

1. (35 points) An open-loop transfer function is given by,

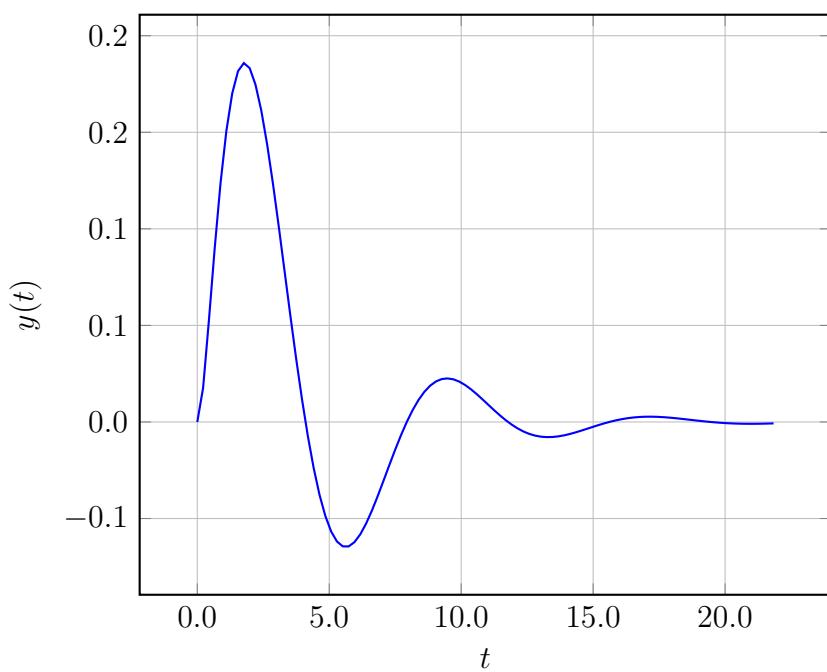
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.36363s + 7.36363}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

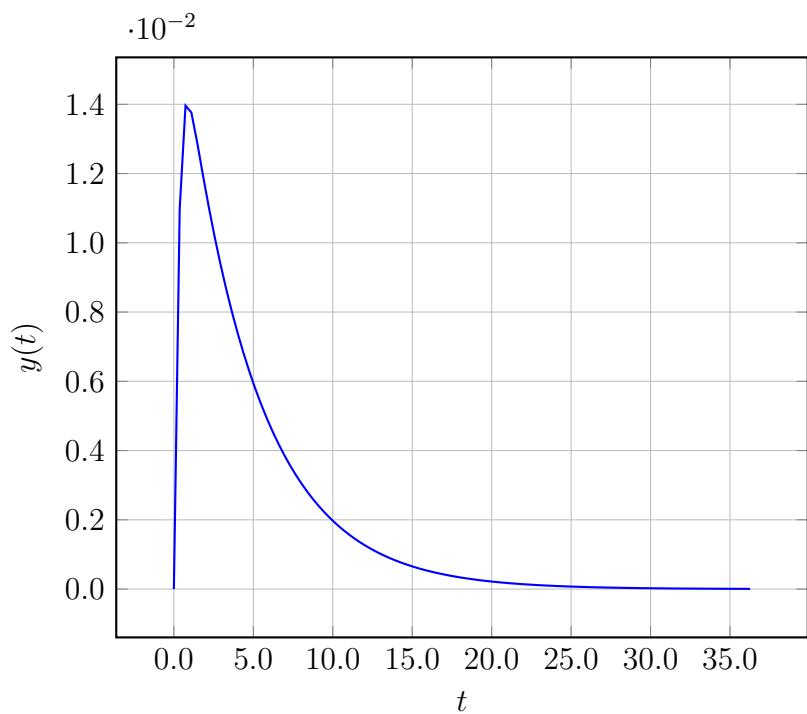
- A. $F(s) = -7.81819 + \frac{3.22726}{s}$
- B. $F(s) = 1.95454 + \frac{3.22726}{s}$
- C. $F(s) = 2.68181 + \frac{1.72726}{s}$
- D. $F(s) = -8.54546 + \frac{1.72726}{s}$
- E. $F(s) = -3.22726 + \frac{0.86363}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

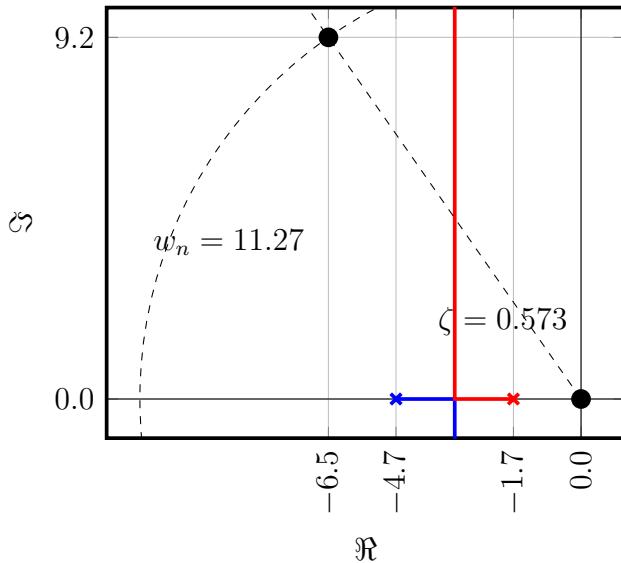
A.



B.

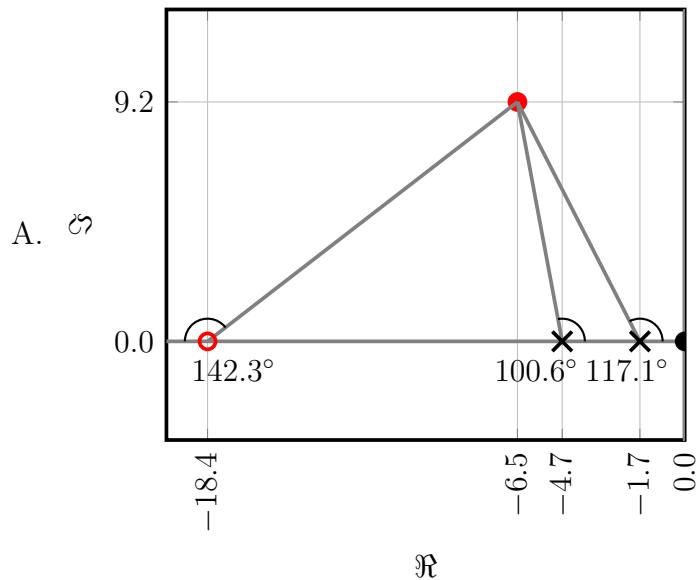


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

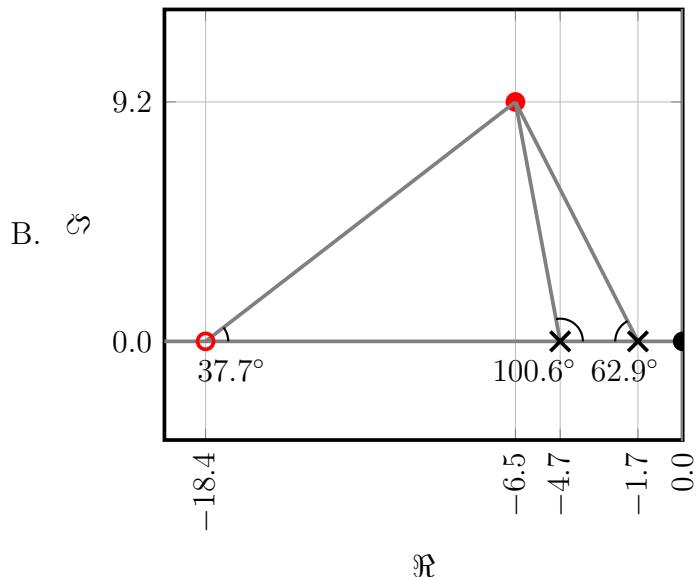


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

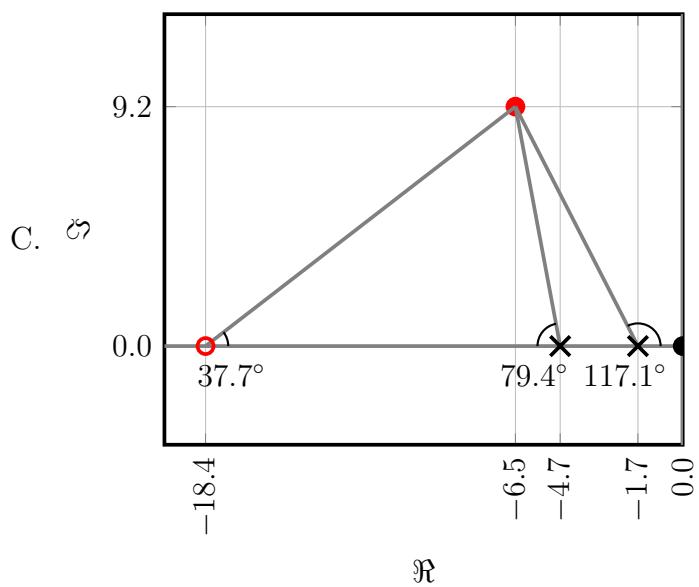
$$\sum \theta = 117.1^\circ + 100.6^\circ + 142.3^\circ =$$



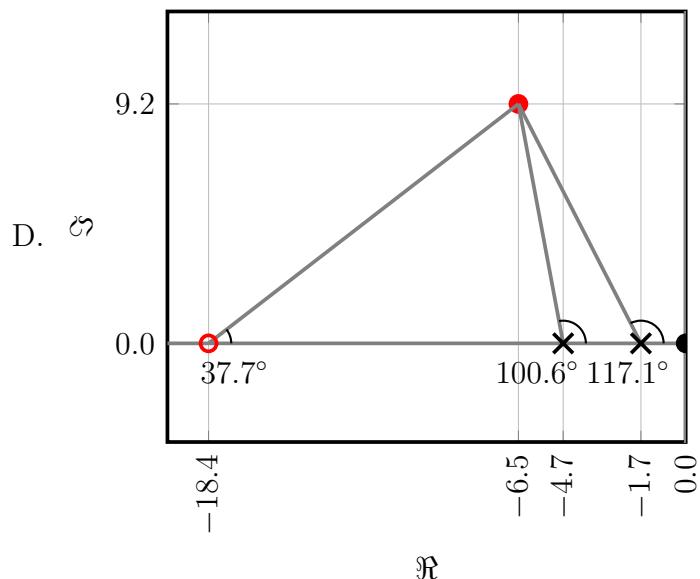
$$\sum \theta = 62.9^\circ + 100.6^\circ + 37.7^\circ =$$



$$\sum \theta = 117.1^\circ + 79.4^\circ + 37.7^\circ =$$



$$\sum \theta = 117.1^\circ + 100.6^\circ - 37.7^\circ =$$



$$\sum \theta = 117.1^\circ + 100.6^\circ + 37.7^\circ =$$

