



$$\delta(q_0, a, z) = \{(q_1, az)\}$$

$$\delta(q_1, a, a) = \{(q_1, aa)\}$$

$$\delta(q_1, b, a) = \{(q_2, a)\}$$

$$\delta(q_2, b, a) = \{(q_2, a)\}$$

$$\delta(q_2, c, a) = \{(q_3, \lambda)\}$$

$$\delta(q_2, c, a) = \{(q_3, \lambda)\}$$

$$\delta(q_3, \lambda, z) = \{(q_f, \lambda)\}$$

$$F = \{q_f\}$$

Prog,

