

## LECTURE 7:

### - METRIC CHANGES CONTINUED

#### EXAMPLES OF METRIC CHANGES

$$\underline{\phi}(\underline{x}) = (x_1 + \alpha x_2^2) \underline{e}_1 + x_2 \underline{e}_2$$

EG. (STRETCH RATIO)

$$\begin{aligned} \begin{bmatrix} \underline{F} \\ \underline{e} \end{bmatrix} &= \begin{bmatrix} 1 & 2\alpha x_2 \\ 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} \underline{C} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ \alpha x_2 & 1 \end{bmatrix} \begin{bmatrix} 1 & \alpha x_2 \\ 0 & 1 \end{bmatrix} = \\ &= \begin{bmatrix} 1 & 2\alpha x_2 \\ 2\alpha x_2 & 1 + 4\alpha x_2^2 \end{bmatrix} \end{aligned}$$

THE STRETCH  $\underline{X}_p = 0.5(\underline{e}_1 + \underline{e}_2)$  IN  
 $\underline{e}_1$  &  $\underline{e}_2$  &  $\underline{e}_1 + \underline{e}_2$

$$\lambda(\underline{e}_1, \underline{x}_p) = \sqrt{\begin{bmatrix} 1 \\ 0 \end{bmatrix}^T \begin{bmatrix} 1 & \alpha \\ \alpha & 1+\alpha \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}} = 1 \quad \leftarrow \text{NO STRETCH!} \checkmark$$

$$\lambda(\underline{e}_2, \underline{x}_p) = \sqrt{\begin{bmatrix} 0 \\ 1 \end{bmatrix}^T \begin{bmatrix} 1 & \alpha \\ \alpha & 1+\alpha \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}} = 1 + \alpha$$

$$\lambda\left(\frac{\underline{e}_1 + \underline{e}_2}{\sqrt{2}}, \underline{x}_p\right) = \frac{1}{\sqrt{2}} \sqrt{\begin{bmatrix} 1 \\ 1 \end{bmatrix}^T \begin{bmatrix} 1 & \alpha \\ \alpha & 1+\alpha \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}} = \sqrt{\frac{2+3\alpha}{2}}$$

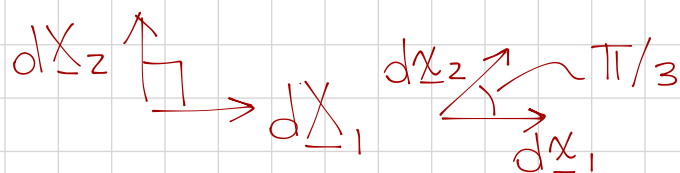
# EXAMPLE: (CHANGE IN ANGLE)

$$\underline{N}_1 = \underline{E}_1, \quad \underline{N}_2 = \underline{E}_2, \quad \underline{X}_P = 0.5 (\underline{E}_1 + \underline{E}_2)$$

$$\cos \theta = \frac{\begin{bmatrix} 1 \\ 0 \end{bmatrix}^T \begin{bmatrix} 1 & \alpha \\ \alpha & 1+\alpha \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}}{1+\alpha} = \frac{\alpha}{1+\alpha}$$

$$\text{if } \alpha = 1$$

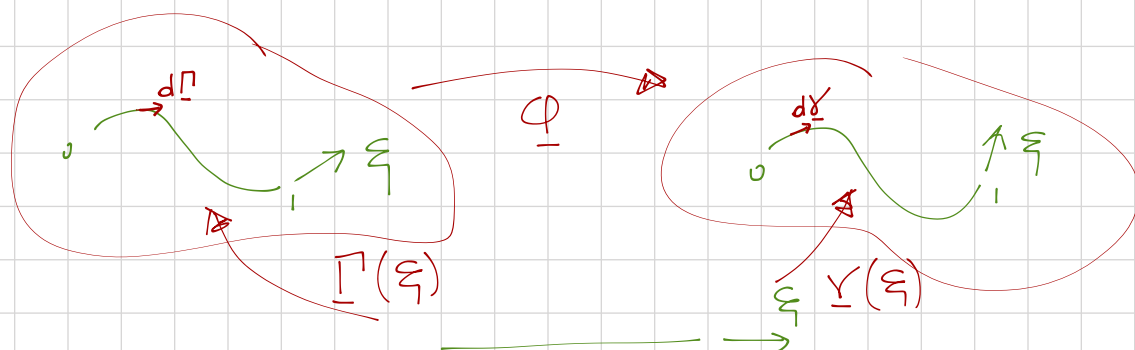
$$\theta = \frac{1}{3}\pi = 60^\circ$$



# DEFORMED CURVES

$$\text{LET } \underline{\Gamma}(\xi): [0,1] \rightarrow \Sigma_0, \quad \underline{\gamma}(\xi) = \underline{\Phi}(\underline{\Gamma}(\xi))$$

WE ARE INTERESTED IN THE LENGTH OF  $\underline{\gamma}(\xi)$



$$l(\underline{\gamma}) = \int \|d\underline{\gamma}\| = \int_0^1 \|\underline{\gamma}'(\xi)\| d\xi$$

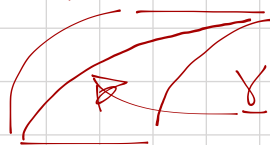
$$\underline{\gamma}'(\xi) = \underline{F}(\underline{\Gamma}(\xi)) \underline{\Gamma}'(\xi)$$

$$\|\underline{\gamma}'(\xi)\|^2 = \underline{\Gamma}'(\xi) \cdot \underline{C}(\underline{\Gamma}(\xi)) \underline{\Gamma}'(\xi)$$

$$\Rightarrow l(\underline{\gamma}) = \int_0^1 [\underline{\Gamma}'(\xi) \cdot \underline{C}(\underline{\Gamma}(\xi)) \underline{\Gamma}'(\xi)]^{1/2} d\xi$$

## EXAMPLE

CONSIDER  $\underline{\Gamma}(\xi) = \xi (\underline{E}_1 + \underline{E}_2)$



$$\underline{C} = \begin{bmatrix} 1 & 2\alpha X_2 \\ 2\alpha X_2 & 1 + 4\alpha X_2^2 \end{bmatrix} = \begin{bmatrix} 1 & 2\sqrt{2}\alpha \xi \\ 2\sqrt{2}\alpha \xi & 1 + 8\xi^2\alpha \end{bmatrix}$$

$$\underline{\Gamma}'(\xi) = (\underline{E}_1 + \underline{E}_2)$$

$$l(\underline{\gamma}) = \int_0^1 [2 + 4\sqrt{2}\alpha \xi + 8\xi^2\alpha] d\xi$$

$$= \left[ 2\xi + 2\sqrt{2}\alpha \xi^2 + \frac{8}{3}\xi^3\alpha \right]_0^1 = \left[ 2 + \alpha (2\sqrt{2} + 8/3) \right]^{1/2}$$

NOTE if  $\alpha=0$   $\sqrt{2}$  ✓

## DEFORMED VOLUMES

RECALL THAT

$$\underline{a} \cdot (\underline{b} \times \underline{c}) = a_i b_j c_k \epsilon_{ijk}$$

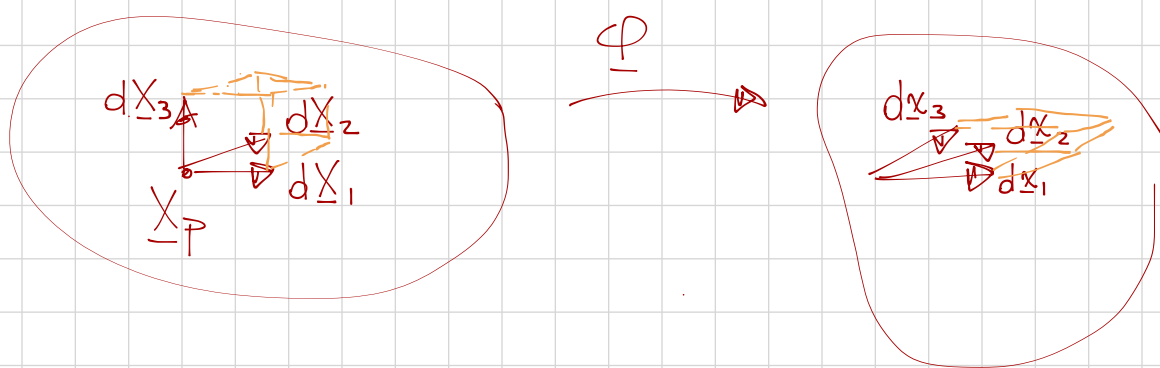
& THAT

$$\text{DET } \underline{\underline{A}} = \epsilon_{ijk} A_{i1} A_{j2} A_{k3}$$

OR EQUIVALENTLY

$$\epsilon_{pqr} \text{DET } \underline{\underline{A}} = \epsilon_{ijk} A_{ip} A_{jq} A_{kr}$$

NOW CONSIDER



$$dV_0 = |d\underline{X}_3 \cdot (d\underline{X}_1 \times d\underline{X}_2)| = |\epsilon_{IJK} dX_{3I} dX_{1J} dX_{2K}|$$

$$dV = |d\underline{x}_3 \cdot (d\underline{x}_1 \times d\underline{x}_2)| = |\epsilon_{ijk} dx_{3i} dx_{1j} dx_{2k}|$$

$$\text{NOW WITH } d\underline{x}_i = \underline{\underline{F}}(\underline{X}_P) d\underline{X}_i$$

$$dV = |\underline{\underline{F}} d\underline{X}_3 \cdot (\underline{\underline{F}} d\underline{X}_1 \times \underline{\underline{F}} d\underline{X}_2)| =$$

$$= |\epsilon_{ijk} F_{iP} dX_{3P} F_{jQ} dX_{1Q} F_{kR} dX_{2R}| =$$

$$= \underbrace{|\epsilon_{ijk} F_{iP} F_{jQ} F_{kR}|}_{\epsilon_{pqr} \text{DET } \underline{\underline{F}}} dX_{3P} dX_{1Q} dX_{2R} =$$

$$= |\text{DET } \underline{\underline{F}}| \epsilon_{pqr} dX_{3P} dX_{1Q} dX_{2R} =$$

$$= \underbrace{\text{DET } \underline{\underline{F}}}_{>0} dV_0$$

DET  $\underline{\underline{F}}$  IS OFTEN DENOTED AS  $J$  & TERMED THE JACOBIAN.

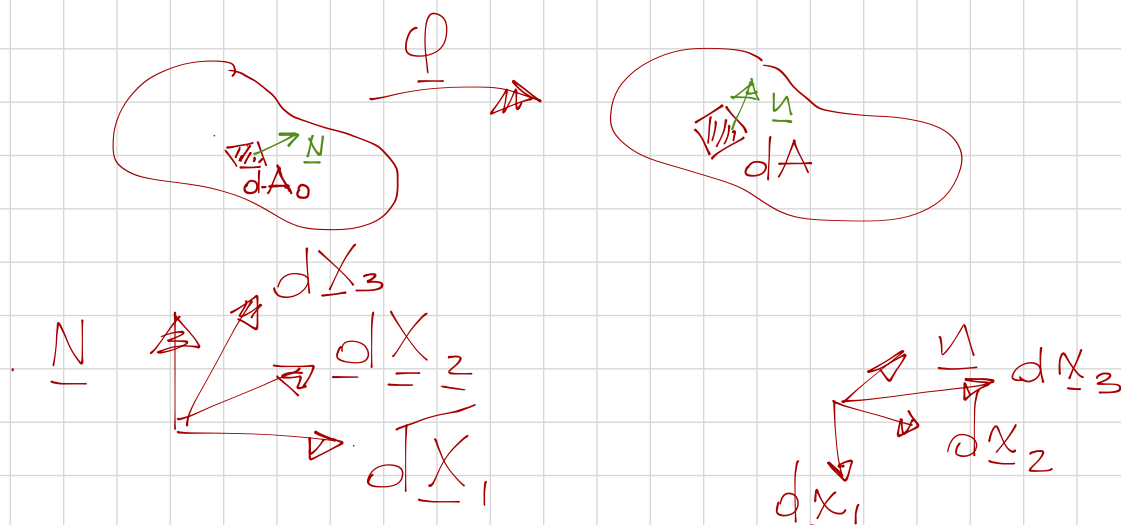
EXAMPLE:  $\phi(\underline{x}) = \alpha \underline{x}$ ,  $\Sigma_0 = [-1, 1]^3$

$$\underline{\underline{F}} = \alpha \underline{\underline{1}} \Rightarrow \det(\alpha \underline{\underline{1}}) = \alpha^3$$

$$V = \int_{\Sigma} dV = \int_{\Sigma_0} J dV_0 = \alpha^3 8$$

## DEFORMED AREAS

CONSIDER AN AREA ELEMENT IN THE REFERENCE CONFIGURATION  $dA_0$  WITH A UNIT NORMAL  $\underline{N}$  AND CORRESPONDING  $dA$  &  $\underline{n}$



SUCH THAT

$$dA_0 \underline{N} = d\underline{x}_1 \times d\underline{x}_2 \quad dA \underline{n} = d\underline{x}_1 \times d\underline{x}_2$$

NOW CONSIDER THE VOLUME GIVEN BY

$$dV_0 = d\underline{x}_3 \cdot (dA_0 \underline{N}) = \frac{1}{J} dV = \frac{1}{J} d\underline{x}_3 \cdot (dA \underline{n})$$

$$\Rightarrow \int dA_0 d\underline{x}_3 \cdot \underline{N} - dA d\underline{x}_3 \cdot \underline{n} = 0$$

$$\Rightarrow \int dA_0 d\underline{x}_3 \cdot \underline{N} - dA \underline{\underline{F}}^T d\underline{x}_3 \cdot \underline{n} = 0$$

$$\Rightarrow d\underline{x}_3 \cdot (J dA_0 \underline{N} - dA \underline{\underline{F}}^T \underline{n}) = 0$$

$$\Rightarrow \int \underline{N} dA_0 = dA \underline{F}^T \underline{u}$$

$$\Rightarrow \int \underline{F}^T \underline{N} dA_0 = dA \underline{u}$$

$$\Rightarrow \|\int \underline{F}^T \underline{N}\| dA_0 = dA \quad (\|\underline{u}\|=1)$$