

1. (35 points) An open-loop transfer function is given by,

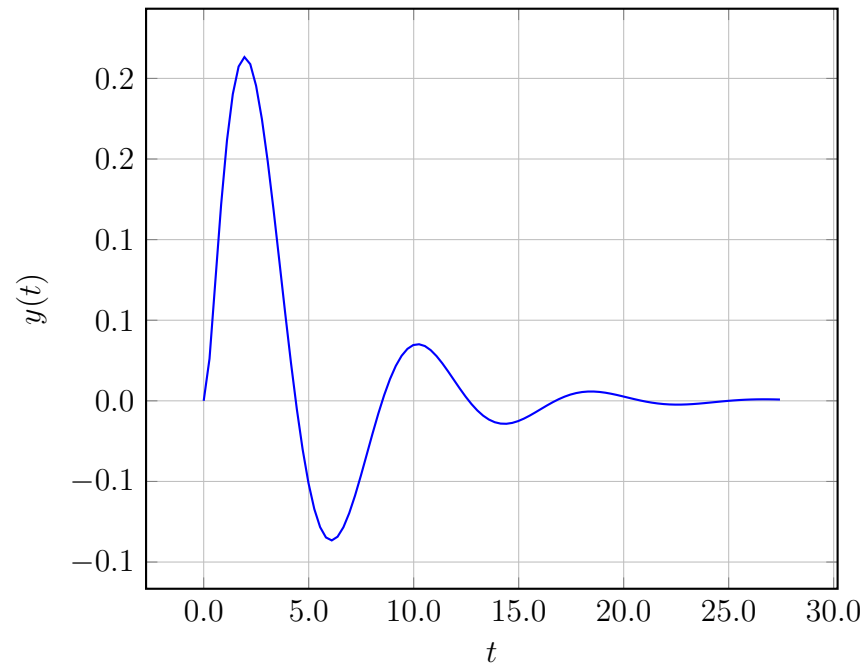
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.29292s + 7.29292}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

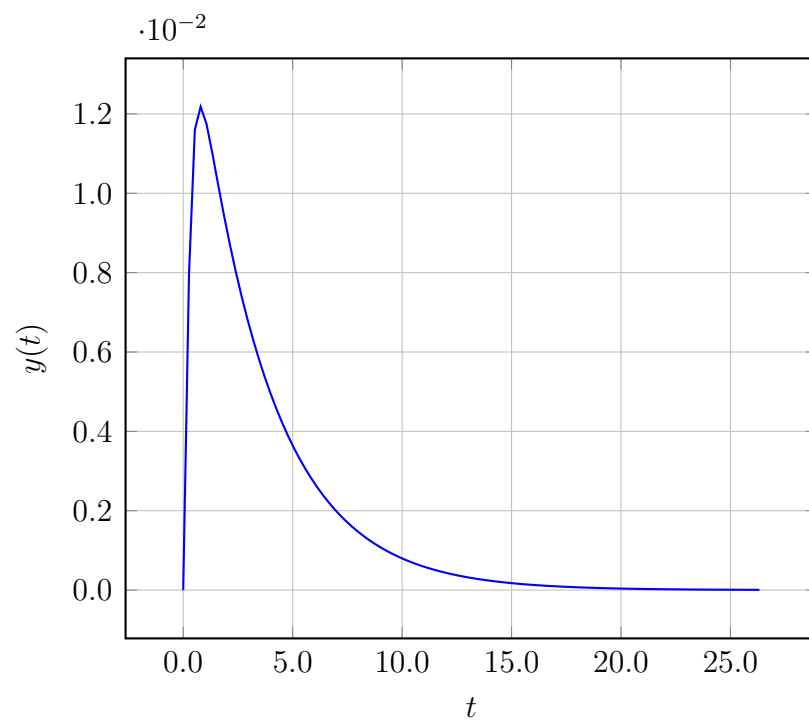
- A. $F(s) = 1.6717 + \frac{3.08585}{s}$
- B. $F(s) = -8.8283 + \frac{1.58585}{s}$
- C. $F(s) = -8.24243 + \frac{3.08585}{s}$
- D. $F(s) = -3.08585 + \frac{0.79292}{s}$**
- E. $F(s) = 2.25757 + \frac{1.58585}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

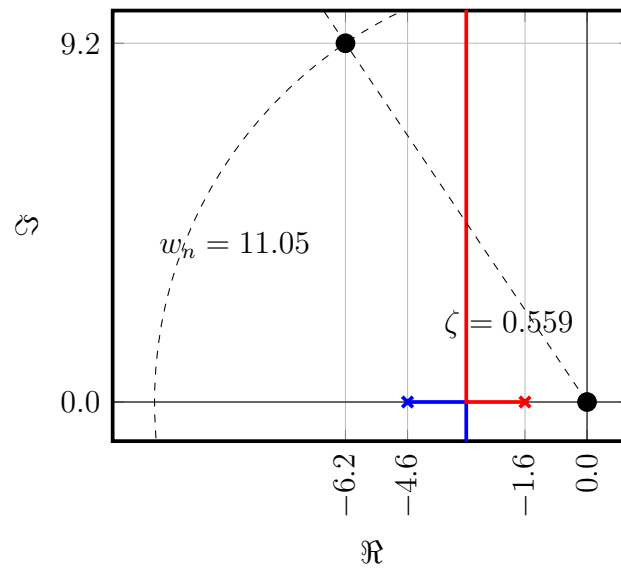
A.



B.

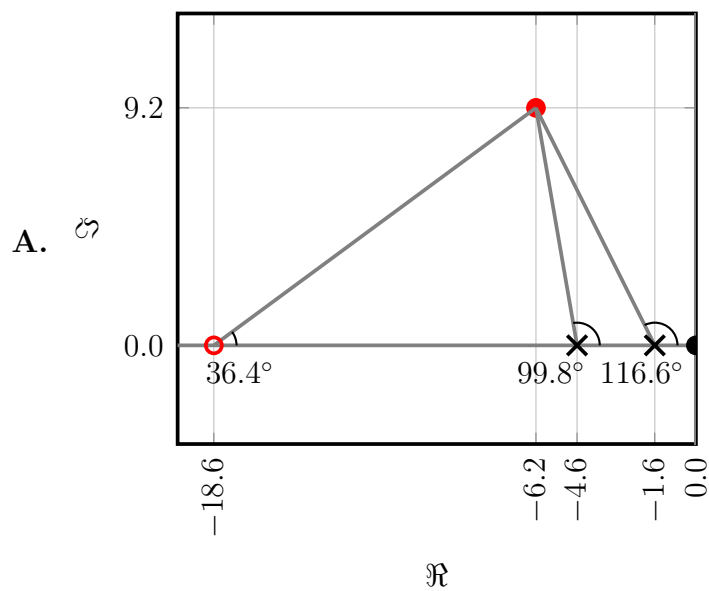


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

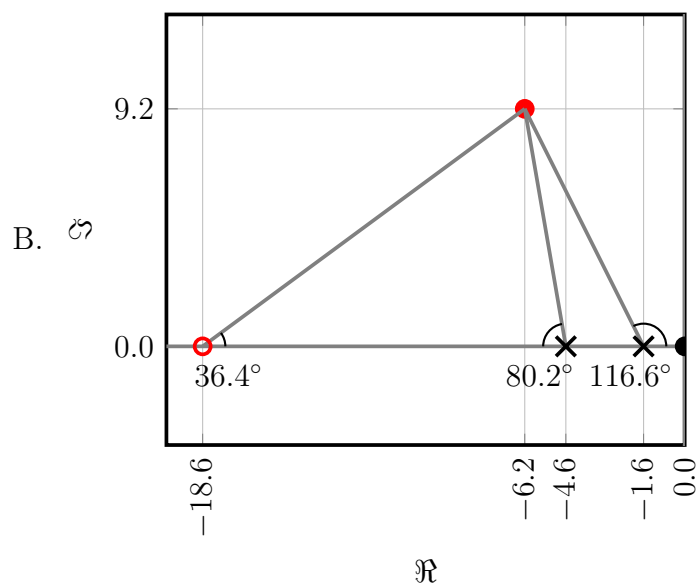


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

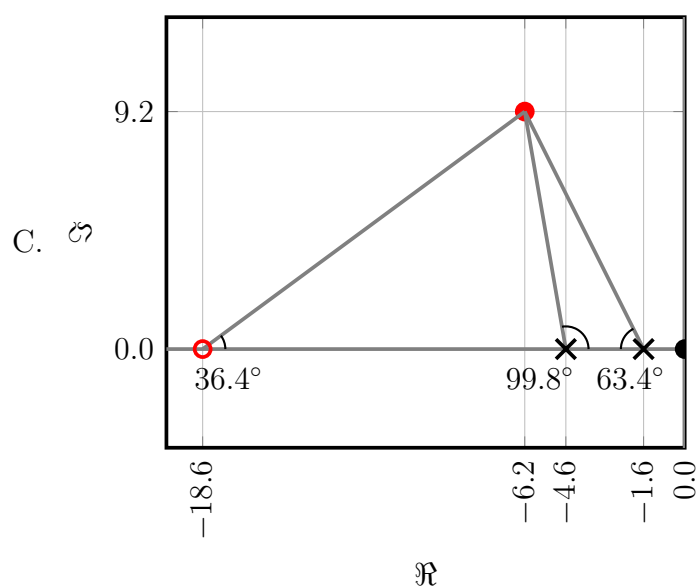
$$\sum \theta = 116.6^\circ + 99.8^\circ - 36.4^\circ = 180.0^\circ$$



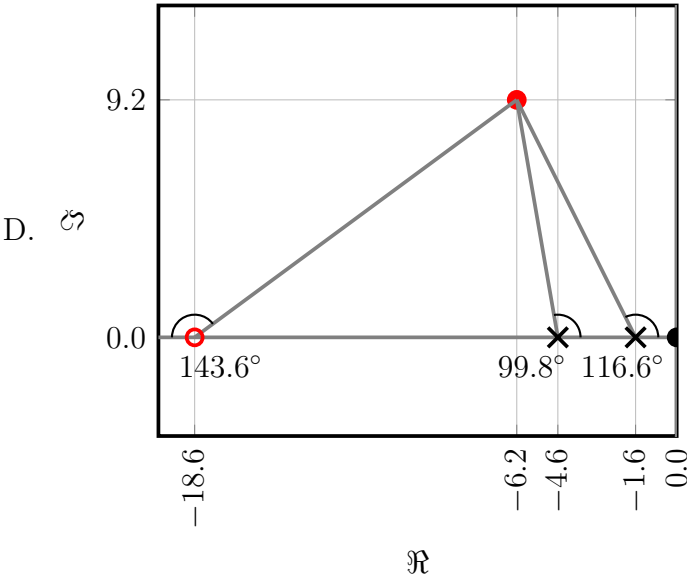
$$\sum \theta = 116.6^\circ + 80.2^\circ + 36.4^\circ = 233.2^\circ$$



$$\sum \theta = 63.4^\circ + 99.8^\circ + 36.4^\circ = 199.6^\circ$$



$$\sum \theta = 116.6^{\circ} + 99.8^{\circ} + 143.6^{\circ} = 360.0^{\circ}$$



Q	A
1	D
2	B
3	A