

CPE 313 : Advanced Machine Learning with Deep Learning

HOA 1.1 Using Tensorflow with a Real Dataset

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Linear Regression with a Real Dataset

This Colab uses a real dataset to predict the prices of houses in California.

Learning Objectives:

After doing this Colab, you'll know how to do the following:

- Read a .csv file into a `pandas` DataFrame.
- Examine a `dataset`.
- Experiment with different `features` in building a model.
- Tune the model's `hyperparameters`.

The Dataset

The `dataset for this exercise` is based on 1990 census data from California. The dataset is old but still provides a great opportunity to learn about machine learning programming.

Import relevant modules

The following hidden code cell imports the necessary code to run the code in the rest of this Colaboratory.

```
#@title Import relevant modules
import pandas as pd
import tensorflow as tf
from matplotlib import pyplot as plt

# The following lines adjust the granularity of reporting.
pd.options.display.max_rows = 10
pd.options.display.float_format = "{:.1f}".format
```

The dataset

Datasets are often stored on disk or at a URL in `.csv` format.

A well-formed .csv file contains column names in the first row, followed by many rows of data. A comma divides each value in each row. For example, here are the first five rows of the .csv file holding the California Housing Dataset:

```
"longitude","latitude","housing_median_age","total_rooms","total_bedrooms","population","households","median_income","median_house_value"  
-  
114.310000,34.190000,15.000000,5612.000000,1283.000000,1015.000000,472  
.000000,1.493600,66900.000000  
-  
114.470000,34.400000,19.000000,7650.000000,1901.000000,1129.000000,463  
.000000,1.820000,80100.000000  
-  
114.560000,33.690000,17.000000,720.000000,174.000000,333.000000,117.00  
0000,1.650900,85700.000000  
-  
114.570000,33.640000,14.000000,1501.000000,337.000000,515.000000,226.0  
00000,3.191700,73400.000000
```

Load the .csv file into a pandas DataFrame

This Colab, like many machine learning programs, gathers the .csv file and stores the data in memory as a pandas Dataframe. Pandas is an open source Python library. The primary datatype in pandas is a DataFrame. You can imagine a pandas DataFrame as a spreadsheet in which each row is identified by a number and each column by a name. Pandas is itself built on another open source Python library called NumPy. If you aren't familiar with these technologies, please view these two quick tutorials:

- [NumPy](#)
- [Pandas DataFrames](#)

The following code cell imports the .csv file into a pandas DataFrame and scales the values in the label (`median_house_value`):

```
# Import the dataset.  
training_df =  
pd.read_csv(filepath_or_buffer="https://download.mlcc.google.com/mledu  
-datasets/california_housing_train.csv")  
  
# Scale the label.  
training_df[ "median_house_value" ] /= 1000.0  
  
# Print the first rows of the pandas DataFrame.  
training_df.head()  
  
    longitude  latitude  housing_median_age  total_rooms  
total_bedrooms  \  
0      -114.3        34.2             15.0       5612.0  
1283.0  
1      -114.5        34.4             19.0       7650.0
```

1901.0				
2	-114.6	33.7	17.0	720.0
174.0				
3	-114.6	33.6	14.0	1501.0
337.0				
4	-114.6	33.6	20.0	1454.0
326.0				
	population	households	median_income	median_house_value
0	1015.0	472.0	1.5	66.9
1	1129.0	463.0	1.8	80.1
2	333.0	117.0	1.7	85.7
3	515.0	226.0	3.2	73.4
4	624.0	262.0	1.9	65.5

Scaling `median_house_value` puts the value of each house in units of thousands. Scaling will keep loss values and learning rates in a friendlier range.

Although scaling a label is usually *not* essential, scaling features in a multi-feature model usually *is* essential.

Examine the dataset

A large part of most machine learning projects is getting to know your data. The pandas API provides a `describe` function that outputs the following statistics about every column in the DataFrame:

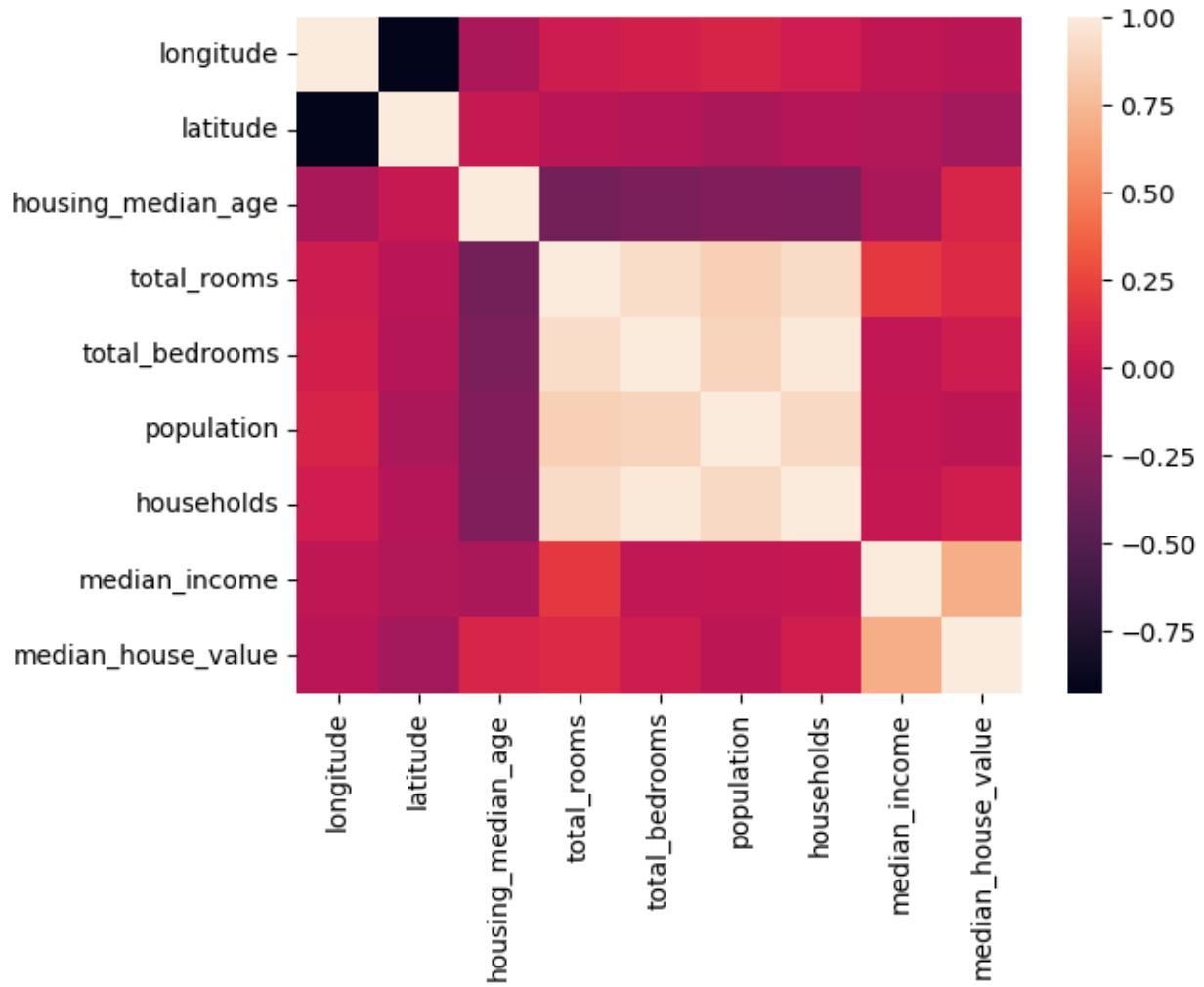
- `count`, which is the number of rows in that column. Ideally, `count` contains the same value for every column.
- `mean` and `std`, which contain the mean and standard deviation of the values in each column.
- `min` and `max`, which contain the lowest and highest values in each column.
- `25%`, `50%`, `75%`, which contain various `quantiles`.

# Get statistics on the dataset.				
training_df.describe()				
	longitude	latitude	housing_median_age	total_rooms
total_bedrooms	\			
count	17000.0	17000.0	17000.0	17000.0
17000.0				
mean	-119.6	35.6	28.6	2643.7
539.4				
std	2.0	2.1	12.6	2179.9
421.5				
min	-124.3	32.5	1.0	2.0
1.0				

```
25%      -121.8      33.9          18.0      1462.0
297.0
50%      -118.5      34.2          29.0      2127.0
434.0
75%      -118.0      37.7          37.0      3151.2
648.2
max      -114.3      42.0          52.0      37937.0
6445.0
```

```
population    households   median_income   median_house_value
count      17000.0      17000.0      17000.0      17000.0
mean       1429.6       501.2        3.9         207.3
std        1147.9       384.5        1.9         116.0
min        3.0          1.0        0.5         15.0
25%       790.0        282.0        2.6         119.4
50%       1167.0       409.0        3.5         180.4
75%       1721.0       605.2        4.8         265.0
max       35682.0      6082.0       15.0        500.0
```

```
import seaborn as sns
corr = training_df.corr()
sns.heatmap(corr)
<Axes: >
```



corr		longitude	latitude	housing_median_age
total_rooms \	longitude	1.0	-0.9	-0.1
longitude	0.0	-0.9	1.0	0.0
latitude	0.0	-0.1	0.0	1.0
housing_median_age	0.4	0.0	-0.0	-0.4
total_rooms	1.0	0.1	-0.1	-0.3
total_bedrooms	0.9	0.1	-0.1	-0.3
population	0.9	0.1	-0.1	-0.3
households	0.9	0.1	-0.1	-0.3
median_income	0.9	-0.0	-0.1	-0.1

0.2				
median_house_value	-0.0	-0.1	0.1	
0.1				
	total_bedrooms	population	households	
median_income \ longitude	0.1	0.1	0.1	-
0.0				
latitude	-0.1	-0.1	-0.1	-
0.1				
housing_median_age	-0.3	-0.3	-0.3	-
0.1				
total_rooms	0.9	0.9	0.9	
0.2				
total_bedrooms	1.0	0.9	1.0	-
0.0				
population	0.9	1.0	0.9	-
0.0				
households	1.0	0.9	1.0	
0.0				
median_income	-0.0	-0.0	0.0	
1.0				
median_house_value	0.0	-0.0	0.1	
0.7				
	median_house_value			
longitude	-0.0			
latitude	-0.1			
housing_median_age	0.1			
total_rooms	0.1			
total_bedrooms	0.0			
population	-0.0			
households	0.1			
median_income	0.7			
median_house_value	1.0			

Task 1: Identify anomalies in the dataset

Do you see any anomalies (strange values) in the data?

Some strange values stand out, especially in total_rooms, total_bedrooms, population, and households, where the maximum values are much higher than what most of the data shows. Median_income also has a few unusually high values compared to the rest. On the other hand, longitude, latitude, and housing_median_age look fairly normal and don't show extreme outliers.

Define functions that build and train a model

The following code defines two functions:

- `build_model(my_learning_rate)`, which builds a randomly-initialized model.
- `train_model(model, feature, label, epochs)`, which trains the model from the examples (feature and label) you pass.

Since you don't need to understand model building code right now, we've hidden this code cell. You may optionally double-click the following headline to see the code that builds and trains a model.

```
#@title Define the functions that build and train a model
def build_model(my_learning_rate):
    """Create and compile a simple linear regression model."""
    # Most simple tf.keras models are sequential.
    model = tf.keras.models.Sequential()

    # Describe the topography of the model.
    # The topography of a simple linear regression model
    # is a single node in a single layer.
    model.add(tf.keras.layers.Dense(units=1,
                                    input_shape=(1,)))

    # Compile the model topography into code that TensorFlow can
    # efficiently
    # execute. Configure training to minimize the model's mean squared
    # error.

    model.compile(optimizer=tf.keras.optimizers.RMSprop(learning_rate=my_learning_rate),
                  loss="mean_squared_error",
                  metrics=[tf.keras.metrics.RootMeanSquaredError()])

    return model


def train_model(model, df, feature, label, epochs, batch_size):
    """Train the model by feeding it data."""

    # Feed the model the feature and the label.
    # The model will train for the specified number of epochs.
    history = model.fit(x=df[feature],
                         y=df[label],
                         batch_size=batch_size,
                         epochs=epochs)

    # Gather the trained model's weight and bias.
    trained_weight = model.get_weights()[0]
    trained_bias = model.get_weights()[1]

    # The list of epochs is stored separately from the rest of history.
    epochs = history.epoch
```

```

# Isolate the error for each epoch.
hist = pd.DataFrame(history.history)

# To track the progression of training, we're going to take a
snapshot
# of the model's root mean squared error at each epoch.
rmse = hist["root_mean_squared_error"]

return trained_weight, trained_bias, epochs, rmse

print("Defined the build_model and train_model functions.")

```

Defined the build_model and train_model functions.

Define plotting functions

The following [matplotlib](#) functions create the following plots:

- a scatter plot of the feature vs. the label, and a line showing the output of the trained model
- a loss curve

You may optionally double-click the headline to see the matplotlib code, but note that writing matplotlib code is not an important part of learning ML programming.

```

#@title Define the plotting functions
def plot_the_model(trained_weight, trained_bias, feature, label):
    """Plot the trained model against 200 random training examples."""

    # Label the axes.
    plt.xlabel(feature)
    plt.ylabel(label)

    # Create a scatter plot from 200 random points of the dataset.
    random_examples = training_df.sample(n=200)
    plt.scatter(random_examples[feature], random_examples[label])

    # Weight and bias are scalars
    w = float(trained_weight)
    b = float(trained_bias)

    # Create a red line representing the model. The red line starts
    # at coordinates (x0, y0) and ends at coordinates (x1, y1).
    x0 = 0
    y0 = b
    x1 = random_examples[feature].max()
    y1 = b + (w * x1)
    plt.plot([x0, x1], [y0, y1], c='r')

    # Render the scatter plot and the red line.

```

```
plt.show()

def plot_the_loss_curve(epochs, rmse):
    """Plot a curve of loss vs. epoch."""
    plt.figure()
    plt.xlabel("Epoch")
    plt.ylabel("Root Mean Squared Error")

    plt.plot(epochs, rmse, label="Loss")
    plt.legend()
    plt.ylim([rmse.min()*0.97, rmse.max()])
    plt.show()

print("Defined the plot_the_model and plot_the_loss_curve functions.")
```

Defined the `plot_the_model` and `plot_the_loss_curve` functions.

Call the model functions

An important part of machine learning is determining which `features` correlate with the `label`. For example, real-life home-value prediction models typically rely on hundreds of features and synthetic features. However, this model relies on only one feature. For now, you'll arbitrarily use `total_rooms` as that feature.

```
print("\nThe learned weight for your model is %.4f" % weight)
print("The learned bias for your model is %.4f\n" % bias)

plot_the_model(weight, bias, my_feature, my_label)
plot_the_loss_curve(epochs, rmse)

Epoch 1/256

c:\Users\micki\anaconda3\envs\tf_env\lib\site-packages\keras\src\layers\core\dense.py:92: UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.
    super().__init__(activity_regularizer=activity_regularizer,
**kwargs)

532/532 ━━━━━━━━ 1s 836us/step - loss: 29036.0273 -
root_mean_squared_error: 170.3996
Epoch 2/256
532/532 ━━━━━━━━ 0s 888us/step - loss: 27966.2520 -
root_mean_squared_error: 167.2311
Epoch 3/256
532/532 ━━━━━━━━ 0s 889us/step - loss: 27141.5586 -
root_mean_squared_error: 164.7469
Epoch 4/256
532/532 ━━━━━━━━ 0s 794us/step - loss: 26505.4355 -
root_mean_squared_error: 162.8049
Epoch 5/256
532/532 ━━━━━━━━ 0s 810us/step - loss: 25793.4277 -
root_mean_squared_error: 160.6033
Epoch 6/256
532/532 ━━━━━━━━ 0s 800us/step - loss: 25039.3828 -
root_mean_squared_error: 158.2384
Epoch 7/256
532/532 ━━━━━━━━ 0s 809us/step - loss: 24430.6758 -
root_mean_squared_error: 156.3031
Epoch 8/256
532/532 ━━━━━━━━ 0s 833us/step - loss: 23885.0234 -
root_mean_squared_error: 154.5478
Epoch 9/256
532/532 ━━━━━━━━ 0s 862us/step - loss: 23215.8750 -
root_mean_squared_error: 152.3676
Epoch 10/256
532/532 ━━━━━━━━ 0s 811us/step - loss: 22664.4160 -
root_mean_squared_error: 150.5471
Epoch 11/256
532/532 ━━━━━━━━ 1s 914us/step - loss: 22170.8633 -
root_mean_squared_error: 148.8988
Epoch 12/256
532/532 ━━━━━━━━ 0s 808us/step - loss: 21662.6504 -
```

```
root_mean_squared_error: 147.1824
Epoch 13/256
532/532 ━━━━━━━━ 0s 826us/step - loss: 21101.1094 -
root_mean_squared_error: 145.2622
Epoch 14/256
532/532 ━━━━━━━━ 0s 874us/step - loss: 20833.0645 -
root_mean_squared_error: 144.3366
Epoch 15/256
532/532 ━━━━━━━━ 0s 815us/step - loss: 20135.6230 -
root_mean_squared_error: 141.9000
Epoch 16/256
532/532 ━━━━━━━━ 0s 826us/step - loss: 19878.8242 -
root_mean_squared_error: 140.9923
Epoch 17/256
532/532 ━━━━━━━━ 0s 821us/step - loss: 19461.2227 -
root_mean_squared_error: 139.5035
Epoch 18/256
532/532 ━━━━━━━━ 0s 828us/step - loss: 18773.3125 -
root_mean_squared_error: 137.0157
Epoch 19/256
532/532 ━━━━━━━━ 0s 870us/step - loss: 18637.6543 -
root_mean_squared_error: 136.5198
Epoch 20/256
532/532 ━━━━━━━━ 0s 821us/step - loss: 18019.2344 -
root_mean_squared_error: 134.2357
Epoch 21/256
532/532 ━━━━━━━━ 0s 822us/step - loss: 17930.0078 -
root_mean_squared_error: 133.9030
Epoch 22/256
532/532 ━━━━━━━━ 0s 821us/step - loss: 17564.8418 -
root_mean_squared_error: 132.5324
Epoch 23/256
532/532 ━━━━━━━━ 0s 830us/step - loss: 17388.8047 -
root_mean_squared_error: 131.8666
Epoch 24/256
532/532 ━━━━━━━━ 0s 826us/step - loss: 16878.5508 -
root_mean_squared_error: 129.9175
Epoch 25/256
532/532 ━━━━━━━━ 0s 837us/step - loss: 16748.9609 -
root_mean_squared_error: 129.4178
Epoch 26/256
532/532 ━━━━━━━━ 0s 817us/step - loss: 16368.7451 -
root_mean_squared_error: 127.9404
Epoch 27/256
532/532 ━━━━━━━━ 1s 824us/step - loss: 16109.0205 -
root_mean_squared_error: 126.9213
Epoch 28/256
532/532 ━━━━━━━━ 0s 812us/step - loss: 16010.8799 -
root_mean_squared_error: 126.5341
```

```
Epoch 29/256
532/532 0s 804us/step - loss: 15684.5439 -
root_mean_squared_error: 125.2379
Epoch 30/256
532/532 0s 855us/step - loss: 15609.9375 -
root_mean_squared_error: 124.9397
Epoch 31/256
532/532 0s 797us/step - loss: 15479.0635 -
root_mean_squared_error: 124.4149
Epoch 32/256
532/532 0s 797us/step - loss: 15165.0518 -
root_mean_squared_error: 123.1465
Epoch 33/256
532/532 0s 803us/step - loss: 14962.0977 -
root_mean_squared_error: 122.3197
Epoch 34/256
532/532 0s 796us/step - loss: 14971.7539 -
root_mean_squared_error: 122.3591
Epoch 35/256
532/532 0s 805us/step - loss: 14783.5566 -
root_mean_squared_error: 121.5876
Epoch 36/256
532/532 0s 824us/step - loss: 14758.0244 -
root_mean_squared_error: 121.4826
Epoch 37/256
532/532 0s 794us/step - loss: 14685.6240 -
root_mean_squared_error: 121.1843
Epoch 38/256
532/532 0s 803us/step - loss: 14493.5732 -
root_mean_squared_error: 120.3893
Epoch 39/256
532/532 0s 792us/step - loss: 14407.0039 -
root_mean_squared_error: 120.0292
Epoch 40/256
532/532 0s 793us/step - loss: 14363.4746 -
root_mean_squared_error: 119.8477
Epoch 41/256
532/532 0s 802us/step - loss: 14286.6494 -
root_mean_squared_error: 119.5268
Epoch 42/256
532/532 0s 803us/step - loss: 14185.5176 -
root_mean_squared_error: 119.1030
Epoch 43/256
532/532 0s 787us/step - loss: 14194.3662 -
root_mean_squared_error: 119.1401
Epoch 44/256
532/532 0s 822us/step - loss: 14157.8115 -
root_mean_squared_error: 118.9866
Epoch 45/256
```

```
532/532 ━━━━━━━━ 0s 853us/step - loss: 14047.2344 -
root_mean_squared_error: 118.5210
Epoch 46/256
532/532 ━━━━━━━━ 0s 810us/step - loss: 14089.3066 -
root_mean_squared_error: 118.6984
Epoch 47/256
532/532 ━━━━━━ 1s 905us/step - loss: 13949.0576 -
root_mean_squared_error: 118.1061
Epoch 48/256
532/532 ━━━━━━ 0s 793us/step - loss: 13959.9297 -
root_mean_squared_error: 118.1521
Epoch 49/256
532/532 ━━━━━━ 0s 832us/step - loss: 13934.0908 -
root_mean_squared_error: 118.0427
Epoch 50/256
532/532 ━━━━━━ 0s 835us/step - loss: 13930.3047 -
root_mean_squared_error: 118.0267
Epoch 51/256
532/532 ━━━━━━ 0s 828us/step - loss: 13876.6230 -
root_mean_squared_error: 117.7991
Epoch 52/256
532/532 ━━━━━━ 0s 858us/step - loss: 13956.8057 -
root_mean_squared_error: 118.1389
Epoch 53/256
532/532 ━━━━━━ 0s 860us/step - loss: 13874.7461 -
root_mean_squared_error: 117.7911
Epoch 54/256
532/532 ━━━━━━ 0s 883us/step - loss: 13802.8965 -
root_mean_squared_error: 117.4857
Epoch 55/256
532/532 ━━━━━━ 0s 858us/step - loss: 13857.4648 -
root_mean_squared_error: 117.7177
Epoch 56/256
532/532 ━━━━ 1s 916us/step - loss: 13843.1855 -
root_mean_squared_error: 117.6571
Epoch 57/256
532/532 ━━━━ 0s 887us/step - loss: 13865.7910 -
root_mean_squared_error: 117.7531
Epoch 58/256
532/532 ━━━━ 1s 927us/step - loss: 13825.2578 -
root_mean_squared_error: 117.5809
Epoch 59/256
532/532 ━━━━ 0s 826us/step - loss: 13779.6318 -
root_mean_squared_error: 117.3867
Epoch 60/256
532/532 ━━━━ 0s 830us/step - loss: 13837.2432 -
root_mean_squared_error: 117.6318
Epoch 61/256
532/532 ━━━━ 0s 815us/step - loss: 13716.6367 -
```

```
root_mean_squared_error: 117.1180
Epoch 62/256
532/532 ━━━━━━━━ 0s 784us/step - loss: 13814.3086 -
root_mean_squared_error: 117.5343
Epoch 63/256
532/532 ━━━━━━━━ 0s 798us/step - loss: 13813.8125 -
root_mean_squared_error: 117.5322
Epoch 64/256
532/532 ━━━━━━━━ 0s 773us/step - loss: 13750.4824 -
root_mean_squared_error: 117.2625
Epoch 65/256
532/532 ━━━━━━━━ 0s 822us/step - loss: 13805.3809 -
root_mean_squared_error: 117.4963
Epoch 66/256
532/532 ━━━━━━━━ 0s 823us/step - loss: 13775.7363 -
root_mean_squared_error: 117.3701
Epoch 67/256
532/532 ━━━━━━━━ 0s 780us/step - loss: 13716.6221 -
root_mean_squared_error: 117.1180
Epoch 68/256
532/532 ━━━━━━━━ 0s 792us/step - loss: 13788.8760 -
root_mean_squared_error: 117.4260
Epoch 69/256
532/532 ━━━━━━━━ 0s 814us/step - loss: 13759.2725 -
root_mean_squared_error: 117.2999
Epoch 70/256
532/532 ━━━━━━━━ 0s 815us/step - loss: 13770.9355 -
root_mean_squared_error: 117.3496
Epoch 71/256
532/532 ━━━━━━━━ 0s 858us/step - loss: 13725.9131 -
root_mean_squared_error: 117.1576
Epoch 72/256
532/532 ━━━━━━━━ 0s 775us/step - loss: 13776.0713 -
root_mean_squared_error: 117.3715
Epoch 73/256
532/532 ━━━━━━━━ 0s 788us/step - loss: 13774.4531 -
root_mean_squared_error: 117.3646
Epoch 74/256
532/532 ━━━━━━━━ 0s 798us/step - loss: 13786.8496 -
root_mean_squared_error: 117.4174
Epoch 75/256
532/532 ━━━━━━━━ 0s 789us/step - loss: 13763.6074 -
root_mean_squared_error: 117.3184
Epoch 76/256
532/532 ━━━━━━━━ 0s 769us/step - loss: 13814.7578 -
root_mean_squared_error: 117.5362
Epoch 77/256
532/532 ━━━━━━━━ 0s 848us/step - loss: 13761.7832 -
root_mean_squared_error: 117.3106
```

```
Epoch 78/256
532/532 0s 772us/step - loss: 13727.6260 -
root_mean_squared_error: 117.1650
Epoch 79/256
532/532 0s 835us/step - loss: 13794.2148 -
root_mean_squared_error: 117.4488
Epoch 80/256
532/532 0s 829us/step - loss: 13831.1396 -
root_mean_squared_error: 117.6059
Epoch 81/256
532/532 0s 779us/step - loss: 13770.4033 -
root_mean_squared_error: 117.3474
Epoch 82/256
532/532 0s 821us/step - loss: 13702.4727 -
root_mean_squared_error: 117.0576
Epoch 83/256
532/532 0s 838us/step - loss: 13765.2002 -
root_mean_squared_error: 117.3252
Epoch 84/256
532/532 0s 833us/step - loss: 13784.0762 -
root_mean_squared_error: 117.4056
Epoch 85/256
532/532 0s 800us/step - loss: 13782.6777 -
root_mean_squared_error: 117.3997
Epoch 86/256
532/532 0s 847us/step - loss: 13697.0996 -
root_mean_squared_error: 117.0346
Epoch 87/256
532/532 0s 809us/step - loss: 13752.7549 -
root_mean_squared_error: 117.2721
Epoch 88/256
532/532 0s 762us/step - loss: 13755.3506 -
root_mean_squared_error: 117.2832
Epoch 89/256
532/532 0s 792us/step - loss: 13777.3809 -
root_mean_squared_error: 117.3771
Epoch 90/256
532/532 0s 750us/step - loss: 13771.1494 -
root_mean_squared_error: 117.3505
Epoch 91/256
532/532 0s 827us/step - loss: 13744.3457 -
root_mean_squared_error: 117.2363
Epoch 92/256
532/532 0s 785us/step - loss: 13771.6055 -
root_mean_squared_error: 117.3525
Epoch 93/256
532/532 0s 781us/step - loss: 13808.8486 -
root_mean_squared_error: 117.5111
Epoch 94/256
```

```
532/532 ━━━━━━━━ 0s 786us/step - loss: 13764.4727 -  
root_mean_squared_error: 117.3221  
Epoch 95/256  
532/532 ━━━━━━━━ 0s 787us/step - loss: 13742.0469 -  
root_mean_squared_error: 117.2265  
Epoch 96/256  
532/532 ━━━━━━ 0s 843us/step - loss: 13719.3730 -  
root_mean_squared_error: 117.1297  
Epoch 97/256  
532/532 ━━━━━━ 0s 828us/step - loss: 13682.3037 -  
root_mean_squared_error: 116.9714  
Epoch 98/256  
532/532 ━━━━━━ 0s 832us/step - loss: 13734.5596 -  
root_mean_squared_error: 117.1945  
Epoch 99/256  
532/532 ━━━━━━ 0s 802us/step - loss: 13705.6885 -  
root_mean_squared_error: 117.0713  
Epoch 100/256  
532/532 ━━━━━━ 0s 802us/step - loss: 13792.9268 -  
root_mean_squared_error: 117.4433  
Epoch 101/256  
532/532 ━━━━━━ 0s 853us/step - loss: 13790.1035 -  
root_mean_squared_error: 117.4313  
Epoch 102/256  
532/532 ━━━━━━ 0s 818us/step - loss: 13742.2988 -  
root_mean_squared_error: 117.2276  
Epoch 103/256  
532/532 ━━━━━━ 0s 795us/step - loss: 13780.4629 -  
root_mean_squared_error: 117.3902  
Epoch 104/256  
532/532 ━━━━━━ 0s 815us/step - loss: 13771.4609 -  
root_mean_squared_error: 117.3519  
Epoch 105/256  
532/532 ━━━━━━ 0s 858us/step - loss: 13755.3076 -  
root_mean_squared_error: 117.2830  
Epoch 106/256  
532/532 ━━━━━━ 1s 900us/step - loss: 13760.7432 -  
root_mean_squared_error: 117.3062  
Epoch 107/256  
532/532 ━━━━━━ 1s 983us/step - loss: 13776.4971 -  
root_mean_squared_error: 117.3733  
Epoch 108/256  
532/532 ━━━━━━ 0s 846us/step - loss: 13735.2822 -  
root_mean_squared_error: 117.1976  
Epoch 109/256  
532/532 ━━━━━━ 0s 766us/step - loss: 13827.3105 -  
root_mean_squared_error: 117.5896  
Epoch 110/256  
532/532 ━━━━━━ 0s 779us/step - loss: 13745.3223 -
```

```
root_mean_squared_error: 117.2404
Epoch 111/256
532/532 ━━━━━━━━ 0s 818us/step - loss: 13795.6924 -
root_mean_squared_error: 117.4551
Epoch 112/256
532/532 ━━━━━━━━ 0s 896us/step - loss: 13756.3975 -
root_mean_squared_error: 117.2877
Epoch 113/256
532/532 ━━━━━━ 1s 917us/step - loss: 13719.8203 -
root_mean_squared_error: 117.1316
Epoch 114/256
532/532 ━━━━━━ 1s 932us/step - loss: 13794.4141 -
root_mean_squared_error: 117.4496
Epoch 115/256
532/532 ━━━━━━ 0s 860us/step - loss: 13754.9023 -
root_mean_squared_error: 117.2813
Epoch 116/256
532/532 ━━━━━━ 0s 791us/step - loss: 13787.3213 -
root_mean_squared_error: 117.4194
Epoch 117/256
532/532 ━━━━━━ 0s 830us/step - loss: 13767.5908 -
root_mean_squared_error: 117.3354
Epoch 118/256
532/532 ━━━━━━ 1s 907us/step - loss: 13693.2891 -
root_mean_squared_error: 117.0183
Epoch 119/256
532/532 ━━━━━━ 0s 836us/step - loss: 13704.8369 -
root_mean_squared_error: 117.0677
Epoch 120/256
532/532 ━━━━━━ 0s 813us/step - loss: 13781.2148 -
root_mean_squared_error: 117.3934
Epoch 121/256
532/532 ━━━━━━ 0s 777us/step - loss: 13753.1250 -
root_mean_squared_error: 117.2737
Epoch 122/256
532/532 ━━━━━━ 0s 777us/step - loss: 13715.7676 -
root_mean_squared_error: 117.1143
Epoch 123/256
532/532 ━━━━━━ 0s 771us/step - loss: 13741.4102 -
root_mean_squared_error: 117.2238
Epoch 124/256
532/532 ━━━━━━ 0s 852us/step - loss: 13786.0176 -
root_mean_squared_error: 117.4139
Epoch 125/256
532/532 ━━━━━━ 0s 843us/step - loss: 13763.9785 -
root_mean_squared_error: 117.3200
Epoch 126/256
532/532 ━━━━━━ 0s 840us/step - loss: 13759.2783 -
root_mean_squared_error: 117.2999
```

```
Epoch 127/256
532/532 ————— 1s 904us/step - loss: 13710.3389 -
root_mean_squared_error: 117.0912
Epoch 128/256
532/532 ————— 0s 852us/step - loss: 13770.9678 -
root_mean_squared_error: 117.3498
Epoch 129/256
532/532 ————— 1s 922us/step - loss: 13742.6104 -
root_mean_squared_error: 117.2289
Epoch 130/256
532/532 ————— 0s 893us/step - loss: 13725.5498 -
root_mean_squared_error: 117.1561
Epoch 131/256
532/532 ————— 0s 871us/step - loss: 13785.6992 -
root_mean_squared_error: 117.4125
Epoch 132/256
532/532 ————— 0s 870us/step - loss: 13744.5371 -
root_mean_squared_error: 117.2371
Epoch 133/256
532/532 ————— 0s 895us/step - loss: 13710.9277 -
root_mean_squared_error: 117.0937
Epoch 134/256
532/532 ————— 0s 836us/step - loss: 13805.6758 -
root_mean_squared_error: 117.4976
Epoch 135/256
532/532 ————— 0s 849us/step - loss: 13708.3232 -
root_mean_squared_error: 117.0826
Epoch 136/256
532/532 ————— 0s 876us/step - loss: 13733.9580 -
root_mean_squared_error: 117.1920
Epoch 137/256
532/532 ————— 1s 973us/step - loss: 13750.8682 -
root_mean_squared_error: 117.2641
Epoch 138/256
532/532 ————— 0s 864us/step - loss: 13736.5908 -
root_mean_squared_error: 117.2032
Epoch 139/256
532/532 ————— 0s 842us/step - loss: 13799.0664 -
root_mean_squared_error: 117.4694
Epoch 140/256
532/532 ————— 1s 1ms/step - loss: 13720.9785 -
root_mean_squared_error: 117.1366
Epoch 141/256
532/532 ————— 0s 850us/step - loss: 13746.4053 -
root_mean_squared_error: 117.2451
Epoch 142/256
532/532 ————— 0s 893us/step - loss: 13832.2969 -
root_mean_squared_error: 117.6108
Epoch 143/256
```

```
532/532 ━━━━━━━━ 1s 903us/step - loss: 13735.0586 -  
root_mean_squared_error: 117.1967  
Epoch 144/256  
532/532 ━━━━━━ 0s 834us/step - loss: 13714.3301 -  
root_mean_squared_error: 117.1082  
Epoch 145/256  
532/532 ━━━━━━ 0s 806us/step - loss: 13779.6885 -  
root_mean_squared_error: 117.3869  
Epoch 146/256  
532/532 ━━━━━━ 0s 829us/step - loss: 13769.8008 -  
root_mean_squared_error: 117.3448  
Epoch 147/256  
532/532 ━━━━━━ 0s 858us/step - loss: 13734.0469 -  
root_mean_squared_error: 117.1924  
Epoch 148/256  
532/532 ━━━━━━ 0s 813us/step - loss: 13782.8701 -  
root_mean_squared_error: 117.4005  
Epoch 149/256  
532/532 ━━━━━━ 0s 812us/step - loss: 13830.1377 -  
root_mean_squared_error: 117.6016  
Epoch 150/256  
532/532 ━━━━━━ 0s 820us/step - loss: 13792.2646 -  
root_mean_squared_error: 117.4405  
Epoch 151/256  
532/532 ━━━━━━ 0s 855us/step - loss: 13779.2061 -  
root_mean_squared_error: 117.3849  
Epoch 152/256  
532/532 ━━━━━━ 0s 808us/step - loss: 13806.2354 -  
root_mean_squared_error: 117.4999  
Epoch 153/256  
532/532 ━━━━━━ 0s 818us/step - loss: 13807.2236 -  
root_mean_squared_error: 117.5041  
Epoch 154/256  
532/532 ━━━━━━ 0s 801us/step - loss: 13734.2471 -  
root_mean_squared_error: 117.1932  
Epoch 155/256  
532/532 ━━━━━━ 0s 861us/step - loss: 13862.6689 -  
root_mean_squared_error: 117.7398  
Epoch 156/256  
532/532 ━━━━━━ 0s 795us/step - loss: 13782.1494 -  
root_mean_squared_error: 117.3974  
Epoch 157/256  
532/532 ━━━━━━ 0s 798us/step - loss: 13779.2656 -  
root_mean_squared_error: 117.3851  
Epoch 158/256  
532/532 ━━━━━━ 0s 820us/step - loss: 13726.2822 -  
root_mean_squared_error: 117.1592  
Epoch 159/256  
532/532 ━━━━━━ 0s 849us/step - loss: 13719.3193 -
```

```
root_mean_squared_error: 117.1295
Epoch 160/256
532/532 ━━━━━━━━ 0s 810us/step - loss: 13722.4512 -
root_mean_squared_error: 117.1429
Epoch 161/256
532/532 ━━━━━━━━ 0s 815us/step - loss: 13748.1631 -
root_mean_squared_error: 117.2526
Epoch 162/256
532/532 ━━━━━━━━ 0s 824us/step - loss: 13728.8877 -
root_mean_squared_error: 117.1703
Epoch 163/256
532/532 ━━━━━━━━ 0s 858us/step - loss: 13797.8252 -
root_mean_squared_error: 117.4641
Epoch 164/256
532/532 ━━━━━━━━ 0s 804us/step - loss: 13726.9609 -
root_mean_squared_error: 117.1621
Epoch 165/256
532/532 ━━━━━━━━ 0s 797us/step - loss: 13773.9854 -
root_mean_squared_error: 117.3626
Epoch 166/256
532/532 ━━━━━━━━ 0s 837us/step - loss: 13743.8398 -
root_mean_squared_error: 117.2341
Epoch 167/256
532/532 ━━━━━━━━ 0s 798us/step - loss: 13781.2598 -
root_mean_squared_error: 117.3936
Epoch 168/256
532/532 ━━━━━━━━ 0s 783us/step - loss: 13779.9111 -
root_mean_squared_error: 117.3879
Epoch 169/256
532/532 ━━━━━━━━ 0s 793us/step - loss: 13815.1230 -
root_mean_squared_error: 117.5378
Epoch 170/256
532/532 ━━━━━━━━ 0s 839us/step - loss: 13796.6104 -
root_mean_squared_error: 117.4590
Epoch 171/256
532/532 ━━━━━━━━ 0s 796us/step - loss: 13773.4004 -
root_mean_squared_error: 117.3601
Epoch 172/256
532/532 ━━━━━━━━ 0s 779us/step - loss: 13754.6064 -
root_mean_squared_error: 117.2800
Epoch 173/256
532/532 ━━━━━━━━ 0s 797us/step - loss: 13783.9688 -
root_mean_squared_error: 117.4052
Epoch 174/256
532/532 ━━━━━━━━ 0s 847us/step - loss: 13768.2539 -
root_mean_squared_error: 117.3382
Epoch 175/256
532/532 ━━━━━━━━ 0s 796us/step - loss: 13783.1738 -
root_mean_squared_error: 117.4018
Epoch 176/256
```

```
532/532 ━━━━━━━━ 0s 795us/step - loss: 13769.3789 -  
root_mean_squared_error: 117.3430  
Epoch 177/256  
532/532 ━━━━━━━━ 0s 821us/step - loss: 13813.4102 -  
root_mean_squared_error: 117.5305  
Epoch 178/256  
532/532 ━━━━━━━━ 0s 777us/step - loss: 13759.7422 -  
root_mean_squared_error: 117.3019  
Epoch 179/256  
532/532 ━━━━━━━━ 0s 806us/step - loss: 13807.5752 -  
root_mean_squared_error: 117.5056  
Epoch 180/256  
532/532 ━━━━━━━━ 0s 787us/step - loss: 13791.0996 -  
root_mean_squared_error: 117.4355  
Epoch 181/256  
532/532 ━━━━━━━━ 0s 825us/step - loss: 13773.2305 -  
root_mean_squared_error: 117.3594  
Epoch 182/256  
532/532 ━━━━━━━━ 0s 794us/step - loss: 13737.0898 -  
root_mean_squared_error: 117.2053  
Epoch 183/256  
532/532 ━━━━━━━━ 0s 811us/step - loss: 13772.8496 -  
root_mean_squared_error: 117.3578  
Epoch 184/256  
532/532 ━━━━━━━━ 0s 783us/step - loss: 13763.5459 -  
root_mean_squared_error: 117.3181  
Epoch 185/256  
532/532 ━━━━━━━━ 0s 836us/step - loss: 13773.1777 -  
root_mean_squared_error: 117.3592  
Epoch 186/256  
532/532 ━━━━━━━━ 0s 778us/step - loss: 13780.6846 -  
root_mean_squared_error: 117.3912  
Epoch 187/256  
532/532 ━━━━━━━━ 0s 779us/step - loss: 13772.8330 -  
root_mean_squared_error: 117.3577  
Epoch 188/256  
532/532 ━━━━━━━━ 0s 809us/step - loss: 13772.6104 -  
root_mean_squared_error: 117.3568  
Epoch 189/256  
532/532 ━━━━━━━━ 0s 808us/step - loss: 13725.1592 -  
root_mean_squared_error: 117.1544  
Epoch 190/256  
532/532 ━━━━━━━━ 0s 772us/step - loss: 13754.1152 -  
root_mean_squared_error: 117.2779  
Epoch 191/256  
532/532 ━━━━━━━━ 0s 797us/step - loss: 13719.6406 -  
root_mean_squared_error: 117.1309  
Epoch 192/256  
532/532 ━━━━━━━━ 0s 804us/step - loss: 13778.3613 -
```

```
root_mean_squared_error: 117.3813
Epoch 193/256
532/532 ━━━━━━━━ 0s 787us/step - loss: 13781.7920 -
root_mean_squared_error: 117.3959
Epoch 194/256
532/532 ━━━━━━━━ 0s 781us/step - loss: 13759.7490 -
root_mean_squared_error: 117.3020
Epoch 195/256
532/532 ━━━━━━━━ 0s 796us/step - loss: 13724.3545 -
root_mean_squared_error: 117.1510
Epoch 196/256
532/532 ━━━━━━━━ 0s 825us/step - loss: 13749.5449 -
root_mean_squared_error: 117.2585
Epoch 197/256
532/532 ━━━━━━━━ 0s 795us/step - loss: 13783.6494 -
root_mean_squared_error: 117.4038
Epoch 198/256
532/532 ━━━━━━━━ 0s 789us/step - loss: 13800.8467 -
root_mean_squared_error: 117.4770
Epoch 199/256
532/532 ━━━━━━━━ 0s 818us/step - loss: 13787.8154 -
root_mean_squared_error: 117.4215
Epoch 200/256
532/532 ━━━━━━━━ 0s 792us/step - loss: 13775.8223 -
root_mean_squared_error: 117.3704
Epoch 201/256
532/532 ━━━━━━━━ 0s 782us/step - loss: 13795.2646 -
root_mean_squared_error: 117.4532
Epoch 202/256
532/532 ━━━━━━━━ 0s 796us/step - loss: 13766.5850 -
root_mean_squared_error: 117.3311
Epoch 203/256
532/532 ━━━━━━━━ 0s 818us/step - loss: 13766.4590 -
root_mean_squared_error: 117.3306
Epoch 204/256
532/532 ━━━━━━━━ 0s 778us/step - loss: 13747.1240 -
root_mean_squared_error: 117.2481
Epoch 205/256
532/532 ━━━━━━━━ 0s 781us/step - loss: 13779.2598 -
root_mean_squared_error: 117.3851
Epoch 206/256
532/532 ━━━━━━━━ 0s 848us/step - loss: 13757.9424 -
root_mean_squared_error: 117.2943
Epoch 207/256
532/532 ━━━━━━━━ 0s 790us/step - loss: 13752.0176 -
root_mean_squared_error: 117.2690
Epoch 208/256
532/532 ━━━━━━━━ 0s 779us/step - loss: 13743.4180 -
root_mean_squared_error: 117.2323
```

```
Epoch 209/256
532/532 ————— 0s 791us/step - loss: 13755.1621 -
root_mean_squared_error: 117.2824
Epoch 210/256
532/532 ————— 0s 828us/step - loss: 13732.5557 -
root_mean_squared_error: 117.1860
Epoch 211/256
532/532 ————— 0s 799us/step - loss: 13724.5537 -
root_mean_squared_error: 117.1518
Epoch 212/256
532/532 ————— 0s 793us/step - loss: 13811.0322 -
root_mean_squared_error: 117.5203
Epoch 213/256
532/532 ————— 0s 881us/step - loss: 13764.2979 -
root_mean_squared_error: 117.3213
Epoch 214/256
532/532 ————— 0s 799us/step - loss: 13740.9590 -
root_mean_squared_error: 117.2218
Epoch 215/256
532/532 ————— 0s 802us/step - loss: 13694.7051 -
root_mean_squared_error: 117.0244
Epoch 216/256
532/532 ————— 0s 856us/step - loss: 13731.5615 -
root_mean_squared_error: 117.1817
Epoch 217/256
532/532 ————— 0s 778us/step - loss: 13775.7012 -
root_mean_squared_error: 117.3699
Epoch 218/256
532/532 ————— 0s 826us/step - loss: 13754.2412 -
root_mean_squared_error: 117.2785
Epoch 219/256
532/532 ————— 0s 774us/step - loss: 13719.0283 -
root_mean_squared_error: 117.1283
Epoch 220/256
532/532 ————— 0s 869us/step - loss: 13708.7256 -
root_mean_squared_error: 117.0843
Epoch 221/256
532/532 ————— 0s 782us/step - loss: 13758.2578 -
root_mean_squared_error: 117.2956
Epoch 222/256
532/532 ————— 0s 800us/step - loss: 13767.4248 -
root_mean_squared_error: 117.3347
Epoch 223/256
532/532 ————— 0s 862us/step - loss: 13844.0479 -
root_mean_squared_error: 117.6607
Epoch 224/256
532/532 ————— 0s 787us/step - loss: 13785.7998 -
root_mean_squared_error: 117.4129
Epoch 225/256
```

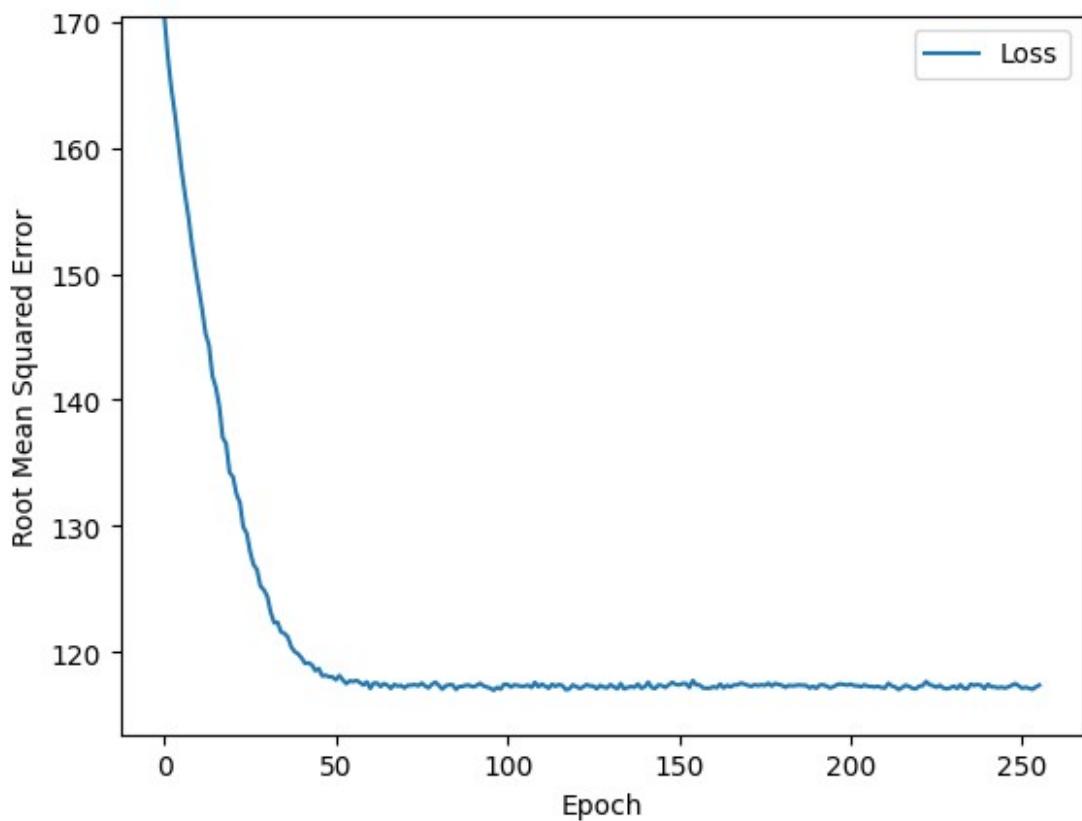
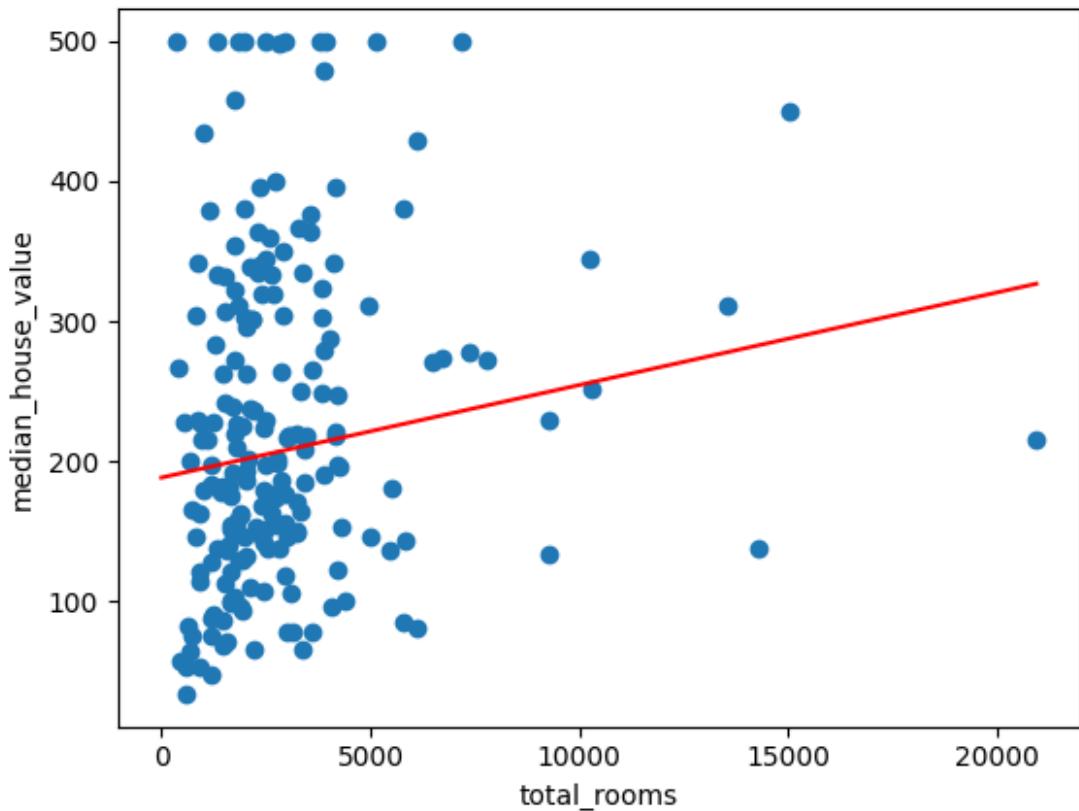
```
532/532 ━━━━━━━━ 0s 805us/step - loss: 13766.0332 -  
root_mean_squared_error: 117.3287  
Epoch 226/256  
532/532 ━━━━━━━━ 0s 819us/step - loss: 13737.6396 -  
root_mean_squared_error: 117.2077  
Epoch 227/256  
532/532 ━━━━━━━━ 0s 787us/step - loss: 13773.7588 -  
root_mean_squared_error: 117.3617  
Epoch 228/256  
532/532 ━━━━━━━━ 0s 803us/step - loss: 13725.5049 -  
root_mean_squared_error: 117.1559  
Epoch 229/256  
532/532 ━━━━━━━━ 0s 821us/step - loss: 13708.3291 -  
root_mean_squared_error: 117.0826  
Epoch 230/256  
532/532 ━━━━━━━━ 0s 778us/step - loss: 13726.3027 -  
root_mean_squared_error: 117.1593  
Epoch 231/256  
532/532 ━━━━━━━━ 0s 780us/step - loss: 13759.2803 -  
root_mean_squared_error: 117.3000  
Epoch 232/256  
532/532 ━━━━━━━━ 0s 782us/step - loss: 13715.3779 -  
root_mean_squared_error: 117.1127  
Epoch 233/256  
532/532 ━━━━━━━━ 0s 853us/step - loss: 13783.7744 -  
root_mean_squared_error: 117.4043  
Epoch 234/256  
532/532 ━━━━━━━━ 0s 769us/step - loss: 13718.4912 -  
root_mean_squared_error: 117.1260  
Epoch 235/256  
532/532 ━━━━━━━━ 0s 777us/step - loss: 13710.2061 -  
root_mean_squared_error: 117.0906  
Epoch 236/256  
532/532 ━━━━━━━━ 0s 824us/step - loss: 13795.7783 -  
root_mean_squared_error: 117.4554  
Epoch 237/256  
532/532 ━━━━━━━━ 0s 800us/step - loss: 13769.4443 -  
root_mean_squared_error: 117.3433  
Epoch 238/256  
532/532 ━━━━━━━━ 0s 773us/step - loss: 13788.2959 -  
root_mean_squared_error: 117.4236  
Epoch 239/256  
532/532 ━━━━━━━━ 0s 826us/step - loss: 13772.9697 -  
root_mean_squared_error: 117.3583  
Epoch 240/256  
532/532 ━━━━━━━━ 0s 799us/step - loss: 13712.5410 -  
root_mean_squared_error: 117.1006  
Epoch 241/256  
532/532 ━━━━━━━━ 0s 775us/step - loss: 13793.9805 -
```

```
root_mean_squared_error: 117.4478
Epoch 242/256
532/532 ━━━━━━━━ 0s 843us/step - loss: 13746.8223 -
root_mean_squared_error: 117.2468
Epoch 243/256
532/532 ━━━━━━━━ 0s 771us/step - loss: 13742.7734 -
root_mean_squared_error: 117.2296
Epoch 244/256
532/532 ━━━━━━━━ 0s 776us/step - loss: 13727.5850 -
root_mean_squared_error: 117.1648
Epoch 245/256
532/532 ━━━━━━━━ 0s 800us/step - loss: 13742.4805 -
root_mean_squared_error: 117.2283
Epoch 246/256
532/532 ━━━━━━━━ 0s 828us/step - loss: 13722.8164 -
root_mean_squared_error: 117.1444
Epoch 247/256
532/532 ━━━━━━━━ 0s 797us/step - loss: 13745.1816 -
root_mean_squared_error: 117.2398
Epoch 248/256
532/532 ━━━━━━━━ 0s 787us/step - loss: 13773.4111 -
root_mean_squared_error: 117.3602
Epoch 249/256
532/532 ━━━━━━━━ 0s 852us/step - loss: 13804.1689 -
root_mean_squared_error: 117.4911
Epoch 250/256
532/532 ━━━━━━━━ 0s 794us/step - loss: 13763.9062 -
root_mean_squared_error: 117.3197
Epoch 251/256
532/532 ━━━━━━━━ 0s 794us/step - loss: 13719.7373 -
root_mean_squared_error: 117.1313
Epoch 252/256
532/532 ━━━━━━━━ 0s 834us/step - loss: 13739.2598 -
root_mean_squared_error: 117.2146
Epoch 253/256
532/532 ━━━━━━━━ 0s 784us/step - loss: 13720.6885 -
root_mean_squared_error: 117.1353
Epoch 254/256
532/532 ━━━━━━━━ 0s 810us/step - loss: 13699.5703 -
root_mean_squared_error: 117.0452
Epoch 255/256
532/532 ━━━━━━━━ 0s 825us/step - loss: 13745.4736 -
root_mean_squared_error: 117.2411
Epoch 256/256
532/532 ━━━━━━━━ 0s 801us/step - loss: 13775.7480 -
root_mean_squared_error: 117.3701
```

The learned weight for your model is 0.0066

```
The learned bias for your model is 188.3858
```

```
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\62330301.py:21:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated  
NumPy 1.25.)  
    print("\nThe learned weight for your model is %.4f" % weight)  
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\62330301.py:22:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated  
NumPy 1.25.)  
    print("The learned bias for your model is %.4f\n" % bias )  
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\2255290996.py:14:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated  
NumPy 1.25.)  
    w = float(trained_weight)  
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\2255290996.py:15:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated  
NumPy 1.25.)  
    b = float(trained_bias)
```



A certain amount of randomness plays into training a model. Consequently, you'll get different results each time you train the model. That said, given the dataset and the hyperparameters, the trained model will generally do a poor job describing the feature's relation to the label.

Use the model to make predictions

You can use the trained model to make predictions. In practice, [you should make predictions on examples that are not used in training](#). However, for this exercise, you'll just work with a subset of the same training dataset. A later Colab exercise will explore ways to make predictions on examples not used in training.

First, run the following code to define the house prediction function:

```
def predict_house_values(n, feature, label):
    """Predict house values based on a feature."""

    batch = training_df[feature][10000:10000 + n]
    predicted_values = my_model.predict_on_batch(x=batch)

    print("feature      label          predicted")
    print("  value      value")
    print("           in thousand$   in thousand$")
    print("-----")
    for i in range(n):
        print ("%5.0f %6.0f %15.0f" % (training_df[feature][10000 + i],
                                           training_df[label][10000 + i],
                                           predicted_values[i][0] ))
```

Now, invoke the house prediction function on 10 examples:

```
predict_house_values(10, my_feature, my_label)

feature      label          predicted
  value      value
           in thousand$   in thousand$
```

feature	label	predicted
value	value	value
	in thousand\$	in thousand\$
1960	53	177
3400	92	210
3677	69	217
2202	62	183
2403	80	188
5652	295	262
3318	500	209
2552	342	191
1364	118	164
3468	128	212

Task 2: Judge the predictive power of the model

Look at the preceding table. How close is the predicted value to the label value? In other words, does your model accurately predict house values?

Using percent error, predictions start off extremely inaccurate—spiking around 226% above the actual values—and then gradually improve, dropping to about 65% error by the tenth iteration. This suggests the model struggles to capture the true relationship between the chosen feature (`total_rooms`) and label (median house values). Still, these first few cases may not fully represent the dataset, so the model's overall predictive power could differ when evaluated more broadly.

Task 3: Try a different feature

The `total_rooms` feature had only a little predictive power. Would a different feature have greater predictive power? Try using `population` as the feature instead of `total_rooms`.

Note: When you change features, you might also need to change the hyperparameters.

```
training_df.columns  
  
Index(['longitude', 'latitude', 'housing_median_age', 'total_rooms',  
       'total_bedrooms', 'population', 'households', 'median_income',  
       'median_house_value'],  
      dtype='object')  
  
my_feature = "population" # Replace the ? with population or  
possibly  
                      # a different column name.  
  
# Experiment with the hyperparameters.  
learning_rate = 0.001  
epochs = 128  
batch_size = 32  
  
# Don't change anything below this line.  
my_model = build_model(learning_rate)  
weight, bias, epochs, rmse = train_model(my_model, training_df,  
                                         my_feature, my_label,  
                                         epochs, batch_size)  
plot_the_model(weight, bias, my_feature, my_label)  
plot_the_loss_curve(epochs, rmse)  
  
predict_house_values(15, my_feature, my_label)  
  
Epoch 1/128  
  
c:\Users\micki\anaconda3\envs\tf_env\lib\site-packages\keras\src\  
layers\core\dense.py:92: UserWarning: Do not pass an  
`input_shape`/`input_dim` argument to a layer. When using Sequential  
models, prefer using an `Input(shape)` object as the first layer in
```

```
the model instead.
super().__init__(activity_regularizer=activity_regularizer,
**kwargs)

532/532 ————— 1s 806us/step - loss: 815981.0000 -
root_mean_squared_error: 903.3167
Epoch 2/128
532/532 ————— 0s 842us/step - loss: 58412.1797 -
root_mean_squared_error: 241.6861
Epoch 3/128
532/532 ————— 0s 837us/step - loss: 30832.9863 -
root_mean_squared_error: 175.5932
Epoch 4/128
532/532 ————— 0s 875us/step - loss: 30769.1523 -
root_mean_squared_error: 175.4114
Epoch 5/128
532/532 ————— 0s 817us/step - loss: 30730.8496 -
root_mean_squared_error: 175.3022
Epoch 6/128
532/532 ————— 0s 798us/step - loss: 30519.0430 -
root_mean_squared_error: 174.6970
Epoch 7/128
532/532 ————— 0s 809us/step - loss: 30451.1953 -
root_mean_squared_error: 174.5027
Epoch 8/128
532/532 ————— 0s 803us/step - loss: 30442.6973 -
root_mean_squared_error: 174.4784
Epoch 9/128
532/532 ————— 0s 818us/step - loss: 30263.0996 -
root_mean_squared_error: 173.9629
Epoch 10/128
532/532 ————— 0s 808us/step - loss: 30242.5371 -
root_mean_squared_error: 173.9038
Epoch 11/128
532/532 ————— 0s 827us/step - loss: 30164.0703 -
root_mean_squared_error: 173.6781
Epoch 12/128
532/532 ————— 0s 799us/step - loss: 30063.0332 -
root_mean_squared_error: 173.3869
Epoch 13/128
532/532 ————— 0s 867us/step - loss: 29996.5332 -
root_mean_squared_error: 173.1951
Epoch 14/128
532/532 ————— 0s 884us/step - loss: 29929.6367 -
root_mean_squared_error: 173.0018
Epoch 15/128
532/532 ————— 1s 1ms/step - loss: 29866.6074 -
root_mean_squared_error: 172.8196
Epoch 16/128
532/532 ————— 1s 1ms/step - loss: 29861.5156 -
```

```
root_mean_squared_error: 172.8049
Epoch 17/128
532/532 ━━━━━━━━ 1s 2ms/step - loss: 29737.1445 -
root_mean_squared_error: 172.4446
Epoch 18/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29688.5898 -
root_mean_squared_error: 172.3038
Epoch 19/128
532/532 ━━━━━━ 1s 991us/step - loss: 29559.5156 -
root_mean_squared_error: 171.9288
Epoch 20/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29468.7676 -
root_mean_squared_error: 171.6647
Epoch 21/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29411.9375 -
root_mean_squared_error: 171.4991
Epoch 22/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29296.1504 -
root_mean_squared_error: 171.1612
Epoch 23/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29290.2812 -
root_mean_squared_error: 171.1440
Epoch 24/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29139.6211 -
root_mean_squared_error: 170.7033
Epoch 25/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29139.5215 -
root_mean_squared_error: 170.7030
Epoch 26/128
532/532 ━━━━━━ 1s 1ms/step - loss: 29040.6113 -
root_mean_squared_error: 170.4131
Epoch 27/128
532/532 ━━━━━━ 1s 1ms/step - loss: 28941.3203 -
root_mean_squared_error: 170.1215
Epoch 28/128
532/532 ━━━━━━ 1s 963us/step - loss: 28907.1152 -
root_mean_squared_error: 170.0209
Epoch 29/128
532/532 ━━━━━━ 0s 876us/step - loss: 28924.6289 -
root_mean_squared_error: 170.0724
Epoch 30/128
532/532 ━━━━━━ 1s 947us/step - loss: 28703.0957 -
root_mean_squared_error: 169.4199
Epoch 31/128
532/532 ━━━━━━ 0s 885us/step - loss: 28644.3770 -
root_mean_squared_error: 169.2465
Epoch 32/128
532/532 ━━━━━━ 0s 821us/step - loss: 28599.8691 -
root_mean_squared_error: 169.1150
```

```
Epoch 33/128
532/532 ━━━━━━━━ 0s 878us/step - loss: 28651.2031 -
root_mean_squared_error: 169.2667
Epoch 34/128
532/532 ━━━━━━━━ 0s 818us/step - loss: 28378.7832 -
root_mean_squared_error: 168.4600
Epoch 35/128
532/532 ━━━━━━━━ 0s 891us/step - loss: 28355.4160 -
root_mean_squared_error: 168.3907
Epoch 36/128
532/532 ━━━━━━━━ 0s 815us/step - loss: 28249.5000 -
root_mean_squared_error: 168.0759
Epoch 37/128
532/532 ━━━━━━━━ 0s 827us/step - loss: 28085.7031 -
root_mean_squared_error: 167.5879
Epoch 38/128
532/532 ━━━━━━━━ 0s 842us/step - loss: 28109.7070 -
root_mean_squared_error: 167.6595
Epoch 39/128
532/532 ━━━━━━━━ 0s 831us/step - loss: 28033.1328 -
root_mean_squared_error: 167.4310
Epoch 40/128
532/532 ━━━━━━━━ 0s 884us/step - loss: 27924.6660 -
root_mean_squared_error: 167.1068
Epoch 41/128
532/532 ━━━━━━━━ 0s 811us/step - loss: 27897.7480 -
root_mean_squared_error: 167.0262
Epoch 42/128
532/532 ━━━━━━━━ 0s 814us/step - loss: 27740.0234 -
root_mean_squared_error: 166.5534
Epoch 43/128
532/532 ━━━━━━━━ 0s 800us/step - loss: 27705.7129 -
root_mean_squared_error: 166.4503
Epoch 44/128
532/532 ━━━━━━━━ 0s 831us/step - loss: 27680.6191 -
root_mean_squared_error: 166.3749
Epoch 45/128
532/532 ━━━━━━━━ 0s 784us/step - loss: 27521.1680 -
root_mean_squared_error: 165.8951
Epoch 46/128
532/532 ━━━━━━━━ 0s 863us/step - loss: 27534.2598 -
root_mean_squared_error: 165.9345
Epoch 47/128
532/532 ━━━━━━━━ 0s 836us/step - loss: 27542.6719 -
root_mean_squared_error: 165.9599
Epoch 48/128
532/532 ━━━━━━━━ 0s 852us/step - loss: 27330.6758 -
root_mean_squared_error: 165.3199
Epoch 49/128
```

```
532/532 ━━━━━━━━ 0s 873us/step - loss: 27382.0195 -  
root_mean_squared_error: 165.4751  
Epoch 50/128  
532/532 ━━━━━━━━ 0s 890us/step - loss: 27198.6602 -  
root_mean_squared_error: 164.9202  
Epoch 51/128  
532/532 ━━━━━━ 1s 925us/step - loss: 27147.2129 -  
root_mean_squared_error: 164.7641  
Epoch 52/128  
532/532 ━━━━━━ 0s 898us/step - loss: 27017.8301 -  
root_mean_squared_error: 164.3710  
Epoch 53/128  
532/532 ━━━━━━ 1s 1ms/step - loss: 27038.0352 -  
root_mean_squared_error: 164.4325  
Epoch 54/128  
532/532 ━━━━━━ 1s 920us/step - loss: 26946.1094 -  
root_mean_squared_error: 164.1527  
Epoch 55/128  
532/532 ━━━━━━ 1s 993us/step - loss: 26824.3066 -  
root_mean_squared_error: 163.7813  
Epoch 56/128  
532/532 ━━━━━━ 1s 960us/step - loss: 26847.9238 -  
root_mean_squared_error: 163.8534  
Epoch 57/128  
532/532 ━━━━━━ 1s 1ms/step - loss: 26741.8438 -  
root_mean_squared_error: 163.5293  
Epoch 58/128  
532/532 ━━━━━━ 0s 854us/step - loss: 26705.3398 -  
root_mean_squared_error: 163.4177  
Epoch 59/128  
532/532 ━━━━━━ 0s 824us/step - loss: 26499.2363 -  
root_mean_squared_error: 162.7859  
Epoch 60/128  
532/532 ━━━━━━ 0s 809us/step - loss: 26548.2461 -  
root_mean_squared_error: 162.9363  
Epoch 61/128  
532/532 ━━━━━━ 0s 872us/step - loss: 26461.0488 -  
root_mean_squared_error: 162.6685  
Epoch 62/128  
532/532 ━━━━━━ 0s 870us/step - loss: 26232.8008 -  
root_mean_squared_error: 161.9654  
Epoch 63/128  
532/532 ━━━━━━ 0s 882us/step - loss: 26269.7070 -  
root_mean_squared_error: 162.0793  
Epoch 64/128  
532/532 ━━━━━━ 1s 913us/step - loss: 26241.0977 -  
root_mean_squared_error: 161.9910  
Epoch 65/128  
532/532 ━━━━━━ 1s 900us/step - loss: 26125.3418 -
```

```
root_mean_squared_error: 161.6334
Epoch 66/128
532/532 ━━━━━━━━ 0s 866us/step - loss: 26131.7246 -
root_mean_squared_error: 161.6531
Epoch 67/128
532/532 ━━━━━━━━ 0s 842us/step - loss: 25946.0215 -
root_mean_squared_error: 161.0777
Epoch 68/128
532/532 ━━━━━━━━ 0s 838us/step - loss: 26027.9551 -
root_mean_squared_error: 161.3318
Epoch 69/128
532/532 ━━━━━━━━ 0s 841us/step - loss: 25887.2500 -
root_mean_squared_error: 160.8952
Epoch 70/128
532/532 ━━━━━━━━ 0s 891us/step - loss: 25809.7793 -
root_mean_squared_error: 160.6542
Epoch 71/128
532/532 ━━━━━━━━ 0s 797us/step - loss: 25754.8926 -
root_mean_squared_error: 160.4833
Epoch 72/128
532/532 ━━━━━━━━ 0s 843us/step - loss: 25666.3789 -
root_mean_squared_error: 160.2073
Epoch 73/128
532/532 ━━━━━━━━ 0s 846us/step - loss: 25609.1777 -
root_mean_squared_error: 160.0287
Epoch 74/128
532/532 ━━━━━━━━ 0s 883us/step - loss: 25589.9102 -
root_mean_squared_error: 159.9685
Epoch 75/128
532/532 ━━━━━━━━ 0s 807us/step - loss: 25456.4219 -
root_mean_squared_error: 159.5507
Epoch 76/128
532/532 ━━━━━━━━ 0s 852us/step - loss: 25397.4844 -
root_mean_squared_error: 159.3659
Epoch 77/128
532/532 ━━━━━━━━ 0s 801us/step - loss: 25332.9473 -
root_mean_squared_error: 159.1633
Epoch 78/128
532/532 ━━━━━━━━ 0s 803us/step - loss: 25276.6543 -
root_mean_squared_error: 158.9863
Epoch 79/128
532/532 ━━━━━━━━ 0s 849us/step - loss: 25169.0508 -
root_mean_squared_error: 158.6476
Epoch 80/128
532/532 ━━━━━━━━ 0s 814us/step - loss: 25108.9414 -
root_mean_squared_error: 158.4580
Epoch 81/128
532/532 ━━━━━━━━ 0s 797us/step - loss: 25047.2578 -
root_mean_squared_error: 158.2633
```

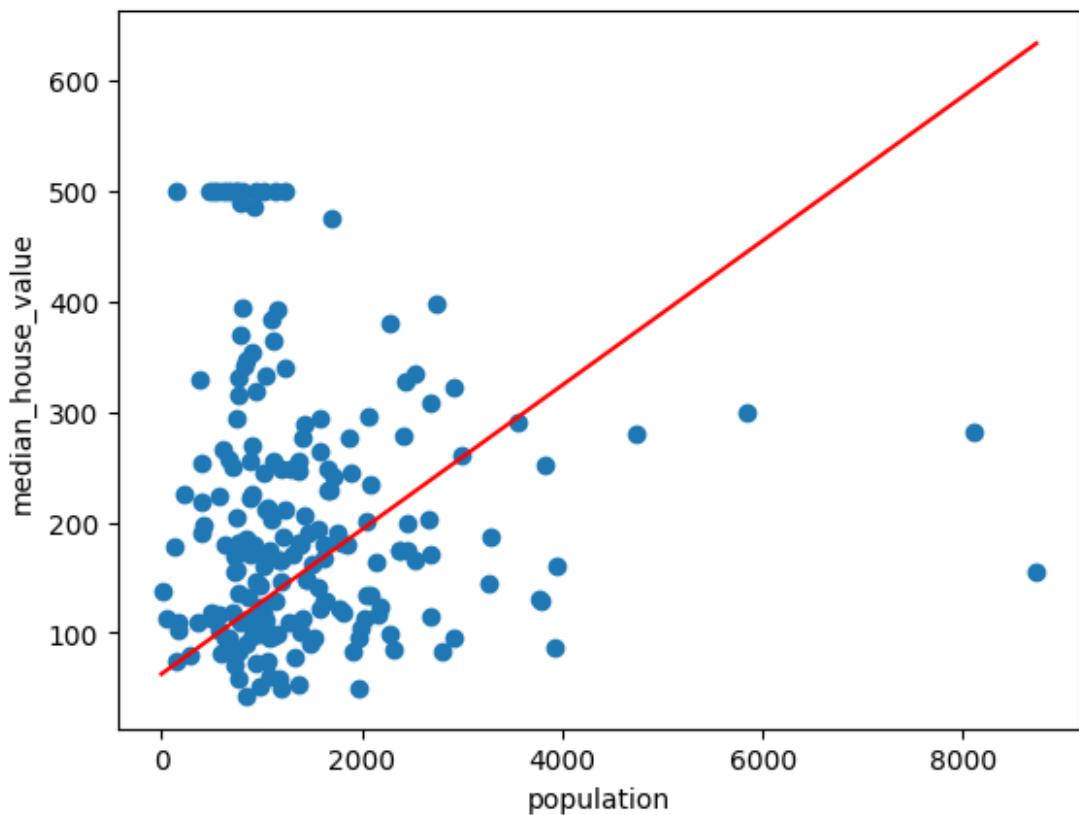
```
Epoch 82/128
532/532 0s 894us/step - loss: 24976.8809 -
root_mean_squared_error: 158.0408
Epoch 83/128
532/532 0s 884us/step - loss: 24946.6484 -
root_mean_squared_error: 157.9451
Epoch 84/128
532/532 0s 873us/step - loss: 24867.2305 -
root_mean_squared_error: 157.6935
Epoch 85/128
532/532 0s 844us/step - loss: 24763.1309 -
root_mean_squared_error: 157.3631
Epoch 86/128
532/532 0s 859us/step - loss: 24781.0684 -
root_mean_squared_error: 157.4200
Epoch 87/128
532/532 0s 889us/step - loss: 24576.7559 -
root_mean_squared_error: 156.7698
Epoch 88/128
532/532 1s 936us/step - loss: 24577.4805 -
root_mean_squared_error: 156.7721
Epoch 89/128
532/532 1s 986us/step - loss: 24541.6504 -
root_mean_squared_error: 156.6577
Epoch 90/128
532/532 0s 836us/step - loss: 24496.8613 -
root_mean_squared_error: 156.5147
Epoch 91/128
532/532 0s 841us/step - loss: 24452.5781 -
root_mean_squared_error: 156.3732
Epoch 92/128
532/532 1s 934us/step - loss: 24353.4961 -
root_mean_squared_error: 156.0561
Epoch 93/128
532/532 1s 901us/step - loss: 24346.0684 -
root_mean_squared_error: 156.0323
Epoch 94/128
532/532 0s 890us/step - loss: 24209.9297 -
root_mean_squared_error: 155.5954
Epoch 95/128
532/532 0s 813us/step - loss: 24327.7656 -
root_mean_squared_error: 155.9736
Epoch 96/128
532/532 0s 852us/step - loss: 24098.3066 -
root_mean_squared_error: 155.2363
Epoch 97/128
532/532 0s 836us/step - loss: 23974.4551 -
root_mean_squared_error: 154.8369
Epoch 98/128
```

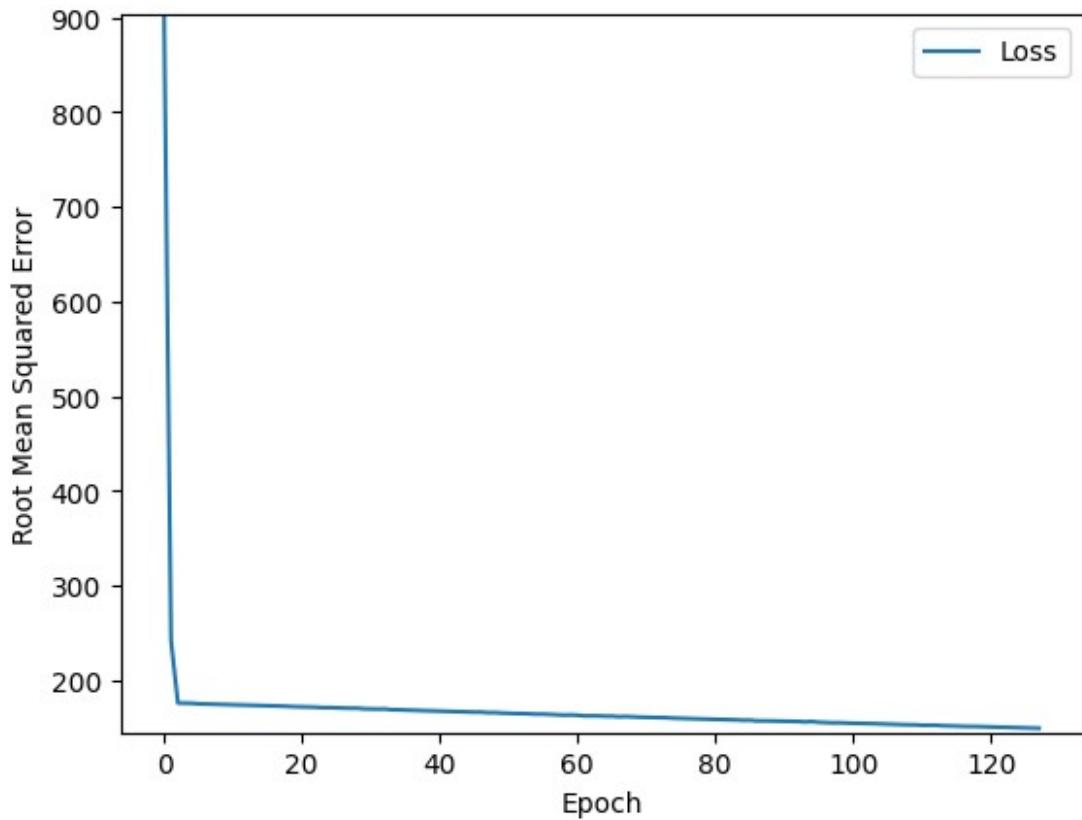
```
532/532 ━━━━━━━━ 0s 827us/step - loss: 23917.1777 -  
root_mean_squared_error: 154.6518  
Epoch 99/128  
532/532 ━━━━━━━━ 0s 836us/step - loss: 23938.2812 -  
root_mean_squared_error: 154.7200  
Epoch 100/128  
532/532 ━━━━━━━━ 0s 859us/step - loss: 23821.2109 -  
root_mean_squared_error: 154.3412  
Epoch 101/128  
532/532 ━━━━━━━━ 0s 830us/step - loss: 23767.3945 -  
root_mean_squared_error: 154.1668  
Epoch 102/128  
532/532 ━━━━━━━━ 0s 806us/step - loss: 23734.5234 -  
root_mean_squared_error: 154.0601  
Epoch 103/128  
532/532 ━━━━━━━━ 0s 823us/step - loss: 23709.4180 -  
root_mean_squared_error: 153.9786  
Epoch 104/128  
532/532 ━━━━━━━━ 0s 832us/step - loss: 23637.2051 -  
root_mean_squared_error: 153.7440  
Epoch 105/128  
532/532 ━━━━━━━━ 0s 879us/step - loss: 23546.0820 -  
root_mean_squared_error: 153.4473  
Epoch 106/128  
532/532 ━━━━━━━━ 0s 820us/step - loss: 23472.4551 -  
root_mean_squared_error: 153.2072  
Epoch 107/128  
532/532 ━━━━━━━━ 0s 810us/step - loss: 23427.3027 -  
root_mean_squared_error: 153.0598  
Epoch 108/128  
532/532 ━━━━━━━━ 0s 826us/step - loss: 23342.7773 -  
root_mean_squared_error: 152.7834  
Epoch 109/128  
532/532 ━━━━━━━━ 0s 889us/step - loss: 23265.5879 -  
root_mean_squared_error: 152.5306  
Epoch 110/128  
532/532 ━━━━━━━━ 0s 836us/step - loss: 23265.5684 -  
root_mean_squared_error: 152.5305  
Epoch 111/128  
532/532 ━━━━━━━━ 0s 824us/step - loss: 23114.7988 -  
root_mean_squared_error: 152.0355  
Epoch 112/128  
532/532 ━━━━━━━━ 0s 838us/step - loss: 23104.2188 -  
root_mean_squared_error: 152.0007  
Epoch 113/128  
532/532 ━━━━━━━━ 0s 872us/step - loss: 23123.3770 -  
root_mean_squared_error: 152.0637  
Epoch 114/128  
532/532 ━━━━━━━━ 0s 811us/step - loss: 22968.3574 -
```

```
root_mean_squared_error: 151.5531
Epoch 115/128
532/532 ━━━━━━━━ 0s 832us/step - loss: 22937.9102 -
root_mean_squared_error: 151.4527
Epoch 116/128
532/532 ━━━━━━━━ 0s 809us/step - loss: 22870.7168 -
root_mean_squared_error: 151.2307
Epoch 117/128
532/532 ━━━━━━━━ 0s 866us/step - loss: 22769.6660 -
root_mean_squared_error: 150.8962
Epoch 118/128
532/532 ━━━━━━━━ 0s 793us/step - loss: 22758.4492 -
root_mean_squared_error: 150.8590
Epoch 119/128
532/532 ━━━━━━━━ 1s 956us/step - loss: 22719.0703 -
root_mean_squared_error: 150.7285
Epoch 120/128
532/532 ━━━━━━━━ 0s 859us/step - loss: 22658.7383 -
root_mean_squared_error: 150.5282
Epoch 121/128
532/532 ━━━━━━━━ 0s 794us/step - loss: 22537.7969 -
root_mean_squared_error: 150.1259
Epoch 122/128
532/532 ━━━━━━━━ 0s 877us/step - loss: 22553.8047 -
root_mean_squared_error: 150.1792
Epoch 123/128
532/532 ━━━━━━━━ 0s 804us/step - loss: 22481.9531 -
root_mean_squared_error: 149.9398
Epoch 124/128
532/532 ━━━━━━━━ 0s 815us/step - loss: 22403.4258 -
root_mean_squared_error: 149.6777
Epoch 125/128
532/532 ━━━━━━━━ 0s 804us/step - loss: 22384.2676 -
root_mean_squared_error: 149.6137
Epoch 126/128
532/532 ━━━━━━━━ 0s 810us/step - loss: 22308.9004 -
root_mean_squared_error: 149.3616
Epoch 127/128
532/532 ━━━━━━━━ 0s 828us/step - loss: 22271.1719 -
root_mean_squared_error: 149.2353
Epoch 128/128
532/532 ━━━━━━━━ 0s 796us/step - loss: 22161.7773 -
root_mean_squared_error: 148.8683
```

```
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\2255290996.py:14:
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar
is deprecated, and will error in future. Ensure you extract a single
element from your array before performing this operation. (Deprecated
NumPy 1.25.)
    w = float(trained_weight)
```

```
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\2255290996.py:15:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated  
NumPy 1.25.)  
    b = float(trained_bias)
```





```

WARNING:tensorflow:5 out of the last 5 calls to <function
TensorFlowTrainer.make_predict_function.<locals>.one_step_on_data_distributed
at 0x00000171DB08EC20> triggered tf.function retracing.
Tracing is expensive and the excessive number of tracings could be due to (1) creating @tf.function repeatedly in a loop, (2) passing tensors with different shapes, (3) passing Python objects instead of tensors.
For (1), please define your @tf.function outside of the loop. For (2), @tf.function has reduce_retracing=True option that can avoid unnecessary retracing. For (3), please refer to
https://www.tensorflow.org/guide/function#controlling\_retracing and
https://www.tensorflow.org/api\_docs/python/tf/function for more details.

```

feature	label	predicted
value	value	value
	in thousand\$	in thousand\$
<hr/>		
1286	53	147
1867	92	185
2191	69	206
1052	62	131
1647	80	170
2312	295	214
1604	500	168
1066	342	132

338	118	85
1604	128	168
1200	187	141
292	80	82
2014	112	194
1817	95	181
1328	69	150

```

my_feature = "population" # Pick a feature other than "total_rooms"

# Possibly, experiment with the hyperparameters.
learning_rate = 0.05
epochs = 18
batch_size = 3

# Don't change anything below.
my_model = build_model(learning_rate)
weight, bias, epochs, rmse = train_model(my_model, training_df,
                                         my_feature, my_label,
                                         epochs, batch_size)

plot_the_model(weight, bias, my_feature, my_label)
plot_the_loss_curve(epochs, rmse)

predict_house_values(10, my_feature, my_label)

Epoch 1/18

c:\Users\micki\anaconda3\envs\tf_env\lib\site-packages\keras\src\
layers\core\dense.py:92: UserWarning: Do not pass an
`input_shape`/`input_dim` argument to a layer. When using Sequential
models, prefer using an `Input(shape)` object as the first layer in
the model instead.
    super().__init__(activity_regularizer=activity_regularizer,
**kwargs)

5667/5667 ██████████ 5s 802us/step - loss: 41442.5352 -
root_mean_squared_error: 203.5744
Epoch 2/18
5667/5667 ██████████ 5s 817us/step - loss: 19937.4512 -
root_mean_squared_error: 141.2000
Epoch 3/18
5667/5667 ██████████ 5s 944us/step - loss: 18317.3809 -
root_mean_squared_error: 135.3417
Epoch 4/18
5667/5667 ██████████ 6s 1ms/step - loss: 17744.2500 -
root_mean_squared_error: 133.2076
Epoch 5/18
5667/5667 ██████████ 5s 842us/step - loss: 18127.0254 -
root_mean_squared_error: 134.6366
Epoch 6/18

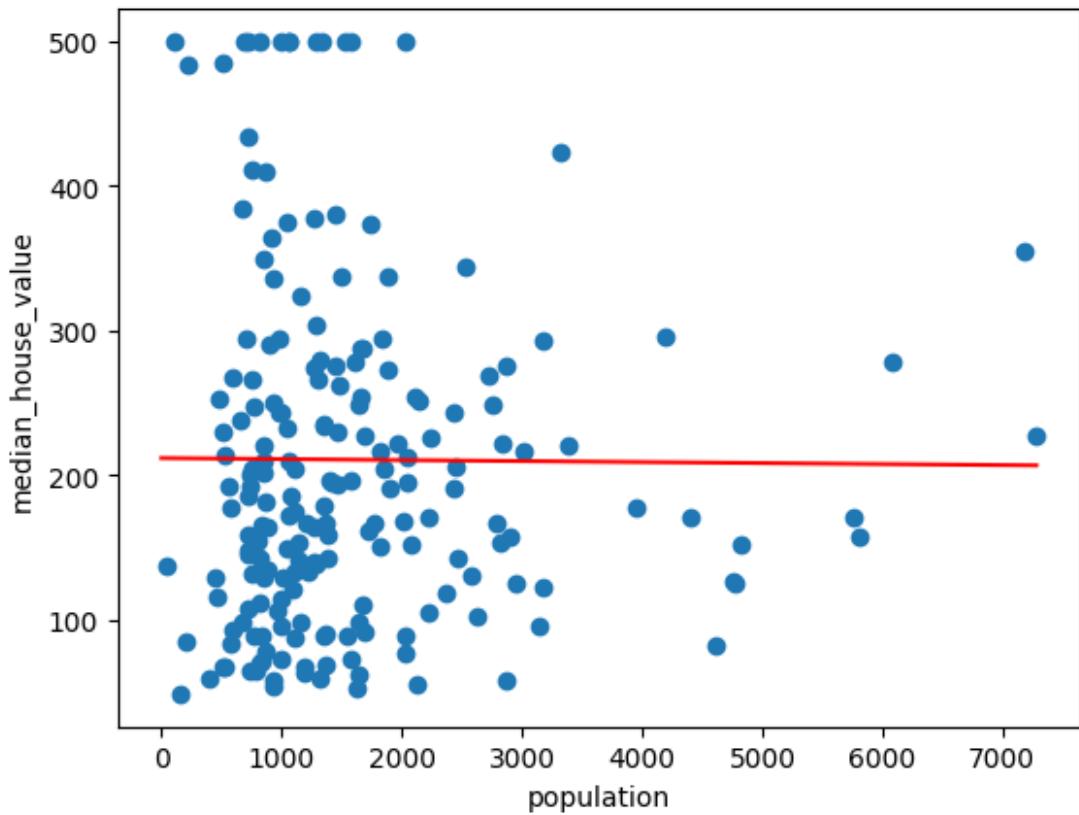
```

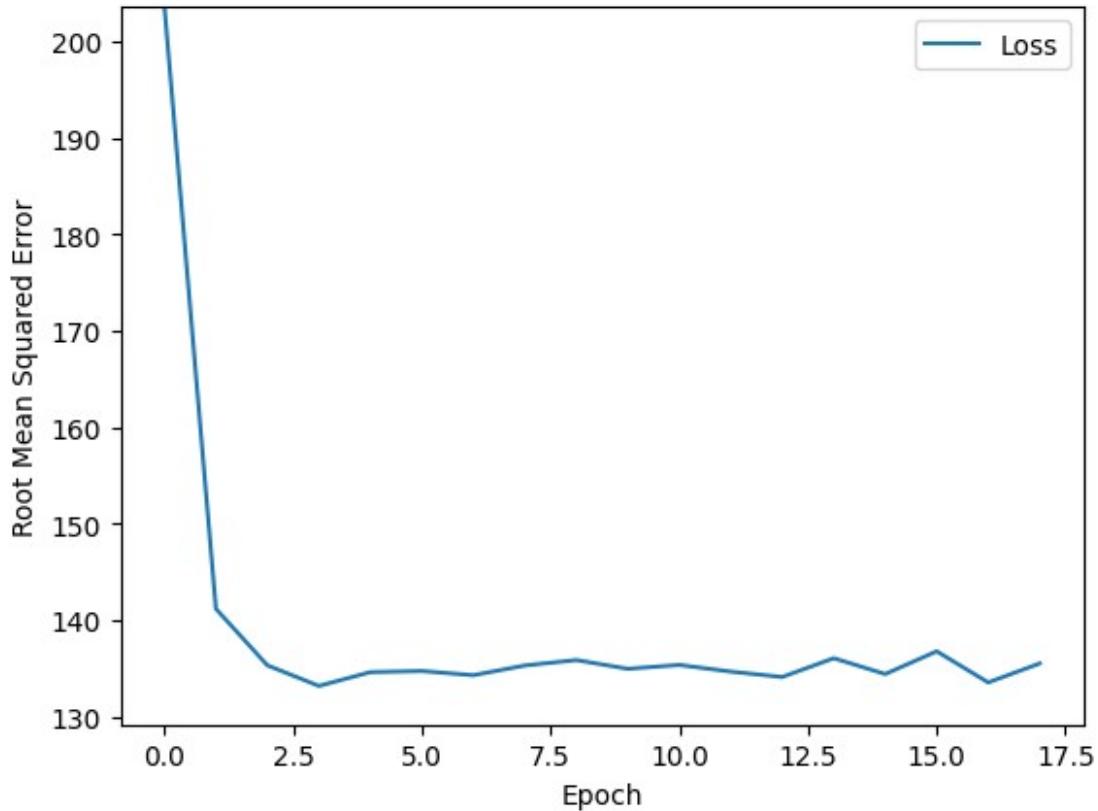
```
5667/5667 ━━━━━━━━ 5s 861us/step - loss: 18158.4492 -  
root_mean_squared_error: 134.7533  
Epoch 7/18  
5667/5667 ━━━━━━━━ 5s 802us/step - loss: 18041.1641 -  
root_mean_squared_error: 134.3174  
Epoch 8/18  
5667/5667 ━━━━━━ 4s 785us/step - loss: 18312.9805 -  
root_mean_squared_error: 135.3255  
Epoch 9/18  
5667/5667 ━━━━━━ 5s 833us/step - loss: 18465.4902 -  
root_mean_squared_error: 135.8878  
Epoch 10/18  
5667/5667 ━━━━━━ 5s 847us/step - loss: 18221.2480 -  
root_mean_squared_error: 134.9861  
Epoch 11/18  
5667/5667 ━━━━━━ 6s 990us/step - loss: 18328.3906 -  
root_mean_squared_error: 135.3824  
Epoch 12/18  
5667/5667 ━━━━━━ 5s 915us/step - loss: 18142.0938 -  
root_mean_squared_error: 134.6926  
Epoch 13/18  
5667/5667 ━━━━━━ 5s 904us/step - loss: 17991.9414 -  
root_mean_squared_error: 134.1340  
Epoch 14/18  
5667/5667 ━━━━━━ 5s 823us/step - loss: 18517.8164 -  
root_mean_squared_error: 136.0802  
Epoch 15/18  
5667/5667 ━━━━━━ 5s 816us/step - loss: 18073.5000 -  
root_mean_squared_error: 134.4377  
Epoch 16/18  
5667/5667 ━━━━━━ 5s 812us/step - loss: 18713.5137 -  
root_mean_squared_error: 136.7973  
Epoch 17/18  
5667/5667 ━━━━━━ 5s 827us/step - loss: 17840.4727 -  
root_mean_squared_error: 133.5682  
Epoch 18/18  
5667/5667 ━━━━━━ 5s 848us/step - loss: 18369.8418 -  
root_mean_squared_error: 135.5354
```

```
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\2255290996.py:14:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated  
NumPy 1.25.)  
    w = float(trained_weight)  
C:\Users\micki\AppData\Local\Temp\ipykernel_22432\2255290996.py:15:  
DeprecationWarning: Conversion of an array with ndim > 0 to a scalar  
is deprecated, and will error in future. Ensure you extract a single  
element from your array before performing this operation. (Deprecated
```

```
NumPy 1.25.)
```

```
b = float(trained_bias)
```





feature value	label value in thousand\$	predicted value in thousand\$
<hr/>		
1286	53	211
1867	92	211
2191	69	210
1052	62	211
1647	80	211
2312	295	210
1604	500	211
1066	342	211
338	118	212
1604	128	211

Did `population` produce better predictions than `total_rooms`?

Using `population` usually ended up with a higher RMSE than `total_rooms`. This suggests that `population` performs a bit worse than `total_rooms` when it comes to making predictions.

Task 4: Define a synthetic feature

You have determined that `total_rooms` and `population` were not useful features. That is, neither the total number of rooms in a neighborhood nor the neighborhood's population successfully predicted the median house price of that neighborhood. Perhaps though, the *ratio* of `total_rooms` to `population` might have some predictive power. That is, perhaps block density relates to median house value.

To explore this hypothesis, do the following:

1. Create a [synthetic feature](#) that's a ratio of `total_rooms` to `population`. (If you are new to pandas DataFrames, please study the [Pandas DataFrame Ultraquick Tutorial](#).)
2. Tune the three hyperparameters.
3. Determine whether this synthetic feature produces a lower loss value than any of the single features you tried earlier in this exercise.

```
# Define a synthetic feature
training_df["rooms_per_person"] = training_df["total_rooms"] /
    training_df["population"]
my_feature = "rooms_per_person"

# Tune the hyperparameters.
learning_rate = 0.06
epochs = 24
batch_size = 30

# Don't change anything below this line.
my_model = build_model(learning_rate)
weight, bias, epochs, mae = train_model(my_model, training_df,
                                         my_feature, my_label,
                                         epochs, batch_size)

plot_the_loss_curve(epochs, mae)
predict_house_values(15, my_feature, my_label)

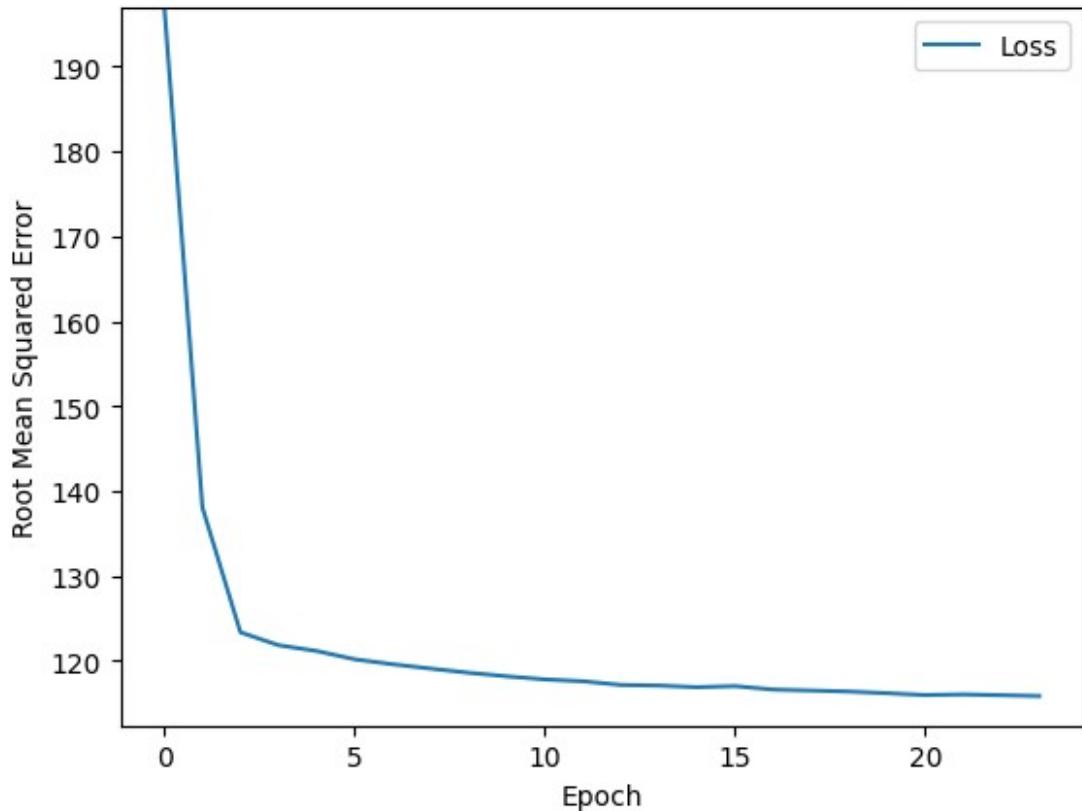
Epoch 1/24

c:\Users\micki\anaconda3\envs\tf_env\lib\site-packages\keras\src\
layers\core\dense.py:92: UserWarning: Do not pass an
`input_shape`/`input_dim` argument to a layer. When using Sequential
models, prefer using an `Input(shape)` object as the first layer in
the model instead.
    super().__init__(activity_regularizer=activity_regularizer,
**kwargs)

567/567 ━━━━━━━━ 1s 857us/step - loss: 38772.3594 -
root_mean_squared_error: 196.9070
Epoch 2/24
567/567 ━━━━━━━━ 0s 825us/step - loss: 19060.9531 -
root_mean_squared_error: 138.0614
Epoch 3/24
```

```
567/567 ━━━━━━━━ 1s 884us/step - loss: 15217.3223 -  
root_mean_squared_error: 123.3585  
Epoch 4/24  
567/567 ━━━━━━ 1s 924us/step - loss: 14845.8965 -  
root_mean_squared_error: 121.8437  
Epoch 5/24  
567/567 ━━━━━━ 1s 1ms/step - loss: 14681.0723 -  
root_mean_squared_error: 121.1655  
Epoch 6/24  
567/567 ━━━━━━ 0s 815us/step - loss: 14444.9307 -  
root_mean_squared_error: 120.1871  
Epoch 7/24  
567/567 ━━━━━━ 0s 789us/step - loss: 14304.4619 -  
root_mean_squared_error: 119.6013  
Epoch 8/24  
567/567 ━━━━━━ 0s 838us/step - loss: 14182.6895 -  
root_mean_squared_error: 119.0911  
Epoch 9/24  
567/567 ━━━━━━ 0s 793us/step - loss: 14065.9951 -  
root_mean_squared_error: 118.6002  
Epoch 10/24  
567/567 ━━━━━━ 0s 792us/step - loss: 13967.2627 -  
root_mean_squared_error: 118.1832  
Epoch 11/24  
567/567 ━━━━━━ 1s 866us/step - loss: 13880.8789 -  
root_mean_squared_error: 117.8171  
Epoch 12/24  
567/567 ━━━━━━ 0s 815us/step - loss: 13829.8428 -  
root_mean_squared_error: 117.6003  
Epoch 13/24  
567/567 ━━━━━━ 1s 845us/step - loss: 13728.5078 -  
root_mean_squared_error: 117.1687  
Epoch 14/24  
567/567 ━━━━━━ 0s 801us/step - loss: 13710.8496 -  
root_mean_squared_error: 117.0933  
Epoch 15/24  
567/567 ━━━━━━ 0s 823us/step - loss: 13665.8115 -  
root_mean_squared_error: 116.9009  
Epoch 16/24  
567/567 ━━━━━━ 0s 784us/step - loss: 13695.6846 -  
root_mean_squared_error: 117.0286  
Epoch 17/24  
567/567 ━━━━━━ 0s 814us/step - loss: 13600.8125 -  
root_mean_squared_error: 116.6225  
Epoch 18/24  
567/567 ━━━━━━ 1s 853us/step - loss: 13574.3486 -  
root_mean_squared_error: 116.5090  
Epoch 19/24  
567/567 ━━━━━━ 0s 776us/step - loss: 13546.3359 -
```

```
root_mean_squared_error: 116.3887
Epoch 20/24
567/567 ██████████ 0s 797us/step - loss: 13500.7686 -
root_mean_squared_error: 116.1928
Epoch 21/24
567/567 ██████████ 0s 840us/step - loss: 13450.1309 -
root_mean_squared_error: 115.9747
Epoch 22/24
567/567 ██████████ 1s 862us/step - loss: 13466.7939 -
root_mean_squared_error: 116.0465
Epoch 23/24
567/567 ██████████ 1s 861us/step - loss: 13446.0537 -
root_mean_squared_error: 115.9571
Epoch 24/24
567/567 ██████████ 0s 787us/step - loss: 13424.3984 -
root_mean_squared_error: 115.8637
```



```
WARNING:tensorflow:6 out of the last 6 calls to <function
TensorFlowTrainer.make_predict_function.<locals>.one_step_on_data_distributed
at 0x00000171DB107F40> triggered tf.function retracing.
Tracing is expensive and the excessive number of tracings could be due
to (1) creating @tf.function repeatedly in a loop, (2) passing tensors
with different shapes, (3) passing Python objects instead of tensors.
```

For (1), please define your `@tf.function` outside of the loop. For (2), `@tf.function` has `reduce_retracing=True` option that can avoid unnecessary retracing. For (3), please refer to https://www.tensorflow.org/guide/function#controlling_retracing and https://www.tensorflow.org/api_docs/python/tf/function for more details.

feature value	label value in thousand\$	predicted value in thousand\$
2	53	190
2	92	202
2	69	196
2	62	213
1	80	187
2	295	227
2	500	212
2	342	225
4	118	292
2	128	216
2	187	226
3	80	237
2	112	227
2	95	221
2	69	212

Based on the loss values, this synthetic feature produces a better model than the individual features you tried in Task 2 and Task 3. However, the model still isn't creating great predictions.

Task 5. Find feature(s) whose raw values correlate with the label

So far, we've relied on trial-and-error to identify possible features for the model. Let's rely on statistics instead.

A **correlation matrix** indicates how each attribute's raw values relate to the other attributes' raw values. Correlation values have the following meanings:

- **1.0**: perfect positive correlation; that is, when one attribute rises, the other attribute rises.
- **-1.0**: perfect negative correlation; that is, when one attribute rises, the other attribute falls.
- **0.0**: no correlation; the two columns [are not linearly related](#).

In general, the higher the absolute value of a correlation value, the greater its predictive power. For example, a correlation value of -0.8 implies far more predictive power than a correlation of -0.2.

The following code cell generates the correlation matrix for attributes of the California Housing Dataset:

```
# Generate a correlation matrix.
training_df.corr()
```

	longitude	latitude	housing_median_age
total_rooms \ longitude	1.0	-0.9	-0.1
0.0 latitude	-0.9	1.0	0.0
0.0 housing_median_age	-0.1	0.0	1.0
0.4 total_rooms	0.0	-0.0	-0.4
1.0 total_bedrooms	0.1	-0.1	-0.3
0.9 population	0.1	-0.1	-0.3
0.9 households	0.1	-0.1	-0.3
0.9 median_income	-0.0	-0.1	-0.1
0.2 median_house_value	-0.0	-0.1	0.1
0.1 rooms_per_person	-0.1	0.1	-0.1
0.1			
	total_bedrooms	population	households
median_income \ longitude	0.1	0.1	0.1
0.0 latitude	-0.1	-0.1	-0.1
0.1 housing_median_age	-0.3	-0.3	-0.3
0.1 total_rooms	0.9	0.9	0.9
0.2 total_bedrooms	1.0	0.9	1.0
0.0 population	0.9	1.0	0.9
0.0 households	1.0	0.9	1.0
0.0 median_income	-0.0	-0.0	0.0
1.0 median_house_value	0.0	-0.0	0.1
0.7 rooms_per_person	0.0	-0.1	-0.0

0.2

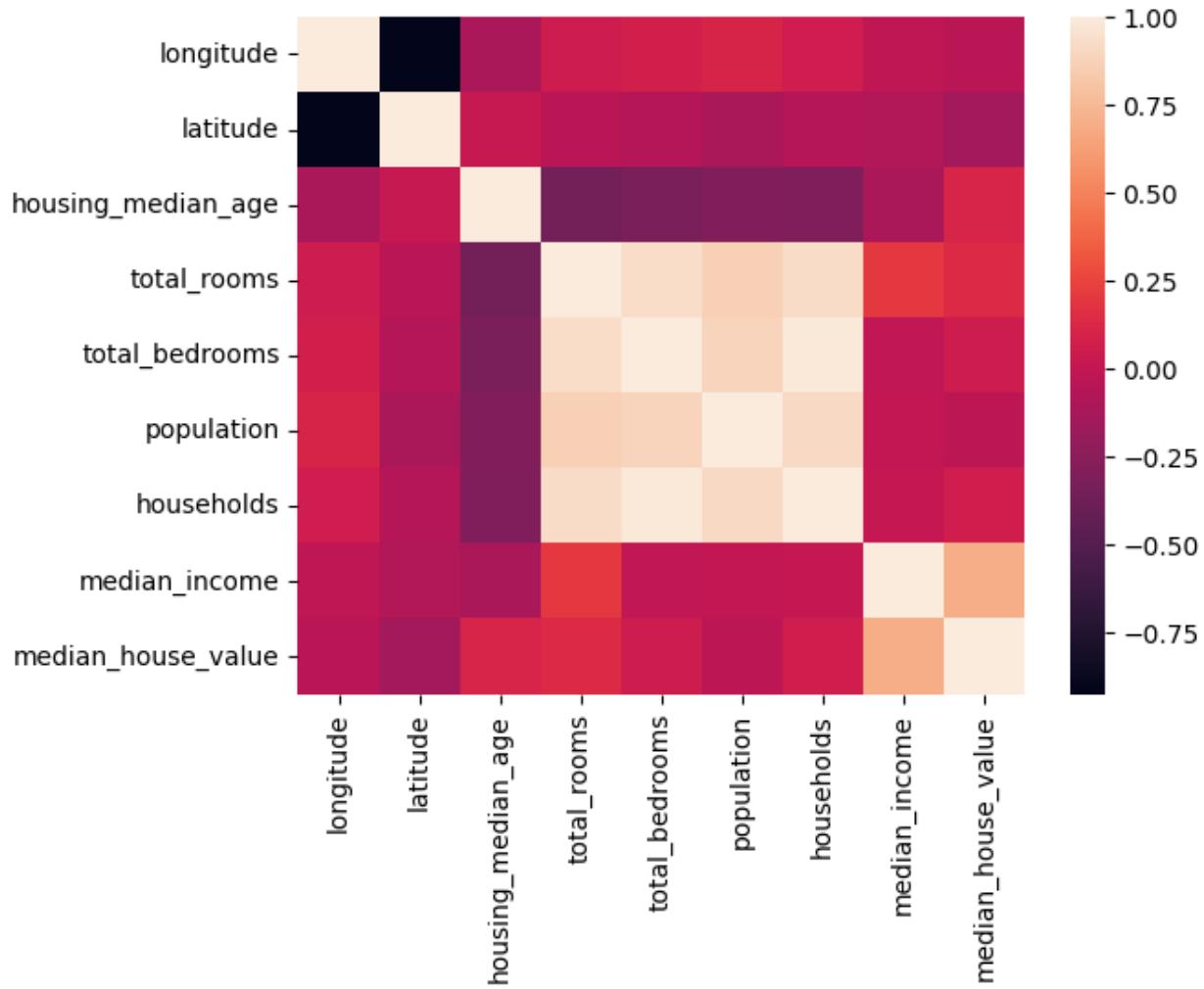
	median_house_value	rooms_per_person
longitude	-0.0	-0.1
latitude	-0.1	0.1
housing_median_age	0.1	-0.1
total_rooms	0.1	0.1
total_bedrooms	0.0	0.0
population	-0.0	-0.1
households	0.1	-0.0
median_income	0.7	0.2
median_house_value	1.0	0.2
rooms_per_person	0.2	1.0

The correlation matrix shows nine potential features (including a synthetic feature) and one label (`median_house_value`). A strong negative correlation or strong positive correlation with the label suggests a potentially good feature.

Your Task: Determine which of the nine potential features appears to be the best candidate for a feature?

```
import seaborn as sns  
sns.heatmap(corr)
```

```
<Axes: >
```



Median_income shows a strong correlation of about 0.7 with the median_house_value, which suggests it could be a good feature to use. The other features have correlations close to zero, so they don't seem very helpful for prediction. If I have time, I can try using median_income as the feature to check if it improves the model's performance.

Correlation matrices don't tell the entire story. In later exercises, you'll find additional ways to unlock predictive power from potential features.

Note: Using `median_income` as a feature may raise some ethical and fairness issues. Towards the end of the course, we'll explore ethical and fairness issues.