



GMAN: A Graph Multi-Attention Network for Traffic Prediction

Chuanpan Zheng¹, Xiaoliang Fan^{1*}, Cheng Wang¹, Jianzhong Qi²

¹Fujian Key Laboratory of Sensing and Computing for Smart Cities, Xiamen University, Xiamen, China

²School of Computing and Information Systems, University of Melbourne, Melbourne, Australia

zhengchuanpan@stu.xmu.edu.cn, {fanxiaoliang, cwang}@xmu.edu.cn, jianzhong.qi@unimelb.edu.au



Introduction

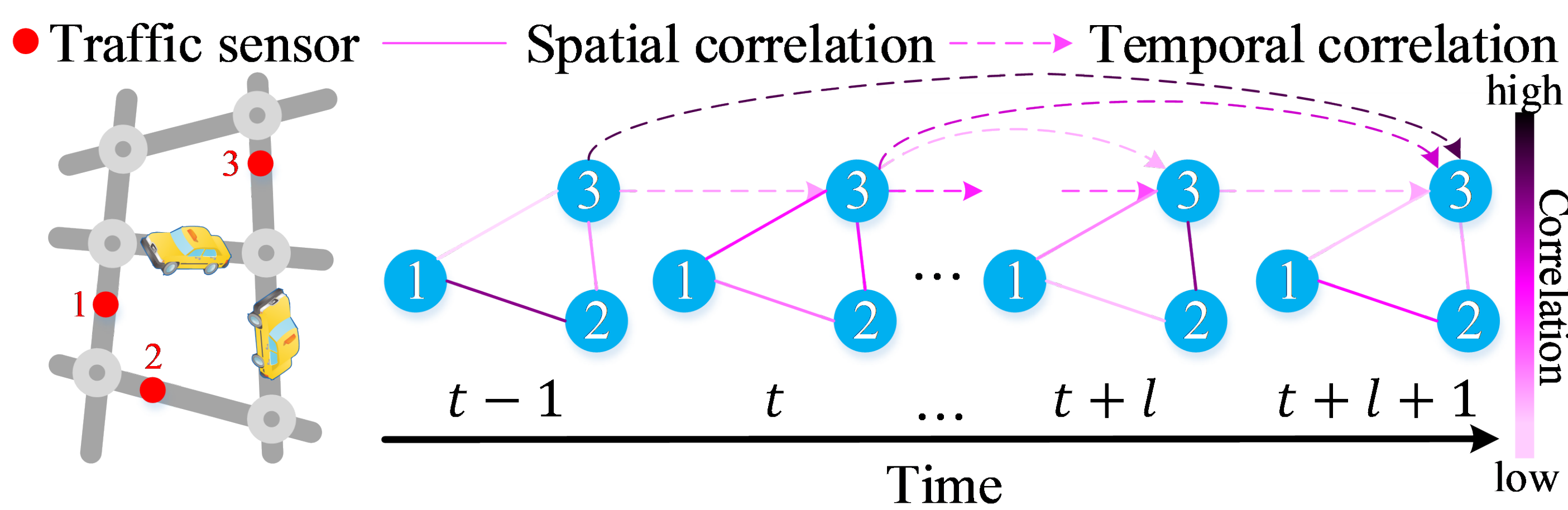
The long-term traffic prediction lacks a satisfactory progress in the literature, mainly due to the following challenges.

1) Complex spatio-temporal correlations.

- Dynamic spatial correlations.
- Non-linear temporal correlations

2) Sensitivity to error propagation.

Small errors in each time step may amplify when predictions are made further into the future.



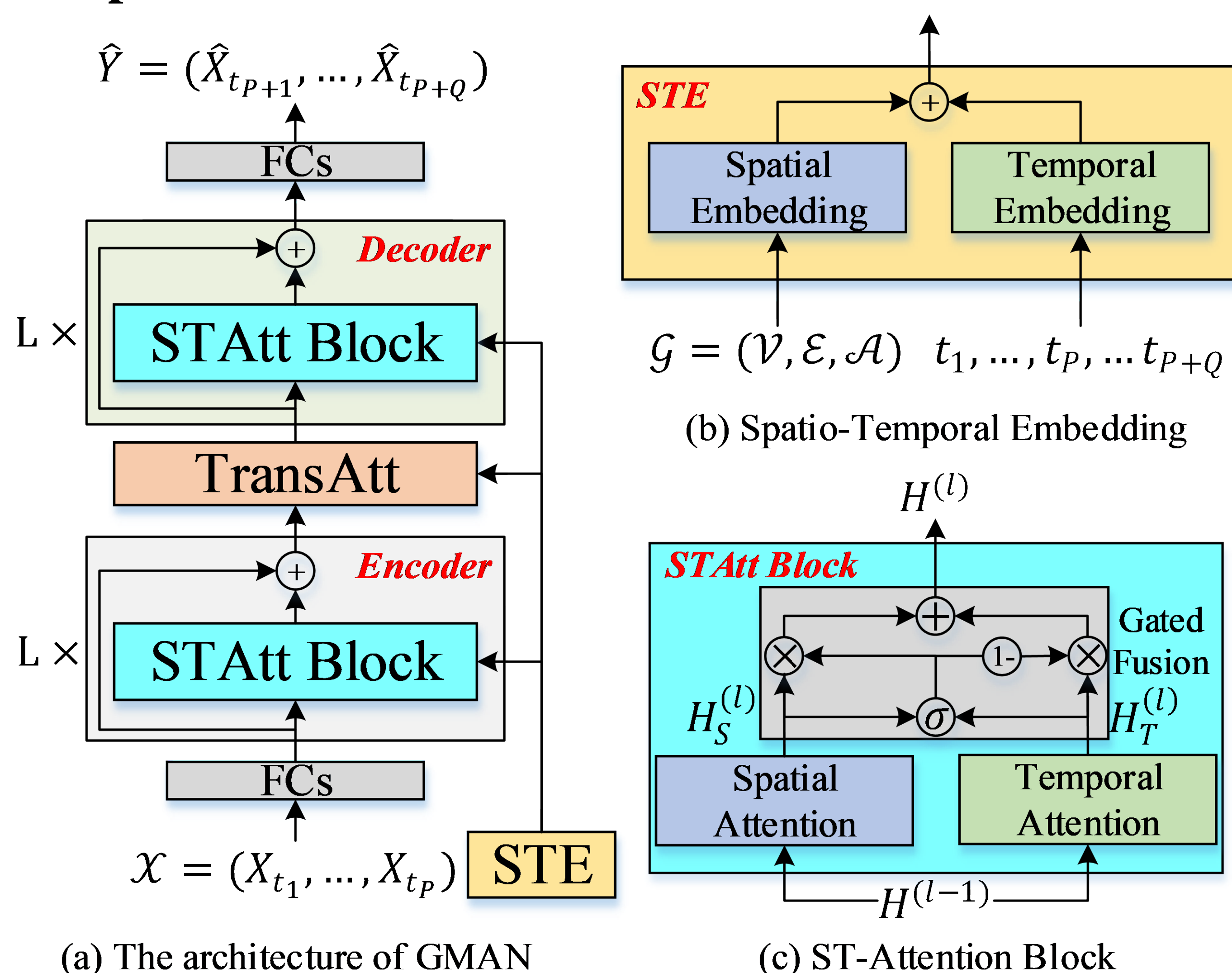
(a) Sensors in a road network (b) Complex spatio-temporal correlations

Figure 1: Complex spatio-temporal correlations.

Contributions

- We propose spatial and temporal attention mechanisms to model the dynamic spatial and non-linear temporal correlations, respectively. Moreover, we design a gated fusion to adaptively fuse the information extracted by spatial and temporal attention mechanisms.
- We propose a transform attention mechanism to transform the historical traffic features to future representations. This attention mechanism models direct relationships between historical and future time steps to alleviate the problem of error propagation.
- We evaluate our graph multi-attention network (GMAN) on two real-world traffic datasets, and observe 4% improvement and superior fault-tolerance ability over state-of-the-art baseline methods in the 1 hour ahead prediction. The source code is available at <https://github.com/zhengchuanpan/GMAN>.

Graph Multi-Attention Network



(a) The architecture of GMAN

(c) ST-Attention Block

Figure 2: The framework of Graph multi-attention network (GMAN).

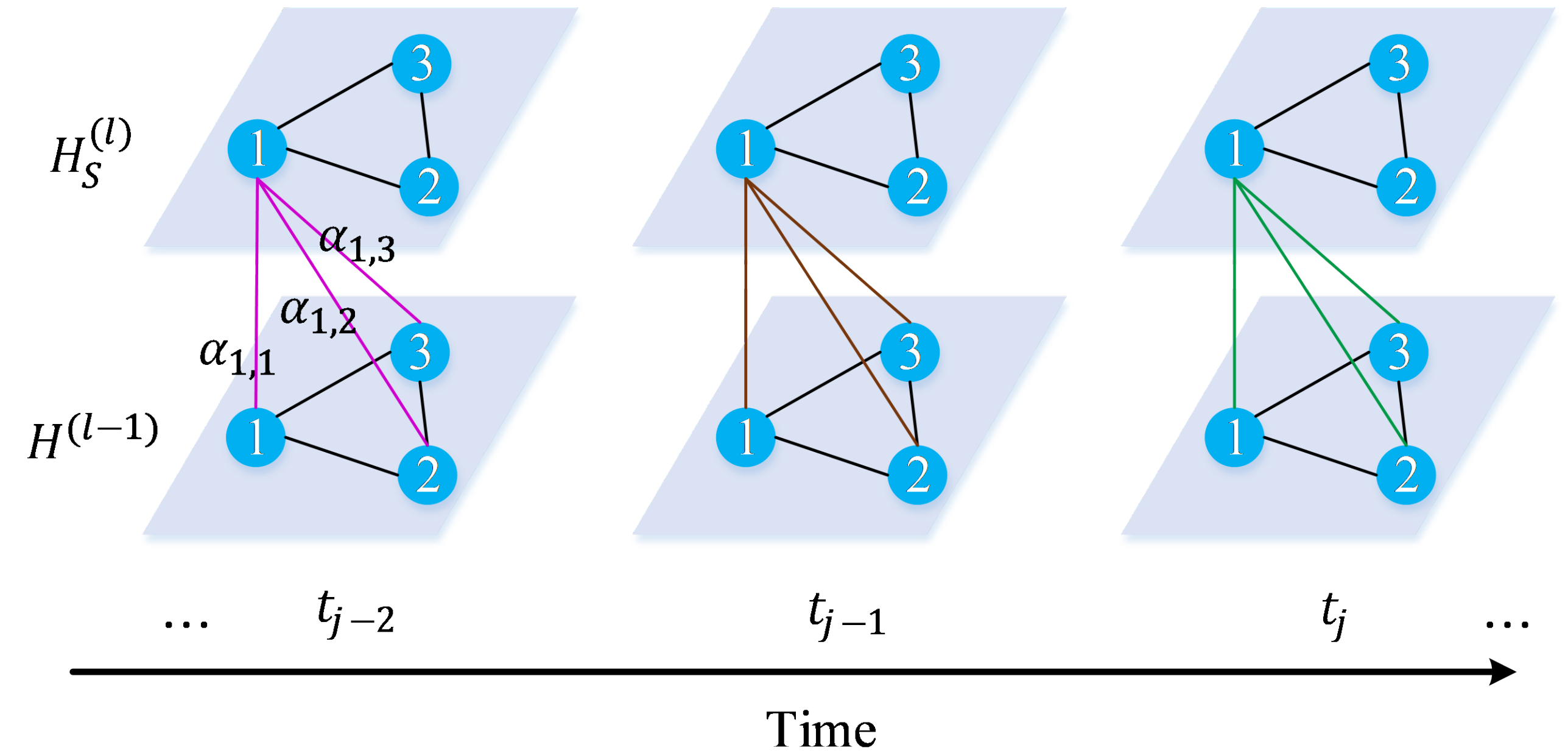


Figure 3: The spatial attention mechanism captures time-variant pair-wise correlations between vertices.

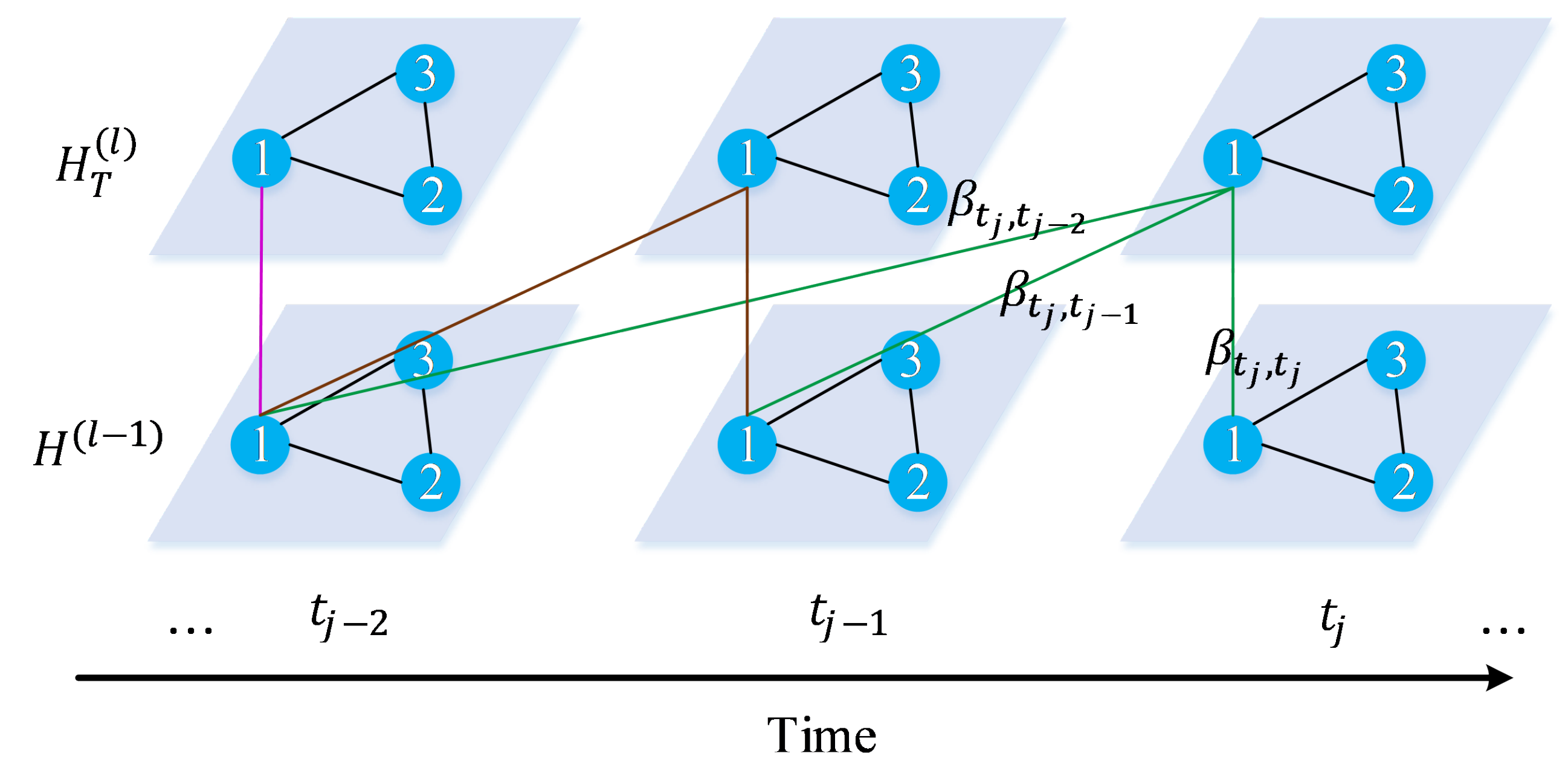


Figure 5: The temporal attention mechanism models the non-linear correlations between different time steps.

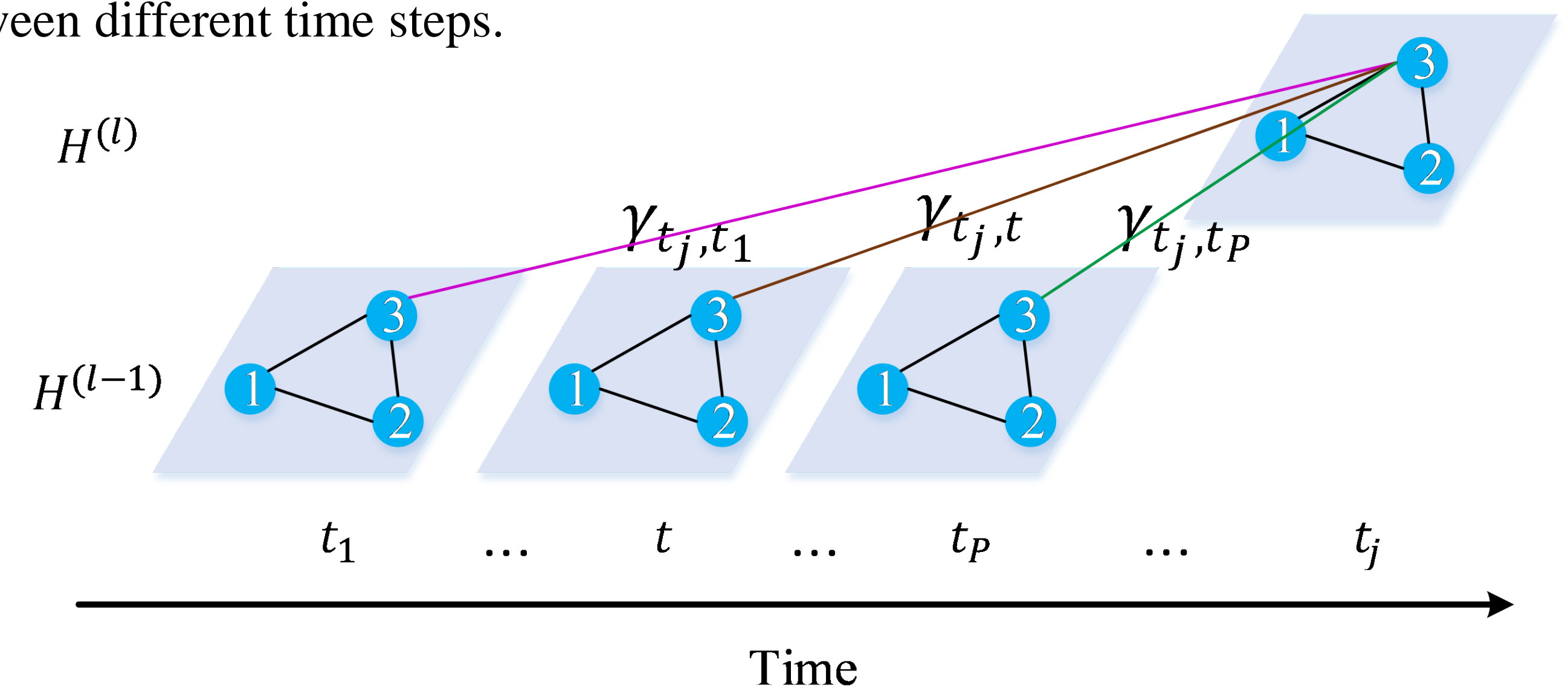


Figure 6: The transform attention mechanism models direct relationships between historical and future time steps.

Experimental Results

| Data | Method | 15 min | | | 30 min | | | 1 hour | | |
|--------|---------------|--------------|--------------|---------------|--------------|--------------|---------------|--------------|--------------|---------------|
| | | MAE | RMSE | MAPE | MAE | RMSE | MAPE | MAE | RMSE | MAPE |
| Xiamen | ARIMA | 14.81 | 25.03 | 18.05% | 18.83 | 33.09 | 22.19% | 26.58 | 46.32 | 30.76% |
| | SVR | 13.05 | 21.47 | 16.46% | 15.66 | 26.34 | 19.68% | 20.69 | 35.86 | 26.24% |
| | FNN | 13.55 | 22.47 | 16.72% | 16.80 | 28.71 | 19.97% | 22.90 | 39.51 | 26.19% |
| | FC-LSTM | 12.51 | 20.79 | 16.08% | 13.74 | 23.93 | 17.23% | 16.02 | 29.57 | 19.33% |
| | STGCN | 11.76 | 19.94 | 14.93% | 13.19 | 23.29 | 16.36% | 15.83 | 29.40 | 18.66% |
| | DCRNN | 11.67 | 19.40 | 14.85% | 12.76 | 22.20 | 15.99% | 14.30 | 25.86 | 17.17% |
| | Graph WaveNet | 11.26 | 19.57 | 14.39% | 12.06 | 21.61 | 15.39% | 13.33 | 24.77 | 16.50% |
| | GMAN | 11.50 | 19.52 | 14.59% | 12.02 | 21.42 | 15.14% | 12.79 | 24.15 | 15.84% |
| PeMS | ARIMA | 1.62 | 3.30 | 3.50% | 2.33 | 4.76 | 5.40% | 3.38 | 6.50 | 8.30% |
| | SVR | 1.85 | 3.59 | 3.80% | 2.48 | 5.18 | 5.50% | 3.28 | 7.08 | 8.00% |
| | FNN | 2.20 | 4.42 | 5.19% | 2.30 | 4.63 | 5.43% | 2.46 | 4.98 | 5.89% |
| | FC-LSTM | 2.05 | 4.19 | 4.80% | 2.20 | 4.55 | 5.20% | 2.37 | 4.96 | 5.70% |
| | STGCN | 1.36 | 2.96 | 2.90% | 1.81 | 4.27 | 4.17% | 2.49 | 5.69 | 5.79% |
| | DCRNN | 1.38 | 2.95 | 2.90% | 1.74 | 3.97 | 3.90% | 2.07 | 4.74 | 4.90% |
| | Graph WaveNet | 1.30 | 2.74 | 2.73% | 1.63 | 3.70 | 3.67% | 1.95 | 4.52 | 4.63% |
| | GMAN | 1.34 | 2.82 | 2.81% | 1.62 | 3.72 | 3.63% | 1.86 | 4.32 | 4.31% |