



Robotic Merit Badge Session #2

- ▼ July 25, 2015
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Agenda

- ▼ Engineering Notebook
- ▼ Mechanical Design
 - ▼ Center of Gravity
 - ▼ Gears
- ▼ Programming
 - ▼ Development Tips
 - ▼ Exercises
- ▼ Assignment to work on before Session #3



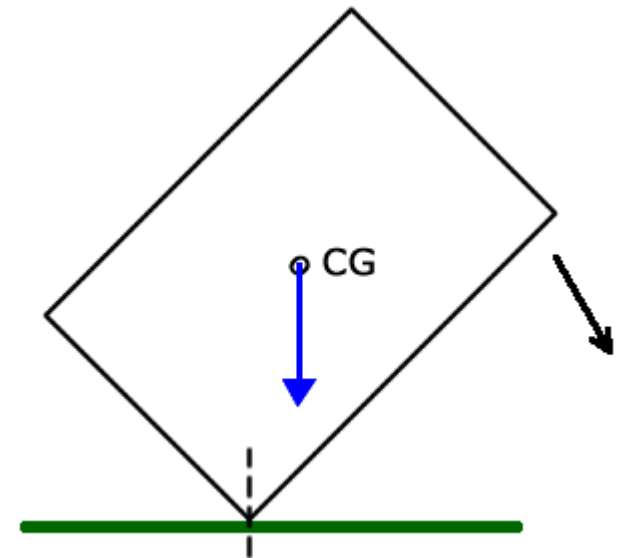
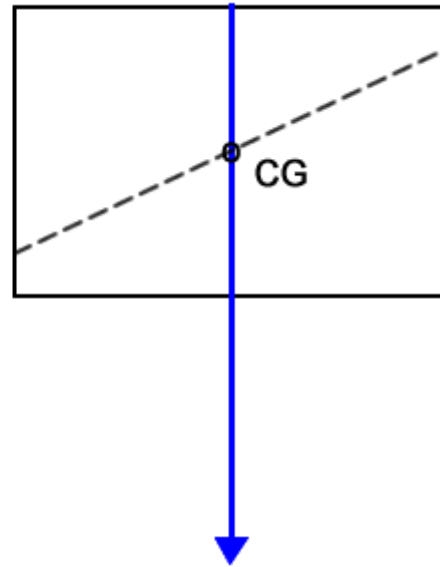
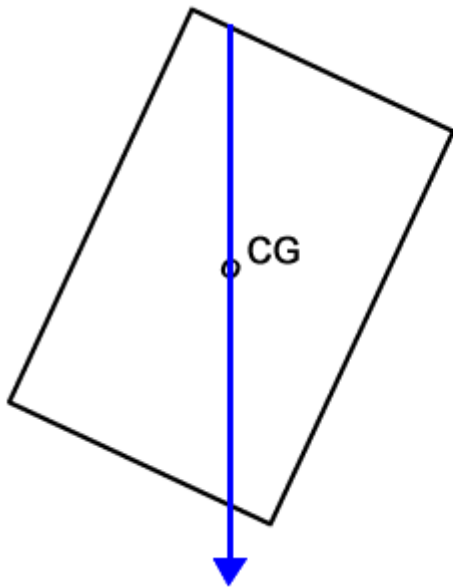
Engineering Notebook

- Put your name on your notebook
- Design
 - Ideas – What tasks will your robot perform?
 - Review with counselor for approval (Deadline August 8th)
- Tests
 - How will you test your robot?
 - How did your tests help refine your design?
- Logic and software
 - What is the logic that your control software will follow?
- Description and sketch/picture of robot
- Potential for Improvements – What could be better?

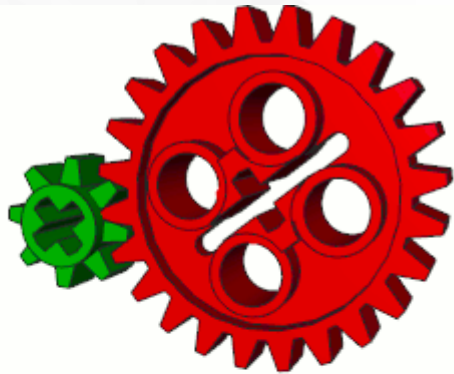


Mechanical Design – Center of Gravity

▼ Center of Gravity- Indicator of stability

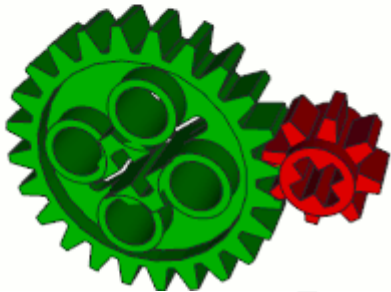


Mechanical Design – Gears

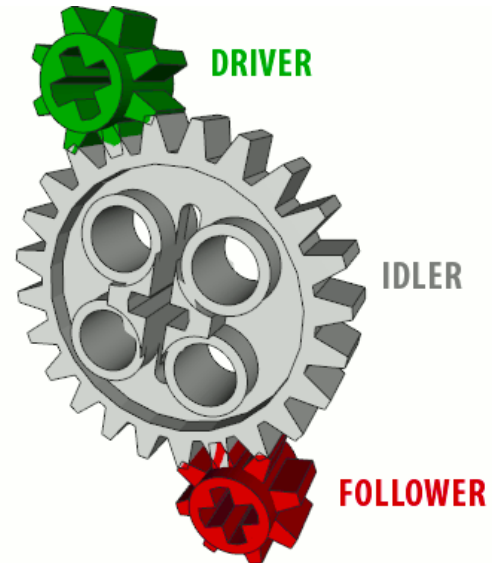
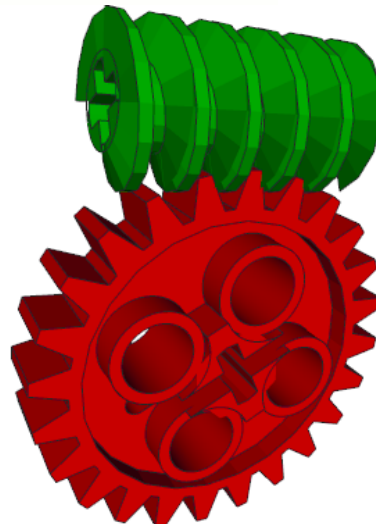


GEARING DOWN

Gear Ratio =
Driver teeth/Follower teeth



GEARING UP



Beveled Gears



Programming Tips

- ▼ A robot will do exactly what you tell it to do, but not always what you want it to do
- ▼ Write a little, test a little
- ▼ Write lots of small programs to understand how things work before attempting a large program.
- ▼ Save programs often.
- ▼ Create different versions of the program at stable development points.
- ▼ Look at example programs to see how they work



Analyzing The Test Program

- ▼ Load the Test Program
- ▼ Follow the logic of the the program. What does it do?
- ▼ Program your Edison using the “Program Edison” button



Programming Exercises – Generating an SOS Signal

- ▼ Create a program to generate the SOS Morse Code signal with one LED
 - ▼ 3 short blinks,
 - ▼ 3 long blinks,
 - ▼ 3 short blinks
 - ▼ Pause
 - ▼ Repeat.
- ▼ A short blink is 0.25 seconds on
- ▼ A long blink is 0.75 seconds on
- ▼ Each blink is separated by 0.75 seconds of “off”
- ▼ Pause between each SOS word is 1.75 seconds
- ▼ Save Program as BlinkSOS



Programming Exercises – Using Sensors

- ▼ Modify the BlinkSOS program to start blinking when an object is detected and stop blinking when no object is detected.
- ▼ Save the program as BlinkSOSDetect



Homework

- ▼ Continue thinking about your robot design and write your ideas in the Engineering Notebook.
- ▼ Be creative and have fun.
- ▼ If you design a robot with two Edisons, I will give you another Edison robot!
- ▼ Design due on or before August 8th.
- ▼ Finish any incomplete programming exercises from EdBook 2 and class.

