

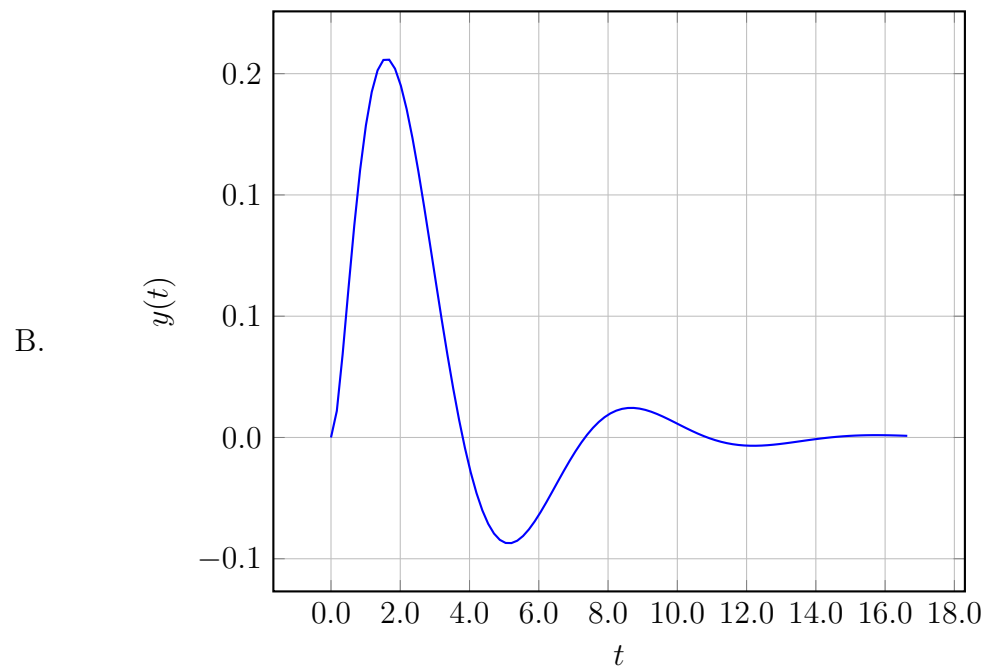
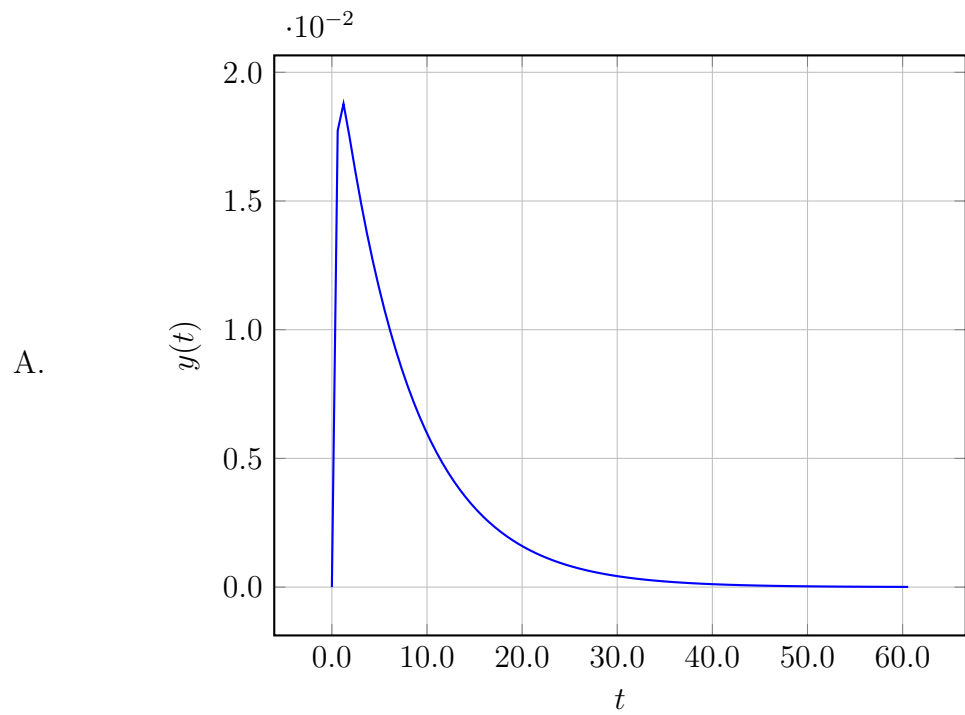
1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.4596s + 7.4596}$$

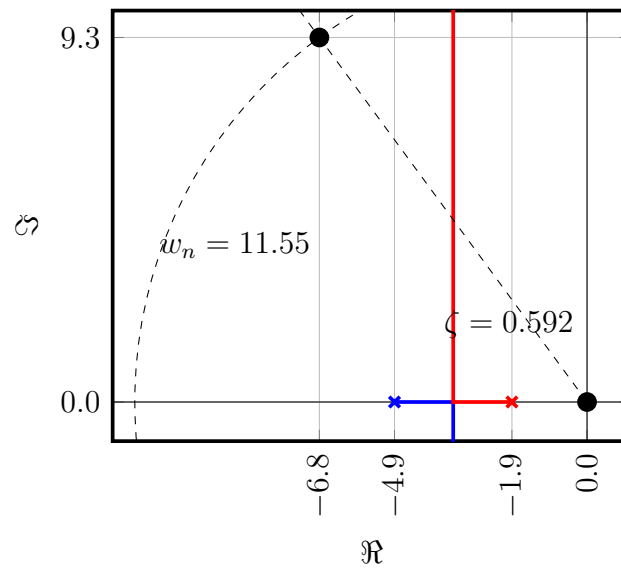
Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

- A.  $F(s) = -8.16162 + \frac{1.91919}{s}$
- B.  $F(s) = 3.25757 + \frac{1.91919}{s}$
- C.  $F(s) = -3.41919 + \frac{0.9596}{s}$
- D.  $F(s) = -7.24243 + \frac{3.41919}{s}$
- E.  $F(s) = 2.33838 + \frac{3.41919}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

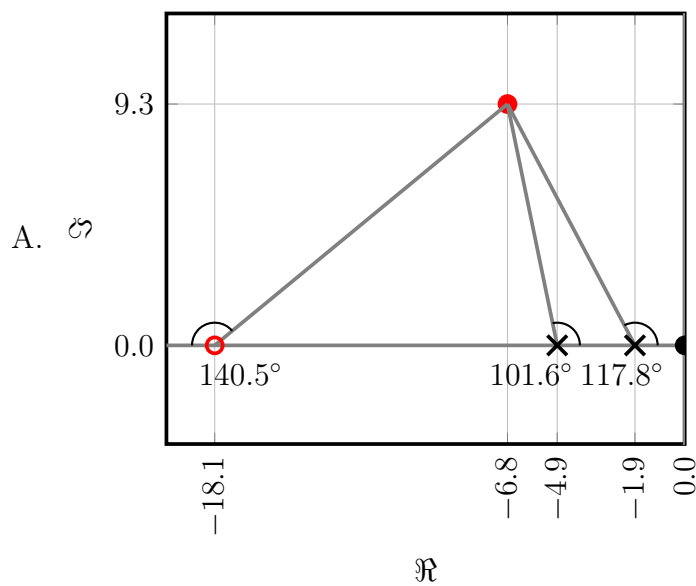


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

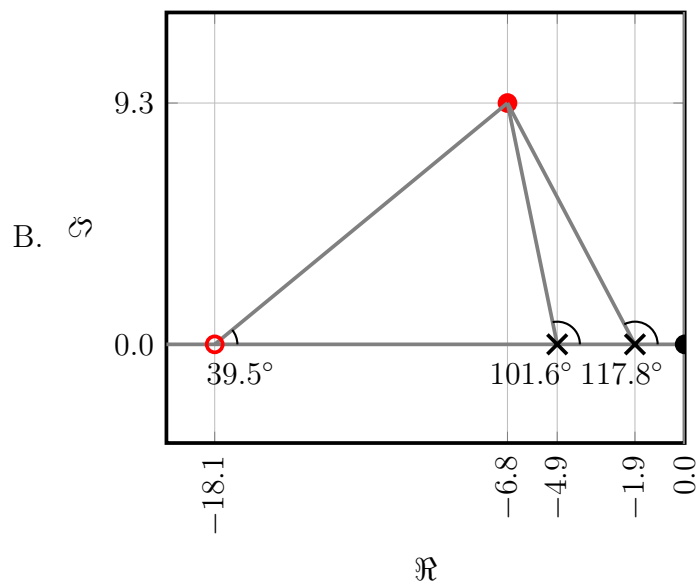


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

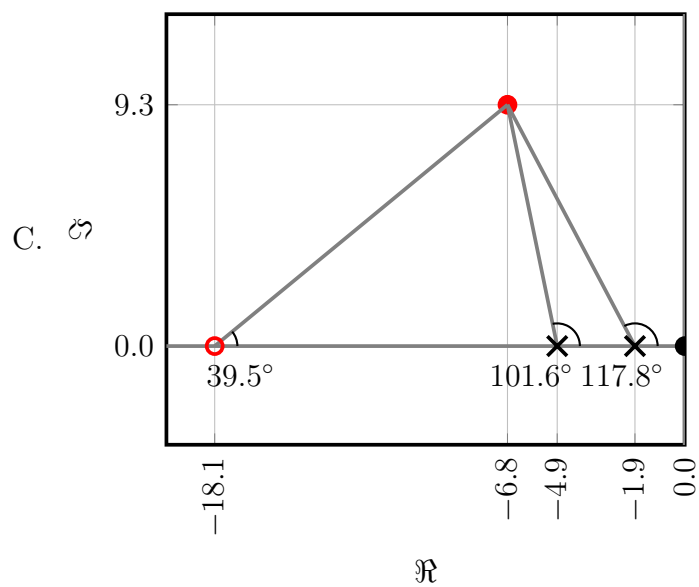
$$\sum \theta = 117.8^\circ + 101.6^\circ + 140.5^\circ =$$



$$\sum \theta = 117.8^\circ + 101.6^\circ - 39.5^\circ =$$

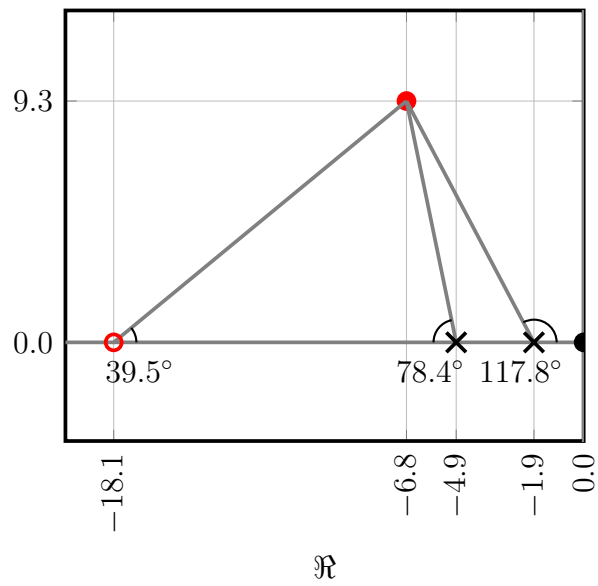


$$\sum \theta = 117.8^\circ + 101.6^\circ + 39.5^\circ =$$



$$\sum \theta = 117.8^\circ + 78.4^\circ + 39.5^\circ =$$

D.  $\Im$



$$\sum \theta = 62.2^\circ + 101.6^\circ + 39.5^\circ =$$

E.  $\Im$

