

# 1. Least Squares

mtcars =

	Model	MPG	Cyl	Disp	HP	DRat	WT	QSec	V8
1	"Mazda RX4"	21.0	6	160.0	110	3.9	2.62	16.46	0
2	"Mazda RX4 Wag"	21.0	6	160.0	110	3.9	2.875	17.02	0
3	"Datsun 710"	22.8	4	108.0	93	3.85	2.32	18.61	1
4	"Hornet 4 Drive"	21.4	6	258.0	110	3.08	3.215	19.44	1
5	"Hornet Sportabout"	18.7	8	360.0	175	3.15	3.44	17.02	0
6	"Valiant"	18.1	6	225.0	105	2.76	3.46	20.22	1
7	"Duster 360"	14.3	8	360.0	245	3.21	3.57	15.84	0
8	"Merc 240D"	24.4	4	146.7	62	3.69	3.19	20.0	1
9	"Merc 230"	22.8	4	140.8	95	3.92	3.15	22.9	1
10	"Merc 280"	19.2	6	167.6	123	3.92	3.44	18.3	1
: more									
32	"Volvo 142E"	21.4	4	121.0	109	4.11	2.78	18.6	1

$x_1 \dots x_4$  are the coefficients

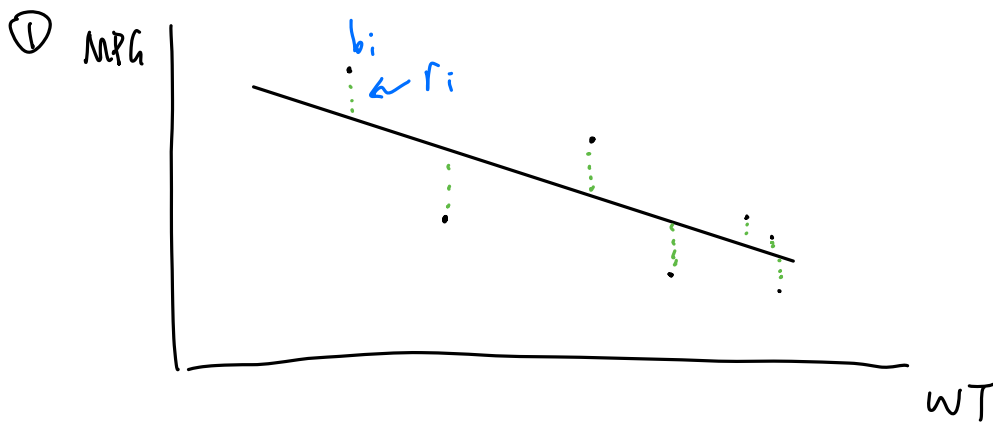
intercept term

observation

$$MPG_i \sim x_1 + x_2 \cdot Disp_i + x_3 \cdot HP_i + x_4 \cdot WT_i \quad i = 1 \dots 32$$

$$\min_{x_1 \dots x_4} \sum_{i=1}^{32} \left( MPG_i - (x_1 + x_2 \cdot Disp_i + x_3 \cdot HP_i + x_4 \cdot WT_i) \right)^2$$

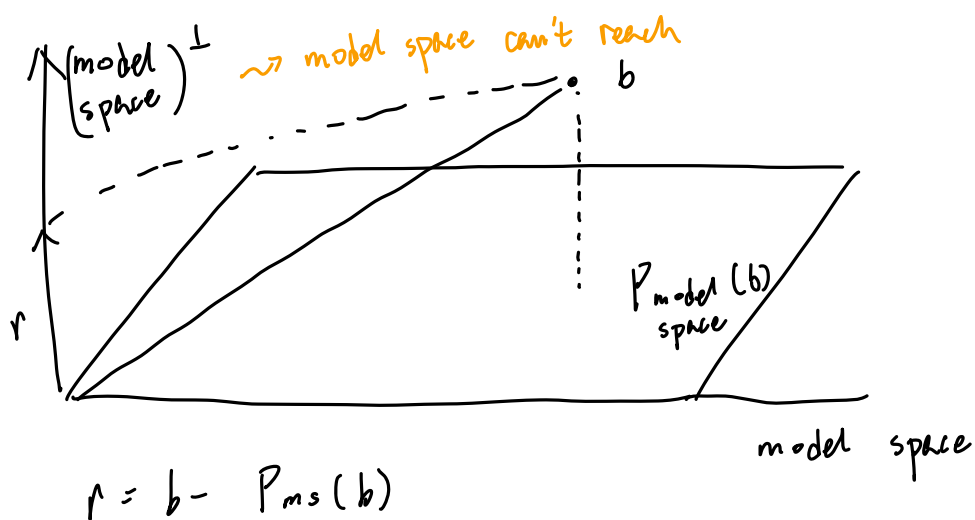
## Points of View



↳ choose  $x_i$  such that  $\sum r_i^2$   $r_i = b_i - \text{model}_i(x)$

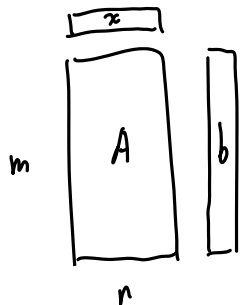
## ② Geometry via Linear Algebra

$$b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} = \begin{bmatrix} \text{MPG}_1 \\ \vdots \\ \text{MPG}_m \end{bmatrix} \quad \text{observations}$$

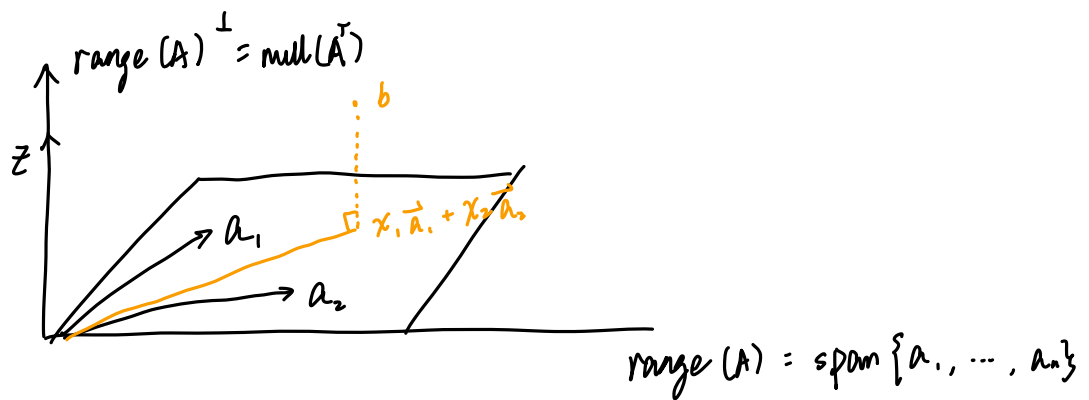


## Matrix Formulation

$$b = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix} \quad A = \begin{bmatrix} 1 & \text{Disp}_1 & \text{HP}_1 & \text{WT}_1 \\ \vdots & \vdots & \vdots & \vdots \\ 1 & \text{Disp}_m & \text{HP}_m & \text{WT}_m \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_4 \end{bmatrix}$$



$$\min_x \|r\|^2 \quad \text{such that} \quad \underbrace{Ax}_{\text{linear model}} + \underbrace{r}_{\text{residual}} = \underbrace{b}_{\text{obs}}$$



$$\text{range}(A) = \{y \mid Ax = y \text{ for some } y\}$$

$$\begin{aligned} 0 &= z^T y & \forall y \in \text{range}(A) \\ &= z^T Ax \\ &= x^T A^T z & \forall x \Rightarrow A^T z = 0 \end{aligned}$$

$$A = \begin{bmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{bmatrix}$$

$$A^T z = \begin{bmatrix} a_1^T \\ \vdots \\ a_n^T \end{bmatrix} \cdot z = \begin{bmatrix} a_1^T z \\ \vdots \\ a_n^T z \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$r \in \text{Null}(A^T) \iff A^T r = 0, \quad r = b - A\bar{x}$$

$$A^T(b - A\bar{x}) = 0$$

$$A^T b - A^T A \bar{x} = 0$$

$$A^T A \bar{x} = A^T b$$

Normal  
Eqn's

↳ show  $\bar{x}$  is unique iff  $A$  has full rank

$$p(t) = \alpha + \beta t$$

$$\min_{\alpha, \beta} \sum_{i=1}^I (p(t_i) - p_i)^2$$

$$A = \begin{bmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix} \quad b = \begin{bmatrix} p_1 \\ \vdots \\ p_m \end{bmatrix} \quad x = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

$$\hookrightarrow \text{Todo: } p_n(t) = \alpha + \beta t + \delta t^2$$