

STAT 240

Personal Notes

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Chapter 1: What is Probability?

RANDOM EXPERIMENTS (1.1)

A "random experiment" is the process of obtaining a random observed result.

Random experiments can be split into two types:

① Controlled experiments; and

eg flipping a coin, rolling a die

② Observational studies.

eg # of students taking STAT 240 in F2021

FEATURES OF RANDOM EXPERIMENTS

Note that random experiments have the following common features:

- ① The outcomes/results cannot be predicted with certainty; and
- ② All the possible outcomes are known beforehand with certainty.

SAMPLE SPACE (1.2)

OUTCOME

An "outcome" is an observed result of interest from a random experiment.

eg the number rolled after rolling a die.

SAMPLE SPACE

The "sample space" of a random experiment is the set of all possible distinct outcomes of said experiment.

eg when rolling a 6-sided die:

$$S = \{1, 2, 3, 4, 5, 6\}$$

EVENTS

An "event" of a random experiment is a group or set of outcomes of said experiment; ie subsets of the sample space.

There are two types of events:

① Simple events - consist of one outcome

eg rolling a 1 on a 6-sided die:

$$S = \{1, \dots, 6\} \quad E = \{1\}$$

② Compound events - consist of multiple outcomes

eg rolling an odd number on a 6-sided die:

$$S = \{1, \dots, 6\} \quad E = \{1, 3, 5\}$$

Note that

① Two simple events will never occur simultaneously; eg can never roll a 1 & 3 at the same time with one die.

② A compound event occurs if and only if one of its simple events occurs; and

eg odd # rolled \Leftrightarrow 1 rolled or 3 rolled or 5 rolled (on a 6-sided die)

③ Two compound events can occur simultaneously.

eg 3 rolled \Rightarrow {odd number rolled ($E = \{1, 3, 5\}$) and multiple of 3 rolled ($E = \{3, 6\}$)}

DEFINITIONS OF PROBABILITY (1.3)

💡 "Probability" is a quantitative measure of how likely an event is to occur.

CLASSICAL DEFINITION

💡 The "classical definition" of probability states that each distinct outcome in the sample space is equally likely to occur.

💡 In this case, the probability of an event E is equal to

eg roll a 6-sided die once.

E = number is odd.

$$\Rightarrow E = \{1, 3, 5\}, \quad S = \{1, 2, 3, 4, 5, 6\}.$$

$$\text{So } P(E) = \frac{3}{6} = \frac{1}{2}.$$

RELATIVE FREQUENCY DEFINITION

💡 The "relative frequency" definition of probability states that the probability of an event occurring is the proportion it occurs in a very long series of repetitions of the experiment.

eg rolling a 6-sided die 300 times

\Rightarrow 3 shows up 49 of those 300 times

\Rightarrow so $P(\text{die}=3) \approx \frac{49}{300} \approx \frac{1}{6}$.

SUBJECTIVE PROBABILITY DEFINITION

💡 In the "subjective probability" definition of probability, the probability of an event is determined by an opinion (ie what a person thinks the probability is).

eg the probability of COVID-19 being eradicated by 2022.

💡 Note that this plays a role in fields like "Bayesian Statistics".

DISCRETE PROBABILITY MODELS (1.4)

💡 In discrete probability models:

- ① The sample space S satisfies $|S| \leq |\mathbb{N}|$; ie there are either a finite or countably infinite number of basic events; and
- ② Each probability p_i satisfies $0 \leq p_i \leq 1$; and
- ③ The probabilities of each basic event sum to 1; ie $\sum p_i = 1$.

CLASSIC DISCRETE MODELS (1.5)

💡 In classic discrete models:

- ① The sample space S satisfies $|S| < |\mathbb{N}|$ (ie it is finite); and
- ② All basic events are equally likely to occur;
ie $P(a_1) = \dots = P(a_{|S|}) = \frac{1}{|S|}$.

Chapter 2: Counting Techniques

FULL FACTORIAL: $n!$ (2.1)

The factorial of n , denoted as " $n!$ " and defined to be

$$n! = n(n-1) \dots 1$$

is the number of ways to put n distinguishable objects in a row.

COMBINATIONS: C_n^r OR ${}^n C_r$ (2.2)

" n choose r ", denoted as " C_n^r " or " ${}^n C_r$ ", defined to be

$$C_n^r = \frac{n!}{r!(n-r)!} = \frac{n(n-1) \dots (n-(r-1))}{r!}$$

is the number of ways to select r objects from n distinguishable objects.

PERMUTATIONS: P_n^r OR ${}^n P_r$ (2.3)

" P_n^r " or " ${}^n P_r$ ", defined to be

$$P_n^r = \frac{n!}{(n-r)!} = n(n-1) \dots (n-(r-1)) = C_r^n \cdot r!$$

is the number of ways to select r objects from n distinguishable objects and put them in a row.

GENERALIZATION OF COMBINATIONS (2.4)

We can show the number of ways to arrange n objects in a row, where n_1 objects are of type 1, n_2 objects are of type 2, ..., n_k objects are of type k , where $n_1 + n_2 + \dots + n_k = n$, is

$$\# \text{ of outcomes} = \frac{n!}{n_1! \dots n_k!} = C_n^{n_1} C_{n-n_1}^{n_2} C_{n-n_1-n_2}^{n_3} \dots C_{n_{k-1}+n_k}^{n_k} C_{n_k}^{n_k}$$

e.g. Roll a die 4 times. Find $P(\text{the sum}=10)$.

Soln. This is equivalent to distributing 10 balls into 4 sections, where each section has at least 1 ball.



9 different spaces for the "dividers", 4 "dividers"

$\Rightarrow C_9^4$ ways of "positioning" the dividers.

But, we exclude the option where one of the sections has 7 balls, i.e.

Hence $P(\text{event}) = \frac{C_9^4 - 4}{6^4}$, since there are 6^4 outcomes of rolling a 6 sided die twice. \blacksquare

STARS & BARS WITHOUT "EMPTY" SECTIONS

Given n stars, the # of ways to divide them up into k sections with $k-1$ rods without one of the sections containing zero elements is

$$\# = C_{k-1}^{n-1}$$

eg $n=5, k=4$

$$\begin{array}{|c|c|c|c|} \hline & \star & | & \star & | & \star & | & \star \\ \hline \end{array}$$

STARS & BARS WITH "EMPTY" SECTIONS

Given n stars, the # of ways to divide them up into k sections with $k-1$ rods with one (or more) sections containing zero elements is

$$\# = C_{k-1}^{n+k-1}$$

$$\begin{array}{|c|c|c|c|c|} \hline & \star & | & \star & | & \star & | & \star \\ \hline \end{array}$$

eg $n=5, k=4$

2nd section has no elements.

Chapter 3: Probability Rules

RELATIONS AMONGST EVENTS

(1.1)

EVERY EVENT $\subseteq S$ (THE "CERTAIN" EVENT)

Let A be an event.

Then necessarily

$A \subseteq S = \{\text{the event that always occurs}\}$.

\emptyset (THE "IMPOSSIBLE" EVENT)

We use " \emptyset " to denote the event that never occurs.

UNION OF EVENTS: $A \cup B$

Let A, B be events.

Then " $A \cup B$ " is the event that at least one of the two occurs.



INTERSECTION OF EVENTS: $A \cap B$

Let A, B be events.

Then, " $A \cap B$ " is the event that both A & B occur.



MUTUALLY EXCLUSIVE / DISJOINT

Let A, B be events.

Then, we say A & B are "mutually exclusive" (or "disjoint") if $A \cap B = \emptyset$.

INCLUSION: $A \subseteq B$

Let A, B be events.

Then, we say " $A \subseteq B$ " if B occurs whenever A occurs; ie

A occurs $\Rightarrow B$ occurs.

COMPLEMENT: $A^c = \overline{A}$

Let A be an event.

Then, \overline{A} is the event such that \overline{A} occurs $\Leftrightarrow A$ does not occur.

PARTITION OF S

Let B_1, \dots, B_n be events.

Then, we say B_1, \dots, B_n form a "partition" of S if

$$B_1 \cup \dots \cup B_n = S \quad \& \quad B_i \cap B_j = \emptyset \quad \forall i \neq j.$$

PROBABILITY RULES (1.2)

A probability function $P: P(S) \rightarrow [0, 1]$ is any function that satisfies the following for any $A, B \subseteq S$:

- ① $P(\emptyset) = 0$;
- ② $P(S) = 1$;
- ③ $P(A) \geq 0 \quad \forall A \subseteq S$; (non-negativity)
- ④ $A \subseteq B \Rightarrow P(A) \leq P(B)$;
- ⑤ $P(A \cup B) = P(A) + P(B) - P(A \cap B)$; & (addition law of probability)
- this generalizes to more variables as well.
- ⑥ $P(A^c) = 1 - P(A)$.

Chapter 4:

Conditional Probability and Event Independence

CONDITIONAL PROBABILITY (1.1)

Let A, B be events.
Then, the probability that A happens given B already happens, denoted as " $P(A|B)$ ", is equal to

$$P(A|B) = \frac{P(A \cap B)}{P(B)}.$$

* note $P(B) \neq 0$ necessarily.

INDEPENDENCE OF TWO EVENTS (1.2)

Let A, B be events.
Then, we say A & B are "independent" if and only if

$$P(A \cap B) = P(A)P(B).$$

Note that if $P(A), P(B) \neq 0$, then A & B cannot be mutually exclusive (ie $P(A \cap B) = 0$) if they are independent.

If A & B are independent, then
 ① A & B^c are independent;
 ② A^c & B are independent; and
 ③ A^c & B^c are independent.

Note that independence arises from independent random events.

INDEPENDENCE OF > 2 EVENTS (1.3)

Let A_1, \dots, A_n be n events.
Then, we say A_1, \dots, A_n are (mutually) independent if

$$P(A_{n_1} A_{n_2} \dots A_{n_k}) = P(A_{n_1}) \dots P(A_{n_k}) \quad \forall \{n_1, \dots, n_k\} \in \mathcal{P}(\{1, \dots, n\}).$$

For the $n=3$ case, A_1, A_2 & A_3 are independent if

- ① $P(A_1 A_2) = P(A_1)P(A_2);$
- ② $P(A_1 A_3) = P(A_1)P(A_3);$
- ③ $P(A_2 A_3) = P(A_2)P(A_3);$ and
- ④ $P(A_1 A_2 A_3) = P(A_1)P(A_2)P(A_3).$

THE MULTIPLICATION FORMULA (1.4.1)

Let A_1, \dots, A_n be independent events.

Then necessarily

$$P(A_1 \dots A_n) = P(A_1)P(A_2|A_1)P(A_3|A_1, A_2) \dots P(A_n|A_1 \dots A_{n-1}).$$

Proof. Note that for any $k=1, \dots, n$, we have

$$P(A_k | A_1 \dots A_{k-1}) = \frac{P(A_1 \dots A_{k-1}, A_k)}{P(A_1 \dots A_{k-1})} = P(A_k).$$

The proof follows trivially. \blacksquare

TOTAL PROBABILITY FORMULA (1.4.2)

Let A_1, A_2, \dots form a partition of S , ie we have that $A_i A_j = \emptyset \quad \forall i \neq j$ & $\bigcup_{i=1}^{\infty} A_i = S$.

Let B be an event. Then necessarily

$$P(B) = P(BS) = \sum_{i=1}^{\infty} P(A_i B) = \sum_{i=1}^{\infty} P(A_i)P(B|A_i).$$

* this also works for finite collections of events as well.

THE BAYES FORMULA (1.4.3)

Let A_1, A_2, \dots form a partition of S , and let B be such that $P(B) \neq 0$.

Then necessarily, for any $i \in \mathbb{N}$, we have that

$$P(A_i | B) = \frac{P(A_i B)}{P(B)} = \frac{P(A_i)P(B|A_i)}{P(B)} = \frac{P(A_i)P(B|A_i)}{\sum_{j=1}^{\infty} P(A_j)P(B|A_j)}.$$

* again, this also generalises to the finite case.

Chapter 5:

Discrete Random Variables and Probability Models

RANDOM VARIABLES (1.1)

RANDOM VARIABLE (RV) (1.1)

\exists_1 Let S be a sample space.
Then, a "random variable" is defined to be some $X: S \rightarrow \mathbb{R}$.

\exists_2 Note that we usually denote random variables by capital letters. (e.g. X, Y, Z , etc.)

DISCRETE [r.v.]

\exists_1 Let $X \in \mathbb{R}^d$ be a r.v.
Then, we say X is "discrete" if $|\text{range}(X)| \leq |\mathbb{N}|$.

PROBABILITY MASS FUNCTION (PMF)

\exists_1 Let $X \in \mathbb{R}^d$ be a r.v.
Then, the "probability mass function" (or pmf) of X is defined to be the function $f: \text{range}(X) \rightarrow [0, 1]$ by $f(x) = P[X=x] \quad \forall x \in \text{range}(X)$.

\exists_2 By construction of f , note that $\sum_{x \in \text{range}(X)} f(x) = 1$.

CUMULATIVE DISTRIBUTION FUNCTION (CDF)

\exists_1 Let $X \in \mathbb{R}^d$ be a r.v.
Then, the "cumulative distribution function" (or cdf) of X is defined to be the function $F: \mathbb{R} \rightarrow [0, 1]$ by $F(x) = P[X \leq x] \quad \forall x \in \mathbb{R}$.

\exists_2 Properties of cdf:
① $F(x_1) \leq F(x_2) \Leftrightarrow x_1 \leq x_2 \quad \forall x_1, x_2 \in \mathbb{R}$; and
② $\lim_{x \rightarrow -\infty} F(x) = 0$ & $\lim_{x \rightarrow \infty} F(x) = 1$.

PMF CAN BE OBTAINED BY CDF, AND VICE VERSA

\exists_1 Let $X \in \mathbb{R}^d$ be discrete.
Then, given the pmf f of X , we can obtain X 's cdf F , and vice versa.

Proof. Let $x \in \text{range}(X)$. See that $f(x) = P[X=x] = P[X \leq x] - P[X \leq x-\epsilon] = F(x) - F(x-\epsilon)$, where $\epsilon > 0$ is such that $\text{range}(X) \cap [x-\epsilon, x] = \{x\}$. (Since X is discrete, such an ϵ will exist.)

FINDING PMF (1)

\exists_1 Let X be the number of heads after flipping a fair coin n times.

Find the pmf of X .

Solⁿ. See that $\text{range}(X) = \{0, 1, \dots, n\}$.

Then

$$P[X=k] = C_n^k \left(\frac{1}{2}\right)^k \left(\frac{1}{2}\right)^{n-k} = C_n^k \left(\frac{1}{2}\right)^n$$

and so the pmf of X is $f: \{0, \dots, n\} \rightarrow [0, 1]$ given by

$$f(k) = P[X=k] = C_n^k \left(\frac{1}{2}\right)^n \quad \forall k=0, \dots, n.$$

BERNOULLI TRIALS & RELATED RV (1.2)

BERNOULLI TRIALS (1.2.1)

\exists_1 A "Bernoulli trial" focuses on a particular random experiment with only two possible outcomes: success or failure.

\exists_2 We call the random variables and the experiment obtained from Bernoulli trials as "Bernoulli random variables" and a "Bernoulli experiment" respectively.

BERNOULLI RV (1.2.2)

\exists_1 In particular, if B is a Bernoulli rv:

① then $P[B=\text{Success}]$, or $P(B)$, is equal to $P(B) = p$ (where p = probability of success); and

② $P[B=\text{Failure}]$, or $P(B^c)$, is equal to $P(B^c) = 1-p$.

\exists_2 Thus, the pmf of B is

$$f: \{0, 1\} \rightarrow [0, 1] \text{ by } f(0) = 1-p \text{ & } f(1) = p,$$

or equivalently by

$$f(x) = p^x (1-p)^{1-x} \quad \forall x \in \{0, 1\}.$$

BERNOULLI SEQUENCE (1.2.3)

\exists_1 A "Bernoulli sequence" occurs when

- ① we repeat a Bernoulli trial many times;
- ② the results are all independent; and
- ③ the success probability p stays the same.

BINOMIAL DISTRIBUTION: $X \sim \text{Binomial}(n, p) / X \sim \text{Bin}(n, p)$ (1.2.4)

\exists_1 Let X be the rv equal to the number of successes after repeating a Bernoulli trial n times independently, with probability of success p .

Then, we say X follows a binomial distribution, and write $X \sim \text{Binomial}(n, p)$.

\exists_2 In this case, the pmf of X is equal to

$$f: \{0, \dots, n\} \rightarrow [0, 1] \text{ by } f(k) = C_n^k p^k (1-p)^{n-k} \quad \forall k \in \mathbb{N}.$$

GEOMETRIC DISTRIBUTION: $X \sim \text{Geometric}(p) / X \sim \text{Geo}(p)$ (1.2.5)

\exists_1 Repeat independent Bernoulli trials, with success probability p , until a trial is successful.

Let the rv X be equal to the number of failures before the success was reached.

Then, we say X follows a geometric distribution, and write $X \sim \text{Geometric}(p)$.

\exists_2 In this case, the pmf of X is equal to

$$f: \mathbb{N} \rightarrow [0, 1] \text{ by } f(k) = (1-p)^k p \quad \forall k \in \mathbb{N}.$$

\exists_3 Note that

① $P(X \geq n) = (1-p)^n \quad \forall n \in \mathbb{N}$; and
Proof. $P(X \geq n) = \sum_{k=n}^{\infty} (1-p)^k p = (1-p)^n p \sum_{k=0}^{\infty} (1-p)^k = (1-p)^n p \left(\frac{1}{1-(1-p)}\right) = (1-p)^n$

② $P(X \geq m+n | X \geq n) = P(X \geq m) \quad \forall m, n \in \mathbb{N}$ (the memory-less property).

Proof. $P(X \geq m+n | X \geq n) = \frac{P(X \geq m+n \cap X \geq n)}{P(X \geq n)} = \frac{P(X \geq m+n)}{P(X \geq n)} = \frac{(1-p)^{m+n}}{(1-p)^n} = (1-p)^m = P(X \geq m)$.

NEGATIVE BINOMIAL DISTRIBUTION:

$X \sim \text{Negative Binomial}(k, p) / X \sim \text{NB}(k, p)$ (1.2.6)

\exists_1 : Repeat independent Bernoulli trials, with success probability p , until the k^{th} success is reached.

Let the rv X be the number of failures before the k^{th} success.

Then, we say X follows a negative binomial distribution, and write $X \sim \text{Negative Binomial}(k, p)$.

In this case, the pmf of X is equal to

$$f: N \rightarrow [0, 1] \text{ by } f(n) = C_{n+k-1}^n p^k (1-p)^n \quad \forall n \in N.$$

Proof. See that

$$\begin{aligned} P[X=n] &= P[\text{having } n \text{ failures before } k^{\text{th}} \text{ success}] \\ &= P[n \text{ failures \& } k-1 \text{ successes, followed by } k^{\text{th}} \text{ success}] \\ &= \frac{(n+k-1)!}{n!(k-1)!} (1-p)^n p^{k-1}. \\ \therefore P[X=n] &= C_{n+k-1}^n (1-p)^n p^k. \end{aligned}$$

HYPERGEOMETRIC DISTRIBUTION:

$X \sim \text{Hypergeometric}(N, M, n) / X \sim \text{Hyp}(N, M, n)$ (1.3)

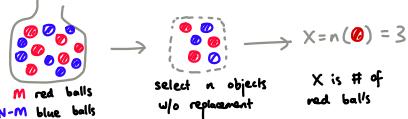
\exists_1 : Suppose we have a collection of N objects; M of one type, and $N-M$ of another (distinct) type.

Randomly select n objects without replacement, where $n \leq \min\{M, N-M\}$.

Let the rv X be the number of objects of the first type in these n objects.

Then, we say X follows a "hypergeometric distribution", and write

$$X \sim \text{Hypergeometric}(N, M, n).$$



\exists_2 : In this case, the pmf of X is equal to

$$f: \{0, \dots, n\} \rightarrow [0, 1] \text{ by } f(k) = \frac{\binom{M}{k} \binom{N-M}{n-k}}{\binom{N}{n}} \quad \forall k=0, \dots, n.$$

POISSON DISTRIBUTION:

$X \sim \text{Poisson}(\lambda) / X \sim \text{Poi}(\lambda)$ (1.4)

\exists_1 : In some observational studies, events happen over time or space.

We say such an event follows a Poisson process if the following conditions are satisfied:

- ① Events in non-overlapping time intervals are independent; $\left\{ \text{independence} \right\}$
- ② $P[\geq 2 \text{ events in } [t, t+\Delta t]] = o(\Delta t)$, where $\left\{ \text{individuality} \right\}$
- $\lim_{\Delta t \rightarrow 0} \frac{o(\Delta t)}{\Delta t} = 0$ and $\Delta t \ll t$; and
- ③ $P[\text{one event in } [t, t+\Delta t]] = \lambda \Delta t + o(\Delta t)$, $\lambda \in \mathbb{R}$. $\left\{ \text{homogeneity} \right\}$

Note that we call " λ " in ③ the "intensity parameter".

\exists_2 : Let the rv X be the number of events in $[0, t]$.

Then we say X follows a Poisson distribution, and write

$$X \sim \text{Poisson}(\lambda).$$

\exists_3 : In this case, the pmf of X is given by

$$f: N \rightarrow [0, 1] \text{ by } f(x) = \frac{e^{-\lambda t} (\lambda t)^x}{x!}.$$

Proof. First, divide $[0, t]$ into n small intervals:



Note that $\Delta t \rightarrow 0$ as $n \rightarrow \infty$.

Let the events

$$\begin{aligned} B_1^{(n,x)} &= \text{there are } x \text{ small intervals each with one event;} \\ B_2^{(n)} &= \geq 1 \text{ small interval exists with two or more events.} \end{aligned}$$

Then, see that

$$\begin{aligned} P(B_1^{(n,x)}) &= \binom{n}{x} (P[\text{one event in interval of length } \frac{\Delta t}{n} = \Delta t])^{x \Delta t} (1-p)^{n-x} \\ &\quad \text{(by binomial distn)} \\ &= \binom{n}{x} (\lambda \frac{\Delta t}{n} + o(\frac{\Delta t}{n}))^x (1 - \lambda \frac{\Delta t}{n} - o(\frac{\Delta t}{n}))^{n-x}. \quad \text{(by point ③ of defn)} \end{aligned}$$

Notice that since we want to consider infinitely small periods of time for our Poisson variable, we can deduce that

$$\begin{aligned} P(X=x) &= \lim_{n \rightarrow \infty} P(B_1^{(n,x)}) \\ &= \lim_{n \rightarrow \infty} \left[\binom{n}{x} \left(\lambda \frac{\Delta t}{n} + o(\frac{\Delta t}{n}) \right)^x \left(1 - \lambda \frac{\Delta t}{n} - o(\frac{\Delta t}{n}) \right)^{n-x} \right] \\ &= \lim_{n \rightarrow \infty} \left[\frac{n!}{x!(n-x)!} \left(\lambda \frac{\Delta t}{n} + o(\frac{\Delta t}{n}) \right)^x \left(1 - \lambda \frac{\Delta t}{n} - o(\frac{\Delta t}{n}) \right)^{n-x} \right] \\ &= \lim_{n \rightarrow \infty} \left[\frac{1}{x!} \frac{n(n-1)\dots(n-x+1)}{n^x} \left(\lambda t + no(\frac{\Delta t}{n}) \right)^x \left(1 - \lambda \frac{\Delta t}{n} - o(\frac{\Delta t}{n}) \right)^n \cdot \right. \\ &\quad \left. \left(1 - \lambda \frac{\Delta t}{n} - o(\frac{\Delta t}{n}) \right)^{-x} \right] \\ &= \frac{1}{x!} (1)(\lambda t)^x \lim_{n \rightarrow \infty} \left(1 - \frac{\lambda \Delta t}{n} \right)^n (1) \\ &= \frac{1}{x!} (\lambda t)^x e^{-\lambda t} \quad \text{(using the identity } e^x = \lim_{n \rightarrow \infty} (1 + \frac{x}{n})^n \text{)} \\ \therefore P(X=x) &= \frac{e^{-\lambda t} (\lambda t)^x}{x!}, \end{aligned}$$

as needed \blacksquare