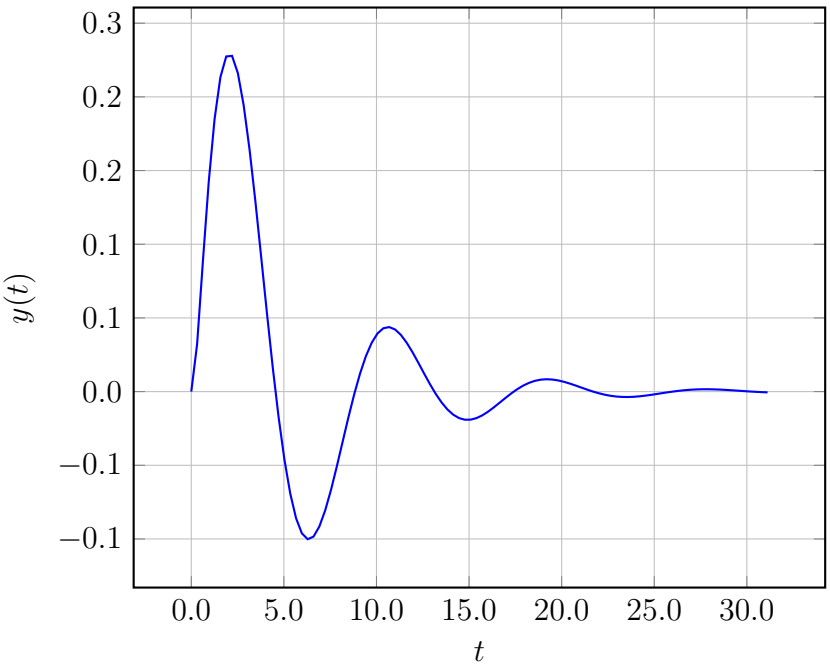
E. $F(s) = 2.04544 + \frac{1.51514}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

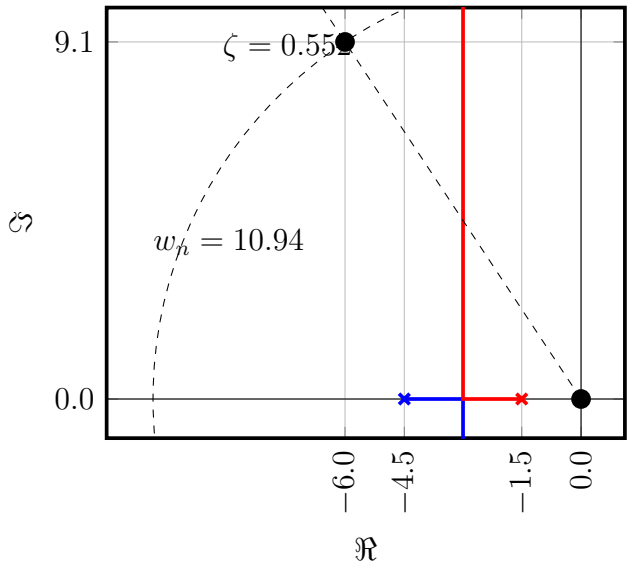
A.



B.



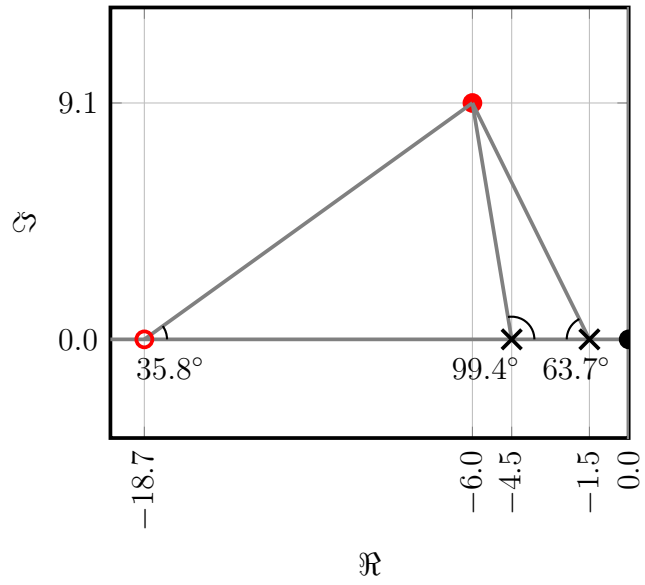
3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.



A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

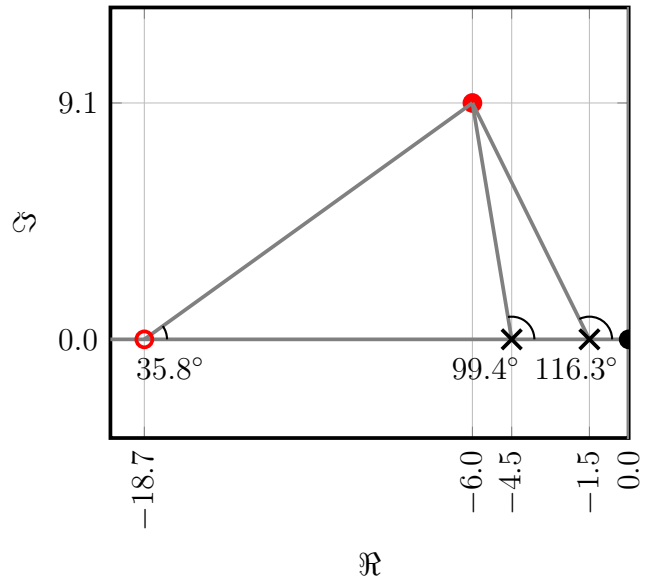
$$\sum \theta = 63.7^\circ + 99.4^\circ + 35.8^\circ = 198.9^\circ$$

A.



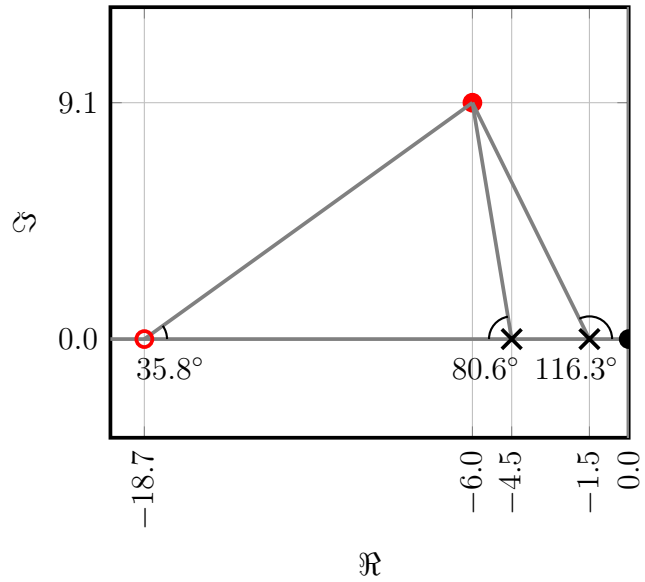
$$\sum \theta = 116.3^\circ + 99.4^\circ + 35.8^\circ = 251.5^\circ$$

B.



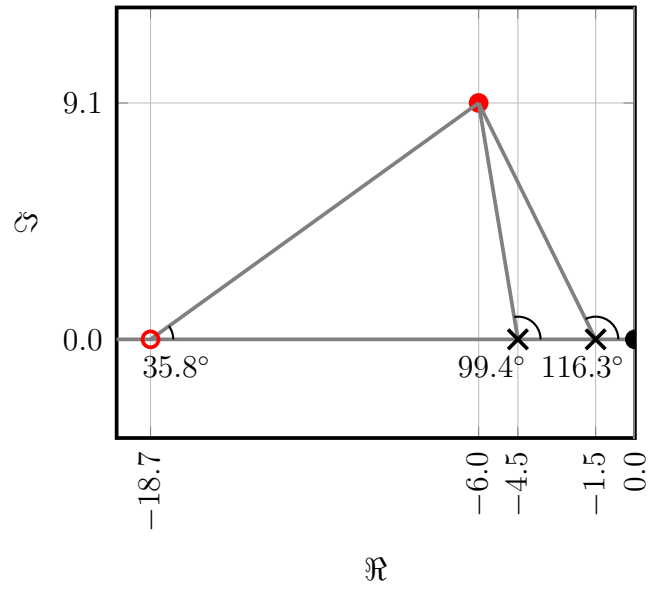
$$\sum \theta = 116.3^\circ + 80.6^\circ + 35.8^\circ = 232.7^\circ$$

C.



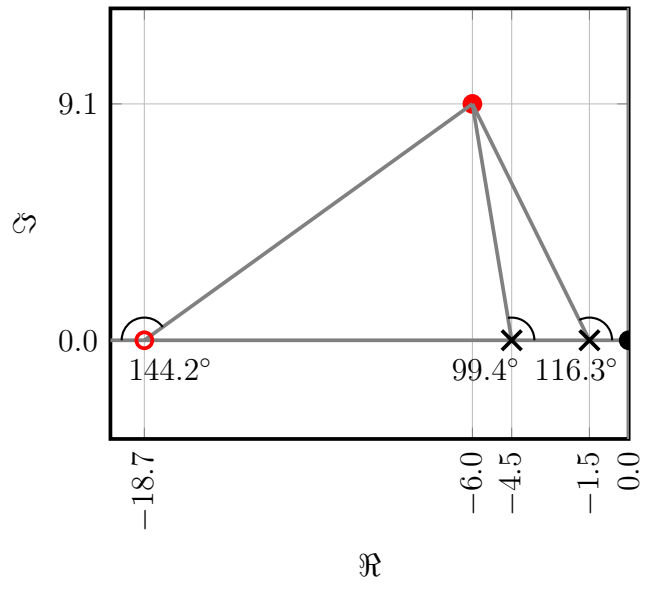
$$\sum \theta = 116.3^\circ + 99.4^\circ - 35.8^\circ = 180.0^\circ$$

D.



$$\sum \theta = 116.3^\circ + 99.4^\circ + 144.2^\circ = 360.0^\circ$$

E.



Q	A
1	C
2	A
3	D