Problem 1:

a) First, we can take the following Taylor Series (considering until 5th deriv)
$$f(x+\delta) \simeq f(x) + f'(x)\delta + f''(x)\frac{\delta^2}{\delta^2} + f'''(x)\frac{\delta^3}{\delta^3} + f''''(x)\frac{\delta^5}{\delta^3} + \dots$$

$$f(x-\delta) \simeq f(x) - f'(x)\delta + f''(x)\frac{\delta^2}{\delta^2} - f'''(x)\frac{\delta^3}{\delta^3} + f'''(x)\frac{\delta^4}{\delta^3} + f'''(x)\frac{\delta^5}{\delta^3} + \dots$$

$$f(x+2\delta) \simeq f(x) + f'(x)2\delta + f''(x)2\delta^2 + f''(x)\frac{4\delta^3}{\delta^3} + f'''(x)\frac{2\delta^4}{\delta^3} + f'''(x)\frac{4\delta^5}{\delta^3} + \dots$$

$$f(x-2\delta) \simeq f(x) - f'(x)2\delta + f''(x)2\delta^2 - f''(x)\frac{4\delta^3}{\delta^3} + f'''(x)\frac{2\delta^4}{\delta^3} - f'''(x)\frac{4\delta^5}{\delta^5} + \dots$$
If we know the exact value of $f(x+\delta)$ and $f(x+2\delta)$ we say

If we know the exact value of $f(x\pm 8)$ and $f(x\pm 28)$ we can try to estimate f'(x). Then, we will try to solve the following system of equations 1 8 3/2 53/6 81/24 85/120

Solving by Gaussian (fix)

elimination:

$$R_2$$
- $R_1 \rightarrow R_2 \Rightarrow \begin{pmatrix} 1 & 5 & 5/2 & 5/6 & 5/4 & 5/120 \\ 0 & -25 & 0 & -5/60 \\ 1 & 25 & 25^2 & 4/35^3 & 25^4 & 4/55 \\ 1 & -25 & 25^2 - 4/5^3 & 25^4 - 4/5/15 \end{pmatrix} = f(x+25)$

$$R_{3}-R_{1} \rightarrow R_{3} \Rightarrow \begin{pmatrix} 1 & 5 & 5^{2}/2 & 5^{3}/6 & 5^{4}/24 & 5^{5}/120 \\ 0 & -25 & 0 & -5^{3}/3 & 0 & -5^{5}/60 \\ 0 & 6 & 35^{2} & +83^{3}/6 & 58^{4}/2 & 318^{5}/6 \\ 1 & -26 & 25^{2} & -48^{3}/3 & 25^{4}/3 & -48^{5}/6 \\ \end{pmatrix} - \frac{f(x+6)}{f(x+26)} + \frac{f(x+26)}{f(x-26)}$$

$$R_{3}-R_{1} \rightarrow R_{3} \Rightarrow \begin{cases} 1 \leq 8/2 & 8/6 & 8/24 & 8/120 \\ 0 - 28 & 0 - 83/2 & 0 - 85/60 \\ 0 \leq 38^{2} + 83/6 & 58/8 & 3185 \\ 1 - 28 & 28^{2} - 48^{3}/8 & 28^{3}/3 - 48^{5} & -4(x+8) + 4(x+26) \\ 1 - 28 & 28^{2} - 48^{3}/8 & 28^{3}/3 - 48^{5} & +4(x+26) \\ 0 - 28 & 0 & -8^{3}/2 & 0 & -8^{3}/20 \\ 0 - 38 & 38^{3}/2 & -38^{3}/2 & 58^{3}/8 & 318^{3}/120 \\ 0 - 38 & 38^{3}/2 & -38^{3}/2 & 58^{3}/8 & -118^{3}/40 & -4(x+8) + 4(x+26) \\ 0 - 38 & 38^{3}/2 & -38^{3}/2 & 58^{3}/8 & -118^{3}/40 & -4(x+8) + 4(x+28) \\ 0 - 38 & 38^{3}/2 & -38^{3}/2 & 58^{3}/8 & -118^{3}/40 & -4(x+8) + 4(x+28) \end{cases}$$

$$\begin{array}{c} R_{2} - \frac{R_{2}}{L} \rightarrow R_{3} \Rightarrow \begin{cases} 1 & \delta & \delta/2 & \delta/6 & \delta/24 & \delta/420 \\ 0 & -25 & 0 & -5/6 & 0 & -5/60 \\ 0 & 0 & 36/2 & \delta^{5} & 58/8 & \delta^{5}4 \\ 0 & -25 & 36/2 & -35/2 & 56/6 & -118/40 & -1(x+5) + (x-5) + 2(x+25)/2 \\ 0 & -25 & 36/2 & -35/2 & 56/6 & -118/40 & -1(x+5) + (x-26)/2 \\ 0 & -25 & 0 & -5/6 & 0 & -5/60 & -1(x+5) + (x-5) + 2(x+25)/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-3(x+5) + (x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-3(x+5) + (x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-3(x+5) + (x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-4(x+5) + 4(x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-4(x+5) + 4(x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-4(x+5) + 4(x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-4(x+5) + 4(x+5) + 2(x+25)]/2 \\ 0 & 0 & 36/2 & \delta^{5} & 56/8 & 5/4 & [-4(x+5) + 4(x+5) + 2(x+5) + 2(x+5$$

b) We can obtain the optimal & using the derivative of Err with respect to S and solving Sopt when that derivative is equal to O.

=> $\frac{dE_m}{ds} = -\frac{18}{12} \frac{|f(x)|}{S_{opt}^2} + \frac{4}{30} S_{opt}^3 |f^{(11)}(x)| = 0 \Rightarrow S_{opt} = 458 |f^{(11)}(x)|$

=)
$$\delta_{opt} = \left(45 \varepsilon |f(x)| \right)^{1/5} \Rightarrow for f(x) = e^{x} \Rightarrow f''''(x) = e^{x}$$

 $\Rightarrow \delta_{opt} = \left(45 \times 10^{-16} \right)^{1/5} \simeq 10^{-3}$

for f(x)= e > f(x) = 10-10e 0.01x => Sopt = (45×10-6)1/5~10-1

In [72]:

```
import numpy as np
import matplotlib.pyplot as plt
```

Defining the optimal δ for every case. dp is $\epsilon = 10^{-16}$ for computational error for double precision.

In [73]:

```
dp=10**-16
delta1=(45*dp)**(1/5)
delta2=((45*10**-6))**(1/5)
```

In [74]:

```
delta1,delta2
```

Out[74]:

```
(0.001350960038520613, 0.13509600385206133)
```

Defining an array dd to try different δ values for 11 values of x in the array x0

In [75]:

```
dd=np.linspace(-5,-1,1001)
x0=np.linspace(-5,5,11)
```

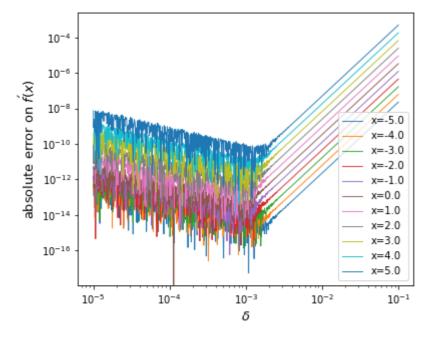
deriv is our estimation for the first derivative for $f(x) = e^x$ and deriv2 is the first derivative for $f(x) = e^{0.01x}$

In [76]:

In [77]:

Since the actual derivative for $f(x) = e^x$ is $f'(x) = e^x$ the following plot shows the absolute error between the actual derivative and our estimation.

In [78]:



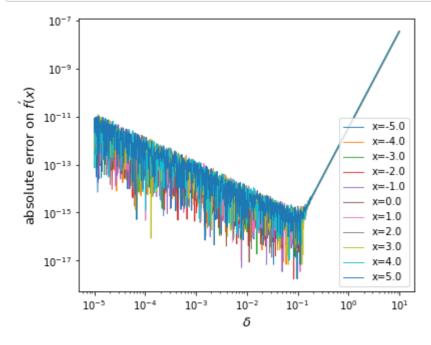
dd1 similar to dd

In [79]:

```
dd1=np.linspace(-5,1,1001)
```

 $f'(x) = 0.01e^{0.01x}$ for the second case.

In [80]:



We can note that the optimal δ observed on the figures are similar for the both cases, i.e., $\sim 10^{-3}$ and $\sim 10^{-1}$ respectively. When δ is lower than those optimal values the error oscillates because of computational errors based on the machine precision, and for higher values the error increases with a constant slope because of errors in the numerical approximation.

In []:

In []:

In []:

Problem 2: If we have the following taylor series: $f(x+dx) \simeq f(x) + f'(x)dx + f''(x)\frac{dx^2}{2} + f''(x)\frac{dx^3}{6} + \frac{1}{6}$ $f(x-dx) \simeq f(x) - f'(x) dx + f''(x) dx^2 - f''(x) dx^3 + ...$ $\Rightarrow f(x+dx) - f(x-dx) = 2f'(x)dx + 2f''(x)dx^3$ \Rightarrow $f'(x) \sim f(x+dx) - f(x-dx) - f''(x) \frac{dx^2}{3}$ then for the centered derivative formula f'(x) = f(x+dx) - f(x-dx)we will have the following estimation for the error: zdxErr = 21f(x) \(\x\) + 1f"(x) \(dx^2 \) Similar to what was done on Problem 1. \(\x = 10^{-16} \) for double precision. $\frac{1}{dx} \frac{dErr}{dx} \sim 0 \Rightarrow -\frac{|f|x||\varepsilon}{dx} + \frac{|f''(x)||dx_{opt}||-0|}{dx_{opt}} = 0 \Rightarrow dx_{opt} \left(3\varepsilon \left|\frac{f(x)}{f''(x)}\right|\right)^{\frac{1}{3}}$ estimation of dx As ax depends on f"(x), an estimation of the third derivative is needed to know dxopt without actually know the exact value of I'(x) and/or ["(x). f'(x) and/or f"(x). From problem 1 we can know the following taylor series; and etc. What if we add f(x+6) = f(x) + f'(x) h + f"(x) h2 + ... f(x+3h) and expands until f(x-h) = f(x) - f'(x)h + f"(x)h2 -... the 7th derivative?

 $f(x+2h) \approx f(x) + f'(x)h + f''(x)\frac{h^2}{2} + \dots$ (sty we do that we will $f(x-2h) \approx f(x) - f'(x)2h + f''(x)2h^2 - \dots$ obtain a larger system of equations whose matrix form is on the next page.

1 h h /2 h /24 1 -h h /2 h /6 h /24 1 2h 2h 2h 2h /3 2h /3 1 -2h 2h 2h -4h /3 2h /3 1 3h 9h /2 9h /2 27h /8 f(x)
f'(x) h/120 h+/5040 h5/120 (f(xth) f"(x) h /720 -h7/5040 -h5/120 f (x-h) f"(x) 4h5/15 847/315 418/45 f(xth) f(x) -415/15 416/45 -847/315 f (x-2h) 8115/40 243h7/560 811/30 f (x) 1 -3h 9h2/2 -9h1/2 27h4/8 -8145/40 f (x+3h) 811/80 -24347/560 f(x) f (x-3h) f (x)/ a matrix solver online we can And using obtain: 13(f(x-h)-f(x+h))+8(f(x+zh)-f(x-zh))+f(x-3h)-f(x+3h)+7f(x)h f"(x) 2 Then, we can note that avoiding the term I fix h we can estimate very precisely the third derivative for a small h, which could be different to dxept or an actual hopt for the third derivative. Without the term of the 7th derivative, we can roughly estimate an error: $Errf''' = \frac{46 \, \epsilon \, lf(x)}{8 \, h^3} \sim \frac{5 \, \epsilon \, lf(x)}{h^3}$ Let's take just $\epsilon \, \frac{lf(x)}{h^3}$ then I chose h = 10-4 => Erry = 10-16 1f(x)1 = 10-4 1f(x)1 > If If(x) < 10-12 > Ent = 6-10= € On the other hand, if $f(x) \sim 0 \Rightarrow dx_{opt} \sim 0$. Even more, if $f'''(x) \sim 0 \Rightarrow dx_{opt} \rightarrow \infty$. Then we will take for the fixed h the following cases to avoid dxopt going to 0 or op: 2) If |f"(x) | < 10-12 => dxopt = (3|f(x)| E) =3 3) $d \times opt = (3 \in \frac{f(x)}{f_{app}^{(u)}(x)})^{1/3}$ for any other case (an using our estimation for the third derivative with the fixed h) I also used the approximation of the third derivative for estimate the error of f'(x) => Erre = If(x) + If(x) | dxopt

```
In [ ]:
```

I defined the ndiff routine as requested. Note that the optimal dx is obtained for three different cases depending on the value of f(x) and the estimation of the third derivative.

In [82]:

```
def ndiff(fun,x,full=False):
    dp=10**-16
    h=0.0001 #for 3rd derivative estimation and then dx and err estimation
    df3=(13*(fun(x-h)-fun(x+h))+8*(fun(x+2*h)-fun(x-2*h))
         +fun(x-3*h)-fun(x+3*h))/(8*(h**3)) #third derivative estimation
    if np.abs(fun(x))<10**-12:</pre>
        dx=(3*dp)**(1/3)
        #print(dx)
    elif np.abs(df3)<10**-12:
        dx=np.abs(3*dp*fun(x))**(1/3)
        #print(dx)
    else:
        dx=np.abs(3*dp*fun(x)/df3)**(1/3)
    err=np.abs((dp*fun(x))/dx)+(dx**2)*np.abs(df3)/3
    if full==False:
        return (fun(x+dx)-fun(x-dx))/(2*dx)
    else:
        return (fun(x+dx)-fun(x-dx))/(2*dx),dx,err
```

Let's test the numerical differentiator.

```
First case, f(x) = x^4 + x^3 + x^2 + 3x + 4
```

My estimation of the derivative, optimal dx, and the absolute error.

In [83]:

```
ndiff(np.poly1d([1,1,1,3,4]),-3,True)
```

Out[83]:

```
(-84.00000000162943, 6.414781657735258e-06, 1.8083234346740647e-09)
```

The actual derivative

```
In [84]:
```

```
np.polyval(np.poly1d([4,3,2,3]),-3)
```

```
Out[84]:
```

-84

The actual absolute error.

```
In [86]:
```

Out[86]:

1.629430812499777e-09

Second case, $f(x) = e^{0.01x}$

In [87]:

```
def exp001(x):
    return np.exp(0.01*x)
```

My estimation of the derivative, optimal dx, the absolute error.

```
In [88]:
```

```
ndiff(exp001,1,True)
```

Out[88]:

(0.01010050167075005, 0.00022183904502537719, 9.106153219949394e-13)

The actual derivative

```
In [89]:
```

```
0.01*np.exp(0.01*1)
```

Out[89]:

0.01010050167084168

The actual absolute error

```
In [90]:
```

```
np.abs(0.01*np.exp(0.01*1)-ndiff(exp001,1))
```

Out[90]:

9.162982872457093e-14

Third case, $f(x) = cos(x^2 - 1)$

In [91]:

```
def cospol(x):
    return np.cos((x**2)-1)
```

My estimation of the derivative, optimal dx, and the absolute error.

```
In [92]:
ndiff(cospol,np.pi,True)
Out[92]:
(-3.3118091750785004, 1.1612951097703305e-06, 1.4635538619068603e-10)
The actual derivative
In [93]:
-np.sin((np.pi**2)-1)*2*(np.pi)
Out[93]:
-3.3118091745987295
The actual absolute error
In [94]:
np.abs(-np.sin((np.pi**2)-1)*2*(np.pi)
        -ndiff(cospol,np.pi))
Out[94]:
4.797708896830954e-10
The ndiff routine works and can estimate an absolute error very accurately, but this estimation can vary from the
actual absolute error since my estimation was made based on an approximation of the third derivative.
In [ ]:
```

```
In [ ]:
```

Problem 3

First, I read the archive an did a plot of the temperature as function of the voltage

```
In [95]:
```

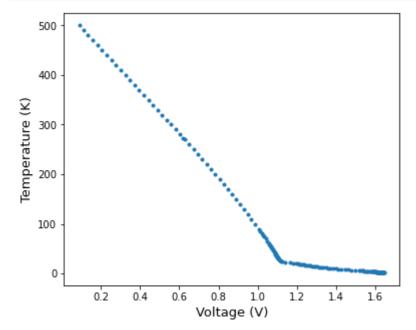
```
dat=np.loadtxt('lakeshore.txt')
```

In [96]:

```
v=np.array([i[1] for i in dat])
t=np.array([i[0] for i in dat])
```

In [97]:

```
plt.figure(figsize=(6,5))
plt.plot(v,t,'.')
plt.xlabel(r'Voltage (V)',fontsize=13)
plt.ylabel(r'Temperature (K)',fontsize=13)
plt.show()
```



We can note that voltages are ordered from the highest to the lowest

```
In [98]:
```

```
v[0]-v[1]
```

Out[98]:

0.0013000000000000789

To define the lakeshore routine we must identify if the entry V is an array or a single value (a float), so I used the format command whose output is a string with the content of the input. If the input on format (v) is an array it will return a string as follows: [1st element 2nd element ...]'; and: 'element', for a float or other. Thus, if format(i)[0]== '[', the lakeshore routine must compute the interpolation for every element of the array.

The routine works as follows:

temp[... vol[len(vol)-1]
... Every (vol[i], temp[i]) are the data in the lake chare. txt cile lake shore. txt file vol[1] Vol

L> The interpolation method used was to fit a cubic polynomial considering four points of the data set, i.e., (vol[i-1], temp[i-1]), (vol [i], temp[i]), (vol[i+1], temp[i+1]), and (vol[i+2], temp[i+2]). Therefore,

However, the cubic fit is made when the voltage v is - V (the input) must be between vol [iti] and Vol [i] (considering vol [i+1] <vol[i]) in the following intervals:

vol[2] & V < Vol[1]; Vol[3] & V < Vol[2]; ...; Vol[len(vol)-2] & V < Vol[len(vol)-3].

Then, if vol [1] < V < vol E0] (or just set as V z vol [1] in my code) a linear polynomial fit is considered taking (Vol [1], temp [1]) and (Vol [0], temp [0]). On the other hand, when vol [len (Vol)-1] < V < Nol [len (Vol)-2] (just V < Vol [len (Vol)-2] in the code) a linear fit is considered taking the data points with indexes len (vol) -1 and len(vol) -2. That linear fits are considered at the borders because he cannot consider the bata points with indexes i-1 to i+2 since we would be out of the range of the data points.

Before returning the temperature interpoled using the polynomial fit I checked if that temperature is 40. When a regative temperature occurred, I just changed it to be o.

Finally, for the absolute error estimation I took the polynomial fit P and obtained the following absolute errors: err1=1P(volini)-templifi); err2 = | P(vol[i]) - temp[i] |. So the error that the routine returns is err1 + errz

In [102]:

```
#Below the lakeshore routine is defined following the description on the previous page.
def lakeshore(V,data):
    vol=np.array([i[1] for i in dat])
    #taking the voltage and temperature from the document
    temp=np.array([i[0] for i in dat])
    v_final=[]
    err=[]
    if format(V)[0]=='[': #to identify if it is an array or not
        for j in V: #if the input is an array
            for i in range(1,len(vol)-2):
                if vol[i+1]<=j<vol[i]:</pre>
                    #third order polynomial fit
                    p3=np.polyfit(vol[i-1:i+3],temp[i-1:i+3],3)
                    v_final.append(np.polyval(p3,j)) # V value
                    err1=np.abs(np.polyval(p3,vol[i+1])-temp[i+1])
                    err2=np.abs(np.polyval(p3,vol[i])-temp[i])
                    #estimation of the error (err1+err2)/2
                    err.append(np.mean([err1,err2]))
                else:
                    continue
            if j<vol[len(vol)-2]: #lower values using linear fit</pre>
                p1=np.polyfit(vol[len(vol)-2:len(vol)],temp[len(vol)-2:len(vol)],1)
                v_final.append(np.polyval(p1,j))
                err1=np.abs(np.polyval(p1,vol[len(vol)-2])-temp[len(vol)-2])
                err2=np.abs(np.polyval(p1,vol[len(vol)-1])-temp[len(vol)-1])
                err.append(np.mean([err1,err2]))
            elif j>=vol[1]: #larger values using linear fit
                p1=np.polyfit(vol[0:2],temp[0:2],1)
                v_final.append(np.polyval(p1,j))
                err1=np.abs(np.polyval(p1,vol[0])-temp[0])
                err2=np.abs(np.polyval(p1,vol[1])-temp[1])
                err.append(np.mean([err1,err2]))
        for k in range(len(v_final)): # turn to 0 negative outputs
            if v_final[k]<0:</pre>
                v final[k]=0
                #estimation of the error taking the lowest temperature in the dataset
                err[k]=np.abs(0-temp[0])
        return np.array(v final),np.array(err)
    for i in range(1,len(vol)-2): #if the input is a float
        if vol[i+1]<=V<vol[i]:</pre>
            p3=np.polyfit(vol[i-1:i+3],temp[i-1:i+3],3)
            err1=np.abs(np.polyval(p3,vol[i+1])-temp[i+1])
            err2=np.abs(np.polyval(p3,vol[i])-temp[i])
            if np.polyval(p3,V)<0: # turn to 0 negative outputs
                err1=np.abs(0-temp[i+1])
                err2=np.abs(0-temp[i])
                return 0,np.mean([err1,err2])
            return np.polyval(p3,V), np.mean([err1,err2])
        else:
            continue
    if V<vol[len(vol)-2]: #lower values using linear fit</pre>
        p1=np.polyfit(vol[len(vol)-2:len(vol)],temp[len(vol)-2:len(vol)],1)
        err1=np.abs(np.polyval(p1,vol[len(vol)-2])-temp[len(vol)-2])
        err2=np.abs(np.polyval(p1,vol[len(vol)-1])-temp[len(vol)-1])
        if np.polyval(p1,V)<0: # turn to 0 negative outputs</pre>
```

```
err1=np.abs(0-temp[len(vol)-2])
    err2=np.abs(0-temp[len(vol)-1])
    return 0,np.mean([err1,err2])

return np.polyval(p1,V),np.mean([err1,err2])

elif V>=vol[1]: #larger values using linear fit
    p1=np.polyfit(vol[0:2],temp[0:2],1)
    err1=np.abs(np.polyval(p1,vol[0])-temp[0])
    err2=np.abs(np.polyval(p1,vol[1])-temp[1])
    if np.polyval(p1,V)<0: # turn to 0 negative outputs
        err1=np.abs(0-temp[0])
        return 0,np.mean([err1])

return np.polyval(p1,V),np.mean([err1,err2])</pre>
```

Let's test the routine. First, for a float V = 1.3V

In [103]:

```
lakeshore(1.3,dat)
```

Out[103]:

```
(13.702570519806386, 2.8421709430404007e-13)
```

Now using an array of values $V \in [0.001, 1.7]V$

In [104]:

```
v1=np.linspace(0.001,1.7,10001)
```

predv will be our interpolation and err our error estimation.

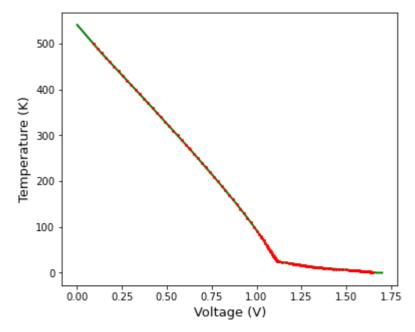
In [105]:

```
predv,err=lakeshore(v1,dat)
```

A plot to compare our interpolation with the data points.

In [106]:

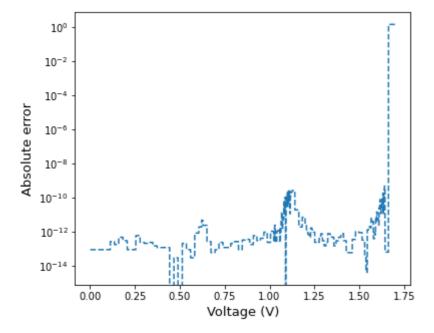
```
plt.figure(figsize=(6,5))
plt.plot(v1,predv,'-',color='green',linewidth=2)
plt.plot(v,t,'.',color='red',markersize=4)
plt.xlabel(r'Voltage (V)',fontsize=13)
plt.ylabel(r'Temperature (K)',fontsize=13)
plt.show()
```



It seems that the interpolation agrees pretty well with the data points. Now let's see the estimated error.

In [107]:

```
plt.figure(figsize=(6,5))
plt.plot(v1,err,'--')
plt.yscale('log')
plt.xlabel(r'Voltage (V)',fontsize=13)
plt.ylabel(r'Absolute error',fontsize=13)
plt.show()
```



The error seems to have a mean value of about $\sim 10^{-13}-10^{12}$. This error should become constant if we pick values larger enough than vol[0], because at some point the linear fit of the border becomes a negative value and the routine turn the extrapolated (and not interpolated in this especific case) temperature to 0. At that point the error becomes very large and the routine cannot give a good approximation.

Problem 4

First, we must define the numerator a denominator order for the rational fit because we will need n+m+1 data points to solve the coefficients. In especific, we will consider a rational fit of the form $f(x) \approx \frac{P(x)}{1+Q(x)}$ and the amount of coefficients must be =length of data=n+m+1 to have a square matrix and can do the inverse.

In [108]:

```
from scipy import interpolate as interp
```

In [109]:

```
nc=5 #numerator order
mc=6 #denominator order
```

(xc,yc) are the points to do an interpolation of cos(x)

```
In [110]:
```

```
xc=np.linspace(-np.pi/2,np.pi/2,nc+mc+1)
yc=np.cos(xc)
```

(xx,yy) are the points to evaluate the interpolations.

```
In [111]:
```

```
xx=np.linspace(-np.pi/2,np.pi/2,1001)
yy=np.cos(xx)
```

For the polynomial fit we set an (n+m)th grade polynomial

```
In [112]:
```

```
polyc=np.polyfit(xc,yc,nc+mc)
ypoly=np.polyval(polyc,xx)
```

The splines interpolation makes a cubic polynomial fit for every point and set the second derivatives to be continuous. I just used the spl interpolation from scipy.

```
In [113]:
```

```
spl=interp.splrep(xc,yc)
yspl=interp.splev(xx,spl)
```

I defined the routine ratfit to make the rational interpolation and ratev to evaluate it.

In [114]:

```
def ratfit(x,y,n,m):
    #polynomial evaluation of the points for the numerator
    pcols=[x**k for k in range(n+1)]
    pmat=np.vstack(pcols)

#polynomial evaluation of the points for the denominator
    qcols=[-x**k*y for k in range(1,m+1)]
    qmat=np.vstack(qcols)
    mat=np.hstack([pmat.T,qmat.T]) #matrix

coeffs=np.linalg.inv(mat)@y #solving the coefficients

pc=coeffs[:n+1]
    qc=coeffs[n+1:]

return pc,qc
```

In [115]:

```
def ratev(x,p,q):
    pp=0
    for i in range(len(p)):
        pp+=p[i]*(x**i)
    qq=1
    for i in range(len(q)):
        qq+=q[i]*(x**(i+1))
    return pp/qq
```

In [116]:

```
pc,qc=ratfit(xc,yc,nc,mc)
yrat=ratev(xx,pc,qc)
```

In [117]:

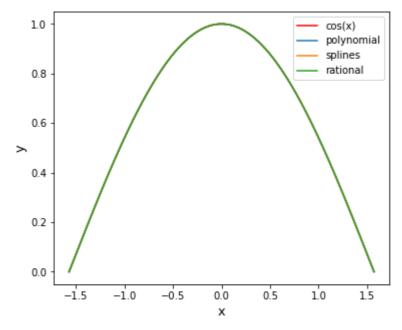
```
pc,qc
```

Out[117]:

Some coefficients are very close to 0.

In [118]:

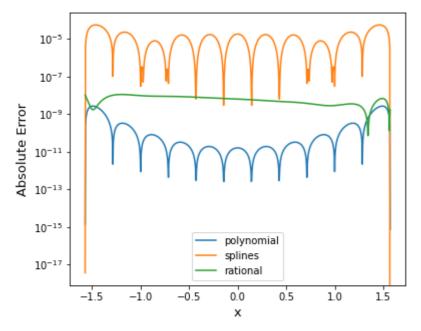
```
plt.figure(figsize=(6,5))
plt.plot(xx,yy,label='cos(x)', color='red')
plt.plot(xx,ypoly,label='polynomial')
plt.plot(xx,yspl,label='splines')
plt.plot(xx,yrat,label='rational')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'y',fontsize=13)
plt.legend()
plt.show()
```



All the interpolations are very similar to the function. Let's see the absolute error.

In [119]:

```
plt.figure(figsize=(6,5))
plt.plot(xx,np.abs(ypoly-yy),label='polynomial')
plt.plot(xx,np.abs(yspl-yy),label='splines')
plt.plot(xx,np.abs(yrat-yy),label='rational')
plt.yscale('log')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'Absolute Error',fontsize=13)
plt.legend()
plt.show()
```



The error in the rational fit is almost constant, while it oscillates for the splines and polynomial

Now I tried the same for $\frac{1}{1+x^2}$

In [120]:

```
n1=2
m1=3
```

```
In [121]:
```

```
xl=np.linspace(-1,1,nl+ml+1)
yl=1/(1+xl**2)
```

In [122]:

```
xx2=np.linspace(-1,1,1001)
yy2=1/(1+xx2**2)
```

In [123]:

```
polyl=np.polyfit(xl,yl,nl+ml)
ypolyl=np.polyval(polyl,xx2)
```

In [124]:

```
spll=interp.splrep(x1,y1)
yspll=interp.splev(xx,spl)
```

In [125]:

```
pl,ql=ratfit(x1,y1,n1,m1)
yratl=ratev(xx2,p1,q1)
```

In [126]:

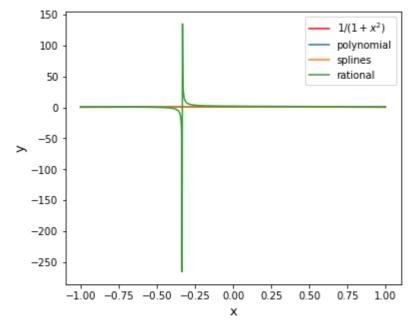
```
pl,ql
```

Out[126]:

```
(array([1.92307692, 4. , 0.02776841]), array([3., 1., 3.]))
```

In [127]:

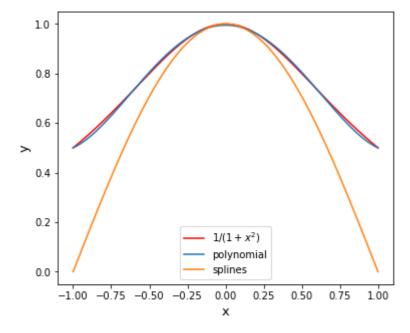
```
plt.figure(figsize=(6,5))
plt.plot(xx2,yy2,color='red',label='$1/(1+x^{2})$')
plt.plot(xx2,ypolyl,label='polynomial')
plt.plot(xx2,yspll,label='splines')
plt.plot(xx2,yratl,label='rational')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'y',fontsize=13)
plt.legend()
plt.show()
```



It seems like the rational fit is not very well because of some points are very out of the distribution when doing the interpolation. So we will take the rational interpolation out of the plot.

In [128]:

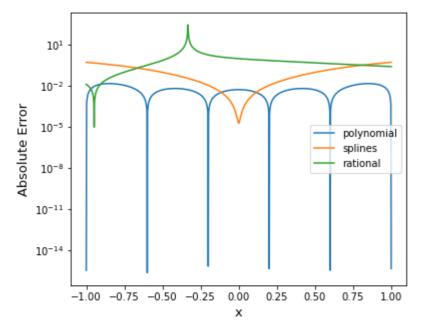
```
plt.figure(figsize=(6,5))
plt.plot(xx2,yy2,color='red',label='$1/(1+x^{2})$')
plt.plot(xx2,ypolyl,label='polynomial')
plt.plot(xx2,yspll,label='splines')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'y',fontsize=13)
plt.legend()
plt.show()
```



The polynomial fit is the best case. Let's see the errors.

In [129]:

```
plt.figure(figsize=(6,5))
plt.plot(xx2,np.abs(ypolyl-yy2),label='polynomial')
plt.plot(xx2,np.abs(yspl1-yy2),label='splines')
plt.plot(xx2,np.abs(yratl-yy2),label='rational')
plt.yscale('log')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'Absolute Error',fontsize=13)
plt.legend()
plt.show()
```



Now I tried a rational fit with n=4 and m=5

In [130]:

```
nll=4
mll=5
```

In [131]:

```
xll=np.linspace(-1,1,nll+mll+1)
yll=1/(1+xll**2)
```

In [132]:

```
pll,qll=ratfit(xll,yll,nll,mll)
yratll=ratev(xx2,pll,qll)
```

In [133]:

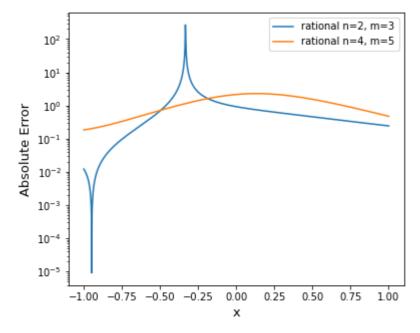
```
pll,qll
```

Out[133]:

```
(array([-1.15426343, -2. , 2. , 1.5 , -0.16231439]), array([0. , 3. , 1. , 1.5 , 0.75]))
```

In [134]:

```
plt.figure(figsize=(6,5))
plt.plot(xx2,np.abs(yratl-yy2),label='rational n=2, m=3')
plt.plot(xx2,np.abs(yratll-yy2),label='rational n=4, m=5')
plt.yscale('log')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'Absolute Error',fontsize=13)
plt.legend()
plt.show()
```



It seems like the error is less than before at some points but is not enough because is still ~ 1 . Then, changing linalg.inv to linalg.pinv this error could be reduced because linalg.pinv uses the pseudo-inverse of the matrix, and then it will work even when a row becomes near to 0.

In [135]:

```
def ratfit2(x,y,n,m):
    pcols=[x**k for k in range(n+1)]
    pmat=np.vstack(pcols)

    qcols=[-x**k*y for k in range(1,m+1)]
    qmat=np.vstack(qcols)
    mat=np.hstack([pmat.T,qmat.T])

    coeffs=np.linalg.pinv(mat)@y

    pc=coeffs[:n+1]
    qc=coeffs[n+1:]

    return pc,qc
```

```
In [136]:
```

```
plk,qlk=ratfit2(xll,yll,nll,mll)
yratlk=ratev(xx2,plk,qlk)
```

In [137]:

```
pll,qll
```

Out[137]:

```
(array([-1.15426343, -2. , 2. , 1.5 , -0.16231439]), array([0. , 3. , 1. , 1.5 , 0.75]))
```

In [138]:

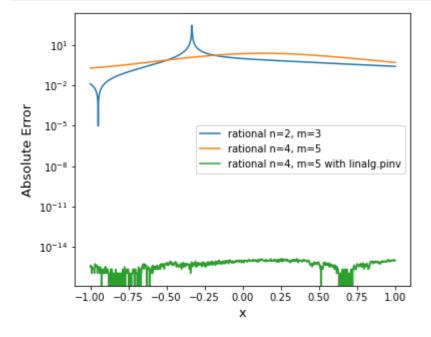
```
plk,qlk
```

Out[138]:

We can note that in the case using linalg.ing some coefficients are overestimated, but with linalg.pinv just a few coefficients are large enough and the others are ~ 0 . Let's see the error.

In [139]:

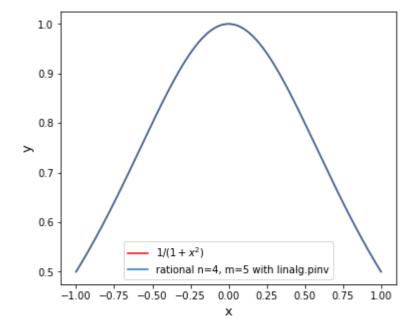
```
plt.figure(figsize=(6,5))
plt.plot(xx2,np.abs(yratl-yy2),label='rational n=2, m=3')
plt.plot(xx2,np.abs(yratll-yy2),label='rational n=4, m=5')
plt.plot(xx2,np.abs(yratlk-yy2),label='rational n=4, m=5 with linalg.pinv')
plt.yscale('log')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'Absolute Error',fontsize=13)
plt.legend()
plt.show()
```



We can note that using linal.pinv the error in the interpolation is reduced to $< 10^{-14}$

In [140]:

```
plt.figure(figsize=(6,5))
plt.plot(xx2,yy2,color='red',label='$1/(1+x^{2})$')
plt.plot(xx2,yratlk,label='rational n=4, m=5 with linalg.pinv')
plt.xlabel(r'x',fontsize=13)
plt.ylabel(r'y',fontsize=13)
plt.legend()
plt.show()
```



In []: