## Assignment 14 (ELEC 341 L14\_RLLeadLag)

## Problem 1:

For a control system with open loop transfer function of C(s).G(s) = C(s)/[s(s+4)], design a lead compensator by selecting  $C_{lead}(s)$  so that the damping frequency is 4 rad/s and  $\zeta = 0.707$ .

**Solution:** 

$$C(s) G(s) = C(s) \cdot \frac{1}{s(s+4)}$$

$$C(s) = d = 2$$

$$W_{3-4} = rad/s$$

$$S = 0 + 0.7$$

$$W_{3} = W_{n} \sqrt{1 - (2 - 2r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} \times \frac{1}{2r} = W_{n} \sqrt{1 - (0 - 30r)^{2}} \times \frac{1}{2r} \times \frac{1}{2r$$

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Design K: Find K at Sd:

We know that 
$$|C_{lead}(s) \cdot G(s)| = \left| \frac{K}{s(s+8)} \right| = 1$$
 $\Rightarrow K \left| \frac{1}{s(s+8)} \right| = 1 \Rightarrow \frac{K}{sd=-4+4j} = 1 \Rightarrow K$ 
 $|K = 32|$ 
 $|C_{lead}(s) \cdot G(s)| = \frac{K}{s(s+8)} = 1 \Rightarrow K$ 
 $|C_{lead}(s) \cdot G(s)| = \frac{K}{s(s+8)} = 1 \Rightarrow K$ 
 $|C_{lead}(s) \cdot G(s)| = \frac{32(s+4)}{(s+8)}$