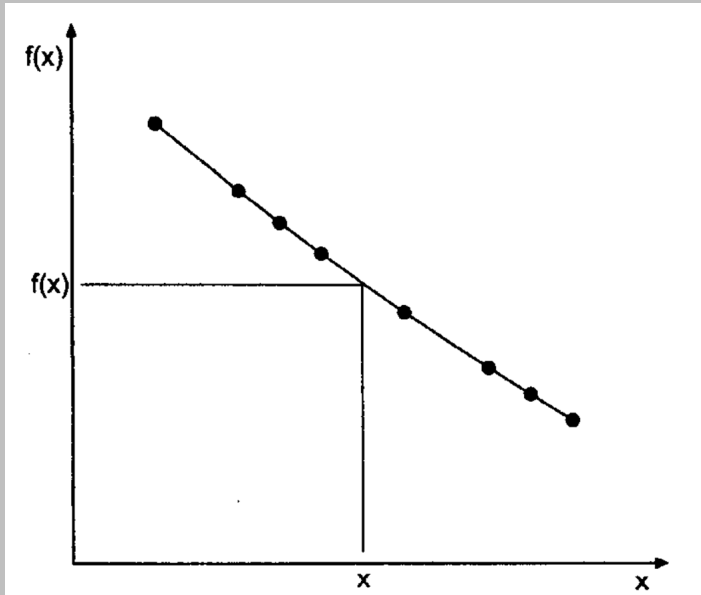


Polynomial Approximation

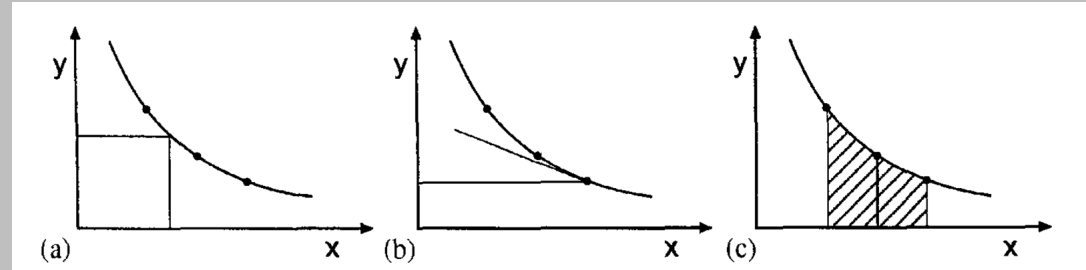
Determination of $f(x)$ at point x not on **discrete** data points

Interpolation- x **inside** the interval of data points

Extrapolation - x **outside** the interval of data points



Differentiation and Integration



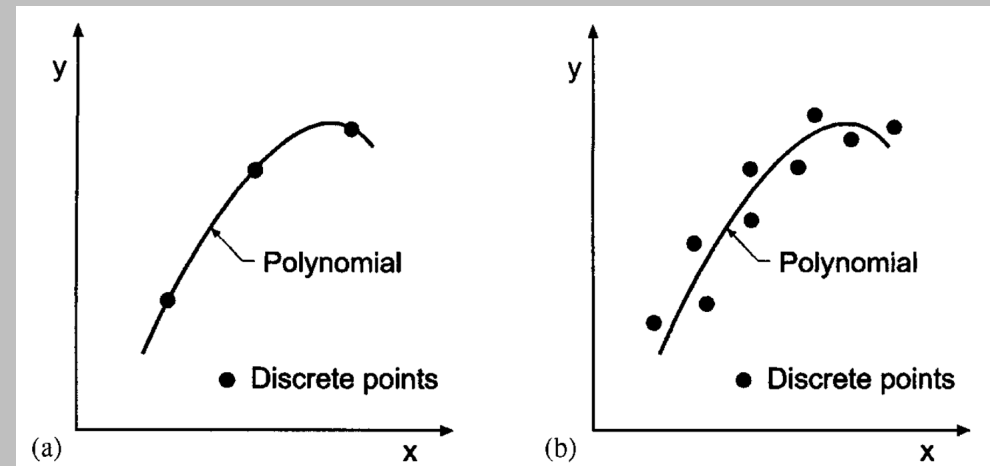
Polynomial Fits

Exact Fit

Direct
Lagrange

Approximate Fits

Cubic Spline
Least Square Approximation



Polynomials

Polynomial $P_n(x)$ of n th degree has $(n + 1)$ coefficients in the form

$$P_n(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

For a given x , how many operations to determine $P_n(x)$ from above polynomial?

Nested operations- by **successive factorization**, $P_n(x)$ written as

$$P_n(x) = a_0 + x(a_1 + x(a_2 + x(a_3 + \dots + x(a_{n-1} + a_nx))))$$

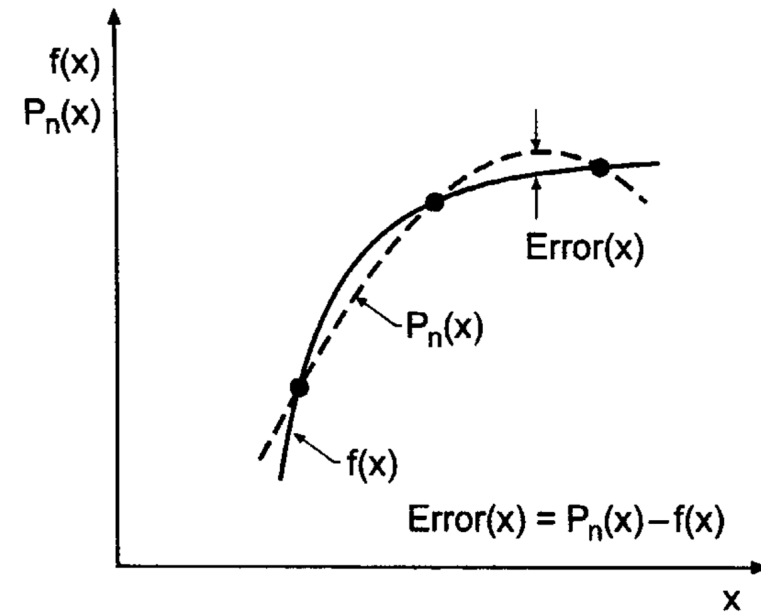
For a given x , how many operations to determine $P_n(x)$ from above nested polynomial?

Weierstrass Theorem

For any small ε , there exist a **positive integer** N such that a smooth function $f(x)$ in interval $[a, b]$ can be approximated by a polynomial of degree N

$$|f(x) - P_N(x)| < \varepsilon$$

Approximation Error



With $(n + 1)$ discrete data points $(x_i, f(x_i))$, $P_n(x)$ can be found that passes through all $(n + 1)$ points with $x = x_i$,

$$P_n(x_i) = f(x_i)$$

When $x \neq x_i$, $P_n(x)$ will approximate $f(x)$ with error

$$P_n(x) - f(x) = \frac{1}{n+1} (x - x_0)(x - x_1)(x - x_2) \dots (x - x_n) f^{n+1}(\xi)$$

$$x_0 < \xi < x_n$$

Direct Fit

With $(n + 1)$ discrete data points $(x_i, f(x_i))$, an n th order polynomial $P_n(x)$ can be specified that exactly fits all $(n + 1)$ points.

To specify $P_n(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$, the $(n + 1)$ unknown coefficients $(a_0, a_1 \dots a_n)$ can be determined

$$\begin{cases} a_0 + a_1x_0 + a_2x_0^2 + a_3x_0^3 + \dots + a_nx_0^n = f(x_0) \\ a_0 + a_1x_1 + a_2x_1^2 + a_3x_1^3 + \dots + a_nx_1^n = f(x_1) \\ a_0 + a_1x_2 + a_2x_2^2 + a_3x_2^3 + \dots + a_nx_2^n = f(x_2) \\ \vdots \\ a_0 + a_1x_n + a_2x_n^2 + a_3x_n^3 + \dots + a_nx_n^n = f(x_n) \end{cases}$$

Vector notation

$$a = [a_0, a_1, a_2, \dots, a_n]^T$$

$$G = \begin{bmatrix} 1 & x_0^1 & x_0^2 & x_0^3 & \dots & x_0^n \\ 1 & x_1^1 & x_1^2 & x_1^3 & \dots & x_1^n \\ 1 & x_2^1 & x_2^2 & x_2^3 & \dots & x_2^n \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n^1 & x_n^2 & x_n^3 & \dots & x_n^n \end{bmatrix}$$

$$F = [f(x_0), f(x_1), f(x_2), \dots, f(x_n)]^T$$

$$Ga = F$$

Lagrange Polynomials

Passing a polynomial through $(n + 1)$ points

Two-point fit (x_1, f_1) and (x_2, f_2)

$$f(x) = \frac{x-x_2}{x_1-x_2}f_1 + \frac{x-x_1}{x_2-x_1}f_2 = P_2(x)$$

Three-point fit $(x_1, f_1), (x_2, f_2), (x_3, f_3)$

$$f(x) = \frac{x-x_2}{x_1-x_2} \frac{x-x_3}{x_1-x_3} f_1 + \frac{x-x_1}{x_2-x_1} \frac{x-x_3}{x_2-x_3} f_2 + \frac{x-x_1}{x_3-x_1} \frac{x-x_2}{x_3-x_2} f_3 = P_3(x)$$

Determine $P_n(x)$ that passes through 3 points

$(0,1); (1, 0.75); (2,0)$

Lagrange Polynomials

Passing a polynomial through (n) points

n -point fit

$$P_{n-1}(x) = \frac{(x-x_2)(x-x_3)(x-x_4) \dots (x-x_n)}{(x_1-x_2)(x_1-x_3)(x_1-x_4) \dots (x_1-x_n)} f_1 \\ + \frac{(x-x_1)(x-x_3)(x-x_4) \dots (x-x_n)}{(x_2-x_1)(x_2-x_3)(x_2-x_4) \dots (x_2-x_n)} f_2 + \\ + \frac{(x-x_1)(x-x_2)(x-x_4) \dots (x-x_n)}{(x_3-x_1)(x_3-x_2)(x_3-x_4) \dots (x_3-x_n)} f_3 + \\ \dots \dots \dots + \frac{(x-x_1)(x-x_2)(x-x_3) \dots (x-x_{n-1})}{(x_n-x_1)(x_n-x_2)(x_n-x_3) \dots (x_n-x_{n-1})} f_n$$

No of operations

Lagrange

Direct method

Gauss-Seidel

Use Lagrange method for

$P_2(x)$ passing through 3 points

(0,1); (1, 0.75); (2,0)

Navielle Method

This a successive **linear** interpolation between **adjacent** points
With n points (x_k, f_k) ,

$$f_k^0 = f_k$$

With

$$f_k^1 = \frac{x-x_k}{x_{k+1}-x_k} f_{k+1}^0 + \frac{x-x_{k+1}}{x_k-x_{k+1}} f_k^0$$

And continuing

$$f_k^2 = \frac{x-x_k}{x_{k+1}-x_k} f_{k+1}^1 + \frac{x-x_{k+1}}{x_k-x_{k+1}} f_k^1$$

$$f_k^n = \frac{x-x_k}{x_{k+1}-x_k} f_{k+1}^{n-1} + \frac{x-x_{k+1}}{x_k-x_{k+1}} f_k^{n-1}$$

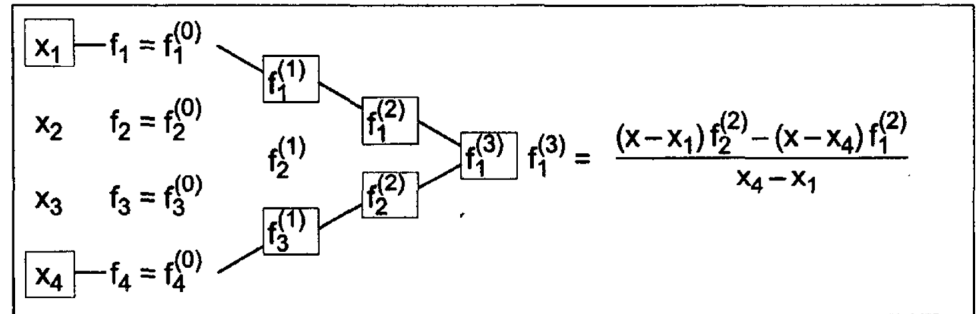
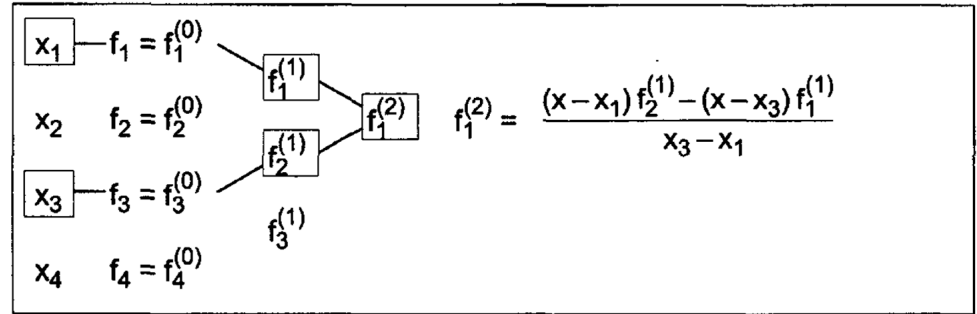
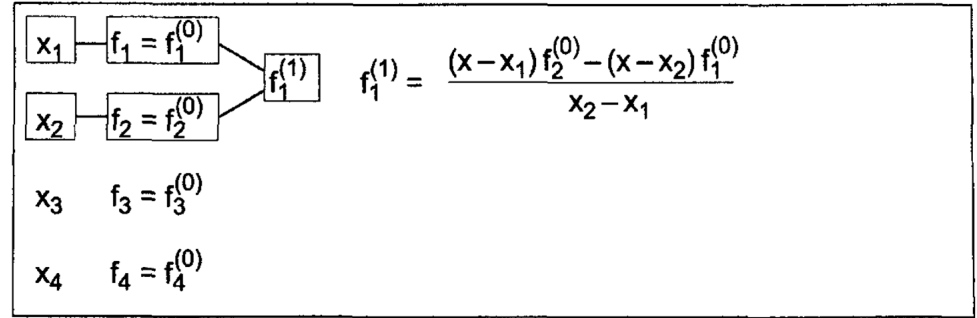
x_i	$f_i^{(0)}$	$f_i^{(1)}$	$f_i^{(2)}$	$f_i^{(3)}$
x_1	$f_1^{(0)}$			
x_2	$f_2^{(0)}$	$f_1^{(1)}$	$f_1^{(2)}$	
x_3	$f_3^{(0)}$	$f_2^{(1)}$	$f_2^{(2)}$	$f_1^{(3)}$
x_4	$f_4^{(0)}$	$f_3^{(1)}$		

$$f_k^n(x) = P_n(x)$$

Advantage:
No. of operations?

Determine $P_n(x)$ that
passes through 3 points

(0,1); (1, 0.75); (2,0)



Divided Difference Method

For $(n + 1)$ points (x_i, f_i) , with $f_i = f(x_i)$, the divided difference is the difference between the f value at two adjacent points divided by the distance between these two points.

Set f_i^o as the original values of f at x_i

$$f_i^o = f_i$$

The next set of divided difference f_i^1 will be

$$f_i^1 = \frac{f_{i+1}^o - f_i^o}{x_{i+1} - x_i}$$

And for k th iteration

$$f_i^{k+1} = \frac{f_{i+1}^k - f_i^k}{x_{i+1} - x_i}$$

At each step of differencing, number of points for next differencing will be reduced by one.

x_i	$f_i^{(0)}$	$f_i^{(1)}$	$f_i^{(2)}$	$f_i^{(3)}$
x_1	$f_1^{(0)}$			
x_2	$f_2^{(0)}$	$f_1^{(1)}$		
x_3	$f_3^{(0)}$	$f_2^{(1)}$	$f_1^{(2)}$	
x_4	$f_4^{(0)}$	$f_3^{(1)}$	$f_2^{(2)}$	$f_1^{(3)}$

Divided Difference Polynomial

Polynomial $P_n(x)$ can be constructed from divided difference values f_i^k

$$\begin{aligned} P_n(x) &= f_i^o + (x - x_o)f_i^1 + (x - x_o)(x - x_1)f_i^2 + \dots \\ &+ (x - x_o)(x - x_1)(x - x_3)\dots(x - x_n)f_i^n \end{aligned}$$

For any $(n + 1)$ points, $P_n(x)$ is unique. The polynomial above passes through all the points, so this expression is equal to Lagrange's.

Differencing

With equal spacing for all points, function f differences correspond to $\frac{df}{dx}$.

Successive differencing of two neighboring values: which neighbor to count for differencing method? Forward, backward or taking a half-step.

Forward differencing Δf_i :

$$\Delta f_i = f_{i+1} - f_i$$

Backward differencing ∇f_i

$$\nabla f_i = f_i - f_{i-1}$$

Centered differencing $\delta f_{i+1/2}$

$$\delta f_{i+1/2} = f_{i+1} - f_i$$

Table of differences

x	f	Δf	$\Delta^2 f$	$\Delta^3 f$
x_0	f_0	Δf_0		
x_1	f_1	Δf_1	$\Delta^2 f_0$	
x_2	f_2	Δf_2	$\Delta^2 f_1$	$\Delta^3 f_0$
x_3	f_3			

Starting from x_0

x	f	∇f	$\nabla^2 f$	$\nabla^3 f$
x_{-3}	f_{-3}			
x_{-2}	f_{-2}	∇f_{-2}	$\nabla^2 f_{-1}$	
x_{-1}	f_{-1}	∇f_{-1}	$\nabla^2 f_0$	$\nabla^3 f_0$
x_0	f_0	∇f_0		

Starting from x_n

x	f	δf	$\delta^2 f$	$\delta^3 f$
x_{-1}	f_{-1}	$\delta f_{-1/2}$		
x_0	f_0	$\delta f_{1/2}$	$\delta^2 f_0$	
x_1	f_1		$\delta^2 f_1$	$\delta^3 f_{1/2}$
x_2	f_2	$\delta f_{3/2}$		

Starting from middle

n - number of spacings

$$\Delta x = \frac{\text{len}_{(i-1) \ i \ i+1}}{\text{spacing}} = \frac{L}{n} = h$$

$$x_i = x_0 + i * h \text{ and } f_i = f(x_i)$$

$(n + 1)$ = number of nodes

Derivatives first second third

x	f(x)			
x_0	f_0			
x_1	f_1	$(f_1 - f_0)$	$(f_2 - 2f_1 + f_0)$	
x_2	f_2	$(f_2 - f_1)$	$(f_3 - 2f_2 + f_1)$	$(f_3 - 3f_2 + 3f_1 - f_0)$
x_3	f_3	$(f_3 - f_2)$		

Forward and backward differencing for 3 points

(0,1); (1, 0.75); (2,0)

Round-off errors in differencing

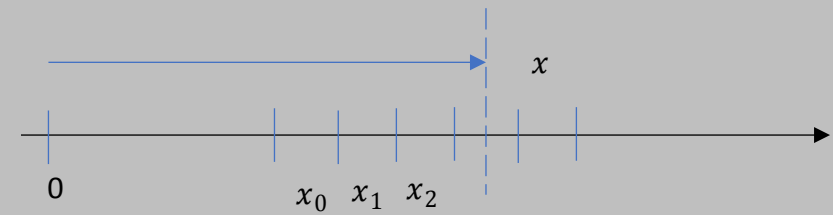
Max. round-off errors in n th derivative = $\pm 2^{n-1}$

x	f	Δf	$\Delta^2 f$	$\Delta^3 f$	$\Delta^4 f$
—	+1/2				
—	-1/2	-1	2		
—	+1/2	1	-2	-4	8
—	-1/2	-1	2	4	-8
—	+1/2	1	-2	-4	
—	-1/2	-1			

Watch out for round-off errors!

In similar manner constructed for Navielle method, $P_n(x)$ can be constructed from the difference tables and called **Newton Polynomials** that passes through $(n + 1)$ points.

Newton polynomials depends on the difference method, forward, backward and centered.



Newton Polynomials

With $x_i = x_o + ih$, we can define **s** instead of x

$$s = \frac{x - x_o}{h}$$

$$s_i = i$$

$$x = x_o + sh$$

Newton Forward Differencing Polynomials

$$P_n(x) = f_o + s\Delta f_o + \frac{s(s-1)}{2!}\Delta^2 f_o + \frac{s(s-1)(s-2)}{3!}\Delta^3 f_o + \dots + \frac{s(s-1)(s-2)\dots(s-n+1)}{n!}\Delta^n f_o$$

Or alternatively in terms of **binomial coefficients**

$$P_n(x) = f_o + \binom{s}{1}\Delta f_o + \binom{s}{2}\Delta^2 f_o + \binom{s}{3}\Delta^3 f_o + \dots + \binom{s}{n}\Delta^n f_o$$

With binomial coefficients defines as $\binom{s}{i} = \frac{s(s-1)(s-2)\dots(s-[i-1])}{i!}$

Newton Backward Differencing Polynomials

$$P_n(x) = f_o + s\nabla f_o + \frac{s(s+1)}{2!}\nabla^2 f_o + \frac{s(s+1)(s+2)}{3!}\nabla^3 f_o + \dots + \frac{s(s+1)(s+2)\dots(s+n-1)}{n!}\nabla^n f_o$$

Or alternatively in terms of **binomial coefficients**

$$P_n(x) = f_o + \binom{s+}{1}\nabla f_o + \binom{s+}{2}\nabla^2 f_o + \binom{s+}{3}\nabla^3 f_o + \dots + \binom{s+}{n}\nabla^n f_o$$

With binomial coefficients defines as $\binom{s+}{i} = \frac{s(s+1)(s+2)\dots(s+i-1)}{i!}$

Expressions for Newton Centered differencing polynomials use similar formulas.

Determine $P_n(x)$ that passes through 3 points using Newton backward differencing

$(0,1); (1, 0.75); (2,0)$