

## LECTURE 22

### TOPICS

- INCOMPRESSIBLE ELASTICITY

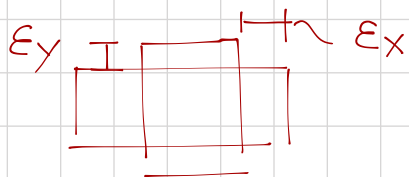
### LOGISTICS

- HW # 8 DUE MONDAY

- FINAL PROJECT DUE JANUARY 15th

## NEARLY INCOMPRESSIBLE

RECALL THE POISSON RATIO  $\nu$  RELATES STRAINS IN DIFFERENT DIRECTIONS



$$\frac{d\epsilon_y}{d\epsilon_x} = -\nu$$

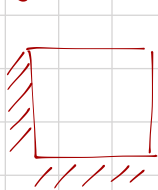


$$\begin{aligned}\hat{V} &= (1 + \Delta \epsilon_x)(1 - \nu \Delta \epsilon_x)^2 \\ &= (1 + \Delta \epsilon_x)(1 + \nu^2 \Delta \epsilon_x^2 - 2\nu \Delta \epsilon_x) \\ &= 1 - 2\nu \Delta \epsilon_x + \Delta \epsilon_x + O(\Delta \epsilon_x^2) \\ &\approx 1 + (1 - 2\nu) \Delta \epsilon_x\end{aligned}$$

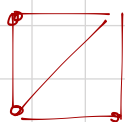
if  $\nu = 0 \Rightarrow \nu = \hat{\nu} \Rightarrow$  MATERIAL IS INCOMPRESSIBLE

$$\lambda = \frac{2\nu\mu}{1-2\nu} \quad \text{if } \nu \rightarrow 0.5, \lambda \rightarrow \infty$$

NOW THINK OF A MESH



if



THE ONLY WAY TO PRESERVE AREA



EFFECTIVELY TWO CONSTRAINTS ONE DOF

SHOW CODE

## INCOMPRESSIBLE

IN THE CASE  $\nu = 0.5$  THEN  $\lambda = \infty$

WE CHANGE THE PROBLEM

$$\lambda \nabla \cdot \underline{u} = -p \Rightarrow \nabla \cdot (\nabla \underline{u}, p) = -p \underline{1} + z \eta \underline{\varepsilon}$$

$$\nabla \cdot \underline{u} = -p/\lambda \text{ BUT if } \lambda \rightarrow \infty \quad \nabla \cdot \underline{u} = 0$$

(S) FIND  $p, \underline{u}$  SUCH THAT

$$\nabla \cdot (\nabla (\nabla \underline{u}, p)) = \underline{b} \quad \forall \underline{x} \in \Sigma$$

$$\nabla \cdot \underline{u} = 0 \quad \forall \underline{x} \in \Sigma$$

AND

$$\underline{u} = \underline{q} \quad \text{ON } \Gamma_D$$

$$\nabla \underline{u} = \underline{t} \quad \text{ON } \Gamma_N$$

(W)

$$S_{\underline{u}} = \{ \underline{u} \in \text{SMOOTH} \mid \underline{u} = \underline{q} \text{ ON } \Gamma_D \}$$

$$S_p = \{ p \in \text{SMOOTH} \}$$

$$V_{\underline{u}} = \{ \underline{v} \in \text{SMOOTH} \mid \underline{v} = 0 \text{ ON } \Gamma_D \}$$

$$V_p = \{ q \in \text{SMOOTH} \}$$

$$\int_{\Sigma} (\nabla \cdot \nabla - \underline{b}) \cdot \underline{v} \, d\Sigma + \int_{\Sigma} (\nabla \cdot \underline{u}) q \, d\Sigma = 0 \quad \forall \underline{v} \in V_{\underline{u}}, \forall q \in V_p$$

$$\int_{\Sigma} \nabla \cdot \nabla \underline{v} \, d\Sigma - \int_{\Gamma_N} \underline{t} \cdot \underline{v} \, d\Gamma + \int_{\Sigma} \underline{b} \cdot \underline{v} \, d\Sigma + \int_{\Sigma} \nabla \cdot \underline{u} \, q \, d\Sigma = 0$$

$$\forall \underline{v} \in V_{\underline{u}}, \forall q \in V_p$$

$$\underline{\nabla} \cdot \underline{\nabla} \underline{v} = (-p \underline{1} + z\gamma \underline{\varepsilon}) : \underline{\nabla} \underline{v} = -p \underline{\nabla} \cdot \underline{v} + z\gamma \underline{\varepsilon} : \underline{\nabla} \underline{v}$$

$$\int_{\Sigma} z\gamma \underline{\varepsilon} : \underline{\nabla} \underline{v} \, d\Sigma - \int_{\Sigma} p \underline{\nabla} \cdot \underline{v} \, d\Sigma = \int_{\Gamma_N} \underline{t} \cdot \underline{v} \, d\Gamma - \int_{\Sigma} \underline{b} \cdot \underline{v} \, d\Sigma \quad \forall \underline{v}$$

$$\int_{\Sigma} \underline{\nabla} \cdot \underline{u} \, q \, d\Sigma = 0 \quad \forall p$$

$$? \quad \underline{u} \in S_u, p \in S_p$$

$$a(\underline{v}, \underline{u}) - (\underline{\nabla} \cdot \underline{v}, p) = F(\underline{v}) \quad \forall \underline{v} \in V_u$$

$$(q, \underline{\nabla} \cdot \underline{u}) = 0 \quad \forall p \in V_p$$

(G)  $P^k \leftarrow$  SPACE OF POLYNOMIALS OF ORDER UP TO  $k$

$$S_u^n = \{ \underline{u}^n \in S_u \mid \underline{u}^n|_{\Sigma^e} \in P^{k_u} \} \quad \begin{array}{l} \swarrow \text{DEGREE OF POLYNOMIAL} \\ \text{APPROXIMANT} \\ \text{FOR DISPLACEMENT} \\ \text{FIELD } u \end{array}$$

$$S_p^n = \{ p \in S_p \mid p^n|_{\Sigma^e} \in P^{k_p} \} \quad \begin{array}{l} \swarrow \text{DEGREE OF POLYNOMIAL} \\ \text{APPROXIMANT} \\ \text{FOR PRESSURE} \end{array}$$

$$V_u^n = \{ \underline{v}^n \in V_u \mid \underline{v}^n|_{\Sigma^e} \in P^{k_u} \}$$

$$V_p^n = \{ p^n \in V_p \mid p^n|_{\Sigma^e} \in P^{k_p} \}$$

$$? \quad \underline{u}^n \in S_u^n, p^n \in S_p^n$$

$$a(\underline{v}^n, \underline{u}^n) - (\underline{\nabla} \cdot \underline{v}^n, p^n) = F(\underline{v}^n) \quad \forall \underline{v} \in V_u$$

$$(q^n, \underline{\nabla} \cdot \underline{u}^n) = 0 \quad \forall p \in V_p$$

(M) LET  $\{u\}$ ,  $\{p\}$  THE VECTORS OF UNKNOWN  
DISPL & PRESS.

$$K_{ij} u_j - Q_{is} p_s = \bar{F}_i \quad \forall i = 1 \dots N_{\text{DOF}_u}$$

$$Q_{ti} u_i = 0 \quad \forall t = 1 \dots N_{\text{DOF}_p}$$

$$K_{ij} = \int_{\Omega} z_{ij} \nabla \phi_i \otimes \nabla \phi_j \, d\Omega \quad Q_{is} = \int_{\Omega} \nabla \phi_i \cdot \psi_s \, d\Omega$$

$\nwarrow$  DISPL BASIS                       $\nwarrow$  PRESSURE BASIS FUNCTIONS

THE WAY YOU MAY THINK OF THIS IS SIMPLY  
THE ELASTICITY PROBLEM WITH  $N_{\text{DOF}_u}$   
DEGREES OF FREEDOM &  $N_{\text{DOF}_p}$  CONSTRAINTS

IF WE HAVE TOO MANY CONSTRAINTS IN  
RESPECT TO DOFS. THE PROBLEM  
IS OVER CONSTRAINED  $\Rightarrow$  LOCKING

NAMELY

$$\frac{N_{\text{DOF}_u}}{N_{\text{DOF}_p}} < d \quad \rightarrow \text{LOCKING}$$

$\nwarrow$  PROBLEM DIM

IF YOU CHOOSE  $K_p = K_u - 1 \rightarrow$  SAFE