

RF Circuit Design

L4

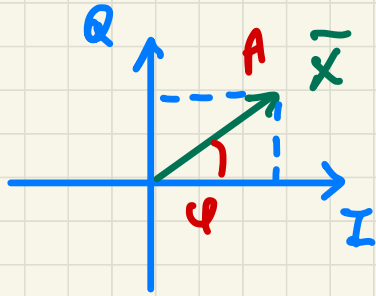


Modulated signal (quadrature mod.) (cartesian)

$$x(t) = I(t) \cos \omega_c t - Q(t) \sin \omega_c t =$$

$$= A(t) \cos [\omega_c t + \varphi(t)]$$

← Polar



$$A(t) = \sqrt{I^2(t) + Q^2(t)}$$

$$\varphi(t) = \arctan \frac{Q(t)}{I(t)}$$

e.g. QPSK modulation $a_n = \pm 1$; $b_n = \pm 1$

$$x(t) = \underbrace{\sum a_n p(t - nT_b)}_{I(t)} \cdot \cos \omega_c t +$$

$$- \underbrace{\sum b_n p(t - nT_b)}_{Q(t)} \cdot \sin \omega_c t =$$

$$= \operatorname{Re} \left\{ \underbrace{\sum (a_n + j b_n) p(t - nT_b)}_{\bar{X}(t)} e^{j \omega_c t} \right\}$$

$\bar{X}(t)$ phasor of $x(t)$

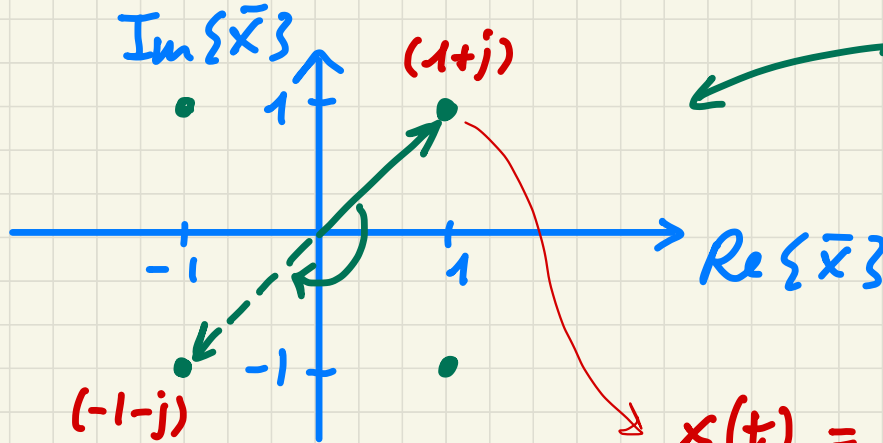
$$x(t) = \text{Re} \{ \bar{X}(t) e^{j\omega_c t} \}$$

$$\bar{X}(t) = \sum (a_n + j b_n) \cdot p(t - nT_b)$$

$$a_n = \pm 1$$

$$b_n = \pm 1$$

QPSK



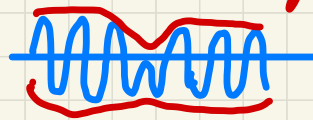
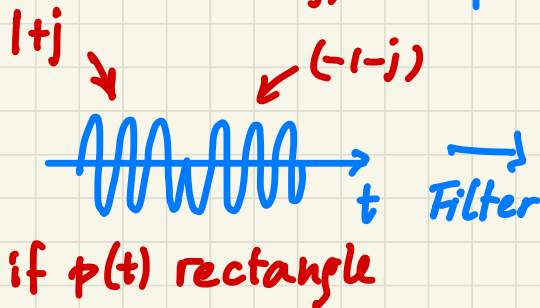
$$t = kT_b$$

$$p(0) = 1$$

$$\bar{X}(kT_b) = a_k + j b_k$$

$$x(t) = \cos \omega_c t + \sin \omega_c t$$

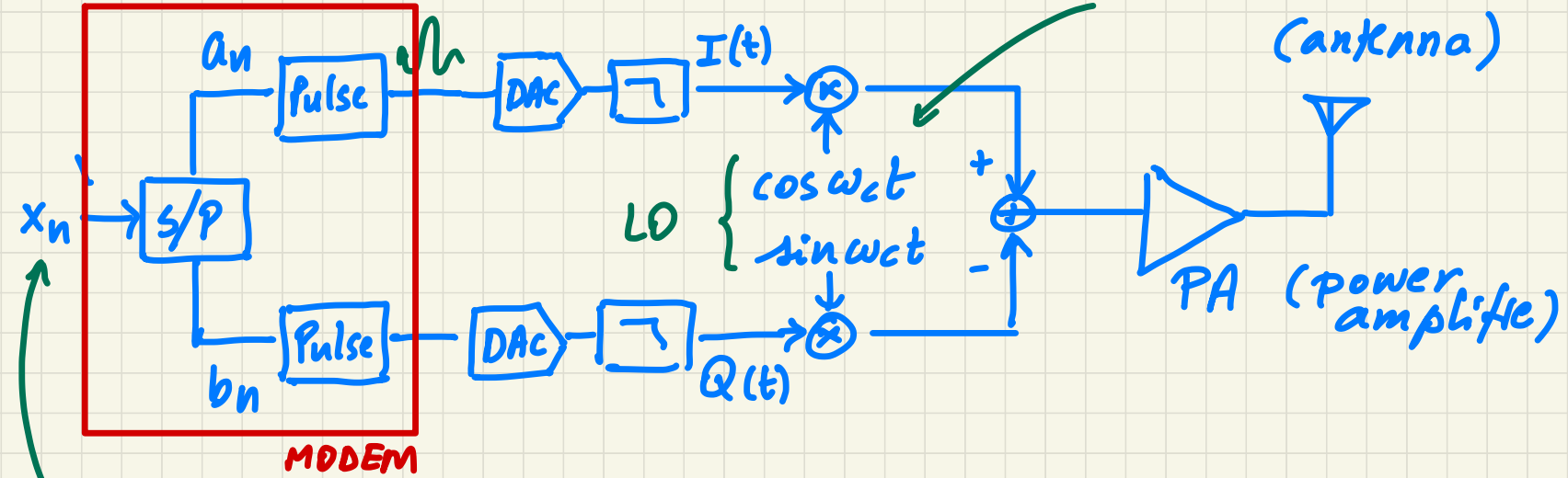
if $p(t)$ is rectangle in time



↳ non-constant envelope

QPSK TX block diagram

ideal LO

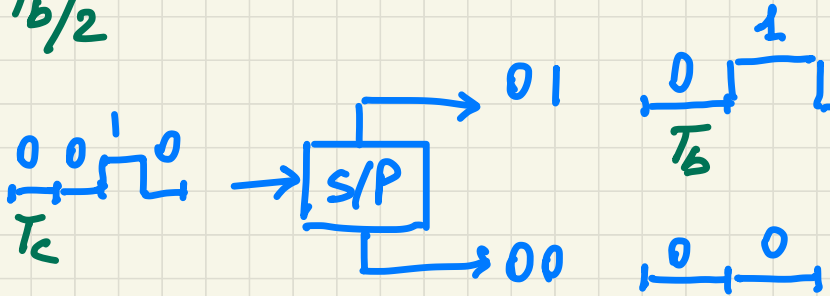


T_c chip period

$1/T_c$ chip rate

$$T_c = T_b/2$$

e.g.



Series-to-parallel
converter

RF bandwidth

For $\alpha = 0$ (Roll-off) : $\text{sinc}(t/T_b)$ shape

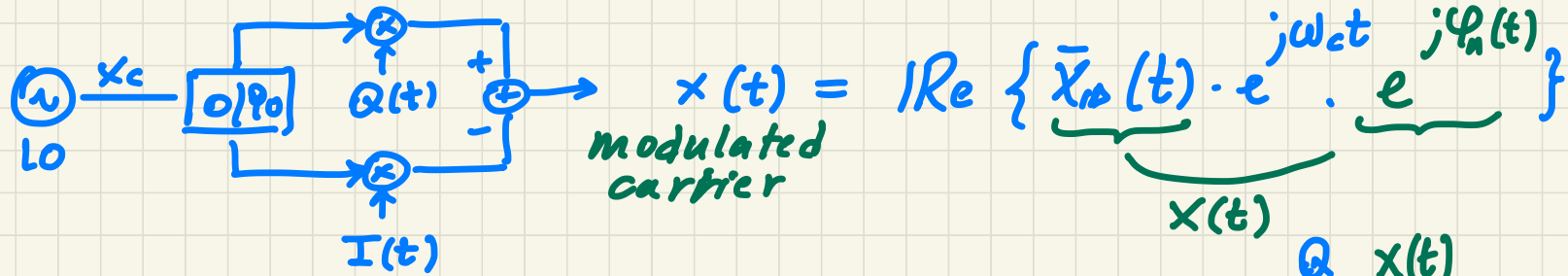
$$BW_{bb} = \frac{1}{2T_b} \Rightarrow BW = \frac{1}{2T_c} = \frac{1}{2T_b}$$

RF bandwidth of QPSK is given by the
CHIP rate divided by 2

Impact of LO PHASE NOISE on the quality of our modulation

$$x_c(t) = \cos[\omega_c t + \varphi_n(t)]$$

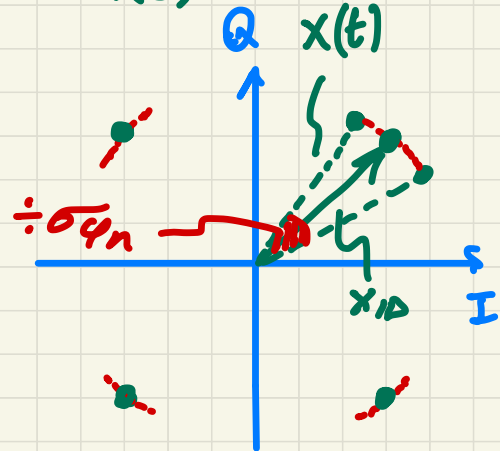
Phasor \rightarrow



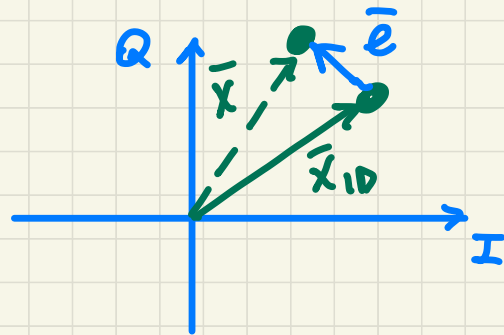
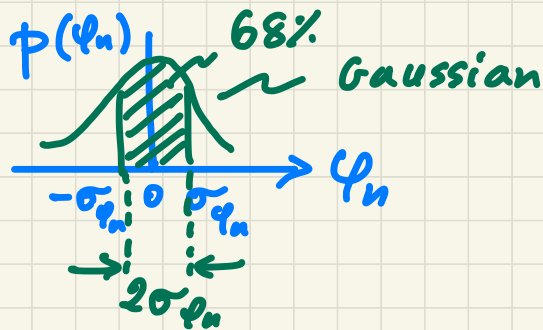
$$\bar{X}_{ID}(t) = I(t) + jQ(t)$$

Phasor affected by LO phase noise :

$$\bar{X}(t) = \bar{X}_{ID}(t) \cdot e^{j\varphi_n(t)}$$



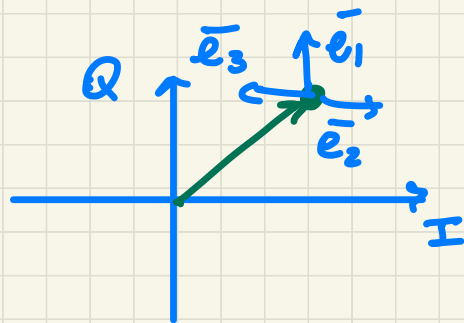
$$\sigma_{\varphi_n}^2 = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \varphi_n^2(t) dt = \int_0^\infty S_{\varphi_n}^{ssB}(f) df$$



Error - vector Magnitude

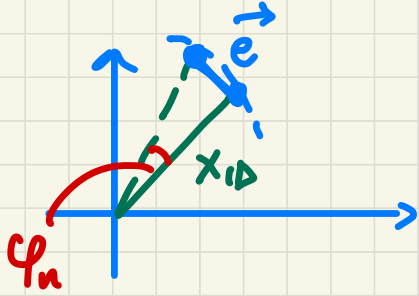
$$EVM \triangleq \frac{\frac{1}{N} \sum_{j=1}^N |e_j|^2}{P_{avg}} = \frac{P_e}{P_{avg}}$$

It is a Noise-to-signal ratio



$$EVM = \frac{1}{SNR}$$

- EVM induced by Phase Noise



$$EVM = \frac{|\bar{e}|^2}{|x_{ID}|^2} \approx \frac{|\bar{x}_{ID}|^2 \cdot \sigma_{\phi_n}^2}{|\bar{x}_{ID}|^2} = \sigma_{\phi_n}^2$$

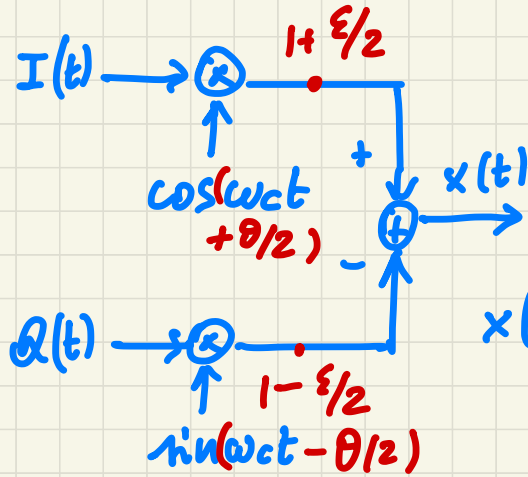
For small ϕ_n : $|\bar{e}| \approx \overbrace{|\bar{x}_{ID}| \cdot \phi_n}^{\text{arc}} \Rightarrow |\bar{e}|^2 \approx |\bar{x}_{ID}|^2 \cdot \sigma_{\phi_n}^2$

$$EVM \approx \sigma_{\phi_n}^2$$

Regardless of P_{avg} (Tx power)
SNR at TX output is limited
by phase noise

Rx phase noise (LO) \rightarrow degrades SNR at Rx.
 $SNR = 1/\sigma_{\phi_n}^2$

- EVM induced by amplitude/phase errors



ϵ amplitude imbalance
 θ phase imbalance

$$x(t) = \underbrace{(1 + \epsilon/2)} \cdot \cos[\omega_c t + \underbrace{\theta/2}] \cdot I(t) + \underbrace{(1 - \epsilon/2)} \cdot \sin[\omega_c t - \underbrace{\theta/2}] \cdot Q(t)$$

$$EVM = \frac{P_e}{P_{avg}} = \frac{|\bar{e}|^2}{|\bar{x}_{ID}|^2}$$

$$\bar{e} = \bar{x} - \bar{x}_{ID}$$

\nearrow $I + jQ$

$$\bar{x} = I \cdot \underbrace{e^{j\theta/2}} \cdot \underbrace{(1 + \epsilon/2)} + jQ \cdot \underbrace{e^{-j\theta/2}} \cdot \underbrace{(1 - \epsilon/2)}$$

$$\begin{aligned}
 -\bar{e} &= \bar{x}_{10} - \bar{x} = \mathcal{I} [1 - e^{j\theta/2} (1 + \varepsilon/2)] + j\mathcal{Q} [1 - e^{-j\theta/2} (1 - \varepsilon/2)] \\
 &= \mathcal{I} \cdot \left[\underbrace{1 - e^{j\theta/2}}_{\approx -j\theta/2} - \underbrace{e^{j\theta/2} \cdot \varepsilon/2}_{(1+j\theta/2)} \right] + j\mathcal{Q} \left[\underbrace{1 - e^{-j\theta/2}}_{\approx +j\theta/2} + \underbrace{e^{-j\theta/2} \cdot \frac{\varepsilon}{2}}_{(1-j\theta/2)} \right]
 \end{aligned}$$

small θ \rightarrow

$$\begin{aligned}
 &\approx \mathcal{I} \cdot [-j\theta/2 - (1+j\theta/2)\varepsilon/2] + \\
 &\quad + j\mathcal{Q} [j\theta/2 + (1-j\theta/2) \cdot \frac{\varepsilon}{2}] \\
 &\approx \mathcal{I} \cdot [-j\theta/2 - \varepsilon/2] + j\mathcal{Q} [j\theta/2 + \varepsilon/2] =
 \end{aligned}$$

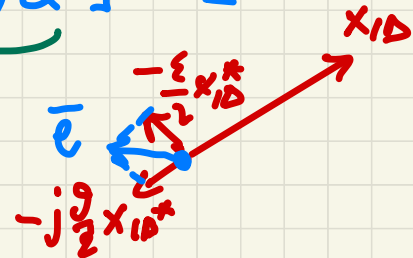
$e^x \approx 1+x$
 $x \approx 0$

$1-e^x \approx -x$

$\theta \ll 1 \text{ rad}$
 $\varepsilon \ll 1$

$\varepsilon \cdot \theta$ negligible

$$\begin{aligned}
 &= -(j\theta/2 + \varepsilon/2) [\mathcal{I} - j\mathcal{Q}] = \\
 &= -(j\theta/2 + \varepsilon/2) \cdot x_{10}^*
 \end{aligned}$$



$$EVM = \frac{|\bar{e}|^2}{|\bar{x}_{ID}|^2} = \frac{|\underbrace{(\epsilon/2 + j\theta/2)}_{|\bar{x}_{ID}|^2} \bar{x}_{ID}^*|^2}{|\bar{x}_{ID}|^2} =$$

$$= (\epsilon^2/4 + \theta^2/4) \cdot \frac{\cancel{|\bar{x}_{ID}^*|^2}}{\cancel{|\bar{x}_{ID}|^2}}$$

$$EVM = \epsilon^2/4 + \theta^2/4$$

e.g. $\epsilon = 1\%$

$\theta = 1 \text{ deg}$



$1 \text{ deg} \cdot \frac{\pi}{180} = 0.0174 \text{ rad}$

$$EVM = \frac{(0.01)^2}{4} + \frac{(0.0174)^2}{4} = \frac{0.00040}{4}$$

$$EVM_{dB} = 10 \log_{10} EVM = -40 \text{ dB}$$

- Impact of Non-linearity on the modulated signal



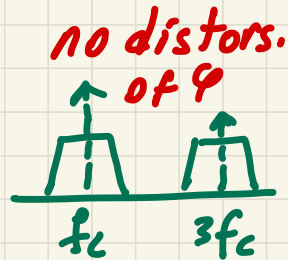
spectral regrowth

$$y = \alpha_1 \cdot x(t) + \underbrace{\alpha_3 \cdot x^3(t)}_{\text{cubic nonlinearity}} + \dots$$

static nonLinear model

- Constant envelope : $x(t)$ is PM modulation

$$x(t) = \underbrace{A_c}_{\text{constant}} \cos[\omega_c t + \underbrace{\varphi(t)}_{\text{information signal}}]$$



$$\alpha_3 x^3(t) = \alpha_3 A_c^3 \cos^3[\omega_c t + \varphi(t)] = \alpha_3 A_c^3 \frac{3}{4} \cos[\omega_c t + \varphi(t)] + \alpha_3 A_c^3 \frac{1}{4} \cos[3\omega_c t + 3\varphi(t)]$$

$$\begin{aligned}
 \bullet \cos^3 x &= \cos x \cdot \cos^2 x = \cos x \cdot \frac{1 + \cos 2x}{2} = \\
 &= \frac{1}{2} \cos x + \frac{1}{2} \left[\frac{1}{2} \cos x + \frac{1}{2} \cos 3x \right] = \\
 &= \underbrace{\left(\frac{1}{2} + \frac{1}{4} \right)}_{\textcircled{3/4}} \cdot \cos x + \textcircled{\frac{1}{4}} \cdot \cos 3x
 \end{aligned}$$

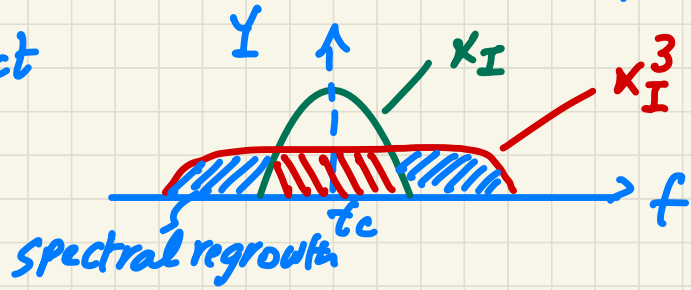
$$\begin{aligned}
 \bullet \sin^3 x &= \\
 &= \frac{3}{4} \sin x - \frac{1}{4} \sin 3x
 \end{aligned}$$

- Non-constant envelope modulation:

$$\alpha_3 x^3(t) = \alpha_3 \cdot \underline{x_I^3} \cdot \left(\frac{1}{4} \cos 3\omega_c t + \underline{\underline{\frac{3}{4} \cos \omega_c t}} \right) - \alpha_3 \underline{x_Q^3} \cdot \left(\frac{3}{4} \underline{\sin \omega_c t} - \frac{1}{4} \sin 3\omega_c t \right)$$

$$x(t) = x_I(t) \cos \omega_c t - x_Q(t) \sin \omega_c t$$

$$y = \alpha_1 x(t) + \alpha_3 x^3(t)$$





Nonlinearity degrades

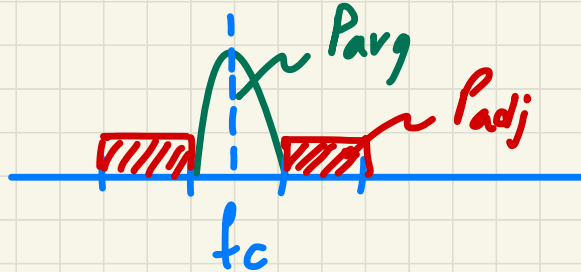
EVM

inband disturbance

ACPR

$$ACPR \triangleq \frac{\text{Power leaking in adj. channel}}{\text{Power of the signal}}$$

(Adjacent channel power ratio)



Amplifiers trade-off

linearity

power efficiency
 $\eta = P_{out} / P_{dc}$