MATH 146 Personal Notes

Marcus Chan

Taught by Ross Willard
and Giang Tran
UW Math '25

Chapter 1: Vector Spaces (S1.1)

Let $\mathbb{F}$ be a field.
Then, we say V is a "vector space" over $\mathbb{F}$ if there exists
① an addition $+ : (V \times V) \to V$ by $+(x,y) = x+y$; and
② a scalar multiplication $\times : (\mathbb{F} \times V) \to V$ by $\times(a,x) = ax$;
and the following conditions hold:
① V is an abelian group with respect to addition; (VS 1 = commutativity; 2 = associativity; 3 = identity; 4 = inverse)
② $1_{\mathbb{F}} x = x \quad \forall x \in V$; (VS 5)
③ multiplication is associative; ie $a(bx) = (ab)x \quad \forall a,b \in \mathbb{F},\ x \in V$; and (VS 6)
④ the left and right distributive laws hold;
ie $a(x+y) = ax + ay$ and $(a+b)x = ax+bx \quad \forall a,b \in \mathbb{F},\ x \in V$. (D2)
(VS 7 = former, VS 8 = latter)

$\mathbb{F}^n$ IS A VECTOR SPACE OVER $\mathbb{F}$ (E2(1))

We can show that the Cartesian product
$\mathbb{F}^n = \{(a_1, a_2, \dots, a_n) : a_i \in \mathbb{F} \ \forall i \in \{1,2,\dots,n\}\}$
is a vector space over $\mathbb{F}$ with respect to the addition operation
$$(a_1, a_2, \dots, a_n) + (b_1, b_2, \dots, b_n) = (a_1+b_1, a_2+b_2, \dots, a_n+b_n)$$
and multiplication operation
$$c(a_1, a_2, \dots, a_n) = (ca_1, ca_2, \dots, ca_n).$$
Proof. This follows from verifying each of the conditions above. ☒

Note that we generally say "the vector space $\mathbb{F}^n$" to refer to the vector space $\mathbb{F}^n$ over $\mathbb{F}$. (R3(4))

COLUMN VECTOR NOTATION (E2(2))

Note that we can also write elements of $\mathbb{F}^n$ as "column vectors"; ie of the form
$$\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}, \quad \text{where } a_1, a_2, \dots, a_n \in \mathbb{F}.$$

$\mathbb{Q}^n$ IS A VECTOR SPACE OVER $\mathbb{Q}$, $\mathbb{R}^n$ IS A VECTOR SPACE OVER $\mathbb{R}$, & $\mathbb{C}^n$ IS A VECTOR SPACE OVER $\mathbb{C}$ (R3(1))

We can show
① $\mathbb{Q}^n$ is a vector space over $\mathbb{Q}$;
② $\mathbb{R}^n$ is a vector space over $\mathbb{R}$; and
③ $\mathbb{C}^n$ is a vector space over $\mathbb{C}$.
Proof. This directly follows from the fact that $\mathbb{Q}$, $\mathbb{R}$ and $\mathbb{C}$ are fields (MATH 145), and substituting the respective fields into the above lemma. ☒

$\mathbb{R}^n$ IS A VECTOR SPACE OVER $\mathbb{Q}$, & $\mathbb{C}^n$ IS A VECTOR SPACE OVER $\mathbb{R}$ (R3(2))

Moreover, we can also show that
① $\mathbb{R}^n$ is a vector space over $\mathbb{Q}$; and
② $\mathbb{C}^n$ is a vector space over $\mathbb{R}$.
Proof. Essentially, this stems from the fact that we can "multiply" vectors in $\mathbb{R}^n$ by scalars in $\mathbb{Q}$, and vectors in $\mathbb{C}^n$ by scalars in $\mathbb{R}$.
The formal proof is left to the reader. ☒

KEY
S : section
D : definition
R : remark
E : example
T : theorem
L : lemma
C : corollary
P : proposition
A : assignment

MATRICES (D3(1))

Let $\mathbb{F}$ be a field, and $m, n \in \mathbb{Z}^+$.
Then, we say A is an "$m \times n$ matrix" with entries from $\mathbb{F}$ if it is of the form
$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \\ a_{m1} & a_{m2} & & a_{mn} \end{pmatrix},$$
where $a_{ij} \in \mathbb{F} \quad \forall i \in \{1,2,\dots,m\},\ j \in \{1,2,\dots,n\}$.

Alternatively, we can represent A via the notation
$$A = (a_{ij}), \quad i \in \{1,2,\dots,m\},\ j \in \{1,2,\dots,n\}.$$

ij-ENTRY OF A MATRIX (D3(2))

Given a $m \times n$ matrix A, the "ij-entry" of A, or "a_{ij}", is defined to be the entry in A at the i^{th} row and j^{th} column.

ZERO MATRIX (D3(3))

The "$m \times n$ zero matrix", or more simply the "zero matrix", denoted as "O", is defined to be
$$O = \underbrace{\begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \\ 0 & 0 & & 0 \end{pmatrix}}_{n} \Big\} m,$$
ie the $m \times n$ matrix where which entry equals 0.

MATRIX EQUALITY (D3(4))

We say two matrices A and B are equal if and only if $a_{ij} = b_{ij} \quad \forall i \in \{1,2,\dots,m\},\ j \in \{1,2,\dots,n\}$.

MATRIX ADDITION (D3(5))

Let A and B be $m \times n$ matrices with entries from some field $\mathbb{F}$.
Then, the "addition" of A and B, denoted by "$A+B$", is defined to be the matrix where
$$(a+b)_{ij} = a_{ij} + b_{ij} \quad \forall i \in \{1,2,\dots,m\},\ j \in \{1,2,\dots,n\}.$$

MATRIX SCALAR MULTIPLICATION (D3(6))

Let A be a $m \times n$ matrix with entries from some field $\mathbb{F}$, and $c \in \mathbb{F}$ be arbitrary.
Then the "scalar multiplication" of A by c, denoted by "cA", is defined to be the matrix where
$$(ca)_{ij} = c(a_{ij}) \quad \forall i \in \{1,2,\dots,m\},\ j \in \{1,2,\dots,n\}.$$

SPACE OF $m \times n$ MATRICES (E3)

Let $\mathbb{F}$ be a field.
Then the "space of all $m \times n$ matrices" with entries from $\mathbb{F}$, denoted by "$M_{m \times n}(\mathbb{F})$", is defined to be the set of all $m \times n$ matrices with entries from $\mathbb{F}$.

Note that $M_{m \times n}(\mathbb{F})$ is a vector space over $\mathbb{F}$ with respect to the matrix addition and scalar multiplication operations.
Proof. This follows from verifying each of the conditions in D2. ☒

FUNCTION SPACES (E4)

1. Let the set $D \neq \emptyset$ be arbitrary, and let $\mathbb{F}$ be a field.

Then the "space of all functions" from D to $\mathbb{F}$, denoted by "$\mathbb{F}^D$", is defined to be the set of all functions of the form $f: D \to \mathbb{F}$.

2. Similarly, we can show that $\mathbb{F}^D$ is a vector space over $\mathbb{F}$ with respect to the operations of function addition

$$(f+g)(x) := f(x) + g(x) \quad \forall f, g \in \mathbb{F}^D, \ x \in \mathbb{F}$$

and function scalar multiplication

$$(cf)(x) := cf(x) \quad \forall f \in \mathbb{F}^D, \ x, c \in \mathbb{F}.$$

Proof. Similar strategy to E3: verify each condition in D2 holds.

POLYNOMIALS (D4)

SET OF ALL POLYNOMIALS OF DEGREE AT MOST n (D4 (1))

1. Let $\mathbb{F}$ be a field.

Then, we denote $P_n(\mathbb{F})$ to be the set of all polynomials with coefficients from $\mathbb{F}$ and of degree at most n; ie

$$P_n(\mathbb{F}) = \left\{ \sum_{i=0}^{n} a_n x^n \ : \ a_j \in \mathbb{F} \ \ \forall j \in \{0, 1, \dots, n\} \right\}.$$

POLYNOMIAL SPACES (D4 (2))

1. Let $\mathbb{F}$ be a field.

Then, we denote "$\mathbb{F}[x]$" to be the set of all polynomials with coefficients from $\mathbb{F}$; ie

$$\mathbb{F}[x] = \left\{ \sum_{i=0}^{\infty} a_i x^i \ : \ a_j \in \mathbb{F} \ \ \forall j \in \mathbb{N} \cup \{0\} \right\}.$$

2. Then, we can show that $\mathbb{F}[x]$ is a vector space over $\mathbb{F}$ with respect to the operations of polynomial addition

$$(f+g)(x) = \sum_{i=0}^{n} (a_n + b_n) x^n \quad \forall f, g \in \mathbb{F}[x]$$

and polynomial scalar multiplication

$$c f(x) = \sum_{i=0}^{n} (c a_n) x^n \quad \forall f \in \mathbb{F}[x], \ c \in \mathbb{F}.$$

Proof. Similar strategy to E4.

BASIC PROPERTIES OF VECTOR SPACES (S1.2)

CANCELLATION PROPERTY FOR VECTOR ADDITION (T1.1)

Let V be a vector space.

Suppose there exists some $x, y, z \in V$ such that $x + z = y + z$.

Then necessarily $x = y$.

Proof. Note that

$$\begin{aligned} x &= x + 0 \\ &= x + (z + (-z)) \\ &= (x+z) + (-z) \\ &= (y+z) + (-z) \\ &= y + (z + (-z)) \end{aligned}$$

and so $x = y$, as required. ∎

UNIQUENESS OF THE ZERO VECTOR IN VECTOR SPACES (C1.1.1 (1))

Let V be a vector space.

Suppose $0_1, 0_2 \in V$ are both zero vectors.

Then necessarily $0_1 = 0_2$.

Proof. This follows from the fact that V is an abelian group under addition. ∎

UNIQUENESS OF ADDITIVE INVERSES IN VECTOR SPACES (C1.1.1 (2))

Let V be a vector space.

Then for any $x \in V$, there exists one and only one vector $y \in V$ that satisfies $x + y = 0$.

Proof. This also follows from the fact that V is an abelian group under addition. ∎

$0x = 0 \quad \forall x \in V$ (T1.2 (1))

Let V be a vector space over some field $\mathbb{F}$, and let 0 be the additive identity of $\mathbb{F}$.

Then, for any $x \in V$, necessarily $0 \cdot x = 0$.

Proof. This, again, follows from the fact that V is an abelian group under addition. ∎

$a0 = 0 \quad \forall a \in \mathbb{F}$ (T1.2 (2))

Let V be a vector space over some field $\mathbb{F}$, and let 0 be the zero vector of V.

Then, for any $a \in \mathbb{F}$, necessarily $a \ 0 = 0$.

Proof. This, again, follows from the fact that V is an abelian group under addition. ∎

$(-a)x = -(ax) = a(-x) \quad \forall a \in \mathbb{F}, \ x \in V$ (T1.2 (3))

Let V be a vector space over some field $\mathbb{F}$, and let $a \in \mathbb{F}$, $x \in V$ be arbitrary.

Then necessarily $(-a)x = -(ax) = a(-x)$.

Proof. Proof is similar to the analog of this statement for rings (MATH 145). ∎

SUBSPACES (S1.3)

Let V be a vector space over some field $\mathbb{F}$.
Then we say the subset $W \subseteq V$ is a "subspace" of V if

① $W \neq \emptyset$;
*we usually check whether $0 \in W$ to verify this claim. (R4)

② If $x \in W$ and $y \in W$, then $(x+y) \in W$; and

③ If $c \in \mathbb{F}$ and $x \in W$, then $cx \in W$. (D6)

SUBSPACES ARE VECTOR SPACES OVER $\mathbb{F}$ WITH RESPECT TO THE OPERATIONS OF V (T1.3)

Let W be a subspace of a vector space V over some field $\mathbb{F}$.
Then W is also a vector space over $\mathbb{F}$ under the operations of V restricted to W.

Proof. This follows from verifying the conditions in D2, taking into account the properties of subspaces. ▨

$\{0\}$ AND V ARE SUBSPACES OF V (E8 (1))

Let V be a vector space.
Then $\{0\}$ and V itself are always subspaces of V.

Proof. $\{0\}$ is vacuously a subspace, and V is trivially a subspace. ▨

$P_2(\mathbb{R})$ IS A SUBSPACE OF $\mathbb{R}[x]$ (E8 (2))

We can show that $P_2(\mathbb{R})$ is a subspace of $\mathbb{R}[x]$.

Proof. This stems from the fact that:
- $P_2(\mathbb{R}) \subset \mathbb{R}[x]$ by definition;
- $0 \in P_2(\mathbb{R})$; and
- $P_2(\mathbb{R})$ is closed under the addition & scalar multiplication defined on $\mathbb{R}[x]$. ▨

$\{(a_{ij}) \in M_{n\times n}(\mathbb{F}) \mid \sum_{k=1}^{n} a_{kk} = 0\}$ IS A SUBSPACE OF $M_{n\times n}(\mathbb{F})$ (E8 (3))

We can show that the set $\{(a_{ij}) \in M_{n\times n}(\mathbb{F}) \mid \sum_{k=1}^{n} a_{kk} = 0\}$ is a subspace of $M_{n\times n}(\mathbb{F})$, where $n \in \mathbb{N}$ is arbitrary.

Proof. Similar proof to the above.

$\{(a_{ij}) \in M_{n\times n}(\mathbb{F}) \mid \sum_{k=1}^{n} a_{kk} = 1\}$ IS NOT A SUBSPACE OF $M_{n\times n}(\mathbb{F})$ (E8 (4))

We can show the set $\{(a_{ij}) \in M_{n\times n}(\mathbb{F}) \mid \sum_{k=1}^{n} a_{kk} = 1\}$ is not a subspace of $M_{n\times n}(\mathbb{F})$.

Proof. Let $a, b \in \{(a_{ij}) \in M_{n\times n}(\mathbb{F}) \mid \sum_{k=1}^{n} a_{kk} = 1\}$ be arbitrary.
Then, notice that

$$\begin{aligned} \sum_{k=1}^{n} (a+b)_{kk} &= \sum_{k=1}^{n} (a_{kk} + b_{kk}) \\ &= 1+1 \\ &= 2, \end{aligned}$$

So that $a+b \notin \{(a_{ij}) \in M_{n\times n}(\mathbb{F}) \mid \sum_{k=1}^{n} a_{kk} = 1\}$. ▨

SUBSPACES OF $\mathbb{R}^2$ (E9 (1))

Note that the subspaces of $\mathbb{R}^2$ are

① $\mathbb{R}^2$ itself;

② $\{0_{\mathbb{R}^2}\} = \{(0,0)\}$; and

③ all lines in $\mathbb{R}^2$ that pass through $(0,0)$.

SUBSPACES OF $\mathbb{F}^2$ (E9 (4a))

In general, for any field $\mathbb{F}$, the subspaces of $\mathbb{F}^2$ are

① $\mathbb{F}^2$ itself;

② $\{0\}$; and

③ all the "lines" in $\mathbb{F}^2$ through 0.
ie of the form $\{(x,y) \in \mathbb{F}^2 \mid \binom{x}{y} = k\binom{x_1}{y_1},\ \binom{x_1}{y_1} \in \mathbb{F}^2\}$

SUBSPACES OF $\mathbb{R}^3$ (E9 (2))

Similarly, the subspaces of $\mathbb{R}^3$ are

① $\mathbb{R}^3$ itself;

② $\{0_{\mathbb{R}^3}\} = \{(0,0,0)\}$;

③ all lines in $\mathbb{R}^3$ that pass through $(0,0,0)$; and

④ all planes in $\mathbb{R}^3$ that pass through $(0,0,0)$.

SUBSPACES OF $\mathbb{F}^3$ (E9 (4b))

Similarly, for any field $\mathbb{F}$, the subspaces of $\mathbb{F}^3$ are

① $\mathbb{F}^3$ itself;

② $\{0\}$;

③ all the "lines" in $\mathbb{F}^3$ through 0; and
ie of the form $\{(x,y,z) \in \mathbb{F}^3 \mid \begin{pmatrix}x\\y\\z\end{pmatrix} = k\begin{pmatrix}x_1\\y_1\\z_1\end{pmatrix},\ \begin{pmatrix}x_1\\y_1\\z_1\end{pmatrix} \in \mathbb{F}^3\}$ (E9(3))

④ all the "planes" in $\mathbb{F}^3$ through 0.
ie of the form $\{(x,y,z) \in \mathbb{F}^3 \mid \exists a,b,c \in \mathbb{F}$ such that $ax+by+cz=0.\}$

LINEAR COMBINATIONS & SYSTEM OF LINEAR EQUATIONS (S1.4)

* knowledge of elimination method is assumed.

LINEAR COMBINATION (D7(1))

1. Let V be a vector space over a field $\mathbb{F}$, and let the subset $S \subseteq V$ be such that $S \neq \emptyset$.
   Then, we say a vector $x \in V$ is a "linear combination" of vectors from S if there exists a finite number of vectors $u_1, u_2, \ldots, u_n \in S$ and scalars $a_1, a_2, \ldots, a_n \in \mathbb{F}$ such that
   $$x = a_1 u_1 + a_2 u_2 + \cdots + a_n u_n,$$
   where $n \geq 1$. (D7(1))
2. In this case, we also say that x is a linear combination of the vectors $u_1, u_2, \ldots, u_n$.

COEFFICIENTS OF A LINEAR COMBINATION (D7 (2))

1. Let V be a vector space over some field $\mathbb{F}$, and let the vector $x \in V$ be a linear combination of the vectors $u_1, u_2, \ldots, u_n \in S$, where $S \subseteq V$ and $S \neq \emptyset$.
   Assume that $x = a_1 u_1 + a_2 u_2 + \cdots + a_n u_n$, where $a_1, a_2, \ldots, a_n \in \mathbb{F}$.
   Then we denote the scalars $a_1, a_2, \ldots, a_n \in \mathbb{F}$ as the "coefficients" of the linear combination.

SPAN (D7(3))

1. Let V be a vector space over some field $\mathbb{F}$, and let the subset $S \subseteq V$ be such that $S \neq \emptyset$.
   Then, we define the "span" of S, denoted as "$\text{span}(S)$", to be the set of all linear combinations of vectors in S.
2. Note that, for convenience, we define
   $$\text{span}(\emptyset) = \{0\}.$$

EXAMPLE 1: SPAN OF (1,0,0) & (0,1,0) IN $\mathbb{R}^3$ (E10(1))

1. Observe that in $\mathbb{R}^3$, the span of $(1,0,0)$ & $(0,1,0)$ in $\mathbb{R}^3$ is
   $$\{a(1,0,0) + b(0,1,0) : a, b \in \mathbb{R}\}$$
   or more simply
   $$\{(a, b, 0) : a, b \in \mathbb{R}\}.$$

EXAMPLE 2: SPAN($\{x^n : n \geq 1\}$) IN $\mathbb{Q}[x]$ (E10(2))

1. We can show that for the vector space $\mathbb{Q}[x]$, the span of $S = \{x, x^2, \ldots, x^n, \ldots\}$ is the set of all polynomials in $\mathbb{Q}[x]$ whose constant coefficient equals 0.

SPAN OF A FINITE AMOUNT OF VECTORS (E10(3.1))

1. Suppose V is a vector space over some field $\mathbb{F}$, and let $S \subseteq V$. Further assume that
   $$S = \{v_1, v_2, \ldots, v_n\},$$
   ie the size of S is finite.
   Then, it follows that
   $$\text{span}(S) = \{a_1 v_1 + a_2 v_2 + \cdots a_n v_n : a_i \in \mathbb{F} \ \forall i \in \{1, 2, \ldots, n\}\}.$$

SPAN OF A COUNTABLE AMOUNT OF VECTORS (E10 (3.2))

1. Suppose V is a vector space over some field $\mathbb{F}$, and let $S \subseteq V$. Further assume that
   $$S = \{v_1, v_2, \ldots, v_n, \ldots\},$$
   ie $|S| = |\mathbb{N}|$.
   Then, we can show that
   $$\text{span}(S) = \text{span}(\{v_1\}) \cup \text{span}(\{v_1, v_2\}) \cup \cdots \cup \text{span}(\{v_1, v_2, \ldots, v_n\}) \cup \cdots$$
   or in other words, that
   $$\text{span}(S) = \bigcup_{n=1}^{\infty} \text{span}\{v_1, v_2, \ldots, v_n\}.$$

SPAN OF AN UNCOUNTABLE AMOUNT OF VECTORS (E10 (3.3))

1. Suppose V is a vector space over some field $\mathbb{F}$, and let $S \subseteq V$. Further assume that $|S| > |\mathbb{N}|$; ie the size of S is uncountable.
   Then note that there are no "obvious" simplifications to the formula for $\text{span}(S)$.

SPAN OF A SET IS ALWAYS A SUBSPACE OF THE PARENT VECTOR SPACE (T1.4)

1. Let V be a vector space over some field $\mathbb{F}$, and let $S \subseteq V$.
   Then necessarily $\text{span}(S)$ is a subspace of V.
   Proof. This follows from verifying each subspace condition for $\text{span}(S)$. ∎
2. Moreover, $\text{span}(S)$ is the "smallest possible" subspace of V that contains S, in the sense that
   ① $S \subseteq \text{span}(S)$; and
   ② If W is any other subspace of V containing S, then $\text{span}(S) \subseteq W$.

"GENERATES/SPANS" (D8)

1. Let V be a vector space, and let $S \subseteq V$.
   Then, we say S "generates" V, or S "spans" V, if $\text{span}(S) = V$.
2. Note to prove $\text{span}(S) = V$, we just need to prove every vector in V can be written as a linear combination of vectors in S, since $\text{span}(S) \subseteq V$ by definition.
   (This follows from extensionality.) (R6)

LINEAR INDEPENDENCE & DEPENDENCE (S1·5)

LINEARLY DEPENDENT (D9 (1))

1. Let V be a vector space over some field $\mathbb{F}$, and let $S \subseteq V$.
Then, we say S is "linearly dependent" if there exists a finite number of distinct vectors $u_1, u_2, \ldots, u_n \in S$ and scalars $c_1, c_2, \ldots, c_n \in \mathbb{F}$, where $c_1, c_2, \ldots, c_n$ are all not zero, such that

$$c_1 u_1 + c_2 u_2 + \cdots + c_n u_n = 0.$$

2. In this case, we also say the vectors of S are linearly dependent.

3. Note that if S is finite, say $S = \{u_1, u_2, \ldots, u_n\}$, then S is linearly dependent if and only if there exists a $(c_1, c_2, \ldots, c_n) \in \mathbb{F}^n$, where $(c_1, c_2, \ldots, c_n) \neq (0, 0, \ldots, 0)$, such that

$$c_1 u_1 + c_2 u_2 + \cdots + c_n u_n = 0. \quad \text{(R7 (4a))}$$

LINEARLY INDEPENDENT (D9 (2))

1. Let V be a vector space over some field $\mathbb{F}$, and let $S \subseteq V$.
Then, we say S is "linearly independent" if it is not "linearly dependent";
ie for every choice of distinct $u_1, u_2, \ldots, u_n \in S$, if $c_1, c_2, \ldots, c_n \in \mathbb{F}$ are scalars such that

$$c_1 u_1 + c_2 u_2 + \cdots + c_n u_n = 0,$$

then necessarily $c_1 = c_2 = \cdots = c_n = 0$.

2. Similarly, if S is finite, say $S = \{u_1, u_2, \ldots, u_n\}$, then S is linearly independent if and only if whenever $(c_1, c_2, \ldots, c_n) \in \mathbb{F}^n$ are such that

$$c_1 u_1 + c_2 u_2 + \cdots + c_n u_n = 0,$$

then necessarily $c_1 = c_2 = \cdots = c_n = 0$.

TRIVIAL REPRESENTATION OF 0 (R7 (1))

Note that for any vector space V and the vectors $u_1, u_2, \ldots, u_n \in V$, we denote the "trivial representation of $0 \in V$" as a linear combination of $u_1, u_2, \ldots, u_n$ by

$$0u_1 + 0u_2 + \cdots + 0u_n = 0.$$

EMPTY SET IS LINEARLY INDEPENDENT (R7 (2))

Note that the empty set, $\emptyset$, is vacuously linearly independent.

* since linearly dependent sets must be non-empty by definition.

$\{0\}$ IS LINEARLY DEPENDENT (R7 (3))

Note that the set $\{0\}$ is linearly dependent, since $1(0) = 0$ is a non-trivial representation of 0 as a linear combination of finitely many distinct vectors in S.

$0 \in S \Rightarrow S$ IS LINEARLY DEPENDENT (R7 (5))

Note that any subset of a vector space that contains the zero vector is linearly dependent.

EXAMPLE 1: $S = \{(0,1,1), (1,0,1), (1,2,3)\}$ IS LINEARLY DEPENDENT IN $\mathbb{R}^3$ (E14)

We can show that the set $S = \{(0,1,1), (1,0,1), (1,2,3)\}$ is linearly dependent in $\mathbb{R}^3$.

Proof. We search for scalars $a, b, c \in \mathbb{R}$, not all 0, such that

$$a\begin{pmatrix}0\\1\\1\end{pmatrix} + b\begin{pmatrix}1\\0\\1\end{pmatrix} + c\begin{pmatrix}1\\2\\3\end{pmatrix} = \begin{pmatrix}0\\0\\0\end{pmatrix}.$$

This reduces to solving the system

$$\begin{cases} b + c = 0 \\ a + 2c = 0 \\ a + b + 3c = 0. \end{cases}$$

Simplifying, we get that $a = -2t$, $b = -t$ and $c = t$, where $t \in \mathbb{R}$.
For instance, $(a, b, c) = (-2, -1, 1)$ is a solution in which not all of a, b, c are 0.
It follows that S is linearly dependent. ∎

EXAMPLE 2: $S = \{1, x, x^2, x^3\}$ IS LINEARLY INDEPENDENT IN $\mathbb{Z}_5[x]$ (E15)

We can show that the set $S = \{1, x, x^2, x^3\}$ is linearly independent in $\mathbb{Z}_5[x]$.

Proof. Note that if there exist $a_0, a_1, a_2, a_3 \in \mathbb{Z}_5$ such that

$$a_0(1) + a_1 x + a_2 x^2 + a_3 x^3 = 0,$$

then by definition necessarily $a_0 = a_1 = a_2 = a_3 = 0$, and this is sufficient to prove the claim. ∎

S IS LINEARLY DEPENDENT $\iff$ $S=\{0\}$ OR SOME VECTOR IN S IS A LINEAR COMBINATION OF OTHER VECTORS IN S (T1.5)

Let V be a vector space, and let $S \subseteq V$.
Then S is linearly dependent if and only if $S=\{0\}$ or some vector in S is a linear combination of other vectors in S.

Proof. We first prove the backward argument.
First, note we know why $\{0\}$ is linearly dependent from a previous section.
So, suppose there exists a vector $v \in S$ such that

$$v = c_1u_1 + c_2u_2 + \cdots + c_nu_n,$$

where $c_i \in \mathbb{F}$ and $u_i \in V$ $\forall i \in \{1,2,\ldots,n\}$.
Without loss in generality, assume $u_1, u_2, \ldots, u_n$ are distinct.
By assumption, since $v \notin \{u_1, u_2, \ldots, u_n\}$, necessarily $u_1, u_2, \ldots, u_n, v$ are distinct.
Finally, since

$$0 = (-1)v + c_1u_1 + c_2u_2 + \cdots + c_nu_n,$$

and $-1 \neq 0$, it follows S is linearly dependent. ※

Next, we prove the forward argument.
Assume S is linearly dependent, so that there exist distinct $u_1, u_2, \ldots, u_n \in S$ and $a_1, a_2, \ldots, a_n \in \mathbb{F}$ (not all 0) such that

$$a_1u_1 + a_2u_2 + \cdots + a_nu_n = 0.$$

Without loss in generality, assume $a_i \neq 0$ $\forall i \in \{1,2,\ldots,n\}$.

Case 1: $n=1$.
Then $a_1u_1=0$, and since $a_1 \neq 0$ it follows that $u_1=0$ (since fields are integral domains, so the cancellation property applies.)
Hence $0 \in S$. If $S=\{0\}$ we are done; otherwise, we can pick a $v \in S \setminus \{0\}$, and we can write $0 = 0v$, proving some vector in S, 0, can be written as a linear combination of another vector, v, in S.

Case 2: $n>1$.
Then since $a_n \neq 0$, we can solve for u_n:

$$u_n = -a_n^{-1}[a_1u_1 + a_2u_2 + \cdots + a_{n-1}u_{n-1}],$$

$$\therefore u_n = (-a_n^{-1}a_1)u_1 + (-a_n^{-1}a_2)u_2 + \cdots + (-a_n^{-1}a_{n-1})u_{n-1},$$

showing u_n can be expressed as a linear combination of other elements in S.

BASES & DIMENSION (S1.6)

BASIS (D10)

Let V be a vector space.
Then, we say a subset $S \subseteq V$ is a "basis" for V if
① S is linearly independent; and
② S spans V.

In this case, we also say that the vectors of S form a basis for V.

STANDARD BASIS (E17)

In $\mathbb{F}^n$, define the "standard basis" for $\mathbb{F}^n$ the subset

$$S = \{e_1, e_2, \dots, e_n\},$$

where $e_j \in \mathbb{F}^n$ is the vector with j^{th} coordinate 1 and other coordinates 0.

(It is easy to prove S is indeed a basis for $\mathbb{F}^n$.)

In $P_n(\mathbb{F})$, define the "standard basis" for $P_n(\mathbb{F})$ as the set

$$S = \{1, x, x^2, \dots, x^n\}.$$

(It is also easy to prove S is indeed a basis for $P_n(\mathbb{F})$).

UNIQUE REPRESENTATION OF ELEMENTS IN VECTOR SPACES UNDER A BASIS (T1.6)

Let $\{v_1, v_2, \dots, v_n\}$ be a basis for a vector space V.
Then for every $x \in V$, x can be uniquely represented as a linear combination of $v_1, v_2, \dots, v_n$;
ie there exists a unique n-tuple $(a_1, a_2, \dots, a_n) \in \mathbb{F}^n$ such that

$$x = a_1 v_1 + a_2 v_2 + \cdots + a_n v_n.$$

Proof. Existence: this follows from the fact that $\{v_1, v_2, \dots, v_n\}$ spans V by definition.
Uniqueness: suppose there exists some $b_1, b_2, \dots, b_n \in \mathbb{F}$ such that

$$x = a_1 v_1 + \cdots + a_n v_n = b_1 v_1 + \cdots + b_n v_n.$$

It follows that

$$0 = (a_1 - b_1) v_1 + \cdots + (a_n - b_n) v_n,$$

and since $\{v_1, v_2, \dots, v_n\}$ is linearly independent, necessarily $a_k = b_k \ \forall k \in \{1, 2, \dots, n\}$. ∎

V IS GENERATED BY S, $|S| = |\mathbb{N}|$ ⇒ $T \subset S$ IS ALSO A BASIS FOR V (T1.7)

Let V be a vector space, and assume that V is generated by a countable set S.
Then there exists a subset of S that is a basis for V.

Proof. If $S = \emptyset$ or $S = \{0\}$, then $\emptyset$ is a basis for V trivially.
Otherwise, S contains at least a non-zero vector.
Hence, we can write S as

$$S = \{v_1, v_2, \dots, v_n\} \quad \text{or} \quad S = \{v_1, v_2, \dots\}.$$

By the WOP, we can pick the smallest index $i_1 \geq 1$ such that $v_{i_1} \neq 0$.
Then $\{v_{i_1}\}$ is linearly independent.
Let i_2 be the smallest index such that $v_{i_2} \in S$ and $v_{i_2} \notin \operatorname{span}(\{v_{i_1}\})$.
Continue this "process" until we obtain the set

$$T = \{v_{i_k} \in S \mid v_{i_k} \notin \operatorname{span}(\{v_{i_1}, \dots, v_{i_{k-1}}\}),\ k \geq 1\}.$$

Finally, we can prove T is a basis for V.
① Assume T is linearly dependent.
Then there exists $a_1, a_2, \dots, a_k$, all not 0, such that

$$a_1 v_{i_1} + \cdots + a_k v_{i_k} = 0.$$

It follows that

$$v_{i_k} = -a_k^{-1} a_1 v_{i_1} - \cdots - a_k^{-1} a_{k-1} v_{i_{k-1}},$$

contradicting the construction of T.

② We can prove by induction that $\operatorname{span}(S_k) = \operatorname{span}(T_k)$ $\forall k \geq 1$, where

$$S_k = \{v_1, v_2, \dots, v_k\} \quad \text{and} \quad T_k = T \cap S_k = \{v_{i_q} \mid i_q \leq k\}.$$

Then, let $x \in V = \operatorname{span}(S)$. Then $x \in \operatorname{span}(S_m)$ for some large m, so that $x \in \operatorname{span}(T_m) \subset \operatorname{span}(T)$.
Hence $V \subseteq \operatorname{span}(T)$, and it follows that $V = \operatorname{span}(T)$. ∎

EVERY VECTOR SPACE HAS A BASIS (T1.8)

We can prove that every vector space has a basis.

(The proof uses Zorn's lemma & maximal linearly independent subsets.)

REPLACEMENT THEOREM (T1.9)

Suppose V is a vector space with a finite spanning set S.
Let T be a linearly independent subset in V. Then

① $|T| \leq |S|$; and

② There exists a set $H \subseteq S$ containing exactly $(|S|-|T|)$ vectors such that $T \cup H$ generates V.

Proof. Let $n=|S|$, and let $m=|T|$.

Then, when $m=0$, clearly $m=0 \leq |S|$.

Next, assume the statement is true for some $m \geq 0$.

This implies that if $T_m \subset V$ is any linearly independent subset in V of size m, then $m \leq n$ and there exists a set $H_m \subseteq S$ containing exactly $n-m$ vectors such that $T_m \cup H_m$ generates V.

Let $T_m = \{v_1, v_2, \dots, v_m\}$ and $T = T_m \cup \{v_{m+1}\}$, such that T is linearly independent and a subset of V.

Note that this implies T_m is also linearly independent.

Now, apply the induction hypothesis on T_m to get that $n \geq m$, and there exist $(n-m)$ vectors $w_{m+1}, \dots, w_n \in S$ such that $\{v_1, \dots, v_m, w_{m+1}, \dots, w_n\}$ generates V.

Then, since $n \geq m$, either $n=m$ or $n>m$.

If $n=m$, $\{v_1, \dots, v_m, w_{m+1}, \dots, w_n\} = \{v_1, \dots, v_m\}$.

Thus, $v_{m+1} \in \operatorname{span}\{v_1, \dots, v_m\}$, so by Theorem 1.5, the set $\{v_1, \dots, v_m, v_{m+1}\}$ is linearly dependent.

But this is a contradiction; hence, it follows that $n>m$, so that $n \geq m+1$, proving ①.

Subsequently, write

$$v_{m+1} = a_1 v_1 + \cdots + a_m v_m + a_{m+1} v_{m+1} + \cdots + a_n w_n$$

for some scalars $a_1, \dots, a_n \in \mathbb{F}$.

Then, if $a_{m+1} = \cdots = a_n = 0$, then we would get that $v_{m+1} = a_1 v_1 + \cdots + a_m v_m$, which is a contradiction; hence, at least one of the scalars $a_{m+1}, \dots, a_n$ must be non-zero.

Then, without loss in generality, assume $a_{m+1} \neq 0$.

It follows that

$$w_{m+1} = -a_{m+1}^{-1} a_1 v_1 - \cdots - a_{m+1}^{-1} a_m v_m - a_{m+1}^{-1} a_{m+1} v_{m+1}$$
$$- a_{m+1}^{-1} a_{m+2} w_{m+2} - \cdots - a_{m+1}^{-1} a_n w_n.$$

Let $H = \{w_{m+2}, \dots, w_n\} \subset S$. The above shows that $w_{m+1} \in \operatorname{span}(T \cup H)$.

Moreover, since $v_1, \dots, v_m \in T \subset T \cup H$ and $w_{m+2}, \dots, w_n \in H \subset T \cup H$, it follows that

$$V = \operatorname{span}\{w_{m+1}, v_1, \dots, v_m, w_{m+2}, \dots, w_n\} \subseteq \operatorname{span}(T \cup H).$$

But since $\operatorname{span}(T \cup H) \subseteq V$, it follows that $V = \operatorname{span}(T \cup H)$, completing the proof. ▨

V IS FINITELY SPANNED ⇒ ALL BASES OF V HAVE EQUAL CARDINALITIES (C1.9.1)

Suppose V is a finitely spanned vector space.
Then all bases of V are finite and have the same amount of elements.

Proof. Let S be a finite spanning set for V, and let B be an arbitrary basis for V.
Then by definition, B is linearly independent.
By the Replacement Theorem, $|B| \leq |S| < \infty$.
Next, let B_1 and B_2 be two bases of V.
Then, since B_1 is linearly independent and B_2 is a finite spanning set for V, by the Replacement Theorem necessarily $|B_1| \leq |B_2|$.
Similarly, since B_2 is linearly independent and B_1 is a finite spanning set for V, by the Replacement Theorem necessarily $|B_2| \leq |B_1|$.
It follows that $|B_1| = |B_2|$, and we are done.

DIMENSION

FINITE/INFINITE-DIMENSIONAL (D12)

1. We say a vector space V is "finite-dimensional" if it has a basis consisting of a finite number of vectors.

2. Otherwise, we say V is "infinite-dimensional".

DIMENSION (D12)

1. Let V be a finite-dimensional vector space.
Then, the "dimension" of V, denoted as "$\dim V$", is defined to be the unique number of vectors in each basis for V.

2. By convention, we let $\dim\{0\} = 0$.

3. Examples:

① $\dim \mathbb{F}^n = n$;

② $\dim \mathbb{C}^n = 2n$;

③ $\dim M_{m \times n}(\mathbb{F}) = mn$; and

④ $\dim P_n(\mathbb{F}) = n+1$. (E18)

ANY FINITE SPANNING SET FOR V CONTAINS AT LEAST n VECTORS (C1.9.2 (1))

Let V be a vector space with $\dim V = n$.
Then if S is a finite spanning set for V, necessarily $|S| \geq n$.

Proof. By the Existence Theorem (T1.7), there exists a subset T of S that is a basis for V.
Therefore $|T| = \dim V = n$, which implies that $|S| \geq |T| = n$. $\boxtimes$

S GENERATES V, |V| = n ⇒ S IS A BASIS FOR V (C1.9.2 (2))

Let V be a vector space with $\dim V = n$, and suppose S generates V, with $|S| = n$.
Then S is a basis for V.

Proof. Again, by the Existence Theorem (T1.7), there exists some subset $T \subseteq S$ such that T is a basis for V.
By the above corollary, $|T| = n$, so that if $|S| = n$, necessarily $S = T$.
It follows that S is a basis for V. $\boxtimes$

S IS LINEARLY INDEPENDENT ⇒ S CONTAINS AT MOST n VECTORS (C1.9.2 (3))

Let V be a vector space, with $\dim V = n$.
Suppose the subset $S \subseteq V$ is linearly independent.
Then S contains at most n vectors.

Proof. Applying the Replacement Theorem for the spanning set β, it follows that $|S| \leq |\beta|$, and since $|\beta| = n$, this tells us that $|S| \leq n$, as needed. $\boxtimes$

S IS LINEARLY INDEPENDENT, |S| = n ⇒ S IS A BASIS FOR V (C1.9.2 (4))

Let V be a vector space, with $\dim V = n$.
Suppose the subset $S \subseteq V$ is linearly independent and $|V| = n$.
Then S is a basis for V.

Proof. Applying the Replacement Theorem for the spanning set β and the linearly independent set S, there must exist a subset $H \subseteq \beta$ containing $|\beta| - |S| = n - n = 0$ vectors such that $S \cup H$ generates V.
But since $|H| = 0$, hence $H = \emptyset$, so that S generates V (and hence is a basis for V.) $\boxtimes$

EVERY LINEARLY INDEPENDENT SUBSET OF V CAN BE "EXTENDED" TO A BASIS OF V (C1.9.2 (5))

Let V be a vector space, with $\dim V = n$.
Suppose $L = \{v_1, \dots, v_k\}$ is a linearly independent subset of V, where $1 \leq k \leq n$.
Then there exists a $H \subset V$ such that $L \cup H$ is a basis of V.

Proof. If $k = n$, by C1.9.2(4) L is trivially a basis for V.
If $k < n$, then by the Replacement Theorem for the spanning set β and L, there necessarily exists a subset $H \subset \beta$ containing $|\beta| - |L| = n - k$ vectors such that $L \cup H$ generates V.
By C1.9.2(1), $|L \cup H| \geq n$. But
$$|L \cup H| \leq |L| + |H| = k + (n-k) = n,$$
so that $|L \cup H| = n$.
It follows by C1.9.2(2) that $L \cup H$ is a basis for V. $\boxtimes$

W IS A SUBSPACE OF V ⇒ dim W ≤ dim V ; dim W = dim V ⇔ W = V (C1.9.2 (6))

Let W be a subspace of the vector space V.
Then $\dim W \leq \dim V$, with equality occurring if and only if $V = W$.

Proof. If $W = \{0\}$, then $\dim W = 0 \leq \dim V$.
Otherwise, W contains a non-zero vector w_1.
Then $\{w_1\}$ is linearly independent.
Continue to choose the vectors $w_1, \dots, w_n \in W$ such that $\{w_1, \dots, w_k\}$ is linearly independent.
Note that this process cannot go on indefinitely, since $\{w_1, \dots, w_k\}$ is also linearly independent in V.
This implies that $k \leq n$.
Next, by T1.5, $W \subset \operatorname{span}(\{w_1, \dots, w_k\}) = \operatorname{span}(T)$.
Then, since $T \subseteq W$, necessarily $\operatorname{span}(T) \subset \operatorname{span}(W) = W$.
It follows that $W = \operatorname{span}(T)$, so that T is a basis (since it is also linearly independent), and
$$\dim W = |T| = k \leq n = \dim V.$$
Note that if $\dim V = n = \dim W$, then a basis for W is also a linearly independent set containing n elements.
Hence, by C1.9.2(4), that set is also a basis for V. $\boxtimes$

W IS A SUBSPACE FOR V ⇒ ANY BASIS OF W CAN BE "EXTENDED" TO A BASIS IN V (C1.9.2 (7))

Let W be a subspace of the vector space V, and let S be a basis of W.
Then we can "extend" S to a basis in V.

Proof. By C1.9.2(6), $\dim W \leq \dim V$.
Let $T = \{w_1, \dots, w_k\}$ be a basis for W, so that T is linearly independent in W, which in turn implies T is linearly independent in V.
So, by C1.9.2(5), we can "extend" T to a basis in V. $\boxtimes$

QUOTIENT SPACES (S1.7)

COSET & REPRESENTATIVE (D13)

Let V be a vector space, and W be a subspace of V.
Then, for a given $x \in V$, its corresponding "coset" of W in V, denoted as "$x+W$", is defined to be the set
$x+W = \{x+w : w \in W\}$.

* note that $x+W \subseteq V$.

In this case, we call "x" a "representative" of the coset $x+W$.

$x \equiv y \pmod{W}$ (D13)

Let V be a vector space, and let W be a subspace of V.
Then, we write "$x \equiv y \pmod{W}$" if and only if $x-y \in W$.

V/W (D13)

Let V be a vector space, and W a subspace of V.
Then, we denote "V/W" (ie "V mod W") as the set
$V/W = \{x+W : x \in V\}$;
ie let V/W be the collection of cosets of W in V.

$V/\{0\} = V$ (E19 (2))

For any vector space V, necessarily $V/\{0\} = V$.

Proof. $V/\{0\} = \{0+x : x \in V\}$
$= \{x : x \in V\}$
$\therefore V/\{0\} = V$. ☒

COSET TEST (P1)

Let W be a subspace of a vector space V, and let $x, y \in V$ be arbitrary.
Then $x+W = y+W$ if and only if $x-y \in W$.

Proof. Similar to test for cosets in MATH 145.

$\equiv \pmod{W}$ IS AN EQUIVALENCE RELATION ON V (R8)

Note that the relation "$\equiv \pmod{W}$" is an equivalence relation on V.

ADDITION & MULTIPLICATION IN V/W (D14)

Let V be a vector space over a field $\mathbb{F}$, and let W be a subspace of V.
Then, we can define an addition on V/W by
$(x+W) + (y+W) := ((x+y) + W)$;
and a scalar multiplication on V/W by
$a(x+W) := (ax) + W$;
for any $a \in \mathbb{F}$ and $x, y \in W$.

Note that these addition and multiplication operations are well-defined. (L1)

Proof. Similar to proof for quotient groups/rings.

V/W IS A VECTOR SPACE (THE QUOTIENT SPACE OF V BY W) (T1.10)

Let V be a vector space, and W a subspace of V.
Then the set V/W is a vector space over $\mathbb{F}$ with the operations of coset addition and scalar multiplication, denoted as "the quotient space of V by W".

Proof. Verify all 8 conditions. (VS 1-8). ☒

BASIS FOR QUOTIENT SPACES (T1.11)

Let V be a vector space with $\dim V = n$, and let W be a subspace of V such that $\dim W = k$.
Let $\{v_1, \dots, v_n\}$ be a basis for V, such that $\{v_1, \dots, v_k\}$ is a basis for W.
Then,
① The set $\{v_{k+1}+W, \dots, v_n+W\}$ is a basis for V/W; and
② $\dim(V/W) = \dim V - \dim W$.

Proof. To prove ①, we show $\{v_{k+1}+W, \dots, v_n+W\}$ is both linearly independent and generates V/W, giving us our basis.
It follows that
$\dim(V/W) = |\{v_{k+1}+W, \dots, v_n+W\}|$
$= n-(k+1)+1$
$= n-k$
$\therefore \dim(V/W) = \dim V - \dim W$. ☒

$\dim V \geq \infty, \dim W \geq \infty \not\Rightarrow \dim V/W \geq \infty$ (R9)

Let V be an infinite-dimensional vector space, and let W be an infinite-dimensional subspace of V.
Then, note that it is not necessarily the case that $\dim(V/W) \geq \infty$.

Example: let $V = \mathbb{F}^\infty$ & $W = \{(0, x_2, \dots) : x_k \in \mathbb{F}\}$.
Note that each element of V/W is simply "determined" by the value of the first coordinate x_1, so that $\dim(V/W) = 1$.

SUMS & INTERNAL DIRECT SUMS OF SUBSPACES (SL8)

SUM OF SUBSPACES (DIS)

Let V be a vector space over $\mathbb{F}$, and let W_1, W_2 be subspaces of V. Then, we define the "sum" of W_1 and W_2, denoted as "$W_1 + W_2$", to be the set

$$W_1 + W_2 := \{v_1 + v_2 : v_1 \in W_1,\ v_2 \in W_2\}.$$

INDEPENDENT / DISJOINT (DIS)

Let V be a vector space, and let W_1, W_2 be subspaces of V. Then, we say W_1 and W_2 are "independent", or "disjoint", if and only if $W_1 \cap W_2 = \{0\}$.

(INTERNAL) DIRECT SUM (DIS)

Let V be a vector space, and let W_1, W_2 be independent subspaces of V. Then, we define the "(internal) direct sum" of W_1 and W_2", denoted as $W_1 \oplus W_2$, to be the set

$$W_1 \oplus W_2 = W_1 + W_2.$$

*ie "$\oplus$" is the notation for "+" used when W_1 & W_2 are independent.

Note that $W_1 \oplus W_2$ is well-defined as long as $W_1 \cap W_2 = \{0\}$. (R10)

$W_1 + W_2$ IS THE "SMALLEST" SUBSPACE CONTAINING W_1 & W_2 (L2 (2))

Let V be a vector space, and let W_1, W_2 be subspaces of V. Then $W_1 + W_2$ is necessarily the smallest subspace of V containing W_1 and W_2.

Proof. First, we prove $W_1 + W_2$ is a subspace of V.

Let $(v_1+v_2), (u_1+u_2) \in W_1 + W_2$ and $a \in F$, where $v_1, u_1 \in W_1$ and $v_2, u_2 \in W_2$.

Then, since W_1 and W_2 are subspaces of $W_1 + W_2$, necessarily $v_1 + u_1 \in W_1$ and $v_2 + u_2 \in W_2$, so that

$$(v_1+v_2) + (u_1+u_2) = (v_1+u_1) + (v_2+u_2) \in W_1 + W_2.$$

Moreover, since $av_1 \in W_1$ and $av_2 \in W_2$, necessarily

$$a(v_1+v_2) = av_1 + av_2 \in W_1 + W_2,$$

proving $W_1 + W_2$ is closed under addition and scalar multiplication.

Then, since $v_1 = v_1 + 0 \in W_1 + W_2$ $\forall v_1 \in W_1$ & $v_2 = 0 + v_2 \in W_1 + W_2$ $\forall v_2 \in W_2$, it follows that $W_1 \subseteq W_1 + W_2$ and $W_2 \subseteq W_1 + W_2$.

Finally, let Y be a subspace of V that contains both W_1 & W_2.

Since Y is closed under addition, $v_1 + v_2 \in Y$ for every $v_1 \in W_1$ and $v_2 \in W_2$ necessarily. It follows that $W_1 + W_2 \subseteq Y$, completing the proof.

$V = W_1 \oplus W_2 \iff \forall v \in V : \exists$ UNIQUE $w_1 \in W_1$, $w_2 \in W_2 \ni v = w_1 + w_2$ (L2 (3))

Let V be a vector space, and let W_1 and W_2 be subspaces of V. Then $W_1 \oplus W_2 = V$ if and only if for every vector $v \in V$, there exist unique elements $w_1 \in W_1$ and $w_2 \in W_2$ such that $v = w_1 + w_2$.

Proof. ($\Rightarrow$) Since $V = W_1 \oplus W_2$, necessarily $V = W_1 + W_2$ and $W_1 \cap W_2 = \{0\}$.

Let $v \in V$, and note that since $V = W_1 + W_2$, it implies that $v \in W_1 + W_2$.

So, by definition, there exist some $w_1 \in W_1$, $w_2 \in W_2$ such that $v = w_1 + w_2$.

Next, suppose we have $v = w_1' + w_2'$ for some $w_1' \in W_1$ and $w_2' \in W_2$.

Then

$$0 = (w_1 + w_2) - (w_1' + w_2') = (w_1 - w_1') + (w_2 - w_2').$$

Since $w_1, w_1' \in W_1$ & $w_2, w_2' \in W_2$, necessarily $w_1 - w_1' \in W_1$ & $w_2 - w_2' \in W_2$ also, so that

$$(w_1 - w_1') = w_2' - w_2 \in W_1 \cap W_2 = \{0\},$$

Hence $w_1 - w_1' = w_2' - w_2 = 0$, implying that $w_1 = w_1'$ & $w_2 = w_2'$, proving uniqueness. #

($\Leftarrow$) By assumption, every vector $v \in V$ can be written as $v = w_1 + w_2$ for some $w_1 \in W_1$ & $w_2 \in W_2$.

Hence $V \subseteq W_1 + W_2$, and by L2(2) necessarily $W_1 + W_2 \subseteq V$; so $V = W_1 + W_2$.

Next, let $x \in W_1 \cap W_2$. Then $-x \in W_1 \cap W_2$.

Then, note that

$$0 = 0 + 0 = x + (-x) \in W_1 + W_2,$$

and due to the uniqueness assumption, necessarily $x = 0$.

Thus $W_1 \cap W_2 = \{0\}$, so that $V = W_1 \oplus W_2$. ☒

$\dim(W_1), \dim(W_2) < \infty \Rightarrow \dim(W_1+W_2) < \infty$ & $\dim(W_1) + \dim(W_2) = \dim(W_1+W_2) + \dim(W_1 \cap W_2)$ (T1.12 (1))

Let V be a vector space over some field $\mathbb{F}$, and let W_1, W_2 be finite dimensional subspaces of V.

Then necessarily $W_1 + W_2$ is finite dimensional, and

$\dim(W_1) + \dim(W_2) = \dim(W_1+W_2) + \dim(W_1 \cap W_2)$.

Proof. First, note $W_1 \cap W_2$ is a subspace of W_1 (A2), so that

$$\dim(W_1 \cap W_2) \leq \dim(W_1) < \infty \quad \text{(C1.9.2 (6))}.$$

Next, let $\{u_1, u_2, \dots, u_k\}$ be a basis for $W_1 \cap W_2$.

Extend this basis to get the bases $S_1 = \{u_1, \dots, u_k, v_1, \dots, v_m\}$ of W_1 and $S_2 = \{u_1, \dots, u_k, z_1, \dots, z_p\}$ of W_2, which we can always do by C1.9.2 (5)).

Let $S = \{u_1, \dots, u_k, v_1, \dots, v_m, z_1, \dots, z_p\}$.

We claim S is a basis for $W_1 + W_2$.

Indeed, consider

$$a_1u_1 + \dots + a_ku_k + b_1v_1 + \dots + b_mv_m + c_1z_1 + \dots + c_pz_p = 0 \quad \text{— ②}$$

for some scalars $a_1, \dots, a_k, b_1, \dots, b_m, c_1, \dots, c_p$.

Then

$$b_1v_1 + \dots + b_mv_m = -a_1u_1 - \dots - a_ku_k - c_1z_1 - \dots - c_pz_p.$$

Since the RHS is a linear combination of vectors in W_2, the RHS $\in W_2$; and since the LHS is a linear combination of vectors in W_1, the LHS $\in W_1$.

Thus $b_1v_1 + \dots + b_mv_m \in W_1 \cap W_2$.

Next, since $\{u_1, \dots, u_k\}$ is a basis for $W_1 \cap W_2$, there exist scalars $d_1, \dots, d_k$ such that

$$b_1v_1 + \dots + b_mv_m = d_1u_1 + \dots + d_ku_k.$$

So

$$b_1v_1 + \dots + b_mv_m - d_1u_1 - \dots - d_ku_k = 0.$$

Since $\{u_1, \dots, u_k, v_1, \dots, v_m\}$ is a basis for W_1, necessarily $b_1 = \dots = b_m = d_1 = \dots = d_k = 0$.

Substitute $b_1 = \dots = b_m$ into ② to get that

$$a_1u_1 + \dots + a_ku_k + c_1z_1 + \dots + c_pz_p = 0.$$

Then, since $\{u_1, \dots, u_k, z_1, \dots, z_p\}$ is a basis for W_2, we have

$$a_1 = \dots = a_k = c_1 = \dots = c_p = 0,$$

proving S is linearly independent.

Subsequently, let $x + y \in W_1 + W_2$ be arbitrary, where $x \in W_1$ and $y \in W_2$.

Then, since S_1 and S_2 are bases for W_1 and W_2 respectively, we can write x and y as linear combinations of vectors in S_1 and S_2, respectively:

$$x = a_1u_1 + \dots + a_ku_k + b_1v_1 + \dots + b_mv_m \ ; \ \&$$
$$y = d_1u_1 + \dots + d_ku_k + c_1z_1 + \dots + c_pz_p,$$

where $a_1, \dots, a_k, b_1, \dots, b_m, d_1, \dots, d_k, c_1, \dots, c_p \in \mathbb{F}$.

Hence

$$x + y = (a_1+d_1)u_1 + \dots + (a_k+d_k)u_k + b_1v_1 + c_1z_1 + \dots + b_mv_m + c_pz_p,$$

which is sufficient to show $x + y \in \operatorname{span}(S)$.

Thus $W_1 + W_2 \subseteq \operatorname{span}(S)$, and since $\operatorname{span}(S) \subseteq W_1 + W_2$ by definition, it follows that $W_1 + W_2 = \operatorname{span}(S)$, verifying that S is indeed a basis for $W_1 + W_2$.

In particular,

$$\begin{aligned} \dim(W_1+W_2) + \dim(W_1 \cap W_2) &= |S| + k \\ &= m + p + k + k \\ &= (m+k) + (p+k) \\ &= \dim W_1 + \dim W_2. \end{aligned}$$

☒

$\dim(V) < \infty$, $W_1 \oplus W_2 = V \Rightarrow \dim W_1 + \dim W_2 = \dim V$ (T1.12 (2))

Let V be a vector space over $\mathbb{F}$, and let W_1, W_2 be finite-dimensional subspaces of V.

Suppose further that V itself is finite dimensional, and $W_1 \oplus W_2 = V$.

Then necessarily $\dim W_1 + \dim W_2 = \dim V$.

Proof. Since $W_1 \oplus W_2 = V$, necessarily $W_1 \cap W_2 = \{0\}$.

So, by T1.12 (1), it follows that

$$\begin{aligned} \dim W_1 + \dim W_2 &= \dim(W_1+W_2) + \dim(W_1 \cap W_2) \\ &= \dim(V) + 0 \end{aligned}$$

$\therefore \dim W_1 + \dim W_2 = \dim(V)$. ☒

COMPLEMENTARY SUBSPACES (D15)

Let V be a vector space, and let W be a subspace of V.

Then a subspace W' of V is said to be a "complementary subspace" to W if $W \oplus W' = V$; ie

① $W \cap W' = \{0\}$; and

② $W + W' = V$.

$\dim W + \dim W' = \dim V$

Let V be a vector space, and let W be a subspace of V.

Let W' be a complementary subspace to W.

Then necessarily $\dim W + \dim W' = \dim V$.

Proof. Follows directly from T1.12 (2).

EXISTENCE OF COMPLEMENTARY SUBSPACES (R11 (1))

Let V be a vector space, and let W be a subspace of V.

Then there always exists a complementary subspace W' to W of V such that $W \oplus W' = V$.

Proof. First, note that every finite linearly independent set can be extended to a basis V that has a countable spanning set (A3).

Hence, every linearly independent subset of V can be extended to a basis for V.

It follows that every subspace W of V has a complementary subspace W'. ☒

NON-UNIQUENESS OF COMPLEMENTARY SUBSPACES (R11 (2))

Note that complementary subspaces of a given vector space V are not necessarily unique.

eg $V = \mathbb{R}^3$, $W = \{(1,0,0), (0,1,0)\}$, $W_1' = \{(0,0,1)\}$, $W_2' = \{(0,0,-1)\}$;

observe that both W_1' and W_2' are complementary subspaces to W.

Chapter 2: Linear Transformations and Matrices

LINEAR TRANSFORMATIONS (S2.1)

Let V and W be vector spaces over the same field $\mathbb{F}$.

Then, we say the function $T: V \to W$ is a "linear transformation" from V to W if

(L1) → ① $T(x+y) = T(x) + T(y) \quad \forall x, y \in V$; and

(L2) → ② $T(cx) = cT(x) \quad \forall x \in V,\ c \in \mathbb{F}$. (D16)

In this case, we say the function $T: V \to W$ is "linear".

T IS LINEAR ⟺ $T(cx+y) = cT(x) + T(y)$ (P2)

Let the function $T: V \to W$, where V and W are vector spaces over the same field $\mathbb{F}$.

Then T is linear if and only if $T(cx+y) = cT(x) + T(y)$ for all $x, y \in V$ and $c \in \mathbb{F}$.

ZERO TRANSFORMATION (E23 (1a))

For any vector spaces V and W, the "zero transformation", given by "$T_0 : V \to W$", is defined by $T_0(x) = 0 \quad \forall x \in V$.

IDENTITY TRANSFORMATION (E23 (1b))

For any vector space V, the "identity transformation" $I_V : V \to V$ is given by $I_V(x) = x \quad \forall x \in V$.

$T: V \to \mathbb{F}^n$ BY $T(a_1v_1 + \cdots + a_nv_n) := (a_1, \ldots, a_n)$ (E23 (3))

Let V be a finite-dimensional vector space over $\mathbb{F}$, and let $\{v_1, v_2, \ldots, v_n\}$ be a basis for V.

Then, the mapping

$$T: V \to \mathbb{F}^n \quad \text{by} \quad T(a_1v_1 + \cdots + a_nv_n) := (a_1, \ldots, a_n)$$

is linear.

$T: \mathbb{F}^n \to \mathbb{F}^k$, $T(x_1, \ldots, x_n) := (x_1, \ldots, x_k)$ (E23 (4))

Let $\mathbb{F}$ be a field, and suppose $1 \le k < n$.

Then the projection mapping

$$T: \mathbb{F}^n \to \mathbb{F}^k \quad \text{by} \quad T(x_1, \ldots, x_n) := (x_1, \ldots, x_k)$$

is linear.

$T(0) = 0$ (P3 (1))

Let $T: V \to W$ be linear.

Then necessarily $T(0) = 0$.

Proof. $T(0) = T(0+0) = T(0) + T(0)$;

thus $0 = T(0) + T(0) - T(0) = T(0)$. ∎

$T(x-y) = T(x) - T(y)$ (P3(2))

Let $T: V \to W$ be linear.

Then necessarily $T(x-y) = T(x) - T(y) \quad \forall x, y \in V$.

Proof. $T(x-y) = T(x) + T(-y)$

$= T(x) + (-1)T(y)$

$\therefore T(x-y) = T(x) - T(y)$. ∎

$T(a_1x_1 + \cdots + a_nx_n) = a_1T(x_1) + \cdots + a_nT(x_n)$ (P3 (3))

Let T be linear, and $a_1, \ldots, a_n \in \mathbb{F}$ and $x_1, \ldots, x_n \in V$ be arbitrary.

Then necessarily

$$T(a_1x_1 + \cdots + a_nx_n) = a_1T(x_1) + \cdots + a_nT(x_n).$$

$\{v_1, \ldots, v_n\}$ IS A BASIS FOR V, $\{w_1, \ldots, w_n\}$ ARE ELEMENTS FOR W ⟹ ∃ A UNIQUE LINEAR MAPPING $T: V \to W$ ∋ $T(v_k) = w_k$ (T2.1)

Let $\{v_1, \ldots, v_n\}$ be a basis for a vector space V, and let $\{w_1, \ldots, w_n\}$ be arbitrary elements of another vector space W.

Then there exists a unique linear mapping $T: V \to W$ such that

$$T(v_1) = w_1, \quad \ldots, \quad T(v_n) = w_n.$$

Proof. Let $v \in V$ be arbitrary. Since $\{v_1, v_2, \ldots, v_n\}$ is a basis for V, there must exist $a_1, \ldots, a_n \in \mathbb{F}$ such that

$$v = a_1v_1 + \cdots + a_nv_n.$$

Let $T(v) = T(a_1v_1 + \cdots + a_nv_n) = a_1w_1 + \cdots + a_nw_n$ (by P3(3)).

Then, by construction, for any $1 \le k \le n$, we have

$$T(v_k) = T(0v_1 + \cdots + 0v_{k-1} + 1v_k + 0v_{k+1} + \cdots + 0v_n)$$
$$= 0w_1 + \cdots + 0w_{k-1} + 1w_k + 0w_{k+1} + \cdots + 0w_n$$
$$= w_k,$$

proving uniqueness.

Next, suppose there exists another linear mapping $L: V \to W$ satisfying $L(v_1) = w_1, \ldots, L(v_n) = w_n$.

Let $v = a_1v_1 + \cdots + a_nv_n$, where $v \in V$ and $a_1, \ldots, a_n \in \mathbb{F}$.

Then

$$\begin{aligned} L(v) &= L(a_1v_1 + \cdots + a_nv_n) \\ &= a_1L(v_1) + \cdots + a_nL(v_n) \\ &= a_1w_1 + \cdots + a_nw_n \\ &= a_1T(v_1) + \cdots + a_nT(v_n) \\ &= T(a_1v_1 + \cdots + a_nv_n) \end{aligned}$$

$\therefore L(v) = T(v)$.

Hence $L(v) = T(v) \quad \forall v \in V$, so that $T = L$, proving uniqueness. ∎

It also follows that we have

$$T(a_1v_1 + \cdots + a_nv_n) = a_1w_1 + \cdots + a_nw_n. \qquad \text{(C2.1.1)}$$

NULL SPACE / KERNEL (D17(1))

Let V and W be vector spaces, and let $T: V \to W$ be linear.
Then the "null space" of T, or the "kernel" of T, denoted as "$N(T)$", is defined to be the set

$$N(T) := \{x \in V \mid T(x) = 0\}.$$

RANGE / IMAGE (D17(2))

Let V and W be vector spaces, and let $T: V \to W$ be linear.
Then the "range" of T, or the "image" of T, denoted as "$R(T)$", is defined to be the set

$$R(T) := \{T(x) : x \in V\}.$$

N(T) IS A SUBSPACE OF V (T2.2)

Let $T: V \to W$ be linear.
Then necessarily $N(T)$ is a subspace of V.

R(T) IS A SUBSPACE OF W (T2.2)

Let $T: V \to W$ be linear.
Then necessarily $R(T)$ is a subspace of W.

$\{v_1, \dots, v_n\}$ IS A BASIS FOR $V \Rightarrow \operatorname{span}(\{T(v_1), \dots, T(v_n)\}) = R(T)$ (T2.3)

Let V and W be vector spaces, and let $T: V \to W$ be linear.
Suppose the set $\{v_1, \dots, v_n\}$ is a basis for V.
Then necessarily $\{T(v_1), \dots, T(v_n)\}$ generates $R(T)$.

NULLITY (D18)

Let $T: V \to W$ be linear, and suppose that $\dim(N(T)) < \infty$.
Then, we define the "nullity" of T, denoted by "nullity(T)", to be equal to

$$\text{nullity}(T) = \dim(N(T)).$$

RANK (D18)

Let $T: V \to W$ be linear, and suppose that $\dim(R(T)) < \infty$.
Then, we define the "rank" of T, denoted by "rank(T)", to be equal to

$$\text{rank}(T) = \dim(R(T)).$$

RANK-NULLITY THEOREM (T2.4)

Let V and W be vector spaces, and let $T: V \to W$ be linear with $\dim(V) < \infty$.
Then necessarily

$$\text{rank}(T) + \text{nullity}(T) = \dim(V).$$

Proof. Since $N(T)$ is a subspace of V (T2.2) and $\dim V < \infty$, by C1.9.2 (6) necessarily $\text{nullity}(T) \leq \dim(V) < \infty$.
Then, let $\text{nullity}(T) = k$, and suppose that $\{v_1, \dots, v_k\}$ is a basis for $N(T)$.
We know that we can "extend" $\{v_1, \dots, v_k\}$ to get a basis for V, $\{v_1, \dots, v_n\}$, so let us do so.
Next, we claim $\{T(v_{k+1}), \dots, T(v_n)\}$ is a basis for $R(T)$.
First, we show $\{T(v_{k+1}), \dots, T(v_n)\}$ spans $R(T)$.
By T2.2, $R(T) = \operatorname{span}(\{T(v_1), \dots, T(v_k), T(v_{k+1}), \dots, T(v_n)\})$.
Then, since $\{v_1, \dots, v_k\}$ is a basis for $N(T)$, necessarily

$$T(v_1) = \dots = T(v_k) = 0.$$

Hence,

$$R(T) = \operatorname{span}(\{T(v_{k+1}), \dots, T(v_n)\}),$$

as needed.
Next, we show $\{T(v_{k+1}), \dots, T(v_n)\}$ is linearly independent.
Consider

$$c_{k+1}T(v_{k+1}) + \dots + c_nT(v_n) = 0, \quad \text{where } c_{k+1}, \dots, c_n \in \mathbb{F}$$

$$\Rightarrow T(c_{k+1}v_{k+1} + \dots + c_nv_n) = 0.$$

Hence $c_{k+1}v_{k+1} + \dots + c_nv_n \in N(T)$; then, since $\{v_1, \dots, v_k\}$ is a basis for $N(T)$, there exist $d_1, \dots, d_k \in \mathbb{F}$ such that

$$c_{k+1}v_{k+1} + \dots + c_nv_n = d_1v_1 + \dots + d_kv_k.$$

$$\Rightarrow -d_1v_1 - \dots - d_kv_k + c_{k+1}v_{k+1} + \dots + c_nv_n = 0.$$

Since $\{v_1, \dots, v_n\}$ is a basis for V, consequently

$$d_1 = \dots = d_k = c_{k+1} = \dots = c_n = 0,$$

showing $\{T(v_{k+1}), \dots, T(v_n)\}$ is linearly independent.
Consequently,

$$\begin{aligned}\text{rank}(T) + \text{nullity}(T) &= \dim(R(T)) + \dim(N(T)) \\ &= k + (n - (k+1) + 1) \\ &= n\end{aligned}$$

$\therefore \text{rank}(T) + \text{nullity}(T) = \dim(V)$. $\blacksquare$

ONE-TO-ONE (1-1) (D19)

Let $T: V \to W$ be linear.
Then, we say T is "one-to-one" if, for any $x, y \in V$, $T(x) = T(y)$ implies $x = y$.

ONTO (D19)

Let $T: V \to W$ be linear.
Then, we say T is "onto" if $R(T) = V$.

ISOMORPHISM (D19)

1. Let $T: V \to W$ be linear.
Then, we say T is an "isomorphism" if it is both one-to-one and onto.

2. We say V is "isomorphic" to W if an isomorphism $T: V \to W$ exists, (D20) and denote this by the notation "$V \cong W$".

T IS 1-1 $\iff$ $N(T) = \{0\}$ (L3)

Let $T: V \to W$ be linear.

Then T is one-to-one if and only if $N(T) = \{0\}$.

Proof. ($\Rightarrow$) Suppose T is one-to-one.

Let $x \in V$ be such that $T(x) = 0$.

Then since $T(0) = 0 = T(x)$, by definition $x = 0$, so that $N(T) = \{0\}$.

($\Leftarrow$) Suppose $N(T) = \{0\}$. Consider $x, y \in V$ such that $T(x) = T(y)$.

Then

$$T(x-y) = T(x) - T(y) = 0,$$

so that $x - y \in N(T)$;

hence $x - y = 0$, so that $x = y$ (and hence T is 1-1). ☒

$\{v_1, \dots, v_n\}$ IS A BASIS FOR V $\Rightarrow$ T IS ISOMORPHIC $\iff$ $\{T(v_1), \dots, T(v_n)\}$ IS A BASIS FOR W (T2.5)

Let V and W be vector spaces over a field $\mathbb{F}$, with $\dim V < \infty$.

Let $\{v_1, \dots, v_n\}$ be a basis for V, and let $T: V \to W$ be linear.

Then T is an isomorphism if and only if $\{T(v_1), \dots, T(v_n)\}$ is a basis for W.

Proof. ($\Rightarrow$) Consider

$$c_1T(v_1) + \dots + c_nT(v_n) = 0$$

$$\Rightarrow T(c_1v_1 + \dots + c_nv_n) = 0.$$

Since T is one-to-one by definition, hence

$$c_1v_1 + \dots + c_nv_n = 0,$$

and as $\{v_1, \dots, v_n\}$ is a basis for V, necessarily $c_1 = \dots = c_n = 0$;

hence $\{T(v_1), \dots, T(v_n)\}$ is a basis for W. #

($\Leftarrow$) If $\{T(v_1), \dots, T(v_n)\}$ is a basis for W, by definition $\{T(v_1), \dots, T(v_n)\}$ generates W.

Thus $W = \operatorname{span}(\{T(v_1), \dots, T(v_n)\}) = R(T)$,

where the second equality comes from T2.3.

Then, since $W = R(T)$, T is necessarily onto.

Let $x \in N(T)$. Since $\{v_1, \dots, v_n\}$ is a basis for V, there must exist some $a_1, \dots, a_n \in \mathbb{F}$ such that

$$x = a_1v_1 + \dots + a_nv_n.$$

Hence

$$0 = T(x) = a_1T(v_1) + \dots + a_nT(v_n).$$

Since $\{T(v_1), \dots, T(v_n)\}$ is a basis for W by assumption,

thus $\{T(v_1), \dots, T(v_n)\}$ is linearly independent, so that

$$a_1 = \dots = a_n = 0,$$

and so

$$x = 0v_1 + \dots + 0v_n = 0.$$

Consequently $N(T) = \{0\}$, so that (by L3) T is 1-1. ☒

CONSTRUCTING AN ISOMORPHISM FROM V TO W

Let V and W be vector spaces.

Then, we can construct an isomorphism from V to W as follows:

① Choose a basis $\{v_1, \dots, v_n\}$ for V, and a basis $\{w_1, \dots, w_n\}$ for W.

② Let the linear transformation $T: V \to W$ be such that $T(v_k) = w_k$ $\forall k \in \{1, 2, \dots, n\}$.

(T exists; this follows from T2.1)

③ Then, by T2.5, T is also an isomorphism.

$V \cong W \iff \dim V = \dim W$ (T2.6)

Let V and W be two finite-dimensional vector spaces over a field $\mathbb{F}$.

Then V is isomorphic to W if and only if $\dim V = \dim W$.

$\dim V = \dim W < \infty$; T IS 1-1 $\iff$ T IS ONTO $\iff$ $\operatorname{rank}(T) = \dim(V)$ (T2.7)

Let V and W be two vector spaces over a field $\mathbb{F}$, and assume $\dim V = \dim W < \infty$.

Let $T: V \to W$ be linear.

Then the following are equivalent to one another:

① T is one-to-one;

② T is onto; and

③ $\operatorname{rank}(T) = \dim(V)$.

SET OF ALL LINEAR TRANSFORMATIONS (D21)

Let V and W be vector spaces over $\mathbb{F}$.

Then, we let $\mathcal{L}(V, W) \subseteq W^V$ denote the set of all linear transformations $T: V \to W$.

$\mathcal{L}(V, W)$ IS A SUBSPACE OF W^V (T2.8)

Let V and W be vector spaces over some field $\mathbb{F}$.

Then necessarily $\mathcal{L}(V, W)$ is a subspace of W^V.

Proof. Clearly $\mathcal{L}(V,W) \subset W^V$, so we only need to show that it is non-empty and is closed under the addition & scalar multiplication operations of W^V.

Also note the zero transformation $T_0: V \to W$ is in $\mathcal{L}(V,W)$, so that $\mathcal{L}(V,W)$ is non-empty.

Next, assume $T, U \in \mathcal{L}(V,W)$. Note that for any $x, y \in V$ & $c \in \mathbb{F}$:

$$(T+U)(cx+y) = T(cx+y) + U(cx+y)$$
$$= cT(x) + T(y) + cU(x) + U(y)$$
$$= c(T+U)(x) + (T+U)(y),$$

showing $T+U$ is linear (by P2), so that $T+U \in \mathcal{L}(V,W)$.

A similar argument shows $cT \in \mathcal{L}(V,W)$ as well $\forall c \in \mathbb{F}$.

Thus $\mathcal{L}(V,W)$ is a subspace of W^V, and we are done. ☒

MORE ON MATRICES

TRANSPOSITION OF A MATRIX

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary, and write

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \\ a_{m1} & a_{m2} & & a_{mn} \end{pmatrix}.$$

Then the "transposition" of A, denoted as "A^T" (or "A^t"), is defined to be the matrix

$$A^T = \begin{pmatrix} a_{11} & a_{21} & \cdots & a_{m1} \\ a_{12} & a_{22} & \cdots & a_{m2} \\ \vdots & \vdots & \ddots & \\ a_{1n} & a_{2n} & & a_{mn} \end{pmatrix} \in M_{n\times m}(\mathbb{F}).$$

MATRIX VECTOR MULTIPLICATION (D22)

Let $A \in M_{m\times n}(\mathbb{F})$ and $x \in \mathbb{F}^n$ be arbitrary, where $\mathbb{F}$ is some field.

We define "Ax" to be equal to

$$Ax = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \\ a_{m1} & a_{m2} & & a_{mn} \end{pmatrix}\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \sum_{k=1}^{n} a_{1k}x_k \\ \sum_{k=1}^{n} a_{2k}x_k \\ \vdots \\ \sum_{k=1}^{n} a_{mk}x_k \end{pmatrix};$$

ie the i^{th} entry of Ax is obtained by multiplying the entries in the i^{th} row of A by the entries of x, and then summing up the resultant products.

$L_A(x) = Ax$ (D23)

Let $\mathbb{F}$ be a field, and let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.

Then, we let the function $L_A : \mathbb{F}^n \to \mathbb{F}^m$ be defined by $L_A(x) = Ax \quad \forall x \in \mathbb{F}^n$.

"a_j" MATRIX NOTATION

Let $A \in M_{m\times n}(\mathbb{F})$, and write

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \\ a_{m1} & a_{m2} & & a_{mn} \end{pmatrix}.$$

Then, we use the notation "a_j" to denote

$$a_j = \begin{pmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{mj} \end{pmatrix},$$

and we can also write A as

$$A = (a_1 \ a_2 \ \cdots \ a_j).$$

$Ax = x_1a_1 + x_2a_2 + \cdots + x_na_n$ (L4(1))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary, and write $A = (a_1 \ a_2 \ \cdots \ a_n)$.

Then for any $x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{F}^n$, we have

$$Ax = x_1a_1 + x_2a_2 + \cdots + x_na_n.$$

$a_j = Ae_j$ (L4 (2))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary, and write $A = (a_1 \ a_2 \ \cdots \ a_n)$.

Suppose $\{e_1, e_2, \ldots, e_n\}$ are the standard basis vectors for $\mathbb{F}^n$.

Then necessarily $Ae_j = a_j$.

MATRIX EQUALITY THEOREM (C2.8.1)

Let $A, B \in M_{m\times n}(\mathbb{F})$ be arbitrary.

Then $A = B$ if and only if $Ax = Bx \quad \forall x \in \mathbb{F}^n$.

Proof. ($\Rightarrow$) is obvious.

($\Leftarrow$) Suppose $Ax = Bx \quad \forall x \in \mathbb{F}^n$.

This implies $Ae_j = Be_j \quad \forall j \in \{1, \ldots, n\}$, which tells us (by L4(2)) that $a_j = b_j \quad \forall j \in \{1, \ldots, n\}$.

It follows that $A = B$, as needed. ■

L_A IS A LINEAR TRANSFORMATION (T2.9)

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.

Then $L_A : \mathbb{F}^n \to \mathbb{F}^m$ is necessarily a linear transformation.

Proof. We prove $L_A(cx+y) = cL_A(x) + L_A(y) \quad \forall x, y \in \mathbb{F}^n$ & $c \in \mathbb{F}$; the result follows from P2.

Write $x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$ and $y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$, and $A = (a_1 \ a_2 \ \cdots \ a_n)$.

Then

$$\begin{aligned} L_A(cx+y) &= A(cx+y) \\ &= (cx_1+y_1)a_1 + (cx_2+y_2)a_2 + \cdots + (cx_n+y_n)a_n \quad \text{(by L4(1))} \\ &= c(x_1a_1 + \cdots + x_na_n) + (y_1a_1 + \cdots + y_na_n) \\ &= c(Ax) + Ay \end{aligned}$$

$\therefore L_A(cx+y) = cL_A(x) + L_A(y)$, as needed. ■

$L : M_{m\times n}(\mathbb{F}) \to \mathcal{L}(\mathbb{F}^n, \mathbb{F}^m)$ BY $L(A) = L_A$ IS A 1-1 LINEAR TRANSFORMATION (P4)

Let $L : M_{m\times n}(\mathbb{F}) \to \mathcal{L}(\mathbb{F}^n, \mathbb{F}^m)$ by $L(A) = L_A \quad \forall A \in M_{m\times n}(\mathbb{F})$, where $\mathbb{F}$ is a field.

Then L is necessarily a one-to-one linear transformation.

Proof. We first show L is linear.

By P2, we just need to show $L(cA+B) = cL(A) + L(B)$ $\forall A, B \in M_{m\times n}(\mathbb{F})$, $c \in \mathbb{F}$; ie $L_{cA+B} = cL_A + L_B$.

To do this, let $x \in \mathbb{F}^n$ be arbitrary.

Write $A = (a_1 \ a_2 \ \cdots \ a_n)$ and $B = (b_1 \ b_2 \ \cdots \ b_n)$, so that $cA + B = (ca_1+b_1 \ \ ca_2+b_2 \ \cdots \ ca_n+b_n)$.

So

$$\begin{aligned} L_{cA+B}(x) &= (cA+B)x \\ &= x_1(ca_1+b_1) + x_2(ca_2+b_2) + \cdots + x_n(ca_n+b_n) \quad \text{(by L4(1))} \\ &= c(x_1a_1 + \cdots + x_na_n) + (x_1b_1 + \cdots + x_nb_n) \\ &= c(Ax) + Bx \\ &= cL_A(x) + L_B(x) \end{aligned}$$

$\therefore L_{cA+B}(x) = (cL_A + L_B)(x)$,

and since $x \in \mathbb{F}^n$ was arbitrary this is sufficient to prove $L_{cA+B} = cL_A + L_B$, as needed. ※

Next, we prove L is 1-1.

Assume for some $A, B \in M_{m\times n}(\mathbb{F})$, we have $L_A = L_B$.

This means $L_A(x) = L_B(x) \quad \forall x \in \mathbb{F}^n$, or $Ax = Bx \quad \forall x \in \mathbb{F}^n$.

So by the Matrix Equality Theorem, $A = B$, which is sufficient to prove L is 1-1. ■

COORDINATES (S2.2)

ORDERED BASIS (D24)

Let V be a vector space with $\dim V < \infty$.
Then, an "ordered basis" for V is a basis $\{v_1, \dots, v_n\}$ with a total order.

eg $\{e_1, e_2, e_3\}$ is the standard ordered basis for $\mathbb{F}^3$, since we can define a "total order" by saying the indexes must be in "increasing order" (E30(1))

COORDINATE VECTOR (D25)

Let $\beta = \{u_1, \dots, u_n\}$ be an "ordered basis" for a finite-dimensional vector space V.
By T1.6, we can write any $x \in V$ in the form $x = \sum_{k=1}^{n} a_k u_k$, where $a_1, \dots, a_n \in \mathbb{F}$.
Then, we define the "coordinate vector" of x relative to β, denoted as "$[x]_\beta$", to be

$$[x]_\beta := \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} \in \mathbb{F}^n.$$

eg for $V = P_2(\mathbb{R})$, $\beta = \{1, x, x^2\}$, $p(x) = 2 - 3x + 4x^2 \in V$,
$[p(x)]_\beta = \begin{pmatrix} 2 \\ -3 \\ 4 \end{pmatrix}$.

$[\ ]_\beta : V \to \mathbb{F}^n$ IS AN ISOMORPHISM (T2.10)

Let V be a vector space over some field $\mathbb{F}$, with $\dim V = n$, and let β be an ordered basis for V.
Then, the map $[\ ]_\beta : V \to \mathbb{F}^n$ is an isomorphism.

MATRIX REPRESENTATION OF LINEAR TRANSFORMATIONS (S2.3)

Let V and W be finite-dimensional vector spaces over $\mathbb{F}$, and let $T: V \to W$ be a linear transformation.

Let $\beta = \{v_1, \dots, v_n\}$ be an ordered basis for V, and let $\gamma = \{w_1, \dots, w_m\}$ be an ordered basis for W.

Then, the "matrix representation" of T in the ordered bases β and γ, denoted as $[T]_\beta^\gamma$, is defined as the matrix

$$[T]_\beta^\gamma := \left([T(v_1)]_\gamma \ [T(v_2)]_\gamma \ \cdots \ [T(v_n)]_\gamma\right).$$

In particular, if $T: V \to V$ is linear and β is an ordered basis of the finite-dimensional vector space V, we denote

$$[T]_\beta := [T]_\beta^\beta.$$

Note that $[T]_\beta^\gamma \in M_{m\times n}(\mathbb{F})$, where $m = \dim W$ and $n = \dim V$. (R12 (1))

Also, we have

$$T(v_j) = \sum_{k=1}^{m} a_{kj} w_k,$$

where a_{kj} denotes the element at the k^{th} row and j^{th} column in the matrix $[T]_\beta^\gamma$. (R12 (2))

eg If $T: P_2(\mathbb{R}) \to \mathbb{R}^2$ by $T(a+bx+cx^2) = \begin{pmatrix} a \\ b+4c \end{pmatrix}$, we can verify T is linear.

Let $\beta = \{1, (x+1), (x+1)^2\}$ and $\gamma = \left\{\begin{pmatrix}1\\1\end{pmatrix}, \begin{pmatrix}1\\-1\end{pmatrix}\right\}$.

Then

$$[T]_\beta^\gamma = \left([T(1)]_\gamma \ [T(x+1)]_\gamma \ [T(x+1)^2]_\gamma\right)$$

$$= \begin{pmatrix} 1 & 1 & 1 \\ 0+4(0) & 1+4(0) & 2+4(1) \end{pmatrix}$$

$$\therefore [T]_\beta^\gamma = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 6 \end{pmatrix}. \quad \text{(E32)}$$

$[L_A]_\beta^\gamma = A$ (E33)

Let $A \in M_{m\times n}(\mathbb{F})$, where $\mathbb{F}$ is a field.

Let β be the standard ordered basis for $\mathbb{F}^n$, and γ the standard ordered basis for $\mathbb{F}^m$.

Then necessarily $[L_A]_\beta^\gamma = A$.

$[T(x)]_\gamma = [T]_\beta^\gamma \cdot [x]_\beta$ (T2.11)

Let $T: V \to W$ be linear, and let $\beta = \{v_1, \dots, v_n\}$ and $\gamma = \{w_1, \dots, w_m\}$ be ordered bases of V and W respectively.

Then necessarily $[T(x)]_\gamma = [T]_\beta^\gamma \cdot [x]_\beta \quad \forall x \in V$.

Proof. Let $x \in V$ be arbitrary. Take $x = \sum_{k=1}^{n} a_k v_k$, where $[x]_\beta = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$.

Then, since T is linear,

$$T(x) = T\left(\sum_{k=1}^{n} a_k v_k\right) = \sum_{k=1}^{n} a_k T(v_k).$$

Thus

$$[T(x)]_\gamma = \left[\sum_{k=1}^{n} a_k T(v_k)\right] = \sum_{k=1}^{n} a_k [T(v_k)]_\gamma. \quad \text{(by linearity of } [\ ]_\gamma \text{ (T2.10))}$$

Note that

$$\sum_{k=1}^{n} a_k [T(v_k)]_\gamma = \left([T(v_1)]_\gamma \ [T(v_2)]_\gamma \cdots [T(v_n)]_\gamma\right)\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$$

$$= [T]_\gamma^\beta \cdot [x]_\beta,$$

so that

$$[T(x)]_\gamma = [T]_\gamma^\beta \cdot [x]_\beta, \quad \text{as needed. } ▨$$

$[\ ]_\beta^\gamma : \mathcal{L}(V, W) \to M_{m\times n}(\mathbb{F})$ IS AN ISOMORPHISM (P5)

Let V and W be finite-dimensional vector spaces over $\mathbb{F}$, and let β and γ be ordered bases of V and W respectively.

Then the map $[\ ]_\beta^\gamma : \mathcal{L}(V,W) \to M_{m\times n}(\mathbb{F})$ is an isomorphism, where $m = \dim W$ and $n = \dim V$; in other words,

① For any $T, U \in \mathcal{L}(V, W)$ and $c \in \mathbb{F}$, we have that $[cT+U]_\beta^\gamma = c[T]_\beta^\gamma + [U]_\beta^\gamma$; and

② For any $C \in M_{m\times n}(\mathbb{F})$, there exists a unique $T \in \mathcal{L}(V,W)$ such that $[T]_\beta^\gamma = C$.

Proof. We first prove ①.

Let $\beta = \{v_1, \dots, v_n\}$. Then

$$[T+U]_\beta^\gamma = \left([(T+U)(v_1)]_\gamma \ [(T+U)(v_2)]_\gamma \ \cdots \ [(T+U)(v_n)]_\gamma\right)$$

$$= \left([T(v_1)+U(v_1)]_\gamma \ [T(v_2)+U(v_2)]_\gamma \ \cdots \ [T(v_n)+U(v_n)]_\gamma\right)$$

$$= \left(([T(v_1)]_\gamma + [U(v_1)]_\gamma) \ ([T(v_2)]_\gamma + [U(v_2)]_\gamma) \ \cdots \ ([T(v_n)]_\gamma + [U(v_n)]_\gamma)\right)$$

$$= \left([T(v_1)]_\gamma \ [T(v_2)]_\gamma \ \cdots \ [T(v_n)]_\gamma\right) + \left([U(v_1)]_\gamma \ [U(v_2)]_\gamma \ \cdots \ [U(v_n)]_\gamma\right)$$

$$\therefore [T+U]_\beta^\gamma = [T]_\beta^\gamma + [U]_\beta^\gamma,$$

and a similar proof shows $[cT]_\beta^\gamma = c[T]_\beta^\gamma$, which is sufficient to show $[cT+U]_\beta^\gamma = c[T]_\beta^\gamma + [U]_\beta^\gamma$, and hence that the map $[\ ]_\beta^\gamma : \mathcal{L}(V,W) \to M_{m\times n}$ is linear. ✻

We next prove ②.

Suppose $[T]_\beta^\gamma = [U]_\beta^\gamma$, so that $[T]_\beta^\gamma$ and $[U]_\beta^\gamma$ have the same j^{th} column $\forall j \in \{1, \dots, n\}$.

This means $[T(v_j)]_\gamma = [U(v_j)]_\gamma$, and since $[\ ]_\gamma : W \to \mathbb{F}^n$ is a bijection (by T2.10) it follows that $T(v_j) = U(v_j) \quad \forall j \in \{1, 2, \dots, n\}$.

So, by T2.1, $T = U$, proving injectivity.

Then, let $C = (c_1 \ c_2 \ \cdots \ c_n) \in M_{m\times n}(\mathbb{F})$ be arbitrary.

For each $j \in \{1, \dots, n\}$, let $w_j \in W$ be the unique vector satisfying $[w_j]_\gamma = c_j$.

By T2.10, there exists a unique linear transformation $T: V \to W$ satisfying $T(v_j) = w_j \quad \forall j \in \{1, \dots, n\}$; it follows this T satisfies $[T]_\beta^\gamma = C$, proving surjectivity, so we are done. ▨

$L : M_{m\times n}(\mathbb{F}) \to \mathcal{L}(\mathbb{F}^n, \mathbb{F}^m)$ IS AN ISOMORPHISM (C2.11.1)

Recall that the map $L : M_{m\times n}(\mathbb{F}) \to \mathcal{L}(\mathbb{F}^n, \mathbb{F}^m)$ is defined by $L(A) = L_A \quad \forall A \in M_{m\times n}(\mathbb{F})$.

Then, L is necessarily an isomorphism.

Proof. We know L is already 1-1 & linear by P4, so we only need to prove it is onto.

Applying P5 to $V = \mathbb{F}^n$ & $W = \mathbb{F}^m$, we get that $\mathcal{L}(\mathbb{F}^n, \mathbb{F}^m) \cong M_{m\times n}(\mathbb{F})$, so that $\dim(\mathcal{L}(\mathbb{F}^n, \mathbb{F}^m)) = \dim(M_{m\times n}(\mathbb{F})) = mn$ (by T2.6).

So L is a 1-1 linear transformation between vector spaces of the same finite dimension; it follows by T2.7 that L is onto. ▨

MATRIX MULTIPLICATION & COMPOSITIONS OF LINEAR TRANSFORMATIONS (S2.4)

MATRIX PRODUCT (D27)

1. Let $\mathbb{F}$ be a field, and let $A \in M_{m\times n}(\mathbb{F})$ and $B \in M_{n\times p}(\mathbb{F})$ be arbitrary.

Note the number of columns in A equals the number of rows in B; this is required.

Then, the matrix product of A and B, denoted by AB, is defined to be the $m\times p$ matrix

$$AB = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & & \ddots & \\ a_{m1} & a_{m2} & & a_{mn} \end{pmatrix}\begin{pmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \\ b_{n1} & b_{n2} & & b_{np} \end{pmatrix}$$

$$= \begin{pmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \\ c_{m1} & c_{m2} & & c_{mp} \end{pmatrix},$$

where $c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj} = \sum_{t=1}^{n} a_{it}b_{tj}$.

In other words, c_{ij} is the sum of products formed multiplying the entries in the i^{th} row of A with the j^{th} column of B.

*an example is highlighted in blue;

$c_{21} = a_{21}b_{11} + a_{22}b_{21} + \cdots + a_{2n}b_{n1}$.

2. Note that c_j is the linear combination of the columns of A formed using the entries in the j^{th} column of B as coefficients. (R13(3))

ZERO MATRIX

The "zero matrix", denoted by the letter O, is defined to be the matrix with each entry being zero.

We write "$O_{m\times n}$" to denote the $m\times n$ zero matrix.

IDENTITY MATRIX

The "$n\times n$ identity matrix", denoted as I_n, is defined as the matrix (δ_{ij}) with

$$\delta_{ij} = \begin{cases} 1, & i=j \\ 0, & i\neq j. \end{cases}$$

*δ_{ij} is known as the "Kronecker delta".

eg $I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$.

RIGHT MATRIX DISTRIBUTIVE LAW (L5(1))

For any $A \in M_{m\times n}(\mathbb{F})$ and $B, C \in M_{n\times p}(\mathbb{F})$, we have

$A(B+C) = AB + AC$.

LEFT MATRIX DISTRIBUTIVE LAW (L5(2))

Similarly, for any $A \in M_{m\times n}(\mathbb{F})$ and $D, E \in M_{q\times m}(\mathbb{F})$, we have

$(D+E)A = DA + EA$.

ASSOCIATIVITY OF MATRIX SCALAR MULTIPLICATION (L5(3))

For any $\alpha \in \mathbb{F}$, $A \in M_{m\times n}(\mathbb{F})$ and $B \in M_{q\times m}(\mathbb{F})$, we have

$\alpha(AB) = (\alpha A)B = A(\alpha B)$.

$(AB)^T = B^T A^T$ (L5(4))

For any $A \in M_{m\times m}(\mathbb{F})$ and $B \in M_{n\times n}(\mathbb{F})$, we have

$(AB)^T = B^T A^T$.

$I_m A = A I_n$ (L5(5))

For any $A \in M_{m\times n}(\mathbb{F})$, we have that

$I_m A = A I_n = A$.

$AO_{n\times p} = O_{m\times p}$, $O_{q\times m}A = O_{q\times n}$ (L5(6))

For any $A \in M_{m\times n}(\mathbb{F})$, we have

① $AO_{n\times p} = O_{m\times p}$; and

② $O_{q\times m}A = O_{q\times n}$.

COMPOSITION OF LINEAR TRANSFORMATIONS IS ALSO A LINEAR TRANSFORMATION (T2.12)

Let $T: V\to W$ and $U: W\to Z$ be linear transformations.

Then the composition $(U\circ T): V\to Z$ is also a linear transformation.

*we usually denote $(U\circ T)$ as UT.

MATRIX OF COMPOSITION OF LINEAR TRANSFORMATIONS (T2.13)

Let V, W and Z be finite-dimensional vector spaces having ordered bases $\alpha = \{v_1, \dots, v_p\}$, $\beta = \{w_1, \dots, w_n\}$ and $\gamma = \{z_1, \dots, z_m\}$ respectively.

Let $T: V\to W$ and $U: W\to Z$ be linear transformations.

Denote $A = [U]_\beta^\gamma \in M_{m\times n}(\mathbb{F})$, $B = [T]_\alpha^\beta \in M_{n\times p}(\mathbb{F})$ and $C = [UT]_\alpha^\gamma \in M_{m\times p}(\mathbb{F})$.

Then necessarily $C = AB$; ie $[UT]_\alpha^\gamma = [U]_\beta^\gamma \cdot [T]_\alpha^\beta$.

Proof. Note that both sides are $m\times p$ matrices.

We show that the j^{th} columns of the LHS & RHS are equal $\forall j \in \{1, \dots, p\}$.

On one hand, the j^{th} column of $[UT]_\alpha^\gamma$ is $[(UT)(v_j)]_\gamma$.

On the other hand, $[T]_\alpha^\beta = B = (b_1\ b_2 \cdots b_p)$.

Hence, the j^{th} column of $[U]_\beta^\gamma \cdot [T]_\alpha^\beta$ is $[U]_\beta^\gamma \cdot b_j$, which equals

$$\begin{aligned} [U]_\beta^\gamma \cdot b_j &= [U]_\beta^\gamma \cdot [T(v_j)]_\beta \\ &= [U(T(v_j))]_\gamma \quad (\text{by T2.11}) \\ &= [(UT)(v_j)]_\gamma. \end{aligned}$$

It follows that $[UT]_\alpha^\gamma$ and $[U]_\beta^\gamma \cdot [T]_\alpha^\beta$ have the same j^{th} columns; since j was arbitrary, it follows that $[UT]_\alpha^\gamma = [U]_\beta^\gamma \cdot [T]_\alpha^\beta$, as needed. ☒

$L_{AB} = L_A L_B$ (C2.13.1(1))

Let $A \in M_{m\times n}(\mathbb{F})$ and $B = M_{n\times p}(\mathbb{F})$ be arbitrary.

Then necessarily $L_{AB} = L_A L_B$.

Proof. Let α, β & γ denote the standard ordered bases for $\mathbb{F}^p$, $\mathbb{F}^n$ and $\mathbb{F}^m$ respectively.

By E33, $[L_A]_\beta^\gamma = A$, $[L_B]_\alpha^\beta = B$ and $[L_{AB}]_\alpha^\gamma = AB$.

On the other hand

$[L_A L_B]_\alpha^\gamma = [L_A]_\beta^\gamma \cdot [L_B]_\alpha^\beta = AB = [L_{AB}]_\alpha^\gamma$ (by T2.13).

Since the mapping $[\ ]_\alpha^\gamma$ is 1-1 (by C2.11.1), it follows that $L_A L_B = L_{AB}$, as needed. ☒

$A(BC) = (AB)C$ (C2.13.1(2))

Assume the matrix product "$A(BC)$" is defined.

Then necessarily $A(BC) = (AB)C$.

Proof. By C2.13.1(1), we get that

$L_{A(BC)} = L_A L_{BC} = L_A(L_B L_C) = (L_A L_B)L_C = L_{AB}L_C = L_{(AB)C}$,

since function composition is associative.

Then, as L is 1-1 (by P4), it follows that $A(BC) = (AB)C$, as needed. ☒

INVERTIBILITY & ISOMORPHISMS (S2.5)

INVERTIBLE MATRICES (D28)

Let $A \in M_{n\times n}(\mathbb{F})$ be arbitrary.
Then, we say A is "invertible" if there exists a matrix $B \in M_{n\times n}(\mathbb{F})$ such that $AB = BA = I_n$.

Note that if such a matrix B exists, it is uniquely determined by A.

Proof. Suppose $B, C \in M_{n\times n}(\mathbb{F})$ are such that $AB = BA = I_n$ & $AC = CA = I_n$.
Then
$$B = BI_n = B(AC) = (BA)C = I_nC = C,$$
proving uniqueness. ☒

INVERSE MATRICES (D28)

Let $A \in M_{n\times n}(\mathbb{F})$ be an invertible square matrix.
Then the "inverse" of A, denoted as "A^{-1}", is the unique $n\times n$ square matrix such that $AA^{-1} = A^{-1}A = I_n$.

INVERTIBLE MAPPING (D29)

Let $T: V \to W$ be a linear mapping between two vector spaces V and W.
Then, we say T is "invertible" if there exists a function $U: W \to V$ such that $UT = I_V$ and $TU = I_W$.

INVERSE MAPPING (D29)

Let $T: V \to W$ be an invertible linear mapping.
Then the "inverse" of T, denoted as "T^{-1}", is the mapping $T^{-1}: W \to V$ such that $TT^{-1} = I_V$ and $T^{-1}T = I_W$.

Similarly, we can show T^{-1} is unique. (T2.14(1))

Proof. Suppose there exist $U_1, U_2: W \to V$ such that $U_1T = I_V$, $TU_1 = I_W$, $U_2T = I_V$ & $TU_2 = I_W$.
Then
$$U_1 = U_1I_W = U_1(TU_2) = (U_1T)U_2 = I_VU_2 = U_2,$$
proving uniqueness. ☒

T IS LINEAR & INVERTIBLE ⇒ T IS AN ISOMORPHISM (T2.14(2))

Let $T: V \to W$ be linear and invertible.
Then T is necessarily an isomorphism.

Proof. Suppose $x, y \in V$ are such that $T(x) = T(y)$.
Then observe that
$$x = (T^{-1}T)(x) = T^{-1}(T(x)) = T^{-1}(T(y)) = y,$$
proving injectivity.
Then, let $z \in W$. Since $TT^{-1} = I_W$, we have that
$$z = I_W(z) = (TT^{-1})(z) = T(T^{-1}(z)).$$
Since $T^{-1}(z) \in V$, it follows that T is surjective.
Hence T is bijective, and since T is also linear, it follows that T is an isomorphism. ☒

T^{-1} IS ALSO LINEAR (T2.14(3))

Let $T: V \to W$ be linear and invertible.
Then T^{-1} is necessarily also linear.

Proof. Let $y_1, y_2 \in V$ and $c \in \mathbb{F}$ be arbitrary.
Since T is bijective (by T2.14(2)), there exist unique $x_1, x_2 \in V$ such that $T(x_1) = y_1$ and $T(x_2) = y_2$.
Then
$$T^{-1}(cy_1 + y_2) = T^{-1}(cT(x_1) + T(x_2)) = T^{-1}(T(cx_1 + x_2))$$
$$= cx_1 + x_2 = cT^{-1}(y_1) + T^{-1}(y_2),$$
and it follows from P2 that T^{-1} is linear. ☒

T IS AN ISOMORPHISM ⇔ $[T]_\alpha^\beta$ IS INVERTIBLE (T2.15(1))

Let V and W be finite-dimensional vector spaces, and let α and β be (ordered) bases of V and W respectively.
Let $T: V \to W$ be linear.
Then T is an isomorphism if and only if $[T]_\alpha^\beta$ is an invertible matrix.

Proof. (⇒) Suppose T is an isomorphism, so that $V \cong W$.
Then, by T2.6, $\dim V = \dim W = n$.
Let $A := [T]_\alpha^\beta$. By the above, A is a $n\times n$ square matrix.
By T2.14(3), $T^{-1}: W \to V$ is also linear.
Let $B := [T^{-1}]_\beta^\alpha$, which is also a $n\times n$ matrix.
Also,
$$AB = [T]_\alpha^\beta[T^{-1}]_\beta^\alpha = [TT^{-1}]_\beta^\beta \quad (T2.12)$$
$$= [I_W]_\beta^\beta$$
$$= I_n.$$
A similar proof shows $BA = [I_V]_\alpha^\alpha = I_n$. So, by D28, A is an invertible matrix, proving the forward argument.

(⇐) Suppose $A = [T]_\alpha^\beta$ is an invertible matrix with inverse A^{-1}.
In particular, A must be square, say $n\times n$, so $\dim V = \dim W = n$.
Then, let $x, y \in V$ such that $T(x) = T(y)$. By T2.11,
$$A[x]_\alpha = [T]_\alpha^\beta[x]_\alpha = [T(x)]_\beta = [T(y)]_\beta = [T]_\alpha^\beta[y]_\alpha = A[y]_\alpha.$$
Thus $A[x]_\alpha = A[y]_\alpha$. It follows that
$$A^{-1}(A[x]_\alpha) = A^{-1}(A[y]_\alpha),$$
or $[x]_\alpha = [y]_\alpha$ and so $x = y$, proving injectivity.
Then, as T is linear and $\dim V = \dim W$, by T2.7 T is also onto.
Hence T is bijective, and since T is also linear, it follows that T is an isomorphism, proving the backward argument. ☒

In particular, if T is an isomorphism, then
$$[T^{-1}]_\beta^\alpha = ([T]_\alpha^\beta)^{-1}.$$

$A \in M_{n\times n}(\mathbb{F}) \Rightarrow$ (L_A IS AN ISOMORPHISM ⇔ A IS INVERTIBLE) (T2.15(2))

Let V and W be finite-dimensional vector spaces, and let α and β be ordered bases of V and W respectively.
Then for any $A \in M_{n\times n}(\mathbb{F})$, necessarily L_A is an isomorphism if and only if A is invertible.

Proof. By T2.15(1), L_A is an isomorphism if and only if $[L_A]_{\sigma_n}^{\sigma_n}$ is invertible, where σ_n is the standard ordered basis for $\mathbb{F}^n$.
By E33, $[L_A]_{\sigma_n}^{\sigma_n} = A$, and this is sufficient to prove the claim. ☒

A IS INVERTIBLE ⟹ A^{-1} IS INVERTIBLE & $(A^{-1})^{-1} = A$ (L6(1))

Let A be an invertible matrix.
Then A^{-1} is also invertible, and $(A^{-1})^{-1} = A$.

Proof. Since A is invertible, A^{-1} exists.
In particular, $A^{-1}A = I_n$.
By uniqueness of matrix inverses, it follows that $A = (A^{-1})^{-1}$, as needed. ☒

$(cA)^{-1} = \frac{1}{c}A^{-1}$ (L6(2))

Let A be an invertible matrix, and let $c \in \mathbb{F}$.
Then necessarily $(cA)^{-1} = \frac{1}{c}A^{-1}$.

$(A^T)^{-1} = (A^{-1})^T$ (L6(3))

Let A be an invertible matrix.
Then necessarily $(A^T)^{-1} = (A^{-1})^T$.

$(AB)^{-1} = B^{-1}A^{-1}$ (L6(4))

Let $A, B \in M_{n\times n}(\mathbb{F})$ be invertible matrices.
Then AB is also invertible, and necessarily $(AB)^{-1} = B^{-1}A^{-1}$.

Proof. $(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AI_nA^{-1} = AA^{-1} = I_n$.
By uniqueness of matrix inverses, it follows that $(AB)^{-1} = B^{-1}A^{-1}$. ☒

AB IS INVERTIBLE ⟹ A & B ARE INVERTIBLE (L6(5))

Let $A, B \in M_{n\times n}(\mathbb{F})$ be such that AB is invertible.
Then necessarily A and B are also invertible matrices.

Proof. By T2.15, L_{AB} is invertible. By T2.14, $L_A L_B$ is an isomorphism.
Thus, $L_A L_B$ is 1-1 and onto. Thus L_A is surjective and L_B is injective.
Then, as L_A and L_B are both linear mappings from $\mathbb{F}^n$ to itself, by T2.7 L_A and L_B are isomorphisms.
Hence A and B are invertible by T2.15(2), and we are done. ☒

INVERSE MATRIX THEOREM, PART I (T2.16)

Let $A \in M_{n\times n}(\mathbb{F})$. Then the following statements are equivalent:

① A is invertible;
② There exists a matrix $C \in M_{n\times n}(\mathbb{F})$ such that $AC = I_n$;
and
③ There exists a matrix $B \in M_{n\times n}(\mathbb{F})$ such that $BA = I_n$.

Proof. This follows directly from the definition of inverse matrices. ☒

THE CHANGE OF COORDINATE MATRIX (S2.6)

CHANGE OF COORDINATE MATRIX FROM α TO β (T2.17(1))

Let α and β be two ordered bases for a finite-dimensional vector space V.
Then the "change of coordinate matrix from α to β" is the matrix

$$Q = [I_V]_\alpha^\beta.$$

The matrix $Q = [I_V]_\alpha^\beta$ is necessarily invertible.

Proof. Since I_V is an isomorphism, by T2.15, Q is necessarily invertible. ☒

Also, note that if we let $\alpha = \{v_1, \dots, v_n\}$ and $\beta = \{w_1, \dots, w_n\}$ and fix an $x \in V$, then

$$[I_V]_\alpha^\beta = ([v_1]_\beta \;\cdots\; [v_n]_\beta).$$

Then, by comparing the j^{th} column on both sides, we have that

$$v_j = \sum_{i=1}^{n} Q_{ij} w_i. \qquad (R15)$$

$[x]_\beta = Q[x]_\alpha$ (T2.17(2))

Let α and β be two ordered bases of the finite-dimensional vector space V.
Let $Q = [I_V]_\alpha^\beta$ be the change of coordinate matrix from α to β.
Then necessarily for any $x \in V$, we have $[x]_\beta = Q[x]_\alpha$.

Proof. By T2.11, we have
$$[x]_\beta = [I_V(x)]_\beta = [I_V]_\alpha^\beta [x]_\alpha = Q[x]_\alpha,$$
as needed. ☒

$T: V \to V$; $[T]_\alpha = Q^{-1}[T]_\beta Q$ (T2.18)

Let $T: V \to V$ be linear, where V is a finite-dimensional vector space.
Let α and β be two ordered bases of V, and let $Q = [I_V]_\alpha^\beta$.
Then necessarily $[T]_\alpha = Q^{-1}[T]_\beta Q$.

Proof. By T2.13, we have
$$Q[T]_\alpha = [I_V]_\alpha^\beta [T]_\alpha^\alpha = [I_V T]_\alpha^\beta = [T]_\alpha^\beta,$$
and
$$[T]_\beta Q = [T]_\beta^\beta [I_V]_\alpha^\beta = [TI_V]_\alpha^\beta = [T]_\alpha^\beta,$$
showing $[T]_\beta Q = Q[T]_\alpha$.
Then, since Q is invertible, Q^{-1} exists; hence
$$Q^{-1}[T]_\beta Q = Q^{-1}Q[T]_\alpha = [T]_\alpha,$$
as needed. ☒

SIMILAR MATRICES (D30)

Let $A, B \in M_{n\times n}(\mathbb{F})$ be arbitrary.
Then, we say B is "similar" to A if there exists an invertible matrix Q such that
$B = Q^{-1}AQ$.

Chapter 3: Elementary Matrix Operations and Systems of Linear Equations

ELEMENTARY MATRIX OPERATIONS & ELEMENTARY MATRICES (S3.1)

ELEMENTARY ROW/COLUMN OPERATIONS (D31)

Let $A \in M_{m\times n}(\mathbb{F})$. Then, we denote the following as "elementary row/column operations" on A:

① Interchanging any two rows/columns of A, denoted as "$R_i \leftrightarrow R_j$";

eg $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{pmatrix} 7 & 8 & 9 \\ 4 & 5 & 6 \\ 1 & 2 & 3 \end{pmatrix}$

② Multiplying any row/column by a non-zero scalar, denoted as "$R_i \leftarrow cR_i$"; and

eg $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \xrightarrow{R_2 \leftarrow 2R_2} \begin{pmatrix} 1 & 2 & 3 \\ 8 & 10 & 12 \\ 7 & 8 & 9 \end{pmatrix}$

③ Adding any scalar multiple of a row/column of A to another row/column, denoted as "$R_i \leftarrow R_i + cR_j$".

eg $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \xrightarrow{R_2 \leftarrow R_2 + 2R_1} \begin{pmatrix} 1 & 2 & 3 \\ 6 & 9 & 12 \\ 7 & 8 & 9 \end{pmatrix}$

nxn ELEMENTARY MATRIX (D32)

1. An "nxn elementary matrix" is a matrix obtained by performing an elementary operation on I_n.

eg performing "$R_3 \leftarrow R_3 + 4R_1$" on I_3 results in

$$I' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 4 & 0 & 1 \end{pmatrix}. \quad (E39)$$

2. Let $A \in M_{m\times n}(\mathbb{F})$, and suppose B is obtained from A by performing an elementary row operation. Then necessarily $B = \underline{E}A$, where E is the nxn elementary matrix obtained from I_n by performing the said elementary row/column operation. (T3.1)

3. Conversely, if E is an mxm elementary matrix, then $\underline{E}A$ is the matrix obtained from A by performing the same elementary row operation as that which produces E from I_m. (T3.1)

* a similar result holds for elementary matrices formed by performing an elementary column operation, but in this case $B = A\underline{E}$. (T3.2)

Proof. This can be proven by verifying each of the three elementary row/column operations "holds" under this transformation.

ELEMENTARY MATRICES ARE INVERTIBLE, & THE INVERSE OF AN ELEMENTARY MATRIX IS OF THE SAME "TYPE" (T3.3)

Note that any elementary matrix $A \in M_{m\times m}(\mathbb{F})$ is invertible, and A^{-1} is also an elementary matrix with the same "type" as A.

Proof. Suppose A is an elementary matrix obtained from I_m. Then, we verify this theorem for each of the three operations;

① $R_i \leftrightarrow R_j$;

② $R_i \leftarrow c \cdot R_i$; and

③ $R_i \leftarrow$

THE RANK OF A MATRIX & MATRIX INVERSES (S3.2)

RANK OF A MATRIX (D33)

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.
Then, we define the "rank" of A, denoted as "rank(A)", to be the rank of the linear transformation $L_A : \mathbb{F}^n \to \mathbb{F}^m$ by $L_A(x) = Ax \ \forall x \in \mathbb{F}^n$.
In other words,
$\text{rank}(A) = \dim(R(L_A)) = \dim(L_A(\mathbb{F}^n))$.

Note that
① $\text{rank}(I_n) = \dim(R(I_n)) = \dim(\mathbb{F}^n) = n$; and
② $\text{rank}(O) = \dim(R(O)) = \dim(\{0\}) = 0$. (E40)
(where O denotes the zero matrix)

$\text{rank}(A) = \dim(\text{span}(\{a_1, \dots, a_n\}))$ (R16 (1))

For any matrix $A \in M_{m\times n}(\mathbb{F})$, we have
$\text{rank}(A) = \dim(\text{span}(\{a_1, \dots, a_n\}))$,
where a_j denotes the j^{th} column of A.

Proof. Let $\{e_1, \dots, e_n\}$ be the standard (ordered) basis for $\mathbb{F}^n$. Then
$R(L_A) = \text{span}(\{L_A(e_1), \dots, L_A(e_n)\})$ (by T2.3)
$= \text{span}(\{Ae_1, \dots, Ae_n\})$
$\therefore R(L_A) = \text{span}(\{a_1, \dots, a_n\})$ (by L4),
so that $\dim(R(L_A)) = \text{rank}(A) = \dim(\text{span}(\{a_1, \dots, a_n\}))$, as needed. ▣

$\text{rank}(A) \leq \min(m, n)$ (R16 (2))

Moreover, for any matrix $A \in M_{m\times n}(\mathbb{F})$, we have that $\text{rank}(A) \leq \min(m, n)$.

Proof. Since $\{a_1, \dots, a_n\}$ generates $R(L_A)$ by the above, and since any finite spanning set for $R(L_A)$ contains at least $\dim(R(L_A)) = \text{rank}(A)$ vectors, by C1.9.2 we must have that $n \geq \text{rank}(A)$.
Then, since $R(L_A)$ is a subspace of $\mathbb{F}^m$, by C1.9.2 $\text{rank}(A) = \dim(R(L_A)) \leq \dim(\mathbb{F}^m) = m$.
Hence $\text{rank}(A) \leq \min(m, n)$, as required. ▣

$T: V \to W$ IS 1-1 & LINEAR, V_0 IS A SUBSPACE OF V $\Rightarrow$ $T(V_0)$ IS A SUBSPACE OF W (L9(1))

Let $T: V \to W$ be a linear injective mapping between vector spaces V and W.
Let V_0 be a subspace of V.
Then necessarily $T(V_0) = \{T(v) : v \in V_0\}$ is a subspace of W.

$T: V \to W$ IS 1-1 & LINEAR, V_0 IS A SUBSPACE OF V, $\dim(V_0) < \infty$ $\Rightarrow$ $\dim(V_0) = \dim(T(V_0))$ (L9(2))

Let $T: V \to W$ be a linear injective mapping between vector spaces V and W.
Let V_0 be a finite-dimensional subspace of V.
Then necessarily $\dim(V_0) = \dim(T(V_0))$.

$\text{rank}(AQ) = \text{rank}(A)$ (T3.4 (1))

Let $A \in M_{m\times n}(\mathbb{F})$, and let $Q \in M_{n\times n}(\mathbb{F})$ be an invertible matrix.
Then necessarily $\text{rank}(AQ) = \text{rank}(A)$.

Proof. Since Q is invertible, L_Q is necessarily an isomorphism.
Thus $L_Q(\mathbb{F}^n) = \mathbb{F}^n$, and so
$L_{AQ}(\mathbb{F}^n) = L_A L_Q(\mathbb{F}^n) = L_A(\mathbb{F}^n)$.
It follows that
$\text{rank}(AQ) = \dim(L_{AQ}(\mathbb{F}^n)) = \dim(L_A(\mathbb{F}^n)) = \text{rank}(A)$,
as required. ▣

$\text{rank}(PA) = \text{rank}(A)$ (T3.4(2))

Let $A \in M_{m\times n}$, and let $P \in M_{m\times m}(\mathbb{F})$ be an invertible matrix.
Then necessarily $\text{rank}(PA) = \text{rank}(A)$.

Proof. Since P is invertible, L_P is an isomorphism.
So, by L9, using $T = L_P$, $V = W = \mathbb{F}^n$ and $V_0 = L_A(\mathbb{F}^n)$, we have
$\dim(L_A(\mathbb{F}^n)) = \dim(L_P(L_A(\mathbb{F}^n)))$
$\Rightarrow \text{rank}(A) = \dim(L_{PA}(\mathbb{F}^n))$
$\Rightarrow \text{rank}(A) = \text{rank}(PA)$, as needed. ▣

$\text{rank}(PAQ) = \text{rank}(A)$ (T3.4 (3))

Let $A \in M_{m\times n}(\mathbb{F})$, and let $P \in M_{m\times m}(\mathbb{F})$ and $Q \in M_{n\times n}(\mathbb{F})$ be invertible matrices.
Then necessarily $\text{rank}(PAQ) = \text{rank}(A)$.

Proof. This follows from T3.4(1) and T3.4(2). ▣

INVERTIBLE MATRIX THEOREM, PART 2 (C3.4.1)

Let $A \in M_{n\times n}(\mathbb{F})$ be arbitrary.
Then A is invertible if and only if $\text{rank}(A) = n$.

Proof. ($\Rightarrow$) If A is invertible, necessarily $I_n = AA^{-1}$.
Since A^{-1} is also invertible, by T3.4, it follows that
$\text{rank}(A) = \text{rank}(AA^{-1}) = \text{rank}(I_n) = n$,
proving the forward argument. #
($\Leftarrow$) If $n = \text{rank}(A)$, necessarily $n = \dim(L_A(\mathbb{F}^n))$.
Then, since $L_A(\mathbb{F}^n)$ is a subspace of $\mathbb{F}^n$, it follows that $L_A(\mathbb{F}^n) = \mathbb{F}^n$ (by C1.9.2(6)).
Hence L_A is onto; thus (by T2.7) it is also 1-1, and so (since L_A is linear by T2.9) L_A is an isomorphism.
It follows that A is invertible (by T2.15(2)), proving the backward argument. ▣

ELEMENTARY ROW & COLUMN OPERATIONS ON A MATRIX ARE RANK-PRESERVING (C3.4.2)

For any matrix $A \in M_{m\times n}(\mathbb{F})$, performing elementary row and column operations on A does not change the rank of the resultant matrix.

Proof. Suppose B is obtained from A by performing an elementary row operation; so, there exists an elementary matrix $E \in M_{m\times m}(\mathbb{F})$ such that $B = EA$.
Since E is invertible, by T3.4 necessarily $\text{rank}(B) = \text{rank}(A)$.
A similar result holds for elementary column operations. ▣

This result can be used to transform complicated matrices into simpler ones to determine their rank.

ANY MATRIX CAN BE TRANSFORMED INTO THE FORM $D = \begin{pmatrix} I_r & O_1 \\ O_2 & O_3 \end{pmatrix}$ (T3.5)

Let $A \in M_{m \times n}(\mathbb{F})$ be arbitrary.
Then there exists a finite sequence of elementary row and column operations such that when applied to A, the resultant matrix D is of the form

$$D = \begin{pmatrix} I_r & O_1 \\ O_2 & O_3 \end{pmatrix},$$

where O_1, O_2, O_3 are zero matrices, and $r = \text{rank}(A)$.

Proof. If $A = O$, we are done.
Then, suppose $A \neq O$. Then A has a non-zero entry.
By means of at most one elementary row and at most one elementary column operation (each of the form $R_k \leftrightarrow R_\ell$ or $C_k \leftrightarrow C_\ell$), we can move the non-zero entry to the $(1,1)$ position.
By means of at most one operation of the form $(R_k \leftarrow c \cdot R_k)$ or $(C_k \leftarrow c \cdot C_k)$, we can change that entry to 1.
Then, by at most $(m-1)$ row operations of type "$R_k \leftarrow R_k + c \cdot R_\ell$" and by at most $(n-1)$ column operations of type "$C_k \leftarrow C_k + c \cdot C_\ell$", we can change all the remaining entries in the first row and in the first column to be 0.
It follows that after a finite number of elementary matrix operations, we have transformed A to a matrix A' of the form

$$A' = \left(\begin{array}{c|c} 1 & 0 \cdots 0 \\ \hline 0 & \\ \vdots & B \\ 0 & \end{array}\right).$$

By continuing this recursive process on B, we can continue this process to obtain a matrix of the form D after a finite number of elementary row/column operations.
Since these preserve rank, it follows that $\text{rank}(A) = \text{rank}(D)$.
Then, by R16,

$$\text{rank}(D) = \dim(\text{span}\{e_1, \dots, e_r, \underset{\sim}{0}, \dots, \underset{\sim}{0}\}) = \dim(\text{span}\{e_1, \dots, e_r\}) = r,$$

where $\{e_1, \dots, e_n\}$ is the standard basis for $\mathbb{F}^n$.
It follows that $\text{rank}(A) = \text{rank}(D) = r$, as desired. ☒

$A \in M_{m \times n}(\mathbb{F}) \Rightarrow \exists$ INVERTIBLE $B \in M_{m \times m}(\mathbb{F})$, $C \in M_{n \times n}(\mathbb{F})$ $\ni D = BAC = \begin{pmatrix} I_r & O_1 \\ O_2 & O_3 \end{pmatrix} \in M_{m \times n}(\mathbb{F})$, $r = \text{rank}(A)$ (C3.5.1)

Let $A \in M_{m \times n}(\mathbb{F})$ be such that $r = \text{rank}(A)$.
Then there necessarily exist invertible matrices $B \in M_{m \times m}(\mathbb{F})$, $C \in M_{n \times n}(\mathbb{F})$ such that the matrix $D = BAC$ is of the form $D = \begin{pmatrix} I_r & O_1 \\ O_2 & O_3 \end{pmatrix} \in M_{m \times n}(\mathbb{F})$, where O_1, O_2, O_3 are zero matrices.

Proof. By T3.5, we can convert A into D via a finite number of elementary row & column operations.
It follows that

$$D = E_p \cdots E_1 A G_1 \cdots G_q,$$

where $E_1, \dots, E_p \in M_{m \times m}(\mathbb{F})$ and $G_1, \dots, G_q \in M_{n \times n}(\mathbb{F})$ are elementary matrices.
Thus they are invertible, so it follows that $B = E_p \cdots E_1$ and $C = G_1 \cdots G_q$ are invertible and $D = BAC$, completing the proof. ☒

ANY MATRIX CAN BE TRANSFORMED INTO "D_{upper}" (T3.6)

Let $A \in M_{m \times n}(\mathbb{F})$ be such that $r = \text{rank}(A)$.
Then there exist a finite sequence of elementary row and column operations such that when applied to A, it transforms into the matrix

$$D_{upper} = \begin{pmatrix} 1 & d_{12} & d_{13} & \cdots & d_{1,r} & d_{1,r+1} & \cdots & d_{1n} \\ 0 & 1 & d_{23} & \cdots & d_{2,r} & d_{2,r+1} & \cdots & d_{2n} \\ 0 & 0 & 1 & \cdots & d_{3,r} & d_{3,r+1} & \cdots & d_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & 1 & d_{r,r+1} & \cdots & d_{rn} \\ 0 & 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \end{pmatrix}.$$

Proof. If $A = O$, we are done.
Suppose $A \neq O$, so that there exists a non-zero entry of A.
By doing at most one row and at most one column (each of type 1; ie "swapping") operation, we can move this non-zero entry to the $(1,1)$ position.
By doing at most one "type 2" operation (ie $R_k \leftarrow c \cdot R_k$ or $C_k \leftarrow c \cdot C_k$), we can change it to 1.
By at most $(m-1)$ type-3 row operations (ie $R_k \leftarrow R_k + c \cdot R_\ell$), we can change all the remaining entries in the first row to be 0.
Hence, we have transformed A to a matrix A' of the form

$$A' = \left(\begin{array}{c|c} 1 & d_{12} \cdots d_{1n} \\ \hline 0 & \\ \vdots & B \\ 0 & \end{array}\right).$$

By repeating this recursive process on B, we can transform A into the form of D_{upper}.
Then,

$$R(D_{upper}) = \dim(\text{span}(\{e_1, d_{12}e_1 + e_2, \dots, \sum_{i=1}^{r-1} d_{i,r}e_i + e_r, d_{r+1}, \dots, d_n\}))$$

$$\therefore R(D_{upper}) = \dim(\text{span}(\{e_1, \dots, e_r, d_{r+1}, \dots, d_n\})),$$

where $\{e_1, \dots, e_n\}$ is the standard (ordered) basis for $\mathbb{F}^n$, and d_k is the k^{th} column of D_{upper} for $1 \leq k \leq n$.
Then, since $d_k = \sum_{i=1}^{r} d_{i,k}e_i$ for $r+1 \leq k \leq n$, we have

$$\text{span}(\{e_1, \dots, e_r, d_{r+1}, \dots, d_n\}) = \text{span}(\{e_1, \dots, e_r\}).$$

It follows that $L_{D_{upper}}(\mathbb{F}^n) = \text{span}(\{e_1, \dots, e_r\})$, so that

$$\text{rank}(D_{upper}) = \dim(L_{D_{upper}}(\mathbb{F}^n)) = \dim(\text{span}(\{e_1, \dots, e_r\})) = r = \text{rank}(A),$$

since elementary matrix operations preserve the rank of the matrix, and we are done. ☒

METHOD TO CONVERT MATRICES TO D_{upper} (R17)

By T3.6, we can formulate a method to convert a complicated matrix A into D_{upper} to find its rank:

1. Find a non-zero entry of A;
2. Apply at most one type-1 row operation and at most one type-1 column operation to move the entry to the position $(1,1)$;
3. Apply at most one type-2 row (or column) operation to make the entry at the position $(1,1)$ to be $1_{\mathbb{F}}$;
4. Apply at most $(m-1)$ type-3 row operations so that all of the remaining entries in the first row is 0, so the new matrix is of the form
$$A' = \left(\begin{array}{c|c} 1 & d_{12} \cdots d_{1n} \\ \hline 0 & \\ \vdots & B \\ 0 & \end{array}\right).$$
5. Repeat steps ①–④ on B recursively until a matrix of the form of D_{upper} is obtained.
6. It follows that $\text{rank}(A) = \text{rank}(D_{upper}) = r$.

$\text{rank}(A^T) = \text{rank}(A)$ (C3.6.1 (1))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.
Then necessarily $\text{rank}(A^T) = \text{rank}(A)$

Proof. From C3.5.1, there exists invertible matrices B, C such that $D = BAC$.
Then $D^T = (BAC)^T = C^T A^T B^T$.
Since B and C are invertible, by L8 B^T and C^T are also invertible.
Thus $\text{rank}(A^T) = \text{rank}(D^T)$.
Then, as $D^T \in M_{n\times m}(\mathbb{F})$ has the form of the matrix D in C3.5.1, necessarily $\text{rank}(D^T) = \text{rank}(A)$.
It follows that $\text{rank}(A^T) = \text{rank}(A)$, as required. ☒

$\text{rank}(A) = \dim(\text{span}(\{R_1, \dots, R_m\})) = \dim(\text{span}(\{C_1, \dots, C_n\}))$ (C3.6.1 (2))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.
Then necessarily $\text{rank}(A) = \dim(\text{span}(\{R_1, \dots, R_m\})) = \dim(\text{span}(\{C_1, \dots, C_n\}))$, where R_i and C_j denote the i^{th} row and j^{th} column of A respectively.

Proof. By R16, $\text{rank}(A) = \dim(\text{span}(\{C_1, \dots, C_n\}))$.
So, the rank of A^T is the dimension of the subspace generated by the columns of A^T.
But since the columns of A^T are the rows of A, and $\text{rank}(A) = \text{rank}(A^T)$ by C3.6.1(1), it follows that $\text{rank}(A)$ is also the dimension of the subspace generated by the rows of A, as needed. ☒

$\text{rank}(AB) \leq \min(\{\text{rank}(A), \text{rank}(B)\})$ (T3.7)

Let A and B be matrices such that AB is defined.
Then necessarily $\text{rank}(AB) \leq \min(\{\text{rank}(A), \text{rank}(B)\})$.

Proof. Let $A \in M_{m\times n}(\mathbb{F})$ and $B \in M_{n\times p}(\mathbb{F})$. Then, since

$$R(L_{AB}) = \{ABx : x \in \mathbb{F}^p\} \subset \{Ay : y \in \mathbb{F}^n\} = R(L_A),$$

we have

$$\text{rank}(AB) = \dim(R(L_{AB})) \leq \dim(R(L_A)) = \text{rank}(A).$$

On the other hand,

$$\text{rank}(AB) = \text{rank}((AB)^T) = \text{rank}(B^T A^T) \leq \text{rank}(B^T) = \text{rank}(B).$$

Thus $\text{rank}(AB) \leq \min(\{\text{rank}(A), \text{rank}(B)\})$, as needed.

FOUR FUNDAMENTAL SUBSPACES OF A MATRIX (S3.3)

COLUMN SPACE OF A MATRIX, Col(A) (D34)

Let $A \in M_{m\times n}(\mathbb{F})$. Then, we define the "column space" of A, denoted as "Col(A)", to be the vector space

$$\mathrm{Col}(A) := \{Ax : x \in \mathbb{F}^n\}$$
$$= \{\text{all linear combinations of columns in } A\}$$
$$= \mathrm{span}(\{\text{columns of } A\}).$$

We can show Col(A) is a subspace of $\mathbb{F}^m$. (T3.8 (1))

Proof. This follows from the fact that $\mathrm{Col}(A) = \mathrm{span}(\{\text{columns of } A\})$. ∎

ROW SPACE OF A MATRIX, Row(A) (D34)

Let $A \in M_{m\times n}(\mathbb{F})$. Then, we define the "row space" of A, denoted as "Row(A)", to be the vector space

$$\mathrm{Row}(A) := \mathrm{Col}(A^T)$$
$$= \{A^T y : y \in \mathbb{F}^m\}$$
$$= \{\text{all linear combinations of rows in } A\}$$
$$= \mathrm{span}(\{\text{rows of } A\}).$$

We can similarly show Row(A) is a subspace of $\mathbb{F}^n$. (T3.8 (1))

Proof. Again, this follows from the fact that $\mathrm{Row}(A) = \mathrm{span}(\{\text{rows of } A\})$.

NULL SPACE OF A MATRIX, Null(A) (D34)

Let $A \in M_{m\times n}(\mathbb{F})$. Then, we define the "null space" of A, denoted as "Null(A)", to be the vector space

$$\mathrm{Null}(A) := \{x \in \mathbb{F}^n \mid Ax = 0\}.$$

We can show that Null(A) is a subspace of $\mathbb{F}^n$. (T3.8(1))

LEFT NULL SPACE OF A MATRIX, $\mathrm{Null}(A^T)$ (D34)

Let $A \in M_{m\times n}(\mathbb{F})$. Then, we define the "left null space" of A, denoted as "$\mathrm{Null}(A^T)$", to be the vector space

$$\mathrm{Null}(A^T) := \{y \in \mathbb{F}^m \mid A^T y = 0\}.$$

We can similarly show that $\mathrm{Null}(A^T)$ is a subspace of $\mathbb{F}^m$. (T3.8(1))

NULLITY OF A MATRIX, Nullity(A) (D34)

For any matrix $A \in M_{m\times n}(\mathbb{F})$, we define the "nullity" of A, denoted as "Nullity(A)", to be

$$\mathrm{Nullity}(A) := \dim(\mathrm{Null}(A)).$$

$\mathrm{rank}(A) = \dim(\mathrm{Col}(A)) = \dim(\mathrm{Row}(A))$ (T3.8(2))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.

Then necessarily $\mathrm{rank}(A) = \dim(\mathrm{Col}(A)) = \dim(\mathrm{Row}(A))$.

Proof. This follows from R16 (1), and the fact that $\mathrm{rank}(A) = \mathrm{rank}(A^T)$ by C3.6.1(1). ∎

$\mathrm{nullity}(A^T) = m - \mathrm{rank}(A)$, $\mathrm{nullity}(A) = n - \mathrm{rank}(A)$ (T3.8(3))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.

Then necessarily $\mathrm{nullity}(A^T) = m - \mathrm{rank}(A)$ and $\mathrm{nullity}(A) = n - \mathrm{rank}(A)$.

Proof. By the Rank-Nullity theorem (T2.4), necessarily

$$\dim(\mathbb{F}^n) = n = \dim(R(L_A)) + \dim(N(L_A)) = \mathrm{rank}(A) + \mathrm{nullity}(A),$$

and

$$\dim(\mathbb{F}^m) = m = \dim(R(L_{A^T})) + \dim(N(L_{A^T})) = \mathrm{rank}(A) + \mathrm{nullity}(A^T).$$

The proof directly follows from this observation. ∎

$\mathbb{F}^m = \mathrm{Col}(A) \oplus \mathrm{Null}(A^T)$, $\mathbb{F}^n = \mathrm{Row}(A) \oplus \mathrm{Null}(A)$ (T3.8 (4))

Let $A \in M_{m\times n}(\mathbb{F})$ be arbitrary.

Then necessarily $\mathbb{F}^m = \mathrm{Col}(A) \oplus \mathrm{Null}(A^T)$ and $\mathbb{F}^n = \mathrm{Row}(A) \oplus \mathrm{Null}(A)$.

Proof. We first prove $\mathrm{Row}(A) \cap \mathrm{Null}(A) = \{0\}$.

Let $v \in \mathrm{Row}(A) \cap \mathrm{Null}(A)$ be arbitrary. By definition, this implies $v \in \mathrm{Col}(A^T) = \{A^T y : y \in \mathbb{F}^m\}$, and $Av = 0$.

Hence there exists $y \in \mathbb{F}^m$ such that $v = A^T y$.

Since $Av = 0$, thus $AA^T y = 0$.

This implies

$$0 = y^T A A^T y = (y^T A)(A^T y)$$
$$= (A^T y)^T (A^T y)$$
$$\therefore 0 = v^T v,$$

hence implying $v = 0$ necessarily, so that $\mathrm{Row}(A) \cap \mathrm{Null}(A) = \{0\}$.

So, by T1.12, we have

$$\dim(\mathrm{Row}(A) + \mathrm{Null}(A)) = \dim(\mathrm{Row}(A)) + \dim(\mathrm{Null}(A)).$$
$$= \dim(\mathrm{Row}(A)) + \mathrm{nullity}(A).$$

Then, by C3.6.1, $\mathrm{rank}(A) = \dim(\mathrm{Row}(A))$. Thus

$$\dim(\mathrm{Row}(A)) + \mathrm{nullity}(A) = \mathrm{rank}(A) + \mathrm{nullity}(A) = n = \dim(\mathbb{F}^n).$$

Since $\mathrm{row}(A) + \mathrm{Null}(A)$ is a subspace of $\mathbb{F}^n$ and $\dim(\mathrm{Row}(A) + \mathrm{Null}(A)) = \dim(\mathbb{F}^n)$, we have $\mathrm{Row}(A) + \mathrm{Null}(A) = \mathbb{F}^n$.

Together with $\mathrm{Row}(A) \cap \mathrm{Null}(A) = \{0\}$, this tells us that

$$\mathrm{Row}(A) \oplus \mathrm{Null}(A) = \mathbb{F}^n,$$

as needed. ∎

THE INVERSE OF A MATRIX (S3.4)

INVERTIBLE MATRIX THEOREM, PART 3 (T3.9)

Let $A \in M_{n\times n}(\mathbb{F})$. Then the following statements are equivalent:

① A is invertible;
② The columns of A form a basis for $\mathbb{F}^n$;
③ The rows of A form a basis for $\mathbb{F}^n$; and
④ A is a product of elementary matrices.

Proof. (② ⟺ ①) Note that $\text{rank}(A) = n \iff \dim(\text{Col}(A)) = n$
$\iff$ the columns of A form a basis for $\mathbb{F}^n$, since A has n columns. (This follows from C1.9.2).
We can similarly prove (③ ⟺ ①) in this manner. #

(④ ⟹ ①) Suppose $A = E_1 \cdots E_p$, where $E_1, \dots, E_p$ are elementary matrices.
Then, since elementary matrices are invertible, and the matrix product of invertible matrices is invertible, it follows that A is invertible and $A^{-1} = E_p^{-1} \cdots E_1^{-1}$. #

(① ⟹ ④) By C3.5.1, we have $D = BAC$, where $D = \begin{pmatrix} I_r & O_1 \\ O_2 & O_3 \end{pmatrix}$, $r = \text{rank}(A)$, and B and C are products of elementary matrices.
Then, since A is invertible, necessarily (by C3.4.1) $r = n$, implying $D = I_n$.
Hence $A = B^{-1} I_n C^{-1} = B^{-1}C^{-1}$.
Finally, since B and C are both products of elementary matrices, and the inverse of an elementary matrix is also an elementary matrix, it follows that A is itself the product of elementary matrices.
This is sufficient to prove the 4 statements are equivalent to one another. ▨

$A \in M_{n\times n}(\mathbb{F})$ IS INVERTIBLE ⟹ CAN TRANSFORM $(A \mid I_n)$ INTO $(I_n \mid A^{-1})$ BY ROW OPERATIONS (T3.10(1))

Let $A \in M_{n\times n}(\mathbb{F})$ be invertible.
Then there exists a finite sequence of elementary row operations which can transform the matrix $(A \mid I_n)$ into the matrix $(I_n \mid A^{-1})$.

Proof. Since $AM = (Av_1 \cdots Av_p)$ for any $M = (v_1 \cdots v_p) \in M_{n\times p}(\mathbb{F})$, we have
$$A^{-1}(A \mid I_n) = (A^{-1}A \mid A^{-1}I_n) = (I_n \mid A^{-1}).$$
Then, by the invertible matrix theorem Part 3, we have
$$A^{-1} = E_p \cdots E_1,$$
where $E_1, \dots, E_p$ are elementary matrices.
It follows that
$$(E_p \cdots E_1)(A \mid I_n) = (I_n \mid A^{-1}),$$
which show (since each E_i is the result of an elementary row operation) that we can transform $A \mid I_n$ into $I_n \mid A^{-1}$ via a finite sequence of elementary row operations. ▨

$A \in M_{n\times n}(\mathbb{F})$, $\exists B \in M_{n\times n} \in \mathbb{F} \ni (A \mid I_n) \rightsquigarrow (I_n \mid B)$ BY FINITELY MANY ROW OPERATIONS ⟹ A IS INVERTIBLE & $B = A^{-1}$ (T3.10(2))

Let $A \in M_{n\times n}(\mathbb{F})$, and suppose there exists a $B \in M_{n\times n}(\mathbb{F})$ such that we can transform the matrix $(A \mid I_n)$ into $(I_n \mid B)$ by finitely many elementary row operations.
Then necessarily A is invertible, and $B = A^{-1}$.

Proof. Let $G_1, \dots, G_q$ be the elementary matrices associated with the elementary row operations that transform $(A \mid I_n)$ into $(I_n \mid B)$, so that
$$(G_q \cdots G_1)(A \mid I_n) = (I_n \mid B).$$
Let $G = G_q \cdots G_1$, so that $G(A \mid I_n) = (GA \mid G) = (I_n \mid B)$.
It follows that $I_n = GA$ and $B = G$, so that $AB = I_n$, and hence that A is invertible and $B = A^{-1}$. ▨

GAUSS-JORDAN METHOD TO FINDING INVERSES TO SQUARE MATRICES (R18)

Using T3.10, we can formulate a method to find the inverse of a square matrix A (if it exists):

① If the first column of A is a zero vector, A is not invertible; otherwise, the first column of A has a non-zero entry.
Why? - follows from the Invertible Matrix Theorem part 3.

② In a manner similar to the process for T3.6, we can convert $(A \mid I_n)$ into a matrix of the form
$$B = \left(\begin{array}{c|ccc} 1 & d_{12} & \cdots & d_{1,2n} \\ \hline 0 & & & \\ \vdots & & Q & \\ 0 & & & \end{array}\right)$$
using only elementary row operations.
- in particular, at most one type-1, at most one type-2, and at most $(n-1)$ type-3 operations.

③ Then, we repeat steps ① and ② recursively on Q, until either
① The first column of Q is a zero vector; or
- then, by the Invertible Matrix Theorem part 3, A is not invertible and so we stop the procedure
② We get a matrix of the form
$$C' = \begin{pmatrix} 1 & d_{12} & \cdots & d_{1,n} & d_{1,n+1} & \cdots & d_{1,2n} \\ 0 & 1 & \cdots & d_{2,n} & d_{2,n+1} & \cdots & d_{2,2n} \\ \vdots & \vdots & & \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1 & d_{n,n+1} & \cdots & d_{n,2n} \end{pmatrix}.$$

④ Then, by at most $(n-1)$ type-3 row operations, we can convert C' to the matrix C_n, where
$$C_n = \begin{pmatrix} 1 & d_{12} & \cdots & 0 & d_{1,n+1} & \cdots & d_{1,2n} \\ 0 & 1 & \cdots & 0 & d_{2,n+1} & \cdots & d_{2,2n} \\ \vdots & \vdots & & \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1 & d_{n,n+1} & \cdots & d_{n,2n} \end{pmatrix};$$
ie C_n is C' but with the n^{th} column having all zero entries except the last one.

⑤ By at most $(n-2)$ type-3 row operations, we can convert C_n into the matrix C_{n-1}, which is C_n but with the $(n-1)^{th}$ column of C_n being zeros except at the $(n-1, n-1)$ position.

⑥ Continue step ⑤ until we get a matrix of the form $(I_n \mid B)$.

Then, by T3.10, necessarily $B = A^{-1}$.

SYSTEMS OF LINEAR EQUATIONS (S3.5)

SYSTEM OF m LINEAR EQUATIONS OVER $\mathbb{F}$ (D35)

A "system of linear equations in n unknowns over the field $\mathbb{F}$" is a system of linear equations of the form

$$\begin{cases} a_{11}x_1 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + \cdots + a_{2n}x_n = b_2 \\ \vdots \qquad\qquad \vdots \\ a_{m1}x_1 + \cdots + a_{mn}x_n = b_n, \end{cases}$$

where $a_{ij}, b_i \in \mathbb{F}$ $\forall 1 \leq i \leq m, 1 \leq j \leq n$ and $x_1, \ldots, x_n$ are variables taking values in $\mathbb{F}$.

Alternatively, we can also write the above system as the matrix product $Ax = b$, where

① $A = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix}$ (called the "coefficient matrix" of the system);

② $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$; and

③ $b = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$.

AUGMENTED MATRIX OF $Ax=b$ (D35)

Let $Ax=b$ be a system of linear equations in n unknowns over $\mathbb{F}$.
Then, the "augmented matrix" of the system is defined to be the $m \times (n+1)$ matrix $(A \mid b)$.

SOLUTION (D35)

Let $Ax=b$ be a system of linear equations in n unknowns over $\mathbb{F}$.
Then, we say $c \in \mathbb{F}^n$ is a "solution" to the system if $Ac=b$.

SOLUTION SET (D35)

Let $Ax=b$ be a system of linear equations in n unknowns over $\mathbb{F}$.
Then the "solution set" of the system is the set of all solutions to the system.

*in particular, we use "K_H" to denote the solution set to the system described by $Ax=0$.

CONSISTENT / INCONSISTENT (D35)

Let $Ax=b$ be a system of linear equations in n unknowns over $\mathbb{F}$.
Then,
① we say the system is "consistent" if $K_H \neq \emptyset$; and
② we say the system is "inconsistent" if $K_H = \emptyset$.

HOMOGENOUS / INHOMOGENOUS (D35)

Let $Ax=b$ be a system of linear equations in n unknowns in $\mathbb{F}$.
Then,
① we say the system is "homogenous" if $b=0$; and
② we say the system is "inhomogenous" if $b \neq 0$.

K_H OF $Ax=0$ IS A SUBSPACE OF $\mathbb{F}^n$; $\dim K_H = n - \mathrm{rank}(A)$ (T3.11)

Let $A \in M_{m\times n}(\mathbb{F})$, and consider the system of linear equations described by $Ax=0$.
Then the solution set K_H of the system is necessarily a subspace of $\mathbb{F}^n$, and $\dim K_H = n - \mathrm{rank}(A)$.

Proof. Observe that $K_H = N(L_A) = \mathrm{Null}(A)$, and so K_H is a subspace of $\mathbb{F}^n$.
Then, by the Rank-Nullity Theorem,
$$\mathrm{rank}(A) + \dim(\mathrm{Null}(A)) = n,$$
and so
$$\dim K_H = \dim \mathrm{Null}(A) = n - \mathrm{rank}(A),$$
as needed. ☒

K_H OF $Ax=0$ IS NON-EMPTY (R19(1))

Note that the solution set K_H of $Ax=0$ is non-empty.
· since $0 \in K_H$

K_H OF $Ax=0$ IS $\{0\}$ $\iff$ $\mathrm{rank}(A) = n$ (R19(2))

Also, the solution set K_H of $Ax=0$ is $\{0\}$ if and only if $\mathrm{rank}(A) = n$.

Proof. ($\Rightarrow$) Suppose $K_H = \{0\}$. This implies $N(L_A) = \mathrm{Null}(A) = \{0\}$, and so $\dim(\mathrm{Null}(A)) = 0$.
By the Rank-Nullity Theorem, necessarily
$$\mathrm{rank}(A) = n - \dim(\mathrm{Null}(A)) = n. \;*$$
($\Leftarrow$) Suppose $\mathrm{rank}(A) = n$. This implies A is invertible.
Then note that
$$Ax=0 \implies A^{-1}(Ax) = A^{-1}(0) \implies x=0,$$
showing that $K_H = \{0\}$. ☒

FULL COLUMN RANK (R19(2))

We say the matrix $A \in M_{m\times n}(\mathbb{F})$ is of "full column rank" if the solution set K_H of $Ax=0$ is $\{0\}$, or equivalently if $\mathrm{rank}(A) = n$.

$m<n \implies Ax=0$ HAS A NON-ZERO SOLUTION (R19(3))

Let $A \in M_{m\times n}(\mathbb{F})$ be such that $m<n$.
Then necessarily $Ax=0$ has a non-zero solution.

Proof. By T3.7, $\mathrm{rank}(A) \leq m < n$, and so $Ax=0$ has a non-zero solution by R19(2). ☒

*in other words, a homogenous system of linear equations with more unknowns than number of equations has a non-zero solution.

$Ax=b$ IS CONSISTENT $\Rightarrow$ SOLUTION SET IS A COSET OF K_H (T3.12)

Let $A \in M_{m\times n}(\mathbb{F})$ and $b \in \mathbb{F}^m$.
Let $K = \{x \in \mathbb{F}^n \mid Ax=b\}$ and $K_H = \{x \in \mathbb{F}^n \mid Ax=0\}$, and suppose that $K \neq \emptyset$.
Then K is a coset of K_H, and in particular, we have $K = c + K_H$, where c is an arbitrary solution of $Ax=b$.

Proof. We first show $c + K_H \subseteq K$.
Let $k \in K_H$ and let $c \in K$ be arbitrary,
so that $c+k \in c+K_H$.
Since $c \in K$, necessarily $Ac=b$, and so
$$A(c+k) = Ac + Ak = b + 0 = b.$$
Hence $c+k \in K$, and thus (since c and k were arbitrary) $c + K_H \subseteq K$.
Next, we show $K \subseteq c + K_H$, which will be sufficient to prove the claim.
Let $x, c \in K$, and let $k = x - c$.
Then $A(x-c) = Ax - Ac = b - b = 0$,
and so $x - c \in K_H$.
Thus (since K_H is a subspace) it follows that $x \in c + K_H$, and so $K \subseteq c + K_H$, as needed. ☒

INVERTIBLE MATRIX THEOREM, PART 4 (T3.13)

Let $A \in M_{n\times n}(\mathbb{F})$ be arbitrary.
Then A is invertible if and only if the equation $Ax = b$ has a unique solution $\forall b \in \mathbb{F}^m$.

Proof. ($\Rightarrow$) $Ax = b \iff A^{-1}Ax = A^{-1}b \iff x = A^{-1}b$, showing $x = A^{-1}b$ is the unique solution to the system.
($\Leftarrow$) Suppose $\forall b \in \mathbb{F}^m$, $Ax = b$ has a unique solution.
Fix $b \in \mathbb{F}^m$, and let c be the unique solution of $Ax = b$.
Let K_H be the solution set of $Ax = 0$.
By T3.12, $\{c\} = c + K_H$, implying $K_H = \{0\}$, which in turn (by R19(2)) tells us that $\text{rank}(A) = n$, and hence (by C3.4.1) that A is invertible. ∎

$Ax = b$ IS CONSISTENT $\iff$ rank(A) = rank(A|b) (T3.14)

Let $Ax = b$ be a system of linear equations.
Then the system is consistent if and only if $\text{rank}(A) = \text{rank}(A|b)$.

Proof. $Ax = b$ has a solution
$\iff b \in R(L_A)$
$\iff b \in \text{span}(\{\text{Col}_1(A), \dots, \text{Col}_n(A)\})$
$\iff \text{span}(\{\text{Col}_1(A), \dots, \text{Col}_n(A), b\}) = \text{span}(\{\text{Col}_1(A), \dots, \text{Col}_n(A)\})$
$\iff \dim(\text{span}(\{\text{Col}_1(A), \dots, \text{Col}_n(A), b\})) = \dim(\text{span}(\{\text{Col}_1(A), \dots, \text{Col}_n(A)\}))$
$\iff \text{rank}(A) = \text{rank}(A|b)$, as needed. ∎

EQUIVALENCE OF LINEAR EQUATIONS (D36)

We say two systems of linear equations are "equivalent" if they have the same solution set.

$C \in M_{m\times m}(\mathbb{F})$, C IS INVERTIBLE $\Rightarrow$ (CA)b = Cb IS EQUIVALENT TO $Ax = b$ (T3.15)

Let $C \in M_{m\times m}(\mathbb{F})$ be an invertible matrix.
Then the system $(CA)x = Cb$ is equivalent to the system $Ax = b$.

Proof. For any $x \in \mathbb{F}^n$, we have that
$(CA)x = Cb \iff C^{-1}(CA)x = C^{-1}(Cb)$
$\iff Ax = b$,
showing the systems have the same solution sets. ∎

(A'|b') IS OBTAINED FROM (A|b) BY FINITELY MANY ELEMENTARY ROW OPERATIONS $\Rightarrow$ $A'x = b'$ IS EQUIVALENT TO $Ax = b$ (C3.15.1)

Let $Ax = b$ be a system of linear equations.
Suppose $(A'|b')$ is obtained by performing a sequence of finitely many elementary row operations on $(A|b)$.
Then the system $A'x = b'$ is equivalent to the system $Ax = b$.

Proof. We must have that $(A'|b') = E_p \cdots E_1 (A|b)$, where $E_p \cdots E_1$ are elementary matrices.
Then since $(E_p \cdots E_1)^{-1} = E_1^{-1} \cdots E_p^{-1}$, it follows that (by T3.15) that $A'x = b'$ is equivalent to $Ax = b$, as required. ∎

REDUCED ROW ECHELON FORM / RREF (D37)

A matrix is said to be in "reduced row echelon form", or "RREF", if

1. Non-zero rows are at the top of the matrix;
2. Zero rows are at the bottom of the matrix;
3. The first non-zero entry in each non-zero row is 1, called a "leading one";
4. The leading one is the only non-zero entry in its column; and
5. The leading one in each non-zero row is to the right of any leading one above it.

eg $\begin{pmatrix} 1 & 0 & 0 & 2 & -1 \\ 0 & 1 & 0 & 5 & 3 \\ 0 & 0 & 1 & 1 & 3 \end{pmatrix}$, $\begin{pmatrix} 1 & 0 & 0 & 0 & 3 \\ 0 & 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ are in RREF;

$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$, $\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$, $\begin{pmatrix} 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ are not in RREF.

GAUSSIAN ELIMINATION TO ROW REDUCE A NON-ZERO MATRIX INTO RREF (T3.16)

We can convert any non-zero matrix into RREF by applying a sequence of elementary row operations, called a "row reduction", in the following manner:

* we use the example matrix

$$A = \begin{pmatrix} 2 & 4 & 1 & 0 & -4 & 2 \\ 0 & 0 & 2 & -4 & 4 & 4 \\ 1 & 2 & 2 & -3 & 1 & 4 \\ 3 & 6 & -2 & 7 & -13 & 4 \end{pmatrix}$$

1. In the leftmost nonzero column, use elementary row operations (if necessary) to get a 1 in the first row;

eg $\begin{pmatrix} 2 & 4 & 1 & 0 & -4 & 2 \\ 0 & 0 & 2 & -4 & 4 & 4 \\ 1 & 2 & 2 & -3 & 1 & 4 \\ 3 & 6 & -2 & 7 & -13 & 4 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 \cdot \frac{1}{2}} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 2 & -4 & 4 & 4 \\ 1 & 2 & 2 & -3 & 1 & 4 \\ 3 & 6 & -2 & 7 & -13 & 4 \end{pmatrix}$

2. Using type-3 elementary row operations, use the first row to create zeroes in the remaining entries of the leftmost column; that is, below the leading one created in the previous step.

eg $\begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 2 & -4 & 4 & 4 \\ 1 & 2 & 2 & -3 & 1 & 4 \\ 3 & 6 & -2 & 7 & -13 & 4 \end{pmatrix} \xrightarrow[R_4 \leftarrow R_4 - 3 \cdot R_1]{R_3 \leftarrow R_3 + R_1} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 2 & -4 & 4 & 4 \\ 0 & 0 & 3/2 & -3 & 3 & 3 \\ 0 & 0 & -7/2 & 7 & -7 & 1 \end{pmatrix}$

3. Consider the "submatrix" consisting of the columns to the right of the column we just modified, and the rows beneath the row that just got a leading one.

Use elementary row operations to get a leading one in the top of the first non-zero column of this submatrix.

eg $\begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 2 & -4 & 4 & 4 \\ 0 & 0 & 3/2 & -3 & 3 & 3 \\ 0 & 0 & -7/2 & 7 & -7 & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow R_2 \cdot \frac{1}{2}} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 3/2 & -3 & 3 & 3 \\ 0 & 0 & -7/2 & 7 & -7 & 1 \end{pmatrix}$

4. Use elementary row operations to obtain zeroes below the 1 created in the preceding step.

eg $\begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 3/2 & -3 & 3 & 3 \\ 0 & 0 & -7/2 & 7 & -7 & 1 \end{pmatrix} \xrightarrow[R_4 \leftarrow R_4 + \frac{7}{2} \cdot R_2]{R_3 \leftarrow R_3 - \frac{3}{2} \cdot R_2} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 8 \end{pmatrix}$

5. Repeat steps 3 and 4 until no non-zero rows remain. (This completes the "forward phase").

eg $\begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 8 \end{pmatrix} \xrightarrow{R_3 \leftrightarrow R_4} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

$\xrightarrow{R_3 \leftarrow \frac{1}{8} \cdot R_3} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

6. Next, starting with the last non-zero row, add multiples of it to each row above it to create zeroes above its leading one.

eg $\begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow[R_2 \leftarrow R_2 - 2 \cdot R_3]{R_1 \leftarrow R_1 - R_3} \begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 0 \\ 0 & 0 & 1 & -2 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

7. Repeat the process in step 6 for the second last row, then the third last row, and so on, for every nonzero row except the first row.

(This completes the "backward phase", and at this point the matrix should be in RREF.)

eg $\begin{pmatrix} 1 & 2 & 1/2 & 0 & -2 & 0 \\ 0 & 0 & 1 & -2 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - \frac{1}{2} \cdot R_2} \begin{pmatrix} 1 & 2 & 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & -2 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$. ← this is in RREF.

*note: Gaussian elimination is non-deterministic; ie we have choices when choosing which operations to use in the algorithm.

FREE VARIABLE (D38)

Let B be the RREF of the coefficient matrix in the system of linear equations $Ax=b$.
Then, if the j^{th} column of B does not contain a leading one, we call x_j a "free variable".

B IS THE RREF OF A ⇒ rank(A) = rank(B) = # OF LEADING ONES IN B = # OF NON-ZERO ROWS IN B (R20 (1))

Let B be the RREF of the matrix A in the system $Ax=b$.
Then necessarily $\operatorname{rank}(A) = \operatorname{rank}(B)$ = number of leading ones in B = number of nonzero rows in B.

Proof. Since B is obtained from A via a finite number of elementary row operations, we have $\operatorname{rank}(A)=\operatorname{rank}(B)$.
On the other hand, by the definition of RREF, we have that the nonzero rows of B are linearly independent, so the non-zero rows form a basis for $\operatorname{Row}(B)$.
Hence $\operatorname{rank}(B) = \dim(\operatorname{Row}(B))$ = # of non-zero rows of B = # of leading ones of B. ∎

B IS THE RREF OF A, $A\in M_{m\times n}(\mathbb{F})$ ⇒ # OF FREE VARIABLES OF $(Ax=b)$ = $n - \operatorname{rank}(A)$ = n − # OF LEADING ONES (R20 (2))

Let B be the RREF of $A\in M_{m\times n}(\mathbb{F})$.
Then necessarily the number of free variables of $(Ax=b)$ = $n-\operatorname{rank}(A)$ = n − # of leading ones.

Proof. This follows directly from R20 (1).

ALGORITHM FOR SOLVING A SYSTEM OF LINEAR EQUATIONS

We can solve the system of linear equations $Ax=b$, where $A\in M_{m\times n}(\mathbb{F})$ and $b\in\mathbb{F}^m$, using the following algorithm:

eg
$$\begin{aligned} x_1 + 2x_2 \quad\quad\quad - x_4 + 7x_5 &= -4\\ 3x_1 + x_2 + 5x_3 \quad\quad - 5x_5 &= -2\\ x_1 \quad\quad + 2x_3 + x_4 - 5x_5 &= 4\\ x_2 - x_3 + x_4 + 2x_5 &= 6\end{aligned}$$

① Write the augmented matrix for the system;

$$(A\mid b) = \left(\begin{array}{ccccc|c} 1 & 2 & 0 & -1 & 7 & -4\\ 3 & 1 & 5 & 0 & -5 & -2\\ 1 & 0 & 2 & 1 & -5 & 4\\ 0 & 1 & -1 & 1 & 2 & 6\end{array}\right)$$

② Use elementary row operations to convert the augmented matrix into RREF;

$$(A'\mid b') = \left(\begin{array}{ccccc|c} 1 & 0 & 2 & 0 & -3 & -1\\ 0 & 1 & -1 & 0 & 4 & 1\\ 0 & 0 & 0 & 1 & -2 & 5\\ 0 & 0 & 0 & 0 & 0 & 0\end{array}\right)$$

③ Write the system of linear equations corresponding to the RREF;

$$\begin{aligned} x_1 \quad + 2x_3 \quad - 3x_5 &= -1\\ x_2 - x_3 \quad + 4x_5 &= 1\\ x_4 - 2x_5 &= 5\\ 0 &= 0\end{aligned}$$

④ If the system contains an equation of the form $0=1$, then we stop as the system is inconsistent.

⑤ Otherwise, assign parametric values $t_1, \dots, t_{n-r}$ to the free variables, where r = # of non-zero rows of A', and then solve the remaining variables in terms of the free variables.

- The free variables in the example are x_3 and x_5.
- So, let $x_3 = t_1$ and $x_5 = t_2$.
- Then, the remaining variables can be expressed as
  - $x_1 = -1 - 2t_1 + 3t_2$;
  - $x_2 = 1 + t_1 - 4t_2$; and
  - $x_4 = 5 + 2t_2$.

⑥ Then, reorganise the equations from the previous step (ie the equations expressing the variables in terms of the parameters) as a vector equation in the form
$$x = x_0 + t_1u_1 + \dots + t_{n-r}u_{n-r},$$
where $x_0, u_1, \dots, u_{n-r}$ are specific vectors in $\mathbb{F}^n$.

- In this example, the equations for all 5 variables can be displayed as

$$\begin{aligned} x_1 &= -1 - 2t_1 + 3t_2\\ x_2 &= 1 + t_1 - 4t_2\\ x_3 &= 0 + t_1\\ x_4 &= 5 \quad\quad + 2t_2\\ x_5 &= 0 \quad\quad + t_2,\end{aligned}$$

so by "inspection" we can write

$$x = \begin{pmatrix}x_1\\x_2\\x_3\\x_4\\x_5\end{pmatrix} = \begin{pmatrix}-1\\1\\0\\5\\0\end{pmatrix} + t_1\begin{pmatrix}-2\\1\\1\\0\\0\end{pmatrix} + t_2\begin{pmatrix}3\\-4\\0\\2\\1\end{pmatrix}.$$

⑦ Then, the solutions to $Ax=b$ are the vectors $x\in\mathbb{F}^n$ of the form $x = x_0 + t_1u_1 + \dots + t_{n-r}u_{n-r}$, with the solution set of $Ax=b$ being the coset $K = x_0 + \operatorname{span}(u_1, \dots, u_{n-r})$.

So the solution to the example we used is

$$x = \begin{pmatrix}x_1\\x_2\\x_3\\x_4\\x_5\end{pmatrix} = \begin{pmatrix}-1\\1\\0\\5\\0\end{pmatrix} + t_1\begin{pmatrix}-2\\1\\1\\0\\0\end{pmatrix} + t_2\begin{pmatrix}3\\-4\\0\\2\\1\end{pmatrix}$$

for arbitrary t_1, t_2.

RREF OF $(A|b)$ HAS r NON-ZERO ROWS, GENERAL SOLUTION TO $Ax=b$ IS $x = x_0 + t_1 u_1 + \cdots + t_{n-r} u_{n-r}$ $\Rightarrow$ x_0 IS A SOLUTION TO $Ax=b$ & $\{u_1, \dots, u_{n-r}\}$ IS A BASIS TO SOLUTION SET OF $Ax=0$ (T3.17)

Let $(A|b)$ be a consistent system of m linear equations in n variables, and suppose the RREF of $(A|b)$ has r non-zero rows.
Let $x = x_0 + t_1 u_1 + \cdots + t_{n-r} u_{n-r}$ be the general solution to the system $Ax=b$, where $t_1, \dots, t_{n-r} \in \mathbb{F}$ and $u_1, \dots, u_{n-r} \in \mathbb{F}^n$.
Then necessarily

① $x_0 \in \mathbb{F}^n$ is a solution to $Ax=b$; and

② $\{u_1, \dots, u_{n-r}\}$ is a basis for the solution set $K_H = \{x \in \mathbb{F}^n \mid Ax=0\}$.

Proof. Let $K = \{x \in \mathbb{F}^n \mid Ax=b\}$ and $K_H = \{x \in \mathbb{F}^n \mid Ax=0\}$.
By R14, we have that $r = \text{rank}(A)$.
Then, if we choose $t_1 = \cdots = t_{n-r} = 0$, we get that $x_0 \in K$ necessarily, and so by T3.12 $K = x_0 + K_H$.
Since $K = x_0 + \text{span}(\{u_1, \dots, u_{n-r}\})$ as well, it follows that $K_H = \text{span}(\{u_1, \dots, u_{n-r}\})$.
On the other hand, $\dim K_H = n - \text{rank}(A) = n-r$, implying that $\{u_1, \dots, u_{n-r}\}$ is a basis for K_H. ☒

RREF OF A MATRIX IS UNIQUE (T3.18)

Let A be a matrix, and let B_1 and B_2 be two RREF matrices such that A can be transformed to both B_1 and B_2 via elementary row operations.
Then necessarily $B_1 = B_2$.

Proof. Let $\text{rank}(A) = r$, so that B_1 and B_2 have exactly r leading ones.
Then, say the leading ones of B_1 appear in columns $i_1, \dots, i_r$, where $1 \le i_1 < \cdots < i_r \le n$.
Consider the columns $\text{Col}_1(B_1), \dots, \text{Col}_n(B_1)$ of B_1.
Note that $\text{Col}_{i_k}(B_1) = e_k \in \mathbb{F}^m$ (by the definition of RREF), and $\text{Col}_j(B_1) = 0 \in \mathbb{F}^m$ $\forall 1 \le j < i_1$.
Then, for each $i = 1, \dots, n$, we have that
$\text{Col}_j(B_1) \in \text{span}(\{\text{Col}_1(B_1), \dots, \text{Col}_{j-1}(B_1)\})$
$\iff j \notin \{i_1, \dots, i_r\}$;
ie the j^{th} column of B_1 is in the span of all the columns to its left <u>if and only if</u> Col_j does not contain a leading one.
Moreover, if $j \notin \{i_1, \dots, i_r\}$ and column j is to the right of the first t leading ones and to the left of the last $r-t$ leading ones, then necessarily
$\text{Col}_j(B_1) \in \text{span}(\{\text{Col}_{i_1}(B_1), \text{Col}_{i_2}(B_1), \dots, \text{Col}_{i_t}(B_1)\})$.
In fact, this implies all but the first t entries of column j must be 0; then, if $\text{Col}_j(B_1) = (a_1, \dots, a_t, 0, \dots, 0)^T$, necessarily $\text{Col}_j(B_1) = a_1 e_1 + \cdots + a_t e_t = a_1 \text{Col}_{i_1}(B_1) + \cdots + a_t \text{Col}_{i_t}(B_1)$.
Thus, the linear dependencies of the columns of B_1 determine the columns that do not contain leading ones.
A similar argument applies for B_2.
Therefore, as B_1 can be transformed to B_2 by a sequence of elementary row operations, and since the columns of B_1 and B_2 satisfy the exact same linear dependencies by PP8 Q4 we have that $B_1 = B_2$, as needed. ☒

Chapter 4: Determinants

WHAT ARE DETERMINANTS? (S4.1)

💡₁ Let $A \in M_{n\times n}(\mathbb{F})$.
Then, the "determinant" of A, denoted as "$\det(A)$" or "$|A|$", is defined as follows:

① $\det(A) := A_{11}$ for $n=1$; and

② $\det(A) := \sum_{i=1}^{n} (-1)^{i+1} A_{i1} \cdot \det(\tilde{A}_{i1})$ for $n \geq 2$,

where

① A_{ij} denotes the entry in row i and column j of A; and

② $\tilde{A}_{ij} \in M_{(n-1)\times(n-1)}(\mathbb{F})$ is the matrix obtained from A by deleting row i and column j. (D39)

💡₂ We also use the following notation to express determinants:

$$\det\left(\begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix}\right) = \begin{vmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{vmatrix} \quad \text{(E47(3))}$$

DETERMINANT FOR 2x2 MATRICES (E47(1))

💡 Let $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$.
Then necessarily $\det(A) = ad - bc$.

Proof. Using the definition above, we get

$$\det(A) = (-1)^2 A_{11} \det(\tilde{A}_{11}) \rightsquigarrow \begin{pmatrix} \cancel{a} & \cancel{b} \\ \cancel{c} & d \end{pmatrix}$$
$$+ (-1)^3 A_{21} \det(\tilde{A}_{21}) \rightsquigarrow \begin{pmatrix} \cancel{a} & b \\ \cancel{c} & \cancel{d} \end{pmatrix}$$

$\therefore \det(A) = ad - bc$, as required. ☒

DETERMINANT FOR 3x3 MATRICES (E47(2))

💡₁ Let $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$.

Then necessarily

$$\det(A) = a_{11}\det\left(\begin{pmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{pmatrix}\right) - a_{21}\det\left(\begin{pmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{pmatrix}\right) + a_{31}\det\left(\begin{pmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{pmatrix}\right).$$

Proof. Again, using the above definition, we get

$$\det(A) = (-1)^2 A_{11} \det(\tilde{A}_{11}) \rightsquigarrow \begin{pmatrix} \cancel{a_{11}} & \cancel{a_{12}} & \cancel{a_{13}} \\ \cancel{a_{21}} & a_{22} & a_{23} \\ \cancel{a_{31}} & a_{32} & a_{33} \end{pmatrix}$$
$$+ (-1)^3 A_{21} \det(\tilde{A}_{21}) \longrightarrow \begin{pmatrix} \cancel{a_{11}} & a_{12} & a_{13} \\ \cancel{a_{21}} & \cancel{a_{22}} & \cancel{a_{23}} \\ \cancel{a_{31}} & a_{32} & a_{33} \end{pmatrix}$$
$$+ (-1)^4 A_{31} \det(\tilde{A}_{31}) \longrightarrow \begin{pmatrix} \cancel{a_{11}} & a_{12} & a_{13} \\ \cancel{a_{21}} & a_{22} & a_{23} \\ \cancel{a_{31}} & \cancel{a_{32}} & \cancel{a_{33}} \end{pmatrix}$$

$$\Rightarrow \det(A) = a_{11}\det\left(\begin{pmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{pmatrix}\right) - a_{21}\det\left(\begin{pmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{pmatrix}\right) + a_{31}\det\left(\begin{pmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{pmatrix}\right),$$ as needed. ☒

💡₂ We can calculate the values of the 2x2 determinants using the strategy in E47(1).

COFACTOR

💡 Let $A \in M_{n\times n}(\mathbb{F})$.
Then, we define the "cofactor" of the entry of A in row i and column j to be equal to

cofactor $= (-1)^{i+j} \det(\tilde{A}_{ij})$.

*for this reason, our definition of discriminants is called the "cofactor expansion along the first column of A".

$A \in M_{2\times 2}(\mathbb{F})$: A IS INVERTIBLE $\Leftrightarrow$ $\det(A) \neq 0$ (T4.1)

💡 Let $A \in M_{2\times 2}(\mathbb{F})$.
Then A is invertible if and only if $\det(A) \neq 0$, and in particular, if A is invertible, then $A^{-1} = \frac{1}{\det(A)}\begin{pmatrix} A_{22} & -A_{12} \\ -A_{21} & A_{11} \end{pmatrix}$.

Proof. ($\Leftarrow$) If $\det(A) \neq 0$, we can verify if $B = \frac{1}{\det(A)}\begin{pmatrix} A_{22} & -A_{12} \\ -A_{21} & A_{11} \end{pmatrix}$, then $AB = I_2$.

($\Rightarrow$) If A is invertible, necessarily $\operatorname{rank}(A) = 2$, so that the first column of A is non-zero.
Hence either $A_{11} \neq 0$ or $A_{21} \neq 0$.

① If $A_{11} \neq 0$, then we can transform

$$\begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \xrightarrow{R_2 \leftarrow R_2 - \frac{A_{21}}{A_{11}} R_1} \begin{pmatrix} A_{11} & A_{12} \\ 0 & A_{22} - \frac{A_{21}A_{12}}{A_{11}} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ 0 & \frac{\det(A)}{A_{11}} \end{pmatrix}.$$

Since elementary operations do not change the rank, the matrix on the right also has rank 2.
Thus, its second row is also non-zero, implying $\frac{\det(A)}{A_{11}} \neq 0$, and so $\det(A) \neq 0$.

② A similar argument can be applied in the case where $A_{21} \neq 0$. ☒

BASIC PROPERTIES OF DETERMINANTS (S4.2)

$\det(I_n) = 1$ (E48)

For any $n \geq 1$, necessarily $\det(I_n) = 1$.

Proof. When $n=1$, the claim is true by definition of determinants in the 1×1 case, and since $I_1 = (1)$.

Next, assume $\det(I_{n-1}) = 1$ for some $n > 1$.

Since

$$I_n = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{pmatrix},$$

note that $(\widetilde{I_n})_{11} = I_{n-1}$, so that

$$\det(I_n) = 1 \cdot \det(I_{n-1}) - 0 \cdot \det((\widetilde{I_n})_{21}) + \cdots + (-1)^{n+1} \cdot 0 \cdot \det((\widetilde{I_n})_{n1})$$

$\therefore \det(I_n) = \det(I_{n-1})$

and so

$\det(I_n) = 1$.

The claim follows from induction. ▨

A IS UPPER TRIANGULAR $\Rightarrow \det(A) = \prod_{i=1}^{n} a_{ii}$ (L10)

Let $A \in M_{n\times n}(\mathbb{F})$ be upper triangular; that is, A is of the form

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ 0 & a_{22} & a_{23} & \cdots & a_{2n} \\ 0 & 0 & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_{nn} \end{pmatrix}.$$

Then necessarily $\det(A) = a_{11} \cdots a_{nn} = \prod_{i=1}^{n} a_{ii}$.

Proof. When $n=1$, the formula is trivially true.

Then, assume the claim is true for $(n-1)\times(n-1)$ upper triangular matrices for some $n>1$.

It follows that, for an $A \in M_{n\times n}(\mathbb{F})$, we have

$$\det(A) = a_{11}\det(\tilde{A}_{11}) - 0 \cdot \det(\tilde{A}_{21}) + \cdots$$
$$= a_{11}\det(\tilde{A}_{11})$$

$\therefore \det(A) = a_{11}(a_{22}\cdots a_{nn})$ (since $\tilde{A}_{11}$ is also upper triangular).

The claim follows by induction. ▨

A HAS A ROW OF ZEROES $\Rightarrow \det(A) = 0$ (L11)

Let $A \in M_{n\times n}(\mathbb{F})$, and suppose A has a row of zeroes.

Then necessarily $\det(A) = 0$.

Proof. If $n=1$, then $A = (0)$, so trivially $\det(A) = 0$.

Then, assume $n>1$, and that the claim is true for matrices of smaller dimensions (ie we are invoking strong induction here).

Suppose $\mathrm{Row}_{i_0}(A) = (0, \ldots, 0)$.

We claim $a_{i1}(-1)^{i+1}\det(\tilde{A}_{i1}) = 0 \quad \forall i = 1, \ldots, n$.

Indeed, if $i \neq i_0$, then $\tilde{A}_{i1}$ has a row of zeroes, so $\det(\tilde{A}_{i1}) = 0$ by induction.

On the other hand, if $i \neq i_0$, then $a_{i_0 1} = 0$.

Hence

$$\det(A) = a_{11}\det(\tilde{A}_{11}) - a_{21}\det(\tilde{A}_{21}) + \cdots \pm a_{n1}\det(\tilde{A}_{n1})$$
$$= 0 - 0 + 0 - \cdots$$

$\therefore \det(A) = 0$.

The claim follows by induction. ▨

A HAS TWO EQUAL <u>ADJACENT</u> ROWS $\Rightarrow \det(A) = 0$ (L12a)

Let $A \in M_{n\times n}(\mathbb{F})$, and suppose A has two equal <u>adjacent</u> rows.

Then necessarily $\det(A) = 0$.

Proof. Suppose $\mathrm{Row}_{i_0}(A) = \mathrm{Row}_{i_0+1}(A)$.

Then for all $i \notin \{i_0, i_0+1\}$, $\tilde{A}_{i1}$ has two adjacent rows, so $\det(\tilde{A}_{i1}) = 0$ by induction.

Moreover, $\tilde{A}_{i_0,1} = \tilde{A}_{i_0+1,1}$, and $a_{i_0,1} = a_{i_0+1,1}$.

$$\begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \\ a_{i_0 1} & \cdots & a_{i_0 n} \\ a_{i_0+1,1} & \cdots & a_{i_0+1,n} \\ \vdots & & \\ a_{n1} & \cdots & a_{nn} \end{pmatrix} = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \\ a_{i_0 1} & \cdots & a_{i_0 n} \\ a_{i_0+1,1} & \cdots & a_{i_0+1,n} \\ \vdots & & \\ a_{n1} & \cdots & a_{nn} \end{pmatrix}$$

(since $\mathrm{Row}_{i_0}(A) = \mathrm{Row}_{i_0+1}(A)$)

Thus in our recursive definition of $\det(A)$, all terms are zero except for those at rows i_0 and i_0+1, and they cancel because they are equal and have opposite sign.

It follows that $\det(A) = 0$, completing the proof. ▨

det IS "LINEAR IN EACH ROW" (T4.2)

1. Note that "det" is "linear in each row"; ie if we fix $n, i_0 \in \mathbb{Z}^+$ and $a_1, \ldots, a_{i_0-1}, a_{i_0+1}, \ldots, a_n \in \mathbb{F}^n$, then for all $b, c \in \mathbb{F}^n$ and $\alpha \in \mathbb{F}$, we have

$$\det\left(\begin{pmatrix} - a_1 - \\ \vdots \\ - b+\alpha c - \\ \vdots \\ - a_n - \end{pmatrix}\right) = \det\left(\begin{pmatrix} - a_1 - \\ \vdots \\ - b - \\ \vdots \\ - a_n - \end{pmatrix}\right) + \alpha \det\left(\begin{pmatrix} - a_1 - \\ \vdots \\ - c - \\ \vdots \\ - a_n - \end{pmatrix}\right).$$

Proof. When $n=1$, we have

$\det(b+\alpha c) = b + \alpha c = \det(b) + \alpha\det(c)$,

proving the base case.

Next, assume $n \geq 2$, and denote

$$A = \begin{pmatrix} - a_1 - \\ \vdots \\ - b+\alpha c - \\ \vdots \\ - a_n - \end{pmatrix}, \quad B = \begin{pmatrix} - a_1 - \\ \vdots \\ - b - \\ \vdots \\ - a_n - \end{pmatrix}, \quad C = \begin{pmatrix} - a_1 - \\ \vdots \\ - c - \\ \vdots \\ - a_n - \end{pmatrix}.$$

By definition, we have

$$\det(A) = \sum_{i=1}^{n} (-1)^{i+1} A_{i1} \det(\tilde{A}_{i1})$$
$$= \left(\sum_{i\neq i_0} (-1)^{i+1} A_{i1}\det(\tilde{A}_{i1})\right) + (-1)^{i_0+1} A_{i_0 1}\det(\tilde{A}_{i_0 1}).$$

Observe that $\tilde{A}_{i_0 1} = \tilde{B}_{i_0 1} = \tilde{C}_{i_0 1}$ and $A_{i_0 1} = B_{i_0 1} + \alpha C_{i_0 1}$.

For $i \neq i_0$, $\tilde{A}_{i1}$, $\tilde{B}_{i1}$ and $\tilde{C}_{i1}$ have the same rows <u>except</u> at one row k, where

$$k = \begin{cases} i_0 - 1, & i < i_0 \\ i_0, & i > i_0 \end{cases}.$$

Moreover, the k^{th} rows of $\tilde{A}_{i1}$, $\tilde{B}_{i1}$ and $\tilde{C}_{i1}$ are $(b+\alpha c)$, b and c respectively.

So by the induction hypothesis, we have

$$\det(\tilde{A}_{i1}) = \det(\tilde{B}_{i1}) + \alpha\det(\tilde{C}_{i1}).$$

We also have $A_{i1} = B_{i1} = C_{i1} \ \forall i \neq i_0$. Thus, it follows that

$$\det(A) = \left(\sum_{i\neq i_0}(-1)^{i+1}A_{i1}\det(\tilde{A}_{i1})\right) + (-1)^{i_0+1}A_{i_0 1}\det(\tilde{A}_{i_0 1}).$$
$$= \left(\sum_{i\neq i_0}(-1)^{i+1}A_{i1}\left(\det(\tilde{B}_{i1}) + \alpha\det(\tilde{C}_{i1})\right)\right) + (-1)^{i_0+1}(B_{i_0 1} + \alpha C_{i_0 1})\det(\tilde{A}_{i_0 1})$$
$$= \sum_{i\neq i_0}(-1)^{i+1}A_{i1}\det(\tilde{B}_{i1}) + \alpha\sum_{i\neq i_0}(-1)^{i+1}A_{i1}\det(\tilde{C}_{i1})$$
$$+ (-1)^{i_0+1}B_{i_0 1}\det(\tilde{A}_{i_0 1}) + \alpha(-1)^{i_0+1}C_{i_0 1}\det(\tilde{A}_{i_0 1})$$
$$= \sum_{i\neq i_0}(-1)^{i+1}B_{i1}\det(\tilde{B}_{i1}) + \alpha\sum_{i\neq i_0}(-1)^{i+1}C_{i1}\det(\tilde{C}_{i1})$$
$$+ (-1)^{i_0+1}B_{i_0 1}\det(\tilde{B}_{i_0 1}) + \alpha(-1)^{i_0+1}C_{i_0 1}\det(\tilde{C}_{i_0 1}) \quad (\text{since } A_{i1} = B_{i1} = C_{i1} \ \& \ \tilde{A}_{i_0 1} = \tilde{B}_{i_0 1} = \tilde{C}_{i_0 1})$$
$$= \left(\sum_{i\neq i_0}(-1)^{i+1}B_{i1}\det(\tilde{B}_{i1}) + (-1)^{i_0+1}B_{i_0 1}\det(\tilde{B}_{i_0 1})\right)$$
$$+ \alpha\left(\sum_{i\neq i_0}(-1)^{i+1}C_{i1}\det(\tilde{C}_{i1}) + (-1)^{i_0+1}C_{i_0 1}\det(\tilde{C}_{i_0 1})\right)$$

$\therefore \det(A) = \det(B) + \alpha\det(C)$,

which is sufficient to prove the claim. ▨

2. If $a_1, \ldots, a_n \in \mathbb{F}^n$, then we use the notation

$$\det(a_1, \ldots, a_n) = \det(A),$$

where $a_i = \mathrm{Row}_i(A) \ \forall i \in 1, \ldots, n)$.

3. Then, by the above theorem, we get that the map

$T: \mathbb{F}^n \to \mathbb{F}$ by $T(x) = \det(a_1, \ldots, a_{i_0-1}, x, a_{i_0+1}, \ldots, a_n)$

is a <u>linear</u> transformation from $\mathbb{F}^n$ to $\mathbb{F}$.

$A \xrightarrow{R_i \leftarrow c\cdot R_i} B \Rightarrow \det(B) = c\det(A)$ (T4.3)

Let $A \xrightarrow{R_i \leftarrow c\cdot R_i} B$; ie let B be the matrix obtained by multiplying a row of A by a scalar c.

Then necessarily $\det(B) = c\det(A)$.

Proof. By T4.2, we have

$$\det(B) = \det(a_1, \dots, ca_i, \dots, a_n) = c\det(a_1, \dots, a_i, \dots, a_n)$$

$\therefore \det(B) = c\det(A)$. ☒

$A \xrightarrow{R_i \leftrightarrow R_{i+1}} B \Rightarrow \det(B) = -\det(A)$ (T4.4a)

Let $A \xrightarrow{R_i \leftrightarrow R_{i+1}} B$; ie let B be the matrix obtained from A by swapping two adjacent rows.

Then necessarily $\det(B) = -\det(A)$.

Proof. Let $a_1, \dots, a_{i-1}, b, c, a_{i+2}, \dots, a_n$ be the rows of A, so that $a_1, \dots, a_{i-1}, c, b, a_{i+2}, \dots, a_n$ are the rows of B.

Let $C \in M_{n\times n}(\mathbb{F})$ be such that its rows are the rows of A, except at row i and $i+1$, where the rows are both equal to $b+c$.

Since C has two identical rows, necessarily $\det(C) = 0$ by L12a.

On the other hand, using T4.2 first in row i and then in row $i+1$, we have

$$\begin{aligned}
0 = \det(C) &= \det(a_1, \dots, a_{i-1}, b+c, b+c, a_{i+2}, \dots, a_n) \\
&= \det(a_1, \dots, a_{i-1}, b, b+c, a_{i+2}, \dots, a_n) \\
&\quad + \det(a_1, \dots, a_{i-1}, c, b+c, a_{i+2}, \dots, a_n) \\
&= \det(a_1, \dots, a_{i-1}, b, b, a_{i+2}, \dots, a_n) \\
&\quad + \det(a_1, \dots, a_{i-1}, b, c, a_{i+2}, \dots, a_n) \\
&\quad + \det(a_1, \dots, a_{i-1}, c, b, a_{i+2}, \dots, a_n) \\
&\quad + \det(a_1, \dots, a_{i-1}, c, c, a_{i+2}, \dots, a_n) \\
&= 0 + \det(A) + \det(B) + 0
\end{aligned}$$

$\therefore 0 = \det(A) + \det(B)$,

and so it follows that $\det(A) = -\det(B)$, as needed. ☒

A HAS TWO EQUAL ROWS $\Rightarrow \det(A) = 0$ (L12)

Let $A \in M_{n\times n}(\mathbb{F})$, and suppose A has two identical rows.

Then necessarily $\det(A) = 0$.

Proof. Suppose $a_1, \dots, a_n$ are rows of A and $a_i = a_j$ for some $i<j$.
By a sequence of k successive swaps of adjacent rows, we can transform A into a matrix B in which the two equal rows are now adjacent.
By T4.4a, each swap of adjacent rows in this transformation changes the determinant by a factor of -1, so that $\det(A) = (-1)^k \det(B)$.

But $\det(B) = 0$ by L12a, proving $\det(A) = 0$. ☒

$A \xrightarrow{R_i \leftrightarrow R_j} B \Rightarrow \det(B) = -\det(A)$ (T4.4)

Let $A \xrightarrow{R_i \leftrightarrow R_j} B$.

Then necessarily $\det(B) = -\det(A)$.

Proof. Let $a_1, \dots, a_n$ be the rows of A.
Let $C \in M_{n\times n}(\mathbb{F})$ be such that the rows of C are the rows of A, except for row i and row j, which are both equal to $a_i + a_j$.
Using a similar argument akin to the proof of T4.4a, but instead using L12 instead of L12a, is sufficient to prove the claim. ☒

$A \xrightarrow{R_i \leftarrow R_i + cR_j} B \Rightarrow \det(B) = \det(A)$ (T4.5)

Let $A \xrightarrow{R_i \leftarrow R_i + cR_j} B$.

Then necessarily $\det(A) = \det(B)$.

Proof. Suppose $a_1, \dots, a_n$ are the rows of A. Suppose first that $i<j$.
Using linearity of det in row i, we have

$$\begin{aligned}
\det(B) &= \det(a_1, \dots, \underbrace{a_i + ca_j}_{\text{position } i}, \dots, a_j, \dots, a_n) \\
&= \det(a_1, \dots, a_i, \dots, a_j, \dots, a_n) + c\det(a_1, \dots, a_j, \dots, a_j, \dots, a_n)
\end{aligned}$$

$\therefore \det(B) = \det(A) + 0$, (since right matrix has two identical rows, so $\det = 0$ by L12)

and so $\det(B) = \det(A)$.

A similar proof proves the claim for the case where $i>j$. ☒

AN ALGORITHM TO CALCULATE $\det(A)$

To calculate the determinant of a square matrix A, we can use the following algorithm:

eg $\det\left(\begin{pmatrix} 0 & 1 & 3 \\ -2 & -3 & -5 \\ 3 & -1 & 1 \end{pmatrix}\right)$ (over $\mathbb{R}$) (E49)

① Transform A into an upper-triangular matrix B using elementary row operations;

$$A = \begin{pmatrix} 0 & 1 & 3 \\ -2 & -3 & -5 \\ 3 & -1 & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} -2 & -3 & -5 \\ 0 & 1 & 3 \\ 3 & -1 & 1 \end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow R_3 + \frac{3}{2}R_1} \begin{pmatrix} -2 & -3 & -5 \\ 0 & 1 & 3 \\ 0 & -\frac{11}{2} & -\frac{13}{2} \end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow 2\cdot R_3} \begin{pmatrix} -2 & -3 & -5 \\ 0 & 1 & 3 \\ 0 & -11 & -13 \end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow R_3 + 11R_2} \begin{pmatrix} -2 & -3 & -5 \\ 0 & 1 & 3 \\ 0 & 0 & 20 \end{pmatrix} = B$$

② Whilst doing ①, keep track of the

i) number of times, k, a type-1 operation was used; and

ii) the constants $c_1, \dots, c_\ell$ used in any type-2 operations.

In the above example, we used
- one type-1 row operation; and
- one type-2 row operation; $R_3 \leftarrow 2\cdot R_3$.

③ Then $\det(B)$ can be calculated via L10; and

$\det(B)$ = product of entries on main diagonal

$\therefore \det(B) = -2\cdot 1\cdot 20 = -40$

④ $\det(B) = \det(A)\cdot(-1)^k c_1 \cdots c_\ell$ by T4.3, T4.4 & T4.5.

$\therefore \det(B) = \det(A)\cdot(-1)(2)$

$\therefore -40 = \det(A)\cdot -2$

$\therefore \det(A) = 20$.

DETERMINANTS, INVERTIBILITY, PRODUCTS & TRANPOSES (S4.3)

DETERMINANTS OF ELEMENTARY MATRICES (C4.5.1)

Let E be the elementary matrix obtained from I_n by an elementary row operation P.

Then,

① If P is type-1, necessarily $\det(E) = -1$;

② If P is type-2, necessarily $\det(E) = c$; and

③ If P is type-3, necessarily $\det(E) = 1$.

Proof. This follows from the fact that $\det(I_n) = 1$, and by T4.3, T4.4 & T4.5. ▨

$\det(E^T) = \det(E)$ (C4.5.2(1))

Let E be an elementary matrix obtained by performing an elementary row operation on I_n.

Then necessarily $\det(E^T) = \det(E)$.

Proof. This follows from the fact that E^T and E are of the same "type", and if the operation is of type-2, then $E^T = E$. ▨

$\det(E^{-1}) = \dfrac{1}{\det(E)}$ (C4.5.2(2))

Let E be an elementary matrix obtained by performing an elementary row operation on I_n.

Then necessarily $\det(E^{-1}) = \frac{1}{\det(E)}$.

Proof. Again, E^{-1} & E are of the same "type".

If the operation is type-1, necessarily $\det(E) = -1$, so $\det(E^{-1}) = -1 = \frac{1}{-1} = \frac{1}{\det(E)}$.

We can verify a similar result if the operation was instead type-2 or type-3 instead. ▨

$\det(EA) = \det(E)\det(A)$ (T4.6)

Let $E \in M_{n \times n}(\mathbb{F})$ be an elementary matrix, and let $A \in M_{n \times n}(\mathbb{F})$.

Then necessarily $\det(EA) = \det(E)\det(A)$.

Proof. EA is the result of applying to A the row operation corresponding to E.

So, by T4.3, T4.4 & T4.5, necessarily $\det(EA)$ is equal to $\det(A)$ multiplied by a factor determined by the row operation.

By C4.5.1, we know this factor is exactly $\det(E)$.

The claim follows from these observations. ▨

$\det(E_1 \cdots E_k A) = \det(E_1) \cdots \det(E_k)\det(A)$ (C4.6.1)

Let $A \in M_{n \times n}(\mathbb{F})$, and let $E_1, \ldots, E_k$ be elementary matrices.

Then necessarily

$\det(E_1 \cdots E_k A) = \det(E_1) \cdots \det(E_k)\det(A)$. (C4.6.1(1))

In particular, if $A = I_n$, we get that

$\det(E_1 \cdots E_k) = \det(E_1) \cdots \det(E_k)$. (C4.6.1(2))

Proof. This follows from T4.6. ▨

INVERTIBLE MATRIX THEOREM, PART 5 (T4.7)

Let $A \in M_{n \times n}(\mathbb{F})$.

Then A is invertible if and only if $\det(A) \neq 0$.

Proof. ($\Rightarrow$) Since A is invertible, necessarily $A = E_1 \cdots E_q$, where $E_1, \ldots, E_q$ are elementary matrices.

By C4.6.1(2), and noting $\det(E_i) \neq 0$ by C4.5.1, it follows that

$\det(A) = \det(E_1) \cdots \det(E_q) \neq 0$. ✱

($\Leftarrow$) Let A be such that $\det(A) \neq 0$.

Suppose A is not invertible, so that $\operatorname{rank}(A) < n$.

Let R be the RREF of A.

By the above, since $\operatorname{rank}(A) = \#$ of non-zero rows of R, necessarily R has at least one zero row.

So, by L11, $\det(R) = 0$.

On the other hand, since R is the RREF of A, we can transform R to A via a sequence of elementary row operations.

Thus, there exist elementary matrices $E_1, \ldots, E_p$ such that $A = E_1 \cdots E_p R$.

So, by C4.6.1(1), we get $\det(A) = \det(E_1) \cdots \det(E_p)\det(R) = 0$, a contradiction.

It follows that A must be invertible. ▨

$\operatorname{rank}(A) < n \Rightarrow \det(A) = 0$ (C4.7.1)

Let $A \in M_{n \times n}(\mathbb{F})$ be such that $\operatorname{rank}(A) < n$.

Then necessarily $\det(A) = 0$.

Proof. If $\operatorname{rank}(A) < n$, A is not invertible, so by the above, $\det(A) = 0$ necessarily. ▨

$\det(AB) = \det(A)\det(B)$ (T4.8)

Let $A, B \in M_{n \times n}(\mathbb{F})$.

Then necessarily $\det(AB) = \det(A)\det(B)$.

Proof. If A is invertible, then $A = E_1 \cdots E_q$, where $E_1, \ldots, E_q$ are elementary matrices.

So, by C4.6.1, we have

$\det(AB) = \det(E_1 \cdots E_q B) = \det(E_1) \cdots \det(E_q)\det(B) = \det(A)\det(B)$.

If A is not invertible, then AB is also not invertible; hence $\det(AB) = 0 = 0 \cdot \det(B) = \det(A)\det(B)$. ▨

$\det(A) = \det(A^T)$ (T4.9)

Let $A \in M_{n \times n}(\mathbb{F})$.

Then necessarily $\det(A) = \det(A^T)$.

Proof. Suppose A is not invertible, so $\det(A) = 0$.

Then $\operatorname{rank}(A) < n$, and since $\operatorname{rank}(A) = \operatorname{rank}(A^T)$ by C3.6.1, we have $\operatorname{rank}(A^T) < n$ too.

So, by C4.7.1, necessarily $\operatorname{rank}(A^T) = 0 = \operatorname{rank}(A)$.

Next, suppose A is invertible, so there exist elementary matrices $E_1, \ldots, E_k$ such that $A = E_1 \cdots E_k$.

Then $A^T = (E_1 \cdots E_k)^T = E_k^T \cdots E_1^T$ by L5, so

$$\begin{aligned}
\det(A^T) &= \det(E_k^T) \cdots \det(E_1)^T \\
&= \det(E_k) \cdots \det(E_1) \quad \text{(by C4.5.2(1))} \\
&= \det(E_1) \cdots \det(E_k) \\
&= \det(E_1 \cdots E_k)
\end{aligned}$$

$\therefore \det(A^T) = \det(A)$. ▨

OTHER COFACTOR EXPANSIONS (S4.4)

$A \xrightarrow{C_i \leftrightarrow C_j} B \Rightarrow \det(B) = -\det(A)$ (C4.9.1)

Let $A \xrightarrow{C_i \leftrightarrow C_j} B$; ie B is obtained from A by swapping two columns.

Then necessarily $\det(B) = \det(A)$.

Proof. If $A \xrightarrow{C_i \leftrightarrow C_j} B$, then $A^T \xrightarrow{R_i \leftrightarrow R_j} B^T$.

Thus $\det(B^T) = -\det(A^T)$ by T4.4, so

$\det(B) = \det(B^T) = -\det(A^T) = -\det(A)$ by

T4.9. ▨

DETERMINANT CAN BE CALCULATED VIA COFACTOR EXPANSION ALONG ANY COLUMN (T4.10)

Let $A \in M_{n\times n}(\mathbb{F})$.

Then $\det(A)$ can be calculated via cofactor expansion along any column.

In other words, for a fixed $j \in \{1, \dots, n\}$, we have

$$\det(A) = \sum_{i=1}^{n} (-1)^{i+j} A_{ij} \det(\tilde{A}_{ij}),$$

where $(-1)^{i+j} \det(\tilde{A}_{ij})$ is the "cofactor" of A at i,j.

Proof. Let $a_1, \dots, a_n$ be columns of A, so

$$A = (a_1 \ \cdots \ a_j \ \cdots \ a_n).$$

Let $B = (a_j \ a_1 \cdots a_{j-1} \ a_{j+1} \cdots a_n)$; ie B is obtained from A by cyclically shifting its first j columns to the right one position.

Also, note that A can be obtained from B by $j-1$ successive swaps of adjacent columns, so $\det(A) = (-1)^{j-1} \det(B)$ by C4.9.1.

We have

$$\det(B) = \sum_{i=1}^{n} (-1)^{i+1} B_{i1} \det(\tilde{B}_{i1}) = \sum_{i=1}^{n} (-1)^{i+1} A_{ij} \det(\tilde{A}_{ij}),$$

and so

$$\det(A) = (-1)^{j-1} \det(B) = \sum_{i=1}^{n} (-1)^{i+j} A_{ij} \det(\tilde{A}_{ij}),$$

as needed. ▨

DETERMINANT CAN BE CALCULATED VIA COFACTOR EXPANSION ALONG ANY ROW (C4.10.1)

Let $A \in M_{n\times n}(\mathbb{F})$.

Then $\det(A)$ can necessarily be calculated by cofactor expansion along any row.

In other words, for any fixed $i \in \{1, \dots, n\}$, we have

$$\det(A) = \sum_{j=1}^{n} (-1)^{i+j} A_{ij} \det(\tilde{A}_{ij}).$$

Proof. Cofactor expansion of A along row i is the same as cofactor expansion of A^T along column i.

The latter gives $\det(A^T)$ by T4.10, and since $\det(A^T) = \det(A)$ by T4.9, this completes the proof. ▨

* these results help us to find determinants of matrices faster, since it is quicker to do cofactor expansion on a row/column with more zeroes.