

# FINITE ELEMENTS IN N-D

## TRIANGULAR ELEMENTS

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Maurizio M. Chiaramonte

# The Local Element View

1. Parametric element domain  $\hat{\Omega}$
2. Physical element domain  $\Omega^e$
3. Map  $\hat{\mathbf{x}}^e(\xi)$  from parametric to physical domain
4. Shape Functions  $\{\hat{\phi}_a(\xi)\}_{a=1}^{n_{dof}^e}$
5. Degrees of freedom  $\{u_a^e\}_{a=1}^{n_{dof}^e}$ ,  $u^h(\xi) = \sum_{a=1}^{n_{dof}^e} u_a^e \hat{\phi}_a(\xi)$
6. Local to global dof map

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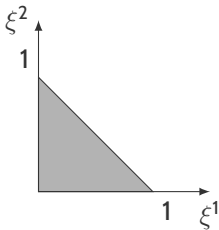
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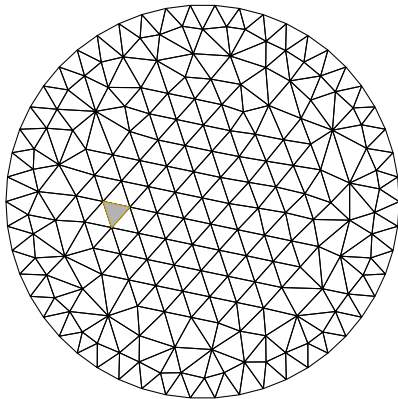
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# The Local Element View

Triangular parametric element  $\hat{\Omega}$



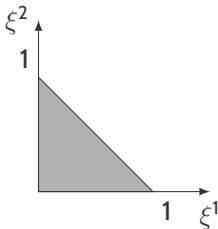
Triangular (simplicial) mesh



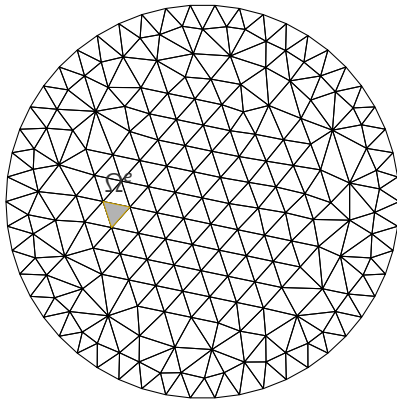


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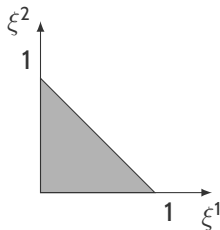


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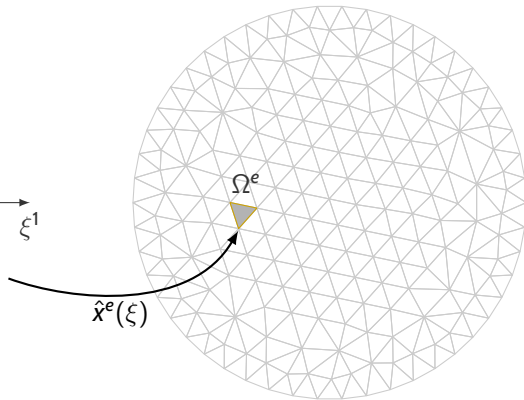


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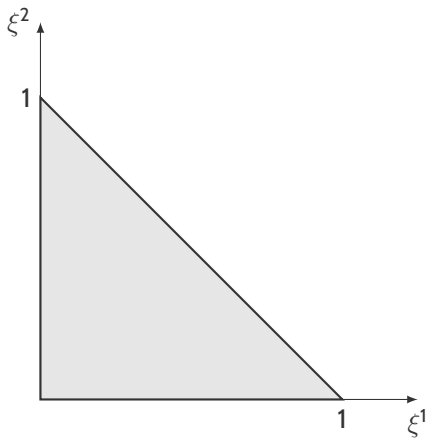
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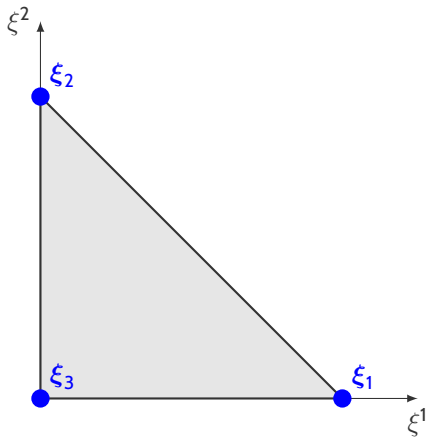
# CONSTRUCTING BASIS FUNCTIONS

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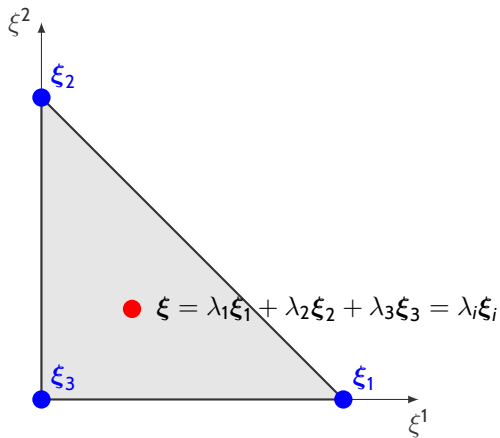
# Barycentric Coordinates



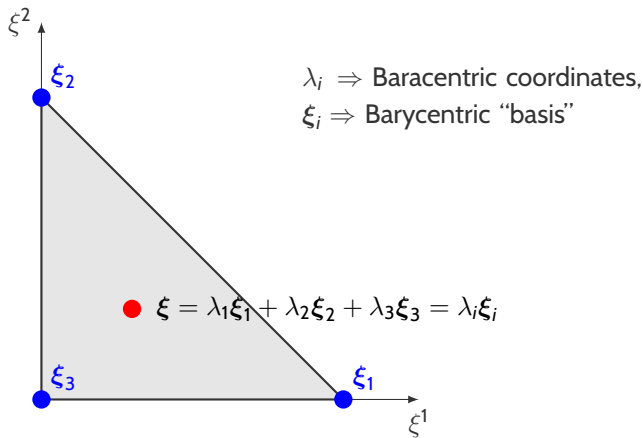
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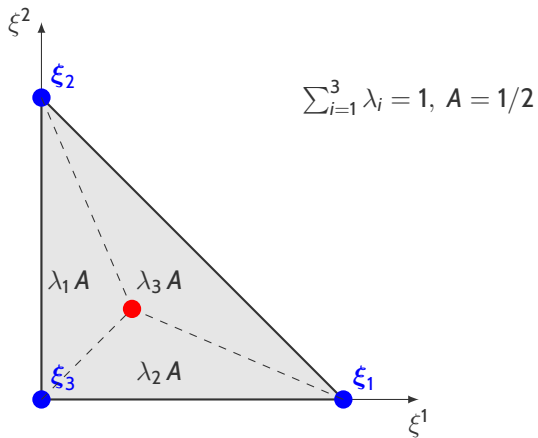
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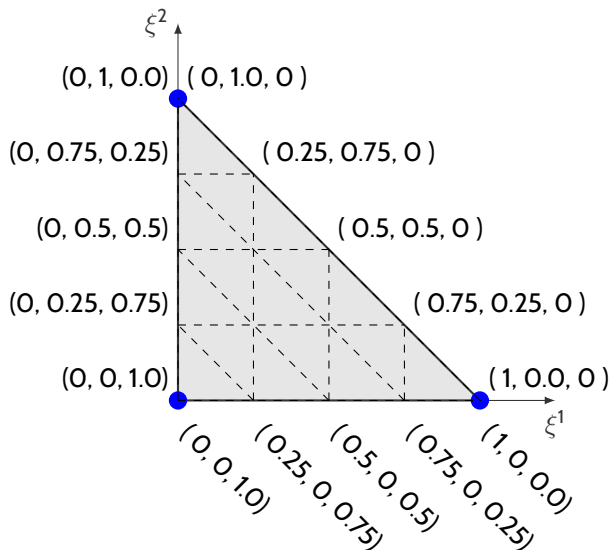


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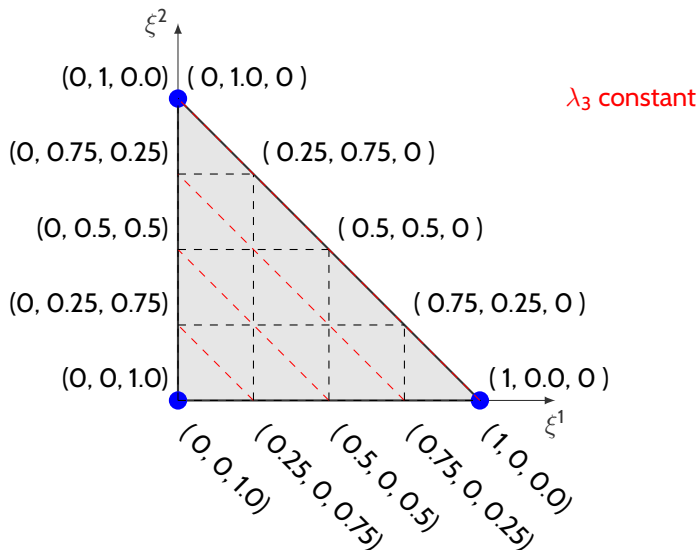




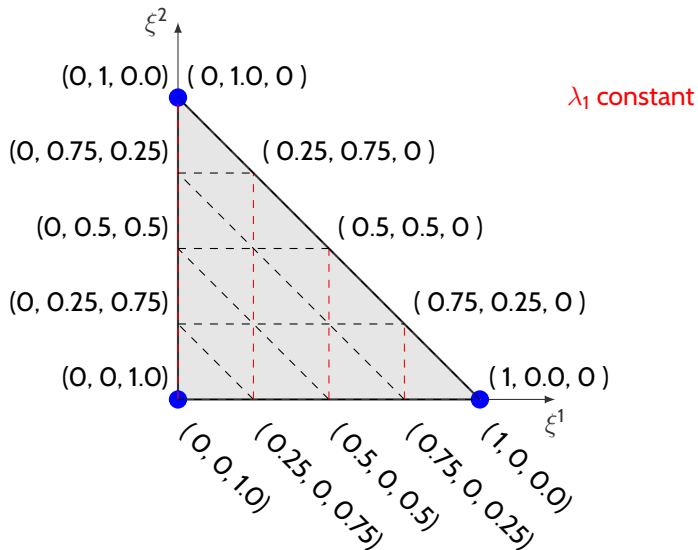
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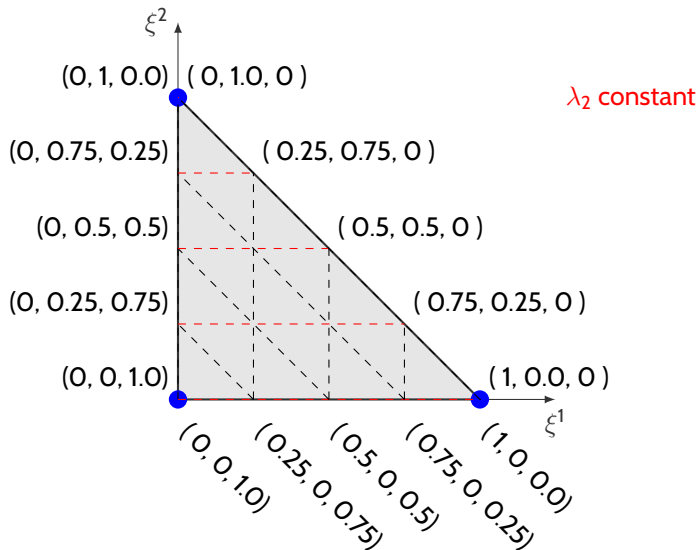
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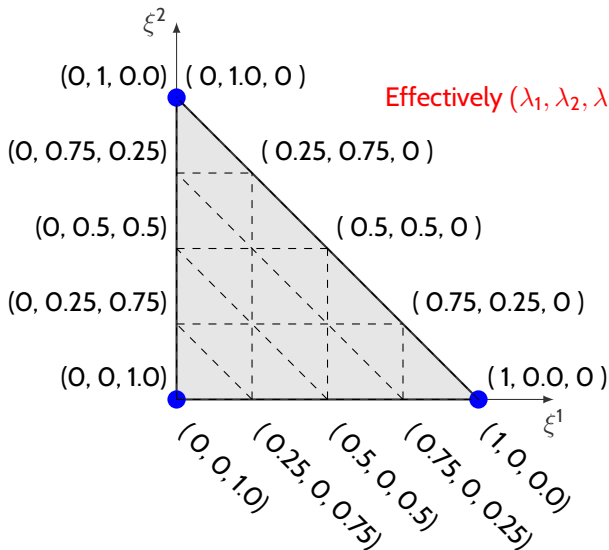
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# The Local Element View

For elements of order  $p$  the shape functions are

$$\hat{\phi}_a(\boldsymbol{\lambda}) = T_i(\lambda_1)T_j(\lambda_2)T_k(\lambda_3)$$

for  $i, j, k = 0 \dots p$ , where

$$T_i(\mathbf{z}) = \begin{cases} \ell_i^i(\mathbf{z}/\mathbf{z}_i) & \text{if } i \neq 0 \\ 1 & \text{if } i = 0 \end{cases}$$

and

$$a = \hat{a}(i, j, k).$$

and, for example, for  $p = 2$

$$\mathbf{z}_i = 0, 1/2, 1$$

are the uniformly spaced nodes in one dimensions for the Lagrange basis construction.

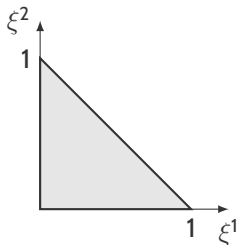
# The Local Element View

The elements of order  $p$  have

$$n_{dof} = \frac{1}{2}(p+1)(p+2)$$

DOFs which correspond to the function evaluation at the points  $\{x_i\}_{i=0}^{n_{dof}-1}$  where

$$\mathbf{x} = (i/p, j/p), \quad 0 \leq i+j \leq p=1$$



# The Local Element View

The elements of order  $p = 1$  have

$$n_{dof} = \frac{1}{2}(p+1)(p+2) = 3$$

DOFs which correspond to the function evaluation at the points  $\{x_i\}_{i=0}^2$  where

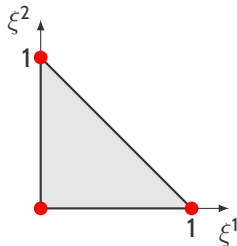
$$\mathbf{x} = (i/p, j/p), \quad 0 \leq i+j \leq p = 1$$

$$\hat{\phi}_a(\boldsymbol{\lambda}) = T_i(\lambda_1)T_j(\lambda_2)T_k(\lambda_3), \quad i, j, k = 0 \dots p$$

$$\hat{\phi}_1(\boldsymbol{\lambda}) = T_1(\lambda_1)T_0(\lambda_2)T_0(\lambda_3) = \ell_1^1(\lambda_1) = \ell_1^1(\xi^1) = \xi^1$$

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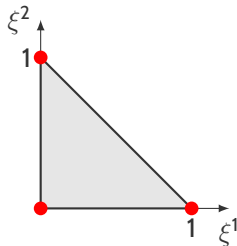
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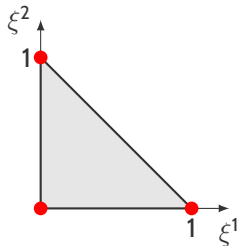
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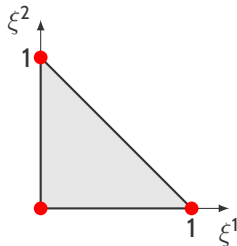
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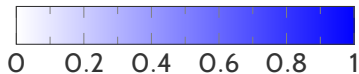
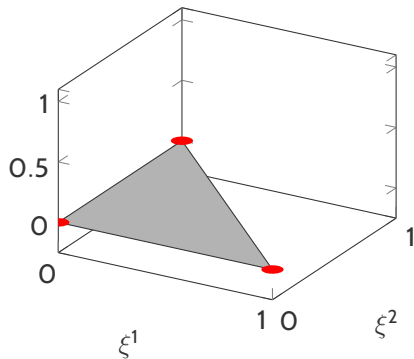
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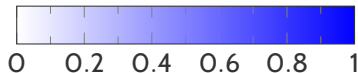
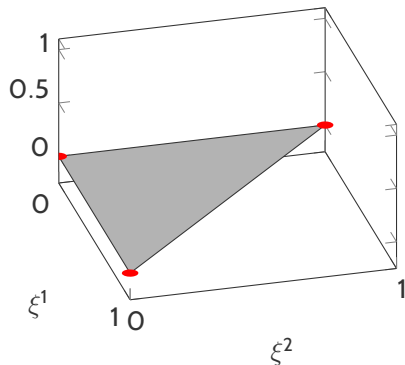
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Triangular (simplicial) basis

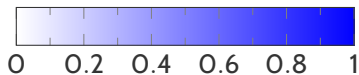
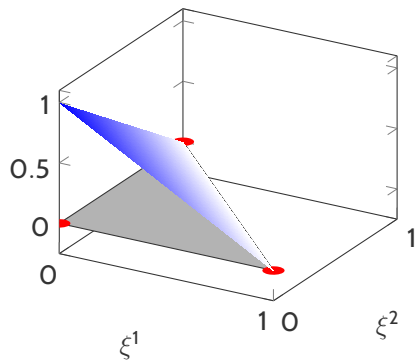


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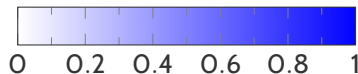
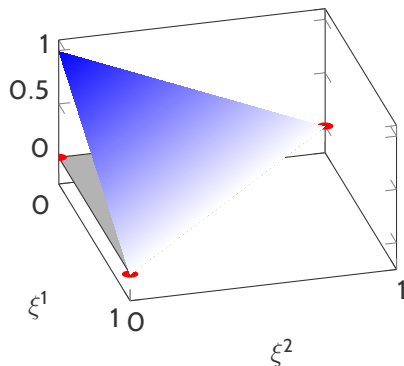


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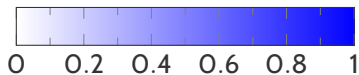
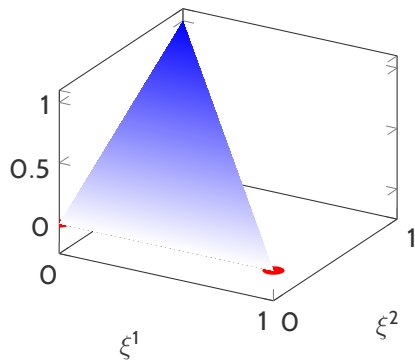


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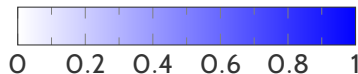
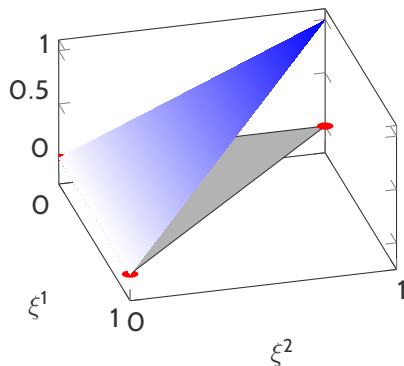


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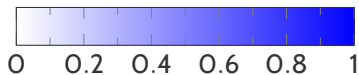
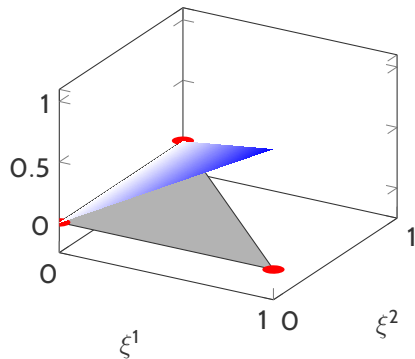


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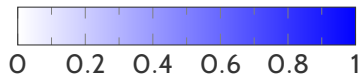
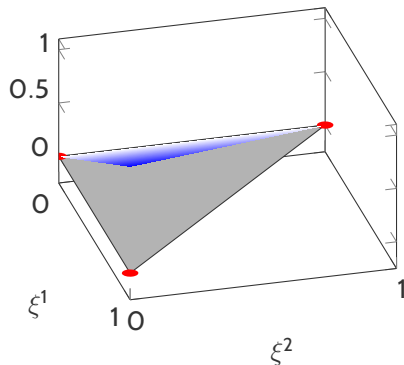


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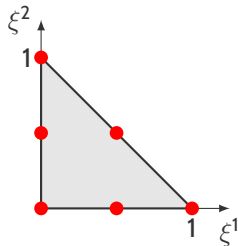
The elements of order  $p = 2$  have

$$n_{dof} = \frac{1}{2}(p+1)(p+2) = 6$$

DOFs which correspond to the function evaluation at the points  $\{x_i\}_{i=0}^5$  where

$$\mathbf{x} = (i/p, j/p), \quad 0 \leq i+j \leq p = 2$$

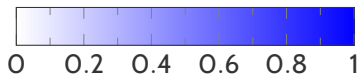
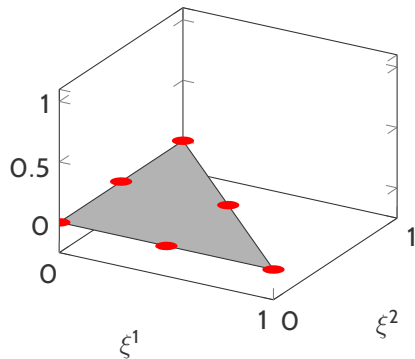
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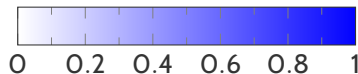
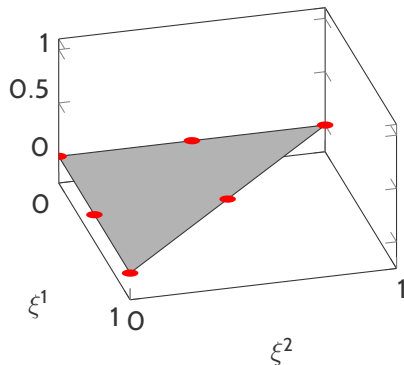


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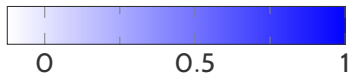
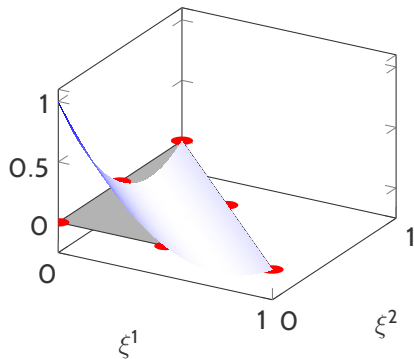


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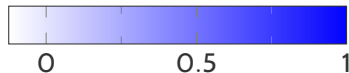
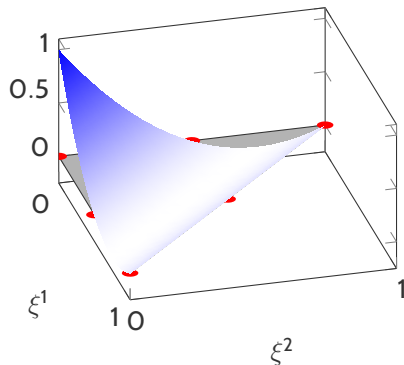


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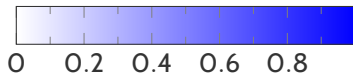
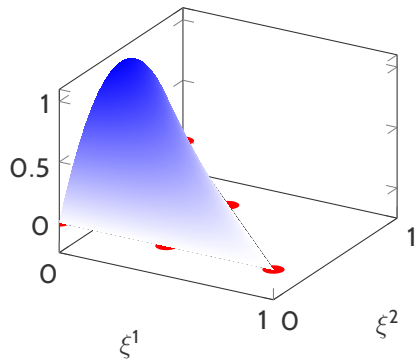


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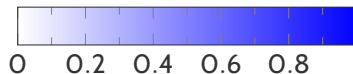
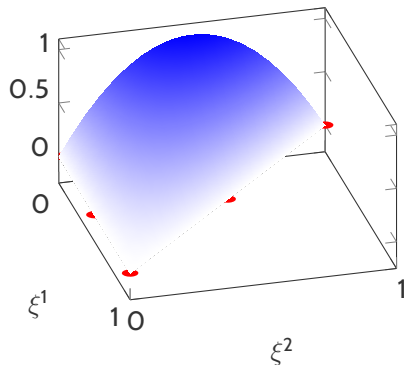


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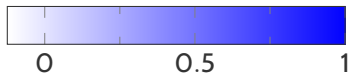
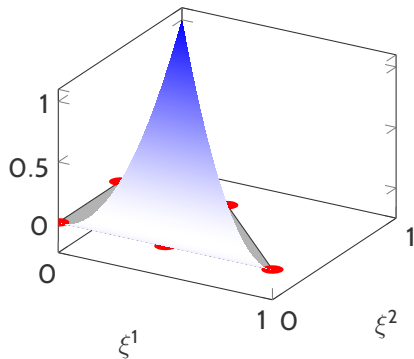


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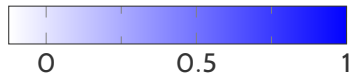
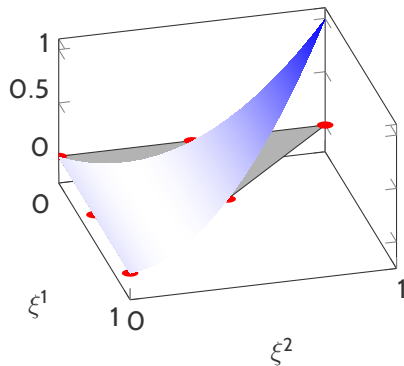


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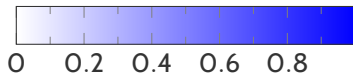
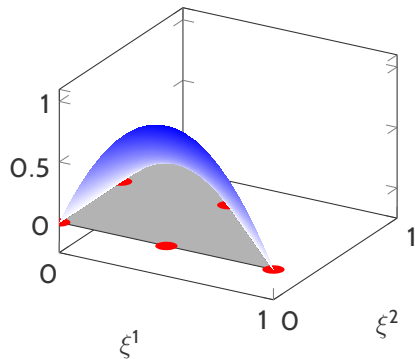


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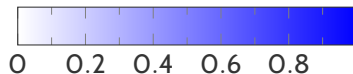
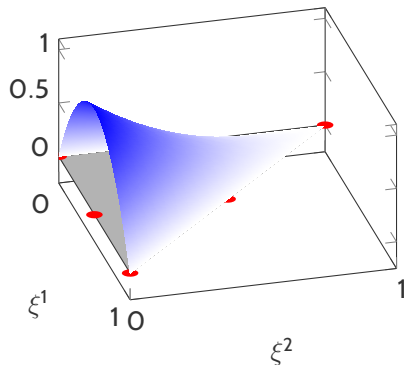


# The Local Element View

Triangular (simplicial) basis

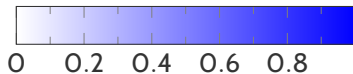
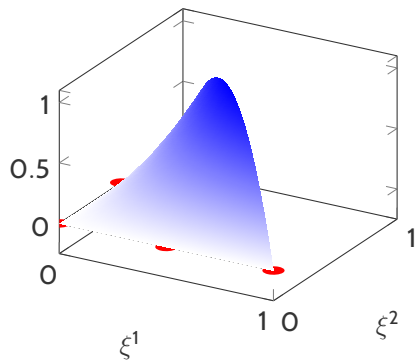


Triangular (simplicial) basis

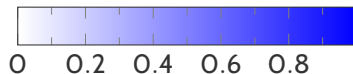
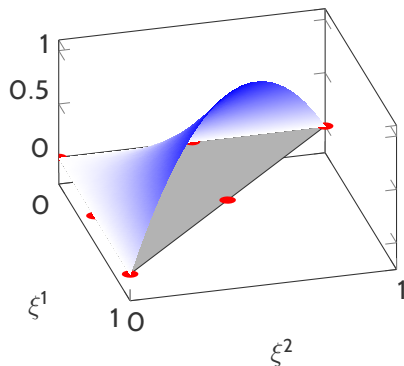


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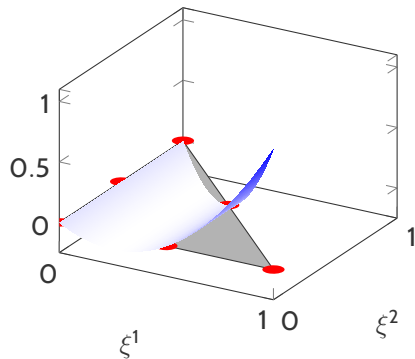


Triangular (simplicial) basis

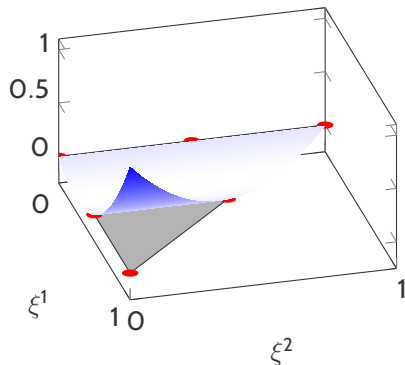


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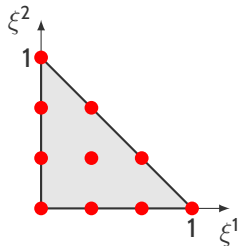
The elements of order  $p = 3$  have

$$n_{dof} = \frac{1}{2}(p+1)(p+2) = 10$$

DOFs which correspond to the function evaluation at the points  $\{x_i\}_{i=0}^9$  where

$$\mathbf{x} = (i/p, j/p), \quad 0 \leq i+j \leq p = 3$$

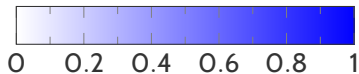
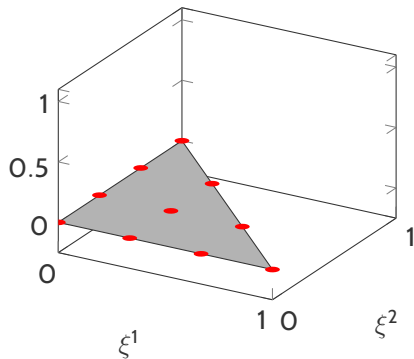
$$\hat{\phi}_a(\boldsymbol{\lambda}) = T_i(\lambda_1)T_j(\lambda_2)T_k(\lambda_3), \quad i, j, k = 0 \dots p$$



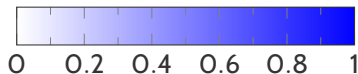
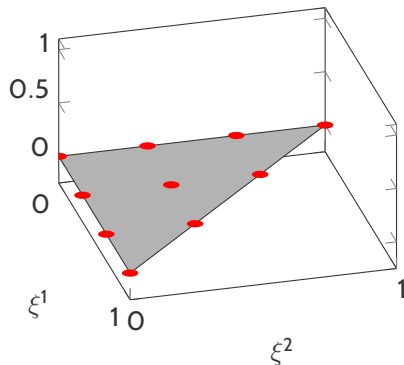


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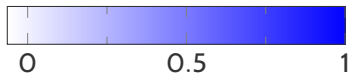
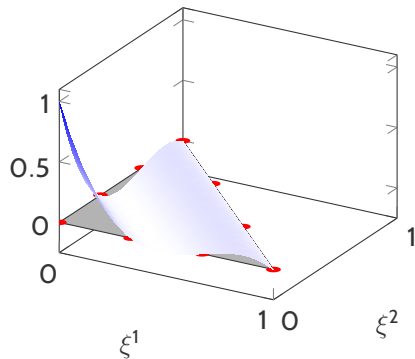


Triangular (simplicial) basis

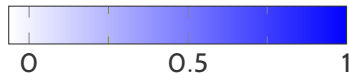
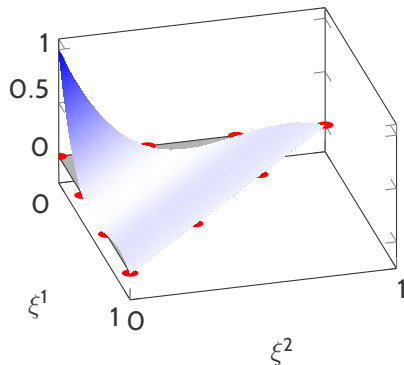


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Triangular (simplicial) basis

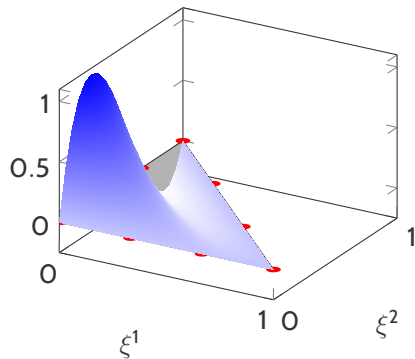


Triangular (simplicial) basis

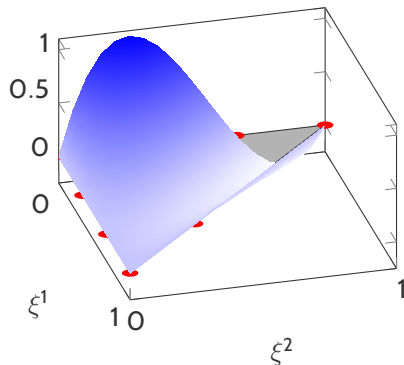


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Triangular (simplicial) basis

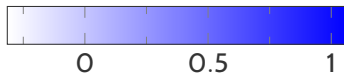
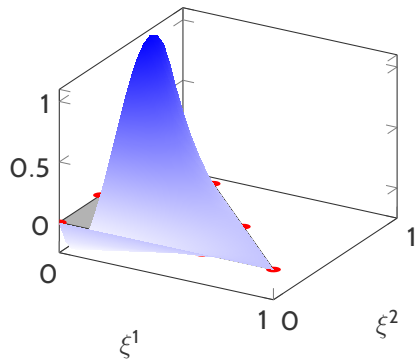


Triangular (simplicial) basis

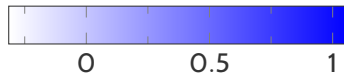
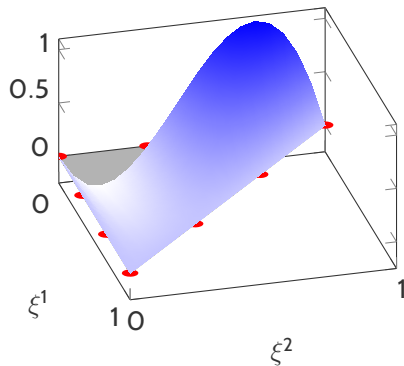


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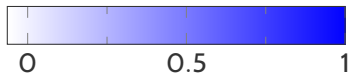
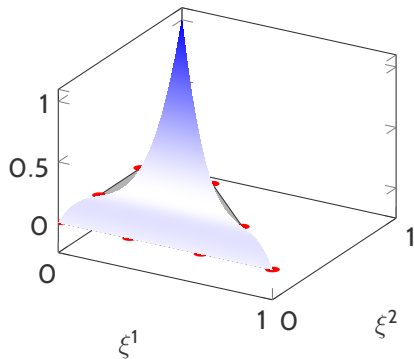


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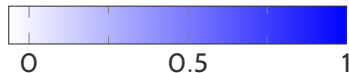
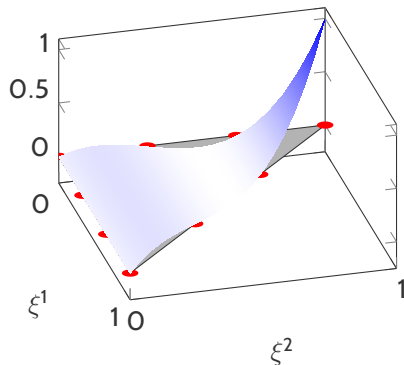


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Triangular (simplicial) basis

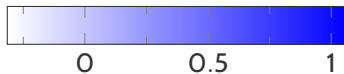
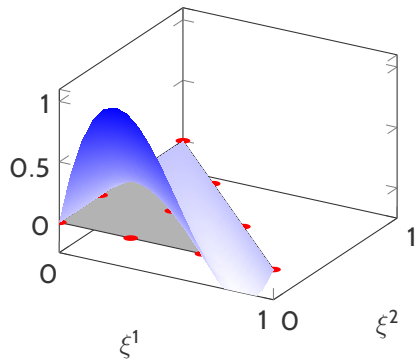


Triangular (simplicial) basis

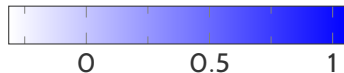
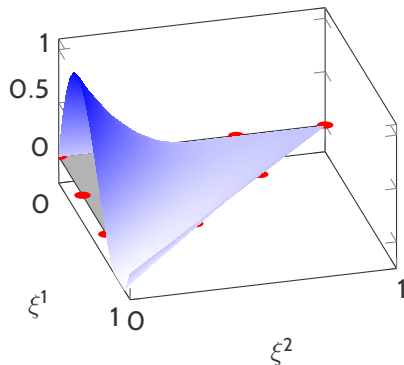


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Triangular (simplicial) basis

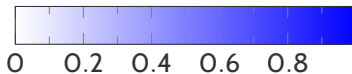
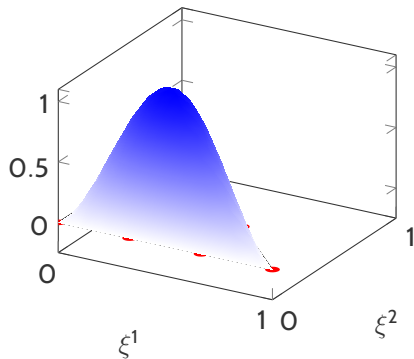


Triangular (simplicial) basis

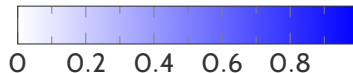
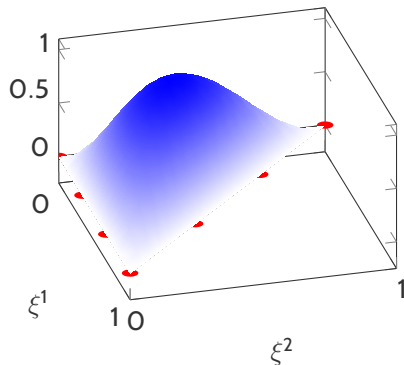


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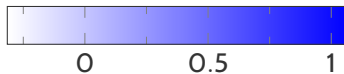
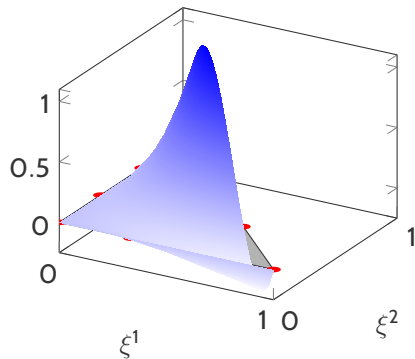


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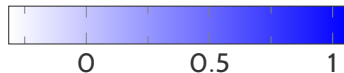
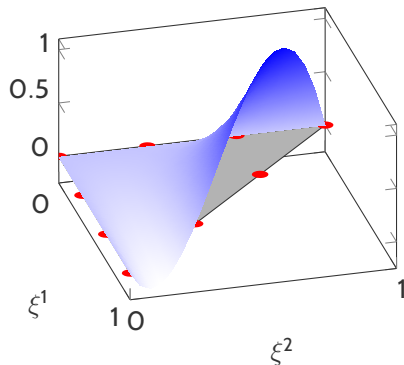


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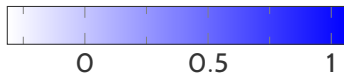
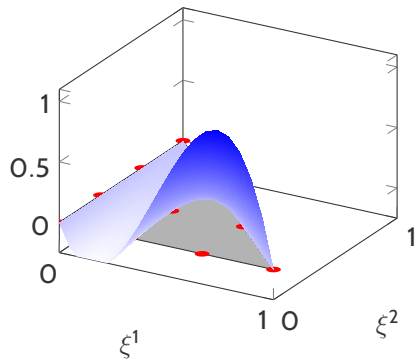
Triangular (simplicial) basis



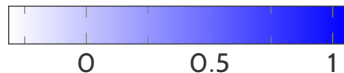
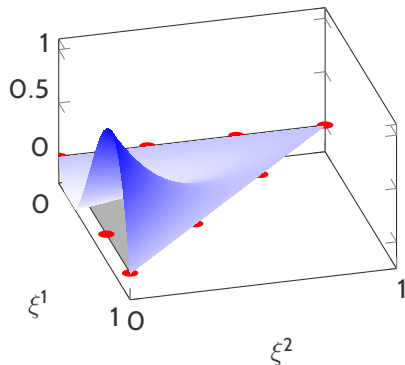


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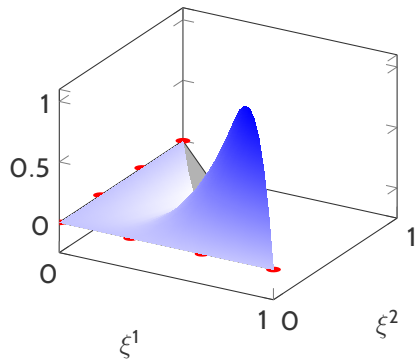


Triangular (simplicial) basis

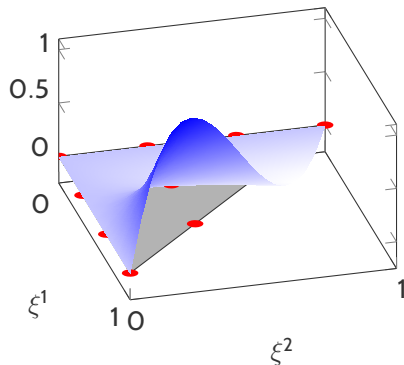


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Triangular (simplicial) basis

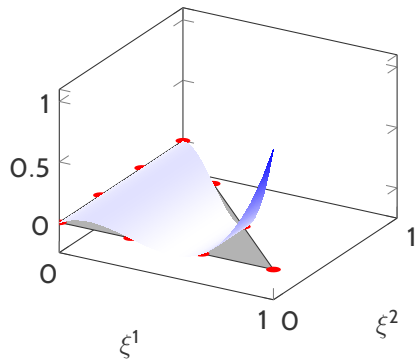


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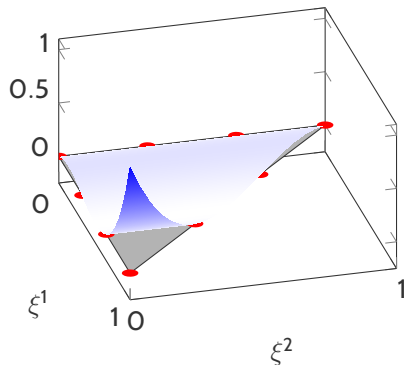


# The Local Element View

Triangular (simplicial) basis



Triangular (simplicial) basis



# NUMERICAL INTEGRATION

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# Numerical Integration

Let  $\mathcal{G}(\mathbf{x})$  be a function defined on  $\Omega^e$  and we would like to compute

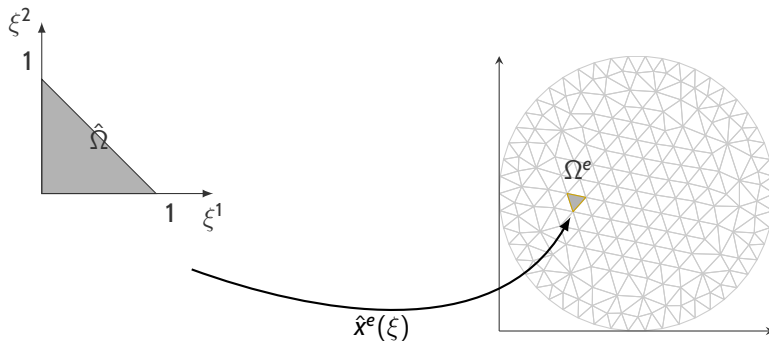
$$\int_{\Omega^e} \mathcal{G}(\mathbf{x}) d\Omega$$

# Numerical Integration

Recall that  $\hat{\mathbf{x}} : \hat{\Omega} \rightarrow \Omega^e$  where

$$\hat{\mathbf{x}}(\boldsymbol{\xi}) = \hat{\phi}_a(\boldsymbol{\xi}) \mathbf{x}_a$$

aka *isoparametric* mapping,  $\mathbf{x}_a$  are the coordinates (in physical space) of the DOFs.



# Numerical Integration

Let  $\mathcal{G}(\mathbf{x})$  be a function defined on  $\Omega^e$  and we would like to compute

$$\int_{\Omega^e} \mathcal{G}(\mathbf{x}) d\Omega$$

then with  $\hat{\mathbf{x}} : \hat{\Omega} \rightarrow \Omega^e$  with  $\hat{\Omega}$  being the unit triangle, we have that

$$\int_{\Omega^e} \mathcal{G}(\mathbf{x}) d\Omega = \int_{\hat{\Omega}} \mathcal{G}(\hat{\mathbf{x}}(\boldsymbol{\xi})) \hat{j}(\boldsymbol{\xi}) d\hat{\Omega}$$

where  $\hat{j}(\boldsymbol{\xi}) = \det(\nabla_{\boldsymbol{\xi}} \hat{\mathbf{x}}(\boldsymbol{\xi}))$ .

# Numerical Integration

We can re-write the integral as

$$\int_{\hat{\Omega}} \mathcal{G}(\hat{\mathbf{x}}(\xi)) \hat{j}(\xi) \, d\hat{\Omega} = \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2$$

We can then approximate the above as

$$\begin{aligned} \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2 \\ \approx \sum_{\xi^1, \xi^2 \in \mathcal{Q}} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \Delta \xi^1 \Delta \xi^2 \end{aligned}$$



# Numerical Integration

We can re-write the integral as

$$\int_{\hat{\Omega}} \mathcal{G}(\hat{\mathbf{x}}(\xi)) \hat{j}(\xi) \, d\hat{\Omega} = \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2$$

We can then approximate the above as

$$\begin{aligned} \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2 \\ = \sum_{(\xi_o^1, \xi_o^2) \in \mathcal{Q}} \mathcal{G}(\hat{\mathbf{x}}_o) \hat{j}(\xi_o) \omega_o \end{aligned}$$

# Numerical Integration

We can re-write the integral as

$$\int_{\hat{\Omega}} \mathcal{G}(\hat{\mathbf{x}}(\xi)) \hat{j}(\xi) \, d\hat{\Omega} = \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2$$

We can then approximate the above as

$$\int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2$$

$$= \sum_{(\xi_0^1, \xi_0^2) \in \mathcal{Q}} \mathcal{G}(\hat{\mathbf{x}}(\xi_0^1, \xi_0^2)) \hat{j}(\xi_0^1, \xi_0^2) \omega_{\xi_0^1, \xi_0^2}$$

# Numerical Integration

We can re-write the integral as

$$\int_{\hat{\Omega}} \mathcal{G}(\hat{\mathbf{x}}(\xi)) \hat{j}(\xi) \, d\hat{\Omega} = \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2$$

We can then approximate the above as

$$\begin{aligned} \int_0^1 \int_0^{1-\xi^2} \mathcal{G}(\hat{\mathbf{x}}(\xi^1, \xi^2)) \hat{j}(\xi^1, \xi^2) \, d\xi^1 d\xi^2 \\ = \sum_{(\tilde{\xi}_Q, \omega_Q) \in \mathcal{Q}} \mathcal{G}(\hat{\mathbf{x}}(\tilde{\xi}_Q)) \hat{j}(\tilde{\xi}_Q) \omega_Q \end{aligned}$$