

MATH 247

Personal Notes

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Module I.I:

Normed Vector Spaces

A "normed vector space", or "NVS", is a vector space V over \mathbb{R} equipped with a function

$$\|\cdot\| : V \rightarrow [0, \infty),$$

and the function satisfies the following:

- ① $\|v\| = 0 \iff v = 0$;
- ② $\|av\| = |a| \cdot \|v\| \quad \forall a \in \mathbb{R}$; and
- ③ $\|u+v\| \leq \|u\| + \|v\|$. (Triangle Inequality).

Such a function $\|\cdot\|$ is called a "norm".

We generally use the notation " $(V, \|\cdot\|)$ " to indicate a normed vector space.

Geometrically,

- ① $\|v\|$ refers to the "length" of v , or the distance between v & 0 ; and
- ② $\|v-w\|$ refers to the "distance" between v & w .

Normed vector spaces are useful in real analysis because the "notion" of "distance" in NVS helps us talk about "approximating" real numbers with more well-behaved ones (eg \mathbb{Q}).

p-NORMS: $\|v\|_p$

Let $p \geq 1$, and let $v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \in \mathbb{R}^n$. Then, the "p-norm" of v , denoted as " $\|v\|_p$ ", is equal to

$$\|v\|_p = \left(\sum_{i=1}^n |v_i|^p \right)^{\frac{1}{p}}.$$

We can show that the p-norm is indeed a norm of \mathbb{R}^n (see A1.)

In particular, the 2-norm,

$$\|v\|_2 = \left(\sum_{i=1}^n |v_i|^2 \right)^{\frac{1}{2}},$$

is called the "Euclidean norm" on \mathbb{R}^n ;

In this course, we equip \mathbb{R}^n with $\|\cdot\|_2$, unless stated otherwise.

INFINITY NORM: $\|v\|_\infty$

Let $v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \in \mathbb{R}^n$. Then, the "infinity norm" of v , denoted as " $\|v\|_\infty$ ", is defined to be

$$\|v\|_\infty = \max \{|v_1|, |v_2|, \dots, |v_n|\}.$$

$(\mathbb{R}^p, \|\cdot\|_p)$ & $(\mathbb{R}^\infty, \|\cdot\|_\infty)$ ARE

NVS OF \mathbb{R}^N

Let $v = (v_1, v_2, \dots) \in \mathbb{R}^N$ (ie let v be a sequence of reals).

Then, we let \mathbb{L}^p be defined by

$$\mathbb{L}^p = \{v \in \mathbb{R}^N : \|v\|_p < \infty\},$$

where

$$\|v\|_p = \left(\sum_{i=1}^{\infty} |v_i|^p \right)^{\frac{1}{p}}.$$

Similarly, we let \mathbb{L}^∞ be defined by

$$\mathbb{L}^\infty = \{v \in \mathbb{R}^N : \|v\|_\infty < \infty\},$$

where

$$\|v\|_\infty = \max \{|v_1|, |v_2|, \dots\}.$$

Then, $(\mathbb{L}^p, \|\cdot\|_p)$ & $(\mathbb{L}^\infty, \|\cdot\|_\infty)$ are NVS.

UNIFORM NORM ON $C([a,b])$: $\|f\|_\infty$

Let $V = C([a,b])$, ie the set of all continuous functions $f: [a,b] \rightarrow \mathbb{R}$.

Then, the "uniform norm" of a $f \in V$, denoted as " $\|f\|_\infty$ ", is defined to be

$$\|f\|_\infty = \sup \{ |f(x)| : x \in [a,b] \}$$

Unless otherwise stated, we assume the uniform norm is used if working with \mathbb{R}^N as a NVS.

An alternative norm to \mathbb{R}^N is the "integration-based" norm $\|f\|_p$, where $p \geq 1$ and $f \in V$, which is defined as

$$\|f\|_p = \left(\int_a^b |f(x)|^p dx \right)^{\frac{1}{p}}.$$

Module 1.2:

Convergence

CONVERGENCE / DIVERGENCE

Q_1 : Let V be a NVS, and let the sequence $(a_n) \subseteq V$. Then, we say (a_n) "converges" to some $a \in V$, denoted " $a_n \rightarrow a$ ", if for all $\epsilon > 0$, there exists a $N \in \mathbb{N}$ such that $\|a_n - a\| < \epsilon \quad \forall n \geq N$.

Q_2 : Otherwise, we say that (a_n) diverges.

eg: $V = \mathbb{R}^\infty, (a_n) \subseteq V$

$$a_n = (1, \frac{1}{2}, \dots, \frac{1}{n}, 0, 0, \dots)$$

$$a = (1, \frac{1}{2}, \frac{1}{3}, \dots)$$

Claim: $a_n \rightarrow a$

Proof: let $\epsilon > 0$, and choose $N \in \mathbb{N}$ such that $\frac{1}{N} < \epsilon$.

Then, for $n \geq N$, note that

$$\begin{aligned} \|a_n - a\|_\infty &= \left\| (0, 0, \dots, 0, \underbrace{\frac{1}{n+1}, \dots, \frac{1}{n+1}}_{n+1}, 0, 0, \dots) \right\|_\infty \\ &= \sup \left\{ 0, \frac{1}{n+1}, \frac{1}{n+2}, \dots \right\} \\ &= \frac{1}{n+1} < \frac{1}{n} < \frac{1}{N} < \epsilon. \end{aligned}$$

showing that the sequence converges. \blacksquare

eg²: $V = \mathbb{R}^\infty, (a_n) \subseteq V$

$$a_n = (\underbrace{1, \dots, 1}_{n}, 0, 0, \dots)$$

$$a = (1, 1, \dots, 1, \dots)$$

Claim: $a_n \rightarrow a$.

Proof: $\forall n \in \mathbb{N}: \|a_n - a\|_\infty = 1$

(since always 1 present in the sequence $(a_n - a)$).

BOUNDED (SUBSET)

Q_1 : Let $A \subseteq V$, where V is a NVS.

Then, we say A is "bounded" if there exists a $M > 0$ such that $\|a\| \leq M$ for all $a \in A$.

BOUNDED (SEQUENCES)

Q_1 : Let $(a_n) \subseteq V$, where V is a NVS.

Then, we say (a_n) is "bounded" if $\{a_1, \dots, a_n, \dots\}$ is itself bounded.

(a_n) IS CONVERGENT $\Rightarrow (a_n)$ IS BOUNDED

Q_1 : Let $(a_n) \subseteq V$ be so that (a_n) is convergent.

Then necessarily (a_n) is bounded.

Proof: Suppose $a_n \rightarrow a \in V$.

$\Rightarrow \exists N \in \mathbb{N}$ such that if $n \geq N$, then $\|a_n - a\| < 1$.

Then, notice that for $n \geq N$,

$$\begin{aligned} \|a_n\| &= \|a_n - a + a\| \\ &\leq \|a_n - a\| + \|a\| \\ &\leq 1 + \|a\|. \end{aligned}$$

Let $M = \max \{ \|a_1\|, \dots, \|a_N\|, 1 + \|a\| \}$, we have that $\|a_n\| \leq M \quad \forall n \in \mathbb{N}$, as needed. \blacksquare

Q_2 : Note the converse is not necessarily true!

eg: $(a_n) = (1, -1, 1, -1, \dots)$

$$a_n \rightarrow a, b_n \rightarrow b \Rightarrow a_n + b_n \rightarrow a + b$$

Q_1 : Let $(a_n, b_n) \subseteq V$, and let $a_n \rightarrow a$ & $b_n \rightarrow b$. Then necessarily $a_n + b_n \rightarrow a + b$.

$$a_n \rightarrow a \Rightarrow a/a_n \rightarrow a/a$$

Q_1 : Let $(a_n) \subseteq V$, and let $a_n \rightarrow a$. Then necessarily $a_n \rightarrow a$.

Module 1.3: Completeness

CAUCHY SEQUENCE

Let $(a_n) \subseteq V$, where V is a NVS.

Then, we say (a_n) is a "Cauchy sequence" if

for all $\epsilon > 0$, there exists a $N \in \mathbb{N}$ such that

$|a_n - a_m| < \epsilon$ for all $n, m \geq N$.

(a_n) IS CONVERGENT \Rightarrow (a_n) IS CAUCHY

Let $(a_n) \subseteq V$ be convergent.

Then necessarily (a_n) is also Cauchy.

Proof. Let $\epsilon > 0$. We know $N \in \mathbb{N}$, $a \in V$ such that $|a_n - a| < \frac{\epsilon}{2} \forall n \geq N$.

Also, for $n, m \geq N$, we know

$$|a_n - a_m| \leq |a_n - a| + |a_m - a|$$

$$< \epsilon.$$

as needed. \square

(a_n) IS CAUCHY \Rightarrow (a_n) IS CONVERGENT

Note that $(a_n) \subseteq V$ is Cauchy does not necessarily imply it is also convergent.

For example, take the NVS $(C_\infty, \| \cdot \|_\infty)$, where

$$C_\infty = \{(x_n) \in \ell^\infty : \exists N \ni x_n=0 \forall n \geq N\},$$

and let $(a_n) \subseteq C_\infty$ be defined by

$$a_n = (1, \frac{1}{2}, \dots, \frac{1}{n}, 0, 0, \dots),$$

and let a be equal to

$$a = (1, \frac{1}{2}, \frac{1}{3}, \dots) \notin C_\infty.$$

We know $a_n \rightarrow a$ in ℓ^∞ , so $(a_n) \subseteq \ell^\infty$ is Cauchy.

$\Rightarrow (a_n) \subseteq C_\infty$ is still Cauchy.

However, since $a_n \rightarrow a \notin C_\infty$, and limits are unique,

it follows that $(a_n) \subseteq C_\infty$ diverges.

COMPLETE

Let $A \subseteq V$, where V is a NVS.

Then, we say A is "complete" if whenever $(a_n) \subseteq A$ is Cauchy,

it follows that there exists an $a \in A$ such that

$$a_n \rightarrow a.$$

BANACH SPACE

Let V be a NVS.

Then, we say V is a "Banach space" if V is

complete.

Module 1.4:

Banach Spaces

\mathbb{R}^n IS A BANACH SPACE WRT $\|\cdot\|_p$ & $\|\cdot\|_\infty$

Q1 First, let $v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \in \mathbb{R}^n$ & $1 \leq p \leq \infty$.

Then, note the following:

$$\textcircled{1} \quad \|v\|_p^p = |v_1|^p + \dots + |v_n|^p \leq n \max\{|v_1|, \dots, |v_n|\}^p$$

$$\therefore \|v\|_p^p \leq n \|v\|_\infty^p;$$

$$\textcircled{2} \quad \|v\|_\infty^p \leq |v_1|^p + \dots + |v_n|^p = \|v\|_p^p.$$

$$\textcircled{3} \quad \text{So, } \|v\|_p \leq \sqrt[n]{n} \|v\|_\infty, \text{ and}$$

$$\|v\|_\infty \leq \|v\|_p.$$

Q2 We can also show $(\mathbb{R}^n, \|\cdot\|_\infty)$ is a Banach space.

Proof. Suppose $(a_k) \subseteq \mathbb{R}^n$ is Cauchy, say

$$a_k = (a_k^{(1)}, \dots, a_k^{(n)})$$

for each $k \in \mathbb{N}$, where $a_k^{(i)} \in \mathbb{R}$.

Let $\epsilon > 0$. We know $\exists N \in \mathbb{N}$ such that $\|a_n - a_N\|_\infty < \epsilon$ for

all $n, k \geq N$.

Then, for all $n, k \geq N$ and $i \in \mathbb{N}$, we have that

$$|a_n^{(i)} - a_k^{(i)}| \leq \|a_n - a_k\|_\infty < \epsilon,$$

and so it follows that $(a_n^{(i)})_{n=1}^\infty \subseteq \mathbb{R}$ is Cauchy.

Finally, since \mathbb{R} is complete, it follows that

$$a_n^{(i)} \rightarrow b_i \in \mathbb{R} \quad \forall i \in \mathbb{N}.$$

To finish, we want to prove $a_n \rightarrow (b_1, \dots, b_n)$, which is sufficient to prove the statement in question.

Let $\epsilon > 0$. Fix $i \in \mathbb{N}$.

We know there exists a $N_i \in \mathbb{N}$ such that $|a_n^{(i)} - b_i| < \epsilon \quad \forall n \geq N_i$.

Let $N = \max\{N_1, N_2, \dots, N_n\}$, so that for $n \geq N$, we have that

$$\|a_n - (b_1, \dots, b_n)\|_\infty = \max\{|a_n^{(i)} - b_i| : 1 \leq i \leq n\}$$

$$\leq \epsilon.$$

Completing the proof (as $a_n \rightarrow (b_1, \dots, b_n)$). \blacksquare

Q3 This is sufficient to prove $(\mathbb{R}^n, \|\cdot\|_p)$ is a Banach space.

Proof. Assume $(\mathbb{R}^n, \|\cdot\|_\infty)$ is a Banach space.

Let $1 \leq p < \infty$, and let $(a_k) \subseteq \mathbb{R}^n$ be Cauchy wrt $\|\cdot\|_p$.

Thus, (a_k) is Cauchy wrt $\|\cdot\|_\infty$, and so

$a_k \rightarrow a \in \mathbb{R}^n$ wrt $\|\cdot\|_\infty$.

Hence $a_k \rightarrow a$ wrt $\|\cdot\|_p$, and so $(\mathbb{R}^n, \|\cdot\|_p)$ is also a Banach space. \blacksquare

ℓ^∞ IS A BANACH SPACE

Q1 We can prove ℓ^∞ is a Banach space.

Proof. Let $(a_n) \subseteq \ell^\infty$ be Cauchy.

For all $n \in \mathbb{N}$, we can write

$$a_n = (a_n^{(1)}, a_n^{(2)}, \dots),$$

where $a_n^{(i)} \in \mathbb{R}$.

We claim for all $i \in \mathbb{N}$, that $(a_n^{(i)})$ is Cauchy.

Proof. Let $\epsilon > 0$ be given.

Then, there exists a $N \in \mathbb{N}$ such that $\|a_n - a_m\|_\infty < \epsilon$ for

$\forall n, m \geq N$.

Next, fix $i \in \mathbb{N}$. For $n, m \geq N$, note that

$$|a_n^{(i)} - a_m^{(i)}| \leq \sup\{|a_n^{(i)} - a_m^{(i)}| : i \in \mathbb{N}\}$$

$$= \|a_n - a_m\|_\infty$$

< ϵ ,

proving the claim. \blacksquare

So, by the completeness of \mathbb{R} , we have that

$$a_n^{(i)} \rightarrow b_i \quad (\text{as } n \rightarrow \infty)$$

for all $i \in \mathbb{N}$.

Next, we claim that $a_n \rightarrow b$, where $b = (b_1, b_2, \dots)$.

Proof. Let $\epsilon > 0$ be given.

Then, we know $\exists N \in \mathbb{N}$ such that $\|a_n - b\|_\infty < \epsilon$ for

$\forall n \geq N$.

We also have that

$$|a_n^{(i)} - b_i| \leq \epsilon \quad \forall n \geq N \text{ and } i \in \mathbb{N}$$

by definition.

Next, taking $n \rightarrow \infty$, we note for $n \geq N$ that

$$|a_n^{(i)} - b_i| \leq \epsilon \quad \forall i \in \mathbb{N}.$$

Thus $\|a_n - b\|_\infty < \epsilon$ for all $n \geq N$, and so indeed

$a_n \rightarrow b$.

It follows that ℓ^∞ is a Banach space, as needed. \blacksquare

Module 2.1:

Closed and Open Sets

CLOSED SET

\exists : let V be a NVS, and let $C \subseteq V$. Then, we say C is "closed" if whenever $(a_n) \subseteq C$ with $a_n \rightarrow a \in V$, then $a \in C$.

OPEN SET

\exists : let V be a NVS, and let $U \subseteq V$. Then, we say U is "open" if $V \setminus U$ is closed.

TOPOLOGY ON A SPACE

\exists : let V be a NVS. Then, the "topology" on V is defined to be the set

$$T = \{U \subseteq V \mid U \text{ is open}\}.$$

\emptyset, V ARE OPEN & CLOSED IN V

\exists : Note \emptyset and V are always open and closed in V .

CLOSED BALL: $\overline{B_r(a)}$

\exists : let $r > 0$ and $a \in V$, where V is a NVS. Then, the "closed ball" of radius r centred at a , denoted as " $\overline{B_r(a)}$ ", is defined to be the set

$$\overline{B_r(a)} = \{x \in V : \|x-a\| \leq r\}.$$

We can prove $\overline{B_r(a)}$ is closed.

Proof: let $(a_n) \subseteq \overline{B_r(a)} \Rightarrow a_n \rightarrow b \in V$.

By defn, $\|a_n-a\| \leq r \quad \forall n \in \mathbb{N}$.

But since $a_n \rightarrow a$, it follows that

$$\|a_n-a\| \rightarrow \|b-a\|,$$

and so $\|b-a\| \leq \max\{\|a_n-a\| : n \in \mathbb{N}\} \leq r$,

and so $b \in \overline{B_r(a)}$, which is sufficient to prove the statement. \blacksquare

OPEN BALL: $B_r(a)$

\exists : let $r > 0$ and $a \in V$, where V is a NVS. Then, the "open ball" of radius r centred at a , denoted as " $B_r(a)$ ", is defined to be the set

$$B_r(a) = \{x \in V : \|x-a\| < r\}.$$

We can show $B_r(a)$ is open.

Proof: By a similar proof to the above, we can show $\{x \in V : \|x-a\| \geq r\}$ is closed.

Hence

$$B_r(a) = V \setminus \{x \in V : \|x-a\| \geq r\}$$

is open. \blacksquare

$V = \mathbb{R}^\infty$, $C_0 = \{(x_n) \in \mathbb{R}^\infty \mid x_n \rightarrow 0\}$ IS CLOSED

\exists : we can show $C_0 = \{(x_n) \in \mathbb{R}^\infty \mid x_n \rightarrow 0\}$ is closed in $V = \mathbb{R}^\infty$.

Proof: let $(a_n) \subseteq C_0 \Rightarrow a_n \rightarrow 0 \in \mathbb{R}^\infty$.

let $a_n = (a_n^{(1)}, a_n^{(2)}, \dots) \quad \forall n \in \mathbb{N}$.

Hence, we know

$$\lim_{n \rightarrow \infty} a_n^{(k)} = 0 \quad \forall k \in \mathbb{N}.$$

Then, say $a = (b_1, b_2, \dots)$, and let $\epsilon > 0$.

we know there exists $N_1, N_2 \in \mathbb{N} \Rightarrow$

$$\textcircled{1} \quad \|a_{N_1} - a\|_\infty < \frac{\epsilon}{2} \quad \forall n \geq N_1 \text{ and}$$

$$\textcircled{2} \quad |a_{N_1}^{(k)}| < \frac{\epsilon}{2} \quad \forall k \geq N_2.$$

Finally, for $k \geq N_2$, note that

$$\begin{aligned} |b_k| &= |a_{N_1}^{(k)} - b_k - a_{N_1}^{(k)}| \\ &\leq |a_{N_1}^{(k)} - b_k| + |a_{N_1}^{(k)}| \\ &\leq \|a_{N_1} - a\|_\infty + |a_{N_1}^{(k)}| \\ &< \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon, \end{aligned}$$

Showing $b_k \rightarrow 0$ and so $a = (b_1, b_2, \dots) \in C_0$, and so C_0 is closed. \blacksquare

U IS OPEN $\Leftrightarrow \forall a \in U : \exists r > 0 \Rightarrow B_r(a) \subseteq U$

\exists : let V be a NVS, and let $U \subseteq V$. Then, U is open if and only if for any $a \in U$, there exists a $r > 0$ such that $B_r(a) \subseteq U$.

Proof: (\Rightarrow) Assume U is open, so

$V \setminus U$ is closed.

Suppose, for a contradiction, that

$$a \in U \Rightarrow (\nexists r > 0 \Rightarrow B_r(a) \not\subseteq U).$$

In particular, $\forall n \in \mathbb{N}$, there exists some $a_n \in B_r(a)$ such that $a_n \notin U$.

Note that

$$\textcircled{1} \quad \|a_n - a\| < \frac{1}{n} \Rightarrow a_n \rightarrow a \quad (\text{since } \frac{1}{n} \rightarrow 0); \text{ and}$$

$$\textcircled{2} \quad (a_n) \subseteq V \setminus U, \text{ and } V \setminus U \text{ is closed}$$

$$\Rightarrow a \in V \setminus U.$$

But $a \in U$ by assumption, a contradiction.

Thus $\forall a \in U : \exists r > 0 \Rightarrow B_r(a) \subseteq U$, as needed. \blacksquare

(\Leftarrow) Assume $\forall a \in U : \exists r > 0 \Rightarrow B_r(a) \subseteq U$.

We claim $V \setminus U$ is closed. Indeed, let

$$(a_n) \subseteq V \setminus U \Rightarrow a_n \notin U.$$

Suppose $a \in U$, so in particular $\exists r > 0 \Rightarrow B_r(a) \subseteq U$.

But since $a_n \rightarrow a$, $\exists N \in \mathbb{N} \Rightarrow \|a_N - a\| < r$,

implying $a_N \in B_r(a) \subseteq U$, and so $a_N \in U$.

However we assumed $a_N \in V \setminus U$, so this is a contradiction!

Hence $V \setminus U$ is closed, and so U is open, as needed.

For any arbitrary point, you can draw a "circle" that is contained in U .

Module 2.2-2.4:

Closure and Interior

UNION OF OPEN SETS IS OPEN

\vdash : let V be a NVS, and let $\{U_\alpha\}_{\alpha \in I}$ be a collection of open sets in V . Then necessarily $U = \bigcup_{\alpha \in I} U_\alpha$ is open.

INTERSECTION OF CLOSED SETS IS CLOSED

\vdash : let V be a NVS, and let $\{C_\alpha\}_{\alpha \in I}$ be a collection of closed sets in V . Then necessarily $C = \bigcap_{\alpha \in I} C_\alpha$ is closed.

FINITE INTERSECTION OF OPEN SETS IS OPEN

\vdash : let $U_1, \dots, U_n \subseteq V$ be open. Then necessarily $U = U_1 \cap \dots \cap U_n$ is open.

FINITE UNION OF CLOSED SETS IS CLOSED

\vdash : let $C_1, \dots, C_n \subseteq V$ be closed. Then necessarily $C = C_1 \cup \dots \cup C_n$ is closed.

CLOSURE OF A SUBSET: \bar{A}

\vdash : let $A \subseteq V$. Then, we define the "closure" of A , denoted as " \bar{A} ", to be the set

$$\bar{A} = \bigcap_{\substack{\text{closed} \\ C \text{ closed}}} C. \quad * \bar{A} \text{ is the smallest closed set containing } A.$$

INTERIOR OF A SUBSET: $\text{Int}(A)$

\vdash : let $A \subseteq V$. Then, we define the "interior" of A , denoted as " $\text{int}(A)$ ", to be the set

$$\text{Int}(A) = \bigcup_{\substack{\text{open} \\ U \subseteq A}} U. \quad * \text{Int}(A) \text{ is the largest open set contained in } A.$$

LIMIT POINT

\vdash : let V be a NVS, and let $a \in V$. Then, we say $a \in V$ is a "limit point" of A if there exists a $(a_n) \subseteq V$ with $a_n \rightarrow a$.

INTERIOR POINT

\vdash : let V be a NVS, and let $a \in V$. Then, we say $a \in V$ is an "interior point" of A if there exists a $r > 0$ such that $B_r(a) \subseteq A$.

$\bar{A} = \{\text{limit points of } A\}$

\vdash : we can show that \bar{A} is the set of limit points of A for any $A \subseteq V$.

Proof: let $X = \{\text{limit points of } A\}$.

claim: X is closed.

Proof: let $(a_n) \subseteq X \Rightarrow a_n \rightarrow a \in V$.

In particular, we know

$$\forall n \in \mathbb{N}, \exists b_n \in A \Rightarrow |a_n - b_n| < \frac{1}{n}.$$

But we also know

$$b_n = b_n - a_n + a_n \rightarrow 0 + a = a,$$

and so $a \in A$, showing X is closed. \blacksquare

By definition, we know $\bar{A} \subseteq X$, since \bar{A} is the smallest closed set that contains A .

Now, let $x \in X$, so that $\exists (a_n) \subseteq A \Rightarrow a_n \rightarrow x$.

let $C \subseteq V$ be closed, so that $A \subseteq C$.

Then, note $(a_n) \subseteq C$, and so $x \in C$ (since C is closed).

Thus x is in any closed set containing A , and so

$X \subseteq \bar{A}$ (and thus $X = \bar{A}$, as needed). \blacksquare

$\text{Int}(A) = \{\text{interior points of } A\}$

\vdash : similarly, we can show $\text{int}(A)$ is the set of interior points of A for any $A \subseteq V$.

Proof: similar to above.

$$A = \{(a_n) \in \mathbb{I}^1 : a_n \in Q\} : \bar{A} = \mathbb{I}^1$$

\vdash : we claim $\bar{A} = \mathbb{I}^1$.

Note: for $x \in \mathbb{I}^1$, assume $\forall \epsilon > 0, \exists a \in A : \|x-a\| < \epsilon$.

Then: $x \in \bar{A}$.

why?: $\forall n \in \mathbb{N} : \exists a_n \in A \Rightarrow \|x-a_n\| < \frac{1}{n}$.

$$\Rightarrow (a_n) \subseteq A \text{ and so } a_n \rightarrow x.$$

Proof: let $x = (x_1, x_2, \dots) \in \mathbb{I}^1$ and let $\epsilon > 0$.

By the density of Q ,

$$\forall n \in \mathbb{N} : \exists y_n \in Q \Rightarrow \|x_n - y_n\| < \frac{\epsilon}{2^n}.$$

Consider $y = (y_1, y_2, \dots)$.

Then, note that

$$\|x-y\|_1 = \sum_{n=1}^{\infty} |x_n - y_n|$$

$$< \sum_{n=1}^{\infty} \frac{\epsilon}{2^n}$$

$$= \epsilon,$$

which is sufficient to show $x \in \bar{A}$, and so

$$\mathbb{I}^1 \subseteq \bar{A}.$$

As $\bar{A} \subseteq \mathbb{I}^1$ by definition, it follows that $\bar{A} = \mathbb{I}^1$, as needed. \blacksquare

$$V = \mathbb{I}^\infty; \bar{C}_0 = C_0$$

\vdash : we can show $\bar{C}_0 = C_0$ in $V = \mathbb{I}^\infty$.

Proof: we know $C_0 \subseteq \bar{C}_0$, and since C_0 is closed, it follows that $\bar{C}_0 \subseteq C_0$.

Now, let $x = (x_1, x_2, \dots) \in C_0$, and let $\epsilon > 0$.

Since $x_n \rightarrow 0$, it follows that

$$\exists N \in \mathbb{N} \Rightarrow \|x_n\| \leq \frac{\epsilon}{2} \forall n \geq N.$$

let $y = (x_1, \dots, x_{N-1}, 0, 0, \dots) \in C_0$.

It follows that

$$\begin{aligned} \|x-y\|_\infty &= \|(0, \dots, 0, x_N, x_{N+1}, \dots)\|_\infty \\ &= \sup_k \{|x_k| : k \geq N\} \\ &\leq \frac{\epsilon}{2} < \epsilon, \end{aligned}$$

and so necessarily $x \in \bar{C}_0$, and so $C_0 \subseteq \bar{C}_0$. Thus $C_0 = \bar{C}_0$, as needed. \blacksquare

$$\overline{A \cup B} = \overline{A} \cup \overline{B}$$

let $A, B \subseteq V$.
Then necessarily $\overline{A \cup B} = \overline{A} \cup \overline{B}$.

Proof. Since $\overline{A \cup B}$ is closed & $A \cup B \subseteq \overline{A \cup B}$, it follows $\overline{A \cup B} \subseteq \overline{A \cup B}$.
Then, since $A, B \subseteq A \cup B$, it follows that $\overline{A}, \overline{B} \subseteq \overline{A \cup B}$.
Thus $\overline{A \cup B} \subseteq \overline{A \cup B}$, and so $\overline{A \cup B} = \overline{A \cup B}$. \square

$$\text{Int}(A \cap B) = \text{Int}(A) \cap \text{Int}(B)$$

let $A, B \subseteq V$.
Then necessarily $\text{Int}(A \cap B) = \text{Int}(A) \cap \text{Int}(B)$.

$$\overline{A \cap B} \subseteq \overline{A} \cap \overline{B}$$

let $A, B \subseteq V$.
Then necessarily $\overline{A \cap B} \subseteq \overline{A} \cap \overline{B}$.

$$\text{Int}(A \cup B) \supseteq \text{Int}(A) \cup \text{Int}(B)$$

let $A, B \subseteq V$.
Then necessarily $\text{Int}(A \cup B) \supseteq \text{Int}(A) \cup \text{Int}(B)$.

$$A = (0, 1), B = (1, 2), V = \mathbb{R}: \overline{A \cap B} \neq \overline{A} \cap \overline{B}$$

let $V = \mathbb{R}$, and let $A = (0, 1), B = (1, 2)$.

Then note that $\overline{A \cap B} \neq \overline{A} \cap \overline{B}$.

Proof. See that

$$\overline{A \cap B} = \overline{\emptyset} = \emptyset \quad \text{but} \quad \overline{A} \cap \overline{B} = [0, 1] \cap [1, 2] = \{1\}. \quad \square$$

$$A = [0, 1], B = [1, 2], V = \mathbb{R}:$$

$$\text{Int}(A \cup B) \neq \text{Int}(A) \cup \text{Int}(B)$$

let $V = \mathbb{R}$, and let $A = [0, 1], B = [1, 2]$.
Then note that $\text{Int}(A \cup B) \neq \text{Int}(A) \cup \text{Int}(B)$.

Proof. See that

$$\text{Int}(A \cup B) = (0, 2) \quad \text{but} \quad \text{Int}(A) \cup \text{Int}(B) = (0, 1) \cup (1, 2) = (0, 2) \setminus \{1\}.$$

$$\text{Int}(V \setminus A) = V \setminus \overline{A}$$

let $A \subseteq V$.
Then necessarily $\text{Int}(V \setminus A) = V \setminus \overline{A}$.

Proof. Since $V \setminus \overline{A} \subseteq V \setminus A$ and $V \setminus \overline{A}$ is open, it follows (by the openness of the interior) that $V \setminus \overline{A} \subseteq \text{Int}(V \setminus A)$.

Then, observe that

$$V \setminus \text{Int}(V \setminus A) \supseteq V \setminus (V \setminus A) = A,$$

and since $\text{Int}(V \setminus A)$ is open, hence $V \setminus \text{Int}(V \setminus A)$ is closed; thus A is closed, and so

$$\overline{A} \subseteq V \setminus \text{Int}(V \setminus A).$$

Hence

$$V \setminus \overline{A} \supseteq V \setminus (V \setminus \text{Int}(V \setminus A)) = \text{Int}(V \setminus A),$$

and so necessarily $V \setminus \overline{A} = \text{Int}(V \setminus A)$, as needed. \square

$$\overline{V \setminus A} = V \setminus \text{Int}(A)$$

let $A \subseteq V$.
Then necessarily $\overline{V \setminus A} = V \setminus \text{Int}(A)$.

$$\text{BOUNDARY OF A SUBSET: } \partial(A)$$

let $A \subseteq V$.
Then, the "boundary" of A , denoted as " $\partial(A)$ ", is defined to be the set $\partial(A) = \overline{A} \setminus \text{Int}(A)$.

$$\partial(A) = \overline{A} \setminus \text{Int}(A)$$

$$\text{DEFINITION: } \partial(A) \text{ IS CLOSED}$$

let $A \subseteq V$.
Then necessarily $\partial(A)$ is closed.

$$\text{Proof. } \partial(A) = \overline{A} \setminus \text{Int}(A)$$

$$= \overline{A} \cap (V \setminus \text{Int}(A)),$$

closed closed

and so $\partial(A)$ is closed. \square

$$A \text{ IS CLOSED} \iff \partial(A) \subseteq A$$

let $A \subseteq V$.
Then necessarily A is closed if and only if

$$\partial(A) \subseteq A.$$

Proof. (\Rightarrow) A is closed $\Rightarrow \partial(A) \subseteq \overline{A} = A$.

(\Leftarrow) Suppose $\partial(A) \not\subseteq A$.

Recall $\partial(A) = \overline{A} \setminus \text{Int}(A)$; in particular, we can write

$$\overline{A} = \partial(A) \cup \text{Int}(A),$$

and since $\partial(A), \text{Int}(A) \subseteq A$ it follows that $A \subseteq \overline{A}$.

As $\overline{A} \subseteq A$ it follows that $A = \overline{A}$, and so A is closed. \square

Module 3: Compactness & Open Covers

BOUNDED (SETS)

Let $A \subseteq V$, where V is a NVS.
Then, we say that A is "bounded" if there exists a $M \in \mathbb{R}$ such that $\|a\| < M \quad \forall a \in A$.

COMPACT (SUBSETS)

Let $C \subseteq V$, where V is a NVS.
Then, we say C is "compact" if every $(c_n) \subseteq C$ has a subsequence $(c_{n_k}) \subseteq (c_n)$ with $c_{n_k} \rightarrow c \in C$.

$A \subseteq \mathbb{R}^n$ IS CLOSED & BOUNDED $\Rightarrow A$ IS COMPACT

IS COMPACT

Let $A \subseteq \mathbb{R}^n$ be closed and bounded.
Then necessarily A is compact.

Proof. Let $(a_n) \subseteq A$.

Since A is bounded, $\exists (a_n) \subseteq A$ is bounded.
By A2, we know $\exists (a_{n_k}) \subseteq (a_n) \ni a_{n_k} \rightarrow a \in \mathbb{R}^n$.
Since A is closed, it follows that $a \in A$, and so A is compact. \square

$A = \{e_i = (1, 0, \dots, 0), e_2 = (0, 1, 0, \dots, 0), \dots\} \subseteq \mathbb{R}^\infty$:

A IS NOT COMPACT

Let A be the above set. We can show A is not compact.

Proof. $\forall n \in \mathbb{N}, \|e_n - e_{n+1}\| = 1$
 $\Rightarrow (e_n)$ is not Cauchy
 $\Rightarrow (e_n)$ is not convergent
 $\Rightarrow A$ is not compact. \square

Then, notice that $A = (e_1, e_2, \dots) \subseteq \overline{B_1(0)}$.

The RHS is trivially closed and bounded, but since A is not compact, necessarily $\overline{B_1(0)}$ cannot be compact!

Therefore, closed & bounded does not automatically imply compactness.

C IS COMPACT $\Rightarrow C$ IS CLOSED & BOUNDED

Let $C \subseteq V$ be compact.
Then necessarily C is closed and bounded.

Proof. Let $C \subseteq V$ be compact.

① We claim C is closed.

Proof. Let $(c_n) \subseteq C \rightarrow c_n \rightarrow b \in V$.
 $\Rightarrow \exists (c_{n_k}) \subseteq (c_n) \ni c_{n_k} \rightarrow b \in C$.
However, we must have $b = c \in C$, and so C is closed. \square

② We claim C is bounded.

Proof. Suppose this were not the case.
 $\Rightarrow \exists n \in \mathbb{N}, \exists a \in C \ni \|a\| \geq n$.
Then consider $(a_n) \subseteq C$.
 $\Rightarrow \exists (a_{n_k}) \subseteq (a_n) \ni a_{n_k} \rightarrow a \in C$.
 $\Rightarrow \exists (a_{n_k}) \subseteq (a_n) \ni a_{n_k} \rightarrow a \in C$.
But $\|a_{n_k}\| \geq n_k$! So it is unbounded, and so has to be divergent.
This is a contradiction!
Hence C is bounded, as needed. \square

HEINE-BOREL THEOREM: $C \subseteq \mathbb{R}^n$ IS COMPACT $\Leftrightarrow C$ IS CLOSED & BOUNDED

Proof. Let $C \subseteq \mathbb{R}^n$.
Then C is compact if and only if it is also closed & bounded.
(This has been proved by previous observations!)

$C \subseteq V$ IS COMPACT, $A \subseteq C$ IS CLOSED $\Rightarrow A$ IS COMPACT

Proof. Let $C \subseteq V$ be compact, and let $A \subseteq C$ be closed.
Then necessarily A is compact.

Proof. Let $(a_n) \subseteq A$. Since $A \subseteq C$,
 $\exists (a_{n_k}) \subseteq (a_n) \ni a_{n_k} \rightarrow a \in C$.
But as A is closed $\Rightarrow a \in A$, and so A is compact. \square

OPEN COVERS (OF SUBSETS)

Let $A \subseteq V$, where V is a NVS.
Then, an "open cover" of A is a collection of open sets $\{U_\alpha : \alpha \in I\}$ such that $A \subseteq \bigcup_{\alpha \in I} U_\alpha$.

We say the open cover is "finite" if $|I| < |\mathbb{N}|$.

Examples:
① $V = \mathbb{R}$, $A = [0, 1]$, $A \subseteq (-\frac{1}{4}, \frac{1}{4}) \cup (0, \frac{1}{2}) \cup \dots \cup (\frac{3}{4}, \frac{5}{4})$
② $V = \mathbb{R}^2$, $A = \mathbb{Z} \times \mathbb{Z}$, $A \subseteq \bigcup_{(a, b) \in \mathbb{Z} \times \mathbb{Z}} B_{\frac{1}{2}}(a, b)$
③ $V = \mathbb{R}$, $A = (0, 1]$, $A \subseteq \bigcup_{n \in \mathbb{N}} (\frac{1}{n}, 2)$.

SUBCOVERS

Let $\{U_\alpha : \alpha \in I\}$ be an open cover of $A \subseteq V$.
Then, we say a subset of $\{U_\alpha : \alpha \in I\}$ is a "subcover" of $\{U_\alpha : \alpha \in I\}$.

Note that subcovers are also open covers of A .

$A \in V$ COMPACT, $A \subseteq \bigcup_{\alpha \in I} U_\alpha$ IS AN OPEN COVER
 $\Rightarrow \exists R > 0 \Rightarrow \forall a \in A: B_R(a) \subseteq U_\alpha$ FOR SOME $\alpha \in I$

Let $A \in V$ be compact, and let $A \subseteq \bigcup_{\alpha \in I} U_\alpha$ be an open cover of A . Then, there necessarily exists some $R > 0$ such that for each $a \in A$, we have $B_R(a) \subseteq U_\alpha$ for some $\alpha \in I$.

Proof. Suppose no such $R > 0$ exists. In particular, $\forall n \in \mathbb{N}: \exists a_n \in A \ni B_{\frac{1}{n}}(a_n) \not\subseteq U_\alpha$

Since $(a_n) \subseteq A$ and A is compact,

$$\Rightarrow \exists (a_{n_k}) \subseteq (a_n) \ni a_{n_k} \rightarrow a \in A.$$

Say $a \in U_{\alpha_0}$, where $\alpha_0 \in I$ (since the union is an open cover).

$$\text{Pick } M \in \mathbb{N} \ni B_{\frac{1}{M}}(a) \subseteq U_{\alpha_0}$$

Moreover, since $a_{n_k} \rightarrow a$, we may find $N \in \mathbb{N}$

$$\Rightarrow a_{n_k} \in B_{\frac{1}{M}}(a) \quad \forall k \geq N.$$

Then, for $k \geq N$ such that $n_k > M$, take

$$x \in B_{\frac{1}{M}}(a_{n_k}).$$

But

$$\begin{aligned} \|x - a\| &= \|x - a_{n_k} + a_{n_k} - a\| \\ &\leq \|x - a_{n_k}\| + \|a_{n_k} - a\| \\ &< \frac{1}{M} + \frac{1}{M} = \frac{2}{M}, \end{aligned}$$

and so $x \in B_{\frac{2}{M}}(a)$.

$$\therefore B_{\frac{1}{M}}(a_{n_k}) \subseteq B_{\frac{2}{M}}(a) \subseteq U_{\alpha_0}.$$

But since $n_k > M$, it follows that

$$B_{\frac{1}{M}}(a_{n_k}) \subseteq B_{\frac{1}{n_k}}(a_{n_k}) \subseteq U_{\alpha_0},$$

which is a contradiction to our earlier assumption that $B_{\frac{1}{n_k}}(a_{n_k}) \not\subseteq U_\alpha$ $\forall \alpha \in I$. \square

$A \in V$ IS COMPACT \Rightarrow EVERY OPEN COVER OF A HAS A FINITE SUBCOVER

Let $A \in V$ be compact. Then necessarily every open cover of A has a finite subcover.

Proof. Suppose $A \in V$ is compact.

Let $A \subseteq \bigcup_{\alpha \in I} U_\alpha$ be an open cover of A .

Since A is compact, by the above lemma,

$$\exists R > 0 \Rightarrow \forall a \in A: B_R(a) \subseteq U_\alpha \text{ for some } \alpha \in I.$$

If $\exists i_1, \dots, i_k \in I \Rightarrow A \subseteq B_{R(i_1)} \cup \dots \cup B_{R(i_k)}$, by the lemma we are done.

So, suppose no such covering existed.

Then, we can find a $a_1 \in A$, $a_2 \in A \ni a_2 \notin B_R(a_1)$, $a_3 \in A \ni a_3 \notin B_R(a_1) \cup B_R(a_2)$, ...

Since $(a_n) \subseteq A$ & A is compact,

$$\exists (a_{n_k}) \subseteq (a_n) \ni a_{n_k} \rightarrow a.$$

However, for $n \geq m$, we have that

$$a_m \notin B_R(a_n),$$

or in other words,

$$\|a_m - a_n\| \geq R.$$

$\Rightarrow (a_n)$ has no Cauchy subsequences.

$\Rightarrow (a_n)$ has no convergent subsequences,

giving us our contradiction. \square

EVERY OPEN COVER OF $A \in V$ HAS A FINITE SUBCOVER, & $A \subseteq \bigcup_{\alpha \in I} U_\alpha$ WHERE EACH U_α IS RELATIVELY OPEN IN $A \Rightarrow \exists \alpha_1, \dots, \alpha_n \in I$

$$\Rightarrow A \subseteq U_{\alpha_1} \cup \dots \cup U_{\alpha_n}$$

Why is the above lemma true?

Proof. $A \subseteq \bigcup_{\alpha \in I} U_\alpha$, where $U_\alpha = A \cap O_\alpha$, $O_\alpha \subseteq V$ open

$$\Rightarrow A \subseteq \bigcup_{\alpha \in I} (A \cap O_\alpha)$$

$$= A \cap (\bigcup_{\alpha \in I} O_\alpha)$$

$$\subseteq \bigcup_{\alpha \in I} O_\alpha,$$

$$\Rightarrow A \subseteq O_{\alpha_1} \cup \dots \cup O_{\alpha_n}$$

$$\Rightarrow A \subseteq \underbrace{U_{\alpha_1} \cup \dots \cup U_{\alpha_n}}_{\text{the relatively open cover.}} \quad \square$$

EVERY OPEN COVER OF A HAS A FINITE SUBCOVER $\Rightarrow A \in V$ IS COMPACT

Let $A \in V$, and suppose every open cover of A has a finite subcover.

Then necessarily $A \in V$ is compact.

Proof. Let $(a_n) \subseteq A$.

For $k \in \mathbb{N}$, consider $C_k = \overline{\bigcap_{n=k}^{\infty} A} \cap A$.

We want to show $\bigcap_{k=1}^{\infty} C_k \neq \emptyset$.

Each C_k is relatively closed in A . Hence every $U_k = A \setminus C_k$ is relatively open.

For contradiction, assume $\bigcap_{k=1}^{\infty} C_k = \emptyset$.

$$\begin{aligned} \Rightarrow A &= A \setminus \emptyset \\ &= A \setminus (\bigcap_{k=1}^{\infty} C_k) \\ &= \bigcup_{k=1}^{\infty} (A \setminus C_k) \\ &= \bigcup_{k=1}^{\infty} U_k \leftarrow \text{the relatively open subcover.} \end{aligned}$$

By the lemma above,

$$\exists i_1, \dots, i_k \in \mathbb{N} \Rightarrow A \subseteq U_{i_1} \cup \dots \cup U_{i_k}.$$

Since $C_1 \supseteq C_2 \supseteq \dots$, we have that $U_1 \subseteq U_2 \subseteq \dots$

$$\therefore A \subseteq U_{i_k} \subseteq A,$$

and so $A = U_{i_k}$.

$$\Rightarrow C_{i_k} = A \setminus U_{i_k} = A \setminus A = \emptyset.$$

But since $a_{i_k} \in C_{i_k} = \emptyset$, this is a contradiction!

Hence, we may find some $a \in \bigcap_{k=1}^{\infty} C_k$.

$$\therefore \exists n, c_n \in \dots \ni \|a_n - a\| < \frac{1}{k} \quad \forall k \in \mathbb{N},$$

and so $(a_n) \subseteq A \ni a_n \rightarrow a \in A$, showing A is compact, as needed. \square

Module 4.1:

Limits

LIMIT

\exists_1 Let $f: A \rightarrow W$, where $A \subseteq V$, and let $a \in V$.
 Then, the "limit" of $f(x)$ as x approaches a is $w \in W$ if
 ① $a \in A \setminus \{a\}$; and
 ② $\forall \epsilon > 0 : \exists \delta > 0$ such that if $x \in A$ with
 $0 < |x-a| < \delta$, then $|f(x) - w| < \epsilon$.

\exists_2 In this case, we write

$$\lim_{x \rightarrow a} f(x) = w.$$

* note that w is unique.

ISOLATED POINT

\exists_1 Let $a \in A$, where $A \subseteq V$.
 Then, we call a an "isolated point" with respect to A if $a \notin A \setminus \{a\}$.
 \exists_2 If $a \notin A \setminus \{a\}$, then there exists $r > 0$ such that $B_r(a) \cap A = \{a\}$ or \emptyset .
 In other words, there does not exist $x \in A$ with $0 < |x-a| < r$.

LIMITS PRESERVE ORDER

\exists Let $A \subseteq V$, and let $f, g, h: A \rightarrow \mathbb{R}$ and $a \in A \setminus \{a\}$.
 Suppose $\lim_{x \rightarrow a} f(x)$ & $\lim_{x \rightarrow a} g(x)$ exist and $f(x) \leq g(x) \quad \forall x \in A$.
 Then necessarily $\lim_{x \rightarrow a} f(x) \leq \lim_{x \rightarrow a} g(x)$.

SQUEEZE THEOREM

\exists Let $A \subseteq V$, and let $f, g, h: A \rightarrow \mathbb{R}$ and $a \in A \setminus \{a\}$.
 Suppose $f(x) \leq g(x) \leq h(x) \quad \forall x \in A$ and
 $\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} h(x) = L$.
 Then necessarily $\lim_{x \rightarrow a} g(x) = L$ as well.

LIMITS OF MULTIVARIABLE FUNCTIONS

eg¹ Evaluate

$$\lim_{(x,y,z) \rightarrow (0,0,0)} \frac{xy^2 + x^2z + xyz}{\sqrt{x^2+y^2+z^2}}.$$

Solⁿ. If $x \neq 0$, then observe that

$$0 \leq \left| \frac{xy^2 + x^2z + xyz}{\sqrt{x^2+y^2+z^2}} \right| \leq \frac{|xy^2 + x^2z + xyz|}{\sqrt{x^2}}$$

$$= \frac{|xy^2 + x^2z + xyz|}{|x|}$$

$$\leq \frac{|xy|^2 + x^2|z| + |xyz|}{|x|}$$

$$= y^2 + (|x| |z| + |y| |z|).$$

If $x=0$, then $f(x,y,z)=0$.

Since

$$\lim_{(x,y,z) \rightarrow (0,0,0)} y^2 + |x||z| + |y||z| = 0,$$

by S.T it follows that $\lim_{(x,y,z) \rightarrow (0,0,0)} f(x,y,z) = 0$.

eg² Evaluate

$$\lim_{(x,y) \rightarrow (0,0)} \frac{xy^2}{x^2+y^4} \quad \{ f(x,y) \}$$

Solⁿ. As $(\frac{1}{n}, 0) \rightarrow (0,0)$, we see that

$$f(\frac{1}{n}, 0) = 0 \rightarrow 0.$$

As $(\frac{1}{n^2}, \frac{1}{n}) \rightarrow (0,0)$, we see that

$$f(\frac{1}{n^2}, \frac{1}{n}) = \frac{\frac{1}{n^2} \cdot \frac{1}{n^2}}{\frac{1}{n^2} + \frac{1}{n^4}} = \frac{1}{2} \rightarrow \frac{1}{2}.$$

Since $0 \neq \frac{1}{2}$, the limit does not exist. *

Module 4.2:

Continuity

CONTINUOUS (FUNCTIONS)

\exists_1 let $f: A \rightarrow W$, where $A \subseteq V$. Then, we say f is "continuous" at $a \in A$ if for any $\epsilon > 0$, there exists $\delta > 0$ such that if $x \in A$ with $\|x - a\| < \delta$, then $\|f(x) - f(a)\| < \epsilon$.

\exists_2 Note that f is continuous at $a \in A \setminus \{a\}$ if and only if $\lim_{x \rightarrow a} f(x) = f(a)$.

\exists_3 However, if $a \notin A \setminus \{a\}$, then f is automatically continuous at a .

Why? $\Rightarrow \exists r > 0, B_r(a) \cap A = \{a\}$

(let $\epsilon > 0$, & chose $\delta = r$.

If $x \in A$ & $\|x - a\| < \delta$, then $x = a$.

$$\therefore \|f(x) - f(a)\| = \|f(a) - f(a)\| = 0 < \epsilon$$

\exists_4 We say f is continuous if f is continuous at all $a \in A$.

f IS CTS $\Leftrightarrow f$ PRESERVES CONVERGENCE $\Leftrightarrow \forall$ OPEN $U \subseteq W$,

$f^{-1}(U)$ IS RELATIVELY OPEN IN A

\exists_1 Let $f: A \rightarrow W$, where $A \subseteq V$. Then, the following are equivalent:

- ① f is continuous;
- ② f preserves convergence; and
- ③ \forall open $U \subseteq W$, $f^{-1}(U)$ is relatively open in A.

Proof. ③ \Rightarrow ② from Assignment 2.

① \Rightarrow ②: Suppose f is cts, and let $(a_n) \subseteq A \rightarrow a$ for $a \in A$. Let $\epsilon > 0$. There exists $\delta > 0 \Rightarrow x \in A$ & $\|x - a\| < \delta$, then $\|f(x) - f(a)\| < \epsilon$.

Take $N \in \mathbb{N} \Rightarrow \|a_n - a\| < \delta \quad \forall n \geq N$.

But then, for $n \geq N$, we see that $\|f(a_n) - f(a)\| < \epsilon$, showing that $f(a_n) \rightarrow f(a)$. #

② \Rightarrow ①: Assume f preserves convergence, and suppose f is discontinuous at a . $\Rightarrow \exists \epsilon > 0$ & $(a_n) \subseteq A \Rightarrow \|a_n - a\| < \frac{1}{n}$ but $\|f(a_n) - f(a)\| \geq \epsilon$. Then, $a_n \rightarrow a$ but $f(a_n) \not\rightarrow f(a)$ — contradiction! #

PROJECTION MAP IS CTS

\exists_1 The " i th projection map" $P_i: \mathbb{R}^n \rightarrow \mathbb{R}$, where $1 \leq i \leq n$, is defined by

$$P_i(x_1, \dots, x_n) = x_i.$$

\exists_2 We can prove the projection map is continuous for any $i \in \mathbb{N}$.

Proof. Let $(a_k) \subseteq \mathbb{R}^n \rightarrow a \in \mathbb{R}^n$, say $a_k = (a_k^{(1)}, \dots, a_k^{(n)})$ and $a = (b_1, \dots, b_n)$.

We know $a_k \xrightarrow{\text{w}} b_i \quad \forall i \in \mathbb{N}$ as $k \rightarrow \infty$;

$$\Rightarrow P_i(a_k) \rightarrow P_i(a)$$

$\therefore P_i$ is cts. #

$f, g: A \rightarrow W$ ARE CTS $\Rightarrow f+g, \alpha f$ ($\alpha \in \mathbb{R}$) ARE CTS

\exists_1 Let $f, g: A \rightarrow W$ be continuous, and let $\alpha \in \mathbb{R}$. Then $f+g$ and αf are necessarily also continuous.
 Proof. Let $(a_n) \subseteq A \rightarrow a$.
 \Rightarrow (since f is cts) $\Rightarrow f(a_n) \rightarrow f(a)$ & $g(a_n) \rightarrow g(a)$.
 $\Rightarrow f(a_n) + g(a_n) \rightarrow f(a) + g(a)$ & $\alpha f(a_n) \rightarrow \alpha f(a)$. #

$f: A \rightarrow W_1, g: B \rightarrow W_2, B \subseteq W_1$ ARE CTS $\Rightarrow g \circ f$ IS CTS

\exists_1 Let $f: A \rightarrow W_1$ and $g: B \rightarrow W_2$ be continuous, where $B \subseteq W_1$. Then necessarily $(g \circ f)$ is continuous.
 Proof. Let $(a_n) \subseteq A \rightarrow a$. Since f is cts, $\Rightarrow f(a_n) \rightarrow f(a)$. Since g is cts, $\Rightarrow g(f(a_n)) \rightarrow g(f(a))$. $\Rightarrow g \circ f$ preserves convergence
 $\Rightarrow g \circ f$ is continuous. #

Module 4.3:

Uniform Continuity

UNIFORM CONTINUITY

Let $f: A \rightarrow W$, where $f: A \rightarrow W$.
Then, we say f is "uniformly continuous".
if for any $\epsilon > 0$, there exists a $\delta > 0$ such
that if $x, a \in A$ with $|x-a| < \delta$, then
 $|f(x) - f(a)| < \epsilon$.

Note that uniform continuity implies continuity.

LIPSCHITZ (FUNCTIONS)

Let $f: A \rightarrow W$.
We say f is "Lipschitz" if there exists a $M > 0$
such that
 $|f(a) - f(b)| \leq M|a-b| \quad \forall a, b \in A$.

LIPSCHITZ \Rightarrow UNIFORM CONTINUITY

Let $f: A \rightarrow W$ be Lipschitz.
Then necessarily f is uniformly continuous.
Proof: let $\epsilon > 0$. Choose $\delta = \frac{\epsilon}{M}$.
If $a, b \in A$ with $|a-b| < \delta$, then
 $|f(a) - f(b)| \leq M|a-b|$
 $< M\delta = M\left(\frac{\epsilon}{M}\right) = \epsilon$,
showing f is uniformly ct. \blacksquare

C IS COMPACT, $f:C \rightarrow W$ IS CTS \Rightarrow f IS UNIF CTS

Let $C \subseteq V$ be compact & $f: C \rightarrow W$ be continuous.
Then f is uniformly continuous.
Why? \rightarrow Suppose for contradiction that f is not unif cts.
 $\Rightarrow \exists (c_n), (b_n) \subseteq C \rightarrow |a_n - b_n| \xrightarrow{n \rightarrow \infty} 0$, $|f(a_n) - f(b_n)| \geq \epsilon$.
By compactness,
 $\exists (a_{n_k}) \subseteq (a_n) \rightarrow a_{n_k} \rightarrow a \in C$.
 $\Rightarrow b_{n_k} = \underbrace{b_{n_k} - a_{n_k}}_{\rightarrow 0} + \underbrace{a_{n_k}}_{\rightarrow a}$
 $\Rightarrow b_{n_k} \rightarrow a$.
By continuity, $f(a_{n_k}) \rightarrow f(a)$, $f(b_{n_k}) \rightarrow f(b)$.
 $\Rightarrow |f(a_n) - f(b_n)| \rightarrow 0$.
But this is a contradiction $\because |f(a_n) - f(b_n)| \geq \epsilon$ by
earlier assumption! \blacksquare

Module 4.4:

Extreme Value Theorem

$C \subseteq W$ IS COMPACT, $f: C \rightarrow W$ IS CTS \Rightarrow

$f(C)$ IS COMPACT

Let $C \subseteq W$ be compact, and let $f: C \rightarrow W$ be continuous.

Then necessarily $f(C)$ is compact.

Why? Take $(f(a_n)) \subseteq f(C)$, $a_n \in C$.

$$\Rightarrow (a_n) \subseteq C.$$

(compact) $\exists (a_{n_k}) \subseteq (a_n) \Rightarrow a_{n_k} \rightarrow a$.

(continuity) $\Rightarrow f(a_{n_k}) \rightarrow f(a) \in f(C)$

$\Rightarrow f(C)$ is compact. \square

$\phi \neq A \subseteq R$ IS BOUNDED $\Rightarrow \inf A, \sup A \in \bar{A}$

Let $\phi \neq A \subseteq R$ be bounded.

Then necessarily $\inf A, \sup A \in \bar{A}$.

Proof: We prove the claim for $\sup A$; $\inf A$ is similar.

V.N.E.D., we know

$$\sup A - \frac{1}{n} < a_n \leq \sup A.$$

\Rightarrow (by S.T) $a_n \rightarrow \sup A$.

$$\therefore \sup A \in \bar{A}.$$

$\phi \neq C \subseteq V$ IS COMPACT, $f: C \rightarrow \mathbb{R}$ IS CTS \Rightarrow

$\exists a, b \in C \Rightarrow f(a) = \min f(C) \text{ & } f(b) = \max f(C)$

(EXTREME VALUE THEOREM (EVT))

Let $\phi \neq C \subseteq V$ be compact, and let $f: C \rightarrow \mathbb{R}$ be continuous.

Then, there must exist some $a, b \in C$ such that

$f(a) = \min f(C) \text{ & } f(b) = \max f(C)$.

Proof: $f(C)$ is compact.

$f(C) \subseteq \mathbb{R} \Rightarrow f(C)$ is closed & bounded.

\Rightarrow (by bounded) $\sup f(C), \inf f(C) \in \bar{f(C)}$.

(since $f(C)$ is compact) $\therefore \bar{f(C)} = f(C)$.

$\therefore \exists a, b \in C \Rightarrow f(a) = \inf f(C) = \min f(C)$

& $f(b) = \sup f(C) = \max f(C)$. \square

UNIFORM NORM (FOR $CCK(W)$)

Let $K \subseteq V$ be compact, and let W be a NVS.

Then, $C(K, W) = \{f: K \rightarrow W \text{ cts}\}$ is a NVS when

equipped with the uniform norm

$$\|f\|_\infty = \max \{ \|f(x)\| : x \in K \}.$$

Module 5:

Sequences of Functions

POINTWISE CONVERGENCE [OF FUNCTIONS]

Let $A \subseteq V$, $f_n: A \rightarrow W$ and $f: A \rightarrow W$

Then, we say f_n converges to f "pointwise" if $f_n(x) \rightarrow f(x) \quad \forall x \in A$.

UNIFORM CONVERGENCE [OF FUNCTIONS]

Let $A \subseteq V$, $f_n: A \rightarrow W$ and $f: A \rightarrow W$

Then, we say f_n converges to f "uniformly" if for any $\epsilon > 0$, there exists a $N \in \mathbb{N}$ such that

$$\|f_n(x) - f(x)\| < \epsilon \quad \forall n \geq N, \quad x \in A.$$

In this case, note that the same N works uniformly for all $x \in A$:

$$\|f_n - f\|_{\infty} := \sup \{ \|f_n(x) - f(x)\| : x \in A \}$$

Let $f_n, f: A \rightarrow W$, where $A \subseteq V$.

Then, we define

$$\|f_n - f\|_{\infty} := \sup \{ \|f_n(x) - f(x)\| : x \in A \}.$$

Note that

$$f_n \rightarrow f \text{ uniformly} \Leftrightarrow \|f_n - f\|_{\infty} < \infty \text{ eventually} \quad \& \quad \|f_n - f\|_{\infty} \rightarrow 0.$$

* note that since A may not be compact & f may not be cts, $\|f_n - f\|_{\infty}$ could be infinite.

For example, take $f_n: \mathbb{R} \rightarrow \mathbb{R}$, with $f_n(x) = x$ & $f_n(x) = 0 \quad \forall n > 1$.

Then $f_n \rightarrow 0$ uniformly, even though $\|f_n - 0\|_{\infty} = \infty$.

EXAMPLES

For each sequence of functions, find the pointwise limit and determine whether the convergence is uniform.

$$\text{eg } f_n: (0, 1) \rightarrow \mathbb{R}, \quad f_n(x) = \frac{nx}{1+nx}$$

$$\text{Pointwise limit: for } x \in (0, 1), \\ f_n(x) = \frac{nx}{1+nx} \rightarrow 1.$$

$\therefore f_n \rightarrow 1$ pointwise.

For $n > 1$, we have

$$|f_n(\frac{1}{n}) - 1| = \frac{1}{2}.$$

$\therefore \|f_n - f\|_{\infty} \not\rightarrow 0$

\Rightarrow convergence is not uniform.

$$\text{eg } f_n: \mathbb{C}_0 \rightarrow \mathbb{R}, \quad f_n(a_n) \rightarrow a_n.$$

Pointwise: For $a_n \in \mathbb{C}_0$, see that

$$f_n(a_n) = a_n \rightarrow 0.$$

$\therefore f_n \rightarrow 0$ pointwise.

Uniform? For $n \in \mathbb{N}$, see that

$$|f_n(\underbrace{c_1, c_2, \dots}_{n}) - 0| = |1 - 0| = 1.$$

$$\therefore \|f_n - 0\| \geq 1 \Rightarrow \|f_n - 0\|_{\infty} \not\rightarrow 0.$$

\Rightarrow convergence is not uniform.

$$\text{eg } f_n: [0, 1] \times [0, 1] \rightarrow \mathbb{R}, \quad f_n(a, b) = \frac{a^n}{n} + \frac{1}{b+n}$$

Pointwise: For $(a, b) \in [0, 1] \times [0, 1]$,

$$f_n(a, b) = \frac{a^n}{n} + \frac{1}{b+n} \in [0, \frac{1}{n}]$$

\therefore (by ST) $f_n(a, b) \rightarrow 0$.

$\Rightarrow f_n(a, b) \rightarrow 0$ pointwise.

Uniform? Note that

$$|f_n(a, b) - 0| = \frac{a^n}{n} + \frac{1}{b+n} \leq \frac{1}{n} + \frac{1}{n} = \frac{2}{n}$$

$$\therefore \|f_n - 0\|_{\infty} \leq \frac{2}{n} \rightarrow 0,$$

$\therefore f_n \rightarrow 0$ uniformly.

$f_n: A \rightarrow W, A \subseteq V : f_n$ IS CTS $\forall n \in \mathbb{N}$, $f_n \rightarrow f$

UNIFORMLY $\Rightarrow f$ IS CTS

Let $f_n: A \rightarrow W$, where $A \subseteq V$.

Suppose each f_n is continuous, and $f_n \rightarrow f$ uniformly.

Then necessarily f is continuous.

Proof. Let $(a_n) \subseteq A \ni a_n \rightarrow a$ & let $\epsilon > 0$.

We know we may find $N \in \mathbb{N} \ni$

$$\|f_N - f\|_{\infty} < \frac{\epsilon}{3}.$$

Since f_N is cts, we know $\exists M \in \mathbb{N} \ni$

$$|f_N(a_n) - f_N(a)| < \frac{\epsilon}{3} \quad \forall n \geq M.$$

Then, for $n \geq M$, see that

$$\begin{aligned} |f(a_n) - f(a)| &= |f(a_n) - f_N(a_n) + f_N(a_n) - f_N(a) + f_N(a) - f(a)| \\ &\leq |f(a_n) - f_N(a_n)| + |f_N(a_n) - f_N(a)| + |f_N(a) - f(a)| \\ &\leq \|f_N - f\|_{\infty} + |f_N(a_n) - f_N(a)| + \|f_N - f\|_{\infty} \\ &\leq \frac{\epsilon}{3} + \frac{\epsilon}{3} + \frac{\epsilon}{3} = \epsilon, \end{aligned}$$

and so $f(a_n) \rightarrow f(a)$, and so f is cts. \square

$A \subseteq V$ IS COMPACT, W IS A BANACH SPACE $\Rightarrow (C(A, W), \|\cdot\|_{\infty})$ IS A BANACH SPACE

Let $A \subseteq V$ be compact, and let W be a Banach space.

Then necessarily $(C(A, W), \|\cdot\|_{\infty})$ is a Banach space.

Proof. Let $(f_n) \subseteq C(A, W)$ be Cauchy, and let $\epsilon > 0$.

We know $\exists N \in \mathbb{N} \ni$

$$\|f_n - f_m\|_{\infty} < \epsilon \quad \forall n, m \geq N.$$

For $x \in A$ & $n, m \in \mathbb{N}$, see that

$$\|f_n(x) - f_m(x)\| \leq \|f_n - f_m\|_{\infty} < \epsilon,$$

and so $(f_n(x)) \subseteq W$ is Cauchy.

Since W is a Banach space, it is complete,

and so $f_n(x) \rightarrow f(x) \in W$ for some $f(x) \in W$.

Thus, we have constructed a $f: A \rightarrow W \ni$

$f_n \rightarrow f$ pointwise.

For $x \in A$ and $n \geq N$, we have that

$$\lim_{m \rightarrow \infty} \|f_n(x) - f_m(x)\| \leq \epsilon,$$

and so

$$\|f_n(x) - f(x)\| \leq \epsilon \quad (\text{limits preserve order});$$

$\Rightarrow \|f_n - f\|_{\infty} \leq \epsilon$ since $x \in A$ was arbitrary.

$\Rightarrow f_n \rightarrow f$ uniformly.

So, by the previous theorem, it follows that $f \in C(A, W)$, and so $f_n \rightarrow f$ in $C(A, W)$.

$\Rightarrow C(A, W)$ is a Banach space (since (f_n) was

an arbitrary Cauchy sequence). \square

Module 6.1:

Partial Derivatives

SCALAR FUNCTION

B1: A "scalar function" is any function of the form $f: A \rightarrow \mathbb{R}$, $A \subseteq \mathbb{R}^n$.

B2: Note for any $f: A \rightarrow \mathbb{R}^m$, $A \subseteq \mathbb{R}^n$, there exist scalar functions $f_1, \dots, f_m: A \rightarrow \mathbb{R}$ such that $f = (f_1, f_2, \dots, f_m)$.
eg $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by $f(x, y, z) = (xe^y, x^2 + z^2)$. Then $f_1(x, y, z) = xe^y$ & $f_2(x, y, z) = x^2 + z^2$. Then $f = (f_1, f_2)$.

i^{th} PARTIAL DERIVATIVE [OF SCALAR FUNCTIONS]:

$$\frac{\partial f}{\partial x_i}(a) = f_{x_i}(a)$$

B1: Let $f: A \rightarrow \mathbb{R}$, where $A \subseteq \mathbb{R}^n$. Let $\{e_1, \dots, e_n\}$ be the standard basis for \mathbb{R}^n . Then, for $1 \leq i \leq n$, we define the " i^{th} partial derivative" of f at $a = (a_1, \dots, a_n) \in A$, denoted as $\frac{\partial f}{\partial x_i}(a)$ or $f_{x_i}(a)$, to be equal to

$$f_{x_i}(a) = \frac{\partial f}{\partial x_i}(a) := \lim_{h \rightarrow 0} \frac{f(a + he_i) - f(a)}{h},$$

provided the limit exists.

B2: We use the notation " $f(x_1, \dots, x_n)$ " when talking about functions $f: A \rightarrow \mathbb{R}$, $A \subseteq \mathbb{R}^n$.

B3: Note that $f_{x_i}(a)$ is the derivative of f at a wrt x_i , treating the other x_j , $j \neq i$ as constants.

B4: Moreover, $f_{x_i}(a)$ is the slope of the tangent line to the surface $y = f(x_1, x_2, \dots, x_n)$ which is parallel to e_i .

B5: For example, for $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, find $\frac{\partial f}{\partial x}(a)$ & $\frac{\partial f}{\partial y}(a)$:

$$f_x(a) = \lim_{h \rightarrow 0} \frac{f(a + he_1) - f(a)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{f(a_1 + h, a_2) - f(a_1, a_2)}{h},$$

$$\text{and similarly } f_y(a) = \lim_{h \rightarrow 0} \frac{f(a_1, a_2 + h) - f(a_1, a_2)}{h}.$$

B6: We also treat $\frac{\partial f}{\partial x_i}$ as a function, and write

$$f_{x_i}(x_1, \dots, x_n) \quad \text{or} \quad \frac{\partial f}{\partial x_i}(x_1, \dots, x_n).$$

EXAMPLE 1: $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, $f(x, y, z) = xy^2z + e^{xy}$,

FIND PARTIAL DERIVATIVES

$$\text{Soln. } f_x(x, y, z) = y^2z + ye^{xy}$$

$$f_y(x, y, z) = 2xyz + xe^{xy}$$

$$f_z(x, y, z) = xy^2.$$

i^{th} PARTIAL DERIVATIVE [OF FUNCTIONS]:

$$\frac{\partial f}{\partial x_i}(a) = f_{x_i}(a)$$

B1: Let $A \subseteq \mathbb{R}^n$ and $f: A \rightarrow \mathbb{R}^m$, where $f = (f_1, \dots, f_m)$. For $a \in A$, we define the " i^{th} partial derivative" of f at a , denoted as $\frac{\partial f}{\partial x_i}(a)$ or $f_{x_i}(a)$, to be equal

$$f_{x_i}(a) = \frac{\partial f}{\partial x_i}(a) := \left(\frac{\partial f_1}{\partial x_i}(a), \dots, \frac{\partial f_m}{\partial x_i}(a) \right) \in \mathbb{R}^m.$$

provided it exists.

EXAMPLE 2: $f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$, $f(x, y) = (2x^2y, 4x, e^{xy})$,

FIND $\frac{\partial f}{\partial x}$ & $\frac{\partial f}{\partial y}$

$$\text{Soln. } f_x(x, y) = (4xy, 4, ye^{xy}) ;$$

$$f_y(x, y) = (2x^2, 0, xe^{xy}).$$

Module 6.2: Differentiability

Differentiable [functions at $a \in A$]

Let $a \in \mathbb{R}^n$ and let $f: A \rightarrow \mathbb{R}^m$.

Then, we say f is "differentiable" at $a \in A$

- if
- ① $a \in \text{Int}(A)$; and
 - ② There exists a $T \in L(\mathbb{R}^n, \mathbb{R}^m)$ such that
- $$\lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - Th}{\|h\|} = 0.$$
- (recall $L(\mathbb{R}^n, \mathbb{R}^m) = \{T: \mathbb{R}^n \rightarrow \mathbb{R}^m \mid T \text{ is linear}\}$)

Note that by ①, $f(a+h)$ is defined for small enough h .

Operator Norm [on $M_{mn}(\mathbb{R})$]: $\|A\|_{op}$

Let $A \in M_{mn}(\mathbb{R})$.

Then, the "operator norm" of A , denoted as

" $\|A\|_{op}$ ", is defined to be equal to

$$\|A\|_{op} = \sup \{ \|Ax\| : x \in \mathbb{R}^n, \|x\|=1 \}.$$

$$\|Ax\| \leq \|A\|_{op} \|x\|$$

Note that for any $A \in M_{mn}(\mathbb{R})$ and $x \in \mathbb{R}^n$, we have

$$\|Ax\| \leq \|A\|_{op} \|x\|.$$

Proof. Clear if $x=0$. Otherwise, see that

$$\begin{aligned} \left\| \frac{x}{\|x\|} \right\| &= 1. \\ \Rightarrow \|A\|_{op} &\geq \left\| A \frac{x}{\|x\|} \right\| = \frac{\|Ax\|}{\|x\|}. \end{aligned}$$

Proof follows. \square

Differentiability \Rightarrow Continuity

Let $a \in \mathbb{R}^n$, and $f: A \rightarrow \mathbb{R}^m$.

Then, if f is diff at a , then necessarily

f is cont at a .

Proof. f is diff $\Rightarrow \exists T \in L(\mathbb{R}^n, \mathbb{R}^m)$ s.t.

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - Th}{\|h\|} &= 0 \\ \Rightarrow \lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - Bh}{\|h\|} &= 0 \quad (\text{where } B \in M_{mn}(\mathbb{R})) \\ \Rightarrow \text{we can find } \delta > 0 \text{ s.t.} \\ 0 < \|h\| < \delta, \text{ then} \\ \left\| \frac{f(a+h) - f(a) - Bh}{\|h\|} \right\| &< 1 \end{aligned}$$

$$\Rightarrow \|f(a+h) - f(a) - Bh\| < \|h\|$$

$$\Rightarrow \|f(a+h) - f(a)\| = \|Bh\| < \|h\|$$

$$\Rightarrow \|f(a+h) - f(a)\| \leq \|Bh\| + \|h\|$$

$$\leq \|B\|_{op} \|h\| + \|h\|$$

As $h \rightarrow 0$, $\|B\|_{op} \|h\| + \|h\| \rightarrow 0$.

$$\Rightarrow (\text{by ST}) \lim_{h \rightarrow 0} f(a+h) = f(a).$$

Setting $x = a+h$,

$$\Rightarrow \lim_{x \rightarrow a} f(x) = f(a). \quad \square$$

Differentiable [functions on open $U \subset \mathbb{R}^n$]

Let $U \subset \mathbb{R}^n$ be open, and let $f: U \rightarrow \mathbb{R}^m$.

Then, we say f is "differentiable" on U

if f is differentiable at every point in U .

Module 6.3:

Total Derivatives

TOTAL DERIVATIVE [OF f AT a]

\exists (let $a \in \mathbb{R}^n$, and $f: A \rightarrow \mathbb{R}^m$).

Then, the "total derivative" of f at a , denoted as " $D_f(a)$ ", is defined to be the matrix

$$D_f(a) = \left(\frac{\partial f_i}{\partial x_j}(a) \right) \in M_{m \times n}(\mathbb{R}),$$

provided it exists.

f IS DIFFERENTIABLE \Rightarrow " B " = $D_f(a)$

\exists (let $a \in \mathbb{R}^n$, $f: A \rightarrow \mathbb{R}^m$).

Suppose f is differentiable at a , so that there exists a $B \in M_{m \times n}(\mathbb{R})$ such that

$$\lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - Bh}{\|h\|} = 0.$$

Then necessarily $B = D_f(a)$.

Proof. It suffices to show that

$$b_j = \frac{\partial f}{\partial x_j} = \left(\frac{\partial f_1}{\partial x_j}, \dots, \frac{\partial f_m}{\partial x_j} \right),$$

so let's do so. Observe that as $t \in \mathbb{R}$, $t \rightarrow 0$, hence $te_j \rightarrow 0$, where $\{e_1, \dots, e_n\}$ is the std basis for \mathbb{R}^n .

Then,

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - Bh}{\|h\|} = 0 &\Leftrightarrow \lim_{t \rightarrow 0} \frac{f(a+te_j) - f(a) - B(te_j)}{\|te_j\|} = 0 \\ &\Leftrightarrow \lim_{t \rightarrow 0^+} \frac{f(a+te_j) - f(a)}{t} = Be_j \quad \& \quad \lim_{t \rightarrow 0^-} \frac{f(a+te_j) - f(a)}{-t} = -Be_j \\ &\Leftrightarrow \lim_{t \rightarrow 0} \frac{f(a+te_j) - f(a)}{t} = Be_j \\ &\Leftrightarrow \frac{\partial f}{\partial x_j}(a) = Be_j = b_j, \end{aligned}$$

as needed. \square

\exists_2 In particular, if f is diff at a , then

① $\frac{\partial f}{\partial x_i}$ exists $\forall 1 \leq i \leq n$; and

$$\text{② } \lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - D_f(a)h}{\|h\|} = 0.$$

GRADIENT [OF $f: A \rightarrow \mathbb{R}$ AT a]: $\nabla f(a)$

\exists (let $a \in \mathbb{R}^n$, and $f: A \rightarrow \mathbb{R}$).

Then, the "gradient" of f at a , denoted as $\nabla f(a)$, is defined to be equal to

$$\nabla f(a) = D_f(a) = \left(\frac{\partial f}{\partial x_1}(a), \dots, \frac{\partial f}{\partial x_n}(a) \right).$$

Module 6.4:

Continuous Partial

$U \subseteq \mathbb{R}^n$ OPEN, $f: U \rightarrow \mathbb{R}$; $\frac{\partial f}{\partial x_j}$ EXISTS $\forall 1 \leq j \leq n$
AND IS CTS AT $a \in U \Rightarrow f$ IS DIFF AT a

B1 let $U \subseteq \mathbb{R}^n$ be open, and let $f: U \rightarrow \mathbb{R}$.

Suppose, for some $a \in U$, that $\frac{\partial f}{\partial x_j}$ exists on U

and is cts at a for each $1 \leq j \leq n$.

Then necessarily f is diff at a .

Proof. Let $a = (a_1, \dots, a_n)$. Since U is open, $\exists r > 0 \ni B_r(a) \subseteq U$.

Then, for any $h = (h_1, \dots, h_n) \neq 0 \ni a \in B_r(a)$, we have that

$$\begin{aligned} f(a+h) - f(a) &= f(a_1 + h_1, \dots, a_n + h_n) - f(a_1, \dots, a_n) \\ &= f(a_1 + h_1, \dots, a_n + h_n) - f(a_1, a_2 + h_2, \dots, a_n + h_n) \\ &\quad + f(a_1, a_2 + h_2, \dots, a_n + h_n) - f(a_1, a_2, a_3 + h_3, \dots, a_n + h_n) \\ &\quad + \dots \\ &\quad + f(a_1, \dots, a_{j-1}, a_j + h_j, \dots, a_n + h_n) - f(a_1, \dots, a_n). \end{aligned}$$

By the single variable MVT on x_i , $\forall 1 \leq i \leq n$, $\exists c_i$ bw $a_i, a_i + h_i$ \exists

$$f(a_1, \dots, a_{j-1}, a_j + h_j, \dots, a_n + h_n) - f(a_1, \dots, a_j, a_j + h_j, \dots, a_n + h_n)$$

$$a_j + h_j - a_j$$

$$= \frac{\partial f}{\partial x_j}(a_1, \dots, a_{j-1}, c_j, a_j + h_j, \dots, a_n + h_n).$$

Thus

$$f(a+h) - f(a) = \sum_{j=1}^n h_j \frac{\partial f}{\partial x_j}(a_1, \dots, a_{j-1}, c_j, a_j + h_j, \dots, a_n + h_n).$$

Next, for $1 \leq j \leq n$, let

$$\delta_j = \frac{\partial f}{\partial x_j}(a_1, \dots, a_{j-1}, c_j, a_j + h_j, \dots, a_n + h_n),$$

and $\delta = (\delta_1, \dots, \delta_n)$, so that

$$f(a+h) - f(a) = \nabla f(a) \cdot h = h\delta.$$

$f(a+h) - f(a) = \nabla f(a) \cdot h \rightarrow 0$, as $h \rightarrow 0$, each $\delta_j \rightarrow 0$, and

so $\delta \rightarrow 0$ in \mathbb{R}^n . Thus

$$\begin{aligned} 0 &\leq \lim_{h \rightarrow 0} \frac{|f(a+h) - f(a) - \nabla f(a) \cdot h|}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{|\delta \cdot h|}{\|h\|} \quad (\because \text{is the dot product}) \\ &\leq \lim_{h \rightarrow 0} \frac{\|\delta\| \|h\|}{\|h\|} \quad (\text{by Cauchy-Schwarz}) \\ &= 0. \end{aligned}$$

Hence

$$\lim_{h \rightarrow 0} \frac{|f(a+h) - f(a) - \nabla f(a) \cdot h|}{\|h\|} = 0,$$

and so

$$\lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - \nabla f(a) \cdot h}{\|h\|} = 0,$$

showing f is diff at a . \blacksquare

Note that the converse is not necessarily true!

e.g. let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ by

$$f(x,y) = \begin{cases} (x^2+y^2) \sin(\frac{1}{\sqrt{x^2+y^2}}), & (x,y) \neq (0,0) \\ 0, & (x,y) = (0,0) \end{cases}$$

we know f is diff at $(0,0)$ (using the theorem).

But

$$f_x(x,y) = 2x \sin\left(\frac{1}{\sqrt{x^2+y^2}}\right) - \cos\left(\frac{1}{\sqrt{x^2+y^2}}\right) \frac{x}{\sqrt{x^2+y^2}}, \quad \forall (x,y) \neq (0,0).$$

see that $\lim_{x \rightarrow 0} f_x(x,0) \rightarrow (0,0)$, but

$$f_x\left(\frac{1}{n}, 0\right) = \frac{2}{n} \sin(n) - \cos(n)$$

diverges, so f_x is not cts at $(0,0)$. \star

Module 7.1-7.2:

Differentiation Rules

$$D_{(f+g)}(a) = D_f(a) + \alpha D_g(a)$$

<< SUM & SCALAR MULTIPLICATION RULE >>

E: Let $f, g: A \rightarrow \mathbb{R}^m$ be diff at $a \in A \subseteq \mathbb{R}^n$.

Then necessarily for any $\alpha \in \mathbb{R}$, $f+g$ is diff at a and

$$D_{(f+g)}(a) = D_f(a) + \alpha D_g(a).$$

Why? Let $p = f+g$.

Then,

$$\begin{aligned} & \lim_{h \rightarrow 0} \frac{p(a+h) - p(a) - (D_f(a) + \alpha D_g(a))}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - D_f(a)}{\|h\|} + \alpha \lim_{h \rightarrow 0} \frac{g(a+h) - g(a) - D_g(a)}{\|h\|} \\ &= 0 + \alpha(0) = 0, \end{aligned}$$

so in particular

$$D_p(a) = D_f(a) + \alpha D_g(a)$$

as needed. \square

$$D_{(f \cdot g)}(a) = g(a) D_f(a) + f(a) D_g(a)$$

<< DOT PRODUCT RULE >>

E: Let $f, g: A \rightarrow \mathbb{R}^m$ be diff at $a \in A \subseteq \mathbb{R}^n$.

Consider $f \cdot g: A \rightarrow \mathbb{R}$ defined by

$$(f \cdot g)(x) = f(x) \cdot g(x) \quad (\text{dot product}).$$

Then necessarily $f \cdot g$ is diff at a and

$$D_{f \cdot g}(a) = g(a) D_f(a) + f(a) D_g(a).$$

Proof. We need to prove that

$$\lim_{h \rightarrow 0} \frac{(f \cdot g)(a+h) - (f \cdot g)(a) - Xh}{\|h\|} = 0,$$

where $X = g(a) D_f(a) + f(a) D_g(a)$, so let's do so.

Let

$$e(h) = f(a+h) - f(a) - D_f(a)h$$

$$\& s(h) = g(a+h) - g(a) - D_g(a)h.$$

Since f and g are diff at a , thus

$$\lim_{h \rightarrow 0} \frac{e(h)}{\|h\|} = \lim_{h \rightarrow 0} \frac{s(h)}{\|h\|} = 0.$$

Then

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{(f \cdot g)(a+h) - (f \cdot g)(a) - Xh}{\|h\|} &= \lim_{h \rightarrow 0} \frac{(f \cdot g)(a+h) - (f \cdot g)(a) - g(a) D_f(a) - f(a) D_g(a)}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{(g(a) f(a+h) - g(a) f(a)) - g(a) D_f(a) - f(a) D_g(a)}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{g(a) \cdot e(h) + f(a) \cdot s(h)}{\|h\|} \\ &\quad + \lim_{h \rightarrow 0} \frac{f(a) \cdot g(a) - g(a) \cdot f(a) - f(a) \cdot g(a+h) + f(a+h) \cdot g(a)}{\|h\|} \\ &= 0 + \lim_{h \rightarrow 0} \frac{f(a) \cdot g(a) - g(a) \cdot f(a) - f(a) \cdot g(a+h) + f(a+h) \cdot g(a)}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{g(a) \cdot (f(a) - f(a+h)) - g(a+h) \cdot (f(a) - f(a+h))}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{(g(a) - g(a+h)) \cdot (f(a) - f(a+h))}{\|h\|}. \end{aligned}$$

By Cauchy-Schwarz, we are taking the Euclidean norm!

$$\frac{|(g(a) - g(a+h)) \cdot (f(a) - f(a+h))|}{\|h\|} \leq \frac{\|(g(a) - g(a+h))\| \cdot \|(f(a) - f(a+h))\|}{\|h\|},$$

and so

$$\begin{aligned} 0 &\leq \lim_{h \rightarrow 0} \frac{|(g(a) - g(a+h)) \cdot (f(a) - f(a+h))|}{\|h\|} \\ &\leq \lim_{h \rightarrow 0} \frac{\|(g(a) - g(a+h))\| \cdot \|(f(a) - f(a+h))\|}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{\|(g(a) - g(a+h))\|}{\|h\|} \cdot \frac{\|(f(a) - f(a+h))\|}{\|h\|} \cdot \|h\| \\ &= \lim_{h \rightarrow 0} \frac{\|(g(a) - g(a+h))\|}{\|h\|} \cdot D_g(a)h + D_g(a)h \cdot \frac{\|(f(a) - f(a+h))\|}{\|h\|} \\ &\leq \lim_{h \rightarrow 0} \frac{\|(g(a) - g(a+h))\|}{\|h\|} \cdot D_g(a)h + \|D_g(a)h\| \cdot \frac{\|(f(a) - f(a+h))\|}{\|h\|} \\ &\leq \lim_{h \rightarrow 0} \frac{\|(g(a) - g(a+h))\|}{\|h\|} \cdot D_g(a)h + \|D_g(a)\|_{op} \|h\| \cdot \frac{\|(f(a) - f(a+h))\|}{\|h\|} + \|D_g(a)\|_{op} \|h\| \\ &= \lim_{h \rightarrow 0} (0 + \underbrace{\|D_g(a)\|_{op}}_{\text{constant}}) (0 + \underbrace{\|D_g(a)\|_{op}}_{\text{constant}}) \|h\| \\ &= 0, \end{aligned}$$

as needed. \square

$$D_{(gof)}(a) = D_g(f(a)) D_f(a)$$

<< THE CHAIN RULE >>

E: Let $A \subseteq \mathbb{R}^n$, $B \subseteq \mathbb{R}^m$, and let $f: A \rightarrow \mathbb{R}^m$, $g: B \rightarrow \mathbb{R}^k$, where $f(a) \in B$.

Suppose f is diff at $a \in A$ & g is diff at $f(a) \in B$. Then necessarily $g \circ f$ is diff at a , and

$$D_{(gof)}(a) = D_g(f(a)) \cdot D_f(a).$$

Proof. Let $X = D_g(f(a)) D_f(a)$.

$$\begin{aligned} \text{Let } b &= f(a), \\ E(h) &= f(a+h) - f(a) - D_f(a)h, \\ S(h) &= g(b+h) - g(b) - D_g(b)h, \end{aligned}$$

so that

$$\lim_{h \rightarrow 0} \frac{E(h)}{\|h\|} = 0 \quad \& \quad \lim_{h \rightarrow 0} \frac{S(h)}{\|h\|} = 0.$$

Consider $u = f(a+h) - f(a)$. By continuity of f at a ,

$$\begin{aligned} h \rightarrow 0 &\Rightarrow u \rightarrow 0. \text{ So } \lim_{h \rightarrow 0} \frac{(gof)(a+h) - (gof)(a) - D_g(f(a)) D_f(a)h}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{(g(b+h) - g(b) - D_g(b)h) - (g(b) - D_g(b)b - D_g(b)f(a)h) - D_g(f(a)) D_f(a)h}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{g(b+h) - g(b) - D_g(b)h - D_g(b)f(a)h + D_g(b)f(a)h - D_g(f(a)) D_f(a)h}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{g(b+h) - g(b) - D_g(b)h}{\|h\|} + \frac{D_g(b)f(a)h - D_g(f(a)) D_f(a)h}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{D_g(b)h}{\|h\|} + \frac{D_g(b)f(a)h - D_g(f(a)) D_f(a)h}{\|h\|}. \end{aligned}$$

Then, since

$$0 \leq \frac{\|D_g(b)\| \|h\|}{\|h\|} \leq \|D_g(b)\|_{op} \frac{\|h\|}{\|h\|} \rightarrow 0,$$

as $h \rightarrow 0$ it follows that

$$\lim_{h \rightarrow 0} \frac{D_g(b)h}{\|h\|} = 0.$$

Next, see that

$$\lim_{h \rightarrow 0} \frac{S(h)}{\|h\|} = \lim_{h \rightarrow 0} \frac{S(h)}{\|h\|} \cdot \frac{\|h\|}{\|h\|}.$$

However $\|h\| = \|Df(a)h + Eh\| \leq \|Df(a)h\|_{op} \|h\| + \|Eh\|$, from which it follows that $\frac{\|h\|}{\|h\|}$ is bounded.

By ST,

$$\lim_{h \rightarrow 0} \frac{S(h)}{\|h\|} = \lim_{h \rightarrow 0} \frac{S(h)}{\|h\|} \cdot \frac{\|h\|}{\|h\|} = 0,$$

and so the "entire" limit evaluates to 0, as needed. \square

We can apply this in a specific context, say \mathbb{R}^3 :

E: Let $f(x, y, z)$ be real-valued & diff.

Suppose $x(t_1, t_2)$, $y(t_1, t_2)$, $z(t_1, t_2)$ are diff real-valued functions themselves.

Let $P(t_1, t_2) = (x(t_1, t_2), y(t_1, t_2), z(t_1, t_2))$. By asmt, this is diff.

Moreover,

$$D_{(f \circ P)}(t_1, t_2) = D_f(P(t_1, t_2)) D_P(t_1, t_2) \quad (\text{chain rule}).$$

So

$$\nabla f(t_1, t_2) = \nabla f(x, y, z) \cdot D_P(t_1, t_2),$$

$$\left(\frac{\partial f}{\partial t_1}, \frac{\partial f}{\partial t_2} \right) = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) \left(\frac{\partial x}{\partial t_1}, \frac{\partial x}{\partial t_2}, \frac{\partial y}{\partial t_1}, \frac{\partial y}{\partial t_2}, \frac{\partial z}{\partial t_1}, \frac{\partial z}{\partial t_2} \right).$$

Equating components, it follows that

$$\frac{\partial f}{\partial t_1} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial t_1} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial t_1} + \frac{\partial f}{\partial z} \cdot \frac{\partial z}{\partial t_1}, \text{ and}$$

$$\frac{\partial f}{\partial t_2} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial t_2} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial t_2} + \frac{\partial f}{\partial z} \cdot \frac{\partial z}{\partial t_2}.$$

Module 7.3:

Mean Value Theorem

A naive approach to the MVT might look like this:

Say if $U \subseteq \mathbb{R}^n$ is open, and $f: U \rightarrow \mathbb{R}^m$ is diff.

If $a, b \in U$, then there exists a $c \in L(a, b) := \{(1-t)a + tb : t \in [0, 1]\}$

such that

$$f(b) - f(a) = D_f(c)(b-a).$$

But this doesn't work!

Eg consider $f: \mathbb{R} \rightarrow \mathbb{R}^2$, $f(x) = (\cos(x), \sin(x))$.

see that $f(0) = f(2\pi) = (1, 0)$.

But $D_f(x) = \begin{pmatrix} -\sin(x) \\ \cos(x) \end{pmatrix} \neq 0 \quad \forall x \in \mathbb{R}$.

$$\therefore 0 \neq 2\pi \begin{pmatrix} -\sin(x) \\ \cos(x) \end{pmatrix} \quad \forall x \in \mathbb{R}.$$

$\varphi: \mathbb{R} \rightarrow \mathbb{R}^n$, $\varphi(t) = (1-t)a + tb$ IS DIFF, WITH

$$D_\varphi(t) = b-a$$

(at $a, b \in \mathbb{R}^n$, and let $\varphi: \mathbb{R} \rightarrow \mathbb{R}^n$ be defined by

$$\varphi(t) = (1-t)a + tb.$$

Then φ is diff with

$$D_\varphi(t) = b-a.$$

Proof.

$$\begin{aligned} & \lim_{h \rightarrow 0} \frac{\|\varphi(t+h) - \varphi(t)\|}{\|h\|} = \frac{\|(1-t+h)a + tb - (1-t)a - tb - (b-a)h\|}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{\|(1-t+h)a + (t+h)b - (1-t)a - tb - (b-a)h\|}{\|h\|} \\ &= \lim_{h \rightarrow 0} \frac{\|h(a+b) - (b-a)h\|}{\|h\|} \\ &= 0. \# \end{aligned}$$

$f: U \rightarrow \mathbb{R}^m$ IS DIFF, $L(a, b) \subseteq U \Rightarrow$

$\forall x \in \mathbb{R}^m: \exists c \in L(a, b) \ni x \cdot (f(b) - f(a)) = x \cdot (D_f(c)(b-a))$

<< THE MEAN VALUE THEOREM / MVT >>

(at $U \subseteq \mathbb{R}^n$ be open, and let $f: U \rightarrow \mathbb{R}^m$ be diff and

$a, b \in U$ such that $L(a, b) \subseteq U$.

$L(a, b) := \text{"line" connecting } a \& b$.

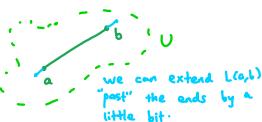
Then necessarily for any $x \in \mathbb{R}^m$, there exists a $c \in L(a, b)$ such that

$$x \cdot (f(b) - f(a)) = x \cdot (D_f(c)(b-a)).$$

Proof. Fix $x \in \mathbb{R}^m$. Consider $\varphi(t) = (1-t)a + tb$.

Note $\varphi([0, 1]) = L(a, b) \subseteq U$.

$\Rightarrow \exists g \in \mathbb{R}: \varphi(0-g, 1+g) \subseteq U$.



Then, for $t \in (-g, 1+g)$, consider

$$D_{f \circ \varphi}(t) = D_f(\varphi(t)) \varphi'(t) \quad (\text{chain rule})$$

$$\Rightarrow D_{f \circ \varphi}(t) = D_f(\varphi(t))(b-a) \quad (\text{by the lemma above}).$$

Now, let $F: (-g, 1+g) \rightarrow \mathbb{R}$ by $F(t) = x \cdot (f \circ \varphi)(t)$.

By the dot product rule:

$$F'(t) = x \cdot D_f(\varphi(t)) D_\varphi(t) = x \cdot D_f(\varphi(t))(b-a).$$

Then, by the single var MVT:

$$\exists t_0 \in (0, 1) \ni F(1) - F(0) = F'(t_0)(1-0).$$

$$\Rightarrow x \cdot f(\varphi(1)) - x \cdot f(\varphi(0)) = F'(t_0)(1-0).$$

$$\Rightarrow x \cdot f(b) - x \cdot f(a) = x \cdot D_f(\varphi(t_0))(b-a).$$

$$\Rightarrow x \cdot (f(b) - f(a)) = x \cdot D_f(\varphi(t_0))(b-a).$$

So, if we let $\varphi(t_0) = c$, we see this is exactly what MVT is asking for, and we're done!

Module 7.4:

Tangent Hyperplanes

HYPERPLANE

A "hyperplane" in \mathbb{R}^n is a set of the form

$$P = \{(x_1, \dots, x_n) \in \mathbb{R}^n : a_1x_1 + \dots + a_nx_n = d\}$$

for some fixed $a_1, \dots, a_n \in \mathbb{R}$ (not all zero) and $d \in \mathbb{R}$.

We note that

- ① $n=2$ hyperplanes = "lines", &
- ② $n=3$ hyperplanes = "planes".

NORMAL [VECTOR OF A HYPERPLANE]

Let $P = \{(x_1, \dots, x_n) : a_1x_1 + \dots + a_nx_n = d\}$ be a hyperplane in \mathbb{R}^n .

We call $n = (a_1, \dots, a_n)$ the "normal" vector of P .

Why is the normal vector important geometrically?

Let $b = (b_1, \dots, b_n) \in P$, so that

$$d = a_1b_1 + \dots + a_nb_n.$$

$$\Rightarrow x = (x_1, \dots, x_n) \in P \Leftrightarrow d = a_1x_1 + \dots + a_nx_n$$

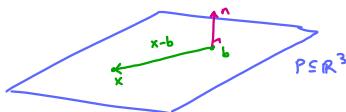
$$\Leftrightarrow 0 = d - d = a_1(x_1 - b_1) + \dots + a_n(x_n - b_n)$$

$$= n \cdot (x - b).$$

dot product.

$$\therefore P = \{x \in \mathbb{R}^n : n \cdot (x - b) = 0\};$$

i.e. $x \in P \Leftrightarrow n$ is orthogonal/perpendicular to $x - b$.



TANGENT [HYPERPLANES]

Let $A \subset \mathbb{R}^n$ and $a \in A$, and let P be a hyperplane with $a \in P$, with normal n .

Then, we say P is "tangent" to A at a

if $n \cdot \frac{a_k - a}{\|a_k - a\|} \rightarrow 0$

$$n \cdot \frac{a_k - a}{\|a_k - a\|} \rightarrow 0$$

for any sequences $(a_k) \subset A \setminus \{a\}$ with $a_k \rightarrow a$.

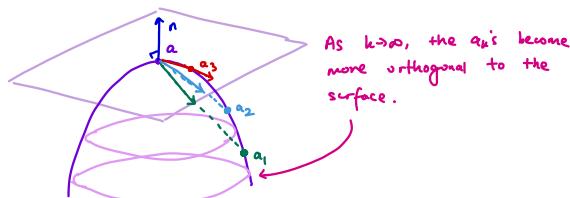
Why is this a good definition?

Recall that $a, b \in \mathbb{R}^n$ are ortho $\Leftrightarrow a \cdot b = 0$.

Then

$$n \cdot \frac{a_k - a}{\|a_k - a\|} \rightarrow 0$$

says that unit vectors in the direction of $a_k - a$ becomes closer and closer to being ortho to n as $k \rightarrow \infty$.



$f: U \rightarrow \mathbb{R}$, f IS DIFF AT $a \in U \Rightarrow$

$S = \{(x, z) \in \mathbb{R}^{n+1} : z = f(x), x \in U\}$ HAS A TANGENT HYPERPLANE AT $(a, f(a))$ WITH NORMAL $n = (\nabla f(a), -1)$

Let $U \subset \mathbb{R}^n$ be open, and let $a \in U$ and $f: U \rightarrow \mathbb{R}$.

Suppose f is diff at a .

Then the surface

$$S = \{(x, z) \in \mathbb{R}^{n+1} : z = f(x), x \in U\}$$

has a tangent hyperplane at $(a, f(a))$ with normal

$$n = (\nabla f(a), -1).$$

Proof. Let $(x_k, f(x_k)) \in S \setminus \{(a, f(a))\}$ be a sequence such that $(x_k, f(x_k)) \rightarrow (a, f(a))$.

So $x_k \rightarrow a$. We need to prove

$$\lim_{k \rightarrow \infty} n \cdot \frac{(x_k, f(x_k)) - (a, f(a))}{\|(x_k, f(x_k)) - (a, f(a))\|} = 0,$$

so let's do so. Since f is diff at a we have that

$$\lim_{k \rightarrow \infty} \frac{f(x_k) - f(a) - \nabla f(a) \cdot h}{\|h\|} = 0.$$

(at $0 \cdot h = f(x_k) - f(a) - \nabla f(a) \cdot h$, so that this implies that

$$\lim_{k \rightarrow \infty} \frac{\nabla f(x_k) \cdot h}{\|h\|} = 0.$$

Moreover, see that

$$\|(x_k, f(x_k)) - (a, f(a))\|^2 = \|(x_k - a, f(x_k) - f(a))\|^2 \geq \|x_k - a\|^2.$$

Since $x_k \rightarrow a$, thus

$$\begin{aligned} 0 &\leq \left| \lim_{k \rightarrow \infty} n \cdot \frac{(x_k, f(x_k)) - (a, f(a))}{\|(x_k, f(x_k)) - (a, f(a))\|} \right| \quad |n = (\nabla f(a), -1)| \\ &= \left| \lim_{k \rightarrow \infty} \frac{|\nabla f(a)(x_k - a) - (f(x_k) - f(a))|}{\|(x_k, f(x_k)) - (a, f(a))\|} \right| \\ &\leq \lim_{k \rightarrow \infty} \frac{|\nabla f(a)(x_k - a) - (f(x_k) - f(a))|}{\|x_k - a\|} \\ &= \lim_{k \rightarrow \infty} \frac{|\nabla f(x_k) \cdot (x_k - a)|}{\|x_k - a\|} \\ &= 0, \end{aligned}$$

and the result follows.

e.g. find the tangent plane to the surface $z = 2x^2 + y^2$ at $(1, 1, 3)$.

Soln. Consider $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ by

$$f(x, y) = 2x^2 + y^2.$$

Note that f_x, f_y exist & arects on \mathbb{R}^2 .

$\therefore f$ is diff on \mathbb{R}^2 .

Then

$$\nabla f(x, y) = (4x, 2y).$$

$$\therefore \nabla f(1, 1) = (4, 2).$$

$$\therefore n = (4, 2, -1).$$

\Rightarrow eq² of P is

$$P: 4x^2 + y^2 - z = d,$$

$$\text{where } d = 4(1)^2 + 2(1)^2 - 3 = 3.$$

\therefore eq² of P is
 $4x^2 + y^2 - z = 3$.

Module 8.1-8.2: Higher Order Total Derivatives

k^{th} ORDER TOTAL DERIVATIVE: $D^k f(a)$

💡 Let $U \subseteq \mathbb{R}^n$ be open, and let $f: U \rightarrow \mathbb{R}$,

Assume all partials of order $\leq k$ exist at $a \in U$.

Then, the " k^{th} order total derivative" of f at a , denoted by " $D^k f(a)$ ", is defined by

$D^k f(a): \mathbb{R}^n \rightarrow \mathbb{R}$ by

$$D^k f(a)(h_1, \dots, h_n) = \sum_{i_1=1}^n \dots \sum_{i_k=1}^n \frac{\partial^k f}{\partial x_{i_1} \dots \partial x_{i_k}}(a) h_{i_1} \dots h_{i_k}.$$

eg ($f: \mathbb{R}^2 \rightarrow \mathbb{R}$)

$$\begin{aligned} D^2 f(a)(h_1, h_2) &= f_{xx}(a)h_1^2 + f_{xy}(a)h_1h_2 \\ &\quad + f_{yx}(a)h_2h_1 + f_{yy}(a)h_2^2. \end{aligned}$$

$f \in C^p(U)$, $L(x, a) \subseteq U \Rightarrow \exists c \in L(x, a) \ni$

$$f(x) = f(a) + \sum_{k=1}^{p-1} \frac{1}{k!} D^k f(a)(x-a) + \frac{1}{p!} D^p f(c)(x-a)$$

«**TAYLOR'S THEOREM»»**

💡 Let $p \in \mathbb{N}$, $U \subseteq \mathbb{R}^n$ be open, and $f \in C^p(U)$.

Suppose $x, a \in U$ are such that $L(x, a) \subseteq U$.

Then, there necessarily exists a $c \in L(x, a)$ such that

$$f(x) = f(a) + \sum_{k=1}^{p-1} \frac{1}{k!} D^k f(a)(x-a) + \frac{1}{p!} D^p f(c)(x-a).$$

Proof. Let $h = x-a = (h_1, \dots, h_n)$. As $L(x, a) \subseteq U$ & U is open,

$$\exists \delta > 0 \ni a + th \in U \quad \forall t \in I := (-\delta, 1+\delta).$$

Then, by the chain rule, the fn $g: I \rightarrow \mathbb{R}$ by

$g(t) = f(a+th)$ is diff and

$$g'(t) = Df(a+th)h = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a+th)h_i.$$

We can also show by induction that for $1 \leq j \leq p$

$$g^{(j)}(t) = \sum_{i_1=1}^n \dots \sum_{i_j=1}^n \frac{\partial^j f}{\partial x_{i_1} \dots \partial x_{i_j}}(a+th)h_{i_1} \dots h_{i_j}.$$

In particular, for $1 \leq j \leq p-1$ we have

$$g^{(j)}(0) = D^j f(a)h$$

and

$$g^{(p)}(t) = D^p f(a+th)h.$$

Hence $g: I \rightarrow \mathbb{R}$ is p -times differentiable and so by the 1D version of Taylor's Theorem,

$$g(1) - g(0) = \sum_{k=1}^{p-1} \frac{1}{k!} g^{(k)}(0) + \frac{1}{p!} g^{(p)}(t)$$

for some $0 < t < 1$. Thus

$$f(x) - f(a) = f(a+th) - f(a) = \sum_{k=1}^{p-1} \frac{1}{k!} D^k f(a)(h) + \frac{1}{p!} D^p f(a+th)(h),$$

as needed. \blacksquare

Module 8.3:

Optimization

LOCAL MAXIMUM / MINIMUM (EXTREMA)

\exists : let $U \in \mathbb{R}^n$ be open, and let $f: U \rightarrow \mathbb{R}$ and $a \in U$. Then, we say $f(a)$ is a "local maximum" of f if there exists a $r > 0$ such that $f(x) \leq f(a) \forall x \in B_r(a)$.

\exists : Note that "local minimum" is defined similarly, but with $f(x) \geq f(a) \forall x \in B_r(a)$ instead.

\exists : We say $f(a)$ is a "(local extrema)" if it is a local minimum or maximum.

$f(a)$ IS A LOCAL EXTREMA $\Rightarrow \nabla f(a) = 0$

\exists : let $f: U \rightarrow \mathbb{R}$ be diff., and let $a \in U$ so that $f(a)$ is a local extrema.

Then necessarily $\nabla f(a) = 0$.

Proof: Say $a = (a_1, \dots, a_n)$.

Then $g_i(t) = f(a_1, \dots, a_{i-1}, t, a_{i+1}, \dots, a_n)$

has a local extrema at $t = a_i$; i.e. $g'_i(a_i) = 0$.

i.e. $\frac{\partial f}{\partial x_i} = 0$.

$\therefore \nabla f(a) = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right) = 0$. \square

SADDLE POINT

\exists : Consider

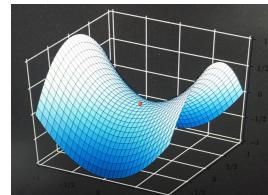
$$f(x, y) = x^2 - y^2$$

So $\nabla f(x, y) = (2x, -2y)$,

and so

$$\nabla f(0, 0) = (0, 0)$$

But the point isn't a local extrema!



\exists : In fact, we say $f(a)$ is a "saddle point" if $\nabla f(a) = 0$ but $f(a)$ is not a local extrema.

2nd DERIVATIVE TEST

\exists : let $U \in \mathbb{R}^n$ be open, let $f: C^2(U)$, and let $a \in U$. Suppose $\nabla f(a) = 0$. Then:

- ① If for all $h \neq 0$, $D^2 f(a)(h) > 0 \Rightarrow f(a)$ is a local min;
- ② If for all $h \neq 0$, $D^2 f(a)(h) < 0 \Rightarrow f(a)$ is a local max;
- ③ If $\exists h, k \in \mathbb{R}^n$ such that $D^2 f(a)(h) > 0$ & $D^2 f(a)(k) < 0$

$\Rightarrow a$ is a saddle point.

Proof: Lemma #1: Let $U \in \mathbb{R}^n$ be open & let $f: C^2(U)$. If $a \in U$ & $D^2 f(a)(h) > 0 \forall h \neq 0$, then $\exists m > 0 \Rightarrow D^2 f(a)(x) \geq m \|x\|^2 \forall x \in \mathbb{R}^n$.

Proof: Consider the compact set $K = \{x \in \mathbb{R}^n : \|x\| = 1\}$.

As $f \in C^2(U)$, thus $D^2 f(a)$ is cts and +ve on K .

By EVT, $\exists m > 0 \Rightarrow m = \min_{x \in K} \{D^2 f(a)(x) : x \in K\}$.

For $0 \neq x \in \mathbb{R}^n$, we see $\frac{x}{\|x\|} \in K$ and so

$$D^2 f(a)\left(\frac{x}{\|x\|}\right) = \frac{1}{\|x\|^2} D^2 f(a)(x) \geq m,$$

and the proof follows. \square

Lemma #2: Let $U \in \mathbb{R}^n$ be open and let $f \in C^2(U)$. Suppose $a \in U$ $\Rightarrow \nabla f(a) = 0$. Let $r > 0 \Rightarrow B_r(a) \subseteq U$. Then \exists a \mathbb{R}^n $E: B_r(a) \rightarrow \mathbb{R} \Rightarrow \lim_{h \rightarrow 0} E(h) = 0$ & $f(a+h) - f(a) = \frac{1}{2} D^2 f(a)(h) + \|h\|^2 E(h)$ for sufficiently small $\|h\|$.

Proof: Consider $E(h) := \frac{f(a+h) - f(a) - \frac{1}{2} D^2 f(a)(h)}{\|h\|^2}$ for $0 \neq h \in B_r(a)$ & $E(0) := 0$.

We just need to prove $\lim_{h \rightarrow 0} E(h) = 0$.

Since $\nabla f(a) = 0$, by Taylor's Theorem it follows that

$$f(a+h) - f(a) = \frac{1}{2} D^2 f(a)h \text{ for some } c \in L(a, a+h).$$

Then

$$\begin{aligned} 0 &\leq |E(h)| \|h\|^2 \\ &= \left| \frac{1}{2} D^2 f(a)h - \frac{1}{2} D^2 f(a)h \right| \\ &\leq \frac{1}{2} \sum_j \left| \frac{\partial^2 f}{\partial x_i \partial x_j}(c) - \frac{\partial^2 f}{\partial x_i \partial x_j}(a) \right| \|h\| \|h\| \\ &\leq \frac{1}{2} \sum_j \left| \frac{\partial^2 f}{\partial x_i \partial x_j}(c) - \frac{\partial^2 f}{\partial x_i \partial x_j}(a) \right| \|h\|^2, \end{aligned}$$

which $\rightarrow 0$ as $c \rightarrow a$ as $h \rightarrow 0$ & $f \in C^2(U)$ (so $\frac{\partial^2 f}{\partial x_i \partial x_j}$ is cts).

Proof follows. \square

We can now prove the main result.

Let $r > 0$ such that $B_r(a) \subseteq U$. By lemma #2, $\exists E: B_r(a) \rightarrow \mathbb{R} \Rightarrow$

$$\lim_{h \rightarrow 0} E(h) = 0$$

$$2 \quad f(a+h) - f(a) = \frac{1}{2} D^2 f(a)(h) + \|h\|^2 E(h)$$

for sufficiently small h .

① Then, suppose $D^2 f(a)(h) > 0 \forall h \neq 0 \in \mathbb{R}^n$. Let $m > 0 \Rightarrow$

$$D^2 f(a)(x) \geq m \|x\|^2 \forall x \in \mathbb{R}^n,$$

which we can do by lemma #1.

Then

$$f(a+h) - f(a) = \frac{1}{2} D^2 f(a)(h) + \|h\|^2 E(h) \geq \left(\frac{m}{2} + E(h) \right) \|h\|^2 > 0$$

as needed.

② If $D^2 f(a)(h) < 0 \forall h \neq 0 \in \mathbb{R}^n$, the result follows by replacing f with $-f$ in ①.

③ Let $h \in \mathbb{R}^n$. For small $t \in \mathbb{R}$,

$$\begin{aligned} f(a+th) - f(a) &= \frac{1}{2} D^2 f(a)(th) + \|th\|^2 E(th) \quad (\text{by lemma #2}) \\ &= t^2 \left(\frac{1}{2} D^2 f(a)(h) + \|h\|^2 E(h) \right). \end{aligned}$$

(Letting $t \rightarrow 0$, we see $E(th) \rightarrow 0$ and so $f(a+th) - f(a)$ takes on the same sign as $D^2 f(a)(h)$, which can be both the + & -ve. Thus a is a saddle point, as needed. \square)

$$\varphi(h, k) = ah^2 + 2bhk + ck^2, \quad a, b, c \in \mathbb{R}, \quad D = b^2 - ac;$$

$D < 0 \Rightarrow \text{sign}(a) = \text{sign}(\varphi(h, k)); \quad D > 0 \Rightarrow \varphi(h, k) \text{ TAKES}$

+VE & -VE VALUES

Let $a, b, c \in \mathbb{R}$, with $\varphi(h, k) = ah^2 + 2bhk + ck^2$ and $D = b^2 - ac$.

Then,

① If $D < 0$, then a and $\varphi(h, k)$ share the same sign;

② If $D > 0$, then $\varphi(h, k)$ can take positive & negative values.

$$f \in C^2(U), \quad \nabla f(a, b) = 0, \quad D = f_{xy}(a, b) - f_{xx}(a, b)f_{yy}(a, b);$$

$D < 0, f_{xx}(a, b) > 0 \Rightarrow f(a, b) \text{ IS A LOCAL MIN}; \quad D > 0,$

$f_{xx}(a, b) < 0 \Rightarrow f(a, b) \text{ IS A LOCAL MAX}; \quad D > 0 \Rightarrow$

(a, b) IS A SADDLE POINT

Let $U \subseteq \mathbb{R}^2$ be open, with $f \in C^2(U)$ and $\nabla f(a, b) = 0$.

Let $D := f_{xy}(a, b)^2 - f_{xx}(a, b)f_{yy}(a, b)$ (this is called the "discriminant").

Then,

① If $D < 0$ & $f_{xx}(a, b) > 0$, then $f(a, b)$ is a local minimum;

② If $D < 0$ & $f_{xx}(a, b) < 0$, then $f(a, b)$ is a local maximum; and

③ If $D > 0$, then (a, b) is a saddle point.

Proof Follows from the above lemma by setting $a = f_{xx}(a, b)$,

$b = f_{xy}(a, b)$ & $c = f_{yy}(a, b)$, so that

$$\varphi(h, k) = D^2 f(a, b)h^2. \quad \square$$

$$\text{Ex: } f(x, y) = x^4 + y^4 - 4xy + 2$$

Q. Classify all local extrema and/or saddle points of

$$f(x, y) = x^4 + y^4 - 4xy + 2.$$

Soln. See that

$$\begin{aligned} \nabla f(x, y) &= (4x^3 - 4y, \quad 4y^3 - 4x) \\ \therefore \nabla f(x, y) = 0 &\Leftrightarrow \begin{cases} x^3 - y = 0 \\ y^3 - x = 0 \end{cases} \Leftrightarrow \begin{cases} x^3 = y \\ y^3 = x \end{cases} \Leftrightarrow x = x^9 \Leftrightarrow x = 0, y = 0 \\ &\quad \text{or } x = 1, y = 1 \\ &\quad \text{or } x = -1, y = -1. \end{aligned}$$

Then,

$$f_{xx}(x, y) = 12x^2, \quad f_{yy}(x, y) = 12y^2, \quad f_{xy}(x, y) = f_{yx}(x, y) = -4.$$

① For $(0, 0)$: $D = 16 - 0(0) > 0 \Rightarrow$ saddle point.

② For $(1, 1)$: $D = 16 - 12(12) < 0$, and $f_{xx}(1, 1) = 12 > 0$

$\Rightarrow f(1, 1) = 0$ is a local min

③ For $(-1, -1)$: $D = 16 - 12(12) < 0$, and $f_{xx}(-1, -1) = 12 > 0$

$\Rightarrow f(-1, -1) = 0$ is a local min.

$$\text{Ex: ABS MAX/MIN OF } f(x, y) = 2x^3 + y^4$$

Q. Note that the "absolute max" and "absolute min" is defined by $\max f(k)$ & $\min f(k)$ respectively, which exist by EVT.

Q. Let $K = \overline{B(0, 0)}$. Find the absolute max & min of $f: K \rightarrow \mathbb{R}$ by $f(x, y) = 2x^3 + y^4$.

Soln. Crit pts of $f: B(0, 0) \rightarrow \mathbb{R}$:

$$\nabla f(x, y) = (6x^2, 4y^3) = (0, 0)$$

$$\Leftrightarrow (x, y) = (0, 0).$$

Note that $f(0, 0) = 0$.

Then,

$$\partial(K) = \{(x, y) : x^2 + y^2 = 1\}.$$

For $(x, y) \in \partial(K)$, we see that

$$\begin{aligned} f(x, y) &= 2x^3 + (1-x^2)^4 \\ &= x^4 + 2x^3 - 2x^2 + 1. \quad (z = g(x)). \end{aligned}$$

consider $g(x)$ on $[-1, 1]$.

$$\begin{aligned} \Rightarrow g'(x) &= 4x^3 + 6x^2 - 4x \\ &= 2x(2x^2 + 3x - 2) \\ &= 2x(2x - 1)(x + 2) \end{aligned}$$

$$\therefore g'(x) = 0 \Leftrightarrow x = 0, x = \frac{1}{2}, x = -2.$$

Then

$$g(0) = 1, \quad g\left(\frac{1}{2}\right) = \frac{13}{16}.$$

$$g(1) = 2, \quad g(-1) = -2.$$

* * *

\therefore abs max: $f(1, 0) = 2$; &
abs min: $f(-1, 0) = -2$. \square

Module 9.1:

Inverse Function Theorem

JACOBIAN [OF f AT a]: $Jf(a) = \det(Df(a))$

(let $U \subseteq \mathbb{R}^n$, $f: U \rightarrow \mathbb{R}^n$ & let $a \in U$.

Then, the "Jacobian" of f at a , denoted by,

" $Jf(a)$ ", is equal to

$$Jf(a) := \det(Df(a)).$$

$B_r(a) \subseteq U$; $f: B_r(a) \rightarrow \mathbb{R}^n$ IS CTS & 1-1; 1ST

ORDER PARTIALS OF f EXIST ON $B_r(a)$;

$Jf \neq 0 \Rightarrow \exists \epsilon > 0 \Rightarrow B_\epsilon(f(a)) \subseteq f(B_r(a))$

(let $U \subseteq \mathbb{R}^n$ be open, and let $a \in U$ so there exists a $r > 0$ such that $B_r(a) \subseteq U$.

(let $f: U \rightarrow \mathbb{R}^n$ be cts and 1-1 when restricted to $B_r(a)$, and assume its first order partials exist on $B_r(a)$).

Suppose $Jf \neq 0$ on $B_r(a)$.

Then there exists a $\epsilon > 0$ such that $B_\epsilon(f(a)) \subseteq f(B_r(a))$.

Proof. Consider $g: B_r(a) \rightarrow \mathbb{R}$ by $g(x) = \|f(x) - f(a)\|$.

As f is cts & injective on $B_r(a)$, thus g is cts, & note $g(x) > 0 \forall x \neq a$.

Thus, by EVT,

$$m = \inf\{g(x) : \|x - a\| = r\} > 0.$$

Take $\epsilon = \frac{m}{2}$. We claim $B_\epsilon(f(a)) \subseteq f(B_r(a))$.

Indeed, let $y \in B_\epsilon(f(a))$. By EVT, there exists a $b \in B_r(a)$ such that

$$\|f(b) - y\| = \inf\{\|f(x) - y\| : x \in B_r(a)\}.$$

Suppose $\|b - a\| = r$. Then

$$\begin{aligned} \epsilon &> \|f(a) - y\| \\ &\geq \|f(b) - y\| \\ &\geq \|f(b) - f(a)\| - \|f(a) - y\| \\ &= g(b) - \|f(a) - y\| \\ &\geq m - \epsilon \\ &= 2\epsilon - \epsilon \\ &= \epsilon, \end{aligned}$$

c contd. Thus $b \in B_r(a)$.

If we show $y = f(b)$ were done.

Consider the cts fn $h: B_r(a) \rightarrow \mathbb{R}$ by $h(x) = \|f(x) - y\|$.

By construction, $h(b)$ is the min value of h .

Moreover, $h^2(b)$ is the min value of h^2 .

As $b \in B_r(a)$, which is open, we have $\partial h^2(b) = 0$.

However,

$$h^2(x) = \sum_{i=1}^n (f_i(x) - y_i)^2,$$

and so

$$0 = \frac{\partial h^2}{\partial x_j} = \sum_{i=1}^n 2(f_i(x) - y_i) \frac{\partial f_i}{\partial x_j}(b) \quad \forall 1 \leq j \leq n.$$

Thus $Df(b)x = 0$, where $x = (2(f_1(b) - y_1), \dots, 2(f_n(b) - y_n))^T$.

Since $Df(b) \neq 0$, thus $Df(b)$ is invertible, and so $x = 0$.

Hence $f(b) = y$. as needed. \square

$f: U \rightarrow \mathbb{R}^n$ IS CTS & 1-1, ALL 1ST ORDER PARTIALS EXIST ON U , $Jf \neq 0$ ON $U \Rightarrow f^{-1}$ IS CTS ON $f(U)$

(let $U \subseteq \mathbb{R}^n$ be open & non-empty.

Then, if $f: U \rightarrow \mathbb{R}^n$ is cts, 1-1, has all first-order

partials existing on U & $Jf \neq 0$ on U ,

then necessarily f^{-1} is cts on $f(U)$.

Proof. To show $f^{-1}: f(U) \rightarrow \mathbb{R}^n$ is cts it suffices to show $f(w)$ is open if $w \in f(U)$ is open.

Well, (let W be such a set, and take $b \in f(W)$)

$$\Rightarrow b = f(a) \text{ for some } a \in W.$$

As W is open, $\exists r > 0 \Rightarrow B_r(a) \subseteq W$. By the prev (lemma), $\exists \epsilon > 0 \Rightarrow$

$$B_\epsilon(b) \subseteq f(B_r(a)).$$

$\Rightarrow B_\epsilon(b) \subseteq f(W)$, so $f(W)$ is open. \square

$\forall c_1, \dots, c_n \in B_r(a)$

(let $U \subseteq \mathbb{R}^n$ be open, and let $f: U \rightarrow \mathbb{R}^n$).

Suppose $a \in U$ such that $Jf(a) \neq 0$.

Then there exists a $r > 0$ such that

$$\textcircled{1} \quad B_r(a) \subseteq U,$$

$$\textcircled{2} \quad f \text{ is injective on } B_r(a);$$

$$\textcircled{3} \quad Jf \neq 0 \text{ on } B_r(a); \text{ & }$$

$$\textcircled{4} \quad \det\left(\frac{\partial f_i}{\partial x_j}(c_i)\right) \neq 0 \quad \forall c_1, \dots, c_n \in B_r(a).$$

Proof. (let $W = U^n$. consider $h: W \rightarrow \mathbb{R}$ by

$$h(x_1, \dots, x_n) = \det\left(\left(\frac{\partial f_i}{\partial x_j}(x_i)\right)_{ij}\right).$$

As $f: U \rightarrow \mathbb{R}^n$, and a determinant is a polynomial of its entries, we must have that h is cts.

Note $h(a, \dots, a) = Jf(a) \neq 0$.

So \exists open interval $(a_1, \dots, a_n) \in W \ni 0 \neq I$.

Then $h^{-1}(I)$ is open (as W is open) and so $\exists r > 0$

$$\Rightarrow B_r(a, \dots, a) \subseteq h^{-1}(I).$$

But then $\exists r > 0 \Rightarrow$

$$B_r(a) \times \dots \times B_r(a) \subseteq B_r(a, \dots, a) \subseteq h^{-1}(I).$$

Thus $Jf \neq 0$ on $B_r(a)$ &

$$\det\left(\left(\frac{\partial f_i}{\partial x_j}(c_i)\right)_{ij}\right) \neq 0 \quad \forall c_1, \dots, c_n \in B_r(a).$$

So, we just need to show f is 1-1 on $B_r(a)$.

Suppose $\exists x, y \in B_r(a) \Rightarrow f(x) = f(y)$.

As f is diff on $B_r(a)$, every f_i is diff on $B_r(a)$.

Fix $i \in \{1, \dots, n\}$. By the MVT, $\exists c_i \in L(x, y) \Rightarrow$

$$0 = f_i(x) - f_i(y) = Df_i(c_i)(x - y).$$

Letting $A = \left(\frac{\partial f_i}{\partial x_j}(c_i)\right)_{ij}$, we see $A(x - y) = 0$.

As $x - y \neq 0$, A is not invertible and so $\det\left(\left(\frac{\partial f_i}{\partial x_j}(c_i)\right)_{ij}\right) = 0$, a contd. \square

$A \in M_{n \times n}(\mathbb{R})$ IS INVERTIBLE $\Rightarrow Ax = b$ HAS A UNIQUE

SOLN $x = (x_1, \dots, x_n)^T$ BY $x_i = \frac{\det(A^{(i)})}{\det(A)}$, $A^{(i)} :=$

A WITH i^{th} COLUMN = b (Cramer's Rule)

(let $A \in M_{n \times n}(\mathbb{R})$ be invertible, and consider a system of equations $Ax = b$.

Then this system has a unique solution $x = (x_1, \dots, x_n)^T \in \mathbb{R}^n$

by

$$x_i = \frac{\det(A^{(i)})}{\det(A)}.$$

where $A^{(i)} :=$ the matrix obtained by replacing its i^{th} column with b .

$f \in C^1(U, \mathbb{R}^n)$, $Jf(a) \neq 0 \Rightarrow \exists$ open $a \in W \ni a$

f is 1-1 on W , $f^{-1} \in C^1(f(W), \mathbb{R}^n)$, &
 $Df^{-1}(y) = [Df(x)]^{-1} \quad \forall y \in f(W), x = f^{-1}(y)$

<< THE INVERSE FUNCTION THEOREM >>

Let $U \subseteq \mathbb{R}^n$ be open, with $f \in C^1(U, \mathbb{R}^n)$.
 Let $a \in U$ such that $Jf(a) \neq 0$.
 Then there exists an open $a \in W \ni a$ such that
 ① f is injective on W ;
 ② $f^{-1} \in C^1(f(W), \mathbb{R}^n)$; &
 ③ For any $y \in f(W)$,
 $D(f^{-1})(y) = [Df(x)]^{-1}$,
 where $x = f^{-1}(y)$.

Proof:
 ① By the most recent lemma (L3), $\exists r > 0 \Rightarrow W := B_r(a) \cap U \ni a$ is

$$\text{injective on } W, Jf \neq 0 \text{ on } W, \text{ &} \\ \det\left(\frac{\partial f_i}{\partial x_j}(c_i)\right) \neq 0 \quad \forall i, j \in \mathbb{N}_n.$$

By the previous lemma (L2), f^{-1} is cts on $f(W)$.

② We claim $f^{-1} \in C^1(f(W), \mathbb{R}^n)$. Fix $y_0 \in f(W)$ & $1 \leq i, j \leq n$.
 choose $t \in \mathbb{R}$ sufficiently small so that $y_0 + te_j \in f(W)$.
 We may then find $x_0, x_t = x_t(t) \in W \Rightarrow f(x_0) = y_0$ & $f(x_t) = y_0 + te_j$.
 By MVT, $\forall i \in \mathbb{N}_n \exists c_i = c_i(t) \in L(x_0, x_t)$ \Rightarrow

$$\nabla f_i(c_i)(x_t - x_0) = f_i(x_t) - f_i(x_0) = \begin{cases} t, & i=j \\ 0, & \text{otherwise.} \end{cases}$$

Thus

$$\nabla f_i(c_i)\left(\frac{x_t - x_0}{t}\right) = \frac{1}{t}(f_i(x_t) - f_i(x_0)) = \begin{cases} 1, & i=j \\ 0, & \text{otherwise.} \end{cases}$$

Now let $A \in M_{n \times n}(\mathbb{R})$ with i th row $= \nabla f_i(c_i)$.
 By assumption, $\det(A_j) \neq 0$, and moreover, $A_j \cdot \left(\frac{x_t - x_0}{t}\right) = e_j$.

For $1 \leq k \leq n$, we see that

$$\frac{(f^{-1})_k(y_0 + te_j) - (f^{-1})_k(y_0)}{t} = \frac{x_{j,k} - x_{0,k}}{t},$$

where by Cramer's Rule, $Q_k(t) := \frac{x_{j,k} - x_{0,k}}{t}$ is a quotient of determinants of matrices whose entries are either 0, 1 or a 1st order partial evaluated at $a \in \mathbb{R}$.

Since $t \rightarrow 0$, thus $y_0 + te_j \rightarrow y_0$. By continuity of f^{-1} , hence $x_t \rightarrow x_0$, and so $c_i \rightarrow x_0$.

As f is C^1 , thus $Q_k(t) \rightarrow Q_k$, where Q_k is a quotient of determinants of matrices whose entries are either 0, 1 or a first-order partial of f evaluated at a $x_0 = f^{-1}(y_0)$.

As $f \in C^1$ & f^{-1} is cts at y_0 , thus f^{-1} is cts at each $y \in f(W)$.

Moreover,

$$\lim_{t \rightarrow 0} \frac{(f^{-1})_k(y_0 + te_j) - (f^{-1})_k(y_0)}{t} = \lim_{t \rightarrow 0} \frac{x_{j,k} - x_{0,k}}{t} = Q_k.$$

Hence all the partial derivatives of f^{-1} exist and are cts at y_0 , ie $f^{-1} \in C^1(f(W), \mathbb{R}^n)$.

③ Therefore, by the chain rule, for $y \in f(W)$, we have

$$I = Df(y) = D(f \circ f^{-1})(y) = Df \circ f^{-1}(y) Df^{-1}(y).$$

The result follows. \square

Ex: $f(x,y) = (x+y, \sin x + \cos y)$

Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $f(x,y) = (x+y, \sin(x) + \cos(y))$.

$$f_x(x,y) = (1, \cos(x)); \quad \&$$

$$f_y(x,y) = (1, -\sin(y)),$$

$$\text{so } f \in C^1(\mathbb{R}^2, \mathbb{R}^2).$$

Prove f^{-1} exists & is diff on some open set containing $(0,1)$, and compute $Df^{-1}(0,1)$.

Sol: Note

$$f(x,y) = (0,1) \Leftrightarrow (x+y, \sin x + \cos y) = (0,1)$$

$$\Leftrightarrow y = -x, \sin(x) + \cos(x) = 1$$

$$\Leftrightarrow y = -x, \sin(x) + \cos(x) = 1$$

$$\Leftrightarrow (x,y) = (2k\pi, -2k\pi), k \in \mathbb{Z} \text{ — case (1)}$$

$$\text{or } (x,y) = (\frac{\pi}{2} + 2k\pi, -\frac{\pi}{2} - 2k\pi), k \in \mathbb{Z} \text{ — case (2).}$$

$$\text{Case (1): } a = (2k\pi, -2k\pi), k \in \mathbb{Z}.$$

$$\Rightarrow Jf(a) = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} = -1 \neq 0.$$

and so by the Inv Fn Thm \exists open $a \in W \subseteq \mathbb{R}^2 \ni a$ is 1-1 on W & $f^{-1} \in C^1(f(W), \mathbb{R}^2)$.

$$\text{Note } (0,1) \in f(W).$$

$$\Rightarrow Df^{-1}(0,1) = [Df(a)]^{-1}$$

$$= \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & -1 \end{pmatrix}.$$

$$\text{Case (2): } a = (\frac{\pi}{2} + 2k\pi, -\frac{\pi}{2} - 2k\pi)$$

$$\Rightarrow Jf(a) = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} = 1 \neq 0.$$

So, \exists open $a \in W \subseteq \mathbb{R}^2 \ni a$ is 1-1 on W & $f^{-1} \in C^1(f(W), \mathbb{R}^2)$ with

$$Df^{-1}(0,1) = Df(a)^{-1}$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}.$$

* Note that the way we reflect f to make it injective depends on our choice for $f^{-1}(y)$.

Module 9.2:

Implicit Function Theorem

$U \subseteq \mathbb{R}^{n+p}$; $f = (f_1, \dots, f_n) \in C^1(U, \mathbb{R}^n)$; $x_0 \in \mathbb{R}^n$, $t_0 \in \mathbb{R}^p \Rightarrow$
 $f(x_0, t_0) = 0$; $\det\left[\frac{\partial f_i}{\partial x_j}(x_0, t_0)\right]_{n \times n} \neq 0 \Rightarrow \exists$ open $V \subseteq \mathbb{R}^p$ &
 A UNIQUE $g \in C^1(V, \mathbb{R}^n) \Rightarrow g(t_0) = x_0 \& f(g(t), t) = 0 \quad \forall t \in V$

<< IMPLICIT FUNCTION THEOREM >>

Q: Let $U \subseteq \mathbb{R}^{n+p}$ be open, and let $f = (f_1, \dots, f_n) \in C^1(U, \mathbb{R}^n)$.
 Let $x_0 \in \mathbb{R}^n$, $t_0 \in \mathbb{R}^p$ be such that $f(x_0, t_0) = 0$.

Suppose $\det\left(\frac{\partial f_i}{\partial x_j}(x_0, t_0)\right)_{n \times n} \neq 0$.

Then there exists an open $V \subseteq \mathbb{R}^p$ and a unique $g \in C^1(V, \mathbb{R}^n)$
 such that

- ① $g(t_0) = x_0$; &
- ② $f(g(t), t) = 0 \quad \forall t \in V$.

Proof: For every $(x, t) \in U$, let
 $F(x, t) := (f_1(x, t), \dots, f_n(x, t), t_1, \dots, t_p)$.

Note $F(x_0, t_0) = (0, t_0)$.

Then, F is a map from U to \mathbb{R}^{n+p} with

$$DF = \begin{pmatrix} \frac{\partial f_i}{\partial x_j}(x_0, t_0) & B \\ 0_{pn} & I_{p \times p} \end{pmatrix}$$

where B is a matrix whose entries are first order
 partials of the f_i 's wrt the t_j 's.

Taking the determinant of DF evaluated at (x_0, t_0)
 yields that

$$JF(x_0, t_0) = \det\left(\frac{\partial f_i}{\partial x_j}(x_0, t_0)\right)_{n \times n} \cdot \det I_{n \times p} \neq 0,$$

so by the Inv Fn Thm there exists an open set
 $(x_0, t_0) \in W \subseteq U \Rightarrow F$ is inj on W & $F^{-1} \in C^1(F(W), (\mathbb{R}^{n+p})^*)$.

Let $G = F^{-1} = (G_1, \dots, G_n, g_1, \dots, g_{n+p})$. Consider $\varphi: F(W) \rightarrow \mathbb{R}^n$

by
 $\varphi = (G_1, \dots, G_n)$.

By construction,

$$\varphi(F(x, t)) = x \quad \forall (x, t) \in W.$$

$$F(\varphi(x, t), t) = (x, t) \quad \forall (x, t) \in F(W).$$

Consider $V = \{t \in \mathbb{R}^p : (0, t) \in F(W)\} \& g: V \rightarrow \mathbb{R}^n$ by $g(t) = \varphi(0, t)$.

As G is C^1 , it follows φ is also C^1 , so $g \in C^1(V, \mathbb{R}^n)$.

Also note V is open since $F(W)$ is open.

Finally, see that

$$g(t_0) = \varphi(0, t_0) = \varphi(F(x_0, t_0)) = x_0,$$

and for $(x, t) \in F(W)$,

$$f(\varphi(x, t), t) = x.$$

In particular,

$$0 = f(\varphi(0, t), t) = f(g(t), t) = 0 \quad \forall t \in V.$$

Uniqueness follows from injectivity of F .

$$\text{eg } 1: xyz + \sin(x+yz) = 0$$

Q: Consider

$$f(x, y, z) = xyz + \sin(x+yz),$$

so $f \in C^1(\mathbb{R}^3)$.

Note $f(0, 0, 0) = 0$.

Now,

$$f_x(x, y, z) = yz + \cos(x+yz)$$

$$\Rightarrow f_x(0, 0, 0) = 1 \neq 0.$$

Hence

$$\det[I] = 1 \neq 0.$$

So, by the Implicit Function Theorem, there exists

a open $V \subseteq \mathbb{R}^2$ with $(0, 0) \in V$ and $g(x, y) \in C^1(V)$

such that $g(0, 0) = 0$ and

$$f(x, y, g(x, y)) = 0 \quad \forall (x, y) \in V.$$

i.e. $z = g(x, y)$ on V .

$$\text{eg } 2: u, v: \mathbb{R}^4 \rightarrow \mathbb{R}$$

Q: Prove there exist $u, v: \mathbb{R}^4 \rightarrow \mathbb{R}$ and $(2, -1, -1, -2) \in U \subseteq \mathbb{R}^4$
 open such that

$$\textcircled{1} \quad u, v \in C^1(U);$$

$$\textcircled{2} \quad u(2, -1, -1, -2) = 4 \quad \& \quad v(2, -1, -1, -2) = 3; \quad \text{and}$$

$$\textcircled{3} \quad \text{For all } (x, y, z, w) \in U, \text{ we have}$$

$$u^2 + v^2 + w^2 = 29; \quad \& \quad u^2 = (u(x, y, z, w))^2$$

$$\frac{u^2}{x^2} + \frac{v^2}{y^2} + \frac{w^2}{z^2} = 17.$$

Sol 2. Let $f: \mathbb{R}^5 \rightarrow \mathbb{R}$ by

$$f(u, v, x, y, z, w) = (u^2 + v^2 + w^2 - 29, \frac{u^2}{x^2} + \frac{v^2}{y^2} + \frac{w^2}{z^2} - 17)$$

we want to replace u, v & w as x, y, z, w ,

i.e. keep u, v & replace x, y, z, w .

$\hookrightarrow n=2, p=4$.

See that

$$f(\underbrace{u}_{2}, \underbrace{v}_{2}, \underbrace{x}_{2}, \underbrace{y}_{2}, \underbrace{z}_{2}, \underbrace{w}_{2}) = 0.$$

and

$$\det\left(\begin{array}{cc} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{array}\right) = \begin{vmatrix} 2u & 2v \\ 2u & 2v \end{vmatrix} = 4uv\left(\frac{1}{y^2} - \frac{1}{x^2}\right).$$

This is non-zero at

$$(4, 3, 2, -1, -1, -2)$$

So by the impl fn thm, \exists open $(2, -1, -1, -2) \in U \&$

$$g \in C^1(U, \mathbb{R}^2) \Rightarrow g(2, -1, -1, -2) = (4, 3) \quad \&$$

$$\forall (x, y, z, w) \in U, \quad f(g(x, y, z, w), x, y, z, w) = 0.$$

$$g = (g_1, g_2)$$

$$\text{Take } u(x, y, z, w) = g_1(x, y, z, w)$$

$$\& v(x, y, z, w) = g_2(x, y, z, w).$$

Since $g \in C^1(U)$, thus $u, v \in C^1(U)$.

See that

$$u(2, -1, -1, -2) = 4$$

$$\& v(2, -1, -1, -2) = 3,$$

and see that

$$f(g(x, y, z, w), x, y, z, w) = 0$$

$$\Rightarrow f(\underbrace{u(x, y, z, w)}_u, \underbrace{v(x, y, z, w)}_v, x, y, z, w) = 0$$

$$\Rightarrow u^2 + v^2 + w^2 = 29 \quad \& \quad \frac{u^2}{x^2} + \frac{v^2}{y^2} + \frac{w^2}{z^2} = 17. \quad \blacksquare$$

Module 9.3:

Lagrange Multipliers

LOCAL MAXIMUM/MINIMUM [SUBJECT TO THE CONSTRAINTS $g_i: U \rightarrow \mathbb{R}$]

Let $U \subset \mathbb{R}^n$ be open, with $f: U \rightarrow \mathbb{R}$.

Let $a \in U$.

Then, we say $f(a)$ is a "local maximum" of f

subject to the constraints

$$g_i: U \rightarrow \mathbb{R}, 1 \leq i \leq m$$

if $g_i(a) = 0$ for each i and there exists a $r > 0$

such that whenever $x \in B_r(a)$ and $g_i(x) = 0 \forall i$,

then $f(x) \leq f(a)$.

Similarly, we say $f(a)$ is a "local minimum" of f

subject to the constraints

$$g_i: U \rightarrow \mathbb{R}, 1 \leq i \leq m$$

if $g_i(a) = 0$ for each i and there exists a $r > 0$

such that whenever $x \in B_r(a)$ and $g_i(x) = 0 \forall i$,

then $f(x) \geq f(a)$.

$f, g_1, \dots, g_m \in C^1(U)$, $\det\left(\frac{\partial g_i}{\partial x_j}(a)\right)_{m \times m} \neq 0$, $f(a)$ IS A LOCAL EXTREMUM SUBJECT TO THE CONSTRAINTS g_i

$$\Rightarrow \exists \lambda_1, \dots, \lambda_m \in \mathbb{R} \ni \nabla f(a) + \sum_{i=1}^m \lambda_i \nabla g_i(a) = 0$$

Let $U \subset \mathbb{R}^n$ be open, and let $m \in \mathbb{N}$.

Let $f, g_1, \dots, g_m \in C^1(U)$.

Suppose $a \in U$ such that

$$\det\left(\frac{\partial g_i}{\partial x_j}(a)\right)_{m \times m} \neq 0, \quad \text{we only use } x_1, \dots, x_m.$$

and let $f(a)$ be a local extremum of f .

Subject to the constraints g_i .

Then there exists $\lambda_1, \dots, \lambda_m \in \mathbb{R}$ such that

$$\nabla f(a) + \sum_{i=1}^m \lambda_i \nabla g_i(a) = 0.$$

Idea: $m=2, n=3$.

We want to show $\exists \lambda_1, \mu \in \mathbb{R}$

$$\lambda \frac{\partial g_1}{\partial x_j}(a) + \mu \frac{\partial g_2}{\partial x_j}(a) = -\frac{\partial f}{\partial x_j}(a) \quad \forall j=1, 2, 3.$$

$$\text{let } A = \begin{pmatrix} \frac{\partial g_1}{\partial x_1}(a) & \frac{\partial g_1}{\partial x_2}(a) \\ \frac{\partial g_2}{\partial x_1}(a) & \frac{\partial g_2}{\partial x_2}(a) \end{pmatrix},$$

so $\det A \neq 0$.

In particular,

$$(\lambda, \mu) A = \begin{pmatrix} -\frac{\partial f}{\partial x_1}(a) \\ -\frac{\partial f}{\partial x_2}(a) \end{pmatrix}$$

has a unique soln (λ, μ) .

We need to show

$$\lambda \frac{\partial g_1}{\partial x_3}(a) + \mu \frac{\partial g_2}{\partial x_3}(a) = -\frac{\partial f}{\partial x_3}(a). \quad (\star)$$

We then "use" the Impl in Thm to replace x_3 w/

$h(x_1, x_2)$, and prove (\star) with what we know

about x_1, x_2 .

eg': $f(x, y, z) = x+2y$

Maximize & minimize $f(x, y, z) = x+2y$ subject to the constraints

$$\textcircled{1} \quad x+y+z=1; \quad \&$$

$$\textcircled{2} \quad y^2+z^2=4.$$

Sol'n: Geometrically, such a max/min must exist (intersection is compact, so follows from EVT).

Let

$$f(x, y, z) = x+2y$$

$$g(x, y, z) = x+y+z-1$$

$$h(x, y, z) = y^2+z^2-4$$

Note

$$\begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 2z & 1 \end{vmatrix} = 2z \neq 0 \quad \text{for } y \neq 0.$$

Then, if $g(x, y, z) = h(x, y, z) = 0$, then

$$z=2, x=-1 \quad \text{or} \quad z=-2, x=3.$$

So

$$f(-1, 0, 2) = 1 \quad \& \quad f(3, 0, -2) = 3.$$

Otherwise, such a max/min is of the form

$$\nabla f = \lambda \nabla g + \mu \nabla h$$

$$\Rightarrow (1, 2, 0) = \lambda(1, 1, 1) + \mu(0, 2z, 2z).$$

$$\Rightarrow y = \pm \sqrt{z}, \quad z = \frac{1}{2}x^2, \quad x = 1.$$

$$\text{Then } f(1, \sqrt{2}, \sqrt{2}) = 1+2\sqrt{2} \quad (\text{max})$$

$$\& \quad f(1, -\sqrt{2}, \sqrt{2}) = 1-2\sqrt{2} \quad (\text{min}).$$

$$\text{f}(1, -\sqrt{2}, -\sqrt{2}) = 1-2\sqrt{2}$$

Module 10.1-2: Riemann Integration

$$\int_a^b f(x) dx := \inf \{U(f, P)\}; \quad \int_a^b f(x) dx := \sup \{L(f, P)\}$$

Q_1 (at P be a partition, and let $f: [a, b] \rightarrow \mathbb{R}$ be bounded.

Recall that

$$U(f, P) = \sum_{i=1}^n M_i (x_i - x_{i-1}), \quad M_i = \sup \{f(x) : x \in [x_{i-1}, x_i]\};$$

$$L(f, P) = \sum_{i=1}^n m_i (x_i - x_{i-1}), \quad m_i = \inf \{f(x) : x \in [x_{i-1}, x_i]\}.$$

Q_2 Then, denote

$$\int_a^b f(x) dx := \inf \{U(f, P) : P \text{ is a partition}\};$$

$$\int_a^b f(x) dx := \sup \{L(f, P) : P \text{ is a partition}\}.$$

Q_3 Recall that f is integrable iff

$$\int_a^b f(x) dx = \int_a^b f(x) dx,$$

and in this case we set

$$\int_a^b f(x) dx = \int_a^b f(x) dx = \int_a^b f(x) dx.$$

RECTANGLE

Q_1 A "rectangle" in \mathbb{R}^n is a set of the form

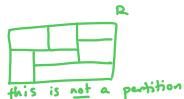
$$R = [a_1, b_1] \times \dots \times [a_n, b_n].$$

PARTITION [OF A RECTANGLE]

Q_1 (at R be a rectangle, say

$$R = [a_1, b_1] \times \dots \times [a_n, b_n].$$

Then, a "partition" of R is a grid of rectangles on R obtained by partitioning each $[a_i, b_i]$.



VOLUME [OF A RECTANGLE]

Q_1 (at $R \subseteq \mathbb{R}^n$ be a rectangle, say

$$R = [a_1, b_1] \times \dots \times [a_n, b_n].$$

Then, the "volume" of R is

$$v(R) = (b_1 - a_1) \dots (b_n - a_n).$$

UPPER/LOWER SUM [OF f RELATIVE TO P]: $U(f, P)$ & $L(f, P)$

Q_1 (at $R \subseteq \mathbb{R}^n$ be a rectangle, and let $f: R \rightarrow \mathbb{R}$ be bounded.

(at $P = \{R_1, \dots, R_n\}$ be a partition of R .

Then, the "upper sum" of f relative to P , denoted by $U(f, P)$, is defined by

$$U(f, P) = \sum_{i=1}^n M_i v(R_i),$$

where $M_i = \sup \{f(x) : x \in R_i\}$.

Q_2 Similarly, the "lower sum" of f relative to P , denoted by $L(f, P)$, is defined by

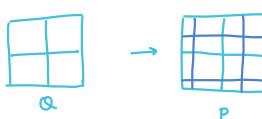
$$L(f, P) = \sum_{i=1}^n m_i v(R_i),$$

where $m_i = \inf \{f(x) : x \in R_i\}$.

REFINEMENT [OF A PARTITION]: $P \leq Q$

Q_1 (at P, Q be partitions of $R \subseteq \mathbb{R}^n$.

Then, we say P is a "refinement" of Q , written " $P \leq Q$ ", if P is obtained from Q by partitioning the sides of R even further.



$$P \leq Q \Rightarrow U(f, P) \leq U(f, Q), \quad L(f, P) \geq L(f, Q)$$

Q_1 (at $P \leq Q$ on R , and let $f: R \rightarrow \mathbb{R}$ be bounded.

Then necessarily

$$\textcircled{1} \quad U(f, P) \leq U(f, Q); \quad \text{and}$$

$$\textcircled{2} \quad L(f, P) \geq L(f, Q).$$

why?



$$M \nu(R) = M_1 \nu(R_1) + \dots + M_4 \nu(R_4)$$

$$\geq m_1 \nu(R_1) + \dots + m_4 \nu(R_4)$$

$$m \nu(R) \leq m_1 \nu(R_1) + \dots + m_4 \nu(R_4).$$

Argument can be generalized. \square

LOWER/UPPER INTEGRAL [OF f ON R]

Q_1 (at $f: R \rightarrow \mathbb{R}$ be bd, where R is a rectangle.

Then, the "lower integral" of f , denoted by $\underline{\int}_R f$, is defined to be

$$\underline{\int}_R f = \sup \{L(f, P) : P\}$$

and the "upper integral" of f , denoted by $\overline{\int}_R f$, is defined to be

$$\overline{\int}_R f = \inf \{U(f, P) : P\}.$$

RIEMANN INTEGRABLE [OVER R]

Q_1 (at $f: R \rightarrow \mathbb{R}$ be bd.

Then, we say f is "Riemann integrable" over R if

$$\int_R f := \underline{\int}_R f + \overline{\int}_R f.$$

SOME FUNCTIONS ARE NOT INTEGRABLE

Q_1 Consider

$$f(x, y) = \begin{cases} 1, & x \in Q, \\ 0, & x \notin Q \end{cases}$$

Then

$$\forall P, \quad U(f, P) = 1$$

$$\& \forall P, \quad L(f, P) = 0$$

so

$$\underline{\int}_R f = 0 \neq 1 = \overline{\int}_R f.$$

$$f: R \rightarrow \mathbb{R} \text{ BD} \Rightarrow L(f, P) \leq U(f, Q)$$

Let $f: R \rightarrow \mathbb{R}$ be bounded, and let P & Q be partitions of R .

Then necessarily $L(f, P) \leq U(f, Q)$.

Why? find a common refinement.

$$S \subseteq P, S \subseteq Q.$$

(eq "overlap" P & Q).

Then

$$L(f, P) \leq L(f, S)$$

$$\leq U(f, S)$$

$$\leq U(f, Q). \quad \#$$

Note: we just proved for any P, Q :

$$L(f, P) \leq U(f, Q).$$

Thus

$$L(f, P) \leq \underline{\int}_R f$$

and

$$\underline{\int}_R f \leq \overline{\int}_R f.$$

$f: R \rightarrow \mathbb{R}$ IS INTEGRABLE $\Leftrightarrow \forall \epsilon > 0, \exists P \ni$

$$U(f, P) - L(f, P) < \epsilon$$

Let $f: R \rightarrow \mathbb{R}$ be bd.

Then f is integrable iff for any $\epsilon > 0$, there exists a partition P such that

$$U(f, P) - L(f, P) < \epsilon.$$

Proof. (\Rightarrow) Assume f is integrable, so that

$$\underline{\int}_R f = \overline{\int}_R f.$$

Let $\epsilon > 0$. we know we may find partition

$P, Q \ni$

$$\underline{\int}_R f - \frac{\epsilon}{2} < L(f, P)$$

$$U(f, Q) < \overline{\int}_R f + \frac{\epsilon}{2}.$$

Thus

$$U(f, Q) \leq L(f, P) + \epsilon.$$

Let S be a common refinement of P & Q ,

so $S \subseteq P, Q$.

Thus

$$U(f, S) \leq U(f, Q)$$

$$< L(f, P) + \epsilon$$

$$< L(f, S) + \epsilon.$$

$$\Rightarrow U(f, S) - L(f, S) < \epsilon. \quad \#$$

(\Leftarrow) Let $\epsilon > 0$. we may find $P \ni$

$$U(f, P) - L(f, P) < \epsilon.$$

Hence

$$0 \leq \overline{\int}_R f - \underline{\int}_R f \leq U(f, P) - L(f, P)$$

$$< \epsilon$$

$$\Rightarrow \overline{\int}_R f = \underline{\int}_R f \quad (\text{as } \epsilon \text{ was arbitrary}).$$

Module 10.3:

Content and Measure

LEBESGUE MEASURE ZERO

Let $A \subseteq \mathbb{R}^n$. Then, we say A has "(Lebesgue) measure zero" if for all $\epsilon > 0$, there exists rectangles R_1, \dots, R_m such that $A \subseteq \bigcup_{i=1}^m R_i$ and $\sum_{i=1}^m v(R_i) < \epsilon$.

JORDAN CONTENT ZERO

Let $A \subseteq \mathbb{R}^n$. Then, we say A has "(Jordan) content zero" if for all $\epsilon > 0$, there exists rectangles R_1, \dots, R_m such that $A \subseteq \bigcup_{i=1}^m R_i$ and $\sum_{i=1}^m v(R_i) < \epsilon$.

Note that if $A \subseteq \mathbb{R}^n$ has content zero, then it has measure zero.

Proof. Let $\epsilon > 0$. Suppose $A \subseteq \mathbb{R}^n$ has content zero. Then, \exists rect R_1, \dots, R_m such that $A \subseteq R_1 \cup \dots \cup R_m$ and $\sum_{i=1}^m v(R_i) < \epsilon$. Now, for $i > m$, let $R_i \subseteq \mathbb{R}^n$ be any rectangle w/ volume 0. $\therefore A \subseteq R_1 \cup \dots \cup R_m \cup R_{m+1} \cup \dots \cup R_n$ and $\sum_{i=1}^n v(R_i) < \epsilon$.

The converse is not true!

e.g. $A = \mathbb{Q} \cap \mathbb{R}$.

① \mathbb{Q} has measure zero.

Proj. we know $|B| = |N|$, i.e.

$$\mathbb{Q} = \{q_1, q_2, \dots\}$$

Let $\epsilon > 0$. Let $R_i = [q_i - \frac{\epsilon}{2^{i+1}}, q_i + \frac{\epsilon}{2^{i+1}}]$.

Then $\mathbb{Q} \subseteq \bigcup_{i=1}^{\infty} R_i$.

And $\sum_{i=1}^{\infty} v(R_i) = \sum_{i=1}^{\infty} \frac{\epsilon}{2^{i+1}}$

$$= \frac{\epsilon}{4} \sum_{i=1}^{\infty} \frac{1}{2^i}$$

$$= \frac{\epsilon}{4} \left(\frac{1}{1 - \frac{1}{2}} \right) = \frac{\epsilon}{2} < \epsilon.$$

② \mathbb{Q} does not have content zero.

Proof. Because it is unbounded. \square

Note that if A has Jordan content zero, it has to be bounded.

$A_i \subseteq \mathbb{R}^n, i \in \mathbb{N}$ HAVE MEASURE ZERO $\Rightarrow A = \bigcup_{i=1}^{\infty} A_i$

HAS MEASURE ZERO

Let $A_1, A_2, \dots \subseteq \mathbb{R}^n$ have measure zero.

Then necessarily $A = \bigcup_{i=1}^{\infty} A_i$ has measure zero.

Why? Let $\epsilon > 0$. We know for each A_i ,

$$A_i \subseteq \bigcup_{j=1}^{\infty} R_{i,j}$$

$$\text{Also } \sum_{j=1}^{\infty} v(R_{i,j}) < \frac{\epsilon}{2^i}.$$

Then

$$A \subseteq \bigcup_{i,j} R_{i,j}.$$

$$\text{Then } \sum_{i,j} v(R_{i,j}) = \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} v(R_{i,j})$$

$$< \sum_{i=1}^{\infty} \frac{\epsilon}{2^i}$$

$$= \frac{\epsilon}{2} \sum_{i=1}^{\infty} \frac{1}{2^i}$$

$$= \epsilon. \quad \square$$

$A \subseteq \mathbb{R}^n$ IS COMPACT AND HAS MEASURE ZERO \Rightarrow

A HAS CONTENT ZERO

Let $A \subseteq \mathbb{R}^n$ be compact, and have measure zero.

Then necessarily A has content zero.

Proof. Let $\epsilon > 0$. By asmt, \exists open rects $R_i \ni A$

$$A \subseteq \bigcup_{i=1}^{\infty} R_i \quad \& \quad \sum_{i=1}^{\infty} v(R_i) < \epsilon.$$

Thm, as A is compact,

$$A \subseteq \bigcup_{i=1}^m R_i$$

for some m .

Moreover,

$$\sum_{i=1}^m v(R_i) \leq \sum_{i=1}^{\infty} v(R_i) < \epsilon. \quad \square$$

Module 10.4:

Integrability and Measure

OSCILLATION COF f AT a]: $\Theta(f,a)$

Let $A \subseteq \mathbb{R}^n$, and let $f: A \rightarrow \mathbb{R}$ be bounded.

For $a \in A$ & $\delta > 0$, denote

$$M(a, f, \delta) = \sup \{f(x) : x \in A, \|x - a\| < \delta\};$$

$$m(a, f, \delta) = \inf \{f(x) : x \in A, \|x - a\| < \delta\}.$$

Then, the "oscillation of f at a ", denoted by " $\Theta(f,a)$ ", is defined to be

$$\Theta(f,a) = \lim_{\delta \rightarrow 0} M(a, f, \delta) - m(a, f, \delta).$$

Note that

① $\Theta(f,a)$ always exists; and

② f is cts at a iff $\Theta(f,a) = 0$.

$A \subseteq \mathbb{R}^n$ IS CLOSED, $f: A \rightarrow \mathbb{R}$ IS BD $\Rightarrow \forall \epsilon > 0, \{x \in A : \Theta(f,x) \geq \epsilon\}$ IS CLOSED

Let $A \subseteq \mathbb{R}^n$ be closed, and let $f: A \rightarrow \mathbb{R}$ be bounded. Then for any $\epsilon > 0$, necessarily $\{x \in A : \Theta(f,x) \geq \epsilon\}$ is closed.

Proof. Let $B = \{x \in A : \Theta(f,x) \geq \epsilon\}$.

Take $x \in A \setminus B$. We will show $A \setminus B$ is rel open

in A .

$\Rightarrow \Theta(f,x) < \epsilon$, and so $\exists \delta > 0$ with

$$M(x, f, \delta) - m(x, f, \delta) < \epsilon.$$

Consider $y \in B_{\frac{\delta}{2}}(x) \cap A$.

Then, for $z \in A$ w/ $\|y - z\| < \frac{\delta}{2}$, thus

$$\|z - x\| \leq \|z - y\| + \|y - x\| < \delta,$$

and

$$m(x, f, \delta) \leq f(z) \leq M(x, f, \delta).$$

Thus

$$M(y, f, \frac{\delta}{2}) - m(y, f, \frac{\delta}{2}) < \epsilon.$$

$$\Rightarrow \Theta(f,y) < \epsilon$$

$$\Rightarrow B_{\frac{\delta}{2}}(x) \cap A \subseteq A \setminus B$$

$\Rightarrow A \setminus B$ is rel open in A

$\Rightarrow B$ is rel closed in A

$\Rightarrow B$ is closed (since A is closed). \square

$f: R \rightarrow \mathbb{R}$ BD, $\Theta(f,x) < \epsilon \forall x \in R \Rightarrow \exists P \ni U(f,P) - L(f,P) < \epsilon \cdot V(R)$

$U(f,P) - L(f,P) < \epsilon \cdot V(R)$

Let $R \subseteq \mathbb{R}^n$ be a rectangle, and let $f: R \rightarrow \mathbb{R}$ be bounded.

Let $\epsilon > 0$. Suppose for each $x \in R$, we have

$$\Theta(f,x) < \epsilon.$$

Then necessarily there exists a partition P such that

$$U(f,P) - L(f,P) < \epsilon \cdot V(R).$$

Proof. For all $x \in R$, $\exists \delta_x > 0$

$$M(x, f, \delta_x) - m(x, f, \delta_x) < \epsilon.$$

For all $x \in R$, let R_x be an open rect s.t.

$$x \in R_x \subseteq B_{\frac{\delta_x}{2}}(x).$$

Let $U_x = R_x \cap R$. Then

$$R = \bigcup_{x \in R} U_x$$

is a rel open cover of R . Since R is compact,

$$\exists x_1, \dots, x_m \in R$$

$$R = U_{x_1} \cup \dots \cup U_{x_m}$$

Let P be a partition of R so fine \rightarrow each subrectangle in P is contained in some U_{x_i} . Note

$$\overline{U_{x_i}} = \overline{R_{x_i}} \cap R$$

$$\subseteq \overline{B_{\frac{\delta_{x_i}}{2}}(x_i)} \cap R \quad (\text{by const of } R_{x_i})$$

$$\subseteq B_{\frac{\delta_{x_i}}{2}}(x_i) \cap R.$$

\therefore for every $R_i \in P$,

$$M_i - m_i < \epsilon.$$

$$\Rightarrow U(f,P) - L(f,P) = \sum_{R_i \in P} (M_i - m_i) V(R_i)$$

$$< \sum_{R_i \in P} \epsilon V(R_i)$$

$$= \epsilon V(R). \quad \square$$

$f: R \rightarrow \mathbb{R}$ BD, $A = \{x \in R : f \text{ is NOT cts at } x\}$

f IS INTEGRABLE $\Leftrightarrow A$ HAS MEASURE ZERO

Let $R \subseteq \mathbb{R}^n$ be a rectangle, and let $f: R \rightarrow \mathbb{R}$ be bounded.

Let $A = \{x \in R : f \text{ is not cts at } x\}$.

Then necessarily f is integrable iff A has measure zero.

Proof. (\Leftarrow)

Let $B = \{x \in R : \Theta(f,x) \geq \epsilon\}$, so B is compact (R is bounded) from our first proposition.

Since $B \subseteq A$, $R \setminus B$ is open at pts of continuity, thus B also has measure zero.

Since B is compact, B also has content zero.

In particular, \exists finitely many rectangles U_1, \dots, U_m (by comp.) whose interiors cover B & $\sum V(U_i) < \epsilon$.

Let X denote the set of subrects of R contained in $\bigcup U_i$.

Let Y denote the set of subrectangles of R contained in $R \setminus B$.

Now, since the U_i 's cover B , we may find a partition $P = \{R_1, \dots, R_k\}$ fine enough so that the elements of P are either from X or Y .

Then, since f is bounded, $\exists M > 0 \Rightarrow |f(x)| \leq M \forall x \in R$.

In particular, $\forall R_i \in P, M_i - m_i \leq 2M$. By defn of X :

$$\sum_{R_i \in X} (M_i - m_i) V(R_i) \leq 2M \sum_{R_i \in X} V(R_i) \leq 2M \sum_{i=1}^m V(U_i) < 2M\epsilon.$$

Now, if $R_i \in Y$ & $x \in R_i$, we have $\Theta(f,x) < \epsilon$. By the 2nd prop in this page, we may find a partition $P_i = \{S_{i1}, \dots, S_{im_i}\}$ of $R_i \ni x$

$$\sum_{j=1}^{m_i} (M_j - m_j) V(S_{ij}) < \epsilon V(R_i).$$

By replacing each $R_i \in Y$ w/ S_{i1}, \dots, S_{im_i} (and leaving $R_i \in X$ alone), this creates a refinement $Q \subseteq P$. Finally,

$$\begin{aligned} U(f,Q) - L(f,Q) &= \sum_{R_i \in X} (M_i - m_i) V(R_i) + \sum_{R_i \in Y} \sum_{j=1}^{m_i} (M_j - m_j) V(S_{ij}) \\ &< 2M\epsilon + \sum_{R_i \in Y} \epsilon V(R_i) \\ &\leq 2M\epsilon + \epsilon V(R), \end{aligned}$$

which can be made arbitrarily small, and so f is integrable, as needed. $\#$

(\Rightarrow)

For every $n \in \mathbb{N}$, let $B_n = \{x \in R : \Theta(f,x) \geq \frac{1}{n}\}$.

As $A = B_1 \cup B_2 \cup \dots$, it suffices to show each B_n has measure zero.

Fix $n \in \mathbb{N}$. Since f is integrable, we may find a

partition P of $R \ni$

$$U(f,P) - L(f,P) < \frac{\epsilon}{n}.$$

Let X be the collection of rect in P that intersect B_n .

In particular, the elements of X cover B_n and are rectangles!

Now, if $R_i \in X$, then $M_i - m_i \geq \frac{1}{n}$ by defn of B . Then

$$\begin{aligned} \frac{1}{n} \sum_{R_i \in X} V(R_i) &\leq \sum_{R_i \in X} (M_i - m_i) V(R_i) \\ &\leq \sum_{R_i \in P} (M_i - m_i) V(R_i) \\ &= U(f,P) - L(f,P) < \frac{\epsilon}{n}. \end{aligned}$$

and so $\sum_{R_i \in X} V(R_i) < \epsilon$, and so B_n has measure (content) zero.

Module III.1:

General Integrability

CHARACTERISTIC FUNCTION [OF A ON R]:

$$\chi_A(x)$$

Let $A \subseteq \mathbb{R}^n$ be bd, and let R be a rectangle such that $A \subseteq R$.

Then, the "characteristic function" of A on R , denoted by χ_A , is

$$\chi_A : R \rightarrow \mathbb{R}$$

defined by

$$\chi_A(x) = \begin{cases} 1, & x \in A \\ 0, & x \notin A \end{cases}$$

RIEMANN INTEGRABLE [OVER A]

Let $A \subseteq \mathbb{R}^n$ be bd, and let $f: A \rightarrow \mathbb{R}$ be bd.

Let R be a rectangle with $A \subseteq R$.

Then, extend $f: R \rightarrow \mathbb{R}$ by setting $f(x) = 0 \forall x \in R \setminus A$.

We say $f: A \rightarrow \mathbb{R}$ is "integrable" iff $f \cdot \chi_A: R \rightarrow \mathbb{R}$ is integrable, in which case we define

$$\int_A f := \int_R f \cdot \chi_A.$$

Note that this definition is independent of choice of $A \subseteq R$. (Asmt).

Note that if $f: R \rightarrow \mathbb{R}$ & $\chi_A: R \rightarrow \mathbb{R}$ are integrable, then $f \cdot \chi_A$ is also integrable, so that f is integrable on A .

$\chi_A: R \rightarrow \mathbb{R}$ IS INTEGRABLE $\Leftrightarrow \delta(A)$ HAS MEASURE ZERO

Let $A \subseteq \mathbb{R}^n$ be bd, and let $A \subseteq R$ for some rect R . Then, $\chi_A: R \rightarrow \mathbb{R}$ is integrable iff $\delta(A)$ has measure zero.

Proof. (at $a \in R$).

① $a \in \text{Int}(A)$.

$\Rightarrow \exists$ open ball $B_\delta(a) \subseteq A$.

Since $\chi_A = 1$ on $B_\delta(a)$, χ_A is clearly cts at a .

② $a \notin \bar{A}$.

$\Rightarrow a \in \text{Int}(\mathbb{R}^n \setminus A) \Rightarrow \exists B_\delta(a) \subseteq \mathbb{R}^n \setminus A$.

Since $\chi_A = 0$ on $B_\delta(a) \cap A$, χ_A is clearly cts at a .

③ $a \in \bar{A} \setminus \text{Int}(A) = \delta(A)$

\Rightarrow then $a \in \bar{A}$ & $a \in \mathbb{R}^n \setminus \text{Int}(A)$

$$= \overline{\mathbb{R}^n \setminus A}.$$

$\Rightarrow \forall \delta > 0, \exists x \in A, y \in \mathbb{R}^n \setminus A \ni$

$$\|x - a\|, \|y - a\| < \delta.$$

Thus

$$\theta(\chi_A, a) \geq 1$$

So χ_A is not cts at a .

\Rightarrow set of discontinuities of χ_A is exactly $\delta(A)$.

\Rightarrow proof follows from big theorem in previous thm.

JORDAN REGION

If let $A \subseteq \mathbb{R}^n$ be bd.

Then, we say A is a "Jordan region" iff

$\delta(A)$ has measure zero

(ie iff χ_A is integrable on $R \setminus A$).

VOLUME [OF A JORDAN REGION]: $\text{Vol}(A)$

If let A be a Jordan region, with $A \subseteq R$.

Then, the "volume" of A , denoted by $\text{Vol}(A)$, is defined to be

$$\text{Vol}(A) = \int_R \chi_A = \int_A 1.$$

A, B ARE JORDAN REGIONS $\Rightarrow A \cup B$ IS A JORDAN REGION; $A \cap B = \emptyset$ & $f: A \cup B \rightarrow \mathbb{R}$ IS INTEGRABLE

$$\Rightarrow \int_{A \cup B} f = \int_A f + \int_B f$$

If let $A, B \subseteq \mathbb{R}^n$ be Jordan regions.

Then necessarily

① $A \cup B$ is a Jordan region; and

② If $A \cap B = \emptyset$ & $f: A \cup B \rightarrow \mathbb{R}$ is integrable, then

$$\int_{A \cup B} f = \int_A f + \int_B f.$$

why? ① $\delta(A \cup B) = (\overline{A \cup B}) \setminus \text{Int}(A \cup B)$

$$= (\overline{A} \cup \overline{B}) \setminus (\text{Int}(A) \cup \text{Int}(B))$$

$$= (\overline{A} \setminus \text{Int}(A)) \cup (\overline{B} \setminus \text{Int}(B))$$

$$= \delta(A) \cup \delta(B).$$

② Let $A \cup B \subseteq R$. Then

$$\int_{A \cup B} f = \int_R f \cdot \chi_{A \cup B}$$

$$= \int_R f (\chi_A + \chi_B) \quad (\text{since } A \cap B = \emptyset)$$

$$= \int_R f \chi_A + \int_R f \chi_B \quad (\text{by asmt})$$

$$= \int_A f + \int_B f. \quad \blacksquare$$

Module 11.2:

Fubini's Theorem

$$B \subseteq \mathbb{R}^2 \text{ JR} ; \int_B f(v) dv \equiv \iint_B f(x,y) dA ;$$

$$B \subseteq \mathbb{R}^3 \text{ JR} ; \int_B f(v) dv \equiv \iiint_B f(x,y,z) dV$$

\exists_1 let $B \subseteq \mathbb{R}^2$ be a JR, and let $f: B \rightarrow \mathbb{R}$ be integrable.

Then, we denote

$$\int_B f(v) dv \equiv \iint_B f(x,y) dA .$$

\exists_2 Similarly, if $B \subseteq \mathbb{R}^3$ is a JR & $f: B \rightarrow \mathbb{R}$ is integrable, then

$$\int_B f(v) dv \equiv \iiint_B f(x,y,z) dV .$$

$R = [a,b] \times [c,d] \subseteq \mathbb{R}^2$, $f: R \rightarrow \mathbb{R}$ BD, $f(x,\cdot): [c,d] \rightarrow \mathbb{R}$ IS INTEGRABLE $\forall x \in [a,b] \Rightarrow$

$$\iint_R f(x,y) dA \leq \overline{\int_a^b} \left(\int_c^d f(x,y) dy \right) dx \leq \overline{\int_a^b} \left(\int_c^d f(x,y) dy \right) dx \\ \leq \iint_R f(x,y) dA$$

\exists_1 let $R = [a,b] \times [c,d] \subseteq \mathbb{R}^2$, and let $f: R \rightarrow \mathbb{R}$ be bd.

let $f(x,\cdot): [c,d] \rightarrow \mathbb{R}$ by $f(x,\cdot)(y) = f(x,y)$ be integrable $\forall x \in [a,b]$.

Then necessarily

$$\begin{aligned} \iint_R f(x,y) dA &\leq \overline{\int_a^b} \left(\int_c^d f(x,y) dy \right) dx \\ &\leq \overline{\int_a^b} \left(\int_c^d f(x,y) dy \right) dx \\ &\leq \iint_R f(x,y) dA . \end{aligned}$$

Proof. Middle ineq is trivial.

We prove the last ineq, and leave the first as an exercise.

Let $\epsilon > 0$. Choose a partition P on R ?

$$U(f, P) - \epsilon \leq \iint_R f(x,y) dA ,$$

say

$$P = \{R_{ij} : 1 \leq i \leq k, 1 \leq j \leq l\} ,$$

$$\text{with } R_{ij} = [x_{i-1}, x_i] \times [y_{j-1}, y_j] ,$$

$$\text{where } x_0 = a, x_k = b, y_0 = c, y_l = d .$$

$$\text{Set } M_{ij} = \sup_{v \in R_{ij}} f(v) .$$

Then

$$\begin{aligned} \overline{\int_a^b} \left(\int_c^d f(x,y) dy \right) dx &= \sum_{i=1}^k \overline{\int_{x_{i-1}}^{x_i}} \left(\sum_{j=1}^l \int_{y_{j-1}}^{y_j} f(x,y) dy \right) dx \\ &\leq \sum_{i=1}^k \sum_{j=1}^l \overline{\int_{x_{i-1}}^{x_i}} \left(\int_{y_{j-1}}^{y_j} f(x,y) dy \right) dx \quad (\text{addition of supers}) \\ &\leq \sum_i \sum_{j=1}^l \overline{\int_{x_{i-1}}^{x_i}} \left(\int_{y_{j-1}}^{y_j} M_{ij} dy \right) dx \\ &= \sum_i \sum_{j=1}^l M_{ij} (x_i - x_{i-1})(y_j - y_{j-1}) \\ &= \sum_{ij} M_{ij} V(R_{ij}) \\ &= U(f, P) \\ &\leq \iint_R f(x,y) dA + \epsilon . \end{aligned}$$

$R = [a,b] \times [c,d] \subseteq \mathbb{R}^2$, $f: R \rightarrow \mathbb{R}$ INTEGRABLE, $f(x,\cdot), f(\cdot,y)$ INTEGRABLE $\Rightarrow \iint_R f(x,y) dA = \int_a^b \int_c^d f(x,y) dy dx = \int_c^d \int_a^b f(x,y) dx dy$ cc FUBINI'S THEOREM >>

\exists_1 Let $R = [a,b] \times [c,d] \subseteq \mathbb{R}^2$, and let $f: R \rightarrow \mathbb{R}$ be integrable.

Suppose $f(x,\cdot)$ and $f(\cdot,y)$ are integrable over $[c,d]$ & $[a,b]$, respectively, for all $x \in [a,b], y \in [c,d]$.

Then necessarily

$$\iint_R f(x,y) dA = \int_a^b \int_c^d f(x,y) dy dx = \int_c^d \int_a^b f(x,y) dx dy .$$

Proof. Since f is integrable,

$$\iint_R f(x,y) dA = \overline{\iint_R f(x,y) dA} .$$

By the prev lemma,

$$\overline{\int_a^b \int_c^d f(x,y) dy dx} = \overline{\int_a^b \int_c^d f(x,y) dy} dx .$$

$$\Rightarrow \iint_R f(x,y) dA = \int_a^b \int_c^d f(x,y) dy dx .$$

Reversing the roles of x & y proves the thm. \square

\exists_2 Note that this also applies when f is cts on R (because this satisfies the conditions needed.)

ITERATED INTEGRALS

\exists_1 An "iterated integral" is an integral of the form

$$\int_{a_n}^{b_n} \dots \int_{a_1}^{b_1} f(x_1, \dots, x_n) dx_1 \dots dx_n .$$

Ex: $R = [1,2] \times [0, \pi]: \iint_R y \sin(xy) dA$

Soln. Note that $f, f(x,\cdot), f(\cdot,y)$ are all cts on closed JR's \Rightarrow they are all integrable.

$$\begin{aligned} \iint_R y \sin(xy) dA &\stackrel{F}=\int_0^\pi \int_1^2 y \sin(xy) dx dy \\ &= \int_0^\pi \left[-\cos(xy) \right]_{x=1}^{x=2} dy \\ &= \int_0^\pi -\cos(2y) + \cos(y) dy \\ &= \left[-\frac{1}{2} \sin(2y) + \sin(y) \right]_0^\pi \\ &= (0 - 0) \\ &= 0 . \end{aligned}$$

Module 1.3-4: Iterated Integrals

$R = [a_1, b_1] \times \dots \times [a_n, b_n] \subseteq \mathbb{R}^n$, $f: R \rightarrow \mathbb{R}$ INTEGRABLE,
 $f(x, \cdot)$ INTEGRABLE $\forall x \in R_n \Rightarrow \int_{a_n}^{b_n} f(x, t) dt$ IS
 INTEGRABLE ON R_n & $\int_R f(x) = \int_{R_n} \int_{a_n}^{b_n} f(x, t) dt dx$

(let $R = [a_1, b_1] \times \dots \times [a_n, b_n] \subseteq \mathbb{R}^n$, and let $f: R \rightarrow \mathbb{R}$ be integrable.)

(let $R_n = [a_1, b_1] \times \dots \times [a_{n-1}, b_{n-1}]$.)

Then, if $f(x, \cdot)$ is integrable for each $x \in R_n$, then

① $\int_{a_n}^{b_n} f(x, t) dt$ is integrable; and

② $\int_R f(x) dv = \int_{R_n} \int_{a_n}^{b_n} f(x, t) dt dx$.

(Note once again that if f is cts, then

$$\int_R f(x) dv = \int_{a_1}^{b_1} \int_{a_2}^{b_2} \dots \int_{a_n}^{b_n} f(x_1, \dots, x_n) dx_1 \dots dx_n.$$

TYPE-1 & TYPE-2 [REGIONS IN \mathbb{R}^2]

(we say $A \subseteq \mathbb{R}^2$ is "type 1" if

$$A = \{(x, y) : x \in [a, b], \varphi(x) \leq y \leq \psi(x)\}$$

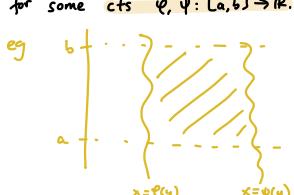
for some cts $\varphi, \psi: [a, b] \rightarrow \mathbb{R}$.



(similarly, we say $A \subseteq \mathbb{R}^2$ is "type 2" if

$$A = \{(x, y) : y \in [a, b], \varphi(y) \leq x \leq \psi(y)\}$$

for some cts $\varphi, \psi: [a, b] \rightarrow \mathbb{R}$.



TYPE 1, 2, 3 [REGIONS IN \mathbb{R}^3]

(let $A \subseteq \mathbb{R}^3$. Then

① A is "type 1" if it is of the form

$$A = \{(x, y, z) : (x, y) \in H, \varphi(x, y) \leq z \leq \psi(x, y)\};$$

② A is "type 2" if it is of the form

$$A = \{(x, y, z) : (x, z) \in H, \varphi(x, z) \leq y \leq \psi(x, z)\};$$

③ A is "type 3" if it is of the form

$$A = \{(x, y, z) : (y, z) \in H, \varphi(y, z) \leq x \leq \psi(y, z)\},$$

where $H \subseteq \mathbb{R}^2$ is a closed Jordan region &

$\varphi, \psi: H \rightarrow \mathbb{R}$ are cts.

TYPE 1, 2, 3 REGIONS ARE JORDAN REGIONS

Note that regions of type 1, 2 or 3 (in \mathbb{R}^2 or \mathbb{R}^3) are Jordan regions.

$A \subseteq \mathbb{R}^2$, $f: A \rightarrow \mathbb{R}$ cts: A IS TYPE-1 \Rightarrow

$$\int_A f(x) dv = \int_a^b \int_{\varphi(x)}^{\psi(x)} f(x, y) dy dx; \quad A \text{ IS TYPE-2 } \Rightarrow$$

$$\int_A f(x) dv = \int_a^b \int_{\varphi(y)}^{\psi(y)} f(x, y) dy dx$$

(let $A \subseteq \mathbb{R}^2$, and let $f: A \rightarrow \mathbb{R}$ be cts.)

Suppose A is type-1, so that

$$A = \{(x, y) : x \in [a, b], \varphi(x) \leq y \leq \psi(x)\}$$

for some cts $\varphi, \psi: [a, b] \rightarrow \mathbb{R}$.

Then

$$\int_A f(x) dv = \int_a^b \int_{\varphi(x)}^{\psi(x)} f(x, y) dy dx.$$

(similarly, suppose A is type-2, so that

$$A = \{(x, y) : y \in [a, b], \varphi(y) \leq x \leq \psi(y)\}$$

for some cts $\varphi, \psi: [a, b] \rightarrow \mathbb{R}$.

Then

$$\int_A f(x) dv = \int_a^b \int_{\varphi(y)}^{\psi(y)} f(x, y) dx dy.$$

Proof: We prove the first part; second part is similar.

(let $R = [a, b] \times [c, d]$ be a rect containing A .

Extend f to R by setting $f=0$ on $R \setminus A$.

By Fubini,

$$\int_A f(x) dv = \int_R f(x) dv = \int_a^b \int_c^d f(x, y) dy dx.$$

However, $f(x, y) = 0$ if it is not the case that

$$\varphi(x) \leq y \leq \psi(x).$$

$$\therefore \int_A f(x) dv = \int_a^b \int_{\varphi(x)}^{\psi(x)} f(x, y) dy dx. \quad \square$$

(The analogous theorem exists for \mathbb{R}^3 ; eg if $A \subseteq \mathbb{R}^3$ is type-1 and $f: A \rightarrow \mathbb{R}$ is cts, then

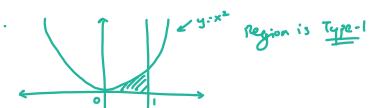
$$\int_A f(x) dv = \int_H \int_{\varphi(x,y)}^{\psi(x,y)} f(x, y, z) dz dy dx,$$

etc.

Ex: $D \subseteq \mathbb{R}^2 = \text{region BD BY } y=0, y=x^2, x=1$:

Calc $\iint_D x \cos(y) dA$.

Soln.

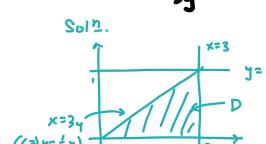


so by thm.

$$\begin{aligned} \iint_D x \cos(y) dA &= \int_0^1 \int_0^{x^2} x \cos(y) dy dx \\ &= \int_0^1 [x \sin(y)]_{y=0}^{y=x^2} dx \\ &= \int_0^1 x \sin(x^2) dx \\ &= [-\frac{1}{2} \cos(x^2)]_0^1 \\ &= \frac{1}{2} - \frac{1}{2} \cos(1). \quad * \end{aligned}$$

Ex: $\int_0^1 \int_{3y}^3 e^{x^2} dx dy$

Soln.

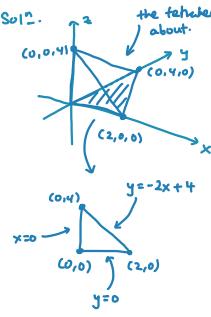


D is a region of type 1 & type 2.

$$\begin{aligned} \Rightarrow \int_0^1 \int_{3y}^3 e^{x^2} dx dy &= \iint_D e^{x^2} dA \\ &= \int_0^3 \int_0^{x/3} e^{x^2} dy dx \\ &= \int_0^3 \frac{1}{3} x e^{x^2} dx \\ &= [\frac{1}{6} e^{x^2}]_0^3 \\ &= \frac{1}{6} (e^9 - 1). \quad * \end{aligned}$$

EX: VOLUME OF TETRAHEDRON T ENCLOSED

BY $x=0, y=0, z=0, 2x+y+z=4$.



the tetrahedron we can see that

$$T = \{(x, y, z) : 0 \leq x \leq 2, 0 \leq y \leq -2x+4, 0 \leq z \leq 4-2x-y\}.$$

at

$$H = \{(x, y) : 0 \leq x \leq 2, 0 \leq y \leq -2x+4\}.$$

$\Rightarrow H$ is type I in \mathbb{R}^2 .

But also

$$T = \{(x, y, z) : (x, y) \in H, 0 \leq z \leq 4-2x-y\}.$$

$$\begin{aligned} \Rightarrow \iiint_T 1 \, dV &= \int_H \int_0^{4-2x-y} 1 \, dz \, dA \\ &= \int_0^2 \int_0^{-2x+4} \int_0^{4-2x-y} 1 \, dz \, dy \, dx \quad \text{ctg!} \\ &= \int_0^2 \int_0^{-2x+4} (4-2x-y) \, dy \, dx \\ &= \int_0^2 [(4-2x)y - \frac{1}{2}y^2]_{y=0}^{y=4-2x} \, dx \\ &= \int_0^2 \frac{1}{2}(4-2x)^2 \, dx \\ &= \dots \\ &= \frac{16}{3}. \quad \# \end{aligned}$$

Module 12.1:

Change of Variables

$U \in \mathbb{R}^n$ open, $A \subseteq U$ closed JR, $f: A \rightarrow \mathbb{R}$ CTS, $\varphi \in C^1(U, \mathbb{R}^n)$, $\exists B \subseteq A \Rightarrow \text{Vol}(B) = 0$, p is 1-1 on $A \setminus B$, $J\varphi(p) \neq 0 \forall p \in A \setminus B$, $f: \varphi(A) \rightarrow \mathbb{R}$ is CTS $\Rightarrow \varphi(A)$ is a JR, f is integrable on $\varphi(A)$, $\int_{\varphi(A)} f(x) dx = \int_A f(\varphi(x)) |J\varphi(x)| dx$

(let $U \in \mathbb{R}^n$ be open, and let $A \subseteq U$ be a closed Jordan region.

let $f: A \rightarrow \mathbb{R}$ be CTS, and let $\varphi \in C^1(U, \mathbb{R}^n)$.

Suppose there exists some $B \subseteq A$ with

- ① $\text{Vol}(B) = 0$;
- ② φ is injective on $A \setminus B$; and
- ③ $J\varphi(p) \neq 0 \forall p \in A \setminus B$.

Also suppose $f: \varphi(A) \rightarrow \mathbb{R}$ is continuous.

Then necessarily

- ① $\varphi(A)$ is a JR;
- ② f is integrable on $\varphi(A)$; and
- ③ $\int_{\varphi(A)} f(x) dx = \int_A f(\varphi(x)) |J\varphi(x)| dx$.

CARTESIAN \rightarrow POLAR COORDINATES

(Recall polar coordinates are coordinates of the form (r, θ) , where "x" = $r\cos\theta$ & "y" = $r\sin\theta$.

Consider $\varphi \in C^1(\mathbb{R}^2, \mathbb{R}^2)$ by $\varphi(r, \theta) = (r\cos\theta, r\sin\theta)$. Note φ is injective on $\mathbb{R}^2 \setminus \{(0, 0)\}: 0 \leq \theta < 2\pi\}$, and see that $\{(0, 0): 0 \leq \theta < 2\pi\}$ has volume zero.

Then,

$$|J\varphi(r, \theta)| = |\det \begin{pmatrix} \cos\theta & -r\sin\theta \\ \sin\theta & r\cos\theta \end{pmatrix}| = |r| = r \quad (\text{since } r > 0).$$

Therefore, given the right conditions,

$$\star \iint_{\varphi(D)} f(x, y) dA = \iint_D f(r\cos\theta, r\sin\theta) r dr d\theta.$$

Ex: $\iint_D \cos(x^2 + y^2) dA$. D is the region BD by $x^2 + y^2 = 9$ & above the x-axis

Soln. See that

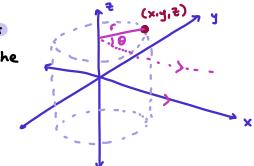
$$\begin{aligned} D &= \{(r, \theta): 0 \leq r \leq 3, 0 \leq \theta \leq \pi\} \\ \Rightarrow \iint_D \cos(x^2 + y^2) dA &= \iint_D \cos(r^2) \cdot r dr d\theta \\ &= \int_0^\pi \int_0^3 \cos(r^2) \cdot r dr d\theta \\ &= \int_0^\pi \left[\frac{1}{2} \sin(r^2) \right]_0^3 d\theta \\ &= \int_0^\pi \frac{1}{2} \sin(9) d\theta \\ &= \frac{\pi}{2} \sin(9). \end{aligned}$$

--

CYLINDRICAL COORDINATES

(let $(x, y, z) \in \mathbb{R}^3$)

Then, we call the point (r, θ, z) (as shown to the right) the "cylindrical coordinates" of (x, y, z) .



To convert, let

$$\varphi(r, \theta, z) = (r\cos\theta, r\sin\theta, z).$$

$$\text{Then } |\iota J\varphi(r, \theta, z)| = \left| \det \begin{pmatrix} \cos\theta & -r\sin\theta & 0 \\ \sin\theta & r\cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \right| = r,$$

so under the right conditions

$$\star \iiint_{\varphi(A)} f(x, y, z) dV = \iiint_A f(r\cos\theta, r\sin\theta, z) r dr d\theta dz.$$

Ex: $\iiint_A e^z dV$, A enclosed by 1) THE PARABOLOID $z = 1 + x^2 + y^2$, 2) $x^2 + y^2 = 5$,

3) THE XY-PLANE

$$\begin{aligned} \text{Let } \varphi(r, \theta, z) : 0 \leq r \leq \sqrt{5}, 0 \leq \theta \leq 2\pi, \\ 0 \leq z \leq 1 + x^2 + y^2 = 1 + r^2. \end{aligned}$$

$$\begin{aligned} \Rightarrow \iiint_A e^z dV &= \int_0^{\sqrt{5}} \int_0^{2\pi} \int_0^{1+r^2} e^z r dr d\theta dz \\ &= \int_0^{\sqrt{5}} \int_0^{2\pi} r e^{1+r^2} - r dr d\theta \\ &= 2\pi \int_0^{\sqrt{5}} r e^{1+r^2} - r dr \\ &= 2\pi \left[\frac{1}{2} e^{1+r^2} - \frac{1}{2} r^2 \right]_0^{\sqrt{5}} \\ &= 2\pi \left(\frac{1}{2} e^6 - \frac{5}{2} - \frac{1}{2} e \right) \\ &= \pi(e^6 - 5 - e). \end{aligned}$$

SPHERICAL COORDINATES

(let $(x, y, z) \in \mathbb{R}^3$)

Then, the "spherical coordinates" of (x, y, z) is equal to (ρ, θ, ϕ) , as shown in the right.

In particular,

- ① $x = \rho \sin\phi \cos\theta$;
- ② $y = \rho \sin\phi \sin\theta$;
- ③ $z = \rho \cos\phi$; and
- ④ $x^2 + y^2 + z^2 = \rho^2$.

To convert, consider

$$\varphi(\rho, \theta, \phi) = (\rho \sin\phi \cos\theta, \rho \sin\phi \sin\theta, \rho \cos\phi),$$

and

$$|J\varphi(\rho, \theta, \phi)| = \dots = \rho^2 \sin\phi.$$

Hence

$$\star \iiint_{\varphi(A)} f(x, y, z) dV = \iiint_A f(\rho \sin\phi \cos\theta, \rho \sin\phi \sin\theta, \rho \cos\phi) \cdot \rho^2 \sin\phi dV.$$

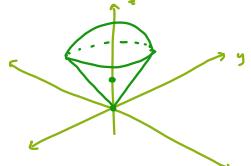
Ex: VOLUME OF $x^2 + y^2 + z^2 = a^2$

$$\begin{aligned} \text{Soln. let } S \text{ be the region (the sphere).} \\ \Rightarrow S &= \{\rho, \theta, \phi\}: 0 \leq \rho \leq a, 0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi \\ \text{& Vol}(S) &= \int_S 1 dV \\ &= \iiint_S 1 dx dy dz \\ &= \int_0^a \int_0^{2\pi} \int_0^\pi \rho^2 \sin\phi d\phi d\theta d\rho \\ &= \int_0^a \int_0^{2\pi} \left[-\rho^2 \cos\phi \right]_0^\pi d\theta d\rho \\ &= \int_0^a \int_0^{2\pi} 2\rho^2 d\theta d\rho \\ &= 2\pi \int_0^a 2\rho^2 d\rho \\ &= 2\pi \left[\frac{2}{3} \rho^3 \right]_0^a \\ &= \frac{4}{3} \pi a^3. \end{aligned}$$

EX: VOLUME OF SOLID WHICH 1) LIES ABOVE THE CONE $z = \sqrt{x^2 + y^2}$, & 2) BELOW THE SPHERE

$$x^2 + y^2 + z^2 = \frac{1}{4}$$

Soln. Note $x^2 + y^2 + z^2 = z \Leftrightarrow x^2 + y^2 + (z - \frac{1}{2})^2 = \frac{1}{4}$.



Cone:
 $\rho \cos \phi = \sqrt{\rho^2 \sin^2 \phi \cos^2 \theta + \rho^2 \sin^2 \phi \sin^2 \theta}$
 $= \rho \sin \phi \quad (\text{since } 0 \leq \phi \leq \pi)$

\Rightarrow the cone, $C = \{(r, \theta, \phi) : r = 0 \text{ or } \phi = \frac{\pi}{4}\}$

Sphere:
 $\rho^2 = \rho \cos \phi$
 \Rightarrow the sphere, $S = \{(r, \theta, \phi) : r = 0 \text{ or } r = \cos \phi\}$.

Letting $D = \text{above region}$,

$$\text{Volume of } D = \iiint_D 1 dV = \int_0^{2\pi} \int_0^{\frac{\pi}{4}} \int_0^{\cos \phi} \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta$$