

1. (35 points) An open-loop transfer function is given by,

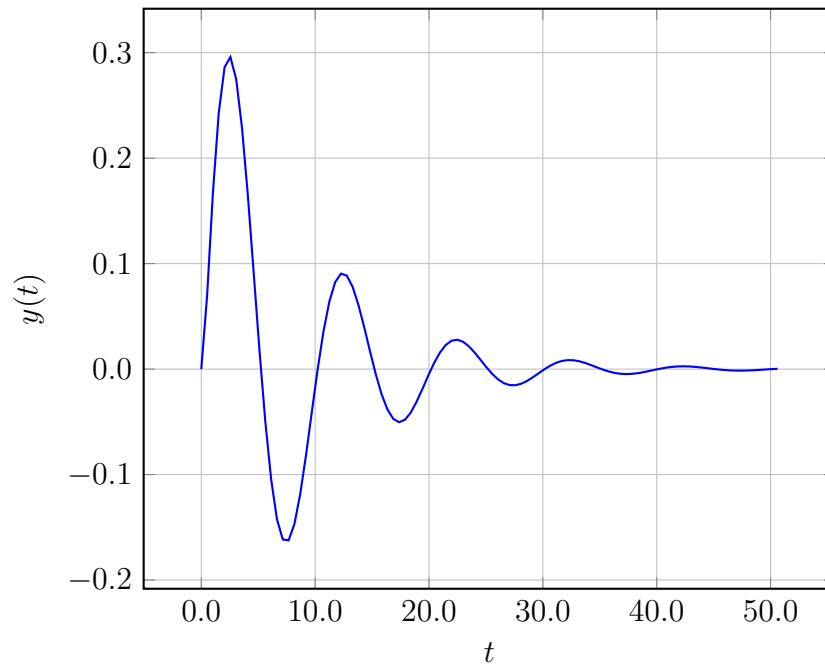
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.1414s + 7.1414}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

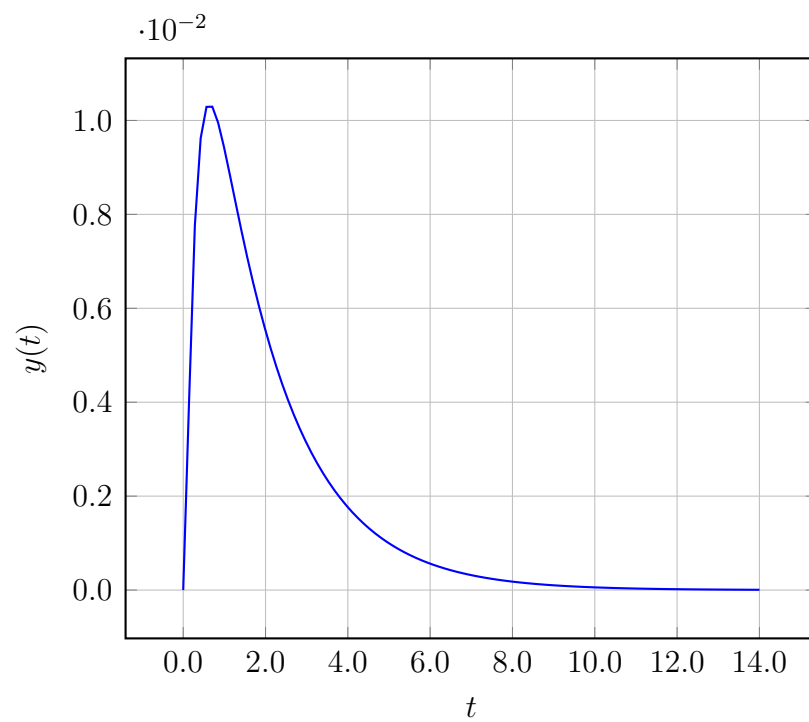
- A. $F(s) = 1.06564 + \frac{2.78282}{s}$
- B. $F(s) = -2.78282 + \frac{0.6414}{s}$**
- C. $F(s) = -9.15152 + \frac{2.78282}{s}$
- D. $F(s) = 1.34848 + \frac{1.28282}{s}$
- E. $F(s) = -9.43436 + \frac{1.28282}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

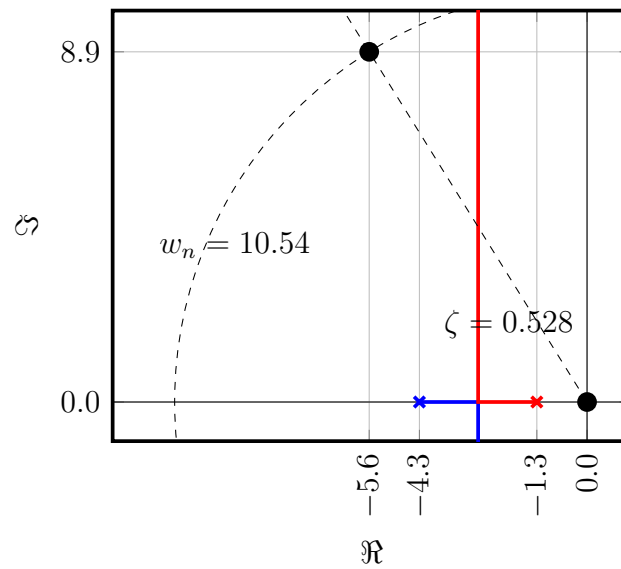
A.



B.

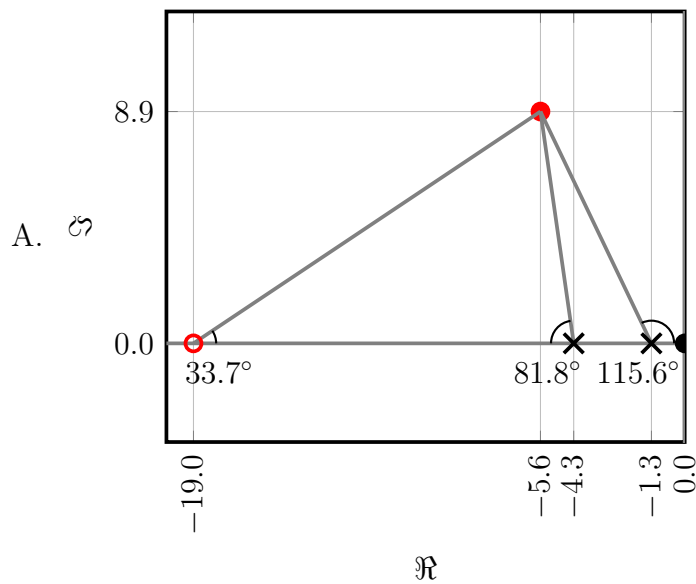


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

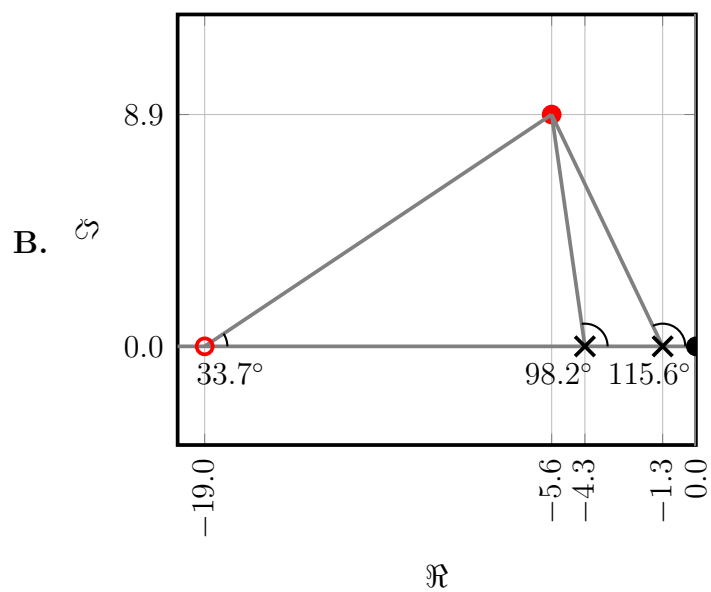


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

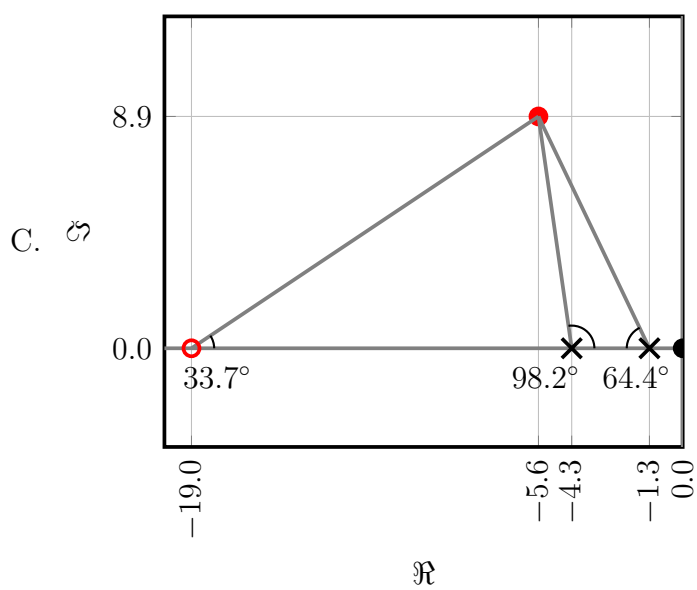
$$\sum \theta = 115.6^\circ + 81.8^\circ + 33.7^\circ = 231.2^\circ$$



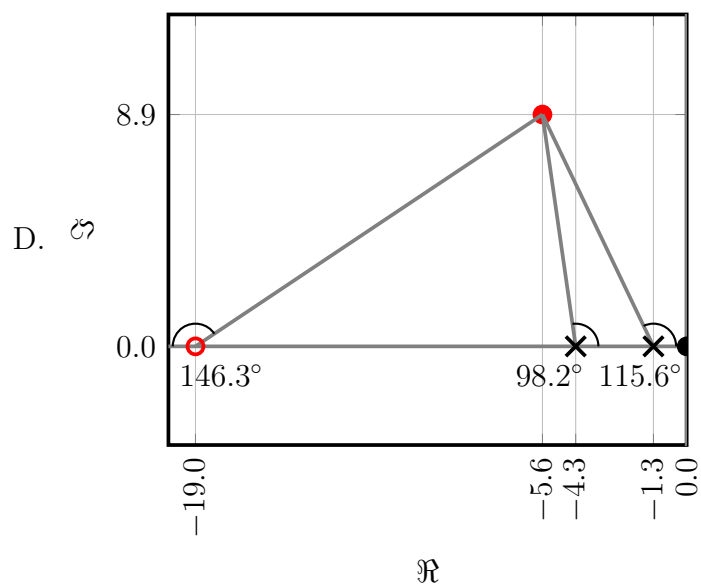
$$\sum \theta = 115.6^\circ + 98.2^\circ - 33.7^\circ = 180.0^\circ$$



$$\sum \theta = 64.4^\circ + 98.2^\circ + 33.7^\circ = 196.3^\circ$$



$$\sum \theta = 115.6^{\circ} + 98.2^{\circ} + 146.3^{\circ} = 360.0^{\circ}$$



Q	A
1	B
2	B
3	B