# **Report Generated by Test Manager**

Title: Test

Author: MCBTI

Date: 30-Sep-2025 14:12:15

## **Test Environment**

Platform: GLNXA64 MATLAB: (R2025a)

## Summary

Name	Outcome	Duration (Seconds)
Results: 2025-Sep-30 14:10:04	3 🕗	3.944
MOT_CTRL-MOT-FUN	3 🕗	3.708
MOT_CTRL-MOT-FUN-001	<b>Ø</b>	1.337
MOT CTRL-MOT-FUN-002	<b>Ø</b>	1.105
■ MOT_CTRL-MOT-FUN-003	•	1.07

## Results: 2025-Sep-30 14:10:04

Result Type: Result Set
Parent: None

Start Time: 30-Sep-2025 14:10:04 End Time: 30-Sep-2025 14:10:08 Outcome: Total: 3, Passed: 3

**Back to Report Summary** 

## **MOT\_CTRL-MOT-FUN**

#### **Test Result Information**

Result Type: Test Suite Result

Parent: Results: 2025-Sep-30 14:10:04

Start Time: 30-Sep-2025 14:10:04 End Time: 30-Sep-2025 14:10:07 Outcome: Total: 3, Passed: 3

#### **Test Suite Information**

Name: MOT\_CTRL-MOT-FUN

**Back to Report Summary** 

## MOT\_CTRL-MOT-FUN-001

#### **Test Result Information**

Result Type: Test Case Result

Parent: <u>MOT\_CTRL-MOT-FUN</u>
Start Time: 30-Sep-2025 14:10:04
End Time: 30-Sep-2025 14:10:05

Outcome: Passed

Description:

Esse modelo implementa o teste de relação entre tensão de alimentação da armadura do motor e velocidade angular no eixo.

#### **Test Case Information**

Name: MOT\_CTRL-MOT-FUN-001

Type: Baseline Test

## **Logical and Temporal Assessments**

Name	Assessment
✓ VoltageSpeedRela	At any point in time, whenever (t > 1.0001) is true then, with no delay, (result_sim == true) must be true
tionship	REQUIREMENTS  Description: MOT_CTRL-MOT-FUN-001 Relação crescente entre tensão e velocidade angular  Document: MOT_CTRL_MOT.slreqx

#### **Simulation**

### **System Under Test Information**

Model: DcMotorSimulink

Harness: MOT\_CTRL\_MOT\_FUN\_001

Harness Owner: DcMotorSimulink

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: Configuration1

Start Time: 0 Stop Time: 10

Checksum: 1288080609 30892339 3360627314 3034279594

Simulink Version: 25.1 Model Version: 1.11

Model Author: tecnicomcbti

Date: Tue Sep 30 13:39:05 2025

User ID: tecnicomcbti

Model Path: /home/tecnicomcbti/cursoMBD/

model\_based\_design\_with\_real\_time\_hardware\_t

esting/Tests/DcMotor/

MOT\_CTRL\_MOT\_FUN\_001.slx

Solver Name: ode3

Solver Type: Fixed-Step

0.0001

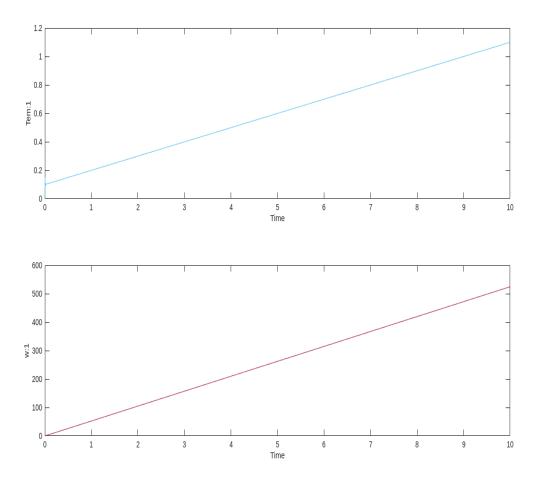
Fixed Step Size: Simulation Start Time: 2025-09-30 14:10:04 Simulation Stop Time: 2025-09-30 14:10:05

Platform: GLNXA64

## **Simulation Output**

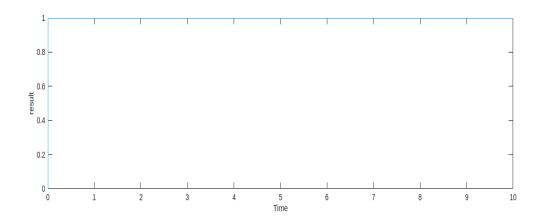
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
Tem:1	double		0.0001	linear	union	<u>Link</u>
w:1	double		0.0001	linear	union	<u>Link</u>
result	boolean		0.0001	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
Tem:1	double		0.0001	linear	union
w:1	double		0.0001	linear	union



Back to Report SummaryBack to Signal Summary

Name	Data Type	Units	Sample Time	Interp	Sync
result	boolean	İ	0.0001	zoh	union



## Back to Report SummaryBack to Signal Summary

Test Logs: No baseline criteria evaluation performed as no baseline data is available for this test.

**Back to Report Summary** 

## MOT\_CTRL-MOT-FUN-002

#### **Test Result Information**

Result Type: Test Case Result

Parent: <u>MOT\_CTRL-MOT-FUN</u>
Start Time: 30-Sep-2025 14:10:05
End Time: 30-Sep-2025 14:10:06

Outcome: Passed

Description:

Verifica se o tempo de resposta do modelo à um degrau satisfaz as condições estabelecidas no requisito MOT\_CTRL-MOT-FUN-002.

#### **Test Case Information**

Name: MOT CTRL-MOT-FUN-002

Type: Baseline Test

### **Logical and Temporal Assessments**

Name	Assessment
	At any point in time, whenever (t > 1.25) is true then, with no delay, (result_simulation == tr ue) must be true
StepResponse	REQUIREMENTS
	Description: MOT_CTRL-MOT-FUN-002 Tempo de resposta do motor a um degrau de tensão
	Document: MOT_CTRL_MOT.slreqx

#### Simulation

## **System Under Test Information**

Model: DcMotorSimulink

Harness: MOT\_CTRL\_MOT\_FUN\_002

Harness Owner: DcMotorSimulink

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: Configuration1

Start Time: 0 Stop Time: 10

Checksum: 1585255872 1921972682 835149912 839820370

Simulink Version: 25.1 Model Version: 1.19

Model Author: tecnicomcbti

Date: Tue Sep 30 14:02:47 2025

User ID: tecnicomcbti

Model Path: /home/tecnicomcbti/cursoMBD/

model\_based\_design\_with\_real\_time\_hardware\_t

esting/Tests/DcMotor/

MOT\_CTRL\_MOT\_FUN\_002.slx

Solver Name: ode3
Solver Type: Fixed-Step
Fixed Step Size: 0.0001

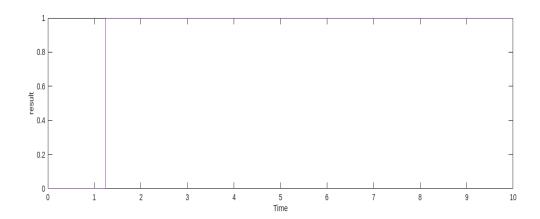
Simulation Start Time: 2025-09-30 14:10:05 Simulation Stop Time: 2025-09-30 14:10:06

Platform: GLNXA64

**Simulation Output** 

Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
result	boolean		0.0001	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
result	boolean		0.0001	zoh	union



## Back to Report SummaryBack to Signal Summary

Test Logs: No baseline criteria evaluation performed as no baseline data is available for this test.

**Back to Report Summary** 

## MOT\_CTRL-MOT-FUN-003

#### **Test Result Information**

Result Type: Test Case Result

Parent: <u>MOT\_CTRL-MOT-FUN</u>
Start Time: 30-Sep-2025 14:10:06
End Time: 30-Sep-2025 14:10:07

Outcome: Passed

Description:

Verifica se a velocidade do motor, em regime estacionário, está dentro dos limites para todas as condições de entrada.

### **Test Case Information**

Name: MOT CTRL-MOT-FUN-003

Type: Baseline Test

## **Logical and Temporal Assessments**

Name	Assessment
	At any point of time, (result_sim == true) must be true
CheckSpeedRange	REQUIREMENTS
Checkspeedkange	Description: MOT_CTRL-MOT-FUN-003 Limite operacional da velocidade angular
	Document: MOT_CTRL_MOT.slreqx

#### **Simulation**

### **System Under Test Information**

Model: DcMotorSimulink

Harness: MOT\_CTRL\_MOT\_FUN\_003

Harness Owner: DcMotorSimulink

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: Configuration1

Start Time: 0 Stop Time: 10

Checksum: 1549691848 2576098024 1622333415 2151603663

Simulink Version: 25.1 Model Version: 1.16

Model Author: tecnicomcbti

Date: Tue Sep 30 14:09:52 2025

User ID: tecnicomcbti

Model Path: /home/tecnicomcbti/cursoMBD/

model\_based\_design\_with\_real\_time\_hardware\_t

esting/Tests/DcMotor/

MOT\_CTRL\_MOT\_FUN\_003.slx

Solver Name: ode3

Solver Type: Fixed-Step Fixed Step Size: 0.0001

 Simulation Start Time:
 2025-09-30 14:10:06

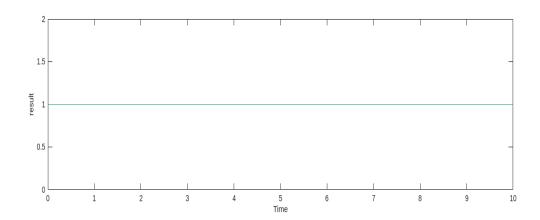
 Simulation Stop Time:
 2025-09-30 14:10:07

Platform: GLNXA64

**Simulation Output** 

ı	Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
	result	boolean		0.0001	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
result	boolean		0.0001	zoh	union



## Back to Report SummaryBack to Signal Summary

Test Logs: No baseline criteria evaluation performed as no baseline data is available for this test.

**Back to Report Summary**