

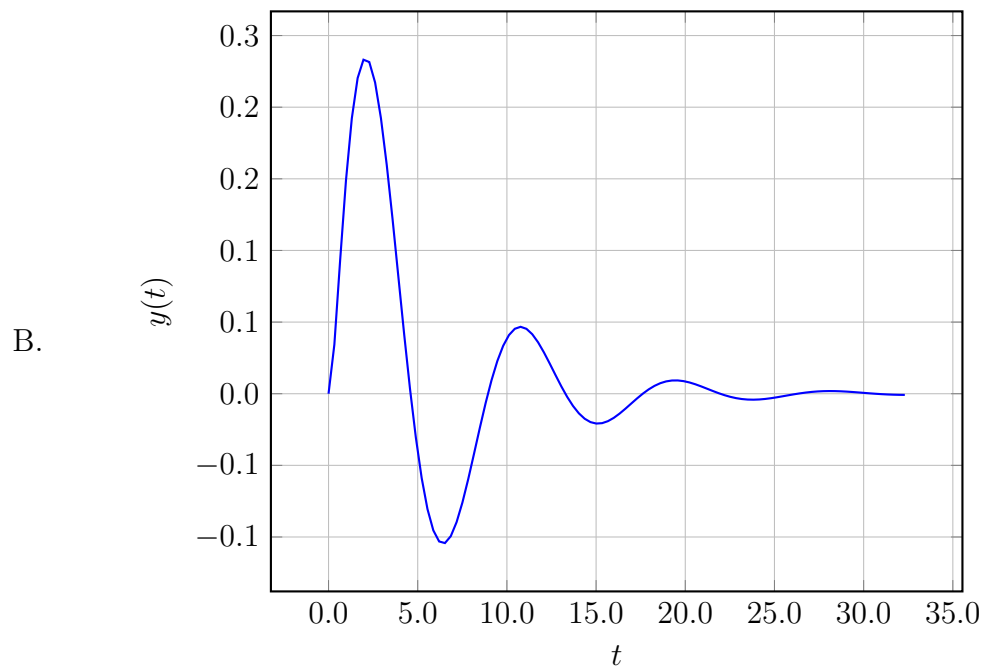
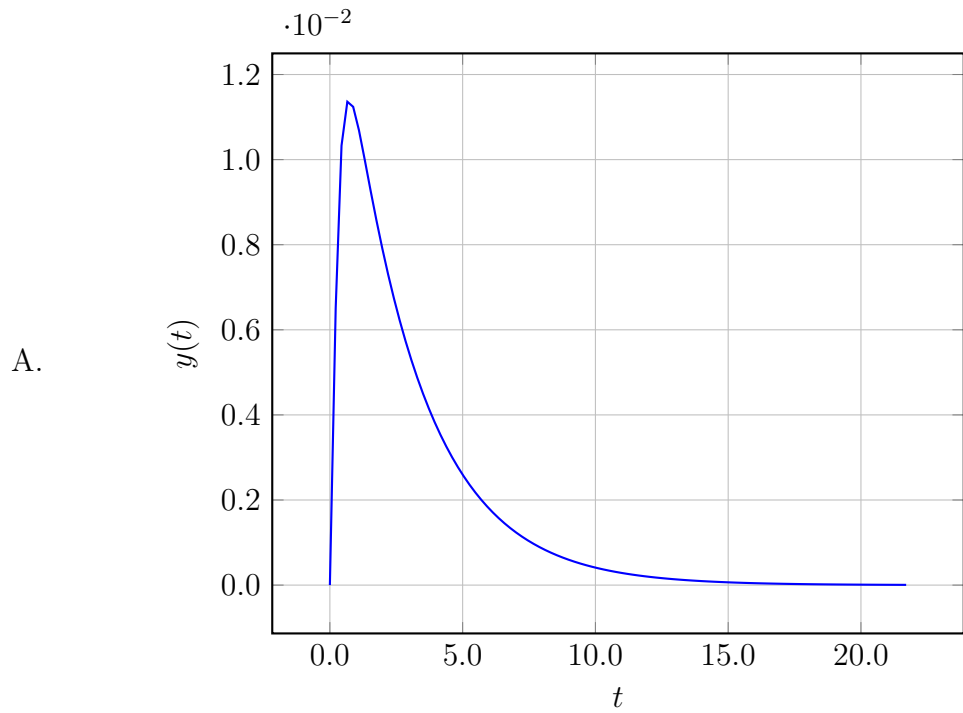
1. (35 points) An open-loop transfer function is given by,

$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.24747s + 7.24747}$$

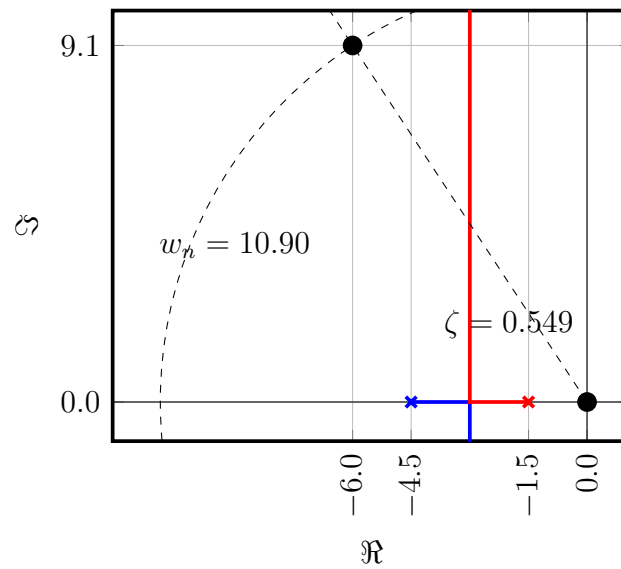
Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

- A. $F(s) = -2.99495 + \frac{0.74747}{s}$
- B. $F(s) = 1.98485 + \frac{1.49495}{s}$
- C. $F(s) = -9.0101 + \frac{1.49495}{s}$
- D. $F(s) = -8.51515 + \frac{2.99495}{s}$
- E. $F(s) = 1.4899 + \frac{2.99495}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

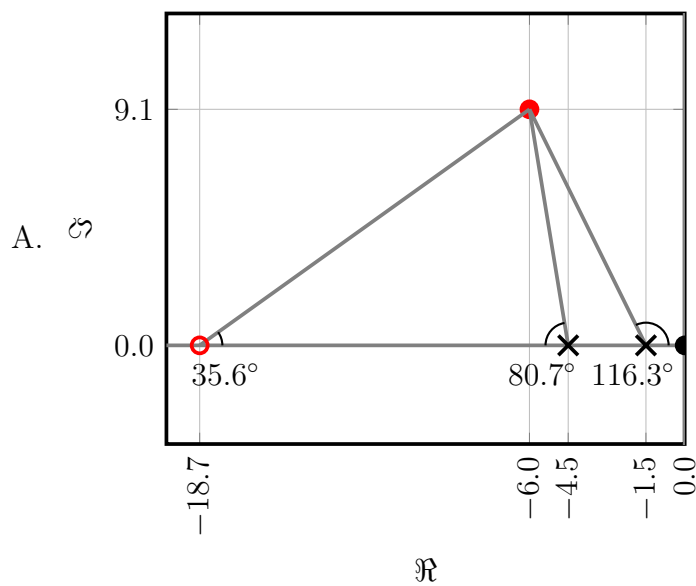


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

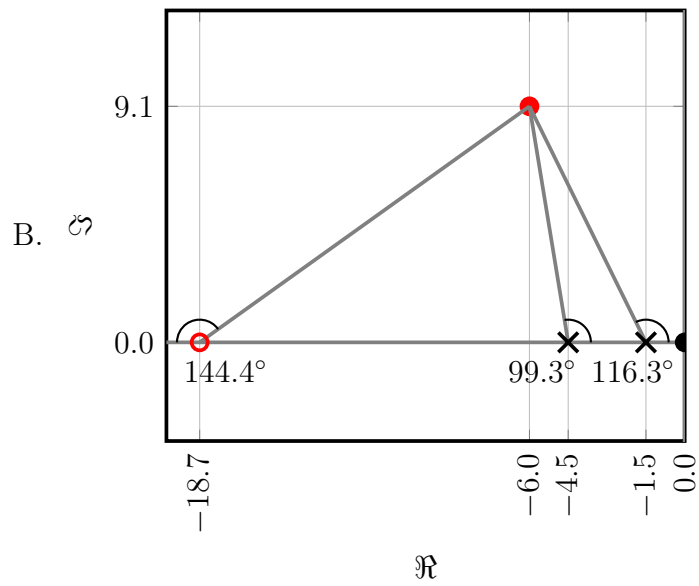


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

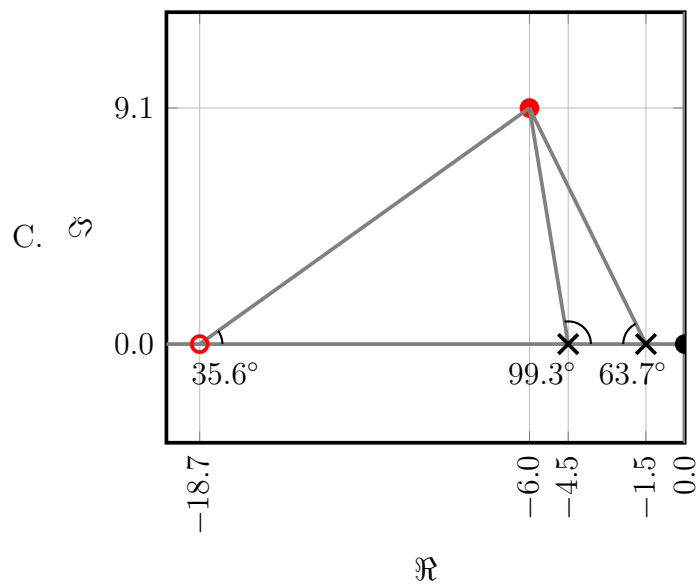
$$\sum \theta = 116.3^\circ + 80.7^\circ + 35.6^\circ =$$



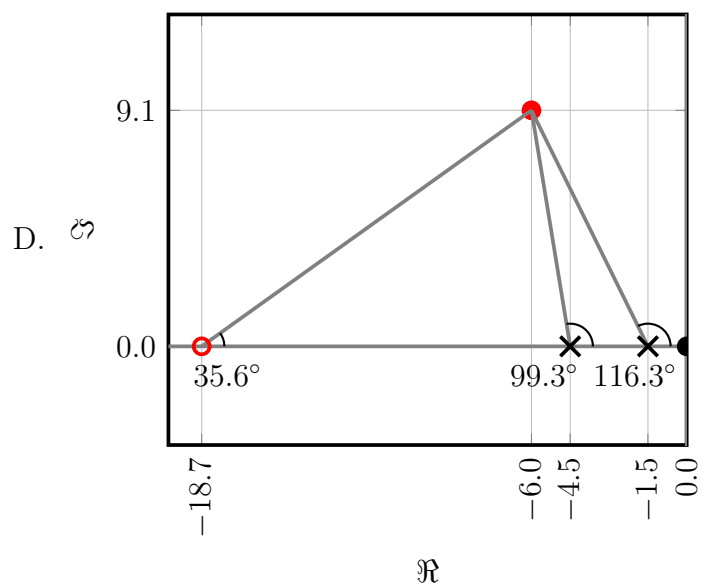
$$\sum \theta = 116.3^\circ + 99.3^\circ + 144.4^\circ =$$



$$\sum \theta = 63.7^\circ + 99.3^\circ + 35.6^\circ =$$



$$\sum \theta = 116.3^\circ + 99.3^\circ - 35.6^\circ =$$



$$\sum \theta = 116.3^\circ + 99.3^\circ + 35.6^\circ =$$

