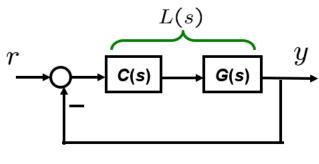
### Problem 1:

Given the unity feedback system below, use frequency response methods to determine the value of gain, C(s), to yield a step response with a 20% overshoot. Use Matlab to graph the step response.



$$G(s) = \frac{(s+4)}{s(s+8)(s+10)(s+15)}$$

**Solution:** 

```
Assignment 20, problem 1:

L(S)= (S+4)

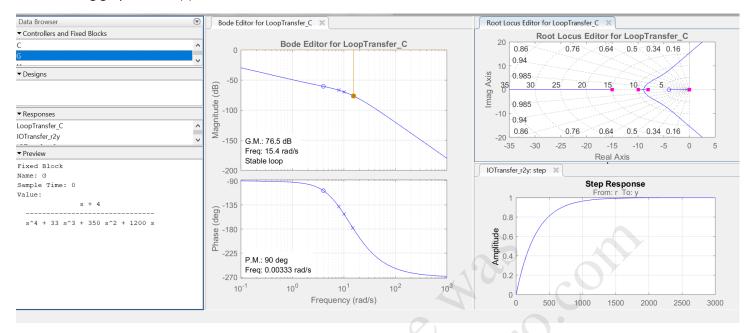
S(S+8)(S+10)(S+15)
  Find C(s) (gain controller compensator) for PO=20%
 Method 1 (use PM=100():
 We must reduce the PM to 45.59, i.e., the
Bode magnitude must be OdB when the Bode
plot is: -180+PM = -180+45.59= -134.41°
 Find w at which LLijus=-134.41
LL(jw)= tan(兴)-{tan(兴)+tan(兴)+ tan(兴)+tan(兴)}=-1344
At w=7.5 -> gain=? -> |L(jx75) = 7552+42
-> |L(j75) |=4.930x104;
- 1L() 7.5) =4.930 x104;
PM=48.06; -180+ PM =-180+ 48.06= -131.94° → W=7.14

→ | L(j7.14)|=5.23(x10) → C = C(s)=1908
```

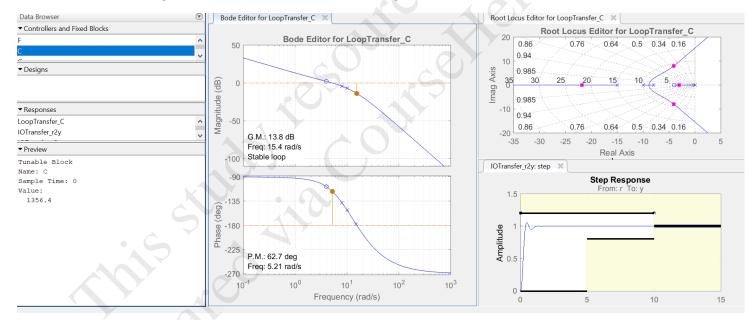
20% overshoot =>  $\zeta = 0.456 => \phi_{M} = 48.15^{\circ}$ .

Looking at the phase diagram, where  $\phi_{\rm M} = 48.15^{\circ}$  (i.e.  $\phi = -131.85^{\circ}$ ), the phase margin frequency = 7.14 rad/s. At this frequency, the magnitude curve is – 65.6 dB. Thus the magnitude curve has to be raised by 65.6 dB (K = 1905).

### The following graph is for C(s) = 1:



## If we use root locus design for $\zeta = 0.455$ . we obtain the following:



If I base my design on Bode plot instead of root locus and using Matlab, I will try to put PM at around the requested value of 45.51 degrees (I managed 47.2 deg), then I will get the following graph (which corresponds to C(s) = 1944.1):

