Recorded at time: 1529086846.373 ref_tf/base Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref sawyer/robot state publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /fixed_frame_pub Average rate: 10000.000 Hz Average rate: 10.195 Hz Most recent transform: 0.000 (1529086846.373 sec old) | Most recent transform: 0.000 (1529086846.373 sec old) | Most recent transform: 0.000 (1529086846.373 sec old) | Most recent transform: 0.000 (1529086846.373 sec old) Most recent transform: 1529086846.421 (-0.048 sec old) Most recent transform: 0.000 (1529086846.373 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.904 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec ref_tf/pedestal_feet ref_tf/right_arm_base_link main_tf/base ref_tf/pedestal ref_tf/torso ref_tf/controller_box Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 48.782 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1529086846.373 sec old) Most recent transform: 0.000 (1529086846.373 sec old) Most recent transform: 1529086846.334 (0.039 sec old) Most recent transform: 0.000 (1529086846.373 sec old) | Most recent transform: 0.000 (1529086846.373 sec old) | Most recent transform: 0.000 (1529086846.373 sec old) | Buffer length: 4.940 sec Buffer length: 0.000 sec main_tf/pedestal_feet ref_tf/right_l0 main_tf/controller_box main_tf/right_arm_base_link main_tf/pedestal main_tf/torso Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Average rate: 48.782 Hz Average rate: 10000.000 Hz Average rate: 48.782 Hz Average rate: 48.609 Hz Most recent transform: 0.000 (1529086846.373 sec old) Most recent transform: 1529086846.334 (0.039 sec old) Most recent transform: 1529086846.334 (0.039 sec old) Most recent transform: 1529086846.351 (0.022 sec old) Buffer length: 4.937 sec Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 0.000 sec ref_tf/head main_tf/right_10 ref_tf/right_11 ref_tf/right_torso_itb Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /ref_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Broadcaster: /main_sawyer/robot_state_publisher Average rate: 48.609 Hz Average rate: 10000.000 Hz Average rate: 48.609 Hz Average rate: 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view_frames Result