$$\frac{Y(s)}{u(s)} = \frac{bs+lc}{ms^2+bs+lc} = \frac{s \cdot bm + bm}{s^2 + bm \cdot s^2 + bm \cdot s^2 + bm}$$

2.
$$A = \begin{bmatrix} 0 & 1 \\ -4m & -b/m \end{bmatrix}$$

$$B = \begin{bmatrix} o \\ i \end{bmatrix}$$

3.
$$\Phi(s) = (sI-A)^{\dagger} = \begin{bmatrix} s & -1 \\ t/m & s+1/m \end{bmatrix}$$

$$= \frac{1}{s^{2} + \frac{1}{2}ms + \frac{1}{2}m} \begin{bmatrix} s + \frac{1}{2}m & +1 \\ -\frac{1}{2}m & s \end{bmatrix}$$

$$= \frac{1}{s^{2} + \frac{1}{2}ms + \frac{1}{2}ms} \begin{bmatrix} s & 1 \\ -\frac{1}{2}s & 1 \\ -\frac{1}{2}s & 1 \end{bmatrix} b = 0$$

$$= \frac{1}{s^{2} + \frac{1}{2}ms} \begin{bmatrix} s & 1 \\ -\frac{1}{2}s & 1 \\ -\frac{1}{2}s & 1 \end{bmatrix} b = 0$$

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$$= \frac{1}{s^{2} + \frac{1}{2}ms} \begin{bmatrix} s & 1 \\ -\frac{1}{2}s & 1 \\ -\frac{1}{2}s & 1 \end{bmatrix} b = 0$$

$$\chi(s) = \overline{\psi}(s) B u(s)$$

$$= \frac{1}{s^{2}+4} \begin{bmatrix} s & 1 \\ -4 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(s) = \frac{1}{s^{2}+4} \begin{bmatrix} 1 \\ s \end{bmatrix} \cdot u(s)$$

$$for u(s) = \frac{1}{s} (u(t) = \frac{1}{2}(t)),$$

$$\chi(s) = \frac{1}{s^{2}+4} \cdot \begin{bmatrix} 1 \\ s \end{bmatrix} \cdot \frac{1}{s} = \begin{bmatrix} \frac{1}{s(s^{2}+4)} \\ \frac{1}{s^{2}+4} \end{bmatrix}$$

$$F_{\text{ev}} \ \text{U(s)} = \frac{1}{5+3} \ \left(\text{u(t)} = e^{-3t} \right),$$

$$\chi(s) = \frac{1}{5^2+4} \left[\frac{1}{5} \cdot \frac{1}{5+3} \cdot \left[\frac{1}{(5^2+4)(5+3)} \right] \cdot \frac{1}{(5^2+4)(5+3)} \right]$$

5. Natural response

$$x(s) = \widehat{\Phi}(s) \times 0$$

$$= \frac{1}{5^{2}+4} \begin{bmatrix} s \\ -4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$X(s) = \begin{bmatrix} \frac{s+1}{s^2+4} \\ \frac{s-4}{s^2+4} \end{bmatrix} \qquad \left(s \begin{bmatrix} \frac{s}{s^2+2^2} + \frac{3}{2} \frac{1}{s^2+2^2} \\ \frac{s}{s^2+2^2} - \frac{3}{s^2+2^2} \end{bmatrix} \right)$$

$$(2t) = \int_{-\infty}^{\infty} \cos(2t) + \frac{1}{2} \sin(2t)$$

$$(2t) - 2 \sin(2t)$$

$$(2t) - 2 \sin(2t)$$

$$(2t) - 2 \sin(2t)$$

Leigh
$$J(snut) = \frac{w}{s^2+w^2}$$

$$J(snut) = \frac{s}{s^2+w^2}$$

[2] RLC Op-Ame Circuit

$$\frac{v_{in}-v_{i}}{R}=\frac{d(v_{i}-v_{out})}{dt}.C+\frac{v_{i}-v_{out}}{R}$$

(1)
$$\frac{v_{in}}{R} = v_{o} \cdot C + \frac{v_{c}}{R} + \frac{v_{c}}{R}$$

2. State-space:
$$x = \begin{bmatrix} v_{\text{out}} \\ v_{\text{c}} \end{bmatrix}$$

$$\dot{x} = \begin{bmatrix} v_{\text{out}} \end{bmatrix} \leftarrow \text{from (12)} \Rightarrow \dot{v}_{\text{out}} = \frac{1}{RC} \cdot v_{i} - \frac{1}{RC} v_{\text{out}}$$

$$= \frac{1}{RC} v_{\text{out}} + \frac{1}{RC} v_{\text{out}} - \frac{1}{RC} v_{\text{out}}$$

$$= \frac{1}{RC} v_{\text{out}} + \frac{1}{RC} v_{\text{out}} - \frac{1}{RC} v_{\text{out}}$$

$$\begin{array}{lll}
\vdots & x = \begin{bmatrix} 0 & k_{C} \\ -\frac{1}{4}nx & -\frac{1}{4}k_{C} \end{bmatrix} \times + \begin{bmatrix} \frac{1}{4}k_{C} \end{bmatrix} u \\
y = \begin{bmatrix} 1 & 0 \end{bmatrix} \times + \begin{bmatrix} 0 \end{bmatrix} u \\
3) & 6(s) = C(s(1-A))^{-1}B \\
& = \begin{bmatrix} 1 & 0 \end{bmatrix} (e(1-A))^{-1}B \begin{bmatrix} 0 \\ k_{C} \end{bmatrix} \\
& = \begin{bmatrix} 1 & 0 \end{bmatrix} (e(1-A))^{-1}B \begin{bmatrix} 0 \\ k_{C} \end{bmatrix} \\
& = \frac{1}{s(s(s(a)))} \begin{bmatrix} s + \frac{1}{4}k_{C} \\ -\frac{1}{4}k_{C} \end{bmatrix} \begin{bmatrix} s + \frac{1}{4}k_{C} \\ -\frac{1}{4}k_{C} \end{bmatrix} \\
& = \frac{1}{s^{2}+s\frac{1}{4}k^{2}} \begin{bmatrix} s + \frac{1}{4}k_{C} \\ -\frac{1}{4}k_{C} \end{bmatrix} \begin{bmatrix} 0 \\ k_{C} \end{bmatrix} \\
& = \frac{(k_{C})^{2}}{s^{2}+s\frac{1}{4}k_{C}} \begin{bmatrix} s + \frac{1}{4}k_{C} \\ -\frac{1}{4}k_{C} \end{bmatrix} \begin{bmatrix} 0 \\ k_{C} \end{bmatrix} \\
& = \frac{(k_{C})^{2}}{s^{2}+s\frac{1}{4}k_{C}} \begin{bmatrix} s + \frac{1}{4}k_{C} \\ -\frac{1}{4}k_{C} \end{bmatrix} \\
& = \frac{(k_{C})^{2}}{(s+k_{C})^{2}} \\
& = \frac{(k_{C})^{2}}{(s+k_{C})^{2}}
\end{array}$$

4)
$$\triangle$$
 eig(A): $|SJ-A|=D = S^2 + \frac{2}{RC}S + (RC)^2$

$$= (S+RC)^2$$

$$S = -\frac{1}{RC} - \frac{1}{RC}S$$

5) Only I characteristic egn exists.

All passible state-pare realizations will have
the same eigenvalues.