

1. (35 points) An open-loop transfer function is given by,

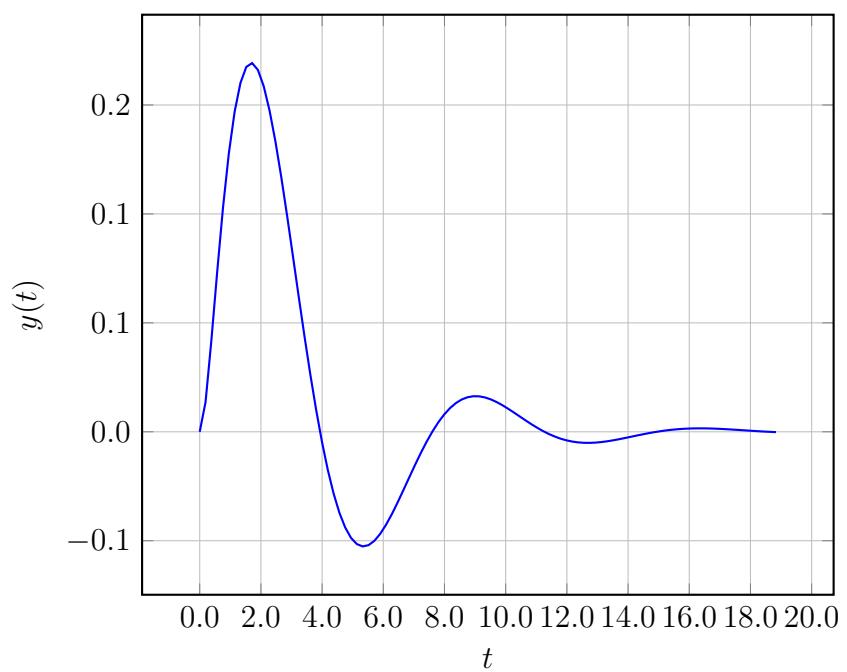
$$G(s) = \frac{1}{s^3 + 2.0s^2 + 3.41414s + 7.41414}$$

Which of the following PI controllers stabilizes the system in a unit-feedback closed-loop configuration?

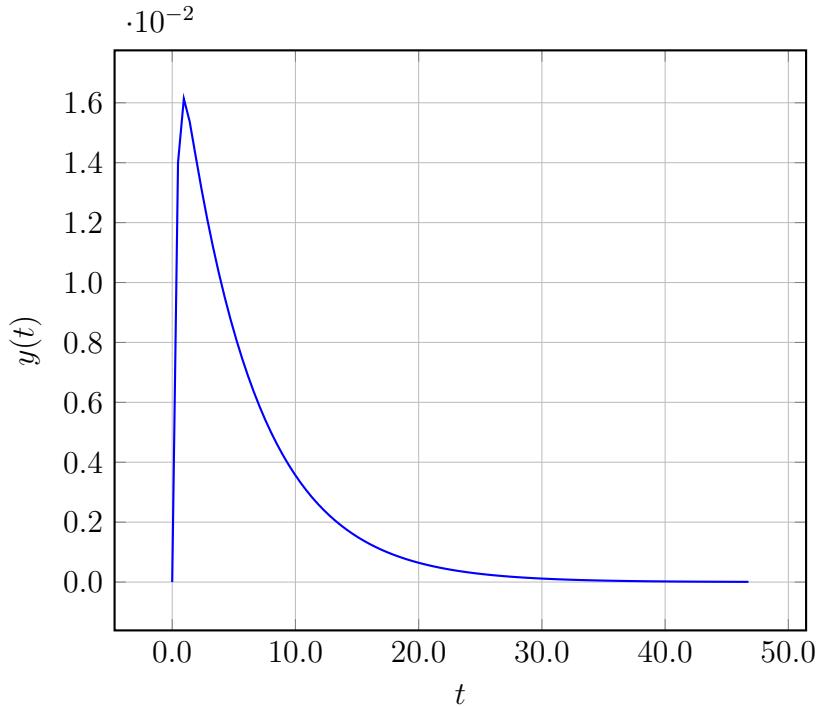
- A. $F(s) = -7.51515 + \frac{3.32828}{s}$
- B. $F(s) = -3.32828 + \frac{0.91414}{s}$
- C. $F(s) = 2.98485 + \frac{1.82828}{s}$
- D. $F(s) = -8.34344 + \frac{1.82828}{s}$
- E. $F(s) = 2.15656 + \frac{3.32828}{s}$

2. (35 points) Which one of the following unit impulse responses corresponds to a system that does not overshoot when subjected to a unit step input?

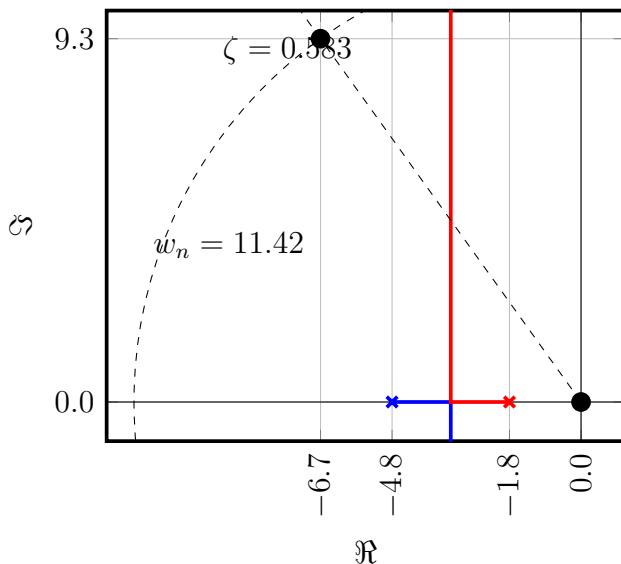
A.



B.

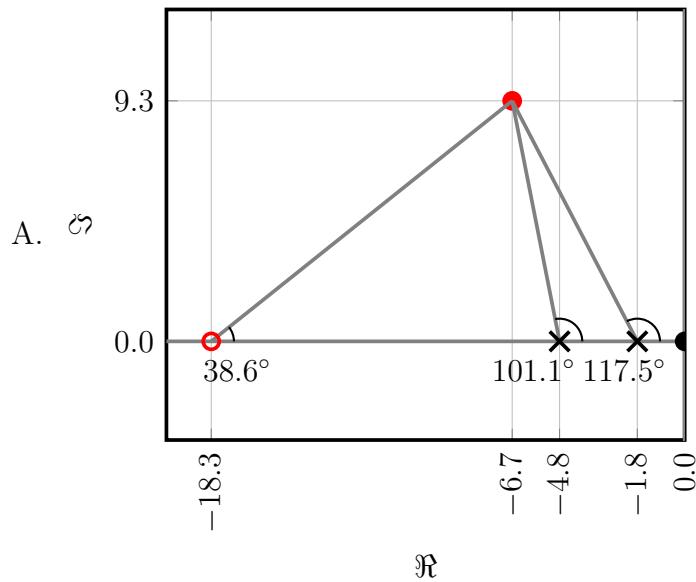


3. (30 points) A design point on the root-locus plot for a P-type controller is shown below.

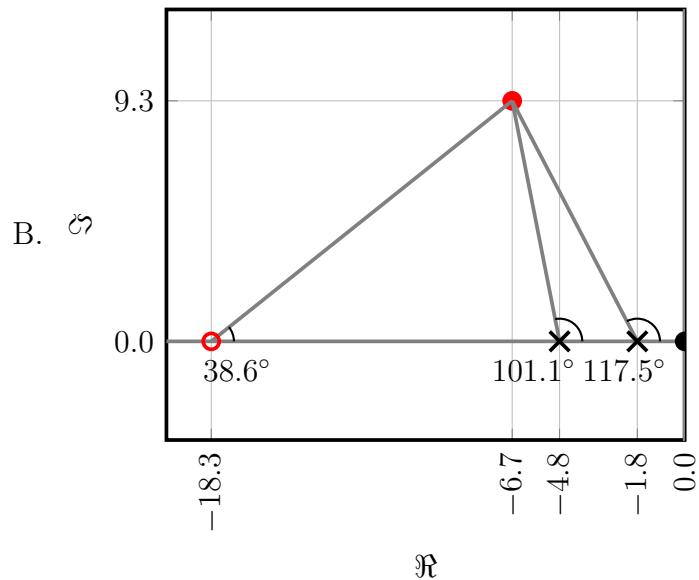


A zero is added so that the root-locus passes through this design point. Which of the following represents the correct angle condition for this design?

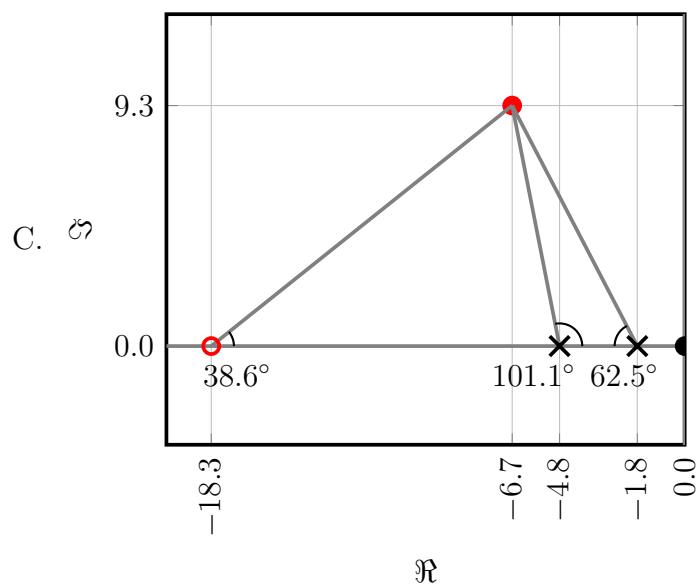
$$\sum \theta = 117.5^\circ + 101.1^\circ + 38.6^\circ =$$



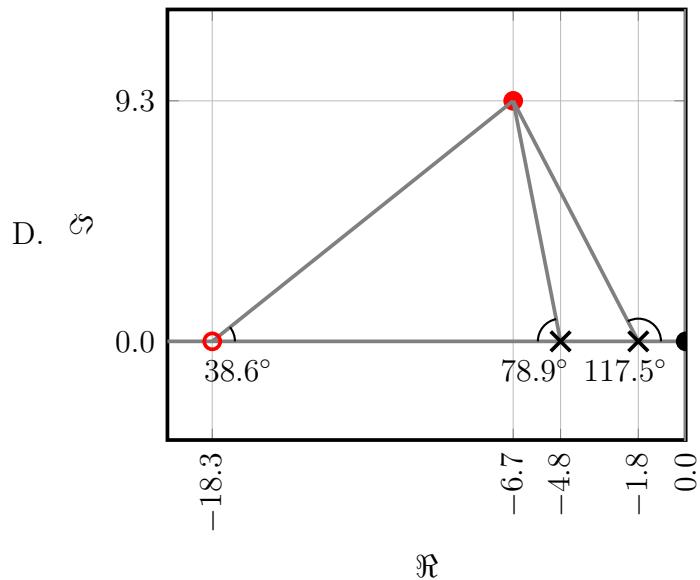
$$\sum \theta = 117.5^\circ + 101.1^\circ - 38.6^\circ =$$



$$\sum \theta = 62.5^\circ + 101.1^\circ + 38.6^\circ =$$



$$\sum \theta = 117.5^\circ + 78.9^\circ + 38.6^\circ =$$



$$\sum \theta = 117.5^\circ + 101.1^\circ + 141.4^\circ =$$

