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Title: Four plots for SVMs

The general form of the mathematics for a linear support vector machine are quite straightforward.

Support Vector Machines are Supervised tools.

SEE: https://rpubs.com/mzc/mlwr svm concrete (https://rpubs.com/mzc/mlwr svm concrete)

Therefore, given a set of labeled pairs of data:

$$(x_i, y_i), i = 1, ..., l$$
 where $x_i \in R^n$ and $y \in \{1, -1\}^l$

Such that
$$f(x_i) = \left\{ \begin{array}{l} \geq 0; \ y_i = 1 \\ < 0; \ y_i = -1 \end{array} \right\}$$

where y is a set of two values which indicate a label, e.g. true or false.

$$\min \frac{1}{2} W^T W + C \sum_{i=1}^{l} \xi_i$$

subject to
$$y_i(w^T\phi(x_i) + b) \ge (1 - \xi_i)$$
 where $\xi_i \ge 0$,

C is the penalty parameter, *cost*, of the error term, such that C > 0.

Furthermore, $K(x_i, x_i) = \phi(x_i)^T \phi(x_i)$ is called the kernel function.

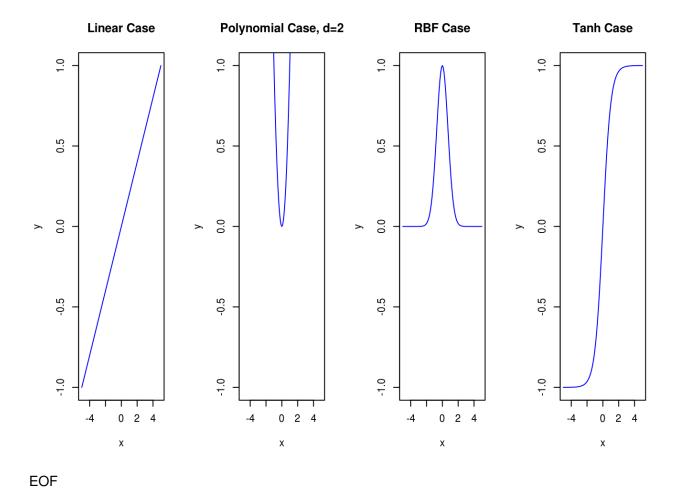
The 4 most common SVM formulae are:

- 1. Linear: $K(x_i, y_i) = \langle x, y \rangle$
 - o The linear kernel does not transform the data at all.
- 2. Polynomial: $K(x_i, x_j) = (\gamma x_i^T x_j + r)^d, \gamma > 0$
 - The polynomial kernel has a simple non-linear transform of the data.
- 3. Radial Basis Function (RBF): $K(x_i, x_j) = exp(-\gamma \|x_i^T x_j\|^2), \ \gamma > 0$
 - The Guassian RBF kernel which performs well on many data and is a good default
- 4. Sigmoid: $K(x_i, x_j) = \tanh(\gamma x_i^T x_j + r), \gamma > 0$
 - The sigmoid kernel produces a SVM analogous to the activation function similar to a perceptron (https://cs.stanford.edu/people/eroberts/courses/soco/projects/neural-networks /Neuron/index.html) with a sigmoid activation function.¹
- Such that γ , r and d are kernel parameters.

There are no reliable rules for which kernel to use with any given data set.

Plots for 4 most common SVM formulae:

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1. https://rpubs.com/mzc/mlwr_svm_concrete (https://rpubs.com/mzc/mlwr_svm_concrete)↔