

1. (35 points) An open-loop transfer function is given by,

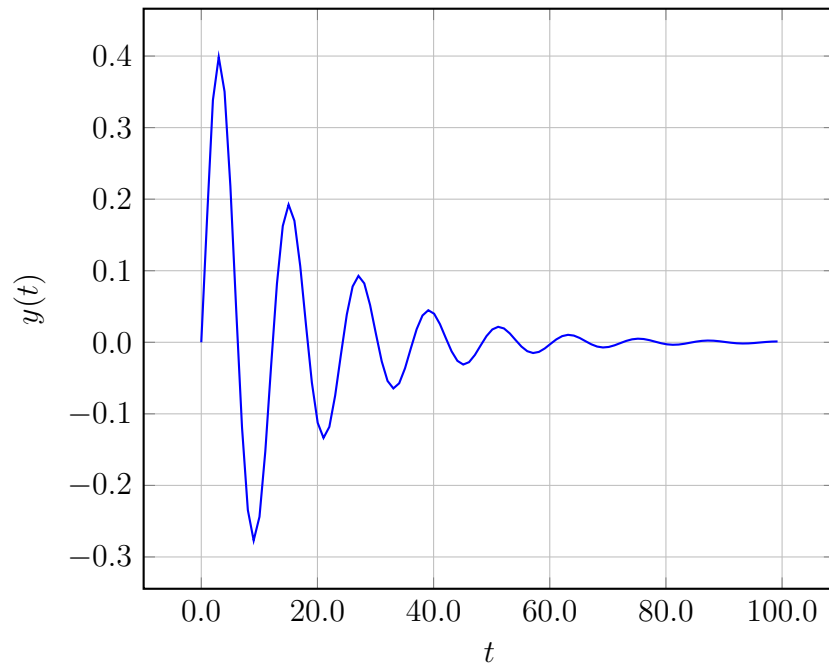
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.02524s + 7.02524}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

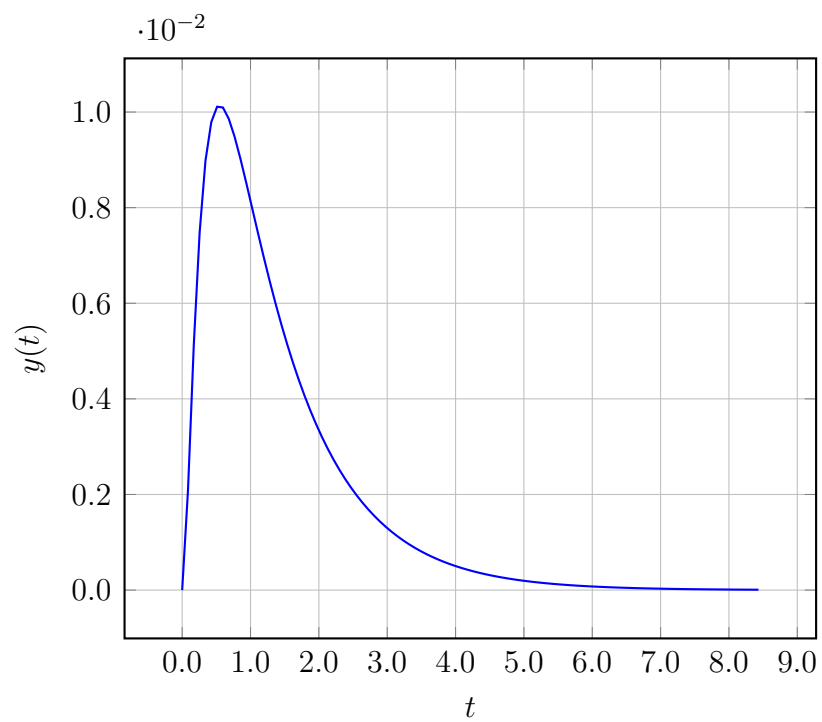
- A.  $F(s) = 0.6515 + \frac{1.05049}{s}$
- B.  $F(s) = -9.899 + \frac{1.05049}{s}$
- C.  $F(s) = -2.55049 + \frac{0.52524}{s}$
- D.  $F(s) = -9.8485 + \frac{2.55049}{s}$
- E.  $F(s) = 0.601 + \frac{2.55049}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

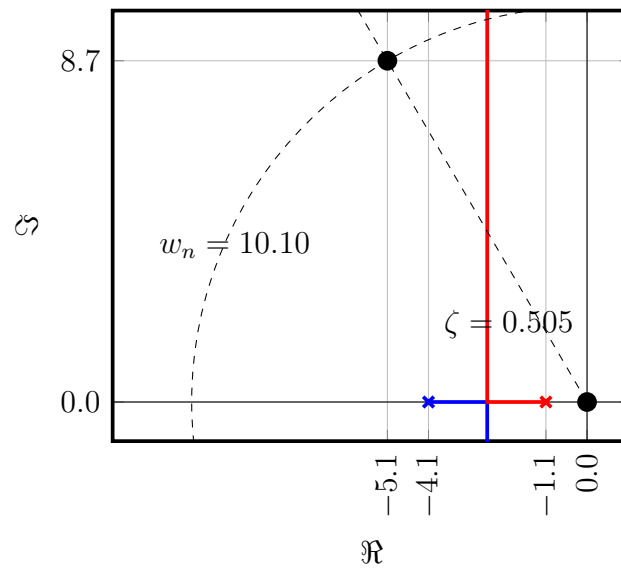
A.



B.

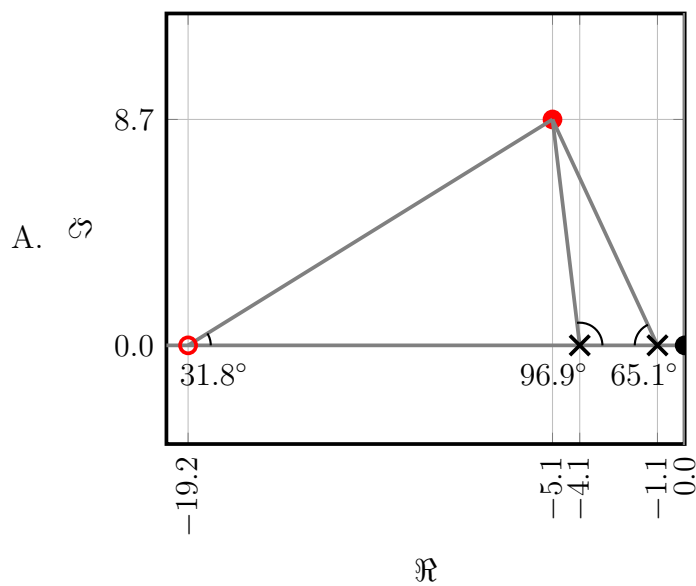


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

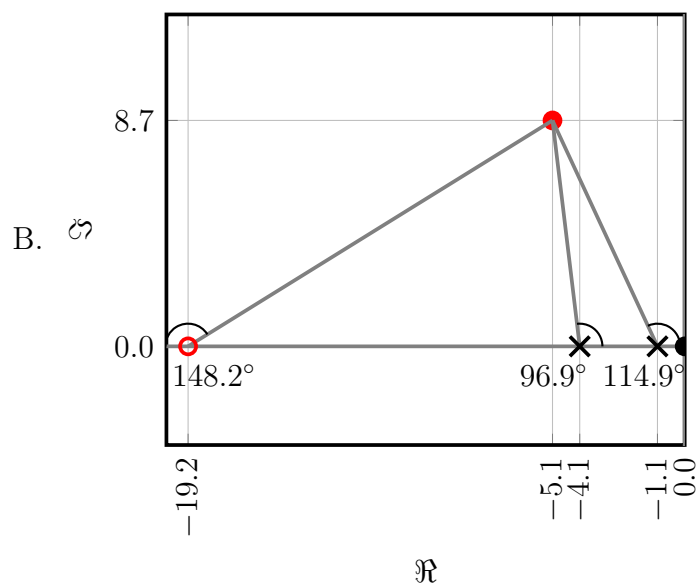


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

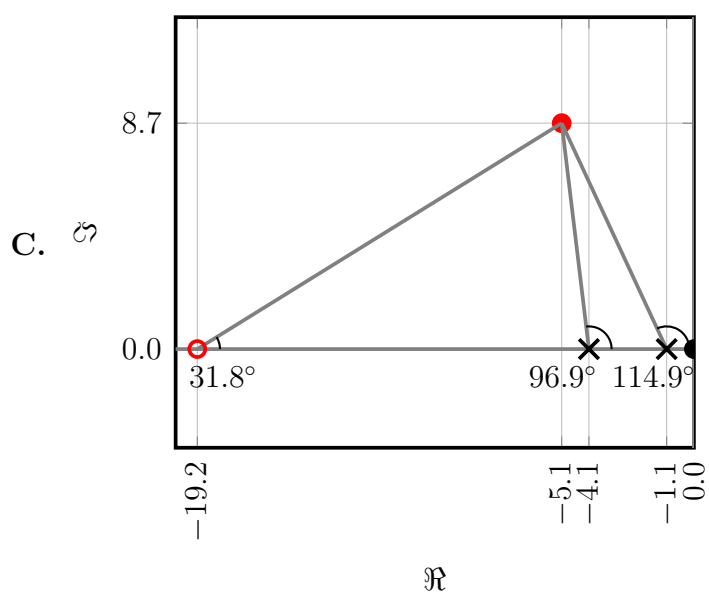
$$\sum \theta = 65.1^\circ + 96.9^\circ + 31.8^\circ = 193.7^\circ$$



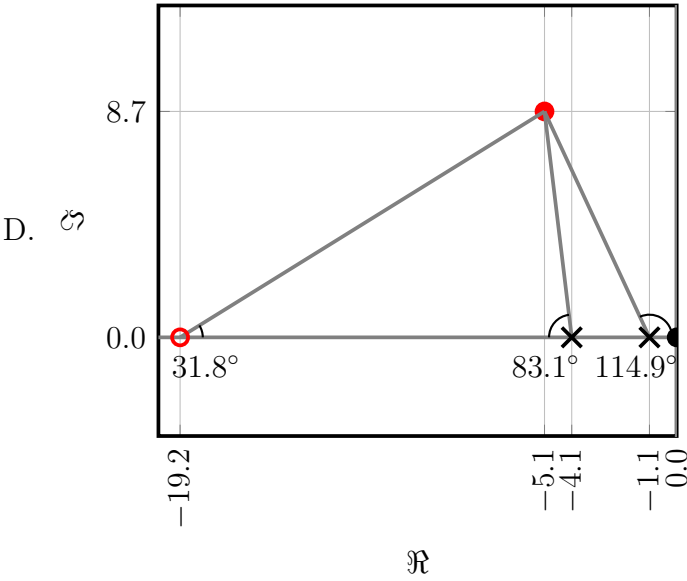
$$\sum \theta = 114.9^\circ + 96.9^\circ + 148.2^\circ = 360.0^\circ$$



$$\sum \theta = 114.9^\circ + 96.9^\circ - 31.8^\circ = 180.0^\circ$$



$$\sum \theta = 114.9^{\circ} + 83.1^{\circ} + 31.8^{\circ} = 229.8^{\circ}$$



Q	A
1	C
2	B
3	C