# **DIRECT STIFFNESS METHODS**

**BEAMS AND BEAM-COLUMNS** 

Maurizio M. Chiaramonte



We arrived at the beam governing equation as

$$\frac{d}{dx^2}\left(EI\frac{dv}{dx^2}\right) = -q(x), \quad \forall x$$

where v is our beam displacement. Where

$$m(x) = \left(EI\frac{dv}{dx^2}\right) \leftarrow \text{Internal moment}$$
 $f(x) = \frac{d}{dx}\left(EI\frac{dv}{dx^2}\right) \leftarrow \text{Internal shear}$ 

The analytical solution of the beam equation becomes

$$v(x) = N_1(x) v_i + N_2(x) \theta_i + N_3(x) v_j + N_4(x) \theta_j$$

where

$$\begin{aligned} N_{1}(x) &= 1 - 3\left(\frac{x}{\ell}\right)^{2} + 2\left(\frac{x}{\ell}\right)^{3} \\ N_{2}(x) &= \ell \left[\left(\frac{x}{\ell}\right) - 2\left(\frac{x}{\ell}\right)^{2} + \left(\frac{x}{\ell}\right)^{3}\right] \\ N_{3}(x) &= 3\left(\frac{x}{\ell}\right)^{2} - 2\left(\frac{x}{\ell}\right)^{3} \\ N_{4}(x) &= \ell \left[\left(\frac{x}{\ell}\right)^{3} - \left(\frac{x}{\ell}\right)^{2}\right] \end{aligned}$$

$$\left\{ \begin{array}{l} V_i \\ M_i \\ V_j \\ M_j \end{array} \right\} = \left[ \begin{array}{l} N_1'''(0) & N_2'''(0) & N_3'''(0) & N_4'''(0) \\ -N_1''(0) & -N_2''(0) & -N_3''(0) & -N_4''(0) \\ -N_1'''(L) & -N_2''(L) & -N_3''(L) & -N_4''(L) \\ N_1''(L) & N_2''(L) & N_3''(L) & N_4''(L) \end{array} \right] \left\{ \begin{array}{l} v_i \\ \theta_i \\ v_j \\ \theta_j \end{array} \right\}.$$

$$\left\{ \begin{array}{l} V_i \\ M_i \\ V_j \\ M_j \end{array} \right\} = \left[ \begin{array}{c} N_1'''(0) & N_2'''(0) & N_3'''(0) & N_4'''(0) \\ -N_1''(0) & -N_2''(0) & -N_3''(0) & -N_4''(0) \\ -N_1''(L) & -N_2''(L) & -N_3''(L) & -N_4''(L) \\ N_1''(L) & N_2''(L) & N_3''(L) & N_4''(L) \end{array} \right] \left\{ \begin{array}{l} v_i \\ \theta_i \\ v_j \\ \theta_j \end{array} \right\}.$$

$$\left\{ \begin{array}{l} V_i \\ M_i \\ V_j \\ M_j \end{array} \right\} = \left[ \begin{array}{l} N_1'''(0) & N_2'''(0) & N_3'''(0) & N_4'''(0) \\ -N_1''(0) & -N_2''(0) & -N_3''(0) & -N_4''(0) \\ -N_1'''(L) & -N_2'''(L) & -N_3'''(L) & -N_4'''(L) \\ N_1''(L) & N_2''(L) & N_3''(L) & N_4''(L) \end{array} \right] \left\{ \begin{array}{l} v_i \\ \theta_i \\ v_j \\ \theta_j \end{array} \right\}.$$

$$\left\{ \begin{array}{l} V_i \\ M_i \\ V_j \\ M_j \end{array} \right\} = \left[ \begin{array}{c} N_1'''(\mathsf{O}) & N_2'''(\mathsf{O}) & N_3'''(\mathsf{O}) & N_4'''(\mathsf{O}) \\ -N_1''(\mathsf{O}) & -N_2''(\mathsf{O}) & -N_3''(\mathsf{O}) & -N_4''(\mathsf{O}) \\ -N_1'''(\mathsf{L}) & -N_2'''(\mathsf{L}) & -N_3'''(\mathsf{L}) & -N_4'''(\mathsf{L}) \\ N_1''(\mathsf{L}) & N_2''(\mathsf{L}) & N_3''(\mathsf{L}) & N_4''(\mathsf{L}) \end{array} \right] \left\{ \begin{array}{c} v_i \\ \theta_i \\ v_j \\ \theta_j \end{array} \right\}.$$

The nodal equilibrium equations then reduce

$$\left\{ \begin{array}{c} V_i \\ M_i \\ V_j \\ M_j \end{array} \right\} = \left[ \begin{array}{cccc} k_{fv} & k_{f\theta} & -k_{fv} & k_{f\theta} \\ k_{mv} & k_{m\theta} & -k_{m\theta} & \hat{k}_{m\theta} \\ k_{fv} & -k_{f\theta} & -k_{fv} & -k_{f\theta} \\ k_{mv} & \hat{k}_{m\theta} & -k_{mv} & k_{m\theta} \end{array} \right] \left\{ \begin{array}{c} v_i \\ \theta_i \\ v_j \\ \theta_j \end{array} \right\}$$

where

$$k_{\text{fv}} = \frac{12EI}{\ell^3}, \quad k_{\text{mv}} = k_{\text{f}\theta} = \frac{6EI}{\ell^2}, \quad k_{\text{m}\theta} = \frac{4EI}{\ell}, \quad \hat{k}_{\text{m}\theta} \frac{2EI}{\ell}$$





## Frame Elements

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