

Gradients, Phase and Magnetisation

FMRIB Graduate Course
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Outline

Simple model of magnetisation behaviour

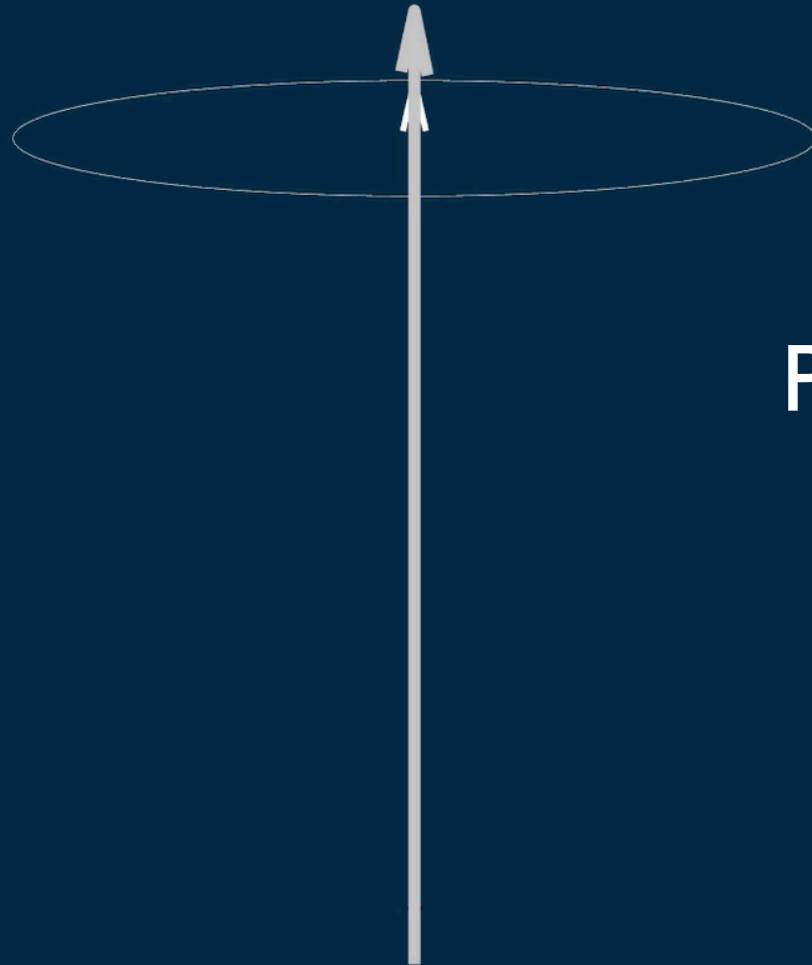
Action of magnetisation in response to gradient magnetic fields

Fourier Transform intuition

Role of gradients in an imaging experiment

Magnetisation

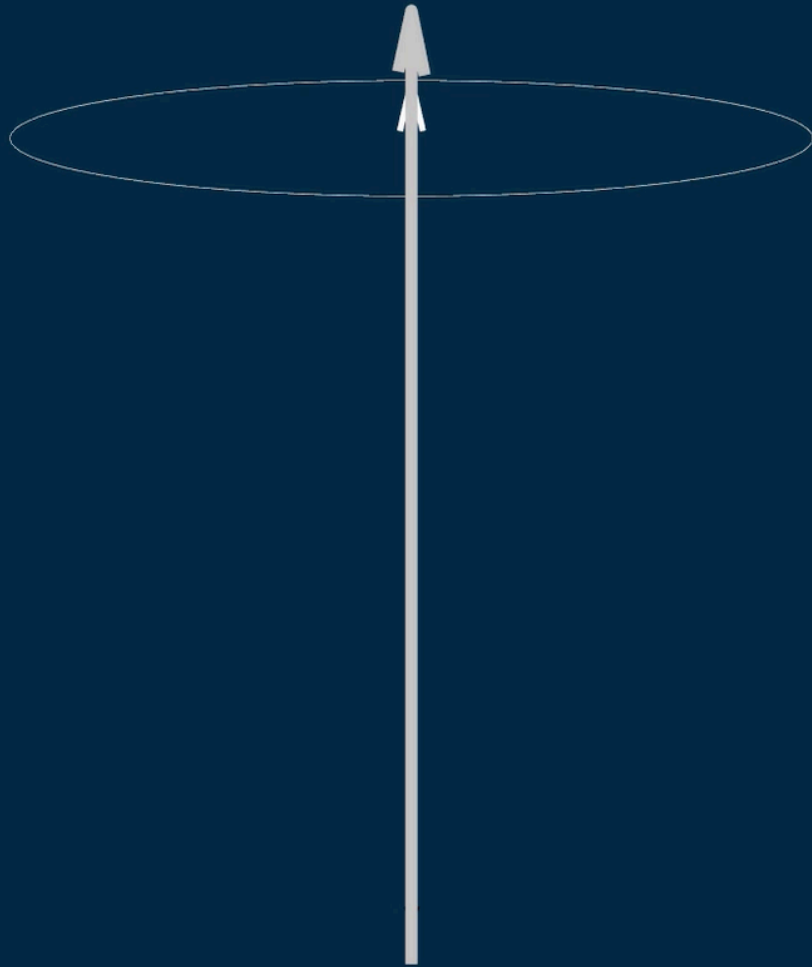
B_0 Magnetic Field Direction



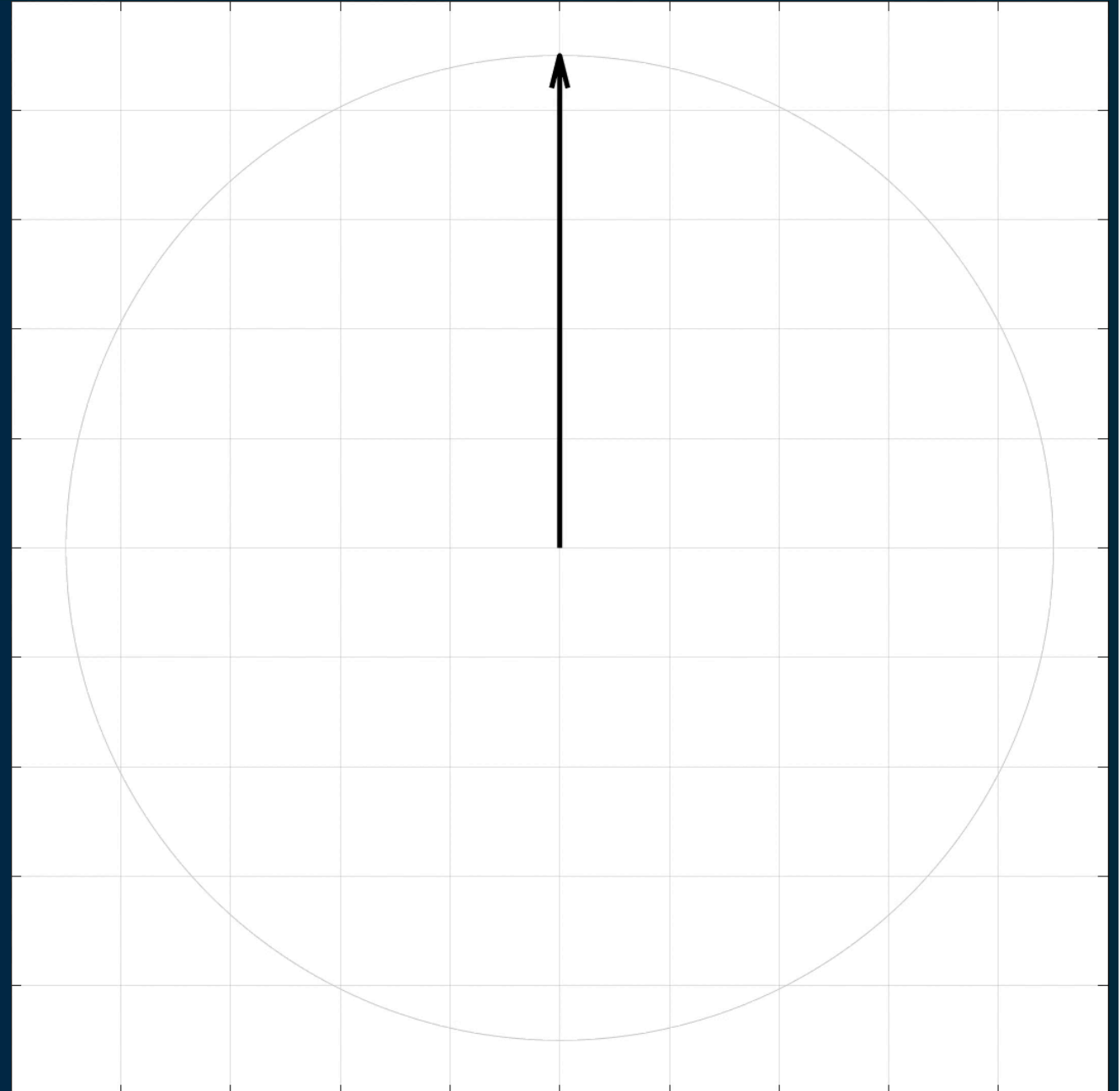
Precessing / Rotating
Magnetisation
within each voxel

Transverse (x-y) Magnetisation

Transverse Magnetisation

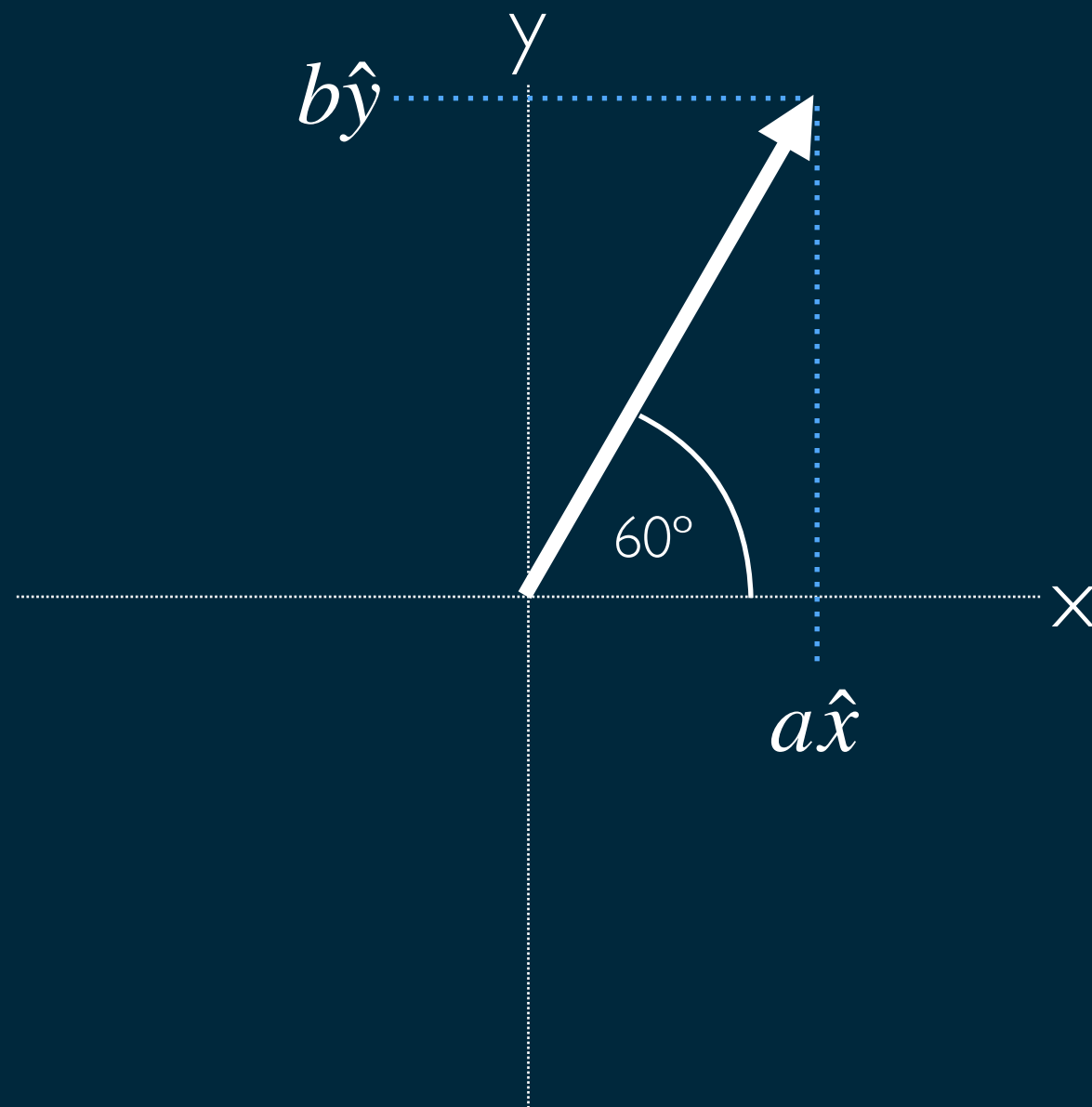


3D View



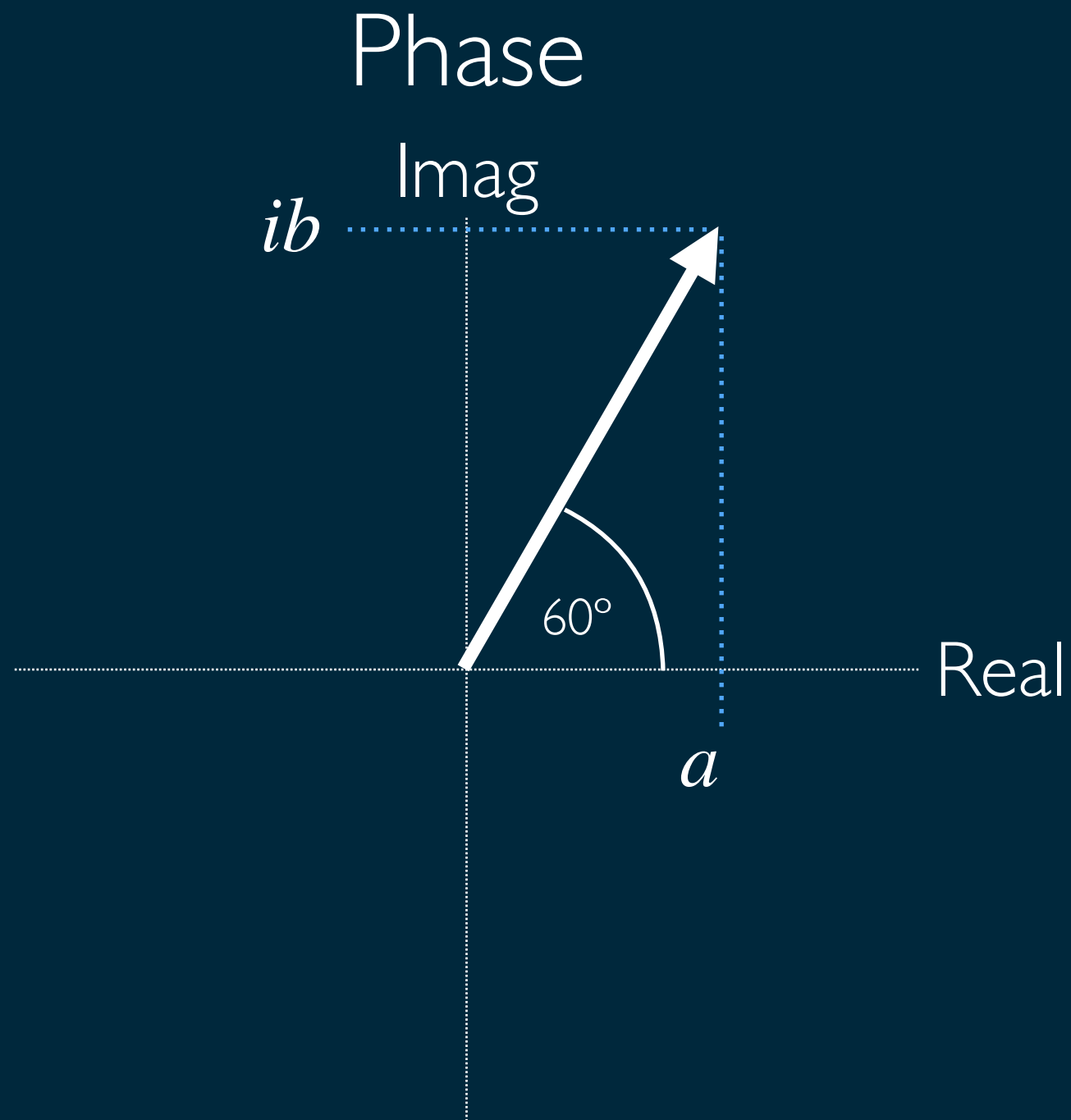
Component in x-y plane

Phase



$$M = (a, b)$$

Angle / Rotation / Orientation / Direction of Magnetisation



$$M = a + ib$$

Can be represented using complex numbers

Larmor Equation

$$\omega = \gamma \times B$$

This equation describes the speed of rotation (precession)
for the magnetisation

Larmor Equation

$$\omega = \gamma \times B$$

Frequency

Frequency is the speed of rotation

Larmor Equation

Gyromagnetic Ratio

$$\omega = \gamma \times B$$

Frequency

The gyromagnetic ratio is a physical constant

$$\gamma_{1H} \approx 2\pi \cdot 42.5 \text{ MHz/T}$$

Larmor Equation

Gyromagnetic Ratio

$$\omega = \gamma \times B$$

Frequency

Magnetic Field Strength

Strength of the **total** magnetic field

Larmor Equation

$$\omega = \gamma \times B$$

Frequency	Main Magnetic Field Strength
~64 MHz	1.5 T
~128 MHz	3.0 T
~300 MHz	7.0 T

Larmor Equation

$$\omega = \gamma \times B$$

Frequency

Main Magnetic Field Strength

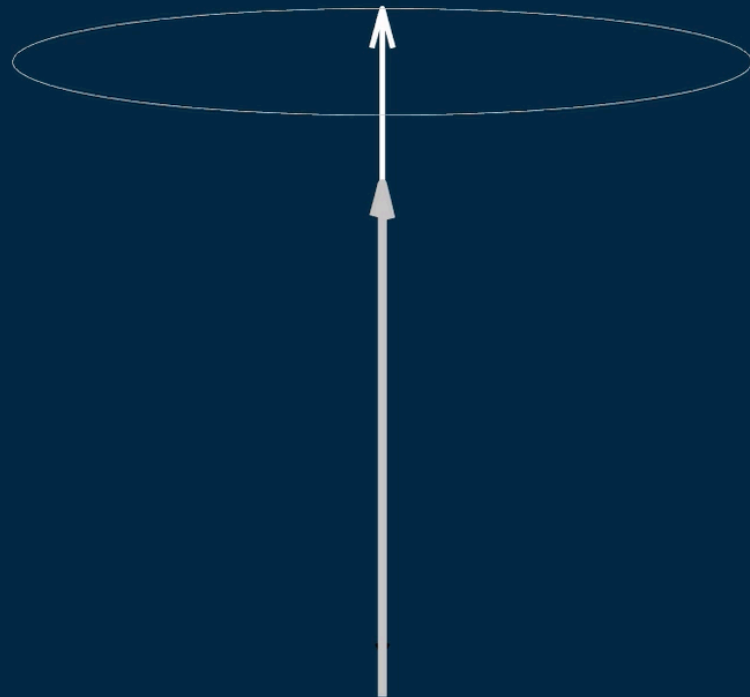
Slower

Weaker

Faster

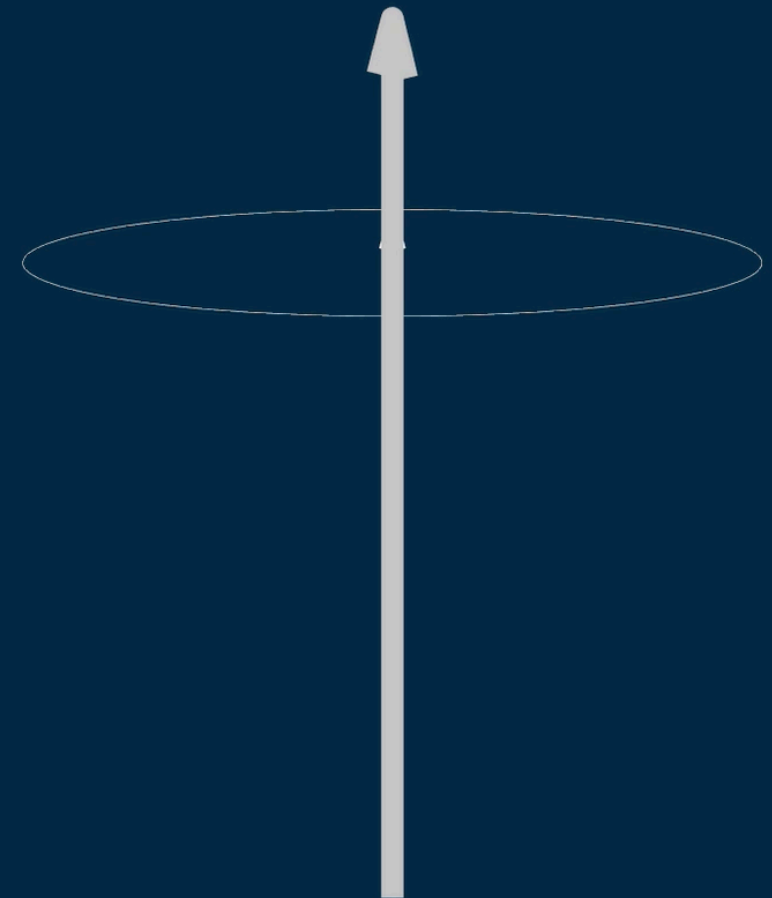
Stronger

Weaker Field



Slower Precession

Stronger Field



Faster Precession

Weaker Field



Slower Precession

Stronger Field

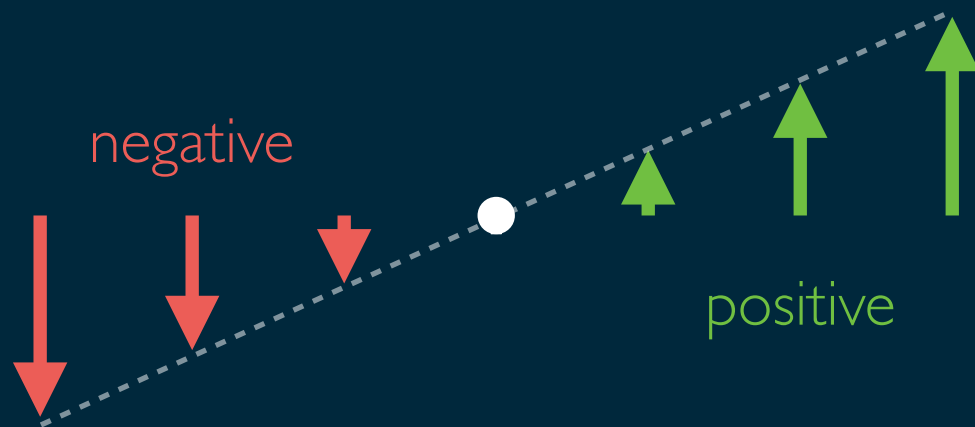


Faster Precession

Sources of Magnetic Fields



B_0 Main Magnetic Field
Constant Strength
Always On

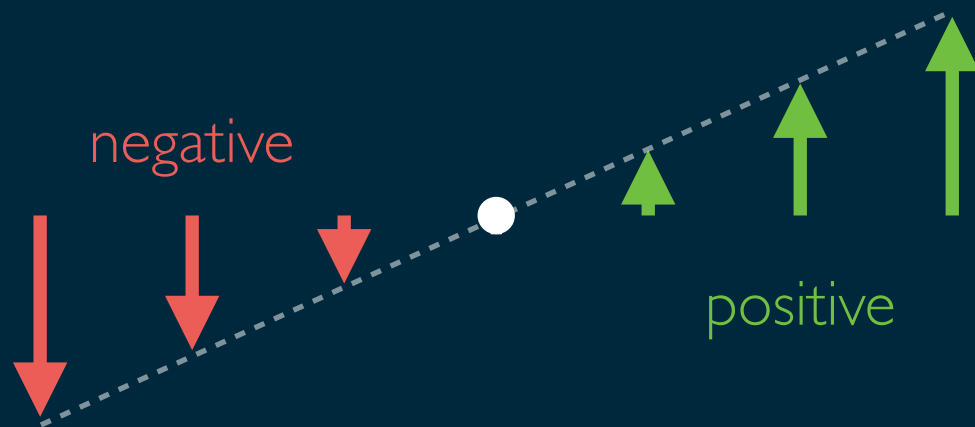


Gradient Magnetic Fields ($G_{x/y/z}$)
Spatially varying strength
Can turn on and off

Sources of Magnetic Fields



B_0 Main Magnetic Field
Constant Strength
Always On



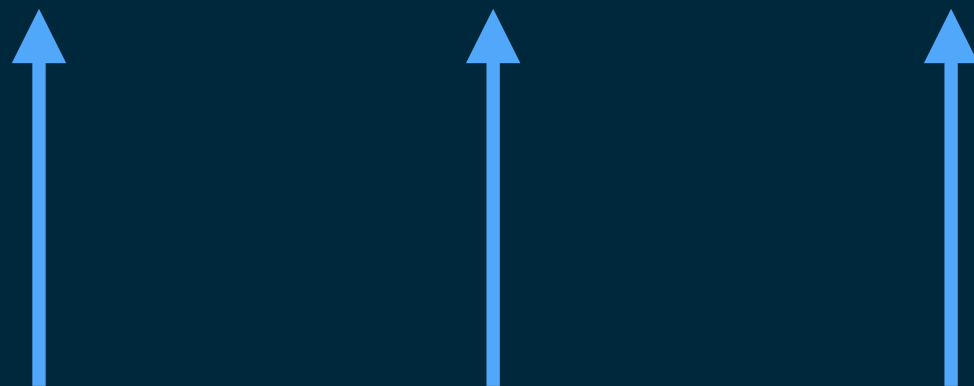
Gradient Magnetic Fields ($G_{x/y/z}$)
Spatially varying strength
Can turn on and off

Total Magnetic Field



Equal Strength

Magnetic Field with Gradient **OFF**



Equal Speed

Magnetisation Precession

Total Magnetic Field

Magnetic Field with Gradient ON

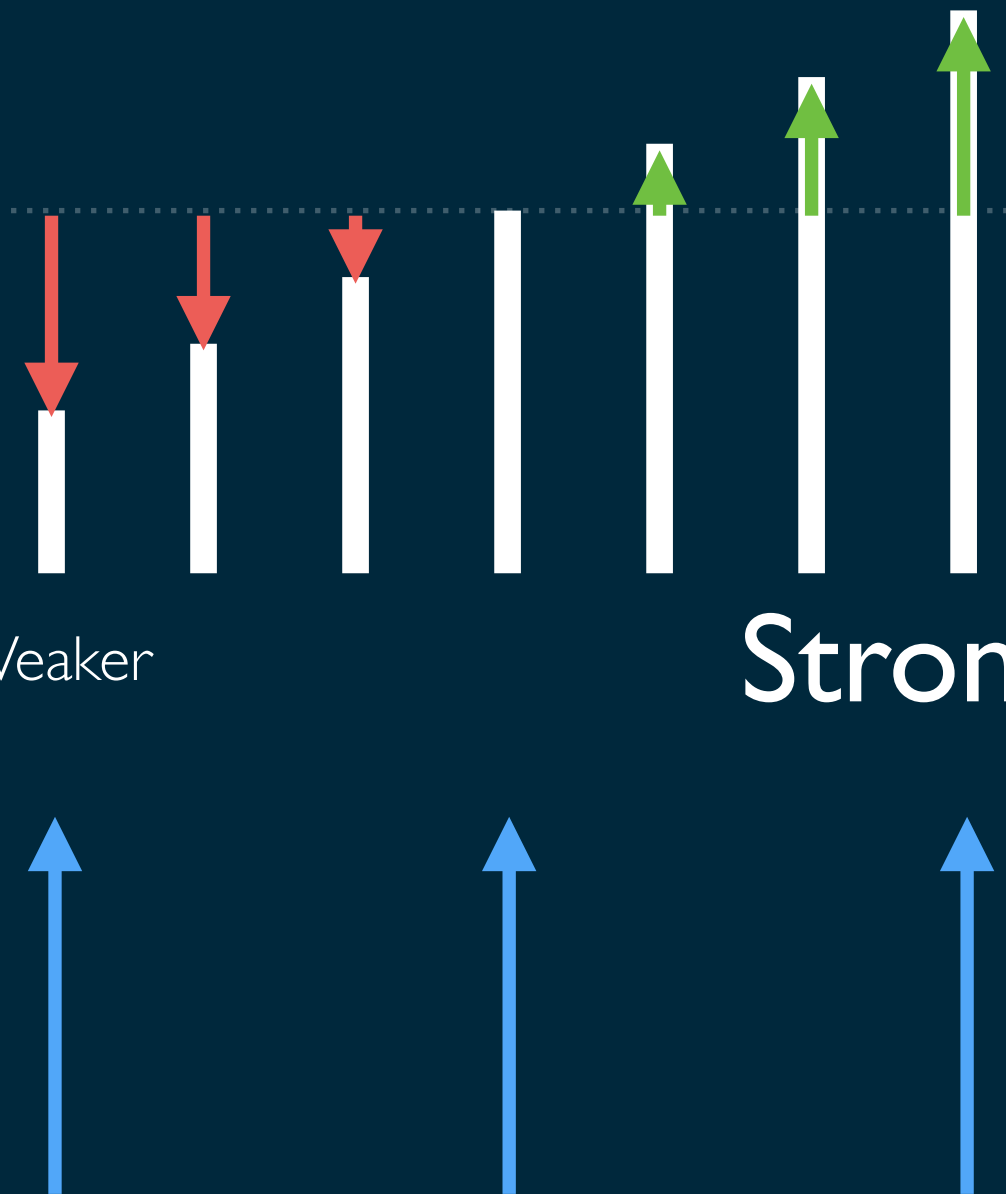
Weaker

Stronger

Magnetisation Precession

Slower

Faster



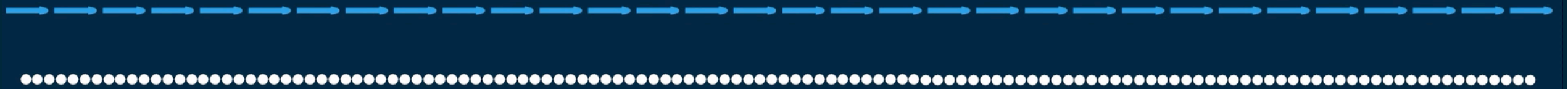
Total Magnetic Field

Stronger

Weaker

left ($-x$)

right ($+x$)



Slower

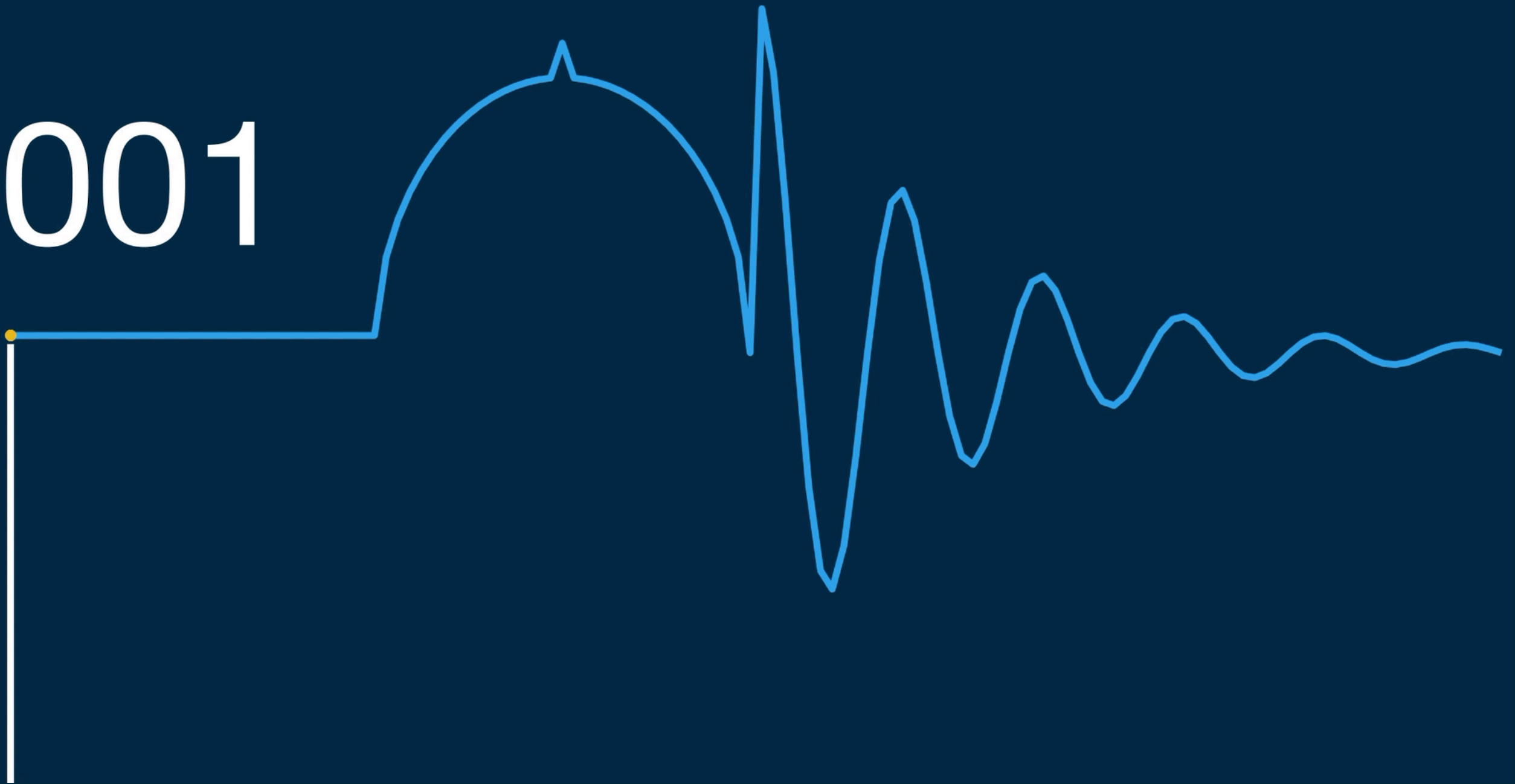
Faster

Gradients cause precession rate to change across space

“Wave-like” spatial patterns of phase emerge at any given time

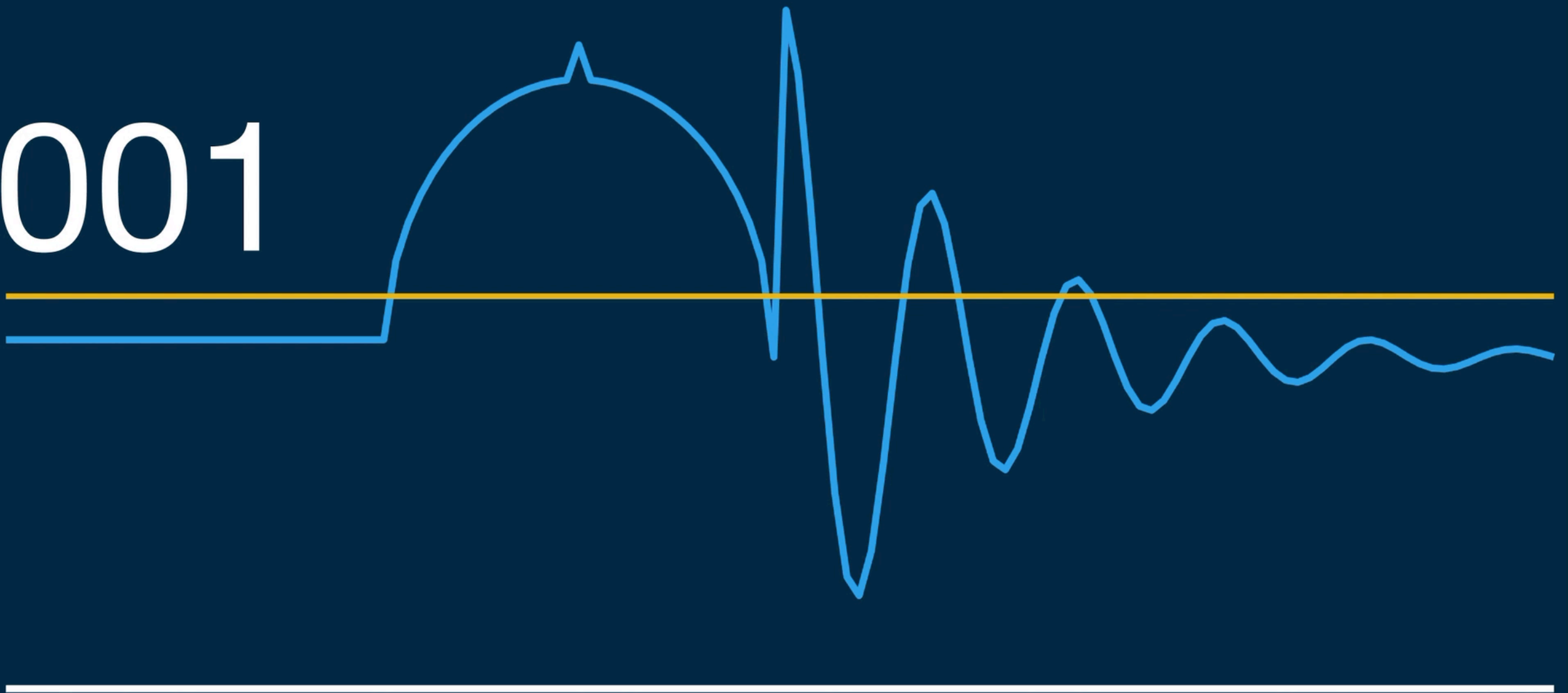
Representing Signals

001



Representing Signals

001

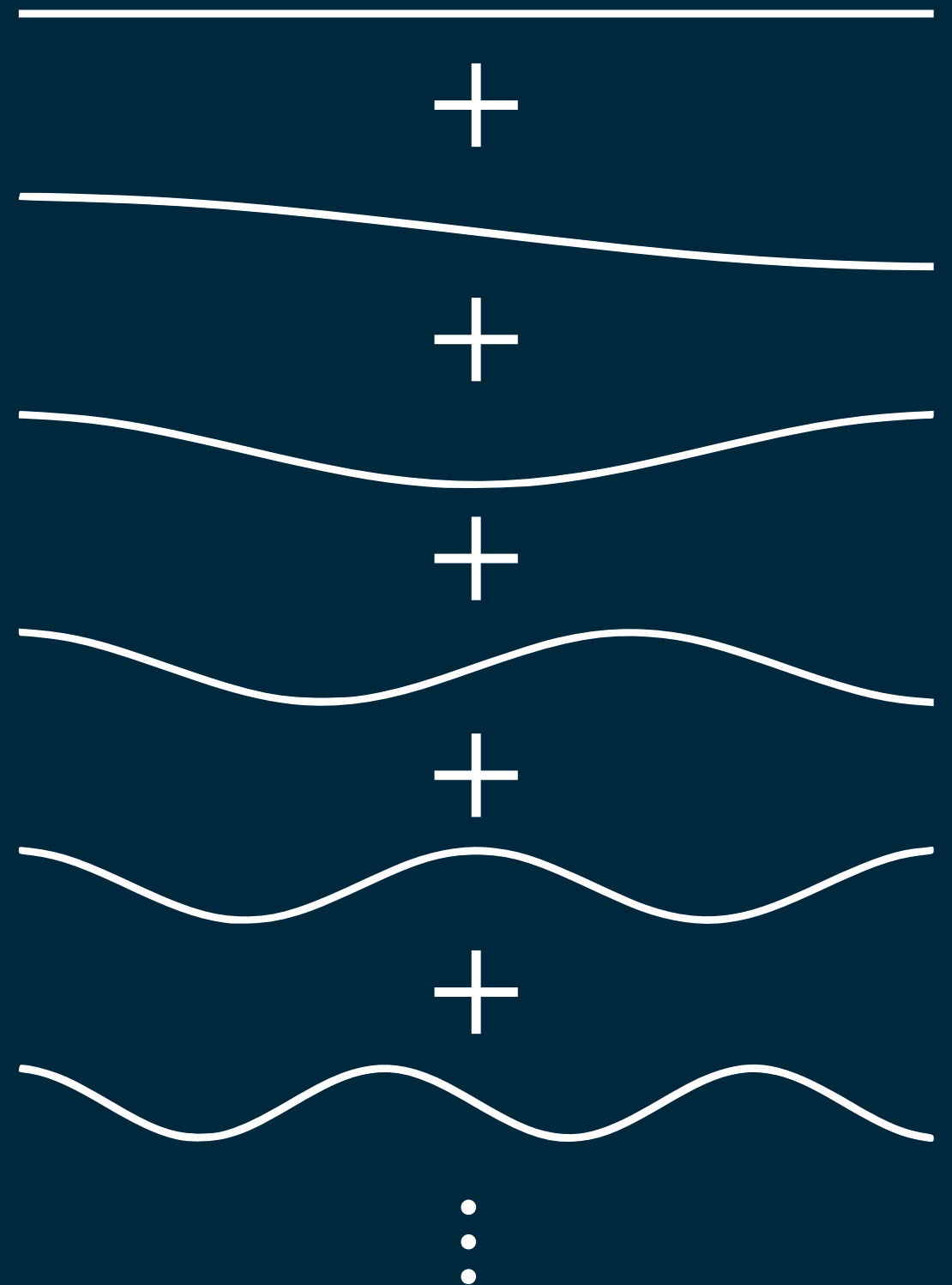


using sinusoidal spatial “wave” patterns

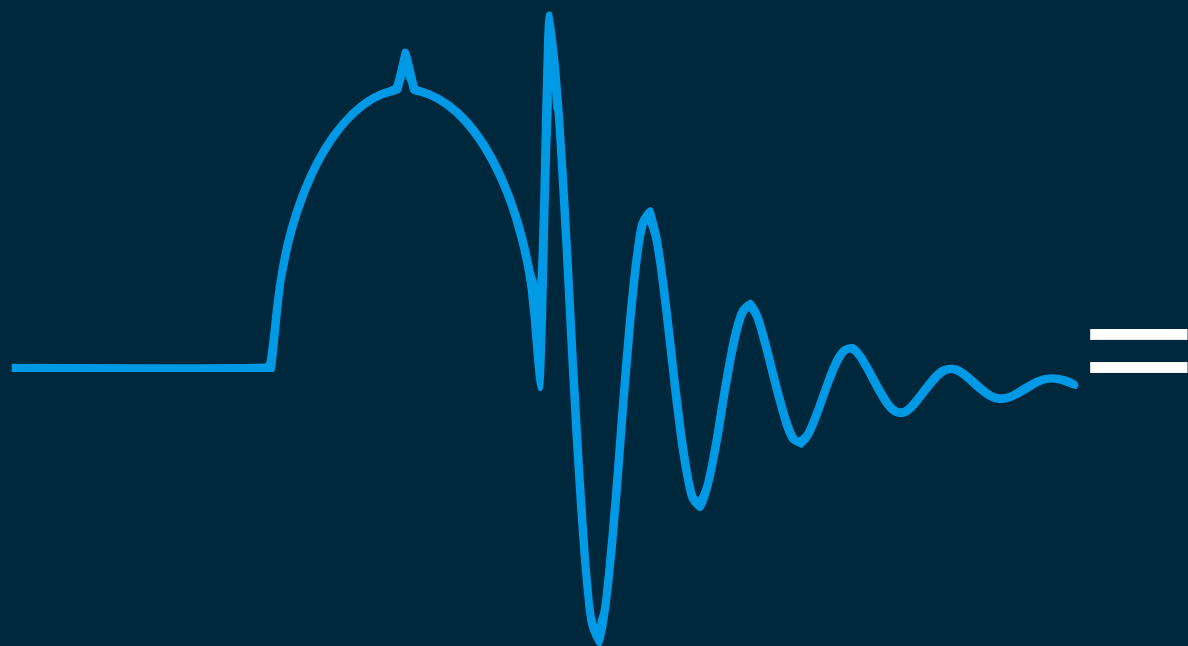
Universal Ingredients



Waves with different wavelengths

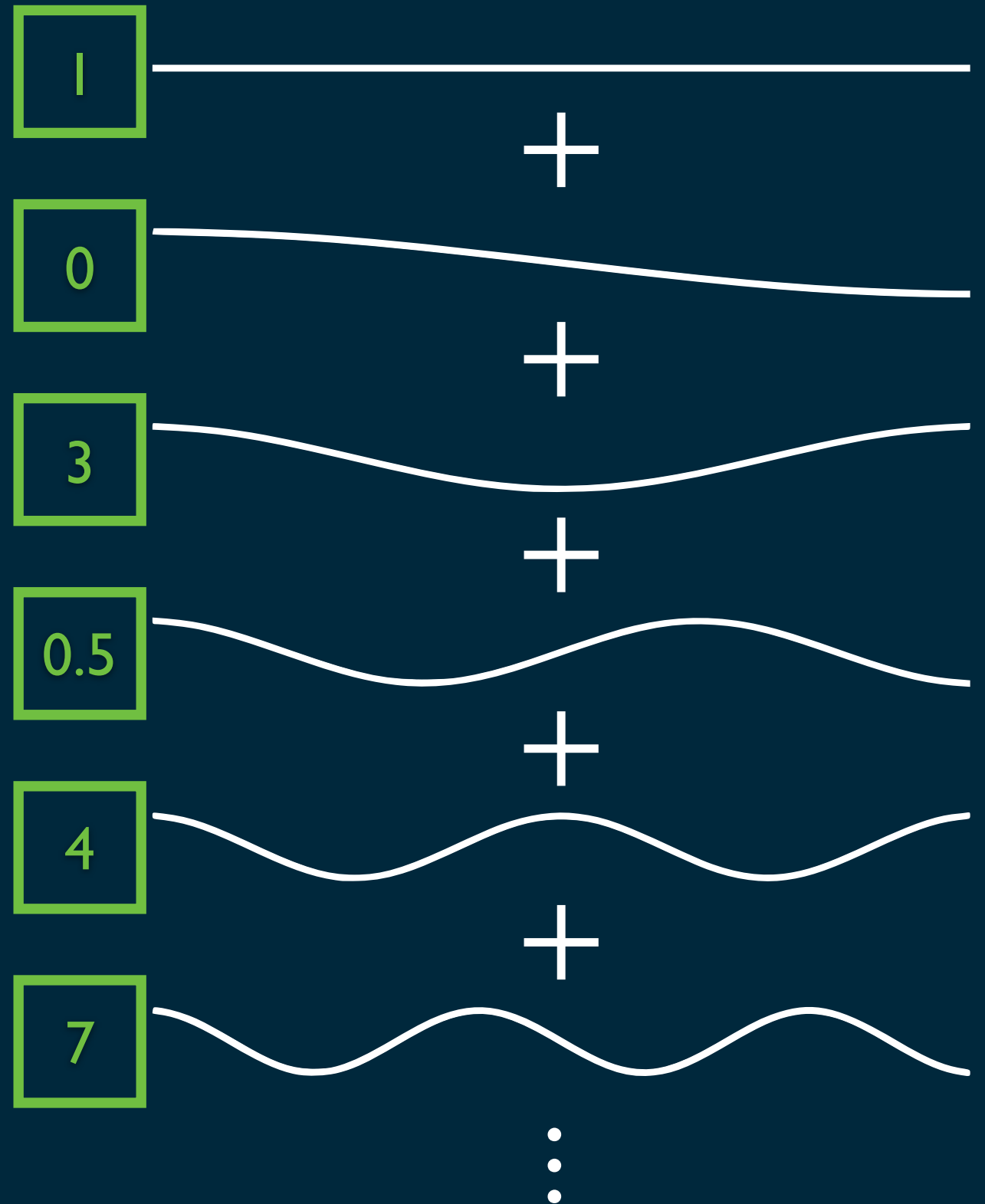


Fourier Transform

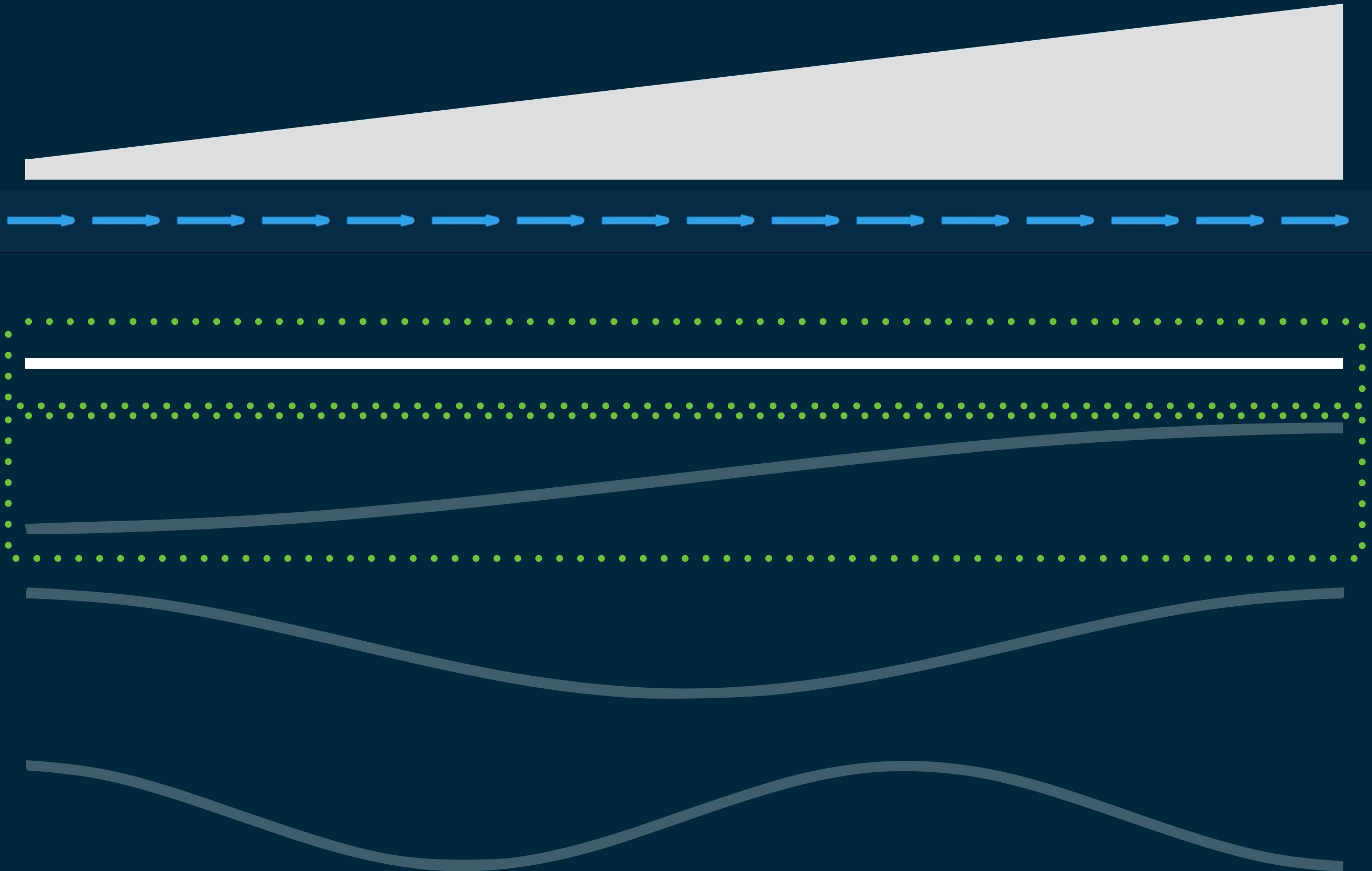


How to combine these
universal ingredients?

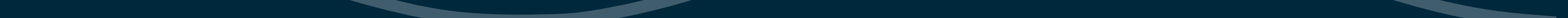
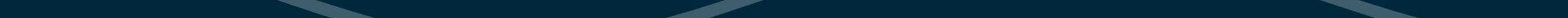
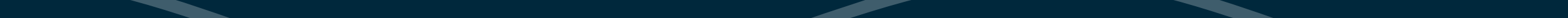
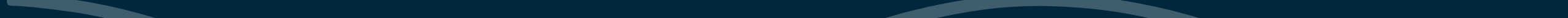
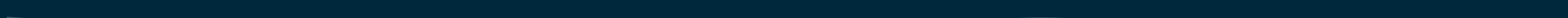
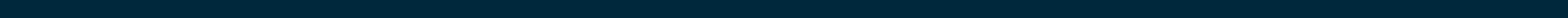
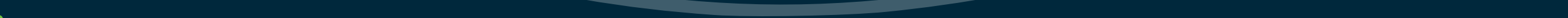
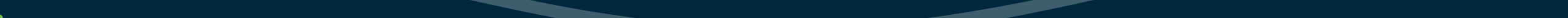
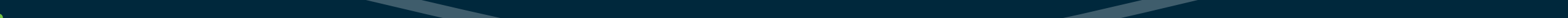
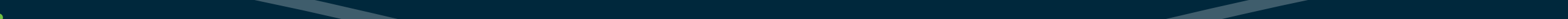
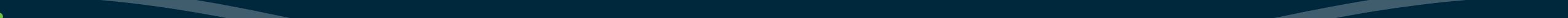
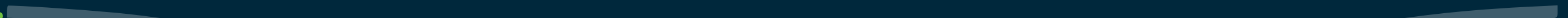
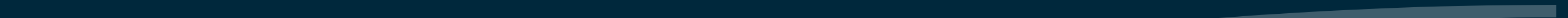
Need to determine
weight of each wave



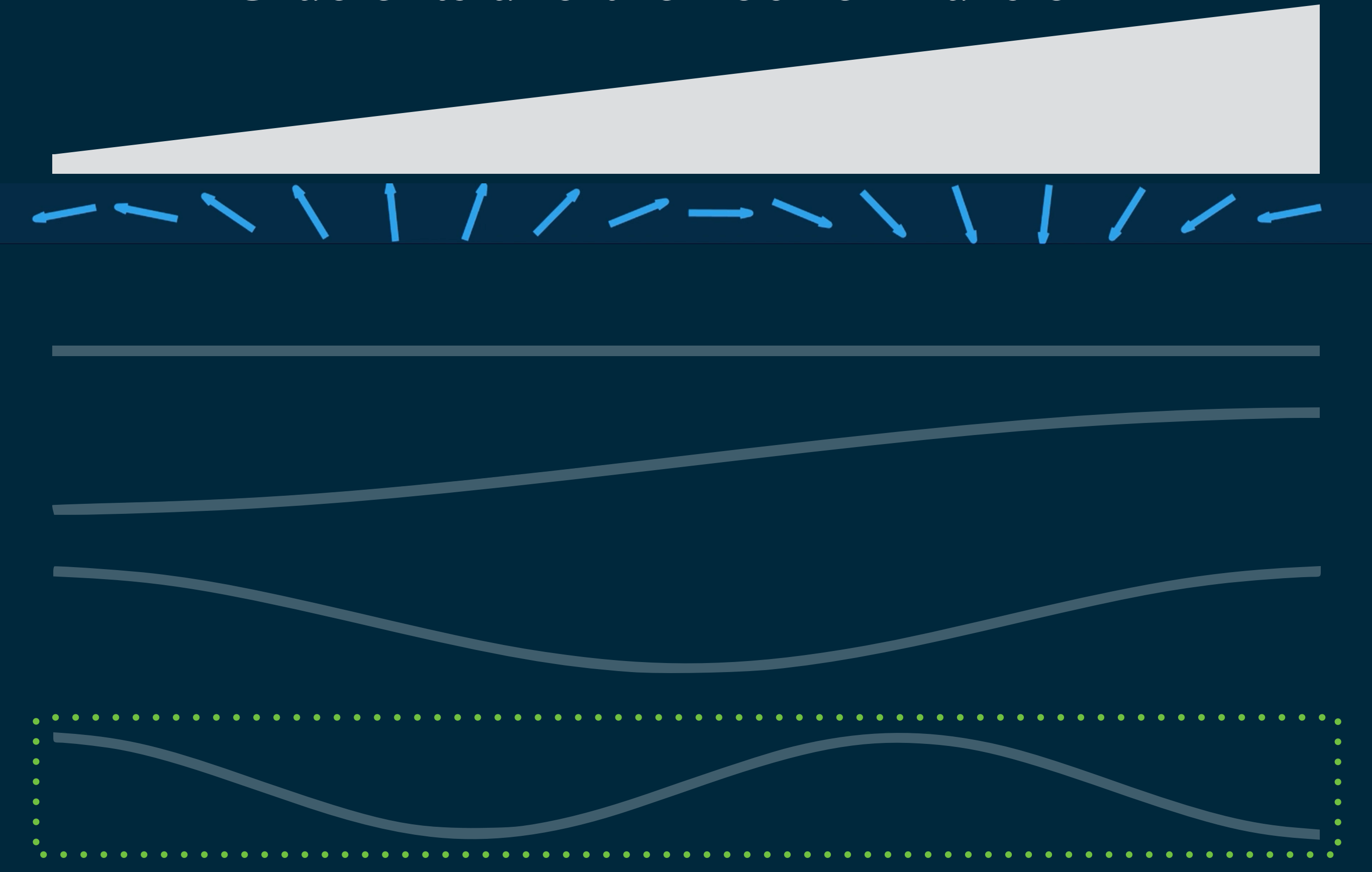
Gradients and the Fourier Transform



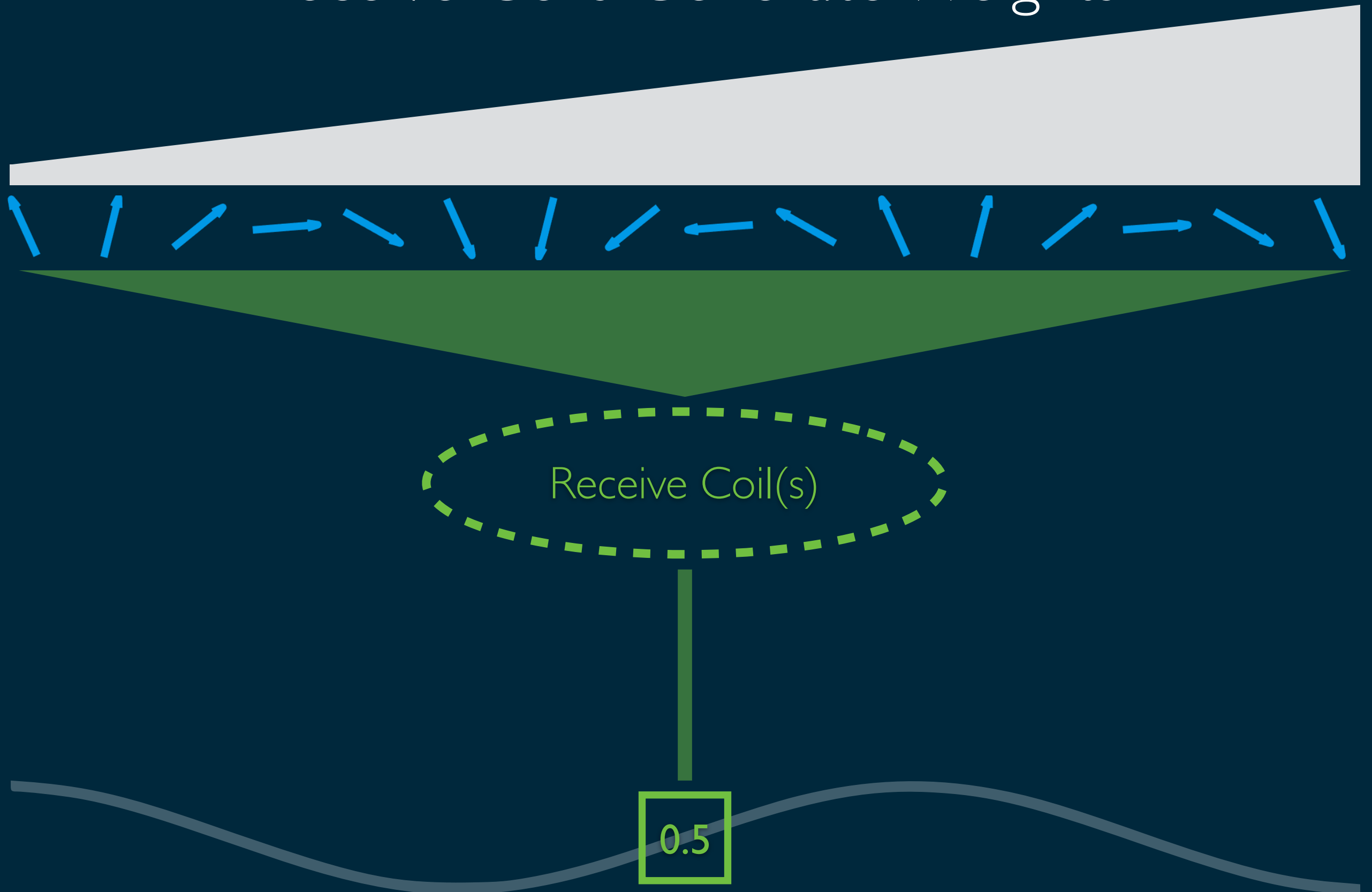
Gradients and the Fourier Transform



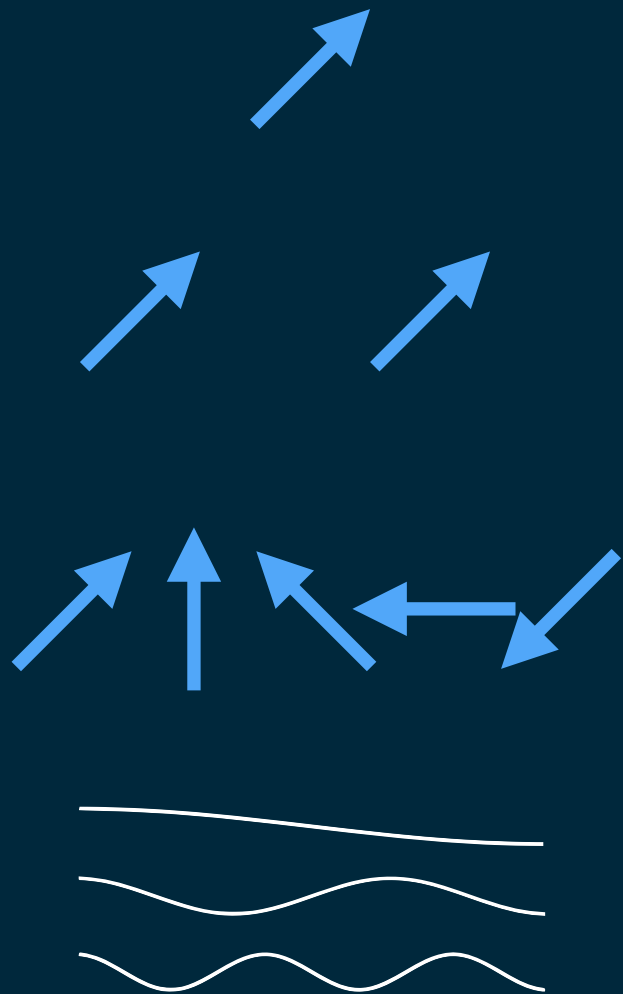
Gradients and the Fourier Transform



Receive Coils Generate Weights



Summary



Every voxel's magnetisation points in some **direction**

Precession **rate** of magnetisation is controlled by the magnetic field **strength** it sees

Varying the field across space using a **gradient** generates **wave**-like patterns in the magnetisation

All signals/images can be **represented** by a combination of different **waves** (Fourier Transform)

Gradients and receive coils find the **Fourier Transform** representation of an object by setting up **waves** over it and evaluating their **weights**