Notes for Explicit Kernel-Split Panel-Based Nyström Scheme for Yukawa Boundary Value Problems

1 Preliminaries

Consider the following boundary value problem in a simply-connected, bounded domain $\Omega \subset \mathbb{R}^2$:

$$u(x) - \alpha^2 \Delta u(x) = 0, \quad x \in \Omega,$$

$$\lim_{\Omega \ni x' \to x} u(x') = f(x), \quad x \in \Gamma,$$
 (1)

where Γ is the boundary of Ω and is assumed to be smooth. We seek the solution u(x) in the form of a double layer potential,

$$u(x) = \frac{1}{2\pi\alpha^2} \int_{\Gamma} \frac{\partial}{\partial n'} K_0\left(\frac{|x'-x|}{\alpha}\right) \sigma(x') \, ds', \qquad x \in \Omega, \tag{2}$$

where $\sigma(x')$ is the value of the unknown density at the boundary point x', and $\partial/\partial n'$ represents the outward normal derivative at the point x'. Substituting (2) into (1), we obtain an integral equation for the layer density σ :

$$\sigma(x) - \frac{1}{\pi} \int_{\Gamma} \frac{\partial}{\partial n'} K_0 \left(\frac{|x' - x|}{\alpha} \right) \sigma(x') \, ds' = -2\alpha^2 f(x). \tag{3}$$

Let M(x, x') be the kernel of the double layer potential,

$$M(x, x') = -\frac{1}{\pi} \frac{\partial}{\partial n'} K_0 \left(\frac{|x' - x|}{\alpha} \right)$$
$$= \frac{1}{\pi \alpha} K_1 \left(\frac{|x' - x|}{\alpha} \right) \frac{x' - x}{|x' - x|} \cdot n'. \tag{4}$$

Following the notation of [1], we will use the subscript Γ or Ω if $x \in \Gamma$ or $x \in \Omega$, respectively. Hence,

$$\sigma(x) + \int_{\Gamma} M_{\Gamma}(x, x') \sigma(x') ds' = -2\alpha^2 f(x), \quad x \in \Gamma$$
 (5)

$$u(x) = -\frac{1}{2\alpha^2} \int_{\Gamma} M_{\Omega}(x, x') \sigma(x') ds', \quad x \in \Omega.$$
 (6)

Consider an $n_{\rm pt}$ -point panel-based Nyström discretization scheme based on Gaussian quadrature (see section 3 of [1]). Let t_i and w_i , $i=1,\cdots n_{\rm pan}n_{\rm pt}$ be the actual nodes and weights, respectively, on the panels of Γ found from transforming the canonical weights and nodes. M(x,x') is not smooth and, as in the case of the Helmholtz equation considered in [1], can contain both logarithmic- and Cauchy-type singularities, depending on how x' approaches x. Special-purpose quadrature is applied to those panels where M(x,x') is not smooth. Introducing the speed function s(t) = |dx(t)/dt|, the discretization of (5) and (6) is

$$\sigma_i + \sum_{j \in \mathcal{C}(x_i)} M_{\Gamma}(x_i, x_j) \sigma_j s_j w_{ij} + \sum_{j \in \mathcal{F}(x_i)} M_{\Gamma}(x_i, x_j) \sigma_j s_j w_j = -2\alpha^2 f_i, \quad (7)$$

$$u(x) = -\frac{1}{2\alpha^2} \sum_{j \in \mathcal{C}(x)} M_{\Omega}(x, x_j) \sigma_j s_j w_{ij} - \frac{1}{2\alpha^2} \sum_{j \in \mathcal{F}(x)} M_{\Omega}(x, x_j) \sigma_j s_j w_j, \quad (8)$$

where C(x) is the set of source points on panels close to x, where special-purpose quadrature weights w_{ij} are used and F(x) are the remaining source points.

2 Special-Purpose Quadrature

Now consider the discretization of the integral

$$I_p(x) = \int_{\Gamma_n} G(x, x') \sigma(x') ds', \tag{9}$$

where Γ_p is a panel on Γ , G(x, x') is non-smooth, and the target point x lies close to, or on, Γ_p . Here, if $x \in \Gamma$ then $I_p(x)$ comes from the discretization of (5), and $G(x, x') = M_{\Gamma}(x, x')$. If $x \in \Omega$, we are considering the discretization of (6), and $G(x, x') = -M_{\Omega}(x, x')/2\alpha^2$.

2.1 Logarithmic singularity plus smooth part

If $x \in \Gamma$, G(x, x') can be expressed as

$$G(x, x') = G_0(x, x') + \log|x - x'|G_L(x, x').$$
(10)

The special quadrature to compute $I(x_i)$, where the target point x_i on Γ_p , is described by equation (30) in [1]. To use this formula, we need $G_0(x_i, x_i)$ and $G_L(x_i, x_j)$, which is found by considering the singularity structure of (4). According to NIST's DLMF (see http://dlmf.nist.gov/10.31)

$$K_1(z) = \frac{1}{z} + \ln\left(\frac{1}{2}z\right)I_1(z) + \tilde{K}_1(z),$$

where $I_1(z)$ is the modified Bessel function of the first kind of order 1 and $\tilde{K}_1(z)$ is a smooth function in z. As $z \to 0$, both of these functions have a limit of zero. This gives

$$G_L(x_i, x_j) = \frac{1}{\pi \alpha} I_1 \left(\frac{|x_j - x_i|}{\alpha} \right) \frac{x_j - x_i}{|x_j - x_i|} \cdot n_j.$$
 (11)

and

$$G_0(x_i, x_i) = \lim_{x_j \to x_i} G(x_i, x_j)$$
$$= -\frac{1}{2\pi} \frac{n_i \cdot \ddot{x}_i}{|\dot{x}_i|^2},$$

where $\dot{x} = dx(t)/dt$, and $\ddot{x} = d^2x(t)/dt^2$. An alternative expression to the above is $G_0(x_i, x_i) = \kappa_i/2\pi$, where κ is the curvature.

A NOTE ABOUT THE CODE: The MATLAB routine dlpYukawaPanelMatrix returns the system matrix associated with the left-hand side of (5), including the modifications made here for product integration for singular integrals. It is implemented exactly as described in [1], and includes the use of the MATLAB function WfrakLinit described in Appendix A of that paper.

2.2 Logarithmic and Cauchy-type singularities plus smooth part

If $x \in \Omega$, G(x, x') is written as

$$G(x,x') = G_0(x,x') + \log|x - x'|G_L(x,x') + \frac{(x'-x)\cdot n'}{|x'-x|^2}G_C(x,x'), \quad (12)$$

where $G_0(x, x')$, $G_L(x, x')$ and $G_C(x, x')$ are smooth functions. Here, $G_L(x, x')$ is the same as (11) except scaled by $-1/2\alpha^2$, and

$$G_C(x, x') = -\frac{1}{2\pi\alpha^2}.$$

The special quadrature to compute $I_p(x)$, where $x \in \Omega$ and close to Γ_p is calculated according to equation (33) in [1]. The compensated weights $w_{Lj}^{\text{corr}}(x)$ and $w_{Cj}^{\text{corr}}(x)$ are computed with the MATLAB function wLCinit found in Appendix B in [1], taking into account the change in orientation of the point x with respect to Γ_p . In [1], $x \in \Omega^c$, i.e. in the unbounded domain exterior to Γ . This requires a change in how p_1 is calculated (see section 7 of [2]). The following modification is included in wLCinit:

```
if imag(rtr) < 0 && abs(real(rtr)) < 1
p(1) = p(1) + 2*1i*pi;
p1 = p1 - 2*1i*pi;
end.</pre>
```

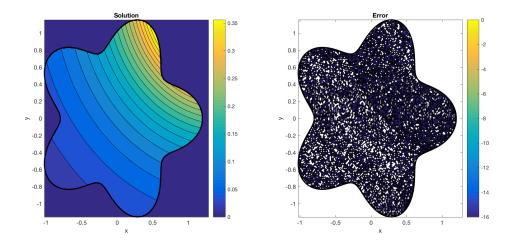
A NOTE ABOUT THE CODE: The MATLAB routine dlpYukawaPanelNSEval evaluates (6) when x is close to the source curve Γ . If x is not close, the routine dlpYukawaPanelEval does this evaluation.

3 Example

The following example was calculated using the routine ModHelmPanelDriver. The boundary value problem (1) is solved with boundary conditions prescribed by the exact solution

$$u(x) = K_0 \left(\frac{|z - z^*|}{\alpha} \right)$$

on the star-shaped domain shown in the figure below. The boundary is discretized with 100 panels using 16-point quadrature. The integral equation (7) is solved directly in MATLAB. A 200x200 grid is superimposed over the domain, resulting in 24258 interior points. In this case, the minimum source-to-target distance is 2.6×10^{-4} . In this grid, (8) is evaluated. The largest point-wise error on the grid is 1.1×10^{-14} . At a set of target points well-separated from the boundary, the largest point-wise error is 2.1×10^{-16} .



FURTHER COMMENTS ABOUT IMPLEMENTATION: In section 8 of [1], four schemes are proposed which use the approach to quadrature described above. We have implemented scheme A, the approach described here, only. While the most straightforward, it shows the poorest convergence for the Helmholtz Equation. It may be worthwhile implementing one of the other experiences, however scheme A already achieves significantly superior results to the Alpert quadrature rules at points well-separated from source points (by about 3 orders of magnitude) [3] and QBX for close-evaluation.

References

- [1] J. Helsing and A. Holst. Variants of an explicit kernel-split panel-based Nyström discretization scheme for Helmholtz boundary value problems. *Adv. Comput. Math*, 41:691–708, 2015.
- [2] J. Helsing and R. Ojala. On the evaluation of layer potentials close to their sources. *J. Comp. Phys.*, 227:2899–2921, 2008.
- [3] M.C.A. Kropinski and B.D. Quaife. Fast integral equation methods for the modified Helmholtz equation. *J. Comp. Phys.*, 230:425–434.