## APMA 1360 Homework 1

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## Problem 1 - ODEs on the Real Line

For each of (i)-(vi) below, find a continuously differentiable function  $f : \mathbb{R} \to \mathbb{R}$  such that the differential equation  $\dot{u} = f(u)$  has the stated properties or, if there is no such function, explain in detail (with a proof or a precise argument) why not. If possible, give an explicit expression of the function; otherwise, sketch its graph.

- (i) Every real number is an equilibrium. f = 0
- (ii) Every integer is an equilibrium, and there are no other fixed points besides those.  $f(u) = \sin(\pi u)$
- (iii) There are exactly two equilibria, and both of them are stable.

Impossible. If there are exactly two equilibria, then f has two roots (say  $u_1, u_2$  and WLOG assume  $u_1 < u_2$ ).

As it is an equilibrium,  $f(u_1) = 0$ . By assumption,  $u_1$  is stable so  $f'(u_1) < 0$ .

CASE 1: f'(u) < 0 for all u.

But then, f is strictly decreasing so  $\forall \varepsilon > 0$ ,  $f(u_1 + \varepsilon) < f(u_1) = 0$ .

In particular, let  $\varepsilon = u_2 - u_1 > 0$ . then  $f(u_1 + \varepsilon) = f(u_2) < f(u_1) = 0 \implies f(u_2) < 0$  which contradicts the fact that  $u_2$  is an equilibrium.

CASE 2:  $\exists I \subseteq \mathbb{R}$  such that  $f'(t) \geq 0$  for  $t \in I$ .

If  $u_2 \in I$ , then  $u_2$  is not a stable equilibrium. Contradiction.

If  $u_2 \notin I$  and f is not strictly decreasing everywhere (Case 1), then since  $f \in C^1$ ,  $u_1 < u_2$ ,  $f(u_1 + \varepsilon) < 0$ , and  $f(u_2) = 0$ , by the Intermediate Value Theorem,  $\exists u_3 \in (u_1, u_2)$  such that  $f(u_3) = 0$ . Contradiction.

- (iv) There are no equilibria. f = 1
- (v) The phase diagram looks as shown in the picture below:



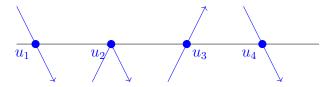
We label the equilibria as  $u_1 < u_2 < u_3 < u_4$ . Then,

- $u_1$ ,  $u_4$  are stable
- $u_2$  is a saddle point
- $u_3$  is unstable

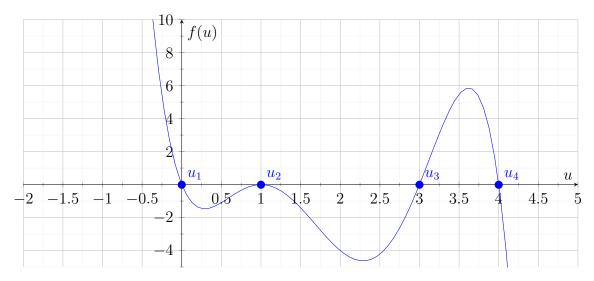
Hence,

$$f'(u_1) < 0$$
,  $f'(u_2) = 0$ ,  $f'(u_3) > 0$ ,  $f'(u_4) < 0$ 

So, the graph of f must resemble



One possible function is  $f(u) = -u(u-1)^2(u-3)(u-4)$ :



(vi) The differential equation has a solution u(t) that is periodic in t: there is a T > 0 with u(t+T) = u(t) for all t, but u(t) is not an equilibrium (that is, not a constant function).

Impossible. Suppose there exists such a periodic solution u for such an f. Consider a point  $u(t_0)$ . By periodicity,  $u(t_0) = u(t_0 + T)$ .

Since  $f \in C^1$ ,  $u \in C^2$  and by Rolle's Theorem,  $\exists t^* \in (t_0, t_0 + T)$  such that

$$f(u(t^*)) = u'(t^*) = \frac{u(t_0 + T) - u(t_0)}{T} = 0$$

If f(u(t)) = 0 for all  $t \in (t_0, t_0 + T)$ , hence u(t) is an equilibrium. Contradiction of assumption.

Otherwise,  $u(t^*)$  is an equilibrium. If f is decreasing at  $u(t^*)$ , then the equilibrium is stable, hence u(t) is constant in t - Contradiction.

If f is increasing at  $u(t^*)$ , then since u is periodic, there must exist some other equilibrium point where f is decreasing, again leading to a stable equilibrium.

## Problem 2 - Logistic model

The differential equation

$$\frac{du}{dt} = ru\left(1 - \frac{u}{K}\right) - \mu u$$

serves as a model for a population of fish with harvesting: u(t) is the size of the population at time t, r > 0 is the growth rate of fish at small population levels, K > 0 is called the carrying capacity, and  $\mu \ge 0$  is the percentage of fish caught per unit time interval.

1. Analyze this model mathematically: find all equilibria, determine their stability, and identify all bifurcation points (if any) at which the number of equilibria changes as a function of the fishing rate  $\mu$ .

Let  $f(u) = ru\left(1 - \frac{u}{K}\right) - \mu u$ . Then, the equilibria are given by

$$u_1 = 0, \quad u_2 = K(1 - \frac{\mu}{r})$$

(these are the only equilibria as f is quadratic in u.)

Further,

$$f'(u) = r - \mu - \frac{2r}{K}u$$

and

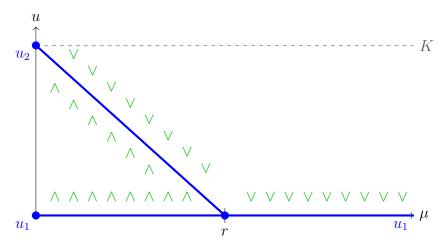
$$f'(u_1) = r - \mu, \quad f'(u_2) = r - \mu - 2(r - \mu) = \mu - r$$

Hence,

- $u_1 = 0$  is stable for  $\mu > r$ , unstable for  $\mu < r$ , and undetermined for  $\mu = r$ .
- $u_2 = \frac{K}{r}(r \mu)$  is stable for  $r > \mu$ . For  $\mu > r$ ,  $u_2 = K(1 \frac{\mu}{r}) < 0$  which is impossible. For  $\mu = r$ ,  $u_2 = 0$  and there exists only one equilibrium.

By the above argument,  $\mu = r$  is a bifurcation point since for  $\mu < r$ , there are two equilibria and for  $\mu > r$ , there is only one equilibrium.

2. Draw the bifurcation diagram with respect to  $(\mu, u)$ .



3. Discuss the meaning of the carrying capacity K and identify which equilibria are meaningful with respect to the underlying application, where u(t) captures the size of the fish population. Discuss the implications of your analysis for the underlying application of fishing/harvesting of fish.

If there were no fishing  $(\mu = 0)$ , then since  $u_1$  is unstable and  $u_2$  is stable, the fish population would stabilize at u = K. As we introduce fishing  $(\mu \nearrow)$ , the equilibrium solution  $K - \frac{K}{r}\mu$ , representing a stable fish population, decreases. Hence, if the fishing rate  $\mu$  exceeds the growth rate r, then the fish population will die out. If, instead,  $0 < \mu < r$ , then the fish population will stabilize at a lower level than K and the fishing rate will be sustainable.

## Problem 3 - Stability of Equilibria

In your own words, write down a concise definition of when we call an equilibrium stable.

For a differential equation of the form  $\dot{u} = f(u)$ ,  $u^*$  is an equilibrium point if  $f(u^*) = 0$ . We say that  $u^*$  is a stable equilibrium if  $\exists \varepsilon > 0$  such that  $\forall u_i \in B_{\varepsilon}(u^*)$ ,  $\lim_{t \to \infty} u(t) = u^*$  for all solutions u(t) with  $u(0) = u_i$ .