PRODUCT SPECIFICATION FOR DC MOTOR

MODEL: CL40 Motor

1. TYPE INDICATION

1.1	Spark suppression	Zenerdiodes parallel to rotorcoils
1.2	Direction of rotation	Reversible
1.3	Rotor	Ironless (9x56x2x140µm])
1.4	Nominal voltage	18 V DC
1.5	Nominal speed	3050 rpm
1.6	Nominal load	22 mNm
1.7	Remarks	General purpose

2 ELECTRICAL DATA

2.1	EMF at 3000 rpm	13.2	V ± 10%
2.2	Voltage constant	4.40	mV/rpm ± 10%
2.3	Torque constant	42.0	mNm/A ± 10%
2.4	Terminal resistance	8.4	Ohm ± 8%
2.5	Rotor inductance at 1kHz	1.33	mH

3 THERMAL DATA

3.1	Thermal coefficient of:		
3.1.1	Motor EMF	-0.12	%/K
3.1.2	Resistance	0.4	%/K
3.2	Thermal resistances:		
3.2.1	From winding to housing (Rth1)	5.5	K/W
3.2.2	From housing to ambient (Rth2)	13.0	K/W
3.2.3	From winding to ambient	18.5	K/W
3.3	Thermal time constant of motor without	20	minutes
	heatsink in free air		

4 ELECTROMECHANICAL DATA

4.1	No load			
4.1.1	Voltage	18	V	
4.1.2	Speed	4050	rpm ±	10%
4.1.3	Current	33	mΑ	max.
		22	mΑ	typical
4.1.4	Starting voltage	0.31	V	max.
4.2	Loaded			
4.2.1	Voltage	18	V	
4.2.2	Torque	22	mNm	
4.2.3	Speed	3050	rpm	
4.2.4	Current	0.544	Α	

	Motor assy			9904 120 16705		99-07-08 09-02-25	KD WR
SUPERS		SHEET. 190- 1	3				
NAME. K.M. Dieleman		DATE 99-07-08		PROPERTY OF PRECISION MOTOR TECHNOLOGY			DM
FILE. 9904 120 16	6705 190-1	CHECK.		DORDRECHT - THE NETH			БV

4.3	Starting torque	89	mNm ± 20%
4.4	Starting current	2.13	A ± 8%
4.5	Speed/torque gradient	45.5	rpm/mNm
4.6	Mechanical time constant	19	ms typical
4.7	Typical performance curves	See sh	neet 112-2
4.8	Insulation resistance between winding and housing according to IEC 335-1 (500 V DC)	>2	MOhm

MECHANICAL DATA

5.1	Weight	190	g
5.2	Housing	steel	

5.3 Operation position All positions permitted

Brushes Precious metal 5.4

5.5 **Bearings** Slide

4.0x10⁻⁶ kgm² Rotor inertia 5.6

NOISE AND VIBRATION

6.1	Measuring conditions	Motor on vibration isolator (foam)
6.1.1	Motor position	Shaft horizontal
6.1.2	Noise level of measuring room	max. 30 dBA
6.1.3	Microphone position	10 cm above middle of motor housing
6.1.4	Load	None
6.1.5	Speed	3000 rpm
6.2	Noise level	51 dBA max.

7 LIFE

7.1	Conditions for continuou	us running with radial loa	d		
7.1.1	Voltage		18	V	
7.1.2	Current		0.544	Α	
7.1.3	Torque		22	mNm	(approx.)
7.1.4	Speed		3050	rpm	(approx.)
7.1.5	Radial force		5 N, 10	mm fro	m mounting surface
7.1.6	Axial force		None		-
7.1.7	Motor position		All pos	itions pe	ermitted
7.1.8	Ambient tempe	erature	22 ± 5	\mathcal{C}	
7.1.9	Cycle		3 hour	s ON	
			1 hour	OFF	
7.2	Life B10 value		1000	hours	min. running hours
7.3	Criteria for approval:	Motor function remains	intact.		-

If the Warning signal level (see below) is reached in the life test setup, the motor is regular tested for the criteria 7.3.1 to 7.3.5

that prescribe when motor life is finished

Warning signal: The motor is build out from the life test setup if as warning signal

> the motor current deviates ± 20% of the initial value as described in item 7.1.2 or the audible noise is dramatically increased or if significantly interruptions occur in the commutation wave form.

							99-07-08	KD
	Motor assy		9904 120 16705		09-02-25	WR		
	— Motor docy							
SUPERS		SHEET.	190- 2	3				
NAME. K.M. Dieleman DATE. 99		99-07-08	PROPERTY OF PRECISION MOTOR TECHNO			DM		
FILE. 9904 120 16705 190-1 CHECK.		DORDRECHT - THE NETH			БУ			

7.3.1	EMF at 3000 rpm	-10% of zero hour value
7.3.2	Commutation wave form	No blocked interruptions;
7.3.3	No load current	2 times the no load current from item 4.1.3
7.3.4	Noise level	60 dBA max.
7.3.5	Bearings	Bearing function and bearing preload
		remains intact

TEMPERATURES

8.1	Ambient temperature	-10 to 60	$\mathcal C$
8.2	Max. housing temperature	80	$\mathcal C$
8.3	Storage temperature	-40 to 70	$\mathcal C$

LIMITING VALUES

9.1 The following maximum values can be applied continuously, however they reduce the life of the motor considerably.

9.1.1	Voltage	22 V
9.1.2	Load	26 mNm
9.1.3	Current	0.640 A
9.1.4	Peak current	2.1 A
9.1.5	Speed	3774 rpm
9.1.6	Output power	10.3 W
9.1.7	Radial force	7N, 10 mm from mounting surface
9.1.8	Axial force	0.5 N
9.1.9	Locked rotor	7.1 V (ambient temp. max

(ambient temp. max 40 ℃)

9.2 The following maximum values should never be exceeded.

at 18 V and 40 ℃ winding start temp.

9.2.1	Voltage	24	V
9.2.2	Load	35	mNm
9.2.3	Peak current	2.7	Α
9.2.4	Maximum speed	5000	rpm
9.2.5	Output power	14	W
9.2.6	Axial force	50	N
9.2.7	Radial force	50	N
9.2.8	Winding temperature	120	$\mathcal C$
9.2.9	Locked rotor	16	S

REMARKS

Unless otherwise specified, the measurements have to be executed under the following conditions:

0000	stron mod opedined, the intededition one have to be	Chocatoa anaoi	
10.1		22 ± 5	${\mathfrak C}$
10.2	Atmospheric pressure	$0.86 - 1.06 \times 10^{5}$	Pa
10.3	Relative humidity	45 – 75	%
10.4	Radial force	None	
10.5	Axial force	None	

GENERAL SPECIFICATIONS

Unless otherwise specified, general requirements are specified in reference sheet PN40-01-98

	Мо	tor assy		9904 120 16705	99-07-08 09-02-25	KD WR
SUPERS		SHEET. 190- 3	3			
NAME. K.M. Dielem	DATE. 99-07-08		PROPERTY OF PRECISION MOTOR TECHNOLOGY BV			
FILE, 9904 120 16705 190-1 CHECK.				DORDRECHT - THE NETHERLANDS		