

Low-Rank 3D Tensor Completion

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Overview

- 1 Motivations
- 2 Overview of algebraic tools
- 3 Description of the problem and algorithms
 - ALS
 - GeomCG
- 4 Examples

Motivations

- Movies
- Signal processing
- Multiple parameters approximation

Matricisation

How to matricise

Tucker Format

Tucker

Problem as in ALS

MB and stuff

Inpainting

Two Algorithms

Alternating Least Squares Algorithm

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1. Form \mathcal{X} from $\mathbf{P}^0, \dots, \mathbf{P}^{K-1}$ using Block Matching criteria
 2. $(\mathcal{X}(:, :, 1))_{\overline{\Omega}} = \left(\frac{1}{K-1} \sum_{i=1}^{K-1} \mathbf{P}^i \right)_{\overline{\Omega}}$
 3. Choose mode ranks $\{R_1, R_2, R_3\}$, tolerance σ ;
Initialize $\mathbf{A}^{(1)}, \mathbf{A}^{(2)}, \mathbf{A}^{(3)}$
 4. $\mathbf{A}^{(3)}(:, 1) = [1, \dots, 1]^T / K$
 5. for $n = 1, 2, 3$
 - $\mathcal{Y} = \mathcal{X} \times_1 \dots \times_{n-1} \mathbf{A}^{(n-1)T} \times_{n+1} \mathbf{A}^{(n+1)T} \dots$
 - $\mathbf{Y}_n \leftarrow \text{unfold } \mathcal{Y} \text{ in mode } n$
 - $\mathbf{A}^{(n)} \leftarrow \text{first } R_n \text{ principal component of } \mathbf{Y}_n$
 6. $\mathcal{G} = \mathcal{X} \times_1 \mathbf{A}^{(1)T} \times_2 \mathbf{A}^{(2)T} \times_3 \mathbf{A}^{(3)T}$
 7. $\mathcal{X}_l = \mathcal{G} \times_1 \mathbf{A}^{(1)} \times_2 \mathbf{A}^{(2)} \times_3 \mathbf{A}^{(3)}$
 8. If $\|\mathcal{X}_l - \mathcal{X}\|_F \leq \sigma$ STOP, otherwise return to Step 4.
 9. Recover missing area in \mathbf{P}^0 : $(\mathbf{P}^0)_{\overline{\Omega}} = (\mathcal{X}_l(:, :, 1))_{\overline{\Omega}}$
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GeomCG

Optimization on the manifold

Movie reconstruction



Error Plot

Error plot, convergence in one iteration

Importance of initial guess

Plot initial guess

Inpainting



Comparison with GeomCG

Compare results for rank 1



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