

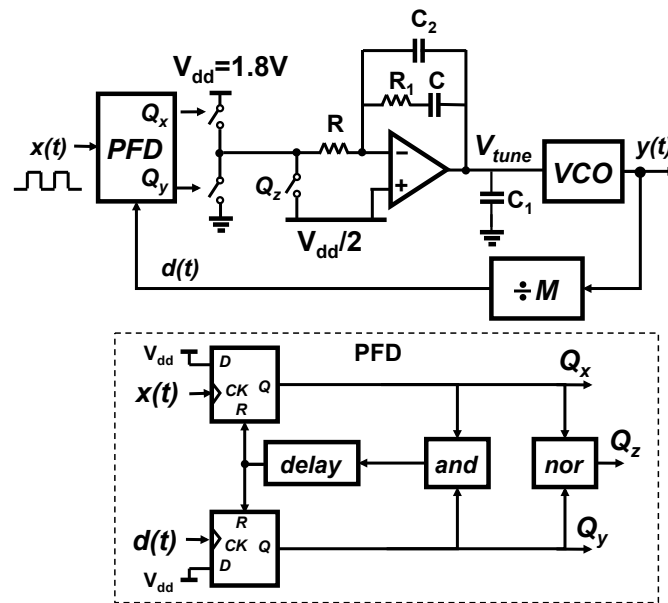
RF Circuit Design

T4



Tutorial T4

T4.1 The PLL in the figure embeds the PFD in the inset, where the block “delay” introduces a delay of 0.5 ns. The switches have infinite resistance (when off) and $10\ \Omega$ (when on). The reference clock $x(t)$ has 50 MHz frequency. The frequency-division factor is $M = 55$ and the VCO frequency varies in the range between 2650 and 2850 MHz, sweeping the V_{tune} from 0 to $V_{dd} = 1.8\text{ V}$. Let the capacitors be $C_1 = 100\text{ pF}$ and the resistor $R_1 = 100\ \Omega$.

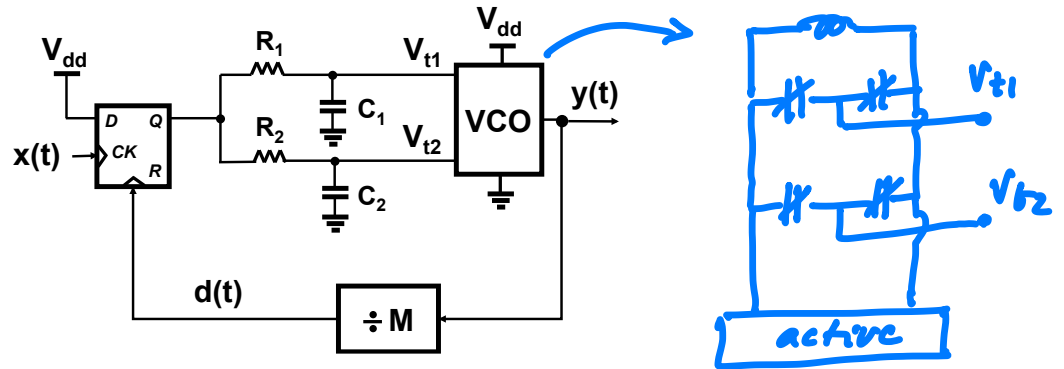


- Assuming an ideal Op-Amp (with infinite gain and bandwidth), set the value of R and C to get two complex dominant (closed-loop) poles at 100 kHz located at 45 degree on the Gauss plane.
- If the resistance of the switch driven by Q_x is $15\ \Omega$ (when on), set the minimum value of C_2 , to get the level of the spur at 50 MHz in the spectrum of $y(t)$ lower than -80 dBc.
- Assuming all the switches with resistance $10\ \Omega$ (when on), but an offset voltage of 100 mV for the Op-Amp, can the loop lock? If yes, what is the value of the output frequency, the delay between $x(t)$ and $d(t)$ at steady state, the reference-spur level?

[Solution: a. $R = 195\ \Omega$, $C = 22.5\text{ nF}$; b. $I_{OS} = -0.92\text{ mA}$, $t_e = 105\text{ ps}$, $C_2 = 154\text{ pF}$; c. $I_L = 0.49\text{ mA}$, $t_e = 2.2\text{ ns}$, SFDR = -32.8 dBc]

$$\begin{aligned}
 & \bullet R_1 C_1 = 300 \text{ ns} = \tau_1 \Rightarrow f_1 \approx 531 \text{ kHz} \\
 & \bullet R_2 C_2 = 1.2 \text{ ms} = \tau_2 \Rightarrow f_2 \approx 133 \text{ Hz}
 \end{aligned}$$

T4.2. Let $V_{dd} = 1.8\text{V}$, $R_1 = 1 \text{ k}\Omega$, $C_1 = 300 \text{ pF}$, $R_2 = 10 \text{ k}\Omega$, $C_2 = 120 \text{ nF}$, $x(t)$ a 10-MHz periodic signal and $M = 135$. The D flip-flop has rails 0 and V_{dd} , and synchronous reset (clock samples data even when reset is "1"). The VCO has two tuning voltages V_{t1} and V_{t2} , which varies linearly VCO frequency, and a free-running frequency of $f_{fr} = 1200 \text{ MHz}$ at $V_{t1} = V_{t2} = 0$.



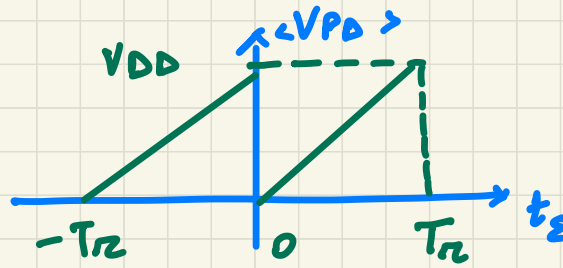
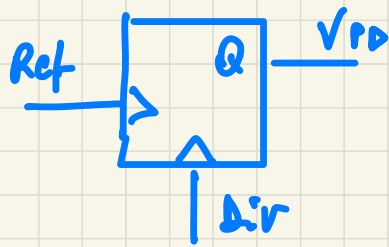
- After deriving the continuous-time phase model of the system, compute the VCO tuning frequency ranges through control voltages V_{t1} and V_{t2} (when varied from 0 to V_{dd}) to set the unity-gain bandwidth of loop gain equal to 100 kHz and phase margin equal to 60 degrees.
- What is the value of V_{t1} and V_{t2} at steady state? Calculate the delay relationship between $x(t)$ and $d(t)$ in seconds at steady state.
- Do you expect any reference spur? If so, compute the level of the spurious tone in the spectrum of $y(t)$ in dBc.

τ_2

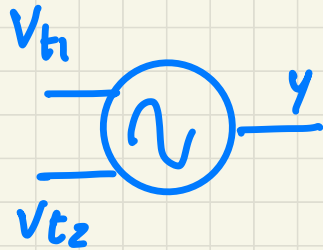
[Solutions: a. $\tau = 4.65 \mu\text{s}$, $\Delta f_{VCO1} = 80 \text{ MHz}$, $\Delta f_{VCO2} = 22.0 \text{ GHz}$; b. $V_{t1} = V_{t2} = 12.2 \text{ mV}$, $t_e = 0.68 \text{ ns}$; c. SFDR = -50 dBc]

$$K_{VCO1} = 2\pi \frac{\Delta f_{VCO1}}{V_{DD}}$$

$$K_{VCO2} = 2\pi \frac{\Delta f_{VCO2}}{V_{DD}}$$



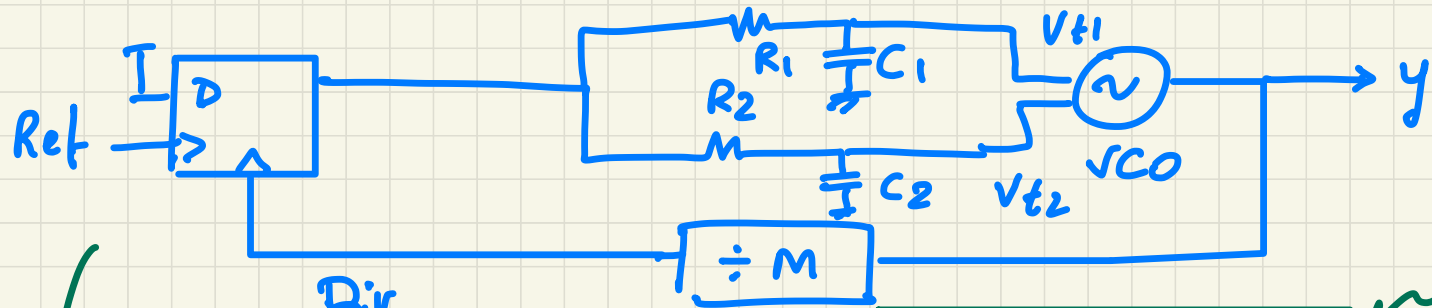
$$K_{PD} = \frac{V_{PD}}{\phi_s} = \frac{V_{DD}}{2\pi}$$



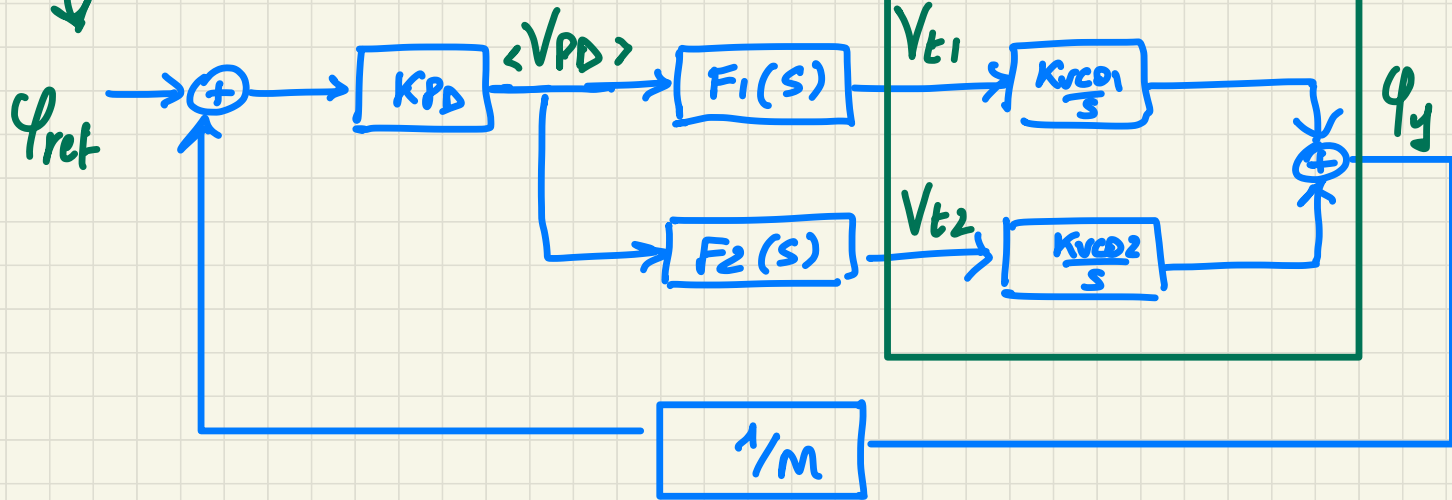
$$\omega_{out} = \omega_{fr} + K_{VCO1} \cdot V_{t1} + K_{VCO2} \cdot V_{t2}$$

↓ L

$$\varphi_{out} = \frac{K_{VCO1}}{s} V_{t1} + \frac{K_{VCO2}}{s} V_{t2}$$



CT model



$$F_1(s) = \frac{1}{1 + sR_1C_1}$$

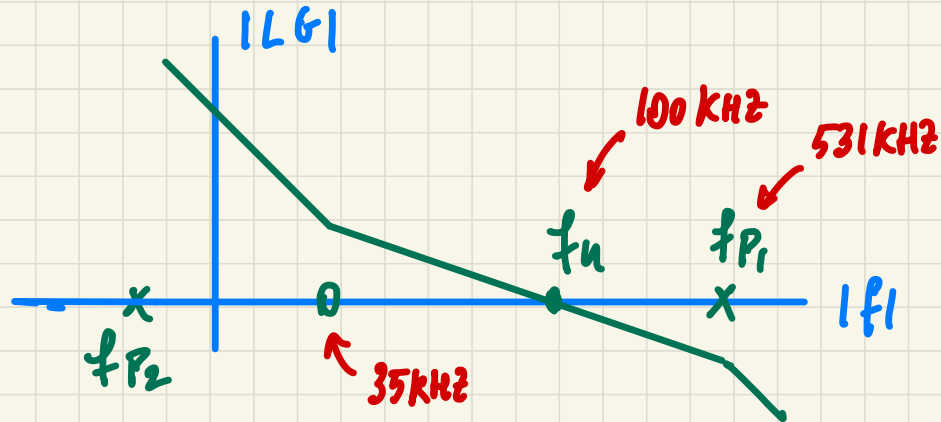
$$F_2(s) = \frac{1}{1 + sR_2C_2}$$

$$\begin{aligned}
 LG(s) &= K_{PD} \cdot \frac{1}{s} \cdot \frac{1}{N} \cdot \left[\frac{K_{VCO1}}{1 + s \underbrace{R_1 C_1}_{\tau_1}} + \frac{K_{VCO2}}{1 + s \underbrace{R_2 C_2}_{\tau_2}} \right] \\
 &= \frac{K_{PD}}{N} \cdot \frac{1}{s} \cdot \frac{K_{VCO1} (1 + s \tau_2) + K_{VCO2} (1 + s \tau_1)}{(1 + s \tau_1) (1 + s \tau_2)} = \\
 &= \frac{K_{PD}}{N} \cdot \frac{K_{VCO1} + K_{VCO2}}{s} \cdot \frac{1 + s \cdot \overbrace{\frac{K_{VCO1} \tau_2 + K_{VCO2} \tau_1}{K_{VCO1} + K_{VCO2}}}^{\tau_z}}{(1 + s \tau_1) (1 + s \tau_2)}
 \end{aligned}$$

3rd order - type I - PLL
 zero comes from the
 two paths in parallel

$$f_{p2} \approx 133 \text{ Hz}$$

$$f_{p1} \approx 531 \text{ kHz}$$



$$L G(s) \cong \frac{K_{PD}}{N} \cdot \frac{K_{VCO1} + K_{VCO2}}{1} \cdot \frac{\cancel{s} + \cancel{s} \tau_2}{(1 + \cancel{s} \tau_1) \cdot (\cancel{s} + \cancel{s} \tau_2)}$$

$s \approx j\omega_u$

$$\omega_u \gg \omega_{P2} \Rightarrow 1 \tau_2 \gg 1$$

$$\omega_u \ll \omega_{P1} \Rightarrow 1 \tau_1 \ll 1$$

$$\omega_u \gg \omega_z \Rightarrow 1 \tau_2 \gg 1$$

$$1 = |L G(j\omega_u)| = \frac{K_{PD} (\cancel{K_{VCO1}} + \cancel{K_{VCO2}})}{N} \cdot \frac{1}{\omega_u} \cdot \frac{K_{VCO1} \tau_2 + K_{VCO2} \tau_1}{\tau_2 (\cancel{K_{VCO1}} + \cancel{K_{VCO2}})}$$

$$\Rightarrow \omega_u = \frac{K_{PD}}{N} (K_{VCO1} + K_{VCO2}) \cdot \frac{\omega_{P2}}{\omega_z} = 2\pi \cdot 100 \text{ k}$$

$$\varphi_m \approx \text{atan}\left(\frac{\omega_u}{\omega_z}\right) - \text{atan}\left(\frac{\omega_u}{\omega_{P1}}\right) = 60^\circ \Rightarrow \omega_z = 2\pi \cdot 35 \frac{\text{krad}}{\text{s}}$$

- TYPE - n : n poles in the origin in the loop gain
- ORDER - m : m poles in the system (loop gain or transfer functions)