

```
[ 34%] [ 34%] Building CXX object
kinect2_tracker/CMakeFiles/kinect2_tracker_node.dir/src/kinect2_t
racker_node.cpp.o
Built target
_kinect2_tracker_generate_messages_check_deps_user_IDs
[ 62%] Built target intera_core_msgs_generate_messages_cpp
[ 90%] Built target intera_core_msgs_generate_messages_lisp
[ 92%] Built target intera_interface_gencfg
[ 93%] [ 95%] Built target slam_gmapping
Generating Lisp code from kinect2_tracker/user_IDs.msg
[ 97%] Built target slam_gmapping_replay
[ 97%] Generating Python from MSG kinect2_tracker/user_IDs
[ 98%] Generating C++ code from kinect2_tracker/user_IDs.msg
[ 98%] Built target kinect2_tracker_generate_messages_lisp
[100%] [100%] Built target intera_core_msgs_generate_messages
Generating Python msg __init__.py for kinect2_tracker
[100%] Built target kinect2_tracker_generate_messages_py
[100%] Built target kinect2_tracker_generate_messages_cpp
[100%] Built target kinect2_tracker_generate_messages
In file included from
/home/sina/ros_ws/src/kinect2_tracker/src/kinect2_tracker_node.cp
p:8:0:
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_track
er.hpp:218:2: error: expected unqualified-id before token
  -// This function publishes the calibration_space opposite the
shoulders of the user
  ^
/
home/sina/ros_ws/src/kinect2_tracker/src/kinect2_tracker_node.cpp
:24:1: error: expected at end of input
}
^
In file included from
/home/sina/ros_ws/src/kinect2_tracker/src/kinect2_tracker_node.cp
p:8:0:
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_track
er.hpp: In constructor :
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_track
er.hpp:55:7: error: class does not have any field named
    it_(nh_)
    ^
/
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home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:55:11: error: was not declared in this scope
    it_(nh_)
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:60:36: error: was not declared in this scope
    if (!pnh.getParam("tf_prefix", tf_prefix_))
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:66:41: error: was not declared in this scope
    if (!pnh.getParam("relative_frame", relative_frame_))
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:82:9: error: was not declared in this scope
    if (devDevice_.open(openni::ANY_DEVICE) != openni::STATUS_OK)
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:94:5: error: was not declared in this scope
    niteRc_ = userTracker_.create();
    ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:94:15: error: was not declared in this scope
    niteRc_ = userTracker_.create();
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:103:5: error: was not declared in this scope
    userPub_ =
nh_.advertise<skeleton_tracker::user_IDs>("/people", 1);
    ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:103:56: error: expected primary-expression before token
    userPub_ =
nh_.advertise<skeleton_tracker::user_IDs>("/people", 1);
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:105:5: error: was not declared in this scope
    rate_ = new ros::Rate(100);

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    ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp: In member function :
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:122:11: error: has no member named
    this->getSkeleton();
        ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:123:5: error: was not declared in this scope
    rate_>sleep();
    ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp: In member function :
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:135:35: error: was not declared in this scope
    else if (user.isVisible() && !g_visibleUsers_[user.getId()])
                                   ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:142:5: error: was not declared in this scope
    g_visibleUsers_[user.getId()] = user.isVisible();
    ^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:144:9: error: was not declared in this scope
    if (g_skeletonStates_[user.getId()] !=
user.getSkeleton().getState())
    ^
In file included from
/home/sina/ros_ws/src/kinect2_tracker/src/kinect2_tracker_node.cpp:8:0:
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp: In member function :
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:195:37: error: was not declared in this scope
    j_frame_id_stream << "/" << tf_prefix_ << "/user_" << uid
<< "/" << j_name;
                                   ^

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/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:206:13: error:   was not declared in this scope

tfBroadcast_.sendTransform(tf::StampedTransform(transform,
    ^
ros::Time::now(), relative_frame_, j_frame_id));

/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:206:90: error:   was not declared in this scope

tfBroadcast_.sendTransform(tf::StampedTransform(transform,
ros::Time::now(), relative_frame_, j_frame_id));

^
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:211:13: error:   was not declared in this scope

tfBroadcast_.sendTransform(tf::StampedTransform(transform,
    ^
ros::Time::now(), r_frame_id, j_frame_id));

/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp: At global scope:
/
home/sina/ros_ws/src/kinect2_tracker/src/./include/kinect2_tracker.hpp:215:3: error: expected unqualified-id at end of input
    }
    ^
make[2]: ***
[kinect2_tracker/CMakeFiles/kinect2_tracker_node.dir/src/kinect2_tracker_node.cpp.o] Error 1
make[1]: ***
[kinect2_tracker/CMakeFiles/kinect2_tracker_node.dir/all] Error 2
make: *** [all] Error 2
Invoking "make -j4 -l4" failed
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