

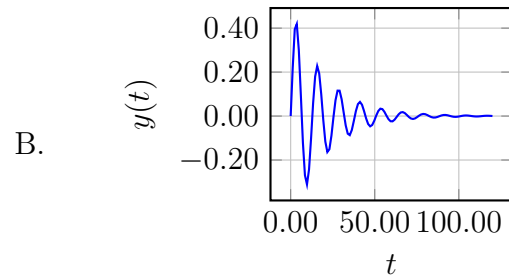
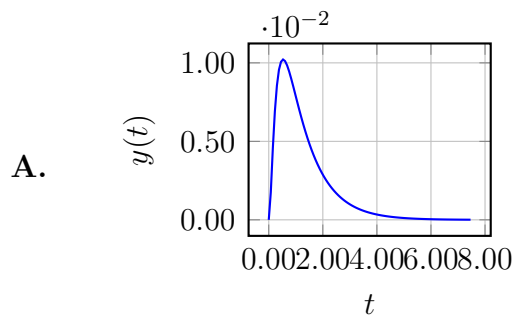
1. (35 points) An open-loop transfer function is given as,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.0s + 7.0}$$

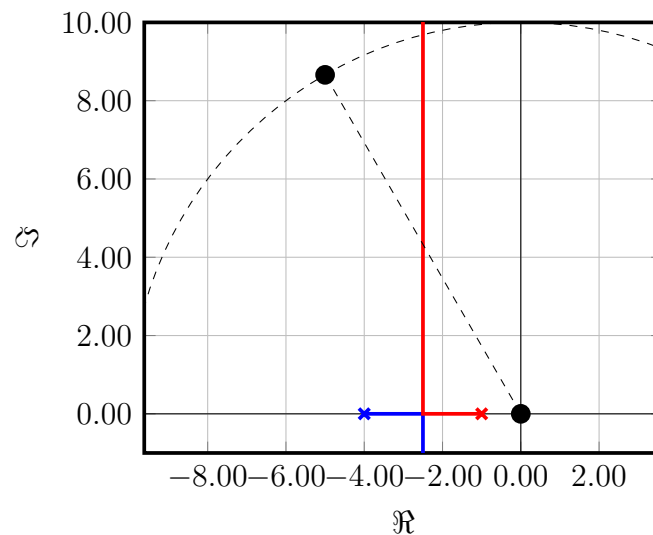
which of the following PI-controllers stabilizes the system in a closed-loop unit feedback structure?

- A. $F(s) = 0.5 + \frac{1.0}{s}$
- B. $F(s) = -10.0 + \frac{1.0}{s}$
- C. $F(s) = -10.0 + \frac{2.5}{s}$
- D. $F(s) = 0.5 + \frac{2.5}{s}$
- E. $F(s) = -2.5 + \frac{0.5}{s}$

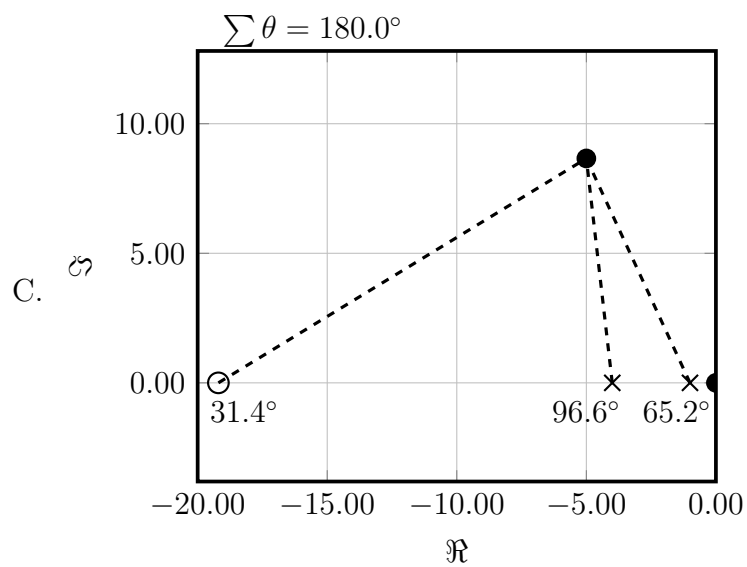
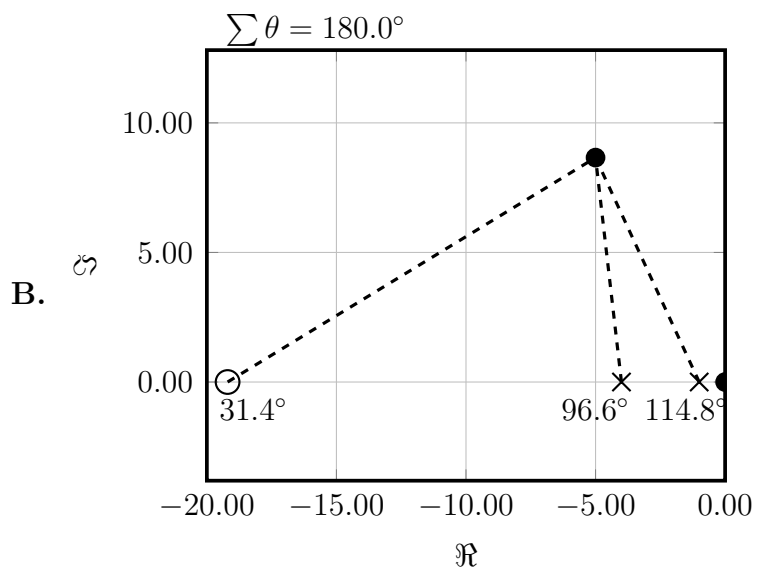
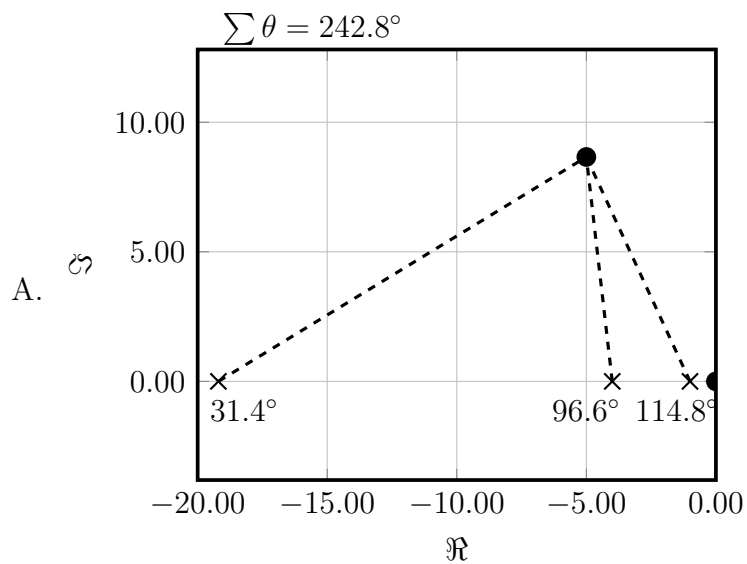
2. (35 points) Which of the following does not overshoot?

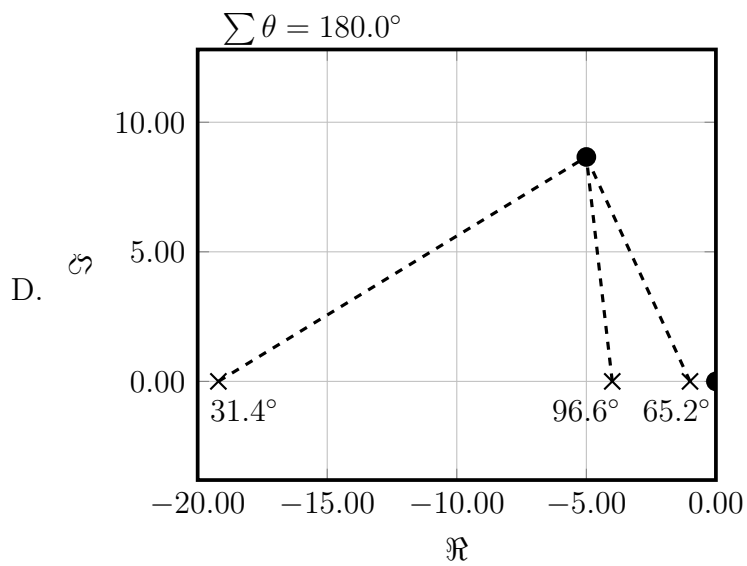


3. (30 points) Time-domain criteria is give as settling time $t_s = 1\text{ s}$ and overshoot $os = 10\%$. The root-locus plot for the P-controller design is depicted below.



Upgrading the controller to a PD-type controller which of the following angle conditions need to be used?





Q	A
1	E
2	A
3	B