

KEA128 Sub-Family Reference Manual

Supports: S9KEAZ64AMLK(R), S9KEAZ128AMLK(R),
S9KEAZ64AVLK(R), S9KEAZ128AVLK(R), S9KEAZ64ACLK(R),
S9KEAZ128ACLK(R), S9KEAZ64AMLH(R), S9KEAZ128AMLH(R),
S9KEAZ64AVLH(R), S9KEAZ128AVLH(R), S9KEAZ64ACLH(R) and
S9KEAZ128ACLH(R)

Document Number: S9KEA128Z80M48SF0RM

Rev 2, July 2014





Contents

| Section number | Title | Page |
|----------------|-------|------|
|----------------|-------|------|

Chapter 1 About This Document

| | | |
|-------|---------------------------|----|
| 1.1 | Overview..... | 37 |
| 1.1.1 | Purpose..... | 37 |
| 1.1.2 | Audience..... | 37 |
| 1.2 | Conventions..... | 37 |
| 1.2.1 | Numbering systems..... | 37 |
| 1.2.2 | Typographic notation..... | 38 |
| 1.2.3 | Special terms..... | 38 |

Chapter 2 Introduction

| | | |
|--------|-------------------------------------|----|
| 2.1 | Overview..... | 39 |
| 2.2 | Module functional categories..... | 39 |
| 2.2.1 | ARM Cortex-M0+ core modules..... | 40 |
| 2.2.2 | System modules..... | 41 |
| 2.2.3 | Memories and memory interfaces..... | 42 |
| 2.2.4 | Clocks..... | 42 |
| 2.2.5 | Security and integrity modules..... | 42 |
| 2.2.6 | Analog modules..... | 43 |
| 2.2.7 | Timer modules..... | 43 |
| 2.2.8 | Communication interfaces..... | 44 |
| 2.2.9 | Human-machine interfaces..... | 44 |
| 2.2.10 | Orderable part numbers..... | 45 |

Chapter 3 Chip Configuration

| | | |
|-------|-------------------------------------|----|
| 3.1 | Introduction..... | 47 |
| 3.2 | Module to Module Interconnects..... | 47 |
| 3.2.1 | Interconnection overview..... | 47 |

| Section number | Title | Page |
|----------------|--|------|
| 3.2.2 | Analog reference options..... | 51 |
| 3.2.3 | ACMP output capture..... | 51 |
| 3.2.4 | UART0_TX modulation..... | 52 |
| 3.2.5 | UART0/1/2_RX capture..... | 52 |
| 3.2.6 | UART0_RX filter..... | 53 |
| 3.2.7 | RTC capture..... | 54 |
| 3.2.8 | FTM2 software synchronization..... | 54 |
| 3.2.9 | ADC hardware trigger..... | 54 |
| 3.3 | Core Modules..... | 55 |
| 3.3.1 | ARM Cortex-M0+ core configuration..... | 55 |
| 3.3.1.1 | ARM Cortex M0+ core | 55 |
| 3.3.1.2 | Buses, interconnects, and interfaces..... | 56 |
| 3.3.1.3 | System Tick Timer..... | 56 |
| 3.3.1.4 | Core privilege levels..... | 57 |
| 3.3.1.5 | Caches..... | 57 |
| 3.3.2 | Nested Vectored Interrupt Controller (NVIC) configuration..... | 57 |
| 3.3.2.1 | Interrupt priority levels..... | 58 |
| 3.3.2.2 | Non-maskable interrupt..... | 58 |
| 3.3.2.3 | Interrupt channel assignments..... | 58 |
| 3.3.3 | Asynchronous wakeup interrupt controller (AWIC) configuration..... | 61 |
| 3.3.3.1 | Wakeup sources..... | 61 |
| 3.4 | System Modules..... | 62 |
| 3.4.1 | SIM configuration..... | 62 |
| 3.4.2 | PMC configuration..... | 63 |
| 3.4.3 | MCM configuration..... | 63 |
| 3.4.4 | Crossbar-light switch configuration..... | 64 |
| 3.4.4.1 | Crossbar-Light switch master assignments..... | 65 |
| 3.4.4.2 | Crossbar switch slave assignments..... | 65 |

| Section number | Title | Page |
|----------------|---|------|
| 3.4.5 | Peripheral bridge configuration..... | 65 |
| 3.4.5.1 | Number of peripheral bridges..... | 66 |
| 3.4.5.2 | Memory maps..... | 66 |
| 3.5 | System Security..... | 66 |
| 3.5.1 | CRC configuration..... | 66 |
| 3.5.2 | Watchdog configuration..... | 67 |
| 3.5.2.1 | WDOG clocks..... | 68 |
| 3.5.2.2 | WDOG operation..... | 68 |
| 3.6 | Clock Modules..... | 69 |
| 3.6.1 | ICS configuration..... | 69 |
| 3.6.1.1 | Clock gating..... | 69 |
| 3.6.2 | OSC configuration..... | 70 |
| 3.7 | Memories and Memory Interfaces..... | 70 |
| 3.7.1 | Flash memory configuration..... | 70 |
| 3.7.1.1 | Flash memory sizes..... | 71 |
| 3.7.1.2 | Flash memory map..... | 71 |
| 3.7.1.3 | Alternate Non-Volatile IRC User Trim Description..... | 72 |
| 3.7.1.4 | Flash security..... | 72 |
| 3.7.1.5 | Erase all flash contents..... | 72 |
| 3.7.2 | Flash memory controller configuration..... | 73 |
| 3.7.3 | SRAM configuration..... | 73 |
| 3.7.3.1 | SRAM sizes..... | 74 |
| 3.7.3.2 | SRAM ranges..... | 74 |
| 3.7.3.3 | SRAM bit operation..... | 76 |
| 3.8 | Analog..... | 76 |
| 3.8.1 | 12-bit analog-to-digital converter (ADC) configuration..... | 76 |
| 3.8.1.1 | ADC instantiation information..... | 77 |
| 3.8.1.2 | ADC0 connections/channel assignment..... | 77 |
| 3.8.1.3 | ADC analog supply and reference connections..... | 78 |

| Section number | Title | Page |
|----------------|-------------------------------------|------|
| 3.8.1.4 | Temperature sensor and bandgap..... | 78 |
| 3.8.1.5 | Alternate clock..... | 79 |
| 3.8.2 | ACMP configuration..... | 79 |
| 3.8.2.1 | ACMP overview..... | 80 |
| 3.8.2.2 | ACMP interconnections..... | 80 |
| 3.8.2.3 | ACMP in Stop mode..... | 81 |
| 3.9 | Timers..... | 82 |
| 3.9.1 | FlexTimer configuration..... | 82 |
| 3.9.1.1 | FTM overview..... | 82 |
| 3.9.1.2 | FTM clock options..... | 84 |
| 3.9.1.3 | FTM interconnections..... | 84 |
| 3.9.1.4 | FTM interrupts..... | 85 |
| 3.9.2 | PIT configuration..... | 85 |
| 3.9.2.1 | PIT overview..... | 85 |
| 3.9.2.2 | PIT interconnections..... | 85 |
| 3.9.3 | RTC configuration..... | 86 |
| 3.9.3.1 | RTC overview..... | 86 |
| 3.9.3.2 | RTC interconnections..... | 86 |
| 3.9.4 | PWT configuration..... | 87 |
| 3.9.4.1 | PWT overview..... | 87 |
| 3.9.4.2 | PWT interconnections..... | 88 |
| 3.10 | Communication interfaces..... | 88 |
| 3.10.1 | SPI configuration..... | 88 |
| 3.10.1.1 | SPI overview..... | 89 |
| 3.10.2 | I2C configuration..... | 89 |
| 3.10.2.1 | I2C overview..... | 90 |
| 3.10.2.2 | I2C0 4-wire interface feature..... | 90 |
| 3.10.3 | UART configuration..... | 91 |
| 3.10.3.1 | UART overview..... | 92 |

| Section number | Title | Page |
|----------------|--|------|
| 3.10.3.2 | UART interconnection..... | 92 |
| 3.10.4 | MSCAN configuration..... | 92 |
| 3.10.4.1 | MSCAN overview..... | 93 |
| 3.10.4.2 | MSCAN clock source..... | 93 |
| 3.10.4.3 | MSCAN wake-up interrupt and glitch filter..... | 93 |
| 3.11 | Human-machine interfaces (HMI)..... | 94 |
| 3.11.1 | GPIO configuration..... | 94 |
| 3.11.1.1 | GPIO overview..... | 94 |
| 3.11.2 | KBI configuration..... | 95 |
| 3.11.2.1 | KBI overview..... | 95 |
| 3.11.2.2 | KBI assignments..... | 95 |
| 3.11.3 | IRQ configuration..... | 96 |
| 3.11.3.1 | IRQ assignment..... | 96 |

Chapter 4 Memory Map

| | | |
|-------|--|-----|
| 4.1 | Introduction..... | 97 |
| 4.2 | System memory map..... | 97 |
| 4.3 | Aliased bit-band region..... | 98 |
| 4.4 | Bit Manipulation Engine..... | 99 |
| 4.5 | System ROM memory map..... | 99 |
| 4.5.1 | Entry (ROM_ENTRY _n)..... | 101 |
| 4.5.2 | End of Table Marker Register (ROM_TABLEMARK)..... | 102 |
| 4.5.3 | System Access Register (ROM_SYSACCESS)..... | 102 |
| 4.5.4 | Peripheral ID Register (ROM_PERIPHID _n)..... | 103 |
| 4.5.5 | Component ID Register (ROM_COMPID _n)..... | 103 |
| 4.6 | Peripheral bridge (AIPS-Lite) memory map..... | 104 |
| 4.6.1 | Read-after-write sequence and required serialization of memory operations..... | 104 |
| 4.6.2 | Peripheral Bridge (AIPS-Lite) Memory Map..... | 105 |
| 4.7 | Private Peripheral Bus (PPB) memory map..... | 108 |

| Section number | Title | Page |
|---------------------------|---|------|
| Chapter 5 | | |
| Clock Distribution | | |
| 5.1 | Introduction..... | 111 |
| 5.2 | Programming model..... | 111 |
| 5.3 | High-level device clocking diagram..... | 111 |
| 5.4 | Clock definitions..... | 113 |
| 5.4.1 | Device clock summary..... | 113 |
| 5.4.2 | Clock distribution..... | 114 |
| 5.5 | Internal clocking sources..... | 115 |
| 5.6 | External clock sources..... | 116 |
| 5.7 | Clock gating..... | 117 |
| 5.8 | Module clocks..... | 117 |
| 5.8.1 | FTM and PWT clocking..... | 119 |
| Chapter 6 | | |
| Reset and Boot | | |
| 6.1 | Introduction..... | 121 |
| 6.2 | Reset..... | 121 |
| 6.2.1 | Power-on reset (POR)..... | 121 |
| 6.2.2 | System reset sources..... | 122 |
| 6.2.2.1 | External pin reset (RESET)..... | 122 |
| 6.2.2.2 | Low-voltage detect (LVD)..... | 123 |
| 6.2.2.3 | Watchdog timer..... | 123 |
| 6.2.2.4 | ICS loss-of-clock (LOC)..... | 123 |
| 6.2.2.5 | Stop mode acknowledge error (SACKERR) | 124 |
| 6.2.2.6 | Software reset (SW)..... | 124 |
| 6.2.2.7 | Lockup reset (LOCKUP)..... | 124 |
| 6.2.2.8 | MDM-AP system reset request..... | 124 |
| 6.2.3 | MCU resets..... | 124 |
| 6.2.3.1 | POR Only | 124 |

| Section number | Title | Page |
|----------------|------------------------|------|
| 6.2.3.2 | Chip POR | 125 |
| 6.2.3.3 | Early Chip Reset | 125 |
| 6.2.3.4 | Chip Reset | 125 |
| 6.3 | Boot..... | 125 |
| 6.3.1 | Boot sources..... | 125 |
| 6.3.2 | Boot sequence..... | 126 |

Chapter 7 Power Management

| | | |
|-----|--|-----|
| 7.1 | Introduction..... | 127 |
| 7.2 | Power modes..... | 127 |
| 7.3 | Entering and exiting power modes..... | 128 |
| 7.4 | Module operation in low-power modes..... | 128 |

Chapter 8 Security

| | | |
|-------|---|-----|
| 8.1 | Introduction..... | 131 |
| 8.2 | Flash security..... | 131 |
| 8.3 | Security interactions with other modules..... | 132 |
| 8.3.1 | Security interactions with debug..... | 132 |

Chapter 9 Debug

| | | |
|-------|---------------------------------------|-----|
| 9.1 | Introduction..... | 133 |
| 9.2 | Debug port pin descriptions..... | 133 |
| 9.3 | SWD status and control registers..... | 134 |
| 9.3.1 | MDM-AP status register..... | 135 |
| 9.3.2 | MDM-AP Control register..... | 136 |
| 9.4 | Debug resets..... | 137 |
| 9.5 | Debug in low-power modes..... | 137 |
| 9.6 | Debug and security..... | 138 |

Chapter 10

Signal Multiplexing and Signal Descriptions

| | | |
|--------|--|-----|
| 10.1 | Introduction..... | 139 |
| 10.2 | Pinout..... | 139 |
| 10.2.1 | Signal multiplexing and pin assignments..... | 139 |
| 10.2.2 | Device pin assignment..... | 142 |
| 10.3 | Module signal description tables..... | 143 |
| 10.3.1 | Core modules..... | 143 |
| 10.3.2 | System modules..... | 144 |
| 10.3.3 | Clock modules..... | 144 |
| 10.3.4 | Analog..... | 144 |
| 10.3.5 | Timer modules..... | 145 |
| 10.3.6 | Communication Interfaces..... | 146 |
| 10.3.7 | Human-machine interfaces (HMI)..... | 147 |

Chapter 11

Port Control (PORT)

| | | |
|--------|---|-----|
| 11.1 | Introduction..... | 149 |
| 11.2 | Port data and data direction..... | 151 |
| 11.3 | Internal pullup enable..... | 152 |
| 11.4 | Input glitch filter setting..... | 152 |
| 11.5 | High current drive..... | 153 |
| 11.6 | Pin behavior in Stop mode..... | 153 |
| 11.7 | Port data registers..... | 154 |
| 11.7.1 | Port Filter Register 0 (PORT_IOFLT0)..... | 154 |
| 11.7.2 | Port Filter Register 1 (PORT_IOFLT1)..... | 157 |
| 11.7.3 | Port Pullup Enable Register 0 (PORT_PUE0)..... | 158 |
| 11.7.4 | Port Pullup Enable Register 1 (PORT_PUE1)..... | 163 |
| 11.7.5 | Port Pullup Enable Register 2 (PORT_PUE2)..... | 168 |
| 11.7.6 | Port High Drive Enable Register (PORT_HDRVE)..... | 170 |

Chapter 12

System Integration Module (SIM)

| | | |
|---------|--|-----|
| 12.1 | Introduction..... | 173 |
| 12.1.1 | Features..... | 173 |
| 12.2 | Memory map and register definition..... | 173 |
| 12.2.1 | System Reset Status and ID Register (SIM_SRSID)..... | 174 |
| 12.2.2 | System Options Register 0 (SIM_SOPT0)..... | 177 |
| 12.2.3 | System Options Register (SIM_SOPT1)..... | 180 |
| 12.2.4 | Pin Selection Register 0 (SIM_PINSEL0)..... | 182 |
| 12.2.5 | Pin Selection Register 1 (SIM_PINSEL1)..... | 184 |
| 12.2.6 | System Clock Gating Control Register (SIM_SCGC)..... | 186 |
| 12.2.7 | Universally Unique Identifier Low Register (SIM_UUIDL)..... | 190 |
| 12.2.8 | Universally Unique Identifier Middle Low Register (SIM_UUIDML)..... | 190 |
| 12.2.9 | Universally Unique Identifier Middle High Register (SIM_UUIDMH)..... | 191 |
| 12.2.10 | Clock Divider Register (SIM_CLKDIV)..... | 191 |
| 12.3 | Functional description..... | 192 |

Chapter 13

Power Management Controller (PMC)

| | | |
|--------|---|-----|
| 13.1 | Introduction..... | 193 |
| 13.2 | Low voltage detect (LVD) system..... | 193 |
| 13.2.1 | Power-on reset (POR) operation..... | 194 |
| 13.2.2 | LVD reset operation..... | 194 |
| 13.2.3 | LVD enabled in Stop mode..... | 194 |
| 13.2.4 | Low-voltage warning (LVW)..... | 195 |
| 13.3 | Bandgap reference..... | 195 |
| 13.4 | Memory map and register descriptions..... | 195 |
| 13.4.1 | System Power Management Status and Control 1 Register (PMC_SPMSC1)..... | 196 |
| 13.4.2 | System Power Management Status and Control 2 Register (PMC_SPMSC2)..... | 197 |

Chapter 14 Miscellaneous Control Module (MCM)

| | | |
|--------|--|-----|
| 14.1 | Introduction..... | 199 |
| 14.1.1 | Features..... | 199 |
| 14.2 | Memory map/register descriptions..... | 199 |
| 14.2.1 | Crossbar Switch (AXBS) Slave Configuration (MCM_PLASC)..... | 200 |
| 14.2.2 | Crossbar Switch (AXBS) Master Configuration (MCM_PLAMC)..... | 200 |
| 14.2.3 | Platform Control Register (MCM_PLACR)..... | 201 |

Chapter 15 Peripheral Bridge (AIPS-Lite)

| | | |
|--------|-----------------------------|-----|
| 15.1 | Introduction..... | 205 |
| 15.1.1 | Features..... | 205 |
| 15.1.2 | General operation..... | 205 |
| 15.2 | Functional description..... | 206 |
| 15.2.1 | Access support..... | 206 |

Chapter 16 Watchdog Timer (WDOG)

| | | |
|--------|--|-----|
| 16.1 | Introduction..... | 207 |
| 16.1.1 | Features..... | 207 |
| 16.1.2 | Block diagram..... | 208 |
| 16.2 | Memory map and register definition..... | 209 |
| 16.2.1 | Watchdog Control and Status Register 1 (WDOG_CS1)..... | 209 |
| 16.2.2 | Watchdog Control and Status Register 2 (WDOG_CS2)..... | 211 |
| 16.2.3 | Watchdog Counter Register: High (WDOG_CNTH)..... | 212 |
| 16.2.4 | Watchdog Counter Register: Low (WDOG_CNTL)..... | 212 |
| 16.2.5 | Watchdog Timeout Value Register: High (WDOG_TOVALH)..... | 213 |
| 16.2.6 | Watchdog Timeout Value Register: Low (WDOG_TOVALL)..... | 213 |
| 16.2.7 | Watchdog Window Register: High (WDOG_WINH)..... | 214 |
| 16.2.8 | Watchdog Window Register: Low (WDOG_WINL)..... | 214 |

| Section number | Title | Page |
|----------------|---|------|
| 16.3 | Functional description..... | 215 |
| 16.3.1 | Watchdog refresh mechanism..... | 215 |
| 16.3.1.1 | Window mode..... | 216 |
| 16.3.1.2 | Refreshing the Watchdog..... | 216 |
| 16.3.1.3 | Example code: Refreshing the Watchdog..... | 217 |
| 16.3.2 | Configuring the Watchdog..... | 217 |
| 16.3.2.1 | Reconfiguring the Watchdog..... | 218 |
| 16.3.2.2 | Unlocking the Watchdog..... | 218 |
| 16.3.2.3 | Example code: Reconfiguring the Watchdog..... | 218 |
| 16.3.3 | Clock source..... | 219 |
| 16.3.4 | Using interrupts to delay resets..... | 220 |
| 16.3.5 | Backup reset..... | 220 |
| 16.3.6 | Functionality in debug and low-power modes..... | 220 |
| 16.3.7 | Fast testing of the watchdog..... | 221 |
| 16.3.7.1 | Testing each byte of the counter..... | 221 |
| 16.3.7.2 | Entering user mode..... | 222 |

Chapter 17

Bit Manipulation Engine (BME)

| | | |
|----------|---|-----|
| 17.1 | Introduction..... | 223 |
| 17.1.1 | Overview..... | 224 |
| 17.1.2 | Features..... | 225 |
| 17.1.3 | Modes of operation..... | 225 |
| 17.2 | Memory map and register definition..... | 225 |
| 17.3 | Functional description..... | 226 |
| 17.3.1 | BME decorated stores..... | 226 |
| 17.3.1.1 | Decorated store logical AND (AND)..... | 228 |
| 17.3.1.2 | Decorated store logical OR (OR)..... | 229 |
| 17.3.1.3 | Decorated store logical XOR (XOR)..... | 230 |
| 17.3.1.4 | Decorated store bit field insert (BFI)..... | 231 |

| Section number | Title | Page |
|----------------|--|------|
| 17.3.2 | BME decorated loads..... | 233 |
| 17.3.2.1 | Decorated load: load-and-clear 1 bit (LAC1)..... | 236 |
| 17.3.2.2 | Decorated Load: Load-and-Set 1 Bit (LAS1)..... | 237 |
| 17.3.2.3 | Decorated load unsigned bit field extract (UBFX)..... | 238 |
| 17.3.3 | Additional details on decorated addresses and GPIO accesses..... | 239 |
| 17.4 | Application information..... | 240 |

Chapter 18

Flash Memory Module (FTMRE)

| | | |
|----------|--|-----|
| 18.1 | Introduction..... | 243 |
| 18.2 | Feature..... | 243 |
| 18.2.1 | Flash memory features..... | 243 |
| 18.2.2 | Other flash module features..... | 244 |
| 18.3 | Functional description..... | 244 |
| 18.3.1 | Modes of operation..... | 244 |
| 18.3.1.1 | Wait mode..... | 244 |
| 18.3.1.2 | Stop mode..... | 244 |
| 18.3.2 | Flash memory map..... | 244 |
| 18.3.3 | Flash initialization after system reset..... | 245 |
| 18.3.4 | Flash command operations..... | 245 |
| 18.3.4.1 | Writing the FCLKDIV register..... | 246 |
| 18.3.4.2 | Command write sequence..... | 248 |
| 18.3.5 | Flash interrupts..... | 250 |
| 18.3.5.1 | Description of flash interrupt operation..... | 250 |
| 18.3.6 | Protection..... | 250 |
| 18.3.7 | Security..... | 255 |
| 18.3.7.1 | Unsecuring the MCU using backdoor key access..... | 255 |
| 18.3.7.2 | Unsecuring the MCU using SWD..... | 256 |
| 18.3.7.3 | Mode and security effects on flash command availability..... | 256 |

| Section number | Title | Page |
|----------------|--|------|
| 18.3.8 | Flash commands..... | 256 |
| 18.3.8.1 | Flash commands..... | 257 |
| 18.3.9 | Flash command summary..... | 257 |
| 18.3.9.1 | Erase Verify All Blocks command..... | 258 |
| 18.3.9.2 | Erase Verify Block command..... | 259 |
| 18.3.9.3 | Erase Verify Flash Section command..... | 259 |
| 18.3.9.4 | Read once command..... | 260 |
| 18.3.9.5 | Program Flash command..... | 261 |
| 18.3.9.6 | Program Once command..... | 262 |
| 18.3.9.7 | Erase All Blocks command..... | 263 |
| 18.3.9.8 | Debugger mass erase request..... | 264 |
| 18.3.9.9 | Erase flash block command..... | 265 |
| 18.3.9.10 | Erase flash sector command..... | 265 |
| 18.3.9.11 | Unsecure flash command..... | 266 |
| 18.3.9.12 | Verify backdoor access key command..... | 267 |
| 18.3.9.13 | Set user margin level command..... | 268 |
| 18.3.9.14 | Set factory margin level command..... | 269 |
| 18.3.9.15 | Configure NVM command..... | 270 |
| 18.4 | Memory map and register definition..... | 273 |
| 18.4.1 | Flash CCOB Index Register (FTMRE_FCCOBIX)..... | 273 |
| 18.4.2 | Flash Security Register (FTMRE_FSEC)..... | 274 |
| 18.4.3 | Flash Clock Divider Register (FTMRE_FCLKDIV)..... | 275 |
| 18.4.4 | Flash Status Register (FTMRE_FSTAT)..... | 276 |
| 18.4.5 | Flash Configuration Register (FTMRE_FCNFG)..... | 277 |
| 18.4.6 | Flash Common Command Object Register: Low (FTMRE_FCCOBLO)..... | 278 |
| 18.4.7 | Flash Common Command Object Register:High (FTMRE_FCCOBHI)..... | 278 |
| 18.4.8 | Flash Protection Register (FTMRE_FPROT)..... | 278 |
| 18.4.9 | Flash Option Register (FTMRE_FOPT)..... | 280 |

| Section number | Title | Page |
|--------------------------------------|---|------|
| Chapter 19 | | |
| Flash Memory Controller (FMC) | | |
| 19.1 | Introduction..... | 281 |
| 19.1.1 | Overview..... | 281 |
| 19.1.2 | Features..... | 281 |
| 19.2 | Modes of operation..... | 282 |
| 19.3 | External signal description..... | 282 |
| 19.4 | Memory map and register descriptions..... | 282 |
| 19.5 | Functional description..... | 282 |

| | | |
|------------------------------------|--|-----|
| Chapter 20 | | |
| Internal Clock Source (ICS) | | |
| 20.1 | Introduction..... | 285 |
| 20.1.1 | Features..... | 285 |
| 20.1.2 | Block diagram..... | 286 |
| 20.1.3 | Modes of operation..... | 286 |
| 20.1.3.1 | FLL engaged internal (FEI)..... | 286 |
| 20.1.3.2 | FLL engaged external (FEE)..... | 286 |
| 20.1.3.3 | FLL bypassed internal (FBI)..... | 287 |
| 20.1.3.4 | FLL bypassed internal low power (FBILP)..... | 287 |
| 20.1.3.5 | FLL bypassed external (FBE)..... | 287 |
| 20.1.3.6 | FLL bypassed external low power (FBELP)..... | 287 |
| 20.1.3.7 | Stop (STOP)..... | 287 |
| 20.2 | External signal description..... | 288 |
| 20.3 | Register definition..... | 288 |
| 20.3.1 | ICS Control Register 1 (ICS_C1)..... | 288 |
| 20.3.2 | ICS Control Register 2 (ICS_C2)..... | 289 |
| 20.3.3 | ICS Control Register 3 (ICS_C3)..... | 290 |
| 20.3.4 | ICS Control Register 4 (ICS_C4)..... | 291 |
| 20.3.5 | ICS Status Register (ICS_S)..... | 292 |

| Section number | Title | Page |
|----------------|--|------|
| 20.4 | Functional description..... | 293 |
| 20.4.1 | Operational modes..... | 293 |
| 20.4.1.1 | FLL engaged internal (FEI)..... | 293 |
| 20.4.1.2 | FLL engaged external (FEE)..... | 294 |
| 20.4.1.3 | FLL bypassed internal (FBI)..... | 294 |
| 20.4.1.4 | FLL bypassed internal low power (FBILP)..... | 294 |
| 20.4.1.5 | FLL bypassed external (FBE)..... | 294 |
| 20.4.1.6 | FLL bypassed external low power (FBELP)..... | 295 |
| 20.4.1.7 | Stop..... | 295 |
| 20.4.2 | Mode switching..... | 295 |
| 20.4.3 | Bus frequency divider..... | 296 |
| 20.4.4 | Low-power field usage..... | 296 |
| 20.4.5 | Internal reference clock..... | 296 |
| 20.4.6 | Fixed frequency clock..... | 297 |
| 20.4.7 | FLL lock and clock monitor..... | 297 |
| 20.4.7.1 | FLL clock lock..... | 297 |
| 20.4.7.2 | External reference clock monitor..... | 298 |
| 20.5 | Initialization/application information..... | 298 |
| 20.5.1 | Initializing FEI mode..... | 298 |
| 20.5.2 | Initializing FBI mode..... | 299 |
| 20.5.3 | Initializing FEE mode..... | 299 |
| 20.5.4 | Initializing FBE mode..... | 299 |

Chapter 21 Oscillator (OSC)

| | | |
|--------|-------------------------|-----|
| 21.1 | Introduction..... | 301 |
| 21.1.1 | Overview..... | 301 |
| 21.1.2 | Features and modes..... | 301 |
| 21.1.3 | Block diagram..... | 301 |
| 21.2 | Signal description..... | 302 |

| Section number | Title | Page |
|----------------|---|------|
| 21.3 | External crystal / resonator connections..... | 303 |
| 21.4 | External clock connections..... | 304 |
| 21.5 | Memory map and register descriptions..... | 305 |
| 21.5.1 | OSC Control Register (OSC_CR)..... | 305 |
| 21.6 | Functional description..... | 306 |
| 21.6.1 | OSC module states..... | 306 |
| 21.6.1.1 | Off..... | 307 |
| 21.6.1.2 | Oscillator startup..... | 308 |
| 21.6.1.3 | Oscillator stable..... | 308 |
| 21.6.1.4 | External clock mode..... | 308 |
| 21.6.2 | OSC module modes..... | 308 |
| 21.6.2.1 | Low-frequency, high-gain mode..... | 309 |
| 21.6.2.2 | Low-frequency, low-power mode..... | 309 |
| 21.6.2.3 | High-frequency, high-gain mode..... | 309 |
| 21.6.2.4 | High-frequency, low-power mode..... | 310 |
| 21.6.3 | Counter..... | 310 |
| 21.6.4 | Reference clock pin requirements..... | 310 |

Chapter 22

Cyclic Redundancy Check (CRC)

| | | |
|----------|---|-----|
| 22.1 | Introduction..... | 311 |
| 22.1.1 | Features..... | 311 |
| 22.1.2 | Block diagram..... | 311 |
| 22.1.3 | Modes of operation..... | 312 |
| 22.1.3.1 | Run mode..... | 312 |
| 22.1.3.2 | Low-power modes (Wait or Stop)..... | 312 |
| 22.2 | Memory map and register descriptions..... | 312 |
| 22.2.1 | CRC Data register (CRC_DATA)..... | 313 |
| 22.2.2 | CRC Polynomial register (CRC_GPOLY)..... | 314 |
| 22.2.3 | CRC Control register (CRC_CTRL)..... | 314 |

| Section number | Title | Page |
|----------------|--|------|
| 22.3 | Functional description..... | 315 |
| 22.3.1 | CRC initialization/reinitialization..... | 315 |
| 22.3.2 | CRC calculations..... | 316 |
| 22.3.2.1 | 16-bit CRC..... | 316 |
| 22.3.2.2 | 32-bit CRC..... | 316 |
| 22.3.3 | Transpose feature..... | 317 |
| 22.3.3.1 | Types of transpose..... | 317 |
| 22.3.4 | CRC result complement..... | 319 |

Chapter 23 Interrupt (IRQ)

| | | |
|--------|---|-----|
| 23.1 | Introduction..... | 321 |
| 23.2 | Features..... | 321 |
| 23.2.1 | Pin configuration options..... | 322 |
| 23.2.2 | Edge and level sensitivity..... | 323 |
| 23.3 | Interrupt pin request register..... | 323 |
| 23.3.1 | Interrupt Pin Request Status and Control Register (IRQ_SC)..... | 323 |

Chapter 24 Analog-to-digital converter (ADC)

| | | |
|--------|--|-----|
| 24.1 | Introduction..... | 325 |
| 24.1.1 | Features..... | 325 |
| 24.1.2 | Block Diagram..... | 326 |
| 24.2 | External Signal Description..... | 326 |
| 24.2.1 | Analog Power (VDDA)..... | 327 |
| 24.2.2 | Analog Ground (VSSA)..... | 327 |
| 24.2.3 | Voltage Reference High (VREFH)..... | 327 |
| 24.2.4 | Voltage Reference Low (VREFL)..... | 327 |
| 24.2.5 | Analog Channel Inputs (ADx)..... | 327 |
| 24.3 | ADC Control Registers..... | 328 |
| 24.3.1 | Status and Control Register 1 (ADC_SC1)..... | 328 |

| Section number | Title | Page |
|----------------|--|------|
| 24.3.2 | Status and Control Register 2 (ADC_SC2)..... | 331 |
| 24.3.3 | Status and Control Register 3 (ADC_SC3)..... | 333 |
| 24.3.4 | Status and Control Register 4 (ADC_SC4)..... | 334 |
| 24.3.5 | Conversion Result Register (ADC_R)..... | 335 |
| 24.3.6 | Compare Value Register (ADC_CV)..... | 336 |
| 24.3.7 | Pin Control 1 Register (ADC_APCTL1)..... | 337 |
| 24.3.8 | Status and Control Register 5 (ADC_SC5)..... | 337 |
| 24.4 | Functional description..... | 338 |
| 24.4.1 | Clock select and divide control..... | 338 |
| 24.4.2 | Input select and pin control..... | 339 |
| 24.4.3 | Hardware trigger..... | 339 |
| 24.4.4 | Conversion control..... | 340 |
| 24.4.4.1 | Initiating conversions..... | 340 |
| 24.4.4.2 | Completing conversions..... | 340 |
| 24.4.4.3 | Aborting conversions..... | 341 |
| 24.4.4.4 | Power control..... | 341 |
| 24.4.4.5 | Sample time and total conversion time..... | 341 |
| 24.4.5 | Automatic compare function..... | 343 |
| 24.4.6 | FIFO operation..... | 344 |
| 24.4.7 | MCU wait mode operation..... | 348 |
| 24.4.8 | MCU Stop mode operation..... | 348 |
| 24.4.8.1 | Stop mode with ADACK disabled..... | 348 |
| 24.4.8.2 | Stop mode with ADACK enabled..... | 348 |
| 24.5 | Initialization information..... | 349 |
| 24.5.1 | ADC module initialization example..... | 349 |
| 24.5.1.1 | Initialization sequence..... | 349 |

| Section number | Title | Page |
|----------------|---|------|
| 24.5.1.2 | Pseudo-code example..... | 350 |
| 24.5.2 | ADC FIFO module initialization example..... | 350 |
| 24.5.2.1 | Pseudo-code example..... | 351 |
| 24.6 | Application information..... | 352 |
| 24.6.1 | External pins and routing..... | 352 |
| 24.6.1.1 | Analog supply pins..... | 352 |
| 24.6.1.2 | Analog reference pins..... | 352 |
| 24.6.1.3 | Analog input pins..... | 353 |
| 24.6.2 | Sources of error..... | 354 |
| 24.6.2.1 | Sampling error..... | 354 |
| 24.6.2.2 | Pin leakage error..... | 354 |
| 24.6.2.3 | Noise-induced errors..... | 354 |
| 24.6.2.4 | Code width and quantization error..... | 355 |
| 24.6.2.5 | Linearity errors..... | 356 |
| 24.6.2.6 | Code jitter, non-monotonicity, and missing codes..... | 356 |

Chapter 25

Analog comparator (ACMP)

| | | |
|----------|---|-----|
| 25.1 | Introduction..... | 359 |
| 25.1.1 | Features..... | 359 |
| 25.1.2 | Modes of operation..... | 359 |
| 25.1.2.1 | Operation in Wait mode..... | 360 |
| 25.1.2.2 | Operation in Stop mode..... | 360 |
| 25.1.2.3 | Operation in Debug mode..... | 360 |
| 25.1.3 | Block diagram..... | 360 |
| 25.2 | External signal description..... | 361 |
| 25.3 | Memory map and register definition..... | 361 |
| 25.3.1 | ACMP Control and Status Register (ACMP _x _CS)..... | 362 |
| 25.3.2 | ACMP Control Register 0 (ACMP _x _C0)..... | 363 |
| 25.3.3 | ACMP Control Register 1 (ACMP _x _C1)..... | 363 |

| Section number | Title | Page |
|----------------|--|------|
| 25.3.4 | ACMP Control Register 2 (ACMP _x _C2)..... | 364 |
| 25.4 | Functional description..... | 364 |
| 25.5 | Setup and operation of ACMP..... | 365 |
| 25.6 | Resets..... | 366 |
| 25.7 | Interrupts..... | 366 |

Chapter 26 FlexTimer Module (FTM)

| | | |
|---------|--|-----|
| 26.1 | Introduction..... | 367 |
| 26.1.1 | FlexTimer philosophy..... | 367 |
| 26.1.2 | Features..... | 368 |
| 26.1.3 | Modes of operation..... | 369 |
| 26.1.4 | Block diagram..... | 370 |
| 26.2 | FTM signal descriptions..... | 372 |
| 26.3 | Memory map and register definition..... | 372 |
| 26.3.1 | Memory map..... | 372 |
| 26.3.2 | Register descriptions..... | 372 |
| 26.3.3 | Status And Control (FTM _x _SC)..... | 376 |
| 26.3.4 | Counter (FTM _x _CNT)..... | 378 |
| 26.3.5 | Modulo (FTM _x _MOD)..... | 378 |
| 26.3.6 | Channel (n) Status And Control (FTM _x _CnSC)..... | 379 |
| 26.3.7 | Channel (n) Value (FTM _x _CnV)..... | 381 |
| 26.3.8 | Counter Initial Value (FTM _x _CNTIN)..... | 382 |
| 26.3.9 | Capture And Compare Status (FTM _x _STATUS)..... | 383 |
| 26.3.10 | Features Mode Selection (FTM _x _MODE)..... | 385 |
| 26.3.11 | Synchronization (FTM _x _SYNC)..... | 386 |
| 26.3.12 | Initial State For Channels Output (FTM _x _OUTINIT)..... | 389 |
| 26.3.13 | Output Mask (FTM _x _OUTMASK)..... | 390 |
| 26.3.14 | Function For Linked Channels (FTM _x _COMBINE)..... | 392 |
| 26.3.15 | Deadtime Insertion Control (FTM _x _DEADTIME)..... | 397 |

| Section number | Title | Page |
|----------------|---|------|
| 26.3.16 | FTM External Trigger (FTMx_EXTTRIG)..... | 398 |
| 26.3.17 | Channels Polarity (FTMx_POL)..... | 400 |
| 26.3.18 | Fault Mode Status (FTMx_FMS)..... | 402 |
| 26.3.19 | Input Capture Filter Control (FTMx_FILTER)..... | 404 |
| 26.3.20 | Fault Control (FTMx_FLTCTRL)..... | 405 |
| 26.3.21 | Configuration (FTMx_CONF)..... | 407 |
| 26.3.22 | FTM Fault Input Polarity (FTMx_FLTPOL)..... | 408 |
| 26.3.23 | Synchronization Configuration (FTMx_SYNCONF)..... | 410 |
| 26.3.24 | FTM Inverting Control (FTMx_INVCTRL)..... | 412 |
| 26.3.25 | FTM Software Output Control (FTMx_SWOCTRL)..... | 413 |
| 26.3.26 | FTM PWM Load (FTMx_PWMLOAD)..... | 415 |
| 26.4 | Functional description..... | 416 |
| 26.4.1 | Clock source..... | 417 |
| 26.4.1.1 | Counter clock source..... | 417 |
| 26.4.2 | Prescaler..... | 418 |
| 26.4.3 | Counter..... | 418 |
| 26.4.3.1 | Up counting..... | 418 |
| 26.4.3.2 | Up-down counting..... | 421 |
| 26.4.3.3 | Free running counter..... | 422 |
| 26.4.3.4 | Counter reset..... | 423 |
| 26.4.3.5 | When the TOF bit is set..... | 423 |
| 26.4.4 | Input Capture mode..... | 424 |
| 26.4.4.1 | Filter for Input Capture mode..... | 425 |
| 26.4.5 | Output Compare mode..... | 426 |
| 26.4.6 | Edge-Aligned PWM (EPWM) mode..... | 427 |
| 26.4.7 | Center-Aligned PWM (CPWM) mode..... | 429 |
| 26.4.8 | Combine mode..... | 431 |
| 26.4.8.1 | Asymmetrical PWM..... | 438 |
| 26.4.9 | Complementary mode..... | 438 |

| Section number | Title | Page |
|----------------|---|------|
| 26.4.10 | Registers updated from write buffers..... | 439 |
| 26.4.10.1 | CNTIN register update..... | 439 |
| 26.4.10.2 | MOD register update..... | 440 |
| 26.4.10.3 | CnV register update..... | 440 |
| 26.4.11 | PWM synchronization..... | 441 |
| 26.4.11.1 | Hardware trigger..... | 441 |
| 26.4.11.2 | Software trigger..... | 442 |
| 26.4.11.3 | Boundary cycle and loading points..... | 443 |
| 26.4.11.4 | MOD register synchronization..... | 444 |
| 26.4.11.5 | CNTIN register synchronization..... | 447 |
| 26.4.11.6 | C(n)V and C(n+1)V register synchronization..... | 448 |
| 26.4.11.7 | OUTMASK register synchronization..... | 448 |
| 26.4.11.8 | INVCTRL register synchronization..... | 451 |
| 26.4.11.9 | SWOCTRL register synchronization..... | 452 |
| 26.4.11.10 | FTM counter synchronization..... | 454 |
| 26.4.12 | Inverting..... | 457 |
| 26.4.13 | Software output control..... | 458 |
| 26.4.14 | Deadtime insertion..... | 460 |
| 26.4.14.1 | Deadtime insertion corner cases..... | 461 |
| 26.4.15 | Output mask..... | 463 |
| 26.4.16 | Fault control..... | 464 |
| 26.4.16.1 | Automatic fault clearing..... | 466 |
| 26.4.16.2 | Manual fault clearing..... | 466 |
| 26.4.16.3 | Fault inputs polarity control..... | 467 |
| 26.4.17 | Polarity control..... | 467 |
| 26.4.18 | Initialization..... | 468 |
| 26.4.19 | Features priority..... | 468 |
| 26.4.20 | Channel trigger output..... | 469 |
| 26.4.21 | Initialization trigger..... | 470 |

| Section number | Title | Page |
|----------------|--|------|
| 26.4.22 | Capture Test mode..... | 472 |
| 26.4.23 | Dual Edge Capture mode..... | 473 |
| 26.4.23.1 | One-Shot Capture mode..... | 474 |
| 26.4.23.2 | Continuous Capture mode..... | 475 |
| 26.4.23.3 | Pulse width measurement..... | 475 |
| 26.4.23.4 | Period measurement..... | 477 |
| 26.4.23.5 | Read coherency mechanism..... | 479 |
| 26.4.24 | Debug mode..... | 480 |
| 26.4.25 | Intermediate load..... | 481 |
| 26.4.26 | Global time base (GTB)..... | 483 |
| 26.4.26.1 | Enabling the global time base (GTB)..... | 484 |
| 26.5 | Reset overview..... | 485 |
| 26.6 | FTM Interrupts..... | 486 |
| 26.6.1 | Timer Overflow Interrupt..... | 487 |
| 26.6.2 | Channel (n) Interrupt..... | 487 |
| 26.6.3 | Fault Interrupt..... | 487 |
| 26.7 | Initialization Procedure..... | 487 |

Chapter 27 Pulse Width Timer (PWT)

| | | |
|--------|--|-----|
| 27.1 | Introduction..... | 489 |
| 27.1.1 | Features..... | 489 |
| 27.1.2 | Modes of operation..... | 489 |
| 27.1.3 | Block diagram..... | 490 |
| 27.2 | PWT signal description..... | 491 |
| 27.2.1 | PWTIN[3:0] - Pulse Width Timer Capture Inputs..... | 491 |
| 27.2.2 | ALTCLK- Alternative Clock Source for Counter..... | 491 |
| 27.3 | Memory Map and Register Descriptions..... | 491 |
| 27.3.1 | Pulse Width Timer Register 1 (PWT_R1)..... | 492 |
| 27.3.2 | Pulse Width Timer Register 2 (PWT_R2)..... | 494 |

| Section number | Title | Page |
|----------------|--|------|
| 27.4 | Functional Description..... | 495 |
| 27.4.1 | PWT Counter and PWT Clock Prescaler..... | 495 |
| 27.4.2 | Edge detection and capture control | 495 |
| 27.5 | Reset..... | 499 |
| 27.5.1 | General..... | 499 |
| 27.5.2 | Description of reset operation..... | 499 |
| 27.6 | Interrupts..... | 499 |
| 27.6.1 | Description of interrupt operation..... | 499 |
| 27.6.2 | Application examples..... | 500 |

Chapter 28 Periodic Interrupt Timer (PIT)

| | | |
|----------|---|-----|
| 28.1 | Introduction..... | 503 |
| 28.1.1 | Block diagram..... | 503 |
| 28.1.2 | Features..... | 504 |
| 28.2 | Signal description..... | 504 |
| 28.3 | Memory map/register description..... | 505 |
| 28.3.1 | PIT Module Control Register (PIT_MCR)..... | 505 |
| 28.3.2 | Timer Load Value Register (PIT_LDVALn)..... | 506 |
| 28.3.3 | Current Timer Value Register (PIT_CVALn)..... | 507 |
| 28.3.4 | Timer Control Register (PIT_TCTRLn)..... | 507 |
| 28.3.5 | Timer Flag Register (PIT_TFLGn)..... | 508 |
| 28.4 | Functional description..... | 509 |
| 28.4.1 | General operation..... | 509 |
| 28.4.1.1 | Timers..... | 509 |
| 28.4.1.2 | Debug mode..... | 510 |
| 28.4.2 | Interrupts..... | 510 |
| 28.4.3 | Chained timers..... | 511 |
| 28.5 | Initialization and application information..... | 511 |
| 28.6 | Example configuration for chained timers..... | 512 |

| Section number | Title | Page |
|--------------------------------|---|------|
| Chapter 29 | | |
| Real-Time Counter (RTC) | | |
| 29.1 | Introduction..... | 515 |
| 29.2 | Features..... | 515 |
| 29.2.1 | Modes of operation..... | 515 |
| 29.2.1.1 | Wait mode..... | 515 |
| 29.2.1.2 | Stop modes..... | 516 |
| 29.2.2 | Block diagram..... | 516 |
| 29.3 | External signal description..... | 516 |
| 29.4 | Register definition..... | 517 |
| 29.4.1 | RTC Status and Control Register (RTC_SC)..... | 517 |
| 29.4.2 | RTC Modulo Register (RTC_MOD)..... | 519 |
| 29.4.3 | RTC Counter Register (RTC_CNT)..... | 519 |
| 29.5 | Functional description..... | 520 |
| 29.5.1 | RTC operation example..... | 521 |
| 29.6 | Initialization/application information..... | 522 |

Chapter 30

Serial Peripheral Interface (SPI)

| | | |
|----------|--|-----|
| 30.1 | Introduction..... | 523 |
| 30.1.1 | Features..... | 523 |
| 30.1.2 | Modes of operation..... | 524 |
| 30.1.3 | Block diagrams..... | 525 |
| 30.1.3.1 | SPI system block diagram..... | 525 |
| 30.1.3.2 | SPI module block diagram..... | 525 |
| 30.2 | External signal description..... | 527 |
| 30.2.1 | SPSCK — SPI Serial Clock..... | 527 |
| 30.2.2 | MOSI — Master Data Out, Slave Data In..... | 528 |
| 30.2.3 | MISO — Master Data In, Slave Data Out..... | 528 |
| 30.2.4 | SS — Slave Select..... | 528 |

| Section number | Title | Page |
|----------------|--|------|
| 30.3 | Memory map/register definition..... | 529 |
| 30.3.1 | SPI Control Register 1 (SPIx_C1)..... | 529 |
| 30.3.2 | SPI Control Register 2 (SPIx_C2)..... | 531 |
| 30.3.3 | SPI Baud Rate Register (SPIx_BR)..... | 532 |
| 30.3.4 | SPI Status Register (SPIx_S)..... | 533 |
| 30.3.5 | SPI Data Register (SPIx_D)..... | 534 |
| 30.3.6 | SPI Match Register (SPIx_M)..... | 535 |
| 30.4 | Functional description..... | 535 |
| 30.4.1 | General..... | 535 |
| 30.4.2 | Master mode..... | 536 |
| 30.4.3 | Slave mode..... | 537 |
| 30.4.4 | SPI clock formats..... | 539 |
| 30.4.5 | SPI baud rate generation..... | 542 |
| 30.4.6 | Special features..... | 542 |
| 30.4.6.1 | SS Output..... | 542 |
| 30.4.6.2 | Bidirectional mode (MOMI or SISO)..... | 543 |
| 30.4.7 | Error conditions..... | 544 |
| 30.4.7.1 | Mode fault error..... | 544 |
| 30.4.8 | Low-power mode options..... | 545 |
| 30.4.8.1 | SPI in Run mode..... | 545 |
| 30.4.8.2 | SPI in Wait mode..... | 545 |
| 30.4.8.3 | SPI in Stop mode..... | 546 |
| 30.4.9 | Reset..... | 546 |
| 30.4.10 | Interrupts..... | 547 |
| 30.4.10.1 | MODF..... | 547 |
| 30.4.10.2 | SPRF..... | 547 |
| 30.4.10.3 | SPTEF..... | 548 |
| 30.4.10.4 | SPMF..... | 548 |
| 30.4.10.5 | Asynchronous interrupt in low-power modes..... | 548 |

| Section number | Title | Page |
|----------------|---|------|
| 30.5 | Initialization/application information..... | 548 |
| 30.5.1 | Initialization sequence..... | 548 |
| 30.5.2 | Pseudo-Code Example..... | 549 |

Chapter 31 Inter-Integrated Circuit (I2C)

| | | |
|----------|---|-----|
| 31.1 | Introduction..... | 553 |
| 31.1.1 | Features..... | 553 |
| 31.1.2 | Modes of operation..... | 554 |
| 31.1.3 | Block diagram..... | 554 |
| 31.2 | I2C signal descriptions..... | 555 |
| 31.3 | Memory map/register definition..... | 556 |
| 31.3.1 | I2C Address Register 1 (I2Cx_A1)..... | 557 |
| 31.3.2 | I2C Frequency Divider register (I2Cx_F)..... | 557 |
| 31.3.3 | I2C Control Register 1 (I2Cx_C1)..... | 558 |
| 31.3.4 | I2C Status register (I2Cx_S)..... | 560 |
| 31.3.5 | I2C Data I/O register (I2Cx_D)..... | 561 |
| 31.3.6 | I2C Control Register 2 (I2Cx_C2)..... | 562 |
| 31.3.7 | I2C Programmable Input Glitch Filter Register (I2Cx_FLT)..... | 563 |
| 31.3.8 | I2C Range Address register (I2Cx_RA)..... | 564 |
| 31.3.9 | I2C SMBus Control and Status register (I2Cx_SMB)..... | 565 |
| 31.3.10 | I2C Address Register 2 (I2Cx_A2)..... | 567 |
| 31.3.11 | I2C SCL Low Timeout Register High (I2Cx_SLTH)..... | 567 |
| 31.3.12 | I2C SCL Low Timeout Register Low (I2Cx_SLTL)..... | 567 |
| 31.4 | Functional description..... | 568 |
| 31.4.1 | I2C protocol..... | 568 |
| 31.4.1.1 | START signal..... | 569 |
| 31.4.1.2 | Slave address transmission..... | 569 |
| 31.4.1.3 | Data transfers..... | 570 |
| 31.4.1.4 | STOP signal..... | 570 |

| Section number | Title | Page |
|----------------|--|------|
| 31.4.1.5 | Repeated START signal..... | 570 |
| 31.4.1.6 | Arbitration procedure..... | 571 |
| 31.4.1.7 | Clock synchronization..... | 571 |
| 31.4.1.8 | Handshaking..... | 572 |
| 31.4.1.9 | Clock stretching..... | 572 |
| 31.4.1.10 | I2C divider and hold values..... | 572 |
| 31.4.2 | 10-bit address..... | 573 |
| 31.4.2.1 | Master-transmitter addresses a slave-receiver..... | 574 |
| 31.4.2.2 | Master-receiver addresses a slave-transmitter..... | 574 |
| 31.4.3 | Address matching..... | 575 |
| 31.4.4 | System management bus specification..... | 576 |
| 31.4.4.1 | Timeouts..... | 576 |
| 31.4.4.2 | FAST ACK and NACK..... | 578 |
| 31.4.5 | Resets..... | 578 |
| 31.4.6 | Interrupts..... | 578 |
| 31.4.6.1 | Byte transfer interrupt..... | 579 |
| 31.4.6.2 | Address detect interrupt..... | 579 |
| 31.4.6.3 | Stop Detect Interrupt..... | 580 |
| 31.4.6.4 | Exit from low-power/stop modes..... | 580 |
| 31.4.6.5 | Arbitration lost interrupt..... | 580 |
| 31.4.6.6 | Timeout interrupt in SMBus..... | 580 |
| 31.4.7 | Programmable input glitch filter..... | 581 |
| 31.4.8 | Address matching wake-up..... | 581 |
| 31.5 | Initialization/application information..... | 582 |

Chapter 32

Freescale's Scalable Controller Area Network (MSCAN)

| | | |
|--------|--------------------|-----|
| 32.1 | Introduction..... | 587 |
| 32.1.1 | Glossary..... | 587 |
| 32.1.2 | Block diagram..... | 588 |

| Section number | Title | Page |
|----------------|--|------|
| 32.1.3 | Features..... | 588 |
| 32.1.4 | Modes of operation..... | 589 |
| 32.1.4.1 | Normal system operating modes..... | 589 |
| 32.1.4.2 | Special system operating modes..... | 589 |
| 32.1.4.3 | Emulation modes..... | 589 |
| 32.1.4.4 | Listen-only mode..... | 589 |
| 32.1.4.5 | MSCAN initialization mode..... | 590 |
| 32.2 | External signal description..... | 591 |
| 32.2.1 | CAN system..... | 591 |
| 32.3 | Memory map and register definition..... | 592 |
| 32.3.1 | Programmer's model of message storage..... | 592 |
| 32.3.2 | MSCAN Control Register 0 (MSCAN_CANCTL0)..... | 596 |
| 32.3.3 | MSCAN Control Register 1 (MSCAN_CANCTL1)..... | 599 |
| 32.3.4 | MSCAN Bus Timing Register 0 (MSCAN_CANBTR0)..... | 601 |
| 32.3.5 | MSCAN Bus Timing Register 1 (MSCAN_CANBTR1)..... | 601 |
| 32.3.6 | MSCAN Receiver Flag Register (MSCAN_CANRFLG)..... | 603 |
| 32.3.7 | MSCAN Receiver Interrupt Enable Register (MSCAN_CANRIER)..... | 605 |
| 32.3.8 | MSCAN Transmitter Flag Register (MSCAN_CANTFLG)..... | 606 |
| 32.3.9 | MSCAN Transmitter Interrupt Enable Register (MSCAN_CANTIER)..... | 607 |
| 32.3.10 | MSCAN Transmitter Message Abort Request Register (MSCAN_CANTARQ)..... | 608 |
| 32.3.11 | MSCAN Transmitter Message Abort Acknowledge Register (MSCAN_CANTAACK)..... | 609 |
| 32.3.12 | MSCAN Transmit Buffer Selection Register (MSCAN_CANTBSEL)..... | 609 |
| 32.3.13 | MSCAN Identifier Acceptance Control Register (MSCAN_CANIDAC)..... | 610 |
| 32.3.14 | MSCAN Miscellaneous Register (MSCAN_CANMISC)..... | 611 |
| 32.3.15 | MSCAN Receive Error Counter (MSCAN_CANRXERR)..... | 612 |
| 32.3.16 | MSCAN Transmit Error Counter (MSCAN_CANTXERR)..... | 613 |
| 32.3.17 | MSCAN Identifier Acceptance Register n of First Bank (MSCAN_CANIDAR _n)..... | 613 |
| 32.3.18 | MSCAN Identifier Mask Register n of First Bank (MSCAN_CANIDMR _n)..... | 614 |
| 32.3.19 | MSCAN Identifier Acceptance Register n of Second Bank (MSCAN_CANIDAR _n)..... | 615 |

| Section number | Title | Page |
|----------------|--|------|
| 32.3.20 | MSCAN Identifier Mask Register n of Second Bank (MSCAN_CANIDMR _n)..... | 616 |
| 32.3.21 | Receive Extended Identifier Register 0 (MSCAN_REIDR0)..... | 616 |
| 32.3.22 | Receive Standard Identifier Register 0 (MSCAN_RSIDR0)..... | 617 |
| 32.3.23 | Receive Extended Identifier Register 1 (MSCAN_REIDR1)..... | 617 |
| 32.3.24 | Receive Standard Identifier Register 1 (MSCAN_RSIDR1)..... | 618 |
| 32.3.25 | Receive Extended Identifier Register 2 (MSCAN_REIDR2)..... | 619 |
| 32.3.26 | Receive Extended Identifier Register 3 (MSCAN_REIDR3)..... | 620 |
| 32.3.27 | Receive Extended Data Segment Register N (MSCAN_REDSR _n)..... | 620 |
| 32.3.28 | Receive Data Length Register (MSCAN_RDLR)..... | 621 |
| 32.3.29 | Receive Time Stamp Register High (MSCAN_RTSRH)..... | 621 |
| 32.3.30 | Receive Time Stamp Register Low (MSCAN_RTSSL)..... | 622 |
| 32.3.31 | Transmit Extended Identifier Register 0 (MSCAN_TEIDR0)..... | 623 |
| 32.3.32 | Transmit Standard Identifier Register 0 (MSCAN_TSIDR0)..... | 623 |
| 32.3.33 | Transmit Extended Identifier Register 1 (MSCAN_TEIDR1)..... | 624 |
| 32.3.34 | Transmit Standard Identifier Register 1 (MSCAN_TSIDR1)..... | 625 |
| 32.3.35 | Transmit Extended Identifier Register 2 (MSCAN_TEIDR2)..... | 626 |
| 32.3.36 | Transmit Extended Identifier Register 3 (MSCAN_TEIDR3)..... | 626 |
| 32.3.37 | Transmit Extended Data Segment Register N (MSCAN_TEDSR _n)..... | 627 |
| 32.3.38 | Transmit Data Length Register (MSCAN_TDLR)..... | 627 |
| 32.3.39 | Transmit Buffer Priority Register (MSCAN_TBPR)..... | 628 |
| 32.3.40 | Transmit Time Stamp Register High (MSCAN_TTSRH)..... | 629 |
| 32.3.41 | Transmit Time Stamp Register Low (MSCAN_TTSSL)..... | 630 |
| 32.4 | Functional description..... | 631 |
| 32.4.1 | Message storage..... | 631 |
| 32.4.2 | Message transmit background..... | 632 |
| 32.4.3 | Transmit structures..... | 632 |
| 32.4.4 | Receive structures..... | 634 |
| 32.4.5 | Identifier acceptance filter..... | 635 |
| 32.4.5.1 | Protocol violation protection..... | 638 |

| Section number | Title | Page |
|----------------|---|------|
| 32.4.5.2 | Clock system..... | 639 |
| 32.4.6 | Low-power options..... | 641 |
| 32.4.6.1 | Operation in run mode..... | 642 |
| 32.4.6.2 | Operation in wait mode..... | 642 |
| 32.4.6.3 | Operation in stop mode..... | 642 |
| 32.4.6.4 | MSCAN normal mode..... | 642 |
| 32.4.6.5 | MSCAN sleep mode..... | 643 |
| 32.4.6.6 | MSCAN power down mode..... | 644 |
| 32.4.6.7 | Disabled mode..... | 645 |
| 32.4.6.8 | Programmable wake-Up function..... | 645 |
| 32.4.7 | Reset initialization..... | 645 |
| 32.4.8 | Interrupts..... | 645 |
| 32.4.8.1 | Description of interrupt operation..... | 646 |
| 32.4.8.2 | Transmit interrupt..... | 646 |
| 32.4.8.3 | Receive interrupt..... | 646 |
| 32.4.8.4 | Wake-up interrupt..... | 646 |
| 32.4.8.5 | Error interrupt..... | 647 |
| 32.4.8.6 | Interrupt acknowledge..... | 647 |
| 32.4.9 | Initialization/Application information..... | 647 |
| 32.4.9.1 | MSCAN initialization..... | 647 |
| 32.4.9.2 | Bus-off recovery..... | 648 |

Chapter 33

Universal Asynchronous Receiver/Transmitter (UART)

| | | |
|--------|-----------------------------------|-----|
| 33.1 | Introduction..... | 649 |
| 33.1.1 | Features..... | 649 |
| 33.1.2 | Modes of operation..... | 649 |
| 33.1.3 | Block diagram..... | 650 |
| 33.2 | UART signal descriptions..... | 652 |
| 33.2.1 | Detailed signal descriptions..... | 652 |

| Section number | Title | Page |
|----------------|--|------|
| 33.3 | Register definition..... | 652 |
| 33.3.1 | UART Baud Rate Register: High (UARTx_BDH)..... | 653 |
| 33.3.2 | UART Baud Rate Register: Low (UARTx_BDL)..... | 654 |
| 33.3.3 | UART Control Register 1 (UARTx_C1)..... | 655 |
| 33.3.4 | UART Control Register 2 (UARTx_C2)..... | 656 |
| 33.3.5 | UART Status Register 1 (UARTx_S1)..... | 658 |
| 33.3.6 | UART Status Register 2 (UARTx_S2)..... | 659 |
| 33.3.7 | UART Control Register 3 (UARTx_C3)..... | 661 |
| 33.3.8 | UART Data Register (UARTx_D)..... | 662 |
| 33.4 | Functional description..... | 663 |
| 33.4.1 | Baud rate generation..... | 663 |
| 33.4.2 | Transmitter functional description..... | 664 |
| 33.4.2.1 | Send break and queued idle..... | 665 |
| 33.4.3 | Receiver functional description..... | 666 |
| 33.4.3.1 | Data sampling technique..... | 667 |
| 33.4.3.2 | Receiver wake-up operation..... | 667 |
| 33.4.4 | Interrupts and status flags..... | 669 |
| 33.4.5 | Baud rate tolerance..... | 670 |
| 33.4.5.1 | Slow data tolerance..... | 670 |
| 33.4.5.2 | Fast data tolerance..... | 671 |
| 33.4.6 | Additional UART functions..... | 672 |
| 33.4.6.1 | 8- and 9-bit data modes..... | 673 |
| 33.4.6.2 | Stop mode operation..... | 673 |
| 33.4.6.3 | Loop mode..... | 673 |
| 33.4.6.4 | Single-wire operation..... | 674 |

Chapter 34

General-Purpose Input/Output (GPIO)

| | | |
|--------|-------------------|-----|
| 34.1 | Introduction..... | 675 |
| 34.1.1 | Features..... | 675 |

| Section number | Title | Page |
|----------------|---|------|
| 34.1.2 | Modes of operation..... | 675 |
| 34.1.3 | GPIO signal descriptions..... | 676 |
| 34.1.3.1 | Detailed signal description..... | 676 |
| 34.2 | Memory map and register definition..... | 677 |
| 34.2.1 | GPIO/FGPIO register bits assignment..... | 677 |
| 34.2.2 | Port Data Output Register (GPIOx_PDOR)..... | 679 |
| 34.2.3 | Port Set Output Register (GPIOx_PSOR)..... | 680 |
| 34.2.4 | Port Clear Output Register (GPIOx_PCOR)..... | 680 |
| 34.2.5 | Port Toggle Output Register (GPIOx_PTOR)..... | 681 |
| 34.2.6 | Port Data Input Register (GPIOx_PDIR)..... | 681 |
| 34.2.7 | Port Data Direction Register (GPIOx_PDDR)..... | 682 |
| 34.2.8 | Port Input Disable Register (GPIOx_PIDR)..... | 682 |
| 34.3 | FGPIO memory map and register definition..... | 683 |
| 34.3.1 | GPIO/FGPIO register bits assignment..... | 683 |
| 34.3.2 | Port Data Output Register (FGPIOx_PDOR)..... | 685 |
| 34.3.3 | Port Set Output Register (FGPIOx_PSOR)..... | 685 |
| 34.3.4 | Port Clear Output Register (FGPIOx_PCOR)..... | 686 |
| 34.3.5 | Port Toggle Output Register (FGPIOx_PTOR)..... | 686 |
| 34.3.6 | Port Data Input Register (FGPIOx_PDIR)..... | 687 |
| 34.3.7 | Port Data Direction Register (FGPIOx_PDDR)..... | 687 |
| 34.3.8 | Port Input Disable Register (FGPIOx_PIDR)..... | 688 |
| 34.4 | Functional description..... | 688 |
| 34.4.1 | General-purpose input..... | 688 |
| 34.4.2 | General-purpose output..... | 688 |
| 34.4.3 | IOPORT..... | 689 |

Chapter 35 Keyboard interrupts (KBI)

| | | |
|--------|-------------------|-----|
| 35.1 | Introduction..... | 691 |
| 35.1.1 | Features..... | 691 |

| Section number | Title | Page |
|----------------|--|------|
| 35.1.2 | Modes of Operation..... | 691 |
| 35.1.2.1 | KBI in Wait mode..... | 691 |
| 35.1.2.2 | KBI in Stop modes..... | 692 |
| 35.1.3 | Block Diagram..... | 692 |
| 35.2 | External signals description..... | 692 |
| 35.3 | Register definition..... | 693 |
| 35.4 | Memory Map and Registers..... | 693 |
| 35.4.1 | KBI Pin Enable Register (KBIx_PE)..... | 694 |
| 35.4.2 | KBI Edge Select Register (KBIx_ES)..... | 694 |
| 35.4.3 | KBI Status and Control Register (KBIx_SC)..... | 695 |
| 35.4.4 | KBI Source Pin Register (KBIx_SP)..... | 696 |
| 35.5 | Functional Description..... | 696 |
| 35.5.1 | Edge-only sensitivity..... | 697 |
| 35.5.2 | Edge and level sensitivity..... | 697 |
| 35.5.3 | KBI Pullup Resistor..... | 697 |
| 35.5.4 | KBI initialization..... | 698 |

Chapter 36

Release Notes for Rev 2

Chapter 1

About This Document

1.1 Overview

1.1.1 Purpose

This document describes the features, architecture, and programming model of the Freescale KEA128 microcontroller.

1.1.2 Audience

This document is primarily for system architects and software application developers who are using or considering using the KEA128 microcontroller in a system.

1.2 Conventions

1.2.1 Numbering systems

The following suffixes identify different numbering systems:

| This suffix | Identifies a |
|-------------|--|
| b | Binary number. For example, the binary equivalent of the number 5 is written 101b. In some cases, binary numbers are shown with the prefix 0b. |
| d | Decimal number. Decimal numbers are followed by this suffix only when the possibility of confusion exists. In general, decimal numbers are shown without a suffix. |
| h | Hexadecimal number. For example, the hexadecimal equivalent of the number 60 is written 3Ch. In some cases, hexadecimal numbers are shown with the prefix 0x. |

1.2.2 Typographic notation

The following typographic notation is used throughout this document:

| Example | Description |
|-----------------------|--|
| <i>placeholder, x</i> | Items in italics are placeholders for information that you provide. Italicized text is also used for the titles of publications and for emphasis. Plain lowercase letters are also used as placeholders for single letters and numbers. |
| <code>code</code> | Fixed-width type indicates text that must be typed exactly as shown. It is used for instruction mnemonics, directives, symbols, subcommands, parameters, and operators. Fixed-width type is also used for example code. Instruction mnemonics and directives in text and tables are shown in all caps; for example, BSR. |
| SR[SCM] | A mnemonic in brackets represents a named field in a register. This example refers to the Scaling Mode (SCM) field in the Status Register (SR). |
| REVNO[6:4], XAD[7:0] | Numbers in brackets and separated by a colon represent either: <ul style="list-style-type: none"> A subset of a register's named field For example, REVNO[6:4] refers to bits 6–4 that are part of the COREREV field that occupies bits 6–0 of the REVNO register. A continuous range of individual signals of a bus For example, XAD[7:0] refers to signals 7–0 of the XAD bus. |

1.2.3 Special terms

The following terms have special meanings:

| Term | Meaning |
|------------|--|
| asserted | Refers to the state of a signal as follows: <ul style="list-style-type: none"> An active-high signal is asserted when high (1). An active-low signal is asserted when low (0). |
| deasserted | Refers to the state of a signal as follows: <ul style="list-style-type: none"> An active-high signal is deasserted when low (0). An active-low signal is deasserted when high (1). In some cases, deasserted signals are described as <i>negated</i> . |
| reserved | Refers to a memory space, register, or field that is either reserved for future use or for which, when written to, the module or chip behavior is unpredictable. |

Chapter 2

Introduction

2.1 Overview

This chapter provides an overview of the Kinetis KEA128 product family of ARM® Cortex®-M0+ MCUs. It also presents high-level descriptions of the modules available on the devices covered by this document.

The Kinetis EA series MCU is a highly scalable portfolio of 32-bits ARM Cortex-M0+ MCUs aimed for the automotive markets. The family is optimized for cost-sensitive applications offering low pin-count option with very low power consumption. With 2.7 - 5.5 V supply and focus on exceptional EMC/ESD robustness, Kinetis EA series MCUs are well suited to a wide range of applications ranging from body applications, safety companion chips or generic sensor nodes. In automotive body applications, the Kinetis EA series MCU is a great option for entry level body controller or gateway module, window/roof/sun-roof controller, immobilizer or seat/mirror controller just to mention a few. Please contact Freescale local representatives for suggestion on extremely safety constrained application. All the members of the Kinetis EA series MCUs share similar peripherals and offer several pin-count and memory options allowing developers to migrate easily to MCUs that take advantage of more memory or peripheral integration. This scalability allows developers to standardize on the Kinetis EA series MCUs for their end product platforms, maximizing hardware and software reuse and reducing time-to-market. The Kinetis EA series MCU is supported by several third party and Freescale development tools including CodeWarrior, Keil, IAR, Processor Expert and MQX support. Developers can start designing quickly and easily take advantages of these broad enabled ecosystems.

2.2 Module functional categories

The modules on this device are grouped into functional categories. The following sections describe the modules assigned to each category in more detail.

Table 2-1. Module functional categories

| Module category | Description |
|--------------------------------|--|
| ARM Cortex-M0+ core | <ul style="list-style-type: none"> 32-bit MCU core from ARM's Cortex-M class, 1.77 CoreMark®/MHz from single-cycle access memories, 48 MHz CPU frequency |
| System | <ul style="list-style-type: none"> System integration module (SIM) Power management and mode controllers (PMC) Miscellaneous control module (MCM) Bit manipulation engine (BME) Peripheral bridge (AIPS) Watchdog (WDOG) |
| Memories | <ul style="list-style-type: none"> Internal memories include: <ul style="list-style-type: none"> Up to 128 KB flash memory Up to 16 KB SRAM |
| Clocks | <ul style="list-style-type: none"> External crystal oscillator or resonator <ul style="list-style-type: none"> Low range: 31.25–39.0625 kHz High range: 4–24 MHz External square wave input clock Internal clock references <ul style="list-style-type: none"> 31.25 to 39.0625 kHz oscillator 1 kHz LPO oscillator Frequency-locked loop (FLL) range: 40–50 MHz |
| Security | <ul style="list-style-type: none"> Watchdog (WDOG) with independent clock source Cyclic redundancy check (CRC) module for error detection |
| Analog | <ul style="list-style-type: none"> One 12-bit analog-to-digital converters (ADC) with up to 16 channels Two analog comparators (ACMP) with internal 6-bit digital-to-analog converter (DAC) |
| Timers | <ul style="list-style-type: none"> One 6-channel FlexTimer (FTM) with full function Two 2-channel FTM with basic TPM function 2-channel periodic interrupt timer (PIT) Real time clock (RTC) One pulse width timer (PWT) System tick timer (SysTick) |
| Communications | <ul style="list-style-type: none"> Two 8-bit serial peripheral interfaces (SPI) Two inter-integrated circuit (I²C) modules Three universal asynchronous receiver/transmitter (UART) modules One Freescale's scalable controller area network (MSCAN) |
| Human-Machine Interfaces (HMI) | <ul style="list-style-type: none"> General purpose input/output (GPIO) controller Two keyboard Interrupt (KBI) Interrupt (IRQ) |

2.2.1 ARM Cortex-M0+ core modules

The following core modules are available on this device.

Table 2-2. Core modules

| Module | Description |
|----------------|--|
| ARM Cortex-M0+ | The ARM Cortex-M0+ is the newest member of the Cortex M Series of processors targeting microcontroller applications focused on very cost sensitive, deterministic, interrupt driven environments. The Cortex M0+ processor is based on the ARMv6 |

Table continues on the next page...

Table 2-2. Core modules (continued)

| Module | Description |
|---|--|
| | <p>Architecture and Thumb®-2 ISA and is 100% instruction set compatible with its predecessor, the Cortex-M0 core, and upward compatible to Cortex-M3 and M4 cores.</p> <p>The ARM Cortex-M0+ improvements include an ARMv6 Thumb-2 DSP, ported from the ARMv6-A/R profile architectures, that provide 32-bit instructions with SIMD (single instruction multiple data) DSP style multiply-accumulates and saturating arithmetic to support single cycle 32x32 multiplier.</p> |
| Nested vectored interrupt controller (NVIC) | <p>The ARMv6-M exception model and nested-vectored interrupt controller (NVIC) implement a relocatable vector table supporting many external interrupts, a single non-maskable interrupt (NMI), and priority levels.</p> <p>The NVIC replaces shadow registers with equivalent system and simplified programmability. The NVIC contains the address of the function to execute for a particular handler. The address is fetched via the instruction port allowing parallel register stacking and look-up. The first sixteen entries are allocated to ARM internal sources with the others mapping to MCU-defined interrupts.</p> |
| Asynchronous wakeup interrupt controller (AWIC) | The primary function of the Asynchronous Wake-up Interrupt Controller (AWIC) is to detect asynchronous wake-up events in stop modes and signal to clock control logic to resume system clocking. After clock restart, the NVIC observes the pending interrupt and performs the normal interrupt or event processing. |
| Single-cycle I/O port (IOPORT) | For high-speed, single-cycle access to peripherals, the Cortex-M0+ processor implements a dedicated single-cycle I/O port. On this device, fast GPIO (FGPIO) is implemented on IOPORT interface. |
| Debug interfaces | <p>Most of this device's debug is based on the ARM CoreSight™ architecture. One debug interface is supported:</p> <ul style="list-style-type: none"> Serial Wire Debug (SWD) |

2.2.2 System modules

The following system modules are available on this device.

Table 2-3. System modules

| Module | Description |
|------------------------------------|---|
| System integration module (SIM) | The SIM includes integration logic and several module configuration settings. |
| Power management controller (PMC) | The PMC provides the user with multiple power options. Multiple modes are supported that allow the user to optimize power consumption for the level of functionality needed. Includes power-on-reset (POR) and integrated low voltage detect (LVD) with reset (brownout) capability and selectable LVD trip points. |
| Miscellaneous control module (MCM) | The MCM includes integration logic and details. |
| Peripheral bridge (AIPS-Lite) | The peripheral bridge converts the ARM AHB interface to an interface to access a majority of peripherals on the device. |
| Watchdog (WDOG) | The WDOG monitors internal system operation and forces a reset in case of failure. It can run from an independent 1 kHz low-power oscillator with a programmable refresh window to detect deviations in program flow or system frequency. |

Table continues on the next page...

Table 2-3. System modules (continued)

| Module | Description |
|---|--|
| Bit manipulation engine (BME) | The BME provides hardware support for atomic read-modify-write memory operations to the peripheral address space in Cortex-M0+ based microcontrollers. |

2.2.3 Memories and memory interfaces

The following memories and memory interfaces are available on this device.

Table 2-4. Memories and memory interfaces

| Module | Description |
|---|--|
| Flash memory (FTMRE) | Flash memory — up to 64/128 KB of the non-volatile flash memory that can execute program code. |
| Flash memory controller (FMC) | FMC is a memory acceleration unit that provides an interface between Cortex M0+ core and the 32-bit program flash memory. The FMC contains one 32-bit speculation buffer and one 32-byte cache that can accelerate instruction fetch and flash access. |
| SRAM | Up to 16 KB internal system RAM, supporting bit operation through BME module or aliased bit-band domain. |

2.2.4 Clocks

The following clock modules are available on this device.

Table 2-5. Clock modules

| Module | Description |
|---|--|
| Internal Clock Source (ICS) | ICS module containing an internal reference clock (ICSIRCLK) and a frequency-locked-loop (FLL). |
| System oscillator (OSC) | The system oscillator, in conjunction with an external crystal or resonator, generates a reference clock for the MCU. |
| Low-Power Oscillator (LPO) | The PMC module contains a 1 kHz low-power oscillator which acts as a standalone low-frequency clock source in all modes. |

2.2.5 Security and integrity modules

The following security and integrity modules are available on this device:

Table 2-6. Security and integrity modules

| Module | Description |
|-------------------------------|---|
| Cyclic Redundancy Check (CRC) | CRC generates 16/32-bit CRC code for error detection. |
| Watchdog (WDOG) | The WDOG monitors internal system operation and forces a reset in case of failure. It can run from an independent 1 kHz low-power oscillator with a programmable refresh window to detect deviations in program flow or system frequency. |

2.2.6 Analog modules

The following analog modules are available on this device:

Table 2-7. Analog modules

| Module | Description |
|--|---|
| Analog-to-digital converters (ADC) | 12-bit successive-approximation ADC module with up to 16 channels. |
| Analog comparators (ACMP) | Two comparators with support of analog input voltages across the full range of the supply voltage and CPU interrupt. ACMP0/1 is further capable to trigger an ADC acquisition and FTM update. |
| 6-bit digital-to-analog converters (DAC) | 64-tap resistor ladder network which provides a selectable voltage reference for comparator. |

2.2.7 Timer modules

The following timer modules are available on this device:

Table 2-8. Timer modules

| Module | Description |
|---------------------------------|---|
| FlexTimer modules (FTM) | <ul style="list-style-type: none"> Selectable FTM source clock, supporting separate timer clock up to 48 MHz, programmable prescaler 16-bit counter supporting free-running or initial/final value, and counting is up or up-down Input capture, output compare, and edge-aligned and center-aligned PWM modes Operation of FTM channels as pairs with equal outputs, pairs with complementary outputs, or independent channels with independent outputs Deadtime insertion is available for each complementary pair Software control of PWM outputs Up to two fault inputs for global fault control Configurable channel polarity Programmable interrupt on input capture, reference compare, overflowed counter, or detected fault condition |
| Periodic interrupt timers (PIT) | <ul style="list-style-type: none"> One general purpose interrupt timer Interrupt timers for triggering ADC conversions |

Table continues on the next page...

Table 2-8. Timer modules (continued)

| Module | Description |
|-------------------------|---|
| | <ul style="list-style-type: none"> • 32-bit counter resolution • Clocked by bus clock frequency |
| Real-time counter (RTC) | <ul style="list-style-type: none"> • 16-bit up-counter <ul style="list-style-type: none"> • 16-bit modulo match limit • Software controllable periodic interrupt on match • Software selectable clock sources for input to prescaler with programmable 16-bit prescaler <ul style="list-style-type: none"> • Bus clock • IRC clock (31.25~39.0625 kHz) • LPO (~1 kHz) • System oscillator output clock |
| Pulse Width Timer (PWT) | <ul style="list-style-type: none"> • Automatic measurement of pulse width with 16-bit resolution • Separate positive and negative pulse width measurements • Programmable triggering edge for starting measurement • Programmable measuring time between successive alternating edges, rising edges or falling edges • Programmable pre-scaler from clock input as 16-bit counter time base • Two selectable clock sources, supporting separate timer clock up to 48 MHz • Four selectable pulse inputs • Programmable interrupt generation upon pulse width value updated and counter overflow |

2.2.8 Communication interfaces

The following communication interfaces are available on this device:

Table 2-9. Communication modules

| Module | Description |
|--|--|
| Serial peripheral interface (SPI) | Two SPIs synchronous serial bus for communication to an external device. |
| Inter-integrated circuit (I2C) | Two I2C modules for inter device communications. Also support the System Management Bus (SMBus) Specification, version 2. I2C0 supports four wire interface feature. |
| Universal asynchronous receiver/transmitters (UART) | Three asynchronous serial bus communication interfaces (UART) modules with optional 13-bit break, full duplex non-return to zero (NRZ), and LIN extension support. |
| Freescale's scalable controller area network (MSCAN) | One Freescale's scalable controller area network (MSCAN). |

2.2.9 Human-machine interfaces

The following human-machine interfaces (HMI) are available on this device:

Table 2-10. HMI modules

| Module | Description |
|-------------------------------------|---|
| General purpose input/output (GPIO) | Up to 71 general purpose input or output (GPIO) pins. |
| Keyboard Interrupts (KBI) | Two KBI modules to support pin interrupts. |
| Interrupt (IRQ) | IRQ module provides a maskable interrupt input. |

2.2.10 Orderable part numbers

The following table summarizes the part numbers of the devices covered by this document.

Table 2-11. Orderable part numbers summary

| Freescal part number | CPU frequency | Pin count | Package | Total flash memory | RAM | Temperature range |
|----------------------|---------------|-----------|---------|--------------------|-------|-------------------|
| S9KEAZ64AMLH(R) | 48 MHz | 64 | LQFP | 64 KB | 8 KB | -40 to 125 °C |
| S9KEAZ128AMLH(R) | 48 MHz | 64 | LQFP | 128 KB | 16 KB | -40 to 125 °C |
| S9KEAZ64AMLK(R) | 48 MHz | 80 | LQFP | 64 KB | 8 KB | -40 to 125 °C |
| S9KEAZ128AMLK(R) | 48 MHz | 80 | LQFP | 128 KB | 16 KB | -40 to 125 °C |
| S9KEAZ64AVLK(R) | 48 MHz | 80 | LQFP | 64 KB | 8 KB | -40 to 125 °C |
| S9KEAZ128AVLK(R) | 48 MHz | 80 | LQFP | 128 KB | 16 KB | -40 to 125 °C |
| S9KEAZ64ACLK(R) | 48 MHz | 80 | LQFP | 64 KB | 8 KB | -40 to 125 °C |
| S9KEAZ128ACLK(R) | 48 MHz | 80 | LQFP | 128 KB | 16 KB | -40 to 125 °C |
| S9KEAZ64AVLH(R) | 48 MHz | 64 | LQFP | 64 KB | 8 KB | -40 to 125 °C |
| S9KEAZ128AVLH(R) | 48 MHz | 64 | LQFP | 128 KB | 16 KB | -40 to 125 °C |
| S9KEAZ64ACLH(R) | 48 MHz | 64 | LQFP | 64 KB | 8 KB | -40 to 125 °C |
| S9KEAZ128ACLH(R) | 48 MHz | 64 | LQFP | 128 KB | 16 KB | -40 to 125 °C |

Chapter 3

Chip Configuration

3.1 Introduction

This chapter provides details on the individual modules of the microcontroller. It includes:

- Module block diagrams showing immediate connections within the device
- Specific module-to-module interactions not necessarily discussed in the individual module chapters
- Links for more information

3.2 Module to Module Interconnects

3.2.1 Interconnection overview

The following table captures the module-to-module interconnections for this device.

Table 3-1. Module-to-module interconnects

| Peripheral | Signal | — | to Peripheral | Use Case | Control | Comment |
|------------|-------------------|----|-----------------------|-----------------|------------------|---------|
| FTM2 | INITTRG, MatchTRG | to | ADC (Trigger) | ADC Triggering | SIM_SOPT0[ADHWT] | — |
| PIT CHx | TIF0,TIF1 | to | ADC (Trigger) | ADC Triggering | SIM_SOPT0[ADHWT] | — |
| RTC | RTC Overflow | to | ADC (Trigger) | ADC Triggering | SIM_SOPT0[ADHWT] | — |
| FTM0 | INITTRG | to | ADC (Trigger) | ADC Triggering | SIM_SOPT0[ADHWT] | — |
| ACMP0 | CMP0_OUT | to | ADC (Trigger) | ADC Triggering | SIM_SOPT0[ADHWT] | — |
| ACMP1 | CMP1_OUT | to | ADC (Trigger) | ADC Triggering | SIM_SOPT0[ADHWT] | — |
| UART0 | TX0 | to | Modulated by FTM0 CH0 | UART modulation | SIM_SOPT0[TXDME] | — |

Table continues on the next page...

Table 3-1. Module-to-module interconnects (continued)

| Peripheral | Signal | — | to Peripheral | Use Case | Control | Comment |
|-------------|-----------------|----|------------------------|----------------------|--|--------------|
| UART0 | RX0 | to | FTM0 CH1 input capture | UART modulation | SIM_SOPT0[RXDCE] | — |
| ACMP0 | CMP0_OUT | to | UART0 RxD | UART RxD Filter | SIM_SOPT0[RXDCE] | — |
| ACMP1 | CMP1_OUT | to | UART0 RxD | UART RxD Filter | SIM_SOPT0[RXDCE] | — |
| ACMP0 | CMP0_OUT | to | FTM1 CH0 input capture | ACMP0 output capture | SIM_SOPT0[ACIC] | — |
| RTC | RTC overflow | to | FTM1 CH1 input capture | RTC overflow capture | SIM_SOPT0[RTCC] | — |
| ACMP0 | CMP0_OUT | to | FTM2 Trigger0 | FTM2 Trigger input | SIM_SOPT0[ACTRG] & FTM2_SYNC[TRIG0] | — |
| ACMP1 | CMP1_OUT | to | FTM2 Trigger0 | FTM2 Trigger input | SIM_SOPT0[ACTRG] & FTM2_SYNC[TRIG0] | — |
| FTM0 | FTM0 CH0 Output | to | FTM2 Trigger1 | FTM2 Trigger input | FTM2_SYNC[TRIG1] | — |
| SIM | FTMSYNC | to | FTM2 Trigger2 | FTM2 Trigger input | FTM2_SYNC[TRIG2] | — |
| ACMP0 | CMP0_OUT | to | FTM2 Fault0 | FTM2 fault input | FTM2_FLTCTRL[FAULT0EN] | — |
| EXTFT_IN | EXTFT_IN | to | FTM2 Fault1 | FTM2 fault input | FTM2_FLTCTRL[FAULT1EN] | PTA6 |
| EXTFT_IN | EXTFT_IN | to | FTM2 Fault2 | FTM2 fault input | FTM2_FLTCTRL[FAULT2EN] | PTA7 |
| ACMP1 | CMP1_OUT | to | FTM2 Fault3 | FTM2 fault input | FTM2_FLTCTRL[FAULT3EN] | — |
| EXT_PWT_IN0 | PWT_IN0 | to | PWT | PWT_IN0 | SIM_PINSEL1[PWTIN0PS] & PWT_R1[PINSEL] | PTD5 or PTE2 |
| EXT_PWT_IN1 | PWT_IN1 | to | PWT | PWT_IN1 | SIM_PINSEL1[PWTIN1PS] & PWT_R1[PINSEL] | PTB0 or PTH7 |
| ACMP0 | ACMP0_OUT | to | PWT | PWT_IN2 | SIM_SOPT1[ACPWTS] & PWT_R1[PINSEL] | — |
| ACMP1 | ACMP1_OUT | to | PWT | PWT_IN2 | SIM_SOPT1[ACPWTS] & PWT_R1[PINSEL] | — |
| UART0 | RX | to | PWT | PWT_IN3 | SIM_SOPT1[UARTPWTS] & PWT_R1[PINSEL] | — |
| UART1 | RX | to | PWT | PWT_IN3 | SIM_SOPT1[UARTPWTS] & PWT_R1[PINSEL] | — |
| UART2 | RX | to | PWT | PWT_IN3 | SIM_SOPT1[UARTPWTS] & PWT_R1[PINSEL] | — |

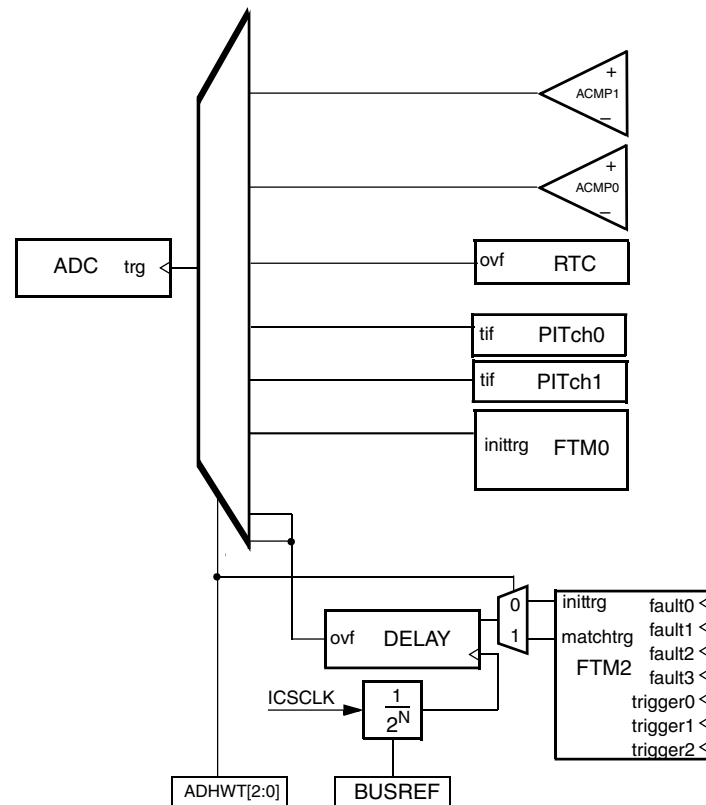


Figure 3-1. ADC hardware trigger connection diagram

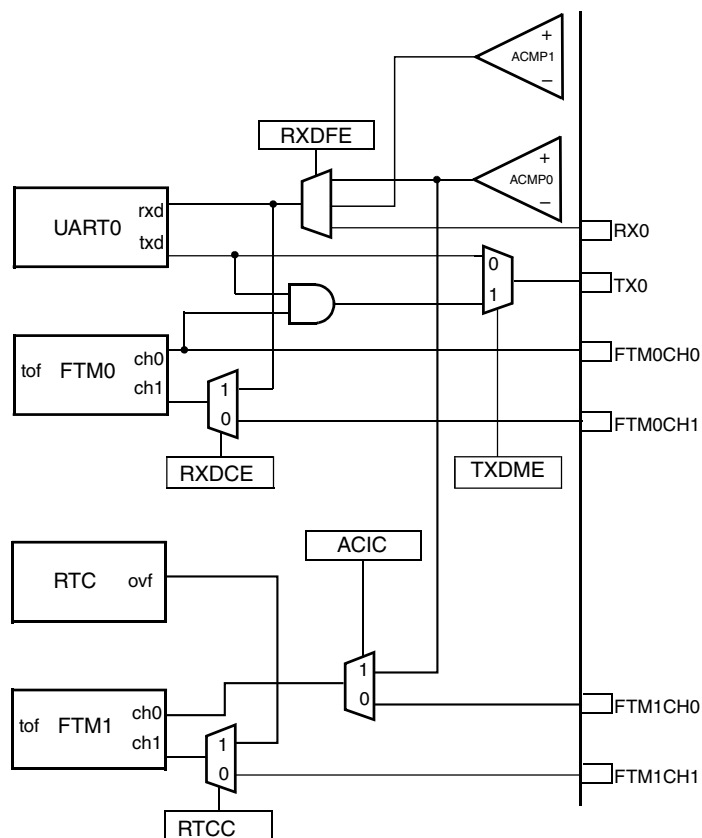


Figure 3-2. FTMx/ACMPx/UARTx connection diagram

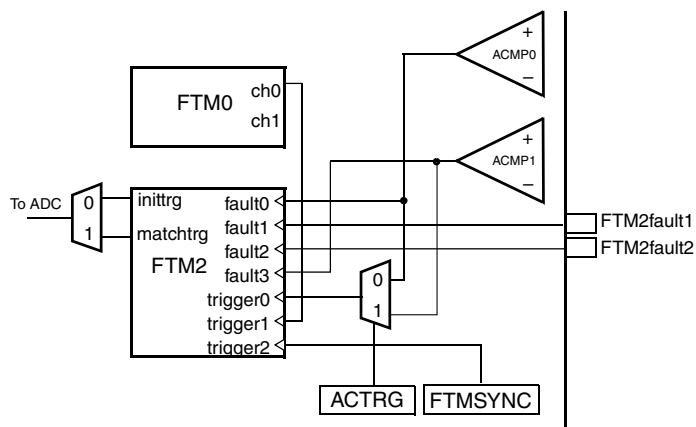


Figure 3-3. FTM2 inteconnection diagram



3.2.2 Analog reference options

Several analog blocks have selectable reference voltages as shown in [Table 3-2](#). These options allow analog peripherals to share or have separate analog references. Care must be taken when selecting analog references to avoid cross talk noise.

Table 3-2. Analog reference options

| Module | Reference option | Comment/ reference selection |
|----------------|---|---|
| 12-bit ADC | <ul style="list-style-type: none"> VREFH VREFL | To improve ADC performance, VREFH pin is available on 80LQFP and it is internally connected to VDDA on 64QFP/LQFP, 44LQFP, VREFL pin is available on every package. |
| ACMP0 ACMP1 | <ul style="list-style-type: none"> VDDA Bandgap | Selected by ACMP0_C1[DACREF] or ACMP1_C1[DACREF] |

3.2.3 ACMP output capture

When set, the SIM_SOPT0[ACIC] bit enables the output of ACMP0 to connect to the FTM1_CH0, the FTM1_CH0 pin is released to other shared functions.

When setting the SIM_SOPT0[RXDFE] to 01b, the ACMP0 outputs can be selected to connect to the receiver channel of UART0. When setting the SIM_SOPT0[RXDFE] to 10b, the ACMP1 outputs can be selected to connect to the receiver channel of UART1.

ACMP0 and ACMP1 output is also connected to PWT input2(PWT_IN2), or can be used as FTM2 trigger/fault input and ADC hardware trigger.

3.2.4 UART0_TX modulation

UART0_TX can be modulated by FTM0 channel 0 output. When SIM_SOPT0[TXDME] is set, the UART0_TX is gated by FTM0 channel0 output through an AND gate, and then mapped to UART0_TX pinout. When this field is clear, the UART0_TX is directly mapped on the pinout. To enable IR modulation function, both FTM0_CH0 and UART must be active. The FTM0_CNT and FTM0_MOD registers specify the period of the PWM, and the FTM0_C0V register specifies the duty cycle of the PWM. Then, when SIM_SOPT0[TXDME] is enabled, each data transmitted via UART0_TX from UART0 is modulated by the FTM0 channel 0 output, and the FTM0_CH0 pin is released to other shared functions regardless of the configuration of FTM0 pin reassignment.

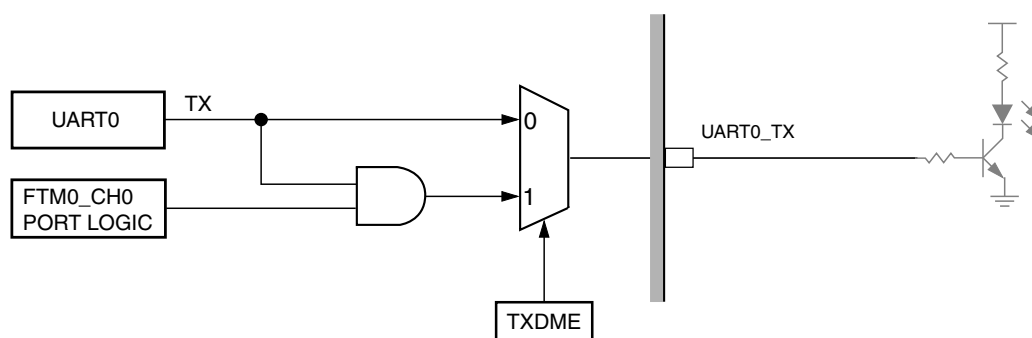


Figure 3-5. IR modulation diagram

3.2.5 UART0/1/2_RX capture

UART0_RX pin is selectable connected to UART0 module directly or tagged to FTM0 channel 1. When SIM_SOPT0[RXDCE] is set, the UART0_RX pin is connected to both UART0 and FTM0 channel 1, and the FTM0_CH1 pin is released to other shared functions regardless of the configuration of FTM0 pin reassignment. When this field is clear, the UART0_RX pin is connected to UART0 only.

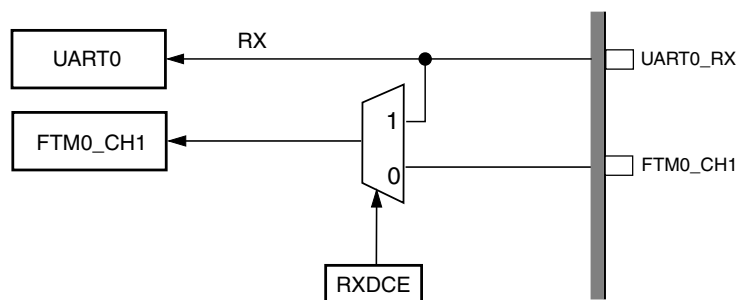


Figure 3-6. UART0_RX capture function diagram

RX signal of UART0, UART1 and UART2 can be captured by PWT. By configuring `SIM_SOPT1[UARTPWTS]`, `UART0_RX`, `UART1_RX` or `UART2_RX` can be connected to PWT input 3.

3.2.6 UART0_RX filter

When `SIM_SOPT0[RXDCE]` is clear, the `UART0_RX` pin is connected to UART0 module directly. When this field is correctly set, the `ACMP0` output can be connected to the receive channel of UART0. To enable `UART0_RX` filter function, both UART0 and `ACMP0` must be active. If this function is active, the `UART0` external `UART0_RX` pin is released to other shared functions regardless of the configuration of UART0 pin reassignment. When `UART0_RX` capture function is active, the `ACMP0` output is injected to FTM0 channel 1 as well.

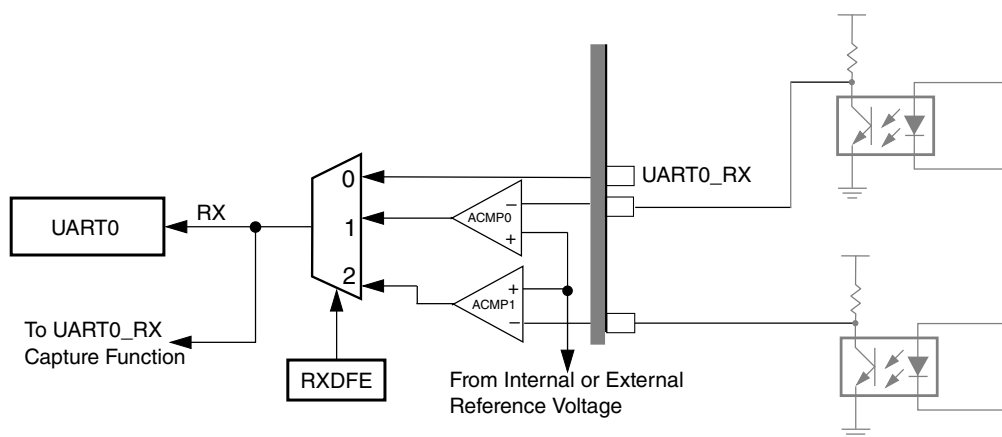


Figure 3-7. IR demodulation diagram

3.2.7 RTC capture

RTC overflow may be captured by FTM1 channel 1 by setting SIM_SOPT0[RTCC] bit. When this bit is set, the RTC overflow is connected to FTM1 channel 1 for capture, the FTM1_CH1 pin is released to other shared functions.

3.2.8 FTM2 software synchronization

FTM2 contains three synchronization input triggers, one of which is a software trigger by writing 1 to SIM_SOPT0[FTMSYNC]. Writing 0 to this field takes no effect. This field is always read 0.

3.2.9 ADC hardware trigger

ADC module may initiate a conversion via a hardware trigger. The following table shows the available ADC hardware trigger sources by setting SIM_SOPT0[ADHWT].

Table 3-3. ADC hardware trigger setting

| ADHWT | ADC hardware trigger |
|-------|--|
| 000 | RTC overflow |
| 001 | FTM0 init trigger |
| 010 | FTM2 init trigger with 8-bit programmable delay |
| 011 | FTM2 match trigger with 8-bit programmable delay |
| 100 | PIT ch0 overflow |
| 101 | PIT ch1 overflow |
| 110 | ACMP0 out |
| 111 | ACMP1 out |

When ADC hardware trigger selects the output of FTM2 triggers, an 8-bit delay block will be enabled. This logic delays any trigger from FTM2 with an 8-bit counter whose value is specified by SIM_SOPT0[DELAY]. The reference clock to this module is the bus clock with selectable predivider specified by SIM_SOPT0[BUSREF].

3.3 Core Modules

3.3.1 ARM Cortex-M0+ core configuration

This section summarizes how the module has been configured in the chip. Full documentation for this module is provided by ARM and can be found at arm.com.

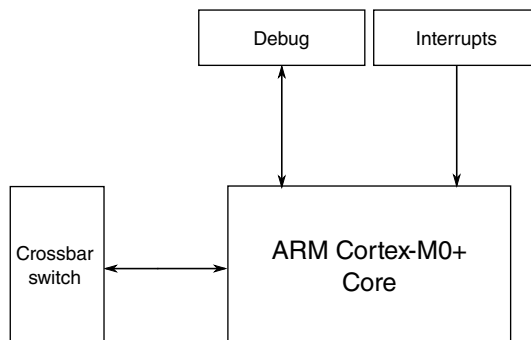


Figure 3-8. Core configuration

Table 3-4. Reference links to related information

| Topic | Related module | Reference |
|------------------------------------|---|---|
| Full description | ARM Cortex-M0+ core, r0p0 | ARM Cortex-M0+ Technical Reference Manual, r0p0 |
| System memory map | | System memory map |
| Clocking | | Clock distribution |
| Power management | | Power management |
| System/instruction/data bus module | Crossbar switch | Crossbar switch |
| Debug | Serial Wire Debug (SWD) | Debug |
| Interrupts | Nested Vectored Interrupt Controller (NVIC) | NVIC |
| | Miscellaneous Control Module (MCM) | MCM |

3.3.1.1 ARM Cortex M0+ core

The ARM Cortex M0+ parameter settings are as follows:

Table 3-5. ARM Cortex-M0+ parameter settings

| Parameter | Verilog name | Value | Description |
|------------------------------|--------------|--------------|--|
| Arch Clock Gating | ACG | 1 = Present | Implements architectural clock gating |
| DAP Slave Port Support | AHBSLV | 1 | Supports any AHB debug access port (like the CM4 DAP) |
| DAP ROM Table Base | BASEADDR | 0xF000_2003 | Base address for DAP ROM table |
| Endianness | BE | 0 | Little endian control for data transfers |
| Breakpoints | BKPT | 2 | Implements 2 breakpoints |
| Debug Support | DBG | 1 = Present | — |
| Halt Event Support | HALTEV | 1 = Present | — |
| I/O Port | IOP | 1 = Present | Implements single-cycle ld/st accesses to special addr space |
| IRQ Mask Enable | IRQDIS | 0x0 | — |
| Debug Port Protocol | JTAGnSW | 0 = SWD | SWD protocol, not JTAG |
| Core Memory Protection | MPU | 0 = Absent | No MPU |
| Number of IRQs | NUMIRQ | 32 | Assume full NVIC request vector |
| Reset all regs | RAR | 0 = Standard | Do not force all registers to be async reset |
| Multiplier | SMUL | 0 = Fast Mul | Implements single-cycle multiplier |
| Multi-drop Support | SWMD | 0 = Absent | Do not include serial wire support for multi-drop |
| System Tick Timer | SYST | 1 = Present | Implements system tick timer (for CM4 compatibility) |
| DAP Target ID | TARGETID | 0 | — |
| User/Privileged | USER | 1 = Present | Implements processor operating modes |
| Vector Table Offset Register | VTOR | 1 = Present | Implements relocation of exception vector table |
| WIC Support | WIC | 1 = Present | Implements WIC interface |
| WIC Requests | WICLINES | 34 | Exact number of wakeup IRQs is 34 |
| Watchpoints | WPT | 2 | Implements 2 watchpoints |

For details on the ARM Cortex-M0+ processor core see the ARM website: arm.com.

3.3.1.2 Buses, interconnects, and interfaces

The ARM Cortex-M0+ core has two bus interfaces:

- Single 32-bit AMBA-3 AHB-Lite system interface that provides connections to peripherals and all system memory, which includes flash and RAM.
- Single 32-bit I/O port bus (IOPORT) interfacing to the FGPIO with 1-cycle loads and stores.

3.3.1.3 System Tick Timer

The CLKSOURCE field in SysTick Control and Status register selects either the core clock (when CLKSOURCE = 1) or a divide-by-16 of the core clock (when CLKSOURCE = 0). Because the timing reference is a variable frequency, the TENMS field in the SysTick Calibration Value Register is always zero.

3.3.1.4 Core privilege levels

The core on this device is implemented with both privileged and unprivileged levels. The ARM documentation uses different terms than this document to distinguish between privilege levels.

| If you see this term... | it also means this term... |
|-------------------------|----------------------------|
| Privileged | Supervisor |
| Unprivileged or user | User |

3.3.1.5 Caches

This device does not have processor related cache memories, but the flash controller has an internal 32-byte cache for flash access.

3.3.2 Nested Vectored Interrupt Controller (NVIC) configuration

This section summarizes how the module has been configured in the chip. Full documentation for this module is provided by ARM and can be found at arm.com.

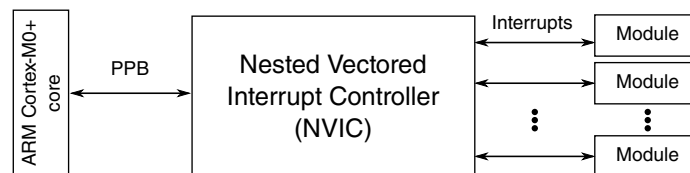


Figure 3-9. NVIC configuration

Table 3-6. Reference links to related information

| Topic | Related module | Reference |
|------------------|---|---|
| Full description | Nested Vectored Interrupt Controller (NVIC) | ARM Cortex-M0+ Technical Reference Manual |

Table continues on the next page...

Table 3-6. Reference links to related information (continued)

| Topic | Related module | Reference |
|------------------------------|---------------------|-------------------------------------|
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | | Power management |
| Private Peripheral Bus (PPB) | ARM Cortex-M0+ core | ARM Cortex-M0+ core |

3.3.2.1 Interrupt priority levels

This device supports four priority levels for interrupts. Therefore in the NVIC, each source in the IPR registers contains two bits. For example, IPR0 is shown below:

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---|-------------|----|----|----|----|----|-------------|----|----|----|----|----|-------------|----|----|----|----|----|-------------|----|----|----|---|---|---|---|---|---|---|---|---|---|
| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | IRQ3 | | | | | | IRQ2 | | | | | | IRQ1 | | | | | | IRQ0 | | | | | | | | | | | | | |
| W | 0 0 0 0 0 0 | | | | | | 0 0 0 0 0 0 | | | | | | 0 0 0 0 0 0 | | | | | | 0 0 0 0 0 0 | | | | | | | | | | | | | |

3.3.2.2 Non-maskable interrupt

The non-maskable interrupt request to the NVIC is controlled by the external $\overline{\text{NMI}}$ signal. The pin, which the $\overline{\text{NMI}}$ signal is multiplexed on, must be configured for the $\overline{\text{NMI}}$ function to generate the non-maskable interrupt request.

3.3.2.3 Interrupt channel assignments

The interrupt vector assignments are defined in the following table.

- Vector number — the value stored on the stack when an interrupt is serviced.
- IRQ number — non-core interrupt source count, which is the vector number minus 16.

The IRQ number is used within ARM's NVIC documentation.

Table 3-8. Interrupt vector assignments

| Address | Vector | IRQ ¹ | NVIC IPR register number ² | Source module | Source description |
|---------------------------------|--------|------------------|---------------------------------------|---------------|--------------------|
| ARM Core System Handler Vectors | | | | | |

Table continues on the next page...

Table 3-8. Interrupt vector assignments (continued)

| Address | Vector | IRQ ¹ | NVIC IPR register number ² | Source module | Source description |
|-------------------------|--------|------------------|---------------------------------------|-------------------|--|
| 0x0000_0000 | 0 | — | — | ARM core | Initial Stack Pointer |
| 0x0000_0004 | 1 | — | — | ARM core | Initial Program Counter |
| 0x0000_0008 | 2 | — | — | ARM core | Non-maskable Interrupt (NMI) |
| 0x0000_000C | 3 | — | — | ARM core | Hard Fault |
| 0x0000_0010 | 4 | — | — | — | — |
| 0x0000_0014 | 5 | — | — | — | — |
| 0x0000_0018 | 6 | — | — | — | — |
| 0x0000_001C | 7 | — | — | — | — |
| 0x0000_0020 | 8 | — | — | — | — |
| 0x0000_0024 | 9 | — | — | — | — |
| 0x0000_0028 | 10 | — | — | — | — |
| 0x0000_002C | 11 | — | — | ARM core | Supervisor call (SVCall) |
| 0x0000_0030 | 12 | — | — | — | — |
| 0x0000_0034 | 13 | — | — | — | — |
| 0x0000_0038 | 14 | — | — | ARM core | Pendable request for system service (PendableSrvReq) |
| 0x0000_003C | 15 | — | — | ARM core | System tick timer (SysTick) |
| Non-Core Vectors | | | | | |
| 0x0000_0040 | 16 | 0 | 0 | — | — |
| 0x0000_0044 | 17 | 1 | 0 | — | — |
| 0x0000_0048 | 18 | 2 | 0 | — | — |
| 0x0000_004C | 19 | 3 | 0 | — | — |
| 0x0000_0050 | 20 | 4 | 1 | — | — |
| 0x0000_0054 | 21 | 5 | 1 | FTMRE | Command complete |
| 0x0000_0058 | 22 | 6 | 1 | PMC | Low-voltage warning |
| 0x0000_005C | 23 | 7 | 1 | IRQ | External interrupt |
| 0x0000_0060 | 24 | 8 | 2 | I ² C0 | Single interrupt vector for all sources |
| 0x0000_0064 | 25 | 9 | 2 | I ² C1 | Single interrupt vector for all sources |
| 0x0000_0068 | 26 | 10 | 2 | SPI0 | Single interrupt vector for all sources |
| 0x0000_006C | 27 | 11 | 2 | SPI1 | Single interrupt vector for all sources |
| 0x0000_0070 | 28 | 12 | 3 | UART0 | Status and error |
| 0x0000_0074 | 29 | 13 | 3 | UART1 | Status and error |
| 0x0000_0078 | 30 | 14 | 3 | UART2 | Status and error |
| 0x0000_007C | 31 | 15 | 3 | ADC0 | ADC conversion complete interrupt |
| 0x0000_0080 | 32 | 16 | 4 | ACMP0 | Analog comparator 0 interrupt |
| 0x0000_0084 | 33 | 17 | 4 | FTM0 | Single interrupt vector for all sources |
| 0x0000_0088 | 34 | 18 | 4 | FTM1 | Single interrupt vector for all sources |
| 0x0000_008C | 35 | 19 | 4 | FTM2 | Single interrupt vector for all sources |

Table continues on the next page...

Table 3-8. Interrupt vector assignments (continued)

| Address | Vector | IRQ ¹ | NVIC IPR register number ² | Source module | Source description |
|-------------|--------|------------------|---------------------------------------|---------------|---|
| 0x0000_0090 | 36 | 20 | 5 | RTC | RTC overflow |
| 0x0000_0094 | 37 | 21 | 5 | ACMP1 | Analog comparator 1 interrupt |
| 0x0000_0098 | 38 | 22 | 5 | PIT_CH0 | PIT CH0 overflow |
| 0x0000_009C | 39 | 23 | 5 | PIT_CH1 | PIT CH1 overflow |
| 0x0000_00A0 | 40 | 24 | 6 | KBI0(32bit) | Keyboard interrupt0(32bit) |
| 0x0000_00A4 | 41 | 25 | 6 | KBI1(32bit) | Keyboard interrupt1(32bit) |
| 0x0000_00A8 | 42 | 26 | 6 | — | |
| 0x0000_00AC | 43 | 27 | 6 | ICS | Clock loss of lock |
| 0x0000_00B0 | 44 | 28 | 7 | WDOG | Watchdog timeout |
| 0x0000_00B4 | 45 | 29 | 7 | PWT | Single interrupt vector for all sources |
| 0x0000_00B8 | 46 | 30 | 7 | MSCAN | MSCAN Rx Interrupt |
| 0x0000_00BC | 47 | 31 | 7 | MSCAN | MSCAN Tx, Err and Wake-up interrupt |

1. Indicates the NVIC's interrupt source number.

2. Indicates the NVIC's IPR register number used for this IRQ. The equation to calculate this value is: $\text{IRQ} \div 4$

3.3.2.3.1 Determining the field and register location for configuring a particular interrupt

Suppose you need to configure the SPI0 interrupt. The following table is an excerpt of the SPI0 row from [Interrupt priority levels](#).

Table 3-9. Interrupt vector assignments

| Address | Vector | IRQ ¹ | NVIC IPR register number ² | Source module | Source description |
|-------------|--------|------------------|---------------------------------------|---------------|---|
| 0x0000_0068 | 26 | 10 | 2 | SPI0 | Single interrupt vector for all sources |

1. Indicates the NVIC's interrupt source number.

2. Indicates the NVIC's IPR register number used for this IRQ. The equation to calculate this value is: $\text{IRQ} \div 4$.

- The NVIC registers you would use to configure the interrupt are:
 - NVICIPR2
- To determine the particular IRQ's field location within these particular registers:
 - NVICIPR2 field starting location = $8 * (\text{IRQ} \bmod 4) + 6 = 22$

Since the NVICIPR fields are 2-bit wide (4 priority levels), the NVICIPR2 field range is bits 22–23.

Therefore, the field locations NVICIPR2[23:22] are used to configure the SPI0 interrupts.

3.3.3 Asynchronous wakeup interrupt controller (AWIC) configuration

This section summarizes how the module has been configured in the chip. Full documentation for this module is provided by ARM and can be found at arm.com.

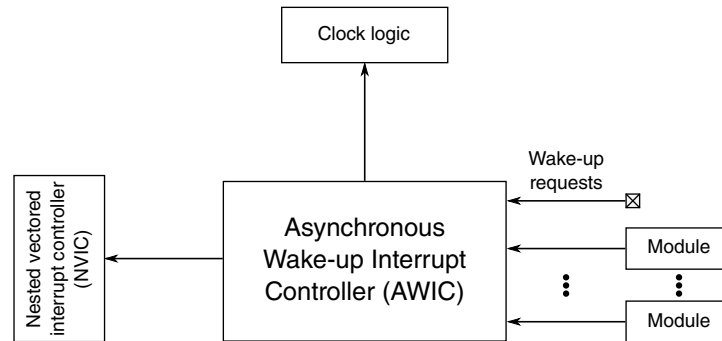


Figure 3-10. Asynchronous wake-up interrupt controller configuration

Table 3-10. Reference links to related information

| Topic | Related module | Reference |
|-------------------|---|--------------------------------------|
| System memory map | | System memory map |
| Clocking | | Clock distribution |
| Power management | | Power management |
| Interrupt control | Nested vectored interrupt controller (NVIC) | NVIC |
| Wake-up requests | | AWIC wake-up sources |

3.3.3.1 Wakeup sources

The device uses the following internal and external inputs to the AWIC module.

Table 3-11. AWIC stop wakeup sources

| Wake-up source | Description |
|-------------------------|--|
| Available system resets | RESET pin when LPO is its clock source |
| Low-voltage warning | Power management controller |
| IRQ | IRQ pin |
| Pin interrupts | KBI - Any enabled pin interrupt is capable of waking the system. |
| ADC | The ADC is functional in Stop mode when using internal clock source. |

Table continues on the next page...

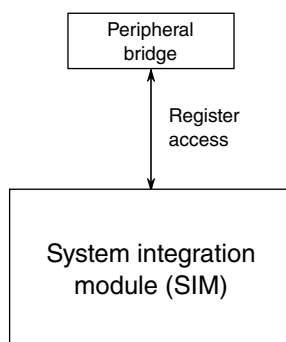
Table 3-11. AWIC stop wakeup sources (continued)

| Wake-up source | Description |
|------------------------|--|
| ACMP | Interrupt in normal |
| I ² C | Address match wake-up |
| SPI | SPI slave mode interrupt |
| UART | UART active edge detect at UART_RX pin |
| RTC | Alarm interrupt |
| Non-maskable interrupt | NMI pin |
| MSCAN | MSCAN wake-up interrupt |

3.4 System Modules

3.4.1 SIM configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

**Figure 3-11. SIM configuration****Table 3-12. Reference links to related information**

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | SIM | SIM |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |

3.4.2 PMC configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

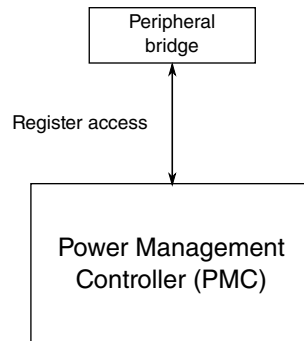


Figure 3-12. PMC configuration

Table 3-13. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | PMC | PMC |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |

3.4.3 MCM configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

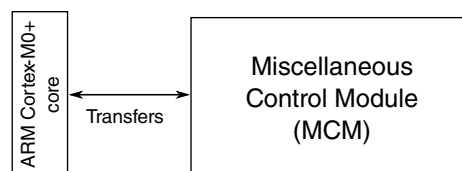


Figure 3-13. MCM configuration

Table 3-14. Reference links to related information

| Topic | Related module | Reference |
|------------------|------------------------------------|---------------------|
| Full description | Miscellaneous Control module (MCM) | MCM |

Table continues on the next page...

Table 3-14. Reference links to related information (continued)

| Topic | Related module | Reference |
|------------------------------|-------------------------|---|
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |
| Private Peripheral Bus (PPB) | ARM Cortex-M0+ core | ARM Cortex-M0+ core |
| Transfer | Flash memory controller | Flash memory controller |

3.4.4 Crossbar-light switch configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module’s dedicated chapter.

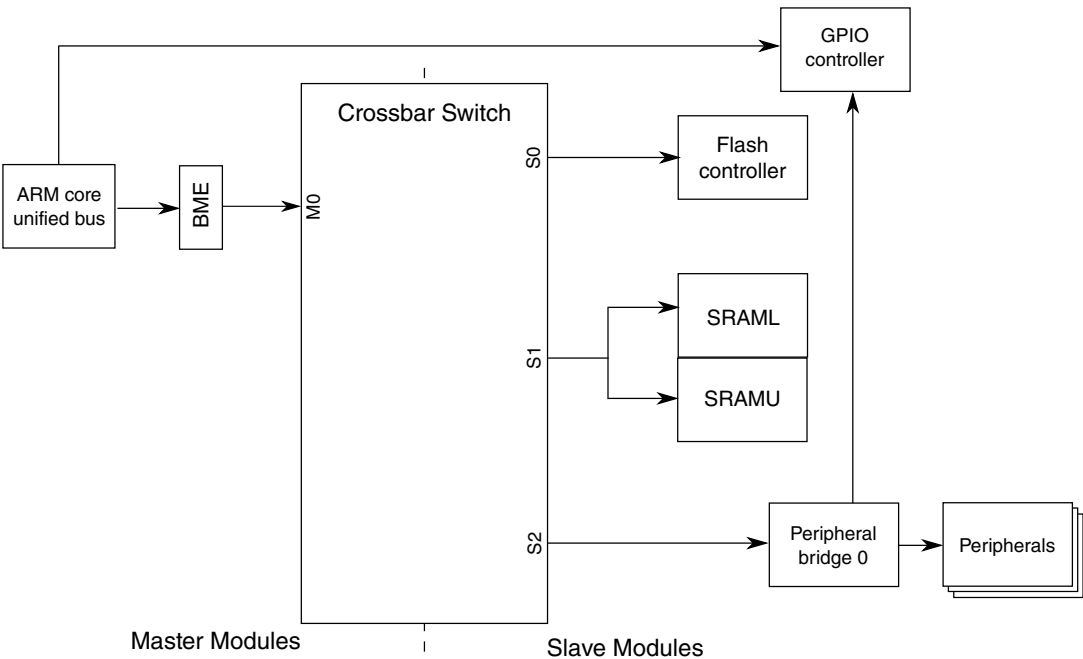


Figure 3-14. Crossbar-Light switch integration

Table 3-15. Reference links to related information

| Topic | Related module | Reference |
|------------------------|---------------------|-------------------------------------|
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Crossbar switch master | ARM Cortex-M0+ core | ARM Cortex-M0+ core |

Table continues on the next page...

Table 3-15. Reference links to related information (continued)

| Topic | Related module | Reference |
|-----------------------|-------------------------|---|
| Crossbar switch slave | Flash memory controller | Flash memory controller |
| Crossbar switch slave | SRAM controller | SRAM configuration |
| Crossbar switch slave | Peripheral bridge | Peripheral bridge |
| 2-ported peripheral | GPIO controller | GPIO controller |

3.4.4.1 Crossbar-Light switch master assignments

The masters connected to the crossbar switch are assigned as follows:

| Master module | Master port number |
|----------------------|--------------------|
| ARM core unified bus | 0 |

3.4.4.2 Crossbar switch slave assignments

This device contains 3 slaves connected to the crossbar switch.

The slave assignment is as follows:

| Slave module | Slave port number |
|-------------------------|-------------------|
| Flash memory controller | 0 |
| SRAM controller | 1 |
| Peripheral bridge | 2 |

3.4.5 Peripheral bridge configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

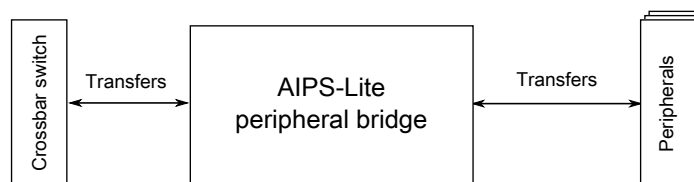


Figure 3-15. Peripheral bridge configuration

Table 3-16. Reference links to related information

| Topic | Related module | Reference |
|-------------------|-------------------------------|---|
| Full description | Peripheral bridge (AIPS-Lite) | Peripheral bridge (AIPS-Lite) |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |

3.4.5.1 Number of peripheral bridges

This device contains one peripheral bridge.

3.4.5.2 Memory maps

The peripheral bridges are used to access the registers of most of the modules on this device. See [AIPS-Lite Memory Map](#) for the memory slot assignment for each module.

3.5 System Security

3.5.1 CRC configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

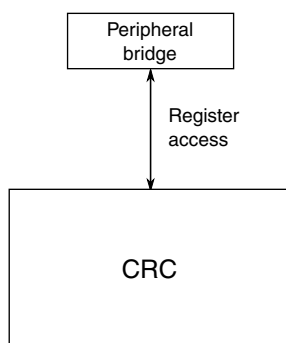


Figure 3-16. CRC configuration

Table 3-17. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|-----------------------------------|
| Full description | CRC | CRC |
| System memory map | — | System memory map |
| Power management | — | Power management |

3.5.2 Watchdog configuration

This section summarizes how the module has been configured in the chip.

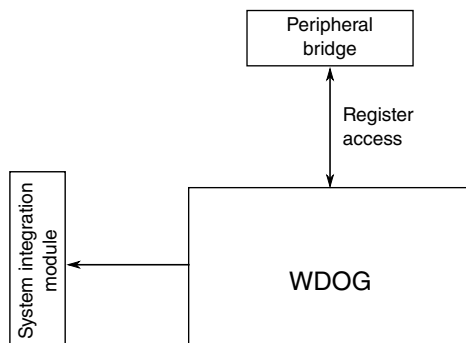


Figure 3-17. Watchdog configuration

Table 3-18. Reference links to related information

| Topic | Related module | Reference |
|-------------------|---------------------------------|------------------------------------|
| Full description | Watchdog (WDOG) | Watchdog (WDOG) |
| Clocking | — | Clock distribution |
| Power management | — | Power management |
| Programming model | System Integration Module (SIM) | SIM |

3.5.2.1 WDOG clocks

The watchdog has four selectable clock sources:

- 1 kHz internal low power oscillator (LPOCLK)
- Internal 32 kHz reference clock (ICSIRCLK)
- External clock (OSCERCLK)
- Bus clock

3.5.2.2 WDOG operation

The WDOG module provides a fail-safe mechanism to ensure the system can be reset to a known state of operation in case of system failure, such as the CPU clock stopping or there being a run away condition in the software code. The watchdog counter runs continuously off a selectable clock source and expects to be serviced (refreshed) periodically. If it is not, it resets the system.

After any reset, the WDOG watchdog is enabled. If the WDOG watchdog is not used in an application, it can be disabled by clearing WDOG_CS1[EN].

The refresh write sequence is a write of 0xA602 followed by a write of 0xB480 to the WDOG_CNTH:L registers. The write of the 0xB480 must occur within 16 bus clocks after the write of 0xA602; otherwise, the watchdog resets the MCU.

The watchdog counter has four clock source options selected by programming WDOG_CS2[CLK]. The clock source options are the bus clock, internal 1 kHz clock, external clock, or an internal 32 kHz clock source.

The refresh timeout time is defined by WDOG_TOVALH:L. In addition, if window mode is used, software must not start the refresh sequence until after the time value set in the WDOG_WINH:L registers.

An optional fixed prescaler for all clock sources allows for longer timeout periods. When WDOG_CS2[PRES] is set, the clock source is prescaled by 256 before clocking the watchdog counter.

The watchdog counter registers CNTH:L provide access to the value of the free-running watchdog counter. The software can read the counter registers at any time but cannot write directly to the watchdog counter. The refresh sequence resets the watchdog counter to 0x0000. Write to the WDOG_CNTH:L registers of 0xC520 followed by 0xD928 within 16 bus clocks start the unlock sequence. On completing the unlock sequence, the user must reconfigure the watchdog within 128 bus clocks; otherwise, the watchdog forces a reset to the MCU.

By default, the watchdog is not functional in Debug mode, Wait mode, or Stop mode. Setting WDOG_CS1[DBG], WDOG_CS1[WAIT] or WDOG_CS1[STOP] can activate the watchdog in Debug, Wait or Stop modes.

3.6 Clock Modules

3.6.1 ICS configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

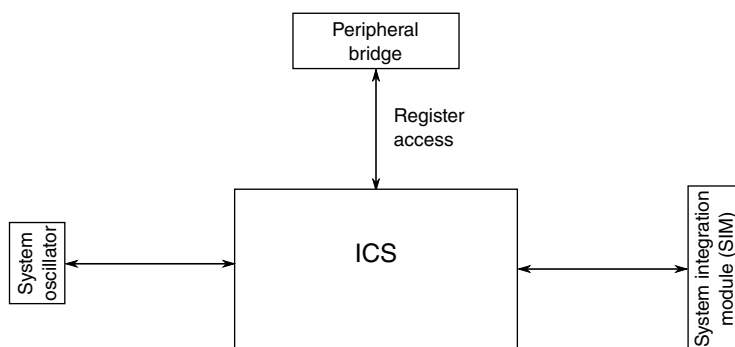


Figure 3-18. ICS configuration

Table 3-19. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | ICS | ICS |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |

3.6.1.1 Clock gating

This family of devices includes clock gating control for each peripheral, that is, the clock to each peripheral can explicitly be gated on or off, using clock-gate control bits in the SIM_SCGC register.

3.6.2 OSC configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module’s dedicated chapter.

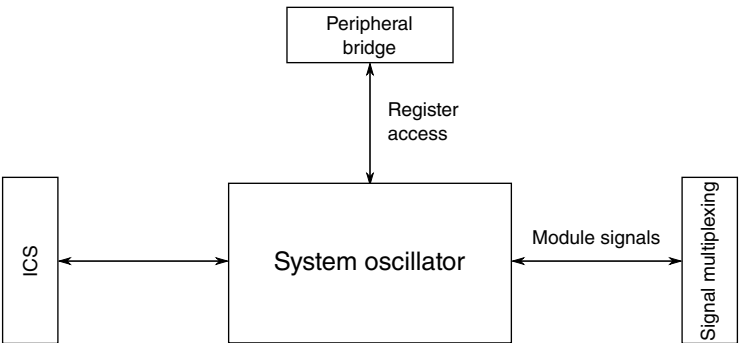


Figure 3-19. OSC configuration

Table 3-20. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | OSC | OSC |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |
| Full description | ICS | ICS |

3.7 Memories and Memory Interfaces

3.7.1 Flash memory configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module’s dedicated chapter.

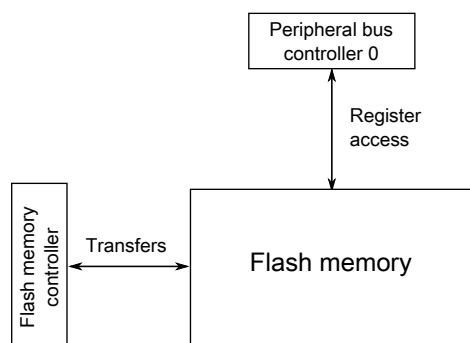


Figure 3-20. Flash memory configuration

Table 3-21. Reference links to related information

| Topic | Related module | Reference |
|-------------------|-------------------------|---|
| Full description | Flash memory | Flash memory |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Transfers | Flash memory controller | Flash memory controller |
| Register access | Peripheral bridge | Peripheral bridge |

3.7.1.1 Flash memory sizes

The amounts of flash memory for the devices covered in this document are:

Table 3-22. KEA128 flash memory size

| Device | Flash (KB) | Block 0 (flash) address range |
|------------------|------------|-------------------------------|
| S9KEAZ64AMLK(R) | 64 | 0x0000_0000 – 0x0000_FFFF |
| S9KEAZ128AMLK(R) | 128 | 0x0000_0000 – 0x0001_FFFF |
| S9KEAZ64AVLK(R) | 64 | 0x0000_0000 – 0x0000_FFFF |
| S9KEAZ128AVLK(R) | 128 | 0x0000_0000 – 0x0001_FFFF |
| S9KEAZ64ACLK(R) | 64 | 0x0000_0000 – 0x0000_FFFF |
| S9KEAZ128ACLK(R) | 128 | 0x0000_0000 – 0x0001_FFFF |
| S9KEAZ64AMLH(R) | 64 | 0x0000_0000 – 0x0000_FFFF |
| S9KEAZ128AMLH(R) | 128 | 0x0000_0000 – 0x0001_FFFF |
| S9KEAZ64AVLH(R) | 64 | 0x0000_0000 – 0x0000_FFFF |
| S9KEAZ128AVLH(R) | 128 | 0x0000_0000 – 0x0001_FFFF |
| S9KEAZ64ACLH(R) | 64 | 0x0000_0000 – 0x0000_FFFF |
| S9KEAZ128ACLH(R) | 128 | 0x0000_0000 – 0x0001_FFFF |

3.7.1.2 Flash memory map

The flash memory and the flash registers are located at different base addresses as shown in the figure found here.

The base address for each is specified in [System memory map](#).

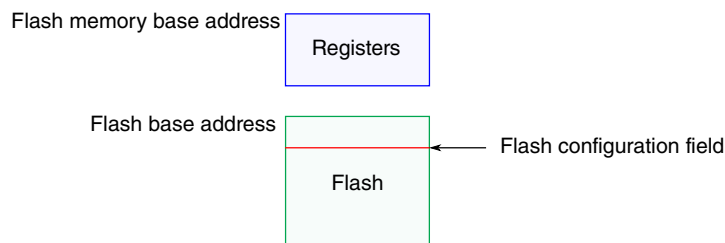


Figure 3-21. Flash memory map

The on-chip flash memory is implemented in a portion of the allocated Flash range to form a contiguous block in the memory map beginning at address 0x0000_0000. See [Flash memory sizes](#) for details of supported ranges.

Access to the flash memory ranges outside the amount of flash on the device causes the bus cycle to be terminated with an error followed by the appropriate response in the requesting bus master.

3.7.1.3 Alternate Non-Volatile IRC User Trim Description

The non-volatile locations (2 bytes) shown in [Table 3-23](#) are reserved for a custom ICS internal reference clock (IRC) trim value supported by some development and programming tools. An alternate IRC trim to the factory loaded trim value can be stored at these locations. To override the factory trim, user software must copy the custom trim values in these locations into the ICS trim fields in ICS_C3 and ICS_C4.

Table 3-23. Alternate non-volatile IRC trim

| Non-Volatile Byte Address | Alternate IRC Trim Value |
|---------------------------|--------------------------|
| 0x0000_03FE (bit 0) | SCFTRIM |
| 0x0000_03FF | SCTRIM |

3.7.1.4 Flash security

For information on how flash security is implemented on this device, see [Chip Security](#).

3.7.1.5 Erase all flash contents

In addition to software, the entire flash memory may be erased external to the flash memory via the SW-DP debug port by setting MDM-AP CONTROL[0] (bit 0 of the MDM-AP Control register). MDM-AP STATUS[0] (bit 0 of the MDM-AP Status register) is set to indicate the mass erase command has been accepted. MDM-AP CONTROL[0] is cleared when the mass erase completes.

3.7.2 Flash memory controller configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

See [Platform Control Register \(MCM_PLACR\)](#) register description for details on the reset configuration of the FMC.

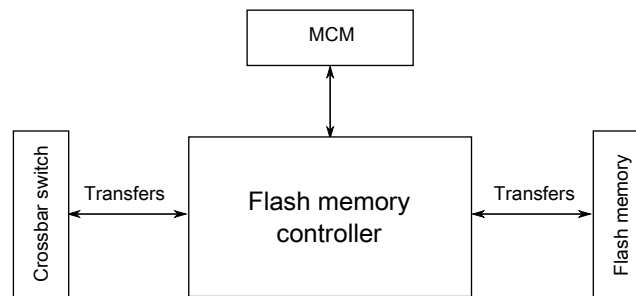


Figure 3-22. Flash memory controller configuration

Table 3-24. Reference links to related information

| Topic | Related module | Reference |
|-------------------|-------------------------|---|
| Full description | Flash memory controller | Flash memory controller |
| System memory map | | System memory map |
| Clocking | | Clock Distribution |
| Transfers | Flash memory | Flash memory |
| Transfers | Crossbar switch | Crossbar Switch |
| Register access | MCM | MCM |

3.7.3 SRAM configuration

This section summarizes how the module has been configured in the chip.

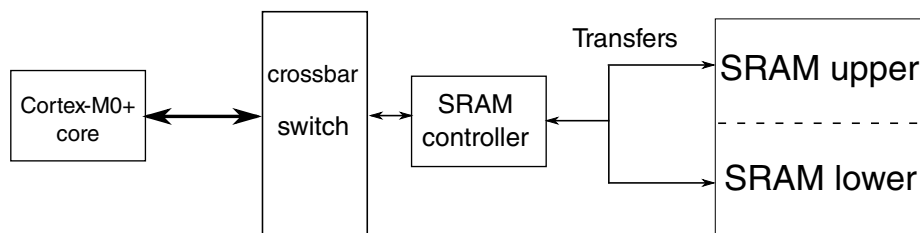


Figure 3-23. SRAM configuration

Table 3-25. Reference links to related information

| Topic | Related module | Reference |
|---------------------|----------------|-------------------------------------|
| Full description | SRAM | SRAM |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| ARM Cortex-M0+ core | — | ARM Cortex-M0+ core |

3.7.3.1 SRAM sizes

The SRAM supports single cycle access (zero wait states) at all core speeds.

The amounts of SRAM for the devices covered in this document are:

Table 3-26. SRAM size

| Freescall part number | SRAM |
|-----------------------|-------|
| S9KEAZ64AMLH(R) | 8 KB |
| S9KEAZ128AMLH(R) | 16 KB |
| S9KEAZ64AMLK(R) | 8 KB |
| S9KEAZ128AMLK(R) | 16 KB |
| S9KEAZ64AVLK(R) | 8 KB |
| S9KEAZ128AVLK(R) | 16 KB |
| S9KEAZ64ACLK(R) | 8 KB |
| S9KEAZ128ACLK(R) | 16 KB |
| S9KEAZ64AVLH(R) | 8 KB |
| S9KEAZ128AVLH(R) | 16 KB |
| S9KEAZ64ACLH(R) | 8 KB |
| S9KEAZ128ACLH(R) | 16 KB |

3.7.3.2 SRAM ranges

The on-chip SRAM is split into two ranges; 1/4 is allocated to SRAM_L and 3/4 is allocated to SRAM_U.

The on-chip RAM is implemented such that the SRAM_L and SRAM_U ranges form a contiguous block in the memory map. As such:

- SRAM_L is anchored to 0x1FFF_FFFF and occupies the space before this ending address.
- SRAM_U is anchored to 0x2000_0000 and occupies the space after this beginning address.

Valid address ranges for SRAM_L and SRAM_U are then defined as:

- SRAM_L = [0x2000_0000 – (SRAM_size/4)] to 0x1FFF_FFFF
- SRAM_U = 0x2000_0000 to [0x2000_0000 + (SRAM_size*(3/4)) - 1]

This is illustrated in the following figure.

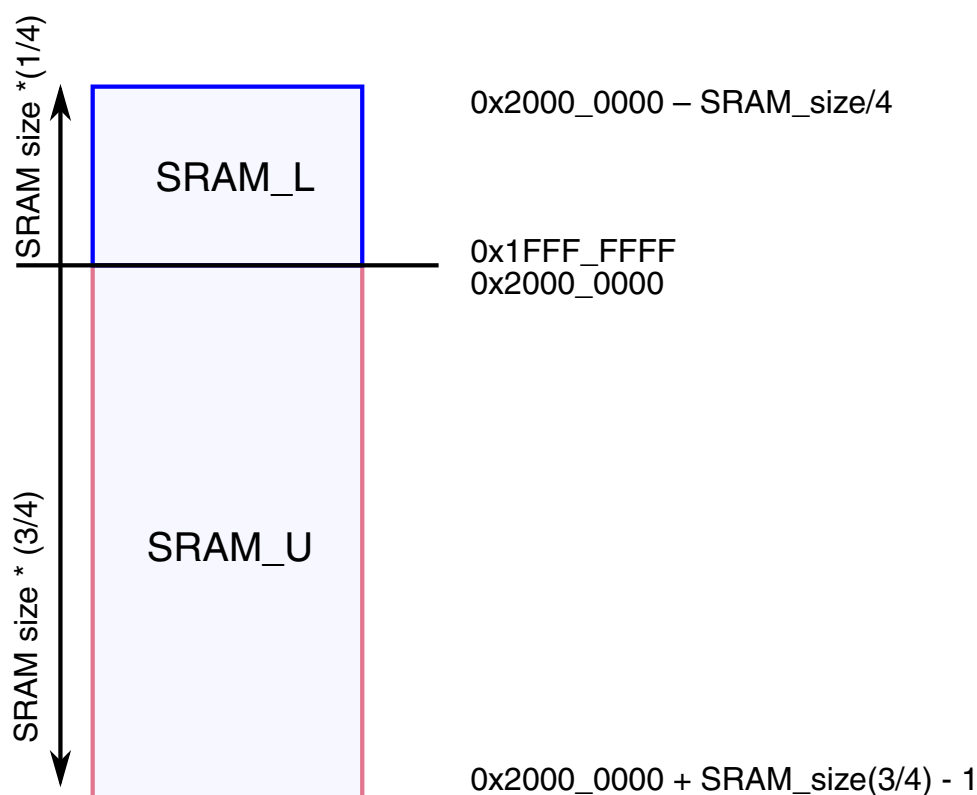


Figure 3-24. SRAM blocks memory map

For example, for a device containing 16 KB of SRAM, the ranges are:

- SRAM_L: 0x1FFF_F000 – 0x1FFF_FFFF
- SRAM_U: 0x2000_0000 – 0x2000_2FFF

3.7.3.3 SRAM bit operation

The on-chip SRAM is split to two range: SRAM_L and SRAM_U. The SRAM_U range supports bit operation on this device through two ways:

- Aliased bit-band region
- Bit Manipulation Engine (BME)

A 32-bit write in the aliased region has the same effect as a read-modify-write operation on the targeted bit in the SRAM_U region. See [Aliased bit-band region](#) for details.

The aliased bit-band region only supports simple set or clear operation. More complicated bit operations (AND, OR, XOR, etc) could be further supported through the BME engine. See [Bit Manipulation Engine](#) for details.

3.8 Analog

3.8.1 12-bit analog-to-digital converter (ADC) configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

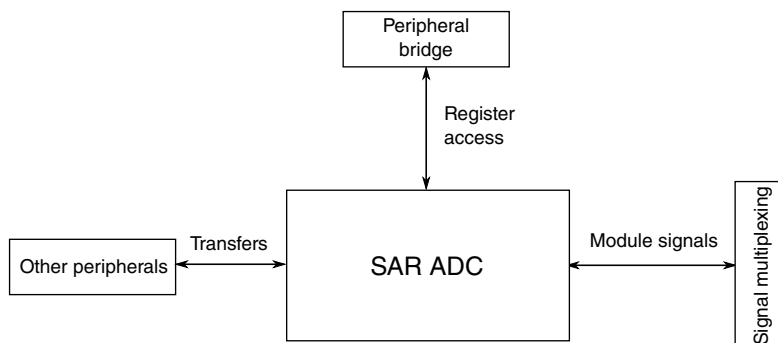


Figure 3-25. 12-bit SAR ADC configuration

Table 3-27. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | 12-bit SAR ADC | 12-bit SAR ADC |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |

3.8.1.1 ADC instantiation information

This device contains one 12-bit successive approximation ADC with up to 16 channels.

Table 3-28. ADC channels

| Freescal part number | ADC channels |
|----------------------|--------------|
| S9KEAZ64AMLH(R) | 16 |
| S9KEAZ128AMLH(R) | 16 |
| S9KEAZ64AMLK(R) | 16 |
| S9KEAZ128AMLK(R) | 16 |
| S9KEAZ64AVLK(R) | 16 |
| S9KEAZ128AVLK(R) | 16 |
| S9KEAZ64ACLK(R) | 16 |
| S9KEAZ128ACLK(R) | 16 |
| S9KEAZ64AVLH(R) | 16 |
| S9KEAZ128AVLH(R) | 16 |
| S9KEAZ64ACLH(R) | 16 |
| S9KEAZ128ACLH(R) | 16 |

The ADC supports both software and hardware triggers. The ADC hardware trigger, ADHWT, is selectable from ACMP0, ACMP1, FTM0 init trigger, FTM2 init trigger, FTM2 match trigger, RTC overflow, or PITCH0/1 overflow. The hardware trigger can be configured to cause a hardware trigger in MCU Run, Wait, and Stop modes.

The hardware trigger sources details are listed in the [Module-to-Module section](#).

3.8.1.2 ADC0 connections/channel assignment

The ADC channel assignments for the device are shown in following table. Reserved channels convert to an unknown value.

Table 3-29. ADC channel assignment

| ADCH | Channel | Input |
|-------|---------|-----------|
| 00000 | AD0 | PTA0/ADP0 |
| 00001 | AD1 | PTA1/ADP1 |
| 00010 | AD2 | PTA6/ADP2 |
| 00011 | AD3 | PTA7/ADP3 |
| 00100 | AD4 | PTB0/ADP4 |
| 00101 | AD5 | PTB1/ADP5 |

Table continues on the next page...

Table 3-29. ADC channel assignment (continued)

| ADCH | Channel | Input |
|-------|-----------------|--------------------|
| 00110 | AD6 | PTB2/ADP6 |
| 00111 | AD7 | PTB3/ADP7 |
| 01000 | AD8 | PTC0/ADP8 |
| 01001 | AD9 | PTC1/ADP9 |
| 01010 | AD10 | PTC2/ADP10 |
| 01011 | AD11 | PTC3/ADP11 |
| 01100 | AD12 | PTF4/ADP12 |
| 01101 | AD13 | PTF5/ADP13 |
| 01110 | AD14 | PTF6/ADP14 |
| 01111 | AD15 | PTF7/ADP15 |
| 10000 | AD16 | Vss |
| 10001 | AD17 | Vss |
| 10010 | AD18 | Vss |
| 10011 | AD19 | Vss |
| 10100 | AD20 | Reserved |
| 10101 | AD21 | Reserved |
| 10110 | AD22 | Temperature Sensor |
| 10111 | AD23 | Bandgap |
| 11000 | AD24 | Reserved |
| 11001 | AD25 | Reserved |
| 11010 | AD26 | Reserved |
| 11011 | AD27 | Reserved |
| 11100 | AD28 | Reserved |
| 11101 | AD29 | VREFH |
| 11110 | AD30 | VREFL |
| 11111 | Module disabled | None |

3.8.1.3 ADC analog supply and reference connections

This device includes dedicated VDDA, VSSA, VREFH and VREFL pins on 80LQFP package. The dedicated VREFL pin is available on on 64QFP\LQFP package and LQFP44 package, while the VREFH pin is internally connected to VDDA .

3.8.1.4 Temperature sensor and bandgap

The ADC module integrates an on-chip temperature sensor. Following actions must be performed to use this temperature sensor.

- Configure ADC for long sample with a maximum of 1 MHz clock
- Convert the bandgap voltage reference channel (AD23)
 - By converting the digital value of the bandgap voltage reference channel using the value of V_{BG} , the user can determine V_{DD} .
- Convert the temperature sensor channel (AD22)
 - By using the calculated value of V_{DD} , convert the digital value of AD22 into a voltage, V_{TEMP}

3.8.1.5 Alternate clock

The ADC module is capable of performing conversions using the MCU bus clock, the bus clock divided by 2, the local asynchronous clock (ADACK) within the module, or the alternate clock, ALTCLK. The alternate clock for the devices is the external oscillator output (OSC_OUT).

The selected clock source must run at a frequency such that the ADC conversion clock (ADCK) runs at a frequency within its specified range (f_{ADCK}) after being divided down from the ALTCLK input as determined by ADC_SC3[ADIV].

ALTCLK is active while the MCU is in Wait mode provided the conditions described above are met. This allows ALTCLK to be used as the conversion clock source for the ADC while the MCU is in Wait mode.

ALTCLK cannot be used as the ADC conversion clock source while the MCU is in Stop mode.

3.8.2 ACMP configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

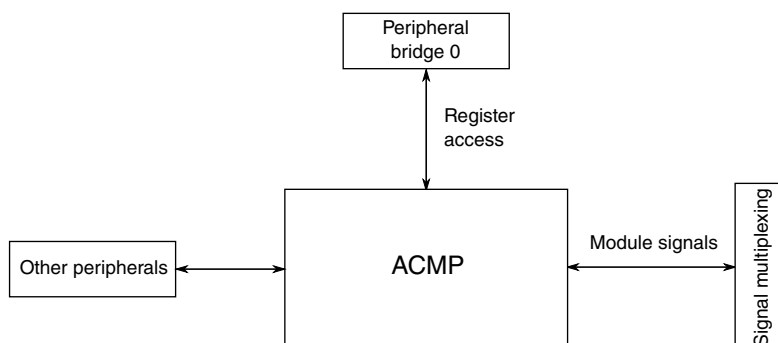


Figure 3-26. ACMP configuration

Table 3-30. Reference links to related information

| Topic | Related module | Reference |
|-------------------|--------------------------|------------------------------------|
| Full description | Analog comparator (ACMP) | Comparator |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |

3.8.2.1 ACMP overview

The device contains two analog comparator modules (ACMP) which provide a circuit for comparing two analog input voltages or for comparing one analog input voltage to an internal reference voltage. The comparator circuit is used to operate across the full range of the supply voltage (rail-to-rail operation).

The ACMP features four different inputs muxed with both positive and negative inputs to the ACMP. One is fixed connected to built-in DAC output, the others are externally mapped on pinouts.

The ACMP modules support internal bandgap reference voltage. When using the bandgap reference, the user must enable the PMC bandgap buffer first.

The ACMP modules can continue to operate in Wait and Stop mode if enabled, and can wake the MCU when a compare event occurs.

3.8.2.2 ACMP interconnections

The ACMP0 output can be configured to connect with FTM1 input capture channel 0 by setting SIM_SOPT0[ACIC]. With ACIC field asserted, the FTM1_CH0 pin is not available externally regardless of the configuration of the FTM1 module for channel 0.

ACMP0 and ACMP1 output are also internal connected to FTM2 trigger input and Fault input. By configuring SIM_SOPT0[ACTRG] user can connect either ACMP0_OUT or ACMP1_OUT to FTM2 trigger input 0. ACMP0_OUT is connected to FTM2 fault input 0 and ACMP1_OUT is connected to FTM2 fault input 3.

ACMP0 output can be directly ejected to UART0_RX by setting SIM_SOPT0[RXDCE]. In this mode, UART0_RX pinout does not work. Any external signal tagged to ACMP0 inputs can be regarded as input pins.

ACMP0 and ACMP1 output can be measured by on PWT module. By configuring SIM_SOPT1[ACPWTS] bit, use can connect ACMP0_OUT or ACMP1_OUT to PWT input 2.

The following table shows the input connections to the ACMP0 and ACMP1:

Table 3-31. ACMP0 input connections

| ACMP0 channel | Connection |
|---------------|----------------|
| 0 | PTA0/ACMP0_IN0 |
| 1 | PTA1/ACMP0_IN1 |
| 2 | PTC4/ACMP0_IN2 |
| 3 | DAC output |

Table 3-32. ACMP1 input connections

| ACMP1 channel | Connection |
|---------------|----------------|
| 0 | PTA6/ACMP1_IN0 |
| 1 | PTA7/ACMP1_IN1 |
| 2 | PTB4/ACMP1_IN2 |
| 3 | DAC output |

3.8.2.3 ACMP in Stop mode

ACMP continues to operate in Stop mode if enabled. If ACMPx_SC[ACOPE] is enabled, comparator output will operate as in the normal operating mode and will control ACMPx_OUT pin. The MCU is brought out of Stop mode when a compare event occurs and ACMPx_CS[ACIE] is enabled; ACMPx_CS[ACF] flag sets accordingly.

3.9 Timers

3.9.1 FlexTimer configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

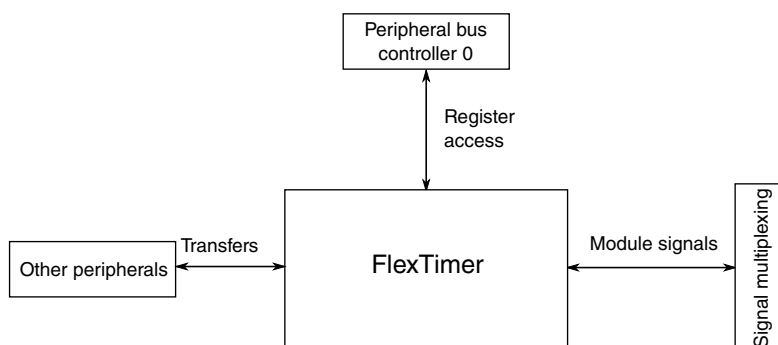


Figure 3-27. FlexTimer configuration

Table 3-33. Reference links to related information

| Topic | Related module | Reference |
|---------------------|----------------|-------------------------------------|
| Full description | FlexTimer | FlexTimer |
| System memory map | — | System memory map |
| Clocking | — | Clock distribution |
| Power management | — | Power management |
| Signal multiplexing | Port control | Signal multiplexing |

3.9.1.1 FTM overview

The FTM timer contains up to six channels which support input capture, output compare and the generation of PWM signals to control electric motor and power management applications. FTM time reference is a 16-bit counter which can be used as an unsigned or signed counter.

This device contains up to three FTM modules of one 6-channel FTM with full functions and two 2-channel FTM with basic TPM functions. Each FTM module can use independent external clock input. The table below summarizes the configuration of FTM modules.

Table 3-34. FTM modules features

| Feature | FTM0/FTM1 | FTM2 |
|--------------------------------------|---|--|
| Number of channels | 2 | 6 |
| Initial counting value | no | yes |
| Periodic TOF | no | yes |
| Input capture mode | yes | yes |
| Channel input filter | no | channels 0, 1, 2 and 3 |
| Output compare mode | yes | yes |
| Edge-Aligned PWM (EPWM) | yes | yes |
| Center-Aligned PWM (CPWM) | yes | yes |
| Combine mode | no | yes |
| Complementary mode | no | yes |
| PWM synchronization | no | yes |
| Inverting | no | yes |
| Software output control (SWOC) | no | yes |
| Deadtime insertion | no | yes |
| Output mask | no | yes |
| Fault control | no | yes |
| Number of fault inputs | 0 | 4 |
| Fault input filter | no | fault inputs 0, 1, 2 and 3 |
| Polarity control | no | yes |
| Initialization | no | yes |
| Channel match trigger | no | yes |
| Initialization trigger | yes | yes |
| Capture test mode | no | yes |
| DMA | no | no |
| Dual edge capture mode | no | yes |
| Quadrature decoder mode | no | no |
| Quadrature decoder input filter | no | no |
| Debug modes | no | yes |
| Intermediary load | no | yes |
| Global time base enable ¹ | no | yes |
| Registers available | FTM_SC, FTM_CNT, FTM_MOD, FTM_C0SC, FTM_C0V, FTM_C1SC, and FTM_C1V, FTM_EXTTRIG | FTM_SC, FTM_CNT, FTM_MOD, FTM_C0SC, FTM_C0V, FTM_C1SC, and FTM_C1V, FTM_C2SC, FTM_C2V, FTM_C3SC, FTM_C3V, FTM_C4SC, FTM_C4V, FTM_C5SC, FTM_C5V, FTM_CNTIN, FTM_STATUS, FTM_MODE, FTM_SYNC, FTM_OUTINIT, FTM_OUTMASK, FTM_COMBINE, FTM_DEADTIME, FTM_EXTTRIG, FTM_POL, FTM_FMS, FTM_FILTER, FTM_FLTCTRL, FTM_CONF, FTM_FLTPOL, FTM_SYNCONF, FTM_INVCTRL, FTM_SWOCTRL, and FTM_PWMLOAD |

1. The global time base (GTB) feature allows the synchronization of multiple FTM modules on a chip. It requires the GTB function supported by all the related FTM modules. On this device, only one FTM module (FTM2) supports the GTB function, so the GTB function is actually not usable.

3.9.1.2 FTM clock options

The selectable FTM source clock can be the timer clock (up to 48 MHz), the fixed frequency clock, or an external clock. The selected control source is controlled by FTMx_SC[CLKS].

- When FTMx_SC[CLKS] = 00, no clock is selected (this in effect, disables the FTM counter).
- When FTMx_SC[CLKS] = 01, the timer clock is selected.
- When FTMx_SC[CLKS] = 10, the fixed frequency clock(ICSFFCLK) is selected.
- When FTMx_SC[CLKS] = 11, the external clock is selected.

3.9.1.3 FTM interconnections

FTM0 has following interconnections:

- UART0_TX signal can be modulated by FTM0 channel 0 PWM output.
- UART0_RX signal can be tagged by FTM0 channel 1 input capture function by writing 1 to SIM_SOPT0[RXDCE].

FTM1 has following interconnections:

- ACMP0 output can be internally connected to FTM1 channel 0 capture input by writing 1 to SIM_SOPT0[ACIC].
- RTC overflow can be connected to FTM1 channel 1 capture input by writing 1 to SIM_SOPT0[RTCC].

FTM2 supports three PWM synchronization sources:

- Trigger0 is connected to the output of ACMP0 or ACMP1 by writing 0 or 1 to SIM_SOPT0[ACTRG].
- Trigger1 is connected to FTM0 channel 0 output.
- Trigger2 is a software trigger by writing 1 to SIM_SOPT0[FTMSYNC].

FTM2 supports four FTM fault sources:

- Fault 0 is connected to ACMP0 output.
- Fault1 is connected to PTA6.
- Fault 2 is connected to PTA7.
- Fault 3 is connected to ACMP1 output.

3.9.1.4 FTM interrupts

The FlexTimer has multiple sources of interrupt. However, either source can generate a single interrupt request to the interrupt controller. When an FTM interrupt occurs, read the FTM status registers to determine the exact interrupt source.

3.9.2 PIT configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

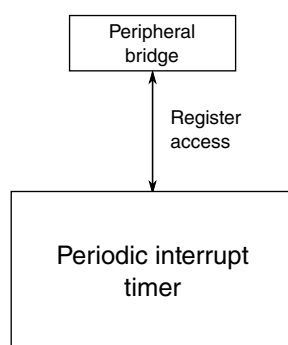


Figure 3-28. PIT configuration

Table 3-35. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | PIT | PIT |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |

3.9.2.1 PIT overview

The PIT module is an array of timers that can be used to raise interrupts and triggers.

This device contains one PIT module with two channels and supporting chained timer mode.

3.9.2.2 PIT interconnections

The PIT channel 0 and channel 1 trigger output can be used as ADC hardware trigger by setting `SIM_SOPT0[ADHWT]`.

3.9.3 RTC configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

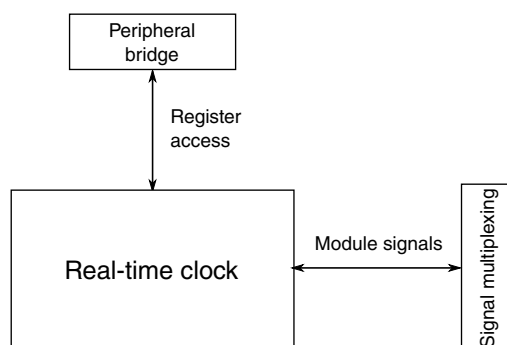


Figure 3-29. RTC configuration

Table 3-36. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | RTC | RTC |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |

3.9.3.1 RTC overview

The real-time counter (RTC) used on this device consists of one 16-bit counter, one 16-bit comparator, several binary-based and decimal-based prescaler dividers, four clock sources, and one programmable periodic interrupt. This module can be used for time-of-day, calendar or any task scheduling functions. It can also serve as a cyclic wake-up from low-power modes without external components.

3.9.3.2 RTC interconnections

Four software selectable clock sources are available for input to prescaler with selectable binary-based and decimal-based divider values

- 1 kHz internal low-power oscillator (LPOCLK)
- External clock (OSCERCLK)
- 32 kHz internal reference clock (ICSIRCLK)
- Bus clock

RTC overflow trigger can be used as hardware trigger for ADC by configuring SIM_SOPT0[ADHWT] and may also be captured by FTM1 channel1 by configuring the SIM_SOPT0[RTCC].

3.9.4 PWT configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

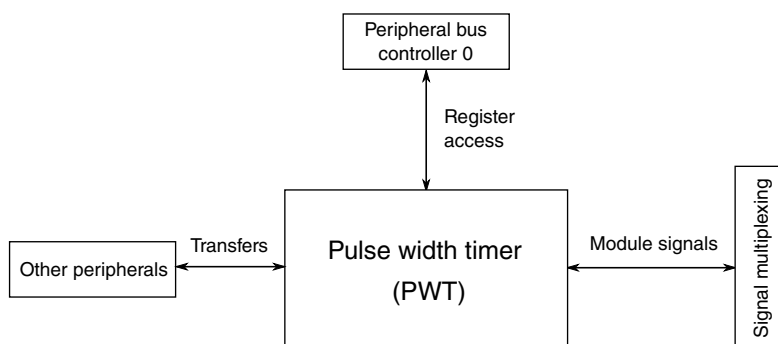


Figure 3-30. PWT configuration

Table 3-37. Reference links to related information

| Topic | Related module | Reference |
|---------------------|----------------|-------------------------------------|
| Full description | PWT | PWT |
| System memory map | | System memory map |
| Clocking | | Clock distribution |
| Power management | | Power management |
| Signal multiplexing | Port control | Signal multiplexing |

3.9.4.1 PWT overview

The Pulse Width Timer (PWT) module on this device consists of one 16-bit counter, which can be used to capture or measure the pulse width mapping on its input channels.

The counter of PWT has two selectable clocks sources, which are sharing with FTM modules, and support up to 48 MHz with internal timer clock. PWT module supports programmable positive or negative pulse edges, and programmable interrupt generation upon pulse width values or counter overflow.

3.9.4.2 PWT interconnections

Two software selectable clock sources are available for input to pre-scaler divider of PWT module:

- Timer clock : up to 48 MHz, also the option of clock source for FTM modules
- TCLK: external clock from the pads

PWT module has four input channels, which is connected as following:

Table 3-38. PWT input connections

| PWT input channel | Connection |
|-------------------|--------------------------------|
| 0 | PTD5 or PTE2 |
| 1 | PTB0 or PTH7 |
| 2 | ACMP0 output or ACMP1 output |
| 3 | UART0_RX, UART1_RX or UART2_RX |

3.10 Communication interfaces

3.10.1 SPI configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

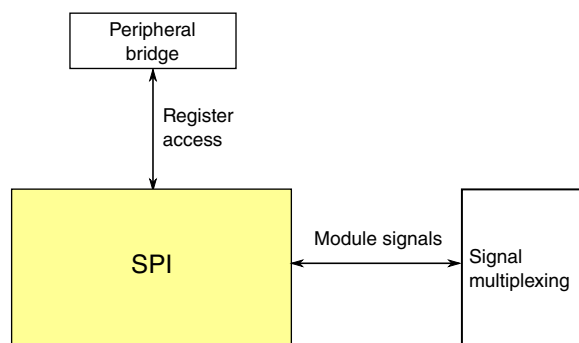


Figure 3-31. SPI configuration

Table 3-39. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | SPI | SPI |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |

3.10.1.1 SPI overview

This device contains two SPI modules that support 8-bit data length.

The serial peripheral interface (SPI) module provides for full-duplex, synchronous, serial communication between the MCU and peripheral devices. These peripheral devices can include other microcontrollers, analog-to-digital converters, shift registers, sensors, memories, etc.

The SPI runs at a baud rate up to the bus clock divided by two in master mode and up to the bus clock divided by 4 in slave mode. Software can poll the status flags, or SPI operation can be interrupt-driven.

3.10.2 I2C configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

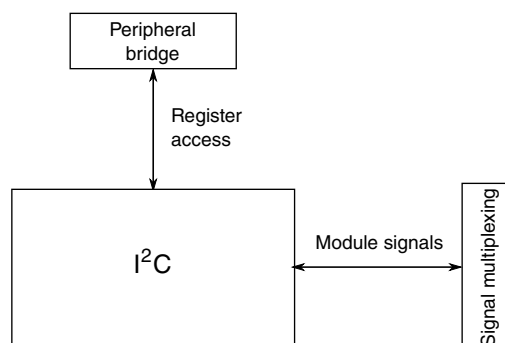


Figure 3-32. I2C configuration

Table 3-40. Reference links to related information

| Topic | Related module | Reference |
|-------------------|------------------|------------------------------------|
| Full description | I ² C | I²C |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |

3.10.2.1 I2C overview

This device contains two inter-integrated circuit (I2C) modules with SMBus feature. I2C provides a method of communication between a number of devices. The interface operates at up to 100 kb/s with maximum bus loading and timing. The device is capable of operating at higher baud rates, up to a maximum of clock/20, with reduced bus loading. The maximum communication length and the number of devices that can be connected are limited by a maximum bus capacitance of 400 pF

I2C0 also provides a 4-wire interface option.

3.10.2.2 I2C0 4-wire interface feature

The 4-wire I2C0 interface has 4 uni-direction signals to improve the noise immunity of the I2C bus instead of 2 bi-direction signals, SCL and SDA of standard I2C.

I2C0 provides 4-wire interface option. When SIM_SOPT1[I2C04WEN] bit is set, SDA/SCL input is from SDA_IN/SCL_IN while SDA/SCL output presents on SDA_OUT/SCL_OUT.

After the 4-wire interface feature is enabled by setting SIM_SOPT1[I2C04WEN] bit, user can set SIM_SOPT1[I2C0OINV], and the SDA_OUT/SCL_OUT will be inverted before output.

This feature is available only when I2C0 pin-out is not remapped.

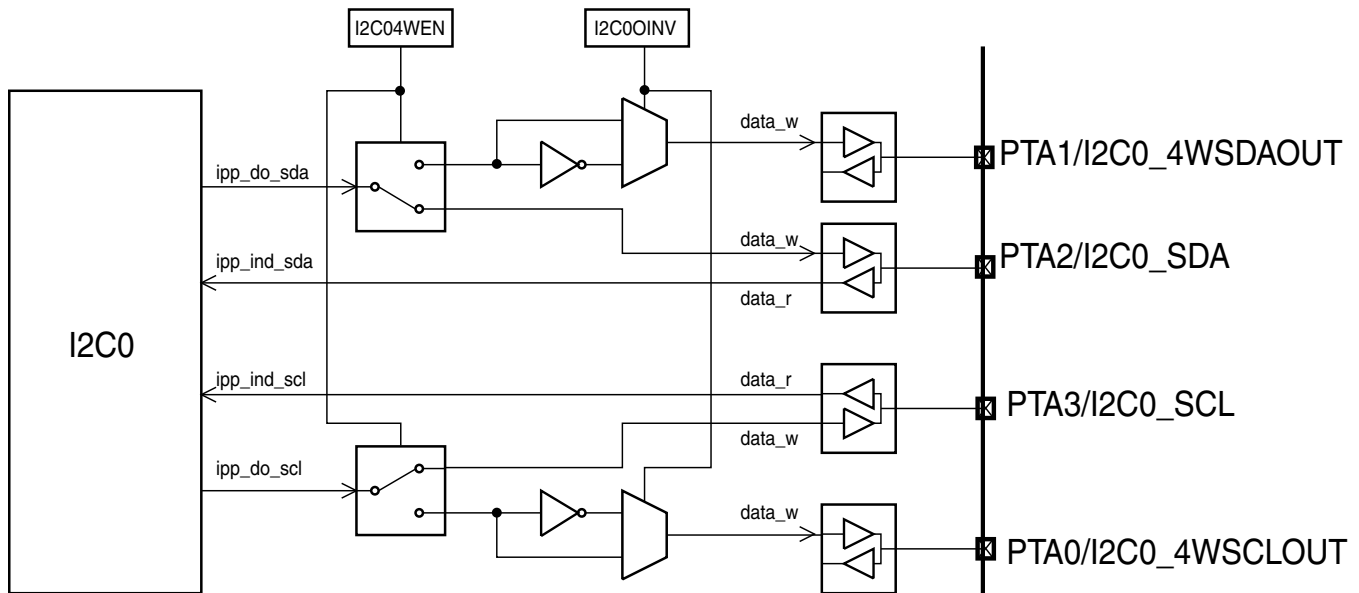


Figure 3-33. I2C0 4-wire interface diagram

3.10.3 UART configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

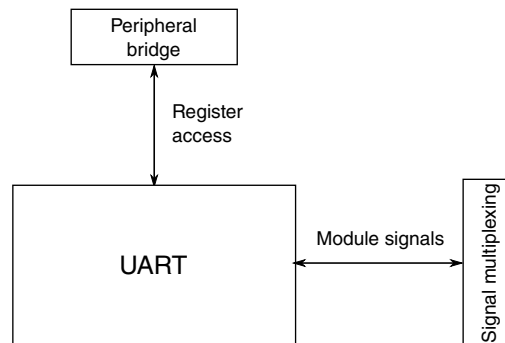


Figure 3-34. UART configuration

Table 3-41. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | UART | UART |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |

3.10.3.1 UART overview

This device includes three universal asynchronous receiver/transmitter (UART) modules. Typically, these systems are used to connect to the RS232 serial input/output port of a personal computer or workstation. They can also be used to communicate with other embedded controllers.

A flexible, 13-bit, modulo-based baud rate generator supports a broad range of standard baud rates beyond 115.2 kbaud. Transmit and receive within the same UART use a common baud rate, and each UART module has a separate baud rate generator.

This UART system offers many advanced features not commonly found on other asynchronous serial I/O peripherals on other embedded controllers. The receiver employs an advanced data sampling technique that ensures reliable communication and noise detection. Hardware parity, receiver wakeup, and double buffering on transmit and receive are also included.

3.10.3.2 UART interconnection

UART0 can implement infrared functions through following tricks:

UART0_TX Modulation:

- UART0_TX output can be modulated by FTM0 channel 0 PWM output.

UART0_RX Tag:

- UART0_RX input can be tagged to FTM0 channel 1 or filtered by ACMP0 or ACMP1. module

UART0_RX, UART1_RX and UART2_RX can be measured by PWT. By configuring SIM_SOPT1[UARTPWTS], user can connect UART0_RX, UART1_RX or UART2_RX to PWT_IN3.

3.10.4 MSCAN configuration

This section summarizes how the module has been configured in the chip. For a comprehensive description of the module itself, see the module's dedicated chapter.

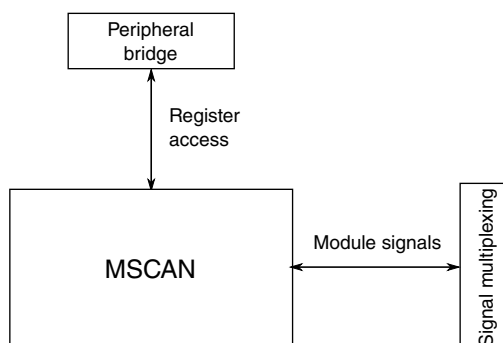


Figure 3-35. MSCAN configuration

Table 3-42. Reference links to related information

| Topic | Related module | Reference |
|-------------------|----------------|------------------------------------|
| Full description | MSCAN | MSCAN |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |

3.10.4.1 MSCAN overview

This device contains a CAN module. It uses the MSCAN module which is a communication controller implementing the CAN 2.0A/B protocol as defined in the Bosch specification dated September 1991.

3.10.4.2 MSCAN clock source

The MSCAN module has programmable clock source. It could be clocked by bus clock or external oscillator clock (OSCERCLK). User can configure MSCAN_CANCTL1[CLKSRC] to select the clock used.

When OSCERCLK is selected as MSCAN clock, its frequency must not be higher than 24 MHz.

3.10.4.3 MSCAN wake-up interrupt and glitch filter

The MSCAN can be programmed to wake from Sleep or Stop mode when the CAN bus activity is detected. The sensitivity to existing CAN bus action can be modified by applying a low-pass filter function to the RXCAN input line by setting MSCAN_CANCTL1[WUPM]. This feature protects the MSCAN from wake-up due to short glitches on the CAN bus lines.

3.11 Human-machine interfaces (HMI)

3.11.1 GPIO configuration

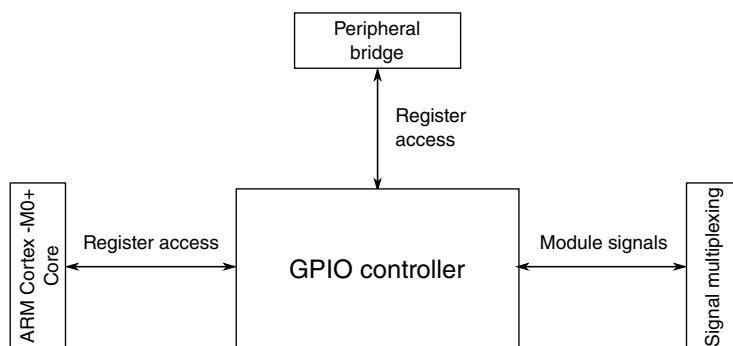


Figure 3-36. GPIO configuration

Table 3-43. Reference links to related information

| Topic | Related module | Reference |
|-------------------|-----------------|------------------------------------|
| Full description | GPIO | GPIO |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |
| Crossbar switch | Crossbar switch | Crossbar switch |

3.11.1.1 GPIO overview

The GPIO is multi-ported and can be accessed directly by the core with zero wait states at base address 0xF800_0000 (FGPIO). It can also be accessed by the core through the crossbar/AIPS interface at 0x400F_F000 and at an aliased slot (15) at address 0x4000_F000. All BME operations to the GPIO space can be accomplished referencing the aliased slot (15) at address 0x4000_F000. Only some of the BME operations can be accomplished referencing GPIO at address 0x400F_F000.

3.11.2 KBI configuration

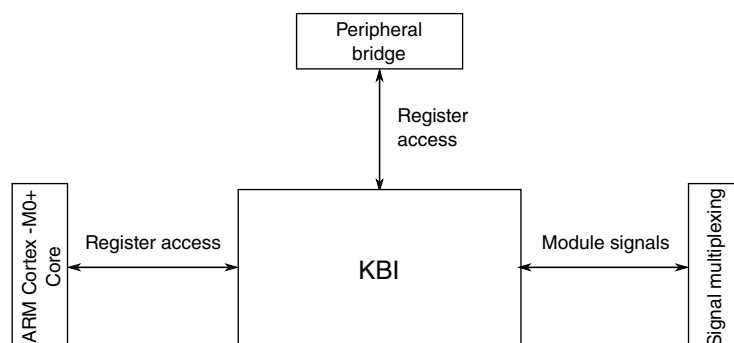


Figure 3-37. KBI configuration

Table 3-44. Reference links to related information

| Topic | Related module | Reference |
|-------------------|-----------------|------------------------------------|
| Full description | KBI | KBI |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |
| Crossbar switch | Crossbar switch | Crossbar switch |

3.11.2.1 KBI overview

This device has two 32bit keyboard interrupt modules (KBI) with up to 64 keyboard interrupt inputs available depending on package.

3.11.2.2 KBI assignments

The KBI port assignments is shown by the following table.

Table 3-45. KBI port assignment

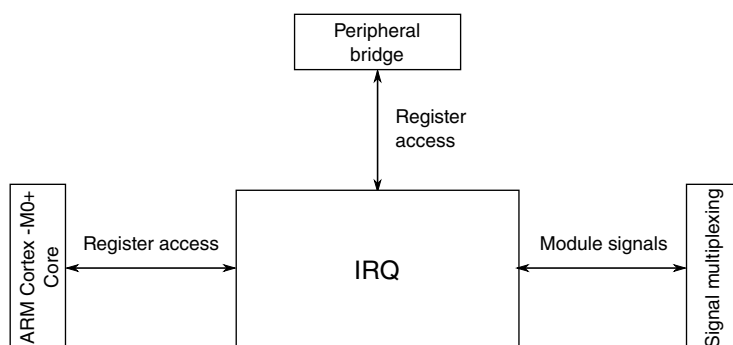
| KBI | Input From |
|-------------------|-------------|
| KBI0P0 ~ KBI0P7 | PTA0 ~ PTA7 |
| KBI0P8 ~ KBI0P15 | PTB0 ~ PTB7 |
| KBI0P16 ~ KBI0P23 | PTC0 ~ PTC7 |
| KBI0P24 ~ KBI0P31 | PTD0 ~ PTD7 |
| KBI1P0 ~ KBI1P7 | PTE0 ~ PTE7 |

Table continues on the next page...

Table 3-45. KBI port assignment (continued)

| KBI | Input From |
|-------------------|-------------|
| KBI1P8 ~ KBI1P15 | PTF0 ~ PTF7 |
| KBI1P16 ~ KBI1P23 | PTG0 ~ PTG7 |
| KBI1P24 ~ KBI1P31 | PTH0 ~ PTH7 |

3.11.3 IRQ configuration

**Figure 3-38. IRQ configuration****Table 3-46. Reference links to related information**

| Topic | Related module | Reference |
|-------------------|-----------------|------------------------------------|
| Full description | IRQ | IRQ |
| System memory map | — | System memory map |
| Clocking | — | Clock Distribution |
| Power management | — | Power management |
| Crossbar switch | Crossbar switch | Crossbar switch |

3.11.3.1 IRQ assignment

The IRQ is assigned to pin PTA5 by default . By configuring SIM_PINSEL0[IRQPS], IRQ can be re-assigned to pin PTI0, PTI1, PTI2, PTI3, PTI4, PTI5 or PTI6.

Chapter 4

Memory Map

4.1 Introduction

This device contains various memories and memory-mapped peripherals which are located in a 4 GB memory space. This chapter describes the memory and peripheral locations within that memory space.

4.2 System memory map

The following table shows the high-level device memory map.

Table 4-1. System memory map

| System 32-bit Address Range | Destination Slave | Access |
|--------------------------------------|---|-----------------|
| 0x0000_0000–0x07FF_FFFF ¹ | Program flash and read-only data (Includes exception vectors in first 196 bytes) | All masters |
| 0x0800_0000–0x0FFF_FFFF | Reserved | — |
| 0x1000_0000– 0x1FFF_EFFF | Reserved | — |
| 0x1FFF_F000–0x1FFF_FFFF ² | SRAM_L: Lower SRAM | All masters |
| 0x2000_0000– 0x2000_2FFF | SRAM_U: Upper SRAM (bit band region) | All masters |
| 0x2000_3000–0x21FF_FFFF | Reserved | – |
| 0x2200_0000– 0x2205_FFFF | Aliased SRAM_U bit-band region | Cortex-M0+ core |
| 0x2206_0000–0x23FF_FFFF | Reserved | – |
| 0x2400_0000–0x3FFF_FFFF | Bit Manipulation Engine (BME) access to SRAM_U | Cortex-M0+ core |
| 0x4000_0000–0x4007_FFFF | AIPS Peripherals | Cortex-M0+ core |
| 0x4008_0000–0x400F_EFFF | Reserved | – |
| 0x400F_F000–0x400F_FFFF | General purpose input/output (GPIO) | Cortex-M0+ core |
| 0x4010_0000–0x43FF_FFFF | Reserved | – |
| 0x4400_0000–0x5FFF_FFFF | Bit Manipulation Engine (BME) access to AIPS Peripherals for slots 0–127 ³ | Cortex-M0+ core |
| 0x6000_0000–0xDFFF_FFFF | Reserved | – |

Table continues on the next page...

Table 4-1. System memory map (continued)

| System 32-bit Address Range | Destination Slave | Access |
|-----------------------------|------------------------------------|-----------------|
| 0xE000_0000–0xE00F_FFFF | Private Peripherals | Cortex-M0+ core |
| 0xE010_0000–0xEFFF_FFFF | Reserved | – |
| 0xF000_0000–0xF000_0FFF | Reserved | – |
| 0xF000_1000–0xF000_1FFF | Reserved | – |
| 0xF000_2000–0xF000_2FFF | System ROM table ⁴ | Cortex-M0+ core |
| 0xF000_3000–0xF000_3FFF | Miscellaneous Control Module (MCM) | Cortex-M0+ core |
| 0xF000_4000–0xF7FF_FFFF | Reserved | – |
| 0xF800_0000–0xFFFF_FFFF | IOPORT: FGPIIO (single cycle) | Cortex-M0+ core |

1. The program flash always begins at 0x0000_0000 but the end of implemented flash varies depending on the amount of flash implemented for a particular device. See [Flash memory sizes](#) for details.
2. This range varies depending on SRAM sizes. See [SRAM sizes](#) for details.
3. Includes BME operations to GPIO at slot 15 (based at 0x4000_F000).
4. This device implements a system ROM table which is used to redirect to ARM Cortex M0+ (Flycatcher) ROM table in CoreSight debug system. See [System ROM memory map](#) for details.

4.3 Aliased bit-band region

The device supports aliased SRAM_U bit-band region with Cortex M0+ core. A 32-bit write in the alias region has the same result as a read-modify-write operation on the targeted bit in the bit-band region, but with only one cycle time. Aliased bit-band region is much more efficient for bit operation.

Bit 0 of the value written to the alias region determines what value is written to the target bit:

- Writing a value with bit 0 set writes a 1 to the target bit.
- Writing a value with bit 0 clear writes a 0 to the target bit.

A 32-bit read in the alias region returns either:

- a value of 0x0000_0000 to indicate the target bit is clear
- a value of 0x0000_0001 to indicate the target bit is set

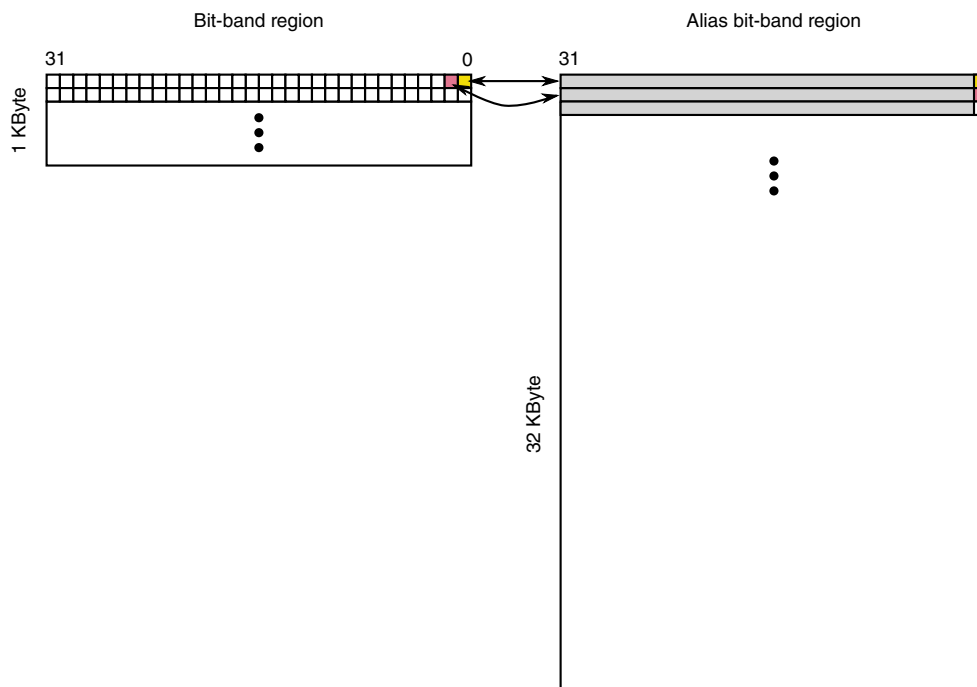


Figure 4-1. Alias bit-band mapping

4.4 Bit Manipulation Engine

The Bit Manipulation Engine (BME) provides hardware support for atomic read-modify-write memory operations to the peripheral and SRAM_U address space. By combining the basic load and store instruction support in the Cortex-M instruction set architecture with the concept of decorated storage provided by the BME, the resulting implementation provides a robust and efficient read-modify-write capability to this class of ultra low-end microcontrollers. See [Bit Manipulation Engine \(BME\)](#) for a detailed description of its functionality.

4.5 System ROM memory map

The system ROM table is optionally required by ARM CoreSight debug infrastructure to discover the components on the chip.

For core configurations like that supported by Cortex-M0+, ARM recommends that a debugger identifies and connects to the debug components using the CoreSight debug infrastructure.

ARM recommends that a debugger follows the flow as shown in the following figure to discover the components in the CoreSight debug infrastructure. In this case, a debugger reads the peripheral and component ID registers for each CoreSight component in the CoreSight system.

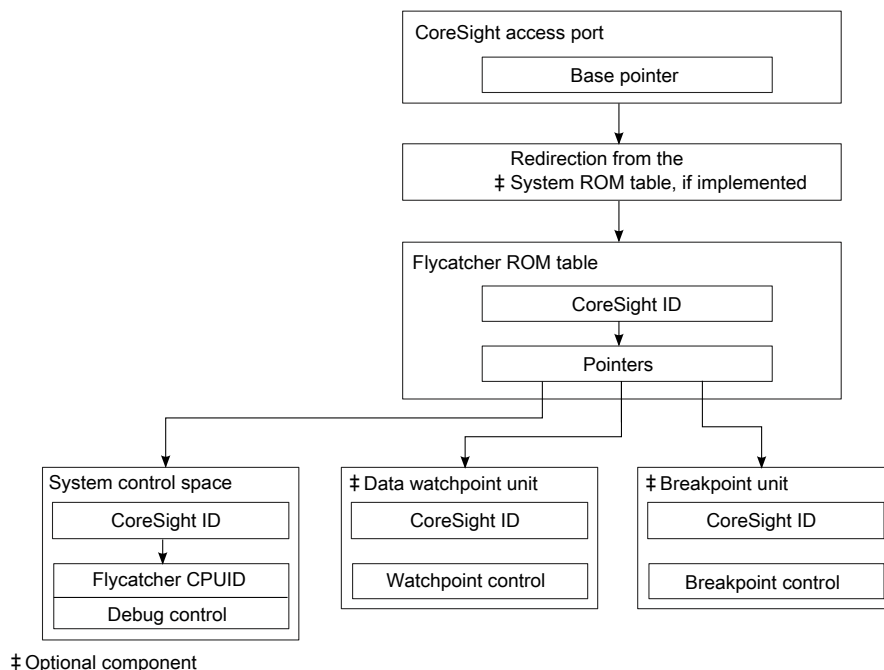


Figure 4-2. CoreSight discovery process

Following table shows the Freescale system ROM table memory map. It includes the ROM entry, peripheral ID and component ID required by ARM CoreSight debug infrastructure.

NOTE

This device contains only standard ARM M0+ core debug components which defined in Flycatcher ROM table. No custom-built debug components are included.

ROM memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-----------------------------|---------------------------|
| F000_2000 | Entry (ROM_ENTRY0) | 32 | R | See section | 4.5.1/101 |
| F000_2004 | End of Table Marker Register (ROM_TABLEMARK) | 32 | R | 0000_0000h | 4.5.2/102 |
| F000_2FCC | System Access Register (ROM_SYSACCESS) | 32 | R | 0000_0001h | 4.5.3/102 |
| F000_2FD0 | Peripheral ID Register (ROM_PERIPHID4) | 32 | R | See section | 4.5.4/103 |
| F000_2FD4 | Peripheral ID Register (ROM_PERIPHID5) | 32 | R | See section | 4.5.4/103 |

Table continues on the next page...

ROM memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-----------------------------|---------------------------|
| F000_2FD8 | Peripheral ID Register (ROM_PERIPHID6) | 32 | R | See section | 4.5.4/103 |
| F000_2FDC | Peripheral ID Register (ROM_PERIPHID7) | 32 | R | See section | 4.5.4/103 |
| F000_2FE0 | Peripheral ID Register (ROM_PERIPHID0) | 32 | R | See section | 4.5.4/103 |
| F000_2FE4 | Peripheral ID Register (ROM_PERIPHID1) | 32 | R | See section | 4.5.4/103 |
| F000_2FE8 | Peripheral ID Register (ROM_PERIPHID2) | 32 | R | See section | 4.5.4/103 |
| F000_2FEC | Peripheral ID Register (ROM_PERIPHID3) | 32 | R | See section | 4.5.4/103 |
| F000_2FF0 | Component ID Register (ROM_COMPID0) | 32 | R | See section | 4.5.5/103 |
| F000_2FF4 | Component ID Register (ROM_COMPID1) | 32 | R | See section | 4.5.5/103 |
| F000_2FF8 | Component ID Register (ROM_COMPID2) | 32 | R | See section | 4.5.5/103 |
| F000_2FFC | Component ID Register (ROM_COMPID3) | 32 | R | See section | 4.5.5/103 |

4.5.1 Entry (ROM_ENTRYn)

The System ROM Table begins with "n" relative 32-bit addresses, one for each debug component present in the device and terminating with an all-zero value signaling the end of the table at the "n+1"-th value.

It is hardwired to specific values used during the auto-discovery process by an external debug agent.

Address: F000_2000h base + 0h offset + (4d × i), where i=0d to 0d

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | ENTRY | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | |

* Notes:

- See field descriptions for reset values.x = Undefined at reset.

ROM_ENTRYn field descriptions

| Field | Description |
|-------|--|
| ENTRY | ENTRY Entry 0 (CM0+ ROM Table) is hardwired to 0xF00F_D003. |

4.5.2 End of Table Marker Register (ROM_TABLEMARK)

This register indicates end of table marker. It is hardwired to specific values used during the auto-discovery process by an external debug agent.

Address: F000_2000h base + 4h offset = F000_2004h

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | MARK | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ROM_TABLEMARK field descriptions

| Field | Description |
|-------|--------------------------|
| MARK | Hardwired to 0x0000_0000 |

4.5.3 System Access Register (ROM_SYSACCESS)

This register indicates system access. It is hardwired to specific values used during the auto-discovery process by an external debug agent.

Address: F000_2000h base + FCCh offset = F000_2FCCh

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | SYSACCESS | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

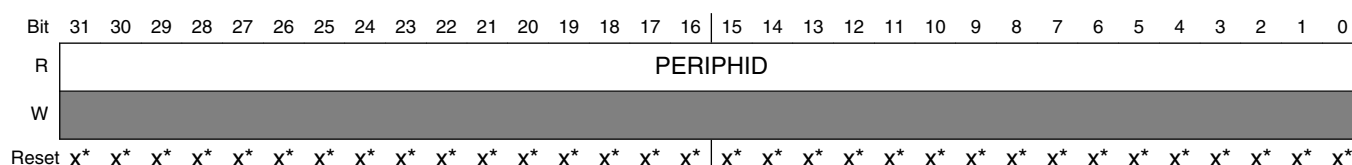
ROM_SYSACCESS field descriptions

| Field | Description |
|-----------|--------------------------|
| SYSACCESS | Hardwired to 0x0000_0001 |

4.5.4 Peripheral ID Register (ROM_PERIPHID_n)

These registers indicate the peripheral IDs. They are hardwired to specific values used during the auto-discovery process by an external debug agent.

Address: F000_2000h base + FD0h offset + (4d × i), where i=0d to 7d



* Notes:

- See field descriptions for reset values.x = Undefined at reset.

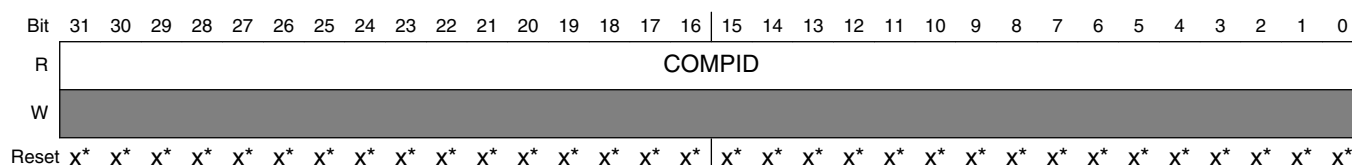
ROM_PERIPHID_n field descriptions

| Field | Description |
|----------|--|
| PERIPHID | Peripheral ID1 is hardwired to 0x0000_00E0; ID2 to 0x0000_0008; and all the others to 0x0000_0000. |

4.5.5 Component ID Register (ROM_COMPID_n)

These registers indicate the component IDs. They are hardwired to specific values used during the auto-discovery process by an external debug agent.

Address: F000_2000h base + FF0h offset + (4d × i), where i=0d to 3d



* Notes:

- See field descriptions for reset values.x = Undefined at reset.

ROM_COMPID_n field descriptions

| Field | Description |
|--------|--|
| COMPID | Component ID Component ID0 is hardwired to 0x0000_000D; ID1 to 0x0000_0010; ID2 to 0x0000_0005; ID3 to 0x0000_00B1. |

4.6 Peripheral bridge (AIPS-Lite) memory map

The Peripheral Bridge memory map is accessible via one slave port on the crossbar in the 0x4000_0000–0x400F_FFFF region. The device implements one peripheral bridge that defines a 1024 KB address space.

The three regions associated with this space are:

- A 128 KB region, partitioned as 32 spaces, each 4 KB in size and reserved for on-platform peripheral devices. The AIPS controller generates unique module enables for all 32 spaces.
- A 384 KB region, partitioned as 96 spaces, each 4 KB in size and reserved for off-platform modules. The AIPS controller generates unique module enables for all 96 spaces.
- The last slot is a 4 KB region beginning at 0x400F_F000 for accessing the GPIO module. The GPIO slot (slot 128) is an alias of slot 15. This block is also directly interfaced to the core and provides direct access without incurring wait states associated with accesses via the AIPS controller.

Modules that are disabled via their clock gate control bits in the SIM registers disable the associated AIPS slots. Access to any address within an unimplemented or disabled peripheral bridge slot results in a transfer error termination.

For programming model accesses via the peripheral bridges, there is generally only a small range within the 4 KB slots that is implemented. Accessing an address that is not implemented in the peripheral results in a transfer error termination.

4.6.1 Read-after-write sequence and required serialization of memory operations

In some situations, a write to a peripheral must be completed fully before a subsequent action can occur. Examples of such situations include:

- Exiting an interrupt service routine (ISR)
- Changing a mode
- Configuring a function

In these situations, the application software must perform a read-after-write sequence to guarantee the required serialization of the memory operations:

1. Write the peripheral register.
2. Read the written peripheral register to verify the write.
3. Continue with subsequent operations.

4.6.2 Peripheral Bridge (AIPS-Lite) Memory Map

NOTE

- Slots 0-95 and 128 are 32-bit data width modules, with the exception that slots 49,82 are 8-bit data width modules (IRQ, WDOG), and slot 36 is 16-bit data width module(MSCAN).
- Slots 96-127 are 8-bit data width modules. While slot 121 and 122 are 32-bit data width modules(KBI0, KBI1)

Table 4-21. Peripheral bridge 0 slot assignments

| System 32-bit base address | Slot number | Module |
|----------------------------|-------------|--|
| 0x4000_0000 | 0 | — |
| 0x4000_1000 | 1 | — |
| 0x4000_2000 | 2 | — |
| 0x4000_3000 | 3 | — |
| 0x4000_4000 | 4 | — |
| 0x4000_5000 | 5 | — |
| 0x4000_6000 | 6 | — |
| 0x4000_7000 | 7 | — |
| 0x4000_8000 | 8 | — |
| 0x4000_9000 | 9 | — |
| 0x4000_A000 | 10 | — |
| 0x4000_B000 | 11 | — |
| 0x4000_C000 | 12 | — |
| 0x4000_D000 | 13 | — |
| 0x4000_E000 | 14 | — |
| 0x4000_F000 | 15 | GPIO controller (aliased to 0x400F_F000) |
| 0x4001_0000 | 16 | — |
| 0x4001_1000 | 17 | — |
| 0x4001_2000 | 18 | — |
| 0x4001_3000 | 19 | — |
| 0x4001_4000 | 20 | — |
| 0x4001_5000 | 21 | — |
| 0x4001_6000 | 22 | — |
| 0x4001_7000 | 23 | — |
| 0x4001_8000 | 24 | — |
| 0x4001_9000 | 25 | — |
| 0x4001_A000 | 26 | — |

Table continues on the next page...

Table 4-21. Peripheral bridge 0 slot assignments (continued)

| System 32-bit base address | Slot number | Module |
|----------------------------|-------------|-----------------------------------|
| 0x4001_B000 | 27 | — |
| 0x4001_C000 | 28 | — |
| 0x4001_D000 | 29 | — |
| 0x4001_E000 | 30 | — |
| 0x4001_F000 | 31 | — |
| 0x4002_0000 | 32 | Flash memory (FTMRE) |
| 0x4002_1000 | 33 | — |
| 0x4002_2000 | 34 | — |
| 0x4002_3000 | 35 | — |
| 0x4002_4000 | 36 | MSCAN |
| 0x4002_5000 | 37 | — |
| 0x4002_6000 | 38 | — |
| 0x4002_7000 | 39 | — |
| 0x4002_8000 | 40 | — |
| 0x4002_9000 | 41 | — |
| 0x4002_A000 | 42 | — |
| 0x4002_B000 | 43 | — |
| 0x4002_C000 | 44 | — |
| 0x4002_D000 | 45 | — |
| 0x4002_E000 | 46 | — |
| 0x4002_F000 | 47 | — |
| 0x4003_0000 | 48 | — |
| 0x4003_1000 | 49 | IRQ controller (IRQ) |
| 0x4003_2000 | 50 | Cyclic Redundancy Check (CRC) |
| 0x4003_3000 | 51 | Pulse width timer (PWT) |
| 0x4003_4000 | 52 | — |
| 0x4003_5000 | 53 | — |
| 0x4003_6000 | 54 | — |
| 0x4003_7000 | 55 | Periodic interrupt timers (PIT) |
| 0x4003_8000 | 56 | Flex timer 0 (FTM0) |
| 0x4003_9000 | 57 | Flex timer 1 (FTM1) |
| 0x4003_A000 | 58 | Flex timer 2 (FTM2) |
| 0x4003_B000 | 59 | Analog-to-digital converter (ADC) |
| 0x4003_C000 | 60 | — |
| 0x4003_D000 | 61 | Real time clock (RTC) |
| 0x4003_E000 | 62 | — |
| 0x4003_F000 | 63 | — |
| 0x4004_0000 | 64 | — |
| 0x4004_1000 | 65 | — |

Table continues on the next page...

Table 4-21. Peripheral bridge 0 slot assignments (continued)

| System 32-bit base address | Slot number | Module |
|----------------------------|-------------|---------------------------------|
| 0x4004_2000 | 66 | — |
| 0x4004_3000 | 67 | — |
| 0x4004_4000 | 68 | — |
| 0x4004_5000 | 69 | — |
| 0x4004_6000 | 70 | — |
| 0x4004_7000 | 71 | — |
| 0x4004_8000 | 72 | System integration module (SIM) |
| 0x4004_9000 | 73 | Port controller |
| 0x4004_A000 | 74 | — |
| 0x4004_B000 | 75 | — |
| 0x4004_C000 | 76 | — |
| 0x4004_D000 | 77 | — |
| 0x4004_E000 | 78 | — |
| 0x4004_F000 | 79 | — |
| 0x4005_0000 | 80 | — |
| 0x4005_1000 | 81 | — |
| 0x4005_2000 | 82 | Watchdog (WDOG) |
| 0x4005_3000 | 83 | — |
| 0x4005_4000 | 84 | — |
| 0x4005_5000 | 85 | — |
| 0x4005_6000 | 86 | — |
| 0x4005_7000 | 87 | — |
| 0x4005_8000 | 88 | — |
| 0x4005_9000 | 89 | — |
| 0x4005_A000 | 90 | — |
| 0x4005_B000 | 91 | — |
| 0x4005_C000 | 92 | — |
| 0x4005_D000 | 93 | — |
| 0x4005_E000 | 94 | — |
| 0x4005_F000 | 95 | — |
| 0x4006_0000 | 96 | — |
| 0x4006_1000 | 97 | — |
| 0x4006_2000 | 98 | — |
| 0x4006_3000 | 99 | — |
| 0x4006_4000 | 100 | Internal clock source (ICS) |
| 0x4006_5000 | 101 | System oscillator (OSC) |
| 0x4006_6000 | 102 | I ² C0 |
| 0x4006_7000 | 103 | I ² C1 |
| 0x4006_8000 | 104 | — |

Table continues on the next page...

Table 4-21. Peripheral bridge 0 slot assignments (continued)

| System 32-bit base address | Slot number | Module |
|----------------------------|-------------|---|
| 0x4006_9000 | 105 | — |
| 0x4006_A000 | 106 | Universal asynchronous receiver/transmitter 0 (UART0) |
| 0x4006_B000 | 107 | Universal asynchronous receiver/transmitter 1 (UART1) |
| 0x4006_C000 | 108 | Universal asynchronous receiver/transmitter 2 (UART2) |
| 0x4006_D000 | 109 | — |
| 0x4006_E000 | 110 | — |
| 0x4006_F000 | 111 | — |
| 0x4007_0000 | 112 | — |
| 0x4007_1000 | 113 | — |
| 0x4007_2000 | 114 | — |
| 0x4007_3000 | 115 | Analog comparator 0 (ACMP0) |
| 0x4007_4000 | 116 | Analog comparator 1 (ACMP1) |
| 0x4007_5000 | 117 | — |
| 0x4007_6000 | 118 | Serial peripheral interface 0 (SPI0) |
| 0x4007_7000 | 119 | Serial peripheral interface 1 (SPI1) |
| 0x4007_8000 | 120 | — |
| 0x4007_9000 | 121 | Keyboard interrupt 0 (KBI0) |
| 0x4007_A000 | 122 | Keyboard interrupt 1 (KBI1) |
| 0x4007_B000 | 123 | — |
| 0x4007_C000 | 124 | — |
| 0x4007_D000 | 125 | Power management controller (PMC) |
| 0x4007_E000 | 126 | — |
| 0x4007_F000 | 127 | — |
| 0x400F_F000 | 128 | GPIO controller |

4.7 Private Peripheral Bus (PPB) memory map

The PPB is part of the defined ARM bus architecture and provides access to select processor-local modules. These resources are only accessible from the core; other system masters do not have access to them.

Table 4-22. PPB memory map

| System 32-bit Address Range | Resource | Additional Range Detail | Resource |
|-----------------------------|----------------------------|-------------------------|----------|
| 0xE000_0000–0xE000_DFFF | Reserved | | |
| 0xE000_E000–0xE000_EFFF | System Control Space (SCS) | 0xE000_E000–0xE000_E00F | Reserved |
| | | 0xE000_E010–0xE000_E0FF | SysTick |

Table continues on the next page...

Table 4-22. PPB memory map (continued)

| System 32-bit Address Range | Resource | Additional Range Detail | Resource |
|-----------------------------|----------------------|-------------------------|----------------------|
| | | 0xE000_E100–0xE000_ECFF | NVIC |
| | | 0xE000_ED00–0xE000_ED8F | System Control Block |
| | | 0xE000_ED90–0xE000_EDEF | Reserved |
| | | 0xE000_EDF0–0xE000_EEFF | Debug |
| | | 0xE000_EF00–0xE000_EFFF | Reserved |
| 0xE000_F000–0xE00F_EFFF | Reserved | | |
| 0xE00F_F000–0xE00F_FFFF | Core ROM Space (CRS) | | |

Chapter 5

Clock Distribution

5.1 Introduction

This chapter presents the clock architecture for the device, the overview of the clocks and includes a terminology section.

The Cortex M0+ resides within a synchronous core platform, where the processor and bus masters, flash and peripherals clocks can be configured independently.

The ICS module will be used for main system clock generation. The ICS module controls which clock sources (internal references, external crystals or external clock signals) generate the source of the system clocks.

5.2 Programming model

The selection and multiplexing of system clock sources is controlled and programmed via the [ICS module](#). The setting of clock dividers and module clock gating for the system are programmed via the [SIM module](#). See those sections for detailed register and bit descriptions.

5.3 High-level device clocking diagram

This device contains following on-chip clock sources:

- Internal Clock Source (ICS) module: The main clock source generator providing bus clock and other reference clocks to peripherals

High-level device clocking diagram

- System Oscillator (OSC) module: The system oscillator providing reference clock to internal clock source (ICS), the real-time clock counter clock module (RTC), and other MCU sub-systems
- Low-Power Oscillator (LPO) module: The on-chip low-power oscillator providing 1 kHz reference clock to RTC and Watchdog (WDOG)

Figure 5-1 shows how clocks from the ICS and OSC modules are distributed to the microcontroller's other function units. Some modules in the microcontroller have selectable clock input.

The following registers of the [system oscillator](#), [ICS](#), and [SIM](#) modules control the multiplexers, dividers, and clock gates shown in the figure:

Table 5-1. Registers controlling multiplexers, dividers, and clock gate

| | OSC | ICS | SIM |
|--------------|--------|--------|------------|
| Multiplexers | OSC_CR | ICS_C1 | SIM_SOPT |
| Dividers | — | ICS_C2 | SIM_CLKDIV |
| Clock gates | OSC_CR | ICS_C1 | SIM_SCGC |

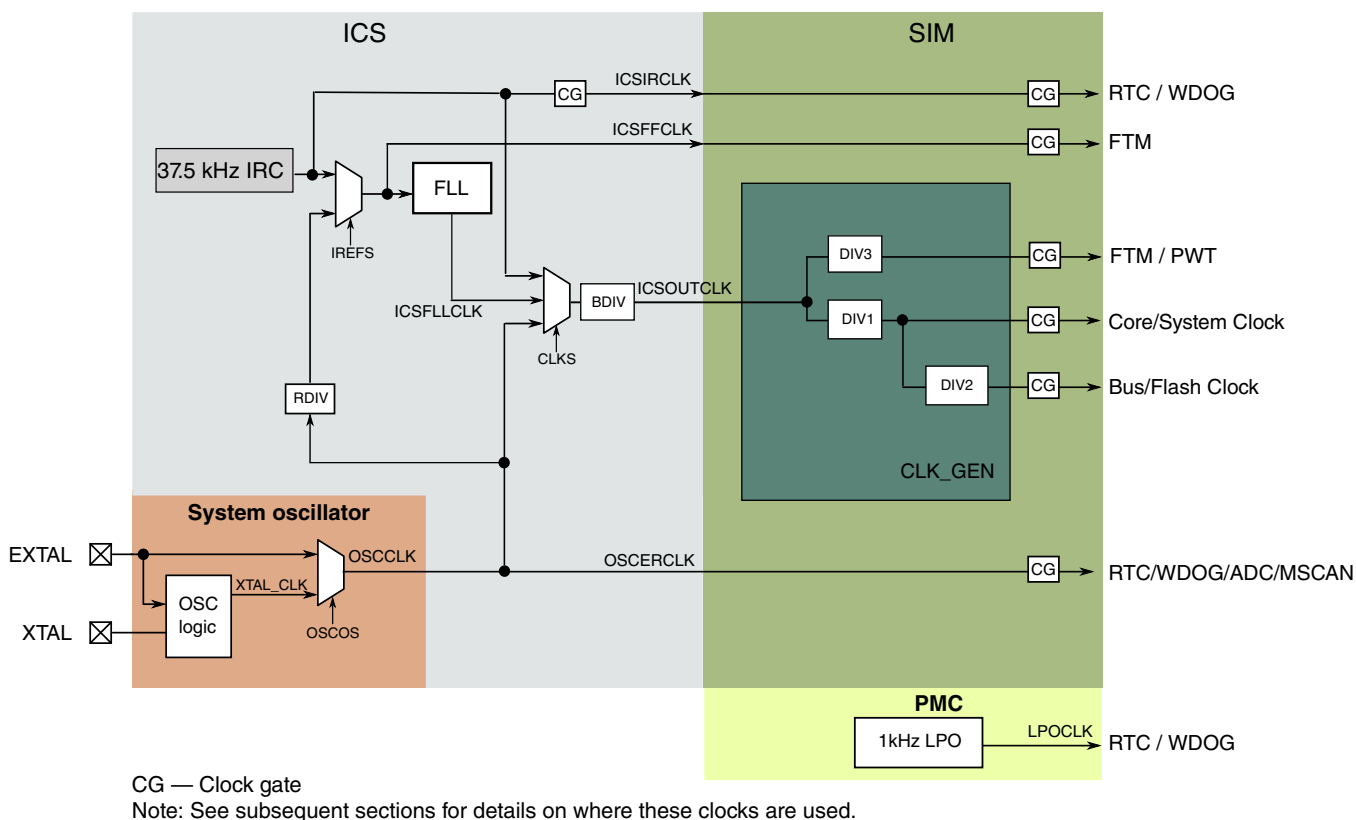


Figure 5-1. Clocking diagram

5.4 Clock definitions

The following table describes the clocks in [Figure 5-1](#).

Table 5-2. Clock definitions

| Clock name | Description |
|----------------|--|
| Core clock | ICSOUTCLK divided by DIV1, clocks the ARM Cortex-M0+ core. It's the CPU HCLK |
| Platform clock | ICSOUTCLK divided by DIV1, clocks the crossbar switch and NVIC, It's the free-running FCLK |
| System clock | ICSOUTCLK divided by DIV1, clocks the bus masters directly |
| Bus clock | System clock divided by DIV2, clocks the bus slaves and peripherals |
| Flash clock | System clock divided by DIV2, clocks the Flash memory module. It is same as Bus clock in this device |
| Timer clock | ICSOUTCLK divided by DIV3, clocks the FTM and PWT modules |
| Debug clock | Debug logic clock. On this device it is derived from platform clock |
| SWD clock | DAP interface clock. SWD clock is typically driven by an external debugger and completely asynchronous to Core clock and platform clock |
| ICSIRCLK | ICS output of the internal 32 kHz IRC reference clock. ICSIRCLK can be selected as the clock source of RTC or WDOG modules |
| ICSOUTCLK | ICS output of either IRC, ICSFLLCLK or ICS's external reference clock that sources the core, system, bus, and flash clock |
| ICSFLLCLK | Output of the FLL, FLL locks the frequency to 1280 times the internal or external reference frequency |
| ICSFFCLK | ICS output of the fixed frequency clock. ICSFFCLK can be selected as clock source for the FTM modules. The frequency of the ICSFFCLK is determined by the setting of the ICS |
| OSCCLK | System oscillator output of the internal oscillator or sourced directly from EXTAL. Used as ICS external reference clock |
| OSCERCLK | System oscillator output sourced from OSCCLK that can be selected as the clock source of MSCAN ¹ , RTC, WDOG or ADC modules |
| LPOCLK | PMC 1 kHz output, The LPOCLK can be selected as the clock source to the RTC or WDOG modules |

1. When OSCERCLK used as MSCAN clock, its frequency should not be higher than 24 MHz

5.4.1 Device clock summary

The following table provides more information regarding the on-chip clocks.

Table 5-3. Clock summary

| Clock name | Run mode frequency | Clock source | Clock is disabled when... |
|------------|--------------------|-------------------------|---------------------------|
| Core clock | Up to 48 MHz | ICSOUTCLK clock divider | In Wait and Stop modes |

Table continues on the next page...

Table 5-3. Clock summary (continued)

| Clock name | Run mode frequency | Clock source | Clock is disabled when... |
|--------------------------------------|--|----------------------------|---|
| Platform clock | Up to 48 MHz | ICSOUTCLK clock divider | In Stop mode |
| System clock | Up to 48 MHz | ICSOUTCLK clock divider | In Stop mode |
| Timer clock | Up to 48 MHz | ICSOUTCLK clock divider | In Stop mode |
| Bus clock | Up to 24 MHz | ICSOUTCLK clock divider | In Stop mode |
| Debug clock | Up to 24 MHz | Derive from Platform clock | Debug not enabled |
| SWD clock | Up to 24MHz | SWD_CLK pin | Input from external clock, so will not be disabled. |
| Flash clock | Up to 24 MHz | ICSOUTCLK clock divider | In Stop mode |
| Internal reference (ICSIRCLK) | 31.25–39.0625 kHz IRC | IRC | ICS_C1[IRCLKEN]=0, or In Stop mode and ICS_C1[IREFSTEN]=0 |
| External reference (OSCERCLK) | DC up to 48 MHz (bypass), 31.25–39.0625 kHz or 4–24 MHz (crystal) | System OSC | OSC_CR[OSCEN]=0, or In Stop mode and OSC_CR[OSCSTEN]=0 |
| FLL out clock (ICSFLLCLK) | 40-50 MHz | System OSC or IRC | In Stop mode, or FLL not enabled |
| ICS Fixed Frequency clock (ICSFFCLK) | 31.25–39.0625 kHz | System OSC or IRC | In Stop mode |
| LPOCLK | 1 kHz | PMC | Available in all power modes |

5.4.2 Clock distribution

The following figure shows a simplified clock distribution diagram

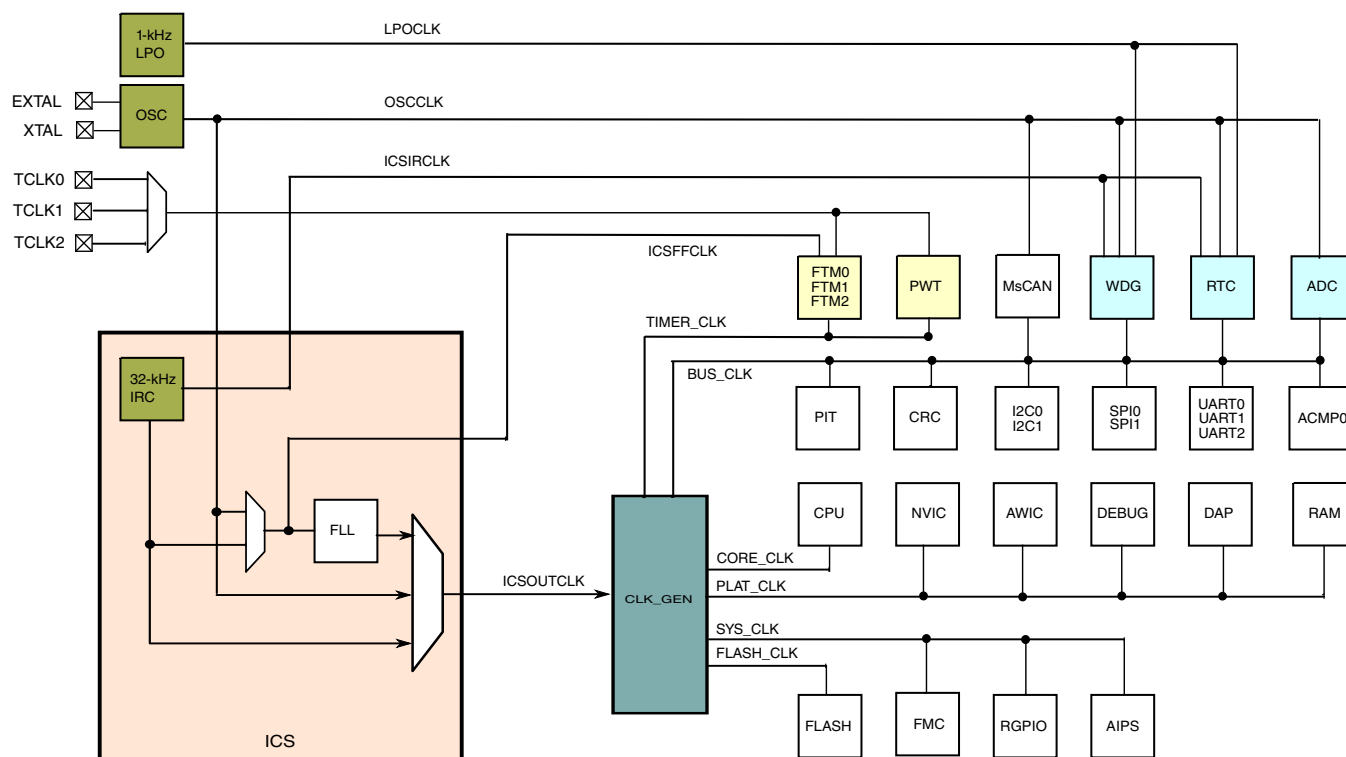


Figure 5-2. High-level clock distribution diagram

NOTE

Clock divide and gating are not shown in clock distribution diagram.

5.5 Internal clocking sources

The internal clock sources on this device are as following:

- On-chip RC oscillator range of 31.25–39.0625 kHz as the reference of FLL input.
- On-chip internal 1 kHz oscillator as the low-frequency low-power source for RTC and WDOG according to specific use case requirement.

The following table shows the frequency availability of this device:

Table 5-4. ICS bus frequency availability with internal reference

| Reference | | ICSOUTCLK |
|------------------|----------|------------------------------|
| FEI (high range) | BDIV = 0 | 40 MHz ~ 50 MHz ¹ |
| | BDIV = 1 | 20 MHz ~ 25 MHz |
| | BDIV = 2 | 10 MHz ~ 12.5 MHz |
| | BDIV = 4 | 5 MHz ~ 6.25 MHz |

Table continues on the next page...

Table 5-4. ICS bus frequency availability with internal reference (continued)

| Reference | | ICSOUTCLK |
|-----------|------------|---------------------------|
| | BDIV = 8 | 2.5 MHz ~ 3.125 MHz |
| | BDIV = 16 | 1.25 MHz ~ 1.5625 MHz |
| | BDIV = 32 | 625 kHz ~ 781.25 kHz |
| | BDIV = 64 | 312.5 kHz ~ 390.625 kHz |
| | BDIV = 128 | 156.25 kHz ~ 195.3125 kHz |

1. Carefully configure SIM_CLKDIV and BDIV to avoid any clock frequency higher than 48 MHz.

5.6 External clock sources

This device supports the following two external clock sources:

- External square wave input clock up to DC-48 MHz.
- External crystal oscillator or resonator:
 - Low-range: 31.25–39.0625 kHz
 - High-range: 4–24 MHz

NOTE

The external square wave input clock is only used when the OSC module is working under external clock mode (bypass). With the external square wave clock source, the user can use FBE mode with FLL disabled to achieve lower power consumption or precise clock source.

The following table shows the frequency availability of this device when sourcing from OSC clock. OSC external clock mode is not shown.

Table 5-5. OSC frequency availability

| ICS configuration | External reference | RDIV |
|-------------------|-------------------------|------------|
| FBE | 31.25 kHz ~ 39.0625 kHz | – |
| | 4 MHz ~ 24 MHz | – |
| FEE ¹ | 31.25 kHz ~ 39.0625 kHz | RDIV = 1 |
| | 62.5 kHz ~ 78.125 kHz | RDIV = 2 |
| | 125 kHz ~ 56.25 kHz | RDIV = 4 |
| | 250 kHz ~ 312.5 kHz | RDIV = 8 |
| | 500 kHz ~ 625 kHz | RDIV = 16 |
| | 1 MHz ~ 1.25 MHz | RDIV = 32 |
| | 2 MHz ~ 2.5 MHz | RDIV = 64 |
| | 4 MHz ~ 5 MHz | RDIV = 128 |

Table continues on the next page...

Table 5-5. OSC frequency availability (continued)

| ICS configuration | External reference | RDIV |
|-------------------|--------------------|------------|
| | 8 MHz ~ 10 MHz | RDIV = 256 |
| | 16 MHz ~ 20 MHz | RDIV = 512 |

1. In FEE mode, FLL output frequency = OSC/RDIV *1280. Select the OSC and RDIV carefully to keep the FLL output frequency within the limits.

5.7 Clock gating

The clock to each module can be individually gated on and off using the [System Clock Gating Control Register \(SIM_SCGC\)](#). Prior to initializing a module, set the corresponding bit in [System Clock Gating Control Register \(SIM_SCGC\)](#) to enable the clock. Before turning off the clock, make sure to disable the module.

Any bus access to a peripheral that has its clock disabled generates an error termination.

5.8 Module clocks

The following table summarizes the clocks associated with each module.

Table 5-6. Module clocks

| Module | Bus interface clock | Internal clocks | I/O interface clocks |
|-----------------------|---------------------|---|----------------------|
| Core modules | | | |
| ARM Cortex-M0+ core | Platform clock | Core clock | — |
| NVIC | Platform clock | — | — |
| DAP | Platform clock | — | SWD_CLK |
| System modules | | | |
| Port control | Bus clock | — | — |
| Crossbar Switch | Platform clock | — | — |
| Peripheral bridges | System clock | Bus clock | — |
| PMC, SIM | Bus clock | LPOCLK | — |
| MCM | Platform clock | — | — |
| CRC | Bus clock | — | — |
| Watchdog timer | Bus clock | Bus clock LPOCLK ICSIRCLK OSCERCLK | — |
| Clocks | | | |

Table continues on the next page...

Table 5-6. Module clocks (continued)

| Module | Bus interface clock | Internal clocks | I/O interface clocks |
|-------------------------------------|---------------------|--|----------------------|
| ICS | Bus clock | ICSOUTCLK ICSFLLCLK ICSIRCLK OSCERCLK | — |
| OSC | Bus clock | OSCERCLK | — |
| Memory and memory interfaces | | | |
| Flash Controller | System clock | — | — |
| Flash memory | Flash clock | — | — |
| SRAM | Platform clock | — | — |
| Analog | | | |
| ADC | Bus clock | Bus clock OSCERCLK ADACK | — |
| ACMP0 | Bus clock | — | — |
| ACMP1 | Bus clock | — | — |
| Timers | | | |
| PIT | Bus clock | — | — |
| PWT | Timer clock | — | TCLK0/1/2 |
| FTM0 | Timer clock | Timer clock ICSFFCLK | TCLK0/1/2 |
| FTM1 | Timer clock | Timer clock ICSFFCLK | TCLK0/1/2 |
| FTM2 | Timer clock | Timer clock ICSFFCLK | TCLK0/1/2 |
| RTC | Bus clock | Bus clock LPOCLK ICSIRCLK OSCERCLK | RTC_CLKOUT |
| Communication interfaces | | | |
| SPI0 | Bus clock | — | SPI0_SCK |
| SPI1 | Bus clock | — | SPI1_SCK |
| I ² C0 | Bus clock | — | I2C0_SCL |
| I ² C1 | Bus clock | — | I2C1_SCL |
| UART0/SCI0 | Bus clock | — | — |
| UART1/SCI1 | Bus clock | — | — |
| UART2/SCI2 | Bus clock | — | — |
| MSCAN | Bus clock | OSCERCLK ¹ | — |
| Human-machine interfaces | | | |
| GPIO | System clock | — | — |

Table continues on the next page...

Table 5-6. Module clocks (continued)

| Module | Bus interface clock | Internal clocks | I/O interface clocks |
|--------|---------------------|-----------------|----------------------|
| KBI0 | Bus clock | — | — |
| KBI1 | Bus clock | — | — |

1. When OSCERCLK is used as MSCAN clock, its frequency should not be higher than 24 MHz

5.8.1 FTM and PWT clocking

The counters for the FTM and PWT modules have a selectable clock as shown in the following figure. TCLK0 TCLK1 and TCLK2 are optional external clock inputs for the timers.

NOTE

If TCLK0, TCLK1 or TCLK2 are selected as the counter clock for FTMs or PWT, the on-chip timer clock (TIMER_CLK) is still required to synchronize the counter results. And the on-chip timer clock (TIMER_CLK) must be at least 4x faster than the external clock from TCLK0, TCLK1 or TCLK2.

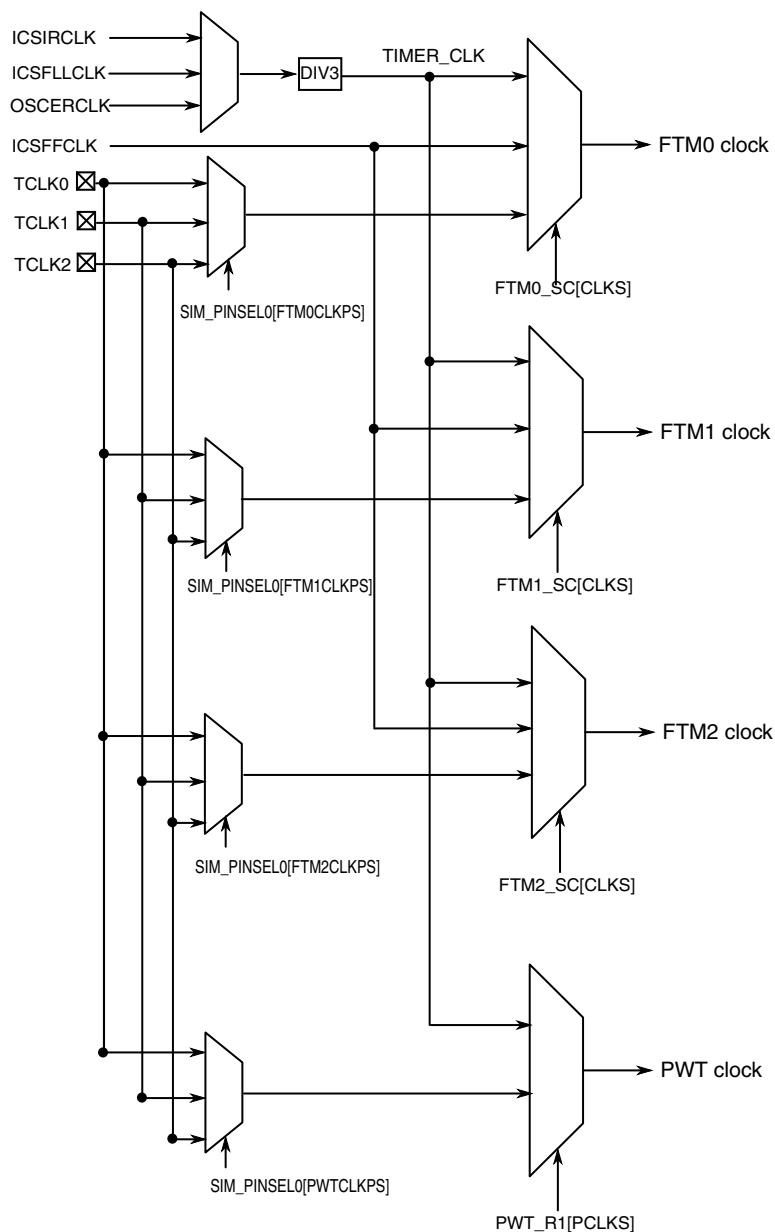


Figure 5-3. FTM and PWT clock generation

Chapter 6

Reset and Boot

6.1 Introduction

The following reset sources are supported in this MCU:

Table 6-1. Reset sources

| Reset sources | Description |
|---------------|--|
| POR reset | <ul style="list-style-type: none">• Power-on reset (POR) |
| System resets | <ul style="list-style-type: none">• External pin reset (PIN)• Low-voltage detect (LVD)• Watchdog (WDOG) timer• ICS loss of clock (LOC) reset• Stop mode acknowledge error (SACKERR)• Software reset (SW)• Lockup reset (LOCKUP)• MDM DAP system reset |

Each of the system reset sources has an associated bit in the [System Reset Status and ID Register \(SIM_SRSID\)](#).

The MCU can exit and reset in functional mode where the CPU is executing code (default) or the CPU is in a debug halted state. There are several boot options that can be configured. See [Boot](#) for more details.

6.2 Reset

This section discusses basic reset mechanisms and sources. Some modules that cause resets can be configured to cause interrupts instead. Consult the individual peripheral chapters for more information.

6.2.1 Power-on reset (POR)

When power is initially applied to the MCU or when the supply voltage drops below the power-on reset voltage level (V_{POR}), the POR circuit causes a POR reset condition.

As the supply voltage rises, the LVD circuit holds the MCU in reset until the supply has risen above the LVD low threshold (V_{LVDL}). POR and LVD fields of the [System Reset Status and ID Register \(SIM_SRSID\)](#). (SIM_SRSID[POR] and SIM_SRSID[LVD]) are set following a POR.

6.2.2 System reset sources

Resetting the MCU provides a way to start processing from a known set of initial conditions. System reset begins with the on-chip regulator in full regulation and system clocking generation from an internal reference. When the processor exits reset, it performs the following:

- Reads the start SP (SP_main) from vector-table offset 0
- Reads the start program counter (PC) from vector-table offset 4
- The Link Register (LR) is set to 0xFFFF_FFFF.

The on-chip peripheral modules are disabled and the non-analog I/O pins are initially configured as disabled (except that the SWD_DIO/SWD_CLK, \overline{NMI} and \overline{RESET} pins could be enabled after system reset according to the [System Options Register 0 \(SIM_SOPT0\)](#) setting). The pins with analog functions assigned to them default to their analog function after reset.

6.2.2.1 External pin reset (\overline{RESET})

This pin has an internal pullup resistor. Asserting \overline{RESET} wakes the device from any mode.

After POR reset, the PTA5 pin functions as \overline{RESET} . SIM_SOPT0[RSTPE] must be programmed to enable the other functions. When this field is clear, this pin can function as PTA5 or other alternative functions.

6.2.2.1.1 Reset pin filter

The \overline{RESET}/IRQ pin filter supports filtering from both the 1 kHz LPO clock and the bus clock. It can be used as a simple low-pass filter to filter any glitch that is introduced from the pin of \overline{RESET}/IRQ .

The glitch width threshold can be adjusted easily by setting [Port Filter Register 0 \(PORT_IOFLT0\)](#) between 1~4096 BUSCLKs (or 1~128 LPOCLKs). This configurable glitch filter can replace an on-board external analog filter, and greatly improve the EMC performance. Setting [Port Filter Register 0 \(PORT_IOFLT0\)](#) can configure the filter of the whole port.

6.2.2.2 Low-voltage detect (LVD)

This device includes a system to protect against low-voltage conditions in order to protect memory contents and control MCU system states during supply voltage variations. This system consists of a power-on reset (POR) circuit, and an LVD circuit with a user selectable trip voltage, either high (V_{LVDH}) or low (V_{LVDL}).

The LVD circuit is enabled when PMC_SPMSC1[LVDE] is set and the trip voltage is selected by PMC_SPMSC2[LVDV]. The LVD is disabled upon entering the stop modes unless PMC_SPMSC1[LVDE] is set or in Serial Wire Debug (SWD) mode. If PMC_SPMSC1[LVDE] and PMC_SPMSC1[LVDE] are both set, the current consumption will be higher in Stop mode with the LVD enabled.

6.2.2.3 Watchdog timer

The watchdog timer (WDOG) monitors the operation of the system by expecting periodic communication from the software. This communication is generally known as servicing (or refreshing) the watchdog. If this periodic refreshing does not occur, the watchdog issues a system reset. The WDOG reset causes SIM_SRSID[WDOG] to set.

6.2.2.4 ICS loss-of-clock (LOC)

The ICS on this chip supports external reference clock monitor with reset capability.

In FBE, or FEE modes, if 1 is written to ICS_C4[CME], the clock monitor is enabled. If the external reference falls below a certain frequency, such as f_{loc_high} or f_{loc_low} depending on OSC_CR[RANGE], the MCU will reset. SIM_SRSID[LOC] will be set to indicate the error.

In FBILP mode, the FLL is not on, so the external reference clock monitor will not function even if 1 is written to ICS_C4[CME].

External reference clock monitor uses FLL as the internal reference clock. The FLL must be functional before ICS_C4[CME] is set.

6.2.2.5 Stop mode acknowledge error (SACKERR)

This reset is generated if the core attempts to enter Stop mode, but not all modules acknowledge Stop mode within 1025 cycles of the 1 kHz LPO clock.

A module might not acknowledge the entry to Stop mode if an error condition occurs. The error can be caused by a failure of an external clock input to a module.

6.2.2.6 Software reset (SW)

The SYSRESETREQ field in the NVIC application interrupt and reset control register can be set to force a software reset on the device. (See ARM's NVIC documentation for the full description of the register fields, especially the VECTKEY field requirements.) Setting SYSRESETREQ generates a software reset request. This reset forces a system reset of all major components except for the debug module.

6.2.2.7 Lockup reset (LOCKUP)

The LOCKUP gives immediate indication of seriously errant kernel software. This is the result of the core being locked because of an unrecoverable exception following the activation of the processor's built in system state protection hardware.

The LOCKUP condition causes a system reset and also causes SIM_SRSID[LOCKUP] to set.

6.2.2.8 MDM-AP system reset request

Set the System Reset Request field in the MDM-AP Control register to initiate a system reset. This is the primary method for resets via the SWD interface. The system reset is held until this bit is cleared.

Set the Core Hold Reset field in the MDM-AP Control register to hold the core in reset as the rest of the chip comes out of system reset.

6.2.3 MCU resets

A variety of resets are generated by the MCU to reset different modules.

6.2.3.1 POR Only

The POR Only reset asserts on the POR reset source only. It resets the PMC and RTC.

The POR Only reset also causes all other reset types to occur.

6.2.3.2 Chip POR

The Chip POR asserts on POR and LVD reset sources. It resets the Reset Pin Filter registers and parts of the SIM and ICS.

The Chip POR also causes the Chip Reset (including Early Chip Reset) to occur.

6.2.3.3 Early Chip Reset

The Early Chip Reset asserts on all reset sources. It resets only the flash memory module and ARM platform. It negates before flash memory initialization begins ("earlier" than when the Chip Reset negates).

6.2.3.4 Chip Reset

Chip Reset asserts on all reset sources and only negates after the $\overline{\text{RESET}}$ pin has also negated. It resets the remaining modules (the modules not reset by other reset types).

6.3 Boot

This section describes the boot sequence, including sources and options.

Some configuration information such as clock trim values stored in factory programmed flash locations is auto-loaded.

6.3.1 Boot sources

The CM0+ core adds support for a programmable Vector Table Offset Register (VTOR¹) to relocate the exception vector table. This device supports booting from internal flash and RAM.

1. VTOR: refer to Vector Table Offset Register in the ARMv6-M Architecture Reference Manual.

This device supports booting from internal flash with the reset vectors located at addresses 0x0 (initial SP_main), 0x4 (initial PC), and RAM with relocating the exception vector table to RAM.

6.3.2 Boot sequence

At power-up, the on-chip regulator holds the system in a POR state until the input supply is above the POR threshold. The system continues to be held in this static state until the internally regulated supplies have reached a safe operating voltage as determined by the LVD. The Reset Controller logic then controls a sequence to exit reset.

1. A system reset is held on internal logic, the $\overline{\text{RESET}}$ pin is driven out low (about 4.2 μs), and the ICS is enabled in its default clocking mode.
2. The $\overline{\text{RESET}}$ pin is released. If $\overline{\text{RESET}}$ pin continues to be asserted (an indication of a slow rise time on the $\overline{\text{RESET}}$ pin or external drive in low), the system continues to be held in reset. Once the $\overline{\text{RESET}}$ pin is detected high, the core clock is enabled and the system is released from reset.
3. The NVM starts internal initialization. Flash Controller is released from reset and begins initialization operations while the core is still halted before the flash initialization completes.
4. When the flash Initialization completes (16 μs), the core sets up the stack, program counter (PC), and link register (LR). The processor reads the start SP (SP_main) from vector-table offset 0. The core reads the start PC from vector-table offset 4. LR is set to 0xFFFF_FFFF. The CPU begins execution at the PC location.

Subsequent system resets follow this same reset flow.

Chapter 7

Power Management

7.1 Introduction

This chapter describes the various chip power modes and functionality of the individual modules in these modes.

7.2 Power modes

The power management controller (PMC) provides the user with multiple power options. The different modes of operation are supported to allow the user to optimize power consumption for the level of functionality needed.

The device supports Run, Wait, and Stop modes which are easy to use for customers both from different power consumption level and functional requirement. I/O states are held in all the modes.

- Run mode—CPU clocks can be run at full speed and the internal supply is fully regulated.
- Wait mode—CPU shuts down to conserve power; system clocks and bus clock are running and full regulation is maintained.
- Stop mode—LVD optional enabled, and voltage regulator is in standby.

The three modes of operation are Run, Wait, and Stop. The WFI instruction invokes both Wait and Stop modes for the chip.

Table 7-1. Chip power modes

| Power mode | Description | Core mode | Normal recover method |
|------------|---|-----------|-----------------------|
| Normal RUN | Allows maximum performance of chip. Default mode out of reset; on-chip voltage regulator is on. | Run | — |

Table continues on the next page...

Table 7-1. Chip power modes (continued)

| Power mode | Description | Core mode | Normal recover method |
|---------------------|---|------------|-----------------------|
| Normal Wait via WFI | Allows peripherals to function while the core is in Sleep mode, reducing power. NVIC remains sensitive to interrupts; peripherals continue to be clocked. | Sleep | Interrupt |
| Normal Stop via WFI | Places chip in static state. Lowest power mode that retains all registers while optionally maintaining LVD protection. NVIC is disabled; AWIC is used to wake up from interrupt; peripheral clocks are stopped. | Sleep Deep | Interrupt |

7.3 Entering and exiting power modes

The WFI instruction invokes Wait and Stop modes for the chip. The processor exits the low-power mode via an interrupt.

NOTE

The WFE instruction can have the side effect of entering a low-power mode, but that is not its intended usage. See ARM documentation for more on the WFE instruction.

7.4 Module operation in low-power modes

The following table illustrates the functionality of each module while the chip is in each of the low-power modes. The standard behavior is shown with some exceptions.

Table 7-2. Module operation in low-power modes

| Modules | Run | Wait | Stop |
|-----------------------|-----------------|-----------------|------------------|
| Core modules | | | |
| CPU | On | Standby | Standby |
| NVIC | On | On | Standby |
| System modules | | | |
| PMC | Full regulation | Full regulation | Loose regulation |
| WDOG | On | On | Optional on |
| LVD | On | On | Optional on |
| CRC | On | On | Standby |
| Clock | | | |
| ICS | On | On | Optional on |
| OSC | On | On | Optional on |
| LPO | On | On | Always on |

Table continues on the next page...

Table 7-2. Module operation in low-power modes (continued)

| Modules | Run | Wait | Stop |
|---------------------------------|-----|----------------------|----------------------|
| Memory | | | |
| Flash | On | On | Standby |
| RAM | On | Standby ¹ | Standby |
| Timer | | | |
| FTM | On | On | Standby |
| PIT | On | On | Standby |
| PWT | On | On | Standby |
| RTC | On | On | Optional on |
| Analog | | | |
| ADC | On | On | Optional on |
| ACMP | On | On | Optional on |
| Communication interfaces | | | |
| UART | On | On | Standby ² |
| SPI | On | On | Standby ³ |
| IIC | On | On | Standby ⁴ |
| MSCAN | On | On | Standby ² |
| Human-machine interfaces | | | |
| KBI | On | On | Standby ⁵ |
| IRQ | On | On | Standby ⁵ |
| I/O | On | On | State held |

1. SRAM enable signal disables internal clock signal and masks the address and data inputs when held low, RAM clock at chip can be active in Wait mode.
2. Supports wake-up on edge in Stop mode
3. Supports slave mode receive and wake-up in Stop mode
4. Supports address match wake-up in Stop mode
5. Supports pin interrupt wake-up in Stop mode

Chapter 8

Security

8.1 Introduction

This device implements security based on the mode selected from the flash module. The following sections provide an overview of flash security and details of the effects of security on non-flash modules.

8.2 Flash security

The flash module provides security information to the MCU based on the state held by the FTMRE_FSEC[SEC]. The MCU, in turn, confirms the security request and limits access to flash resources. During reset, the flash module initializes the [Flash Security Register \(FTMRE_FSEC\)](#) using data read from the security byte of the flash configuration field.

NOTE

The security features apply only to external accesses: CPU accesses to the flash are not affected by the status of [Flash Security Register \(FTMRE_FSEC\)](#).

In the unsecured state all flash commands are available on the programming interfaces either from the debug port (SWD) or user code execution. When the flash is secured (FTMRE_FSEC[SEC] = 00, 01, or 11), the programmer interfaces are only allowed to launch mass erase operations. Additionally, in this mode, the debug port has no access to memory locations.

8.3 Security interactions with other modules

The flash security settings are used by the system to determine what resources are available. The following sections describe the interactions between modules and the flash security settings or the impact that the flash security has on non-flash modules.

8.3.1 Security interactions with debug

When flash security is active, the SWD port cannot access the memory resources of the MCU.

Although most debug functions are disabled, the debugger can write to the Flash Mass Erase in Progress field of the MDM-AP Control Register to trigger a mass erase (Erase All Blocks) command. A mass erase via the debugger is allowed even when some memory locations are protected.

Chapter 9

Debug

9.1 Introduction

This device's debug is based on the ARM CoreSight architecture and is configured to provide the maximum flexibility as allowed by the restrictions of the pinout and other available resources.

It provides register and memory accessibility from the external debugger interface, basic run/halt control plus 2 breakpoints and 2 watchpoints.

This device supports only one debug interface, Serial Wire Debug (SWD).

9.2 Debug port pin descriptions

The debug port pins default to their SWD functionality after power-on-reset (POR).

Table 9-1. Serial wire debug pin description

| Pin Name | Type | Description |
|----------|----------------|--|
| SWD_CLK | Input | Serial Wire Clock. This pin is the clock for debug logic when in the Serial Wire Debug mode. ¹ |
| SWD_DIO | Input / Output | Serial Wire Debug Data input/output. The SWD_DIO pin is used by an external debug tool for communication and device control. This pin is pulled up internally. |

1. The pad library of this device does not support on-chip pull down; the SWD_CLK pin supports only pullup controlled by PTAPE0, external pulldown resistor is required to fully support SWD protocol.

9.3 SWD status and control registers

Through the ARM Debug Access Port (DAP), the debugger has access to the status and control elements, implemented as registers on the DAP bus as shown in [Figure 9-1](#). These registers provide additional control and status for low-power mode recovery and typical run-control scenarios. The status register bits also provide a means for the debugger to get updated status of the core without having to initiate a bus transaction across the crossbar switch, thus remaining less intrusive during a debug session.

A miscellaneous debug module (MDM) is implemented on this device, which contains the DAP control and status registers. It is important to note that these DAP control and status registers are not memory-mapped within the system memory map and are only accessible via the Debug Access Port using SWD. The MDM-AP is accessible as Debug Access Port 1 with the available registers shown in the table below.

Table 9-2. MDM-AP register summary

| Address | Register | Description |
|-------------|----------|--|
| 0x0100_0000 | Status | See MDM-AP status register |
| 0x0100_0004 | Control | See MDM-AP Control register |
| 0x0100_00FC | IDR | Read-only identification register that always reads as 0x001C_0020 |

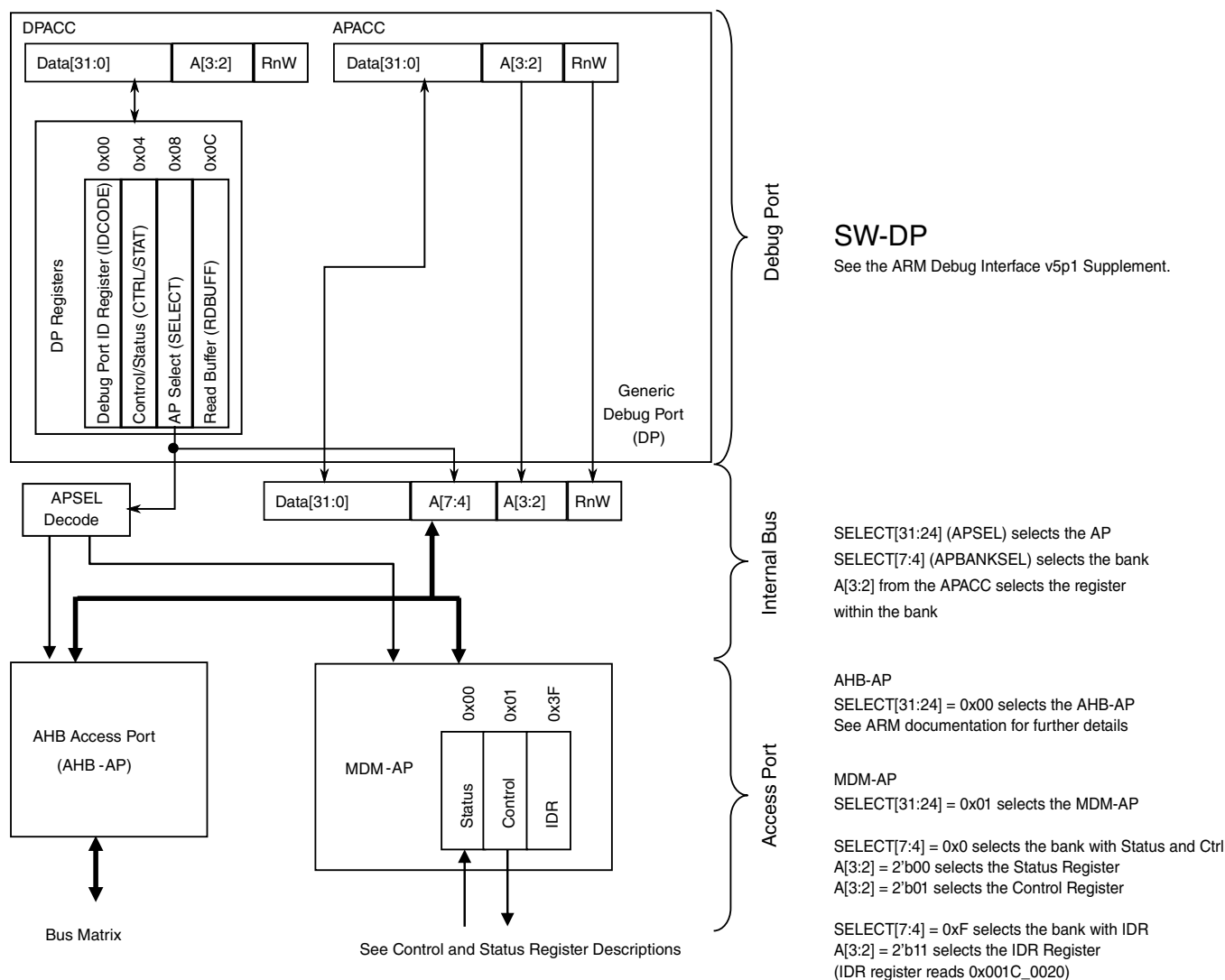


Figure 9-1. MDM AP addressing

9.3.1 MDM-AP status register

Table 9-3. MDM-AP status register assignments

| Bit | Name | Description |
|-----|------------------------------|---|
| 0 | Flash Mass Erase Acknowledge | The Flash Mass Erase Acknowledge field is cleared after POR reset. The field is also cleared at launch of a mass erase command due to write of Flash Mass Erase in Progress field in MDM AP Control Register. The Flash Mass Erase Acknowledge is set after Flash control logic has started the mass erase operation. |
| 1 | Flash Ready | Indicates that flash memory has been initialized and debugger can be configured even if system is continuing to be held in reset via the debugger. 0 Flash is under initialization. |

Table continues on the next page...

Table 9-3. MDM-AP status register assignments (continued)

| Bit | Name | Description |
|---------|-------------------------|--|
| | | 1 Flash is ready. |
| 2 | System Security | Indicates the security state. When secure, the debugger does not have access to the system bus or any memory mapped peripherals. This field indicates when the part is locked and no system bus access is possible. NOTE: This bit is not valid until Flash Ready bit set. 0 Device is unsecured. 1 Device is secured. |
| 3 | System Reset | Indicates the system reset state. 0 System is in reset. 1 System is not in reset. |
| 4 | Reserved | |
| 5 – 15 | Reserved for future use | Always read 0. |
| 16 | Core Halted | Indicates the core has entered Debug Halt mode 0 Core is not halted. 1 Core is halted. |
| 17 | Core SLEEPDEEP | SLEEPDEEP=1 indicates the core has entered Stop mode. |
| 18 | Core SLEEPING | SLEEPING=1 indicates the core has entered Wait mode. |
| 19 – 31 | Reserved for future use | Always reads 0. |

9.3.2 MDM-AP Control register

Table 9-4. MDM-AP Control register assignments

| Bit | Name | Secure ¹ | Description |
|-----|------------------------------|---------------------|---|
| 0 | Flash Mass Erase in Progress | Y | Set to cause mass erase. Cleared by hardware after mass erase operation completes. |
| 1 | Debug Disable | N | Set to disable debug. Clear to allow debug operation. When set, it overrides the C_DEBUGEN field within the DHCSR ² and forces to disable Debug logic. |
| 2 | Debug Request | N | Set to force the core to halt. If the core is in Stop or Wait mode, this field can be used to wake the core and transition to a halted state. |
| 3 | System Reset Request | Y | Set to force a system reset. The system remains held in reset until this field is cleared. When this bit is set, RESET pin does not reflect the status of system reset and does not keep low. |
| 4 | Core Hold | N | Configuration field to control core operation at the end of system reset sequencing. 0 Normal operation—release the core from reset along with the rest of the system at the end of system reset sequencing. |

Table continues on the next page...

Table 9-4. MDM-AP Control register assignments (continued)

| Bit | Name | Secure ¹ | Description |
|-------|-------------------------|---------------------|--|
| | | | 1 Suspend operation—hold the core in reset at the end of reset sequencing. Once the system enters this suspended state, clearing this control bit immediately releases the core from reset and CPU operation begins. |
| 5– 31 | Reserved for future use | N | |

1. Command available in secure mode

2. DHCSR: refer to the Debug Halting Control and Status Register in the ARMv6-M Architecture Reference Manual.

9.4 Debug resets

The debug system receives the following sources of reset:

- System POR reset

Conversely, the debug system is capable of generating system reset using the following mechanism:

- A system reset in the DAP control register which allows the debugger to hold the system in reset.
- Writing 1 to the SYSRESETREQ field in the NVIC Application Interrupt and Reset Control register
- A system reset in the DAP control register which allows the debugger to hold the core in reset.

9.5 Debug in low-power modes

In low-power modes in which the debug modules are kept static or powered off, the debugger cannot gather any debug data for the duration of the low-power mode.

- If the debugger is held static, the debug port returns to full functionality as soon as the low-power mode exits and the system returns to a state with active debug.
- If the debugger logic is powered off, the debugger is reset on recovery and must be reconfigured once the low-power mode is exited.

The active debug will prevent the chip from entering low-power mode. In case the chip is already in low-power mode, a debug request from MDM-AP control register will wake the chip from low-power mode.

9.6 Debug and security

When flash security is enabled, the debug port capabilities are limited in order to prevent exploitation of secure data. In the secure state, the debugger still has access to the status register and can determine the current security state of the device. In the case of a secure device, the debugger has the capability of performing only a mass erase operation.

Chapter 10

Signal Multiplexing and Signal Descriptions

10.1 Introduction

To optimize functionality in small packages, pins have several functions available via signal multiplexing. This chapter illustrates which of this device's signals are multiplexed on which external pin.

The [Pin Selection Register 0 \(SIM_PINSEL0\)](#) and [Pin Selection Register 1 \(SIM_PINSEL1\)](#) control which signal is present on the external pin. Refer to that register to find the detailed control operation of a specific multiplexed pin.

10.2 Pinout

10.2.1 Signal multiplexing and pin assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

NOTE

VSS and VSSA are internally connected.

VREFH and VDDA are internally connected in 64-pin packages.

PTB4, PTB5, PTD0, PTD1, PTE0, PTE1, PTH0, and PTH1 are high-current drive pins when operated as output.

PTA2 and PTA3 are true open-drain pins when operated as output.

Pinout

| 80 LQFP | 64 LQFP /QFP | Pin Name | Default | ALT0 | ALT1 | ALT2 | ALT3 | ALT4 | ALT5 | ALT6 | ALT7 |
|---------|--------------|--------------|--------------|------|----------|-----------|-----------|-----------|---------|-------|------|
| 1 | 1 | PTD1 | DISABLED | PTD1 | KBIO_P25 | FTM2_CH3 | SPI1_MOSI | | | | |
| 2 | 2 | PTD0 | DISABLED | PTD0 | KBIO_P24 | FTM2_CH2 | SPI1_SCK | | | | |
| 3 | 3 | PTH7 | DISABLED | PTH7 | KB11_P31 | PWT_IN1 | | | | | |
| 4 | 4 | PTH6 | DISABLED | PTH6 | KB11_P30 | | | | | | |
| 5 | — | PTH5 | DISABLED | PTH5 | KB11_P29 | | | | | | |
| 6 | 5 | PTE7 | DISABLED | PTE7 | KB11_P7 | TCLK2 | | FTM1_CH1 | CAN0_TX | | |
| 7 | 6 | PTH2 | DISABLED | PTH2 | KB11_P26 | BUSOUT | | FTM1_CH0 | CAN0_RX | | |
| 8 | 7 | VDD | VDD | | | | | | | VDD | |
| 9 | 8 | VDDA | VDDA | | | | | | VREFH | VDDA | |
| 10 | — | VREFH | VREFH | | | | | | | VREFH | |
| 11 | 9 | VREFL | VREFL | | | | | | | VREFL | |
| 12 | 10 | VSS/ VSSA | VSS/ VSSA | | | | | | VSSA | VSS | |
| 13 | 11 | PTB7 | EXTAL | PTB7 | KBIO_P15 | I2C0_SCL | | | | EXTAL | |
| 14 | 12 | PTB6 | XTAL | PTB6 | KBIO_P14 | I2C0_SDA | | | | XTAL | |
| 15 | 13 | PTI4 | DISABLED | PTI4 | | IRQ | | | | | |
| 16 | — | PTI1 | DISABLED | PTI1 | | IRQ | UART2_TX | | | | |
| 17 | — | PTI0 | DISABLED | PTI0 | | IRQ | UART2_RX | | | | |
| 18 | 14 | PTH1 | DISABLED | PTH1 | KB11_P25 | FTM2_CH1 | | | | | |
| 19 | 15 | PTH0 | DISABLED | PTH0 | KB11_P24 | FTM2_CH0 | | | | | |
| 20 | 16 | PTE6 | DISABLED | PTE6 | KB11_P6 | | | | | | |
| 21 | 17 | PTE5 | DISABLED | PTE5 | KB11_P5 | | | | | | |
| 22 | 18 | PTB5 | DISABLED | PTB5 | KBIO_P13 | FTM2_CH5 | SPI0_PCS | ACMP1_OUT | | | |
| 23 | 19 | PTB4 | NMI_b | PTB4 | KBIO_P12 | FTM2_CH4 | SPI0_MISO | ACMP1_IN2 | NMI_b | | |
| 24 | 20 | PTC3 | ADC0_SE11 | PTC3 | KBIO_P19 | FTM2_CH3 | | ADC0_SE11 | | | |
| 25 | 21 | PTC2 | ADC0_SE10 | PTC2 | KBIO_P18 | FTM2_CH2 | | ADC0_SE10 | | | |
| 26 | 22 | PTD7 | DISABLED | PTD7 | KBIO_P31 | UART2_TX | | | | | |
| 27 | 23 | PTD6 | DISABLED | PTD6 | KBIO_P30 | UART2_RX | | | | | |
| 28 | 24 | PTD5 | DISABLED | PTD5 | KBIO_P29 | PWT_IN0 | | | | | |
| 29 | — | PTI6 | DISABLED | PTI6 | IRQ | | | | | | |
| 30 | — | PTI5 | DISABLED | PTI5 | IRQ | | | | | | |
| 31 | 25 | PTC1 | ADC0_SE9 | PTC1 | KBIO_P17 | FTM2_CH1 | | ADC0_SE9 | | | |
| 32 | 26 | PTC0 | ADC0_SE8 | PTC0 | KBIO_P16 | FTM2_CH0 | | ADC0_SE8 | | | |
| 33 | — | PTH4 | DISABLED | PTH4 | KB11_P28 | I2C1_SCL | | | | | |
| 34 | — | PTH3 | DISABLED | PTH3 | KB11_P27 | I2C1_SDA | | | | | |
| 35 | 27 | PTF7 | ADC0_SE15 | PTF7 | KB11_P15 | | | ADC0_SE15 | | | |
| 36 | 28 | PTF6 | ADC0_SE14 | PTF6 | KB11_P14 | | | ADC0_SE14 | | | |
| 37 | 29 | PTF5 | ADC0_SE13 | PTF5 | KB11_P13 | | | ADC0_SE13 | | | |
| 38 | 30 | PTF4 | ADC0_SE12 | PTF4 | KB11_P12 | | | ADC0_SE12 | | | |
| 39 | 31 | PTB3 | ADC0_SE7 | PTB3 | KBIO_P11 | SPI0_MOSI | FTM0_CH1 | ADC0_SE7 | | | |
| 40 | 32 | PTB2 | ADC0_SE6 | PTB2 | KBIO_P10 | SPI0_SCK | FTM0_CH0 | ADC0_SE6 | | | |

| 80 LQFP | 64 LQFP /QFP | Pin Name | Default | ALT0 | ALT1 | ALT2 | ALT3 | ALT4 | ALT5 | ALT6 | ALT7 |
|---------|--------------|----------|----------|------|----------|------------|---------------|-----------|------------|------|------|
| 41 | 33 | PTB1 | ADC0_SE5 | PTB1 | KBIO_P9 | UART0_TX | | ADC0_SE5 | | | |
| 42 | 34 | PTB0 | ADC0_SE4 | PTB0 | KBIO_P8 | UART0_RX | PWT_IN1 | ADC0_SE4 | | | |
| 43 | 35 | PTF3 | DISABLED | PTF3 | KB1_P11 | UART1_TX | | | | | |
| 44 | 36 | PTF2 | DISABLED | PTF2 | KB1_P10 | UART1_RX | | | | | |
| 45 | 37 | PTA7 | ADC0_SE3 | PTA7 | KBIO_P7 | FTM2_FLT2 | ACMP1_IN1 | ADC0_SE3 | | | |
| 46 | 38 | PTA6 | ADC0_SE2 | PTA6 | KBIO_P6 | FTM2_FLT1 | ACMP1_IN0 | ADC0_SE2 | | | |
| 47 | 39 | PTE4 | DISABLED | PTE4 | KB1_P4 | | | | | | |
| 48 | 40 | VSS | VSS | | | | | | | VSS | |
| 49 | 41 | VDD | VDD | | | | | | | VDD | |
| 50 | — | PTG7 | DISABLED | PTG7 | KB1_P23 | FTM2_CH5 | SPI1_PCS | | | | |
| 51 | — | PTG6 | DISABLED | PTG6 | KB1_P22 | FTM2_CH4 | SPI1_MISO | | | | |
| 52 | — | PTG5 | DISABLED | PTG5 | KB1_P21 | FTM2_CH3 | SPI1_MOSI | | | | |
| 53 | — | PTG4 | DISABLED | PTG4 | KB1_P20 | FTM2_CH2 | SPI1_SCK | | | | |
| 54 | 42 | PTF1 | DISABLED | PTF1 | KB1_P9 | FTM2_CH1 | | | | | |
| 55 | 43 | PTF0 | DISABLED | PTF0 | KB1_P8 | FTM2_CH0 | | | | | |
| 56 | 44 | PTD4 | DISABLED | PTD4 | KBIO_P28 | | | | | | |
| 57 | 45 | PTD3 | DISABLED | PTD3 | KBIO_P27 | SPI1_PCS | | | | | |
| 58 | 46 | PTD2 | DISABLED | PTD2 | KBIO_P26 | SPI1_MISO | | | | | |
| 59 | 47 | PTA3 | DISABLED | PTA3 | KBIO_P3 | UART0_TX | I2C0_SCL | | | | |
| 60 | 48 | PTA2 | DISABLED | PTA2 | KBIO_P2 | UART0_RX | I2C0_SDA | | | | |
| 61 | 49 | PTA1 | ADC0_SE1 | PTA1 | KBIO_P1 | FTM0_CH1 | I2C0_4WSDAOUT | ACMP0_IN1 | ADC0_SE1 | | |
| 62 | 50 | PTA0 | ADC0_SE0 | PTA0 | KBIO_P0 | FTM0_CH0 | I2C0_4WSCLOUT | ACMP0_IN0 | ADC0_SE0 | | |
| 63 | 51 | PTC7 | DISABLED | PTC7 | KBIO_P23 | UART1_TX | | | CAN0_TX | | |
| 64 | 52 | PTC6 | DISABLED | PTC6 | KBIO_P22 | UART1_RX | | | CAN0_RX | | |
| 65 | — | PTI3 | DISABLED | PTI3 | IRQ | | | | | | |
| 66 | — | PTI2 | DISABLED | PTI2 | IRQ | | | | | | |
| 67 | 53 | PTE3 | DISABLED | PTE3 | KB1_P3 | SPI0_PCS | | | | | |
| 68 | 54 | PTE2 | DISABLED | PTE2 | KB1_P2 | SPI0_MISO | PWT_IN0 | | | | |
| 69 | — | VSS | VSS | | | | | | | VSS | |
| 70 | — | VDD | VDD | | | | | | | VDD | |
| 71 | 55 | PTG3 | DISABLED | PTG3 | KB1_P19 | | | | | | |
| 72 | 56 | PTG2 | DISABLED | PTG2 | KB1_P18 | | | | | | |
| 73 | 57 | PTG1 | DISABLED | PTG1 | KB1_P17 | | | | | | |
| 74 | 58 | PTG0 | DISABLED | PTG0 | KB1_P16 | | | | | | |
| 75 | 59 | PTE1 | DISABLED | PTE1 | KB1_P1 | SPI0_MOSI | | I2C1_SCL | | | |
| 76 | 60 | PTE0 | DISABLED | PTE0 | KB1_P0 | SPI0_SCK | TCLK1 | I2C1_SDA | | | |
| 77 | 61 | PTC5 | DISABLED | PTC5 | KBIO_P21 | | FTM1_CH1 | | RTC_CLKOUT | | |
| 78 | 62 | PTC4 | SWD_CLK | PTC4 | KBIO_P20 | RTC_CLKOUT | FTM1_CH0 | ACMP0_IN2 | SWD_CLK | | |
| 79 | 63 | PTA5 | RESET_b | PTA5 | KBIO_P5 | IRQ | TCLK0 | RESET_b | | | |

Pinout

| 80 LQFP | 64 LQFP /QFP | Pin Name | Default | ALT0 | ALT1 | ALT2 | ALT3 | ALT4 | ALT5 | ALT6 | ALT7 |
|------------|--------------------|----------|---------|------|---------|------|-----------|---------|------|------|------|
| 80 | 64 | PTA4 | SWD_DIO | PTA4 | KBIO_P4 | | ACMP0_OUT | SWD_DIO | | | |

10.2.2 Device pin assignment

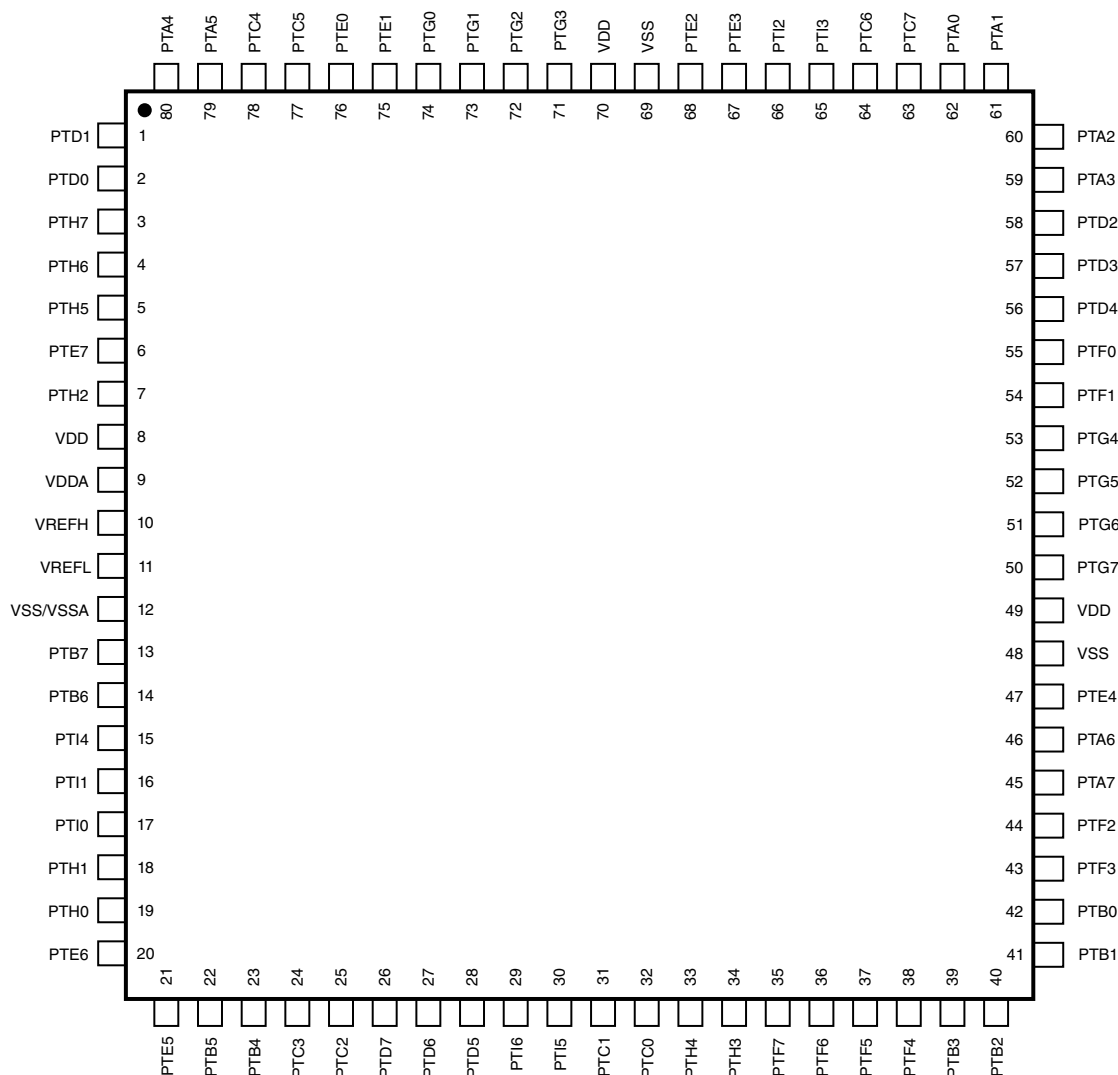


Figure 10-1. 80-pin LQFP package

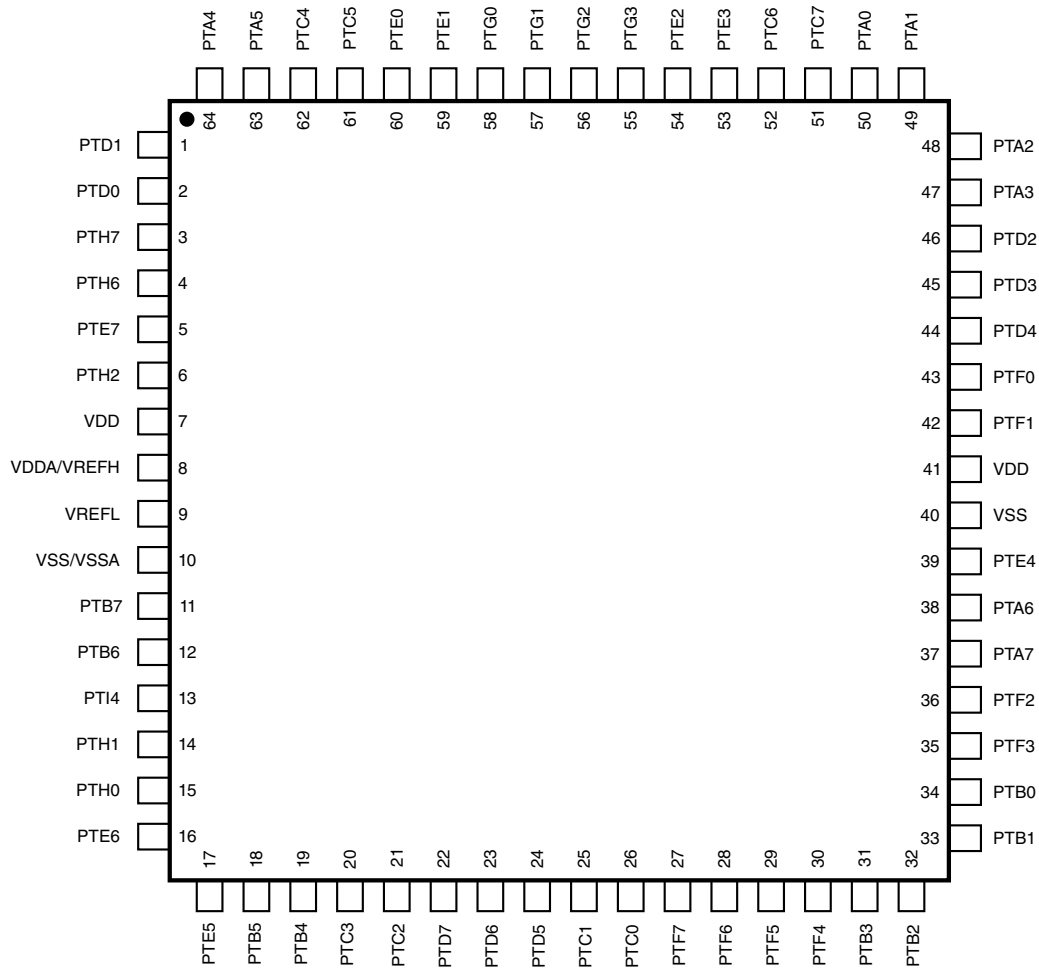


Figure 10-2. 64-pin LQFP packages

10.3 Module signal description tables

The following sections correlate the chip-level signal name with the signal name used in the module's chapter. They also briefly describe the signal function and direction.

10.3.1 Core modules

Table 10-1. SWD signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--|----------------|
| SWD_DIO | SWD_DIO | Serial Wire Debug Data input/output. The SWD_DIO pin is used by an external debug tool for communication and device control. This pin is pulled up internally. | Input / Output |
| SWD_CLK | SWD_CLK | Serial Wire Clock. This pin is the clock for debug logic when in the Serial Wire Debug mode. ¹ | Input |

1. The pad library of this device does not support on-chip pull down; the SWD_CLK pin supports only pullup controlled by PTAPE0, external pulldown resistor is required to fully support SWD protocol.

10.3.2 System modules

Table 10-2. System signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--|-----|
| NMI | — | Non-maskable interrupt NOTE: Driving the $\overline{\text{NMI}}$ signal low forces a non-maskable interrupt, if the $\overline{\text{NMI}}$ function is selected on the corresponding pin. | I |
| RESET | — | Reset bidirectional signal | I/O |
| VDD | — | MCU power | I |
| VSS | — | MCU ground | I |

10.3.3 Clock modules

Table 10-3. OSC signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---------------------------------|---------------|
| EXTAL | EXTAL | External clock/oscillator input | Analog input |
| XTAL | XTAL | Oscillator output | Analog output |

10.3.4 Analog

Table 10-4. ADC0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--|-----|
| ADC0_SEn | AD15-AD0 | Analog channel inputs | I |
| VDD/VREFH | VDDA/VREFH | Analog power supply / voltage reference high | I |
| VSS/VREFL | VSSA/VREFL | Analog power ground / voltage reference low | I |

Table 10-5. ACMP0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|-----------------------|-----|
| ACMP0_INn | ACMP0_IN[2:0] | Analog voltage inputs | I |
| ACMP0_OUT | ACMP0_OUT | Comparator output | O |

Table 10-6. ACMP1 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|-----------------------|-----|
| ACMP1_INn | ACMP1_IN[2:0] | Analog voltage inputs | I |
| ACMP1_OUT | ACMP1_OUT | Comparator output | O |

10.3.5 Timer modules

Table 10-7. FTM0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--------------------|-----|
| TCLKn | EXTCLK | FTM external clock | I |
| FTM0_CH[1:0] | CHn | FTM channel | I/O |

Table 10-8. FTM1 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--------------------|-----|
| TCLKn | EXTCLK | FTM external clock | I |
| FTM1_CH[1:0] | CHn | FTM channel | I/O |

Table 10-9. FTM2 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--------------------|-----|
| TCLKn | EXTCLK | FTM external clock | I |
| FTM2_CHn | CHn | FTM channel | I/O |
| FTM2_FLT1 | FAULT1 | Fault input (1) | I |
| FTM2_FLT2 | FAULT2 | Fault input (2) | I |

Table 10-10. RTC signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|------------------|-----|
| RTC_CLKOUT | RTCO | RTC clock output | O |

Table 10-11. PWT signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|------------------------------|-----|
| TCLKn | ALTCLK | PWT alternate external clock | O |
| PWT_IN0 | PWTIN[0] | PWT input channel0 | I |
| PWT_IN1 | PWTIN[1] | PWT input channel1 | I |

10.3.6 Communication Interfaces

Table 10-12. SPI0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--------------------------------|-----|
| SPI0_MISO | MISO | Master Data In, Slave Data Out | I/O |
| SPI0_MOSI | MOSI | Master Data Out, Slave Data In | I/O |
| SPI0_SCK | SPSCK | SPI Serial Clock | I/O |
| SPI0_PCS | \overline{SS} | Slave Select | I/O |

Table 10-13. SPI1 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--------------------------------|-----|
| SPI1_MISO | MISO | Master Data In, Slave Data Out | I/O |
| SPI1_MOSI | MOSI | Master Data Out, Slave Data In | I/O |
| SPI1_SCK | SPSCK | SPI Serial Clock | I/O |
| SPI1_PCS | \overline{SS} | Slave Select | I/O |

Table 10-14. I²C0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---|-----|
| I2C0_SCL | SCL | Bidirectional serial clock line of the I ² C system. | I/O |
| I2C0_SDA | SDA | Bidirectional serial data line of the I ² C system. | I/O |
| I2C0_4WSCLOUT | | Serial clock line output of I ² C0 in 4 wire interface configuration | O |
| I2C0_4WSDAOUT | | Serial data line output of I ² C0 in 4 wire interface configuration | O |

Table 10-15. I²C1 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---|-----|
| I2C1_SCL | SCL | Bidirectional serial clock line of the I ² C system. | I/O |
| I2C1_SDA | SDA | Bidirectional serial data line of the I ² C system. | I/O |

Table 10-16. UART0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---------------|-----|
| UART0_TX | TxD | Transmit data | I/O |
| UART0_RX | RxD | Receive data | I |

Table 10-17. UART1 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---------------|-----|
| UART1_TX | TxD | Transmit data | I/O |
| UART1_RX | RxD | Receive data | I |

Table 10-18. UART2 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---------------|-----|
| UART2_TX | TxD | Transmit data | I/O |
| UART2_RX | RxD | Receive data | I |

Table 10-19. MSCAN signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|---------------|-----|
| CAN0_RX | RXCAN | Transmit data | I |
| CAN0_TX | TXCAN | Receive data | O |

10.3.7 Human-machine interfaces (HMI)

Table 10-20. GPIO signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|-----------------------|--------------------|------------------------------|-----|
| PTA[7:0] ¹ | PORTA7-PORTA0 | General-purpose input/output | I/O |

Table continues on the next page...

Table 10-20. GPIO signal descriptions (continued)

| Chip signal name | Module signal name | Description | I/O |
|-----------------------|--------------------|------------------------------|-----|
| PTB[7:0] ¹ | PORTA15-PORTA8 | General-purpose input/output | I/O |
| PTC[7:0] ¹ | PORTA23-PORTA16 | General-purpose input/output | I/O |
| PTD[7:0] ¹ | PORTA31-PORTA24 | General-purpose input/output | I/O |
| PTE[7:0] ¹ | PORTB7-PORTB0 | General-purpose input/output | I/O |
| PTF[7:0] ¹ | PORTB15-PORTB8 | General-purpose input/output | I/O |
| PTG[7:0] ¹ | PORTB23-PORTB16 | General-purpose input/output | I/O |
| PTH[7:0] ¹ | PORTB31-PORTB24 | General-purpose input/output | I/O |
| PTI[6:0] ¹ | PORTC6-PORTC0 | General-purpose input/output | I/O |

1. The available GPIO pins depend on the specific package. See the signal multiplexing section for which exact GPIO signals are available.

Table 10-21. KBI0 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--|-----|
| KBI0_Pn | KBI0Pn | Keyboard interrupt pins, n can be 0 ~ 31 | I/O |

Table 10-22. KBI1 signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|--|-----|
| KBI1_Pn | KBI1Pn | Keyboard interrupt pins, n can be 0 ~ 31 | I/O |

Table 10-23. IRQ signal descriptions

| Chip signal name | Module signal name | Description | I/O |
|------------------|--------------------|-------------|-----|
| IRQ | IRQ | IRQ input | I |

Chapter 11

Port Control (PORT)

11.1 Introduction

This device has nine sets of I/O ports, which include up to 71 general-purpose I/O pins.

Not all pins are available on all devices.

Many of the I/O pins are shared with on-chip peripheral functions. The peripheral modules have priority over the I/O, so when a peripheral is enabled, the associated I/O functions are disabled.

After reset, the shared peripheral functions are disabled so that the pins are controlled by the parallel I/O except PTA4, PTA5, PTB4 and PTC4 that are default to SWD_DIO, SWD_CLK, $\overline{\text{NMI}}$ and $\overline{\text{RESET}}$ function. All of the parallel I/O are configured as high-impedance (Hi-Z). The pin control functions for each pin are configured as follows:

- input disabled (GPIOx_PIDR[PID] = 1),
- output disabled (GPIOx_PDDR[PDD] = 0), and
- internal pullups disabled (PORT_PUE(0/1/2)[PTxPE_n] = 0).

Additionally, the parallel I/O that support high drive capability are disabled (HDRVE = 0x00) after reset.

The following three figures show the structures of each I/O pin.

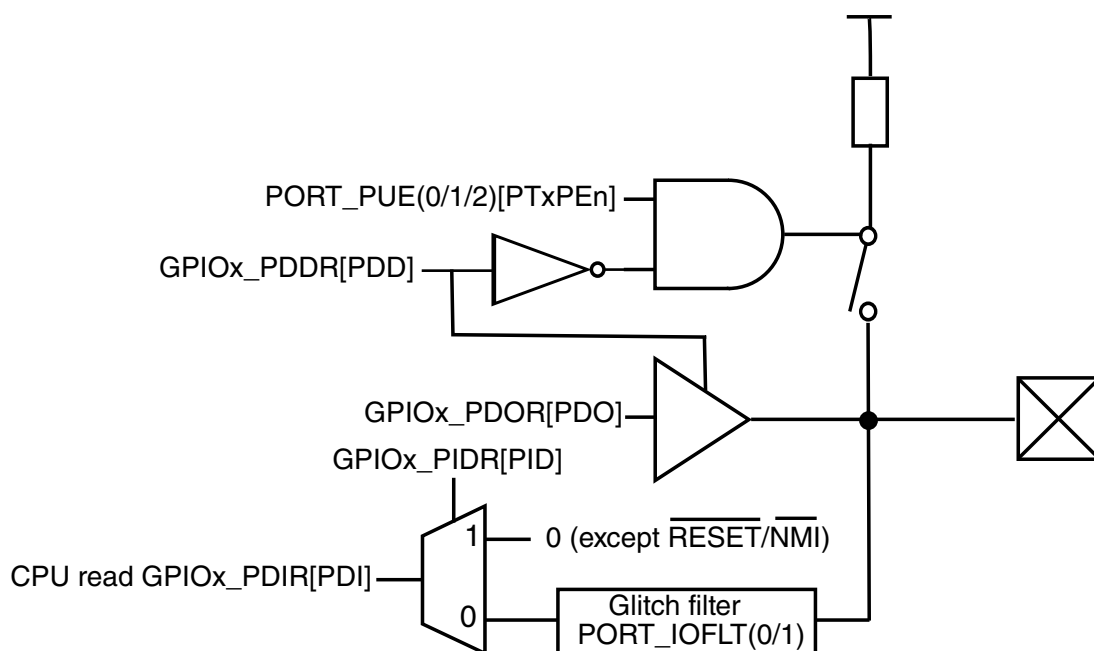


Figure 11-1. Normal I/O structure

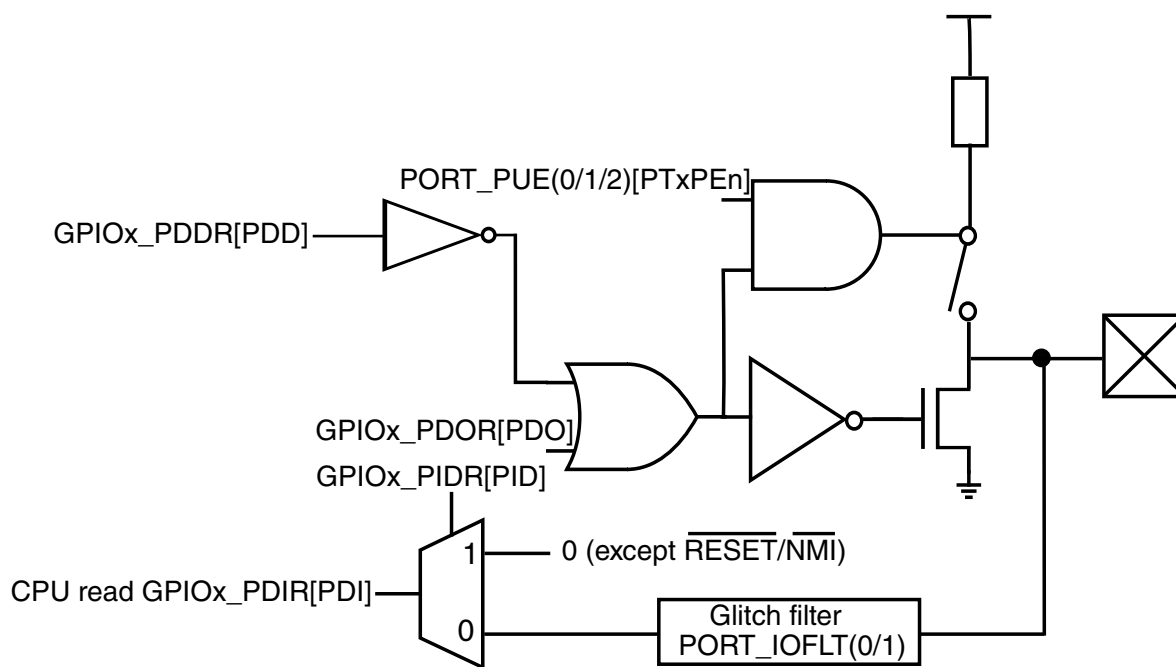


Figure 11-2. SDA(PTA2)/SCL(PTA3) structure

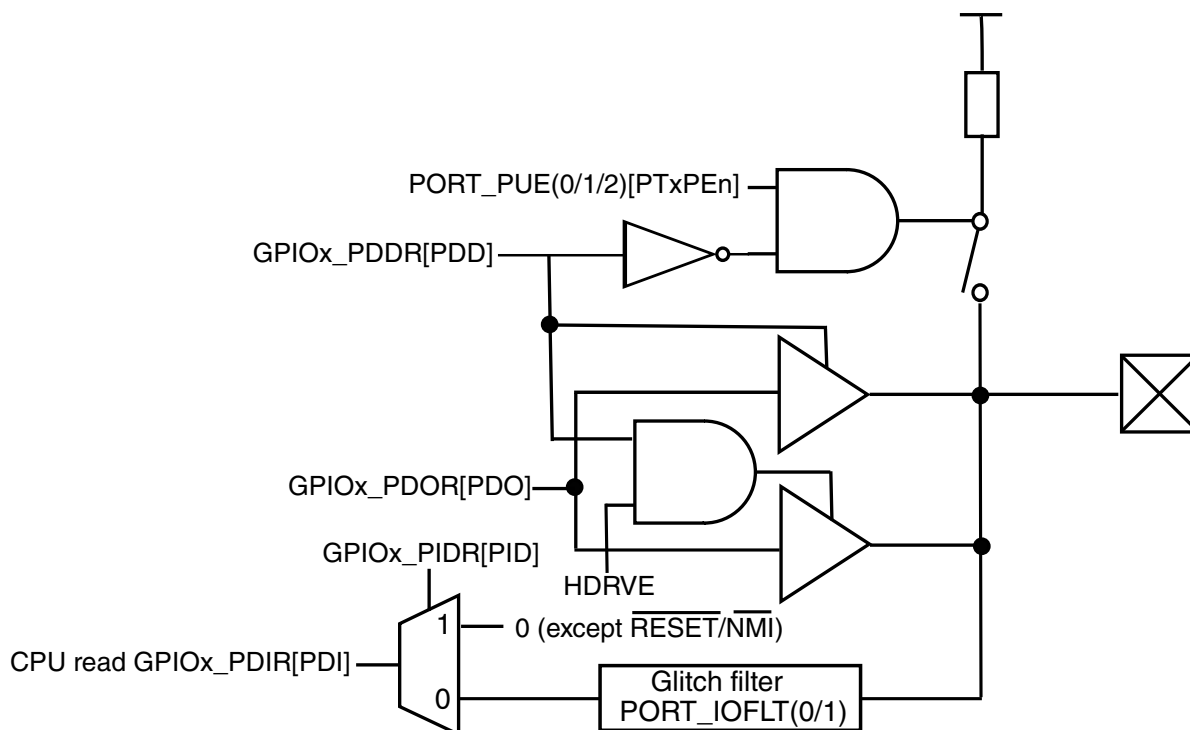


Figure 11-3. High drive I/O structure

11.2 Port data and data direction

Reading and writing of parallel I/O is accomplished through the port data registers (GPIOx_PDOR/PDIR). The direction, input or output, is controlled through the input disable register (GPIOx_PIDR) and data direction register (GPIOx_PDDR).

After reset, all parallel I/O default to the Hi-Z state. The corresponding bit in port data direction register (GPIOx_PDDR) or input disable register (GPIOx_PIDR) must be configured for output or input operation. Each port pin has an input disable bit and an output enable bit. When GPIOx_PIDR[PID] = 0, a read from GPIOx_PDIR returns the input value of the associated pin; when $\overline{\text{GPIOx_PIDR[PID]}}$ = 1, a read from GPIOx_PDIR[PDI] returns 0 except for $\overline{\text{RESET/NMI}}$.

NOTE

The GPIOx_PDDR must be clear when the corresponding pin is used as input function to avoid contention. If set the corresponding GPIOx_PDDR and GPIOx_PIDR bits at same time, read from GPIOx_PDIR will always read the pin status.

When a peripheral module or system function is in control of a port pin, the data direction register bit still controls what is returned for reads of the port data register, even though the peripheral system has overriding control of the actual pin direction.

When a shared analog function is enabled for a pin, all digital pin functions are disabled. A read of the port data register returns a value of 0 for any bits that have shared analog functions enabled. In general, whenever a pin is shared with both an alternate digital function and an analog function, the analog function has priority such that if both of the digital and analog functions are enabled, the analog function controls the pin.

A write of valid data to a port data register must occur before setting the output enable bit of an associated port pin. This ensures that the pin will not be driven with an incorrect data value.

11.3 Internal pullup enable

An internal pullup device can be enabled for each port pin by setting the corresponding bit in one of the pullup enable registers (PORT_PUE(0/1/2)). The internal pullup device is disabled if the pin is configured as an output by the parallel I/O control logic, or by any shared peripheral function, regardless of the state of the corresponding pullup enable register bit. The internal pullup device is also disabled if the pin is controlled by an analog function.

NOTE

When configuring I2C0 to use "SDA(PTA2/PTB6) and SCL(PTA3/PTB7)" pins or I2C1 to use "SDA (PTE0/PTH3) and SCL (PTE1/PTH4)" pins, and if an application uses internal pullups instead of external pullups, the internal pullups remain at present setting when the pins are configured as outputs, but they are automatically disabled to save power when the output values are low.

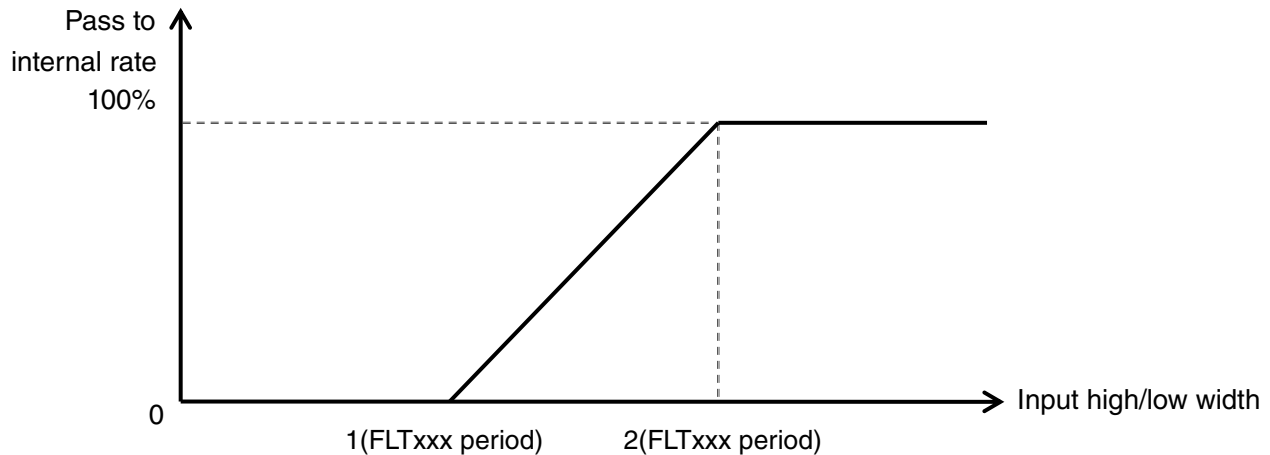
11.4 Input glitch filter setting

A filter is implemented for each port pin that is configured as a digital input. It can be used as a simple low-pass filter to filter any glitch that is introduced from the pins of GPIO, FTM0, FTM1, I2C0, I2C1, PWT, IRQ, $\overline{\text{RESET}}$, $\overline{\text{NMI}}$ and KBI. The glitch width threshold can be adjusted easily by setting PORT_IOFLT0[FLTDIVn] between 1~4096

BUSCLKs (or 1~128 LPOCLKs). This configurable glitch filter can take the place of an on board external analog filter, and greatly improve the EMC performance because any glitch will not be wrongly sampled or ignored.

Setting register PORT_IOFLT(0/1) can configure the filters of the whole port or peripheral inputs. For example, setting PORT_IOFLT0[FLTA] will affect all PTAn pins.

Glitches that are shorter than the selected clock period will be filtered out; Glitches that are more than twice the selected clock period will not be filtered out. It will pass to internal circuitry.



Note: FLTxxx is contents in register PORT_IOFLT(0/1).

Figure 11-4. Input glitch filter

11.5 High current drive

Output high sink/source current drive can be enabled by setting the corresponding bit in the HDRVE register for . These pins can be used as output and input; the pins output high sink/source current when they are operated as output.

- High-current drive function is disabled, if the pin is configured as an input by the parallel I/O control logic.
- When configured as any shared peripheral function, high-current drive function still works on these pins, but only when they are configured as outputs.

11.6 Pin behavior in Stop mode

In Stop mode, all I/O is maintained because internal logic circuitry stays powered up. Upon recovery, normal I/O function is available to the user.

11.7 Port data registers

PORT memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|--------|-------------|----------------------------|
| 4004_9000 | Port Filter Register 0 (PORT_IOFLT0) | 32 | R/W | 00C0_0000h | 11.7.1/154 |
| 4004_9004 | Port Filter Register 1 (PORT_IOFLT1) | 32 | R/W | 0000_0000h | 11.7.2/157 |
| 4004_9008 | Port Pullup Enable Register 0 (PORT_PUE0) | 32 | R/W | 0010_0000h | 11.7.3/158 |
| 4004_900C | Port Pullup Enable Register 1 (PORT_PUE1) | 32 | R/W | 0000_0000h | 11.7.4/163 |
| 4004_9010 | Port Pullup Enable Register 2 (PORT_PUE2) | 32 | R/W | 0000_0000h | 11.7.5/168 |
| 4004_9014 | Port High Drive Enable Register (PORT_HDRVE) | 32 | R/W | 0000_0000h | 11.7.6/170 |

11.7.1 Port Filter Register 0 (PORT_IOFLT0)

This register sets the filters for input pins. Configure the high/low level glitch width threshold. Glitches that are shorter than the selected clock period will be filtered out; glitches that are more than twice the selected clock period will not be filtered out and will pass to internal circuitry.

Address: 4004_9000h base + 0h offset = 4004_9000h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PORT_IOFLT0 field descriptions

| Field | Description |
|------------------|---|
| 31–29 FLTDIV3 | Filter Division Set 3 Port Filter Division Set 3 000 LPOCLK 001 LPOCLK/2 010 LPOCLK/4 011 LPOCLK/8 100 LPOCLK/16 101 LPOCLK/32 |

Table continues on the next page...

PORT_IOFLT0 field descriptions (continued)

| Field | Description |
|-------------------|--|
| | 110 LPOCLK/64 111 LPOCLK/128 |
| 28–26 FLTDIV2 | Filter Division Set 2 Port Filter Division Set 2 000 BUSCLK/32 001 BUSCLK/64 010 BUSCLK/128 011 BUSCLK/256 100 BUSCLK/512 101 BUSCLK/1024 110 BUSCLK/2048 111 BUSCLK/4096 |
| 25–24 FLTDIV1 | Filter Division Set 1 Port Filter Division Set 1 00 BUSCLK/2 01 BUSCLK/4 10 BUSCLK/8 11 BUSCLK/16 |
| 23–22 FLT NMI | Filter Selection for Input from NMI 00 No filter. 01 Selects FLTDIV1, and will switch to FLTDIV3 in Stop mode automatically. 10 Selects FLTDIV2, and will switch to FLTDIV3 in Stop mode automatically. 11 FLTDIV3 |
| 21–20 FLT KBI1 | Filter Selection for Input from KBI1 00 No filter 01 Selects FLTDIV1, and will switch to FLTDIV3 in Stop mode automatically. 10 Selects FLTDIV2, and will switch to FLTDIV3 in Stop mode automatically. 11 FLTDIV3 |
| 19–18 FLT KBI0 | Filter selection for Input from KBI0 00 No filter. 01 Selects FLTDIV1, and will switch to FLTDIV3 in Stop mode automatically. 10 Selects FLTDIV2, and will switch to FLTDIV3 in Stop mode automatically. 11 FLTDIV3 |
| 17–16 FLTRST | Filter Selection for Input from RESET/IRQ 00 No filter. 01 Selects FLTDIV1, and will switch to FLTDIV3 in Stop mode automatically. 10 Selects FLTDIV2, and will switch to FLTDIV3 in Stop mode automatically. 11 FLTDIV3 |
| 15–14 FLTH | Filter Selection for Input from PTH 00 BUSCLK |

Table continues on the next page...

PORT_IOFLT0 field descriptions (continued)

| Field | Description |
|---------------|--|
| | 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| 13–12 FLTG | Filter Selection for Input from PTG 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| 11–10 FLTF | Filter Selection for Input from PTF 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| 9–8 FLTE | Filter Selection for Input from PTD 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| 7–6 FLTD | Filter Selection for Input from PTD 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| 5–4 FLTC | Filter Selection for Input from PTC 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| 3–2 FLTB | Filter Selection for Input from PTB 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |
| FLTA | Filter Selection for Input from PTA 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |

11.7.2 Port Filter Register 1 (PORT_IOFLT1)

This register sets the filters for input pins. Configure the high/low level glitch width threshold. Glitches that are shorter than the selected clock period will be filtered out; glitches that are more than twice the selected clock period will not be filtered out and will pass to internal circuitry.

Address: 4004_9000h base + 4h offset = 4004_9004h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|---------|----|---------|----|--------|----|---------|---|---------|---|--------|---|---|---|------|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | FLT12C1 | | FLT12C0 | | FLTPWT | | FLTFTM1 | | FLTFTM0 | | FLTIRQ | | 0 | | FLT1 | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PORT_IOFLT1 field descriptions

| Field | Description |
|-------------------|--|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 15–14 FLT12C1 | Filter Selection For Input from SCL1/SDA1 00 No filter 01 Select FLTDIV1 10 Select FLTDIV2 11 Select BUSCLK |
| 13–12 FLT12C0 | Filter Selection For Input from SCL0/SDA0 00 No filter 01 Select FLTDIV1 10 Select FLTDIV2 11 Select BUSCLK |
| 11–10 FLTPWT | Filter Selection For Input from PWT_IN1/PWT_IN0 00 No filter 01 Select FLTDIV1 10 Select FLTDIV2 11 Select FLTDIV3 |
| 9–8 FLTFTM1 | Filter Selection For Input from FTM1CH0/FTM1CH1 00 No filter 01 Select FLTDIV1 10 Select FLTDIV2 11 Select FLTDIV3 |

Table continues on the next page...

PORT_IOFLT1 field descriptions (continued)

| Field | Description |
|-----------------|---|
| 7–6 FLTFTM0 | Filter Selection For Input from FTM0CH0/FTM0CH1 00 No filter 01 Select FLTDIV1 10 Select FLTDIV2 11 Select FLTDIV3 |
| 5–4 FLTIRQ | Filter Selection for Input from IRQ 00 No filter 01 Selects FLTDIV1, and will switch to FLTDIV3 in Stop mode automatically. 10 Selects FLTDIV2, and will switch to FLTDIV3 in Stop mode automatically. 11 FLTDIV3 |
| 3–2 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| FLT1 | Filter Selection for Input from PTI 00 BUSCLK 01 FLTDIV1 10 FLTDIV2 11 FLTDIV3 |

11.7.3 Port Pullup Enable Register 0 (PORT_PUE0)

Address: 4004_9000h base + 8h offset = 4004_9008h

| | | | | | | | | | | | | | | | | |
|-------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | PTDPE7 | PTDPE6 | PTDPE5 | PTDPE4 | PTDPE3 | PTDPE2 | PTDPE1 | PTDPE0 | PTCPE7 | PTCPE6 | PTCPE5 | PTCPE4 | PTCPE3 | PTCPE2 | PTCPE1 | PTCPE0 |
| W | PTDPE7 | PTDPE6 | PTDPE5 | PTDPE4 | PTDPE3 | PTDPE2 | PTDPE1 | PTDPE0 | PTCPE7 | PTCPE6 | PTCPE5 | PTCPE4 | PTCPE3 | PTCPE2 | PTCPE1 | PTCPE0 |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PTBPE7 | PTBPE6 | PTBPE5 | PTBPE4 | PTBPE3 | PTBPE2 | PTBPE1 | PTBPE0 | PTAPE7 | PTAPE6 | PTAPE5 | PTAPE4 | PTAPE3 | PTAPE2 | PTAPE1 | PTAPE0 |
| W | PTBPE7 | PTBPE6 | PTBPE5 | PTBPE4 | PTBPE3 | PTBPE2 | PTBPE1 | PTBPE0 | PTAPE7 | PTAPE6 | PTAPE5 | PTAPE4 | PTAPE3 | PTAPE2 | PTAPE1 | PTAPE0 |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PORT_PUE0 field descriptions

| Field | Description |
|--------------|--|
| 31 PTDPE7 | Pull Enable for Port D Bit 7 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. |

Table continues on the next page...

PORT_PUE0 field descriptions (continued)

| Field | Description |
|--------------|---|
| | 0 Pullup is disabled for port D bit 7. 1 Pullup is enabled for port D bit 7. |
| 30 PTDPE6 | Pull Enable for Port D Bit 6 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port D bit 6. 1 Pullup is enabled for port D bit 6. |
| 29 PTDPE5 | Pull Enable for Port D Bit 5 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port D bit 5. 1 Pullup is enabled for port D bit 5. |
| 28 PTDPE4 | Pull Enable for Port D Bit 4 This control bit determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, these bits have no effect. 0 Pullup is disabled for port D bit 4. 1 Pullup is enabled for port D bit 4. |
| 27 PTDPE3 | Pull Enable for Port D Bit 3 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port D bit 3. 1 Pullup is enabled for port D bit 3. |
| 26 PTDPE2 | Pull Enable for Port D Bit 2 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port D bit 2. 1 Pullup is enabled for port D bit 2. |
| 25 PTDPE1 | Pull Enable for Port D Bit 1 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port D bit 1. 1 Pullup is enabled for port D bit 1. |
| 24 PTDPE0 | Pull Enable for Port D Bit 0 This control field determines if the internal pullup device is enabled for the associated PTD pin. For port D pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port D bit 0. 1 Pullup is enabled for port D bit 0. |

Table continues on the next page...

PORT_PUE0 field descriptions (continued)

| Field | Description |
|--------------|---|
| 23 PTCPE7 | <p>Pull Enable for Port C Bit 7</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 7. 1 Pullup is enabled for port C bit 7.</p> |
| 22 PTCPE6 | <p>Pull Enable for Port C Bit 6</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 6. 1 Pullup is enabled for port C bit 6.</p> |
| 21 PTCPE5 | <p>Pull Enable for Port C Bit 5</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 5. 1 Pullup is enabled for port C bit 5.</p> |
| 20 PTCPE4 | <p>Pull Enable for Port C Bit 4</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 4. 1 Pullup is enabled for port C bit 4.</p> |
| 19 PTCPE3 | <p>Pull Enable for Port C Bit 3</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 3. 1 Pullup is enabled for port C bit 3.</p> |
| 18 PTCPE2 | <p>Pull Enable for Port C Bit 2</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 2. 1 Pullup is enabled for port C bit 2.</p> |
| 17 PTCPE1 | <p>Pull Enable for Port C Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 1. 1 Pullup is enabled for port C bit 1.</p> |
| 16 PTCPE0 | <p>Pull Enable for Port C Bit 0</p> |

Table continues on the next page...

PORT_PUE0 field descriptions (continued)

| Field | Description |
|--------------|---|
| | <p>This control field determines if the internal pullup device is enabled for the associated PTC pin. For port C pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port C bit 0. 1 Pullup is enabled for port C bit 0.</p> |
| 15 PTBPE7 | <p>Pull Enable for Port B Bit 7</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port B bit 7. 1 Pullup is enabled for port B bit 7.</p> |
| 14 PTBPE6 | <p>Pull Enable for Port B Bit 6</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port B bit 6. 1 Pullup is enabled for port B bit 6.</p> |
| 13 PTBPE5 | <p>Pull Enable for Port B Bit 5</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port B bit 5. 1 Pullup is enabled for port B bit 5.</p> |
| 12 PTBPE4 | <p>Pull Enable for Port B Bit 4</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port B bit 4. 1 Pullup is enabled for port B bit 4.</p> |
| 11 PTBPE3 | <p>Pull Enable for Port B Bit 3</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port B bit 3. 1 Pullup is enabled for port B bit 3.</p> |
| 10 PTBPE2 | <p>Pull Enable for Port B Bit 2</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port B bit 2. 1 Pullup is enabled for port B bit 2.</p> |
| 9 PTBPE1 | <p>Pull Enable for Port B Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect.</p> |

Table continues on the next page...

PORT_PUE0 field descriptions (continued)

| Field | Description |
|-------------|--|
| | 0 Pullup is disabled for port B bit 1. 1 Pullup is enabled for port B bit 1. |
| 8 PTBPE0 | Pull Enable for Port B Bit 0 This control field determines if the internal pullup device is enabled for the associated PTB pin. For port B pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port B bit 0. 1 Pullup is enabled for port B bit 0. |
| 7 PTAPE7 | Pull Enable for Port A Bit 7 This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port A bit 7. 1 Pullup is enabled for port A bit 7. |
| 6 PTAPE6 | Pull Enable for Port A Bit 6 This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port A bit 6. 1 Pullup is enabled for port A bit 6. |
| 5 PTAPE5 | Pull Enable for Port A Bit 5 This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port A bit 5. 1 Pullup is enabled for port A bit 5. |
| 4 PTAPE4 | Pull Enable for Port A Bit 4 This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port A bit 4. 1 Pullup is enabled for port A bit 4. |
| 3 PTAPE3 | Pull Enable for Port A Bit 3 This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect. NOTE: When configuring to use this pin as output high for IIC, the internal pullup device remains active when PTAPE3 is set. It is automatically disabled to save power when output low. 0 Pullup is disabled for port A bit 3. 1 Pullup is enabled for port A bit 3. |
| 2 PTAPE2 | Pull Enable for Port A Bit 2 This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect. |

Table continues on the next page...

PORT_PUE0 field descriptions (continued)

| Field | Description |
|-------------|---|
| | <p>NOTE: When configuring to use this pin as output high for IIC, the internal pullup device remains active when PTAPE2 is set. It is automatically disabled to save power when output low.</p> <p>0 Pullup is disabled for port A bit 2. 1 Pullup is enabled for port A bit 2.</p> |
| 1 PTAPE1 | <p>Pull Enable for Port A Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port A bit 1. 1 Pullup is enabled for port A bit 1.</p> |
| 0 PTAPE0 | <p>Pull Enable for Port A Bit 0</p> <p>This control field determines if the internal pullup device is enabled for the associated PTA pin. For port A pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port A bit 0. 1 Pullup is enabled for port A bit 0.</p> |

11.7.4 Port Pullup Enable Register 1 (PORT_PUE1)

Address: 4004_9000h base + Ch offset = 4004_900Ch

| | | | | | | | | | | | | | | | | |
|-------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | PTHPE7 | PTHPE6 | PTHPE5 | PTHPE4 | PTHPE3 | PTHPE2 | PTHPE1 | PTHPE0 | PTGPE7 | PTGPE6 | PTGPE5 | PTGPE4 | PTGPE3 | PTGPE2 | PTGPE1 | PTGPE0 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PTFPE7 | PTFPE6 | PTFPE5 | PTFPE4 | PTFPE3 | PTFPE2 | PTFPE1 | PTFPE0 | PTEPE7 | PTEPE6 | PTEPE5 | PTEPE4 | PTEPE3 | PTEPE2 | PTEPE1 | PTEPE0 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PORT_PUE1 field descriptions

| Field | Description |
|--------------|---|
| 31 PTHPE7 | <p>Pull Enable for Port H Bit 7</p> <p>This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect.</p> |

Table continues on the next page...

PORT_PUE1 field descriptions (continued)

| Field | Description |
|--------------|---|
| | 0 Pullup is disabled for port H bit 7. 1 Pullup is enabled for port H bit 7. |
| 30 PTHPE6 | Pull Enable for Port H Bit 6 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 6. 1 Pullup is enabled for port H bit 6. |
| 29 PTHPE5 | Pull Enable for Port H Bit 5 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 5. 1 Pullup is enabled for port H bit 5. |
| 28 PTHPE4 | Pull Enable for Port H Bit 4 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 4. 1 Pullup is enabled for port H bit 4. |
| 27 PTHPE3 | Pull Enable for Port H Bit 3 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 3. 1 Pullup is enabled for port H bit 3. |
| 26 PTHPE2 | Pull Enable for Port H Bit 2 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 2. 1 Pullup is enabled for port H bit 2. |
| 25 PTHPE1 | Pull Enable for Port H Bit 1 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 1. 1 Pullup is enabled for port H bit 1. |
| 24 PTHPE0 | Pull Enable for Port H Bit 0 This control field determines if the internal pullup device is enabled for the associated PTH pin. For port H pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port H bit 0. 1 Pullup is enabled for port H bit 0. |

Table continues on the next page...

PORT_PUE1 field descriptions (continued)

| Field | Description |
|--------------|---|
| 23 PTGPE7 | <p>Pull Enable for Port G Bit 7</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 7. 1 Pullup is enabled for port G bit 7.</p> |
| 22 PTGPE6 | <p>Pull Enable for Port G Bit 6</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 6. 1 Pullup is enabled for port G bit 6.</p> |
| 21 PTGPE5 | <p>Pull Enable for Port G Bit 5</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 5. 1 Pullup is enabled for port G bit 5.</p> |
| 20 PTGPE4 | <p>Pull Enable for Port G Bit 4</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 4. 1 Pullup is enabled for port G bit 4.</p> |
| 19 PTGPE3 | <p>Pull Enable for Port G Bit 3</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 3. 1 Pullup is enabled for port G bit 3.</p> |
| 18 PTGPE2 | <p>Pull Enable for Port G Bit 2</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 2. 1 Pullup is enabled for port G bit 2.</p> |
| 17 PTGPE1 | <p>Pull Enable for Port G Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 1. 1 Pullup is enabled for port G bit 1.</p> |
| 16 PTGPE0 | <p>Pull Enable for Port G Bit 0</p> |

Table continues on the next page...

PORT_PUE1 field descriptions (continued)

| Field | Description |
|--------------|---|
| | <p>This control field determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port G bit 0. 1 Pullup is enabled for port G bit 0.</p> |
| 15 PTFPE7 | <p>Pull Enable for Port F Bit 7</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port F bit 7. 1 Pullup is enabled for port F bit 7.</p> |
| 14 PTFPE6 | <p>Pull Enable for Port F Bit 6</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port F bit 6. 1 Pullup is enabled for port F bit 6.</p> |
| 13 PTFPE5 | <p>Pull Enable for Port F Bit 5</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port F bit 5. 1 Pullup is enabled for port F bit 5.</p> |
| 12 PTFPE4 | <p>Pull Enable for Port F Bit 4</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port F bit 4. 1 Pullup is enabled for port F bit 4.</p> |
| 11 PTFPE3 | <p>Pull Enable for Port F Bit 3</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port F bit 3. 1 Pullup is enabled for port F bit 3.</p> |
| 10 PTFPE2 | <p>Pull Enable for Port F Bit 2</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port F bit 2. 1 Pullup is enabled for port F bit 2.</p> |
| 9 PTFPE1 | <p>Pull Enable for Port F Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect.</p> |

Table continues on the next page...

PORT_PUE1 field descriptions (continued)

| Field | Description |
|-------------|---|
| | 0 Pullup is disabled for port F bit 1. 1 Pullup is enabled for port F bit 1. |
| 8 PTFPE0 | Pull Enable for Port F Bit 0 This control field determines if the internal pullup device is enabled for the associated PTF pin. For port F pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port F bit 0. 1 Pullup is enabled for port F bit 0. |
| 7 PTEPE7 | Pull Enable for Port E Bit 7 This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port E bit 7. 1 Pullup is enabled for port E bit 7. |
| 6 PTEPE6 | Pull Enable for Port E Bit 6 This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port E bit 6. 1 Pullup is enabled for port E bit 6. |
| 5 PTEPE5 | Pull Enable for Port E Bit 5 This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port E bit 5. 1 Pullup is enabled for port E bit 5. |
| 4 PTEPE4 | Pull Enable for Port E Bit 4 This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port E bit 4. 1 Pullup is enabled for port E bit 4. |
| 3 PTEPE3 | Pull Enable for Port E Bit 3 This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port E bit 3. 1 Pullup is enabled for port E bit 3. |
| 2 PTEPE2 | Pull Enable for Port E Bit 2 This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect. 0 Pullup is disabled for port E bit 2. 1 Pullup is enabled for port E bit 2. |

Table continues on the next page...

PORT_PUE1 field descriptions (continued)

| Field | Description |
|-------------|---|
| 1 PTEPE1 | <p>Pull Enable for Port E Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port E bit 1. 1 Pullup is enabled for port E bit 1.</p> |
| 0 PTEPE0 | <p>Pull Enable for Port E Bit 0</p> <p>This control field determines if the internal pullup device is enabled for the associated PTE pin. For port E pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port E bit 0. 1 Pullup is enabled for port E bit 0.</p> |

11.7.5 Port Pullup Enable Register 2 (PORT_PUE2)

Address: 4004_9000h base + 10h offset = 4004_9010h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|--------|--------|--------|--------|--------|--------|--------|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | PTIPE6 | PTIPE5 | PTIPE4 | PTIPE3 | PTIPE2 | PTIPE1 | PTIPE0 | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PORT_PUE2 field descriptions

| Field | Description |
|------------------|---|
| 31–7 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 6 PTIPE6 | <p>Pull Enable for Port I Bit 6</p> <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 6. 1 Pullup is enabled for port I bit 6.</p> |
| 5 PTIPE5 | <p>Pull Enable for Port I Bit 5</p> |

Table continues on the next page...

PORT_PUE2 field descriptions (continued)

| Field | Description |
|-------------|---|
| | <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 5. 1 Pullup is enabled for port I bit 5.</p> |
| 4 PTIPE4 | <p>Pull Enable for Port I Bit 4</p> <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 4. 1 Pullup is enabled for port I bit 4.</p> |
| 3 PTIPE3 | <p>Pull Enable for Port I Bit 3</p> <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 3. 1 Pullup is enabled for port I bit 3.</p> |
| 2 PTIPE2 | <p>Pull Enable for Port I Bit 2</p> <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 2. 1 Pullup is enabled for port I bit 2.</p> |
| 1 PTIPE1 | <p>Pull Enable for Port I Bit 1</p> <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 1. 1 Pullup is enabled for port I bit 1.</p> |
| 0 PTIPE0 | <p>Pull Enable for Port I Bit 0</p> <p>This control field determines if the internal pullup device is enabled for the associated PTI pin. For port I pins that are configured as outputs or Hi-Z, this field has no effect.</p> <p>0 Pullup is disabled for port I bit 0. 1 Pullup is enabled for port I bit 0.</p> |

11.7.6 Port High Drive Enable Register (PORT_HDRVE)

Address: 4004_9000h base + 14h offset = 4004_9014h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|------|------|------|------|------|------|------|------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | PTH1 | PTH0 | PTE1 | PTE0 | PTD1 | PTD0 | PTB5 | PTB4 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PORT_HDRVE field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 PTH1 | High Current Drive Capability of PTH1 This read/write field enables the high-current drive capability of PTH1. 0 PTH1 is disabled to offer high current drive capability. 1 PTH1 is enabled to offer high current drive capability. |
| 6 PTH0 | High Current Drive Capability of PTH0 This read/write field enables the high current drive capability of PTH0. 0 PTH0 is disabled to offer high current drive capability. 1 PTH0 is enabled to offer high current drive capability. |
| 5 PTE1 | High Current Drive Capability of PTE1 This read/write field enables the high current drive capability of PTE1. 0 PTE1 is disabled to offer high current drive capability. 1 PTE1 is enabled to offer high current drive capability. |
| 4 PTE0 | High Current Drive Capability of PTE0 This read/write field enables the high current drive capability of PTE0. 0 PTE0 is disabled to offer high current drive capability. 1 PTE0 is enable to offer high current drive capability. |
| 3 PTD1 | High Current Drive Capability of PTD1 This read/write field enables the high current drive capability of PTD1. 0 PTD1 is disabled to offer high current drive capability. 1 PTD1 is enable to offer high current drive capability. |
| 2 PTD0 | High Current Drive Capability of PTD0 This read/write field enables the high current drive capability of PTD0 |

Table continues on the next page...

PORT_HDRVE field descriptions (continued)

| Field | Description |
|--------------|---|
| | 0 PTD0 is disabled to offer high current drive capability. 1 PTD0 is enabled to offer high current drive capability. |
| 1 PTB5 | High Current Drive Capability of PTB5 This read/write field enables the high current drive capability of PTB5 0 PTB5 is disabled to offer high current drive capability. 1 PTB5 is enabled to offer high current drive capability. |
| 0 PTB4 | High Current Drive Capability of PTB4 This read/write field enables the high current drive capability of PTB4 0 PTB4 is disabled to offer high current drive capability. 1 PTB4 is enabled to offer high current drive capability. |

Chapter 12

System Integration Module (SIM)

12.1 Introduction

The system integration module (SIM) provides system control and chip configuration registers.

12.1.1 Features

The features of the SIM module are listed below.

- Reset status and device ID information
- System interconnection configuration and special pin enable
- Pin re-map control
- System clock gating control and clock divide

12.2 Memory map and register definition

The SIM module contains many fields for selecting the clock source and dividers for various module clocks.

SIM memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-----------------------------|----------------------------|
| 4004_8000 | System Reset Status and ID Register (SIM_SRSID) | 32 | R | See section | 12.2.1/174 |
| 4004_8004 | System Options Register 0 (SIM_SOPT0) | 32 | R/W | See section | 12.2.2/177 |
| 4004_8008 | System Options Register (SIM_SOPT1) | 32 | R/W | 0000_0000h | 12.2.3/180 |
| 4004_800C | Pin Selection Register 0 (SIM_PINSEL0) | 32 | R/W | 0000_0000h | 12.2.4/182 |
| 4004_8010 | Pin Selection Register 1 (SIM_PINSEL1) | 32 | R/W | 0000_0000h | 12.2.5/184 |

Table continues on the next page...

SIM memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-----------------------------|-----------------------------|
| 4004_8014 | System Clock Gating Control Register (SIM_SCGC) | 32 | R/W | 0000_3000h | 12.2.6/186 |
| 4004_8018 | Universally Unique Identifier Low Register (SIM_UUIDL) | 32 | R | Undefined | 12.2.7/190 |
| 4004_801C | Universally Unique Identifier Middle Low Register (SIM_UUIDML) | 32 | R | Undefined | 12.2.8/190 |
| 4004_8020 | Universally Unique Identifier Middle High Register (SIM_UUIDMH) | 32 | R | Undefined | 12.2.9/191 |
| 4004_8024 | Clock Divider Register (SIM_CLKDIV) | 32 | R/W | See section | 12.2.10/191 |

12.2.1 System Reset Status and ID Register (SIM_SRSID)

Address: 4004_8000h base + 0h offset = 4004_8000h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-------|-------|---------|----|----|----------|----|--------|----|-------|-----|------|----|-------|-----|----|----|
| R | FAMID | | | | SUBFAMID | | | | RevID | | | | PINID | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | * | * | * | * | * | * | * | * |
| LVD | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | * | * | * | * | * | * | * | * |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | SACKERR | | 0 | MDMAP | SW | LOCKUP | 0 | POR | PIN | WDOG | 0 | LOC | LVD | 0 | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| LVD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | u* | 0 | 0 | 0 | 0 | 0 | 1 | 0 |

* Notes:

- RevID field: Decided by device revision number.
- PINID field: Decided by device pin number.
- u = Unaffected by reset.

SIM_SRSID field descriptions

| Field | Description |
|-------------------|--|
| 31–28 FAMID | Kinetis family ID 0000 KE0x family. other Reserved. |
| 27–24 SUBFAMID | Kinetis sub-family ID 0100 KEx4 sub-family 0110 KEx6 sub-family other Reserved |
| 23–20 RevID | Device Revision Number |
| 19–16 PINID | Device Pin ID 0000 8-pin 0001 16-pin 0010 20-pin 0011 24-pin 0100 32-pin 0101 44-pin 0110 48-pin 0111 64-pin 1000 80-pin 1010 100-pin other Reserved |
| 15–14 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 13 SACKERR | Stop Mode Acknowledge Error Reset Indicates that after an attempt to enter Stop mode, a reset has been caused by the failure of one or more IICs to acknowledge within approximately one second to enter stop mode. 0 Reset is not caused by peripheral failure to acknowledge attempt to enter Stop mode. 1 Reset is caused by peripheral failure to acknowledge attempt to enter Stop mode. |
| 12 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 11 MDMAP | MDM-AP System Reset Request Indicates a reset has been caused by the host debugger system setting of the System Reset Request field in the MDM-AP Control Register. 0 Reset is not caused by host debugger system setting of the System Reset Request bit. 1 Reset is caused by host debugger system setting of the System Reset Request bit. |
| 10 SW | Software Indicates a reset has been caused by software setting of SYSRESETREQ bit in Application Interrupt and Reset Control Register in the ARM core. 0 Reset is not caused by software setting of SYSRESETREQ bit. 1 Reset caused by software setting of SYSRESETREQ bit |

Table continues on the next page...

SIM_SRSID field descriptions (continued)

| Field | Description |
|-----------------|--|
| 9 LOCKUP | <p>Core Lockup</p> <p>Indicates a reset has been caused by the ARM core indication of a LOCKUP event.</p> <p>0 Reset is not caused by core LOCKUP event. 1 Reset is caused by core LOCKUP event.</p> |
| 8 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 7 POR | <p>Power-On Reset</p> <p>Causes reset by the power-on detection logic. When the internal supply voltage is ramping up, the low-voltage reset (LVR) status field is also set at that time, to indicate that the reset has occurred while the internal supply was below the LVR threshold.</p> <p>NOTE: This bit POR to 1, LVR to uncertain value and reset to 0 at any other conditions.</p> <p>0 Reset not caused by POR. 1 POR caused reset.</p> |
| 6 PIN | <p>External Reset Pin</p> <p>Causes reset by an active low-level on the external reset pin.</p> <p>0 Reset is not caused by external reset pin. 1 Reset came from external reset pin.</p> |
| 5 WDOG | <p>Watchdog (WDOG)</p> <p>Causes reset by the WDOG timer timing out. This reset source may be blocked by WDOG_CS1[EN] = 0.</p> <p>0 Reset is not caused by WDOG timeout. 1 Reset is caused by WDOG timeout.</p> |
| 4–3 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 2 LOC | <p>Internal Clock Source Module Reset</p> <p>Causes reset by an ICS module reset.</p> <p>0 Reset is not caused by the ICS module. 1 Reset is caused by the ICS module.</p> |
| 1 LVD | <p>Low Voltage Detect</p> <p>If PMC_SPMSC1[LVDRE] is set in Run mode or both PMC_SPMSC1[LVDRE] and PMC_SPMSC1[LVDSE] are set in Stop mode, and the supply drops below the LVD trip voltage, an LVD reset will occur. This field is also set by POR.</p> <p>NOTE: This field is reset to 1 on POR and LVR, and reset to 0 on other reset.</p> <p>0 Reset is not caused by LVD trip or POR. 1 Reset is caused by LVD trip or POR.</p> |
| 0 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |

12.2.2 System Options Register 0 (SIM_SOPT0)

NOTE

RSTPE and NMIE are write-once only on each reset.

Address: 4004_8000h base + 4h offset = 4004_8004h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-------------|-------|----|----|----|----|----|----|----|--------|-------|----|----|----|-------|--------|----|
| R | DELAY | | | | | | | | DLYACT | ADHWT | | | | CLKOE | BUSREF | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| POR/ LVD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|-------|----|----|-------|------|------|-------|---|---|---|---|---|------|-------|------|---|
| R | TXDME | 0 | 0 | RXDCE | ACIC | RTCC | RXDFE | 0 | 0 | 0 | 0 | 0 | SWDE | RSTPE | NMIE | 0 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | u* | u* | 0 |
| POR/ LVD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 |

* Notes:

- u = Unaffected by reset.

SIM_SOPT0 field descriptions

| Field | Description |
|----------------|--|
| 31–24 DELAY | FTM2 Trigger Delay Specifies the delay from FTM2 initial or match trigger to ADC hardware trigger when 1 is written to ADHWT. The 8-bit modulo value allows the delay from 0 to 255 upon the BUSREF clock settings. This is a |

Table continues on the next page...

SIM_SOPT0 field descriptions (continued)

| Field | Description |
|-----------------|--|
| | one-shot counter that starts ticking when the trigger arrives and stops ticking when the counter value reaches the modulo value that is defined. |
| 23 DLYACT | FTM2 Trigger Delay Active This read-only field specifies the status if the FTM2 initial or match delay is active. This field is set when an FTM2 trigger arrives and the delay counter is ticking. Otherwise, this field will be clear. 0 The delay is inactive. 1 The delay is active. |
| 22–20 ADHWT | ADC Hardware Trigger Source Selects the ADC hardware trigger source. All trigger sources start ADC conversion on rising-edge. 000 RTC overflow as the ADC hardware trigger 001 FTM0 as the ADC hardware trigger 010 FTM2 init trigger with 8-bit programmable counter delay 011 FTM2 match trigger with 8-bit programmable counter delay 100 PIT channel0 overflow as the ADC hardware trigger 101 PIT channel1 overflow as the ADC hardware trigger 110 ACMP0 out as the ADC hardware trigger. 111 ACMP1 out as the ADC hardware trigger |
| 19 CLKOE | Bus Clock Output Enable Enables bus clock output on 0 Bus clock output is disabled on PTH2. 1 Bus clock output is enabled on PTH2. |
| 18–16 BUSREF | BUS Clock Output select Enables bus clock output via an optional prescaler. 000 Bus 001 Bus divided by 2 010 Bus divided by 4 011 Bus divided by 8 100 Bus divided by 16 101 Bus divided by 32 110 Bus divided by 64 111 Bus divided by 128 |
| 15 TXDME | UART0_TX Modulation Select Enables the UART0_TX output modulated by FTM0 channel 0. 0 UART0_TX output is connected to pinout directly. 1 UART0_TX output is modulated by FTM0 channel 0 before mapped to pinout. |
| 14 FTMSYNC | FTM2 Synchronization Select Generates a PWM synchronization trigger to the FTM2 module if 1 is written to this field. 0 No synchronization triggered. 1 Generates a PWM synchronization trigger to the FTM2 modules. |

Table continues on the next page...

SIM_SOPT0 field descriptions (continued)

| Field | Description |
|-----------------|--|
| 13 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 12 RXDCE | UART0_RX Capture Select Enables the UART0_RX to be captured by FTM0 channel 1. 0 UART0_RX input signal is connected to the UART0 module only. 1 UART0_RX input signal is connected to the UART0 module and FTM0 channel 1. |
| 11 ACIC | Analog Comparator to Input Capture Enable Connects the output of ACMP0 to FTM1 input channel 0. 0 ACMP0 output is not connected to FTM1 input channel 0. 1 ACMP0 output is connected to FTM1 input channel 0. |
| 10 RTCC | Real-Time Counter Capture Allows the Real-time Counter (RTC) overflow to be captured by FTM1 channel 1. 0 RTC overflow is not connected to FTM1 input channel 1. 1 RTC overflow is connected to FTM1 input channel 1. |
| 9–8 RXDFE | UART0 RxD Filter Select Enables the UART0 RxD input to be filtered by ACMP. When this function is enabled, any signal tagged with ACMP inputs can be regarded UART0. 00 RXD0 input signal is connected to UART0 module directly. 01 RXD0 input signal is filtered by ACMP0, then injected to UART0. 10 RXD0 input signal is filtered by ACMP1, then injected to UART0. 11 Reserved. |
| 7–6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5 ACTRG | ACMP Trigger FTM2 selection Selects the two ACMP outputs as the trigger0 input of FTM2 0 ACMP0 out 1 ACMP1 out |
| 4 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 3 SWDE | Single Wire Debug Port Pin Enable Enables the PTA4/KBI0_P4/ACMP0_OUT/SWD_DIO pin to function as SWD_DIO, and PTC4/KBI0_P20/RTC_CLKOUT/FTM1_CH0/ACMP0_IN2/SWD_CLK pin function as SWD_CLK. When clear, the two pins function as PTA4 and PTC4. This pin defaults to the SWD_DIO and SWD_CLK function following any MCU reset. 0 PTA4/KBI0_P4/ACMP0_OUT/SWD_DIO as PTA4 or ACMP0_OUT function, PTC4/KBI0_P20/RTC_CLKOUT/FTM1_CH0/ACMP0_IN2/SWD_CLK as PTC4, KBI0_P20, RTC_CLKOUT, FTM1_CH0, OR ACMP0_IN2 function. 1 PTA4/KBI0_P4/ACMP0_OUT/SWD_DIO as SWD_DIO function, PTC4/KBI0_P20/RTC_CLKOUT/FTM1_CH0/ACMP0_IN2/SWD_CLK as SWD_CLK function. |

Table continues on the next page...

SIM_SOPT0 field descriptions (continued)

| Field | Description |
|---------------|---|
| 2 RSTPE | <p>RESET Pin Enable</p> <p>This write-once field can be written after any reset. When RSTPE is set, the PTA5/KBI0_P5/IRQ/TCLK0/RESET pin functions as RESET. When clear, the pin functions as one of its alternative functions. This pin defaults to RESET following an MCU POR. Other resets will not affect this field. When RSTPE is set, an internal pullup device on RESET is enabled.</p> <p>0 PTA5/KBI0_P5/IRQ/TCLK0/RESET pin functions as PTA5/KBI0_P5/IRQ/TCLK0. 1 PTA5/KBI0_P5/IRQ/TCLK0/RESET pin functions as RESET.</p> |
| 1 NMIE | <p>NMI Pin Enable</p> <p>This write-once field can be written after any reset. When NMIE is set, the PTB4/KBI0_P12/FTM2_CH4/SPI0_MISO/ACMP1_IN2/NMI pin functions as NMI. When clear, the pin functions as one of its alternative functions. This pin defaults to NMI following an MCU POR. Other resets will not affect this bit. When NMIE is set, an internal pullup device on NMI is enabled.</p> <p>0 PTB4/KBI0_P12/FTM2_CH4/SPI0_MISO/ACMP1_IN2/NMI pin functions as PTB4, KBI0_P12, FTM2_CH4, SPI0_MISO or ACMP1_IN2. 1 PTB4/KBI0_P12/FTM2_CH4/SPI0_MISO/ACMP1_IN2/NMI pin functions as NMI.</p> |
| 0 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |

12.2.3 System Options Register (SIM_SOPT1)**NOTE**

RSTPE and NMIE are write-only on each reset.

Address: 4004_8000h base + 8h offset = 4004_8008h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----------|----|----|----|--------|----|----------|----------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | UARTPWTS | | | | ACPWTS | 0 | I2C0OINV | I2C04WEN |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SIM_SOPT1 field descriptions

| Field | Description |
|------------------|--|
| 31–6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5–4 UARTPWTS | PWT UART RX select This field select PWTIN3 input signal 00 UART0 RX is connected to PWTIN3. 01 UART1 RX is connected to PWTIN3. 10 UART2 RX is connected to PWTIN3. 11 Reserved. |
| 3 ACPWTS | PWT ACMP_OUT select This field select PWTIN2 input signal. 0 ACMP1_OUT is connected to PWTIN2. 1 ACMP0_OUT is connected to PWTIN2. |
| 2 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 1 I2C0OINV | I2C0 Output Invert This field controls inversion of the I2C0 output. NOTE: This bit does not work when I2C0 4-wire interface is disabled (I2C04WEN = 0) 0 Under I2C0 4-wire interface configuration, SDA_OUT and SCL_OUT are not inverted before output 1 Under I2C0 4-wire interface configuration, SDA_OUT and SCL_OUT are inverted before output |
| 0 I2C04WEN | I2C0 4-Wire Interface Enable This field controls I2C0 4-wire interface configuration. NOTE: This field works only when SIM_PINSEL0[I2C0PS] is 0. 0 I2C0 4-wire interface configuration is disabled. 1 I2C0 4-wire interface configuration is enabled. |

12.2.4 Pin Selection Register 0 (SIM_PINSEL0)

Address: 4004_8000h base + Ch offset = 4004_800Ch

| | | | | | | | | | | | | | | | | |
|-------|----------|----|----|----|-----------|---------|-----------|---------|-----------|--------|--------|-------|----|-------|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | PWTCLKPS | | | | FTM2CLKPS | | FTM1CLKPS | | FTM0CLKPS | | 0 | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | FTM1PS1 | FTM1PS0 | FTM0PS1 | FTM0PS0 | UART0PS | SPI0PS | I2C0PS | RTCPS | 0 | IRQPS | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SIM_PINSEL0 field descriptions

| Field | Description |
|--------------------|---|
| 31–30 PWTCLKPS | <p>PWT TCLK Pin Select</p> <p>Selects the TCLK pinout.</p> <p>00 Selects TCLK0 for PWT module. 01 Selects TCLK1 for PWT module. 10 Selects TCLK2 for PWT module. 11 Reserved.</p> |
| 29–28 FTM2CLKPS | <p>FTM2 TCLK Pin Select</p> <p>Selects the TCLK pinout.</p> <p>00 Selects TCLK0 for FTM2 module.. 01 Selects TCLK1 for FTM2 module. 10 Selects TCLK2 for FTM2 module. 11 Reserved.</p> |
| 27–26 FTM1CLKPS | <p>FTM1 TCLK Pin Select</p> <p>Selects the TCLK pinout.</p> <p>00 Selects TCLK0 for FTM1 module.. 01 Selects TCLK1 for FTM1 module. 10 Selects TCLK2 for FTM1 module. 11 Reserved.</p> |
| 25–24 FTM0CLKPS | <p>FTM0 TCLK Pin Select</p> <p>Selects the TCLK pinout.</p> <p>00 Selects TCLK0 for FTM0 module.. 01 Selects TCLK1 for FTM0 module.</p> |

Table continues on the next page...

SIM_PINSEL0 field descriptions (continued)

| Field | Description |
|-------------------|--|
| | 10 Selects TCLK2 for FTM0 module. 11 Reserved. |
| 23–12 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 11 FTM1PS1 | FTM1_CH1 Port Pin Select Selects the FTM1_CH1 channel pinout. 0 FTM1_CH1 channels are mapped on PTC5. 1 FTM1_CH1 channels are mapped on PTE7. |
| 10 FTM1PS0 | FTM1_CH0 Port Pin Select Selects the FTM1_CH0 channel pinout. 0 FTM1_CH0 channels are mapped on PTC4. 1 FTM1_CH0 channels are mapped on PTH2. |
| 9 FTM0PS1 | FTM0_CH1 Port Pin Select Selects the FTM0_CH1 channel pinout. 0 FTM0_CH1 channels are mapped on PTA1. 1 FTM0_CH1 channels are mapped on PTB3. |
| 8 FTM0PS0 | FTM0_CH0 Port Pin Select Selects the FTM0_CH0 channel pinout. 0 FTM0_CH0 channels are mapped on PTA0. 1 FTM0_CH0 channels are mapped on PTB2. |
| 7 UART0PS | UART0 Pin Select Selects the UART0 pinouts. 0 UART0_RX and UART0_TX are mapped on PTB0 and PTB1. 1 UART0_RX and UART0_TX are mapped on PTA2 and PTA3. |
| 6 SPI0PS | SPI0 Pin Select Selects the SPI0 Pinouts. 0 SPI0_SCK, SPI0_MOSI, SPI0_MISO, and SPI0_PCS are mapped on PTB2, PTB3, PTB4, and PTB5. 1 SPI0_SCK, SPI0_MOSI, SPI0_MISO, and SPI0_PCS are mapped on PTE0, PTE1, PTE2, and PTE3. |
| 5 I2C0PS | I2C0 Port Pin Select Selects the I2C0 port pins. 0 I2C0_SCL and I2C0_SDA are mapped on PTA3 and PTA2, respectively. 1 I2C0_SCL and I2C0_SDA are mapped on PTB7 and PTB6, respectively. |
| 4 RTCP5 | RTCO Pin Select Selects the RTCO port pins. |

Table continues on the next page...

SIM_PINSEL0 field descriptions (continued)

| Field | Description |
|---------------|---|
| | 0 RTCO is mapped on PTC4. 1 RTCO is mapped on PTC5. |
| 3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| IRQPS | IRQ Port Pin Select Selects the IRQ port pins. 000 IRQ is mapped on PTA5. 001 IRQ is mapped on PTI0. 010 IRQ is mapped on PTI1. 011 IRQ is mapped on PTI2. 100 IRQ is mapped on PTI3. 101 IRQ is mapped on PTI4. 110 IRQ is mapped on PTI5. 111 IRQ is mapped on PTI6. |

12.2.5 Pin Selection Register 1 (SIM_PINSEL1)

Address: 4004_8000h base + 10h offset = 4004_8010h

| | | | | | | | | | | | | | | | | |
|-------|----------|----------|---------|---------|--------|--------|---------|---------|---------|----|---------|----|---------|----|---------|---------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | MSCANPS |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PWTIN1PS | PWTIN0PS | UART2PS | UART1PS | SPI1PS | I2C1PS | FTM2PS5 | FTM2PS4 | FTM2PS3 | | FTM2PS2 | | FTM2PS1 | | FTM2PS0 | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SIM_PINSEL1 field descriptions

| Field | Description |
|-------------------|---|
| 31–17 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 16 MSCANPS | MSCAN Pin Select Selects the MSCAN pinout. 0 CAN_TX on PTC7, CAN_RX on PTC6. 1 CAN_TX on PTE7, CAN_RX on PTH2. |

Table continues on the next page...

SIM_PINSEL1 field descriptions (continued)

| Field | Description |
|----------------|---|
| 15 PWTIN1PS | <p>PWTIN1 Pin Select</p> <p>Selects the PWTIN1 pinout.</p> <p>0 PWTIN1 on PTB0. 1 PWTIN1 on PTH7.</p> |
| 14 PWTIN0PS | <p>PWTIN0 Pin Select</p> <p>Selects the PWTIN0 pinout.</p> <p>0 PWTIN0 on PTD5. 1 PWTIN0 on PTE2.</p> |
| 13 UART2PS | <p>UART2 Pin Select</p> <p>Selects the UART2 pinout.</p> <p>0 UART2_TX on PTD7, UART2_RX on PTD6. 1 UART2_TX on PTI1, UART2_RX on PTI0.</p> |
| 12 UART1PS | <p>UART1 Pin Select</p> <p>Selects the UART1 pinout.</p> <p>0 UART1_TX on PTC7, UART1_RX on PTC6. 1 UART1_TX on PTF3, UART1_RX on PTF2.</p> |
| 11 SPI1PS | <p>SPI1 Pin Select</p> <p>Selects the SPI1 pinout.</p> <p>0 SPI1_SCK, SPI1_MOSI, SPI1_MISO, and SPI1_PCS are mapped on PTD0, PTD1, PTD2, and PTD3. 1 SPI1_SCK, SPI1_MOSI, SPI1_MISO, and SPI1_PCS are mapped on PTG4, PTG5, PTG6, and PTG7.</p> |
| 10 I2C1PS | <p>I2C1 Pin Select</p> <p>Selects the I2C1 pinout.</p> <p>0 I2C1_SCL on PTE1, I2C1_SDA on PTE0. 1 I2C1_SCL on PTH4, I2C1_SDA on PTH3.</p> |
| 9 FTM2PS5 | <p>FTM2 Channel 5 Pin Select</p> <p>Selects the FTM2 Channel 5 pinout.</p> <p>0 FTM2 CH5 mapped on PTB5. 1 FTM2 CH5 mapped on PTG7.</p> |
| 8 FTM2PS4 | <p>FTM2 Channel4 Pin Select</p> <p>Selects the FTM2 Channel4 pinout.</p> <p>0 FTM2 CH4 mapped on PTB4. 1 FTM2 CH4 mapped on PTG6.</p> |
| 7–6 FTM2PS3 | <p>FTM2 Channel 3 Pin Select</p> <p>Selects the FTM2 Channel 3 pinout.</p> |

Table continues on the next page...

SIM_PINSEL1 field descriptions (continued)

| Field | Description |
|----------------|--|
| | 00 FTM2 CH3 mapped on PTC3. 01 FTM2 CH3 mapped on PTD1. 10 FTM2 CH3 mapped on PTG5. 11 Reserved. |
| 5–4 FTM2PS2 | FTM2 Channel 2 Pin Select Selects the FTM2 Channel 2 pinout. 00 FTM2 CH2 mapped on PTC2. 01 FTM2 CH2 mapped on PTD0. 10 FTM2 CH2 mapped on PTG4. 11 Reserved. |
| 3–2 FTM2PS1 | FTM2 Channel 1 Pin Select Selects the FTM2 Channel 1 pinout. 00 FTM2 CH1 mapped on PTC1. 01 FTM2 CH1 mapped on PTH1. 10 FTM2 CH1 mapped on PTF1. 11 Reserved. |
| FTM2PS0 | FTM2 Channel 0 Pin Select Selects the FTM2 Channel 0 pinout. 00 FTM2 CH0 mapped on PTC0. 01 FTM2 CH0 mapped on PTH0. 10 FTM2 CH0 mapped on PTF0. 11 Reserved. |

12.2.6 System Clock Gating Control Register (SIM_SCGC)

Address: 4004_8000h base + 14h offset = 4004_8014h

| | | | | | | | | | | | | | | | | |
|-------|-------|-------|-----|-------|-----|-----|------|------|------|-------|-------|-------|------|------|------|------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | | | | 0 | | 0 | | | 0 | | | | | | | |
| W | ACMP1 | ACMP0 | ADC | | IRQ | | KBI1 | KBI0 | | UART2 | UART1 | UART0 | SPI1 | SPI0 | I2C1 | I2C0 |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | | 0 | | | 0 | | 0 | | | | | | 0 | | | |
| W | MSCAN | | SWD | FLASH | | CRC | | | FTM2 | FTM1 | FTM0 | PWT | | | PIT | RTC |
| Reset | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SIM_SCGC field descriptions

| Field | Description |
|----------------|---|
| 31 ACMP1 | ACMP1 Clock Gate Control Controls the clock gate to the ACMP1 module. 0 Bus clock to the ACMP1 module is disabled. 1 Bus clock to the ACMP1 module is enabled. |
| 30 ACMP0 | ACMP0 Clock Gate Control Controls the clock gate to the ACMP0 module. 0 Bus clock to the ACMP0 module is disabled. 1 Bus clock to the ACMP0 module is enabled. |
| 29 ADC | ADC Clock Gate Control Controls the clock gate to the ADC module. 0 Bus clock to the ADC module is disabled. 1 Bus clock to the ADC module is enabled. |
| 28 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 27 IRQ | IRQ Clock Gate Control Controls the clock gate to the IRQ module. 0 Bus clock to the IRQ module is disabled. 1 Bus clock to the IRQ module is enabled. |
| 26 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 25 KBI1 | KBI1 Clock Gate Control Controls the clock gate to the KBI1 module. 0 Bus clock to the KBI1 module is disabled. 1 Bus clock to the KBI1 module is enabled. |
| 24 KBI0 | KBI0 Clock Gate Control Controls the clock gate to the KBI0 module. 0 Bus clock to the KBI0 module is disabled. 1 Bus clock to the KBI0 module is enabled. |
| 23 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 22 UART2 | UART2 Clock Gate Control Controls the clock gate to the UART2 module. 0 Bus clock to the UART2 module is disabled. 1 Bus clock to the UART2 module is enabled. |
| 21 UART1 | UART1 Clock Gate Control Controls the clock gate to the UART1 module. |

Table continues on the next page...

SIM_SCGC field descriptions (continued)

| Field | Description |
|----------------|--|
| | 0 Bus clock to the UART1 module is disabled. 1 Bus clock to the UART1 module is enabled. |
| 20 UART0 | UART0 Clock Gate Control Controls the clock gate to the UART0 module. 0 Bus clock to the UART0 module is disabled. 1 Bus clock to the UART0 module is enabled. |
| 19 SPI1 | SPI1 Clock Gate Control Controls the clock gate to the SPI1 module. 0 Bus clock to the SPI1 module is disabled. 1 Bus clock to the SPI1 module is enabled. |
| 18 SPI0 | SPI0 Clock Gate Control Controls the clock gate to the SPI0 module. 0 Bus clock to the SPI0 module is disabled. 1 Bus clock to the SPI0 module is enabled. |
| 17 I2C1 | I2C1 Clock Gate Control Controls the clock gate to the I2C1 module. 0 Bus clock to the I2C1 module is disabled. 1 Bus clock to the I2C1 module is enabled. |
| 16 I2C0 | I2C0 Clock Gate Control Controls the clock gate to the I2C0 module. 0 Bus clock to the I2C0 module is disabled. 1 Bus clock to the I2C0 module is enabled. |
| 15 MSCAN | MSCAN Clock Gate Control Controls the clock gate to the MSCAN module. 0 Bus clock to the MSCAN module is disabled. 1 Bus clock to the MSCAN module is enabled. |
| 14 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 13 SWD | SWD (single wire debugger) Clock Gate Control Controls the clock gate to the SWD module. 0 Bus clock to the SWD module is disabled. 1 Bus clock to the SWD module is enabled. |
| 12 FLASH | Flash Clock Gate Control Controls the clock gate to the flash module. |

Table continues on the next page...

SIM_SCGC field descriptions (continued)

| Field | Description |
|-----------------|---|
| | 0 Bus clock to the flash module is disabled. 1 Bus clock to the flash module is enabled. |
| 11 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 10 CRC | CRC Clock Gate Control Controls the clock gate to the CRC module. 0 Bus clock to the CRC module is disabled. 1 Bus clock to the CRC module is enabled. |
| 9–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 FTM2 | FTM2 Clock Gate Control Controls the clock gate to the FTM2 module. 0 Bus clock to the FTM2 module is disabled. 1 Bus clock to the FTM2 module is enabled. |
| 6 FTM1 | FTM1 Clock Gate Control Controls the clock gate to the FTM1 module. 0 Bus clock to the FTM1 module is disabled. 1 Bus clock to the FTM1 module is enabled. |
| 5 FTM0 | FTM0 Clock Gate Control Controls the clock gate to the FTM0 module. 0 Bus clock to the FTM0 module is disabled. 1 Bus clock to the FTM0 module is enabled. |
| 4 PWT | PWT Clock Gate Control Controls the clock gate to the PWT module. 0 Timer clock to the PWT module is disabled. 1 Timer clock to the PWT module is enabled. |
| 3–2 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 1 PIT | PIT Clock Gate Control Controls the clock gate to the PIT module. 0 Bus clock to the PIT module is disabled. 1 Bus clock to the PIT module is enabled. |
| 0 RTC | RTC Clock Gate Control Controls the clock gate to the RTC module. 0 Bus clock to the RTC module is disabled. 1 Bus clock to the RTC module is enabled. |

12.2.7 Universally Unique Identifier Low Register (SIM_UUIDL)

The read-only SIM_UUIDL register contains a series of number to identify the unique device in the family.

Address: 4004_8000h base + 18h offset = 4004_8018h

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | ID[31:0] | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | |

* Notes:

- x = Undefined at reset.

SIM_UUIDL field descriptions

| Field | Description |
|----------|-------------------------------|
| ID[31:0] | Universally Unique Identifier |

12.2.8 Universally Unique Identifier Middle Low Register (SIM_UUIDML)

The read-only SIM_UUIDML register contains a series of number to identify the unique device in the family.

Address: 4004_8000h base + 1Ch offset = 4004_801Ch

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | ID[63:32] | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | |

* Notes:

- x = Undefined at reset.

SIM_UUIDML field descriptions

| Field | Description |
|-----------|-------------------------------|
| ID[63:32] | Universally Unique Identifier |

12.2.9 Universally Unique Identifier Middle High Register (SIM_UUIDMH)

The read-only SIM_UUIDMH register contains a series of number to identify the unique device in the family.

Address: 4004_8000h base + 20h offset = 4004_8020h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|
| R | 0 | | | | | | | | | | | | | | | | ID[80:64] | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | x* | |

* Notes:

- x = Undefined at reset.

SIM_UUIDMH field descriptions

| Field | Description |
|-------------------|---|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ID[80:64] | Universally Unique Identifier |

12.2.10 Clock Divider Register (SIM_CLKDIV)

This register sets the divide value for the clock.

NOTE

Carefully configure the OUTDIV1 and OUTDIV2 to avoid bus clock frequency higher than 24 MHz.

Address: 4004_8000h base + 24h offset = 4004_8024h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-------------|----|----|---------|----|----|----|----|----|----|----|----|---------|----|----|----|----|
| R | 0 | | OUTDIV1 | | | | 0 | | | 0 | | OUTDIV3 | | 0 | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | u* | u* | 0 | 0 | 0 | u* | 0 | 0 | 0 | u* | 0 | 0 | 0 | 0 |
| POR/ LVD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Functional description

| | | | | | | | | | | | | | | | | |
|-------------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| POR/ LVD | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

* Notes:

- u = Unaffected by reset.

SIM_CLKDIV field descriptions

| Field | Description |
|-------------------|---|
| 31–30 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 29–28 OUTDIV1 | Clock 1 output divider value This field sets the divide value for the core/system clock., 00 Same as ICSOUTCLK. 01 ICSOUTCLK divides by 2. 10 ICSOUTCLK divides by 3. 11 ICSOUTCLK divides by 4. |
| 27–25 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 24 OUTDIV2 | Clock 2 output divider value This field sets the divide value for the bus/FLASH, follow OUTDIV1. 0 Not divided from divider1. 1 Divide by 2 from divider1. |
| 23–21 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 20 OUTDIV3 | Clock 3 output divider value This field sets the divide value for the timers(FTM0, FTM1, FTM2,PWT). 0 Same as ICSOUTCLK. 1 ICSOUTCLK divides by 2. |
| Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

12.3 Functional description

See [Introduction](#) section.

Chapter 13

Power Management Controller (PMC)

13.1 Introduction

This chapter describes the functionality of the individual modules in the chip's low-power modes and the operation of Power Management Controller module.

13.2 Low voltage detect (LVD) system

This device includes a system to protect against low voltage conditions in order to protect memory contents and control MCU system states during supply voltage variations. This system consists of a power-on reset (POR) circuit and an LVD circuit with a user selectable trip voltage, either high (V_{LVDH}) or low (V_{LVDL}). The LVD circuit is enabled when SPMSC1[LVDE] is set and the trip voltage is selected by SPMSC2[LVDV]. The LVD is disabled upon entering the Stop mode unless SPMSC1[LVDSE] is set. If SPMSC1[LVDSE] and SPMSC1[LVDE] are both set, the current consumption will be greater in Stop mode with the LVD system enabled.

The following figure presents the block diagram of the low-voltage detect (LVD) system.

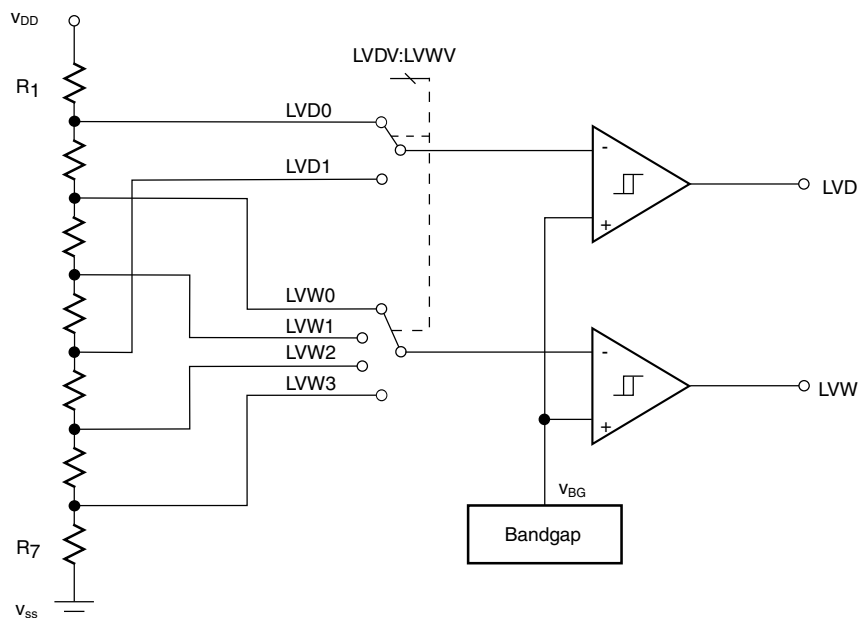


Figure 13-1. Low voltage detect (LVD) block diagram

13.2.1 Power-on reset (POR) operation

When power is initially applied to the MCU, or when the supply voltage drops below the V_{POR} level, the POR circuit will cause a reset condition. As the supply voltage rises, the LVD circuit will hold the chip in reset until the supply has risen above the V_{LVDL} level. Both the `SIM_SRSID[POR]` and `SIM_SRSID[LVD]` are set following a POR.

13.2.2 LVD reset operation

The LVD can be configured to generate a reset upon detection of a low-voltage condition by setting `SPMSC1[LVDRE]` to 1. After an LVD reset has occurred, the LVD system will hold the MCU in reset until the supply voltage has risen above the level determined by `LVDV`. `SIM_SRSID[LVD]` is set following either an LVD reset or POR.

13.2.3 LVD enabled in Stop mode

The LVD system is capable of generating a reset when the supply voltage drops below the LVD voltage. If the LVD is enabled in Stop (both `SPMSC1[LVDE]` and `SPMSC1[LVDSE]` set to 1) at the time the CPU executes a `STOP` instruction, then the voltage regulator remains active during Stop mode.

13.2.4 Low-voltage warning (LVW)

The LVD system has a low voltage warning flag to indicate that the supply voltage is approaching the LVW voltage. When a low voltage condition is detected and the LVD circuit is configured for interrupt operation (SPMSC1[LVDE] set, SPMSC1[LVWIE] set), SPMSC1[LVWF] will be set and LVW interrupt will occur. There are four user-selectable trip voltages for the LVW upon each LVDV configuration. The trip voltage is selected by SPMSC2[LVWV].

13.3 Bandgap reference

This device includes an on-chip bandgap reference (≈ 1.2 V) connected to the ADC channel. The bandgap reference voltage will not drop under the full operating voltage even when the operating voltage is falling. This reference voltage acts as an ideal reference voltage for accurate measurements.

13.4 Memory map and register descriptions

PMC memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|----------------------------|
| 4007_D000 | System Power Management Status and Control 1 Register (PMC_SPMSC1) | 8 | R/W | 1Ch | 13.4.1/196 |
| 4007_D001 | System Power Management Status and Control 2 Register (PMC_SPMSC2) | 8 | R/W | 00h | 13.4.2/197 |

13.4.1 System Power Management Status and Control 1 Register (PMC_SPMSC1)

This high-page register contains status and control bits to support the low-voltage detection function, and to enable the bandgap voltage reference for use by the ADC module. This register must be written during the user's reset initialization program to set the desired controls, even if the desired settings are the same as the reset settings.

Address: 4007_D000h base + 0h offset = 4007_D000h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|--------|-------|-------|-------|------|---|------|
| Read | LVWF | 0 | LVWIE | LVDRE | LVDSE | LVDE | | BGBE |
| Write | | LVWACK | | | | | 0 | |
| Reset | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 0 |

PMC_SPMSC1 field descriptions

| Field | Description |
|-------------|--|
| 7 LVWF | <p>Low-Voltage Warning Flag</p> <p>Indicates the low-voltage warning status.</p> <p>NOTE: LVWF will be set in the case when V_{Supply} transitions below the trip point or after reset and V_{Supply} is already below V_{LVW}. LVWF may be 1 after power-on-reset, therefore, to use LVW interrupt function, before enabling LVWIE, LVWF must be cleared by writing LVWACK first.</p> <p>0 Low-voltage warning is not present. 1 Low-voltage warning is present or was present.</p> |
| 6 LVWACK | <p>Low-Voltage Warning Acknowledge</p> <p>If LVWF = 1, a low-voltage condition has occurred. To acknowledge this low-voltage warning, write 1 to LVWACK, which automatically clears LVWF to 0 if the low-voltage warning is no longer present.</p> |
| 5 LVWIE | <p>Low-Voltage Warning Interrupt Enable</p> <p>Enables hardware interrupt requests for LVWF.</p> <p>0 Hardware interrupt is disabled (use polling). 1 Requests a hardware interrupt when LVWF = 1.</p> |
| 4 LVDRE | <p>Low-Voltage Detect Reset Enable</p> <p>This write-once bit enables LVD events to generate a hardware reset (provided LVDE = 1).</p> <p>NOTE: This field can be written only one time after reset. Additional writes are ignored.</p> <p>If LVDRE = 0, use LVW to monitor status because no flag was assert.</p> <p>0 LVD events do not generate hardware resets. 1 Forces an MCU reset when an enabled low-voltage detect event occurs.</p> |
| 3 LVDSE | <p>Low-Voltage Detect Stop Enable</p> |

Table continues on the next page...

PMC_SPMSC1 field descriptions (continued)

| Field | Description |
|---------------|--|
| | <p>Provided LVDE = 1, this read/write field determines whether the low-voltage detect function operates when the MCU is in Stop mode.</p> <p>0 Low-voltage detect is disabled during Stop mode. 1 Low-voltage detect is enabled during Stop mode.</p> |
| 2 LVDE | <p>Low-Voltage Detect Enable</p> <p>This write-once bit enables low-voltage detect logic and qualifies the operation of other fields in this register.</p> <p>NOTE: This field can be written only one time after reset. Additional writes are ignored.</p> <p>0 LVD logic is disabled. 1 LVD logic is enabled.</p> |
| 1 Reserved | This field is reserved. |
| 0 BGBE | <p>Bandgap Buffer Enable</p> <p>Enables an internal buffer for the bandgap voltage reference for use by the ADC module on one of its internal channels or bandgap selected as ACMP's reference.</p> <p>0 Bandgap buffer is disabled. 1 Bandgap buffer is enabled.</p> |

13.4.2 System Power Management Status and Control 2 Register (PMC_SPMSC2)

This register is used to report the status of the low-voltage warning function, and to configure the Stop mode behavior of the MCU. This register should be written during the user's reset initialization program to set the desired controls, even if the desired settings are the same as the reset settings.

Address: 4007_D000h base + 1h offset = 4007_D001h

| | | | | | | | | |
|-------|---|------|------|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | LVDV | LVWV | | | 0 | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PMC_SPMSC2 field descriptions

| Field | Description |
|---------------|--|
| 7 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 6 LVDV | <p>Low-Voltage Detect Voltage Select</p> <p>This write-once bit selects the low-voltage detect (LVD) trip point setting. See data sheet for details.</p> |

Table continues on the next page...

PMC_SPMSC2 field descriptions (continued)

| Field | Description |
|-------------|--|
| | 0 Low trip point is selected ($V_{LVD} = V_{LVDL}$). 1 High trip point is selected ($V_{LVD} = V_{LV DH}$). |
| 5–4 LVWV | Low-Voltage Warning Voltage Select Selects the low-voltage warning (LVW) trip point voltage. See data sheet for details. 00 Low trip point is selected ($V_{LVW} = V_{LVW1}$). 01 Middle 1 trip point is selected ($V_{LVW} = V_{LVW2}$). 10 Middle 2 trip point is selected ($V_{LVW} = V_{LVW3}$). 11 High trip point is selected ($V_{LVW} = V_{LVW4}$). |
| Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

Chapter 14

Miscellaneous Control Module (MCM)

14.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The Miscellaneous Control Module (MCM) provides a myriad of miscellaneous control functions.

14.1.1 Features

The MCM includes the following features:

- Program-visible information on the platform configuration
- Flash controller speculation buffer and cache configurations

14.2 Memory map/register descriptions

The memory map and register descriptions found here describe the registers using byte addresses. The registers can be written only when in supervisor mode.

MCM memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-------------|----------------------------|
| F000_3008 | Crossbar Switch (AXBS) Slave Configuration (MCM_PLASC) | 16 | R | 0007h | 14.2.1/200 |
| F000_300A | Crossbar Switch (AXBS) Master Configuration (MCM_PLAMC) | 16 | R | 0001h | 14.2.2/200 |
| F000_300C | Platform Control Register (MCM_PLACR) | 32 | R/W | 0000_0800h | 14.2.3/201 |

14.2.1 Crossbar Switch (AXBS) Slave Configuration (MCM_PLASC)

PLASC is a 16-bit read-only register identifying the presence/absence of bus slave connections to the device's crossbar switch.

Address: F000_3000h base + 8h offset = F000_3008h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|-----|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | | | | ASC | | | | | | | |
| Write | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 |

MCM_PLASC field descriptions

| Field | Description |
|------------------|---|
| 15–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ASC | Each bit in the ASC field indicates whether there is a corresponding connection to the crossbar switch's slave input port. 0 A bus slave connection to AXBS input port <i>n</i> is absent. 1 A bus slave connection to AXBS input port <i>n</i> is present. |

14.2.2 Crossbar Switch (AXBS) Master Configuration (MCM_PLAMC)

PLAMC is a 16-bit read-only register identifying the presence/absence of bus master connections to the device's crossbar switch.

Address: F000_3000h base + Ah offset = F000_300Ah

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|-----|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | | | | AMC | | | | | | | |
| Write | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

MCM_PLAMC field descriptions

| Field | Description |
|------------------|--|
| 15–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| AMC | Each bit in the AMC field indicates whether there is a corresponding connection to the AXBS master input port. |

Table continues on the next page...

MCM_PLAMC field descriptions (continued)

| Field | Description |
|-------|--|
| 0 | A bus master connection to AXBS input port <i>n</i> is absent |
| 1 | A bus master connection to AXBS input port <i>n</i> is present |

14.2.3 Platform Control Register (MCM_PLACR)

The speculation buffer and cache in the flash memory controller is configurable via PLACR[15:10].

The speculation buffer is enabled only for instructions after reset. It is possible to have these states for the speculation buffer:

| DFCS | EFDS | Description |
|------|------|--|
| 0 | 0 | Speculation buffer is on for instruction and off for data. |
| 0 | 1 | Speculation buffer is on for instruction and on for data. |
| 1 | X | Speculation buffer is off. |

The cache in flash controller is enabled and caching both instruction and data type fetches after reset. It is possible to have these states for the cache:

| DFCC | DFCIC | DFCDA | Description |
|------|-------|-------|---|
| 0 | 0 | 0 | Cache is on for both instruction and data. |
| 0 | 0 | 1 | Cache is on for instruction and off for data. |
| 0 | 1 | 0 | Cache is off for instruction and on for data. |
| 0 | 1 | 1 | Cache is off for both instruction and data. |
| 1 | X | X | Cache is off. |

Memory map/register descriptions

Address: F000_3000h base + Ch offset = F000_300Ch

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | ESFC |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|------|------|------|-------|-------|------|---|---|---|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | DFCS | EFDS | DFCC | DFCIC | DFCDA | 0 | 0 | | | | | | | | | |
| W | | | | | | CFCC | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MCM_PLACR field descriptions

| Field | Description |
|-------------------|--|
| 31–17 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 16 ESFC | Enable Stalling Flash Controller Enables stalling flash controller when flash is busy. When software needs to access the flash memory while a flash memory resource is being manipulated by a flash command, software can enable a stall mechanism to avoid a read collision. The stall mechanism allows software to execute code from the same block on which flash operations are being performed. However, software must ensure the sector the flash operations are being performed on is not the same sector from which the code is executing. ESFC enables the stall mechanism. This bit must be set only just before the flash operation is executed and must be cleared when the operation completes. 0 Disable stalling flash controller when flash is busy. 1 Enable stalling flash controller when flash is busy. |
| 15 DFCS | Disable Flash Controller Speculation Disables flash controller speculation. 0 Enable flash controller speculation. 1 Disable flash controller speculation. |
| 14 EFDS | Enable Flash Data Speculation Enables flash data speculation. |

Table continues on the next page...

MCM_PLACR field descriptions (continued)

| Field | Description |
|-------------|---|
| | 0 Disable flash data speculation. 1 Enable flash data speculation. |
| 13 DFCC | Disable Flash Controller Cache Disables flash controller cache. 0 Enable flash controller cache. 1 Disable flash controller cache. |
| 12 DFCIC | Disable Flash Controller Instruction Caching Disables flash controller instruction caching. 0 Enable flash controller instruction caching. 1 Disable flash controller instruction caching. |
| 11 DFCDA | Disable Flash Controller Data Caching Disables flash controller data caching. 0 Enable flash controller data caching 1 Disable flash controller data caching. |
| 10 CFCC | Clear Flash Controller Cache Writing a 1 to this field clears the cache. Writing a 0 to this field is ignored. This field always reads as 0. |
| Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

Chapter 15

Peripheral Bridge (AIPS-Lite)

15.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The peripheral bridge converts the crossbar switch interface to an interface that can access most of the slave peripherals on this chip.

The peripheral bridge occupies 64 MB of the address space, which is divided into peripheral slots of 4 KB. (It might be possible that all the peripheral slots are not used. See the memory map chapter for details on slot assignments.) The bridge includes separate clock enable inputs for each of the slots to accommodate slower peripherals.

15.1.1 Features

Key features of the peripheral bridge are:

- Supports peripheral slots with 8-, 16-, and 32-bit datapath width

15.1.2 General operation

The slave devices connected to the peripheral bridge are modules which contain a programming model of control and status registers. The system masters read and write these registers through the peripheral bridge. The peripheral bridge performs a bus protocol conversion of the master transactions and generates the following as inputs to the peripherals:

- Module enables
- Module addresses

Functional description

- Transfer attributes
- Byte enables
- Write data

The peripheral bridge selects and captures read data from the peripheral interface and returns it to the crossbar switch.

The register maps of the peripherals are located on 4-KB boundaries. Each peripheral is allocated one or more 4-KB block(s) of the memory map.

The AIPS-Lite module uses the data width of accessed peripheral to perform proper data byte lane routing; bus decomposition (bus sizing) is performed when the access size is larger than the peripheral's data width.

15.2 Functional description

The peripheral bridge functions as a bus protocol translator between the crossbar switch and the slave peripheral bus.

The peripheral bridge manages all transactions destined for the attached slave devices and generates select signals for modules on the peripheral bus by decoding accesses within the attached address space.

15.2.1 Access support

All combinations of access size and peripheral data port width are supported. An access that is larger than the target peripheral's data width will be decomposed to multiple, smaller accesses. Bus decomposition is terminated by a transfer error caused by an access to an empty register area.

Chapter 16

Watchdog Timer (WDOG)

16.1 Introduction

The Watchdog Timer (WDOG) module is an independent timer that is available for system use. It provides a safety feature to ensure that software is executing as planned and that the CPU is not stuck in an infinite loop or executing unintended code. If the WDOG module is not serviced (refreshed) within a certain period, it resets the MCU.

16.1.1 Features

Features of the WDOG module include:

- Configurable clock source inputs independent from the:
 - bus clock
 - Internal 32 kHz RC oscillator
 - Internal 1 kHz RC oscillator
 - External clock source
- Programmable timeout period
 - Programmable 16-bit timeout value
 - Optional fixed 256 clock prescaler when longer timeout periods are needed
- Robust write sequence for counter refresh
 - Refresh sequence of writing 0x02A6 and then 0x80B4 within 16 bus clocks
- Window mode option for the refresh mechanism
 - Programmable 16-bit window value

- Provides robust check that program flow is faster than expected
- Early refresh attempts trigger a reset.
- Optional timeout interrupt to allow post-processing diagnostics
 - Interrupt request to CPU with interrupt vector for an interrupt service routine (ISR)
 - Forced reset occurs 128 bus clocks after the interrupt vector fetch.
- Configuration bits are write-once-after-reset to ensure watchdog configuration cannot be mistakenly altered.
- Robust write sequence for unlocking write-once configuration bits
 - Unlock sequence of writing 0x20C5 and then 0x28D9 within 16 bus clocks for allowing updates to write-once configuration bits
 - Software must make updates within 128 bus clocks after unlocking and before WDOG closing unlock window.

16.1.2 Block diagram

The following figure provides a block diagram of the WDOG module.

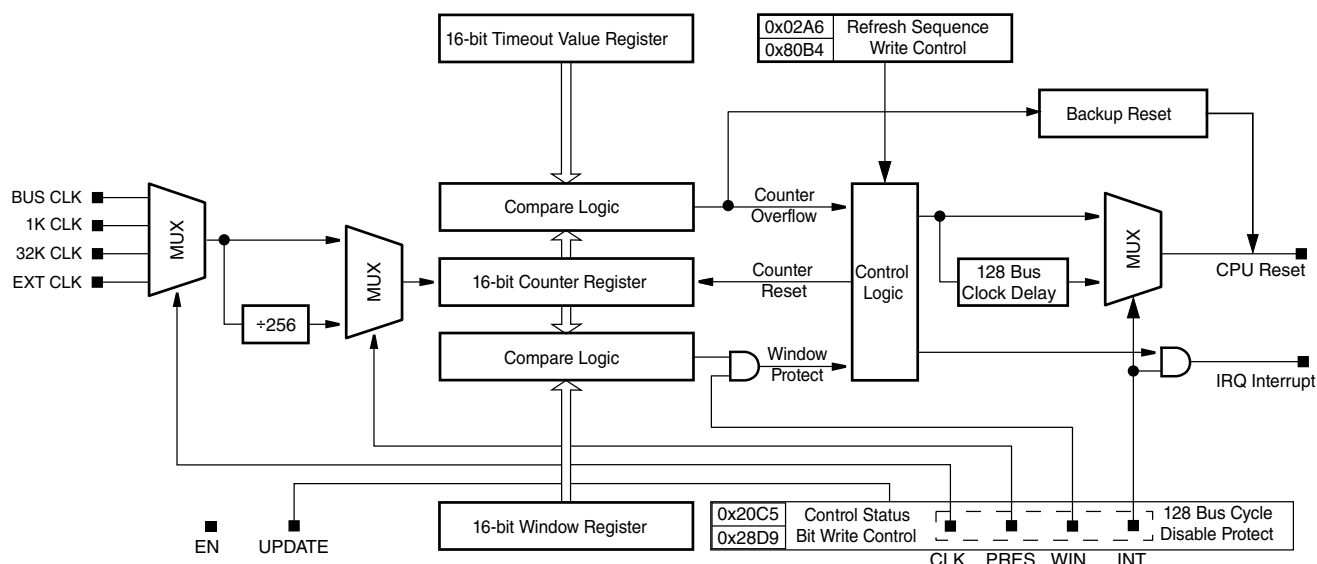


Figure 16-1. WDOG block diagram

16.2 Memory map and register definition

NOTE

If the device uses half-word to access WDOG_CNT, WDOG_TOVAL and WDOG_WIN, the transposed 16-bit bytes must follow the format of LowByte:HighByte. So 8-bit R/W is preferred.

WDOG memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|---|-----------------|--------|-------------|----------------------------|
| 4005_2000 | Watchdog Control and Status Register 1 (WDOG_CS1) | 8 | R/W | 80h | 16.2.1/209 |
| 4005_2001 | Watchdog Control and Status Register 2 (WDOG_CS2) | 8 | R/W | 01h | 16.2.2/211 |
| 4005_2002 | Watchdog Counter Register: High (WDOG_CNTH) | 8 | R | 00h | 16.2.3/212 |
| 4005_2003 | Watchdog Counter Register: Low (WDOG_CNTL) | 8 | R | 00h | 16.2.4/212 |
| 4005_2004 | Watchdog Timeout Value Register: High (WDOG_TOVALH) | 8 | R/W | 00h | 16.2.5/213 |
| 4005_2005 | Watchdog Timeout Value Register: Low (WDOG_TOVAL) | 8 | R/W | 04h | 16.2.6/213 |
| 4005_2006 | Watchdog Window Register: High (WDOG_WINH) | 8 | R/W | 00h | 16.2.7/214 |
| 4005_2007 | Watchdog Window Register: Low (WDOG_WINL) | 8 | R/W | 00h | 16.2.8/214 |

16.2.1 Watchdog Control and Status Register 1 (WDOG_CS1)

This section describes the function of Watchdog Control and Status Register 1.

NOTE

TST is cleared (0:0) on POR only. Any other reset does not affect the value of this field.

Address: 4005_2000h base + 0h offset = 4005_2000h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|-----|--------|-----|---|-----|------|------|
| Read | EN | INT | UPDATE | TST | | DBG | WAIT | STOP |
| Write | | | | | | | | |
| Reset | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

WDOG_CS1 field descriptions

| Field | Description |
|---------|--|
| 7 EN | <p>Watchdog Enable</p> <p>This write-once bit enables the watchdog counter to start counting.</p> <p>0 Watchdog disabled.</p> <p>1 Watchdog enabled.</p> |

Table continues on the next page...

WDOG_CS1 field descriptions (continued)

| Field | Description |
|-------------|--|
| 6 INT | <p>Watchdog Interrupt</p> <p>This write-once bit configures the watchdog to generate an interrupt request upon a reset-triggering event (timeout or illegal write to the watchdog), prior to forcing a reset. After the interrupt vector fetch, the reset occurs after a delay of 128 bus clocks.</p> <p>0 Watchdog interrupts are disabled. Watchdog resets are not delayed. 1 Watchdog interrupts are enabled. Watchdog resets are delayed by 128 bus clocks.</p> |
| 5 UPDATE | <p>Allow updates</p> <p>This write-once bit allows software to reconfigure the watchdog without a reset.</p> <p>0 Updates not allowed. After the initial configuration, the watchdog cannot be later modified without forcing a reset. 1 Updates allowed. Software can modify the watchdog configuration registers within 128 bus clocks after performing the unlock write sequence.</p> |
| 4–3 TST | <p>Watchdog Test</p> <p>Enables the fast test mode. The test mode allows software to exercise all bits of the counter to demonstrate that the watchdog is functioning properly. See the Fast testing of the watchdog section.</p> <p>This write-once field is cleared (0:0) on POR only. Any other reset does not affect the value of this field.</p> <p>00 Watchdog test mode disabled. 01 Watchdog user mode enabled. (Watchdog test mode disabled.) After testing the watchdog, software should use this setting to indicate that the watchdog is functioning normally in user mode. 10 Watchdog test mode enabled, only the low byte is used. WDOG_CNTL is compared with WDOG_TOVALL. 11 Watchdog test mode enabled, only the high byte is used. WDOG_CNTH is compared with WDOG_TOVALH.</p> |
| 2 DBG | <p>Debug Enable</p> <p>This write-once bit enables the watchdog to operate when the chip is in debug mode.</p> <p>0 Watchdog disabled in chip debug mode. 1 Watchdog enabled in chip debug mode.</p> |
| 1 WAIT | <p>Wait Enable</p> <p>This write-once bit enables the watchdog to operate when the chip is in wait mode.</p> <p>0 Watchdog disabled in chip wait mode. 1 Watchdog enabled in chip wait mode.</p> |
| 0 STOP | <p>Stop Enable</p> <p>This write-once bit enables the watchdog to operate when the chip is in stop mode.</p> <p>0 Watchdog disabled in chip stop mode. 1 Watchdog enabled in chip stop mode.</p> |

16.2.2 Watchdog Control and Status Register 2 (WDOG_CS2)

This section describes the function of the watchdog control and status register 2.

Address: 4005_2000h base + 1h offset = 4005_2001h

| | | | | | | | | |
|-------|-----|-----|---|------|---|---|---|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | WIN | FLG | 0 | PRES | 0 | | | |
| Write | | w1c | | | | | | CLK |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

WDOG_CS2 field descriptions

| Field | Description |
|-----------------|--|
| 7 WIN | <p>Watchdog Window</p> <p>This write-once bit enables window mode. See the Window mode section.</p> <p>0 Window mode disabled. 1 Window mode enabled.</p> |
| 6 FLG | <p>Watchdog Interrupt Flag</p> <p>This bit is an interrupt indicator when INT is set in control and status register 1. Write 1 to clear it.</p> <p>0 No interrupt occurred. 1 An interrupt occurred.</p> |
| 5 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |
| 4 PRES | <p>Watchdog Prescaler</p> <p>This write-once bit enables a fixed 256 pre-scaling of watchdog counter reference clock. (The block diagram shows this clock divider option.)</p> <p>0 256 prescaler disabled. 1 256 prescaler enabled.</p> |
| 3–2 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |
| CLK | <p>Watchdog Clock</p> <p>This write-once field indicates the clock source that feeds the watchdog counter. See the Clock source section.</p> <p>00 Bus clock. 01 1 kHz internal low-power oscillator (LPOCLK). 10 32 kHz internal oscillator (ICSIRCLK). 11 External clock source.</p> |

16.2.3 Watchdog Counter Register: High (WDOG_CNTH)

This section describes the watchdog counter registers: high (CNTH) and low (CNTL) combined.

The watchdog counter registers CNTH and CNTL provide access to the value of the free-running watchdog counter. Software can read the counter registers at any time.

Software cannot write directly to the watchdog counter; however, two write sequences to these registers have special functions:

1. The *refresh sequence* resets the watchdog counter to 0x0000. See the [Refreshing the Watchdog](#) section.
2. The *unlock sequence* allows the watchdog to be reconfigured without forcing a reset (when WDOG_CS1[UPDATE] = 1). See the [Example code: Reconfiguring the Watchdog](#) section.

NOTE

All other writes to these registers are illegal and force a reset.

Address: 4005_2000h base + 2h offset = 4005_2002h

| | | | | | | | | |
|-------|---------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | CNTHIGH | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

WDOG_CNTH field descriptions

| Field | Description |
|---------|-----------------------------------|
| CNTHIGH | High byte of the Watchdog Counter |

16.2.4 Watchdog Counter Register: Low (WDOG_CNTL)

See the description of the WDOG_CNTH register.

Address: 4005_2000h base + 3h offset = 4005_2003h

| | | | | | | | | |
|-------|--------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | CNTLOW | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

WDOG_CNTL field descriptions

| Field | Description |
|--------|----------------------------------|
| CNTLOW | Low byte of the Watchdog Counter |

16.2.5 Watchdog Timeout Value Register: High (WDOG_TOVALH)

This section describes the watchdog timeout value registers: high (WDOG_TOVALH) and low (WDOG_TOVALL) combined. WDOG_TOVALH and WDOG_TOVALL contains the 16-bit value used to set the timeout period of the watchdog.

The watchdog counter (WDOG_CNTH and WDOG_CNTL) is continuously compared with the timeout value (WDOG_TOVALH and WDOG_TOVALL). If the counter reaches the timeout value, the watchdog forces a reset.

NOTE

Do not write 0 to the Watchdog Timeout Value Register, otherwise, the watchdog always generates a reset.

Address: 4005_2000h base + 4h offset = 4005_2004h

| | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

WDOG_TOVALH field descriptions

| Field | Description |
|-----------|--------------------------------|
| TOVALHIGH | High byte of the timeout value |

16.2.6 Watchdog Timeout Value Register: Low (WDOG_TOVALL)

See the description of the WDOG_TOVALH register.

NOTE

All the bits reset to 0 in read.

Address: 4005_2000h base + 5h offset = 4005_2005h

| | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

WDOG_TOVALL field descriptions

| Field | Description |
|----------|-------------------------------|
| TOVALLOW | Low byte of the timeout value |

16.2.7 Watchdog Window Register: High (WDOG_WINH)

This section describes the watchdog window registers: high (WDOG_WINH) and low (WDOG_WINL) combined. When window mode is enabled (WDOG_CS2[WIN] is set), WDOG_WINH and WDOG_WINL determine the earliest time that a refresh sequence is considered valid. See the [Watchdog refresh mechanism](#) section.

WDOG_WINH and WDOG_WINL must be less than WDOG_TOVALH and WDOG_TOVALL.

Address: 4005_2000h base + 6h offset = 4005_2006h

| | | | | | | | | |
|-------|---------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | WINHIGH | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

WDOG_WINH field descriptions

| Field | Description |
|---------|------------------------------|
| WINHIGH | High byte of Watchdog Window |

16.2.8 Watchdog Window Register: Low (WDOG_WINL)

See the description of the WDOG_WINH register.

Address: 4005_2000h base + 7h offset = 4005_2007h

| | | | | | | | | |
|-------|--------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | WINLOW | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

WDOG_WINL field descriptions

| Field | Description |
|--------|-----------------------------|
| WINLOW | Low byte of Watchdog Window |

16.3 Functional description

The WDOG module provides a fail safe mechanism to ensure the system can be reset to a known state of operation in case of system failure, such as the CPU clock stopping or there being a run away condition in the software code. The watchdog counter runs continuously off a selectable clock source and expects to be serviced (refreshed) periodically. If it is not, it resets the system.

The timeout period, window mode, and clock source are all programmable but must be configured within 128 bus clocks after a reset.

16.3.1 Watchdog refresh mechanism

The watchdog resets the MCU if the watchdog counter is not refreshed. A robust refresh mechanism makes it very unlikely that the watchdog can be refreshed by runaway code.

To refresh the watchdog counter, software must execute a refresh write sequence before the timeout period expires. In addition, if window mode is used, software must not start the refresh sequence until after the time value set in the WDOG_WINH and WDOG_WINL registers. See the following figure.

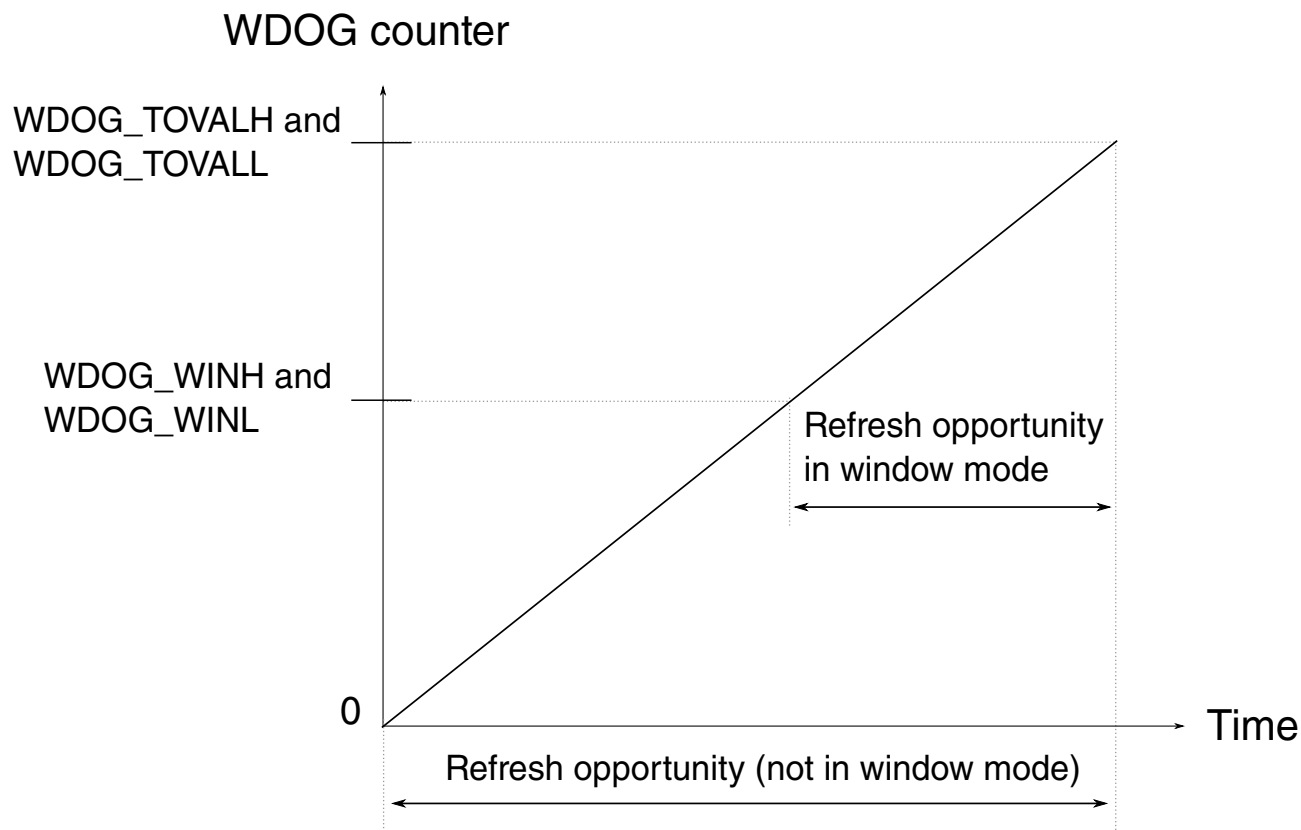


Figure 16-10. Refresh opportunity for the Watchdog counter

16.3.1.1 Window mode

Software finishing its main control loop faster than expected could be an indication of a problem. Depending on the requirements of the application, the WDOG can be programmed to force a reset when refresh attempts are early.

When Window mode is enabled, the watchdog must be refreshed after the counter has reached a minimum expected time value; otherwise, the watchdog resets the MCU. The minimum expected time value is specified in the WDOG_WINH:L registers. Setting CS1[WIN] enables Window mode.

16.3.1.2 Refreshing the Watchdog

The refresh write sequence is a write of 0x02A6 followed by a write of 0x80B4 to the WDOG_CNTH and WDOG_CNTL registers. The write of the 0x80B4 must occur within 16 bus clocks after the write of 0x02A6; otherwise, the watchdog resets the MCU.

Note

Before starting the refresh sequence, disable global interrupts. Otherwise, an interrupt could effectively invalidate the refresh sequence if writing the four bytes takes more than 16 bus clocks. Re-enable interrupts when the sequence is finished.

16.3.1.3 Example code: Refreshing the Watchdog

The following code segment shows the refresh write sequence of the WDOG module.

NOTE

The following example code combines the 8-bit WDOG_CNTH and WDOG_CNTL as one 16-bit WDOG_CNT, the 8-bit WDOG_TOVALH and WDOG_TOVAL as one 16-bit WDOG_TOVAL, WDOG_WINH and WDOG_WINL as WDOG_WIN and uses 16-bit access.

```
/* Refresh watchdog */
for (;;) // main loop
{
    ...

    DisableInterrupts; // disable global interrupt

    WDOG_CNT = 0x02A6; // write the 1st refresh word

    WDOG_CNT = 0x80B4; // write the 2nd refresh word to refresh counter

    EnableInterrupts; // enable global interrupt

    ...
}
```

16.3.2 Configuring the Watchdog

All watchdog control bits, timeout value, and window value are write-once after reset. This means that after a write has occurred they cannot be changed unless a reset occurs. This provides a robust mechanism to configure the watchdog and ensure that a runaway condition cannot mistakenly disable or modify the watchdog configuration after configured.

This is guaranteed by the user configuring the window and timeout value first, followed by the other control bits, and ensuring that CS1[UPDATE] is also set to 0. The new configuration takes effect only after all registers except WDOG_CNTH:L are written

once after reset. Otherwise, the WDOG uses the reset values by default. If window mode is not used (CS2[WIN] is 0), writing to WDOG_WINH:L is not required to make the new configuration take effect.

16.3.2.1 Reconfiguring the Watchdog

In some cases (such as when supporting a bootloader function), users may want to reconfigure or disable the watchdog without forcing a reset first. By setting CS1[UPDATE] to a 1 on the initial configuration of the watchdog after a reset, users can reconfigure the watchdog at any time by executing an unlock sequence. (Conversely, if CS1[UPDATE] remains 0, the only way to reconfigure the watchdog is by initiating a reset.) The unlock sequence is similar to the refresh sequence but uses different values.

16.3.2.2 Unlocking the Watchdog

The unlock sequence is a write to the WDOG_CNTH:L registers of 0x20C5 followed by 0x28D9 within 16 bus clocks at any time after the watchdog has been configured. On completing the unlock sequence, the user must reconfigure the watchdog within 128 bus clocks; .

NOTE

Due to 128 bus clocks requirement for reconfiguring the watchdog, some delays must be inserted before executing STOP or WAIT instructions after reconfiguring the watchdog. This ensures that the watchdog's new configuration takes effect before MCU enters low power mode. Otherwise, the MCU may not be waken up from low power mode.

16.3.2.3 Example code: Reconfiguring the Watchdog

The following code segment shows an example reconfiguration of the WDOG module.

```
/* Initialize watchdog with ~1-kHz clock source, ~1s time-out */
DisableInterrupts; // disable global interrupt
WDOG_CNT = 0x20C5; // write the 1st unlock word
WDOG_CNT = 0x28D9; // write the 2nd unlock word
WDOG_TOVAL = 1000; // setting timeout value
WDOG_CS2 = WDOG_CS2_CLK_MASK; // setting 1-kHz clock source
WDOG_CS1 = WDOG_CS1_EN_MASK; // enable counter running
```

```
EnableInterrupts; // enable global interrupt
```

16.3.3 Clock source

The watchdog counter has four clock source options selected by programming CS2[CLK]:

- bus clock
- internal Low-Power Oscillator (LPO) running at approximately 1 kHz (This is the default source.)
- internal 32 kHz clock
- external clock

The options allow software to select a clock source independent of the bus clock for applications that need to meet more robust safety requirements. Using a clock source other than the bus clock ensures that the watchdog counter continues to run if the bus clock is somehow halted; see [Backup reset](#).

An optional fixed prescaler for all clock sources allows for longer timeout periods. When CS2[PRES] is set, the clock source is prescaled by 256 before clocking the watchdog counter.

The following table summarizes the different watchdog timeout periods available.

Table 16-10. Watchdog timeout availability

| Reference clock | Prescaler | Watchdog time-out availability |
|-------------------------------|--------------|--------------------------------|
| Internal ~1 kHz (LPO) | Pass through | ~1 ms–65.5 s ¹ |
| | ÷256 | ~256 ms–16,777 s |
| Internal ~32 kHz | Pass through | ~31.25 μs–2.048 s |
| | ÷256 | ~8 ms–524.3 s |
| 1 MHz (from bus or external) | Pass through | 1 μs–65.54 ms |
| | ÷256 | 256 μs–16.777 s |
| 20 MHz (from bus or external) | Pass through | 50 ns–3.277 ms |
| | ÷256 | 12.8 μs–838.8 ms |

1. The default timeout value after reset is approximately 4 ms.

NOTE

When the programmer switches clock sources during reconfiguration, the watchdog hardware holds the counter at zero for 2.5 periods of the previous clock source and 2.5 periods of the new clock source after the configuration time period (128 bus clocks) ends. This delay ensures a smooth

transition before restarting the counter with the new configuration.

16.3.4 Using interrupts to delay resets

When interrupts are enabled ($CS1[INT] = 1$), the watchdog first generates an interrupt request upon a reset triggering event (such as a counter timeout or invalid refresh attempt). The watchdog delays forcing a reset for 128 bus clocks to allow the interrupt service routine (ISR) to perform tasks, such as analyzing the stack to debug code.

When interrupts are disabled ($CS1[INT] = 0$), the watchdog does not delay forcing a reset.

16.3.5 Backup reset

NOTE

A clock source other than the bus clock must be used as the reference clock for the counter; otherwise, the backup reset function is not available.

The backup reset function is a safeguard feature that independently generates a reset in case the main WDOG logic loses its clock (the bus clock) and can no longer monitor the counter. If the watchdog counter overflows twice in succession (without an intervening reset), the backup reset function takes effect and generates a reset.

16.3.6 Functionality in debug and low-power modes

By default, the watchdog is not functional in Active Background mode, Wait mode, or Stop mode. However, the watchdog can remain functional in these modes as follows:

- For Active Background mode, set $CS1[DBG]$. (This way the watchdog is functional in Active Background mode even when the CPU is held by the Debug module.)
- For Wait mode, set $CS1[WAIT]$.
- For Stop mode, set $CS1[STOP]$.

NOTE

The watchdog can not generate interrupt in Stop mode even if $CS1[STOP]$ is set and will not wake the MCU from Stop mode. It can generate reset during Stop mode.

For Active Background mode and Stop mode, in addition to the above configurations, a clock source other than the bus clock must be used as the reference clock for the counter; otherwise, the watchdog cannot function.

16.3.7 Fast testing of the watchdog

Before executing application code in safety critical applications, users are required to test that the watchdog works as expected and resets the MCU. Testing every bit of a 16-bit counter by letting it run to the overflow value takes a relatively long time (64 kHz clocks).

To help minimize the startup delay for application code after reset, the watchdog has a feature to test the watchdog more quickly by splitting the counter into its constituent byte-wide stages. The low and high bytes are run independently and tested for timeout against the corresponding byte of the timeout value register. (For complete coverage when testing the high byte of the counter, the test feature feeds the input clock via the 8th bit of the low byte, thus ensuring that the overflow connection from the low byte to the high byte is tested.)

Using this test feature reduces the test time to 512 clocks (not including overhead, such as user configuration and reset vector fetches). To further speed testing, use a faster clock (such as the bus clock) for the counter reference.

On a power-on reset, the POR bit in the system reset register is set, indicating the user should perform the WDOG fast test.

16.3.7.1 Testing each byte of the counter

The test procedure follows these steps:

1. Program the preferred watchdog timeout value in the WDOG_TOVALH and WDOG_TOVALL registers during the watchdog configuration time period.
2. Select a byte of the counter to test using the WDOG_CS1[TST] = 10b for the low byte; WDOG_CS1[TST] = 11b for the high byte.
3. Wait for the watchdog to timeout. Optionally, in the idle loop, increment RAM locations as a parallel software counter for later comparison. Because the RAM is not affected by a watchdog reset, the timeout period of the watchdog counter can be compared with the software counter to verify the timeout period has occurred as expected.
4. The watchdog counter times out and forces a reset.

5. Confirm the WDOG flag in the system reset register is set, indicating that the watchdog caused the reset. (The POR flag remains clear.)
6. Confirm that WDOG_CS1[TST] shows a test (10b or 11b) was performed.

If confirmed, the count and compare functions work for the selected byte. Repeat the procedure, selecting the other byte in step 2.

NOTE

WDOG_CS1[TST] is cleared by a POR only and not affected by other resets.

16.3.7.2 Entering user mode

After successfully testing the low and high bytes of the watchdog counter, the user can configure WDOG_CS1[TST] to 01b to indicate the watchdog is ready for use in application user mode. Thus if a reset occurs again, software can recognize the reset trigger as a real watchdog reset caused by runaway or faulty application code.

As an ongoing test when using the default 1-kHz clock source, software can periodically read the WDOG_CNTH and WDOG_CNTL registers to ensure the counter is being incremented.

Chapter 17

Bit Manipulation Engine (BME)

17.1 Introduction

The Bit Manipulation Engine (BME) provides hardware support for atomic read-modify-write memory operations to the peripheral address space in Cortex-M0+ based microcontrollers.

This architectural capability is also known as "decorated storage" as it defines a mechanism for providing additional semantics for load and store operations to memory-mapped peripherals beyond just the reading and writing of data values to the addressed memory locations. In the BME definition, the "decoration", that is, the additional semantic information, is encoded into the peripheral address used to reference the memory.

By combining the basic load and store instructions of the ARM Cortex-M instruction set architecture (v6M, v7M) with the concept of decorated storage provided by the BME, the resulting implementation provides a robust and efficient read-modify-write capability to this class of ultra low-end microcontrollers. The resulting architectural capability defined by this core platform function is targeted at the manipulation of n-bit fields in peripheral registers and is consistent with I/O hardware addressing in the Embedded C standard. For most BME commands, a single core read or write bus cycle is converted into an atomic read-modify-write, that is, an indivisible "read followed by a write" bus sequence.

BME decorated references are only available on system bus transactions generated by the processor core and targeted at the standard 512 KB peripheral address space based at 0x4000_0000¹ and SRAM_U space based at 0x2000_0000. The decoration semantic is embedded into address bits[28:19], creating a 448 MB space at addresses 0x4400_0000–

1. To be perfectly accurate, the peripheral address space occupies a 516 KB region: 512 KB based at 0x4000_0000 plus a 4 KB space based at 0x400F_F000 for GPIO accesses. This organization provides compatibility with the Kinetis K Family. Attempted accesses to the memory space located between 0x4008_0000 - 0x400F_EFFF are error terminated due to an illegal address.

0x5FFF_FFFF for AIPS and a 448 MB space at addresses 0x2400_0000–0x3FFF_FFFF for SRAM_U; these bits are stripped out of the actual address sent to the peripheral bus controller and used by the BME to define and control its operation.

17.1.1 Overview

The following figure is a generic block diagram of the processor core and platform for this class of ultra low-end microcontrollers.

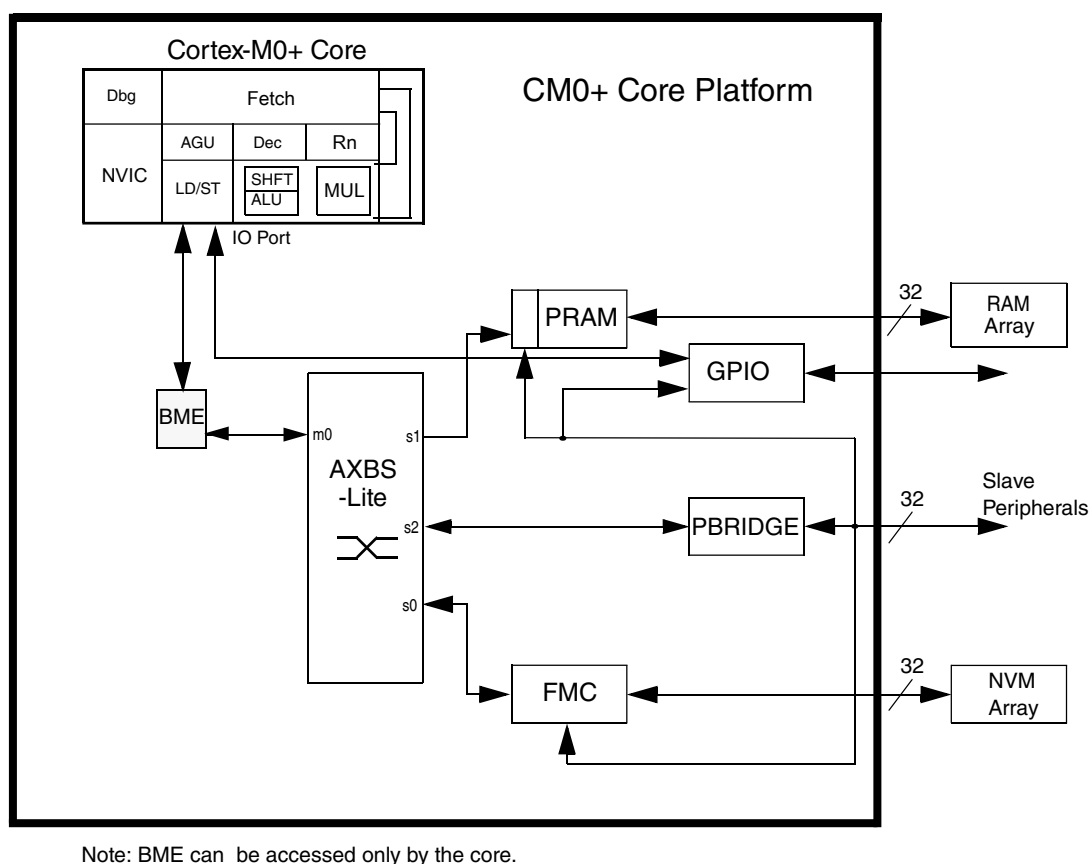


Figure 17-1. Cortex-M0+ core platform block diagram

As shown in the block diagram, the BME module interfaces to the master port on the crossbar switch allowing it to support atomic read-modify-write operations to the SRAM_U (shown as platform RAM (PRAM) in the figure) and the Peripheral Bridge (PBRIDGE) controller. The BME hardware microarchitecture is a 2-stage pipeline design matching the protocol of the AMBA-AHB system bus interfaces. The PBRIDGE module converts the AHB system bus protocol into the IPS/APB protocol used by the attached slave peripherals.

17.1.2 Features

The key features of the BME include:

- Lightweight implementation of decorated storage for selected address spaces
- Additional access semantics encoded into the reference address
- Resides between processor core and a switch master port
- Two-stage pipeline design matching the AHB system bus protocol
- Combinationally passes non-decorated accesses to slave bus controllers
- Conversion of decorated loads and stores from processor core into atomic read-modify-writes
- Decorated loads support unsigned bit field extracts, load-and-`{set,clear}` 1-bit operations
- Decorated stores support bit field inserts, logical AND, OR, and XOR operations
- Support for byte, halfword and word-sized decorated operations
- Supports minimum signal toggling on AHB output bus to reduce power dissipation

17.1.3 Modes of operation

The BME module does not support any special modes of operation. As a memory-mapped device located on a crossbar master AHB system bus port, BME responds strictly on the basis of memory addresses for accesses to the SRAM_U and peripheral bridge bus controller.

All functionality associated with the BME module resides in the core platform's clock domain; this includes its connections with the crossbar master port, SRAM_U and the PBRIDGE bus controller.

17.2 Memory map and register definition

The BME module provides a memory-mapped capability and does not include any programming model registers.

The exact set of functions supported by the BME are detailed in the [Functional description](#).

The peripheral address space occupies a 516 KB region: 512 KB based at 0x4000_0000 plus a 4 KB space based at 0x400F_F000 for GPIO accesses; the decorated address space is mapped to the 448 MB region located at 0x4400_0000–0x5FFF_FFFF. The decorated address space associated with the SRAM_U is the 448 MB region mapped at 0x2400_0000 - 0x3FFF_FFFF.

17.3 Functional description

Information found here details the specific functions supported by the BME.

Recall the combination of the basic load and store instructions of the Cortex-M instruction set architecture (v6M, v7M) plus the concept of decorated storage provided by the BME, the resulting implementation provides a robust and efficient read-modify-write capability to this class of ultra low-end microcontrollers. The resulting architectural capability defined by this core platform function is targeted at the manipulation of n-bit fields in peripheral registers and RAM and is consistent with I/O hardware addressing in the Embedded C standard. For most BME commands, a single core read or write bus cycle is converted into an atomic read-modify-write, that is, an indivisible "read followed by a write" bus sequence.

Consider decorated store operations first, then decorated loads.

17.3.1 BME decorated stores

The functions supported by the BME's decorated stores include three logical operators (AND, OR, XOR) plus a bit field insert.

For all these operations, BME converts a single decorated AHB store transaction into a 2-cycle atomic read-modify-write sequence, where the combined read-modify operation is performed in the first AHB data phase, and then the write is performed in the second AHB data phase.

A generic timing diagram of a decorated store showing a peripheral bit field insert operation is shown as follows:

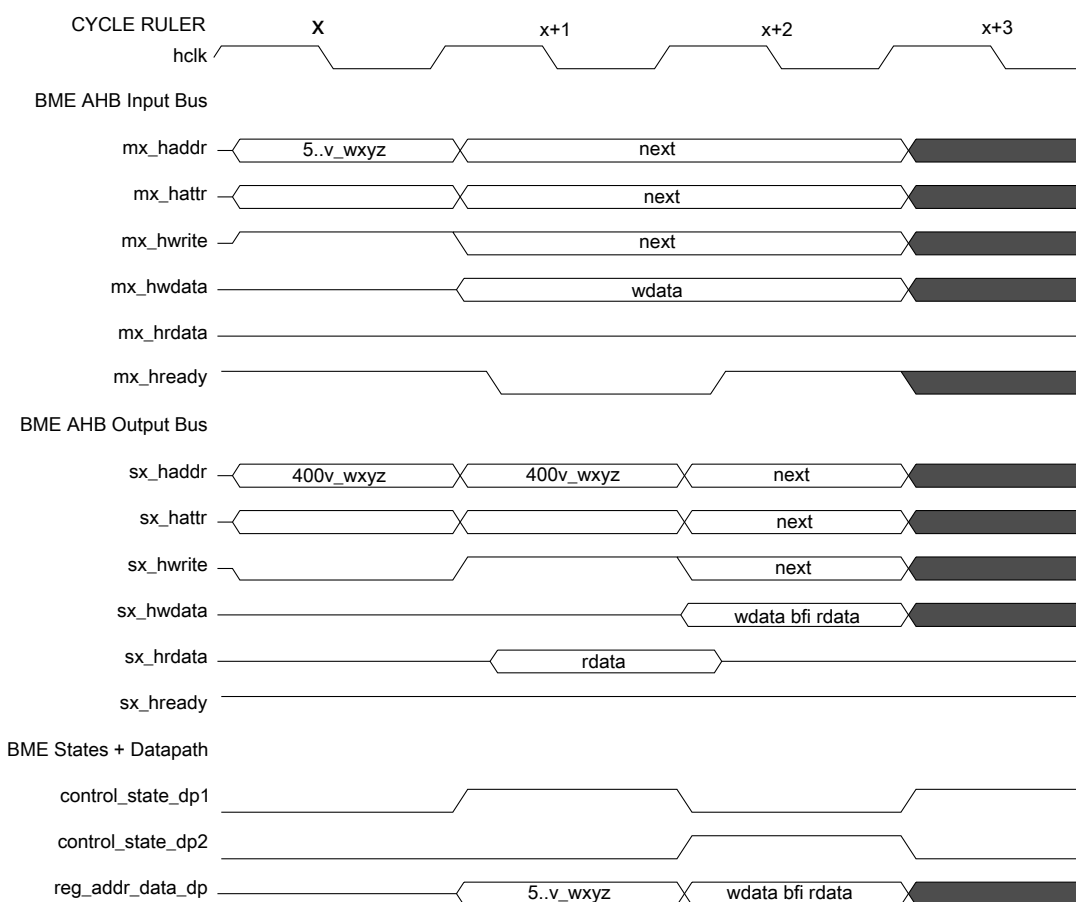


Figure 17-2. Decorated store: bit field insert timing diagram

All the decorated store operations follow the same execution template shown in [Figure 17-2](#), a two-cycle read-modify-write operation:

1. Cycle x, 1st AHB address phase: Write from input bus is translated into a read operation on the output bus using the actual memory address (with the decoration removed) and then captured in a register.
2. Cycle x+1, 2nd AHB address phase: Write access with the registered (but actual) memory address is output
3. Cycle x+1, 1st AHB data phase: Memory read data is modified using the input bus write data and the function defined by the decoration and captured in a data register; the input bus cycle is stalled.
4. Cycle x+2, 2nd AHB data phase: Registered write data is sourced onto the output write data bus.

NOTE

Any wait states inserted by the slave device are simply passed through the BME back to the master input bus, stalling the AHB transaction cycle for cycle.

17.3.1.1 Decorated store logical AND (AND)

This command performs an atomic read-modify-write of the referenced memory location.

1. First, the location is read;
2. It is then modified by performing a logical AND operation using the write data operand sourced for the system bus cycle
3. Finally, the result of the AND operation is written back into the referenced memory location.

The data size is specified by the write operation and can be byte (8-bit), halfword (16-bit) or word (32-bit). The core performs the required write data lane replication on byte and halfword transfers.

| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----|----|----|----|----|----|----|----|----|----|----|----|----------|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| ioandb | 0 | * | * | 0 | 0 | 1 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | | | | | |
| ioandh | 0 | * | * | 0 | 0 | 1 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | | | | 0 | |
| ioandw | 0 | * | * | 0 | 0 | 1 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | | | 0 | 0 | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 17-3. Decorated store address: logical AND

See [Figure 17-3](#) where `addr[30:29] = 01` for SRAM_U, `addr[30:29] = 10` for peripheral, `addr[28:26] = 001` specifies the AND operation, and `mem_addr[19:0]` specifies the address offset into the space based at `0x2000_0000` for SRAM_U, and `0x4000_0000` for peripherals. The "-" indicates an address bit "don't care".

The decorated AND write operation is defined in the following pseudo-code as:

```
ioand<sz>(accessAddress, wdata)           // decorated store AND
tmp  = mem[accessAddress & 0xE0FFFFFF, size] // memory read
tmp  = tmp & wdata                          // modify
mem[accessAddress & 0xE0FFFFFF, size] = tmp // memory write
```

where the operand size `<sz>` is defined as b(yte, 8-bit), h(alfword, 16-bit) and w(ord, 32-bit). This notation is used throughout the document.

In the cycle definition tables, the notations AHB_ap and AHB_dp refer to the address and data phases of the BME AHB transaction. The cycle-by-cycle BME operations are detailed in the following table.

Table 17-1. Cycle definitions of decorated store: logical AND

| Pipeline stage | Cycle | | |
|----------------|--|--|--|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Convert master_wt to slave_rd; Capture address, attributes | Recirculate captured addr + attr to memory as slave_wt | <next> |
| BME AHB_dp | <previous> | Perform memory read; Form (rdata & wdata) and capture destination data in register | Perform write sending registered data to memory |

17.3.1.2 Decorated store logical OR (OR)

This command performs an atomic read-modify-write of the referenced memory location.

1. First, the location is read.
2. It is then modified by performing a logical OR operation using the write data operand sourced for the system bus cycle.
3. Finally, the result of the OR operation is written back into the referenced memory location.

The data size is specified by the write operation and can be byte (8-bit), halfword (16-bit) or word (32-bit). The core performs the required write data lane replication on byte and halfword transfers.

| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----------|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| ioorb | 0 | * | * | 0 | 1 | 0 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | | | | | |
| ioorh | 0 | * | * | 0 | 1 | 0 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | 0 | | | | |
| ioorw | 0 | * | * | 0 | 1 | 0 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | 0 | | | 0 | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 17-4. Decorated address store: logical OR

See [Figure 17-4](#), where $\text{addr}[30:29] = 01$ for SRAM_U, $\text{addr}[30:29] = 10$ for peripheral, $\text{addr}[28:26] = 010$ specifies the OR operation, and $\text{mem_addr}[19:0]$ specifies the address offset into the space based at $0x2000_0000$ for SRAM_U, and $0x4000_0000$ for peripherals. The "-" indicates an address bit "don't care".

The decorated OR write operation is defined in the following pseudo-code as:

```
ioor<sz>(accessAddress, wdata)           // decorated store OR

tmp   = mem[accessAddress & 0xE0FFFFFF, size] // memory read
tmp   = tmp | wdata                          // modify
mem[accessAddress & 0xE0FFFFFF, size] = tmp   // memory write
```

The cycle-by-cycle BME operations are detailed in the following table.

Table 17-2. Cycle definitions of decorated store: logical OR

| Pipeline stage | Cycle | | |
|----------------|--|--|--|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Convert master_wt to slave_rd; Capture address, attributes | Recirculate captured addr + attr to memory as slave_wt | <next> |
| BME AHB_dp | <previous> | Perform memory read; Form (rdata wdata) and capture destination data in register | Perform write sending registered data to memory |

17.3.1.3 Decorated store logical XOR (XOR)

This command performs an atomic read-modify-write of the referenced memory location.

1. First, the location is read.
2. It is then modified by performing a logical XOR (exclusive-OR) operation using the write data operand sourced for the system bus cycle.
3. Finally, the result of the XOR operation is written back into the referenced memory location.

The data size is specified by the write operation and can be byte (8-bit), halfword (16-bit) or word (32-bit). The core performs the required write data lane replication on byte and halfword transfers.

| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----|----|----|----|----|----|----|----|----|----|----|----|----------|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| ioxorb | 0 | * | * | 0 | 1 | 1 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | | | | | |
| ioxorh | 0 | * | * | 0 | 1 | 1 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | 0 | | | | |
| ioxorw | 0 | * | * | 0 | 1 | 1 | - | - | - | - | - | - | mem_addr | | | | | | | | | | | | | | | 0 | | 0 | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 17-5. Decorated address store: logical XOR

See [Figure 17-5](#), where `addr[30:29] = 01` for SRAM_U, `addr[30:29] = 10` for peripheral, `addr[28:26] = 011` specifies the XOR operation, and `mem_addr[19:0]` specifies the address offset into the peripheral space based at `0x2000_0000` for SRAM_U, and `0x4000_0000` for peripherals. The "-" indicates an address bit "don't care".

The decorated XOR write operation is defined in the following pseudo-code as:

```
ioxor<sz>(accessAddress, wdata)           // decorated store XOR

tmp    = mem[accessAddress & 0xE0FFFFFF, size] // memory read
tmp    = tmp ^ wdata                          // modify
mem[accessAddress & 0xE0FFFFFF, size] = tmp    // memory write
```

The cycle-by-cycle BME operations are detailed in the following table.

Table 17-3. Cycle definitions of decorated store: logical XOR

| Pipeline Stage | Cycle | | |
|----------------|--|--|--|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Convert master_wt to slave_rd; Capture address, attributes | Recirculate captured addr + attr to memory as slave_wt | <next> |
| BME AHB_dp | <previous> | Perform memory read; Form (rdata ^ wdata) and capture destination data in register | Perform write sending registered data to memory |

17.3.1.4 Decorated store bit field insert (BFI)

This command inserts a bit field contained in the write data operand, defined by LSB position (b) and the bit field width (w+1), into the memory "container" defined by the access size associated with the store instruction using an atomic read-modify-write sequence.

The data size is specified by the write operation and can be byte (8-bit), halfword (16-bit) or word (32-bit).

NOTE

For the word sized operation, the maximum bit field width is 16 bits. The core performs the required write data lane replication on byte and halfword transfers.

The BFI operation can be used to insert a single bit into a peripheral. For this case, the w field is simply set to 0, indicating a bit field width of 1.

| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----|----|----|----|----|----|----|----|----|----|----|----|----|----------|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| iobfib | 0 | * | * | 1 | - | - | b | b | b | - | w | w | w | mem_addr | | | | | | | | | | | | | | | | | | |
| iobfih | 0 | * | * | 1 | - | b | b | b | b | w | w | w | w | mem_addr | | | | | | | | | | | | | | 0 | | | | |
| iobfiw | 0 | * | * | 1 | b | b | b | b | b | w | w | w | w | mem_addr | | | | | | | | | | | | | | 0 | | 0 | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 17-6. Decorated address store: bit field insert

where $\text{addr}[30:29] = 01$ for SRAM_U, $\text{addr}[30:29] = 10$ for peripheral, $\text{addr}[28] = 1$ signals a BFI operation, $\text{addr}[27:23]$ is "b", the LSB identifier, $\text{addr}[22:19]$ is "w", the bit field width minus 1 identifier, and $\text{addr}[18:0]$ specifies the address offset into the peripheral space based at 0x2000_0000 for SRAM_U, and 0x4000_0000 for peripherals.

Functional description

The "-" indicates an address bit "don't care". Note, unlike the other decorated store operations, BFI uses `addr[19]` as the least significant bit in the "w" specifier and not as an address bit.

The decorated BFI write operation is defined in the following pseudo-code as:

```
iobfi<sz>(accessAddress, wdata)           // decorated bit field insert

tmp   = mem[accessAddress & 0xE007FFFF, size] // memory read
mask  = ((1 << (w+1)) - 1) << b           // generate bit mask
tmp   = tmp & ~mask                        // modify
      | wdata & mask
mem[accessAddress & 0xE007FFFF, size] = tmp // memory write
```

The write data operand (`wdata`) associated with the store instruction contains the bit field to be inserted. It must be properly aligned within a right-aligned container, that is, within the lower 8 bits for a byte operation, the lower 16 bits for a halfword, or the entire 32 bits for a word operation.

To illustrate, consider the following example of the insertion of the 3-bit field "xyz" into an 8-bit memory container, initially set to "abcd_efgh". For all cases, `w` is 2, signaling a bit field width of 3.

```
if b = 0 and the decorated store (strb) Rt register[7:0] = ----_xyz,
    then destination is "abcd_exyz"
if b = 1 and the decorated store (strb) Rt register[7:0] = ----_xyz-,
    then destination is "abcd_xyzh"
if b = 2 and the decorated store (strb) Rt register[7:0] = ---x_yz--,
    then destination is "abcx_yzgh"
if b = 3 and the decorated store (strb) Rt register[7:0] = --xy_z---,
    then destination is "abxy_zfgh"
if b = 4 and the decorated store (strb) Rt register[7:0] = -xyz_----,
    then destination is "axyz_efgh"
if b = 5 and the decorated store (strb) Rt register[7:0] = xyz_----,
    then destination is "xyzd_efgh"
if b = 6 and the decorated store (strb) Rt register[7:0] = yz--_----,
    then destination is "yzcd_efgh"
if b = 7 and the decorated store (strb) Rt register[7:0] = z---_----,
    then destination is "zbcd_efgh"
```

Note from the example, when the starting bit position plus the field width exceeds the container size, only part of the source bit field is inserted into the destination memory location. Stated differently, if $(b + w + 1) > \text{container_width}$, only the low-order " $\text{container_width} - b$ " bits are actually inserted.

The cycle-by-cycle BME operations are detailed in the following table.

Table 17-4. Cycle definitions of decorated store: bit field insert

| Pipeline stage | Cycle | | |
|----------------|--|---|--------|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Convert master_wt to slave_rd; Capture address, attributes | Recirculate captured addr + attr to memory as slave_wt | <next> |

Table continues on the next page...

Table 17-4. Cycle definitions of decorated store: bit field insert (continued)

| Pipeline stage | Cycle | | |
|----------------|------------|---|---|
| | x | x+1 | x+2 |
| BME AHB_dp | <previous> | Perform memory read; Form bit mask; Form bitwise ((mask) ? wdata : rdata)) and capture destination data in register | Perform write sending registered data to memory |

17.3.2 BME decorated loads

The functions supported by the BME's decorated loads include two single-bit load-and-
{set, clear} operators plus unsigned bit field extracts.

For the two load-and-
{set, clear} operations, BME converts a single decorated AHB load transaction into a two-cycle atomic read-modify-write sequence, where the combined read-modify operations are performed in the first AHB data phase, and then the write is performed in the second AHB data phase as the original read data is returned to the processor core. For an unsigned bit field extract, the decorated load transaction is stalled for one cycle in the BME as the data field is extracted, then aligned and returned to the processor in the second AHB data phase. This is the only decorated transaction that is not an atomic read-modify-write, as it is a simple data read.

A generic timing diagram of a decorated load showing a peripheral load-and-set 1-bit operation is shown as follows.

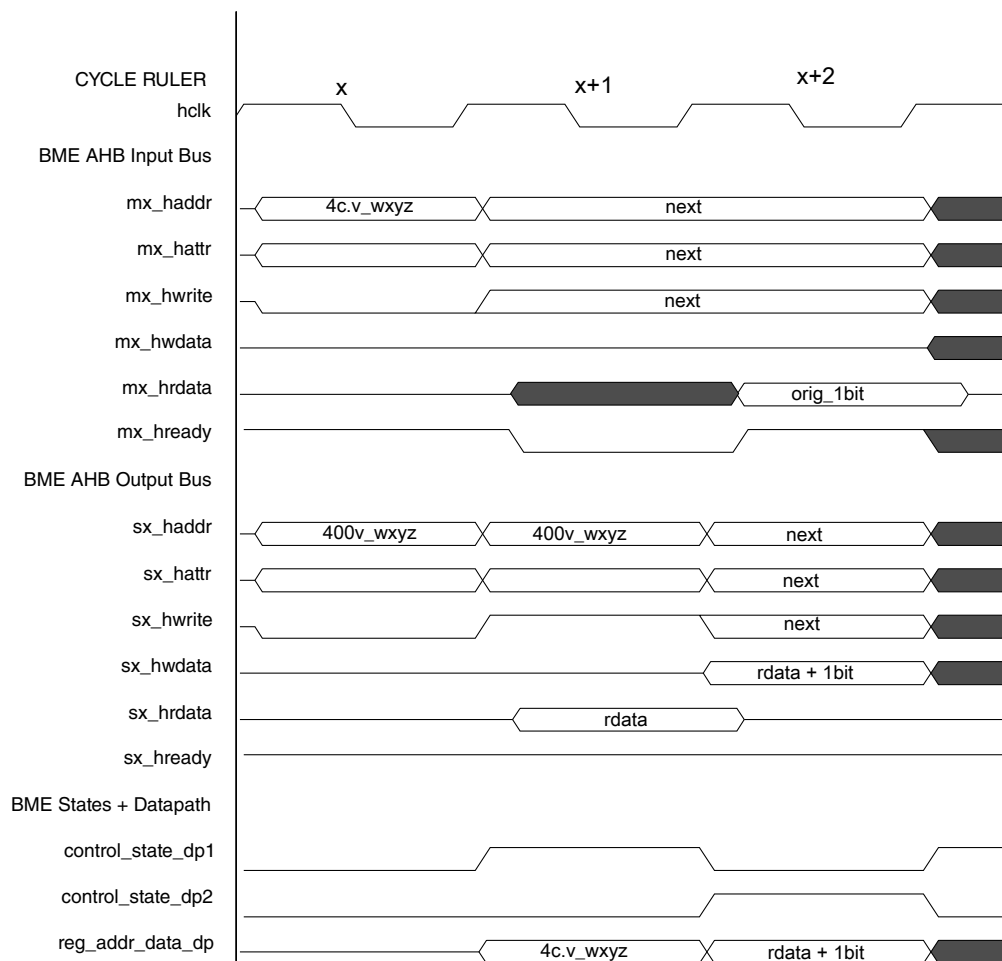


Figure 17-7. Decorated load: load-and-set 1-bit field insert timing diagram

Decorated load-and-`{set, clear}` 1-bit operations follow the execution template shown in the above figure: a 2-cycle read-modify-write operation:

1. Cycle x, first AHB address phase: Read from input bus is translated into a read operation on the output bus with the actual memory address (with the decoration removed) and then captured in a register
2. Cycle x+1, second AHB address phase: Write access with the registered (but actual) memory address is output
3. Cycle x+1, first AHB data phase: The "original" 1-bit memory read data is captured in a register, while the 1-bit field is set or clear based on the function defined by the decoration with the modified data captured in a register; the input bus cycle is stalled
4. Cycle x+2, second AHB data phase: The selected original 1-bit is right-justified, zero-filled and then driven onto the input read data bus, while the registered write data is sourced onto the output write data bus

NOTE

Any wait states inserted by the slave device are simply passed through the BME back to the master input bus, stalling the AHB transaction cycle for cycle.

A generic timing diagram of a decorated load showing an unsigned peripheral bit field operation is shown in the following figure.

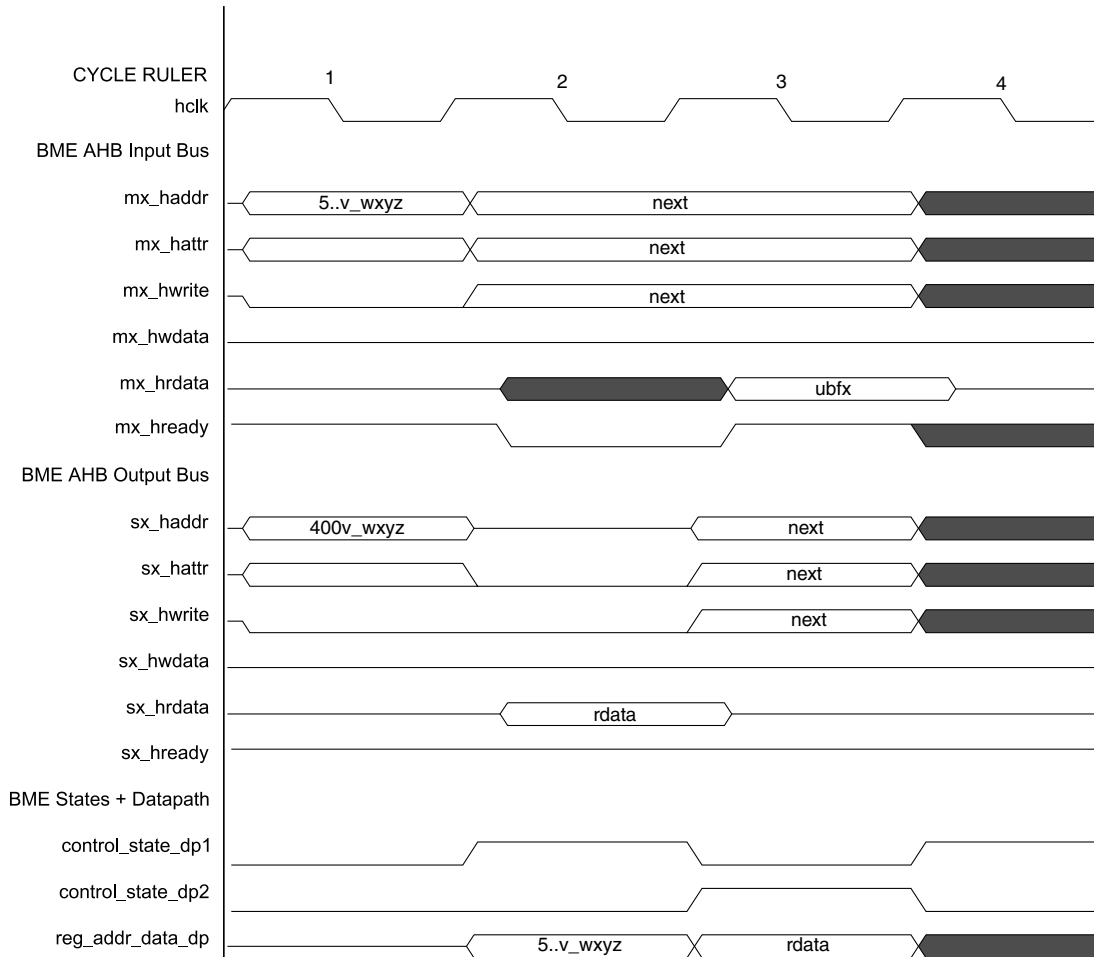


Figure 17-8. Decorated load: unsigned bit field insert timing diagram

The decorated unsigned bit field extract follows the same execution template shown in the above figure, a 2-cycle read operation:

- Cycle x, 1st AHB address phase: Read from input bus is translated into a read operation on the output bus with the actual memory address (with the decoration removed) and then captured in a register
- Cycle x+1, 2nd AHB address phase: Idle cycle

- Cycle x+1, 1st AHB data phase: A bit mask is generated based on the starting bit position and the field width; the mask is AND'ed with the memory read data to isolate the bit field; the resulting data is captured in a data register; the input bus cycle is stalled
- Cycle x+2, 2nd AHB data phase: Registered data is logically right-aligned for proper alignment and driven onto the input read data bus

NOTE

Any wait states inserted by the slave device are simply passed through the BME back to the master input bus, stalling the AHB transaction cycle for cycle.

17.3.2.1 Decorated load: load-and-clear 1 bit (LAC1)

This command loads a 1-bit field defined by the LSB position (b) into the core's general purpose destination register (Rt) and zeroes the bit in the memory space after performing an atomic read-modify-write sequence.

The extracted 1-bit data field from the memory address is right-justified and zero-filled in the operand returned to the core.

The data size is specified by the read operation and can be byte (8-bit), halfword (16-bit) or word (32-bit).

| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
|---------|----|----|----|----|----|----|----|----|----|----|----|----|----------|----|----|----|----|----|----|----|----|----|---|---|---|---|---|-----|---|---|---|---|--|--|
| ol ac1b | 0 | * | * | 0 | 1 | 0 | - | - | b | b | b | - | mem_addr | | | | | | | | | | | | | | | | | | | | | |
| ol ac1h | 0 | * | * | 0 | 1 | 0 | - | b | b | b | b | - | mem_addr | | | | | | | | | | | | | | | 0 | | | | | | |
| ol ac1w | 0 | * | * | 0 | 1 | 0 | b | b | b | b | b | - | mem_addr | | | | | | | | | | | | | | | 0 0 | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 17-9. Decorated load address: load-and-clear 1 bit

See [Figure 17-9](#) where `addr[30:29] = 01` for SRAM_U, `addr[30:29] = 10` for peripheral, `addr[28:26] = 010` specifies the load-and-clear 1 bit operation, `addr[25:21]` is "b", the bit identifier, and `mem_addr[19:0]` specifies the address offset into the space based at `0x2000_0000` for SRAM_U, and `0x4000_0000` for peripheral. The "-" indicates an address bit "don't care".

The decorated load-and-clear 1-bit read operation is defined in the following pseudo-code as:

```

rdata = iolacl<sz>(accessAddress)           // decorated load-and-clear 1

tmp    = mem[accessAddress & 0xE00FFFFFFF, size] // memory read
mask   = 1 << b                               // generate bit mask
rdata  = (tmp & mask) >> b                     // read data returned to core

```

```
tmp = tmp & ~mask // modify
mem[accessAddress & 0xE00FFFFF, size] = tmp // memory write
```

The cycle-by-cycle BME operations are detailed in the following table.

Table 17-5. Cycle definitions of decorated load: load-and-clear 1 bit

| Pipeline Stage | Cycle | | |
|----------------|--|---|---|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Capture address, attributes | Recirculate captured addr + attr to memory as slave_wt | <next> |
| BME AHB_dp | <previous> | Perform memory read; Form bit mask; Extract bit from rdata; Form (rdata & ~mask) and capture destination data in register | Return extracted bit to master; Perform write sending registered data to memory |

17.3.2.2 Decorated Load: Load-and-Set 1 Bit (LAS1)

This command loads a 1-bit field defined by the LSB position (b) into the core's general purpose destination register (Rt) and sets the bit in the memory space after performing an atomic read-modify-write sequence.

The extracted one bit data field from the memory address is right justified and zero filled in the operand returned to the core.

The data size is specified by the read operation and can be byte (8-bit), halfword (16-bit) or word (32-bit).

| | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----|----|----|----|----|----|----|----|----|----|----|----|----------|----|----|----|----|----|----|----|----|----|---|---|---|---|---|----|---|---|---|---|
| iolaslb | 0 | * | * | 0 | 1 | 1 | - | - | b | b | b | - | mem_addr | | | | | | | | | | | | | | | | | | | |
| iolash | 0 | * | * | 0 | 1 | 1 | - | b | b | b | b | - | mem_addr | | | | | | | | | | | | | | | 0 | | | | |
| iolaslw | 0 | * | * | 0 | 1 | 1 | b | b | b | b | b | - | mem_addr | | | | | | | | | | | | | | | 00 | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Figure 17-10. Decorated load address: load-and-set 1 bit

where $\text{addr}[30:29] = 01$ for SRAM_U, $\text{addr}[30:29] = 10$ for peripheral, $\text{addr}[28:26] = 011$ specifies the load-and-set 1 bit operation, $\text{addr}[25:21]$ is "b", the bit identifier, and $\text{mem_addr}[19:0]$ specifies the address offset into the space based at 0x2000_0000 for SRAM_U, and 0x4000_0000 for peripheral. The "-" indicates an address bit "don't care".

The decorated Load-and-Set 1 Bit read operation is defined in the following pseudo-code as:

```
rdata = iolas1<sz>(accessAddress) // decorated load-and-set 1
```

Functional description

```

tmp  = mem[accessAddress & 0xE00FFFFF, size] // memory read
mask = 1 << b                                // generate bit mask
rdata = (tmp & mask) >> b                     // read data returned to core
tmp  = tmp | mask                             // modify
mem[accessAddress & 0xE00FFFFF, size] = tmp  // memory write

```

The cycle-by-cycle BME operations are detailed in the following table.

Table 17-6. Cycle definitions of decorated load: load-and-set 1-bit

| Pipeline Stage | Cycle | | |
|----------------|--|--|---|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Capture address, attributes | Recirculate captured addr + attr to memory as slave_wt | <next> |
| BME AHB_dp | <previous> | Perform memory read; Form bit mask; Extract bit from rdata; Form (rdata mask) and capture destination data in register | Return extracted bit to master; Perform write sending registered data to memory |

17.3.2.3 Decorated load unsigned bit field extract (UBFX)

This command extracts a bit field defined by LSB position (b) and the bit field width (w +1) from the memory "container" defined by the access size associated with the load instruction using a two-cycle read sequence.

The extracted bit field from the memory address is right-justified and zero-filled in the operand returned to the core. Recall this is the only decorated operation that does not perform a memory write, that is, UBFX only performs a read.

The data size is specified by the write operation and can be byte (8-bit), halfword (16-bit) or word (32-bit). Note for the word sized operation, the maximum bit field width is 16 bits.

The use of a UBFX operation is recommended to extract a single bit. For this case, the w field is simply set to 0, indicating a bit field width of 1.

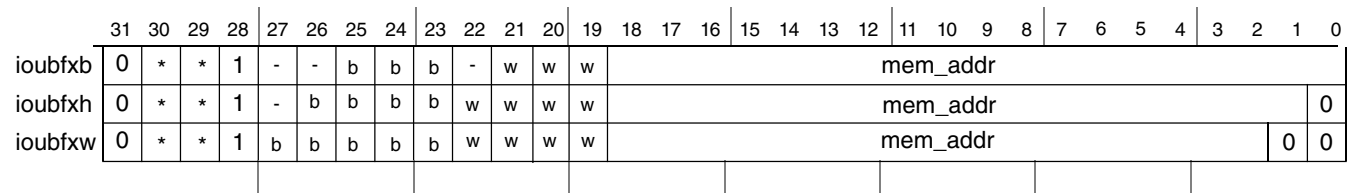


Figure 17-11. Decorated load address: unsigned bit field extract

See Figure 17-11, where $\text{addr}[30:29] = 01$ for SRAM_U, $\text{addr}[30:29] = 10$ for peripheral, $\text{addr}[28] = 1$ specifies the unsigned bit field extract operation, $\text{addr}[27:23]$ is "b", the LSB identifier, $\text{addr}[22:19]$ is "w", the bit field width minus 1 identifier, and $\text{mem_addr}[18:0]$ specifies the address offset into the space based at 0x2000_0000 for SRAM_U, and 0x4000_0000 for peripheral. The "-" indicates an address bit "don't care". Note, unlike the other decorated load operations, UBFX uses $\text{addr}[19]$ as the least significant bit in the "w" specifier and not as an address bit.

The decorated unsigned bit field extract read operation is defined in the following pseudo-code as:

```
rdata = ioubfx<sz>(accessAddress)           // unsigned bit field extract

tmp    = mem[accessAddress & 0xE007FFFF, size] // memory read
mask   = ((1 << (w+1)) - 1) << b             // generate bit mask
rdata  = (tmp & mask) >> b                   // read data returned to core
```

Like the BFI operation, when the starting bit position plus the field width exceeds the container size, only part of the source bit field is extracted from the destination memory location. Stated differently, if $(b + w + 1) > \text{container_width}$, only the low-order " $\text{container_width} - b$ " bits are actually extracted. The cycle-by-cycle BME operations are detailed in the following table.

Table 17-7. Cycle definitions of decorated load: unsigned bit field extract

| Pipeline Stage | Cycle | | |
|----------------|--|---|---|
| | x | x+1 | x+2 |
| BME AHB_ap | Forward addr to memory; Decode decoration; Capture address, attributes | Idle AHB address phase | <next> |
| BME AHB_dp | <previous> | Perform memory read; Form bit mask; Form (rdata & mask) and capture destination data in register | Logically right shift registered data; Return justified rdata to master |

17.3.3 Additional details on decorated addresses and GPIO accesses

As previously noted, the peripheral address space occupies a 516 KB region: 512 KB based at 0x4000_0000 plus a 4 KB space based at 0x400F_F000 for GPIO accesses. This memory layout provides compatibility with the Kinetis K Family and provides 129 address "slots", each 4 KB in size.

The GPIO address space is multiply-mapped by the hardware: it appears at the "standard" system address 0x400F_F000 and is physically located in the address slot corresponding to address 0x4000_F000. Decorated loads and stores create a slight complication

involving accesses to the GPIO. Recall the use of address[19] varies by decorated operation; for AND, OR, XOR, LAC1 and LAS1, this bit functions as a true address bit, while for BFI and UBFX, this bit defines the least significant bit of the "w" bit field specifier.

As a result, undecorated GPIO references and decorated AND, OR, XOR, LAC1 and LAS1 operations can use the standard 0x400F_F000 base address, while decorated BFI and UBFX operations must use the alternate 0x4000_F000 base address. Another implementation can simply use 0x400F_F000 as the base address for all undecorated GPIO accesses and 0x4000_F000 as the base address for all decorated accesses. Both implementations are supported by the hardware.

Table 17-8. Decorated peripheral and GPIO address details

| Peripheral address space | Description |
|--------------------------|--|
| 0x4000_0000–0x4007_FFFF | Undecorated (normal) peripheral accesses |
| 0x4008_0000–0x400F_EFFF | Illegal addresses; attempted references are aborted and error terminated |
| 0x400F_F000–0x400F_FFFF | Undecorated (normal) GPIO accesses using standard address |
| 0x4010_0000–0x43FF_FFFF | Illegal addresses; attempted references are aborted and error terminated |
| 0x4400_0000–0x4FFF_FFFF | Decorated AND, OR, XOR, LAC1, LAS1 references to peripherals and GPIO based at either 0x4000_F000 or 0x400F_F000 |
| 0x5000_0000–0x5FFF_FFFF | Decorated BFI, UBFX references to peripherals and GPIO only based at 0x4000_F000 |

17.4 Application information

In this section, GNU assembler macros with C expression operands are presented as examples of the required instructions to perform decorated operations.

This section specifically presents a partial bme.h file defining the assembly language expressions for decorated logical stores: AND, OR, and XOR. Comparable functions for BFI and the decorated loads are more complex and available in the complete BME header file.

These macros use the same function names presented in [Functional description](#).

```
#define IOANDW(ADDR, WDATA) \
    __asm("ldr    r3, =(1<<26);" \
          "orr     r3, %[addr];" \
          "mov     r2, %[wdata];" \
          "str     r2, [r3];" \
          ":: [addr] \"r\" (ADDR), [wdata] \"r\" (WDATA) : \"r2\", \"r3\");

#define IOANDH(ADDR, WDATA) \
    __asm("ldr    r3, =(1<<26);" \
          "orr     r3, %[addr];" \
          "mov     r2, %[wdata];" \
          "strh    r2, [r3];" \
          ":: [addr] \"r\" (ADDR), [wdata] \"r\" (WDATA) : \"r2\", \"r3\");
```



```

#define IOANDB(ADDR,WDATA)          \
    __asm("ldr    r3, =(1<<26);"    \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "strb    r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

#define IOORW(ADDR,WDATA)           \
    __asm("ldr    r3, =(1<<27);"     \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "str     r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

#define IOORH(ADDR,WDATA)           \
    __asm("ldr    r3, =(1<<27);"     \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "strh    r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

#define IOORB(ADDR,WDATA)           \
    __asm("ldr    r3, =(1<<27);"     \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "strb    r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

#define IOXORW(ADDR,WDATA)          \
    __asm("ldr    r3, =(3<<26);"     \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "str     r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

#define IOXORH(ADDR,WDATA)          \
    __asm("ldr    r3, =(3<<26);"     \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "strh    r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

#define IOXORB(ADDR,WDATA)          \
    __asm("ldr    r3, =(3<<26);"     \
          "orr     r3, %[addr];"      \
          "mov     r2, %[wdata];"     \
          "strb    r2, [r3];"         \
          ":: [addr] "r" (ADDR), [wdata] "r" (WDATA) : "r2", "r3");

```


Chapter 18

Flash Memory Module (FTMRE)

18.1 Introduction

The FTMRE module implements the following:

- Program flash (flash) memory

The flash memory is ideal for single-supply applications allowing for field reprogramming without requiring external high voltage sources for program or erase operations. The flash module includes a memory controller that executes commands to modify flash memory contents. The user interface to the memory controller consists of the indexed Flash Common Command Object (FCCOB) register which is written to with the command, global address, data, and any required command parameters. The memory controller must complete the execution of a command before the FCCOB register can be written to with a new command.

CAUTION

A flash byte or longword must be in the erased state before being programmed. Cumulative programming of bits within a flash byte or longword is not allowed.

The flash memory is read as bytes. Read access time is one bus cycle for bytes. For flash memory, an erased bit reads 1 and a programmed bit reads 0.

18.2 Feature

18.2.1 Flash memory features

The flash memory has the following features:

- 64 KB of flash memory composed of one 64 KB flash block divided into 128 sectors of 512 bytes
- Automated program and erase algorithm with verify

- Fast sector erase and longword program operation
- Flexible protection scheme to prevent accidental programming or erasing of flash memory

18.2.2 Other flash module features

The flash memory module has the following other features:

- No external high-voltage power supply required for flash memory program and erase operations
- Interrupt generation on flash command completion
- Security mechanism to prevent unauthorized access to the flash memory

18.3 Functional description

18.3.1 Modes of operation

The flash memory module provides the normal user mode of operation. The operating mode is determined by module-level inputs and affects the FCNFG, and FCLKDIV registers.

18.3.1.1 Wait mode

The flash memory module is not affected if the MCU enters Wait mode. The flash module can recover the MCU from Wait via the CCIF interrupt. See [Flash interrupts](#).

18.3.1.2 Stop mode

If a flash command is active, that is, $FSTAT[CCIF] = 0$, when the MCU requests Stop mode, the current NVM operation will be completed before the MCU is allowed to enter Stop mode.

18.3.2 Flash memory map

The MCU places the flash memory as shown in the following table.

Table 18-1. Flash memory addressing

| Global address | Flash size | Description |
|-------------------------|------------|---|
| 0x0000_0000–0x0000_FFFF | 64 KB | Flash block contains flash configuration field. |
| 0x0000_0000–0x0001_FFFF | 128 KB | Flash block contains flash configuration field. |

18.3.3 Flash initialization after system reset

On each system reset, the flash module executes an initialization sequence that establishes initial values for the flash block configuration parameters, the FPROT protection register, and the FOPT and FSEC registers. The initialization routine reverts to built-in default values that leave the module in a fully protected and secured state if errors are encountered during execution of the reset sequence. If an error is detected during the reset sequence, both FSTAT[MGSTAT] bits will be set.

FSTAT[CCIF] is cleared throughout the initialization sequence. The NVM module holds off all CPU access for a portion of the initialization sequence. Flash reads are allowed after the hold is removed. Completion of the initialization sequence is marked by setting FSTAT[CCIF] high, which enables user commands. While FSTAT[CCIF] remains cleared, it is not possible to write on registers FCCOBIX or FCCOB.

If a reset occurs while any flash command is in progress, that command will be immediately aborted. The state of the word being programmed or the sector/block being erased is not guaranteed.

18.3.4 Flash command operations

Flash command operations are used to modify flash memory contents.

The command operations contain three steps:

1. Configure the clock for flash program and erase command operations.
2. Use command write sequence to set flash command parameters and launch execution.
3. Execute valid flash commands according to MCU functional mode and MCU security state.

The figure below shows a general flowchart of the flash command write sequence.

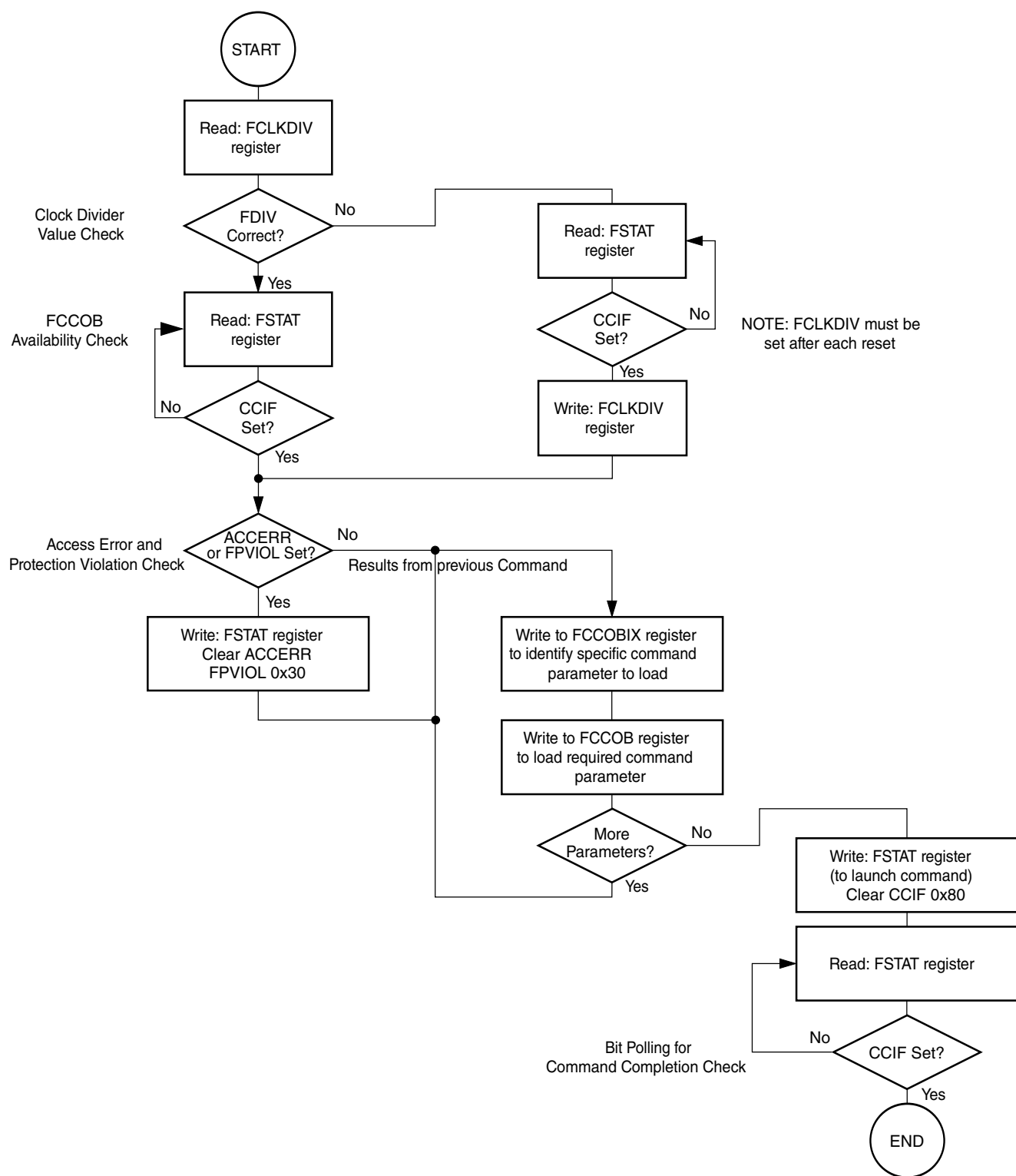


Figure 18-1. Generic flash command write sequence flowchart

18.3.4.1 Writing the FCLKDIV register

Prior to issuing any flash program or erase command after a reset, the user is required to write the FCLKDIV register to divide BUSCLK down to a target FCLK of 1 MHz. The following table shows recommended values for FCLKDIV[FDIV] based on BUSCLK frequency.

Table 18-2. FDIV values for various BUSCLK frequencies

| BUSCLK frequency (MHz) | | FDIV[5:0] |
|---------------------------|------------------|-----------|
| MIN ¹ | MAX ² | |
| 1.0 | 1.6 | 0x00 |
| 1.6 | 2.6 | 0x01 |
| 2.6 | 3.6 | 0x02 |
| 3.6 | 4.6 | 0x03 |
| 4.6 | 5.6 | 0x04 |
| 5.6 | 6.6 | 0x05 |
| 6.6 | 7.6 | 0x06 |
| 7.6 | 8.6 | 0x07 |
| 8.6 | 9.6 | 0x08 |
| 9.6 | 10.6 | 0x09 |
| 10.6 | 11.6 | 0x0A |
| 11.6 | 12.6 | 0x0B |
| 12.6 | 13.6 | 0x0C |
| 13.6 | 14.6 | 0x0D |
| 14.6 | 15.6 | 0x0E |
| 15.6 | 16.6 | 0x0F |
| 16.6 | 17.6 | 0x10 |
| 17.6 | 18.6 | 0x11 |
| 18.6 | 19.6 | 0x12 |
| 19.6 | 20.6 | 0x13 |
| 20.6 | 21.6 | 0x14 |
| 21.6 | 22.6 | 0x15 |
| 22.6 | 23.6 | 0x16 |
| 23.6 | 24.6 | 0x17 |
| 24.6 | 25.6 | 0x18 |

1. BUSCLK is greater than this value.
2. BUSCLK is less than or equal to this value.

CAUTION

Programming or erasing the flash memory cannot be performed if the bus clock runs at less than 0.8 MHz. Setting FCLKDIV[FDIV] too high can destroy the flash memory due to overstress. Setting FCLKDIV[FDIV] too low can result in incomplete programming or erasure of the flash memory cells.

When the FCLKDIV register is written, FCLKDIV[FDIVLD] is set automatically. If FCLKDIV[FDIVLD] is 0, the FCLKDIV register has not been written since the last reset. If the FCLKDIV register has not been written, any flash program or erase command loaded during a command write sequence will not execute and FSTAT[ACCERR] will be set.

18.3.4.2 Command write sequence

The memory controller will launch all valid flash commands entered using a command write sequence.

Before launching a command, FSTAT[ACCERR] and FSTAT[FPVIOL] must be cleared and the FSTAT[CCIF] flag will be tested to determine the status of the current command write sequence. If FSTAT[CCIF] is 0, indicating that the previous command write sequence is still active, a new command write sequence cannot be started and all writes to the FCCOB register are ignored.

The FCCOB parameter fields must be loaded with all required parameters for the flash command being executed. Access to the FCCOB parameter fields is controlled via FCCOBIX[CCOBIX].

Flash command mode uses the indexed FCCOB register to provide a command code and its relevant parameters to the memory controller. First, the user must set up all required FCCOB fields. Then they can initiate the command's execution by writing a 1 to FSTAT[CCIF]. This action clears the CCIF command completion flag to 0. When the user clears FSTAT[CCIF], all FCCOB parameter fields are locked and cannot be changed by the user until the command completes (evidenced by the memory controller returning FSTAT[CCIF] to 1). Some commands return information to the FCCOB register array.

The generic format for the FCCOB parameter fields in flash command mode is shown in the following table. The return values are available for reading after the FSTAT[CCIF] flag has been returned to 1 by the memory controller. Writes to the unimplemented parameter fields, FCCOBIX[CCOBIX] = 110b and FCCOBIX[CCOBIX] = 111b, are ignored with read from these fields returning 0x0000.

Table 18-3 shows the generic flash command format. The high byte of the first word in the CCOB array contains the command code, followed by the parameters for this specific flash command. For details on the FCCOB settings required by each command, see the flash command descriptions in [Flash command summary](#).

Table 18-3. FCCOB – flash command mode typical usage

| CCOBIX[2:0] | Byte | FCCOB parameter fields in flash command mode |
|-------------|------|--|
| 000 | HI | FCMD[7:0] defining flash command |
| | LO | Global address [23:16] |
| 001 | HI | Global address [15:8] |
| | LO | Global address [7:0] |
| 010 | HI | Data 0 [15:8] |
| | LO | Data 0 [7:0] |
| 011 | HI | Data 1 [15:8] |
| | LO | Data 1 [7:0] |
| 100 | HI | Data 2 [15:8] |
| | LO | Data 2 [7:0] |
| 101 | HI | Data 3 [15:8] |
| | LO | Data 3 [7:0] |

The contents of the FCCOB parameter fields are transferred to the memory controller when the user clears the FSTAT[CCIF] command completion flag by writing 1. The CCIF flag will remain clear until the flash command has completed. Upon completion, the memory controller will return FSTAT[CCIF] to 1 and the FCCOB register will be used to communicate any results.

The following table presents the valid flash commands, as enabled by the combination of the functional MCU mode with the MCU security state of unsecured or secured.

MCU secured state is selected by FSEC[SEC].

Table 18-4. Flash commands by mode and security state

| FCMD | Command | Unsecured | Secured |
|------|----------------------------|----------------|----------------|
| | | U ¹ | U ² |
| 0x01 | Erase verify all blocks | * | * |
| 0x02 | Erase verify block | * | * |
| 0x03 | Erase verify flash section | * | * |
| 0x04 | Read once | * | * |
| 0x06 | Program flash | * | * |
| 0x07 | Program once | * | * |
| 0x08 | Erase all block | * | * |
| 0x09 | Erase flash block | * | * |

Table continues on the next page...

Table 18-4. Flash commands by mode and security state (continued)

| FCMD | Command | Unsecured | Secured |
|------|----------------------------|----------------|----------------|
| | | U ¹ | U ² |
| 0x0A | Erase flash sector | * | * |
| 0x0B | Unsecure flash | * | * |
| 0x0C | Verify backdoor access key | * | * |
| 0x0D | Set user margin level | * | * |
| 0x0E | Set factory margin level | * | * |
| 0x0F | Configure NVM | * | * |

1. Unsecured user mode
2. Secured user mode

18.3.5 Flash interrupts

The flash module can generate an interrupt when a flash command operation has completed.

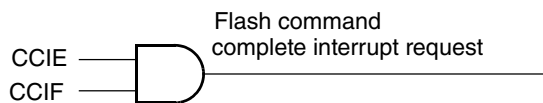
Table 18-5. Flash interrupt source

| Interrupt source | Interrupt flag | Local enable | Global (CCR) mask |
|------------------------|--------------------------|--------------------------|-------------------|
| Flash command complete | CCIF (FSTAT register) | CCIE (FCNFG register) | I Bit |

18.3.5.1 Description of flash interrupt operation

The flash module uses the FSTAT[CCIF] flag in combination with the FCNFG[CCIE] interrupt enable bit to generate the flash command interrupt request.

The logic used for generating the flash module interrupts is shown in the following figure.

**Figure 18-2. Flash module interrupts implementation**

18.3.6 Protection

The FPROT register can be set to protect regions in the flash memory from accidental programming or erasing. Three separate memory regions, one growing upward from global address 0x0000 in the flash memory, called the lower region; one growing downward from global address 0x7FFF in the flash memory, called the higher region; and the remaining addresses in the flash memory, can be activated for protection. The flash memory addresses covered by these protectable regions are shown in the flash memory map.

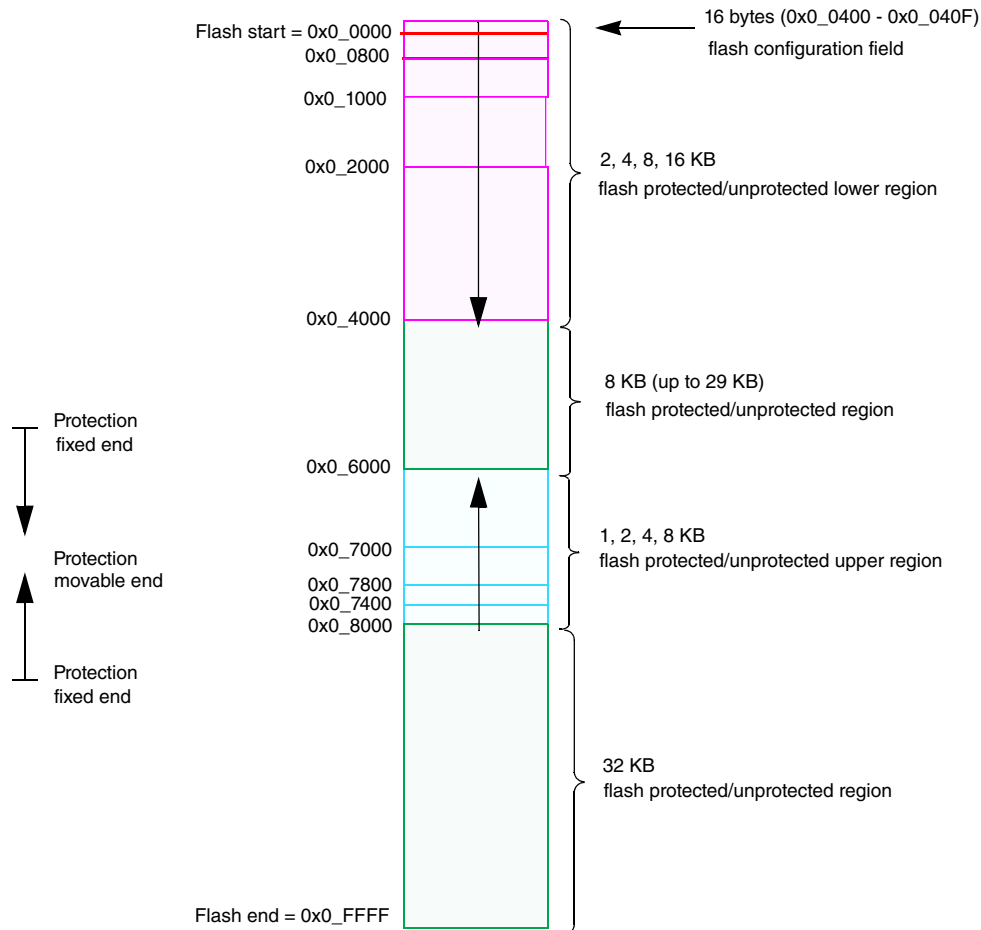


Figure 18-3. 64 KB flash protection memory map

Default protection settings as well as security information that allows the MCU to restrict access to the flash module are stored in the flash configuration field as described in the table below.

Table 18-6. Flash configuration field

| Global address | Size (Bytes) | Description |
|----------------------------|--------------|--|
| 0x0400–0x0407 | 8 | Backdoor comparison key. See Verify backdoor access key command and Unsecuring the MCU using backdoor key access . |
| 0x0408–0x040B 1 | 4 | Reserved |
| 0x040C–0x040F ¹ | 1 | Flash nonvolatile byte - data[31:24] |
| | 1 | Flash security byte - data[23:16] |
| | 1 | Flash protection byte - data[15:8] |
| | 1 | Reserved - data [7:0] |

1. 0x0_0408–0x040B and 0x040C–0x0_040F form a flash longword in each address range and must be programmed in a single command write sequence. Each byte in these longwords that are marked as reserved must be programmed to 0xFF. Alternatively, the Flash phrase 0x0408-0x040F can also be programmed in a single command write sequence.

The flash module provides protection to the MCU. During the reset sequence, the FPROT register is loaded with the contents of the flash protection byte in the flash configuration field at global address 0x040D in flash memory. The protection functions depend on the configuration of bit settings in FPROT register.

Table 18-7. Flash protection function

| FPOPEN | FPHDIS | FPLDIS | Function ¹ |
|--------|--------|--------|---------------------------------|
| 1 | 1 | 1 | No flash protection |
| 1 | 1 | 0 | Protected low range |
| 1 | 0 | 1 | Protected high range |
| 1 | 0 | 0 | Protected high and low ranges |
| 0 | 1 | 1 | Full flash memory protected |
| 0 | 1 | 0 | Unprotected low range |
| 0 | 0 | 1 | Unprotected high range |
| 0 | 0 | 0 | Unprotected high and low ranges |

1. For range sizes, see [Table 4](#) and [Table 5](#)

1. For range sizes, see [Table 4](#) and [Table 5](#)

The flash protection scheme can be used by applications requiring reprogramming in single chip mode while providing as much protection as possible if reprogramming is not required.

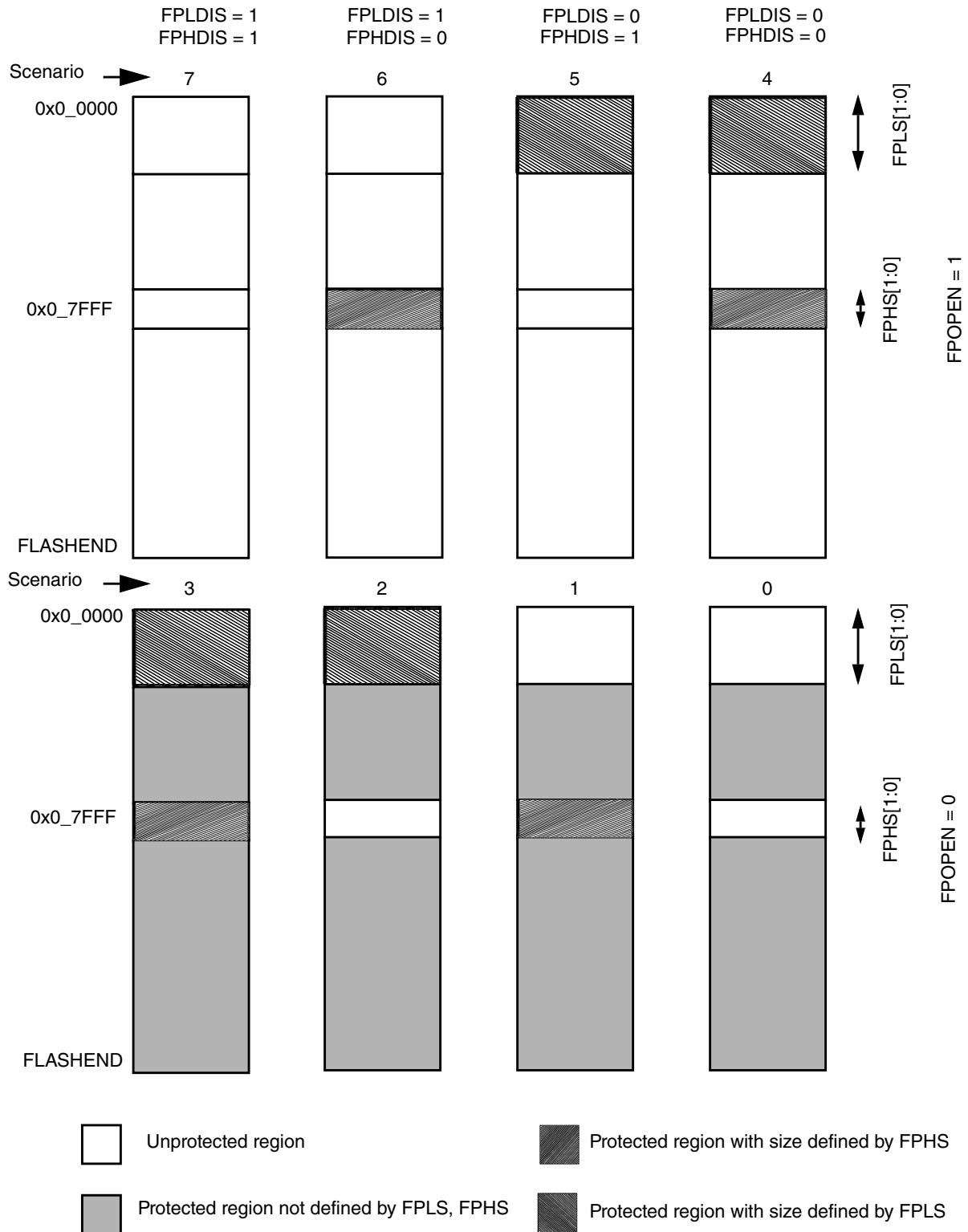


Figure 18-4. Flash protection scenarios

Functional description

The general guideline is that flash protection can only be added and not removed. The following table specifies all valid transitions between flash protection scenarios. Any attempt to write an invalid scenario to the FPROT register will be ignored. The contents of the FPROT register reflect the active protection scenario. See the FPROT[FPHS] and FPROT[FPLS] field descriptions for additional restrictions.

Table 18-8. Flash protection scenario transitions

| From protection scenario | To protection scenario ¹ | | | | | | | |
|--------------------------|-------------------------------------|---|---|---|---|---|---|---|
| | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| 0 | x | x | x | x | | | | |
| 1 | | x | | x | | | | |
| 2 | | | x | x | | | | |
| 3 | | | | x | | | | |
| 4 | | | | x | x | | | |
| 5 | | | x | x | x | x | | |
| 6 | | x | | x | x | | x | |
| 7 | x | x | x | x | x | x | x | x |

1. Allowed transitions marked with X.

The flash protection address range is listed in the following two tables regarding the scenarios in the table above.

Table 18-9. Flash protection higher address range

| FPHS[1:0] | Global address range | Protected size |
|-----------|----------------------|----------------|
| 00 | 0x7C00–0x7FFF | 1 KB |
| 01 | 0x7800–0x7FFF | 2 KB |
| 10 | 0x7000–0x7FFF | 4 KB |
| 11 | 0x6000–0x7FFF | 8 KB |

Table 18-10. Flash protection lower address range

| FPLS[1:0] | Global address range | Protected size |
|-----------|----------------------|----------------|
| 00 | 0x0000–0x07FF | 2 KB |
| 01 | 0x0000–0x0FFF | 4 KB |
| 10 | 0x0000–0x1FFF | 8 KB |
| 11 | 0x0000–0x3FFF | 16 KB |

All possible flash protection scenarios are shown in [Figure 18-4](#). Although the protection scheme is loaded from the flash memory at global address 0x040D during the reset sequence, it can be changed by the user.

18.3.7 Security

The flash module provides security information to the MCU. The flash security state is defined by FSEC[SEC]. During reset, the flash module initializes the FSEC register using data read from the security byte of the flash configuration field. The security state out of reset can be permanently changed by programming the security byte, assuming that the MCU is starting from a mode where the necessary flash erase and program commands are available and that the upper region of the flash is unprotected. If the flash security byte is successfully programmed, its new value will take effect after the next MCU reset.

The following subsections describe these security-related subjects:

- Unsecuring the MCU using backdoor key access
- Unsecuring the MCU using SWD
- Mode and security effects on flash command availability

18.3.7.1 Unsecuring the MCU using backdoor key access

The MCU may be unsecured by using the backdoor key access feature which requires knowledge of the contents of the backdoor keys, which are four 16-bit words programmed at addresses 0x400–0x407. If the KEYEN[1:0] bits are in the enabled state, the verify backdoor access key command – see [Verify backdoor access key command](#), allows the user to present four prospective keys for comparison to the keys stored in the flash memory via the memory controller. If the keys presented in the verify backdoor access key command match the backdoor keys stored in the flash memory, FSEC[SEC] will be changed to unsecure the MCU. Key values of 0x0000 and 0xFFFF are not permitted as backdoor keys. While the Verify Backdoor Access Key command is active, flash memory will not be available for read access and will return invalid data.

The user code stored in the flash memory must have a method of receiving the backdoor keys from an external stimulus. This external stimulus would typically be through one of the on-chip serial ports.

If the KEYEN[1:0] bits are in the enabled state, the MCU can be unsecured by the backdoor key access sequence described below:

1. Follow the command sequence for the verify backdoor access key command as explained in [Verify backdoor access key command](#).

2. If the verify backdoor access key command is successful, the MCU is unsecured and FSEC[SEC] is forced to the unsecure state of 10.

The verify backdoor access key command is monitored by the memory controller and an illegal key will prohibit future use of the verify backdoor access key command. A reset of the MCU is the only method to re-enable the verify backdoor access key command. The security as defined in the flash security byte is not changed by using the verify backdoor access key command sequence. The backdoor keys stored in addresses 0x400–0x407 are unaffected by the verify backdoor access key command sequence. The verify backdoor access key command sequence has no effect on the program and erase protections defined in the flash protection register, FPROT.

After the backdoor keys have been correctly matched, the MCU will be unsecured. After the MCU is unsecured, the sector containing the flash security byte can be erased and the flash security byte can be reprogrammed to the unsecure state, if desired. In the unsecure state, the user has full control of the contents of the backdoor keys by programming addresses 0x400–0x407 in the flash configuration field.

18.3.7.2 Unsecuring the MCU using SWD

A secured MCU can be unsecured by using the following method to erase the flash memory:

1. Reset the device by asserting $\overline{\text{RESET}}$ pin or DAP_CTRL[3].
2. Set DAP_CTRL[0] bit to invoke debug mass erase via SWD
3. Release reset by deasserting $\overline{\text{RESET}}$ pin or DAP_CTRL[3] bit via SWD.
4. Wait till DAP_CTRL[0] bit is cleared (After mass erase completes, DAP_CTRL[0] bit is cleared automatically). At this time, CPU will be in hold state, MASS erase is completed, and the device is in unsecure state (flash security byte in flash configuration field is programmed with 0xFE) .
5. Reset the device.

18.3.7.3 Mode and security effects on flash command availability

The availability of flash module commands depends on the MCU operating mode and security state as shown in [Table 18-4](#).

18.3.8 Flash commands

18.3.8.1 Flash commands

The following table summarizes the valid flash commands as well as the effects of the commands on the flash block and other resources within the flash module.

Table 18-11. Flash commands

| FCMD | Command | Function on flash memory |
|------|----------------------------|--|
| 0x01 | Erase Verify All Blocks | Verifies that all flash blocks are erased |
| 0x02 | Erase Verify Block | Verifies that a flash block is erased |
| 0x03 | Erase Verify Flash Section | Verifies that a given number of words starting at the address provided are erased |
| 0x04 | Read Once | Reads a dedicated 64-byte field in the nonvolatile information register in flash block that was previously programmed using the program once command |
| 0x06 | Program Flash | Programs up to two longwords in a flash block |
| 0x07 | Program Once | Programs a dedicated 64 byte field in the nonvolatile information register in flash block that is allowed to be programmed only once |
| 0x08 | Erase All Block | Erases all flash blocks An erase of all flash blocks is possible only when the FPROT[FPHDIS], FPROT[FPLDIS] and FPROT[FPOEN] and the bit are set prior to launching the command |
| 0x09 | Erase Flash Block | Erases a flash block An erase of the full flash block is possible only when FPROT[FPLDIS], FPROT[FPHDIS], and FPROT[FPOEN] are set prior to launching the command. |
| 0x0A | Erase Flash Sector | Erases all bytes in a flash sector |
| 0x0B | Unsecure Flash | Supports a method of releasing MCU security by erasing all flash blocks and verifying that all flash blocks are erased |
| 0x0C | Verify Backdoor Access key | Supports a method of releasing MCU security by verifying a set of security keys |
| 0x0D | Set User Margin Level | Specifies a user margin read level for all flash blocks |
| 0x0E | Set Factory Margin Level | Specifies a factory margin read level for all flash blocks |
| 0x0F | Configure NVM | Configure NVM parameters to enable or disable some features in the NVM array, allowing to save current/power under certain circumstances. |

18.3.9 Flash command summary

This section provides details of all available flash commands launched by a command write sequence. The FSTAT[ACCERR] will be set during the command write sequence if any of the following illegal steps are performed, causing the command not to be processed by the memory controller:

- Starting any command write sequence that programs or erases flash memory before initializing the FLCKDIV register.
- Writing an invalid command as part of the command write sequence.
- For additional possible errors, refer to the error handling table provided for each command.

If a flash block is read during the execution of an algorithm (FSTAT[CCIF] = 0) on that same block, the read operation will return invalid data. It will also trigger an illegal access exception.

If FSTAT[ACCERR] or FSTAT[FPVIOL] are set, the user must clear these fields before starting any command write sequence.

CAUTION

An flash longword must be in the erased state before being programmed. Cumulative programming of bits within an flash longword is not allowed.

18.3.9.1 Erase Verify All Blocks command

The Erase Verify All Blocks command will verify that all flash blocks have been erased.

Table 18-12. Erase Verify All Blocks command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|--------------------|--------------------|
| 000 | 0x01 | Not required |

Upon clearing FSTAT[CCIF] to launch the Erase Verify All Blocks command, the memory controller will verify that the entire flash memory space is erased. The FSTAT[CCIF] flag will set after the erase verify all blocks operation has completed. If all blocks are not erased, it means blank check failed and both FSTAT[MGSTAT] bits will be set.

Table 18-13. Erase verify all blocks command error handling

| Register | Error bit | Error condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 000 at command launch |
| | FPVIOL | None |
| | MGSTAT1 | Set if any errors have been encountered during the read ¹ or if blank check failed |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the read or if blank check failed |

1. As found in the memory map for NVM

18.3.9.2 Erase Verify Block command

The Erase Verify Block command allows the user to verify that an entire flash block has been erased. The FCCOB global address [23:0] bits determine which block must be verified.

Table 18-14. Erase Verify Block Command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|---|--|
| 000 | 0x02 | Global address [23:16] to identify flash block |
| 001 | Global address [15:0] in flash block to be verified | |

Upon clearing FSTAT[CCIF] to launch the erase verify block command, the memory controller will verify that the selected flash block is erased. The FSTAT[CCIF] flag will set after the erase verify block operation has completed. If the block is not erased, it means blank check failed and both FSTAT[MGSTAT] bits will be set.

Table 18-15. Erase Verify Block command error handling

| Register | Error bit | Error condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 000 at command launch |
| | | Set if an invalid global address [23:0] is supplied ¹ |
| | FPVIOL | None |
| | MGSTAT1 | Set if any errors have been encountered during the read or if blank check failed |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the read or if blank check failed |

1. As found in the memory map for NVM

18.3.9.3 Erase Verify Flash Section command

The Erase Verify Flash Section command will verify that a section of code in the flash memory is erased. The Erase Verify Flash Section command defines the starting point of the code to be verified and the number of longwords.

Table 18-16. Erase verify flash section command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|---|---------------------------------------|
| 000 | 0x03 | Global address [23:16] of flash block |
| 001 | Global address [15:0] of the first longwords to be verified | |
| 010 | Number of long words to be verified | |

Upon clearing FSTAT[CCIF] to launch the erase verify flash section command, the memory controller will verify that the selected section of flash memory is erased. The FSTAT[CCIF] flag will set after the erase verify flash section operation has completed. If the section is not erased, it means blank check failed and both FSTAT[MGSTAT] bits will be set.

Table 18-17. Erase Verify Flash Section command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 010 at command launch |
| | | Set if command not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:0] is supplied (see Table 18-1) ¹ |
| | | Set if a misaligned long words address is supplied (global address[1:0] != 00) |
| | | Set if the requested section crosses flash address boundary |
| | FPVIOL | None |
| | MGSTAT1 | Set if any errors have been encountered during the read ² or if blank check failed |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the read ² or if blank check failed |

1. As defined by the memory map for NVM

2. As found in the memory map for NVM

18.3.9.4 Read once command

The read once command provides read access to a reserved 64-byte field (8 phrase) located in the nonvolatile information register of flash. The read once field can only be programmed once and can not be erased. It can be used to store the product ID or any other information that can be written only once. It is programmed using the program once command described in [Program Once command](#). To avoid code runaway, the read once command must not be executed from the flash block containing the program once reserved field.

Table 18-18. Read Once command FCCOB requirements

| CCOBIX[2:0] | FCCOB parameters | |
|-------------|--|--------------|
| 000 | 0x04 | Not required |
| 001 | Read once phrase index (0x0000 – 0x0007) | |
| 010 | Read once word 0 value | |
| 011 | Read once word 1 value | |
| 100 | Read once word 2 value | |
| 101 | Read once word 3 value | |

Upon clearing FSTAT[CCIF] to launch the read once command, a read once phrase is fetched and stored in the FCCOB indexed register. The FSTAT[CCIF] flag will set after the read once operation has completed. Valid phrase index values for the read once command range from 0x0000 to 0x0007. During execution of the read once command, any attempt to read addresses within flash block will return invalid data.

Table 18-19. Read Once command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 001 at command launch |
| | | Set if command is not available in current mode (see Table 18-4) |
| | | Set if an invalid phrase index is supplied |
| | FPVIOL | None |
| | MGSTAT1 | Set if any errors have been encountered during the read |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the read |

18.3.9.5 Program Flash command

The program flash operation will program up to two previously erased longwords in the flash memory using an embedded algorithm.

Note

A flash phrase must be in the erased state before being programmed. Cumulative programming of bits within a flash phrase is not allowed.

Table 18-20. Program Flash command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|---|--|
| 000 | 0x06 | Global address [23:16] to identify flash block |
| 001 | Global address [15:0] of longwords location to be programmed ¹ | |
| 010 | Word 0 (longword 0) program value | |
| 011 | Word 1 (longword 0) program value | |
| 100 | Word 2 (longword 1) program value | |
| 101 | Word 3 (longword 1) program value | |

1. Global address [1:0] must be 00.

Upon clearing FSTAT[CCIF] to launch the Program Flash command, the memory controller will program the data words to the supplied global address and will then proceed to verify the data words read back as expected. The FSTAT[CCIF] flag will set after the program flash operation has completed.

Table 18-21. Program Flash command error handling

| Register | Error bit | Error condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] ≠ 011 or 101 at command launch |
| | | Set if command not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:0] is supplied (see Table 18-1 . ¹) |
| | | Set if a misaligned longword address is supplied (global address [1:0] != 00) |
| | | Set if the requested group of words breaches the end of the flash block. |
| | FPVIOL | Set if the global address [23:0] points to a protected data |
| | MGSTAT1 | Set if any errors have been encountered during the verify operation |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the verify operation |

1. As defined by the memory map of NVM.

18.3.9.6 Program Once command

The Program Once command restricts programming to a reserved 64-byte field (8 phrases) in the nonvolatile information register located in flash. The program once reserved field can be read using the read once command as described in [Read once command](#). The program once command must be issued only once because the nonvolatile information register in flash cannot be erased. To avoid code runaway, the program once command must not be executed from the flash block containing the program once reserved field.

Table 18-22. Program Once command FCCOB requirements

| CCOBIX[2:0] | FCCOB parameters | |
|-------------|--|--------------|
| 000 | 0x07 | Not required |
| 001 | Program Once phrase index (0x000 – 0x0007) | |
| 010 | Program once Word 0 value | |
| 011 | Program once Word 1 value | |
| 100 | Program once Word 2 value | |
| 101 | Program once Word 3 value | |

Upon clearing FSTAT[CCIF] to launch the program once command, the memory controller first verifies that the selected phrase is erased. If erased, then the selected phrase will be programmed and then verified with read back. The FSTAT[CCIF] flag will remain clear, setting only after the program once operation has completed.

The reserved nonvolatile information register accessed by the Program Once command cannot be erased, and any attempt to program one of these phrases a second time will not be allowed. Valid phrase index values for the program once command range from 0x0000 to 0x0007. During execution of the program once command, any attempt to read addresses within flash will return invalid data.

Table 18-23. Program Once command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 101 at command launch |
| | | Set if command not available in current mode (see Table 18-4) |
| | | Set if an invalid phrase index is supplied |
| | | Set if the requested phrase has already been programmed ¹ |
| | FPVIOL | None |
| | MGSTAT1 | Set if any errors have been encountered during the verify operation |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the verify operation |

1. If a program once phrase is initially programmed to 0xFFFF_FFFF_FFFF_FFFF, the program once command will be allowed to execute again on that same phrase.

18.3.9.7 Erase All Blocks command

The Erase All Blocks operation will erase the entire flash memory space.

Table 18-24. Erase All Blocks command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|--------------------|--------------------|
| 000 | 0x08 | Not required |

Upon clearing FSTAT[CCIF] to launch the Erase All Blocks command, the memory controller will erase the entire NVM memory space and verify that it is erased. If the memory controller verifies that the entire NVM memory space was properly erased, security will be released. Therefore, the device is in unsecured state. During the execution of this command (FSTAT[CCIF] = 0) the user must not write to any NVM module register. The FSTAT[CCIF] flag will set after the erase all blocks operation has completed.

Table 18-25. Erase All Blocks command error handling

| Register | Error bit | Error condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] ≠ 000 at command launch |
| | | Set if command not available in current mode (see Table 18-4) |
| | FPVIOL | Set if any area of the flash memory is protected |

Table continues on the next page...

Table 18-25. Erase All Blocks command error handling (continued)

| Register | Error bit | Error condition |
|----------|-----------|--|
| | MGSTAT1 | Set if any errors have been encountered during the verify operation ¹ |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the verify operation ¹ |

1. As found in the memory map for NVM.

18.3.9.8 Debugger mass erase request

The functionality of the Erase All Blocks command is also available in an uncommanded fashion from the Debugger Mass Erase Request feature.

The Debugger Mass Erase request requires the clock divider register FCLKDIV to be loaded before invoking this function. Please look into the Reference Manual for information about the default value of FCLKDIV in case direct writes to register FCLKDIV are not allowed by the time this feature is invoked. If FCLKDIV is not set the Debugger Mass Erase request will not execute and the FSTAT[ACCERR] flag will set. After the execution of the Mass Erase function, the FCLKDIV register will be reset and the value of register FCLKDIV must be loaded before launching any other command afterwards.

Before invoking the erase-all function, the FSTAT[ACCERR] and FSTAT[FPVIOL] flags must be clear. When invoked the Debugger Mass Erase request will erase all flash memory space regardless of the protection settings. If the post-erase verify passes, the routine will then release security by setting the FSEC[SEC] to the unsecure state. The security byte in the Flash Configuration Field will be programmed to the unsecure state. The status of the Debugger Mass Erase request is reflected in the FCNFG[ERSAREQ]. The FCNFG[ERSAREQ] will be cleared once the operation has completed and the normal FSTAT error reporting will be available as described in the following table.

At the end of the Mass Erase sequence Protection will remain configured as it was before executing the Mass Erase function. If the application requires programming P-Flash after the Mass Erase function completes, the existing protection limits must be taken into account. If protection needs to be disabled the user may need to reset the system right after completing the Mass Erase function.

Table 18-26. Debugger mass erase request error handling

| Register | Error Bit | Error Condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if command not available in current mode. |
| | MGSTAT1 | Set if any errors have been encountered during the erase verify operation, or during the program verify operation. |

Table continues on the next page...

Table 18-26. Debugger mass erase request error handling (continued)

| Register | Error Bit | Error Condition |
|----------|-----------|--|
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the erase verify operation, or during the program verify operation. |

18.3.9.9 Erase flash block command

The erase flash block operation will erase all addresses in a flash block.

Table 18-27. Erase flash block command FCCOB requirements

| CCOBIX[2:0] | FCCOB parameters | |
|-------------|--|--|
| 000 | 0x09 | Global address [23:16] to identify flash block |
| 001 | Global address[15:0] in flash block to be erased | |

Upon clearing FSTAT[CCIF] to launch the erase flash block command, the memory controller will erase the selected flash block and verify that it is erased. The FSTAT[CCIF] flag will set after the erase flash block operation has completed.

Table 18-28. Erase flash block command error handling

| Register | Error Bit | Error Condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 001 at command launch |
| | | Set if command not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:16] is supplied ¹ |
| | FPVIOL | Set if an area of the selected flash block is protected |
| | MGSTAT1 | Set if any errors have been encountered during the verify operation ² |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the verify operation ² |

1. As defined by the memory map for NVM.

2. As found in the memory map for NVM.

18.3.9.10 Erase flash sector command

The erase flash sector operation will erase all addresses in a flash sector.

Table 18-29. Erase flash sector command FCCOB requirements

| CCOBIX[2:0] | FCCOB parameters | |
|-------------|--|---|
| 000 | 0x0A | Global address [23:16] to identify flash block to be erased |
| 001 | Global address [15:0] anywhere within the sector to be erased. Refer to Overview for the flash sector size | |

Upon clearing FSTAT[CCIF] to launch the erase flash sector command, the memory controller will erase the selected flash sector and then verify that it is erased. The FSTAT[CCIF] flag will be set after the erase flash sector operation has completed.

Table 18-30. Erase flash sector command error handling

| Register | Error bit | Error condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 001 at command launch |
| | | Set if command not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:16] is supplied. ¹ (see Table 18-1) |
| | | Set if a misaligned longword address is supplied (global address [1:0] != 00) |
| | FPVIOL | Set if the selected flash sector is protected |
| | MGSTAT1 | Set if any errors have been encountered during the verify operation |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the verify operation |

1. As defined by the memory map for NVM

18.3.9.11 Unsecure flash command

The unsecure flash command will erase the entire flash memory space, and if the erase is successful, will release security.

Table 18-31. Unsecure flash command FCCOB requirements

| CCOBIX[2:0] | FCCOB parameters | |
|-------------|------------------|--------------|
| 000 | 0x0B | Not required |

Upon clearing FSTAT[CCIF] to launch the unsecure flash command, the memory controller will erase the entire flash memory space and verify that it is erased. If the memory controller verifies that the entire flash memory space was properly erased, security will be released. If the erase verify is not successful, the unsecure flash operation sets FSTAT[MGSTAT1] and terminates without changing the security state. During the execution of this command (FSTAT[CCIF] = 0), the user must not write to any flash module register. The FSTAT[CCIF] flag is set after the unsecure flash operation has completed.

Table 18-32. Unsecure flash command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 000 at command launch |
| | | Set if command is not available in current mode (see Table 18-4) |

Table continues on the next page...

Table 18-32. Unsecure flash command error handling (continued)

| Register | Error bit | Error condition |
|----------|-----------|--|
| | FPVIOL | Set if any area of the flash memory is protected |
| | MGSTAT1 | Set if any errors have been encountered during the verify operation ¹ |
| | MGSTAT0 | Set if any non-correctable errors have been encountered during the verify operation ¹ |

1. As found in the memory map for NVM

18.3.9.12 Verify backdoor access key command

The verify backdoor access key command will execute only if it is enabled by the FSEC[KEYEN] bits. The verify backdoor access key command releases security if user-supplied keys match those stored in the flash security bytes of the flash configuration field. See [Table 18-1](#) for details. The code that performs verifying backdoor access command must be running from RAM.

Table 18-33. Verify backdoor access key command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|--------------------|--------------------|
| 000 | 0x0C | Not required |
| 001 | | Key 0 |
| 010 | | Key 1 |
| 011 | | Key 2 |
| 100 | | Key 3 |

Upon clearing FSTAT[CCIF] to launch the verify backdoor access key command, the memory controller will check the FSEC[KEYEN] bits to verify that this command is enabled. If not enabled, the memory controller sets the FSTAT[ACCERR] bit. If the command is enabled, the memory controller compares the key provided in FCCOB to the backdoor comparison key in the flash configuration field with Key 0 compared to 0x0400, and so on. If the backdoor keys match, security will be released. If the backdoor keys do not match, security is not released and all future attempts to execute the verify backdoor access key command are aborted (set FSTAT[ACCERR]) until a reset occurs. The FSTAT[CCIF] flag is set after the verify backdoor access key operation has completed.

Table 18-34. Verify backdoor access key command error handling

| Register | Error bit | Error condition |
|----------|-----------|--|
| FSTAT | ACCERR | Set if CCOBIX[2:0] ≠ 100 at command launch |
| | | Set if an incorrect backdoor key is supplied |

Table continues on the next page...

Table 18-34. Verify backdoor access key command error handling (continued)

| Register | Error bit | Error condition |
|----------|-----------|---|
| | | Set if backdoor key access has not been enabled (KEYEN[1:0] ≠ 10) |
| | | Set if the backdoor key has mismatched since the last reset |
| | FPVIOL | None |
| | MGSTAT1 | None |
| | MGSTAT0 | None |

18.3.9.13 Set user margin level command

The user margin is a small delta to the normal read reference level and, in effect, is a minimum safety margin. That is, if the reads pass at the tighter tolerances of the user margins, the normal reads have at least that much safety margin before users experience data loss.

The set user margin level command causes the memory controller to set the margin level for future read operations of the flash block.

Table 18-35. Set user margin level command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|---|--|
| 000 | 0x0D | Global address [23:16] to identify flash block |
| 001 | Global address [15:0] to identify flash block | |
| 010 | Margin level setting | |

Upon clearing FSTAT[CCIF] to launch the set user margin level command, the memory controller will set the user margin level for the targeted block and then set the FSTAT[CCIF] flag.

Note

Valid margin level settings for the set user margin level command are defined in the following tables.

Table 18-36. Valid set user margin level settings

| CCOB (CCOBIX = 010) | Level description |
|------------------------|----------------------------------|
| 0x0000 | Return to normal level |
| 0x0001 | User margin-1 level ¹ |
| 0x0002 | User margin-0 level ² |

1. Read margin to the erased state

2. Read margin to the programmed state

Table 18-37. Set user margin level command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 010 at command launch |
| | | Set if command is not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:0] is supplied |
| | | Set if an invalid margin level setting is supplied |
| | FPVIOL | None |
| | MGSTAT1 | None |
| | MGSTAT0 | None |

Note

User margin levels can be used to check that NVM memory contents have adequate margin for normal level read operations. If unexpected results are encountered when checking NVM memory contents at user margin levels, a potential loss of information has been detected.

18.3.9.14 Set factory margin level command

The set factory margin Level command causes the memory controller to set the margin level specified for future read operations of the flash block.

Table 18-38. Set factory margin level command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|---|--|
| 000 | 0x0E | Global address [23:16] to identify flash block |
| 001 | Global address [15:0] to identify flash block | |
| 010 | Margin level setting | |

Upon clearing FSTAT[CCIF] to launch the set factory margin level command, the memory controller will set the factory margin level for the targeted block and then set the FSTAT[CCIF] flag.

Note

Valid margin level settings for the set factory margin level command are defined in the following tables.

Table 18-39. Valid set factory margin level settings

| CCOB (CCOBIX = 010) | Level description |
|------------------------|-------------------------------------|
| 0x0000 | Return to normal level |
| 0x0001 | User margin-1 level ¹ |
| 0x0002 | User margin-0 level ² |
| 0x0003 | Factory margin-1 level ¹ |
| 0x0004 | Factory margin-0 level ² |

1. Read margin to the erased state
2. Read margin to the programmed state

Table 18-40. Set factory margin level command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 010 at command launch |
| | | Set if command is not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:0] is supplied |
| | | Set if an invalid margin level setting is supplied |
| | FPVIOL | None |
| | MGSTAT1 | None |
| | MGSTAT0 | None |

CAUTION

Factory margin levels must only be used during verify of the initial factory programming.

Note

Factory margin levels can be used to check that Flash memory contents have adequate margin for data retention at the normal level setting. If unexpected results are encountered when checking flash memory contents at factory margin levels, the flash memory contents must be erased and reprogrammed.

18.3.9.15 Configure NVM command

The Configure NVM command allows the user to control some features in the NVM array, enabling or disabling them with the purpose to save current/power under certain circumstances. The settings modified with Configure NVM command are not permanent, therefore the command must be invoked after each reset if changing these settings is required in the user application.

Table 18-41. Configure NVM command FCCOB requirements

| CCOBIX[2:0] | FCCOBHI parameters | FCCOBLO parameters |
|-------------|--------------------|--|
| 000 | 0x0F | Configure NVM control byte as the following table. |

Table 18-42. NVM Control Byte - field descriptions

| Field | Description |
|------------|---|
| 7 QUERY | <p>Query / Drive Mode - This bit controls if Configure NVM command will be used to drive or to retrieve current status of FLPHV and FLPLF bits.</p> <p>0 Drive option on bits FLPHV and FLPLF into the NVM array</p> <p>1 Query current status of FLPHV and FLPLF. FCCOB[0] can be read after command execution to retrieve current status of FLPHV and FLPLV.</p> |
| 6-2 RNV | <p>Reserved Bits - The RNV bits should be 1'b0, reserved for future enhancements.</p> |
| 1 FLPHV | <p>Flash Low Power Control With High Supply Voltage - The FLPHV bit controls a circuit in the NVM Array that generates an internal voltage reference to be used in Flash reads when the device is operating in the lower range of the external supply voltage specification. Under specific circumstances this circuit can be disabled to save power.</p> <p>0 Circuit enabled (recommended, default value) - this ensures that the NVM Array will work correctly for reads across the full range of the external supply voltage.</p> <p>1 Circuit disabled - to be set only if the external voltage supply is guaranteed to drive voltage above a minimum level.</p> |
| 0 FLPLF | <p>Flash Low Power Control In Low Frequency - The FLPLF bit controls a circuit in the NVM Array that limits current consumption during Flash reads if the device is running in low frequencies. The circuit itself consumes some power and is recommended to be disabled for typical frequency settings. Under specific circumstances (low bus frequency) this circuit can be enabled to save power.</p> <p>0 Circuit disabled (recommended, default value¹) - for typical bus frequency values this circuit can be left disabled to minimize power consumption.</p> <p>1 Circuit enabled - to be set if the bus frequency is setup to be below a minimum threshold, so the Flash will save power while operating in low frequency.</p> |

1. Freescale might deliver parts with a different initial setting for this control in the NVM Array, eventually under a different part number, if the part is to be used specifically in a low frequency range of operation. Therefore, if the user is not sure about the initial setting of this control it is advisable to first run the Configure NVM command in Query mode to retrieve the initial status of FLPLF.

FLPHV controls an internal circuit that guarantees correct Flash reads across the full range of the external voltage supply, more specifically in the lower levels of the voltage specification. FLPHV can be used to disable this circuit if the external supply source drives the voltage above a minimum level specified in the NVM Electrical Parameters - please refer to the proper section in the Reference Manual to identify this minimum required voltage level and the current savings in case this circuit can be disabled.

CAUTION

There is a risk if the user incorrectly disables the circuit controlled by FLPHV and the operating voltage goes below the minimum supply voltage level as specified. Under this condition the Flash will not read meaningful data, with unpredictable results. The only way to restore the Flash functionality may be to reset the part, so the NVM Array will be restored to default conditions (i.e. the circuit controlled by FLPHV is enabled)

FLPLF controls an internal circuit that limits current consumption during Flash reads if the Flash is running at lower bus frequencies (BUSCLK). Under typical frequency values this circuit is recommended to be disabled to save power, but for applications that run at low frequencies this circuit can be enabled to minimize current consumption. For details about the threshold bus frequency value under which there can be some power savings by enabling this circuit.

NOTE

Bit FLPLF relates to Read operations, that are affected by the bus frequency (BUSCLK), whereas program and erase operations are affected by the FCLK time base that is unrelated to FLPLF.

Upon clearing CCIF to launch the Configure NVM command the MGATE will set the NVM Array parameters accordingly (if the command is launched in Drive mode - QUERY=0) and then set the CCIF flag. The current status of FLPHV and FLPLV can always be read in FCCOB[0] after the command execution. The Configure NVM command can be executed in Query Mode (QUERY=1) to retrieve the status of these bits without driving them into the NVM array.

The user is not required to run the Configure NVM command for correct operation of the Flash array. The default value after reset are the recommended / safe states for operation of the Flash. The Configure NVM command is intended to be invoked only in conditions where it can be used to save some power, as explained above.

Table 18-43. Configure NVM command error handling

| Register | Error bit | Error condition |
|----------|-----------|---|
| FSTAT | ACCERR | Set if CCOBIX[2:0] != 000 at command launch |
| | | Set if command is not available in current mode (see Table 18-4) |
| | | Set if an invalid global address [23:0] is supplied |
| | | Set if an invalid margin level setting is supplied |
| | FPVIOL | None |

Table continues on the next page...

Table 18-43. Configure NVM command error handling (continued)

| Register | Error bit | Error condition |
|----------|-----------|-----------------|
| | MGSTAT1 | None |
| | MGSTAT0 | None |

18.4 Memory map and register definition

This section presents a high-level summary of the registers and how they are mapped. The registers can be accessed in 32-bits, 16-bits (aligned on data[31:16] or on data[15:0]) or 8-bits. In the case of the writable registers, the write accesses are forbidden during flash command execution. For more details, see Caution note in [Flash memory map](#).

FTMRE memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|--------|-----------------------------|----------------------------|
| 4002_0001 | Flash CCOB Index Register (FTMRE_FCCOBIX) | 8 | R/W | 00h | 18.4.1/273 |
| 4002_0002 | Flash Security Register (FTMRE_FSEC) | 8 | R | Undefined | 18.4.2/274 |
| 4002_0003 | Flash Clock Divider Register (FTMRE_FCLKDIV) | 8 | R/W | 00h | 18.4.3/275 |
| 4002_0005 | Flash Status Register (FTMRE_FSTAT) | 8 | R/W | 80h | 18.4.4/276 |
| 4002_0007 | Flash Configuration Register (FTMRE_FCNFG) | 8 | R/W | 00h | 18.4.5/277 |
| 4002_0008 | Flash Common Command Object Register: Low (FTMRE_FCCOBLO) | 8 | R/W | 00h | 18.4.6/278 |
| 4002_0009 | Flash Common Command Object Register: High (FTMRE_FCCOBHI) | 8 | R/W | 00h | 18.4.7/278 |
| 4002_000B | Flash Protection Register (FTMRE_FPROT) | 8 | R | See section | 18.4.8/278 |
| 4002_000F | Flash Option Register (FTMRE_FOPT) | 8 | R | Undefined | 18.4.9/280 |

18.4.1 Flash CCOB Index Register (FTMRE_FCCOBIX)

The FCCOBIX register is used to index the FCCOB register for NVM memory operations.

Address: 4002_0000h base + 1h offset = 4002_0001h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---|---|---|---|--------|---|---|---|
| Read | 0 | | | | CCOBIX | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMRE_FCCOBIX field descriptions

| Field | Description |
|-----------------|--|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| CFOBIX | Common Command Register Index Selects which word of the FCCOB register array is being read or written to. |

18.4.2 Flash Security Register (FTMRE_FSEC)

The FSEC register holds all bits associated with the security of the MCU and NVM module. All fields in the FSEC register are readable but not writable. During the reset sequence, the FSEC register is loaded with the contents of the flash security byte in the flash configuration field located in flash memory.

See [Security](#) for security function.

Address: 4002_0000h base + 2h offset = 4002_0002h

| | | | | | | | | |
|-------|-------|----|----------|----|----|----|-----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | KEYEN | | Reserved | | | | SEC | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

FTMRE_FSEC field descriptions

| Field | Description |
|-----------------|---|
| 7–6 KEYEN | Backdoor Key Security Enable Bits The KEYEN[1:0] bits define the enabling of backdoor key access to the flash module. NOTE: 01 is the preferred KEYEN state to disable backdoor key access. 00 Disabled 01 Disabled 10 Enabled 11 Disabled |
| 5–2 Reserved | This field is reserved. |
| SEC | Flash Security Bits Defines the security state of the MCU. If the flash module is unsecured using backdoor key access, the SEC field is forced to 10. NOTE: 00 is the preferred SEC state to set MCU to secured state. |

Table continues on the next page...

FTMRE_FSEC field descriptions (continued)

| Field | Description |
|-------|-------------|
| 00 | Secured |
| 01 | Secured |
| 10 | Unsecured |
| 11 | Secured |

18.4.3 Flash Clock Divider Register (FTMRE_FCLKDIV)

The FCLKDIV register is used to control timed events in program and erase algorithms.

NOTE

The FCLKDIV register must not be written while a flash command is executing (FSTAT[CCIF] = 0)

Address: 4002_0000h base + 3h offset = 4002_0003h

| | | | | | | | | |
|-------|--------|---------|------|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | FDIVLD | FDIVLCK | FDIV | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMRE_FCLKDIV field descriptions

| Field | Description |
|--------------|---|
| 7 FDIVLD | Clock Divider Loaded 0 FCLKDIV register has not been written since the last reset. 1 FCLKDIV register has been written since the last reset. |
| 6 FDIVLCK | Clock Divider Locked 0 FDIV field is open for writing. 1 FDIV value is locked and cannot be changed. After the lock bit is set high, only reset can clear this bit and restore writability to the FDIV field in user mode. |
| FDIV | Clock Divider Bits FDIV[5:0] must be set to effectively divide BUSCLK down to 1MHz to control timed events during flash program and erase algorithms. Refer to the table in the Writing the FCLKDIV register for the recommended values of FDIV based on the BUSCLK frequency. |

18.4.4 Flash Status Register (FTMRE_FSTAT)

The FSTAT register reports the operational status of the flash module.

Address: 4002_0000h base + 5h offset = 4002_0005h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|---|--------|--------|--------|---|--------|---|
| Read | CCIF | 0 | ACCERR | FPVIOL | MGBUSY | 0 | MGSTAT | |
| Write | | | | | | | | |
| Reset | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMRE_FSTAT field descriptions

| Field | Description |
|---------------|--|
| 7 CCIF | <p>Command Complete Interrupt Flag</p> <p>Indicates that a flash command has completed. The CCIF flag is cleared by writing a 1 to CCIF to launch a command and CCIF will stay low until command completion or command violation.</p> <p>0 Flash command is in progress. 1 Flash command has completed.</p> |
| 6 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 5 ACCERR | <p>Flash Access Error Flag</p> <p>Indicates an illegal access has occurred to the flash memory caused by either a violation of the command write sequence or issuing an illegal flash command. While ACCERR is set, the CCIF flag cannot be cleared to launch a command. Writing 1 to this field clears it while writing a 0 to this field has no effect.</p> <p>0 No access error is detected. 1 Access error is detected.</p> |
| 4 FPVIOL | <p>Flash Protection Violation Flag</p> <p>Indicates an attempt was made to program or erase an address in a protected area of flash memory during a command write sequence. Writing 1 to FPVIOL clears this field while writing 0 to this field has no effect. While FPIOL is set, it is not possible to launch a command or start a command write sequence.</p> <p>0 No protection violation is detected. 1 Protection violation is detected.</p> |
| 3 MGBUSY | <p>Memory Controller Busy Flag</p> <p>Reflects the active state of the memory controller.</p> <p>0 Memory controller is idle. 1 Memory controller is busy executing a flash command (CCIF = 0).</p> |
| 2 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| MGSTAT | Memory Controller Command Completion Status Flag |

Table continues on the next page...

FTMRE_FSTAT field descriptions (continued)

| Field | Description |
|-------|--|
| | One or more MGSTAT flag bits are set if an error is detected during execution of a flash command or during the flash reset sequence. NOTE: Reset value can deviate from the value shown if a double bit fault is detected during the reset sequence. |

18.4.5 Flash Configuration Register (FTMRE_FCNFG)

The FCNFG register enables the flash command complete interrupt and forces ECC faults on flash array read access from the CPU.

Address: 4002_0000h base + 7h offset = 4002_0007h

| | | | | | | | | |
|-------|------|---|---------|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | CCIE | 0 | ERSAREQ | | | 0 | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMRE_FCNFG field descriptions

| Field | Description |
|---------------|--|
| 7 CCIE | Command Complete Interrupt Enable Controls interrupt generation when a flash command has completed. 0 Command complete interrupt is disabled. 1 An interrupt will be requested whenever the CCIF flag in the FSTAT register is set. |
| 6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5 ERSAREQ | Debugger Mass Erase Request Requests the MGATE to execute the Erase All Blocks command and release security. ERSAREQ is not directly writable but is under indirect user control. The ERSAREQ field sets to 1 when the MGATE starts executing the sequence. ERSAREQ will be reset to 0 by the MGATE when the operation is completed 0 No request or request complete 1 Request to <ul style="list-style-type: none"> run the Erase All Blocks command verify the erased state program the security byte in the Flash Configuration Field to the unsecure state release MCU security by setting FSEC[SEC] to the unsecure state |
| Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

18.4.6 Flash Common Command Object Register: Low (FTMRE_FCCOBLO)

The FCCOB is an array of six words addressed via the CCOBIX index found in the FCCOBIX register. Byte-wide reads and writes are allowed to the FCCOB register.

Address: 4002_0000h base + 8h offset = 4002_0008h

| | | | | | | | | |
|-------|------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | CCOB | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMRE_FCCOBLO field descriptions

| Field | Description |
|-------|---|
| CCOB | Common Command Object Bit 7:0 Low 8 bits of Common Command Object register |

18.4.7 Flash Common Command Object Register:High (FTMRE_FCCOBHI)

The FCCOB is an array of six words addressed via the CCOBIX index found in the FCCOBIX register. Byte-wide reads and writes are allowed to the FCCOB register.

Address: 4002_0000h base + 9h offset = 4002_0009h

| | | | | | | | | |
|-------|------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | CCOB | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMRE_FCCOBHI field descriptions

| Field | Description |
|-------|---|
| CCOB | Common Command Object Bit 15:8 High 8 bits of Common Command Object register |

18.4.8 Flash Protection Register (FTMRE_FPROT)

The FPROT register defines which flash sectors are protected against program and erase operations.

The unreserved bits of the FPROT register are writable with the restriction that the size of the protected region can only be increased (see [Protection](#)).

During the reset sequence, the FPROT register is loaded with the contents of the flash protection byte in the flash configuration field at global address 0x40D located in flash memory. To change the flash protection that will be loaded during the reset sequence, the upper sector of the flash memory must be unprotected, then the flash protection byte must be reprogrammed.

Trying to alter data in any protected area in the flash memory will result in a protection violation error and the FPVIOL bit will be set in the FSTAT register. The block erase of a flash block is not possible if any of the flash sectors contained in the same flash block are protected.

Address: 4002_0000h base + Bh offset = 4002_000Bh

| | | | | | | | | |
|-------|--------|------|--------|------|--------|------|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | FPOPEN | RNV6 | FPHDIS | FPHS | FPLDIS | FPLS | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

FTMRE_FPROT field descriptions

| Field | Description |
|-------------|--|
| 7 FPOPEN | Flash Protection Operation Enable The FPOPEN bit determines the protection function for program or erase operations. 0 When FPOPEN is clear, the FPHDIS and FPLDIS fields define unprotected address ranges as specified by the corresponding FPHS and FPLS fields. 1 When FPOPEN is set, the FPHDIS and FPLDIS fields enable protection for the address range specified by the corresponding FPHS and FPLS fields. |
| 6 RNV6 | Reserved Nonvolatile Bit The RNV bit must remain in the erased state. |
| 5 FPHDIS | Flash Protection Higher Address Range Disable The FPHDIS bit determines whether there is a protected/unprotected area in a specific region of the flash memory ending with global address 0x7FFF. 0 Protection/Unprotection enabled. 1 Protection/Unprotection disabled. |
| 4–3 FPHS | Flash Protection Higher Address Size The FPHS bits determine the size of the protected/unprotected area in flash memory. The FPHS bits can be written to only while the FPHDIS bit is set. |
| 2 FPLDIS | Flash Protection Lower Address Range Disable The FPLDIS bit determines whether there is a protected/unprotected area in a specific region of the flash memory beginning with global address 0x0_0000. 0 Protection/Unprotection enabled. 1 Protection/Unprotection disabled. |
| FPLS | Flash Protection Lower Address Size |

Table continues on the next page...

FTMRE_FPROT field descriptions (continued)

| Field | Description |
|-------|---|
| | The FPLS bits determine the size of the protected/unprotected area in flash memory. The FPLS bits can only be written to while the FPLDIS bit is set. |

18.4.9 Flash Option Register (FTMRE_FOPT)

The FOPT register is the flash option register.

During the reset sequence, the FOPT register is loaded from the flash nonvolatile byte in the flash configuration field at global address 0x040F located in flash memory as indicated by reset condition.

Address: 4002_0000h base + Fh offset = 4002_000Fh

| | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | NV | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

FTMRE_FOPT field descriptions

| Field | Description |
|-------|--|
| NV | Nonvolatile Bits The NV[7:0] bits are available as nonvolatile bits. During the reset sequence, the FOPT register is loaded from the flash nonvolatile byte in the flash configuration field at global address 0x40F located in flash memory. |

Chapter 19

Flash Memory Controller (FMC)

19.1 Introduction

The Flash Memory Controller (FMC) is a memory acceleration unit. A list of features provided by the FMC can be found here.

- an interface between bus masters and the 32-bit program flash memory.
- a buffer and a cache that can accelerate program flash memory data transfers.

19.1.1 Overview

The Flash Memory Controller manages the interface between bus masters and the 32-bit program flash memory. The FMC receives status information detailing the configuration of the flash memory and uses this information to ensure a proper interface. The FMC supports 8-bit, 16-bit, and 32-bit read operations from the program flash memory. A write operation to program flash memory results in a bus error.

In addition, the FMC provides two separate mechanisms for accelerating the interface between bus masters and program flash memory. A 32-bit speculation buffer can prefetch the next 32-bit flash memory location, and a 4-way, 2-set program flash memory cache can store previously accessed program flash memory data for quick access times.

19.1.2 Features

The features of FMC module include:

- Interface between bus masters and the 32-bit program flash memory:
 - 8-bit, 16-bit, and 32-bit read operations to nonvolatile flash memory.
- Acceleration of data transfer from the program flash memory to the device:

- 32-bit prefetch speculation buffer for program flash accesses with controls for instruction/data access
- 4-way, 2-set, 32-bit line size program flash memory cache for a total of eight 32-bit entries with invalidation control

19.2 Modes of operation

The FMC operates only when a bus master accesses the program flash memory.

In terms of chip power modes:

- The FMC operates only in Run and Wait modes.
- For any power mode where the program flash memory cannot be accessed, the FMC is disabled.

19.3 External signal description

The FMC has no external (off-chip) signals.

19.4 Memory map and register descriptions

The MCM's programming model provides control and configuration of the FMC's features.

For details, see the description of the MCM's Platform Control Register (PLACR).

19.5 Functional description

The FMC is a flash acceleration unit with flexible buffers for user configuration.

Besides managing the interface between bus masters and the program flash memory, the FMC can be used to customize the program flash memory cache and buffer to provide single-cycle system clock data access times. Whenever a hit occurs for the prefetch speculation buffer or the cache (when enabled), the requested data is transferred within a single system clock.

Upon system reset, the FMC is configured as follows:

- Flash cache is enabled.
- Instruction speculation and caching are enabled.

- Data speculation is disabled.
- Data caching is enabled.

Though the default configuration provides flash acceleration, advanced users may desire to customize the FMC buffer configurations to maximize throughput for their use cases. For example, the user may adjust the controls to enable buffering per access type (data or instruction).

NOTE

When reconfiguring the FMC, do not program the control and configuration inputs to the FMC while the program flash memory is being accessed. Instead, change them with a routine executing from RAM in supervisor mode.

Chapter 20

Internal Clock Source (ICS)

20.1 Introduction

The internal clock source (ICS) module provides clock source choices for the MCU. The module contains a frequency-locked loop (FLL) as a clock source that is controllable by either an internal or an external reference clock. The module can provide this FLL clock or either of the internal or external reference clocks as a source for the MCU system clock. There are also signals provided to control a low-power oscillator (OSC) module. These signals configure and enable the OSC module to generate its external crystal/resonator clock (OSC_OUT) used by peripheral modules and as the ICS external reference clock source. The ICS external reference clock can be the external crystal/resonator (OSC_OUT) supplied by an OSC, or it can be another external clock source.

The ICS clock source chosen is passed through a reduced bus divider (BDIV) which allows a lower final output clock frequency to be derived.

20.1.1 Features

The key features of the ICS module are given below:

- Internal reference clock is trimmable for accuracy
- Internal or external reference clocks can be used to control the FLL.
- Selectable dividers for external reference clock to ensure proper input frequency to FLL.
- Internal reference clock has 9 trim bits available.
- Internal or external reference clocks can be selected as the clock source for the MCU.
- FLL Engaged Internal mode is automatically selected out of reset.
- FLL lock detector and external clock monitor
 - FLL lock detector with interrupt capability
 - External reference clock monitor with reset capability
- Digitally controlled oscillator optimized for 40-48 MHz frequency range

20.1.2 Block diagram

The following figure is the ICS block diagram.

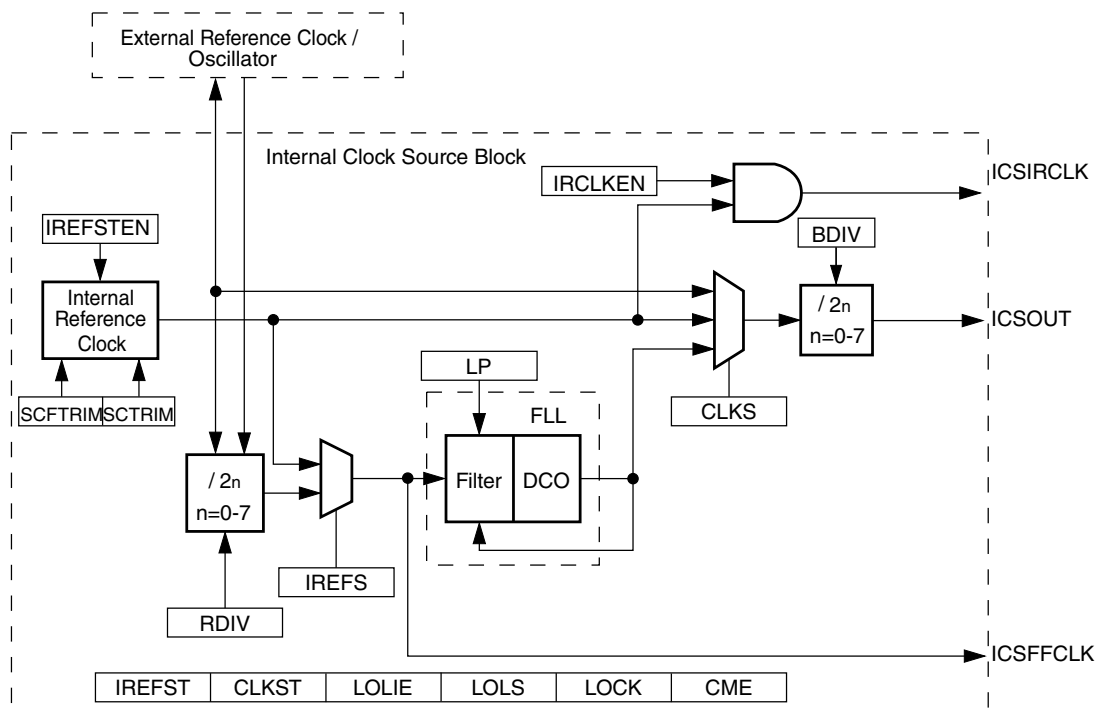


Figure 20-1. Internal clock source (ICS) block diagram

20.1.3 Modes of operation

There are seven modes of operation for the ICS: FEI, FEE, FBI, FBILP, FBE, FBELP, and STOP. Each of these modes is explained briefly in the following subsections.

20.1.3.1 FLL engaged internal (FEI)

In FLL engaged internal mode, which is the default mode, the ICS supplies a clock derived from the FLL which is controlled by the internal reference clock.

20.1.3.2 FLL engaged external (FEE)

In FLL engaged external mode, the ICS supplies a clock derived from the FLL which is controlled by an external reference clock source.

20.1.3.3 FLL bypassed internal (FBI)

In FLL bypassed internal mode, the FLL is enabled and controlled by the internal reference clock, but is bypassed. The ICS supplies a clock derived from the internal reference clock.

20.1.3.4 FLL bypassed internal low power (FBILP)

In FLL bypassed internal low power mode, the FLL is disabled and bypassed, and the ICS supplies a clock derived from the internal reference clock.

20.1.3.5 FLL bypassed external (FBE)

In FLL bypassed external mode, the FLL is enabled and controlled by an external reference clock, but is bypassed. The ICS supplies a clock derived from the external reference clock source.

20.1.3.6 FLL bypassed external low power (FBELP)

In FLL bypassed external low power mode, the FLL is disabled and bypassed, and the ICS supplies a clock derived from the external reference clock.

20.1.3.7 Stop (STOP)

In Stop mode, the FLL is disabled and the internal or the ICS external reference clocks source (OSC_OUT) can be selected to be enabled or disabled. The ICS does not provide any MCU clock sources.

NOTE

The DCO frequency changes from the pre-stop value to its reset value and the FLL needs to reacquire the lock before the frequency is stable. Timing sensitive operations must wait for the FLL acquisition time, $t_{Acquire}$, before executing.

20.2 External signal description

There are no ICS signals that connect off chip.

20.3 Register definition

ICS memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---------------------------------|-----------------|--------|-----------------------------|----------------------------|
| 4006_4000 | ICS Control Register 1 (ICS_C1) | 8 | R/W | 04h | 20.3.1/288 |
| 4006_4001 | ICS Control Register 2 (ICS_C2) | 8 | R/W | 20h | 20.3.2/289 |
| 4006_4002 | ICS Control Register 3 (ICS_C3) | 8 | R/W | Undefined | 20.3.3/290 |
| 4006_4003 | ICS Control Register 4 (ICS_C4) | 8 | R/W | See section | 20.3.4/291 |
| 4006_4004 | ICS Status Register (ICS_S) | 8 | R | 10h | 20.3.5/292 |

20.3.1 ICS Control Register 1 (ICS_C1)

Address: 4006_4000h base + 0h offset = 4006_4000h

| | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

ICS_C1 field descriptions

| Field | Description |
|-------------|---|
| 7–6 CLKS | <p>Clock Source Select</p> <p>Selects the clock source that controls the bus frequency. The actual bus frequency depends on the value of ICS_C2[BDIV].</p> <p>00 Output of FLL is selected. 01 Internal reference clock is selected. 10 External reference clock is selected. 11 Reserved, defaults to 00.</p> |
| 5–3 RDIV | <p>Reference Divider</p> <p>Changing RDIV will cause the change of reference clock frequency of FLL, RDIV is not allowed to be changed in FEE/FBE mode.</p> <p>Selects the amount to divide down the FLL reference clock selected by the IREFS bits. Resulting frequency must be in the range 31.25 kHz to 39.0625 kHz.</p> |

Table continues on the next page...

ICS_C1 field descriptions (continued)

| Field | Description | | |
|---------------|---|--------------------------|--------------------------|
| | RDIV | OSC_CR[RANGE] = 0 | OSC_CR[RANGE] = 1 |
| | 000 | 1 ¹ | 32 |
| | 001 | 2 | 64 |
| | 010 | 4 | 128 |
| | 011 | 8 | 256 |
| | 100 | 16 | 512 |
| | 101 | 32 | 1024 |
| | 110 | 64 | Reserved |
| | 111 | 128 | Reserved |
| | 1. Reset default | | |
| 2 IREFS | Internal Reference Select Selects the reference clock source for the FLL. 0 External reference clock is selected. 1 Internal reference clock is selected. | | |
| 1 IRCLKEN | Internal Reference Clock Enable Enables the internal reference clock for use as ICSIRCLK. 0 ICSIRCLK is inactive. 1 ICSIRCLK is active. | | |
| 0 IREFSTEN | Internal Reference Stop Enable Controls whether or not the internal reference clock remains enabled when the ICS enters Stop mode. 0 Internal reference clock is disabled in Stop mode. 1 Internal reference clock stays enabled in Stop mode if IRCLKEN is set, or if ICS is in FEI, FBI, or FBILP mode before entering Stop. | | |

1. Reset default

20.3.2 ICS Control Register 2 (ICS_C2)

Address: 4006_4000h base + 1h offset = 4006_4001h

| | | | | | | | | |
|-------|------|---|---|----|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | BDIV | | | LP | 0 | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |

ICS_C2 field descriptions

| Field | Description |
|-------------|-----------------------|
| 7–5 BDIV | Bus Frequency Divider |

Table continues on the next page...

ICS_C2 field descriptions (continued)

| Field | Description |
|----------|---|
| | <p>Selects the amount to divide down the clock source selected by ICS_C1[CLKS]. This controls the bus frequency.</p> <p>000 Encoding 0—Divides the selected clock by 1. 001 Encoding 1—Divides the selected clock by 2 (reset default). 010 Encoding 2—Divides the selected clock by 4. 011 Encoding 3—Divides the selected clock by 8. 100 Encoding 4—Divides the selected clock by 16. 101 Encoding 5—Divides the selected clock by 32. 110 Encoding 6—Divides the selected clock by 64. 111 Encoding 7—Divides the selected clock by 128.</p> |
| 4 LP | <p>Low Power Select</p> <p>Controls whether the FLL is disabled in FLL bypassed modes.</p> <p>0 FLL is not disabled in bypass mode. 1 FLL is disabled in bypass modes unless debug is active.</p> |
| Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |

20.3.3 ICS Control Register 3 (ICS_C3)

Address: 4006_4000h base + 2h offset = 4006_4002h

| | | | | | | | | |
|-------|--------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | SCTRIM | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

ICS_C3 field descriptions

| Field | Description |
|--------|---|
| SCTRIM | <p>Slow Internal Reference Clock Trim Setting</p> <p>Controls the slow internal reference clock frequency by controlling the internal reference clock period. The bits are binary weighted. In other words, bit 1 adjusts twice as much as bit 0. Increasing the binary value of SCTRIM will increase the period, and decreasing the value will decrease the period. An additional fine trim bit is available as the ICS_C4[SCFTRIM].</p> <p>ICS_C3 is automatically loaded during reset from a factory programmed location when not in a debug mode. The factory programmed trim value adjusts the internal oscillator frequency to fint_ft as specified in the datasheet. The user can provide a custom trim value to attain other internal reference clock frequencies within the fint_t range. The custom trim value must be programmed into reserved flash location 0x0000_03FF and copied to ICS_C3 during code initialization.</p> |

20.3.4 ICS Control Register 4 (ICS_C4)

Address: 4006_4000h base + 3h offset = 4006_4003h

| | | | | | | | | |
|-------|-------|---|-----|---|---|---|---|---------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | LOLIE | 0 | CME | 0 | | | | SCFTRIM |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | x* |

* Notes:

- x = Undefined at reset.

ICS_C4 field descriptions

| Field | Description |
|-----------------|---|
| 7 LOLIE | <p>Loss of Lock Interrupt</p> <p>Determines if an interrupt request is made following a loss of lock indication. This field has an effect only when ICS_S[LOLS] is set.</p> <p>0 No request on loss of lock. 1 Generates an interrupt request on loss of lock.</p> |
| 6 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 5 CME | <p>Clock Monitor Enable</p> <p>Determines if a reset request is made following a loss of external clock indication. This field must be set to a logic 1 only when the ICS is in an operational mode that uses the external clock (FEE, FBE, or FBELP).</p> <p>0 Clock monitor is disabled. 1 Generates a reset request on loss of external clock.</p> |
| 4–1 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 0 SCFTRIM | <p>Slow Internal Reference Clock Fine Trim</p> <p>Controls the smallest adjustment of the internal reference clock frequency. Setting SCFTRIM will increase the period and clearing SCFTRIM will decrease the period by the smallest amount possible.</p> <p>ICS_C4[SCFTRIM] is automatically loaded during reset from a factory programmed location when not in a debug mode. The factory programmed trim value adjusts the internal oscillator frequency to fint_ft as specified in the datasheet. The user can provide a custom trim value to attain other internal reference clock frequencies within the fint_t range. The custom fine trim bit value must be programmed into reserved flash location 0x0000_03FE and copied to ICS_C4 during code initialization.</p> |

20.3.5 ICS Status Register (ICS_S)

Address: 4006_4000h base + 4h offset = 4006_4004h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|------|---|--------|-------|---|---|---|
| Read | LOLS | LOCK | 0 | IREFST | CLKST | | 0 | |
| Write | w1c | | | | | | | |
| Reset | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

ICS_S field descriptions

| Field | Description |
|---------------|---|
| 7 LOLS | <p>Loss of Lock Status</p> <p>Indicates the lock status for the FLL. LOLS is set when lock detection is enabled and after acquiring lock, the FLL output frequency has fallen outside the lock exit frequency tolerance, from $\pm 4.7\%$ to $\pm 5.97\%$. ICS_C4[LOLIE] determines whether an interrupt request is made when set. LOLS is cleared by reset or by writing a logic 1 to LOLS when LOLS is set. Writing a logic 0 to LOLS has no effect.</p> <p>0 FLL has not lost lock since LOLS was last cleared. 1 FLL has lost lock since LOLS was last cleared.</p> |
| 6 LOCK | <p>Lock Status</p> <p>Indicates whether the FLL has acquired lock. Lock detection is disabled when FLL is disabled. If the lock status bit is set then changing the value of any of the following fields IREFS, RDIV[2:0], or, if in FEI or FBI modes, SCTRIM[7:0] will cause the lock status bit to clear and stay cleared until the FLL has reacquired lock. Stop mode entry will also cause the lock status bit to clear and stay cleared until the FLL has reacquired lock.</p> <p>0 FLL is currently unlocked. 1 FLL is currently locked.</p> |
| 5 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |
| 4 IREFST | <p>Internal Reference Status</p> <p>Indicates the current source for the reference clock. This field does not update immediately after a write to ICS_C1[IREFS] due to internal synchronization between clock domains.</p> <p>0 Source of reference clock is external clock. 1 Source of reference clock is internal clock.</p> |
| 3–2 CLKST | <p>Clock Mode Status</p> <p>Indicates the current clock mode. This field doesn't update immediately after a write to ICS_C1[CLKS] due to internal synchronization between clock domains.</p> <p>00 Output of FLL is selected. 01 FLL Bypassed, internal reference clock is selected. 10 FLL Bypassed, external reference clock is selected. 11 Reserved.</p> |
| Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |

20.4 Functional description

20.4.1 Operational modes

The seven states of the ICS are shown as a state diagram and are described below. The arrows indicate the allowed movements among the states.

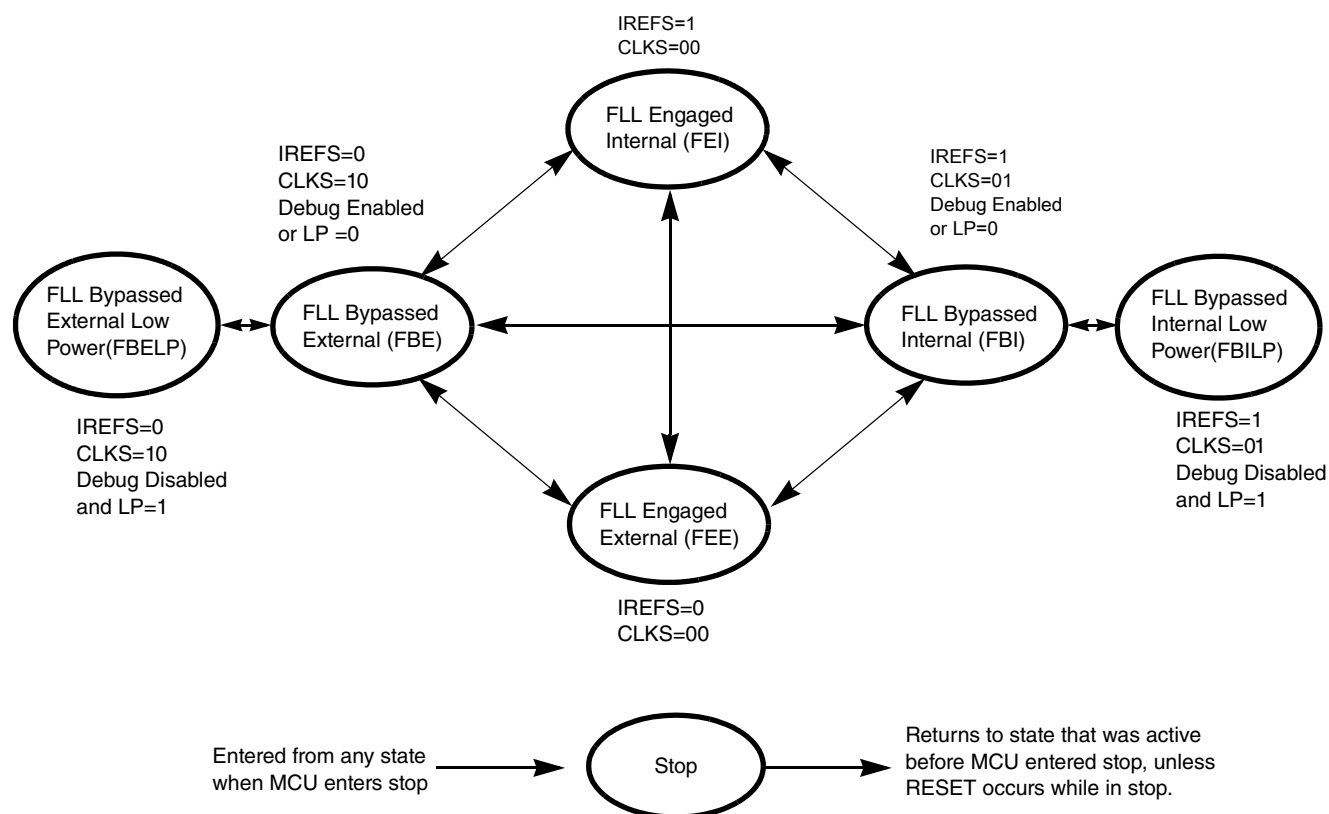


Figure 20-7. Clock switching modes

20.4.1.1 FLL engaged internal (FEI)

FLL engaged internal (FEI) is the default mode of operation and is entered when all the following conditions occur:

- 00b is written to ICS_C1[CLKS].
- 1b is written to ICS_C1[IREFS].

In FLL engaged internal mode, the ICSOUT clock is derived from the FLL clock, which is controlled by the internal reference clock. The FLL loop locks the frequency to 1280 times the internal reference frequency. The internal reference clock is enabled.

20.4.1.2 FLL engaged external (FEE)

The FLL engaged external (FEE) mode is entered when all the following conditions occur:

- 00b is written to ICS_C1[CLKS].
- 0b is written to ICS_C1[IREFS].
- ICS_C1[RDIV] and OSC_CR[RANGE] are written to divide external reference clock to be within the range of 31.25 kHz to 39.0625 kHz.

In FLL engaged external mode, the ICSOUT clock is derived from the FLL clock which is controlled by the external reference clock source. The FLL loop locks the frequency to 1280 times the external reference frequency, as selected by ICS_C1[RDIV] and OSC_CR[RANGE]. The external reference clock is enabled.

20.4.1.3 FLL bypassed internal (FBI)

The FLL bypassed internal (FBI) mode is entered when all the following conditions occur:

- 01b is written to ICS_C1[CLKS].
- 1b is written to ICS_C1[IREFS].

In FLL bypassed internal mode, the ICSOUT clock is derived from the internal reference clock. The FLL clock is controlled by the internal reference clock, and the FLL loop locks the FLL frequency to 1280 times the internal reference frequency. The internal reference clock is enabled.

20.4.1.4 FLL bypassed internal low power (FBILP)

The FLL bypassed internal low power (FBILP) mode is entered when all the following conditions occur:

- 01b is written to ICS_C1[CLKS].
- 1b is written to ICS_C1[IREFS].

In FLL bypassed internal low-power mode, the ICSOUT clock is derived from the internal reference clock and the FLL is disabled. The internal reference clock is enabled.

20.4.1.5 FLL bypassed external (FBE)

The FLL bypassed external (FBE) mode is entered when all the following conditions occur:

- 10b is written to ICS_C1[CLKS].
- 0b is written to ICS_C1[IREFS].
- ICS_C1[RDIV] and OSC_CR[RANGE] fields are written to divide external reference clock to be within the range of 31.25 kHz to 39.0625 kHz.

In FLL bypassed external mode, the ICSOUT clock is derived from the external reference clock source. The FLL clock is controlled by the external reference clock, and the FLL loop locks the FLL frequency to 1280 times the external reference frequency, as selected by ICS_C1[RDIV] and OSC_CR[RANGE].

20.4.1.6 FLL bypassed external low power (FBELP)

The FLL bypassed external low-power (FBELP) mode is entered when all the following conditions occur:

- 10b is written to ICS_C1[CLKS].
- 0b is written to ICS_C1[IREFS].

In FLL bypassed external low-power mode, the ICSOUT clock is derived from the external reference clock source and the FLL is disabled. The external reference clock source is enabled.

20.4.1.7 Stop

NOTE

The DCO frequency changes from the pre-stop value to its reset value and the FLL need to re-acquire the lock before the frequency is stable. Timing sensitive operations must wait for the FLL acquisition time, $t_{Acquire}$, before executing.

Stop mode is entered whenever the MCU enters a STOP state. In this mode, all ICS clock signals are static except in the following cases:

ICSIRCLK will be active in Stop mode when all the following conditions occur:

- 1b is written to ICS_C1[IRCLKEN].
- 1b is written to ICS_C1[IREFSTEN].

20.4.2 Mode switching

ICS_C1[IREFS] can be changed at anytime, but the actual switch to the newly selected clock is shown by ICS_S[IREFST]. When switching between FLL engaged internal (FEI) and FLL engaged external (FEE) modes, the FLL begins locking again after the switch is completed.

ICS_C1[CLKS] can also be changed at anytime, but the actual switch to the newly selected clock is shown by ICS_S[CLKST]. If the newly selected clock is not available, the previous clock remains selected.

NOTE

When mode switching is from FEE, FBE or FBELP to FEI, it is suggested to wait IREFST switch completion, then change ICS_C1[CLKS].

20.4.3 Bus frequency divider

ICS_C2[BDIV] can be changed anytime and the actual switch to the new frequency occurs immediately.

20.4.4 Low-power field usage

The Low-Power (LP) field in the ICS_C2 register is provided to allow the FLL to be disabled and thus conserve power when it is not being used.

However, in some applications it may be desirable to allow the FLL to be enabled and to lock for maximum accuracy before switching to an FLL engaged mode. To do this, write 0b to ICS_C2[LP].

20.4.5 Internal reference clock

When ICS_C1[IRCLKEN] is set, the internal reference clock signal is presented as ICSIRCLK, which can be used as an additional clock source. To re-target the ICSIRCLK frequency, write a new value to the ICS_C3[SCTRIM] bits to trim the period of the internal reference clock:

- Writing a larger value slows down the ICSIRCLK frequency.
- Writing a smaller value to the ICS_C3 register speeds up the ICSIRCLK frequency.

The trim bits affect the ICSOUT frequency if the ICS is in FLL engaged internal (FEI), FLL bypassed internal (FBI), or FLL bypassed internal low power (FBILP) mode.

Until ICSIRCLK is trimmed, programming low bus divider (ICS_C2[BDIV]) factors may result in ICSOUT frequencies that exceed the maximum chip-level frequency and violate the chip-level clock timing specifications.

If ICS_C1[IREFSTEN] is set and 1b is written to ICS_C1[IRCLKEN], the internal reference clock keeps running during Stop mode in order to provide a fast recovery upon exiting Stop mode.

All MCU devices are factory programmed with a trim value in a reserved memory location. This value is uploaded to the ICS_C3 register and ICS_C4[SCFTRIM] during any reset initialization. For finer precision, trim the internal oscillator in the application and set ICS_C4[SCFTRIM] accordingly.

20.4.6 Fixed frequency clock

The ICS presents the divided FLL reference clock as ICSFFCLK for use as an additional clock source. ICSFFCLK frequency must be no more than 1/4 of the ICSOUT frequency to be valid. Because of this requirement, in bypass modes, the ICSFFCLK is valid only in bypass external modes (FBE and FBELP) for the following conditions of ICS_C2[BDIV], and divider factor of ICS_C1[RDIV] and OSC_CR[RANGE] values:

if OSC_CR[RANGE] is high,

- ICS_C2[BDIV] = 000, ICS_C2[RDIV] ≥ 010
- ICS_C2[BDIV] = 001 (divide by 2), ICS_C2[RDIV] ≥ 011
- ICS_C2[BDIV] = 010 (divide by 4), ICS_C2[RDIV] ≥ 100
- ICS_C2[BDIV] = 011 (divide by 8), ICS_C2[RDIV] ≥ 101

20.4.7 FLL lock and clock monitor

20.4.7.1 FLL clock lock

In FBE and FEE modes, the clock detector source uses the external reference as the reference. When FLL is detected from lock to unlock, ICS_S[LOLS] is set. An interrupt will be generated if ICS_C4[LOLIE] is set. ICS_S[LOLS] is cleared by reset or by writing a logic 1 to ICS_S[LOLS] when ICS_S[LOLS] is set. Writing a logic 0 to ICS_S[LOLS] has no effect.

In FBI and FEI modes, the lock detector source uses the internal reference as the reference. When FLL is detected from lock to unlock, ICS_S[LOLS] is set. An interrupt will be generated if ICS_C4[LOLIE] is set. ICS_S[LOLS] is cleared by reset or by writing a logic 1 to ICS_S[LOLS] when ICS_S[LOLS] is set. Writing a logic 0 to ICS_S[LOLS] has no effect.

In FBELP and FBILP modes, the FLL is not on so that lock detect function is not applicable.

20.4.7.2 External reference clock monitor

In FBE, FEE, or FBELP modes, if 1 is written to ICS_C4[CME], the clock monitor is enabled. If the external reference falls below a certain frequency, the MCU will reset. The SIM_SRSID[LOC] will be set to indicate the error.

20.5 Initialization/application information

This section provides example code to give some basic direction to a user on how to initialize and configure the ICS module. The example software is implemented in C language.

20.5.1 Initializing FEI mode

The following code segment demonstrates setting ICS to FEI mode.

Example: 20.5.1.1 FEI mode initialization routine

```
/* the following code segment demonstrates setting the ICS to FEI mode using the factory
trim value. The resulting ICSOUT frequency is fint_ft*1280/BDIV. */
ICS_C2 = 0x20; // BDIV=divide by 2 - use default until clock dividers configured
ICS_C1 = 0x04; // internal reference clock as source to FLL
while ((ICS_S & ICS_S_LOCK_MASK) == 0); // wait for FLL to lock
SIM_CLKDIV = 0x01100000; // core clock = ICSOUT/1 and bus clock = core clock/2
ICS_C2 = 0x00; // BDIV=divide by 1 - allows max core and bus clock frequencies

/* the following code segment demonstrates setting the ICS to FEI mode using a custom trim
value provided by a programming tool. The resulting ICSOUT frequency is fint_t*1280/BDIV. */
ICS_C3 = *((uint8_t*) 0x03FF); // trim internal reference clock
ICS_C4 = *((uint8_t*) 0x03FE); // fine trim internal reference clock
ICS_C2 = 0x20; // BDIV=divide by 2 - use default until clock dividers configured
ICS_C1 = 0x04; // internal reference clock as source to FLL
while ((ICS_S & ICS_S_LOCK_MASK) == 0); // wait for FLL to lock
SIM_CLKDIV = 0x01100000; // core clock = ICSOUT/1 and bus clock = core clock/2
ICS_C2 = 0x00; // BDIV=divide by 1 - allows max core and bus clock frequencies
```

20.5.2 Initializing FBI mode

The following code segment demonstrates setting ICS to FBI mode.

Example: 20.5.2.1 FBI mode initialization routine

```
/* the following code segment demonstrates setting the ICS to FBI mode using the factory
trim value. The resulting ICSOUT frequency is fint_ft/BDIV. Note that the FLL will be
running at a frequency of fint_ft*1280/BDIV even though the FLL is bypassed. */
ICS_C2 = 0x20; // BDIV=divide by 2 - use default until clock dividers configured
ICS_C1 = 0x44; // internal reference clock as source for ICSOUT
while ((ICS_S & 0x0C) != 0x04); // wait until internal reference is selected
SIM_CLKDIV = 0x00000000; // core clock = ICSOUT/1; bus clock = core clock/1
ICS_C2 = 0x00; // BDIV=divide by 1 - allows max core and bus clock frequencies
```

20.5.3 Initializing FEE mode

The following code segment demonstrates setting ICS to FEE mode.

Example: 20.5.3.1 FEE mode initialization routine

```
/* the following code segment demonstrates setting the ICS to FEE mode generating a 40MHZ
core clock frequency using an external 8MHz crystal */
OSC_CR = 0x96; // high-range, high-gain oscillator selected
while ((OSC_CR & OSC_CR_OSCINIT_MASK) == 0); // wait until oscillator is ready
ICS_C2 = 0x20; // BDIV=divide by 2 - use default until clock dividers configured
ICS_C1 = 0x18; // 8MHz external reference clock/256 as source to FLL
while ((ICS_S & ICS_S_IREFST_MASK) == 1); // wait for external source selected
while ((ICS_S & ICS_S_LOCK_MASK) == 0); // wait for FLL to lock
SIM_CLKDIV = 0x01100000; // core clock = ICSOUT/1 and bus clock = core clock/2
ICS_C2 = 0x00; // BDIV=divide by 1 - allows max core and bus clock frequencies
```

20.5.4 Initializing FBE mode

The following code segment demonstrates setting ICS to FBE mode.

Example: 20.5.4.1 FBE mode initialization routine

```
/* the following code segment demonstrates setting the ICS to FBE mode generating 20MHZ core
clock frequency using an external 20MHz crystal */
OSC_CR = 0x96; // high-range, high-gain oscillator selected
while ((OSC_CR & OSC_CR_OSCINIT_MASK) == 0); // wait until oscillator is ready
ICS_C2 = 0x20; // BDIV=divide by 2 - use default until clock dividers configured
ICS_C1 = 0xA0; // 20MHz external clock as ICSOUT source; FLL source = 20MHz/512
while ((ICS_S & ICS_S_IREFST_MASK) == 1); // wait for external source selected
while ((ICS_S & 0x0C) != 0x08); // wait until FBE mode is selected
SIM_CLKDIV = 0x00000000; // core clock = ICSOUT/1 and bus clock = core clock/1
ICS_C2 = 0x00; // BDIV=divide by 1 - allows max core and bus clock frequencies
```


Chapter 21

Oscillator (OSC)

21.1 Introduction

21.1.1 Overview

The OSC module provides the clock source for the MCU. The OSC module, in conjunction with an external crystal or resonator, generates a clock for the MCU that can be used as reference clock or bus clock.

21.1.2 Features and modes

Key features of the OSC module are:

- Supports 32 kHz crystals (low range mode)
- Supports 4–24 MHz crystals and resonators (high range mode)
- Automatic gain control (AGC) to optimize power consumption in both frequency ranges using low-power mode (low gain mode)
- High gain option in both frequency ranges: 32 kHz, 4–24 MHz
- Voltage and frequency filtering to guarantee clock frequency and stability
- Supports to be enabled by ICS.

21.1.3 Block diagram

See the following figure for OSC module block diagram.

The OSC module uses a crystal or resonator to generate three filtered oscillator clock signals(XTL_CLK). The XTL_CLK can work in Stop mode since they come from Hard block which always has power.

Signal description

The OSCOS decides whether OSC_OUT comes from internal oscillators(XTL_CLK) or directly from external clock driven on EXTAL pin. The OSCOS signal allows the XTAL pad to be used as I/O or test clock.

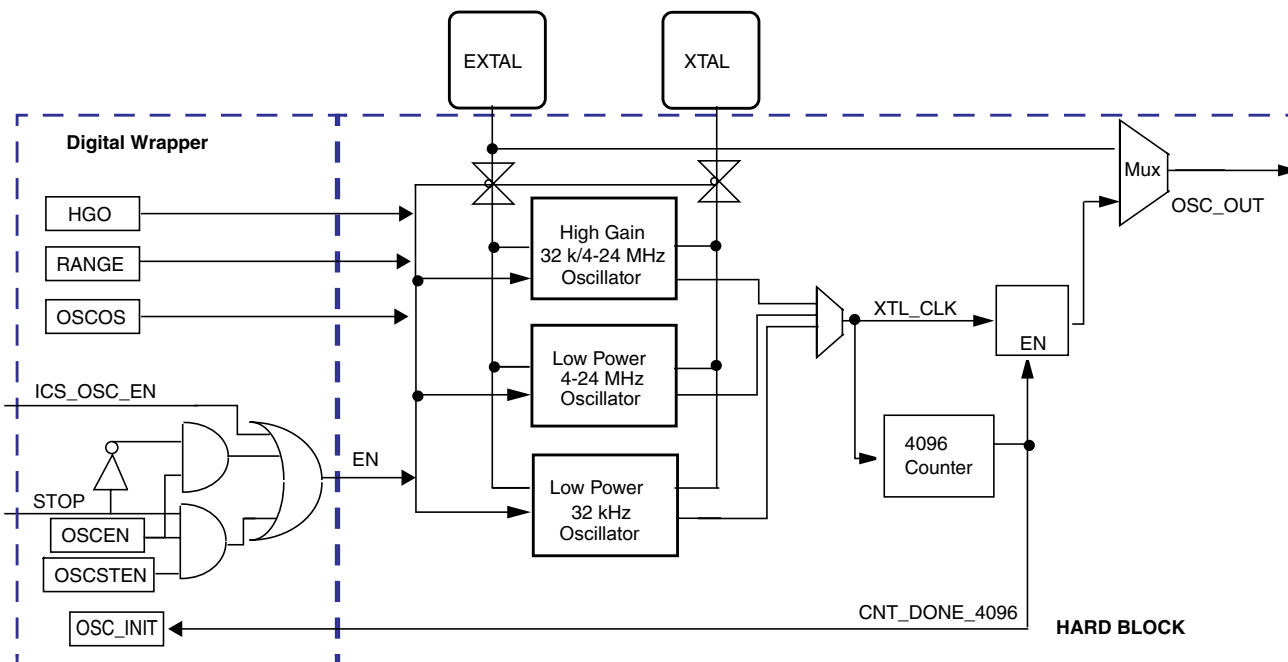


Figure 21-1. OSC module block diagram

21.2 Signal description

The following table shows the user-accessible signals available for the OSC module. See the chip-level specification to find out which signals are actually connected to external pins.

Table 21-1. OSC signal descriptions

| Signal | Description | I/O |
|--------|---------------------------------|---------------|
| EXTAL | External clock/oscillator input | Analog input |
| XTAL | Oscillator output | Analog output |

21.3 External crystal / resonator connections

The connections for a crystal/resonator frequency reference are shown in [Figure 21-2](#) and [Figure 21-3](#). When using low-frequency, low-power mode, the only external component is the crystal or resonator itself. In the other oscillator modes, load capacitors (C_x , C_y) and feedback resistor (R_F) are required. In addition, a series resistor (R_S) may be used in high-gain modes. Recommended component values are listed in the data sheet.

Table 21-2. External crystal/resonator connections

| Oscillator mode | Connections |
|--------------------------------------|-------------|
| Low frequency, high gain | Connection2 |
| Low frequency, low-power | Connection1 |
| High frequency, high gain (4–20 MHz) | Connection2 |
| High frequency, low-power (4–20 MHz) | Connection2 |

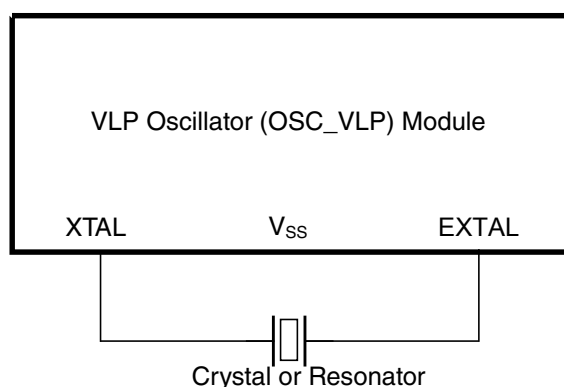


Figure 21-2. Crystal/resonator connections - connection 1

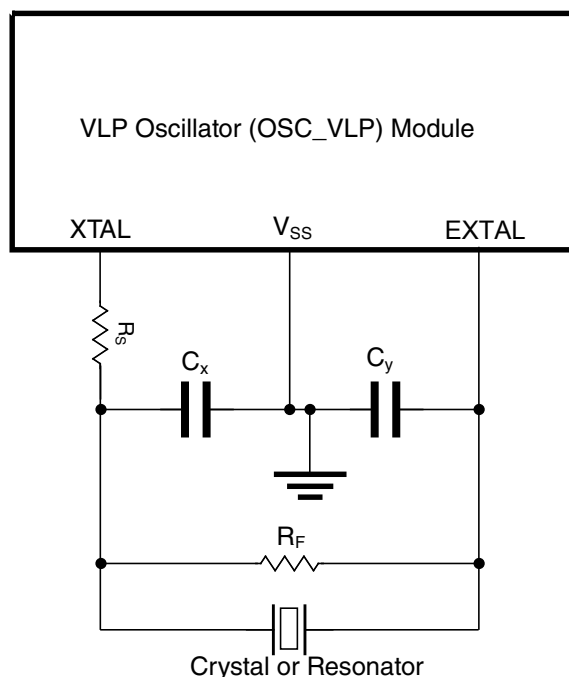


Figure 21-3. Crystal/resonator connections - connection 2

21.4 External clock connections

In external clock mode ($\text{OSC_CR}[\text{OSCOS}] = 0$), the pins can be connected as shown in the following figure.

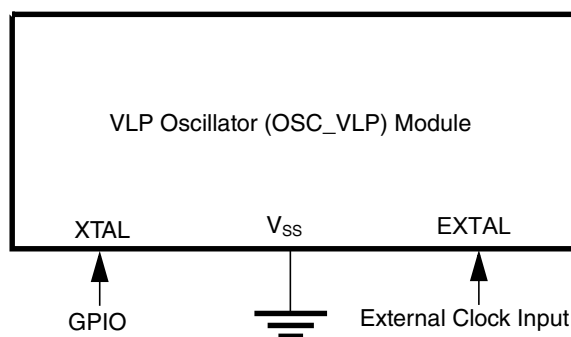


Figure 21-4. External clock connections

21.5 Memory map and register descriptions

OSC memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|-------------------------------|-----------------|--------|-------------|----------------------------|
| 4006_5000 | OSC Control Register (OSC_CR) | 8 | R/W | 00h | 21.5.1/305 |

21.5.1 OSC Control Register (OSC_CR)

Address: 4006_5000h base + 0h offset = 4006_5000h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|---|---------|-------|---|-------|-----|---------|
| Read | OSCEN | 0 | OSCSTEN | OSCOS | 0 | RANGE | HGO | OSCINIT |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

OSC_CR field descriptions

| Field | Description |
|---------------|--|
| 7 OSCEN | OSC Enable Enables the OSC module. The OSC module can also be enabled by the ICS module. 0 OSC module is disabled. 1 OSC module is enabled. |
| 6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5 OSCSTEN | OSC Enable in Stop mode Controls whether or not the OSC clock remains enabled when MCU enters Stop mode and OSCEN is set. OSCSTEN has no effect if ICS requests OSC enable. 0 OSC clock is disabled in Stop mode. 1 OSC clock stays enabled in Stop mode. |
| 4 OSCOS | OSC Output Select Selects the output clock of the OSC module. 0 External clock source from EXTAL pin is selected. 1 Oscillator clock source is selected. |
| 3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 2 RANGE | Frequency Range Select Selects the frequency range for the OSC module. This bit must be configured before the OSC is enabled and DO NOT change it after the OSC is enabled |

Table continues on the next page...

OSC_CR field descriptions (continued)

| Field | Description |
|--------------|---|
| | 0 Low frequency range of 32 kHz. 1 High frequency range of 4–24 MHz. |
| 1 HGO | High Gain Oscillator Select Controls the OSC mode of operation. 0 Low-power mode 1 High-gain mode |
| 0 OSCINIT | OSC Initialization This field is set after the initialization cycles of oscillator are completed. 0 Oscillator initialization is not complete. 1 Oscillator initialization is completed. |

21.6 Functional description

21.6.1 OSC module states

There are three states of the OSC module. A state diagram is shown in [Figure 21-6](#). The states and the transitions among each other are described in this section.

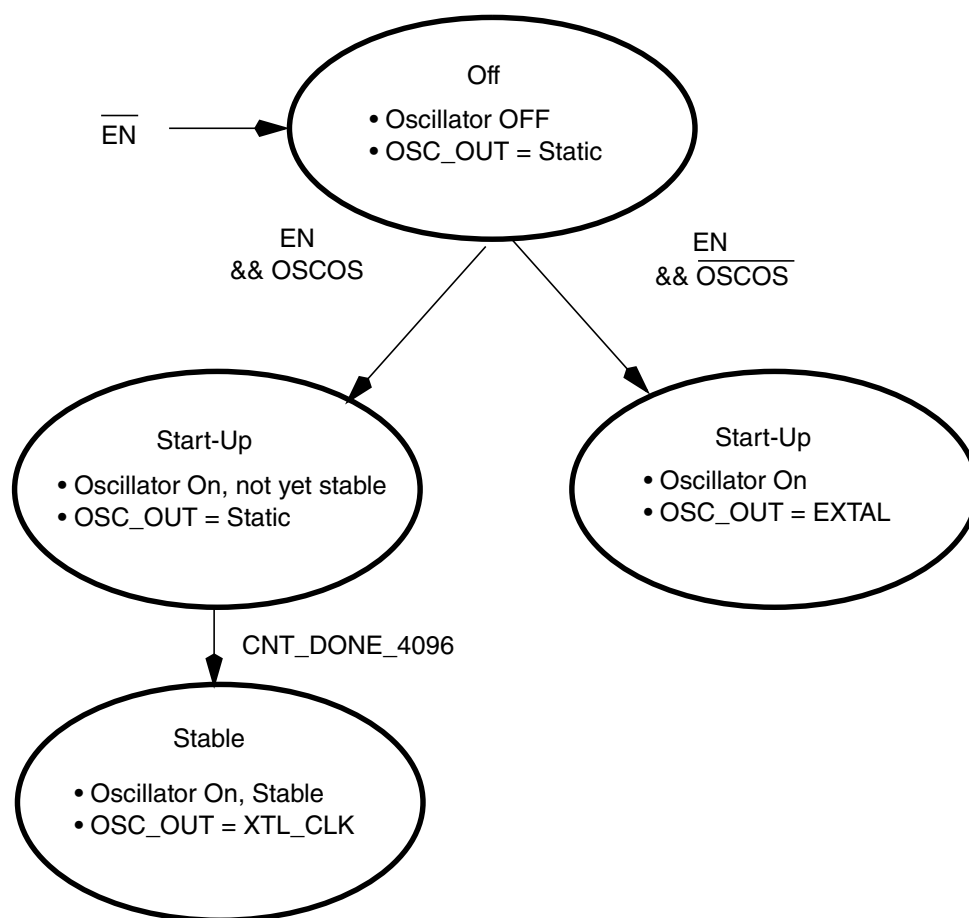


Figure 21-6. OSC module state diagram

EN is decided by OSC_CR[OSCEN], Stop, OSC_CR[OSCSTEN], and external request (ICS_OSC_EN). See the following table for details.

Table 21-5. EN status

| EN | ICS_OSC_EN | OSC_CR[OSCEN] | OSC_CR[OSCSTEN] | Stop |
|----|------------|---------------|-----------------|------|
| 1 | 1 | - | - | - |
| 1 | 0 | 1 | - | 0 |
| 1 | 0 | 1 | 1 | 1 |
| 0 | 0 | 1 | 0 | 1 |
| 0 | 0 | 0 | - | - |

21.6.1.1 Off

The off state is entered whenever the EN signal is negated. Upon entering this state, XTL_CLK and OSC_OUT is static. The EXTAL and XTAL pins are also decoupled from all other oscillator circuitry in this state. The OSC module circuitry is configured to draw minimal current.

21.6.1.2 Oscillator startup

The oscillator startup state is entered whenever the oscillator is first enabled (EN transitions high) and OSC_CR[OSCOS] is high. In this state, the OSC module is enabled and oscillations are starting up, but have not yet stabilized. When the oscillation amplitude becomes large enough to pass through the input buffer, XTL_CLK begins clocking the counter. When the counter has seen 4096 cycles of XTL_CLK, the oscillator is considered stable and XTL_CLK is passed to the output clock OSC_OUT.

21.6.1.3 Oscillator stable

The oscillator stable state is entered whenever the oscillator is enabled (EN is high), OSC_CR[OSCOS] is high, and the counter has seen 4096 cycles of XTL_CLK (CNT_DONE_4096 is high). In this state, the OSC module is producing a stable output clock on OSC_OUT. Its frequency is determined by the external components being used.

21.6.1.4 External clock mode

The external clock state is entered when the oscillator is enabled (EN is high) and OSC_CR[OSCOS] is low. In this state, the OSC module is set up to buffer (with hysteresis) a clock from EXTAL onto the OSC_OUT. Its frequency is determined by the external clock being supplied.

21.6.2 OSC module modes

The oscillator is a Pierce-type oscillator that supports external crystals or resonators operating over the frequency ranges shown in the following table. These modes assume EN = 1, OSC_CR[OSCOS] = 1.

Table 21-6. Oscillator modes

| RANGE | HGO | Mode | Frequency range |
|-------|-----|---------------------------------|---|
| 0 | 1 | Low-frequency, high-gain | $f_{lo}(\text{min})$ up to $f_{lo}(\text{max})$ |
| 0 | 0 | Low-frequency, low-power (VLP) | |
| 1 | 1 | High-frequency mode1, high-gain | $f_{hi}(\text{min})$ up to $f_{hi}(\text{max})$ |
| 1 | 0 | High-frequency mode1, low-power | |

21.6.2.1 Low-frequency, high-gain mode

In low-frequency, high-gain mode (OSC_CR[RANGE] = 0, OSC_CR[HGO] = 1) the oscillator uses a simple inverter-style amplifier. The gain is set to achieve rail-to-rail oscillation amplitudes. The oscillator input buffer in this mode is single-ended. It provides low pass frequency filtering as well as hysteresis for voltage filtering and converts the output to logic levels.

21.6.2.2 Low-frequency, low-power mode

In low-frequency, low-power mode (OSC_CR[RANGE] = 0, OSC_CR[HGO] = 0), the oscillator uses a gain control loop to minimize power consumption. As the oscillation amplitude increases, the amplifier current is reduced. This continues until a desired amplitude is achieved at steady-state.

The oscillator input buffer in this mode is single-ended. It provides low pass frequency filtering as well as hysteresis for voltage filtering and converts the output to logic levels.

In this mode, the amplifier inputs, gain-control input, and input buffer input are all capacitively coupled for leakage tolerance (not sensitive to the DC level of EXTAL).

Also in this mode, all external components except for the resonator itself are integrated, which includes the load capacitors and feedback resistor which biases EXTAL.

21.6.2.3 High-frequency, high-gain mode

In high-frequency, high-gain Mode (OSC_CR[RANGE] = 1, OSC_CR[HGO] = 1), the oscillator uses a simple inverter-style amplifier. The gain is set to achieve rail-to-rail oscillation amplitudes.

The oscillator input buffer in this mode is single-ended. It provides low pass frequency filtering as well as hysteresis for voltage filtering and converts the output to logic levels.

21.6.2.4 High-frequency, low-power mode

In high-frequency, low-power mode ($\text{OSC_CR}[\text{RANGE}] = 1$, $\text{OSC_CR}[\text{HGO}] = 0$) the oscillator uses a gain control loop to minimize power consumption. As the oscillation amplitude increases, the amplifier current is reduced. This continues until a desired amplitude is achieved at steady-state.

The oscillator input buffer in this mode is differential. It provides low pass frequency filtering as well as hysteresis for voltage filtering and converts the output to logic levels.

21.6.3 Counter

The oscillator output clock (OSC_OUT) is gated off until the counter has detected 4096 cycles of its input clock (XTL_CLK). Once 4096 cycles are complete, the counter passes XTL_CLK onto OSC_OUT . This counting timeout is used to guarantee output clock stability.

21.6.4 Reference clock pin requirements

The OSC module requires use of both the EXTAL and XTAL pins to generate an output clock in oscillator mode but requires only the EXTAL pin in external clock mode. The EXTAL and XTAL pins can be used for I/O or test clock purposes as long as the specifications listed in the data sheet are met.

Chapter 22

Cyclic Redundancy Check (CRC)

22.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The cyclic redundancy check (CRC) module generates 16/32-bit CRC code for error detection.

The CRC module provides a programmable polynomial, WAS, and other parameters required to implement a 16-bit or 32-bit CRC standard.

The 16/32-bit code is calculated for 32 bits of data at a time.

22.1.1 Features

Features of the CRC module include:

- Hardware CRC generator circuit using a 16-bit or 32-bit programmable shift register
- Programmable initial seed value and polynomial
- Option to transpose input data or output data (the CRC result) bitwise or byte-wise. This option is required for certain CRC standards. A byte-wise transpose operation is not possible when accessing the CRC data register via 8-bit accesses. In this case, the user's software must perform the byte-wise transpose function.
- Option for inversion of final CRC result
- 32-bit CPU register programming interface

22.1.2 Block diagram

The following is a block diagram of the CRC.

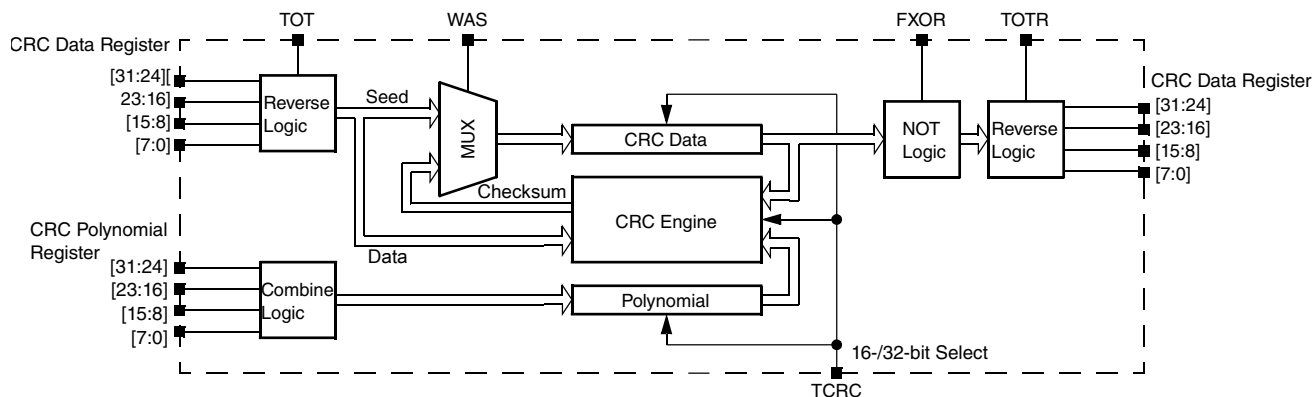


Figure 22-1. Programmable cyclic redundancy check (CRC) block diagram

22.1.3 Modes of operation

Various MCU modes affect the CRC module's functionality.

22.1.3.1 Run mode

This is the basic mode of operation.

22.1.3.2 Low-power modes (Wait or Stop)

Any CRC calculation in progress stops when the MCU enters a low-power mode that disables the module clock. It resumes after the clock is enabled or via the system reset for exiting the low-power mode. Clock gating for this module is dependent on the MCU.

22.2 Memory map and register descriptions

CRC memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|-------------------------------------|-----------------|--------|-------------|----------------------------|
| 4003_2000 | CRC Data register (CRC_DATA) | 32 | R/W | FFFF_FFFFh | 22.2.1/313 |
| 4003_2004 | CRC Polynomial register (CRC_GPOLY) | 32 | R/W | 0000_1021h | 22.2.2/314 |
| 4003_2008 | CRC Control register (CRC_CTRL) | 32 | R/W | 0000_0000h | 22.2.3/314 |

22.2.1 CRC Data register (CRC_DATA)

The CRC Data register contains the value of the seed, data, and checksum. When CTRL[WAS] is set, any write to the data register is regarded as the seed value. When CTRL[WAS] is cleared, any write to the data register is regarded as data for general CRC computation.

In 16-bit CRC mode, the HU and HL fields are not used for programming the seed value, and reads of these fields return an indeterminate value. In 32-bit CRC mode, all fields are used for programming the seed value.

When programming data values, the values can be written 8 bits, 16 bits, or 32 bits at a time, provided all bytes are contiguous; with MSB of data value written first.

After all data values are written, the CRC result can be read from this data register. In 16-bit CRC mode, the CRC result is available in the LU and LL fields. In 32-bit CRC mode, all fields contain the result. Reads of this register at any time return the intermediate CRC value, provided the CRC module is configured.

Address: 4003_2000h base + 0h offset = 4003_2000h

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|----|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | HU | | | | | | | | HL | | | | | | | | LU | | | | | | | | LL | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | |

CRC_DATA field descriptions

| Field | Description |
|-------------|---|
| 31–24 HU | CRC High Upper Byte In 16-bit CRC mode (CTRL[TCRC] is 0), this field is not used for programming a seed value. In 32-bit CRC mode (CTRL[TCRC] is 1), values written to this field are part of the seed value when CTRL[WAS] is 1. When CTRL[WAS] is 0, data written to this field is used for CRC checksum generation in both 16-bit and 32-bit CRC modes. |
| 23–16 HL | CRC High Lower Byte In 16-bit CRC mode (CTRL[TCRC] is 0), this field is not used for programming a seed value. In 32-bit CRC mode (CTRL[TCRC] is 1), values written to this field are part of the seed value when CTRL[WAS] is 1. When CTRL[WAS] is 0, data written to this field is used for CRC checksum generation in both 16-bit and 32-bit CRC modes. |
| 15–8 LU | CRC Low Upper Byte When CTRL[WAS] is 1, values written to this field are part of the seed value. When CTRL[WAS] is 0, data written to this field is used for CRC checksum generation. |
| LL | CRC Low Lower Byte When CTRL[WAS] is 1, values written to this field are part of the seed value. When CTRL[WAS] is 0, data written to this field is used for CRC checksum generation. |

22.2.2 CRC Polynomial register (CRC_GPOLY)

This register contains the value of the polynomial for the CRC calculation. The HIGH field contains the upper 16 bits of the CRC polynomial, which are used only in 32-bit CRC mode. Writes to the HIGH field are ignored in 16-bit CRC mode. The LOW field contains the lower 16 bits of the CRC polynomial, which are used in both 16- and 32-bit CRC modes.

Address: 4003_2000h base + 4h offset = 4003_2004h

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | HIGH | | | | | | | | | | | | | | | | LOW | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |

CRC_GPOLY field descriptions

| Field | Description |
|---------------|---|
| 31–16 HIGH | High Polynomial Half-word Writable and readable in 32-bit CRC mode (CTRL[TCRC] is 1). This field is not writable in 16-bit CRC mode (CTRL[TCRC] is 0). |
| LOW | Low Polynomial Half-word Writable and readable in both 32-bit and 16-bit CRC modes. |

22.2.3 CRC Control register (CRC_CTRL)

This register controls the configuration and working of the CRC module. Appropriate bits must be set before starting a new CRC calculation. A new CRC calculation is initialized by asserting CTRL[WAS] and then writing the seed into the CRC data register.

Address: 4003_2000h base + 8h offset = 4003_2008h

| | | | | | | | | | | | | | | | | |
|-------|-----|----|------|----|----|------|-----|------|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | TOT | | TOTR | | 0 | FXOR | WAS | TCRC | 0 | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

CRC_CTRL field descriptions

| Field | Description |
|----------------|---|
| 31–30 TOT | <p>Type Of Transpose For Writes</p> <p>Defines the transpose configuration of the data written to the CRC data register. See the description of the transpose feature for the available transpose options.</p> <p>00 No transposition. 01 Bits in bytes are transposed; bytes are not transposed. 10 Both bits in bytes and bytes are transposed. 11 Only bytes are transposed; no bits in a byte are transposed.</p> |
| 29–28 TOTR | <p>Type Of Transpose For Read</p> <p>Identifies the transpose configuration of the value read from the CRC Data register. See the description of the transpose feature for the available transpose options.</p> <p>00 No transposition. 01 Bits in bytes are transposed; bytes are not transposed. 10 Both bits in bytes and bytes are transposed. 11 Only bytes are transposed; no bits in a byte are transposed.</p> |
| 27 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |
| 26 FXOR | <p>Complement Read Of CRC Data Register</p> <p>Some CRC protocols require the final checksum to be XORed with 0xFFFFFFFF or 0xFFFF. Asserting this bit enables on the fly complementing of read data.</p> <p>0 No XOR on reading. 1 Invert or complement the read value of the CRC Data register.</p> |
| 25 WAS | <p>Write CRC Data Register As Seed</p> <p>When asserted, a value written to the CRC data register is considered a seed value. When deasserted, a value written to the CRC data register is taken as data for CRC computation.</p> <p>0 Writes to the CRC data register are data values. 1 Writes to the CRC data register are seed values.</p> |
| 24 TCRC | <p>Width of CRC protocol.</p> <p>0 16-bit CRC protocol. 1 32-bit CRC protocol.</p> |
| Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |

22.3 Functional description

22.3.1 CRC initialization/reinitialization

To enable the CRC calculation, the user must program `CRC_CTRL[WAS]`, `CRC_GPOLY`, necessary parameters for transposition and CRC result inversion in the applicable registers. Asserting `CRC_CTRL[WAS]` enables the programming of the seed value into the `CRC_DATA` register.

After a completed CRC calculation, the module can be reinitialized for a new CRC computation by reasserting `CRC_CTRL[WAS]` and programming a new, or previously used, seed value. All other parameters must be set before programming the seed value and subsequent data values.

22.3.2 CRC calculations

In 16-bit and 32-bit CRC modes, data values can be programmed 8 bits, 16 bits, or 32 bits at a time, provided all bytes are contiguous. Noncontiguous bytes can lead to an incorrect CRC computation.

22.3.2.1 16-bit CRC

To compute a 16-bit CRC:

1. Clear `CRC_CTRL[TCRC]` to enable 16-bit CRC mode.
2. Program the transpose and complement options in the CTRL register as required for the CRC calculation. See [Transpose feature](#) and [CRC result complement](#) for details.
3. Write a 16-bit polynomial to the `CRC_GPOLY[LOW]` field. The `CRC_GPOLY[HIGH]` field is not usable in 16-bit CRC mode.
4. Set `CRC_CTRL[WAS]` to program the seed value.
5. Write a 16-bit seed to `CRC_DATA[LU:LL]`. `CRC_DATA[HU:HL]` are not used.
6. Clear `CRC_CTRL[WAS]` to start writing data values.
7. Write data values into `CRC_DATA[HU:HL:LU:LL]`. A CRC is computed on every data value write, and the intermediate CRC result is stored back into `CRC_DATA[LU:LL]`.
8. When all values have been written, read the final CRC result from `CRC_DATA[LU:LL]`.

Transpose and complement operations are performed on the fly while reading or writing values. See [Transpose feature](#) and [CRC result complement](#) for details.

22.3.2.2 32-bit CRC

To compute a 32-bit CRC:

1. Set CRC_CTRL[TCRC] to enable 32-bit CRC mode.
2. Program the transpose and complement options in the CTRL register as required for the CRC calculation. See [Transpose feature](#) and [CRC result complement](#) for details.
3. Write a 32-bit polynomial to CRC_GPOLY[HIGH:LOW].
4. Set CRC_CTRL[WAS] to program the seed value.
5. Write a 32-bit seed to CRC_DATA[HU:HL:LU:LL].
6. Clear CRC_CTRL[WAS] to start writing data values.
7. Write data values into CRC_DATA[HU:HL:LU:LL]. A CRC is computed on every data value write, and the intermediate CRC result is stored back into CRC_DATA[HU:HL:LU:LL].
8. When all values have been written, read the final CRC result from CRC_DATA[HU:HL:LU:LL]. The CRC is calculated byte-wise, and two clocks are required to complete one CRC calculation.

Transpose and complement operations are performed on the fly while reading or writing values. See [Transpose feature](#) and [CRC result complement](#) for details.

22.3.3 Transpose feature

By default, the transpose feature is not enabled. However, some CRC standards require the input data and/or the final checksum to be transposed. The user software has the option to configure each transpose operation separately, as desired by the CRC standard. The data is transposed on the fly while being read or written.

Some protocols use little endian format for the data stream to calculate a CRC. In this case, the transpose feature usefully flips the bits. This transpose option is one of the types supported by the CRC module.

22.3.3.1 Types of transpose

The CRC module provides several types of transpose functions to flip the bits and/or bytes, for both writing input data and reading the CRC result, separately using the CTRL[TOT] or CTRL[TOTR] fields, according to the CRC calculation being used.

The following types of transpose functions are available for writing to and reading from the CRC data register:

1. CTRL[TOT] or CTRL[TOTR] is 00.

No transposition occurs.

2. CTRL[TOT] or CTRL[TOTR] is 01

Bits in a byte are transposed, while bytes are not transposed.

reg[31:0] becomes {reg[24:31], reg[16:23], reg[8:15], reg[0:7]}

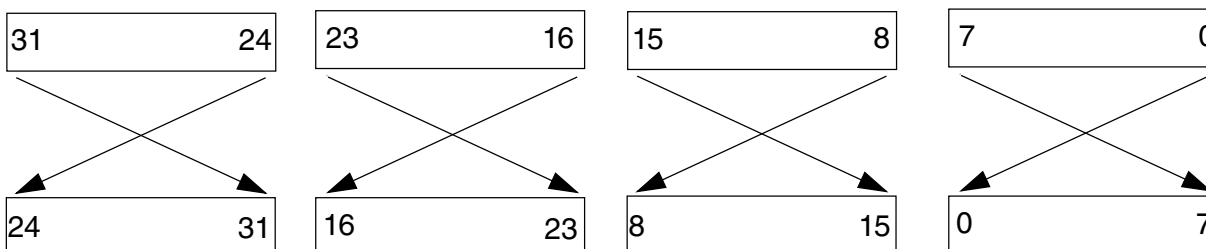


Figure 22-5. Transpose type 01

3. CTRL[TOT] or CTRL[TOTR] is 10.

Both bits in bytes and bytes are transposed.

reg[31:0] becomes = {reg[0:7], reg[8:15], reg[16:23], reg[24:31]}

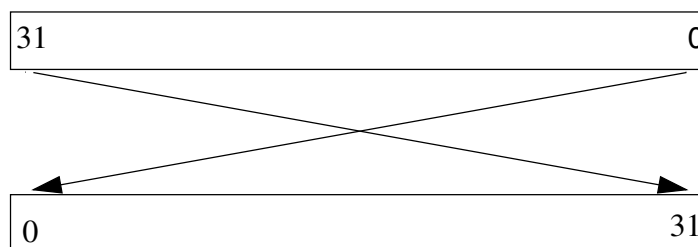


Figure 22-6. Transpose type 10

4. CTRL[TOT] or CTRL[TOTR] is 11.

Bytes are transposed, but bits are not transposed.

reg[31:0] becomes {reg[7:0], reg[15:8], reg[23:16], reg[31:24]}

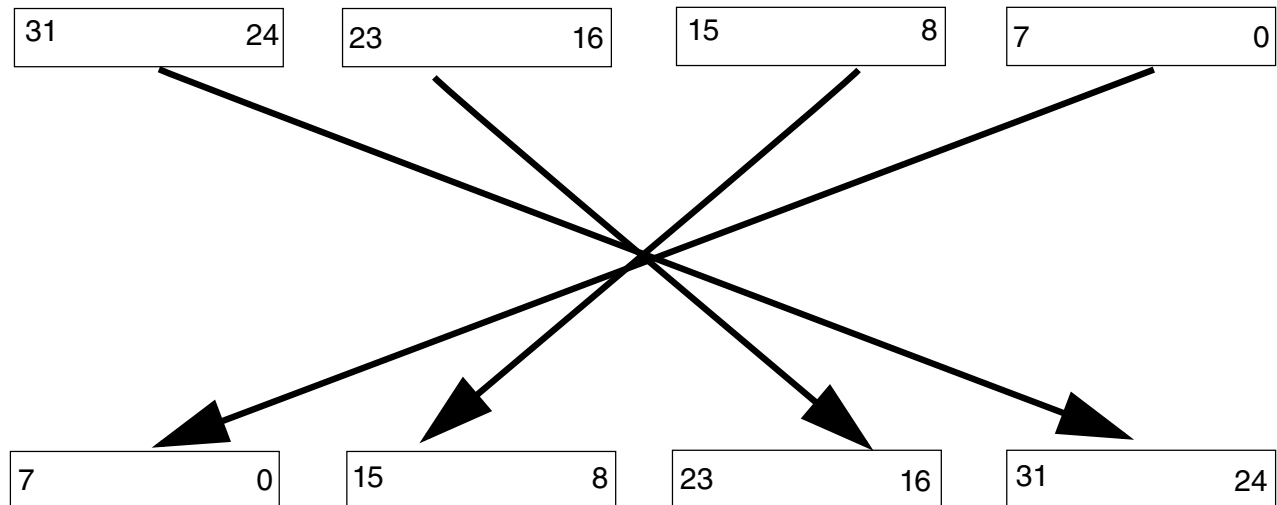


Figure 22-7. Transpose type 11

NOTE

For 8-bit and 16-bit write accesses to the CRC data register, the data is transposed with zeros on the unused byte or bytes (taking 32 bits as a whole), but the CRC is calculated on the valid byte(s) only. When reading the CRC data register for a 16-bit CRC result and using transpose options 10 and 11, the resulting value after transposition resides in the CRC[HU:HL] fields. The user software must account for this situation when reading the 16-bit CRC result, so reading 32 bits is preferred.

22.3.4 CRC result complement

When CTRL[FXOR] is set, the checksum is complemented. The CRC result complement function outputs the complement of the checksum value stored in the CRC data register every time the CRC data register is read. When CTRL[FXOR] is cleared, reading the CRC data register accesses the raw checksum value.

Chapter 23

Interrupt (IRQ)

23.1 Introduction

The external interrupt (IRQ) module provides a maskable interrupt input.

23.2 Features

Features of the IRQ module include:

- IRQ Interrupt Control bits
- Programmable edge-only or edge and level interrupt sensitivity
- Automatic interrupt acknowledge
- Internal pullup device

A low level applied to the external interrupt request (IRQ) pin can latch a CPU interrupt request. The following figure shows the structure of the IRQ module:

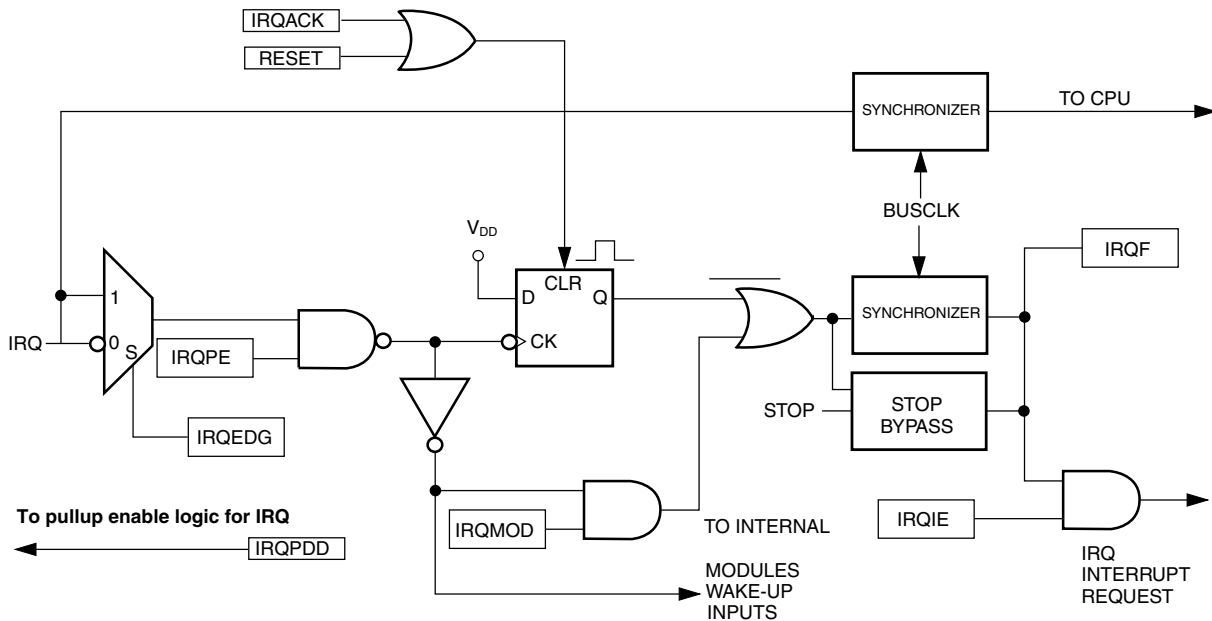


Figure 23-1. IRQ module block diagram

External interrupts are managed by the IRQSC status and control register. When the IRQ function is enabled, synchronous logic monitors the pin for edge-only or edge-and-level events. When the MCU is in Stop mode and system clocks are shut down, a separate asynchronous path is used so that the IRQ, if enabled, can wake the MCU.

23.2.1 Pin configuration options

The IRQ Pin Enable (IRQSC[IRQPE]) control field must be 1 for the IRQ pin to act as the IRQ input. The user can choose the polarity of edges or levels detected (IRQEDG), whether the pin detects edges-only or edges and levels (IRQMOD), or whether an event causes an interrupt or only sets the IRQSC[IRQF] flag, which can be polled by software.

When enabled, the IRQ pin defaults to use an internal pullup device (IRQSC[IRQPDD] = 0). If the user uses an external pullup or pulldown, the IRQSC[IRQPDD] can be written to a 1 to turn off the internal device.

BIH and BIL instructions may be used to detect the level on the IRQ pin when it is configured to act as the IRQ input.

Note

This pin does not contain a clamp diode to V_{DD} and must not be driven above V_{DD} . The voltage measured on the internally pullup IRQ pin may be as low as $V_{DD} - 0.7$ V. The internal gates connected to this pin are pulled all the way to V_{DD} .

When enabling the IRQ pin for use, IRQSC[IRQF] will be set, and must be cleared prior to enabling the interrupt. When configuring the pin for falling edge and level sensitivity in a 3 V system, it is necessary to wait at least cycles between clearing the flag and enabling the interrupt.

23.2.2 Edge and level sensitivity

The IRQSC[IRQMOD] control field reconfigures the detection logic so that it can detect edge events and pin levels. In this detection mode, IRQSC[IRQF] status flag is set when an edge is detected, if the IRQ pin changes from the deasserted to the asserted level, but the flag is continuously set and cannot be cleared as long as the IRQ pin remains at the asserted level.

23.3 Interrupt pin request register

IRQ memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|--------|-------------|----------------------------|
| 4003_1000 | Interrupt Pin Request Status and Control Register (IRQ_SC) | 8 | R/W | 00h | 23.3.1/323 |

23.3.1 Interrupt Pin Request Status and Control Register (IRQ_SC)

This direct page register includes status and control bits, which are used to configure the IRQ function, report status, and acknowledge IRQ events.

Address: 4003_1000h base + 0h offset = 4003_1000h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---|--------|--------|-------|------|--------|-------|--------|
| Read | 0 | IRQPDD | IRQEDG | IRQPE | IRQF | 0 | IRQIE | IRQMOD |
| Write | | | | | | IRQACK | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

IRQ_SC field descriptions

| Field | Description |
|---------------|---|
| 7 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 6 IRQPDD | Interrupt Request (IRQ) Pull Device Disable |

Table continues on the next page...

IRQ_SC field descriptions (continued)

| Field | Description |
|-------------|---|
| | <p>This read/write control bit is used to disable the internal pullup device when the IRQ pin is enabled (IRQPE = 1) allowing for an external device to be used.</p> <p>0 IRQ pull device enabled if IRQPE = 1. 1 IRQ pull device disabled if IRQPE = 1.</p> |
| 5 IRQEDG | <p>Interrupt Request (IRQ) Edge Select</p> <p>This read/write control field is used to select the polarity of edges or levels on the IRQ pin that cause IRQF to be set. The IRQMOD control field determines whether the IRQ pin is sensitive to both edges and levels or only edges. When the IRQ pin is enabled as the IRQ input and is configured to detect rising edges, the optional pullup resistor is disabled.</p> <p>0 IRQ is falling-edge or falling-edge/low-level sensitive. 1 IRQ is rising-edge or rising-edge/high-level sensitive.</p> |
| 4 IRQPE | <p>IRQ Pin Enable</p> <p>This read/write control field enables the IRQ pin function. When this field is set, the IRQ pin can be used as an interrupt request.</p> <p>0 IRQ pin function is disabled. 1 IRQ pin function is enabled.</p> |
| 3 IRQF | <p>IRQ Flag</p> <p>This read-only status field indicates when an interrupt request event has occurred.</p> <p>0 No IRQ request 1 IRQ event is detected.</p> |
| 2 IRQACK | <p>IRQ Acknowledge</p> <p>This write-only field is used to acknowledge interrupt request events (write 1 to clear IRQF). Writing 0 has no meaning or effect. Reads always return 0. If edge-and-level detection is selected (IRQMOD = 1), IRQF cannot be cleared while the IRQ pin remains at its asserted level.</p> |
| 1 IRQIE | <p>IRQ Interrupt Enable</p> <p>This read/write control field determines whether IRQ events generate an interrupt request.</p> <p>0 Interrupt request when IRQF set is disabled (use polling). 1 Interrupt requested whenever IRQF = 1.</p> |
| 0 IRQMOD | <p>IRQ Detection Mode</p> <p>This read/write control field selects either edge-only detection or edge-and-level detection.</p> <p>0 IRQ event is detected only on falling/rising edges. 1 IRQ event is detected on falling/rising edges and low/high levels.</p> |

Chapter 24

Analog-to-digital converter (ADC)

24.1 Introduction

The 12-bit analog-to-digital converter (ADC) is a successive approximation ADC designed for operation within an integrated microcontroller system-on-chip.

24.1.1 Features

Features of the ADC module include:

- Linear Successive Approximation algorithm with 8-, 10-, or 12-bit resolution
- Up to 16 external analog inputs, external pin inputs, and 5 internal analog inputs including internal bandgap, temperature sensor, and references
- Output formatted in 8-, 10-, or 12-bit right-justified unsigned format
- Single or Continuous Conversion (automatic return to idle after single conversion)
- Support up to eight result FIFO with selectable FIFO depth
- Configurable sample time and conversion speed/power
- Conversion complete flag and interrupt
- Input clock selectable from up to four sources
- Operation in Wait or Stop modes for lower noise operation
- Asynchronous clock source for lower noise operation
- Selectable asynchronous hardware conversion trigger
- Automatic compare with interrupt for less-than, or greater-than or equal-to, programmable value

24.1.2 Block Diagram

This figure provides a block diagram of the ADC module.

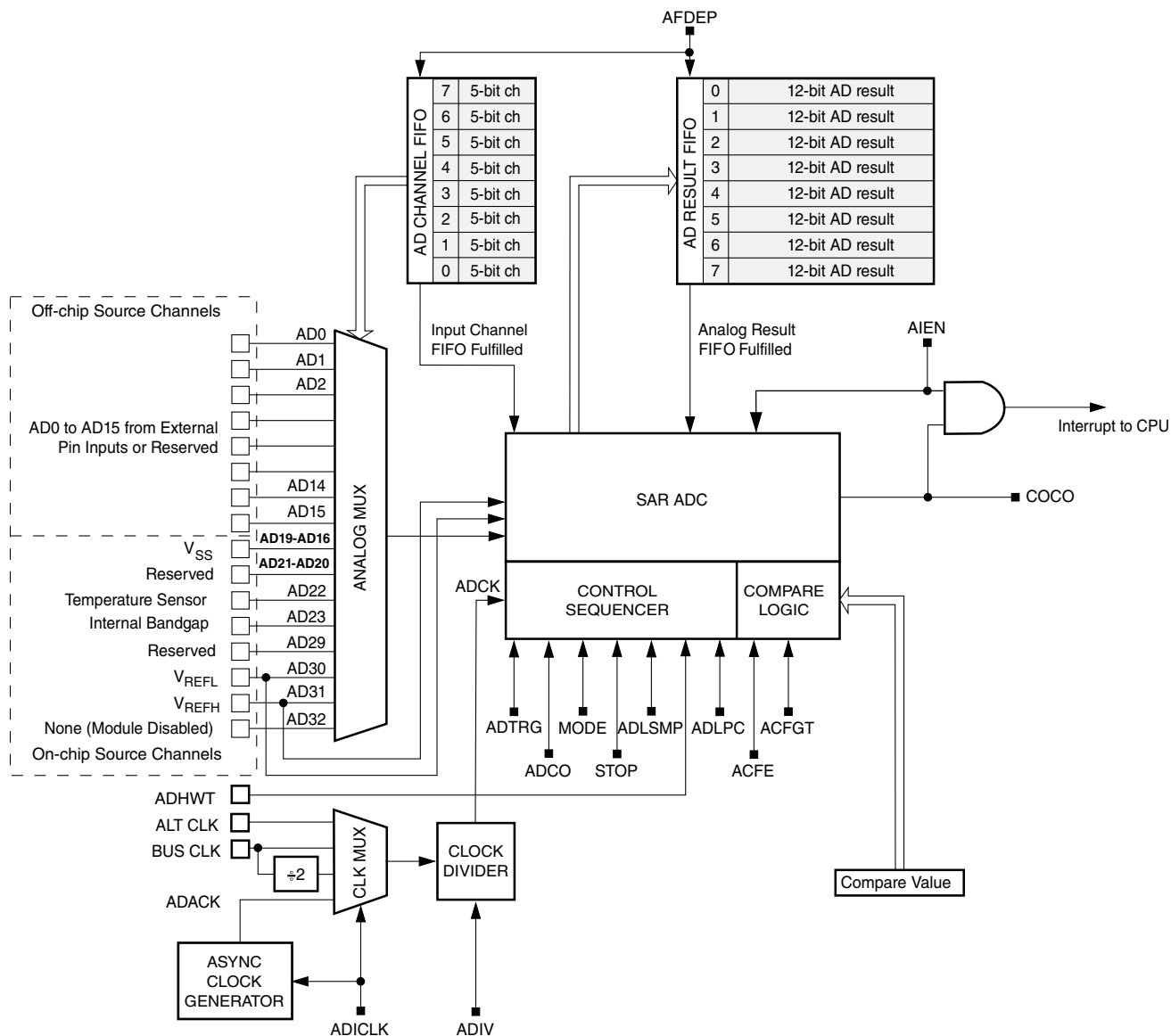


Figure 24-1. ADC Block Diagram

24.2 External Signal Description

The ADC module supports up to 24 separate analog inputs. It also requires four supply/reference/ground connections.

Table 24-1. Signal Properties

| Name | Function |
|------------|------------------------|
| AD23–AD0 | Analog Channel inputs |
| V_{REFH} | High reference voltage |
| V_{REFL} | Low reference voltage |
| V_{DDA} | Analog power supply |
| V_{SSA} | Analog ground |

24.2.1 Analog Power (V_{DDA})

The ADC analog portion uses V_{DDA} as its power connection. In some packages, V_{DDA} is connected internally to V_{DD} . If externally available, connect the V_{DDA} pin to the same voltage potential as V_{DD} . External filtering may be necessary to ensure clean V_{DDA} for good results.

24.2.2 Analog Ground (V_{SSA})

The ADC analog portion uses V_{SSA} as its ground connection. In some packages, V_{SSA} is connected internally to V_{SS} . If externally available, connect the V_{SSA} pin to the same voltage potential as V_{SS} .

24.2.3 Voltage Reference High (V_{REFH})

V_{REFH} is the high reference voltage for the converter. In some packages, V_{REFH} is connected internally to V_{DDA} . If externally available, V_{REFH} may be connected to the same potential as V_{DDA} or may be driven by an external source between the minimum V_{DDA} specified in the data sheet and the V_{DDA} potential (V_{REFH} must never exceed V_{DDA}).

24.2.4 Voltage Reference Low (V_{REFL})

V_{REFL} is the low-reference voltage for the converter. In some packages, V_{REFL} is connected internally to V_{SSA} . If externally available, connect the V_{REFL} pin to the same voltage potential as V_{SSA} .

24.2.5 Analog Channel Inputs (ADx)

The ADC module supports up to 24 separate analog inputs. An input is selected for conversion through the ADCH channel select bits.

24.3 ADC Control Registers

ADC memory map

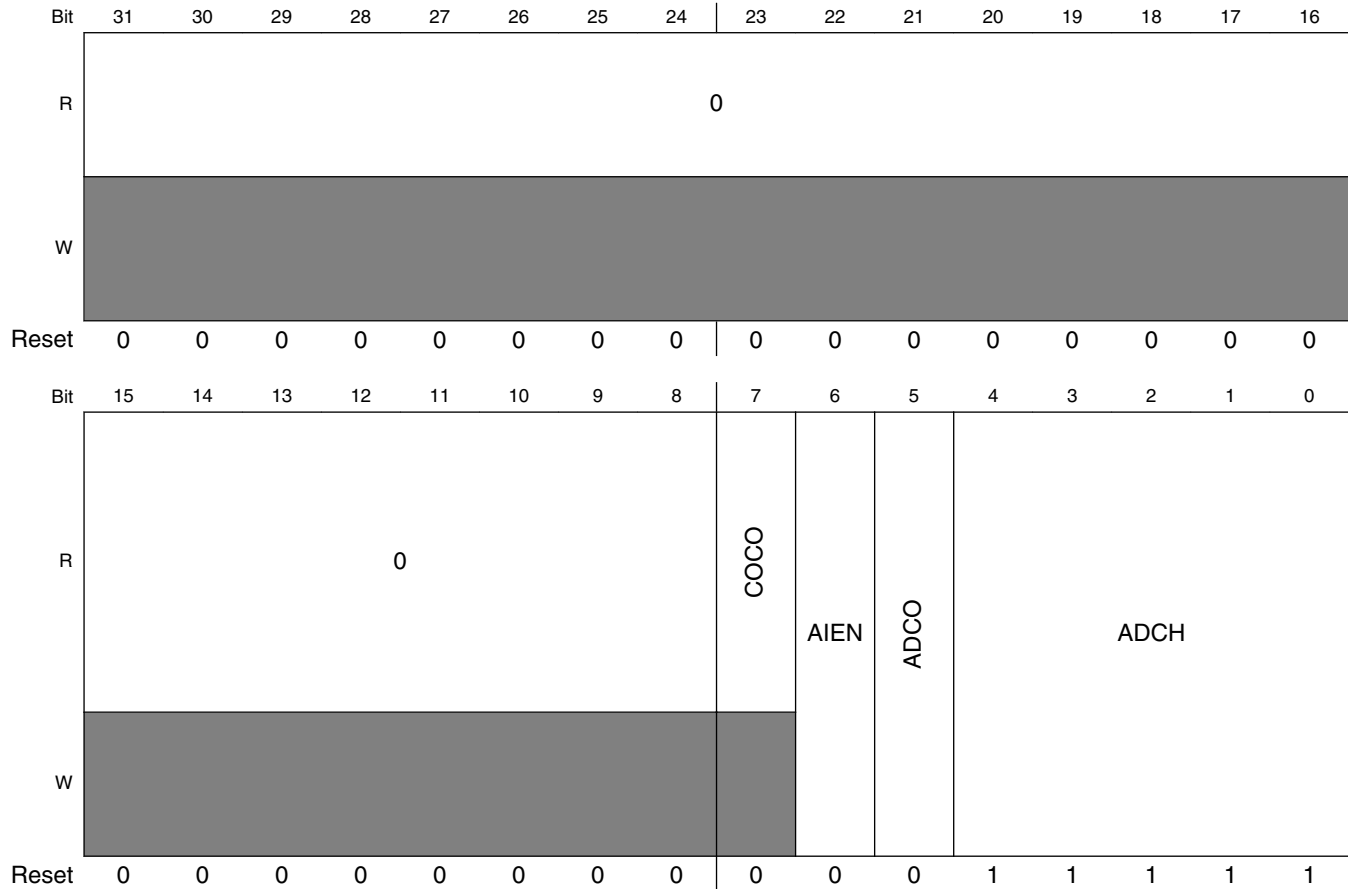
| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-------------|----------------------------|
| 4003_B000 | Status and Control Register 1 (ADC_SC1) | 32 | R/W | 0000_001Fh | 24.3.1/328 |
| 4003_B004 | Status and Control Register 2 (ADC_SC2) | 32 | R/W | 0000_0008h | 24.3.2/331 |
| 4003_B008 | Status and Control Register 3 (ADC_SC3) | 32 | R/W | 0000_0000h | 24.3.3/333 |
| 4003_B00C | Status and Control Register 4 (ADC_SC4) | 32 | R/W | 0000_0000h | 24.3.4/334 |
| 4003_B010 | Conversion Result Register (ADC_R) | 32 | R | 0000_0000h | 24.3.5/335 |
| 4003_B014 | Compare Value Register (ADC_CV) | 32 | R/W | 0000_0000h | 24.3.6/336 |
| 4003_B018 | Pin Control 1 Register (ADC_APCTL1) | 32 | R/W | 0000_0000h | 24.3.7/337 |
| 4003_B01C | Status and Control Register 5 (ADC_SC5) | 32 | R/W | 0000_0000h | 24.3.8/337 |

24.3.1 Status and Control Register 1 (ADC_SC1)

This section describes the function of the ADC status and control register (ADC_SC1). Writing ADC_SC1 aborts the current conversion and initiates a new conversion (if the ADCH bits are equal to a value other than all 1s).

When FIFO is enabled, the analog input channel FIFO is written via ADCH. The analog input channel queue must be written to ADCH continuously. The resulting FIFO follows the order in which the analog input channel is written. The ADC will start conversion when the input channel FIFO is fulfilled at the depth indicated by the ADC_SC4[AFDEP]. Any write 0x1F to these bits will reset the FIFO and stop the conversion if it is active.

Address: 4003_B000h base + 0h offset = 4003_B000h

**ADC_SC1 field descriptions**

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 COCO | Conversion Complete Flag Conversion Complete Flag. The COCO flag is a read-only bit set each time a conversion is completed when the compare function is disabled (ADC_SC2[ACFE] = 0). When the compare function is enabled (ADC_SC2[ACFE] = 1), the COCO flag is set upon completion of a conversion only if the compare result is true. When the FIFO function is enabled (ADC_SC4[AFDEP] > 0), the COCO flag is set upon completion of the set of FIFO conversion. This bit is cleared when ADC_SC1 is written or when ADC_R is read. 0 Conversion not completed. 1 Conversion completed. |
| 6 AIEN | Interrupt Enable AIEN enables conversion complete interrupts. When COCO becomes set while AIEN is high, an interrupt is asserted. 0 Conversion complete interrupt disabled. 1 Conversion complete interrupt enabled. |
| 5 ADCO | Continuous Conversion Enable |

Table continues on the next page...

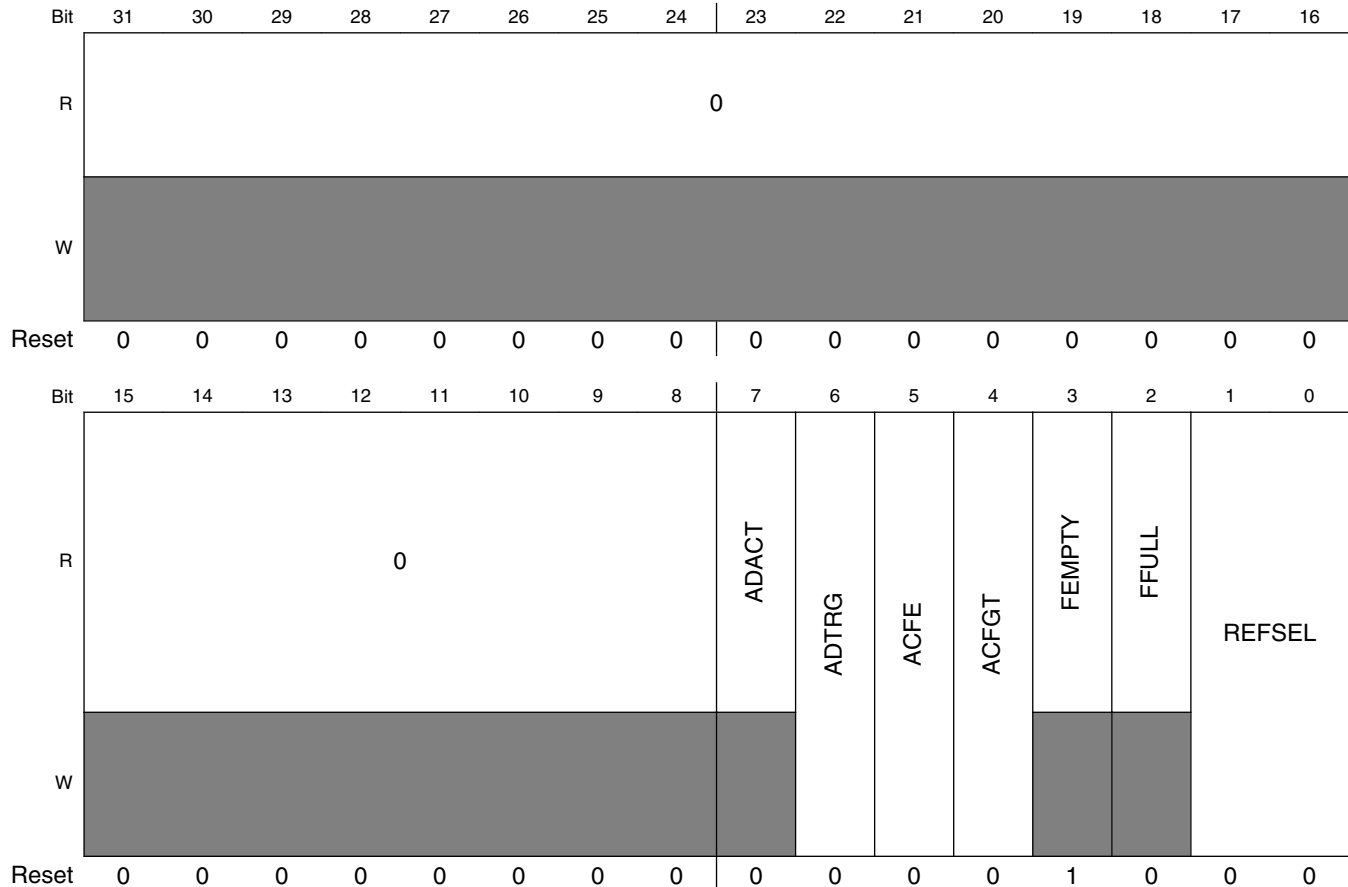
ADC_SC1 field descriptions (continued)

| Field | Description | | | | | | | | | | | | | | | | | | |
|-------------|--|-------------|----------|-------------|-----------------|-------------|----------|-------|--------------------|-------|---------|-------------|----------|-------|-------------------|-------|-------------------|-------|-----------------|
| | <p>ADCO enables continuous conversions.</p> <p>0 One conversion following a write to the ADC_SC1 when software triggered operation is selected, or one conversion following assertion of ADHWT when hardware triggered operation is selected. When the FIFO function is enabled (AFDEP > 0), a set of conversion are triggered when ADC_SC2[ADTRG]=0 or both ADC_SC2[ADTRG]=1 and ADC_SC4[HTRGME]=1.</p> <p>1 Continuous conversions are initiated following a write to ADC_SC1 when software triggered operation is selected. Continuous conversions are initiated by an ADHWT event when hardware triggered operation is selected. When the FIFO function is enabled (AFDEP > 0), a set of conversions are loop triggered.</p> | | | | | | | | | | | | | | | | | | |
| ADCH | <p>Input Channel Select</p> <p>The ADCH bits form a 5-bit field that selects one of the input channels.</p> <table> <tr> <td>00000-01111</td><td>AD0-AD15</td></tr> <tr> <td>10000-10011</td><td>V_{SS}</td></tr> <tr> <td>10100-10101</td><td>Reserved</td></tr> <tr> <td>10110</td><td>Temperature Sensor</td></tr> <tr> <td>10111</td><td>Bandgap</td></tr> <tr> <td>11000-11100</td><td>Reserved</td></tr> <tr> <td>11101</td><td>V_{REFH}</td></tr> <tr> <td>11110</td><td>V_{REFL}</td></tr> <tr> <td>11111</td><td>Module disabled</td></tr> </table> <p>NOTE: Reset FIFO in FIFO mode.</p> | 00000-01111 | AD0-AD15 | 10000-10011 | V _{SS} | 10100-10101 | Reserved | 10110 | Temperature Sensor | 10111 | Bandgap | 11000-11100 | Reserved | 11101 | V _{REFH} | 11110 | V _{REFL} | 11111 | Module disabled |
| 00000-01111 | AD0-AD15 | | | | | | | | | | | | | | | | | | |
| 10000-10011 | V _{SS} | | | | | | | | | | | | | | | | | | |
| 10100-10101 | Reserved | | | | | | | | | | | | | | | | | | |
| 10110 | Temperature Sensor | | | | | | | | | | | | | | | | | | |
| 10111 | Bandgap | | | | | | | | | | | | | | | | | | |
| 11000-11100 | Reserved | | | | | | | | | | | | | | | | | | |
| 11101 | V _{REFH} | | | | | | | | | | | | | | | | | | |
| 11110 | V _{REFL} | | | | | | | | | | | | | | | | | | |
| 11111 | Module disabled | | | | | | | | | | | | | | | | | | |

24.3.2 Status and Control Register 2 (ADC_SC2)

The ADC_SC2 register controls the compare function, conversion trigger, and conversion active of the ADC module.

Address: 4003_B000h base + 4h offset = 4003_B004h



ADC_SC2 field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 ADACT | Conversion Active Indicates that a conversion is in progress. ADACT is set when a conversion is initiated and cleared when a conversion is completed or aborted. 0 Conversion not in progress. 1 Conversion in progress. |
| 6 ADTRG | Conversion Trigger Select Selects the type of trigger used for initiating a conversion. Two types of trigger are selectable: software trigger and hardware trigger. When software trigger is selected, a conversion is initiated following a write |

Table continues on the next page...

ADC_SC2 field descriptions (continued)

| Field | Description |
|-------------|---|
| | to ADC_SC1. When hardware trigger is selected, a conversion is initiated following the assertion of the ADHWT input. 0 Software trigger selected. 1 Hardware trigger selected. |
| 5 ACFE | Compare Function Enable Enables the compare function. 0 Compare function disabled. 1 Compare function enabled. |
| 4 ACFGT | Compare Function Greater Than Enable Configures the compare function to trigger when the result of the conversion of the input being monitored is greater than or equal to the compare value. The compare function defaults to triggering when the result of the compare of the input being monitored is less than the compare value. 0 Compare triggers when input is less than compare level. 1 Compare triggers when input is greater than or equal to compare level. |
| 3 FEMPTY | Result FIFO empty 0 Indicates that ADC result FIFO have at least one valid new data. 1 Indicates that ADC result FIFO have no valid new data. |
| 2 FFULL | Result FIFO full 0 Indicates that ADC result FIFO is not full and next conversion data still can be stored into FIFO. 1 Indicates that ADC result FIFO is full and next conversion will override old data in case of no read action. |
| REFSEL | Voltage Reference Selection Selects the voltage reference source used for conversions. 00 Default voltage reference pin pair (V_{REFH}/V_{REFL}). 01 Analog supply pin pair (V_{DDA}/V_{SSA}). 10 Reserved. 11 Reserved - Selects default voltage reference (V_{REFH}/V_{REFL}) pin pair. |

24.3.3 Status and Control Register 3 (ADC_SC3)

ADC_SC3 selects the mode of operation, clock source, clock divide, and configure for low power or long sample time.

Address: 4003_B000h base + 8h offset = 4003_B008h

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|-------|------|----|--------|------|----|--------|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | ADLPC | ADIV | | ADLSMP | MODE | | ADICLK | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ADC_SC3 field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 ADLPC | Low-Power Configuration ADLPC controls the speed and power configuration of the successive approximation converter. This optimizes power consumption when higher sample rates are not required. 0 High speed configuration. 1 Low power configuration: The power is reduced at the expense of maximum clock speed. |
| 6–5 ADIV | Clock Divide Select ADIV selects the divide ratio used by the ADC to generate the internal clock ADCK. 00 Divide ration = 1, and clock rate = Input clock. 01 Divide ration = 2, and clock rate = Input clock ÷ 2. 10 Divide ration = 3, and clock rate = Input clock ÷ 4. 11 Divide ration = 4, and clock rate = Input clock ÷ 8. |
| 4 ADLSMP | Long Sample Time Configuration ADLSMP selects between long and short sample time. This adjusts the sample period to allow higher impedance inputs to be accurately sampled or to maximize conversion speed for lower impedance inputs. Longer sample times can also be used to lower overall power consumption when continuous conversions are enabled if high conversion rates are not required. 0 Short sample time. 1 Long sample time. |

Table continues on the next page...

ADC_SC3 field descriptions (continued)

| Field | Description |
|-------------|---|
| 3–2 MODE | Conversion Mode Selection MODE bits are used to select between 12-, 10-, or 8-bit operation. 00 8-bit conversion (N = 8) 01 10-bit conversion (N = 10) 10 12-bit conversion (N = 12) 11 Reserved |
| ADICLK | Input Clock Select ADICLK bits select the input clock source to generate the internal clock ADCK. 00 Bus clock 01 Bus clock divided by 2 10 Alternate clock (ALTCLK) 11 Asynchronous clock (ADACK) |

24.3.4 Status and Control Register 4 (ADC_SC4)

This register controls the FIFO scan mode, FIFO compare function and FIFO depth selection of the ADC module.

Address: 4003_B000h base + Ch offset = 4003_B00Ch

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|--------|--------|--------|----|----|-------|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | 0 | ASCANE | ACFSEL | 0 | | AFDEP | | |
| W | | | | | | | | | HTRGME | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ADC_SC4 field descriptions

| Field | Description |
|------------------|---|
| 31–9 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 8 HTRGME | Hardware Trigger Multiple Conversion Enable This field enables hardware trigger multiple conversion. |

Table continues on the next page...

ADC_SC4 field descriptions (continued)

| Field | Description |
|-----------------|--|
| | 0 One hardware trigger pulse triggers one conversion. 1 One hardware trigger pulse triggers multiple conversions in fifo mode. |
| 7 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 6 ASCANE | FIFO Scan Mode Enable The FIFO always use the first dummied FIFO channels when it is enabled. When this bit is set and FIFO function is enabled, ADC will repeat using the first FIFO channel as the conversion channel until the result FIFO is fulfilled. In continuous mode (ADCO = 1), ADC will start next conversion with the same channel when COCO is set. 0 FIFO scan mode disabled. 1 FIFO scan mode enabled. |
| 5 ACFSEL | Compare Function Selection Compare function select OR/AND when the FIFO function is enabled (AFDEP > 0). When this field is cleared, ADC will OR all of compare triggers and set COCO after at least one of compare trigger occurs. When this field is set, ADC will AND all of compare triggers and set COCO after all of compare triggers occur. 0 OR all of compare trigger. 1 AND all of compare trigger. |
| 4–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| AFDEP | FIFO Depth FIFO Depth enables the FIFO function and sets the depth of FIFO. When AFDEP is cleared, the FIFO is disabled. When AFDEP is set to nonzero, the FIFO function is enabled and the depth is indicated by the AFDEP bits. The ADC_SC1[ADCH] and ADC_R must be accessed by FIFO mode when FIFO function is enabled. ADC starts conversion when the analog channel FIFO is upon the level indicated by AFDEP bits. The COCO bit is set when the set of conversions are completed and the result FIFO is upon the level indicated by AFDEP bits. 000 FIFO is disabled. 001 2-level FIFO is enabled. 010 3-level FIFO is enabled.. 011 4-level FIFO is enabled. 100 5-level FIFO is enabled. 101 6-level FIFO is enabled. 110 7-level FIFO is enabled. 111 8-level FIFO is enabled. |

24.3.5 Conversion Result Register (ADC_R)

In 12-bit operation, ADC_R contains the 12 bits of the result of a 12-bit conversion.

In 10-bit mode, ADC_R contains the 10 bits of the result of a 10-bit conversion.

In 8-bit mode, ADC_R contains the 8 bits of the result of a 8-bit conversion.

ADC Control Registers

ADC_R is updated each time a conversion completes except when automatic compare is enabled and the compare condition is not met.

When FIFO is enabled, the result FIFO is read via ADC_R. The ADC conversion completes when the input channel FIFO is fulfilled at the depth indicated by the AFDEP. The AD result FIFO can be read via ADC_R continuously by the order set in analog input channel ADCH.

If the MODE bits are changed, any data in ADC_R becomes invalid.

Address: 4003_B000h base + 10h offset = 4003_B010h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | 0 | | | | | | | | | | | | | | | | ADR | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ADC_R field descriptions

| Field | Description |
|-------------------|---|
| 31–12 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ADR | Conversion Result |

24.3.6 Compare Value Register (ADC_CV)

This register holds the compare value. Bits ADCV11:ADCV0 are compared to the 12 bits of the result following a conversion in 12-bit mode.

Address: 4003_B000h base + 14h offset = 4003_B014h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | 0 | | | | | | | | | | | | | | | | CV | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ADC_CV field descriptions

| Field | Description |
|-------------------|---|
| 31–12 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| CV | Conversion Result[11:0] |

24.3.7 Pin Control 1 Register (ADC_APCTL1)

The pin control registers disable the I/O port control of MCU pins used as analog inputs. APCTL1 is used to control the pins associated with channels 0-31 of the ADC module.

Address: 4003_B000h base + 18h offset = 4003_B018h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | 0 | | | | | | | | | | | | | | | | ADPC | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ADC_APCTL1 field descriptions

| Field | Description |
|-------------------|---|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ADPC | ADC Pin Control ADPCx controls the pin associated with channel ADx. 0 ADx pin I/O control enabled. 1 ADx pin I/O control disabled. |

24.3.8 Status and Control Register 5 (ADC_SC5)

ADC_SC5 selects the hardware trigger mask.

Address: 4003_B000h base + 1Ch offset = 4003_B01Ch

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|-----------|-----------------|
| R | 0 | | | | | | | | | | | | | | HTRGMASKE | HTRGMASKS EL |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ADC_SC5 field descriptions

| Field | Description |
|------------------|--|
| 31–2 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 1 HTRGMASKE | Hardware Trigger Mask Enable This field enables hardware trigger mask when HTRGMASKSEL is low. 0 Hardware trigger mask disable. 1 Hardware trigger mask enable and hardware trigger cannot trigger ADC conversion.. |
| 0 HTRGMASKSEL | Hardware Trigger Mask Mode Select This field selects hardware trigger mask mode. 0 Hardware trigger mask with HTRGMASKE. 1 Hardware trigger mask automatically when data fifo is not empty. |

24.4 Functional description

The ADC module is disabled during reset or when the ADC_SC1[ADCH] bits are all high. The module is idle when a conversion has completed and another conversion has not been initiated. When idle, the module is in its lowest power state.

The ADC can perform an analog-to-digital conversion on any of the software selectable channels. In 12-bit mode, the selected channel voltage is converted by a successive approximation algorithm into a 12-bit digital result. In 10-bit mode, the selected channel voltage is converted by a successive approximation algorithm into a 10-bit digital result. In 8-bit mode, the selected channel voltage is converted by a successive approximation algorithm into a 8-bit digital result.

When the conversion is completed, the result is placed in the data registers (ADC_R). In 10-bit mode, the result is rounded to 10 bits and placed in the data registers (ADC_R). In 8-bit mode, the result is rounded to 8 bits and placed in ADC_R. The conversion complete flag (ADC_SC1[COCO]) is then set and an interrupt is generated if the conversion complete interrupt has been enabled (ADC_SC1[AIEN] = 1).

The ADC module has the capability of automatically comparing the result of a conversion with the contents of its compare registers. The compare function is enabled by setting the ADC_SC2[ACFE] bit and operates with any of the conversion modes and configurations.

24.4.1 Clock select and divide control

One of four clock sources can be selected as the clock source for the ADC module. This clock source is then divided by a configurable value to generate the input clock to the converter (ADCK). The clock is selected from one of the following sources by means of the ADC_SC3[ADICLK] bits.

- The bus clock divided by 2: For higher bus clock rates, this allows a maximum divide by 16 of the bus clock.
- ALTCLK, that is, alternate clock which is OSC_OUT
- The asynchronous clock (ADACK): This clock is generated from a clock source within the ADC module. When selected as the clock source, this clock remains active while the MCU is in Wait or Stop mode and allows conversions in these modes for lower noise operation.

Whichever clock is selected, its frequency must fall within the specified frequency range for ADCK. If the available clocks are too slow, the ADC does not perform according to specifications. If the available clocks are too fast, the clock must be divided to the appropriate frequency. This divider is specified by the ADC_SC3[ADIV] bits and can be divide-by 1, 2, 4, or 8.

24.4.2 Input select and pin control

The Pin Control register (ADC_APCTL1) disables the I/O port control of the pins used as analog inputs. When a pin control register bit is set, the following conditions are forced for the associated MCU pin:

- The output buffer is forced to its high impedance state.
- The input buffer is disabled. A read of the I/O port returns a zero for any pin with its input buffer disabled.
- The pullup is disabled.

24.4.3 Hardware trigger

The ADC module has a selectable asynchronous hardware conversion trigger, ADHWT, that is enabled when the ADC_SC2[ADTRG] bit is set. This source is not available on all MCUs. See the module introduction for information on the ADHWT source specific to this MCU.

When ADHWT source is available and hardware trigger is enabled (ADC_SC2[ADTRG] = 1), a conversion is initiated on the rising edge of ADHWT. If a conversion is in progress when a rising edge occurs, the rising edge is ignored. In continuous convert configuration, only the initial rising edge to launch continuous conversions is observed. The hardware trigger function operates in conjunction with any of the conversion modes and configurations.

24.4.4 Conversion control

Conversions can be performed in 12-bit mode, 10-bit mode, or 8-bit mode as determined by the ADC_SC3[MODE] bits. Conversions can be initiated by a software or hardware trigger. In addition, the ADC module can be configured for low power operation, long sample time, continuous conversion, and an automatic compare of the conversion result to a software determined compare value.

24.4.4.1 Initiating conversions

A conversion initiates under the following conditions:

- A write to ADC_SC1 or a set of write to ADC_SC1 in FIFO mode (with ADCH bits not all 1s) if software triggered operation is selected.
- A hardware trigger (ADHWT) event if hardware triggered operation is selected.
- The transfer of the result to the data registers when continuous conversion is enabled.

If continuous conversions are enabled, a new conversion is automatically initiated after the completion of the current conversion. In software triggered operation, continuous conversions begin after ADC_SC1 is written and continue until aborted. In hardware triggered operation, continuous conversions begin after a hardware trigger event and continue until aborted.

24.4.4.2 Completing conversions

A conversion is completed when the result of the conversion is transferred into the data result register, ADC_R. This is indicated by the setting of ADC_SC1[COCO]. An interrupt is generated if ADC_SC1[AIEN] is high at the time that ADC_SC1[COCO] is set.

24.4.4.3 Aborting conversions

Any conversion in progress is aborted in the following cases:

- A write to ADC_SC1 occurs.
 - The current conversion will be aborted and a new conversion will be initiated, if ADC_SC1[ADCH] are not all 1s and ADC_SC4[AFDEP] are all 0s.
 - The current conversion and the rest of conversions will be aborted and no new conversion will be initiated, if ADC_SC4[AFDEP] are not all 0s.
 - A new conversion will be initiated when the FIFO is re-fulfilled upon the levels indicated by the ADC_SC4[AFDEP] bits).
- A write to ADC_SC2, ADC_SC3, ADC_SC4, ADC_CV occurs. This indicates a mode of operation change has occurred and the current and rest of conversions (when ADC_SC4[AFDEP] are not all 0s) are therefore invalid.
- The MCU is reset.
- The MCU enters Stop mode with ADACK not enabled.

When a conversion is aborted, the contents of the data register, ADC_R, are not altered. However, they continue to be the values transferred after the completion of the last successful conversion. If the conversion was aborted by a reset, ADC_R returns to their reset states.

24.4.4.4 Power control

The ADC module remains in its idle state until a conversion is initiated. If ADACK is selected as the conversion clock source, the ADACK clock generator is also enabled.

Power consumption when active can be reduced by setting ADC_SC3[ADLPC]. This results in a lower maximum value for f_{ADCK} (see the data sheet).

24.4.4.5 Sample time and total conversion time

The total conversion time depends on the sample time (as determined by ADC_SC3[ADLSMP]), the MCU bus frequency, the conversion mode (8-bit, 10-bit or 12-bit), and the frequency of the conversion clock (f_{ADCK}). After the module becomes active, sampling of the input begins. ADC_SC3[ADLSMP] selects between short (3.5 ADCK cycles) and long (23.5 ADCK cycles) sample times. When sampling is complete, the converter is isolated from the input channel and a successive approximation algorithm is performed to determine the digital value of the analog signal. The result of the conversion is transferred to ADC_R upon completion of the conversion algorithm.

If the bus frequency is less than the f_{ADCK} frequency, precise sample time for continuous conversions cannot be guaranteed when short sample is enabled (ADC_SC3[ADLSMP] = 0). If the bus frequency is less than 1/11th of the f_{ADCK} frequency, precise sample time for continuous conversions cannot be guaranteed when long sample is enabled (ADC_SC3[ADLSMP] = 1).

The maximum total conversion time for different conditions is summarized in the table below.

Table 24-11. Total conversion time vs. control conditions

| Conversion type | ADICLK | ADLSMP | Max total conversion time |
|--|--------|--------|--|
| Single or first continuous 8-bit | 0x, 10 | 0 | 20 ADCK cycles + 5 bus clock cycles |
| Single or first continuous 10-bit or 12-bit | 0x, 10 | 0 | 23 ADCK cycles + 5 bus clock cycles |
| Single or first continuous 8-bit | 0x, 10 | 1 | 40 ADCK cycles + 5 bus clock cycles |
| Single or first continuous 10-bit or 12-bit | 0x, 10 | 1 | 43 ADCK cycles + 5 bus clock cycles |
| Single or first continuous 8-bit | 11 | 0 | 5 μ s + 20 ADCK + 5 bus clock cycles |
| Single or first continuous 10-bit or 12-bit | 11 | 0 | 5 μ s + 23 ADCK + 5 bus clock cycles |
| Single or first continuous 8-bit | 11 | 1 | 5 μ s + 40 ADCK + 5 bus clock cycles |
| Single or first continuous 10-bit or 12-bit | 11 | 1 | 5 μ s + 43 ADCK + 5 bus clock cycles |
| Subsequent continuous 8-bit; $f_{BUS} > f_{ADCK}$ | xx | 0 | 17 ADCK cycles |
| Subsequent continuous 10-bit or 12-bit; $f_{BUS} > f_{ADCK}$ | xx | 0 | 20 ADCK cycles |
| Subsequent continuous 8-bit; $f_{BUS} > f_{ADCK}/11$ | xx | 1 | 37 ADCK cycles |
| Subsequent continuous 10-bit or 12-bit; $f_{BUS} > f_{ADCK}/11$ | xx | 1 | 40 ADCK cycles |

The maximum total conversion time is determined by the selected clock source and the divide ratio. The clock source is selectable by the ADC_SC3[ADICLK] bits, and the divide ratio is specified by the ADC_SC3[ADIV] bits. For example, in 10-bit mode, with

the bus clock selected as the input clock source, the input clock divide-by-1 ratio selected, and a bus frequency of 8 MHz, then the conversion time for a single conversion as given below:

$$\text{Conversion time} = \frac{23 \text{ ADCK Cyc}}{8 \text{ MHz}/1} + \frac{5 \text{ bus Cyc}}{8 \text{ MHz}} = 3.5 \mu\text{s}$$

The number of bus cycles at 8 MHz is:

$$\text{Bus cycles} = 3.5 \mu\text{s} \times 8 \text{ MHz} = 28$$

Note

The ADCK frequency must be between f_{ADCK} minimum and f_{ADCK} maximum to meet ADC specifications.

24.4.5 Automatic compare function

The compare function can be configured to check for an upper or lower limit. After the input is sampled and converted, the result is added to the complement of the compare value (ADC_CV). When comparing to an upper limit (ADC_SC2[ACFGT] = 1), if the result is greater-than or equal-to the compare value, ADC_SC1[COCO] is set. When comparing to a lower limit (ADC_SC2[ACFGT] = 0), if the result is less than the compare value, ADC_SC1[COCO] is set. The value generated by the addition of the conversion result and the complement of the compare value is transferred to ADC_R.

On completion of a conversion while the compare function is enabled, if the compare condition is not true, ADC_SC1[COCO] is not set and no data is transferred to the result registers. An ADC interrupt is generated on the setting of ADC_SC1[COCO] if the ADC interrupt is enabled (ADC_SC1[AIEN] = 1).

On completion of all conversions while the compare function is enabled and FIFO enabled, if none of the compare conditions are not true when ADC_SC4[ACFSEL] is low or if not all of compare conditions are true when ADC_SC4[ACFSEL] is high, ADC_SC1[COCO] is not set. The compare data are transferred to the result registers regardless of compare condition true or false when FIFO enabled.

Note

The compare function can monitor the voltage on a channel while the MCU is in Wait or Stop mode. The ADC interrupt wakes the MCU when the compare condition is met.

Note

The compare function can not work in continuous conversion mode when FIFO enabled.

24.4.6 FIFO operation

The ADC module supports FIFO operation to minimize the interrupts to CPU in order to reduce CPU loading in ADC interrupt service routines. This module contains two FIFOs to buffer analog input channels and analog results respectively.

The FIFO function is enabled when the ADC_SC4[AFDEP] bits are set non-zero. The FIFO depth is indicated by these bits. The FIFO supports up to eight level buffer.

The analog input channel FIFO is accessed by ADC_SC1[ADCH] bits, when FIFO function is enabled. The analog channel must be written to this FIFO in order. The ADC will not start the conversion if the channel FIFO is fulfilled below the level indicated by the ADC_SC4[AFDEP] bits, no matter whether software or hardware trigger is set. Read ADC_SC1[ADCH] will read the current active channel value. Write to ADC_SC1[ADCH] will re-fill channel FIFO to initial new conversion. It will abort current conversion and any other conversions that did not start. Write to the ADC_SC1 after all the conversions are completed or ADC is in idle state.

The result of the FIFO is accessed by ADC_R register, when FIFO function is enabled. The result must be read via these two registers by the same order of analog input channel FIFO to get the proper results. Don't read ADC_R until all of the conversions are completed in FIFO mode. The ADC_SC1[COCO] bit will be set only when all conversions indicated by the analog input channel FIFO complete whatever software or hardware trigger is set. An interrupt request will be submitted to CPU if the ADC_SC1[AIEN] is set when the FIFO conversion completes and the ADC_SC1[COCO] bit is set.

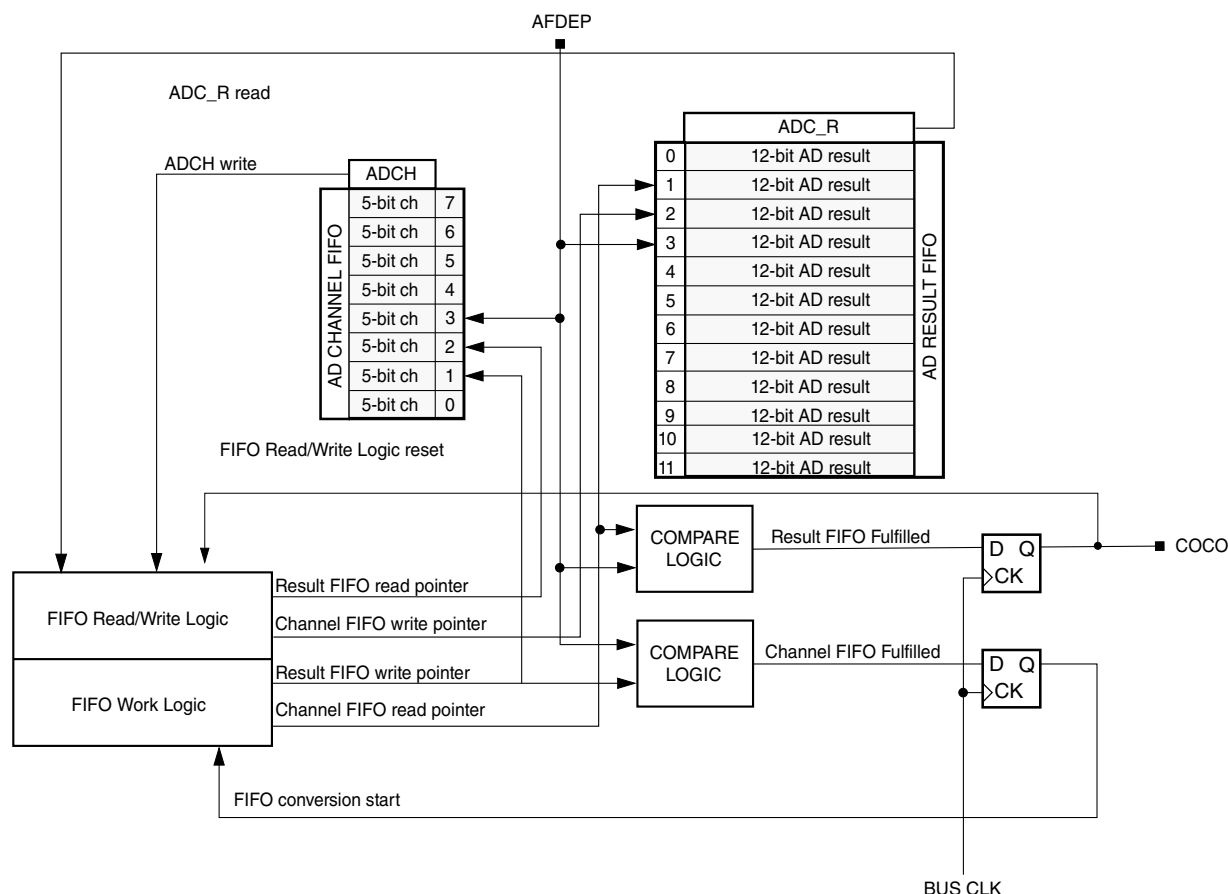


Figure 24-10. FADC FIFO structure

If software trigger is enabled, the next analog channel is fetched from analog input channel FIFO as soon as a conversion completes and its result is stored in the result FIFO. When all conversions set in the analog input channel FIFO completes, the ADC_SC1[COCO] bit is set and an interrupt request will be submitted to CPU if the ADC_SC1[AIEN] bit is set.

If single hardware trigger mode is enabled(ADC_SC2[ADTRG]= 1 and ADC_SC4[HTRGME]=0), the next analog is fetched from analog input channel FIFO only when this conversion completes, its result is stored in the result FIFO, and the next hardware trigger is fed to ADC module. If multi hardware trigger mode is enabled(ADC_SC2[ADTRG]=1 and ADC_SC4[HTRGME]=1), the next analog is fetched from analog input channel FIFO only when this conversion completes, its result is stored in the result FIFO, and next conversion will start without waiting for next hardware trigger. When all conversions set in the analog input channel FIFO completes, the ADC_SC1[COCO] bit is set and an interrupt request will be submitted to CPU if the ADC_SC1[AIEN] bit is set.

In single conversion in which ADC_SC1[ADCO] bit is clear, the ADC stops conversions when ADC_SC1[COCO] bit is set until the channel FIFO is fulfilled again or new hardware trigger occur.

The FIFO also provides scan mode to simplify the dummy work of input channel FIFO. When the ADC_SC4[ASCANE] bit is set in FIFO mode, the FIFO will always use the first dummied channel in spite of the value in the input channel FIFO. The ADC conversion start to work in FIFO mode as soon as the first channel is dummied. The following write operation to the input channel FIFO will cover the first channel element in this FIFO. In scan FIFO mode, the ADC_SC1[COCO] bit is set when the result FIFO is fulfilled according to the depth indicated by the ADC_SC4[AFDEP] bits.

In continuous conversion in which the ADC_SC1[ADCO] bit is set, the ADC starts next conversion immediately when all conversions are completed. ADC module will fetch the analog input channel from the beginning of analog input channel FIFO.

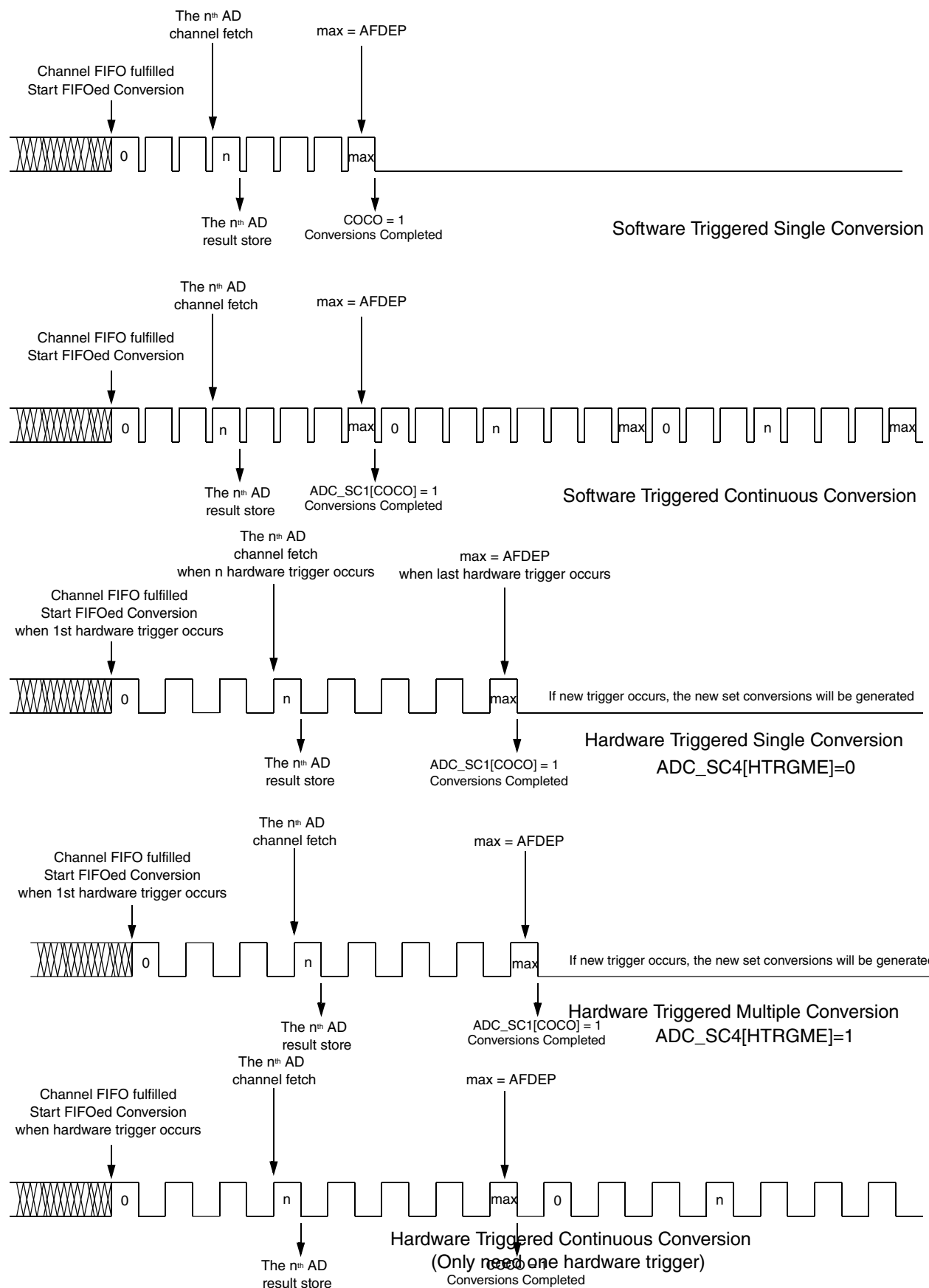


Figure 24-11. ADC FIFO conversion sequence

KEA128 Sub-Family Reference Manual, Rev. 2, July 2014

24.4.7 MCU wait mode operation

Wait mode is a low-power consumption standby mode from which recovery is fast because the clock sources remain active. If a conversion is in progress when the MCU enters wait mode, it continues until completion. Conversions can be initiated while the MCU is in wait mode by means of the hardware trigger or if continuous conversions are enabled.

The bus clock, bus clock divided by two, ALTCLK and ADACK are available as conversion clock sources while in wait mode.

ADC_SC1[COCO] is set by a conversion complete event that generates an ADC interrupt to wake the MCU from wait mode if the ADC interrupt is enabled (ADC_SC1[AIEN] = 1).

24.4.8 MCU Stop mode operation

Stop mode is a low-power consumption standby mode during which most or all clock sources on the MCU are disabled.

24.4.8.1 Stop mode with ADACK disabled

If the asynchronous clock, ADACK, is not selected as the conversion clock, executing a STOP instruction aborts the current conversion and places the ADC in its idle state. The contents of ADC_R are unaffected by Stop mode. After exiting from Stop mode, a software or hardware trigger is required to resume conversions.

24.4.8.2 Stop mode with ADACK enabled

If ADACK is selected as the conversion clock, the ADC continues operation during Stop mode. For guaranteed ADC operation, the MCU's voltage regulator must remain active during Stop mode. See the module introduction for configuration information for this MCU.

If a conversion is in progress when the MCU enters Stop mode, it continues until completion. Conversions can be initiated while the MCU is in Stop mode by means of the hardware trigger or if continuous conversions are enabled.

A conversion complete event sets the ADC_SC1[COCO] and generates an ADC interrupt to wake the MCU from Stop mode if the ADC interrupt is enabled (ADC_SC1[AIEN] = 1). In fifo mode, ADC cannot complete the conversion operation fully or wake the MCU from Stop mode.

Note

The ADC module can wake the system from low-power stop and cause the MCU to begin consuming run-level currents without generating a system level interrupt. To prevent this scenario, the data transfer blocking mechanism must be cleared when entering Stop and continuing ADC conversions.

24.5 Initialization information

This section gives an example that provides some basic direction on how to initialize and configure the ADC module. You can configure the module for 8-, 10-, or 12-bit resolution, single or continuous conversion, and a polled or interrupt approach, among many other options. Refer to ADC_SC3 register for information used in this example.

Note

Hexadecimal values prefixed by a 0x, binary values prefixed by a %, and decimal values have no preceding character.

24.5.1 ADC module initialization example

Before the ADC module can be used to complete conversions, it must be initialized. Given below is a method to initialize ADC module.

24.5.1.1 Initialization sequence

A typical initialization sequence is as follows:

1. Update the configuration register (ADC_SC3) to select the input clock source and the divide ratio used to generate the internal clock, ADCK. This register is also used for selecting sample time and low-power configuration.
2. Update status and control register 2 (ADC_SC2) to select the hardware or software conversion trigger and compare function options, if enabled.

3. Update status and control register 1 (ADC_SC1) to select whether conversions will be continuous or completed only once, and to enable or disable conversion complete interrupts. The input channel on which conversions will be performed is also selected here.

24.5.1.2 Pseudo-code example

In this example, the ADC module is set up with interrupts enabled to perform a single 10-bit conversion at low power with a long sample time on input channel 1, where the internal ADCK clock is derived from the bus clock divided by 1.

Example: 24.5.1.2.1 General ADC initialization routine

```
void ADC_init(void)
{
    /* The following code segment demonstrates how to initialize ADC by low-power mode,
long    sample time, bus frequency, software triggered from AD1 external pin without FIFO
enabled */
    ADC_APCTL1 = ADC_APCTL1_ADPC1_MASK;
    ADC_SC3 = ADC_SC3_ADLPF_MASK | ADC_SC3_ADLSMP_MASK | ADC_SC3_MODE0_MASK;
    ADC_SC2 = 0x00;
    ADC_SC1 = ADC_SC1_AIEN_MASK | ADC_SC1_ADCH0_MASK;
}
```

24.5.2 ADC FIFO module initialization example

Before the ADC module can be used to start FIFOed conversions, an initialization procedure must be performed. A typical sequence is as follows:

1. Update the configuration register (ADC_SC3) to select the input clock source and the divide ratio used to generate the internal clock, ADCK. This register is also used to select sample time and low-power configuration.
2. Update the configuration register (ADC_SC4) to select the FIFO scan mode, FIFO compare function selection (OR or AND function) and FIFO depth.
3. Update status and control register 2 (ADC_SC2) to select the hardware or software conversion trigger, compare function options if enabled.
4. Update status and control register 1 (ADC_SC1) to select whether conversions will be continuous or completed only once, and to enable or disable conversion complete interrupts. The input channel on which conversions will be performed is also selected here.

24.5.2.1 Pseudo-code example

In this example, the ADC module is set up with interrupts enabled to perform a single hardware triggered 10-bit 4-level-FIFO conversion at low power with a long sample time on input channels of 1, 3, 5, and 7. Here the internal ADCK clock is derived from the bus clock divided by 1.

Example: 24.5.2.1.1 FIFO ADC initialization routine

```
void ADC_init(void)
{
    /* The following code segment demonstrates how to initialize ADC by low-power mode, long
    sample time, bus frequency, hardware triggered from AD1, AD3, AD5, and AD7 external pins
    with 4-level FIFO enabled */

    ADC_APCTL1 = ADC_APCTL1_ADPC6_MASK | ADC_APCTL1_ADPC5_MASK | ADC_APCTL1_ADPC3_MASK |
    ADC_APCTL1_ADPC1_MASK;

    ADC_SC3 = ADC_SC3_ADLPC_MASK | ADC_SC3_ADLSP_MASK | ADC_SC3_MODE1_MASK;

    // setting hardware trigger
    ADC_SC2 = ADC_SC2_ADTRG_MASK ;

    //4-Level FIFO
    ADC_SC4 = ADC_SC4_AFDEP1_MASK | ADC_SC4_AFDEP0_MASK;

    // dummy the 1st channel
    ADC_SC1 = ADC_SC1_ADCH0_MASK;

    // dummy the 2nd channel
    ADC_SC1 = ADC_SC1_ADCH1_MASK | ADC_SC1_ADCH0_MASK;

    // dummy the 3rd channel
    ADC_SC1 = ADC_SC1_ADCH2_MASK | ADC_SC1_ADCH0_MASK;

    // dummy the 4th channel and ADC starts conversion
    ADC_SC1 = ADC_SC1_AIEN_MASK | ADC_SC1_ADCH2_MASK | ADC_SC1_ADCH1_MASK | ADC_SC1_ADCH0_MASK;
}
```

Example: 24.5.2.1.2 FIFO ADC interrupt service routine

```
unsigned short buffer[4];
interrupt VectorNumber_Vadc void ADC_isr(void)
{
    /* The following code segment demonstrates read AD result FIFO */
    // read conversion result of channel 1 and COCO bit is cleared
    buffer[0] = ADC_R;
    // read conversion result of channel 3
    buffer[1] = ADC_R;
    // read conversion result of channel 5
    buffer[2] = ADC_R;
    // read conversion result of channel 7
    buffer[3] = ADC_R;
}
```

NOTE

ADC_R is 16-bit ADC result register, combined from ADC_RH and ADC_RL

24.6 Application information

This section contains information for using the ADC module in applications. The ADC has been designed to be integrated into a microcontroller for use in embedded control applications requiring an A/D converter.

24.6.1 External pins and routing

The following sections discuss the external pins associated with the ADC module and how they are used for best results.

24.6.1.1 Analog supply pins

The ADC module has analog power and ground supplies (V_{DDA} and V_{SSA}) available as separate pins on some devices. V_{SSA} is shared on the same pin as the MCU digital V_{SS} on some devices. On other devices, V_{SSA} and V_{DDA} are shared with the MCU digital supply pins. In these cases, there are separate pads for the analog supplies bonded to the same pin as the corresponding digital supply so that some degree of isolation between the supplies is maintained.

When available on a separate pin, both V_{DDA} and V_{SSA} must be connected to the same voltage potential as their corresponding MCU digital supply (V_{DD} and V_{SS}) and must be routed carefully for maximum noise immunity and bypass capacitors placed as near as possible to the package.

If separate power supplies are used for analog and digital power, the ground connection between these supplies must be at the V_{SSA} pin. This should be the only ground connection between these supplies if possible. The V_{SSA} pin makes a good single point ground location.

24.6.1.2 Analog reference pins

In addition to the analog supplies, the ADC module has connections for two reference voltage inputs. The high reference is V_{REFH} , which may be shared on the same pin as V_{DDA} on some devices. The low reference is V_{REFL} , which may be shared on the same pin as V_{SSA} on some devices.

When available on a separate pin, V_{REFH} may be connected to the same potential as V_{DDA} , or may be driven by an external source between the minimum V_{DDA} spec and the V_{DDA} potential (V_{REFH} must never exceed V_{DDA}). When available on a separate pin, V_{REFL} must be connected to the same voltage potential as V_{SSA} . V_{REFH} and V_{REFL} must be routed carefully for maximum noise immunity and bypass capacitors placed as near as possible to the package.

AC current in the form of current spikes required to supply charge to the capacitor array at each successive approximation step is drawn through the V_{REFH} and V_{REFL} loop. The best external component to meet this current demand is a 0.1 μF capacitor with good high frequency characteristics. This capacitor is connected between V_{REFH} and V_{REFL} and must be placed as near as possible to the package pins. Resistance in the path is not recommended because the current causes a voltage drop that could result in conversion errors. Inductance in this path must be minimum (parasitic only).

24.6.1.3 Analog input pins

The external analog inputs are typically shared with digital I/O pins on MCU devices. The pin I/O control is disabled by setting the appropriate control bit in one of the pin control registers. Conversions can be performed on inputs without the associated pin control register bit set. It is recommended that the pin control register bit always be set when using a pin as an analog input. This avoids problems with contention because the output buffer is in its high impedance state and the pullup is disabled. Also, the input buffer draws DC current when its input is not at V_{DD} or V_{SS} . Setting the pin control register bits for all pins used as analog inputs should be done to achieve lowest operating current.

Empirical data shows that capacitors on the analog inputs improve performance in the presence of noise or when the source impedance is high. Use of 0.01 μF capacitors with good high-frequency characteristics is sufficient. These capacitors are not necessary in all cases, but when used they must be placed as near as possible to the package pins and be referenced to V_{SSA} .

For proper conversion, the input voltage must fall between V_{REFH} and V_{REFL} . If the input is equal to or exceeds V_{REFH} , the converter circuit converts the signal to 0xFFF (full scale 12-bit representation), 0x3FF (full scale 10-bit representation) or 0xFF (full scale 8-bit

representation). If the input is equal to or less than V_{REFL} , the converter circuit converts it to 0x000. Input voltages between V_{REFH} and V_{REFL} are straight-line linear conversions. There is a brief current associated with V_{REFL} when the sampling capacitor is charging. The input is sampled for 3.5 cycles of the ADCK source when ADC_SC3[ADLSMP] is low, or 23.5 cycles when ADC_SC3[ADLSMP] is high.

For minimal loss of accuracy due to current injection, pins adjacent to the analog input pins should not be transitioning during conversions.

24.6.2 Sources of error

Several sources of error exist for A/D conversions. These are discussed in the following sections.

24.6.2.1 Sampling error

For proper conversions, the input must be sampled long enough to achieve the proper accuracy. Given the maximum input resistance of approximately 7 k Ω and input capacitance of approximately 5.5 pF, sampling to within 1/4 LSB (at 12-bit resolution) can be achieved within the minimum sample window (3.5 cycles at 8 MHz maximum ADCK frequency) provided the resistance of the external analog source (R_{AS}) is kept below 2 k Ω .

Higher source resistances or higher-accuracy sampling is possible by setting ADC_SC3[ADLSMP] (to increase the sample window to 23.5 cycles) or decreasing ADCK frequency to increase sample time.

24.6.2.2 Pin leakage error

Leakage on the I/O pins can cause conversion error if the external analog source resistance (R_{AS}) is high. If this error cannot be tolerated by the application, keep R_{AS} lower than $V_{DDA} / (2^N * I_{LEAK})$ for less than 1/4 LSB leakage error ($N = 8$ in 8-bit, 10 in 10-bit or 12 in 12-bit mode).

24.6.2.3 Noise-induced errors

System noise that occurs during the sample or conversion process can affect the accuracy of the conversion. The ADC accuracy numbers are guaranteed as specified only if the following conditions are met:

- There is a 0.1 μF low-ESR capacitor from V_{REFH} to V_{REFL} .
- There is a 0.1 μF low-ESR capacitor from V_{DDA} to V_{SSA} .
- If inductive isolation is used from the primary supply, an additional 1 μF capacitor is placed from V_{DDA} to V_{SSA} .
- V_{SSA} (and V_{REFL} , if connected) is connected to V_{SS} at a quiet point in the ground plane.
- Operate the MCU in wait or Stop mode before initiating (hardware triggered conversions) or immediately after initiating (hardware or software triggered conversions) the ADC conversion.
 - For software triggered conversions, immediately follow the write to ADC_SC1 with a stop instruction.
 - For Stop mode operation, select ADACK as the clock source. Operation in Stop reduces V_{DD} noise but increases effective conversion time due to stop recovery.
- There is no I/O switching, input or output, on the MCU during the conversion.

There are some situations where external system activity causes radiated or conducted noise emissions or excessive V_{DD} noise is coupled into the ADC. In these situations, or when the MCU cannot be placed in wait or Stop or I/O activity cannot be halted, these recommended actions may reduce the effect of noise on the accuracy:

- Place a 0.01 μF capacitor (C_{AS}) on the selected input channel to V_{REFL} or V_{SSA} (this improves noise issues, but affects the sample rate based on the external analog source resistance).
- Average the result by converting the analog input many times in succession and dividing the sum of the results. Four samples are required to eliminate the effect of a 1LSB, one-time error.
- Reduce the effect of synchronous noise by operating off the asynchronous clock (ADACK) and averaging. Noise that is synchronous to ADCK cannot be averaged out.

24.6.2.4 Code width and quantization error

The ADC quantizes the ideal straight-line transfer function into 4096 steps (in 12-bit mode). Each step ideally has the same height (1 code) and width. The width is defined as the delta between the transition points to one code and the next. The ideal code width for an N bit converter (in this case N can be 8, 10 or 12), defined as 1LSB, is:

$$1\text{lsb} = (V_{\text{REFH}} - V_{\text{REFL}}) / 2^N$$

There is an inherent quantization error due to the digitization of the result. For 8-bit or 10-bit conversions the code transitions when the voltage is at the midpoint between the points where the straight line transfer function is exactly represented by the actual transfer function. Therefore, the quantization error will be $\pm 1/2$ lsb in 8- or 10-bit mode. As a consequence, however, the code width of the first (0x000) conversion is only $1/2$ lsb and the code width of the last (0xFF or 0x3FF) is 1.5 lsb.

For 12-bit conversions the code transitions only after the full code width is present, so the quantization error is -1 lsb to 0 lsb and the code width of each step is 1 lsb.

24.6.2.5 Linearity errors

The ADC may also exhibit non-linearity of several forms. Every effort has been made to reduce these errors but the system must be aware of them because they affect overall accuracy. These errors are:

- Zero-scale error (E_{ZS}) (sometimes called offset) — This error is defined as the difference between the actual code width of the first conversion and the ideal code width ($1/2$ lsb in 8-bit or 10-bit modes and 1 lsb in 12-bit mode). If the first conversion is 0x001, the difference between the actual 0x001 code width and its ideal (1 lsb) is used.
- Full-scale error (E_{FS}) — This error is defined as the difference between the actual code width of the last conversion and the ideal code width (1.5 lsb in 8-bit or 10-bit modes and 1LSB in 12-bit mode). If the last conversion is 0x3FE, the difference between the actual 0x3FE code width and its ideal (1 lsb) is used.
- Differential non-linearity (DNL) — This error is defined as the worst-case difference between the actual code width and the ideal code width for all conversions.
- Integral non-linearity (INL) — This error is defined as the highest-value that the absolute value of the running sum of DNL achieves. More simply, this is the worst-case difference of the actual transition voltage to a given code and its corresponding ideal transition voltage, for all codes.
- Total unadjusted error (TUE) — This error is defined as the difference between the actual transfer function and the ideal straight-line transfer function and includes all forms of error.

24.6.2.6 Code jitter, non-monotonicity, and missing codes

Analog-to-digital converters are susceptible to three special forms of error. These are code jitter, non-monotonicity, and missing codes.

Code jitter occurs when, at certain points, a given input voltage converts to one of two values when sampled repeatedly. Ideally, when the input voltage is infinitesimally smaller than the transition voltage, the converter yields the lower code (and vice-versa). However, even small amounts of system noise can cause the converter to be indeterminate, between two codes, for a range of input voltages around the transition voltage. This range is normally around $\pm 1/2$ lsb in 8-bit or 10-bit mode, or around 2 lsb in 12-bit mode, and increases with noise.

This error may be reduced by repeatedly sampling the input and averaging the result. Additionally the techniques discussed in [Noise-induced errors](#) reduces this error.

Non-monotonicity is defined when, except for code jitter, the converter converts to a lower code for a higher input voltage. Missing codes are those values that are never converted for any input value.

In 8-bit or 10-bit mode, the ADC is guaranteed to be monotonic and have no missing codes.

Chapter 25

Analog comparator (ACMP)

25.1 Introduction

The analog comparator module (ACMP) provides a circuit for comparing two analog input voltages. The comparator circuit is designed to operate across the full range of the supply voltage (rail-to-rail operation).

The analog mux provides a circuit for selecting an analog input signal from four channels. One signal provided by the 6-bit DAC. The mux circuit is designed to operate across the full range of the supply voltage. The 6-bit DAC is 64-tap resistor ladder network which provides a selectable voltage reference for applications where voltage reference is needed. The 64-tap resistor ladder network divides the supply reference V_{in} into 64 voltage level. A 6-bit digital signal input selects output voltage level, which varies from V_{in} to $V_{in}/64$. V_{in} can be selected from two voltage sources.

25.1.1 Features

ACMP features include:

- Operational over the whole supply range of 2.7 V to 5.5 V
- On-chip 6-bit resolution DAC with selectable reference voltage from V_{DD} or internal bandgap
- Configurable hysteresis
- Selectable interrupt on rising edge, falling edge, or both rising or falling edges of comparator output
- Selectable inversion on comparator output
- Up to four selectable comparator inputs
- Operational in Stop mode

25.1.2 Modes of operation

This section defines the ACMP operation in Wait, Stop, and Background Debug modes.

25.1.2.1 Operation in Wait mode

The ACMP continues to operate in Wait mode, if enabled. The interrupt can wake the MCU if enabled.

25.1.2.2 Operation in Stop mode

The ACMP (including DAC and CMP) continues to operate in Stop mode if enabled. If ACMP_CS[ACIE] is set, a ACMP interrupt can be generated to wake the MCU up from Stop mode.

If the Stop is exited by an interrupt, the ACMP setting remains before entering the Stop mode. If Stop is exited with a reset, the ACMP goes into its reset.

The user must turn off the DAC if the output is not used as a reference input of ACMP to save power, because the DAC consumes additional power.

25.1.2.3 Operation in Debug mode

When the MCU is in Debug mode, the ACMP continues operating normally.

25.1.3 Block diagram

The block diagram of the ACMP module is shown in the following figure.

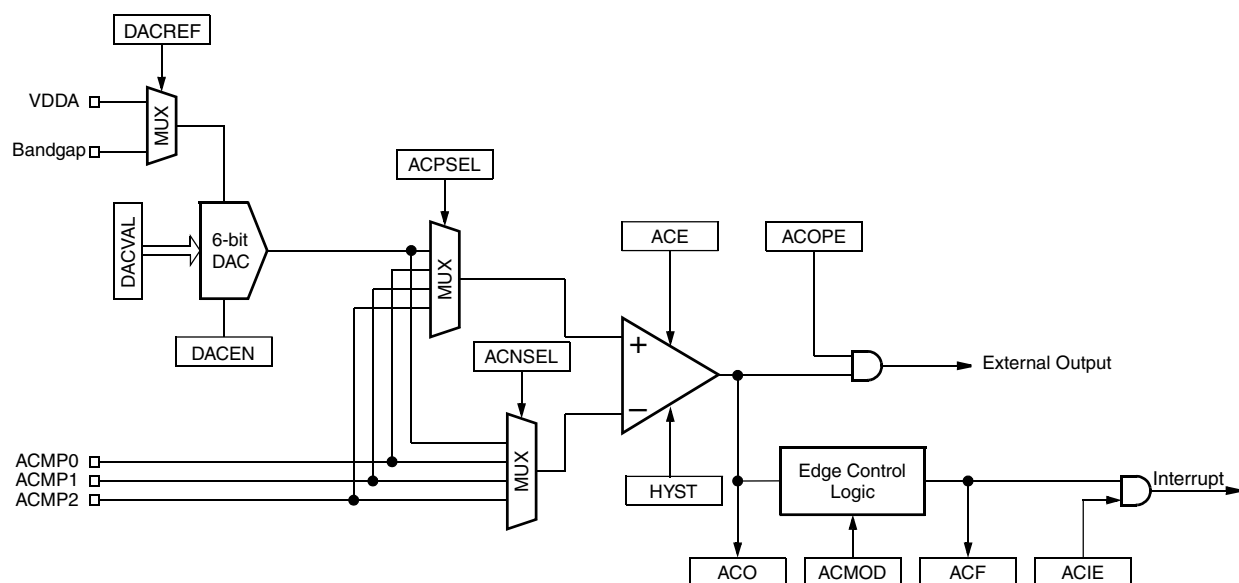


Figure 25-1. ACMP block diagram

25.2 External signal description

The output of ACMP can also be mapped to an external pin. When the output is mapped to an external pin, ACMP_CS[ACOPE] controls the pin to enable/disable the ACMP output function.

25.3 Memory map and register definition

ACMP memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-------------|----------------------------|
| 4007_3000 | ACMP Control and Status Register (ACMP0_CS) | 8 | R/W | 00h | 25.3.1/362 |
| 4007_3001 | ACMP Control Register 0 (ACMP0_C0) | 8 | R/W | 00h | 25.3.2/363 |
| 4007_3002 | ACMP Control Register 1 (ACMP0_C1) | 8 | R/W | 00h | 25.3.3/363 |
| 4007_3003 | ACMP Control Register 2 (ACMP0_C2) | 8 | R/W | 00h | 25.3.4/364 |
| 4007_4000 | ACMP Control and Status Register (ACMP1_CS) | 8 | R/W | 00h | 25.3.1/362 |
| 4007_4001 | ACMP Control Register 0 (ACMP1_C0) | 8 | R/W | 00h | 25.3.2/363 |
| 4007_4002 | ACMP Control Register 1 (ACMP1_C1) | 8 | R/W | 00h | 25.3.3/363 |
| 4007_4003 | ACMP Control Register 2 (ACMP1_C2) | 8 | R/W | 00h | 25.3.4/364 |

25.3.1 ACMP Control and Status Register (ACMPx_CS)

Address: Base address + 0h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----|------|-----|------|-----|-------|-------|---|
| Read | ACE | HYST | ACF | ACIE | ACO | ACOPE | ACMOD | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ACMPx_CS field descriptions

| Field | Description |
|------------|---|
| 7 ACE | Analog Comparator Enable Enables the ACMP module. 0 The ACMP is disabled. 1 The ACMP is enabled. |
| 6 HYST | Analog Comparator Hysterisis Selection Selects ACMP hysterisis. 0 20 mV. 1 30 mV. |
| 5 ACF | ACMP Interrupt Flag Bit Synchronously set by hardware when ACMP output has a valid edge defined by ACMOD. The setting of this bit lags the ACMPO to bus clocks. Clear ACF bit by writing a 0 to this bit. Writing a 1 to this bit has no effect. |
| 4 ACIE | ACMP Interrupt Enable Enables an ACMP CPU interrupt. 0 Disable the ACMP Interrupt. 1 Enable the ACMP Interrupt. |
| 3 ACO | ACMP Output Reading ACO will return the current value of the analog comparator output. ACO is reset to a 0 and will read as a 0 when the ACMP is disabled (ACE = 0) |
| 2 ACOPE | ACMP Output Pin Enable ACOPE enables the pad logic so that the output can be placed onto an external pin. 0 ACMP output cannot be placed onto external pin. 1 ACMP output can be placed onto external pin. |
| ACMOD | ACMP MOD Determines the sensitivity modes of the interrupt trigger. 00 ACMP interrupt on output falling edge. 01 ACMP interrupt on output rising edge. 10 ACMP interrupt on output falling edge. 11 ACMP interrupt on output falling or rising edge. |

25.3.2 ACMP Control Register 0 (ACMPx_C0)

Address: Base address + 1h offset

| | | | | | | | | |
|-------|---|---|--------|---|---|---|--------|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | ACPSEL | | 0 | | ACNSEL | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ACMPx_C0 field descriptions

| Field | Description |
|-----------------|--|
| 7–6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5–4 ACPSEL | ACMP Positive Input Select 00 External reference 0 01 External reference 1 10 External reference 2 11 DAC output |
| 3–2 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ACNSEL | ACMP Negative Input Select 00 External reference 0 01 External reference 1 10 External reference 2 11 DAC output |

25.3.3 ACMP Control Register 1 (ACMPx_C1)

Address: Base address + 2h offset

| | | | | | | | | |
|-------|-------|--------|--------|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | DACEN | DACREF | DACVAL | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ACMPx_C1 field descriptions

| Field | Description |
|-------------|---|
| 7 DACEN | DAC Enable Enables the output of 6-bit DAC. 0 The DAC is disabled. 1 The DAC is enabled. |
| 6 DACREF | DAC Reference Select |

Table continues on the next page...

ACMPx_C1 field descriptions (continued)

| Field | Description |
|--------|--|
| | 0 The DAC selects Bandgap as the reference. 1 The DAC selects V_{DDA} as the reference. |
| DACVAL | DAC Output Level Selection Selects the output voltage using the given formula: $V_{output} = (V_{in}/64) \times (DACVAL[5:0] + 1)$ The V_{output} range is from $V_{in}/64$ to V_{in} , the step is $V_{in}/64$ |

25.3.4 ACMP Control Register 2 (ACMPx_C2)

Address: Base address + 3h offset

| | | | | | | | | |
|-------|---|---|---|---|---|-------|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | ACIPE | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ACMPx_C2 field descriptions

| Field | Description |
|-----------------|---|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ACIPE | ACMP Input Pin Enable This 3-bit field controls if the corresponding ACMP external pin can be driven by an analog input. 0 The corresponding external analog input is not allowed. 1 The corresponding external analog input is allowed. |

25.4 Functional description

The ACMP module is functionally composed of two parts: digital-to-analog (DAC) and comparator (CMP).

The DAC includes a 64-level DAC (digital to analog converter) and relevant control logic. DAC can select one of two reference inputs, V_{DD} or on-chip bandgap, as the DAC input V_{in} by setting ACMP_C1[DACREF]. After the DAC is enabled, it converts the data set in ACMP_C1[DACVAL] to a stepped analog output, which is fed into ACMP as an internal reference input. This stepped analog output is also mapped out of the module. The output voltage range is from $V_{in}/64$ to V_{in} . The step size is $V_{in}/64$.

The ACMP can achieve the analog comparison between positive input and negative input, and then give out a digital output and relevant interrupt. Both the positive and negative input of ACMP can be selected from the four common inputs: three external

reference inputs and one internal reference input from the DAC output. The positive input of ACMP is selected by ACMP_C0[ACPSEL] and the negative input is selected by ACMP_C0[ACNSEL]. Any pair of the eight inputs can be compared by configuring the ACMP_C0 with the appropriate value.

After the ACMP is enabled by setting ACMP_CS[ACE], the comparison result appears as a digital output. Whenever a valid edge defined in ACMP_CS[ACMOD] occurs, ACMP_CS[ACF] is asserted. If ACMP_CS[ACIE] is set, a ACMP CPU interrupt occurs. The valid edge is defined by ACMP_CS[ACMOD]. When ACMP_CS[ACMOD] = 00b or 10b, only the falling-edge on ACMP output is valid. When ACMP_CS[ACMOD] = 01b, only rising-edge on ACMP output is valid. When ACMP_CS[ACMOD] = 11b, both the rising-edge and falling-edge on the ACMP output are valid.

The ACMP output is synchronized by the bus clock to generate ACMP_CS[ACO] so that the CPU can read the comparison. In stop3 mode, if the output of ACMP is changed, ACMP_O cannot be updated in time. The output can be synchronized and ACMP_CS[ACO] can be updated upon the waking up of the CPU because of the availability of the bus clock. ACMP_CS[ACO] changes following the comparison result, so it can serve as a tracking flag that continuously indicates the voltage delta on the inputs.

If a reference input external to the chip is selected as an input of ACMP, the corresponding ACMP_C2[ACIPE] bit must be set to enable the input from pad interface. If the output of the ACMP needs to be put onto the external pin, the ACMP_CS[ACOPE] bit must enable the ACMP pin function of pad logic.

25.5 Setup and operation of ACMP

The two parts of ACMP (DAC and CMP) can be set up and operated independently. But if the DAC works as an input of the CMP, the DAC must be configured before the ACMP is enabled.

Because the input-switching can cause problems on the ACMP inputs, the user should complete the input selection before enabling the ACMP and must not change the input selection setting when the ACMP is enabled to avoid unexpected output. Similarly, because the DAC experiences a setup delay after ACMP_C1[DACVAL] is changed, the user should complete the setting of ACMP_C1[DACVAL] before DAC is enabled.

25.6 Resets

During a reset the ACMP is configured in the default mode. Both CMP and DAC are disabled.

25.7 Interrupts

If the bus clock is available when a valid edge defined in ACMP_CS[ACMOD] occurs, the ACMP_CS[ACF] is asserted. If ACMP_CS[ACIE] is set, a ACMP interrupt event occurs. The ACMP_CS[ACF] bit remains asserted until the ACMP interrupt is cleared by software. When in stop mode, a valid edge on ACMP output generates an asynchronous interrupt that can wake the MCU from stop. The interrupt can be cleared by writing a 0 to the ACMP_CS[ACF] bit.

Chapter 26

FlexTimer Module (FTM)

26.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The FlexTimer module (FTM) is a two-to-eight channel timer that supports input capture, output compare, and the generation of PWM signals to control electric motor and power management applications. The FTM time reference is a 16-bit counter that can be used as an unsigned or signed counter.

26.1.1 FlexTimer philosophy

The FlexTimer is built upon a simple timer, the HCS08 Timer PWM Module – TPM, used for many years on Freescale's 8-bit microcontrollers. The FlexTimer extends the functionality to meet the demands of motor control, digital lighting solutions, and power conversion, while providing low cost and backwards compatibility with the TPM module.

Several key enhancements are made:

- Signed up counter
- Deadtime insertion hardware
- Fault control inputs
- Enhanced triggering functionality
- Initialization and polarity control

All of the features common with the TPM have fully backwards compatible register assignments. The FlexTimer can also use code on the same core platform without change to perform the same functions.

Motor control and power conversion features have been added through a dedicated set of registers and defaults turn off all new features. The new features, such as hardware deadtime insertion, polarity, fault control, and output forcing and masking, greatly reduce loading on the execution software and are usually each controlled by a group of registers.

FlexTimer input triggers can be from comparators, ADC, or other submodules to initiate timer functions automatically. These triggers can be linked in a variety of ways during integration of the sub modules so please note the options available for used FlexTimer configuration.

More than one FlexTimers may be synchronized to provide a larger timer with their counters incrementing in unison, assuming the initialization, the input clocks, the initial and final counting values are the same in each FlexTimer.

All main user access registers are buffered to ease the load on the executing software. A number of trigger options exist to determine which registers are updated with this user defined data.

26.1.2 Features

The FTM features include:

- FTM source clock is selectable
 - Source clock can be the system clock, the fixed frequency clock, or an external clock
 - Fixed frequency clock is an additional clock input to allow the selection of an on chip clock source other than the system clock
 - Selecting external clock connects FTM clock to a chip level input pin therefore allowing to synchronize the FTM counter with an off chip clock source
- Prescaler divide-by 1, 2, 4, 8, 16, 32, 64, or 128
- 16-bit counter
 - It can be a free-running counter or a counter with initial and final value
 - The counting can be up or up-down
- Each channel can be configured for input capture, output compare, or edge-aligned PWM mode
- In Input Capture mode:

- The capture can occur on rising edges, falling edges or both edges
- An input filter can be selected for some channels
- In Output Compare mode the output signal can be set, cleared, or toggled on match
- All channels can be configured for center-aligned PWM mode
- Each pair of channels can be combined to generate a PWM signal with independent control of both edges of PWM signal
- The FTM channels can operate as pairs with equal outputs, pairs with complementary outputs, or independent channels with independent outputs
- The deadtime insertion is available for each complementary pair
- Generation of match triggers
- Software control of PWM outputs
- Up to 4 fault inputs for global fault control
- The polarity of each channel is configurable
- The generation of an interrupt per channel
- The generation of an interrupt when the counter overflows
- The generation of an interrupt when the fault condition is detected
- Synchronized loading of write buffered FTM registers
- Write protection for critical registers
- Backwards compatible with TPM
- Testing of input captures for a stuck at zero and one conditions
- Dual edge capture for pulse and period width measurement

26.1.3 Modes of operation

When the MCU is in an active Debug mode, the FTM temporarily suspends all counting until the MCU returns to normal user operating mode. During Stop mode, all FTM input clocks are stopped, so the FTM is effectively disabled until clocks resume. During Wait mode, the FTM continues to operate normally. If the FTM does not need to produce a

real time reference or provide the interrupt sources needed to wake the MCU from Wait mode, the power can then be saved by disabling FTM functions before entering Wait mode.

26.1.4 Block diagram

The FTM uses one input/output (I/O) pin per channel, CHn (FTM channel (n)) where n is the channel number (0–7).

The following figure shows the FTM structure. The central component of the FTM is the 16-bit counter with programmable initial and final values and its counting can be up or up-down.

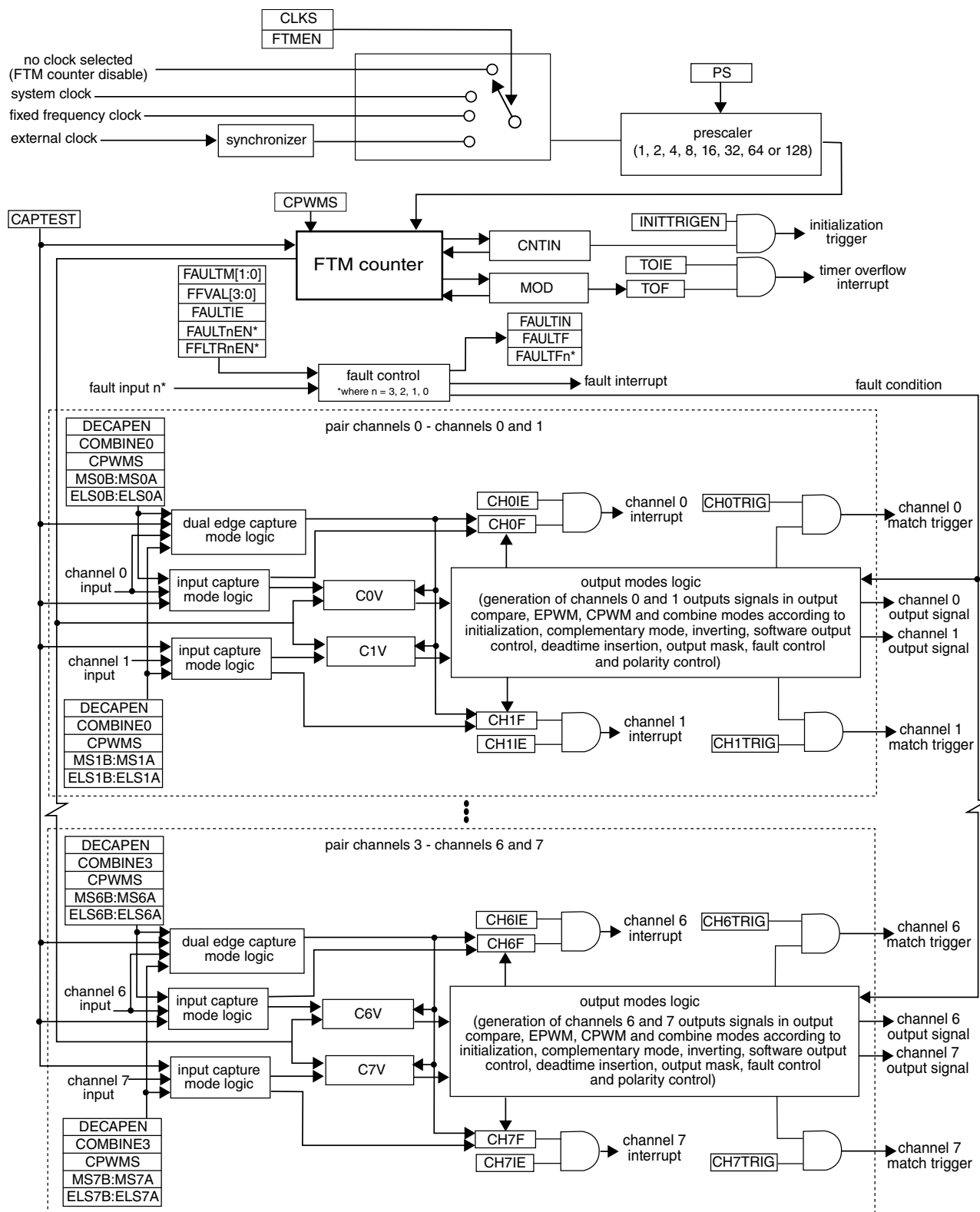


Figure 26-1. FTM block diagram

26.2 FTM signal descriptions

Table 26-1 shows the user-accessible signals for the FTM.

Table 26-1. FTM signal descriptions

| Signal | Description | I/O | Function |
|--------|--|-----|---|
| EXTCLK | External clock. FTM external clock can be selected to drive the FTM counter. | I | The external clock input signal is used as the FTM counter clock if selected by CLKS[1:0] bits in the SC register. This clock signal must not exceed 1/4 of system clock frequency. The FTM counter prescaler selection and settings are also used when an external clock is selected. |
| CHn | FTM channel (n), where n can be 7-0 | I/O | Each FTM channel can be configured to operate either as input or output. The direction associated with each channel, input or output, is selected according to the mode assigned for that channel. |
| FAULTj | Fault input (j), where j can be 3-0 | I | The fault input signals are used to control the CHn channel output state. If a fault is detected, the FAULTj signal is asserted and the channel output is put in a safe state. The behavior of the fault logic is defined by the FAULTM[1:0] control bits in the MODE register and FAULTEN bit in the COMBINEm register. Note that each FAULTj input may affect all channels selectively since FAULTM[1:0] and FAULTEN control bits are defined for each pair of channels. Because there are several FAULTj inputs, maximum of 4 for the FTM module, each one of these inputs is activated by the FAULTJEN bit in the FLTCTRL register. |

26.3 Memory map and register definition

26.3.1 Memory map

This section presents a high-level summary of the FTM registers and how they are mapped.

The registers and bits of an unavailable function in the FTM remain in the memory map and in the reset value, but they have no active function.

Note

Do not write in the region from the CNTIN register through the PWMLOAD register when FTMEN = 0.

26.3.2 Register descriptions

Accesses to reserved addresses result in transfer errors. Registers for absent channels are considered reserved.

FTM memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|-----------------------------|
| 4003_8000 | Status And Control (FTM0_SC) | 32 | R/W | 0000_0000h | 26.3.3/376 |
| 4003_8004 | Counter (FTM0_CNT) | 32 | R/W | 0000_0000h | 26.3.4/378 |
| 4003_8008 | Modulo (FTM0_MOD) | 32 | R/W | 0000_0000h | 26.3.5/378 |
| 4003_800C | Channel (n) Status And Control (FTM0_C0SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8010 | Channel (n) Value (FTM0_C0V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_8014 | Channel (n) Status And Control (FTM0_C1SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8018 | Channel (n) Value (FTM0_C1V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_801C | Channel (n) Status And Control (FTM0_C2SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8020 | Channel (n) Value (FTM0_C2V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_8024 | Channel (n) Status And Control (FTM0_C3SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8028 | Channel (n) Value (FTM0_C3V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_802C | Channel (n) Status And Control (FTM0_C4SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8030 | Channel (n) Value (FTM0_C4V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_8034 | Channel (n) Status And Control (FTM0_C5SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8038 | Channel (n) Value (FTM0_C5V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_803C | Channel (n) Status And Control (FTM0_C6SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8040 | Channel (n) Value (FTM0_C6V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_8044 | Channel (n) Status And Control (FTM0_C7SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_8048 | Channel (n) Value (FTM0_C7V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_804C | Counter Initial Value (FTM0_CNTIN) | 32 | R/W | 0000_0000h | 26.3.8/382 |
| 4003_8050 | Capture And Compare Status (FTM0_STATUS) | 32 | R/W | 0000_0000h | 26.3.9/383 |
| 4003_8054 | Features Mode Selection (FTM0_MODE) | 32 | R/W | 0000_0004h | 26.3.10/385 |
| 4003_8058 | Synchronization (FTM0_SYNC) | 32 | R/W | 0000_0000h | 26.3.11/386 |
| 4003_805C | Initial State For Channels Output (FTM0_OUTINIT) | 32 | R/W | 0000_0000h | 26.3.12/389 |
| 4003_8060 | Output Mask (FTM0_OUTMASK) | 32 | R/W | 0000_0000h | 26.3.13/390 |
| 4003_8064 | Function For Linked Channels (FTM0_COMBINE) | 32 | R/W | 0000_0000h | 26.3.14/392 |
| 4003_8068 | Deadtime Insertion Control (FTM0_DEADTIME) | 32 | R/W | 0000_0000h | 26.3.15/397 |
| 4003_806C | FTM External Trigger (FTM0_EXTTRIG) | 32 | R/W | 0000_0000h | 26.3.16/398 |
| 4003_8070 | Channels Polarity (FTM0_POL) | 32 | R/W | 0000_0000h | 26.3.17/400 |
| 4003_8074 | Fault Mode Status (FTM0_FMS) | 32 | R/W | 0000_0000h | 26.3.18/402 |
| 4003_8078 | Input Capture Filter Control (FTM0_FILTER) | 32 | R/W | 0000_0000h | 26.3.19/404 |
| 4003_807C | Fault Control (FTM0_FLTCTRL) | 32 | R/W | 0000_0000h | 26.3.20/405 |
| 4003_8084 | Configuration (FTM0_CONF) | 32 | R/W | 0000_0000h | 26.3.21/407 |
| 4003_8088 | FTM Fault Input Polarity (FTM0_FLTPOL) | 32 | R/W | 0000_0000h | 26.3.22/408 |

Table continues on the next page...

FTM memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|-----------------------------|
| 4003_808C | Synchronization Configuration (FTM0_SYNCONF) | 32 | R/W | 0000_0000h | 26.3.23/410 |
| 4003_8090 | FTM Inverting Control (FTM0_INVCTRL) | 32 | R/W | 0000_0000h | 26.3.24/412 |
| 4003_8094 | FTM Software Output Control (FTM0_SWOCTRL) | 32 | R/W | 0000_0000h | 26.3.25/413 |
| 4003_8098 | FTM PWM Load (FTM0_PWMLOAD) | 32 | R/W | 0000_0000h | 26.3.26/415 |
| 4003_9000 | Status And Control (FTM1_SC) | 32 | R/W | 0000_0000h | 26.3.3/376 |
| 4003_9004 | Counter (FTM1_CNT) | 32 | R/W | 0000_0000h | 26.3.4/378 |
| 4003_9008 | Modulo (FTM1_MOD) | 32 | R/W | 0000_0000h | 26.3.5/378 |
| 4003_900C | Channel (n) Status And Control (FTM1_C0SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9010 | Channel (n) Value (FTM1_C0V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_9014 | Channel (n) Status And Control (FTM1_C1SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9018 | Channel (n) Value (FTM1_C1V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_901C | Channel (n) Status And Control (FTM1_C2SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9020 | Channel (n) Value (FTM1_C2V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_9024 | Channel (n) Status And Control (FTM1_C3SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9028 | Channel (n) Value (FTM1_C3V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_902C | Channel (n) Status And Control (FTM1_C4SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9030 | Channel (n) Value (FTM1_C4V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_9034 | Channel (n) Status And Control (FTM1_C5SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9038 | Channel (n) Value (FTM1_C5V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_903C | Channel (n) Status And Control (FTM1_C6SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9040 | Channel (n) Value (FTM1_C6V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_9044 | Channel (n) Status And Control (FTM1_C7SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_9048 | Channel (n) Value (FTM1_C7V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_904C | Counter Initial Value (FTM1_CNTIN) | 32 | R/W | 0000_0000h | 26.3.8/382 |
| 4003_9050 | Capture And Compare Status (FTM1_STATUS) | 32 | R/W | 0000_0000h | 26.3.9/383 |
| 4003_9054 | Features Mode Selection (FTM1_MODE) | 32 | R/W | 0000_0004h | 26.3.10/385 |
| 4003_9058 | Synchronization (FTM1_SYNC) | 32 | R/W | 0000_0000h | 26.3.11/386 |
| 4003_905C | Initial State For Channels Output (FTM1_OUTINIT) | 32 | R/W | 0000_0000h | 26.3.12/389 |
| 4003_9060 | Output Mask (FTM1_OUTMASK) | 32 | R/W | 0000_0000h | 26.3.13/390 |
| 4003_9064 | Function For Linked Channels (FTM1_COMBINE) | 32 | R/W | 0000_0000h | 26.3.14/392 |
| 4003_9068 | Deadtime Insertion Control (FTM1_DEADTIME) | 32 | R/W | 0000_0000h | 26.3.15/397 |
| 4003_906C | FTM External Trigger (FTM1_EXTTRIG) | 32 | R/W | 0000_0000h | 26.3.16/398 |
| 4003_9070 | Channels Polarity (FTM1_POL) | 32 | R/W | 0000_0000h | 26.3.17/400 |
| 4003_9074 | Fault Mode Status (FTM1_FMS) | 32 | R/W | 0000_0000h | 26.3.18/402 |
| 4003_9078 | Input Capture Filter Control (FTM1_FILTER) | 32 | R/W | 0000_0000h | 26.3.19/404 |
| 4003_907C | Fault Control (FTM1_FLTCTRL) | 32 | R/W | 0000_0000h | 26.3.20/405 |
| 4003_9084 | Configuration (FTM1_CONF) | 32 | R/W | 0000_0000h | 26.3.21/407 |
| 4003_9088 | FTM Fault Input Polarity (FTM1_FLTPOL) | 32 | R/W | 0000_0000h | 26.3.22/408 |

Table continues on the next page...

FTM memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|-----------------------------|
| 4003_908C | Synchronization Configuration (FTM1_SYNCONF) | 32 | R/W | 0000_0000h | 26.3.23/410 |
| 4003_9090 | FTM Inverting Control (FTM1_INVCTRL) | 32 | R/W | 0000_0000h | 26.3.24/412 |
| 4003_9094 | FTM Software Output Control (FTM1_SWOCTRL) | 32 | R/W | 0000_0000h | 26.3.25/413 |
| 4003_9098 | FTM PWM Load (FTM1_PWMLOAD) | 32 | R/W | 0000_0000h | 26.3.26/415 |
| 4003_A000 | Status And Control (FTM2_SC) | 32 | R/W | 0000_0000h | 26.3.3/376 |
| 4003_A004 | Counter (FTM2_CNT) | 32 | R/W | 0000_0000h | 26.3.4/378 |
| 4003_A008 | Modulo (FTM2_MOD) | 32 | R/W | 0000_0000h | 26.3.5/378 |
| 4003_A00C | Channel (n) Status And Control (FTM2_C0SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A010 | Channel (n) Value (FTM2_C0V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A014 | Channel (n) Status And Control (FTM2_C1SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A018 | Channel (n) Value (FTM2_C1V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A01C | Channel (n) Status And Control (FTM2_C2SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A020 | Channel (n) Value (FTM2_C2V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A024 | Channel (n) Status And Control (FTM2_C3SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A028 | Channel (n) Value (FTM2_C3V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A02C | Channel (n) Status And Control (FTM2_C4SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A030 | Channel (n) Value (FTM2_C4V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A034 | Channel (n) Status And Control (FTM2_C5SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A038 | Channel (n) Value (FTM2_C5V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A03C | Channel (n) Status And Control (FTM2_C6SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A040 | Channel (n) Value (FTM2_C6V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A044 | Channel (n) Status And Control (FTM2_C7SC) | 32 | R/W | 0000_0000h | 26.3.6/379 |
| 4003_A048 | Channel (n) Value (FTM2_C7V) | 32 | R/W | 0000_0000h | 26.3.7/381 |
| 4003_A04C | Counter Initial Value (FTM2_CNTIN) | 32 | R/W | 0000_0000h | 26.3.8/382 |
| 4003_A050 | Capture And Compare Status (FTM2_STATUS) | 32 | R/W | 0000_0000h | 26.3.9/383 |
| 4003_A054 | Features Mode Selection (FTM2_MODE) | 32 | R/W | 0000_0004h | 26.3.10/385 |
| 4003_A058 | Synchronization (FTM2_SYNC) | 32 | R/W | 0000_0000h | 26.3.11/386 |
| 4003_A05C | Initial State For Channels Output (FTM2_OUTINIT) | 32 | R/W | 0000_0000h | 26.3.12/389 |
| 4003_A060 | Output Mask (FTM2_OUTMASK) | 32 | R/W | 0000_0000h | 26.3.13/390 |
| 4003_A064 | Function For Linked Channels (FTM2_COMBINE) | 32 | R/W | 0000_0000h | 26.3.14/392 |
| 4003_A068 | Deadtime Insertion Control (FTM2_DEADTIME) | 32 | R/W | 0000_0000h | 26.3.15/397 |
| 4003_A06C | FTM External Trigger (FTM2_EXTTRIG) | 32 | R/W | 0000_0000h | 26.3.16/398 |
| 4003_A070 | Channels Polarity (FTM2_POL) | 32 | R/W | 0000_0000h | 26.3.17/400 |
| 4003_A074 | Fault Mode Status (FTM2_FMS) | 32 | R/W | 0000_0000h | 26.3.18/402 |
| 4003_A078 | Input Capture Filter Control (FTM2_FILTER) | 32 | R/W | 0000_0000h | 26.3.19/404 |
| 4003_A07C | Fault Control (FTM2_FLTCTRL) | 32 | R/W | 0000_0000h | 26.3.20/405 |
| 4003_A084 | Configuration (FTM2_CONF) | 32 | R/W | 0000_0000h | 26.3.21/407 |
| 4003_A088 | FTM Fault Input Polarity (FTM2_FLTPOL) | 32 | R/W | 0000_0000h | 26.3.22/408 |

Table continues on the next page...

FTM memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|--------|-------------|-----------------------------|
| 4003_A08C | Synchronization Configuration (FTM2_SYNCONF) | 32 | R/W | 0000_0000h | 26.3.23/410 |
| 4003_A090 | FTM Inverting Control (FTM2_INVCTRL) | 32 | R/W | 0000_0000h | 26.3.24/412 |
| 4003_A094 | FTM Software Output Control (FTM2_SWOCTRL) | 32 | R/W | 0000_0000h | 26.3.25/413 |
| 4003_A098 | FTM PWM Load (FTM2_PWMLOAD) | 32 | R/W | 0000_0000h | 26.3.26/415 |

26.3.3 Status And Control (FTMx_SC)

SC contains the overflow status flag and control bits used to configure the interrupt enable, FTM configuration, clock source, and prescaler factor. These controls relate to all channels within this module.

Address: Base address + 0h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|-----|------|----|-------|----|------|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | TOF | TOIE | | CPWMS | | CLKS | | PS |
| W | | | | | | | | | 0 | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_SC field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 TOF | <p>Timer Overflow Flag</p> <p>Set by hardware when the FTM counter passes the value in the MOD register. The TOF bit is cleared by reading the SC register while TOF is set and then writing a 0 to TOF bit. Writing a 1 to TOF has no effect.</p> <p>If another FTM overflow occurs between the read and write operations, the write operation has no effect; therefore, TOF remains set indicating an overflow has occurred. In this case, a TOF interrupt request is not lost due to the clearing sequence for a previous TOF.</p> <p>0 FTM counter has not overflowed. 1 FTM counter has overflowed.</p> |
| 6 TOIE | <p>Timer Overflow Interrupt Enable</p> <p>Enables FTM overflow interrupts.</p> <p>0 Disable TOF interrupts. Use software polling. 1 Enable TOF interrupts. An interrupt is generated when TOF equals one.</p> |
| 5 CPWMS | <p>Center-Aligned PWM Select</p> <p>Selects CPWM mode. This mode configures the FTM to operate in Up-Down Counting mode.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 FTM counter operates in Up Counting mode. 1 FTM counter operates in Up-Down Counting mode.</p> |
| 4–3 CLKS | <p>Clock Source Selection</p> <p>Selects one of the three FTM counter clock sources.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>00 No clock selected. This in effect disables the FTM counter. 01 System clock 10 Fixed frequency clock 11 External clock</p> |
| PS | <p>Prescale Factor Selection</p> <p>Selects one of 8 division factors for the clock source selected by CLKS. The new prescaler factor affects the clock source on the next system clock cycle after the new value is updated into the register bits.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>000 Divide by 1 001 Divide by 2 010 Divide by 4 011 Divide by 8 100 Divide by 16 101 Divide by 32 110 Divide by 64 111 Divide by 128</p> |

26.3.4 Counter (FTMx_CNT)

The CNT register contains the FTM counter value.

Reset clears the CNT register. Writing any value to COUNT updates the counter with its initial value, CNTIN.

When Debug is active, the FTM counter is frozen. This is the value that you may read.

Address: Base address + 4h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | COUNT | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_CNT field descriptions

| Field | Description |
|-------------------|---|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| COUNT | Counter Value |

26.3.5 Modulo (FTMx_MOD)

The Modulo register contains the modulo value for the FTM counter. After the FTM counter reaches the modulo value, the overflow flag (TOF) becomes set at the next clock, and the next value of FTM counter depends on the selected counting method; see [Counter](#).

Writing to the MOD register latches the value into a buffer. The MOD register is updated with the value of its write buffer according to [Registers updated from write buffers](#).

If FTMEN = 0, this write coherency mechanism may be manually reset by writing to the SC register whether Debug is active or not.

Initialize the FTM counter, by writing to CNT, before writing to the MOD register to avoid confusion about when the first counter overflow will occur.

Address: Base address + 8h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | Reserved | | | | | | | | | | | | | | | | MOD | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_MOD field descriptions

| Field | Description |
|-------------------|-------------------------|
| 31–16 Reserved | This field is reserved. |
| MOD | Modulo Value |

26.3.6 Channel (n) Status And Control (FTMx_CnSC)

CnSC contains the channel-interrupt-status flag and control bits used to configure the interrupt enable, channel configuration, and pin function.

Table 26-69. Mode, edge, and level selection

| DECAPEN | COMBINE | CPWMS | MSnB:MSnA | ELSnB:ELSnA | Mode | Configuration |
|---------|---------|-------|-----------|-------------|--|---|
| X | X | X | XX | 00 | Pin not used for FTM—revert the channel pin to general purpose I/O or other peripheral control | |
| 0 | 0 | 0 | 00 | 01 | Input Capture | Capture on Rising Edge Only |
| | | | | 10 | | Capture on Falling Edge Only |
| | | | | 11 | | Capture on Rising or Falling Edge |
| | | | 01 | 01 | Output Compare | Toggle Output on match |
| | | | | 10 | | Clear Output on match |
| | | | | 11 | | Set Output on match |
| | | | 1X | 10 | Edge-Aligned PWM | High-true pulses (clear Output on match) |
| | | | | X1 | | Low-true pulses (set Output on match) |
| | | 1 | XX | 10 | Center-Aligned PWM | High-true pulses (clear Output on match-up) |
| | | | | X1 | | Low-true pulses (set Output on match-up) |

Table continues on the next page...

Table 26-69. Mode, edge, and level selection (continued)

| DECAPEN | COMBINE | CPWMS | MSnB:MSnA | ELSnB:ELSnA | Mode | Configuration |
|---------|---------|-------|-----------|---------------------------------------|-------------------|---|
| | 1 | 0 | XX | 10 | Combine PWM | High-true pulses (set on channel (n) match, and clear on channel (n+1) match) |
| | | | | X1 | | Low-true pulses (clear on channel (n) match, and set on channel (n+1) match) |
| 1 | 0 | 0 | X0 | See the following table (Table 26-8). | Dual Edge Capture | One-Shot Capture mode |
| | | | X1 | | | Continuous Capture mode |

Table 26-70. Dual Edge Capture mode — edge polarity selection

| ELSnB | ELSnA | Channel Port Enable | Detected Edges |
|-------|-------|---------------------|--------------------------|
| 0 | 0 | Disabled | No edge |
| 0 | 1 | Enabled | Rising edge |
| 1 | 0 | Enabled | Falling edge |
| 1 | 1 | Enabled | Rising and falling edges |

Address: Base address + Ch offset + (8d × i), where i=0d to 7d

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|-----|------|-----|-----|------|------|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | CHF | CHIE | MSB | MSA | ELSB | ELSA | 0 | 0 |
| W | | | | | | | | | 0 | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_CnSC field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 CHF | Channel Flag Set by hardware when an event occurs on the channel. CHF is cleared by reading the CSC register while CHnF is set and then writing a 0 to the CHF bit. Writing a 1 to CHF has no effect. |

Table continues on the next page...

FTMx_CnSC field descriptions (continued)

| Field | Description |
|---------------|---|
| | <p>If another event occurs between the read and write operations, the write operation has no effect; therefore, CHF remains set indicating an event has occurred. In this case a CHF interrupt request is not lost due to the clearing sequence for a previous CHF.</p> <p>0 No channel event has occurred. 1 A channel event has occurred.</p> |
| 6 CHIE | <p>Channel Interrupt Enable</p> <p>Enables channel interrupts.</p> <p>0 Disable channel interrupts. Use software polling. 1 Enable channel interrupts.</p> |
| 5 MSB | <p>Channel Mode Select</p> <p>Used for further selections in the channel logic. Its functionality is dependent on the channel mode. See Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> |
| 4 MSA | <p>Channel Mode Select</p> <p>Used for further selections in the channel logic. Its functionality is dependent on the channel mode. See Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> |
| 3 ELSB | <p>Edge or Level Select</p> <p>The functionality of ELSB and ELSA depends on the channel mode. See Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> |
| 2 ELSA | <p>Edge or Level Select</p> <p>The functionality of ELSB and ELSA depends on the channel mode. See Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> |
| 1 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |
| 0 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |

26.3.7 Channel (n) Value (FTMx_CnV)

These registers contain the captured FTM counter value for the input modes or the match value for the output modes.

In Input Capture, Capture Test, and Dual Edge Capture modes, any write to a CnV register is ignored.

In output modes, writing to a CnV register latches the value into a buffer. A CnV register is updated with the value of its write buffer according to [Registers updated from write buffers](#).

Memory map and register definition

If FTMEN = 0, this write coherency mechanism may be manually reset by writing to the CnSC register whether Debug mode is active or not.

Address: Base address + 10h offset + (8d × i), where i=0d to 7d

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | 0 | | | | | | | | | | | | | | | | VAL | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_CnV field descriptions

| Field | Description |
|-------------------|--|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| VAL | Channel Value Captured FTM counter value of the input modes or the match value for the output modes |

26.3.8 Counter Initial Value (FTMx_CNTIN)

The Counter Initial Value register contains the initial value for the FTM counter.

Writing to the CNTIN register latches the value into a buffer. The CNTIN register is updated with the value of its write buffer according to [Registers updated from write buffers](#).

When the FTM clock is initially selected, by writing a non-zero value to the CLKS bits, the FTM counter starts with the value 0x0000. To avoid this behavior, before the first write to select the FTM clock, write the new value to the the CNTIN register and then initialize the FTM counter by writing any value to the CNT register.

Address: Base address + 4Ch offset

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | Reserved | | | | | | | | | | | | | | | | INIT | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_CNTIN field descriptions

| Field | Description |
|-------------------|----------------------------------|
| 31–16 Reserved | This field is reserved. |
| INIT | Initial Value Of The FTM Counter |

26.3.9 Capture And Compare Status (FTMx_STATUS)

The STATUS register contains a copy of the status flag CHnF bit in CnSC for each FTM channel for software convenience.

Each CHnF bit in STATUS is a mirror of CHnF bit in CnSC. All CHnF bits can be checked using only one read of STATUS. All CHnF bits can be cleared by reading STATUS followed by writing 0x00 to STATUS.

Hardware sets the individual channel flags when an event occurs on the channel. CHnF is cleared by reading STATUS while CHnF is set and then writing a 0 to the CHnF bit. Writing a 1 to CHnF has no effect.

If another event occurs between the read and write operations, the write operation has no effect; therefore, CHnF remains set indicating an event has occurred. In this case, a CHnF interrupt request is not lost due to the clearing sequence for a previous CHnF.

Address: Base address + 50h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|------|------|------|------|------|------|------|------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | CH7F | CH6F | CH5F | CH4F | CH3F | CH2F | CH1F | CH0F |
| W | | | | | | | | | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_STATUS field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

Table continues on the next page...

FTMx_STATUS field descriptions (continued)

| Field | Description |
|-----------|--|
| 7 CH7F | Channel 7 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 6 CH6F | Channel 6 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 5 CH5F | Channel 5 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 4 CH4F | Channel 4 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 3 CH3F | Channel 3 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 2 CH2F | Channel 2 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 1 CH1F | Channel 1 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |
| 0 CH0F | Channel 0 Flag See the register description. 0 No channel event has occurred. 1 A channel event has occurred. |

26.3.10 Features Mode Selection (FTMx_MODE)

This register contains the global enable bit for FTM-specific features and the control bits used to configure:

- Fault control mode and interrupt
- Capture Test mode
- PWM synchronization
- Write protection
- Channel output initialization

These controls relate to all channels within this module.

Address: Base address + 54h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|---------|--------|----|---------|---------|-------|------|-------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | FAULTIE | FAULTM | | CAPTEST | PWMSYNC | WPDIS | INIT | FTMEN |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

FTMx_MODE field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 FAULTIE | Fault Interrupt Enable Enables the generation of an interrupt when a fault is detected by FTM and the FTM fault control is enabled. 0 Fault control interrupt is disabled. 1 Fault control interrupt is enabled. |
| 6–5 FAULTM | Fault Control Mode Defines the FTM fault control mode. This field is write protected. It can be written only when MODE[WPDIS] = 1. 00 Fault control is disabled for all channels. 01 Fault control is enabled for even channels only (channels 0, 2, 4, and 6), and the selected mode is the manual fault clearing. |

Table continues on the next page...

FTMx_MODE field descriptions (continued)

| Field | Description |
|--------------|--|
| | <p>10 Fault control is enabled for all channels, and the selected mode is the manual fault clearing.</p> <p>11 Fault control is enabled for all channels, and the selected mode is the automatic fault clearing.</p> |
| 4 CAPTEST | <p>Capture Test Mode Enable</p> <p>Enables the capture test mode.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Capture test mode is disabled.</p> <p>1 Capture test mode is enabled.</p> |
| 3 PWMSYNC | <p>PWM Synchronization Mode</p> <p>Selects which triggers can be used by MOD, CnV, OUTMASK, and FTM counter synchronization. See PWM synchronization. The PWMSYNC bit configures the synchronization when SYNCMODE is 0.</p> <p>0 No restrictions. Software and hardware triggers can be used by MOD, CnV, OUTMASK, and FTM counter synchronization.</p> <p>1 Software trigger can only be used by MOD and CnV synchronization, and hardware triggers can only be used by OUTMASK and FTM counter synchronization.</p> |
| 2 WPDIS | <p>Write Protection Disable</p> <p>When write protection is enabled (WPDIS = 0), write protected bits cannot be written. When write protection is disabled (WPDIS = 1), write protected bits can be written. The WPDIS bit is the negation of the WPEN bit. WPDIS is cleared when 1 is written to WPEN. WPDIS is set when WPEN bit is read as a 1 and then 1 is written to WPDIS. Writing 0 to WPDIS has no effect.</p> <p>0 Write protection is enabled.</p> <p>1 Write protection is disabled.</p> |
| 1 INIT | <p>Initialize The Channels Output</p> <p>When a 1 is written to INIT bit the channels output is initialized according to the state of their corresponding bit in the OUTINIT register. Writing a 0 to INIT bit has no effect.</p> <p>The INIT bit is always read as 0.</p> |
| 0 FTMEN | <p>FTM Enable</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 TPM compatibility. Free running counter and synchronization compatible with TPM.</p> <p>1 Free running counter and synchronization are different from TPM behavior.</p> |

26.3.11 Synchronization (FTMx_SYNC)

This register configures the PWM synchronization.

A synchronization event can perform the synchronized update of MOD, CV, and OUTMASK registers with the value of their write buffer and the FTM counter initialization.

NOTE

The software trigger, SWSYNC bit, and hardware triggers TRIG0, TRIG1, and TRIG2 bits have a potential conflict if used together when SYNCMODE = 0. Use only hardware or software triggers but not both at the same time, otherwise unpredictable behavior is likely to happen.

The selection of the loading point, CNTMAX and CNTMIN bits, is intended to provide the update of MOD, CNTIN, and CnV registers across all enabled channels simultaneously. The use of the loading point selection together with SYNCMODE = 0 and hardware trigger selection, TRIG0, TRIG1, or TRIG2 bits, is likely to result in unpredictable behavior.

The synchronization event selection also depends on the PWMSYNC (MODE register) and SYNCMODE (SYNCONF register) bits. See [PWM synchronization](#).

Address: Base address + 58h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|--------|-------|-------|-------|---------|--------|--------|--------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | SWSYNC | TRIG2 | TRIG1 | TRIG0 | SYNCHOM | REINIT | CNTMAX | CNTMIN |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_SYNC field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 SWSYNC | PWM Synchronization Software Trigger Selects the software trigger as the PWM synchronization trigger. The software trigger happens when a 1 is written to SWSYNC bit. 0 Software trigger is not selected. 1 Software trigger is selected. |
| 6 TRIG2 | PWM Synchronization Hardware Trigger 2 |

Table continues on the next page...

FTMx_SYNC field descriptions (continued)

| Field | Description |
|--------------|---|
| | <p>Enables hardware trigger 2 to the PWM synchronization. Hardware trigger 2 happens when a rising edge is detected at the trigger 2 input signal.</p> <p>0 Trigger is disabled. 1 Trigger is enabled.</p> |
| 5 TRIG1 | <p>PWM Synchronization Hardware Trigger 1</p> <p>Enables hardware trigger 1 to the PWM synchronization. Hardware trigger 1 happens when a rising edge is detected at the trigger 1 input signal.</p> <p>0 Trigger is disabled. 1 Trigger is enabled.</p> |
| 4 TRIG0 | <p>PWM Synchronization Hardware Trigger 0</p> <p>Enables hardware trigger 0 to the PWM synchronization. Hardware trigger 0 occurs when a rising edge is detected at the trigger 0 input signal.</p> <p>0 Trigger is disabled. 1 Trigger is enabled.</p> |
| 3 SYNCHOM | <p>Output Mask Synchronization</p> <p>Selects when the OUTMASK register is updated with the value of its buffer.</p> <p>0 OUTMASK register is updated with the value of its buffer in all rising edges of the system clock. 1 OUTMASK register is updated with the value of its buffer only by the PWM synchronization.</p> |
| 2 REINIT | <p>FTM Counter Reinitialization By Synchronization (FTM counter synchronization)</p> <p>Determines if the FTM counter is reinitialized when the selected trigger for the synchronization is detected. The REINIT bit configures the synchronization when SYNCMODE is zero.</p> <p>0 FTM counter continues to count normally. 1 FTM counter is updated with its initial value when the selected trigger is detected.</p> |
| 1 CNTMAX | <p>Maximum Loading Point Enable</p> <p>Selects the maximum loading point to PWM synchronization. See Boundary cycle and loading points. If CNTMAX is 1, the selected loading point is when the FTM counter reaches its maximum value (MOD register).</p> <p>0 The maximum loading point is disabled. 1 The maximum loading point is enabled.</p> |
| 0 CNTMIN | <p>Minimum Loading Point Enable</p> <p>Selects the minimum loading point to PWM synchronization. See Boundary cycle and loading points. If CNTMIN is one, the selected loading point is when the FTM counter reaches its minimum value (CNTIN register).</p> <p>0 The minimum loading point is disabled. 1 The minimum loading point is enabled.</p> |

26.3.12 Initial State For Channels Output (FTMx_OUTINIT)

Address: Base address + 5Ch offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | CH7OI | CH6OI | CH5OI | CH4OI | CH3OI | CH2OI | CH1OI | CH0OI |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_OUTINIT field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 CH7OI | Channel 7 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |
| 6 CH6OI | Channel 6 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |
| 5 CH5OI | Channel 5 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |
| 4 CH4OI | Channel 4 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |
| 3 CH3OI | Channel 3 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. |

Table continues on the next page...

FTMx_OUTINIT field descriptions (continued)

| Field | Description |
|------------|---|
| | 0 The initialization value is 0. 1 The initialization value is 1. |
| 2 CH2OI | Channel 2 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |
| 1 CH1OI | Channel 1 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |
| 0 CH0OI | Channel 0 Output Initialization Value Selects the value that is forced into the channel output when the initialization occurs. 0 The initialization value is 0. 1 The initialization value is 1. |

26.3.13 Output Mask (FTMx_OUTMASK)

This register provides a mask for each FTM channel. The mask of a channel determines if its output responds, that is, it is masked or not, when a match occurs. This feature is used for BLDC control where the PWM signal is presented to an electric motor at specific times to provide electronic commutation.

Any write to the OUTMASK register, stores the value in its write buffer. The register is updated with the value of its write buffer according to [PWM synchronization](#).

Address: Base address + 60h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | CH7OM | CH6OM | CH5OM | CH4OM | CH3OM | CH2OM | CH1OM | CH0OM |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_OUTMASK field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 CH7OM | Channel 7 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 6 CH6OM | Channel 6 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 5 CH5OM | Channel 5 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 4 CH4OM | Channel 4 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 3 CH3OM | Channel 3 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 2 CH2OM | Channel 2 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 1 CH1OM | Channel 1 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |
| 0 CH0OM | Channel 0 Output Mask Defines if the channel output is masked or unmasked. 0 Channel output is not masked. It continues to operate normally. 1 Channel output is masked. It is forced to its inactive state. |

26.3.14 Function For Linked Channels (FTMx_COMBINE)

This register contains the control bits used to configure the fault control, synchronization, deadtime insertion, Dual Edge Capture mode, Complementary, and Combine mode for each pair of channels (n) and (n+1), where n equals 0, 2, 4, and 6.

Address: Base address + 64h offset

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-------|----|----------|---------|-------|--------|----------|-------|----------|----|----------|---------|-------|--------|----------|-------|----------|
| R | 0 | FAULTEN3 | SYNCEN3 | DTEN3 | DECAP3 | DECAPEN3 | COMP3 | COMBINE3 | 0 | FAULTEN2 | SYNCEN2 | DTEN2 | DECAP2 | DECAPEN2 | COMP2 | COMBINE2 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----------|---------|-------|--------|----------|-------|----------|---|----------|---------|-------|--------|----------|-------|----------|
| R | 0 | FAULTEN1 | SYNCEN1 | DTEN1 | DECAP1 | DECAPEN1 | COMP1 | COMBINE1 | 0 | FAULTEN0 | SYNCEN0 | DTEN0 | DECAP0 | DECAPEN0 | COMP0 | COMBINE0 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_COMBINE field descriptions

| Field | Description |
|----------------|--|
| 31 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 30 FAULTEN3 | Fault Control Enable For n = 6 Enables the fault control in channels (n) and (n+1). This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The fault control in this pair of channels is disabled. 1 The fault control in this pair of channels is enabled. |
| 29 SYNCEN3 | Synchronization Enable For n = 6 Enables PWM synchronization of registers C(n)V and C(n+1)V. 0 The PWM synchronization in this pair of channels is disabled. 1 The PWM synchronization in this pair of channels is enabled. |
| 28 DTEN3 | Deadtime Enable For n = 6 Enables the deadtime insertion in the channels (n) and (n+1). This field is write protected. It can be written only when MODE[WPDIS] = 1. |

Table continues on the next page...

FTMx_COMBINE field descriptions (continued)

| Field | Description |
|----------------|---|
| | <p>0 The deadtime insertion in this pair of channels is disabled.</p> <p>1 The deadtime insertion in this pair of channels is enabled.</p> |
| 27 DECAP3 | <p>Dual Edge Capture Mode Captures For n = 6</p> <p>Enables the capture of the FTM counter value according to the channel (n) input event and the configuration of the dual edge capture bits.</p> <p>This field applies only when DECAPEN = 1.</p> <p>DECAP bit is cleared automatically by hardware if dual edge capture – one-shot mode is selected and when the capture of channel (n+1) event is made.</p> <p>0 The dual edge captures are inactive.</p> <p>1 The dual edge captures are active.</p> |
| 26 DECAPEN3 | <p>Dual Edge Capture Mode Enable For n = 6</p> <p>Enables the Dual Edge Capture mode in the channels (n) and (n+1). This bit reconfigures the function of MSnA, ELSnB:ELSnA and ELS(n+1)B:ELS(n+1)A bits in Dual Edge Capture mode according to Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The Dual Edge Capture mode in this pair of channels is disabled.</p> <p>1 The Dual Edge Capture mode in this pair of channels is enabled.</p> |
| 25 COMP3 | <p>Complement Of Channel (n) for n = 6</p> <p>Enables Complementary mode for the combined channels. In Complementary mode the channel (n+1) output is the inverse of the channel (n) output.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The channel (n+1) output is the same as the channel (n) output.</p> <p>1 The channel (n+1) output is the complement of the channel (n) output.</p> |
| 24 COMBINE3 | <p>Combine Channels For n = 6</p> <p>Enables the combine feature for channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Channels (n) and (n+1) are independent.</p> <p>1 Channels (n) and (n+1) are combined.</p> |
| 23 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 22 FAULTEN2 | <p>Fault Control Enable For n = 4</p> <p>Enables the fault control in channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The fault control in this pair of channels is disabled.</p> <p>1 The fault control in this pair of channels is enabled.</p> |
| 21 SYNCEN2 | <p>Synchronization Enable For n = 4</p> <p>Enables PWM synchronization of registers C(n)V and C(n+1)V.</p> |

Table continues on the next page...

FTMx_COMBINE field descriptions (continued)

| Field | Description |
|----------------|---|
| | <p>0 The PWM synchronization in this pair of channels is disabled.</p> <p>1 The PWM synchronization in this pair of channels is enabled.</p> |
| 20 DTEN2 | <p>Deadtime Enable For n = 4</p> <p>Enables the deadtime insertion in the channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The deadtime insertion in this pair of channels is disabled.</p> <p>1 The deadtime insertion in this pair of channels is enabled.</p> |
| 19 DECAP2 | <p>Dual Edge Capture Mode Captures For n = 4</p> <p>Enables the capture of the FTM counter value according to the channel (n) input event and the configuration of the dual edge capture bits.</p> <p>This field applies only when DECAPEN = 1.</p> <p>DECAP bit is cleared automatically by hardware if dual edge capture – one-shot mode is selected and when the capture of channel (n+1) event is made.</p> <p>0 The dual edge captures are inactive.</p> <p>1 The dual edge captures are active.</p> |
| 18 DECAPEN2 | <p>Dual Edge Capture Mode Enable For n = 4</p> <p>Enables the Dual Edge Capture mode in the channels (n) and (n+1). This bit reconfigures the function of MSnA, ELSnB:ELSnA and ELS(n+1)B:ELS(n+1)A bits in Dual Edge Capture mode according to Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The Dual Edge Capture mode in this pair of channels is disabled.</p> <p>1 The Dual Edge Capture mode in this pair of channels is enabled.</p> |
| 17 COMP2 | <p>Complement Of Channel (n) For n = 4</p> <p>Enables Complementary mode for the combined channels. In Complementary mode the channel (n+1) output is the inverse of the channel (n) output.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The channel (n+1) output is the same as the channel (n) output.</p> <p>1 The channel (n+1) output is the complement of the channel (n) output.</p> |
| 16 COMBINE2 | <p>Combine Channels For n = 4</p> <p>Enables the combine feature for channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Channels (n) and (n+1) are independent.</p> <p>1 Channels (n) and (n+1) are combined.</p> |
| 15 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 14 FAULTEN1 | <p>Fault Control Enable For n = 2</p> <p>Enables the fault control in channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> |

Table continues on the next page...

FTMx_COMBINE field descriptions (continued)

| Field | Description |
|----------------|---|
| | <p>0 The fault control in this pair of channels is disabled.</p> <p>1 The fault control in this pair of channels is enabled.</p> |
| 13 SYNEN1 | <p>Synchronization Enable For n = 2</p> <p>Enables PWM synchronization of registers C(n)V and C(n+1)V.</p> <p>0 The PWM synchronization in this pair of channels is disabled.</p> <p>1 The PWM synchronization in this pair of channels is enabled.</p> |
| 12 DTEN1 | <p>Deadtime Enable For n = 2</p> <p>Enables the deadtime insertion in the channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The deadtime insertion in this pair of channels is disabled.</p> <p>1 The deadtime insertion in this pair of channels is enabled.</p> |
| 11 DECAP1 | <p>Dual Edge Capture Mode Captures For n = 2</p> <p>Enables the capture of the FTM counter value according to the channel (n) input event and the configuration of the dual edge capture bits.</p> <p>This field applies only when DECAPEN = 1.</p> <p>DECAP bit is cleared automatically by hardware if Dual Edge Capture – One-Shot mode is selected and when the capture of channel (n+1) event is made.</p> <p>0 The dual edge captures are inactive.</p> <p>1 The dual edge captures are active.</p> |
| 10 DECAPEN1 | <p>Dual Edge Capture Mode Enable For n = 2</p> <p>Enables the Dual Edge Capture mode in the channels (n) and (n+1). This bit reconfigures the function of MSnA, ELSnB:ELSnA and ELS(n+1)B:ELS(n+1)A bits in Dual Edge Capture mode according to Table 26-7.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The Dual Edge Capture mode in this pair of channels is disabled.</p> <p>1 The Dual Edge Capture mode in this pair of channels is enabled.</p> |
| 9 COMP1 | <p>Complement Of Channel (n) For n = 2</p> <p>Enables Complementary mode for the combined channels. In Complementary mode the channel (n+1) output is the inverse of the channel (n) output.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 The channel (n+1) output is the same as the channel (n) output.</p> <p>1 The channel (n+1) output is the complement of the channel (n) output.</p> |
| 8 COMBINE1 | <p>Combine Channels For n = 2</p> <p>Enables the combine feature for channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Channels (n) and (n+1) are independent.</p> <p>1 Channels (n) and (n+1) are combined.</p> |

Table continues on the next page...

FTMx_COMBINE field descriptions (continued)

| Field | Description |
|---------------|---|
| 7 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 6 FAULTEN0 | Fault Control Enable For n = 0 Enables the fault control in channels (n) and (n+1). This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The fault control in this pair of channels is disabled. 1 The fault control in this pair of channels is enabled. |
| 5 SYNCEN0 | Synchronization Enable For n = 0 Enables PWM synchronization of registers C(n)V and C(n+1)V. 0 The PWM synchronization in this pair of channels is disabled. 1 The PWM synchronization in this pair of channels is enabled. |
| 4 DTEN0 | Deadtime Enable For n = 0 Enables the deadtime insertion in the channels (n) and (n+1). This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The deadtime insertion in this pair of channels is disabled. 1 The deadtime insertion in this pair of channels is enabled. |
| 3 DECAP0 | Dual Edge Capture Mode Captures For n = 0 Enables the capture of the FTM counter value according to the channel (n) input event and the configuration of the dual edge capture bits. This field applies only when DECAPEN = 1. DECAP bit is cleared automatically by hardware if dual edge capture – one-shot mode is selected and when the capture of channel (n+1) event is made. 0 The dual edge captures are inactive. 1 The dual edge captures are active. |
| 2 DECAPEN0 | Dual Edge Capture Mode Enable For n = 0 Enables the Dual Edge Capture mode in the channels (n) and (n+1). This bit reconfigures the function of MSnA, ELSnB:ELSnA and ELS(n+1)B:ELS(n+1)A bits in Dual Edge Capture mode according to Table 26-7 . This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The Dual Edge Capture mode in this pair of channels is disabled. 1 The Dual Edge Capture mode in this pair of channels is enabled. |
| 1 COMP0 | Complement Of Channel (n) For n = 0 Enables Complementary mode for the combined channels. In Complementary mode the channel (n+1) output is the inverse of the channel (n) output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel (n+1) output is the same as the channel (n) output. 1 The channel (n+1) output is the complement of the channel (n) output. |

Table continues on the next page...

FTMx_COMBINE field descriptions (continued)

| Field | Description |
|---------------|--|
| 0 COMBINE0 | <p>Combine Channels For $n = 0$</p> <p>Enables the combine feature for channels (n) and (n+1).</p> <p>This field is write protected. It can be written only when $\text{MODE}[\text{WPDIS}] = 1$.</p> <p>0 Channels (n) and (n+1) are independent. 1 Channels (n) and (n+1) are combined.</p> |

26.3.15 Deadtime Insertion Control (FTMx_DEADTIME)

This register selects the deadtime prescaler factor and deadtime value. All FTM channels use this clock prescaler and this deadtime value for the deadtime insertion.

Address: Base address + 68h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|------|----|-------|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | DTPS | | DTVAL | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

FTMx_DEADTIME field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 7–6 DTPS | <p>Deadtime Prescaler Value</p> <p>Selects the division factor of the system clock. This prescaled clock is used by the deadtime counter.</p> <p>This field is write protected. It can be written only when $\text{MODE}[\text{WPDIS}] = 1$.</p> <p>0x Divide the system clock by 1. 10 Divide the system clock by 4. 11 Divide the system clock by 16.</p> |
| DTVAL | <p>Deadtime Value</p> <p>Selects the deadtime insertion value for the deadtime counter. The deadtime counter is clocked by a scaled version of the system clock. See the description of DTPS.</p> <p>Deadtime insert value = $(\text{DTPS} \times \text{DTVAL})$.</p> <p>DTVAL selects the number of deadtime counts inserted as follows:</p> <p>When DTVAL is 0, no counts are inserted. When DTVAL is 1, 1 count is inserted. When DTVAL is 2, 2 counts are inserted.</p> <p>This pattern continues up to a possible 63 counts.</p> <p>This field is write protected. It can be written only when $\text{MODE}[\text{WPDIS}] = 1$.</p> |

26.3.16 FTM External Trigger (FTMx_EXTTRIG)

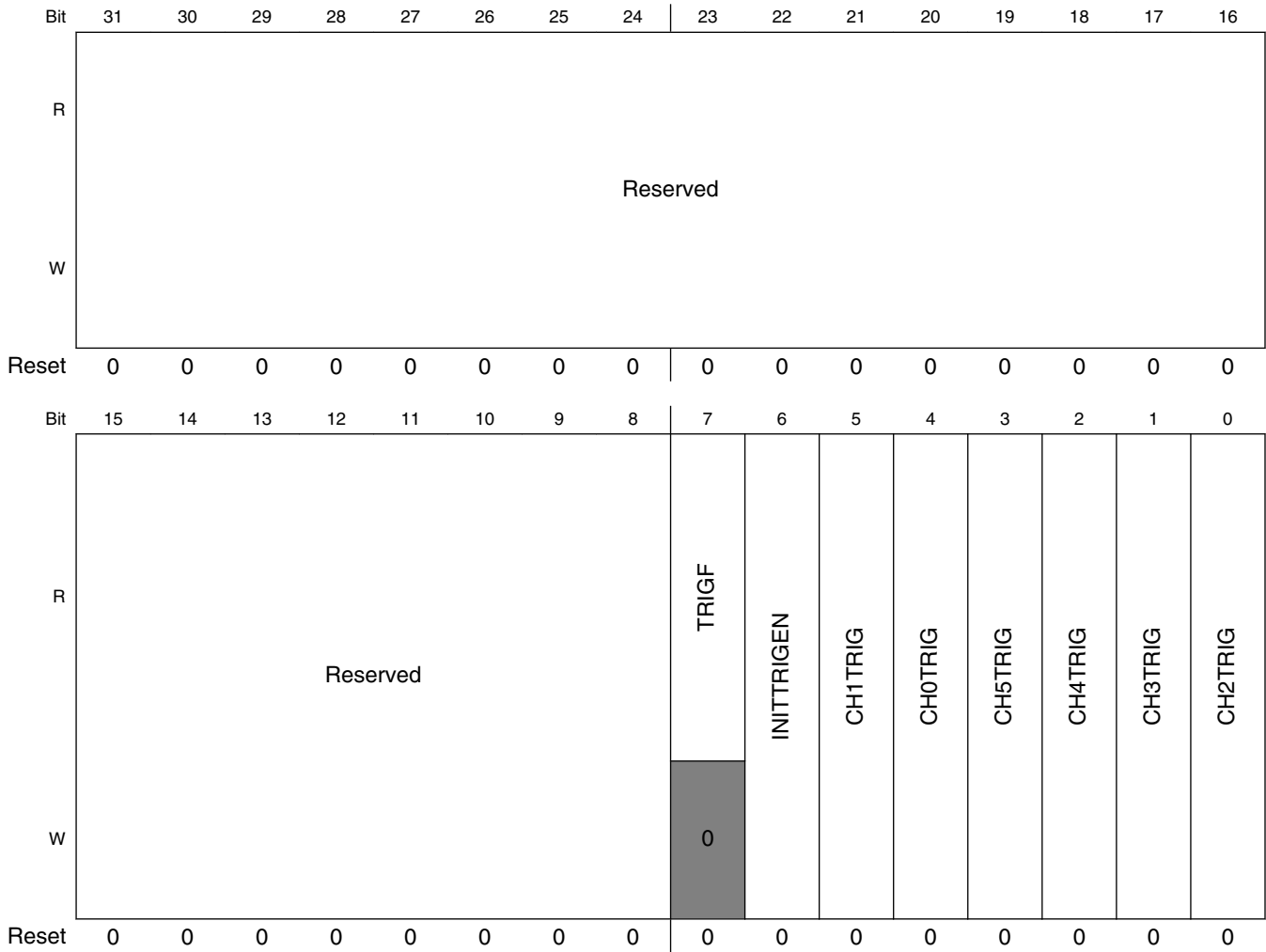
This register:

- Indicates when a channel trigger was generated
- Enables the generation of a trigger when the FTM counter is equal to its initial value
- Selects which channels are used in the generation of the channel triggers

Several channels can be selected to generate multiple triggers in one PWM period.

Channels 6 and 7 are not used to generate channel triggers.

Address: Base address + 6Ch offset



FTMx_EXTTRIG field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | This field is reserved. |
| 7 TRIGF | <p>Channel Trigger Flag</p> <p>Set by hardware when a channel trigger is generated. Clear TRIGF by reading EXTTRIG while TRIGF is set and then writing a 0 to TRIGF. Writing a 1 to TRIGF has no effect.</p> <p>If another channel trigger is generated before the clearing sequence is completed, the sequence is reset so TRIGF remains set after the clear sequence is completed for the earlier TRIGF.</p> <p>0 No channel trigger was generated. 1 A channel trigger was generated.</p> |
| 6 INITTRIGEN | <p>Initialization Trigger Enable</p> <p>Enables the generation of the trigger when the FTM counter is equal to the CNTIN register.</p> <p>0 The generation of initialization trigger is disabled. 1 The generation of initialization trigger is enabled.</p> |
| 5 CH1TRIG | <p>Channel 1 Trigger Enable</p> <p>Enables the generation of the channel trigger when the FTM counter is equal to the CnV register.</p> <p>0 The generation of the channel trigger is disabled. 1 The generation of the channel trigger is enabled.</p> |
| 4 CH0TRIG | <p>Channel 0 Trigger Enable</p> <p>Enables the generation of the channel trigger when the FTM counter is equal to the CnV register.</p> <p>0 The generation of the channel trigger is disabled. 1 The generation of the channel trigger is enabled.</p> |
| 3 CH5TRIG | <p>Channel 5 Trigger Enable</p> <p>Enables the generation of the channel trigger when the FTM counter is equal to the CnV register.</p> <p>0 The generation of the channel trigger is disabled. 1 The generation of the channel trigger is enabled.</p> |
| 2 CH4TRIG | <p>Channel 4 Trigger Enable</p> <p>Enables the generation of the channel trigger when the FTM counter is equal to the CnV register.</p> <p>0 The generation of the channel trigger is disabled. 1 The generation of the channel trigger is enabled.</p> |
| 1 CH3TRIG | <p>Channel 3 Trigger Enable</p> <p>Enables the generation of the channel trigger when the FTM counter is equal to the CnV register.</p> <p>0 The generation of the channel trigger is disabled. 1 The generation of the channel trigger is enabled.</p> |
| 0 CH2TRIG | <p>Channel 2 Trigger Enable</p> <p>Enables the generation of the channel trigger when the FTM counter is equal to the CnV register.</p> |

Table continues on the next page...

FTMx_EXTTRIG field descriptions (continued)

| Field | Description |
|-------|--|
| 0 | The generation of the channel trigger is disabled. |
| 1 | The generation of the channel trigger is enabled. |

26.3.17 Channels Polarity (FTMx_POL)

This register defines the output polarity of the FTM channels.

NOTE

The safe value that is driven in a channel output when the fault control is enabled and a fault condition is detected is the inactive state of the channel. That is, the safe value of a channel is the value of its POL bit.

Address: Base address + 70h offset

| | | | | | | | | | | | | | | | | |
|-------|----------|----|----|----|----|----|----|----|------|------|------|------|------|------|------|------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | Reserved | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | Reserved | | | | | | | | POL7 | POL6 | POL5 | POL4 | POL3 | POL2 | POL1 | POL0 |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_POL field descriptions

| Field | Description |
|------------------|---|
| 31–8 Reserved | This field is reserved. |
| 7 POL7 | Channel 7 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 6 POL6 | Channel 6 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 5 POL5 | Channel 5 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. |

Table continues on the next page...

FTMx_POL field descriptions (continued)

| Field | Description |
|-----------|---|
| | 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 4 POL4 | Channel 4 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 3 POL3 | Channel 3 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 2 POL2 | Channel 2 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 1 POL1 | Channel 1 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |
| 0 POL0 | Channel 0 Polarity Defines the polarity of the channel output. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The channel polarity is active high. 1 The channel polarity is active low. |

26.3.18 Fault Mode Status (FTMx_FMS)

This register contains the fault detection flags, write protection enable bit, and the logic OR of the enabled fault inputs.

Address: Base address + 74h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|--------|------|---------|---|---------|---------|---------|---------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | FAULTF | WPEN | FAULTIN | 0 | FAULTF3 | FAULTF2 | FAULTF1 | FAULTF0 |
| W | | | | | | | | | 0 | | | | 0 | 0 | 0 | 0 |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_FMS field descriptions

| Field | Description |
|------------------|--|
| 31–8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 FAULTF | <p>Fault Detection Flag</p> <p>Represents the logic OR of the individual FAULTFj bits where j = 3, 2, 1, 0. Clear FAULTF by reading the FMS register while FAULTF is set and then writing a 0 to FAULTF while there is no existing fault condition at the enabled fault inputs. Writing a 1 to FAULTF has no effect.</p> <p>If another fault condition is detected in an enabled fault input before the clearing sequence is completed, the sequence is reset so FAULTF remains set after the clearing sequence is completed for the earlier fault condition. FAULTF is also cleared when FAULTFj bits are cleared individually.</p> <p>0 No fault condition was detected. 1 A fault condition was detected.</p> |

Table continues on the next page...

FTMx_FMS field descriptions (continued)

| Field | Description |
|---------------|--|
| 6 WPEN | <p>Write Protection Enable</p> <p>The WPEN bit is the negation of the WPDIS bit. WPEN is set when 1 is written to it. WPEN is cleared when WPEN bit is read as a 1 and then 1 is written to WPDIS. Writing 0 to WPEN has no effect.</p> <p>0 Write protection is disabled. Write protected bits can be written. 1 Write protection is enabled. Write protected bits cannot be written.</p> |
| 5 FAULTIN | <p>Fault Inputs</p> <p>Represents the logic OR of the enabled fault inputs after their filter (if their filter is enabled) when fault control is enabled.</p> <p>0 The logic OR of the enabled fault inputs is 0. 1 The logic OR of the enabled fault inputs is 1.</p> |
| 4 Reserved | <p>This field is reserved. This read-only field is reserved and always has the value 0.</p> |
| 3 FAULTF3 | <p>Fault Detection Flag 3</p> <p>Set by hardware when fault control is enabled, the corresponding fault input is enabled and a fault condition is detected at the fault input.</p> <p>Clear FAULTF3 by reading the FMS register while FAULTF3 is set and then writing a 0 to FAULTF3 while there is no existing fault condition at the corresponding fault input. Writing a 1 to FAULTF3 has no effect. FAULTF3 bit is also cleared when FAULTF bit is cleared.</p> <p>If another fault condition is detected at the corresponding fault input before the clearing sequence is completed, the sequence is reset so FAULTF3 remains set after the clearing sequence is completed for the earlier fault condition.</p> <p>0 No fault condition was detected at the fault input. 1 A fault condition was detected at the fault input.</p> |
| 2 FAULTF2 | <p>Fault Detection Flag 2</p> <p>Set by hardware when fault control is enabled, the corresponding fault input is enabled and a fault condition is detected at the fault input.</p> <p>Clear FAULTF2 by reading the FMS register while FAULTF2 is set and then writing a 0 to FAULTF2 while there is no existing fault condition at the corresponding fault input. Writing a 1 to FAULTF2 has no effect. FAULTF2 bit is also cleared when FAULTF bit is cleared.</p> <p>If another fault condition is detected at the corresponding fault input before the clearing sequence is completed, the sequence is reset so FAULTF2 remains set after the clearing sequence is completed for the earlier fault condition.</p> <p>0 No fault condition was detected at the fault input. 1 A fault condition was detected at the fault input.</p> |
| 1 FAULTF1 | <p>Fault Detection Flag 1</p> <p>Set by hardware when fault control is enabled, the corresponding fault input is enabled and a fault condition is detected at the fault input.</p> <p>Clear FAULTF1 by reading the FMS register while FAULTF1 is set and then writing a 0 to FAULTF1 while there is no existing fault condition at the corresponding fault input. Writing a 1 to FAULTF1 has no effect. FAULTF1 bit is also cleared when FAULTF bit is cleared.</p> |

Table continues on the next page...

FTMx_FMS field descriptions (continued)

| Field | Description |
|--------------|--|
| | <p>If another fault condition is detected at the corresponding fault input before the clearing sequence is completed, the sequence is reset so FAULTF1 remains set after the clearing sequence is completed for the earlier fault condition.</p> <p>0 No fault condition was detected at the fault input. 1 A fault condition was detected at the fault input.</p> |
| 0 FAULTF0 | <p>Fault Detection Flag 0</p> <p>Set by hardware when fault control is enabled, the corresponding fault input is enabled and a fault condition is detected at the fault input.</p> <p>Clear FAULTF0 by reading the FMS register while FAULTF0 is set and then writing a 0 to FAULTF0 while there is no existing fault condition at the corresponding fault input. Writing a 1 to FAULTF0 has no effect. FAULTF0 bit is also cleared when FAULTF bit is cleared.</p> <p>If another fault condition is detected at the corresponding fault input before the clearing sequence is completed, the sequence is reset so FAULTF0 remains set after the clearing sequence is completed for the earlier fault condition.</p> <p>0 No fault condition was detected at the fault input. 1 A fault condition was detected at the fault input.</p> |

26.3.19 Input Capture Filter Control (FTMx_FILTER)

This register selects the filter value for the inputs of channels.

Channels 4, 5, 6 and 7 do not have an input filter.

NOTE

Writing to the FILTER register has immediate effect and must be done only when the channels 0, 1, 2, and 3 are not in input modes. Failure to do this could result in a missing valid signal.

Address: Base address + 78h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---------|----|----|----|---------|----|---|---|---------|---|---|---|---------|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | Reserved | | | | | | | | | | | | | | | | CH3FVAL | | | | CH2FVAL | | | | CH1FVAL | | | | CH0FVAL | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

FTMx_FILTER field descriptions

| Field | Description |
|-------------------|--|
| 31–16 Reserved | This field is reserved. |
| 15–12 CH3FVAL | <p>Channel 3 Input Filter</p> <p>Selects the filter value for the channel input.</p> <p>The filter is disabled when the value is zero.</p> |

Table continues on the next page...

FTMx_FILTER field descriptions (continued)

| Field | Description |
|-----------------|---|
| 11–8 CH2FVAL | Channel 2 Input Filter Selects the filter value for the channel input. The filter is disabled when the value is zero. |
| 7–4 CH1FVAL | Channel 1 Input Filter Selects the filter value for the channel input. The filter is disabled when the value is zero. |
| CH0FVAL | Channel 0 Input Filter Selects the filter value for the channel input. The filter is disabled when the value is zero. |

26.3.20 Fault Control (FTMx_FLTCTRL)

This register selects the filter value for the fault inputs, enables the fault inputs and the fault inputs filter.

Address: Base address + 7Ch offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|-------|----|---|---|----------|----------|----------|----------|----------|----------|----------|----------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | FFVAL | | | | FFLTR3EN | FFLTR2EN | FFLTR1EN | FFLTR0EN | FAULT3EN | FAULT2EN | FAULT1EN | FAULT0EN |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_FLTCTRL field descriptions

| Field | Description |
|-------------------|--|
| 31–12 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 11–8 FFVAL | Fault Input Filter Selects the filter value for the fault inputs. The fault filter is disabled when the value is zero. |

Table continues on the next page...

FTMx_FLTCTRL field descriptions (continued)

| Field | Description |
|---------------|--|
| | NOTE: Writing to this field has immediate effect and must be done only when the fault control or all fault inputs are disabled. Failure to do this could result in a missing fault detection. |
| 7 FFLTR3EN | <p>Fault Input 3 Filter Enable</p> <p>Enables the filter for the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Fault input filter is disabled. 1 Fault input filter is enabled.</p> |
| 6 FFLTR2EN | <p>Fault Input 2 Filter Enable</p> <p>Enables the filter for the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Fault input filter is disabled. 1 Fault input filter is enabled.</p> |
| 5 FFLTR1EN | <p>Fault Input 1 Filter Enable</p> <p>Enables the filter for the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Fault input filter is disabled. 1 Fault input filter is enabled.</p> |
| 4 FFLTR0EN | <p>Fault Input 0 Filter Enable</p> <p>Enables the filter for the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Fault input filter is disabled. 1 Fault input filter is enabled.</p> |
| 3 FAULT3EN | <p>Fault Input 3 Enable</p> <p>Enables the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Fault input is disabled. 1 Fault input is enabled.</p> |
| 2 FAULT2EN | <p>Fault Input 2 Enable</p> <p>Enables the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> <p>0 Fault input is disabled. 1 Fault input is enabled.</p> |
| 1 FAULT1EN | <p>Fault Input 1 Enable</p> <p>Enables the fault input.</p> <p>This field is write protected. It can be written only when MODE[WPDIS] = 1.</p> |

Table continues on the next page...

FTMx_FLTCTRL field descriptions (continued)

| Field | Description |
|---------------|--|
| | 0 Fault input is disabled. 1 Fault input is enabled. |
| 0 FAULT0EN | Fault Input 0 Enable Enables the fault input. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 Fault input is disabled. 1 Fault input is enabled. |

26.3.21 Configuration (FTMx_CONF)

This register selects the number of times that the FTM counter overflow should occur before the TOF bit to be set, the FTM behavior in Debug modes, the use of an external global time base, and the global time base signal generation.

Address: Base address + 84h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|---------|--------|----|---------|----|----|--------|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | GTBEOUT | GTBEEN | 0 | BDMMODE | | 0 | NUMTOF | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_CONF field descriptions

| Field | Description |
|-------------------|---|
| 31–11 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 10 GTBEOUT | Global Time Base Output Enables the global time base signal generation to other FTMs. 0 A global time base signal generation is disabled. 1 A global time base signal generation is enabled. |

Table continues on the next page...

FTMx_CONF field descriptions (continued)

| Field | Description |
|---------------|---|
| 9 GTBEEN | Global Time Base Enable Configures the FTM to use an external global time base signal that is generated by another FTM. 0 Use of an external global time base is disabled. 1 Use of an external global time base is enabled. |
| 8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7–6 BDMODE | Debug Mode Selects the FTM behavior in Debug mode. See Debug mode . |
| 5 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| NUMTOF | TOF Frequency Selects the ratio between the number of counter overflows to the number of times the TOF bit is set. NUMTOF = 0: The TOF bit is set for each counter overflow. NUMTOF = 1: The TOF bit is set for the first counter overflow but not for the next overflow. NUMTOF = 2: The TOF bit is set for the first counter overflow but not for the next 2 overflows. NUMTOF = 3: The TOF bit is set for the first counter overflow but not for the next 3 overflows. This pattern continues up to a maximum of 31. |

26.3.22 FTM Fault Input Polarity (FTMx_FLTPOL)

This register defines the fault inputs polarity.

Address: Base address + 88h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|---------|---------|---------|---------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | FLT3POL | FLT2POL | FLT1POL | FLT0POL |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_FLTPOL field descriptions

| Field | Description |
|------------------|--|
| 31–4 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 3 FLT3POL | Fault Input 3 Polarity Defines the polarity of the fault input. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The fault input polarity is active high. A 1 at the fault input indicates a fault. 1 The fault input polarity is active low. A 0 at the fault input indicates a fault. |
| 2 FLT2POL | Fault Input 2 Polarity Defines the polarity of the fault input. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The fault input polarity is active high. A 1 at the fault input indicates a fault. 1 The fault input polarity is active low. A 0 at the fault input indicates a fault. |
| 1 FLT1POL | Fault Input 1 Polarity Defines the polarity of the fault input. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The fault input polarity is active high. A 1 at the fault input indicates a fault. 1 The fault input polarity is active low. A 0 at the fault input indicates a fault. |
| 0 FLT0POL | Fault Input 0 Polarity Defines the polarity of the fault input. This field is write protected. It can be written only when MODE[WPDIS] = 1. 0 The fault input polarity is active high. A 1 at the fault input indicates a fault. 1 The fault input polarity is active low. A 0 at the fault input indicates a fault. |

26.3.23 Synchronization Configuration (FTMx_SYNCONF)

This register selects the PWM synchronization configuration, SWOCTRL, INVCTRL and CNTIN registers synchronization, if FTM clears the TRIGj bit, where $j = 0, 1, 2$, when the hardware trigger j is detected.

Address: Base address + 8Ch offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|-------|--------|------|---------|----------|----------|----|------|-------|--------|--------|---------|------------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | HWSOC | HWINVC | HWOM | HWWRBUF | HWRSTCNT |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | SWSOC | SWINVC | SWOM | SWWRBUF | SWRSTCNT | SYNCMODE | 0 | SWOC | INVC | 0 | CNTINC | 0 | HWTRIGMODE |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_SYNCONF field descriptions

| Field | Description |
|-------------------|--|
| 31–21 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 20 HWSOC | Software output control synchronization is activated by a hardware trigger. 0 A hardware trigger does not activate the SWOCTRL register synchronization. 1 A hardware trigger activates the SWOCTRL register synchronization. |
| 19 HWINVC | Inverting control synchronization is activated by a hardware trigger. 0 A hardware trigger does not activate the INVCTRL register synchronization. 1 A hardware trigger activates the INVCTRL register synchronization. |
| 18 HWOM | Output mask synchronization is activated by a hardware trigger. 0 A hardware trigger does not activate the OUTMASK register synchronization. 1 A hardware trigger activates the OUTMASK register synchronization. |
| 17 HWWRBUF | MOD, CNTIN, and CV registers synchronization is activated by a hardware trigger. 0 A hardware trigger does not activate MOD, CNTIN, and CV registers synchronization. 1 A hardware trigger activates MOD, CNTIN, and CV registers synchronization. |
| 16 HWRSTCNT | FTM counter synchronization is activated by a hardware trigger. 0 A hardware trigger does not activate the FTM counter synchronization. 1 A hardware trigger activates the FTM counter synchronization. |

Table continues on the next page...

FTMx_SYNCONF field descriptions (continued)

| Field | Description |
|-------------------|--|
| 15–13 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 12 SWSOC | Software output control synchronization is activated by the software trigger. 0 The software trigger does not activate the SWOCTRL register synchronization. 1 The software trigger activates the SWOCTRL register synchronization. |
| 11 SWINVC | Inverting control synchronization is activated by the software trigger. 0 The software trigger does not activate the INVCTRL register synchronization. 1 The software trigger activates the INVCTRL register synchronization. |
| 10 SWOM | Output mask synchronization is activated by the software trigger. 0 The software trigger does not activate the OUTMASK register synchronization. 1 The software trigger activates the OUTMASK register synchronization. |
| 9 SWWRBUF | MOD, CNTIN, and CV registers synchronization is activated by the software trigger. 0 The software trigger does not activate MOD, CNTIN, and CV registers synchronization. 1 The software trigger activates MOD, CNTIN, and CV registers synchronization. |
| 8 SWRSTCNT | FTM counter synchronization is activated by the software trigger. 0 The software trigger does not activate the FTM counter synchronization. 1 The software trigger activates the FTM counter synchronization. |
| 7 SYNCMODE | Synchronization Mode Selects the PWM Synchronization mode. 0 Legacy PWM synchronization is selected. 1 Enhanced PWM synchronization is selected. |
| 6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5 SWOC | SWOCTRL Register Synchronization 0 SWOCTRL register is updated with its buffer value at all rising edges of system clock. 1 SWOCTRL register is updated with its buffer value by the PWM synchronization. |
| 4 INVC | INVCTRL Register Synchronization 0 INVCTRL register is updated with its buffer value at all rising edges of system clock. 1 INVCTRL register is updated with its buffer value by the PWM synchronization. |
| 3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 2 CNTINC | CNTIN Register Synchronization 0 CNTIN register is updated with its buffer value at all rising edges of system clock. 1 CNTIN register is updated with its buffer value by the PWM synchronization. |
| 1 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 0 HWTRIGMODE | Hardware Trigger Mode |

Table continues on the next page...

FTMx_SYNCONF field descriptions (continued)

| Field | Description |
|-------|--|
| 0 | FTM clears the TRIGj bit when the hardware trigger j is detected, where j = 0, 1, 2. |
| 1 | FTM does not clear the TRIGj bit when the hardware trigger j is detected, where j = 0, 1, 2. |

26.3.24 FTM Inverting Control (FTMx_INVCTRL)

This register controls when the channel (n) output becomes the channel (n+1) output, and channel (n+1) output becomes the channel (n) output. Each INVmEN bit enables the inverting operation for the corresponding pair channels m.

This register has a write buffer. The INVmEN bit is updated by the INVCTRL register synchronization.

Address: Base address + 90h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|--------|--------|--------|--------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | INV3EN | INV2EN | INV1EN | INV0EN |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_INVCTRL field descriptions

| Field | Description |
|------------------|---|
| 31–4 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 3 INV3EN | Pair Channels 3 Inverting Enable 0 Inverting is disabled. 1 Inverting is enabled. |
| 2 INV2EN | Pair Channels 2 Inverting Enable 0 Inverting is disabled. 1 Inverting is enabled. |
| 1 INV1EN | Pair Channels 1 Inverting Enable 0 Inverting is disabled. 1 Inverting is enabled. |

Table continues on the next page...

FTMx_INVCTRL field descriptions (continued)

| Field | Description |
|-------------|---|
| 0 INV0EN | Pair Channels 0 Inverting Enable 0 Inverting is disabled. 1 Inverting is enabled. |

26.3.25 FTM Software Output Control (FTMx_SWOCTRL)

This register enables software control of channel (n) output and defines the value forced to the channel (n) output:

- The CHnOC bits enable the control of the corresponding channel (n) output by software.
- The CHnOCV bits select the value that is forced at the corresponding channel (n) output.

This register has a write buffer. The fields are updated by the SWOCTRL register synchronization.

Address: Base address + 94h offset

| | | | | | | | | | | | | | | | | |
|-------|--------|--------|--------|--------|--------|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | CH7OCV | CH6OCV | CH5OCV | CH4OCV | CH3OCV | CH2OCV | CH1OCV | CH0OCV | CH7OC | CH6OC | CH5OC | CH4OC | CH3OC | CH2OC | CH1OC | CH0OC |
| W | CH7OCV | CH6OCV | CH5OCV | CH4OCV | CH3OCV | CH2OCV | CH1OCV | CH0OCV | CH7OC | CH6OC | CH5OC | CH4OC | CH3OC | CH2OC | CH1OC | CH0OC |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_SWOCTRL field descriptions

| Field | Description |
|-------------------|---|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 15 CH7OCV | Channel 7 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 14 CH6OCV | Channel 6 Software Output Control Value |

Table continues on the next page...

FTMx_SWOCTRL field descriptions (continued)

| Field | Description |
|--------------|--|
| | 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 13 CH5OCV | Channel 5 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 12 CH4OCV | Channel 4 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 11 CH3OCV | Channel 3 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 10 CH2OCV | Channel 2 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 9 CH1OCV | Channel 1 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 8 CH0OCV | Channel 0 Software Output Control Value 0 The software output control forces 0 to the channel output. 1 The software output control forces 1 to the channel output. |
| 7 CH7OC | Channel 7 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 6 CH6OC | Channel 6 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 5 CH5OC | Channel 5 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 4 CH4OC | Channel 4 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 3 CH3OC | Channel 3 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 2 CH2OC | Channel 2 Software Output Control Enable |

Table continues on the next page...

FTMx_SWOCTRL field descriptions (continued)

| Field | Description |
|------------|--|
| | 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 1 CH1OC | Channel 1 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |
| 0 CH0OC | Channel 0 Software Output Control Enable 0 The channel output is not affected by software output control. 1 The channel output is affected by software output control. |

26.3.26 FTM PWM Load (FTMx_PWMLOAD)

Enables the loading of the MOD, CNTIN, C(n)V, and C(n+1)V registers with the values of their write buffers when the FTM counter changes from the MOD register value to its next value or when a channel (j) match occurs. A match occurs for the channel (j) when FTM counter = C(j)V.

Address: Base address + 98h offset

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|------|--------|--------|--------|--------|--------|--------|--------|--------|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | 0 | CH7SEL | CH6SEL | CH5SEL | CH4SEL | CH3SEL | CH2SEL | CH1SEL | CH0SEL |
| W | | | | | | | | LDOK | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FTMx_PWMLOAD field descriptions

| Field | Description |
|-------------------|---|
| 31–10 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 9 LDOK | Load Enable Enables the loading of the MOD, CNTIN, and CV registers with the values of their write buffers. 0 Loading updated values is disabled. 1 Loading updated values is enabled. |

Table continues on the next page...

FTMx_PWMLOAD field descriptions (continued)

| Field | Description |
|---------------|---|
| 8 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 7 CH7SEL | Channel 7 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 6 CH6SEL | Channel 6 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 5 CH5SEL | Channel 5 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 4 CH4SEL | Channel 4 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 3 CH3SEL | Channel 3 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 2 CH2SEL | Channel 2 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 1 CH1SEL | Channel 1 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |
| 0 CH0SEL | Channel 0 Select 0 Do not include the channel in the matching process. 1 Include the channel in the matching process. |

26.4 Functional description

The notation used in this document to represent the counters and the generation of the signals is shown in the following figure.

FTM counting is up.
Channel (n) is in high-true EPWM mode.

PS[2:0] = 001
CNTIN = 0x0000
MOD = 0x0004
CnV = 0x0002

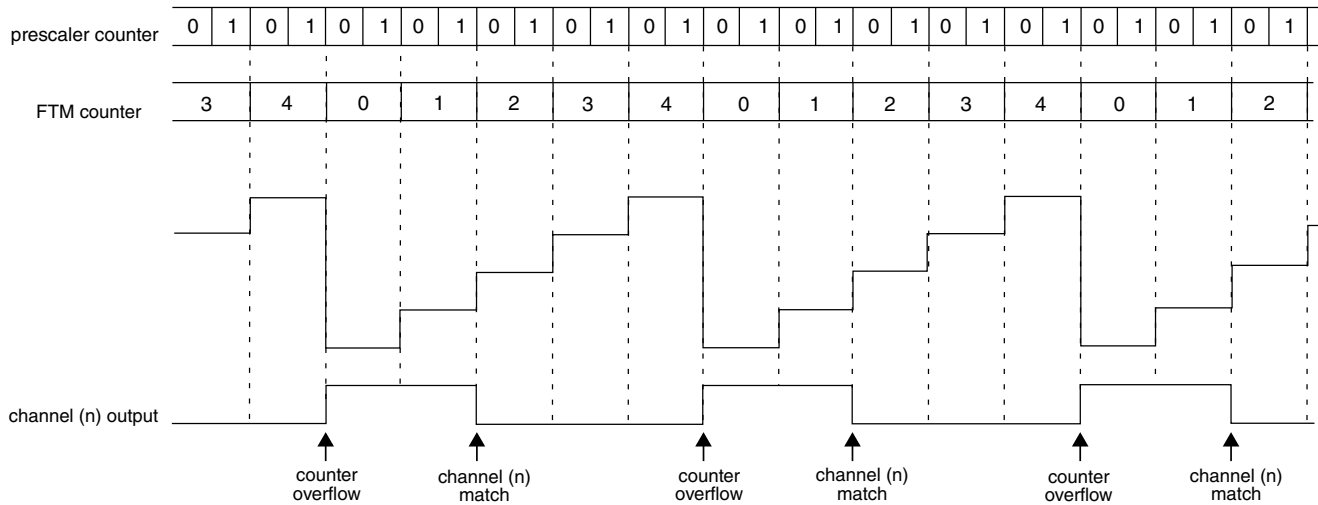


Figure 26-162. Notation used

26.4.1 Clock source

The FTM has only one clock domain: the system clock.

26.4.1.1 Counter clock source

The CLKS[1:0] bits in the SC register select one of three possible clock sources for the FTM counter or disable the FTM counter. After any MCU reset, CLKS[1:0] = 0:0 so no clock source is selected.

The CLKS[1:0] bits may be read or written at any time. Disabling the FTM counter by writing 0:0 to the CLKS[1:0] bits does not affect the FTM counter value or other registers.

The fixed frequency clock is an alternative clock source for the FTM counter that allows the selection of a clock other than the system clock or an external clock. This clock input is defined by chip integration. Refer to the chip specific documentation for further information. Due to FTM hardware implementation limitations, the frequency of the fixed frequency clock must not exceed 1/2 of the system clock frequency.

The external clock passes through a synchronizer clocked by the system clock to assure that counter transitions are properly aligned to system clock transitions. Therefore, to meet Nyquist criteria considering also jitter, the frequency of the external clock source must not exceed 1/4 of the system clock frequency.

26.4.2 Prescaler

The selected counter clock source passes through a prescaler that is a 7-bit counter. The value of the prescaler is selected by the PS[2:0] bits. The following figure shows an example of the prescaler counter and FTM counter.

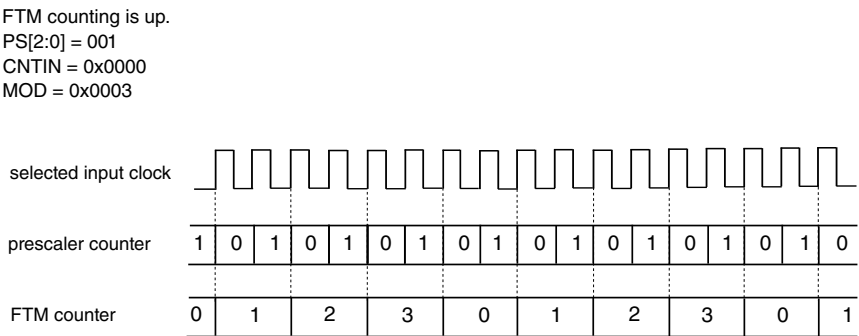


Figure 26-163. Example of the prescaler counter

26.4.3 Counter

The FTM has a 16-bit counter that is used by the channels either for input or output modes. The FTM counter clock is the selected clock divided by the prescaler.

The FTM counter has these modes of operation:

- Up counting
- Up-down counting

26.4.3.1 Up counting

Up counting is selected when:

- CPWMS = 0

CNTIN defines the starting value of the count and MOD defines the final value of the count, see the following figure. The value of CNTIN is loaded into the FTM counter, and the counter increments until the value of MOD is reached, at which point the counter is reloaded with the value of CNTIN.

The FTM period when using up counting is $(MOD - CNTIN + 0x0001) \times \text{period of the FTM counter clock}$.

The TOF bit is set when the FTM counter changes from MOD to CNTIN.

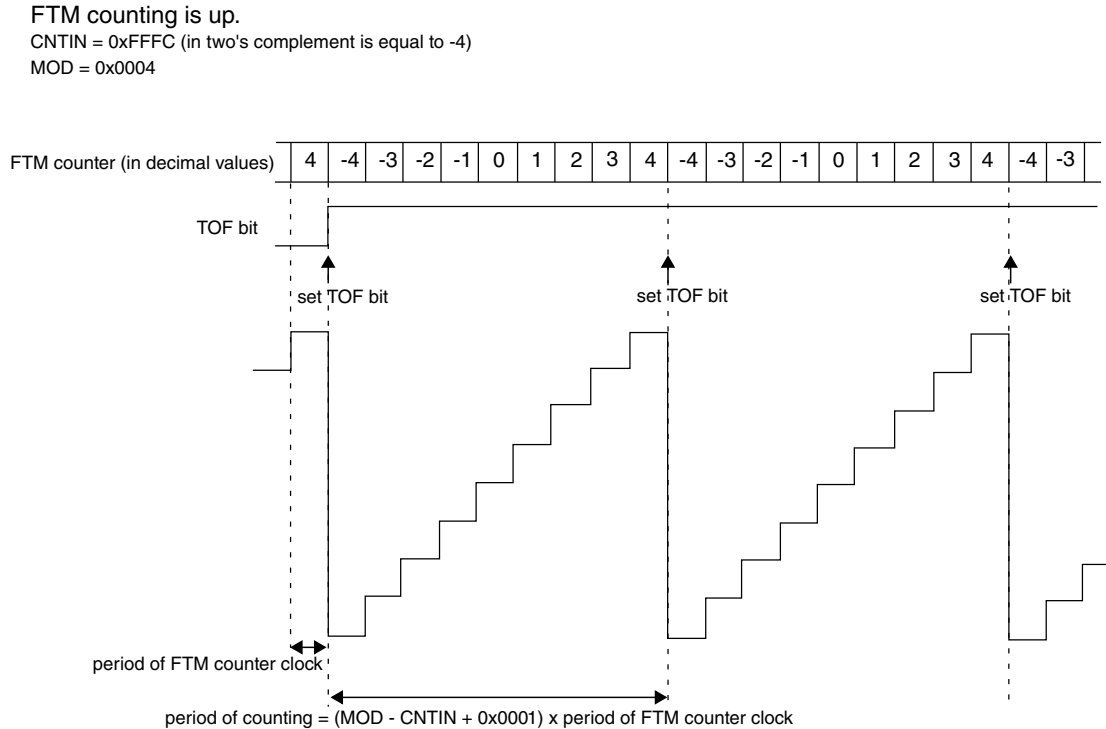


Figure 26-164. Example of FTM up and signed counting

Table 26-238. FTM counting based on CNTIN value

| When | Then |
|---------------------------------------|--|
| CNTIN = 0x0000 | The FTM counting is equivalent to TPM up counting, that is, up and unsigned counting. See the following figure. |
| CNTIN[15] = 1 | The initial value of the FTM counter is a negative number in two's complement, so the FTM counting is up and signed. |
| CNTIN[15] = 0 and CNTIN \neq 0x0000 | The initial value of the FTM counter is a positive number, so the FTM counting is up and unsigned. |

Functional description

FTM counting is up

CNTIN = 0x0000

MOD = 0x0004

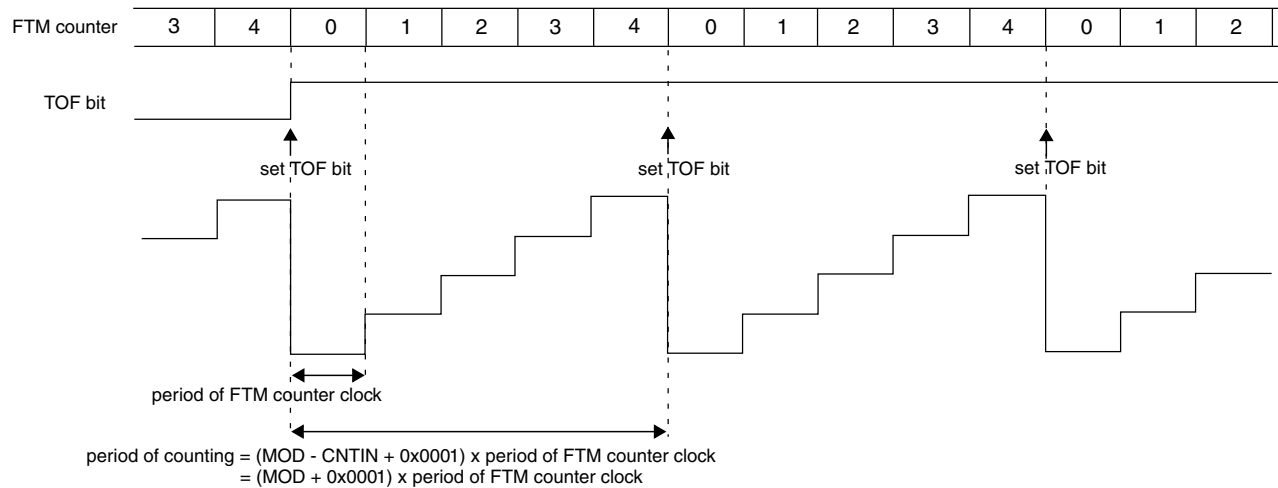


Figure 26-165. Example of FTM up counting with CNTIN = 0x0000

Note

- FTM operation is only valid when the value of the CNTIN register is less than the value of the MOD register, either in the unsigned counting or signed counting. It is the responsibility of the software to ensure that the values in the CNTIN and MOD registers meet this requirement. Any values of CNTIN and MOD that do not satisfy this criteria can result in unpredictable behavior.
- MOD = CNTIN is a redundant condition. In this case, the FTM counter is always equal to MOD and the TOF bit is set in each rising edge of the FTM counter clock.
- When MOD = 0x0000, CNTIN = 0x0000, for example after reset, and FTMMEN = 1, the FTM counter remains stopped at 0x0000 until a non-zero value is written into the MOD or CNTIN registers.
- Setting CNTIN to be greater than the value of MOD is not recommended as this unusual setting may make the FTM operation difficult to comprehend. However, there is no restriction on this configuration, and an example is shown in the following figure.

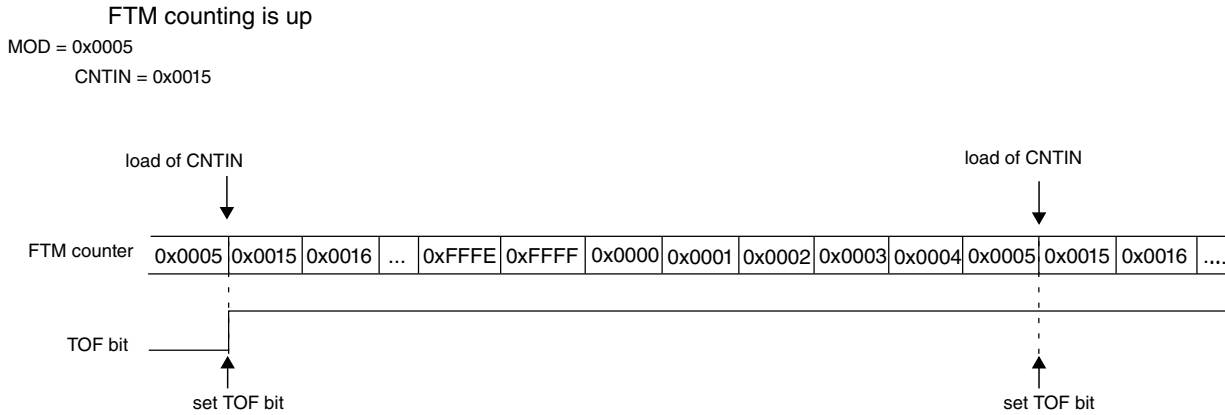


Figure 26-166. Example of up counting when the value of CNTIN is greater than the value of MOD

26.4.3.2 Up-down counting

Up-down counting is selected when:

- CPWMS = 1

CNTIN defines the starting value of the count and MOD defines the final value of the count. The value of CNTIN is loaded into the FTM counter, and the counter increments until the value of MOD is reached, at which point the counter is decremented until it returns to the value of CNTIN and the up-down counting restarts.

The FTM period when using up-down counting is $2 \times (\text{MOD} - \text{CNTIN}) \times \text{period of the FTM counter clock}$.

The TOF bit is set when the FTM counter changes from MOD to (MOD – 1).

If (CNTIN = 0x0000), the FTM counting is equivalent to TPM up-down counting, that is, up-down and unsigned counting. See the following figure.

Functional description

FTM counting is up-down
 CNTIN = 0x0000
 MOD = 0x0004

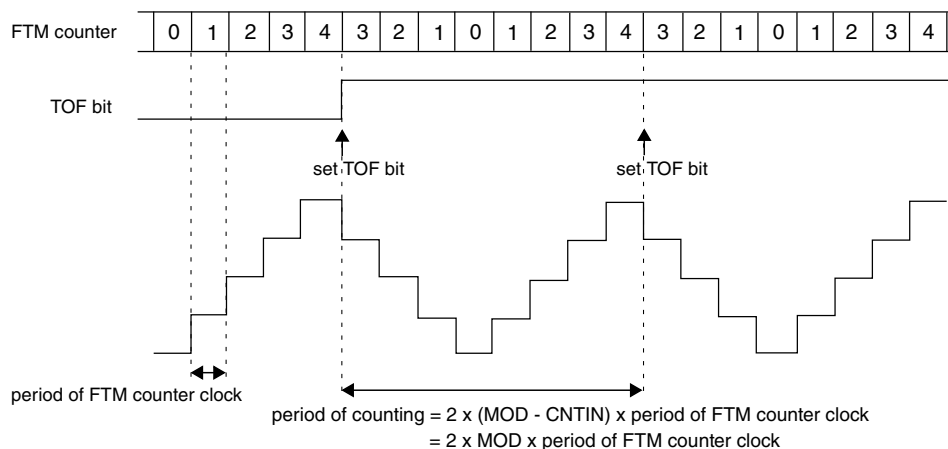


Figure 26-167. Example of up-down counting when CNTIN = 0x0000

Note

When CNTIN is different from zero in the up-down counting, a valid CPWM signal is generated:

- if $CnV > CNTIN$, or
- if $CnV = 0$ or if $CnV[15] = 1$. In this case, 0% CPWM is generated.

26.4.3.3 Free running counter

If (FTMEN = 0) and (MOD = 0x0000 or MOD = 0xFFFF), the FTM counter is a free running counter. In this case, the FTM counter runs free from 0x0000 through 0xFFFF and the TOF bit is set when the FTM counter changes from 0xFFFF to 0x0000. See the following figure.

FTMEN = 0
 MOD = 0x0000

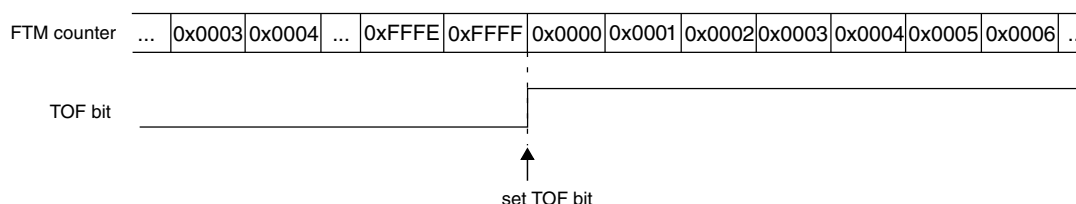


Figure 26-168. Example when the FTM counter is free running

The FTM counter is also a free running counter when:

- FTMEN = 1
- CPWMS = 0
- CNTIN = 0x0000, and
- MOD = 0xFFFF

26.4.3.4 Counter reset

Any one of the following cases resets the FTM counter to the value in the CNTIN register and the channels output to its initial value, except for channels in Output Compare mode.

- Any write to CNT.
- [FTM counter synchronization](#).

26.4.3.5 When the TOF bit is set

The NUMTOF[4:0] bits define the number of times that the FTM counter overflow should occur before the TOF bit to be set. If NUMTOF[4:0] = 0x00, then the TOF bit is set at each FTM counter overflow.

Initialize the FTM counter, by writing to CNT, after writing to the NUMTOF[4:0] bits to avoid confusion about when the first counter overflow will occur.

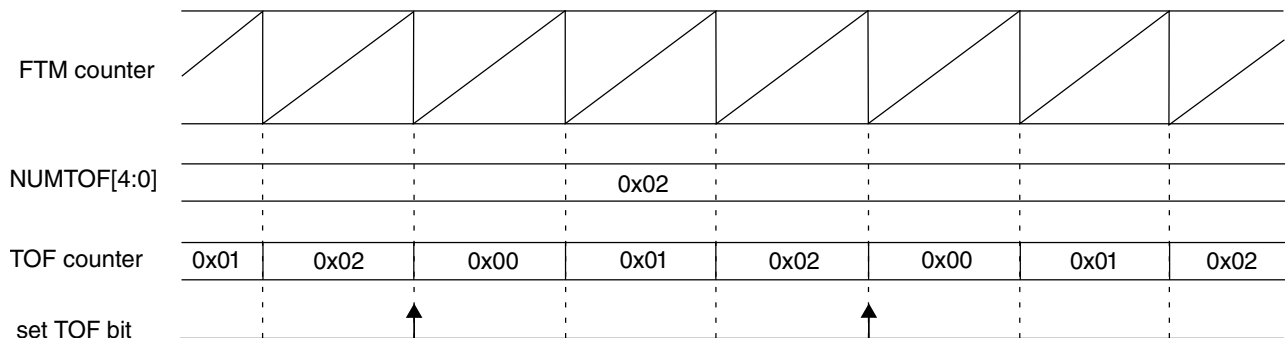


Figure 26-169. Periodic TOF when NUMTOF = 0x02

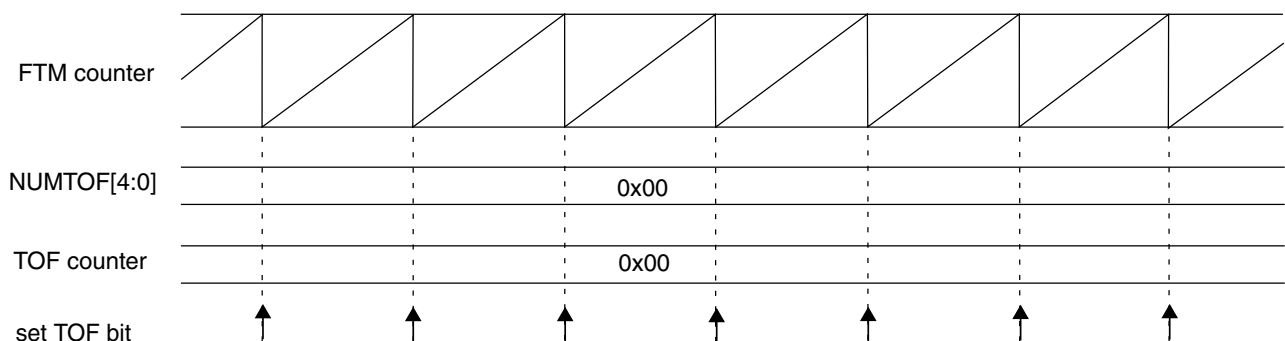


Figure 26-170. Periodic TOF when NUMTOF = 0x00

26.4.4 Input Capture mode

The Input Capture mode is selected when:

- DECAPEN = 0
- COMBINE = 0
- CPWMS = 0
- MSnB:MSnA = 0:0, and
- ELSnB:ELSnA ≠ 0:0

When a selected edge occurs on the channel input, the current value of the FTM counter is captured into the CnV register, at the same time the CHnF bit is set and the channel interrupt is generated if enabled by CHnIE = 1. See the following figure.

When a channel is configured for input capture, the FTMxCHn pin is an edge-sensitive input. ELSnB:ELSnA control bits determine which edge, falling or rising, triggers input-capture event. Note that the maximum frequency for the channel input signal to be detected correctly is system clock divided by 4, which is required to meet Nyquist criteria for signal sampling.

Writes to the CnV register is ignored in Input Capture mode.

While in Debug mode, the input capture function works as configured. When a selected edge event occurs, the FTM counter value, which is frozen because of Debug, is captured into the CnV register and the CHnF bit is set.

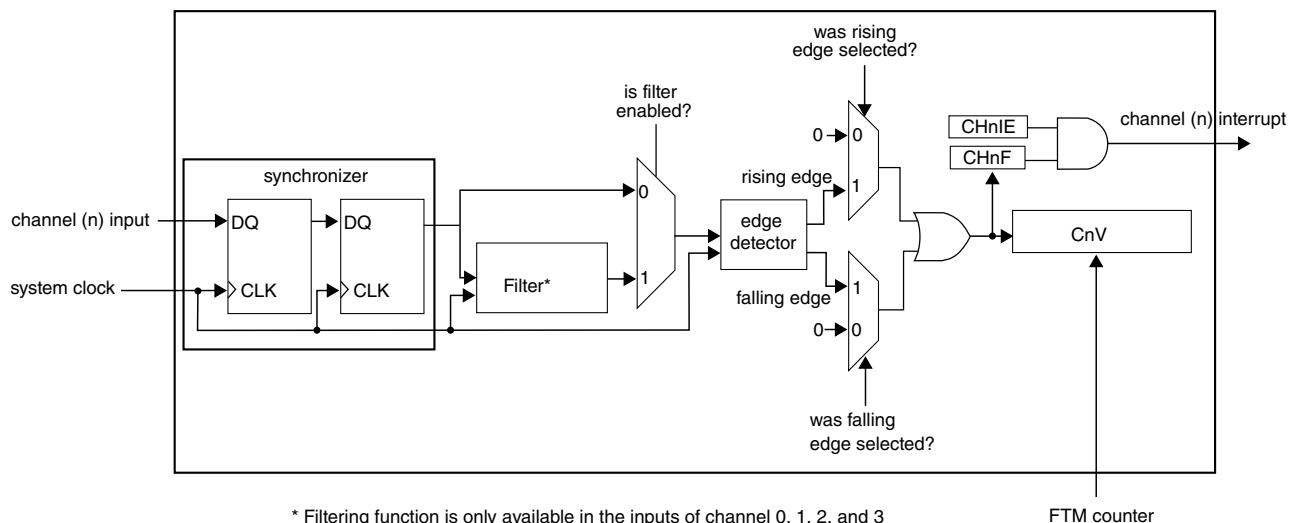


Figure 26-171. Input Capture mode

If the channel input does not have a filter enabled, then the input signal is always delayed 3 rising edges of the system clock, that is, two rising edges to the synchronizer plus one more rising edge to the edge detector. In other words, the CHnF bit is set on the third rising edge of the system clock after a valid edge occurs on the channel input.

26.4.4.1 Filter for Input Capture mode

The filter function is only available on channels 0, 1, 2, and 3.

First, the input signal is synchronized by the system clock. Following synchronization, the input signal enters the filter block. See the following figure.

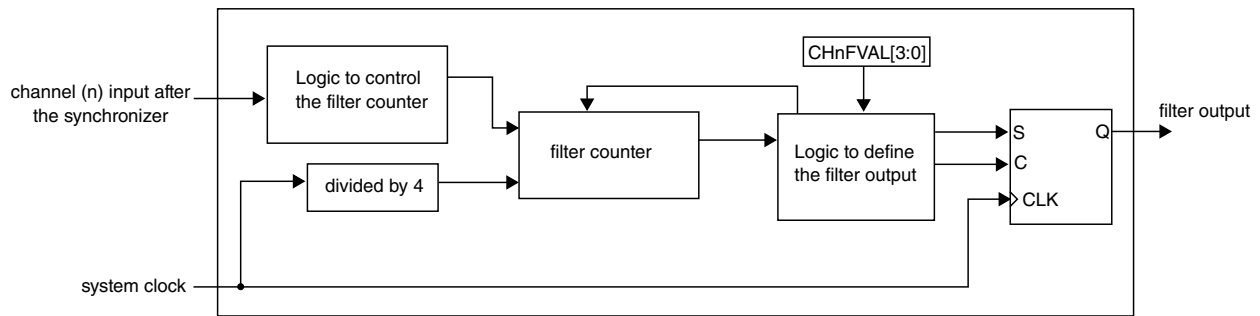


Figure 26-172. Channel input filter

When there is a state change in the input signal, the counter is reset and starts counting up. As long as the new state is stable on the input, the counter continues to increment. When the counter is equal to CHnFVAL[3:0], the state change of the input signal is validated. It is then transmitted as a pulse edge to the edge detector.

If the opposite edge appears on the input signal before it can be validated, the counter is reset. At the next input transition, the counter starts counting again. Any pulse that is shorter than the minimum value selected by CHnFVAL[3:0] ($\times 4$ system clocks) is regarded as a glitch and is not passed on to the edge detector. A timing diagram of the input filter is shown in the following figure.

The filter function is disabled when CHnFVAL[3:0] bits are zero. In this case, the input signal is delayed 3 rising edges of the system clock. If $(\text{CHnFVAL}[3:0] \neq 0000)$, then the input signal is delayed by the minimum pulse width ($\text{CHnFVAL}[3:0] \times 4$ system clocks) plus a further 4 rising edges of the system clock: two rising edges to the synchronizer, one rising edge to the filter output, plus one more to the edge detector. In other words, CHnF is set $(4 + 4 \times \text{CHnFVAL}[3:0])$ system clock periods after a valid edge occurs on the channel input.

The clock for the counter in the channel input filter is the system clock divided by 4.

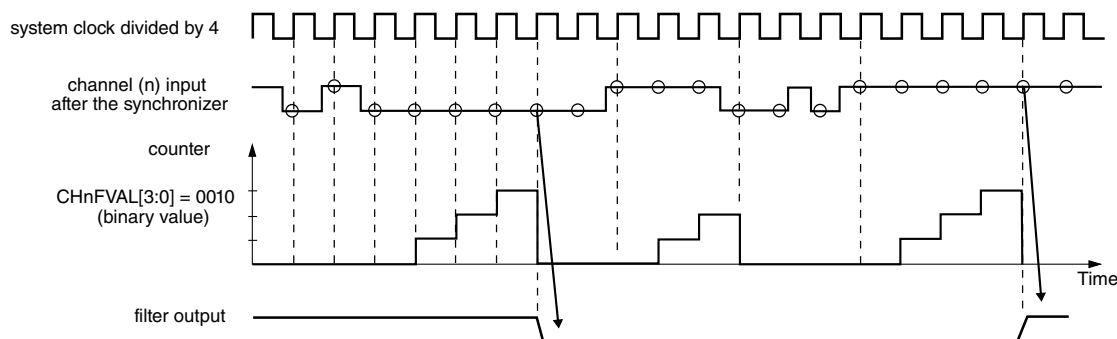


Figure 26-173. Channel input filter example

26.4.5 Output Compare mode

The Output Compare mode is selected when:

- DECAPEN = 0
- COMBINE = 0
- CPWMS = 0, and
- MSnB:MSnA = 0:1

In Output Compare mode, the FTM can generate timed pulses with programmable position, polarity, duration, and frequency. When the counter matches the value in the CnV register of an output compare channel, the channel (n) output can be set, cleared, or toggled.

When a channel is initially configured to Toggle mode, the previous value of the channel output is held until the first output compare event occurs.

The CHnF bit is set and the channel (n) interrupt is generated if CHnIE = 1 at the channel (n) match (FTM counter = CnV).

MOD = 0x0005
CnV = 0x0003

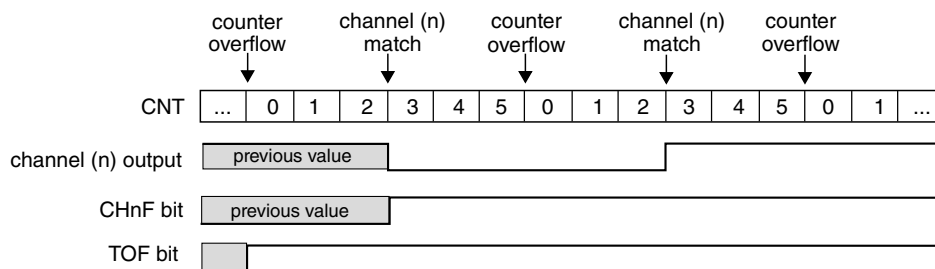


Figure 26-174. Example of the Output Compare mode when the match toggles the channel output

MOD = 0x0005
CnV = 0x0003

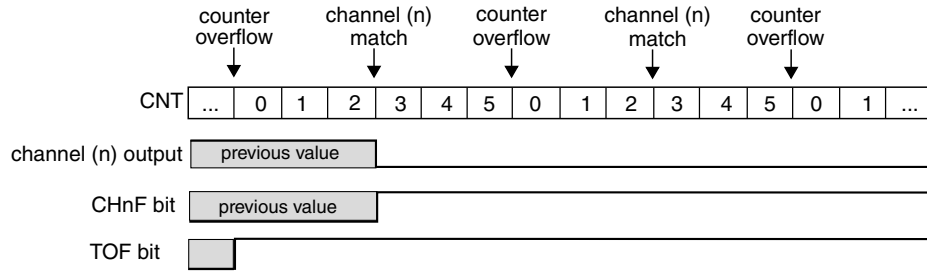


Figure 26-175. Example of the Output Compare mode when the match clears the channel output

MOD = 0x0005
CnV = 0x0003

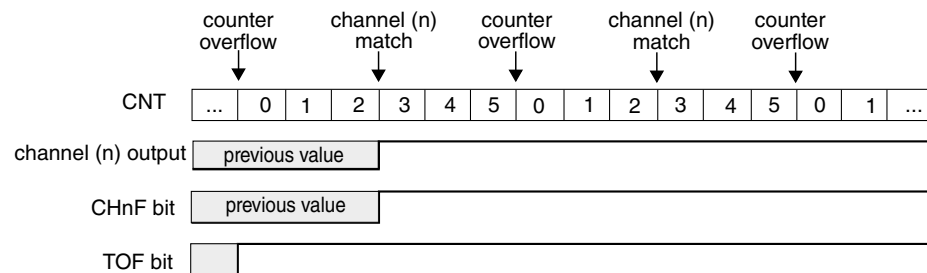


Figure 26-176. Example of the Output Compare mode when the match sets the channel output

If (ELSnB:ELSnA = 0:0) when the counter reaches the value in the CnV register, the CHnF bit is set and the channel (n) interrupt is generated if CHnIE = 1, however the channel (n) output is not modified and controlled by FTM.

26.4.6 Edge-Aligned PWM (EPWM) mode

The Edge-Aligned mode is selected when:

- DECAPEN = 0
- COMBINE = 0
- CPWMS = 0, and
- MSnB = 1

The EPWM period is determined by (MOD – CNTIN + 0x0001) and the pulse width (duty cycle) is determined by (CnV – CNTIN).

The CHnF bit is set and the channel (n) interrupt is generated if CHnIE = 1 at the channel (n) match (FTM counter = CnV), that is, at the end of the pulse width.

This type of PWM signal is called edge-aligned because the leading edges of all PWM signals are aligned with the beginning of the period, which is the same for all channels within an FTM.

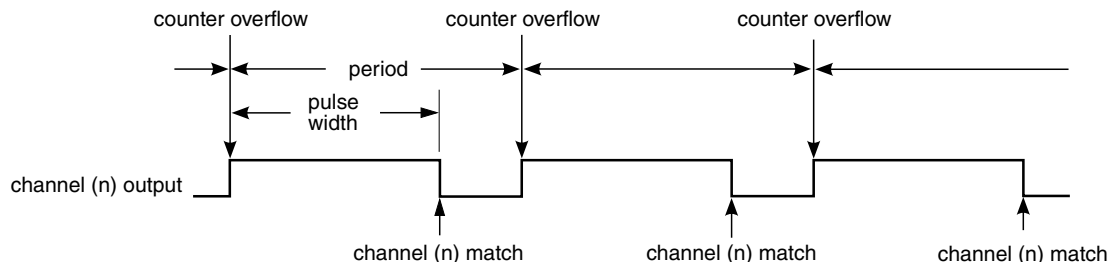


Figure 26-177. EPWM period and pulse width with ELSnB:ELSnA = 1:0

If (ELSnB:ELSnA = 0:0) when the counter reaches the value in the CnV register, the CHnF bit is set and the channel (n) interrupt is generated if CHnIE = 1, however the channel (n) output is not controlled by FTM.

If (ELSnB:ELSnA = 1:0), then the channel (n) output is forced high at the counter overflow when the CNTIN register value is loaded into the FTM counter, and it is forced low at the channel (n) match (FTM counter = CnV). See the following figure.

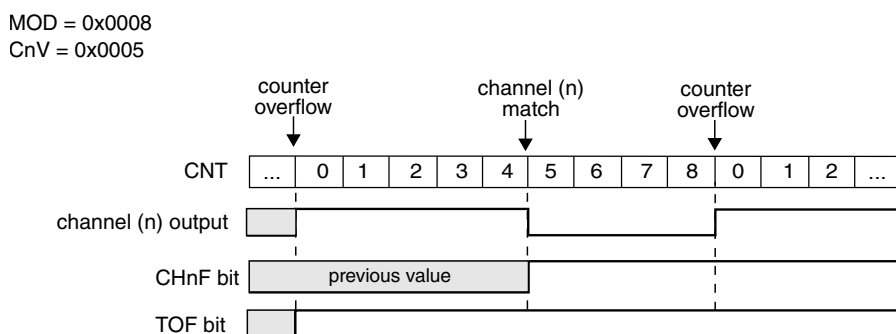


Figure 26-178. EPWM signal with ELSnB:ELSnA = 1:0

If (ELSnB:ELSnA = X:1), then the channel (n) output is forced low at the counter overflow when the CNTIN register value is loaded into the FTM counter, and it is forced high at the channel (n) match (FTM counter = CnV). See the following figure.

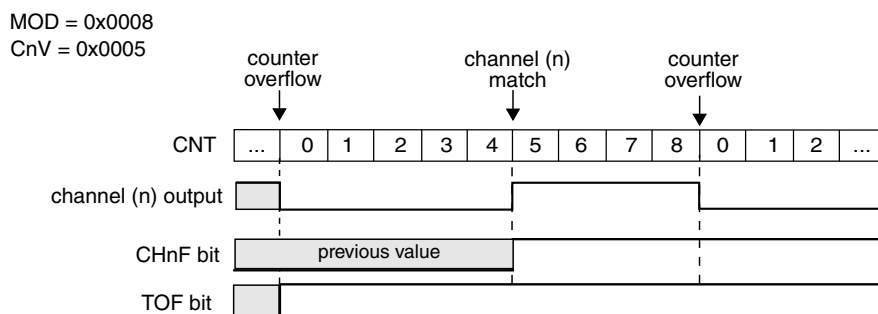


Figure 26-179. EPWM signal with ELSnB:ELSnA = X:1

If ($CnV = 0x0000$), then the channel (n) output is a 0% duty cycle EPWM signal and CHnF bit is not set even when there is the channel (n) match. If ($CnV > MOD$), then the channel (n) output is a 100% duty cycle EPWM signal and CHnF bit is not set even when there is the channel (n) match. Therefore, MOD must be less than 0xFFFF in order to get a 100% duty cycle EPWM signal.

Note

When CNTIN is different from zero the following EPWM signals can be generated:

- 0% EPWM signal if $CnV = CNTIN$,
- EPWM signal between 0% and 100% if $CNTIN < CnV \leq MOD$,
- 100% EPWM signal when $CNTIN > CnV$ or $CnV > MOD$.

26.4.7 Center-Aligned PWM (CPWM) mode

The Center-Aligned mode is selected when:

- $DECAPEN = 0$
- $COMBINE = 0$, and
- $CPWMS = 1$

The CPWM pulse width (duty cycle) is determined by $2 \times (CnV - CNTIN)$ and the period is determined by $2 \times (MOD - CNTIN)$. See the following figure. MOD must be kept in the range of 0x0001 to 0x7FFF because values outside this range can produce ambiguous results.

In the CPWM mode, the FTM counter counts up until it reaches MOD and then counts down until it reaches CNTIN.

The CHnF bit is set and channel (n) interrupt is generated (if CHnIE = 1) at the channel (n) match (FTM counter = CnV) when the FTM counting is down (at the begin of the pulse width) and when the FTM counting is up (at the end of the pulse width).

This type of PWM signal is called center-aligned because the pulse width centers for all channels are aligned with the value of CNTIN.

The other channel modes are not compatible with the up-down counter ($CPWMS = 1$). Therefore, all FTM channels must be used in CPWM mode when ($CPWMS = 1$).

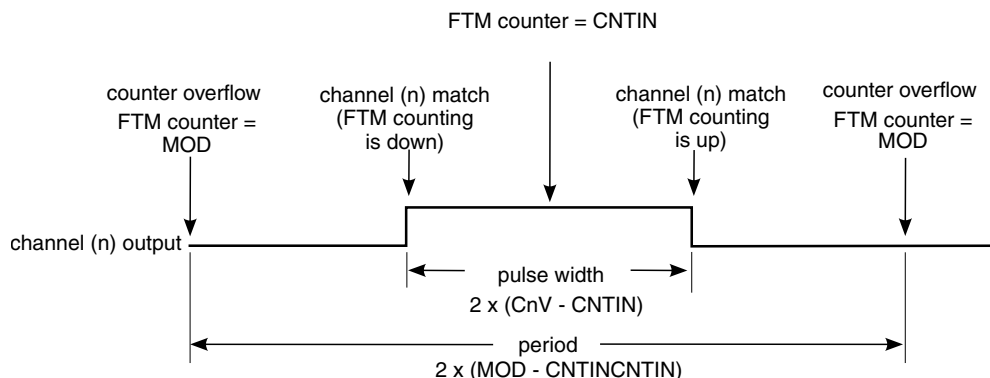


Figure 26-180. CPWM period and pulse width with ELSnB:ELSnA = 1:0

If (ELSnB:ELSnA = 0:0) when the FTM counter reaches the value in the CnV register, the CHnF bit is set and the channel (n) interrupt is generated (if CHnIE = 1), however the channel (n) output is not controlled by FTM.

If (ELSnB:ELSnA = 1:0), then the channel (n) output is forced high at the channel (n) match (FTM counter = CnV) when counting down, and it is forced low at the channel (n) match when counting up. See the following figure.

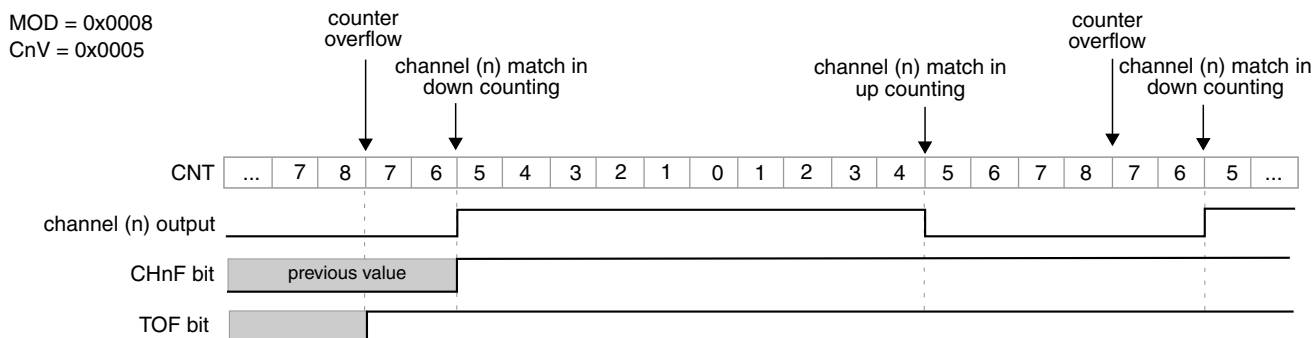


Figure 26-181. CPWM signal with ELSnB:ELSnA = 1:0

If (ELSnB:ELSnA = X:1), then the channel (n) output is forced low at the channel (n) match (FTM counter = CnV) when counting down, and it is forced high at the channel (n) match when counting up. See the following figure.

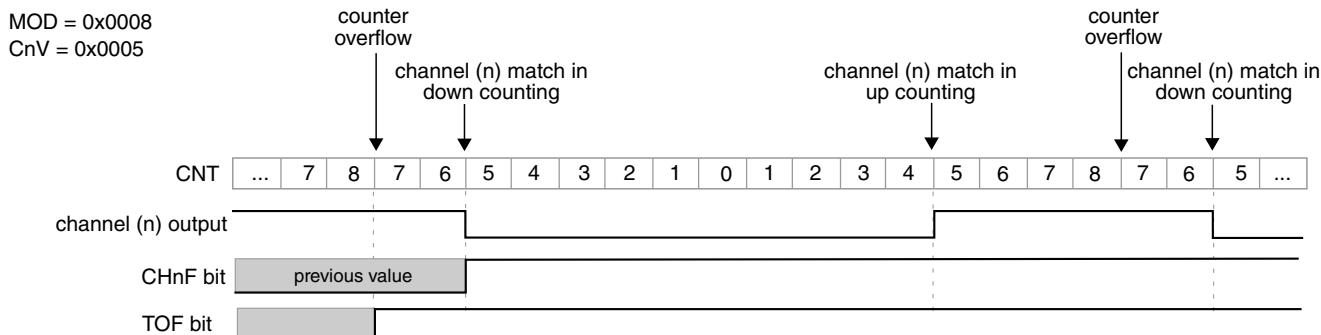


Figure 26-182. CPWM signal with ELSnB:ELSnA = X:1

If ($CnV = 0x0000$) or CnV is a negative value, that is ($CnV[15] = 1$), then the channel (n) output is a 0% duty cycle CPWM signal and $CHnF$ bit is not set even when there is the channel (n) match.

If CnV is a positive value, that is ($CnV[15] = 0$), ($CnV \geq MOD$), and ($MOD \neq 0x0000$), then the channel (n) output is a 100% duty cycle CPWM signal and $CHnF$ bit is not set even when there is the channel (n) match. This implies that the usable range of periods set by MOD is $0x0001$ through $0x7FFE$, $0x7FFF$ if you do not need to generate a 100% duty cycle CPWM signal. This is not a significant limitation because the resulting period is much longer than required for normal applications.

The CPWM mode must not be used when the FTM counter is a free running counter.

26.4.8 Combine mode

The Combine mode is selected when:

- $DECAPEN = 0$
- $COMBINE = 1$, and
- $CPWMS = 0$

In Combine mode, an even channel (n) and adjacent odd channel (n+1) are combined to generate a PWM signal in the channel (n) output.

In the Combine mode, the PWM period is determined by $(MOD - CNTIN + 0x0001)$ and the PWM pulse width (duty cycle) is determined by $(IC(n+1)V - C(n)V)$.

The $CHnF$ bit is set and the channel (n) interrupt is generated (if $CHnIE = 1$) at the channel (n) match (FTM counter = $C(n)V$). The $CH(n+1)F$ bit is set and the channel (n+1) interrupt is generated, if $CH(n+1)IE = 1$, at the channel (n+1) match (FTM counter = $C(n+1)V$).

If ($ELSnB:ELSnA = 1:0$), then the channel (n) output is forced low at the beginning of the period (FTM counter = $CNTIN$) and at the channel (n+1) match (FTM counter = $C(n+1)V$). It is forced high at the channel (n) match (FTM counter = $C(n)V$). See the following figure.

If ($ELSnB:ELSnA = X:1$), then the channel (n) output is forced high at the beginning of the period (FTM counter = $CNTIN$) and at the channel (n+1) match (FTM counter = $C(n+1)V$). It is forced low at the channel (n) match (FTM counter = $C(n)V$). See the following figure.

Functional description

In Combine mode, the ELS(n+1)B and ELS(n+1)A bits are not used in the generation of the channels (n) and (n+1) output. However, if (ELSnB:ELSnA = 0:0) then the channel (n) output is not controlled by FTM, and if (ELS(n+1)B:ELS(n+1)A = 0:0) then the channel (n+1) output is not controlled by FTM.

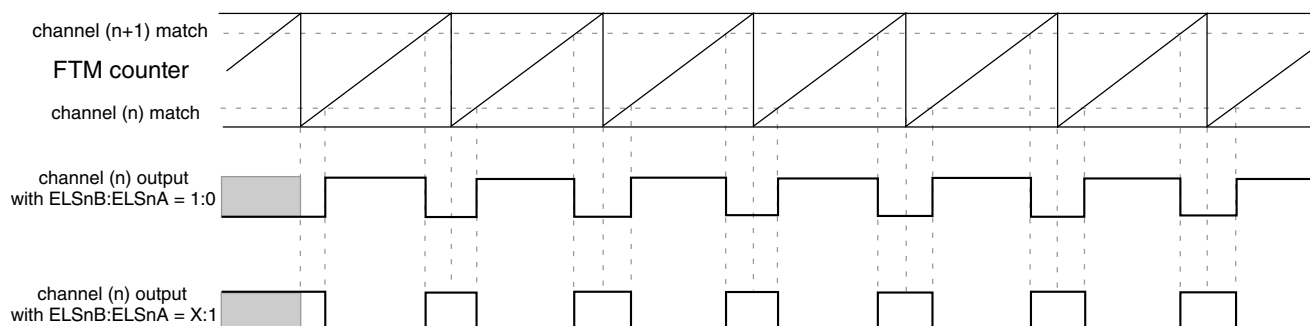


Figure 26-183. Combine mode

The following figures illustrate the PWM signals generation using Combine mode.

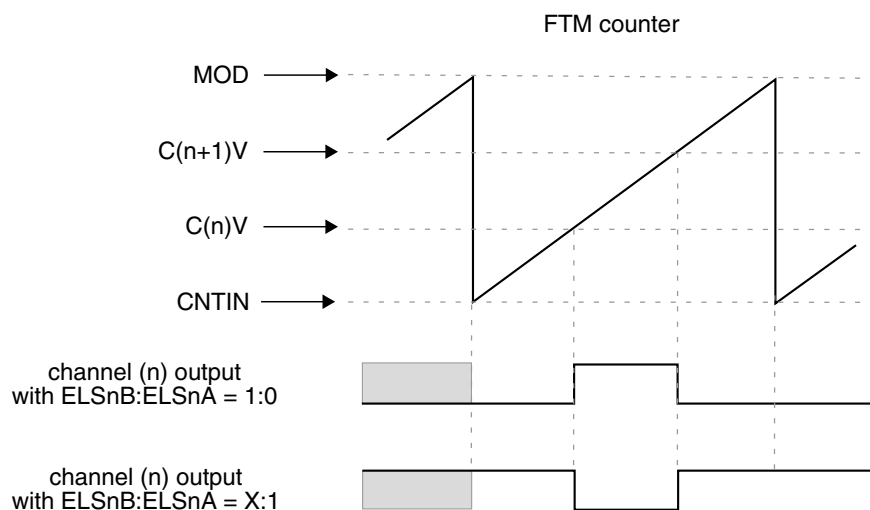


Figure 26-184. Channel (n) output if (CNTIN < C(n)V < MOD) and (CNTIN < C(n+1)V < MOD) and (C(n)V < C(n+1)V)

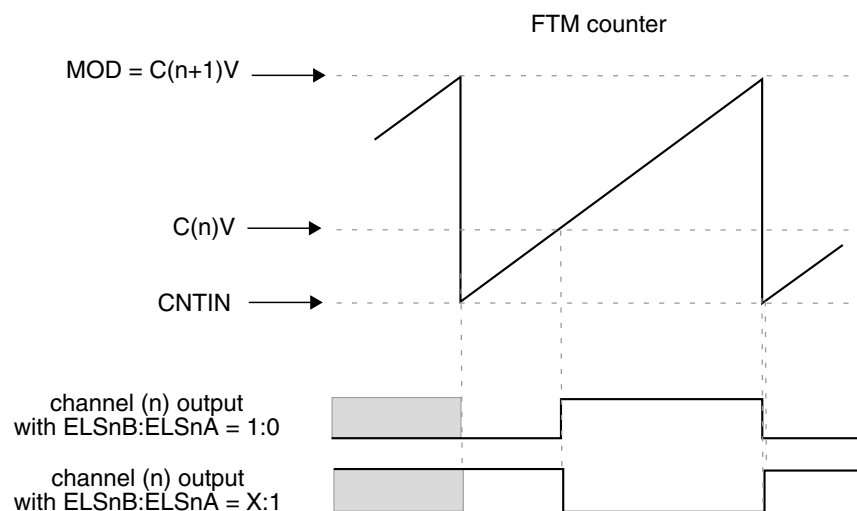


Figure 26-185. Channel (n) output if $(CNTIN < C(n)V < MOD)$ and $(C(n+1)V = MOD)$

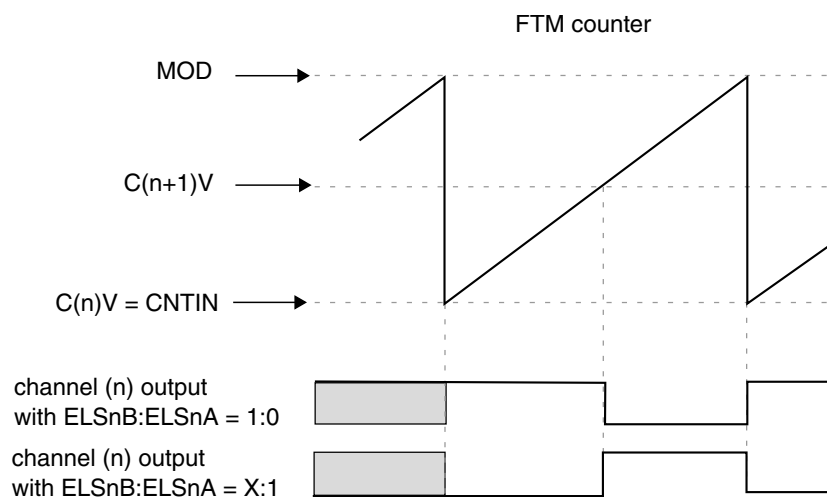


Figure 26-186. Channel (n) output if $(C(n)V = CNTIN)$ and $(CNTIN < C(n+1)V < MOD)$

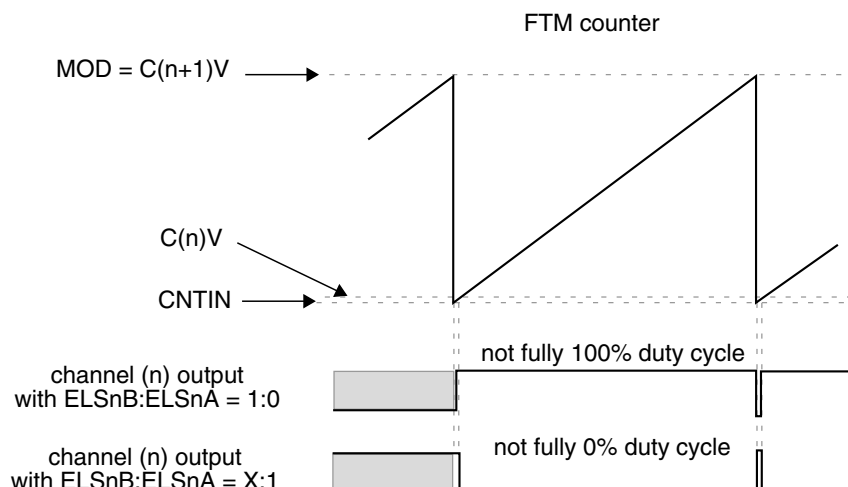


Figure 26-187. Channel (n) output if $(CNTIN < C(n)V < MOD)$ and $(C(n)V$ is Almost Equal to $CNTIN$) and $(C(n+1)V = MOD)$

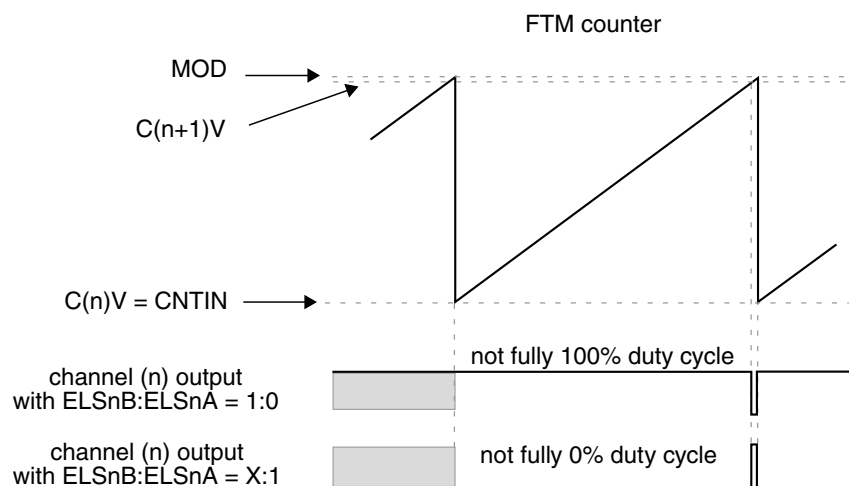


Figure 26-188. Channel (n) output if $(C(n)V = CNTIN)$ and $(CNTIN < C(n+1)V < MOD)$ and $(C(n+1)V$ is Almost Equal to MOD)

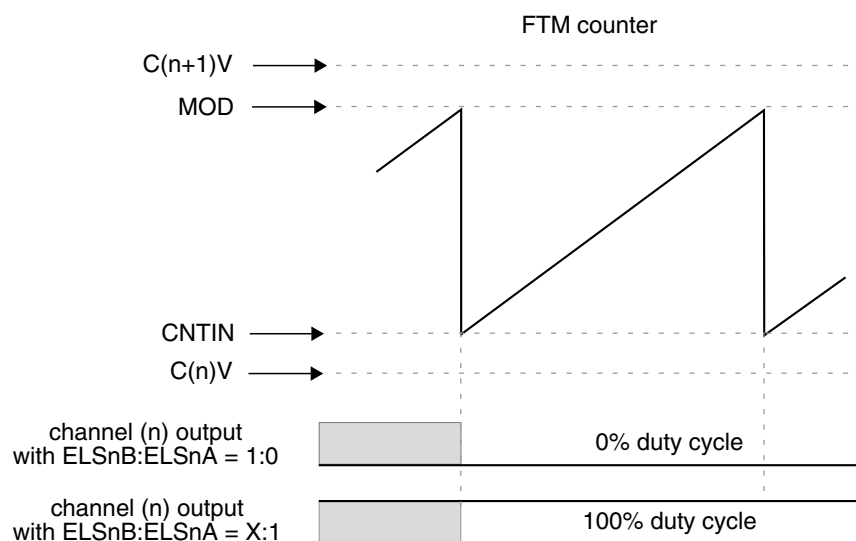


Figure 26-189. Channel (n) output if $C(n)V$ and $C(n+1)V$ are not between CNTIN and MOD

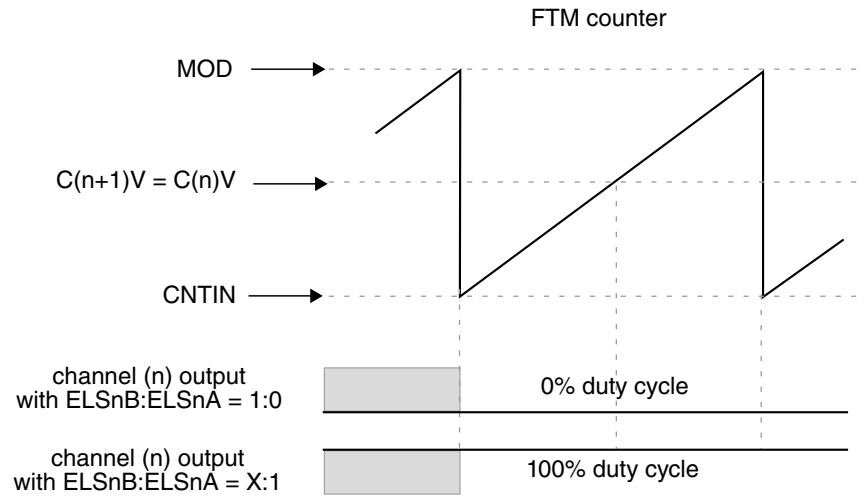


Figure 26-190. Channel (n) output if $(CNTIN < C(n)V < MOD)$ and $(CNTIN < C(n+1)V < MOD)$ and $(C(n)V = C(n+1)V)$

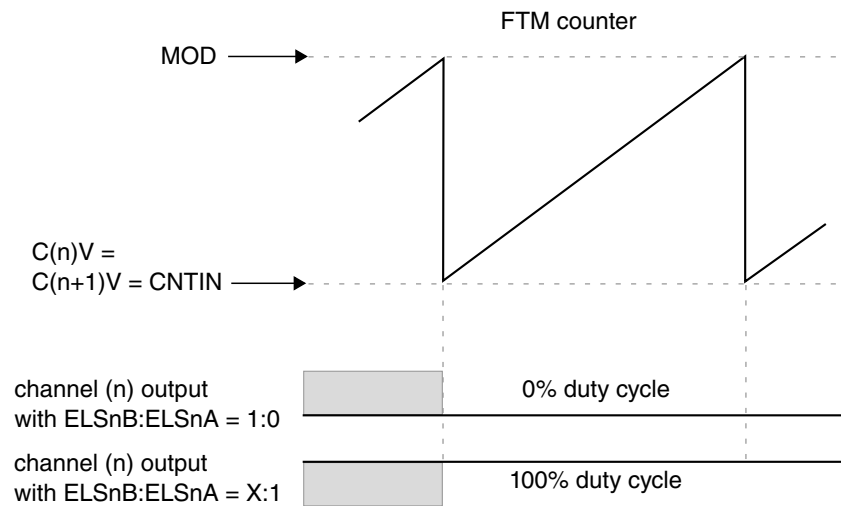


Figure 26-191. Channel (n) output if $(C(n)V = C(n+1)V = CNTIN)$

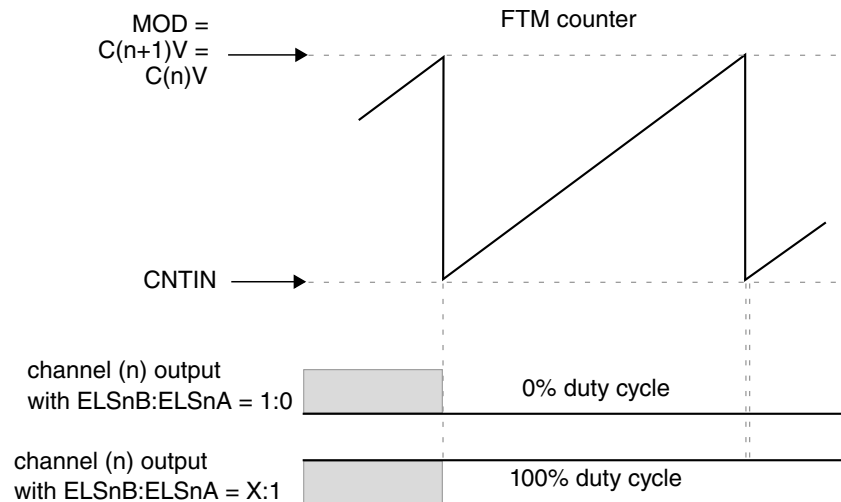


Figure 26-192. Channel (n) output if $(C(n)V = C(n+1)V = MOD)$

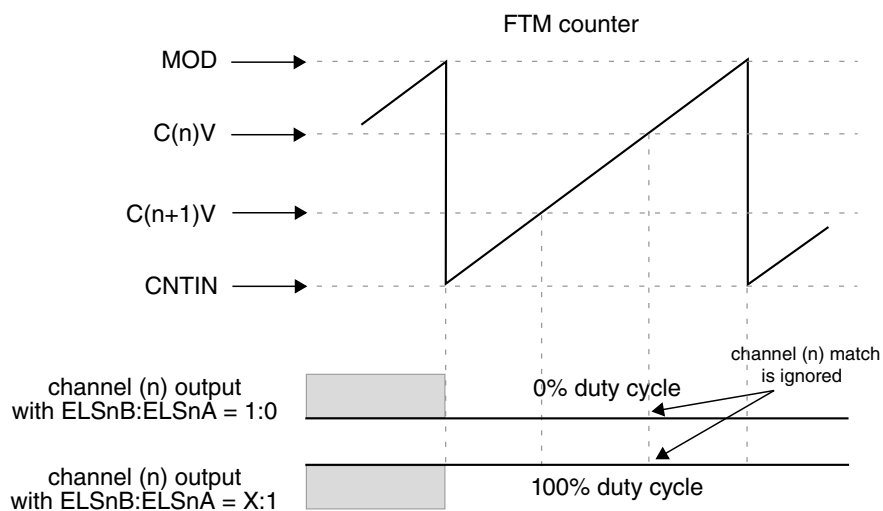


Figure 26-193. Channel (n) output if $(CNTIN < C(n)V < MOD)$ and $(CNTIN < C(n+1)V < MOD)$ and $(C(n)V > C(n+1)V)$

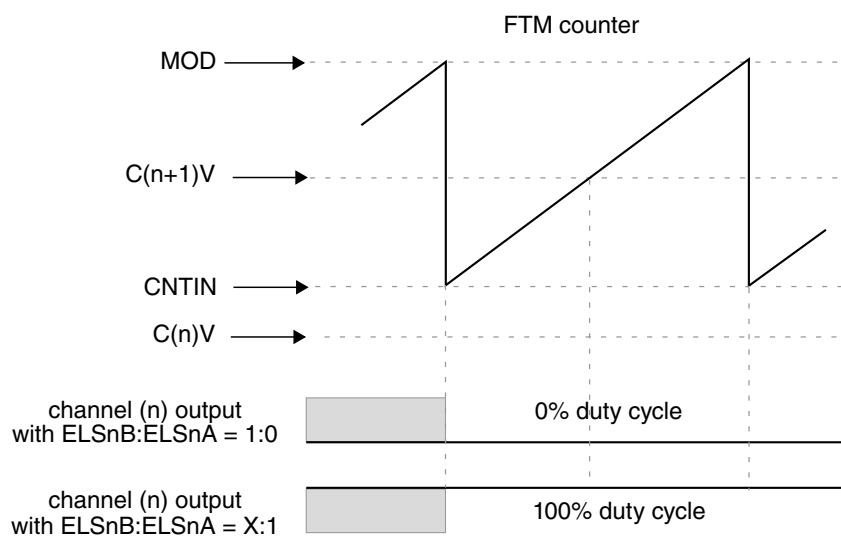


Figure 26-194. Channel (n) output if $(C(n)V < CNTIN)$ and $(CNTIN < C(n+1)V < MOD)$

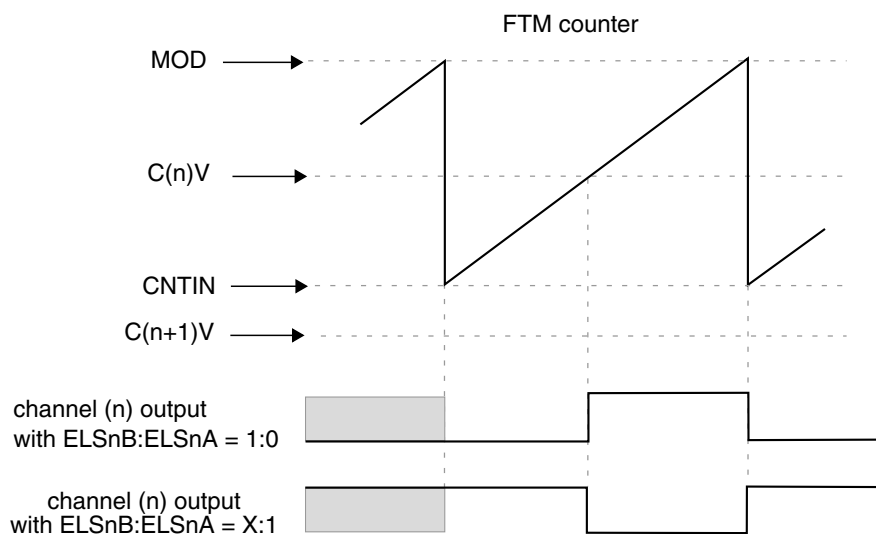


Figure 26-195. Channel (n) output if $(C(n+1)V < CNTIN)$ and $(CNTIN < C(n)V < MOD)$

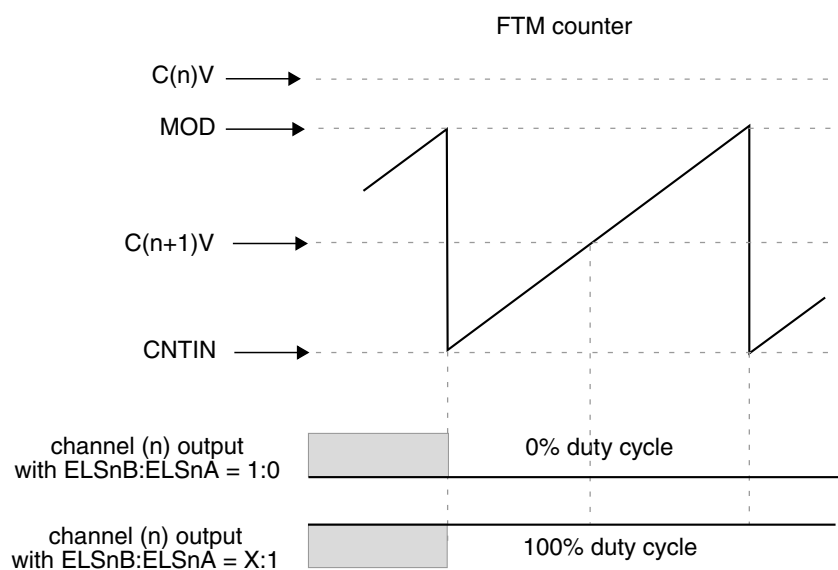


Figure 26-196. Channel (n) output if $(C(n)V > MOD)$ and $(CNTIN < C(n+1)V < MOD)$

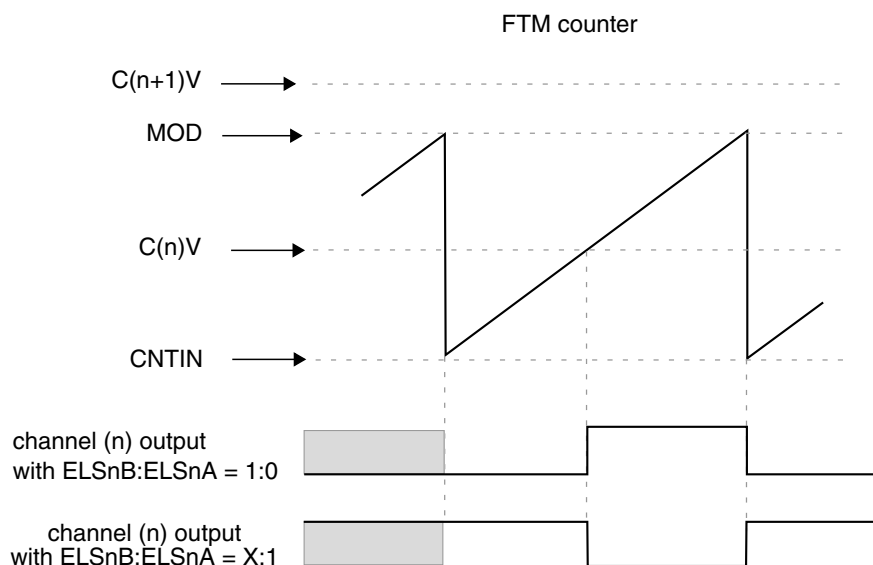


Figure 26-197. Channel (n) output if $(C(n+1)V > MOD)$ and $(CNTIN < C(n)V < MOD)$

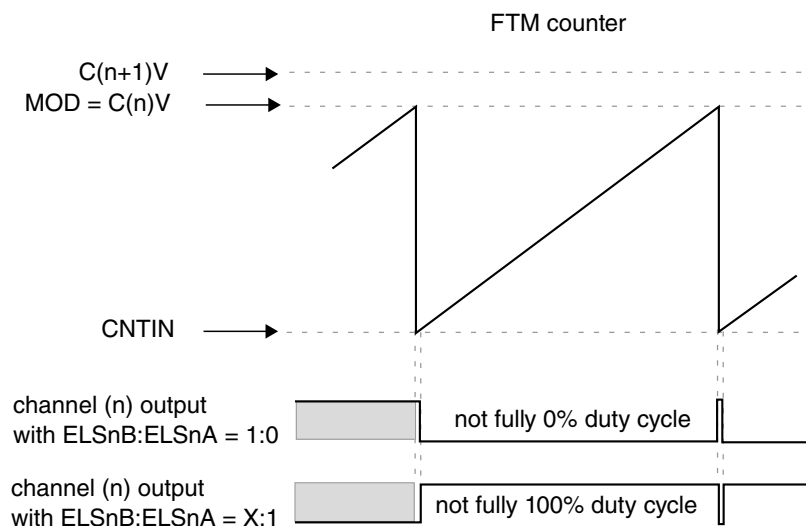


Figure 26-198. Channel (n) output if $(C(n+1)V > MOD)$ and $(CNTIN < C(n)V = MOD)$

26.4.8.1 Asymmetrical PWM

In Combine mode, the control of the PWM signal first edge, when the channel (n) match occurs, that is, $FTM\ counter = C(n)V$, is independent of the control of the PWM signal second edge, when the channel (n+1) match occurs, that is, $FTM\ counter = C(n+1)V$. So, Combine mode allows the generation of asymmetrical PWM signals.

26.4.9 Complementary mode

The Complementary mode is selected when:

- $DECAPEN = 0$
- $COMP = 1$

In Complementary mode, the channel (n+1) output is the inverse of the channel (n) output.

So, the channel (n+1) output is the same as the channel (n) output when:

- $DECAPEN = 0$
- $COMP = 0$

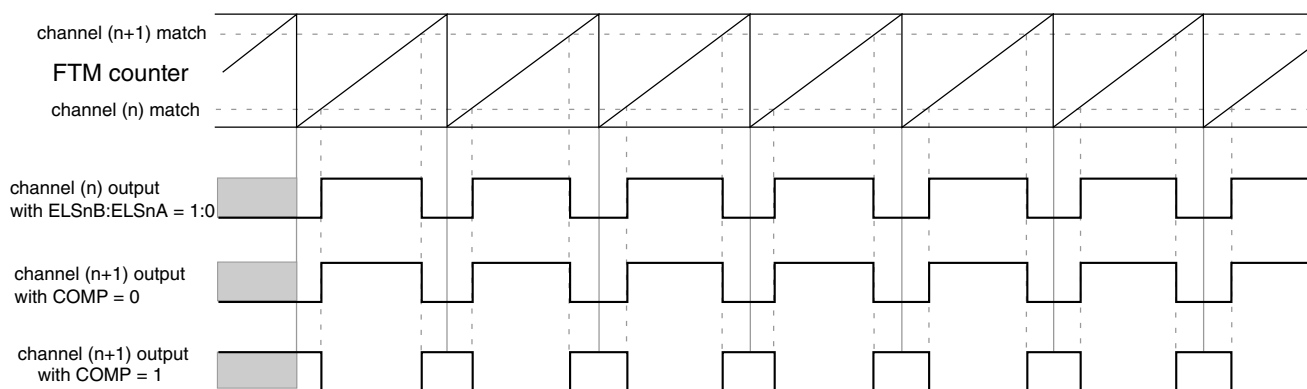


Figure 26-199. Channel (n+1) output in Complementary mode with ($ELSnB:ELSnA = 1:0$)

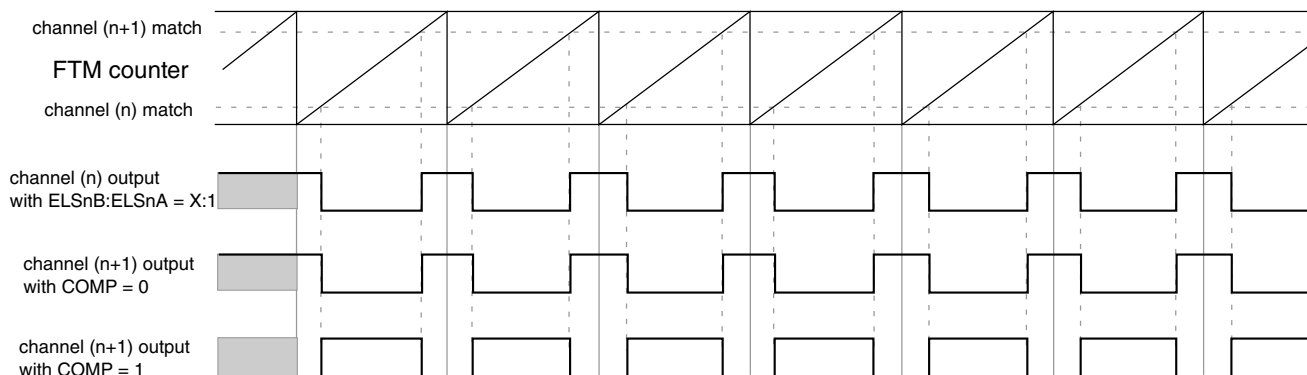


Figure 26-200. Channel (n+1) output in Complementary mode with ($ELSnB:ELSnA = X:1$)

NOTE

The complementary mode is not available in Output Compare mode.

26.4.10 Registers updated from write buffers

26.4.10.1 CNTIN register update

The following table describes when CNTIN register is updated:

Table 26-239. CNTIN register update

| When | Then CNTIN register is updated |
|---|---|
| CLKS[1:0] = 0:0 | When CNTIN register is written, independent of FTMEN bit. |
| <ul style="list-style-type: none"> FTMEN = 0, or CNTINC = 0 | At the next system clock after CNTIN was written. |
| <ul style="list-style-type: none"> FTMEN = 1, SYNCMODE = 1, and CNTINC = 1 | By the CNTIN register synchronization . |

26.4.10.2 MOD register update

The following table describes when MOD register is updated:

Table 26-240. MOD register update

| When | Then MOD register is updated |
|---|---|
| CLKS[1:0] = 0:0 | When MOD register is written, independent of FTMEN bit. |
| <ul style="list-style-type: none"> CLKS[1:0] ≠ 0:0, and FTMEN = 0 | According to the CPWMS bit, that is: <ul style="list-style-type: none"> If the selected mode is not CPWM then MOD register is updated after MOD register was written and the FTM counter changes from MOD to CNTIN. If the FTM counter is at free-running counter mode then this update occurs when the FTM counter changes from 0xFFFF to 0x0000. If the selected mode is CPWM then MOD register is updated after MOD register was written and the FTM counter changes from MOD to (MOD – 0x0001). |
| <ul style="list-style-type: none"> CLKS[1:0] ≠ 0:0, and FTMEN = 1 | By the MOD register synchronization . |

26.4.10.3 CnV register update

The following table describes when CnV register is updated:

Table 26-241. CnV register update

| When | Then CnV register is updated |
|---|---|
| CLKS[1:0] = 0:0 | When CnV register is written, independent of FTMEN bit. |
| <ul style="list-style-type: none"> CLKS[1:0] ≠ 0:0, and FTMEN = 0 | According to the selected mode, that is: |

Table continues on the next page...

Table 26-241. CnV register update (continued)

| When | Then CnV register is updated |
|---|---|
| | <ul style="list-style-type: none"> If the selected mode is Output Compare, then CnV register is updated on the next FTM counter change, end of the prescaler counting, after CnV register was written. If the selected mode is EPWM, then CnV register is updated after CnV register was written and the FTM counter changes from MOD to CNTIN. If the FTM counter is at free-running counter mode then this update occurs when the FTM counter changes from 0xFFFF to 0x0000. If the selected mode is CPWM, then CnV register is updated after CnV register was written and the FTM counter changes from MOD to (MOD – 0x0001). |
| <ul style="list-style-type: none"> CLKS[1:0] ≠ 0:0, and FTMEN = 1 | <p>According to the selected mode, that is:</p> <ul style="list-style-type: none"> If the selected mode is output compare then CnV register is updated according to the SYNCEN bit. If (SYNCEN = 0) then CnV register is updated after CnV register was written at the next change of the FTM counter, the end of the prescaler counting. If (SYNCEN = 1) then CnV register is updated by the C(n)V and C(n+1)V register synchronization. If the selected mode is not output compare and (SYNCEN = 1) then CnV register is updated by the C(n)V and C(n+1)V register synchronization. |

26.4.11 PWM synchronization

The PWM synchronization provides an opportunity to update the MOD, CNTIN, CnV, OUTMASK, INVCTRL and SWOCTRL registers with their buffered value and force the FTM counter to the CNTIN register value.

Note

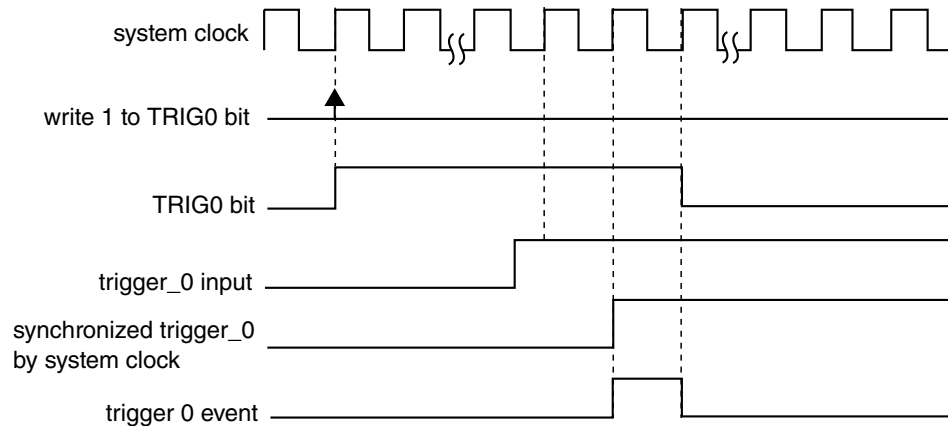
The legacy PWM synchronization (SYNCMODE = 0) is a subset of the enhanced PWM synchronization (SYNCMODE = 1). Thus, only the enhanced PWM synchronization must be used.

26.4.11.1 Hardware trigger

Three hardware trigger signal inputs of the FTM module are enabled when TRIGn = 1, where n = 0, 1 or 2 corresponding to each one of the input signals, respectively. The hardware trigger input n is synchronized by the system clock. The PWM synchronization with hardware trigger is initiated when a rising edge is detected at the enabled hardware trigger inputs.

If (HWTRIGMODE = 0) then the TRIGn bit is cleared when 0 is written to it or when the trigger n event is detected.

In this case, if two or more hardware triggers are enabled (for example, TRIG0 and TRIG1 = 1) and only trigger 1 event occurs, then only TRIG1 bit is cleared. If a trigger n event occurs together with a write setting TRIGn bit, then the synchronization is initiated, but TRIGn bit remains set due to the write operation.



Note
All hardware trigger inputs have the same behavior.

Figure 26-201. Hardware trigger event with HWTRIGMODE = 0

If HWTRIGMODE = 1, then the TRIGn bit is only cleared when 0 is written to it.

NOTE

The HWTRIGMODE bit must be 1 only with enhanced PWM synchronization (SYNCMODE = 1).

26.4.11.2 Software trigger

A software trigger event occurs when 1 is written to the SYNC[SWSYNC] bit. The SWSYNC bit is cleared when 0 is written to it or when the PWM synchronization, initiated by the software event, is completed.

If another software trigger event occurs (by writing another 1 to the SWSYNC bit) at the same time the PWM synchronization initiated by the previous software trigger event is ending, a new PWM synchronization is started and the SWSYNC bit remains equal to 1.

If SYNCMODE = 0 then the SWSYNC bit is also cleared by FTM according to PWMSYNC and REINIT bits. In this case if (PWMSYNC = 1) or (PWMSYNC = 0 and REINIT = 0) then SWSYNC bit is cleared at the next selected loading point after that the software trigger event occurred; see [Boundary cycle and loading points](#) and the following figure. If (PWMSYNC = 0) and (REINIT = 1) then SWSYNC bit is cleared when the software trigger event occurs.

If SYNCMODE = 1 then the SWSYNC bit is also cleared by FTM according to the SWRSTCNT bit. If SWRSTCNT = 0 then SWSYNC bit is cleared at the next selected loading point after that the software trigger event occurred; see the following figure. If SWRSTCNT = 1 then SWSYNC bit is cleared when the software trigger event occurs.

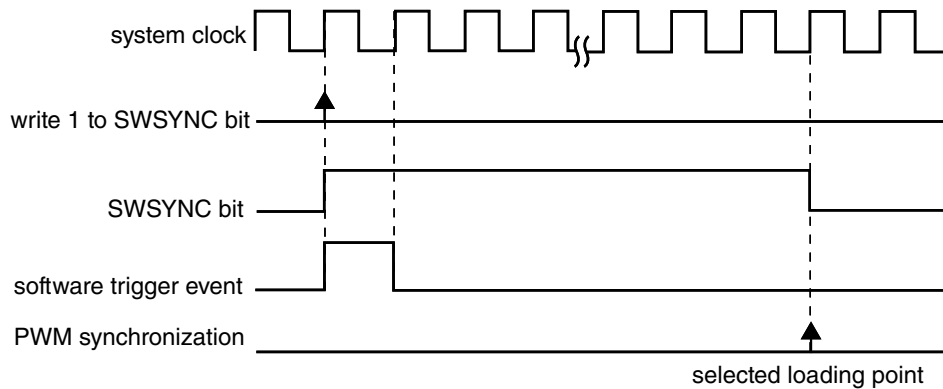


Figure 26-202. Software trigger event

26.4.11.3 Boundary cycle and loading points

The boundary cycle definition is important for the loading points for the registers MOD, CNTIN, and C(n)V.

In **Up counting** mode, the boundary cycle is defined as when the counter wraps to its initial value (CNTIN). If in **Up-down counting** mode, then the boundary cycle is defined as when the counter turns from down to up counting and when from up to down counting.

The following figure shows the boundary cycles and the loading points for the registers. In the Up Counting mode, the loading points are enabled if one of CNTMIN or CTMAX bits are 1. In the Up-Down Counting mode, the loading points are selected by CNTMIN and CNTMAX bits, as indicated in the figure. These loading points are safe places for register updates thus allowing a smooth transitions in PWM waveform generation.

For both counting modes, if neither CNTMIN nor CNTMAX are 1, then the boundary cycles are not used as loading points for registers updates. See the register synchronization descriptions in the following sections for details.

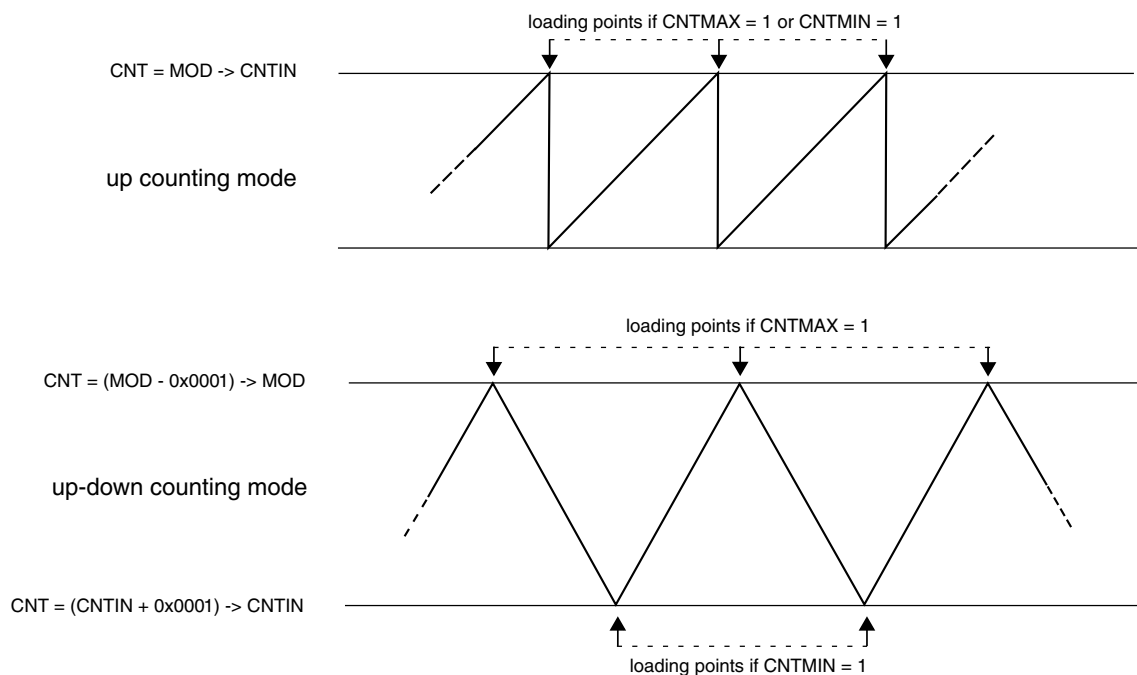


Figure 26-203. Boundary cycles and loading points

26.4.11.4 MOD register synchronization

The MOD register synchronization updates the MOD register with its buffer value. This synchronization is enabled if (FTMEN = 1).

The MOD register synchronization can be done by either the enhanced PWM synchronization (SYNCMODE = 1) or the legacy PWM synchronization (SYNCMODE = 0). However, it is expected that the MOD register be synchronized only by the enhanced PWM synchronization.

In the case of enhanced PWM synchronization, the MOD register synchronization depends on SWWRBUF, SWRSTCNT, HWWRBUF, and HWRSTCNT bits according to this flowchart:

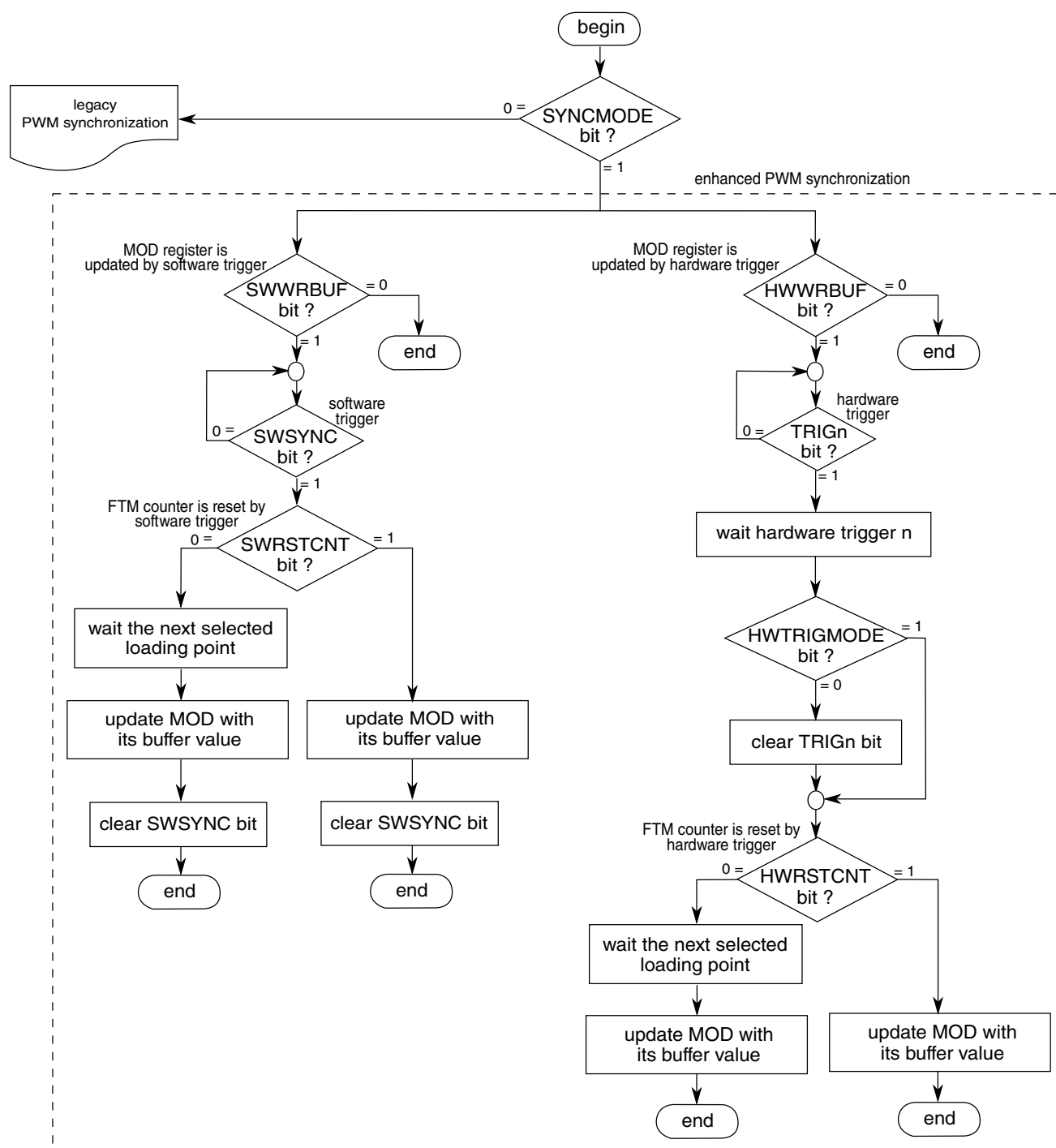


Figure 26-204. MOD register synchronization flowchart

In the case of legacy PWM synchronization, the MOD register synchronization depends on PWMSYNC and REINIT bits according to the following description.

If (SYNCMODE = 0), (PWMSYNC = 0), and (REINIT = 0), then this synchronization is made on the next selected loading point after an enabled trigger event takes place. If the trigger event was a software trigger, then the SWSYNC bit is cleared on the next selected

loading point. If the trigger event was a hardware trigger, then the trigger enable bit (TRIGn) is cleared according to [Hardware trigger](#). Examples with software and hardware triggers follow.

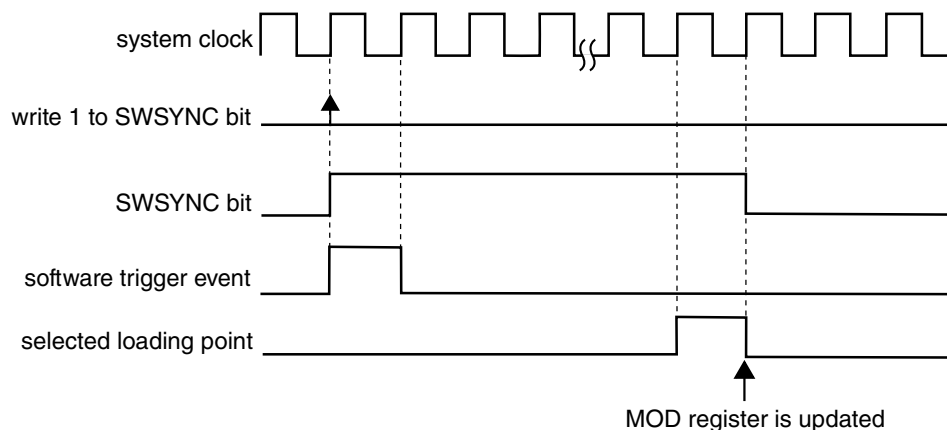


Figure 26-205. MOD synchronization with (SYNCMODE = 0), (PWMSYNC = 0), (REINIT = 0), and software trigger was used

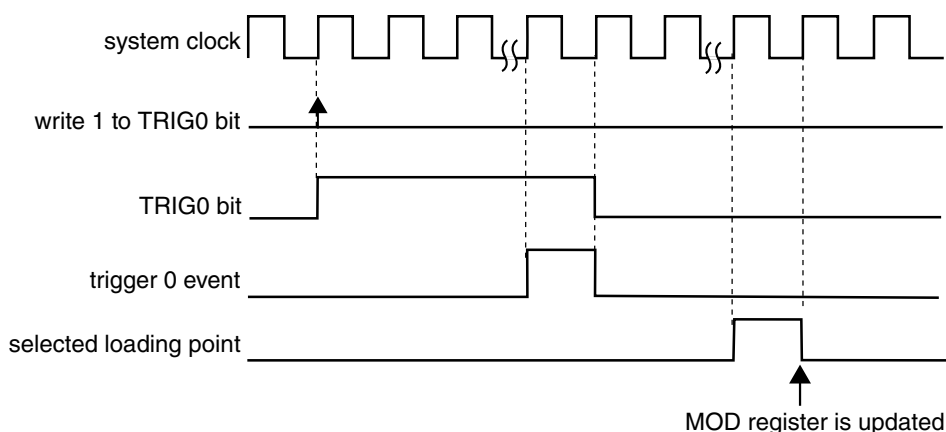


Figure 26-206. MOD synchronization with (SYNCMODE = 0), (HWTRIGMODE = 0), (PWMSYNC = 0), (REINIT = 0), and a hardware trigger was used

If (SYNCMODE = 0), (PWMSYNC = 0), and (REINIT = 1), then this synchronization is made on the next enabled trigger event. If the trigger event was a software trigger, then the SWSYNC bit is cleared according to the following example. If the trigger event was a hardware trigger, then the TRIGn bit is cleared according to [Hardware trigger](#). Examples with software and hardware triggers follow.

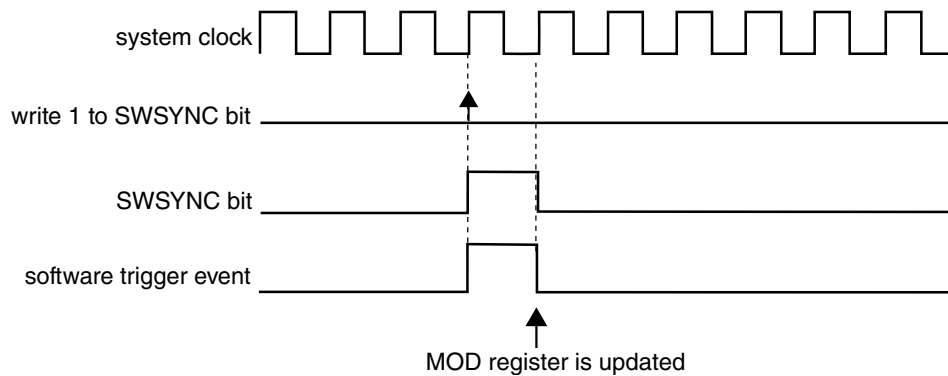


Figure 26-207. MOD synchronization with (SYNCMODE = 0), (PWMSYNC = 0), (REINIT = 1), and software trigger was used

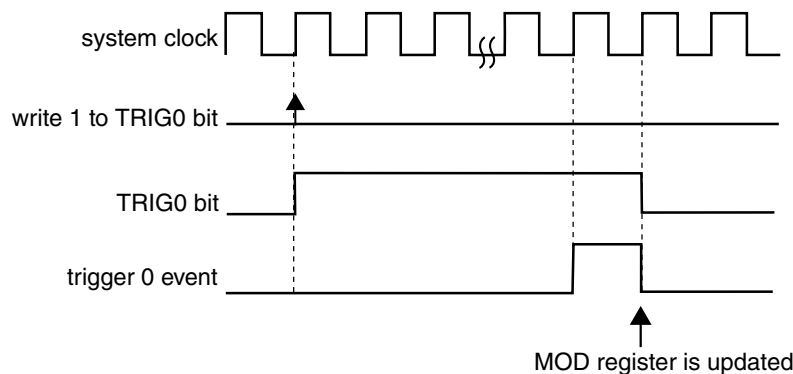


Figure 26-208. MOD synchronization with (SYNCMODE = 0), (HWTRIGMODE = 0), (PWMSYNC = 0), (REINIT = 1), and a hardware trigger was used

If (SYNCMODE = 0) and (PWMSYNC = 1), then this synchronization is made on the next selected loading point after the software trigger event takes place. The SWSYNC bit is cleared on the next selected loading point:

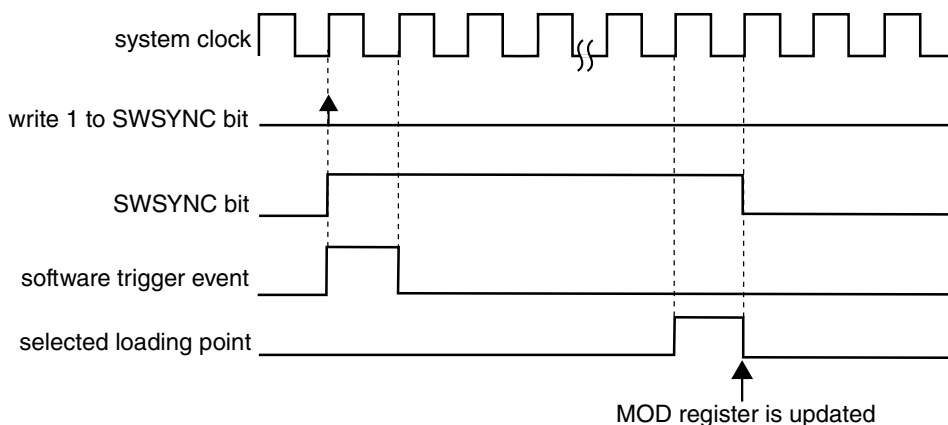


Figure 26-209. MOD synchronization with (SYNCMODE = 0) and (PWMSYNC = 1)

26.4.11.5 CNTIN register synchronization

The CNTIN register synchronization updates the CNTIN register with its buffer value.

This synchronization is enabled if (FTMEN = 1), (SYNCMODE = 1), and (CNTINC = 1). The CNTIN register synchronization can be done only by the enhanced PWM synchronization (SYNCMODE = 1). The synchronization mechanism is the same as the MOD register synchronization done by the enhanced PWM synchronization; see [MOD register synchronization](#).

26.4.11.6 C(n)V and C(n+1)V register synchronization

The C(n)V and C(n+1)V registers synchronization updates the C(n)V and C(n+1)V registers with their buffer values.

This synchronization is enabled if (FTMEN = 1) and (SYNCEN = 1). The synchronization mechanism is the same as the [MOD register synchronization](#). However, it is expected that the C(n)V and C(n+1)V registers be synchronized only by the enhanced PWM synchronization (SYNCMODE = 1).

26.4.11.7 OUTMASK register synchronization

The OUTMASK register synchronization updates the OUTMASK register with its buffer value.

The OUTMASK register can be updated at each rising edge of system clock (SYNCHOM = 0), by the enhanced PWM synchronization (SYNCHOM = 1 and SYNCMODE = 1) or by the legacy PWM synchronization (SYNCHOM = 1 and SYNCMODE = 0). However, it is expected that the OUTMASK register be synchronized only by the enhanced PWM synchronization.

In the case of enhanced PWM synchronization, the OUTMASK register synchronization depends on SWOM and HWOM bits. See the following flowchart:

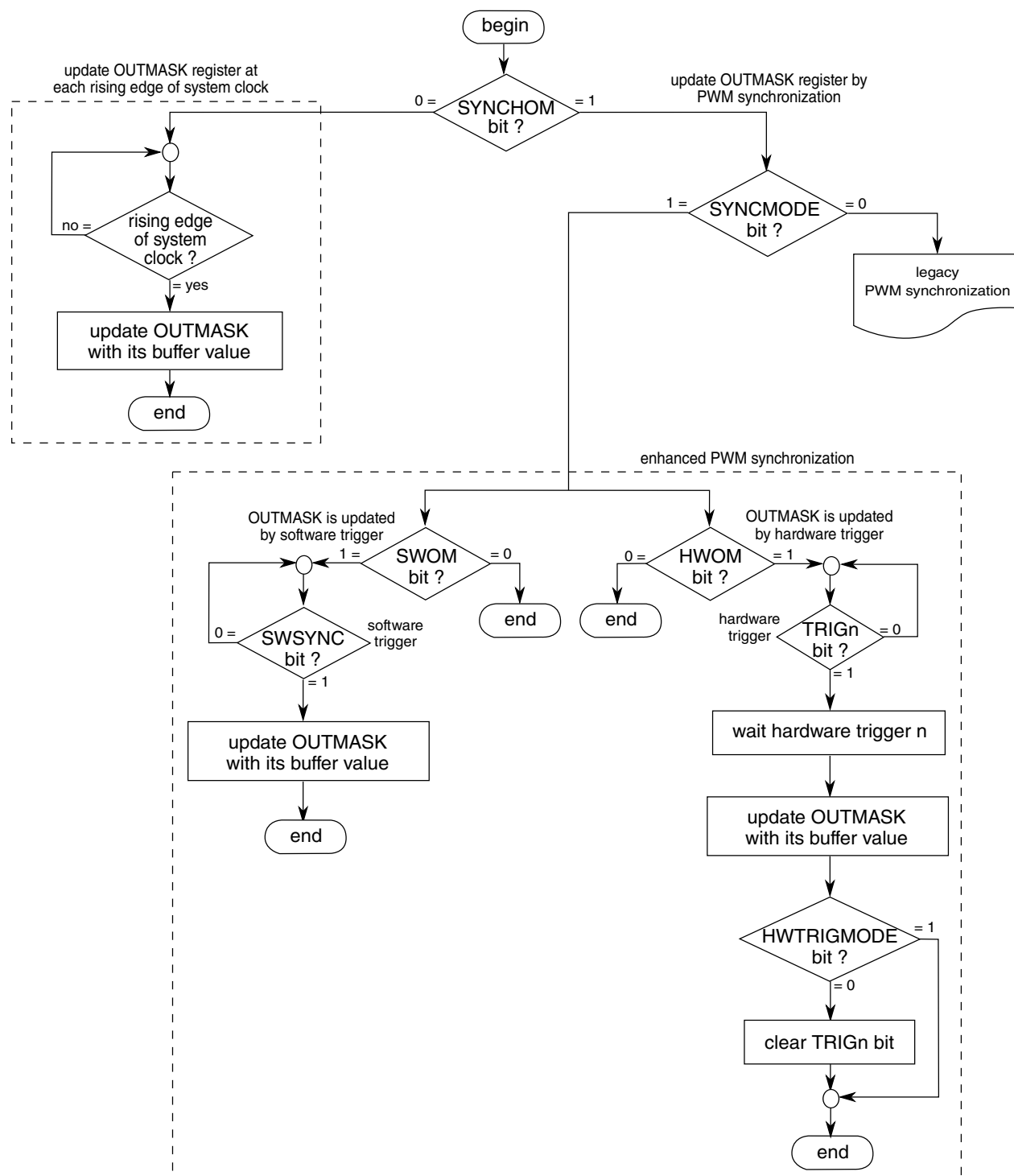


Figure 26-210. OUTMASK register synchronization flowchart

In the case of legacy PWM synchronization, the OUTMASK register synchronization depends on PWMSYNC bit according to the following description.

If (SYNCMODE = 0), (SYNCHOM = 1), and (PWMSYNC = 0), then this synchronization is done on the next enabled trigger event. If the trigger event was a software trigger, then the SWSYNC bit is cleared on the next selected loading point. If the trigger event was a hardware trigger, then the TRIGN bit is cleared according to [Hardware trigger](#). Examples with software and hardware triggers follow.

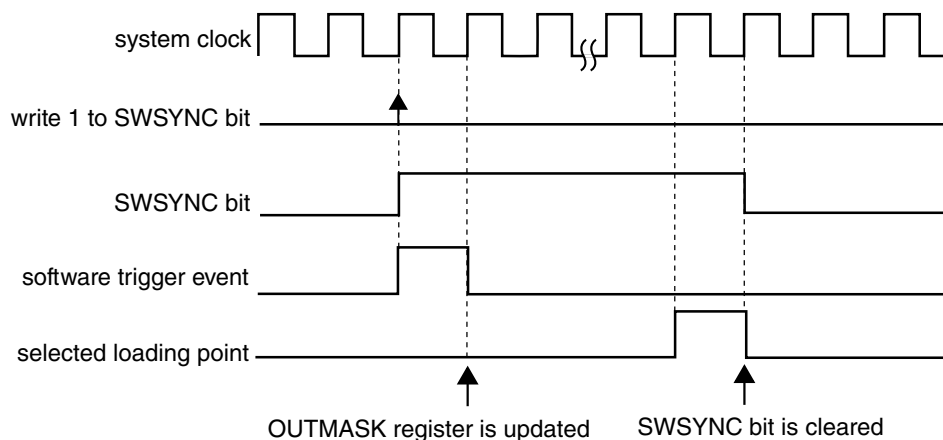


Figure 26-211. OUTMASK synchronization with (SYNCMODE = 0), (SYNCHOM = 1), (PWMSYNC = 0) and software trigger was used

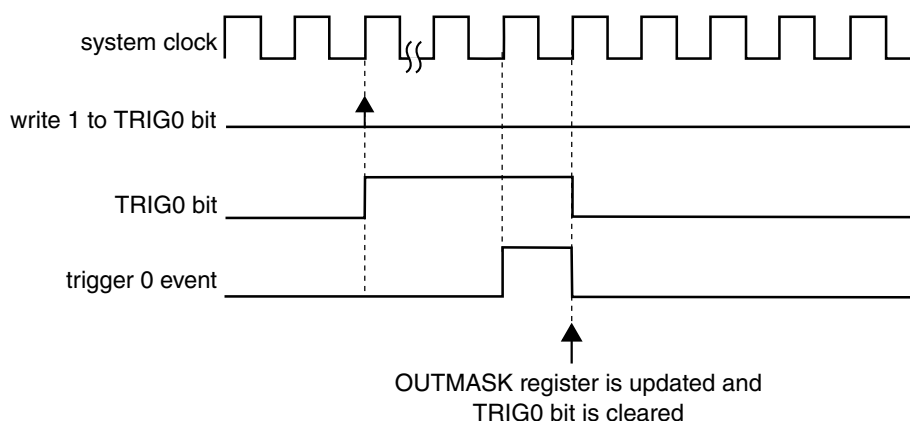


Figure 26-212. OUTMASK synchronization with (SYNCMODE = 0), (HWTRIGMODE = 0), (SYNCHOM = 1), (PWMSYNC = 0), and a hardware trigger was used

If (SYNCMODE = 0), (SYNCHOM = 1), and (PWMSYNC = 1), then this synchronization is made on the next enabled hardware trigger. The TRIGN bit is cleared according to [Hardware trigger](#). An example with a hardware trigger follows.

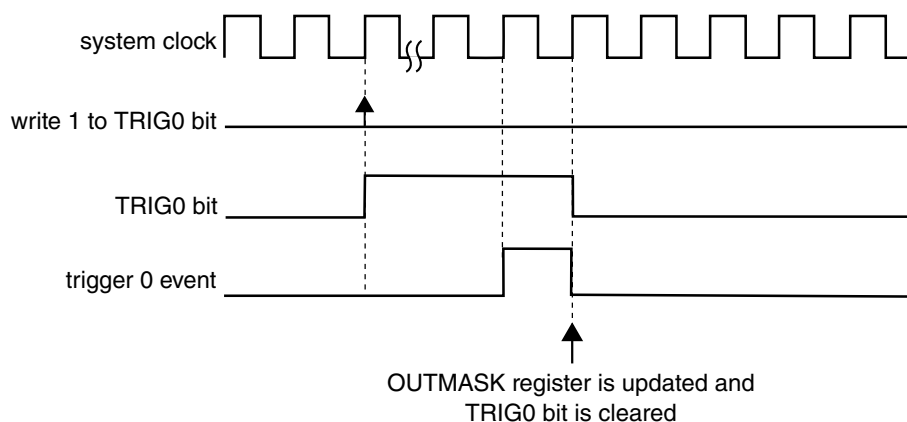


Figure 26-213. OUTMASK synchronization with (SYNCMODE = 0), (HWTRIGMODE = 0), (SYNCHOM = 1), (PWMSYNC = 1), and a hardware trigger was used

26.4.11.8 INVCTRL register synchronization

The INVCTRL register synchronization updates the INVCTRL register with its buffer value.

The INVCTRL register can be updated at each rising edge of system clock (INVC = 0) or by the enhanced PWM synchronization (INVC = 1 and SYNCMODE = 1) according to the following flowchart.

In the case of enhanced PWM synchronization, the INVCTRL register synchronization depends on SWINVC and HWINVC bits.

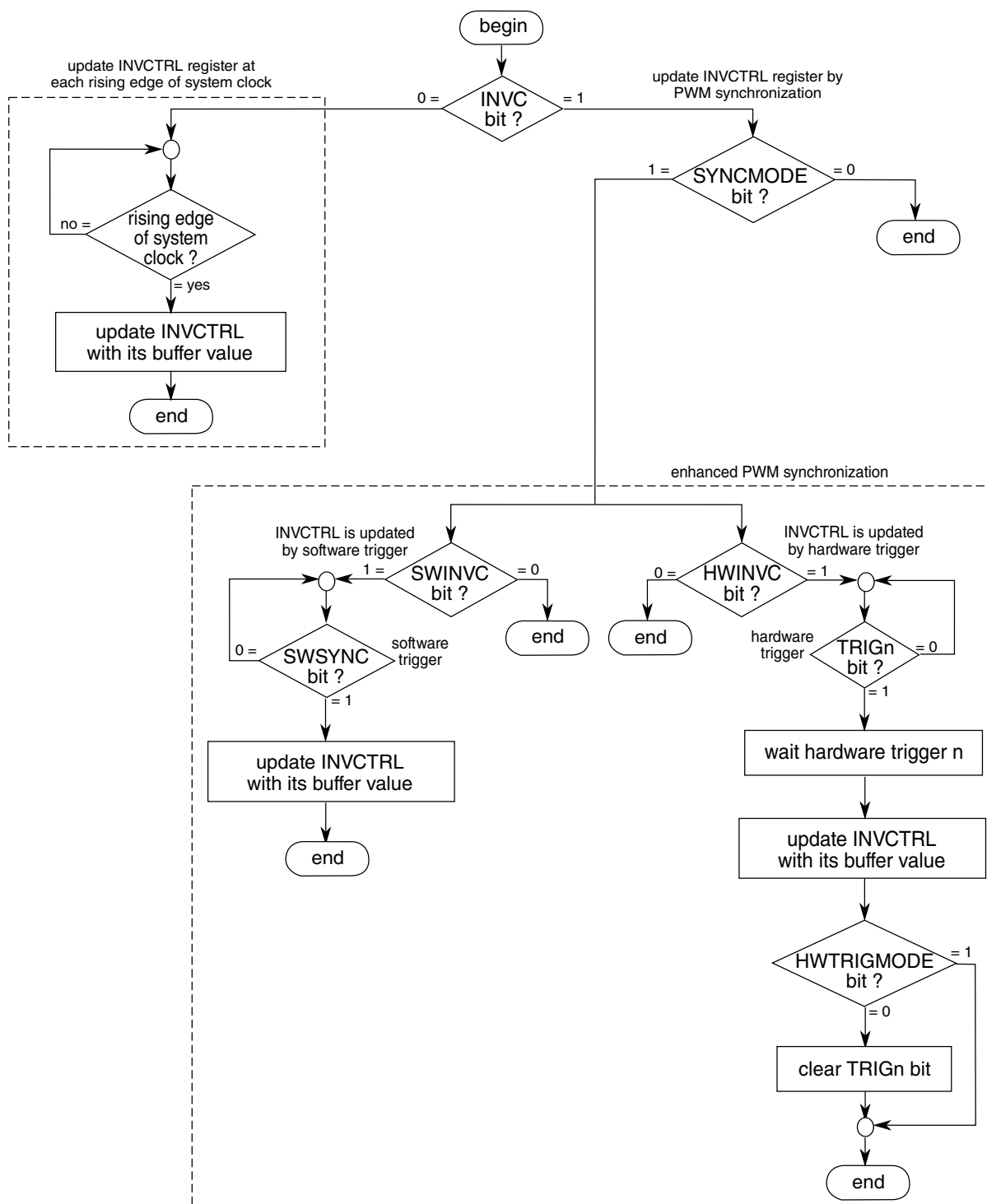


Figure 26-214. INVCTRL register synchronization flowchart

26.4.11.9 SWOCTRL register synchronization

The SWOCTRL register synchronization updates the SWOCTRL register with its buffer value.

The SWOCTRL register can be updated at each rising edge of system clock (SWOC = 0) or by the enhanced PWM synchronization (SWOC = 1 and SYNCMODE = 1) according to the following flowchart.

In the case of enhanced PWM synchronization, the SWOCTRL register synchronization depends on SWSOC and HWSOC bits.

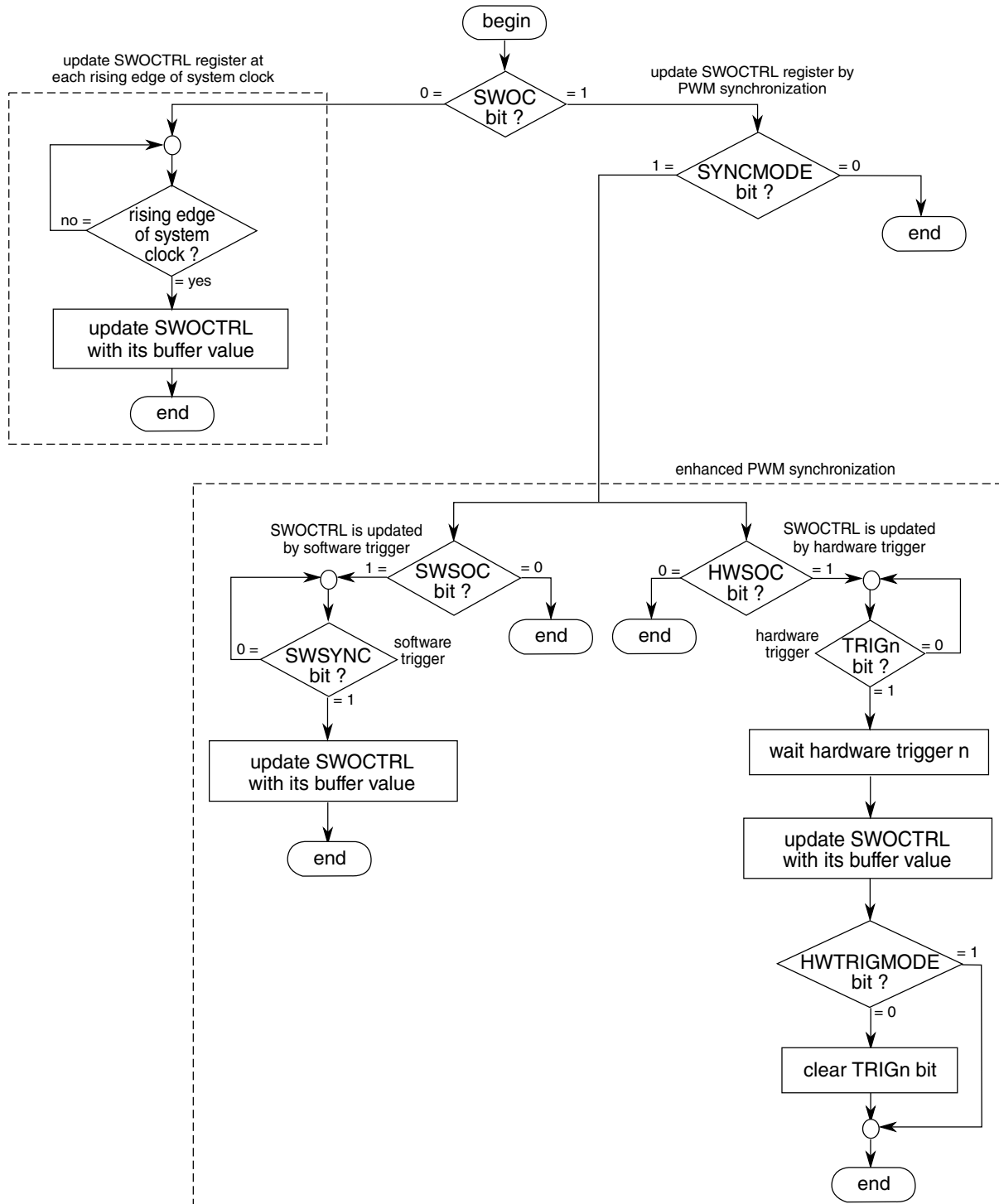


Figure 26-215. SWOCTRL register synchronization flowchart

26.4.11.10 FTM counter synchronization

The FTM counter synchronization is a mechanism that allows the FTM to restart the PWM generation at a certain point in the PWM period. The channels outputs are forced to their initial value, except for channels in Output Compare mode, and the FTM counter is forced to its initial counting value defined by CNTIN register.

The following figure shows the FTM counter synchronization. Note that after the synchronization event occurs, the channel (n) is set to its initial value and the channel (n+1) is not set to its initial value due to a specific timing of this figure in which the deadtime insertion prevents this channel output from transitioning to 1. If no deadtime insertion is selected, then the channel (n+1) transitions to logical value 1 immediately after the synchronization event occurs.

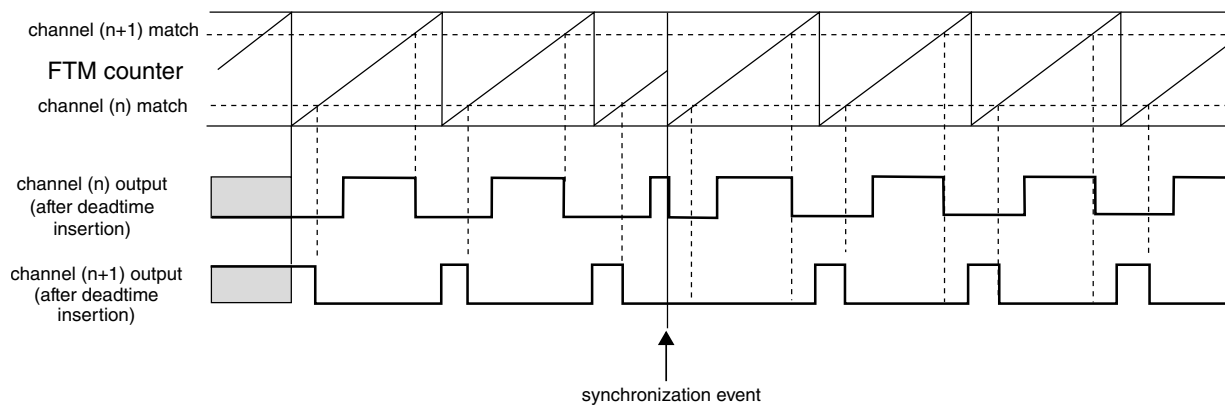


Figure 26-216. FTM counter synchronization

The FTM counter synchronization can be done by either the enhanced PWM synchronization (SYNCMODE = 1) or the legacy PWM synchronization (SYNCMODE = 0). However, the FTM counter must be synchronized only by the enhanced PWM synchronization.

In the case of enhanced PWM synchronization, the FTM counter synchronization depends on SWRSTCNT and HWRSTCNT bits according to the following flowchart.

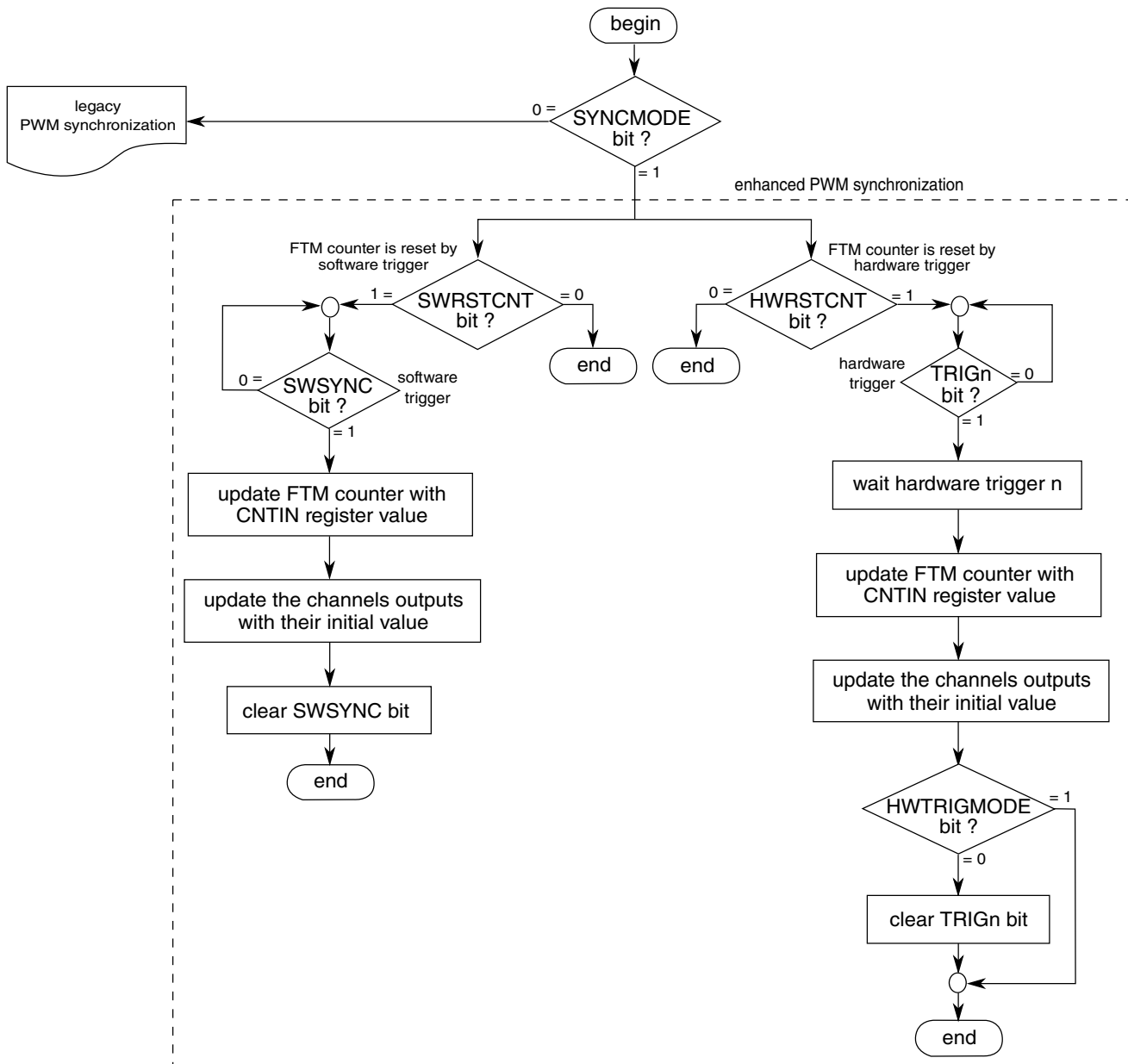


Figure 26-217. FTM counter synchronization flowchart

In the case of legacy PWM synchronization, the FTM counter synchronization depends on REINIT and PWMSYNC bits according to the following description.

If (SYNCMODE = 0), (REINIT = 1), and (PWMSYNC = 0) then this synchronization is made on the next enabled trigger event. If the trigger event was a software trigger then the SWSYNC bit is cleared according to the following example. If the trigger event was a hardware trigger then the TRIGN bit is cleared according to [Hardware trigger](#). Examples with software and hardware triggers follow.

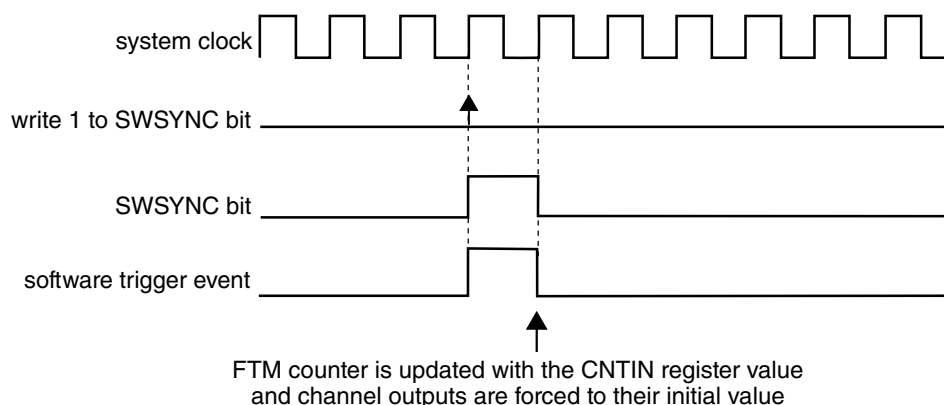


Figure 26-218. FTM counter synchronization with (SYNCMODE = 0), (REINIT = 1), (PWMSYNC = 0), and software trigger was used

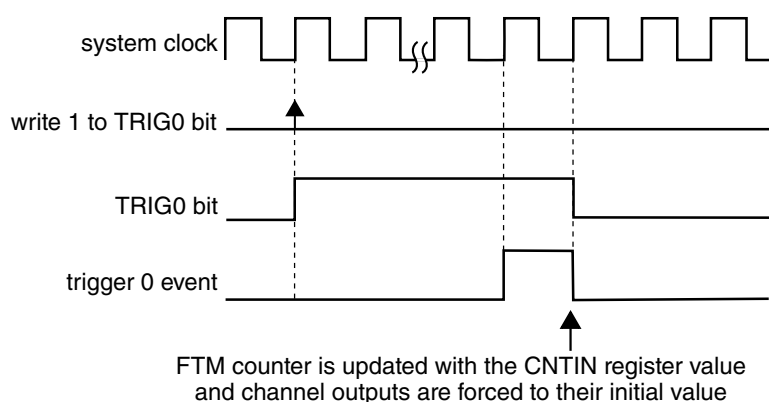


Figure 26-219. FTM counter synchronization with (SYNCMODE = 0), (HWTRIGMODE = 0), (REINIT = 1), (PWMSYNC = 0), and a hardware trigger was used

If (SYNCMODE = 0), (REINIT = 1), and (PWMSYNC = 1) then this synchronization is made on the next enabled hardware trigger. The TRIGn bit is cleared according to [Hardware trigger](#).

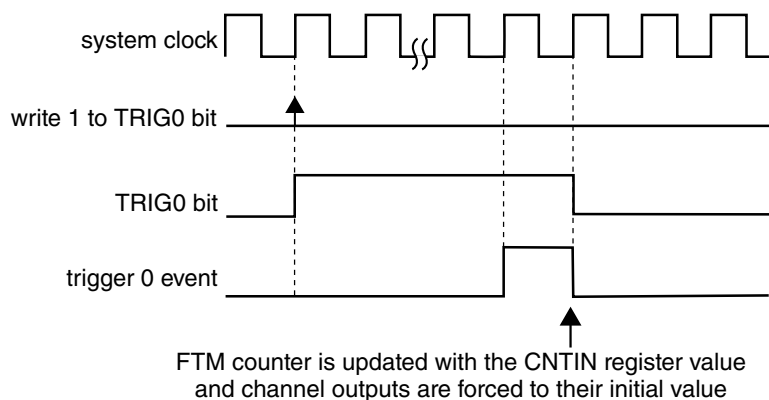


Figure 26-220. FTM counter synchronization with (SYNCMODE = 0), (HWTRIGMODE = 0), (REINIT = 1), (PWMSYNC = 1), and a hardware trigger was used

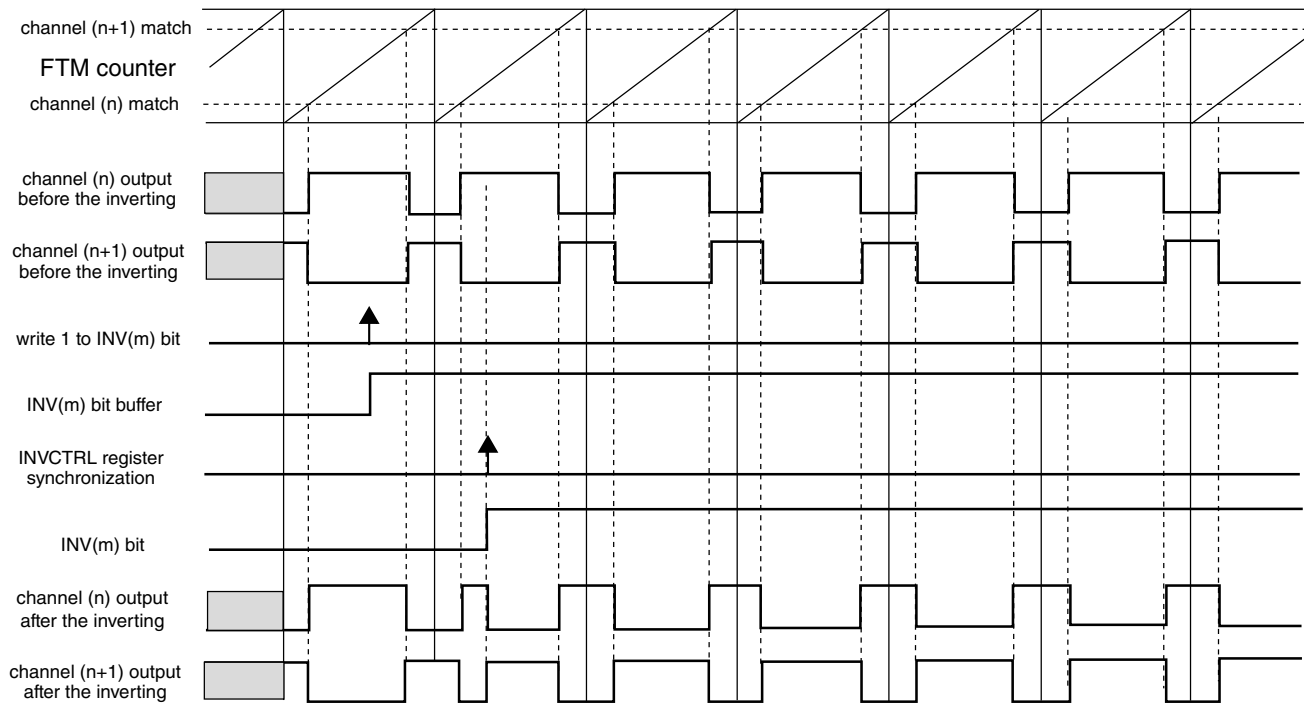
26.4.12 Inverting

The invert functionality swaps the signals between channel (n) and channel (n+1) outputs. The inverting operation is selected when:

- $DECAPEN = 0$
- $COMP = 1$, and
- $INV_m = 1$ (where m represents a channel pair)

The INV_m bit in $INVCTRL$ register is updated with its buffer value according to [INVCTRL register synchronization](#)

In High-True ($ELSnB:ELSnA = 1:0$) Combine mode, the channel (n) output is forced low at the beginning of the period (FTM counter = $CNTIN$), forced high at the channel (n) match and forced low at the channel (n+1) match. If the inverting is selected, the channel (n) output behavior is changed to force high at the beginning of the PWM period, force low at the channel (n) match and force high at the channel (n+1) match. See the following figure.

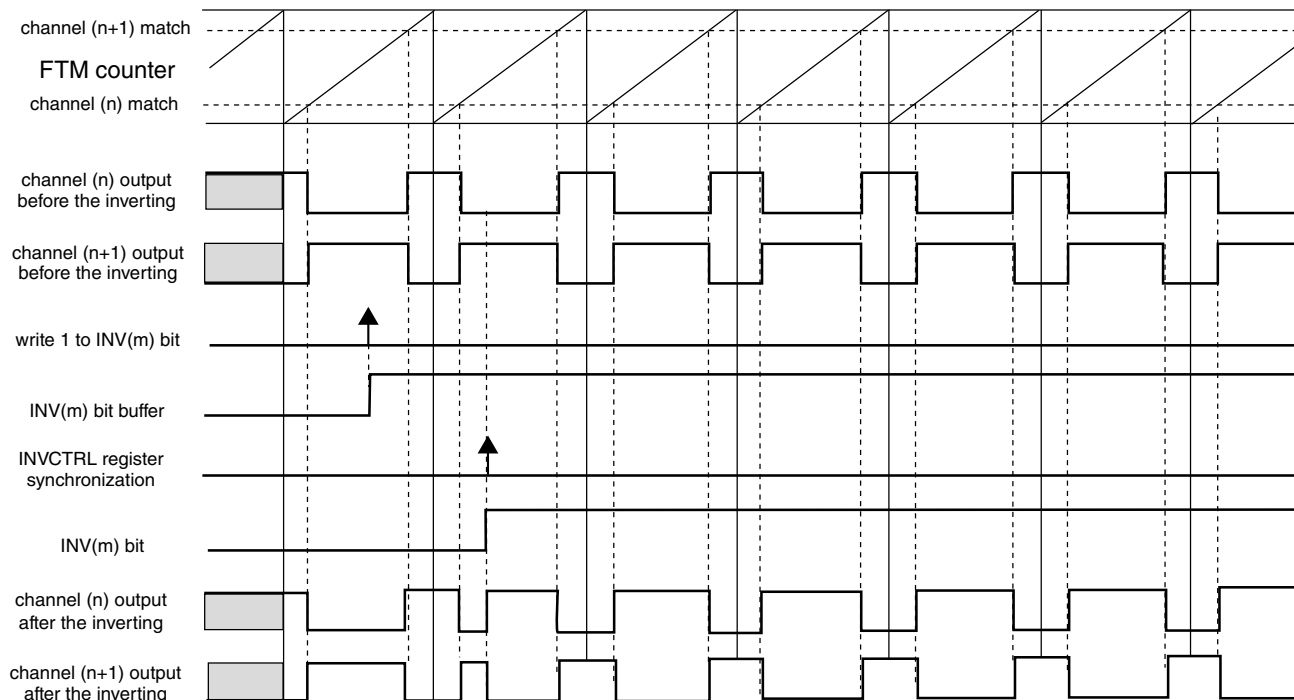


NOTE

$INV(m)$ bit selects the inverting to the pair channels (n) and (n+1).

Figure 26-221. Channels (n) and (n+1) outputs after the inverting in High-True ($ELSnB:ELSnA = 1:0$) Combine mode

Note that the ELSnB:ELSnA bits value should be considered because they define the active state of the channels outputs. In Low-True (ELSnB:ELSnA = X:1) Combine mode, the channel (n) output is forced high at the beginning of the period, forced low at the channel (n) match and forced high at the channel (n+1) match. When inverting is selected, the channels (n) and (n+1) present waveforms as shown in the following figure.



NOTE

INV(m) bit selects the inverting to the pair channels (n) and (n+1).

Figure 26-222. Channels (n) and (n+1) outputs after the inverting in Low-True (ELSnB:ELSnA = X:1) Combine mode

Note

The inverting feature is not available in Output Compare mode.

26.4.13 Software output control

The software output control forces the channel output according to software defined values at a specific time in the PWM generation.

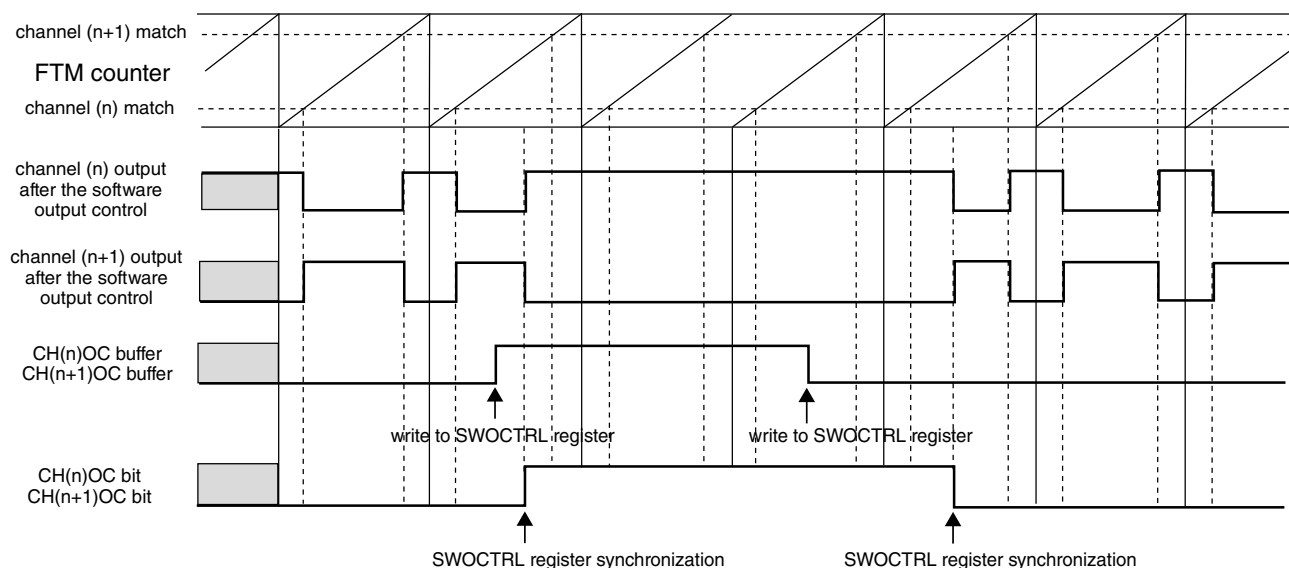
The software output control is selected when:

- DECAPEN = 0, and
- CHnOC = 1

The CHnOC bit enables the software output control for a specific channel output and the CHnOCV selects the value that is forced to this channel output.

Both CHnOC and CHnOCV bits in SWOCTRL register are buffered and updated with their buffer value according to [SWOCTRL register synchronization](#).

The following figure shows the channels (n) and (n+1) outputs signals when the software output control is used. In this case the channels (n) and (n+1) are set to Combine and Complementary mode.



NOTE

CH(n)OCV = 1 and CH(n+1)OCV = 0.

Figure 26-223. Example of software output control in Combine and Complementary mode

Software output control forces the following values on channels (n) and (n+1) when the COMP bit is zero.

Table 26-242. Software output control behavior when (COMP = 0)

| CH(n)OC | CH(n+1)OC | CH(n)OCV | CH(n+1)OCV | Channel (n) Output | Channel (n+1) Output |
|---------|-----------|----------|------------|-------------------------|-------------------------|
| 0 | 0 | X | X | is not modified by SWOC | is not modified by SWOC |
| 1 | 1 | 0 | 0 | is forced to zero | is forced to zero |
| 1 | 1 | 0 | 1 | is forced to zero | is forced to one |
| 1 | 1 | 1 | 0 | is forced to one | is forced to zero |
| 1 | 1 | 1 | 1 | is forced to one | is forced to one |

Software output control forces the following values on channels (n) and (n+1) when the COMP bit is one.

Table 26-243. Software output control behavior when (COMP = 1)

| CH(n)OC | CH(n+1)OC | CH(n)OCV | CH(n+1)OCV | Channel (n) Output | Channel (n+1) Output |
|---------|-----------|----------|------------|-------------------------|-------------------------|
| 0 | 0 | X | X | is not modified by SWOC | is not modified by SWOC |
| 1 | 1 | 0 | 0 | is forced to zero | is forced to zero |
| 1 | 1 | 0 | 1 | is forced to zero | is forced to one |
| 1 | 1 | 1 | 0 | is forced to one | is forced to zero |
| 1 | 1 | 1 | 1 | is forced to one | is forced to zero |

Note

- The CH(n)OC and CH(n+1)OC bits should be equal.
- The COMP bit must not be modified when software output control is enabled, that is, CH(n)OC = 1 and/or CH(n+1)OC = 1.
- Software output control has the same behavior with disabled or enabled FTM counter (see the CLKS field description in the Status and Control register).

26.4.14 Deadtime insertion

The deadtime insertion is enabled when (DTEN = 1) and (DTVAL[5:0] is non-zero).

DEADTIME register defines the deadtime delay that can be used for all FTM channels. The DTPS[1:0] bits define the prescaler for the system clock and the DTVAL[5:0] bits define the deadtime modulo, that is, the number of the deadtime prescaler clocks.

The deadtime delay insertion ensures that no two complementary signals (channels (n) and (n+1)) drive the active state at the same time.

If POL(n) = 0, POL(n+1) = 0, and the deadtime is enabled, then when the channel (n) match (FTM counter = C(n)V) occurs, the channel (n) output remains at the low value until the end of the deadtime delay when the channel (n) output is set. Similarly, when the channel (n+1) match (FTM counter = C(n+1)V) occurs, the channel (n+1) output remains at the low value until the end of the deadtime delay when the channel (n+1) output is set. See the following figures.

If POL(n) = 1, POL(n+1) = 1, and the deadtime is enabled, then when the channel (n) match (FTM counter = C(n)V) occurs, the channel (n) output remains at the high value until the end of the deadtime delay when the channel (n) output is cleared. Similarly,

when the channel (n+1) match (FTM counter = $C(n+1)V$) occurs, the channel (n+1) output remains at the high value until the end of the deadtime delay when the channel (n) output is cleared.

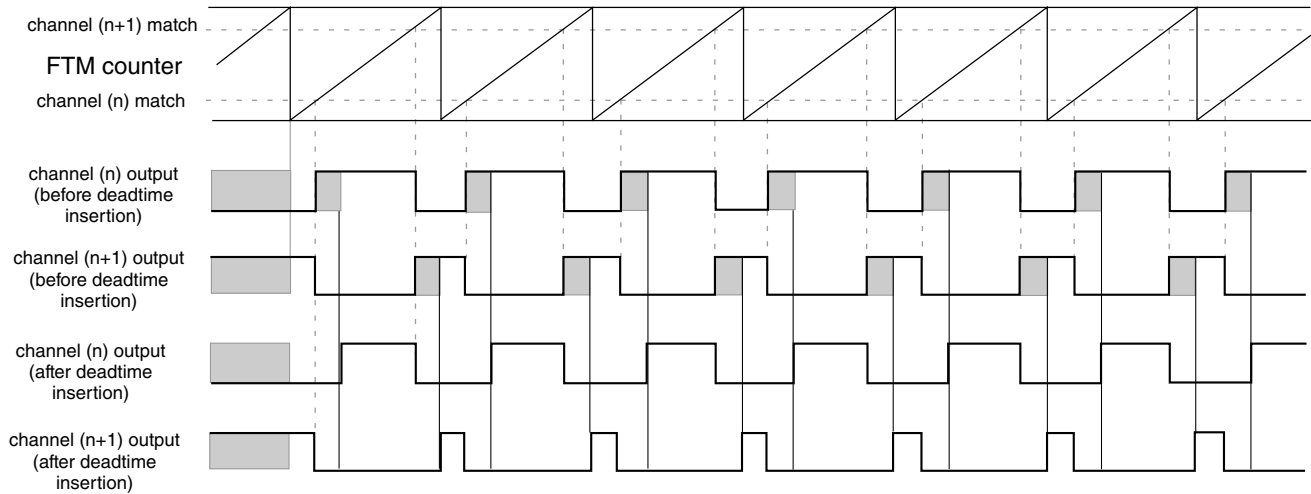


Figure 26-224. Deadtime insertion with $ELSnB:ELSnA = 1:0$, $POL(n) = 0$, and $POL(n+1) = 0$

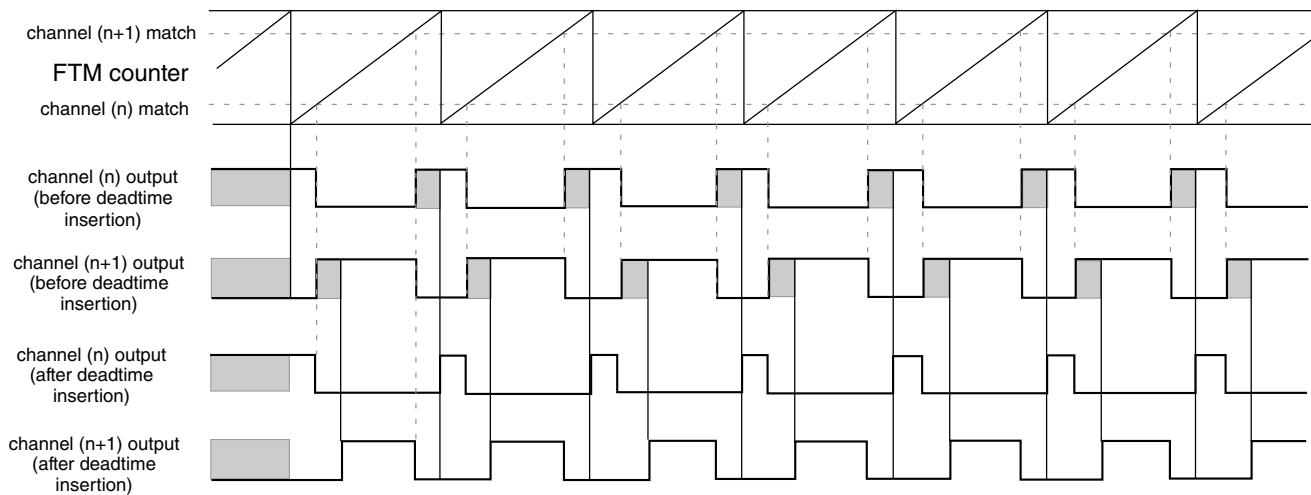


Figure 26-225. Deadtime insertion with $ELSnB:ELSnA = X:1$, $POL(n) = 0$, and $POL(n+1) = 0$

NOTE

- The deadtime feature must be used only in Complementary mode.
- The deadtime feature is not available in Output Compare mode.

26.4.14.1 Deadtime insertion corner cases

If (PS[2:0] is cleared), (DTPS[1:0] = 0:0 or DTPS[1:0] = 0:1):

- and the deadtime delay is greater than or equal to the channel (n) duty cycle ($((C(n+1)V - C(n)V) \times \text{system clock})$), then the channel (n) output is always the inactive value (POL(n) bit value).
- and the deadtime delay is greater than or equal to the channel (n+1) duty cycle ($((MOD - CNTIN + 1 - (C(n+1)V - C(n)V)) \times \text{system clock})$), then the channel (n+1) output is always the inactive value (POL(n+1) bit value).

Although, in most cases the deadtime delay is not comparable to channels (n) and (n+1) duty cycle, the following figures show examples where the deadtime delay is comparable to the duty cycle.

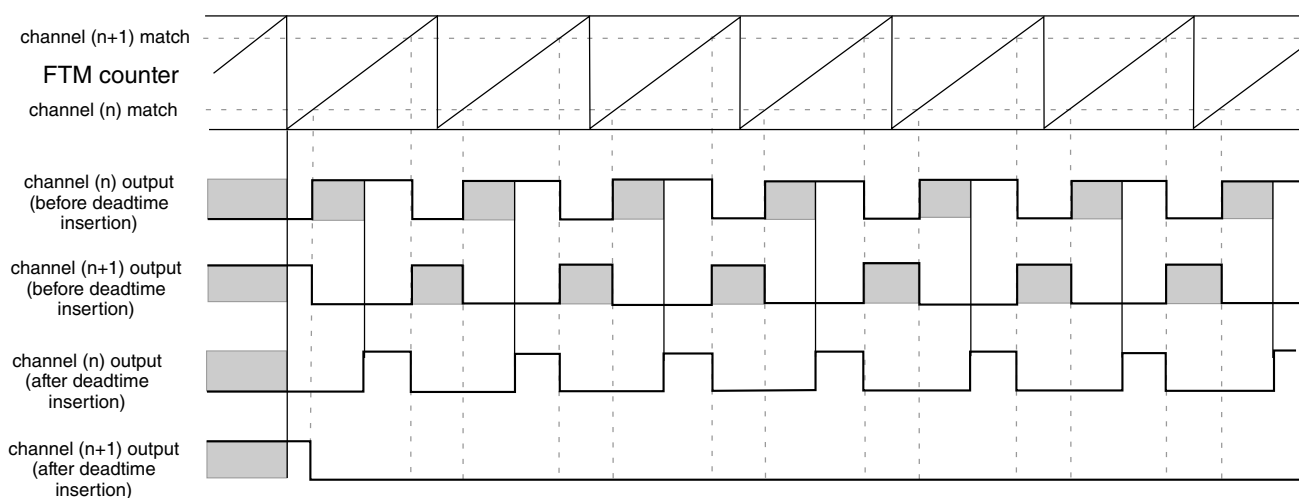


Figure 26-226. Example of the deadtime insertion (ELSnB:ELSnA = 1:0, POL(n) = 0, and POL(n+1) = 0) when the deadtime delay is comparable to channel (n+1) duty cycle

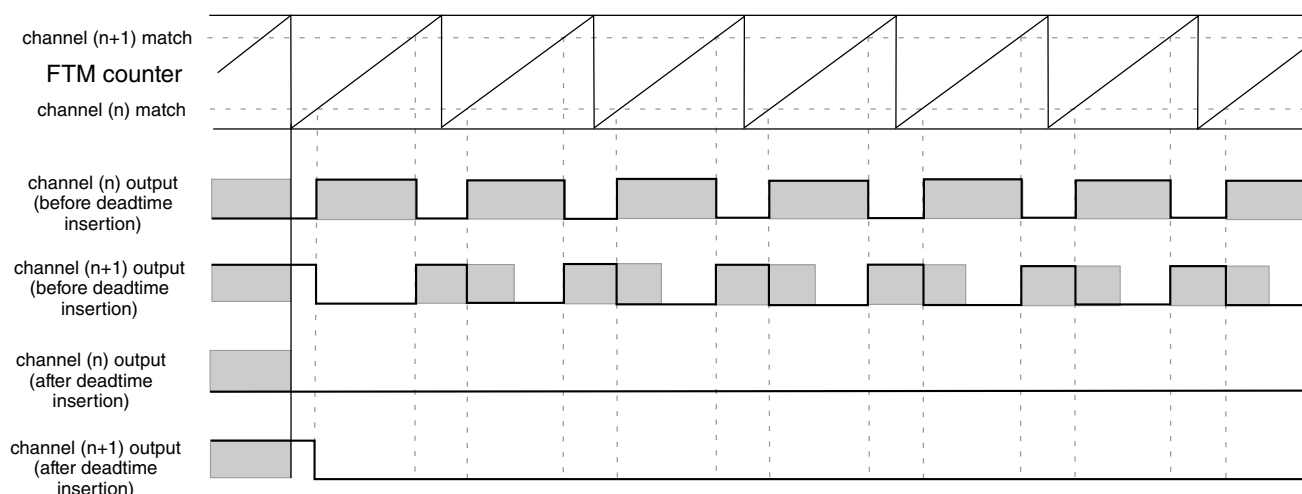


Figure 26-227. Example of the deadtime insertion ($ELSnB:ELSnA = 1:0$, $POL(n) = 0$, and $POL(n+1) = 0$) when the deadtime delay is comparable to channels (n) and (n+1) duty cycle

26.4.15 Output mask

The output mask can be used to force channels output to their inactive state through software. For example: to control a BLDC motor.

Any write to the OUTMASK register updates its write buffer. The OUTMASK register is updated with its buffer value by PWM synchronization; see [OUTMASK register synchronization](#).

If $CHnOM = 1$, then the channel (n) output is forced to its inactive state ($POLn$ bit value). If $CHnOM = 0$, then the channel (n) output is unaffected by the output mask. See the following figure.

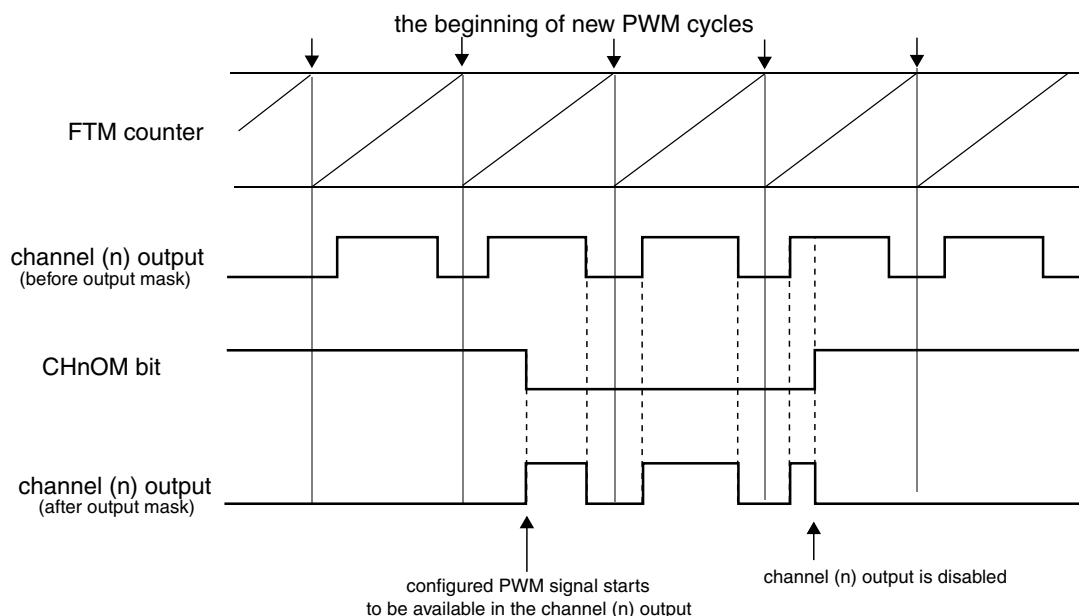


Figure 26-228. Output mask with POLn = 0

The following table shows the output mask result before the polarity control.

Table 26-244. Output mask result for channel (n) before the polarity control

| CHnOM | Output Mask Input | Output Mask Result |
|-------|-------------------|--------------------|
| 0 | inactive state | inactive state |
| | active state | active state |
| 1 | inactive state | inactive state |
| | active state | |

26.4.16 Fault control

The fault control is enabled if (FAULTM[1:0] ≠ 0:0).

FTM can have up to four fault inputs. FAULTnEN bit (where n = 0, 1, 2, 3) enables the fault input n and FFLTRnEN bit enables the fault input n filter. FFVAL[3:0] bits select the value of the enabled filter in each enabled fault input.

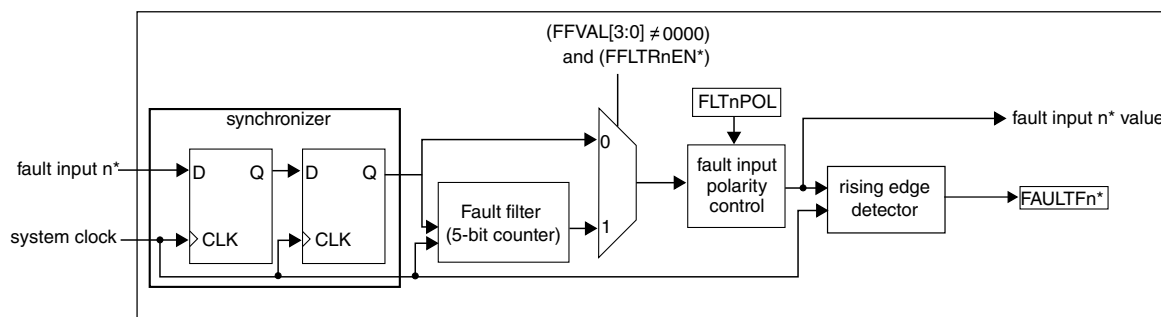
First, each fault input signal is synchronized by the system clock; see the synchronizer block in the following figure. Following synchronization, the fault input n signal enters the filter block. When there is a state change in the fault input n signal, the 5-bit counter is reset and starts counting up. As long as the new state is stable on the fault input n, the

counter continues to increment. If the 5-bit counter overflows, that is, the counter exceeds the value of the FFVAL[3:0] bits, the new fault input n value is validated. It is then transmitted as a pulse edge to the edge detector.

If the opposite edge appears on the fault input n signal before validation (counter overflow), the counter is reset. At the next input transition, the counter starts counting again. Any pulse that is shorter than the minimum value selected by FFVAL[3:0] bits (\times system clock) is regarded as a glitch and is not passed on to the edge detector.

The fault input n filter is disabled when the FFVAL[3:0] bits are zero or when FAULTnEN = 0. In this case, the fault input n signal is delayed 2 rising edges of the system clock and the FAULTFn bit is set on 3th rising edge of the system clock after a rising edge occurs on the fault input n.

If FFVAL[3:0] \neq 0000 and FAULTnEN = 1, then the fault input n signal is delayed (3 + FFVAL[3:0]) rising edges of the system clock, that is, the FAULTFn bit is set (4 + FFVAL[3:0]) rising edges of the system clock after a rising edge occurs on the fault input n.



* where n = 3, 2, 1, 0

Figure 26-229. Fault input n control block diagram

If the fault control and fault input n are enabled and a rising edge at the fault input n signal is detected, a fault condition has occurred and the FAULTFn bit is set. The FAULTF bit is the logic OR of FAULTFn[3:0] bits. See the following figure.

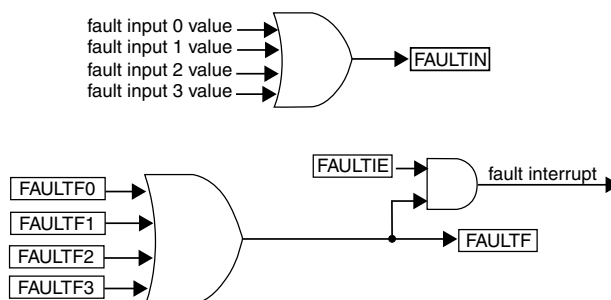


Figure 26-230. FAULTF and FAULTIN bits and fault interrupt

If the fault control is enabled ($\text{FAULTM}[1:0] \neq 0:0$), a fault condition has occurred and ($\text{FAULTEN} = 1$), then outputs are forced to their safe values:

- Channel (n) output takes the value of $\text{POL}(n)$
- Channel (n+1) takes the value of $\text{POL}(n+1)$

The fault interrupt is generated when ($\text{FAULTF} = 1$) and ($\text{FAULTIE} = 1$). This interrupt request remains set until:

- Software clears the FAULTF bit by reading FAULTF bit as 1 and writing 0 to it
- Software clears the FAULTIE bit
- A reset occurs

26.4.16.1 Automatic fault clearing

If the automatic fault clearing is selected ($\text{FAULTM}[1:0] = 1:1$), then the channels output disabled by fault control is again enabled when the fault input signal (FAULTIN) returns to zero and a new PWM cycle begins. See the following figure.

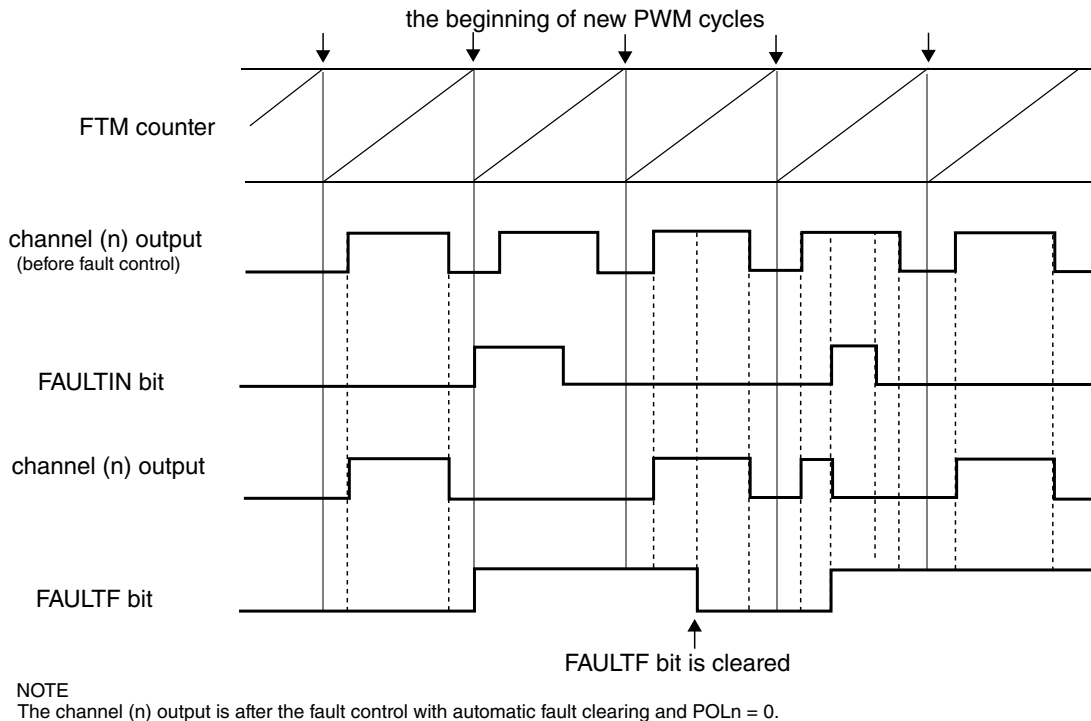
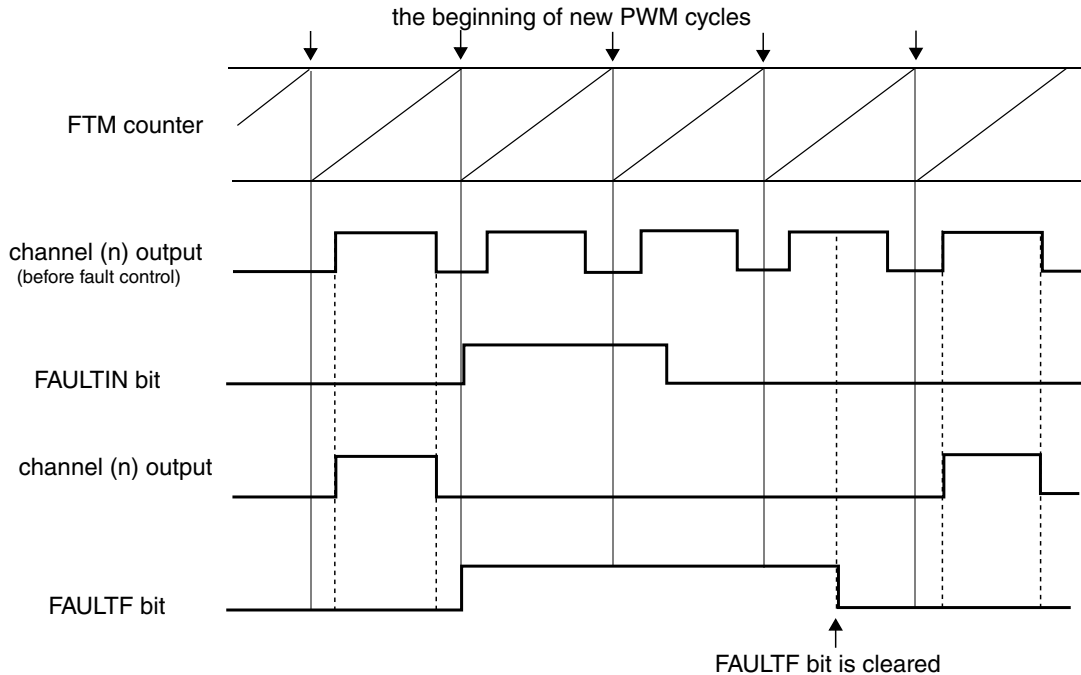


Figure 26-231. Fault control with automatic fault clearing

26.4.16.2 Manual fault clearing

If the manual fault clearing is selected ($\text{FAULTM}[1:0] = 0:1$ or $1:0$), then the channels output disabled by fault control is again enabled when the FAULTF bit is cleared and a new PWM cycle begins. See the following figure.



NOTE
The channel (n) output is after the fault control with manual fault clearing and $\text{POLn} = 0$.

Figure 26-232. Fault control with manual fault clearing

26.4.16.3 Fault inputs polarity control

The FLTjPOL bit selects the fault input j polarity, where $j = 0, 1, 2, 3$:

- If $\text{FLTjPOL} = 0$, the fault j input polarity is high, so the logical one at the fault input j indicates a fault.
- If $\text{FLTjPOL} = 1$, the fault j input polarity is low, so the logical zero at the fault input j indicates a fault.

26.4.17 Polarity control

The POLn bit selects the channel (n) output polarity:

- If $POL_n = 0$, the channel (n) output polarity is high, so the logical one is the active state and the logical zero is the inactive state.
- If $POL_n = 1$, the channel (n) output polarity is low, so the logical zero is the active state and the logical one is the inactive state.

26.4.18 Initialization

The initialization forces the CH_nOI bit value to the channel (n) output when a one is written to the INIT bit.

The initialization depends on COMP and DTEN bits. The following table shows the values that channels (n) and (n+1) are forced by initialization when the COMP and DTEN bits are zero.

Table 26-245. Initialization behavior when (COMP = 0 and DTEN = 0)

| CH(n)OI | CH(n+1)OI | Channel (n) Output | Channel (n+1) Output |
|---------|-----------|--------------------|----------------------|
| 0 | 0 | is forced to zero | is forced to zero |
| 0 | 1 | is forced to zero | is forced to one |
| 1 | 0 | is forced to one | is forced to zero |
| 1 | 1 | is forced to one | is forced to one |

The following table shows the values that channels (n) and (n+1) are forced by initialization when (COMP = 1) or (DTEN = 1).

Table 26-246. Initialization behavior when (COMP = 1 or DTEN = 1)

| CH(n)OI | CH(n+1)OI | Channel (n) Output | Channel (n+1) Output |
|---------|-----------|--------------------|----------------------|
| 0 | X | is forced to zero | is forced to one |
| 1 | X | is forced to one | is forced to zero |

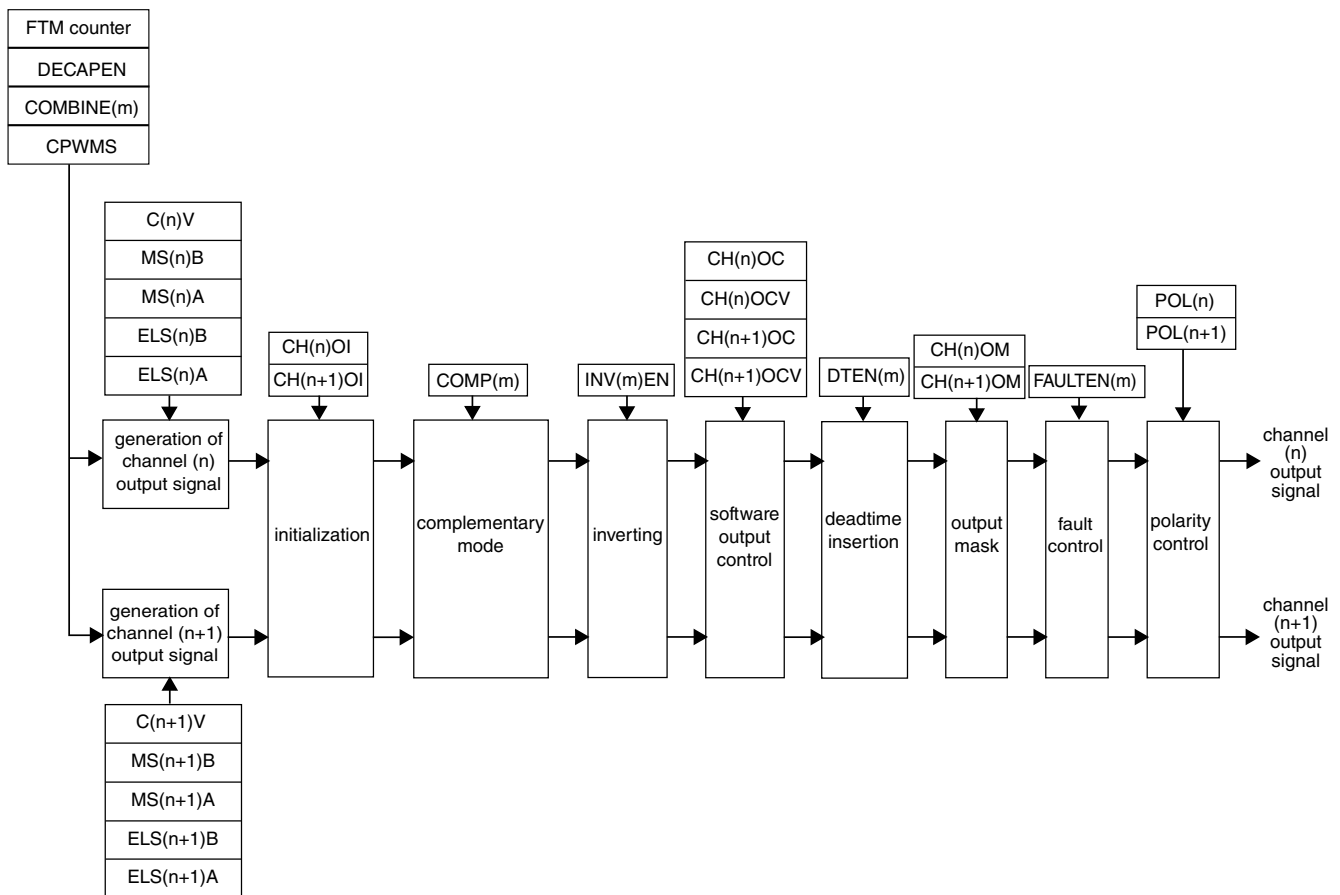
Note

The initialization feature must be used only with disabled FTM counter. See the description of the CLKS field in the Status and Control register.

26.4.19 Features priority

The following figure shows the priority of the features used at the generation of channels (n) and (n+1) outputs signals.

pair channels (m) - channels (n) and (n+1)



NOTE

The channels (n) and (n+1) are in output compare, EPWM, CPWM or combine modes.

Figure 26-233. Priority of the features used at the generation of channels (n) and (n+1) outputs signals

Note

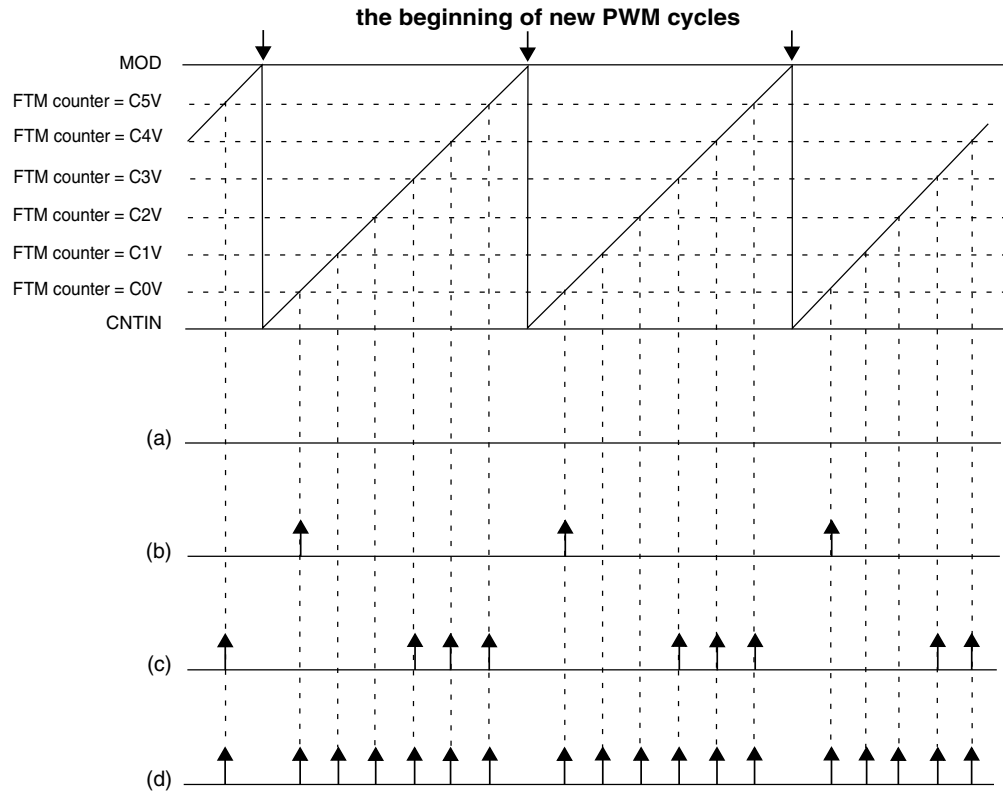
The **Initialization** feature must not be used with **Inverting** and **Software output control** features.

26.4.20 Channel trigger output

If $CH_jTRIG = 1$, where $j = 0, 1, 2, 3, 4$, or 5 , then the FTM generates a trigger when the channel (j) match occurs (FTM counter = $C(j)V$).

The channel trigger output provides a trigger signal that is used for on-chip modules.

The FTM is able to generate multiple triggers in one PWM period. Because each trigger is generated for a specific channel, several channels are required to implement this functionality. This behavior is described in the following figure.



NOTE

- (a) CH0TRIG = 0, CH1TRIG = 0, CH2TRIG = 0, CH3TRIG = 0, CH4TRIG = 0, CH5TRIG = 0
- (b) CH0TRIG = 1, CH1TRIG = 0, CH2TRIG = 0, CH3TRIG = 0, CH4TRIG = 0, CH5TRIG = 0
- (c) CH0TRIG = 0, CH1TRIG = 0, CH2TRIG = 0, CH3TRIG = 1, CH4TRIG = 1, CH5TRIG = 1
- (d) CH0TRIG = 1, CH1TRIG = 1, CH2TRIG = 1, CH3TRIG = 1, CH4TRIG = 1, CH5TRIG = 1

Figure 26-234. Channel match trigger

26.4.21 Initialization trigger

If INITTRIGEN = 1, then the FTM generates a trigger when the FTM counter is updated with the CNTIN register value in the following cases.

- The FTM counter is automatically updated with the CNTIN register value by the selected counting mode.
- When there is a write to CNT register.

- When there is the **FTM counter synchronization**.
- If (CNT = CNTIN), (CLKS[1:0] = 0:0), and a value different from zero is written to CLKS[1:0] bits.

The following figures show these cases.

CNTIN = 0x0000
MOD = 0x000F
CPWMS = 0

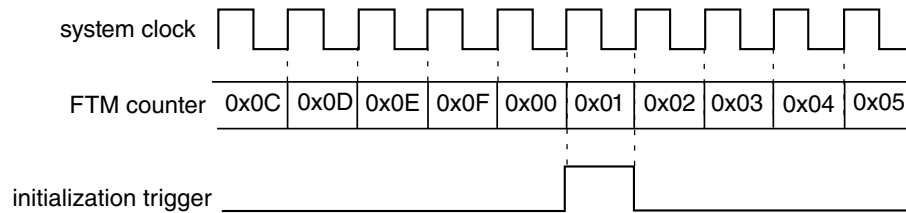


Figure 26-235. Initialization trigger is generated when the FTM counting achieves the CNTIN register value

CNTIN = 0x0000
MOD = 0x000F
CPWMS = 0

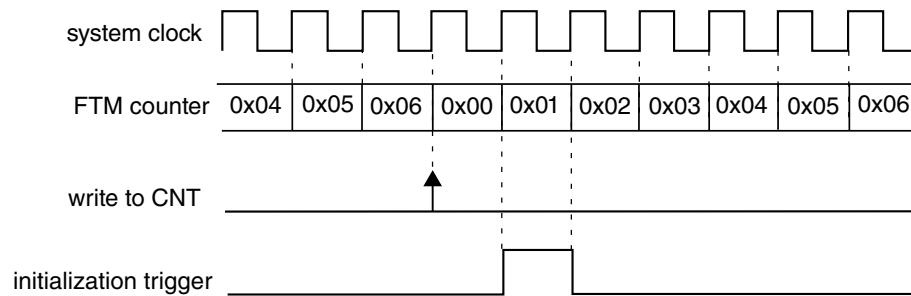


Figure 26-236. Initialization trigger is generated when there is a write to CNT register

CNTIN = 0x0000
MOD = 0x000F
CPWMS = 0

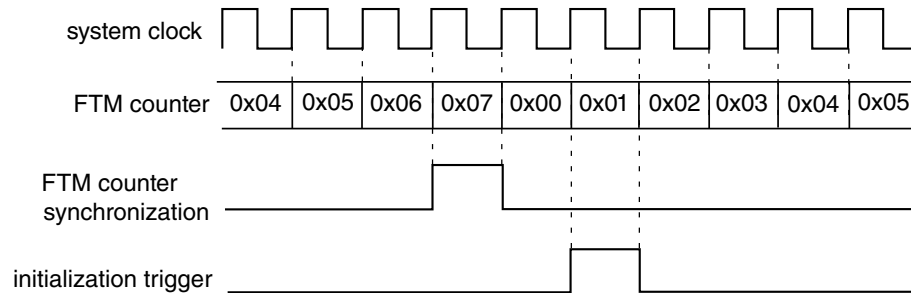


Figure 26-237. Initialization trigger is generated when there is the FTM counter synchronization

Functional description

CNTIN = 0x0000
MOD = 0x000F
CPWMS = 0

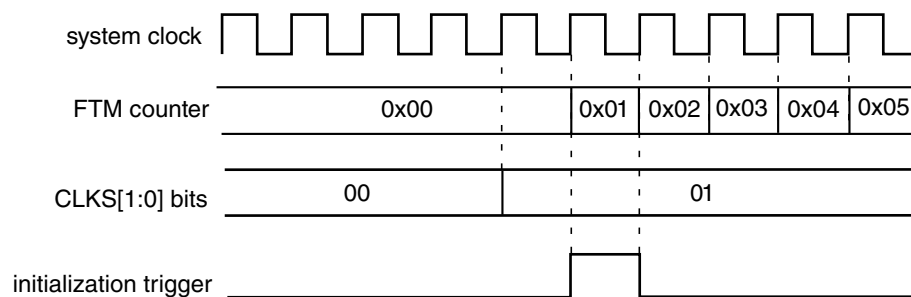


Figure 26-238. Initialization trigger is generated if (CNT = CNTIN), (CLKS[1:0] = 0:0), and a value different from zero is written to CLKS[1:0] bits

The initialization trigger output provides a trigger signal that is used for on-chip modules.

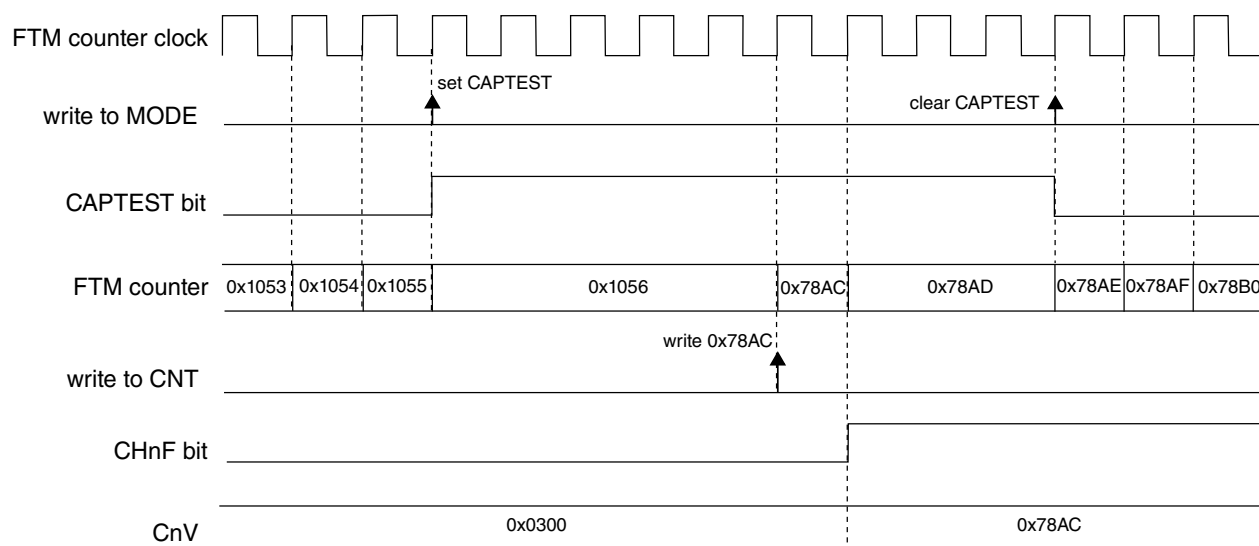
26.4.22 Capture Test mode

The Capture Test mode allows to test the CnV registers, the FTM counter and the interconnection logic between the FTM counter and CnV registers.

In this test mode, all channels must be configured for [Input Capture mode](#) and FTM counter must be configured to the [Up counting](#).

When the Capture Test mode is enabled (CAPTEST = 1), the FTM counter is frozen and any write to CNT register updates directly the FTM counter; see the following figure. After it was written, all CnV registers are updated with the written value to CNT register and CHnF bits are set. Therefore, the FTM counter is updated with its next value according to its configuration. Its next value depends on CNTIN, MOD, and the written value to FTM counter.

The next reads of CnV registers return the written value to the FTM counter and the next reads of CNT register return FTM counter next value.



NOTE

- FTM counter configuration: (FTMEN = 1), (CAPTEST = 1), (CPWMS = 0), (CNTIN = 0x0000), and (MOD = 0xFFFF)
- FTM channel n configuration: input capture mode - (DECAPEN = 0), (COMBINE = 0), and (MSnB:MSnA = 0:0)

Figure 26-239. Capture Test mode

26.4.23 Dual Edge Capture mode

The Dual Edge Capture mode is selected if DECAPEN = 1. This mode allows to measure a pulse width or period of the signal on the input of channel (n) of a channel pair. The channel (n) filter can be active in this mode when n is 0 or 2.

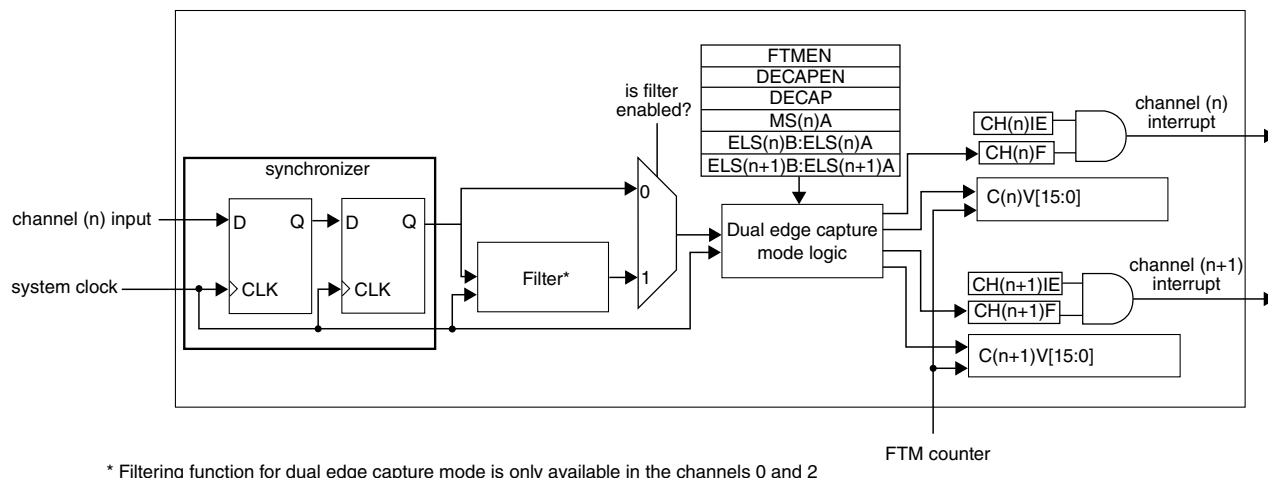


Figure 26-240. Dual Edge Capture mode block diagram

The MS(n)A bit defines if the Dual Edge Capture mode is one-shot or continuous.

The ELS(n)B:ELS(n)A bits select the edge that is captured by channel (n), and ELS(n+1)B:ELS(n+1)A bits select the edge that is captured by channel (n+1). If both ELS(n)B:ELS(n)A and ELS(n+1)B:ELS(n+1)A bits select the same edge, then it is the period measurement. If these bits select different edges, then it is a pulse width measurement.

In the Dual Edge Capture mode, only channel (n) input is used and channel (n+1) input is ignored.

If the selected edge by channel (n) bits is detected at channel (n) input, then CH(n)F bit is set and the channel (n) interrupt is generated (if CH(n)IE = 1). If the selected edge by channel (n+1) bits is detected at channel (n) input and (CH(n)F = 1), then CH(n+1)F bit is set and the channel (n+1) interrupt is generated (if CH(n+1)IE = 1).

The C(n)V register stores the value of FTM counter when the selected edge by channel (n) is detected at channel (n) input. The C(n+1)V register stores the value of FTM counter when the selected edge by channel (n+1) is detected at channel (n) input.

In this mode, a coherency mechanism ensures coherent data when the C(n)V and C(n+1)V registers are read. The only requirement is that C(n)V must be read before C(n+1)V.

Note

- The CH(n)F, CH(n)IE, MS(n)A, ELS(n)B, and ELS(n)A bits are channel (n) bits.
- The CH(n+1)F, CH(n+1)IE, MS(n+1)A, ELS(n+1)B, and ELS(n+1)A bits are channel (n+1) bits.
- The Dual Edge Capture mode must be used with ELS(n)B:ELS(n)A = 0:1 or 1:0, ELS(n+1)B:ELS(n+1)A = 0:1 or 1:0 and the FTM counter in [Free running counter](#).

26.4.23.1 One-Shot Capture mode

The One-Shot Capture mode is selected when (DECAPEN = 1), and (MS(n)A = 0). In this capture mode, only one pair of edges at the channel (n) input is captured. The ELS(n)B:ELS(n)A bits select the first edge to be captured, and ELS(n+1)B:ELS(n+1)A bits select the second edge to be captured.

The edge captures are enabled while DECAP bit is set. For each new measurement in One-Shot Capture mode, first the CH(n)F and CH(n+1) bits must be cleared, and then the DECAP bit must be set.

In this mode, the DECAP bit is automatically cleared by FTM when the edge selected by channel (n+1) is captured. Therefore, while DECAP bit is set, the one-shot capture is in process. When this bit is cleared, both edges were captured and the captured values are ready for reading in the C(n)V and C(n+1)V registers.

Similarly, when the CH(n+1)F bit is set, both edges were captured and the captured values are ready for reading in the C(n)V and C(n+1)V registers.

26.4.23.2 Continuous Capture mode

The Continuous Capture mode is selected when (DECAPEN = 1), and (MS(n)A = 1). In this capture mode, the edges at the channel (n) input are captured continuously. The ELS(n)B:ELS(n)A bits select the initial edge to be captured, and ELS(n+1)B:ELS(n+1)A bits select the final edge to be captured.

The edge captures are enabled while DECAP bit is set. For the initial use, first the CH(n)F and CH(n+1)F bits must be cleared, and then DECAP bit must be set to start the continuous measurements.

When the CH(n+1)F bit is set, both edges were captured and the captured values are ready for reading in the C(n)V and C(n+1)V registers. The latest captured values are always available in these registers even after the DECAP bit is cleared.

In this mode, it is possible to clear only the CH(n+1)F bit. Therefore, when the CH(n+1)F bit is set again, the latest captured values are available in C(n)V and C(n+1)V registers.

For a new sequence of the measurements in the Dual Edge Capture – Continuous mode, clear the CH(n)F and CH(n+1)F bits to start new measurements.

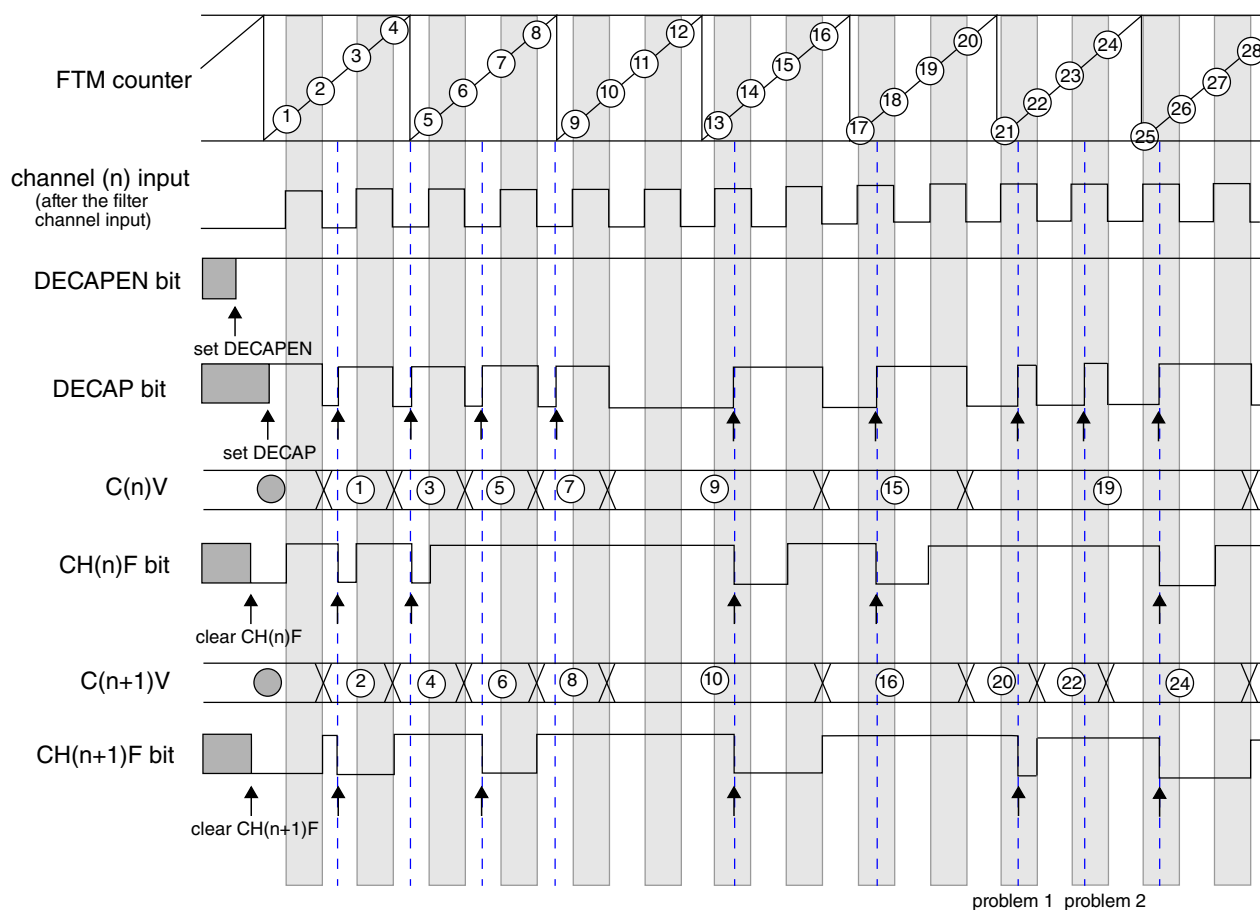
26.4.23.3 Pulse width measurement

If the channel (n) is configured to capture rising edges (ELS(n)B:ELS(n)A = 0:1) and the channel (n+1) to capture falling edges (ELS(n+1)B:ELS(n+1)A = 1:0), then the positive polarity pulse width is measured. If the channel (n) is configured to capture falling edges (ELS(n)B:ELS(n)A = 1:0) and the channel (n+1) to capture rising edges (ELS(n+1)B:ELS(n+1)A = 0:1), then the negative polarity pulse width is measured.

The pulse width measurement can be made in [One-Shot Capture mode](#) or [Continuous Capture mode](#).

The following figure shows an example of the Dual Edge Capture – One-Shot mode used to measure the positive polarity pulse width. The DECAPEN bit selects the Dual Edge Capture mode, so it remains set. The DECAP bit is set to enable the measurement of next

positive polarity pulse width. The CH(n)F bit is set when the first edge of this pulse is detected, that is, the edge selected by ELS(n)B:ELS(n)A bits. The CH(n+1)F bit is set and DECAP bit is cleared when the second edge of this pulse is detected, that is, the edge selected by ELS(n+1)B:ELS(n+1)A bits. Both DECAP and CH(n+1)F bits indicate when two edges of the pulse were captured and the C(n)V and C(n+1)V registers are ready for reading.



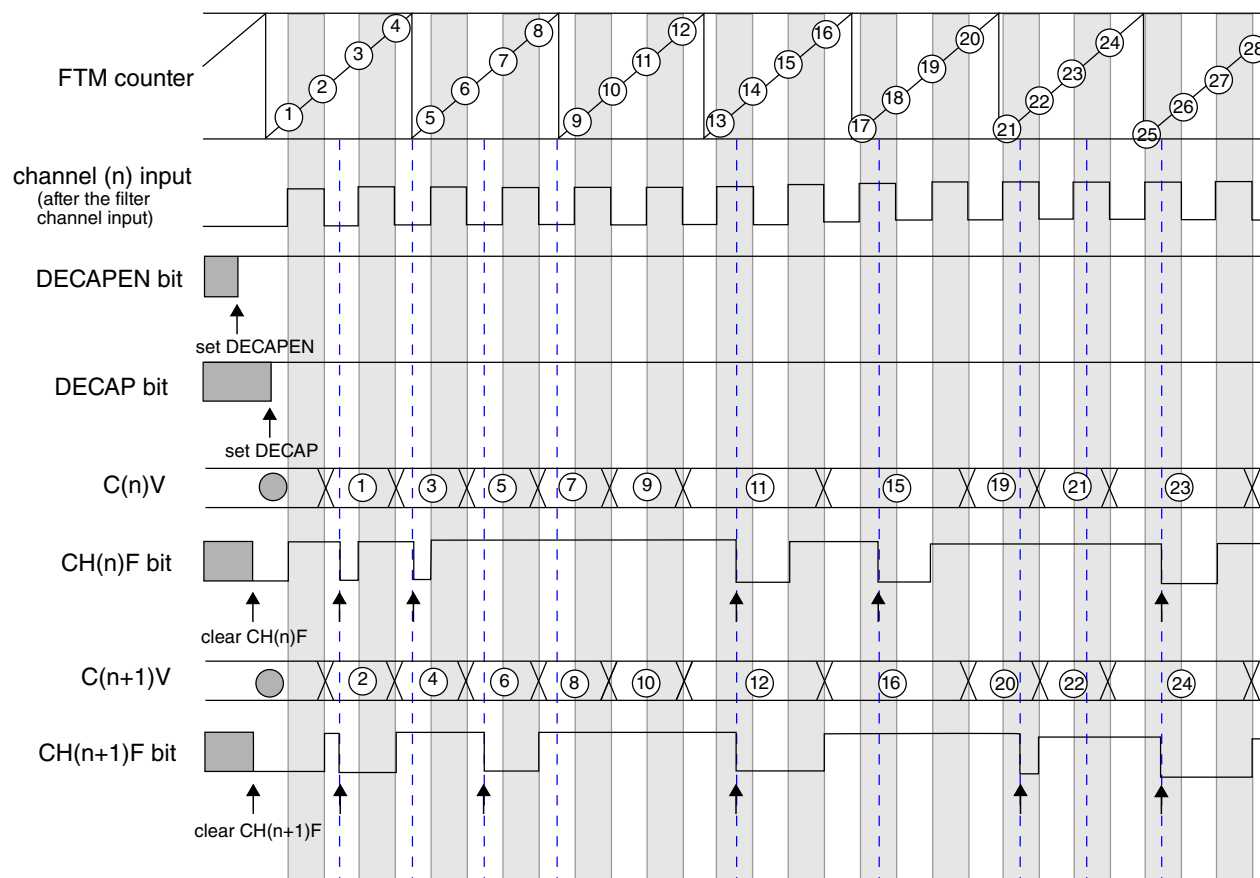
Note

- The commands set DECAPEN, set DECAP, clear CH(n)F, and clear CH(n+1)F are made by the user.
- Problem 1: channel (n) input = 1, set DECAP, not clear CH(n)F, and clear CH(n+1)F.
- Problem 2: channel (n) input = 1, set DECAP, not clear CH(n)F, and not clear CH(n+1)F.

Figure 26-241. Dual Edge Capture – One-Shot mode for positive polarity pulse width measurement

The following figure shows an example of the Dual Edge Capture – Continuous mode used to measure the positive polarity pulse width. The DECAPEN bit selects the Dual Edge Capture mode, so it remains set. While the DECAP bit is set the configured measurements are made. The CH(n)F bit is set when the first edge of the positive polarity pulse is detected, that is, the edge selected by ELS(n)B:ELS(n)A bits. The CH(n+1)F bit

is set when the second edge of this pulse is detected, that is, the edge selected by $ELS(n+1)B:ELS(n+1)A$ bits. The $CH(n+1)F$ bit indicates when two edges of the pulse were captured and the $C(n)V$ and $C(n+1)V$ registers are ready for reading.



Note

- The commands set DECAPEN, set DECAP, clear $CH(n)F$, and clear $CH(n+1)F$ are made by the user.

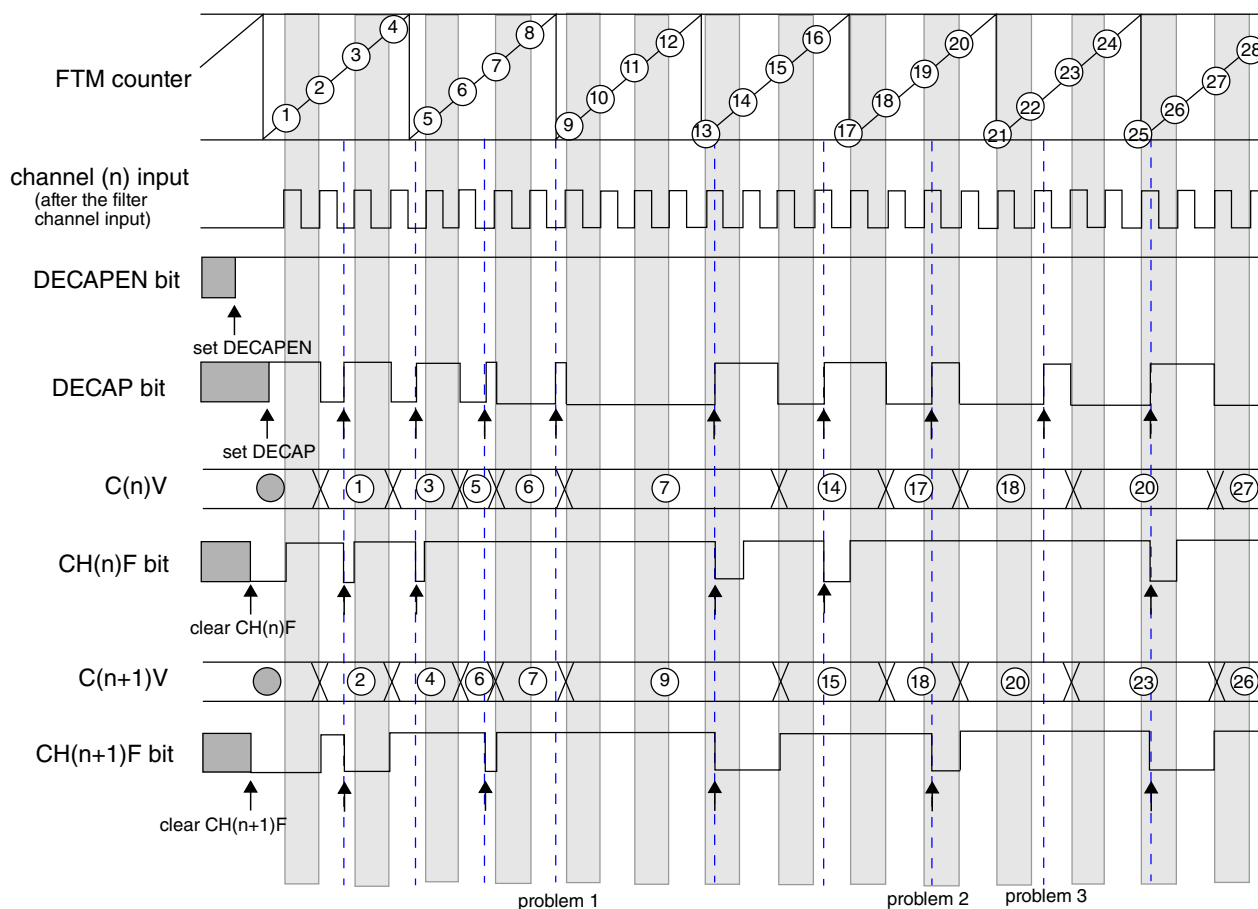
Figure 26-242. Dual Edge Capture – Continuous mode for positive polarity pulse width measurement

26.4.23.4 Period measurement

If the channels (n) and (n+1) are configured to capture consecutive edges of the same polarity, then the period of the channel (n) input signal is measured. If both channels (n) and (n+1) are configured to capture rising edges ($ELS(n)B:ELS(n)A = 0:1$ and $ELS(n+1)B:ELS(n+1)A = 0:1$), then the period between two consecutive rising edges is measured. If both channels (n) and (n+1) are configured to capture falling edges ($ELS(n)B:ELS(n)A = 1:0$ and $ELS(n+1)B:ELS(n+1)A = 1:0$), then the period between two consecutive falling edges is measured.

The period measurement can be made in [One-Shot Capture mode](#) or [Continuous Capture mode](#).

The following figure shows an example of the Dual Edge Capture – One-Shot mode used to measure the period between two consecutive rising edges. The DECAPEN bit selects the Dual Edge Capture mode, so it remains set. The DECAP bit is set to enable the measurement of next period. The CH(n)F bit is set when the first rising edge is detected, that is, the edge selected by ELS(n)B:ELS(n)A bits. The CH(n+1)F bit is set and DECAP bit is cleared when the second rising edge is detected, that is, the edge selected by ELS(n+1)B:ELS(n+1)A bits. Both DECAP and CH(n+1)F bits indicate when two selected edges were captured and the C(n)V and C(n+1)V registers are ready for reading.

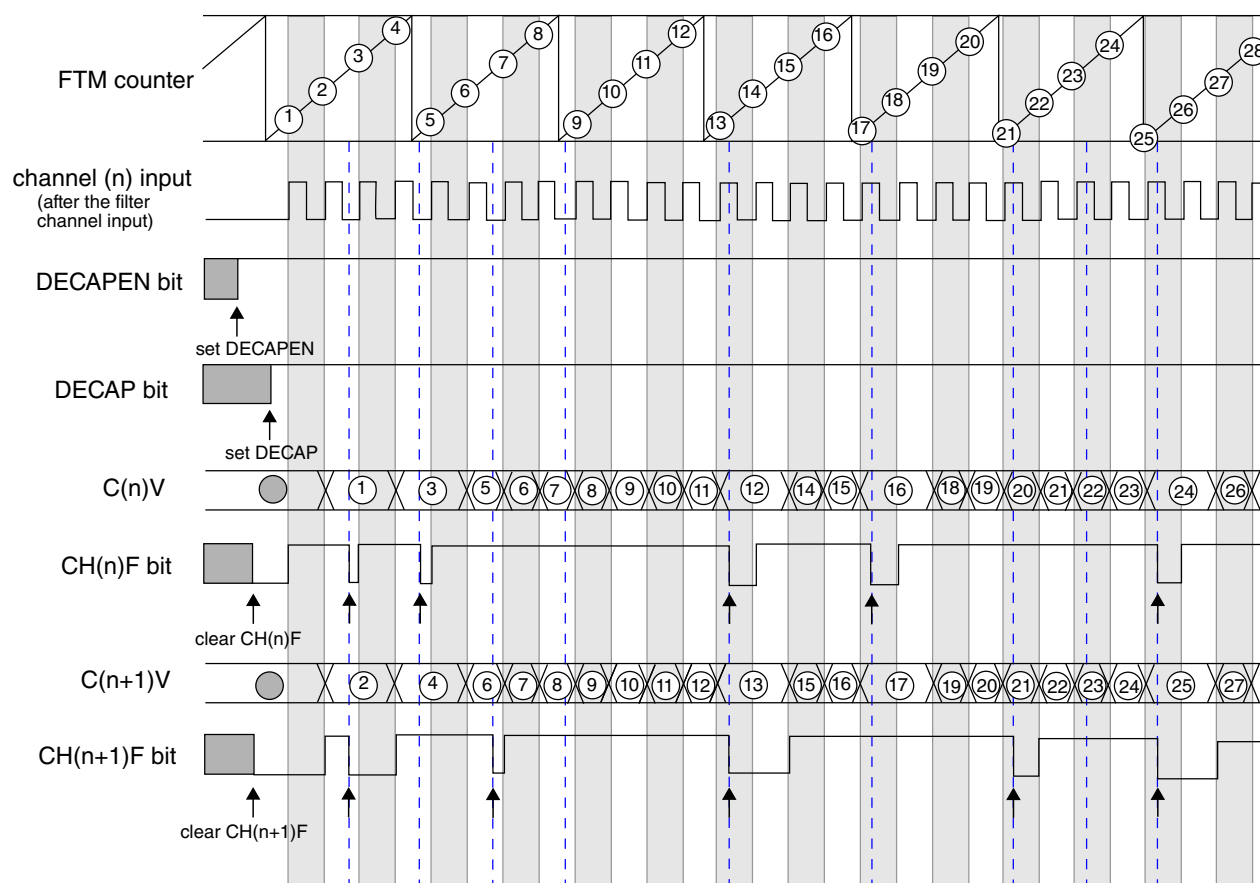


Note

- The commands set DECAPEN, set DECAP, clear CH(n)F, and clear CH(n+1)F are made by the user.
- Problem 1: channel (n) input = 0, set DECAP, not clear CH(n)F, and not clear CH(n+1)F.
- Problem 2: channel (n) input = 1, set DECAP, not clear CH(n)F, and clear CH(n+1)F.
- Problem 3: channel (n) input = 1, set DECAP, not clear CH(n)F, and not clear CH(n+1)F.

Figure 26-243. Dual Edge Capture – One-Shot mode to measure of the period between two consecutive rising edges

The following figure shows an example of the Dual Edge Capture – Continuous mode used to measure the period between two consecutive rising edges. The DECAPEN bit selects the Dual Edge Capture mode, so it remains set. While the DECAP bit is set the configured measurements are made. The CH(n)F bit is set when the first rising edge is detected, that is, the edge selected by ELS(n)B:ELS(n)A bits. The CH(n+1)F bit is set when the second rising edge is detected, that is, the edge selected by ELS(n+1)B:ELS(n+1)A bits. The CH(n+1)F bit indicates when two edges of the period were captured and the C(n)V and C(n+1)V registers are ready for reading.



Note

- The commands set DECAPEN, set DECAP, clear CH(n)F, and clear CH(n+1)F are made by the user.

Figure 26-244. Dual Edge Capture – Continuous mode to measure of the period between two consecutive rising edges

26.4.23.5 Read coherency mechanism

The Dual Edge Capture mode implements a read coherency mechanism between the FTM counter value captured in C(n)V and C(n+1)V registers. The read coherency mechanism is illustrated in the following figure. In this example, the channels (n) and (n

+1) are in Dual Edge Capture – Continuous mode for positive polarity pulse width measurement. Thus, the channel (n) is configured to capture the FTM counter value when there is a rising edge at channel (n) input signal, and channel (n+1) to capture the FTM counter value when there is a falling edge at channel (n) input signal.

When a rising edge occurs in the channel (n) input signal, the FTM counter value is captured into channel (n) capture buffer. The channel (n) capture buffer value is transferred to C(n)V register when a falling edge occurs in the channel (n) input signal. C(n)V register has the FTM counter value when the previous rising edge occurred, and the channel (n) capture buffer has the FTM counter value when the last rising edge occurred.

When a falling edge occurs in the channel (n) input signal, the FTM counter value is captured into channel (n+1) capture buffer. The channel (n+1) capture buffer value is transferred to C(n+1)V register when the C(n)V register is read.

In the following figure, the read of C(n)V returns the FTM counter value when the event 1 occurred and the read of C(n+1)V returns the FTM counter value when the event 2 occurred.

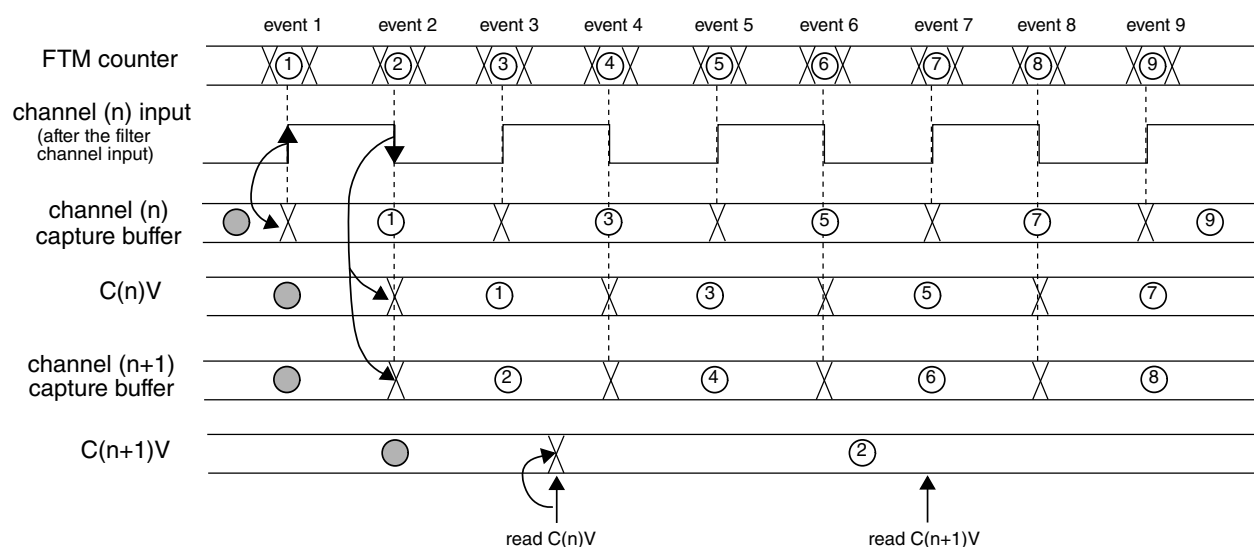


Figure 26-245. Dual Edge Capture mode read coherency mechanism

C(n)V register must be read prior to C(n+1)V register in dual edge capture one-shot and continuous modes for the read coherency mechanism works properly.

26.4.24 Debug mode

When the chip is in Debug mode, the BDMODE[1:0] bits select the behavior of the FTM counter, the CH(n)F bit, the channels output, and the writes to the MOD, CNTIN, and C(n)V registers according to the following table.

Table 26-247. FTM behavior when the chip is in Debug mode

| BDMMODE | FTM Counter | CH(n)F Bit | FTM Channels Output | Writes to MOD, CNTIN, and C(n)V Registers |
|---------|-----------------|------------|---|--|
| 00 | Stopped | can be set | Functional mode | Writes to these registers bypass the registers buffers |
| 01 | Stopped | is not set | The channels outputs are forced to their safe value according to POLn bit | Writes to these registers bypass the registers buffers |
| 10 | Stopped | is not set | The channels outputs are frozen when the chip enters in Debug mode | Writes to these registers bypass the registers buffers |
| 11 | Functional mode | can be set | Functional mode | Functional mode |

Note that if BDMMODE[1:0] = 2'b00 then the channels outputs remain at the value when the chip enters in Debug mode, because the FTM counter is stopped. However, the following situations modify the channels outputs in this Debug mode.

- Write any value to CNT register; see [Counter reset](#). In this case, the FTM counter is updated with the CNTIN register value and the channels outputs are updated to the initial value – except for those channels set to Output Compare mode.
- FTM counter is reset by PWM Synchronization mode; see [FTM counter synchronization](#). In this case, the FTM counter is updated with the CNTIN register value and the channels outputs are updated to the initial value – except for channels in Output Compare mode.
- In the channels outputs initialization, the channel (n) output is forced to the CH(n)OI bit value when the value 1 is written to INIT bit. See [Initialization](#).

Note

The BDMMODE[1:0] = 2'b00 must not be used with the [Fault control](#). Even if the fault control is enabled and a fault condition exists, the channels outputs values are updated as above.

Note

If CLKS[1:0] = 2'b00 in BDM, a non-zero value is written to CLKS in BDM, and CnV = CNTIN when the BDM is disabled, then the CHnF bit is set (since if the channel is a 0% EPWM signal) when the BDM is disabled.

26.4.25 Intermediate load

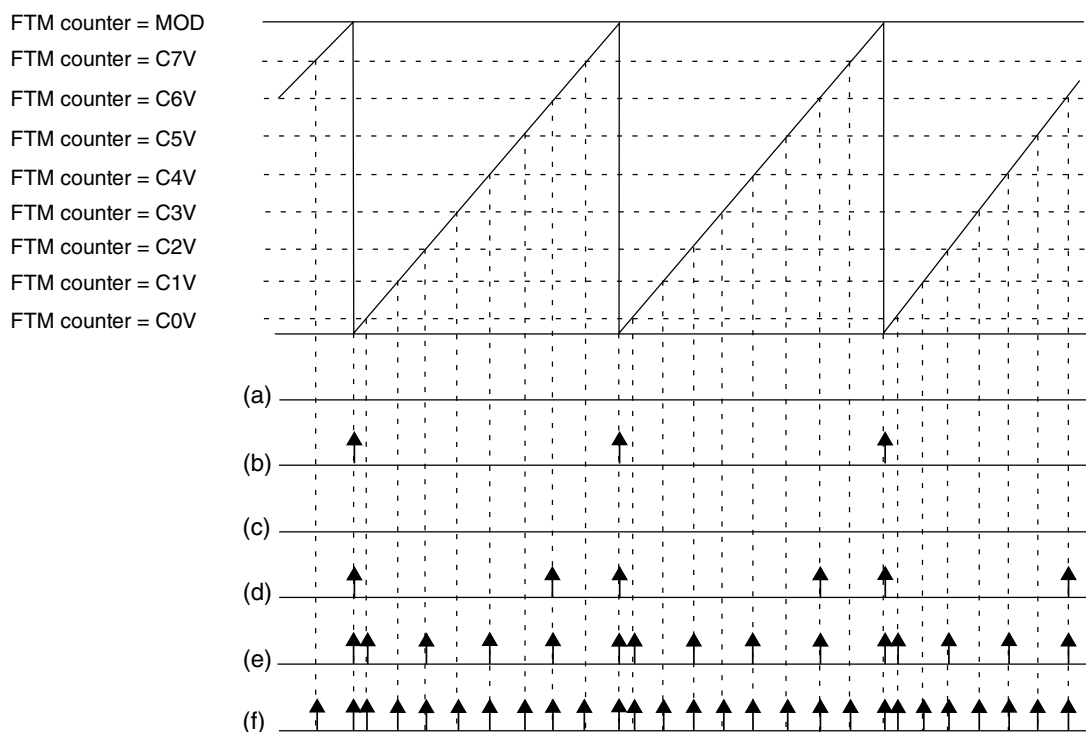
The PWMLOAD register allows to update the MOD, CNTIN, and C(n)V registers with the content of the register buffer at a defined load point. In this case, it is not required to use the PWM synchronization.

There are multiple possible loading points for intermediate load:

Table 26-248. When possible loading points are enabled

| Loading point | Enabled |
|--|-----------------|
| When the FTM counter wraps from MOD value to CNTIN value | Always |
| At the channel (j) match (FTM counter = C(j)V) | When CHjSEL = 1 |

The following figure shows some examples of enabled loading points.



NOTE

- (a) LDOK = 0, CH0SEL = 0, CH1SEL = 0, CH2SEL = 0, CH3SEL = 0, CH4SEL = 0, CH5SEL = 0, CH6SEL = 0, CH7SEL = 0
- (b) LDOK = 1, CH0SEL = 0, CH1SEL = 0, CH2SEL = 0, CH3SEL = 0, CH4SEL = 0, CH5SEL = 0, CH6SEL = 0, CH7SEL = 0
- (c) LDOK = 0, CH0SEL = 0, CH1SEL = 0, CH2SEL = 0, CH3SEL = 1, CH4SEL = 0, CH5SEL = 0, CH6SEL = 0, CH7SEL = 0
- (d) LDOK = 1, CH0SEL = 0, CH1SEL = 0, CH2SEL = 0, CH3SEL = 0, CH4SEL = 0, CH5SEL = 0, CH6SEL = 1, CH7SEL = 0
- (e) LDOK = 1, CH0SEL = 1, CH1SEL = 0, CH2SEL = 1, CH3SEL = 0, CH4SEL = 1, CH5SEL = 0, CH6SEL = 1, CH7SEL = 0
- (f) LDOK = 1, CH0SEL = 1, CH1SEL = 1, CH2SEL = 1, CH3SEL = 1, CH4SEL = 1, CH5SEL = 1, CH6SEL = 1, CH7SEL = 1

Figure 26-246. Loading points for intermediate load

After enabling the loading points, the LDOK bit must be set for the load to occur. In this case, the load occurs at the next enabled loading point according to the following conditions:

Table 26-249. Conditions for loads occurring at the next enabled loading point

| When a new value was written | Then |
|---|--|
| To the MOD register | The MOD register is updated with its write buffer value. |
| To the CNTIN register and CNTINC = 1 | The CNTIN register is updated with its write buffer value. |
| To the C(n)V register and SYNCENm = 1 – where m indicates the pair channels (n) and (n+1) | The C(n)V register is updated with its write buffer value. |
| To the C(n+1)V register and SYNCENm = 1 – where m indicates the pair channels (n) and (n+1) | The C(n+1)V register is updated with its write buffer value. |

NOTE

- If ELSjB and ELSjA bits are different from zero, then the channel (j) output signal is generated according to the configured output mode. If ELSjB and ELSjA bits are zero, then the generated signal is not available on channel (j) output.
- If CHjIE = 1, then the channel (j) interrupt is generated when the channel (j) match occurs.
- At the intermediate load neither the channels outputs nor the FTM counter are changed. Software must set the intermediate load at a safe point in time.

26.4.26 Global time base (GTB)

The global time base (GTB) is a FTM function that allows the synchronization of multiple FTM modules on a chip. The following figure shows an example of the GTB feature used to synchronize two FTM modules. In this case, the FTM A and B channels can behave as if just one FTM module was used, that is, a global time base.

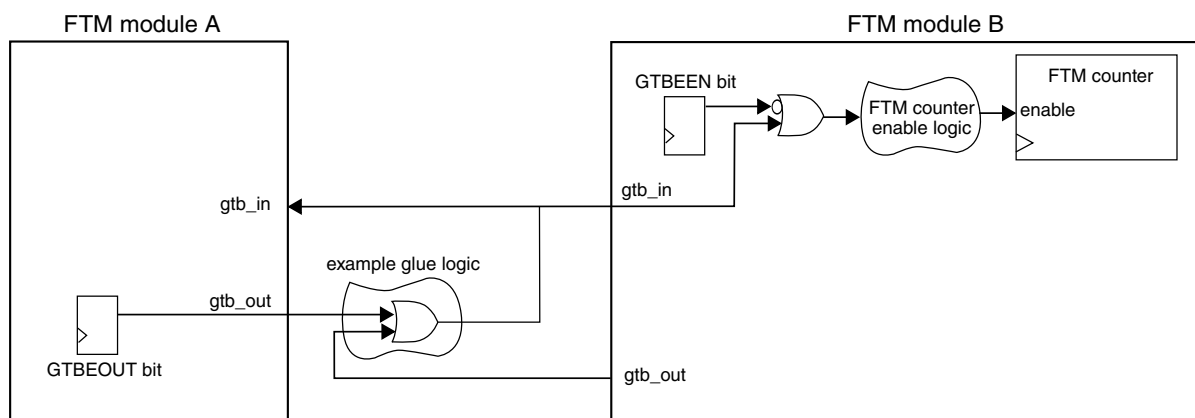


Figure 26-247. Global time base (GTB) block diagram

The GTB functionality is implemented by the GTBEEN and GTBEOUT bits in the CONF register, the input signal *gtb_in*, and the output signal *gtb_out*. The GTBEEN bit enables *gtb_in* to control the FTM counter enable signal:

- If GTBEEN = 0, each one of FTM modules works independently according to their configured mode.
- If GTBEEN = 1, the FTM counter update is enabled only when *gtb_in* is 1.

In the configuration described in the preceding figure, FTM modules A and B have their FTM counters enabled if at least one of the *gtb_out* signals from one of the FTM modules is 1. There are several possible configurations for the interconnection of the *gtb_in* and *gtb_out* signals, represented by the example glue logic shown in the figure. Note that these configurations are chip-dependent and implemented outside of the FTM modules. See the chip-specific FTM information for the chip's specific implementation.

NOTE

- In order to use the GTB signals to synchronize the FTM counter of different FTM modules, the configuration of each FTM module should guarantee that its FTM counter starts counting as soon as the *gtb_in* signal is 1.
- The GTB feature does not provide continuous synchronization of FTM counters, meaning that the FTM counters may lose synchronization during FTM operation. The GTB feature only allows the FTM counters to *start* their operation synchronously.

26.4.26.1 Enabling the global time base (GTB)

To enable the GTB feature, follow these steps for each participating FTM module:

1. Stop the FTM counter: Write 00b to SC[CLKS].

2. Program the FTM to the intended configuration. The FTM counter mode needs to be consistent across all participating modules.
3. Write 1 to CONF[GTBEEN] and write 0 to CONF[GTBEOU] at the same time.
4. Select the intended FTM counter clock source in SC[CLKS]. The clock source needs to be consistent across all participating modules.
5. Reset the FTM counter: Write any value to the CNT register.

To initiate the GTB feature in the configuration described in the preceding figure, write 1 to CONF[GTBEOU] in the FTM module used as the time base.

26.5 Reset overview

The FTM is reset whenever any chip reset occurs.

When the FTM exits from reset:

- the FTM counter and the prescaler counter are zero and are stopped (CLKS[1:0] = 00b);
- the timer overflow interrupt is zero, see [Timer Overflow Interrupt](#);
- the channels interrupts are zero, see [Channel \(n\) Interrupt](#);
- the fault interrupt is zero, see [Fault Interrupt](#);
- the channels are in input capture mode, see [Input Capture mode](#);
- the channels outputs are zero;
- the channels pins are not controlled by FTM (ELS(n)B:ELS(n)A = 0:0) (See the table in the description of CnSC register).

The following figure shows the FTM behavior after the reset. At the reset (item 1), the FTM counter is disabled (see the description of the CLKS field in the Status and Control register), its value is updated to zero and the pins are not controlled by FTM (See the table in the description of CnSC register).

After the reset, the FTM should be configured (item 2). It is necessary to define the FTM counter mode, the FTM counting limits (MOD and CNTIN registers value), the channels mode and CnV registers value according to the channels mode.

Thus, it is recommended to write any value to CNT register (item 3). This write updates the FTM counter with the CNTIN register value and the channels output with its initial value (except for channels in output compare mode) ([Counter reset](#)).

The next step is to select the FTM counter clock by the CLKS[1:0] bits (item 4). It is important to highlight that the pins are only controlled by FTM when CLKS[1:0] bits are different from zero (See the table in the description of CnSC register).

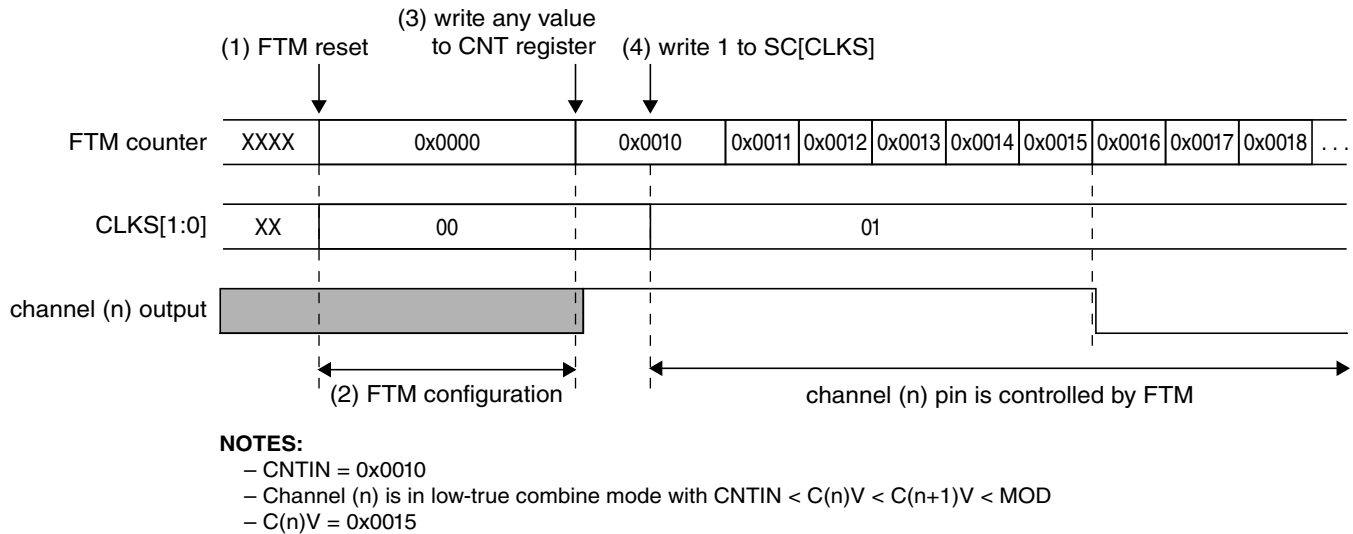


Figure 26-248. FTM behavior after reset when the channel (n) is in Combine mode

The following figure shows an example when the channel (n) is in Output Compare mode and the channel (n) output is toggled when there is a match. In the Output Compare mode, the channel output is not updated to its initial value when there is a write to CNT register (item 3). In this case, use the software output control ([Software output control](#)) or the initialization ([Initialization](#)) to update the channel output to the selected value (item 4).

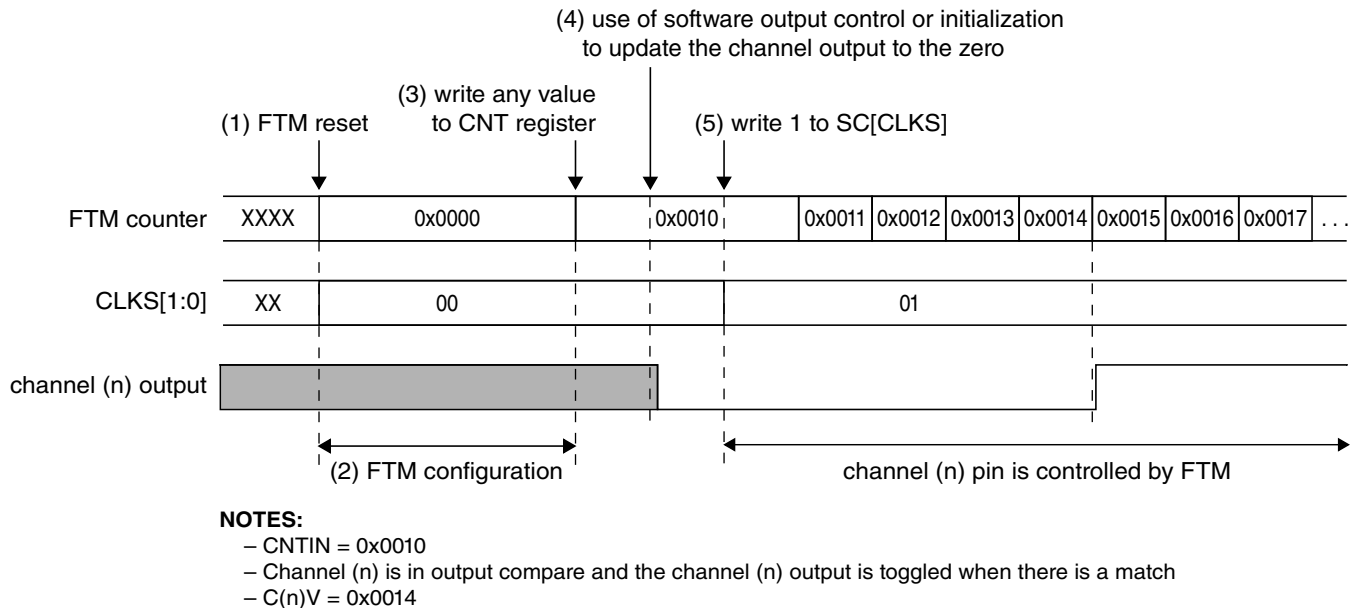


Figure 26-249. FTM behavior after reset when the channel (n) is in Output Compare mode

26.6 FTM Interrupts

26.6.1 Timer Overflow Interrupt

The timer overflow interrupt is generated when (TOIE = 1) and (TOF = 1).

26.6.2 Channel (n) Interrupt

The channel (n) interrupt is generated when (CHnIE = 1) and (CHnF = 1).

26.6.3 Fault Interrupt

The fault interrupt is generated when (FAULTIE = 1) and (FAULTF = 1).

26.7 Initialization Procedure

The following initialization procedure is recommended to configure the FlexTimer operation. This procedure can also be used to do a new configuration of the FlexTimer operation.

- Define the POL bits.
- Mask the channels outputs using SYNCHOM = 0. Two clocks after the write to OUTMASK, the channels output are in the safe value.
- (Re)Configuration FTM counter and channels to generation of periodic signals - Disable the clock. If the selected mode is Quadrature Decoder, then disable this mode. Examples of the (re)configuration:
 - Write to MOD.
 - Write to CNTIN.
 - Select OC, EPWM, CPWM, Combine, Complement modes for all channels that will be used
 - Select the high-true and low-true channels modes.
 - Write to CnV for all channels that will be used .
 - (Re)Configure deadtime and fault control.
 - Do not use the SWOC without SW synchronization (see item 6).
 - Do not use the Inverting without SW synchronization (see item 6).
 - Do not use the Initialization.
 - Do not change the polarity control.
 - Do not configure the HW synchronization

- Write any value to CNT. The FTM Counter is reset and the channels output are updated according to new configuration.
- Enable the clock. Write to CLKS[1:0] bits a value different from zero. If in the Quadrature Decoder mode, enable this mode.
- Configure the SW synchronization for SWOC (if it is necessary), Inverting (if it is necessary) and Output Mask (always)
 - Select synchronization for Output Mask Write to SYNC (SWSYNC = 0, TRIG2 = 0, TRIG1 = 0, TRIG0 = 0, SYNCHOM = 1, REINIT = 0, CNTMAX = 0, CNTMIN = 0)
 - Write to SYNCONF.
 - HW Synchronization can not be enabled (HWSOC = 0, HWINVC = 0, HWOM = 0, HWWRBUF = 0, HWRSTCNT = 0, HWTRIGMODE = 0).
 - SW Synchronization for SWOC (if it is necessary): SWSOC = [0/1] and SWOC = [0/1].
 - SW Synchronization for Inverting (if it is necessary): SWINVC = [0/1] and INVC = [0/1].
 - SW Synchronization for SWOM (always): SWOM = 1. No enable the SW Synchronization for write buffers (because the writes to registers with write buffer are done using CLKS[1:0] = 2'b00): SWWRBUF = 0 and CNTINC = 0.
 - SW Synchronization for counter reset (always): SWRSTCNT = 1.
 - Enhanced synchronization (always): SYNCMODE = 1
 - If the SWOC is used (SWSOC = 1 and SWOC = 1), then write to SWOCTRL register.
 - If the Inverting is used (SWINVC = 1 and INVC = 1), then write to INVCTRL register.
 - Write to OUTMASK to enable the masked channels.
- Generate the Software Trigger Write to SYNC (SWSYNC = 1, TRIG2 = 0, TRIG1 = 0, TRIG0 = 0, SYNCHOM = 1, REINIT = 0, CNTMAX = 0, CNTMIN = 0)

Chapter 27

Pulse Width Timer (PWT)

27.1 Introduction

27.1.1 Features

The pulse width timer (PWT) includes the following features:

- Automatic measurement of pulse width with 16-bit resolution
- Separate positive and negative pulse width measurements
- Programmable triggering edge for starting measurement
- Programmable measuring time between successive alternating edges, rising edges or falling edges
- Programmable prescaler from clock input as 16-bit counter time base
- Two selectable clock sources—bus clock and alternative clock
- Four selectable pulse inputs
- Programmable interrupt generation upon pulse width value updated and counter overflow

27.1.2 Modes of operation

The following table describes the operation of the PWT module in various modes.

| Modes | Description |
|-------------------|--|
| Run | When enabled, the pulse width timer module is active. |
| Wait | When enabled, the pulse width timer module is active and can perform the waking up function if the corresponding interrupt is enabled. |
| Stop | The pulse width timer module is halted when entering stop and the register contents and operating status is preserved. If stop exits with reset then the module resets. If stop exits with another source, the module resumes operation based on module status upon exit. |
| Active background | Upon entering Debug mode, the PWT suspends all counting and pulse edge detection until the microcontroller returns to normal user operating mode. Counting and edge detection resume from the suspended value when normal user operating mode returns as long as the PWTSR bit (PWT software reset) is not written to 1 and the PWT module is still enabled. |

27.1.3 Block diagram

The following is the block diagram of the pulse width timer module (PWT).

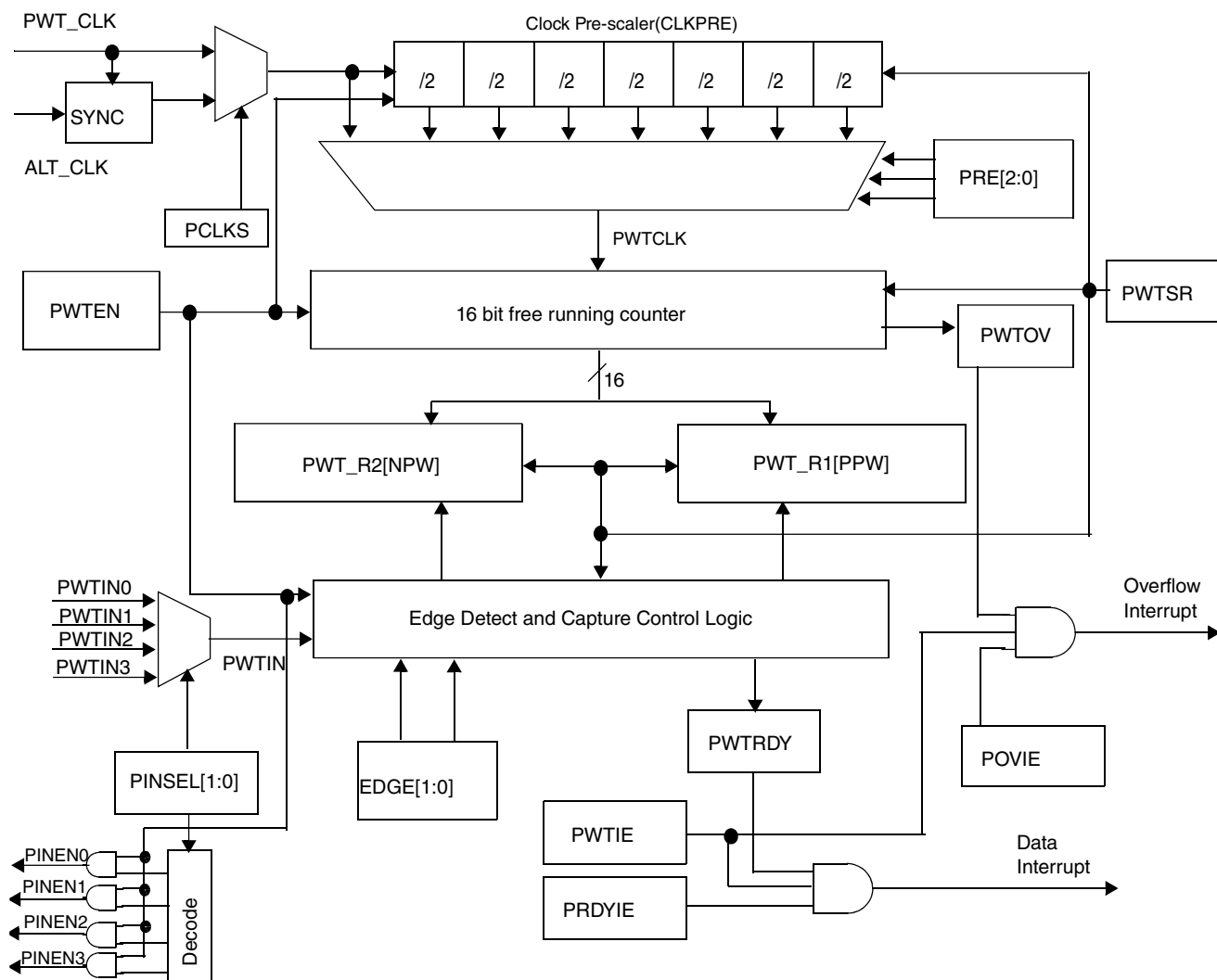


Figure 27-1. Pulse width timer (PWT) block diagram

NOTE

The PWT_CLK depends on the Chip input clock. For this chip it is TIMER_CLK.

27.2 PWT signal description

Table 27-2. PWT signal description

| Signal | I/O | Pullup | Description |
|------------|-----|--------|--|
| PWTIN[3:0] | I | No | Pulse Inputs |
| ALTCLK | I | No | Alternative clock source for the counter |

27.2.1 PWTIN[3:0] - Pulse Width Timer Capture Inputs

The input signals are pulse capture inputs which can come from internal or external sources. The PWT input is selected by PINSEL[1:0] to be routed to the pulse width timer. If the input comes from external source and is selected as the PWT input, the input port is enabled for PWT function by PINSEL[1:0] automatically. The minimum pulse width to be measured is 1 PWTCLK cycle, any pulse narrower than this value is ignored by PWT module. The PWTCLK cycle time depends on the PWT clock source selection and prescaler rate setting.

27.2.2 ALTCLK- Alternative Clock Source for Counter

The PWT has an alternative clock input ALTCLK which can be selected as the clock source of the counter when R1[PCLKS] is set. The ALTCLK input must be synchronized by the bus clock. Variations in duty cycle and clock jitter must also be accommodated so that the ALTCLK signal must not exceed one-fourth of the bus frequency. The ALTCLK pin can be shared with a general-purpose port pin. See the Pins and Connections chapter for the pin location and priority of this function.

27.3 Memory Map and Register Descriptions

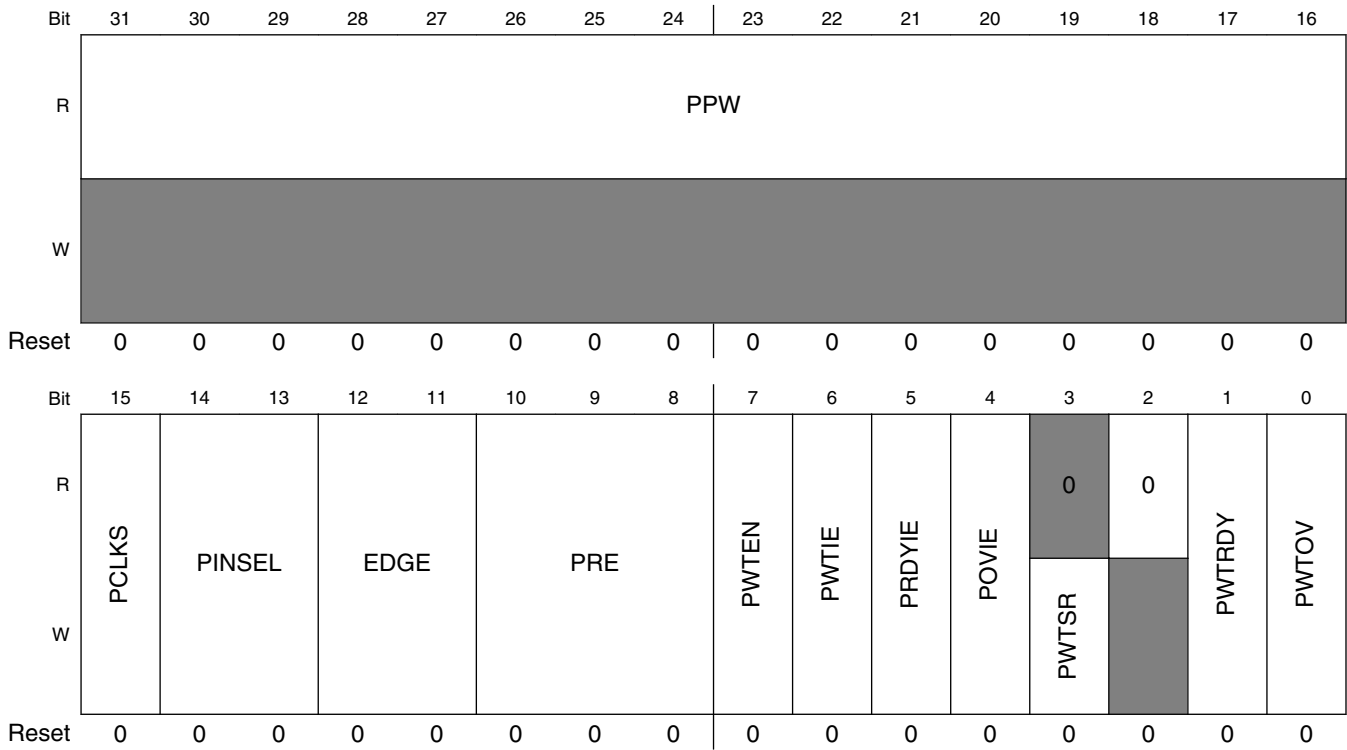
PWT memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---------------------------------------|-----------------|--------|-------------|----------------------------|
| 4003_3000 | Pulse Width Timer Register 1 (PWT_R1) | 32 | R/W | 0000_0000h | 27.3.1/492 |
| 4003_3004 | Pulse Width Timer Register 2 (PWT_R2) | 32 | R | 0000_0000h | 27.3.2/494 |

27.3.1 Pulse Width Timer Register 1 (PWT_R1)

This register defines the general control and status bits for the PWT. It also contains the Positive Pulse Width contents.

Address: 4003_3000h base + 0h offset = 4003_3000h



PWT_R1 field descriptions

| Field | Description |
|-----------------|---|
| 31–16 PPW | Positive Pulse Width Captured positive pulse width value. It is suggested to use half-word (16-bit) or word (32-bit) to read out this value. |
| 15 PCLKS | PWT Clock Source Selection Controls the selection of clock source for the PWT counter. 0 BUS_CLK is selected as the clock source of PWT counter. 1 Alternative clock is selected as the clock source of PWT counter. |
| 14–13 PINSEL | PWT Pulse Inputs Selection Enables the corresponding PWT input port, if this PWT input comes from an external source. 00 PWTIN[0] is enabled. 01 PWTIN[1] is enabled. |

Table continues on the next page...

PWT_R1 field descriptions (continued)

| Field | Description |
|---------------|---|
| | 10 PWTIN[2] enabled. 11 PWTIN[3] enabled. |
| 12–11 EDGE | <p>PWT Input Edge Sensitivity</p> <p>Selects which edge triggers the pulse width measurement and which edges trigger the capture. If user needs to change the trigger and capture mode by changing the value of EDGE[1:0], a PWT software reset is required after changing the EDGE[1:0] value. Clearing PWTEN and then setting it has the same effect.</p> 00 The first falling-edge starts the pulse width measurement, and on all the subsequent falling edges, the pulse width is captured. 01 The first rising edge starts the pulse width measurement, and on all the subsequent rising and falling edges, the pulse width is captured. 10 The first falling edge starts the pulse width measurement, and on all the subsequent rising and falling edges, the pulse width is captured. 11 The first-rising edge starts the pulse width measurement, and on all the subsequent rising edges, the pulse width is captured. |
| 10–8 PRE | <p>PWT Clock Prescaler (CLKPRE) Setting</p> <p>Selects the value by which the clock is divided to clock the PWT counter.</p> 000 Clock divided by 1. 001 Clock divided by 2. 010 Clock divided by 4. 011 Clock divided by 8. 100 Clock divided by 16. 101 Clock divided by 32. 110 Clock divided by 64. 111 Clock divided by 128. |
| 7 PWTEN | <p>PWT Module Enable</p> <p>Enables/disables the PWT module. To avoid unexpected behavior, do not change any PWT configurations as long as PWTEN is set.</p> 0 The PWT is disabled. 1 The PWT is enabled. |
| 6 PWTIE | <p>PWT Module Interrupt Enable</p> <p>Enables the PWT module to generate an interrupt.</p> 0 Disables the PWT to generate interrupt. 1 Enables the PWT to generate interrupt. |
| 5 PRDYIE | <p>PWT Pulse Width Data Ready Interrupt Enable</p> <p>Enables/disables the PWT to generate an interrupt when PWTRDY is set as long as PWTIE is set.</p> 0 Disable PWT to generate interrupt when PWTRDY is set. 1 Enable PWT to generate interrupt when PWTRDY is set. |
| 4 POVIE | <p>PWT Counter Overflow Interrupt Enable</p> <p>Enables/disables the PWT to generate an interrupt when PWTOV is set due to PWT counter overflow.</p> |

Table continues on the next page...

PWT_R1 field descriptions (continued)

| Field | Description |
|---------------|---|
| | 0 Disable PWT to generate interrupt when PWTOV is set. 1 Enable PWT to generate interrupt when PWTOV is set. |
| 3 PWTSR | PWT Soft Reset Performs a soft reset to the PWT. This field always reads as 0. 0 No action taken. 1 Writing 1 to this field will perform soft reset to PWT. |
| 2 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 1 PWTRDY | PWT Pulse Width Valid Indicates that the PWT Pulse Width register(s) has been updated and is ready to be read. This field is cleared by reading PWTRDY and then writing 0 to PWTRDY bit when PWTRDY is set. Writing 1 to this field has no effect. PWTRDY setting is associated with the EDGE[1:0] bits. 0 PWT pulse width register(s) is not up-to-date. 1 PWT pulse width register(s) has been updated. |
| 0 PWTOV | PWT Counter Overflow Indicates that the PWT counter has run from 0x0000_0xFFFF to 0x0000_0x0000. This field is cleared by writing 0 to PWTOV when PWTOV is set. Writing 1 to this field has no effect. If another overflow occurs when this field is being cleared, the clearing fails. 0 PWT counter no overflow. 1 PWT counter runs from 0xFFFF to 0x0000. |

27.3.2 Pulse Width Timer Register 2 (PWT_R2)

This register contains the Negative Pulse Width contents and the 16-bit free running counter contents.

Address: 4003_3000h base + 4h offset = 4003_3004h

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PWTC | | | | | | | | | | | | | | | | NPW | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

PWT_R2 field descriptions

| Field | Description |
|---------------|--|
| 31–16 PWTC | PWT Counter. It is suggested to use half-word (16-bit) or word (32-bit) to read out this value. |
| NPW | Negative Pulse Width. It is suggested to use half-word (16-bit) or word (32-bit) to read out this value. |

27.4 Functional Description

27.4.1 PWT Counter and PWT Clock Prescaler

The pulse width timer (PWT) measures duration of a pulse or the period of a signal input to the PWTIN by a 16-bit free running counter (PWT_R2[PWTC]). There is a clock prescaler (CLKPRE) in PWT module that provides the frequency divided clock to PWT_R2[PWTC]. The clock prescaler can select clock input from bus clock and alternative clock by PWT_R1[PCKLS].

The PWT counter uses the frequency divided clock from CLKPRE for counter advancing. The frequency of prescaler is programmable as the clock frequency divided by 1, 2, 4, 8, 16, 32, 64, 128 (depending on the setting of PRE[2:0]).

As soon as the PWT counter is enabled, it starts counting using the selected and divided clock source; the counter is cleared without loading to the registers when the first valid edge (trigger edge) is detected. If no valid trigger edge is detected for a long time, it is possible for the counter to overflow. When 16-bit free running counter is running, any edge to be measured after the trigger edge causes the value of PWT_R2[PWTC] to be uploaded to the appropriate pulse width registers. At the same time, PWT_R2[PWTC] will be reset to 0x0000 and the clock prescaler output will also be reset together. PWT_R2[PWTC] will then start advancing again with the input clock. If the PWT_R2[PWTC] runs from 0xFFFF to 0x0000, the PWTOV bit is set.

27.4.2 Edge detection and capture control

The edge detection and capture control part detects measurement trigger edges and controls when and which pulse width register(s) will be updated.

Based on the setting of EDGE[1:0], the edge detection logic determines the starting and ending edge of the pulse width to be measured on PWTIN, and the registers fields to be updated. See [Edge detection and capture control](#) for details.

The PWTIN can be selected from one of four sources by configuring PINSEL[1:0].

It must be noted that inside the edge detection and capture logic, the system slave clock is used for PWT to sample and synchronize the PWTIN pulse, therefore the minimal PWTIN pulse width is determined by this slave clock frequency. For example, if this clock frequency is 50 MHz, the minimal PWTIN pulse width must be longer than 20 ns(the period of 50 MHz), otherwise, PWT won't be able to capture this pulse and the

counter would overflow. See the chip configuration chapters to check the slave clock frequency to PWT. Also, if there isn't any valid edge of the PWTIN width for a long time, the PWT counter would overflow as well.

When EDGE[1:0] is 00, the first falling edge is the trigger edge from which the pulse width begins to be measured. The counter value is uploaded to PWT_R1[PPW] upon each of the subsequent falling edges. When EDGE[1:0] is 11, the first rising edge is the trigger edge from which the pulse width begins to be measured. The counter value is uploaded to PWT_R2[NPW] upon each successive rising-edge. In these two cases, the period of PWTIN is measured.

When EDGE[1:0] is 01, the first rising edge is the trigger edge. The pulse width begins to be measured from this edge. PWT_R1[PPW] is uploaded upon each of the subsequent falling edges. PWT_R2[NPW] is uploaded upon each successive rising edge. When EDGE[1:0] is 10, the first falling edge is the trigger edge from which the pulse width is measured. PWT_R2[NPW] is uploaded on each successive rising edge and PWT_R1[PPW] is uploaded on each successive falling edge. In these two cases, the positive pulse and negative pulse are measured separately and the positive pulse width is uploaded into PWT_R1[PPW]. The negative pulse width is uploaded into PWT_R2[NPW].

The following figure illustrates the trigger edge detection and pulse width registers update of PWT.

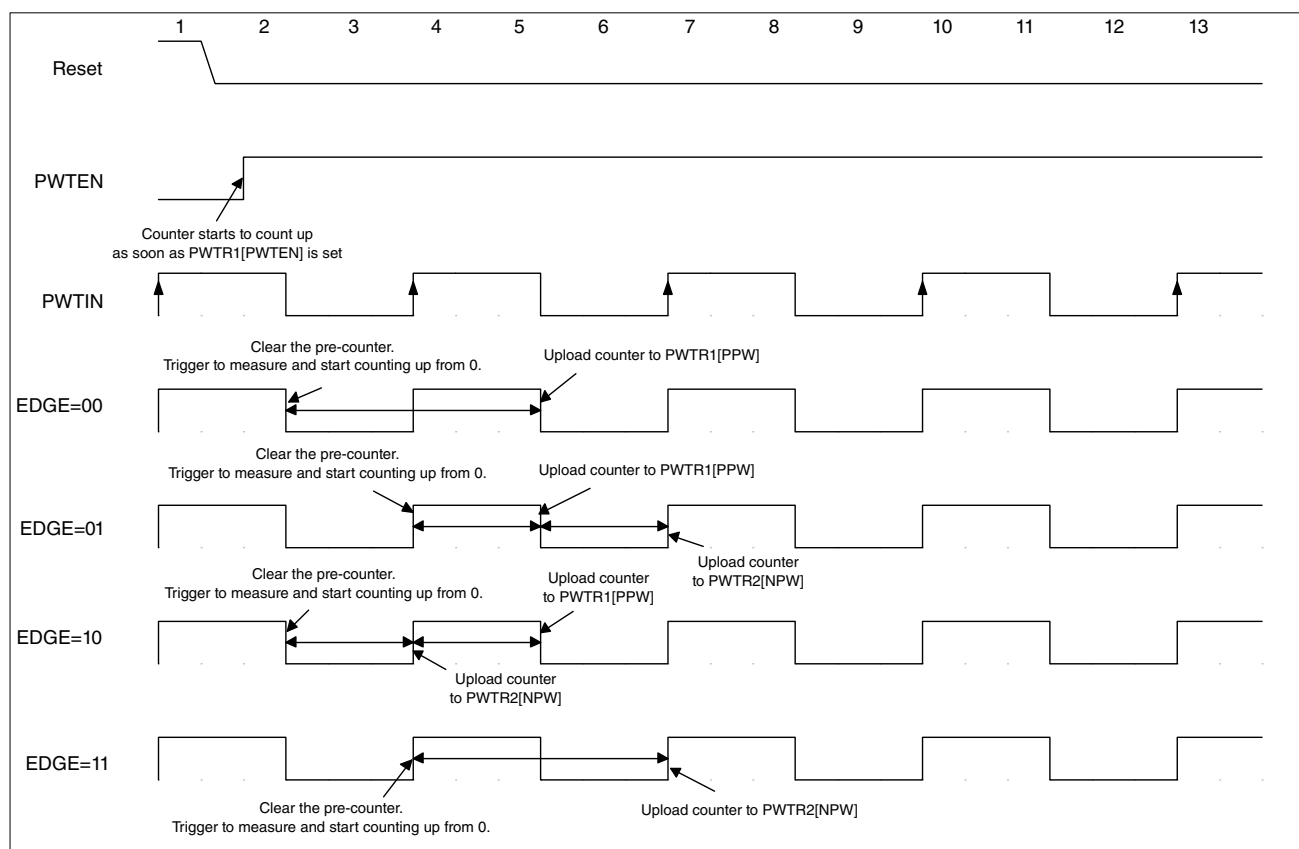


Figure 27-4. Trigger edge detection and pulse width registers update

PWT_R1[PWTRDY] indicates that the data can be read in PWT_R1[PPW] and/or PWT_R2[NPW], based on the setting of EDGE[1:0].

- When EDGE[1:0] is 00, PWT_R1[PWTRDY] is set whenever PWT_R1[PPW] is updated.
- When EDGE[1:0] is 11, PWT_R1[PWTRDY] is set whenever PWT_R2[NPW] is updated.
- When EDGE[1:0] is 01, PWT_R1[PWTRDY] is set whenever PWTxPPH:L is updated, followed by PWT_R2[NPW]'s update.
- When EDGE[1:0] is 10, PWT_R1[PWTRDY] is set whenever PWT_R2[NPW] is updated, followed by PWT_R1[PPW]'s update.

When PWT_R1[PWTRDY] is set, the updated pulse width register(s) transfers the data to corresponding 16-bit read buffer(s). The read value of pulse width registers actually comes from the corresponding read buffers, whenever the chip is in normal run mode or Debug mode. Reading followed by writing 0 to PWT_R1[PWTRDY] flag clears this field. Until PWT_R1[PWTRDY] is cleared, the 16-bit read buffer(s) cannot be updated. But this does not affect the upload of pulse width registers from the PWT counter.

If another pulse measurement is completed and the pulse width registers are updated, the clearing of the PWT_R1[PWTRDY] flag fails, that is, PWT_R1[PWTRDY] will still be set, but the 16-bit read buffer(s) will be updated again as long as the action is cleared.. The user should complete the pulse width data reading before clearing PWT_R1[PWTRDY] to avoid missing data. This mechanism assures that the second pulse measurement will not be lost in case the MCU does not have enough time to read the first one ready for read. The mechanism is automatically restarted by an MCU reset , writing 1 to PWT_R1[PWTSR] or writing a 0 to PWT_R1[PWTEN] followed by writing a 1 to it.

The following figure illustrates the buffering mechanism of pulse width register:

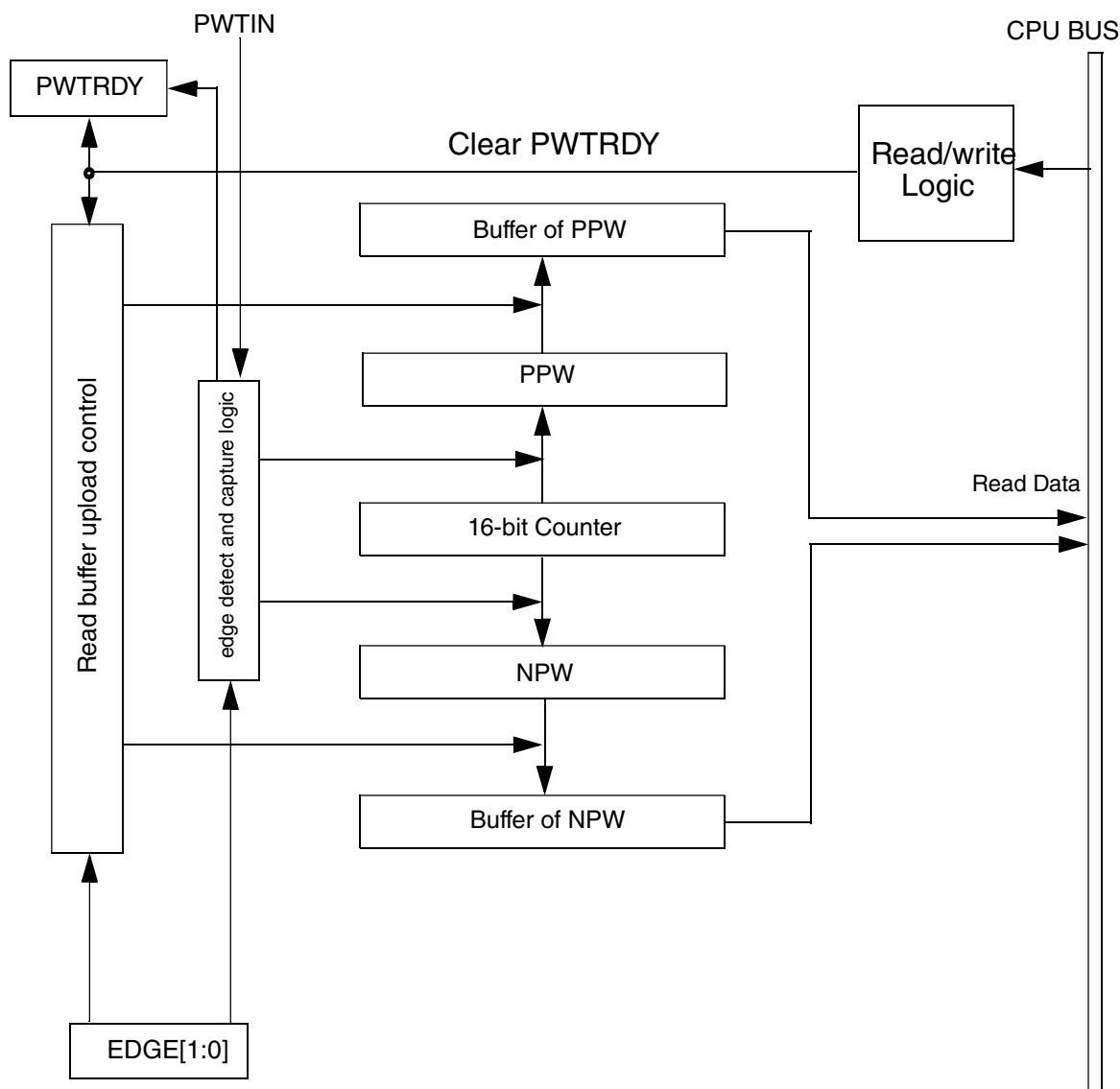


Figure 27-5. Buffering mechanism of Pulse Width register

When PWT completes any pulse width measurement, a signal is generated to reset PWT_R2[CNTC] and the clock prescaler output after the data has been uploaded to the pulse width registers. To assure that there is no missing count, PWT_R2[CNTC] and the clock prescaler output are reset in a bus clock cycle after the completion of a pulse width measurement.

27.5 Reset

27.5.1 General

27.5.2 Description of reset operation

PWT soft reset is built into PWT as a mechanism used to reset/restart the pulse width timer. The PWT soft reset is triggered by writing 1 to PWT_R1[PWTSR]. (This field always reads 0). Unlike reset by the CPU, the PWT reset does not restore everything in the PWT to its reset state. The following steps can be used to describe the reset operation.

1. The PWT counter is set to 0x0000.
2. The 16-bit buffer of PWT counter is reset.
3. The PWT clock prescaler output is reset.
4. The edge detection logic is reset.
5. The capture logic is reset and the latching mechanism of pulse width registers is also restarted.
6. PWT_R1[PPW] and PWT_R2[NPW] are set to 0x0000.
7. PWT_R1[PWTOV] and PWT_R1[PWTRDY] are set to 0.
8. All other PWT register settings are not changed.

Writing a 0 to PWT_R1[PWTEN] also has the above effects except that the reset state will be held until PWT_R1[PWTEN] is set to 1.

27.6 Interrupts

27.6.1 Description of interrupt operation

The other major component of the PWT is the interrupts control logic. When PWT_R1[PWTOV] and PWT_R1[POVIE] are set, a PWT overflow interrupt can be generated. When PWT_R1[PWTRDY] bit and PWT_R1[PRDYIE] are set, a pulse width

data ready interrupt can be generated. PWT_R1[PWTIE] controls the interrupt generation of the PWT module. The functionality of the PWT is not affected while the interrupt is being generated.

27.6.2 Application examples

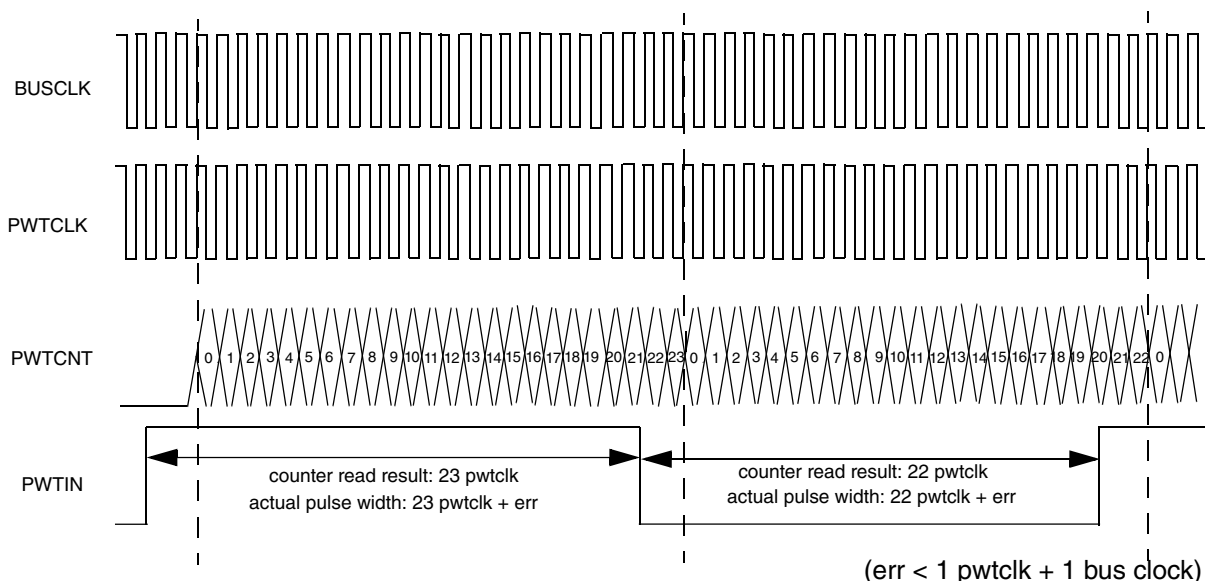


Figure 27-6. Example at PWTCLK is Bus Clock divided by 1

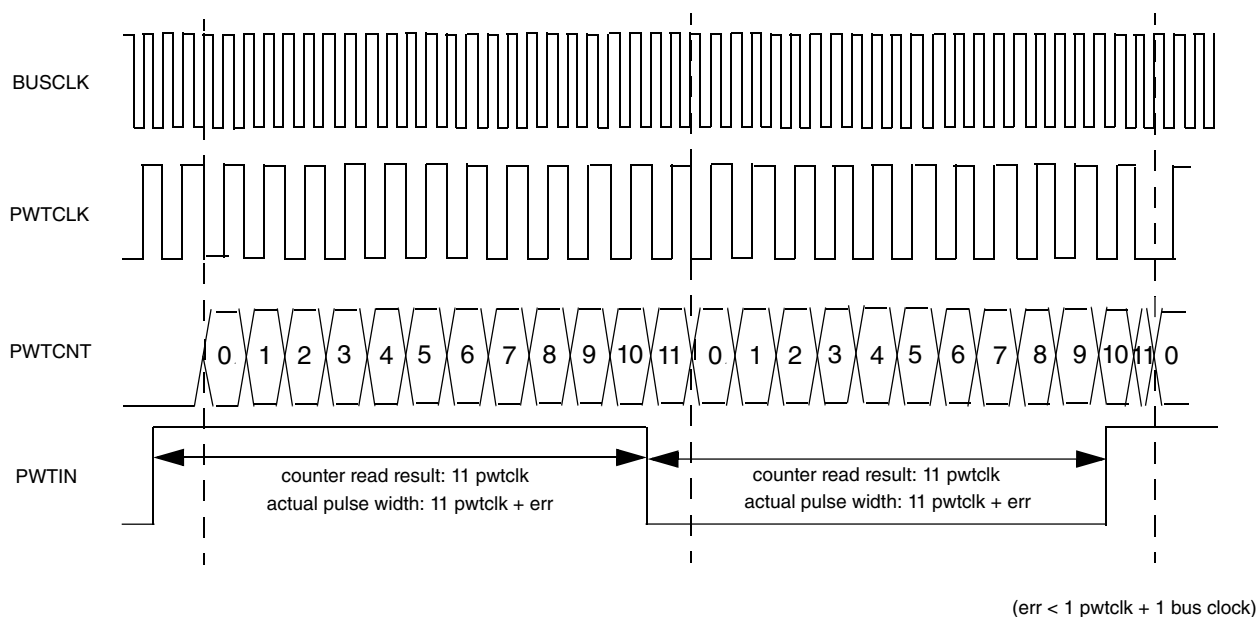


Figure 27-7. Example at PWTCLK is Bus Clock divided by 2

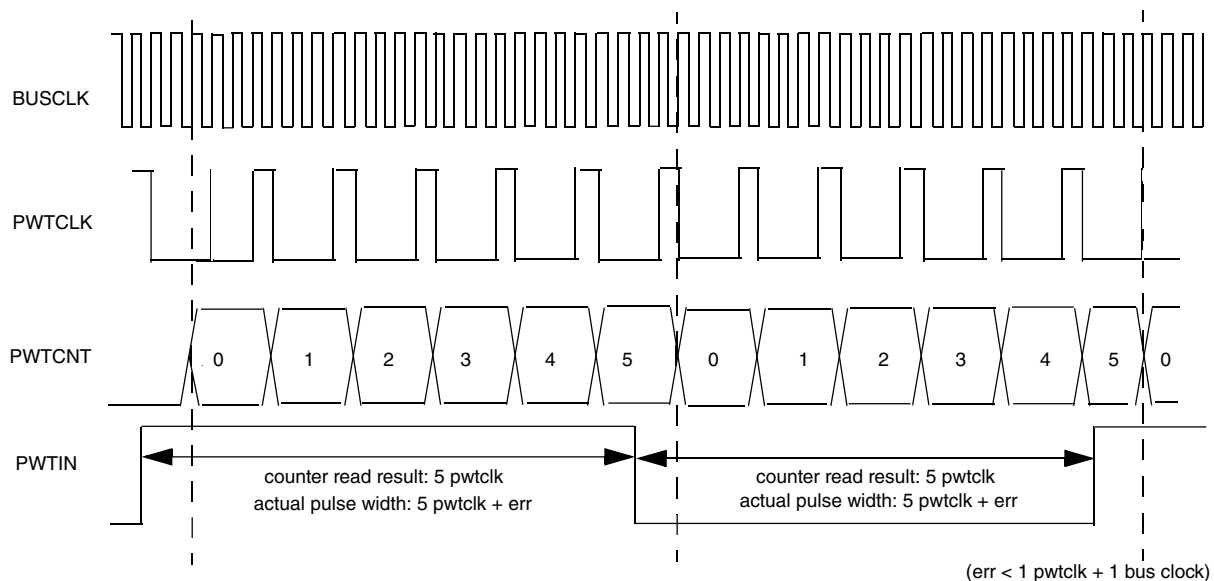


Figure 27-8. Example at PWTCLK is Bus Clock divided by 4

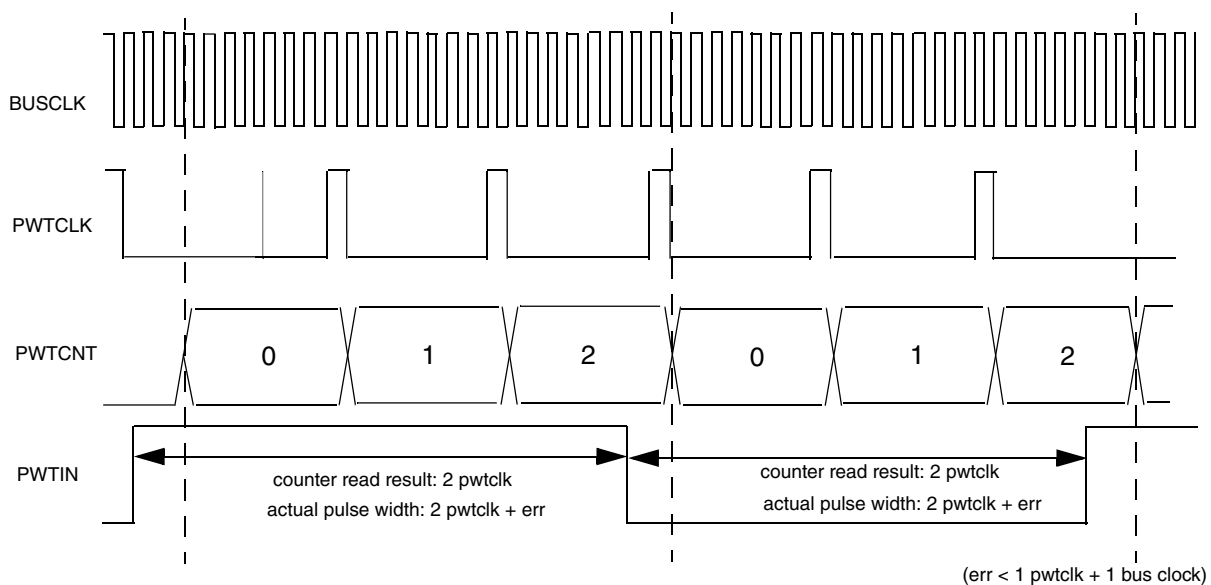


Figure 27-9. Example at PWTCLK is Bus Clock divided by 8

Chapter 28

Periodic Interrupt Timer (PIT)

28.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The PIT module is an array of timers that can be used to raise interrupts and triggers.

28.1.1 Block diagram

The following figure shows the block diagram of the PIT module.

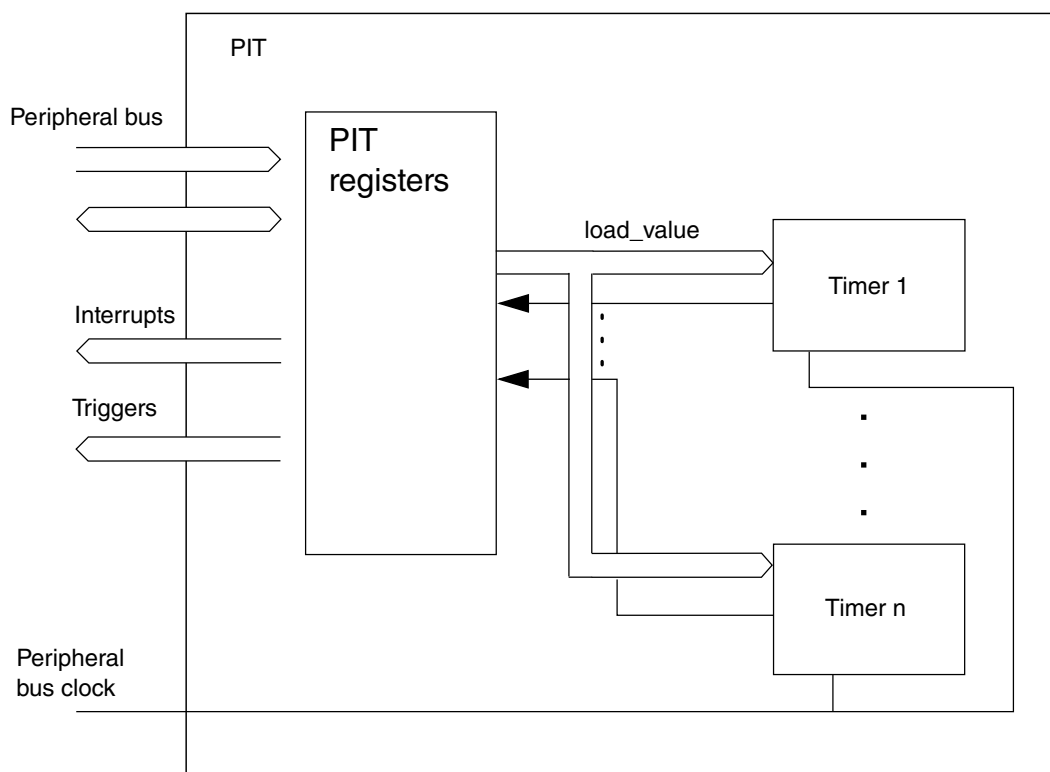


Figure 28-1. Block diagram of the PIT

NOTE

See the chip-specific PIT information for the number of PIT channels used in this MCU.

28.1.2 Features

The main features of this block are:

- Ability of timers to generate trigger pulses
- Ability of timers to generate interrupts
- Maskable interrupts
- Independent timeout periods for each timer

28.2 Signal description

The PIT module has no external pins.

28.3 Memory map/register description

This section provides a detailed description of all registers accessible in the PIT module.

- Reserved registers will read as 0, writes will have no effect.
- See the chip-specific PIT information for the number of PIT channels used in this MCU.

PIT memory map

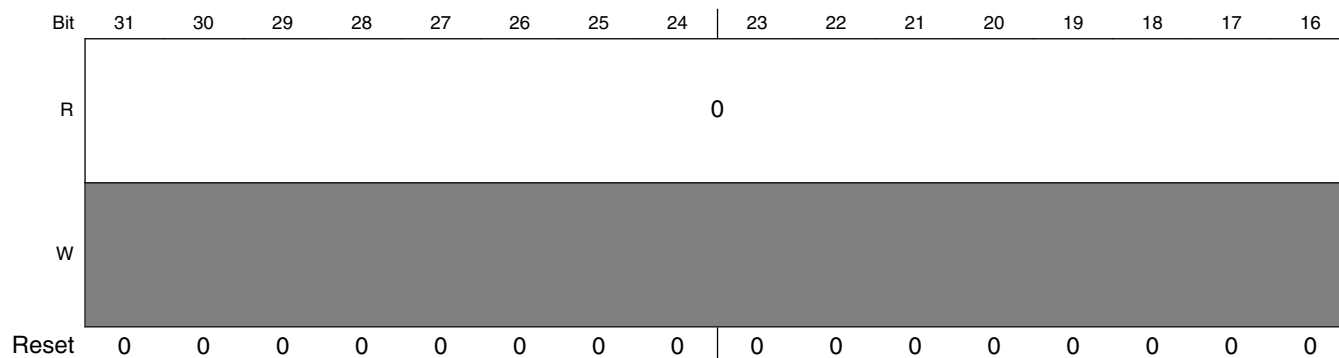
| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|----------------------------|
| 4003_7000 | PIT Module Control Register (PIT_MCR) | 32 | R/W | 0000_0006h | 28.3.1/505 |
| 4003_7100 | Timer Load Value Register (PIT_LDVAL0) | 32 | R/W | 0000_0000h | 28.3.2/506 |
| 4003_7104 | Current Timer Value Register (PIT_CVAL0) | 32 | R | 0000_0000h | 28.3.3/507 |
| 4003_7108 | Timer Control Register (PIT_TCTRL0) | 32 | R/W | 0000_0000h | 28.3.4/507 |
| 4003_710C | Timer Flag Register (PIT_TFLG0) | 32 | R/W | 0000_0000h | 28.3.5/508 |
| 4003_7110 | Timer Load Value Register (PIT_LDVAL1) | 32 | R/W | 0000_0000h | 28.3.2/506 |
| 4003_7114 | Current Timer Value Register (PIT_CVAL1) | 32 | R | 0000_0000h | 28.3.3/507 |
| 4003_7118 | Timer Control Register (PIT_TCTRL1) | 32 | R/W | 0000_0000h | 28.3.4/507 |
| 4003_711C | Timer Flag Register (PIT_TFLG1) | 32 | R/W | 0000_0000h | 28.3.5/508 |

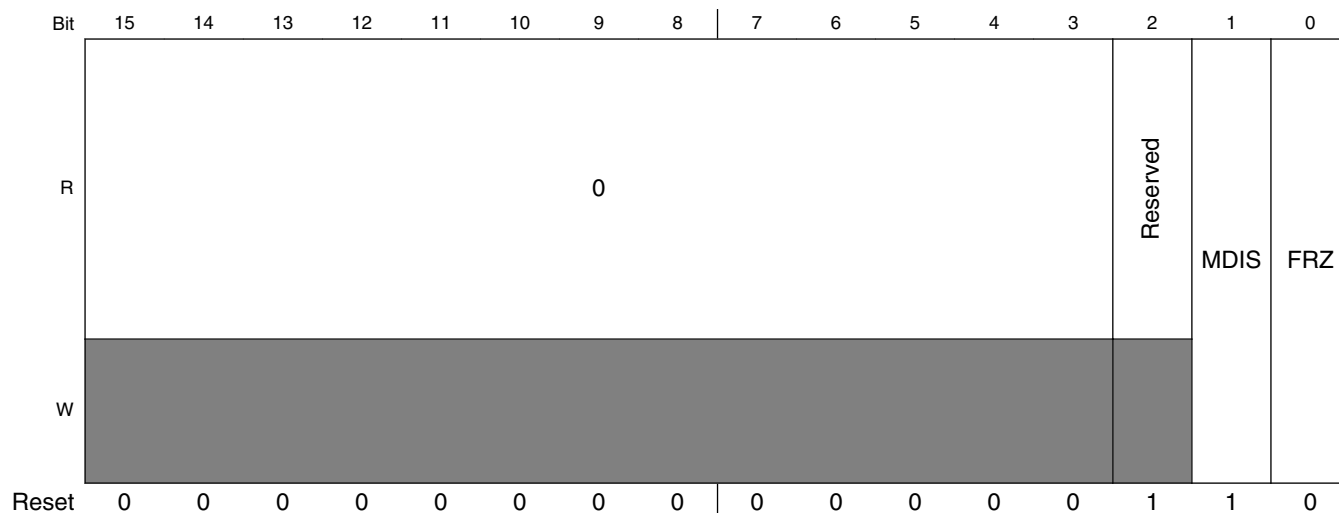
28.3.1 PIT Module Control Register (PIT_MCR)

This register enables or disables the PIT timer clocks and controls the timers when the PIT enters the Debug mode.

Access: User read/write

Address: 4003_7000h base + 0h offset = 4003_7000h





PIT_MCR field descriptions

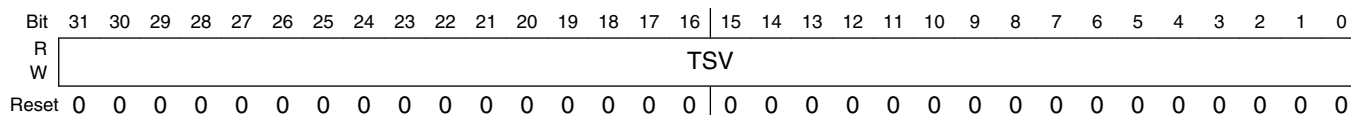
| Field | Description |
|------------------|---|
| 31–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 2 Reserved | This field is reserved. |
| 1 MDIS | Module Disable - (PIT section) Disables the standard timers. This field must be enabled before any other setup is done. 0 Clock for standard PIT timers is enabled. 1 Clock for standard PIT timers is disabled. |
| 0 FRZ | Freeze Allows the timers to be stopped when the device enters the Debug mode. 0 Timers continue to run in Debug mode. 1 Timers are stopped in Debug mode. |

28.3.2 Timer Load Value Register (PIT_LDVALn)

These registers select the timeout period for the timer interrupts.

Access: User read/write

Address: 4003_7000h base + 100h offset + (16d × i), where i=0d to 1d



PIT_LDVALn field descriptions

| Field | Description |
|-------|---|
| TSV | <p>Timer Start Value</p> <p>Sets the timer start value. The timer will count down until it reaches 0, then it will generate an interrupt and load this register value again. Writing a new value to this register will not restart the timer; instead the value will be loaded after the timer expires. To abort the current cycle and start a timer period with the new value, the timer must be disabled and enabled again.</p> |

28.3.3 Current Timer Value Register (PIT_CVALn)

These registers indicate the current timer position.

Access: User read only

Address: 4003_7000h base + 104h offset + (16d × i), where i=0d to 1d

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | TVL | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PIT_CVALn field descriptions

| Field | Description |
|-------|---|
| TVL | <p>Current Timer Value</p> <p>Represents the current timer value, if the timer is enabled.</p> <p>NOTE:</p> <ul style="list-style-type: none"> If the timer is disabled, do not use this field as its value is unreliable. The timer uses a downcounter. The timer values are frozen in Debug mode if MCR[FRZ] is set. |

28.3.4 Timer Control Register (PIT_TCTRLn)

These registers contain the control bits for each timer.

Access: User read/write

Address: 4003_7000h base + 108h offset + (16d × i), where i=0d to 1d

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PIT_TCTRLn field descriptions

| Field | Description |
|------------------|---|
| 31–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 2 CHN | Chain Mode When activated, Timer n-1 needs to expire before timer n can decrement by 1. Timer 0 cannot be chained. 0 Timer is not chained. 1 Timer is chained to previous timer. For example, for Channel 2, if this field is set, Timer 2 is chained to Timer 1. |
| 1 TIE | Timer Interrupt Enable When an interrupt is pending, or, TFLGn[TIF] is set, enabling the interrupt will immediately cause an interrupt event. To avoid this, the associated TFLGn[TIF] must be cleared first. 0 Interrupt requests from Timer n are disabled. 1 Interrupt will be requested whenever TIF is set. |
| 0 TEN | Timer Enable Enables or disables the timer. 0 Timer n is disabled. 1 Timer n is enabled. |

28.3.5 Timer Flag Register (PIT_TFLGn)

These registers hold the PIT interrupt flags.

Access: User read/write

Address: 4003_7000h base + 10Ch offset + (16d × i), where i=0d to 1d

| | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | TIF |
| W | | | | | | | | | | | | | | | | w1c |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

PIT_TFLGn field descriptions

| Field | Description |
|------------------|---|
| 31–1 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

Table continues on the next page...

PIT_TFLGn field descriptions (continued)

| Field | Description |
|----------|--|
| 0 TIF | <p>Timer Interrupt Flag</p> <p>Sets to 1 at the end of the timer period. Writing 1 to this flag clears it. Writing 0 has no effect. If enabled, or, when TCTRLn[TIE] = 1, TIF causes an interrupt request.</p> <p>0 Timeout has not yet occurred.</p> <p>1 Timeout has occurred.</p> |

28.4 Functional description

This section provides the functional description of the module.

28.4.1 General operation

This section gives detailed information on the internal operation of the module. Each timer can be used to generate trigger pulses and interrupts. Each interrupt is available on a separate interrupt line.

28.4.1.1 Timers

The timers generate triggers at periodic intervals, when enabled. The timers load the start values as specified in their LDVAL registers, count down to 0 and then load the respective start value again. Each time a timer reaches 0, it will generate a trigger pulse and set the interrupt flag.

All interrupts can be enabled or masked by setting TCTRLn[TIE]. A new interrupt can be generated only after the previous one is cleared.

If desired, the current counter value of the timer can be read via the CVAL registers.

The counter period can be restarted, by first disabling, and then enabling the timer with TCTRLn[TEN]. See the following figure.

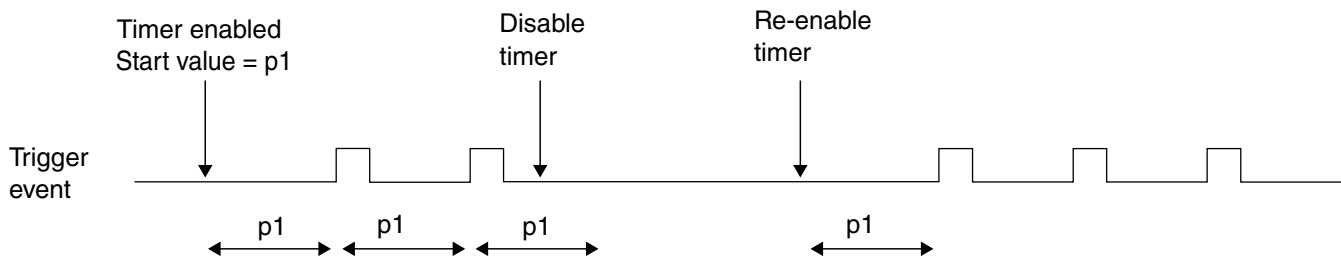


Figure 28-15. Stopping and starting a timer

The counter period of a running timer can be modified, by first disabling the timer, setting a new load value, and then enabling the timer again. See the following figure.

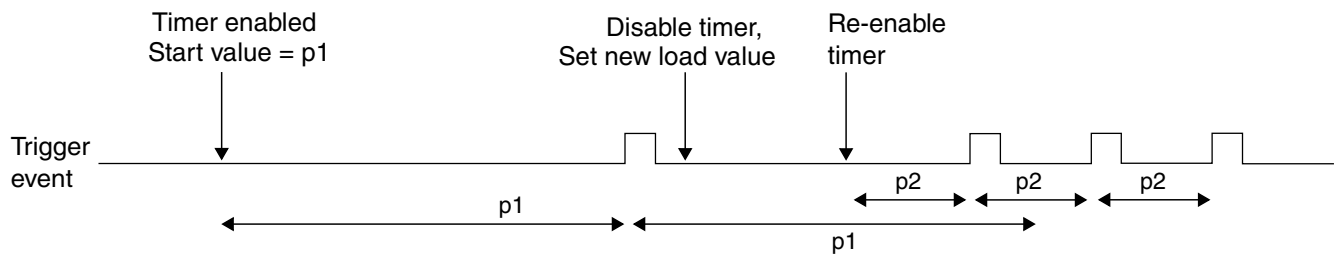


Figure 28-16. Modifying running timer period

It is also possible to change the counter period without restarting the timer by writing LDVAL with the new load value. This value will then be loaded after the next trigger event. See the following figure.

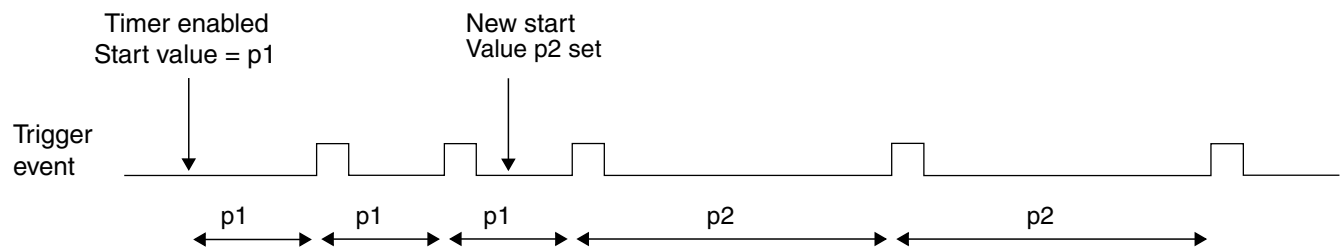


Figure 28-17. Dynamically setting a new load value

28.4.1.2 Debug mode

In Debug mode, the timers will be frozen based on MCR[FRZ]. This is intended to aid software development, allowing the developer to halt the processor, investigate the current state of the system, for example, the timer values, and then continue the operation.

28.4.2 Interrupts

All the timers support interrupt generation. See the MCU specification for related vector addresses and priorities.

Timer interrupts can be enabled by setting TCTRLn[TIE]. TFLGn[TIF] are set to 1 when a timeout occurs on the associated timer, and are cleared to 0 by writing a 1 to the corresponding TFLGn[TIF].

28.4.3 Chained timers

When a timer has chain mode enabled, it will only count after the previous timer has expired. So if timer n-1 has counted down to 0, counter n will decrement the value by one. This allows to chain some of the timers together to form a longer timer. The first timer (timer 0) cannot be chained to any other timer.

28.5 Initialization and application information

In the example configuration:

- The PIT clock has a frequency of 50 MHz.
- Timer 1 creates an interrupt every 5.12 ms.
- Timer 3 creates a trigger event every 30 ms.

The PIT module must be activated by writing a 0 to MCR[MDIS].

The 50 MHz clock frequency equates to a clock period of 20 ns. Timer 1 needs to trigger every $5.12 \text{ ms} / 20 \text{ ns} = 256,000$ cycles and Timer 3 every $30 \text{ ms} / 20 \text{ ns} = 1,500,000$ cycles. The value for the LDVAL register trigger is calculated as:

$\text{LDVAL trigger} = (\text{period} / \text{clock period}) - 1$

This means LDVAL1 and LDVAL3 must be written with 0x0003E7FF and 0x0016E35F respectively.

The interrupt for Timer 1 is enabled by setting TCTRL1[TIE]. The timer is started by writing 1 to TCTRL1[TEN].

Timer 3 shall be used only for triggering. Therefore, Timer 3 is started by writing a 1 to TCTRL3[TEN]. TCTRL3[TIE] stays at 0.

The following example code matches the described setup:

```
// turn on PIT
PIT_MCR = 0x00;

// Timer 1
PIT_LDVAL1 = 0x0003E7FF; // setup timer 1 for 256000 cycles
PIT_TCTRL1 = TIE; // enable Timer 1 interrupts
PIT_TCTRL1 |= TEN; // start Timer 1

// Timer 3
PIT_LDVAL3 = 0x0016E35F; // setup timer 3 for 1500000 cycles
PIT_TCTRL3 |= TEN; // start Timer 3
```

28.6 Example configuration for chained timers

In the example configuration:

- The PIT clock has a frequency of 100 MHz.
- Timers 1 and 2 are available.
- An interrupt shall be raised every 1 minute.

The PIT module needs to be activated by writing a 0 to MCR[MDIS].

The 100 MHz clock frequency equates to a clock period of 10 ns, so the PIT needs to count for 6000 million cycles, which is more than a single timer can do. So, Timer 1 is set up to trigger every 6 s (600 million cycles). Timer 2 is chained to Timer 1 and programmed to trigger 10 times.

The value for the LDVAL register trigger is calculated as number of cycles-1, so LDVAL1 receives the value 0x23C345FF and LDVAL2 receives the value 0x00000009.

The interrupt for Timer 2 is enabled by setting TCTRL2[TIE], the Chain mode is activated by setting TCTRL2[CHN], and the timer is started by writing a 1 to TCTRL2[TEN]. TCTRL1[TEN] needs to be set, and TCTRL1[CHN] and TCTRL1[TIE] are cleared.

The following example code matches the described setup:

```
// turn on PIT
PIT_MCR = 0x00;

// Timer 2
PIT_LDVAL2 = 0x00000009; // setup Timer 2 for 10 counts
PIT_TCTRL2 = TIE; // enable Timer 2 interrupt
PIT_TCTRL2 |= CHN; // chain Timer 2 to Timer 1
PIT_TCTRL2 |= TEN; // start Timer 2
```



```
// Timer 1  
PIT_LDVAL1 = 0x23C345FF; // setup Timer 1 for 600 000 000 cycles  
PIT_TCTRL1 = TEN; // start Timer 1
```


Chapter 29

Real-Time Counter (RTC)

29.1 Introduction

The real-time counter (RTC) consists of one 16-bit counter, one 16-bit comparator, several binary-based and decimal-based prescaler dividers, three clock sources, one programmable periodic interrupt, and one programmable external toggle pulse output. This module can be used for time-of-day, calendar or any task scheduling functions. It can also serve as a cyclic wake-up from low-power modes, Stop and Wait without the need of external components.

29.2 Features

Features of the RTC module include:

- 16-bit up-counter
 - 16-bit modulo match limit
 - Software controllable periodic interrupt on match
- Software selectable clock sources for input to prescaler with programmable 16 bit prescaler
 - OSC 32.768KHz nominal.
 - LPO (~1 kHz)
 - Bus clock
 - Internal reference clock (32 kHz)

29.2.1 Modes of operation

This section defines the RTC operation in Stop, Wait, and Background Debug modes.

29.2.1.1 Wait mode

The RTC continues to run in Wait mode if enabled before executing the WAIT instruction. Therefore, the RTC can be used to bring the MCU out of Wait mode if the real-time interrupt is enabled. For lowest possible current consumption, the RTC must be stopped by software if not needed as an interrupt source during Wait mode.

29.2.1.2 Stop modes

The RTC continues to run in Stop mode if the RTC is enabled before executing the STOP instruction. Therefore, the RTC can be used to bring the MCU out of stop modes with no external components, if the real-time interrupt is enabled.

29.2.2 Block diagram

The block diagram for the RTC module is shown in the following figure.

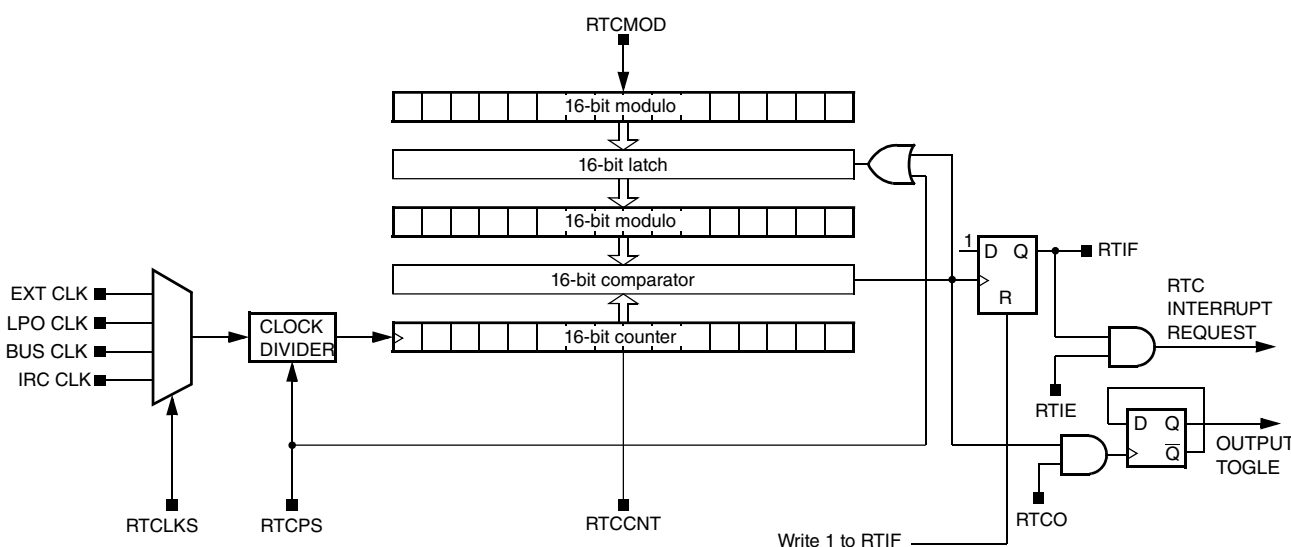


Figure 29-1. Real-time counter (RTC) block diagram

29.3 External signal description

RTCO is the output of RTC. After MCU reset, the RTC_SC[RTCO] is set to high. When the counter overflows, the output is toggled.

29.4 Register definition

The RTC includes a status and control register, a 16-bit counter register, and a 16-bit modulo register.

RTC memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|----------------------------|
| 4003_D000 | RTC Status and Control Register (RTC_SC) | 32 | R/W | 0000_0000h | 29.4.1/517 |
| 4003_D004 | RTC Modulo Register (RTC_MOD) | 32 | R/W | 0000_0000h | 29.4.2/519 |
| 4003_D008 | RTC Counter Register (RTC_CNT) | 32 | R | 0000_0000h | 29.4.3/519 |

29.4.1 RTC Status and Control Register (RTC_SC)

RTC_SC contains the real-time interrupt status flag (RTIF), and the toggle output enable bit (RTCO).

Address: 4003_D000h base + 0h offset = 4003_D000h

| | | | | | | | | | | | | | | | | |
|-------|--------|----|----|----|----|----|-------|----|----|------|------|----|------|----|----|----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| R | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | RTCLKS | | 0 | | | | RTCPs | | | RTIF | RTIE | 0 | RTCO | 0 | | |
| W | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

RTC_SC field descriptions

| Field | Description |
|-------------------|--|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 15–14 RTCLKS | Real-Time Clock Source Select This read/write field selects the clock source input to the RTC prescaler. Changing the clock source clears the prescaler and RTCCNT counters. Reset clears RTCLKS to 00. |

Table continues on the next page...

RTC_SC field descriptions (continued)

| Field | Description |
|-------------------|--|
| | 00 External clock source. 01 Real-time clock source is 1 kHz (LPOCLK). 10 Internal reference clock (ICSIRCLK). 11 Bus clock. |
| 13–11 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 10–8 RTCPs | Real-Time Clock Prescaler Select This read/write field selects binary-based or decimal-based divide-by values for the clock source. Changing the prescaler value clears the prescaler and RTCCNT counters. Reset clears RTCPs to 000. 000 Off 001 If RTCLKS = x0, it is 1; if RTCLKS = x1, it is 128. 010 If RTCLKS = x0, it is 2; if RTCLKS = x1, it is 256. 011 If RTCLKS = x0, it is 4; if RTCLKS = x1, it is 512. 100 If RTCLKS = x0, it is 8; if RTCLKS = x1, it is 1024. 101 If RTCLKS = x0, it is 16; if RTCLKS = x1, it is 2048. 110 If RTCLKS = x0, it is 32; if RTCLKS = x1, it is 100. 111 If RTCLKS = x0, it is 64; if RTCLKS = x1, it is 1000. |
| 7 RTIF | Real-Time Interrupt Flag This status bit indicates the RTC counter register reached the value in the RTC modulo register. Writing a logic 0 has no effect. Writing a logic 1 clears the bit and the real-time interrupt request. Reset clears RTIF to 0. 0 RTC counter has not reached the value in the RTC modulo register. 1 RTC counter has reached the value in the RTC modulo register. |
| 6 RTIE | Real-Time Interrupt Enable This read/write bit enables real-time interrupts. If RTIE is set, then an interrupt is generated when RTIF is set. Reset clears RTIE to 0. 0 Real-time interrupt requests are disabled. Use software polling. 1 Real-time interrupt requests are enabled. |
| 5 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 4 RTCO | Real-Time Counter Output The read/write bit enables real-time to toggle output on pinout. If this bit is set, the RTCO pinout will be toggled when RTC counter overflows. 0 Real-time counter output disabled. 1 Real-time counter output enabled. |
| Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

29.4.2 RTC Modulo Register (RTC_MOD)

RTC_MOD indicates the value of the 16-bit modulo value.

Address: 4003_D000h base + 4h offset = 4003_D004h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | 0 | | | | | | | | | | | | | | | | MOD | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

RTC_MOD field descriptions

| Field | Description |
|-------------------|---|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| MOD | RTC Modulo This read/write field contains the modulo value used to reset the count to 0x0000 upon a compare match and set SC[RTIF] status field. A value of 0x0000 sets SC[RTIF] on each rising-edge of the prescaler output. Reset sets the modulo to 0x0000. |

29.4.3 RTC Counter Register (RTC_CNT)

RTC_CNT indicates the read-only value of the current RTC count of the 16-bit counter.

Address: 4003_D000h base + 8h offset = 4003_D008h

| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| R | 0 | | | | | | | | | | | | | | | | CNT | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

RTC_CNT field descriptions

| Field | Description |
|-------------------|---|
| 31–16 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| CNT | RTC Count This read-only field contains the current value of the 16-bit counter, read CNT[7:0] first and, then CNT[15:8]. Writes have no effect to this register. Reset or writing different values to SC[RTCLKS] and SC[RTCPS] clear the count to 0x0000. |

29.5 Functional description

The RTC is composed of a main 16-bit up-counter with a 16-bit modulo register, a clock source selector, and a prescaler block with binary-based and decimal-based selectable values. The module also contains software selectable interrupt logic and toggle logic for pinout.

After any MCU reset, the counter is stopped and reset to 0x0000, the modulus register is set to 0x0000, and the prescaler is off. The external oscillator clock is selected as the default clock source. To start the prescaler, write any value other than 0 to the Prescaler Select field (RTC_SC[RTCPs]).

The clock sources are software selectable: the external oscillator (OSC), on-chip low power oscillator (LPO), 32-kHz internal reference clock, and bus clock. The RTC Clock Select field (RTC_SC[RTCLKS]) is used to select the desired clock source to the prescaler dividers. If a different value is written to RTC_SC[RTCLKS], the prescaler and CNT counters are reset to 0x00.

RTC_SC[RTCPs] and RTC_SC[RTCLKS] select the desired divide-by value. If a different value is written to RTC_SC[RTCPs], the prescaler and RTCCNT counters are reset to 0x00. The following table shows different prescaler period values.

Table 29-5. Prescaler period

| RTCPs | 32768Hz OSC clock source prescaler period (RTCLKS = 00) | LPO clock (1 kHz) source prescaler period (RTCLKS = 01) | Internal reference clock (32.768 kHz) source prescaler period (RTCLKS = 10) | Bus clock (8 MHz) source prescaler period (RTCLKS = 11) |
|-------|---|---|--|---|
| 000 | Off | Off | Off | Off |
| 001 | 30.5176 μ s | 128 ms | 30.5176 μ s | 16 μ s |
| 010 | 61.0351 μ s | 256 ms | 61.0351 μ s | 32 μ s |
| 011 | 122.0703 μ s | 512 ms | 122.0703 μ s | 64 μ s |
| 100 | 244.1406 μ s | 1024 ms | 244.1406 μ s | 128 μ s |
| 101 | 488.28125 μ s | 2048 ms | 488.28125 μ s | 256 μ s |
| 110 | 976.5625 μ s | 100 ms | 976.5625 μ s | 12.5 μ s |
| 111 | 1.9531 ms | 1 s | 1.9531 ms | 125 μ s |

The RTC Modulo register (RTC_MOD) allows the compare value to be set to any value from 0x0000 to 0xFFFF. When the counter is active, the counter increments at the selected rate until the count matches the modulo value. When these values match, the counter resets to 0x0000 and continues counting. The Real-Time Interrupt Flag

(RTC_SC[RTIF]) is set whenever a match occurs. The flag sets on the transition from the modulo value to 0x0000. The modulo value written to RTC_MOD is latched until the RTC counter overflows or RTC_SC[RTCPS] is selected nonzero.

The RTC allows for an interrupt to be generated whenever RTC_SC[RTIF] is set. To enable the real-time interrupt, set the Real-Time Interrupt Enable field (RTC_SC[RTIE]). RTC_SC[RTIF] is cleared by writing a 1 to RTC_SC[RTIF].

The RTC also allows an output to external pinout by toggling the level. RTC_SC[RTCO] must be set to enable toggling external pinout. The level depends on the previous state of the pinout when the counter overflows if this function is active.

29.5.1 RTC operation example

This section shows an example of the RTC operation as the counter reaches a matching value from the modulo register.

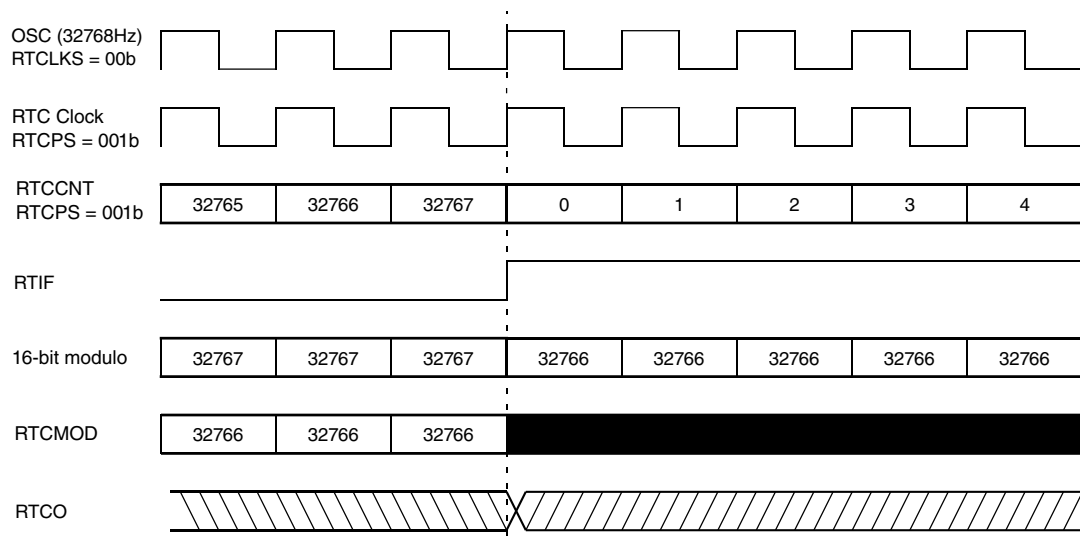


Figure 29-5. RTC counter overflow example

In the above example, the external clock source is selected. The prescaler is set to RTC_SC[RTCPS] = 001b or passthrough. The actual modulo value used by 16-bit comparator is 32767, when the modulo value in the RTC_MOD register is set to 32766. When the counter, RTC_CNT, reaches the modulo value of 32767, the counter overflows to 0x00 and continues counting. The modulo value is updated by fetching from RTC_MOD register. The real-time interrupt flag, RTC_SC[RTIF], sets when the counter value changes from 0x7FFF to 0x0000. The RTC_SC[RTCO] toggles as well when the RTC_SC[RTIF] is set.

29.6 Initialization/application information

This section provides example code to give some basic direction to a user on how to initialize and configure the RTC module. The example software is implemented in C language.

The example below shows how to implement time of day with the RTC using the OSC clock source to achieve the lowest possible power consumption.

Example: 29.6.1 Software calendar implementation in RTC ISR

```
/* Initialize the elapsed time counters */
Seconds = 0;
Minutes = 0;
Hours = 0;
Days=0;

/* Configure RTC to interrupt every 1 second from OSC (32.768KHz) clock source */
RTC_MOD = 511; // overflow every 32 times
RTC_SC = RTC_SC_RTCPS_MASK; // external 32768 clock selected with 1/64 predivider.
RTC_SC = RTC_SC_RTIF_MASK | RTC_SC_RTIE_MASK; // interrupt cleared and enabled

/*****
Function Name : RTC_ISR
Notes : Interrupt service routine for RTC module.
*****/
void RTC_ISR(void)
{
/* Clears the interrupt flag, RTIF, and interrupt request */
RTC_SC |= RTC_SC_RTIF_MASK;

/* RTC interrupts every 1 Second */
Seconds++;

/* 60 seconds in a minute */
if (Seconds > 59)
{
Minutes++;
Seconds = 0;
}

/* 60 minutes in an hour */
if (Minutes > 59)
{
Hours++;
Minutes = 0;
}

/* 24 hours in a day */
if (Hours > 23)
{
Days ++;
Hours = 0;
}
}
```

Chapter 30

Serial Peripheral Interface (SPI)

30.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The serial peripheral interface (SPI) module provides for full-duplex, synchronous, serial communication between the MCU and peripheral devices. These peripheral devices can include other microcontrollers, analog-to-digital converters, shift registers, sensors, and memories, among others.

The SPI runs at a baud rate up to the bus clock divided by two in master mode and up to the bus clock divided by four in slave mode. Software can poll the status flags, or SPI operation can be interrupt driven.

NOTE

For the actual maximum SPI baud rate, refer to the Chip Configuration details and to the device's Data Sheet.

The SPI also includes a hardware match feature for the receive data buffer.

30.1.1 Features

The SPI includes these distinctive features:

- Master mode or slave mode operation
- Full-duplex or single-wire bidirectional mode
- Programmable transmit bit rate

- Double-buffered transmit and receive data register
- Serial clock phase and polarity options
- Slave select output
- Mode fault error flag with CPU interrupt capability
- Control of SPI operation during wait mode
- Selectable MSB-first or LSB-first shifting
- Receive data buffer hardware match feature

30.1.2 Modes of operation

The SPI functions in the following three modes.

- Run mode

This is the basic mode of operation.

- Wait mode

SPI operation in Wait mode is a configurable low power mode, controlled by the SPISWAI bit located in the SPIx_C2 register. In Wait mode, if C2[SPISWAI] is clear, the SPI operates like in Run mode. If C2[SPISWAI] is set, the SPI goes into a power conservative state, with the SPI clock generation turned off. If the SPI is configured as a master, any transmission in progress stops, but is resumed after CPU enters Run mode. If the SPI is configured as a slave, reception and transmission of a byte continues, so that the slave stays synchronized to the master.

- Stop mode

To reduce power consumption, the SPI is inactive in stop modes where the peripheral bus clock is stopped but internal logic states are retained. If the SPI is configured as a master, any transmission in progress stops, but is resumed after the CPU enters run mode. If the SPI is configured as a slave, reception and transmission of a data continues, so that the slave stays synchronized to the master.

The SPI is completely disabled in Stop modes where the peripheral bus clock is stopped and internal logic states are not retained. When the CPU wakes from these Stop modes, all SPI register content is reset.

Detailed descriptions of operating modes appear in [Low-power mode options](#).

30.1.3 Block diagrams

This section includes block diagrams showing SPI system connections, the internal organization of the SPI module, and the SPI clock dividers that control the master mode bit rate.

30.1.3.1 SPI system block diagram

The following figure shows the SPI modules of two MCUs connected in a master-slave arrangement. The master device initiates all SPI data transfers. During a transfer, the master shifts data out (on the MOSI pin) to the slave while simultaneously shifting data in (on the MISO pin) from the slave. The transfer effectively exchanges the data that was in the SPI shift registers of the two SPI systems. The SPSCCK signal is a clock output from the master and an input to the slave. The slave device must be selected by a low level on the slave select input (SS pin). In this system, the master device has configured its SS pin as an optional slave select output.

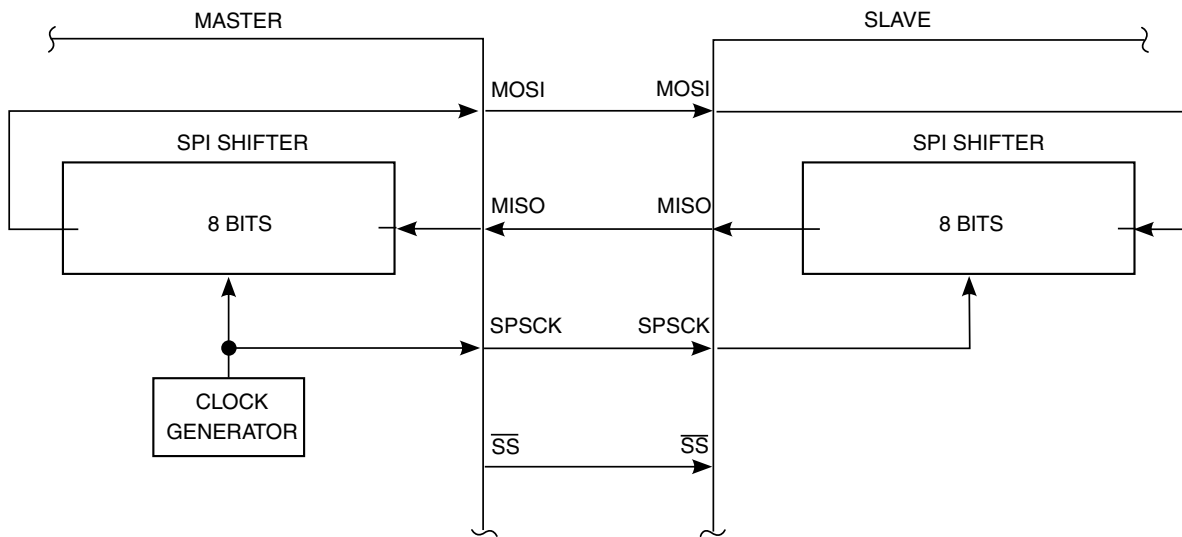


Figure 30-1. SPI system connections

30.1.3.2 SPI module block diagram

The following is a block diagram of the SPI module. The central element of the SPI is the SPI shift register. Data is written to the double-buffered transmitter (write to SPIx_D) and gets transferred to the SPI Shift Register at the start of a data transfer. After shifting in 8

bits of data, the data is transferred into the double-buffered receiver where it can be read from SPIx_D. Pin multiplexing logic controls connections between MCU pins and the SPI module.

When the SPI is configured as a master, the clock output is routed to the SPSCCK pin, the shifter output is routed to MOSI, and the shifter input is routed from the MISO pin.

When the SPI is configured as a slave, the SPSCCK pin is routed to the clock input of the SPI, the shifter output is routed to MISO, and the shifter input is routed from the MOSI pin.

In the external SPI system, simply connect all SPSCCK pins to each other, all MISO pins together, and all MOSI pins together. Peripheral devices often use slightly different names for these pins.

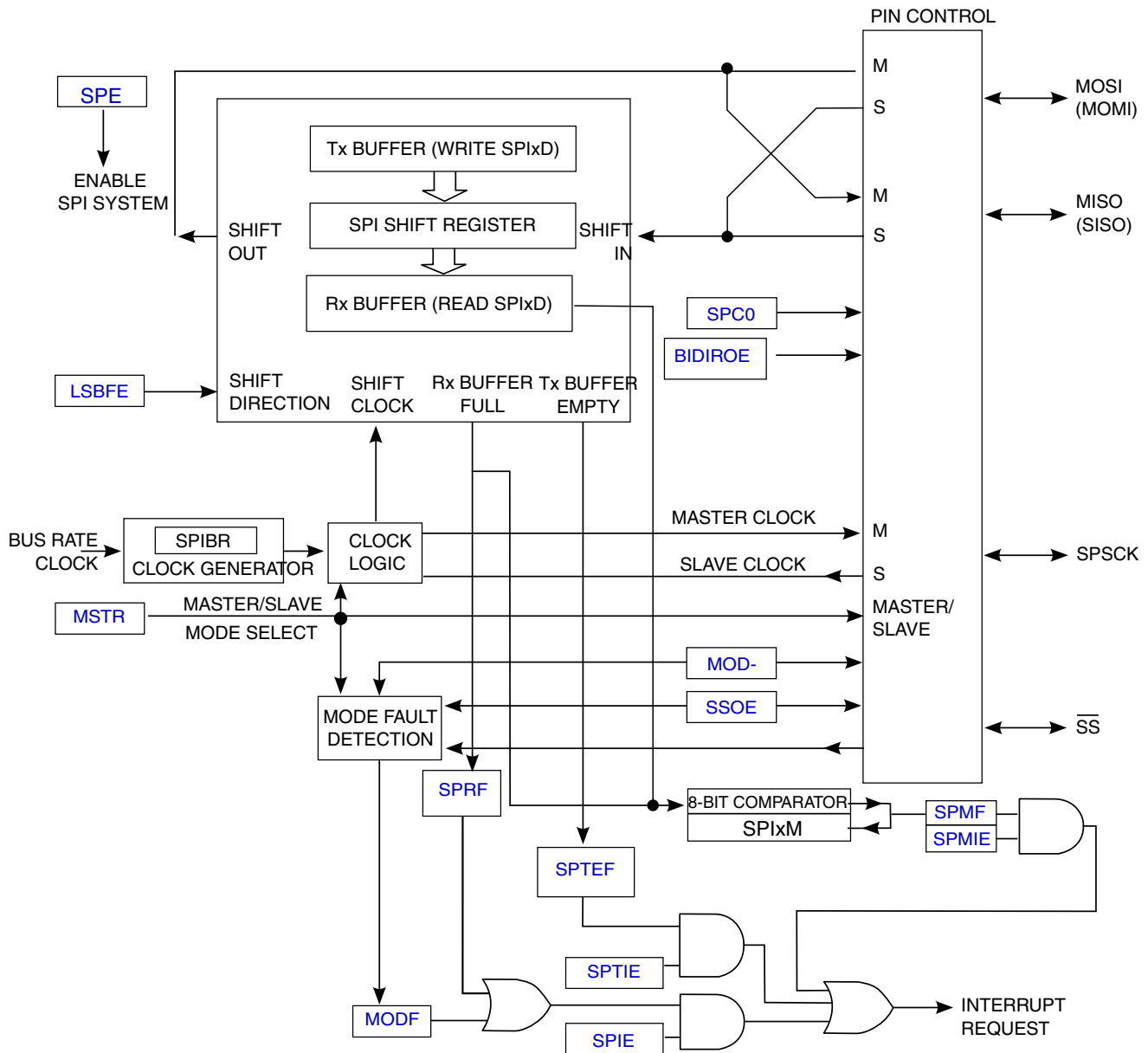


Figure 30-2. SPI module block diagram without FIFO

30.2 External signal description

The SPI optionally shares four port pins. The function of these pins depends on the settings of SPI control bits. When the SPI is disabled ($SPE = 0$), these four pins revert to other functions that are not controlled by the SPI (based on chip configuration).

30.2.1 SPCK — SPI Serial Clock

When the SPI is enabled as a slave, this pin is the serial clock input. When the SPI is enabled as a master, this pin is the serial clock output.

30.2.2 MOSI — Master Data Out, Slave Data In

When the SPI is enabled as a master and SPI pin control zero (SPC0) is 0 (not bidirectional mode), this pin is the serial data output. When the SPI is enabled as a slave and SPC0 is 0, this pin is the serial data input. If SPC0 is 1 to select single-wire bidirectional mode, and master mode is selected, this pin becomes the bidirectional data I/O pin (MOMI). Also, the bidirectional mode output enable bit determines whether the pin acts as an input (BIDIROE is 0) or an output (BIDIROE is 1). If SPC0 is 1 and slave mode is selected, this pin is not used by the SPI and reverts to other functions (based on chip configuration).

30.2.3 MISO — Master Data In, Slave Data Out

When the SPI is enabled as a master and SPI pin control zero (SPC0) is 0 (not bidirectional mode), this pin is the serial data input. When the SPI is enabled as a slave and SPC0 is 0, this pin is the serial data output. If SPC0 is 1 to select single-wire bidirectional mode, and slave mode is selected, this pin becomes the bidirectional data I/O pin (SISO), and the bidirectional mode output enable bit determines whether the pin acts as an input (BIDIROE is 0) or an output (BIDIROE is 1). If SPC0 is 1 and master mode is selected, this pin is not used by the SPI and reverts to other functions (based on chip configuration).

30.2.4 \overline{SS} — Slave Select

When the SPI is enabled as a slave, this pin is the low-true slave select input. When the SPI is enabled as a master and mode fault enable is off (MODFEN is 0), this pin is not used by the SPI and reverts to other functions (based on chip configuration). When the SPI is enabled as a master and MODFEN is 1, the slave select output enable bit determines whether this pin acts as the mode fault input (SSOE is 0) or as the slave select output (SSOE is 1).

30.3 Memory map/register definition

The SPI has 8-bit registers to select SPI options, to control baud rate, to report SPI status, to hold an SPI data match value, and for transmit/receive data.

SPI memory map

| Address offset (hex) | Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|----------------------|------------------------|----------------------------------|-----------------|--------|-------------|----------------------------|
| 0 | 4007_6000 | SPI Control Register 1 (SPI0_C1) | 8 | R/W | 04h | 30.3.1/529 |
| 1 | 4007_6001 | SPI Control Register 2 (SPI0_C2) | 8 | R/W | 00h | 30.3.2/531 |
| 2 | 4007_6002 | SPI Baud Rate Register (SPI0_BR) | 8 | R/W | 00h | 30.3.3/532 |
| 3 | 4007_6003 | SPI Status Register (SPI0_S) | 8 | R | 20h | 30.3.4/533 |
| 5 | 4007_6005 | SPI Data Register (SPI0_D) | 8 | R/W | 00h | 30.3.5/534 |
| 7 | 4007_6007 | SPI Match Register (SPI0_M) | 8 | R/W | 00h | 30.3.6/535 |
| 0 | 4007_7000 | SPI Control Register 1 (SPI1_C1) | 8 | R/W | 04h | 30.3.1/529 |
| 1 | 4007_7001 | SPI Control Register 2 (SPI1_C2) | 8 | R/W | 00h | 30.3.2/531 |
| 2 | 4007_7002 | SPI Baud Rate Register (SPI1_BR) | 8 | R/W | 00h | 30.3.3/532 |
| 3 | 4007_7003 | SPI Status Register (SPI1_S) | 8 | R | 20h | 30.3.4/533 |
| 5 | 4007_7005 | SPI Data Register (SPI1_D) | 8 | R/W | 00h | 30.3.5/534 |
| 7 | 4007_7007 | SPI Match Register (SPI1_M) | 8 | R/W | 00h | 30.3.6/535 |

30.3.1 SPI Control Register 1 (SPIx_C1)

This read/write register includes the SPI enable control, interrupt enables, and configuration options.

Address: 4007_6000h base + 0h offset = 4007_6000h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|-----|-------|------|------|------|------|-------|
| Read | SPIE | SPE | SPTIE | MSTR | CPOL | CPHA | SSOE | LSBFE |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

SPI0_C1 field descriptions

| Field | Description |
|-----------|---|
| 7 SPIE | SPI Interrupt Enable: for SPRF and MODF Enables the interrupt for SPI receive buffer full (SPRF) and mode fault (MODF) events. |

Table continues on the next page...

SPI0_C1 field descriptions (continued)

| Field | Description |
|------------|--|
| | 0 Interrupts from SPRF and MODF are inhibited—use polling 1 Request a hardware interrupt when SPRF or MODF is 1 |
| 6 SPE | SPI System Enable Enables the SPI system and dedicates the SPI port pins to SPI system functions. If SPE is cleared, the SPI is disabled and forced into an idle state, and all status bits in the S register are reset. 0 SPI system inactive 1 SPI system enabled |
| 5 SPTIE | SPI Transmit Interrupt Enable This is the interrupt enable bit for SPI transmit buffer empty (SPTEF). An interrupt occurs when the SPI transmit buffer is empty (SPTEF is set). 0 Interrupts from SPTEF inhibited (use polling) 1 When SPTEF is 1, hardware interrupt requested |
| 4 MSTR | Master/Slave Mode Select Selects master or slave mode operation. 0 SPI module configured as a slave SPI device 1 SPI module configured as a master SPI device |
| 3 CPOL | Clock Polarity Selects an inverted or non-inverted SPI clock. To transmit data between SPI modules, the SPI modules must have identical CPOL values. This bit effectively places an inverter in series with the clock signal either from a master SPI device or to a slave SPI device. Refer to the description of “SPI Clock Formats” for details. 0 Active-high SPI clock (idles low) 1 Active-low SPI clock (idles high) |
| 2 CPHA | Clock Phase Selects one of two clock formats for different kinds of synchronous serial peripheral devices. Refer to the description of “SPI Clock Formats” for details. 0 First edge on SPSCCK occurs at the middle of the first cycle of a data transfer. 1 First edge on SPSCCK occurs at the start of the first cycle of a data transfer. |
| 1 SSOE | Slave Select Output Enable This bit is used in combination with the Mode Fault Enable (MODFEN) field in the C2 register and the Master/Slave (MSTR) control bit to determine the function of the \overline{SS} pin. 0 When C2[MODFEN] is 0: In master mode, \overline{SS} pin function is general-purpose I/O (not SPI). In slave mode, \overline{SS} pin function is slave select input. When C2[MODFEN] is 1: In master mode, \overline{SS} pin function is \overline{SS} input for mode fault. In slave mode, \overline{SS} pin function is slave select input. 1 When C2[MODFEN] is 0: In master mode, \overline{SS} pin function is general-purpose I/O (not SPI). In slave mode, \overline{SS} pin function is slave select input. When C2[MODFEN] is 1: In master mode, \overline{SS} pin function is automatic \overline{SS} output. In slave mode: \overline{SS} pin function is slave select input. |

Table continues on the next page...

SPI0_C1 field descriptions (continued)

| Field | Description |
|------------|---|
| 0 LSBFE | <p>LSB First (shifter direction)</p> <p>This bit does not affect the position of the MSB and LSB in the data register. Reads and writes of the data register always have the MSB in bit 7.</p> <p>0 SPI serial data transfers start with the most significant bit. 1 SPI serial data transfers start with the least significant bit.</p> |

30.3.2 SPI Control Register 2 (SPIx_C2)

This read/write register is used to control optional features of the SPI system. Bit 6 is not implemented and always reads 0.

Address: 4007_6000h base + 1h offset = 4007_6001h

| | | | | | | | | |
|-------|-------|----------|----------|--------|---------|----------|---------|------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | SPMIE | Reserved | Reserved | MODFEN | BIDIROE | Reserved | SPISWAI | SPC0 |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SPI0_C2 field descriptions

| Field | Description |
|---------------|---|
| 7 SPMIE | <p>SPI Match Interrupt Enable</p> <p>This is the interrupt enable bit for the SPI receive data buffer hardware match (SPMF) function.</p> <p>0 Interrupts from SPMF inhibited (use polling) 1 When SPMF is 1, requests a hardware interrupt</p> |
| 6 Reserved | <p>This field is reserved. Do not write to this reserved bit.</p> |
| 5 Reserved | <p>This field is reserved. Do not write to this reserved bit.</p> |
| 4 MODFEN | <p>Master Mode-Fault Function Enable</p> <p>When the SPI is configured for slave mode, this bit has no meaning or effect. (The \overline{SS} pin is the slave select input.) In master mode, this bit determines how the \overline{SS} pin is used. For details, refer to the description of the SSOE bit in the C1 register.</p> <p>0 Mode fault function disabled, master \overline{SS} pin reverts to general-purpose I/O not controlled by SPI 1 Mode fault function enabled, master \overline{SS} pin acts as the mode fault input or the slave select output</p> |
| 3 BIDIROE | <p>Bidirectional Mode Output Enable</p> <p>When bidirectional mode is enabled because SPI pin control 0 (SPC0) is set to 1, BIDIROE determines whether the SPI data output driver is enabled to the single bidirectional SPI I/O pin. Depending on whether the SPI is configured as a master or a slave, it uses the MOSI (MOMI) or MISO (SISO) pin, respectively, as the single SPI data I/O pin. When SPC0 is 0, BIDIROE has no meaning or effect.</p> |

Table continues on the next page...

SPI0_C2 field descriptions (continued)

| Field | Description |
|---------------|--|
| | 0 Output driver disabled so SPI data I/O pin acts as an input 1 SPI I/O pin enabled as an output |
| 2 Reserved | This field is reserved. Do not write to this reserved bit. |
| 1 SPISWAI | SPI Stop in Wait Mode This bit is used for power conservation while the device is in Wait mode. 0 SPI clocks continue to operate in Wait mode. 1 SPI clocks stop when the MCU enters Wait mode. |
| 0 SPC0 | SPI Pin Control 0 Enables bidirectional pin configurations. 0 SPI uses separate pins for data input and data output (pin mode is normal). In master mode of operation: MISO is master in and MOSI is master out. In slave mode of operation: MISO is slave out and MOSI is slave in. 1 SPI configured for single-wire bidirectional operation (pin mode is bidirectional). In master mode of operation: MISO is not used by SPI; MOSI is master in when BIDIROE is 0 or master I/O when BIDIROE is 1. In slave mode of operation: MISO is slave in when BIDIROE is 0 or slave I/O when BIDIROE is 1; MOSI is not used by SPI. |

30.3.3 SPI Baud Rate Register (SPIx_BR)

Use this register to set the prescaler and bit rate divisor for an SPI master. This register may be read or written at any time.

Address: 4007_6000h base + 2h offset = 4007_6002h

| | | | | | | | | |
|-------|---|-----------|---|---|----------|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | SPPR[2:0] | | | SPR[3:0] | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SPI0_BR field descriptions

| Field | Description |
|------------------|---|
| 7 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 6–4 SPPR[2:0] | SPI Baud Rate Prescale Divisor This 3-bit field selects one of eight divisors for the SPI baud rate prescaler. The input to this prescaler is the bus rate clock (BUSCLK). The output of this prescaler drives the input of the SPI baud rate divider. Refer to the description of “SPI Baud Rate Generation” for details. |

Table continues on the next page...

SPI0_BR field descriptions (continued)

| Field | Description |
|----------|---|
| | 000 Baud rate prescaler divisor is 1. 001 Baud rate prescaler divisor is 2. 010 Baud rate prescaler divisor is 3. 011 Baud rate prescaler divisor is 4. 100 Baud rate prescaler divisor is 5. 101 Baud rate prescaler divisor is 6. 110 Baud rate prescaler divisor is 7. 111 Baud rate prescaler divisor is 8. |
| SPR[3:0] | SPI Baud Rate Divisor This 4-bit field selects one of nine divisors for the SPI baud rate divider. The input to this divider comes from the SPI baud rate prescaler. Refer to the description of “SPI Baud Rate Generation” for details. 0000 Baud rate divisor is 2. 0001 Baud rate divisor is 4. 0010 Baud rate divisor is 8. 0011 Baud rate divisor is 16. 0100 Baud rate divisor is 32. 0101 Baud rate divisor is 64. 0110 Baud rate divisor is 128. 0111 Baud rate divisor is 256. 1000 Baud rate divisor is 512. All others Reserved |

30.3.4 SPI Status Register (SPIx_S)

This register contains read-only status bits. Writes have no meaning or effect.

NOTE

Bits 3 through 0 are not implemented and always read 0.

Address: 4007_6000h base + 3h offset = 4007_6003h

| | | | | | | | | |
|-------|------|------|-------|------|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | SPRF | SPMF | SPTEF | MODF | 0 | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |

SPI0_S field descriptions

| Field | Description |
|-----------|--|
| 7 SPRF | SPI Read Buffer Full Flag SPRF is set at the completion of an SPI transfer to indicate that received data may be read from the SPI data (D) register. SPRF is cleared by reading SPRF while it is set and then reading the SPI data register. |

Table continues on the next page...

SPI0_S field descriptions (continued)

| Field | Description |
|------------|--|
| | 0 No data available in the receive data buffer 1 Data available in the receive data buffer |
| 6 SPMF | SPI Match Flag SPMF is set after SPRF is 1 when the value in the receive data buffer matches the value in the M register. To clear the flag, read SPMF when it is set and then write a 1 to it. 0 Value in the receive data buffer does not match the value in the M register 1 Value in the receive data buffer matches the value in the M register |
| 5 SPTEF | SPI Transmit Buffer Empty Flag This bit is set when the transmit data buffer is empty. SPTEF is cleared by reading the S register with SPTEF set and then writing a data value to the transmit buffer at D. The S register must be read with SPTEF set to 1 before writing data to the D register; otherwise, the D write is ignored. SPTEF is automatically set when all data from the transmit buffer transfers into the transmit shift register. For an idle SPI, data written to D is transferred to the shifter almost immediately so that SPTEF is set within two bus cycles, allowing a second set of data to be queued into the transmit buffer. After completion of the transfer of the data in the shift register, the queued data from the transmit buffer automatically moves to the shifter, and SPTEF is set to indicate that room exists for new data in the transmit buffer. If no new data is waiting in the transmit buffer, SPTEF simply remains set and no data moves from the buffer to the shifter. If a transfer does not stop, the last data that was transmitted is sent out again. 0 SPI transmit buffer not empty 1 SPI transmit buffer empty |
| 4 MODF | Master Mode Fault Flag MODF is set if the SPI is configured as a master and the slave select input goes low, indicating some other SPI device is also configured as a master. The SS pin acts as a mode fault error input only when C1[MSTR] is 1, C2[MODFEN] is 1, and C1[SSOE] is 0; otherwise, MODF will never be set. MODF is cleared by reading MODF while it is 1 and then writing to the SPI Control Register 1 (C1). 0 No mode fault error 1 Mode fault error detected |
| Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

30.3.5 SPI Data Register (SPIx_D)

This register is both the input and output register for SPI data. A write to the register writes to the transmit data buffer, allowing data to be queued and transmitted.

When the SPI is configured as a master, data queued in the transmit data buffer is transmitted immediately after the previous transmission has completed.

The SPTEF bit in the S register indicates when the transmit data buffer is ready to accept new data. The S register must be read when S[SPTEF] is set before writing to the SPI data register; otherwise, the write is ignored.

Data may be read from the SPI data register any time after S[SPRF] is set and before another transfer is finished. Failure to read the data out of the receive data buffer before a new transfer ends causes a receive overrun condition, and the data from the new transfer is lost. The new data is lost because the receive buffer still held the previous character and was not ready to accept the new data. There is no indication for a receive overrun condition, so the application system designer must ensure that previous data has been read from the receive buffer before a new transfer is initiated.

Address: 4007_6000h base + 5h offset = 4007_6005h

| | | | | | | | | |
|-------|-----------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | Bits[7:0] | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SPI0_D field descriptions

| Field | Description |
|-----------|-----------------|
| Bits[7:0] | Data (low byte) |

30.3.6 SPI Match Register (SPIx_M)

This register contains the hardware compare value. When the value received in the SPI receive data buffer equals this hardware compare value, the SPI Match Flag in the S register (S[SPMF]) sets.

Address: 4007_6000h base + 7h offset = 4007_6007h

| | | | | | | | | |
|-------|-----------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | Bits[7:0] | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

SPI0_M field descriptions

| Field | Description |
|-----------|-----------------------------------|
| Bits[7:0] | Hardware compare value (low byte) |

30.4 Functional description

This section provides the functional description of the module.

30.4.1 General

The SPI system is enabled by setting the SPI enable (SPE) bit in SPI Control Register 1. While C1[SPE] is set, the four associated SPI port pins are dedicated to the SPI function as:

- Slave select (SS)
- Serial clock (SPSCK)
- Master out/slave in (MOSI)
- Master in/slave out (MISO)

An SPI transfer is initiated in the master SPI device by reading the SPI status register (SPIx_S) when S[SPTEF] = 1 and then writing data to the transmit data buffer (write to SPIxD). When a transfer is complete, received data is moved into the receive data buffer. The SPIxD register acts as the SPI receive data buffer for reads and as the SPI transmit data buffer for writes.

The Clock Phase Control (CPHA) and Clock Polarity Control (CPOL) bits in the SPI Control Register 1 (SPIx_C1) select one of four possible clock formats to be used by the SPI system. The CPOL bit simply selects a non-inverted or inverted clock. C1[CPHA] is used to accommodate two fundamentally different protocols by sampling data on odd numbered SPSCK edges or on even numbered SPSCK edges.

The SPI can be configured to operate as a master or as a slave. When the MSTR bit in SPI Control Register 1 is set, master mode is selected; when C1[MSTR] is clear, slave mode is selected.

30.4.2 Master mode

The SPI operates in master mode when C1[MSTR] is set. Only a master SPI module can initiate transmissions. A transmission begins by reading the SPIx_S register while S[SPTEF] = 1 and writing to the master SPI data registers. If the shift register is empty, the byte immediately transfers to the shift register. The data begins shifting out on the MOSI pin under the control of the serial clock.

- SPSCK
 - The SPR3, SPR2, SPR1, and SPR0 baud rate selection bits in conjunction with the SPPR2, SPPR1, and SPPR0 baud rate preselection bits in the SPI Baud Rate register control the baud rate generator and determine the speed of the

transmission. The SPSCCK pin is the SPI clock output. Through the SPSCCK pin, the baud rate generator of the master controls the shift register of the slave peripheral.

- MOSI, MISO pin
 - In master mode, the function of the serial data output pin (MOSI) and the serial data input pin (MISO) is determined by the SPC0 and BIDIROE control bits.
- \overline{SS} pin
 - If C2[MODFEN] and C1[SSOE] are set, the SS pin is configured as slave select output. The SS output becomes low during each transmission and is high when the SPI is in idle state. If C2[MODFEN] is set and C1[SSOE] is cleared, the \overline{SS} pin is configured as input for detecting mode fault error. If the SS input becomes low this indicates a mode fault error where another master tries to drive the MOSI and SPSCCK lines. In this case, the SPI immediately switches to slave mode by clearing C1[MSTR] and also disables the slave output buffer MISO (or SISO in bidirectional mode). As a result, all outputs are disabled, and SPSCCK, MOSI and MISO are inputs. If a transmission is in progress when the mode fault occurs, the transmission is aborted and the SPI is forced into idle state. This mode fault error also sets the Mode Fault (MODF) flag in the SPI Status Register (SPIx_S). If the SPI Interrupt Enable bit (SPIE) is set when S[MODF] gets set, then an SPI interrupt sequence is also requested. When a write to the SPI Data Register in the master occurs, there is a half SPSCCK-cycle delay. After the delay, SPSCCK is started within the master. The rest of the transfer operation differs slightly, depending on the clock format specified by the SPI clock phase bit, CPHA, in SPI Control Register 1 (see [SPI clock formats](#)).

Note

A change of C1[CPOL], C1[CPHA], C1[SSOE], C1[LSBFE], C2[MODFEN], C2[SPC0], C2[BIDIROE] with C2[SPC0] set, SPPR2-SPPR0 and SPR3-SPR0 in master mode abort a transmission in progress and force the SPI into idle state. The remote slave cannot detect this, therefore the master has to ensure that the remote slave is set back to idle state.

30.4.3 Slave mode

The SPI operates in slave mode when the MSTR bit in SPI Control Register 1 is clear.

- SPSCCK

In slave mode, SPSCCK is the SPI clock input from the master.

- MISO, MOSI pin

In slave mode, the function of the serial data output pin (MISO) and serial data input pin (MOSI) is determined by the SPC0 bit and BIDIROE bit in SPI Control Register 2.

- SS pin

The SS pin is the slave select input. Before a data transmission occurs, the SS pin of the slave SPI must be low. SS must remain low until the transmission is complete. If SS goes high, the SPI is forced into an idle state.

The SS input also controls the serial data output pin. If SS is high (not selected), the serial data output pin is high impedance. If SS is low, the first bit in the SPI Data Register is driven out of the serial data output pin. Also, if the slave is not selected (SS is high), then the SPSCCK input is ignored and no internal shifting of the SPI shift register occurs.

Although the SPI is capable of duplex operation, some SPI peripherals are capable of only receiving SPI data in a slave mode. For these simpler devices, there is no serial data out pin.

Note

When peripherals with duplex capability are used, take care not to simultaneously enable two receivers whose serial outputs drive the same system slave's serial data output line.

As long as no more than one slave device drives the system slave's serial data output line, it is possible for several slaves to receive the same transmission from a master, although the master would not receive return information from all of the receiving slaves.

If the CPHA bit in SPI Control Register 1 is clear, odd numbered edges on the SPSCCK input cause the data at the serial data input pin to be latched. Even numbered edges cause the value previously latched from the serial data input pin to shift into the LSB or MSB of the SPI shift register, depending on the LSBFE bit.

If C1[CPHA] is set, even numbered edges on the SPSCCK input cause the data at the serial data input pin to be latched. Odd numbered edges cause the value previously latched from the serial data input pin to shift into the LSB or MSB of the SPI shift register, depending on C1[LSBFE].

When C1[CPHA] is set, the first edge is used to get the first data bit onto the serial data output pin. When C1[CPHA] is clear and the SS input is low (slave selected), the first bit of the SPI data is driven out of the serial data output pin. After the eighth shift, the transfer is considered complete and the received data is transferred into the SPI Data register. To indicate transfer is complete, the SPRF flag in the SPI Status Register is set.

Note

A change of the bits C2[BIDIROE] with C2[SPC0] set, C1[CPOL], C1[CPHA], C1[SSOE], C1[LSBFE], C2[MODFEN], and C2[SPC0] in slave mode will corrupt a transmission in progress and must be avoided.

30.4.4 SPI clock formats

To accommodate a wide variety of synchronous serial peripherals from different manufacturers, the SPI system has a Clock Polarity (CPOL) bit and a Clock Phase (CPHA) control bit in the Control Register 1 to select one of four clock formats for data transfers. C1[CPOL] selectively inserts an inverter in series with the clock. C1[CPHA] chooses between two different clock phase relationships between the clock and data.

The following figure shows the clock formats when CPHA = 1. At the top of the figure, the eight bit times are shown for reference with bit 1 starting at the first SPSCCK edge and bit 8 ending one-half SPSCCK cycle after the eighth SPSCCK edge. The MSB first and LSB first lines show the order of SPI data bits depending on the setting in LSBFE. Both variations of SPSCCK polarity are shown, but only one of these waveforms applies for a specific transfer, depending on the value in C1[CPOL]. The SAMPLE IN waveform applies to the MOSI input of a slave or the MISO input of a master. The MOSI waveform applies to the MOSI output pin from a master and the MISO waveform applies to the MISO output from a slave. The \overline{SS} OUT waveform applies to the slave select output from a master (provided C2[MODFEN] and C1[SSOE] = 1). The master \overline{SS} output goes to active low one-half SPSCCK cycle before the start of the transfer and goes back high at the end of the eighth bit time of the transfer. The \overline{SS} IN waveform applies to the slave select input of a slave.

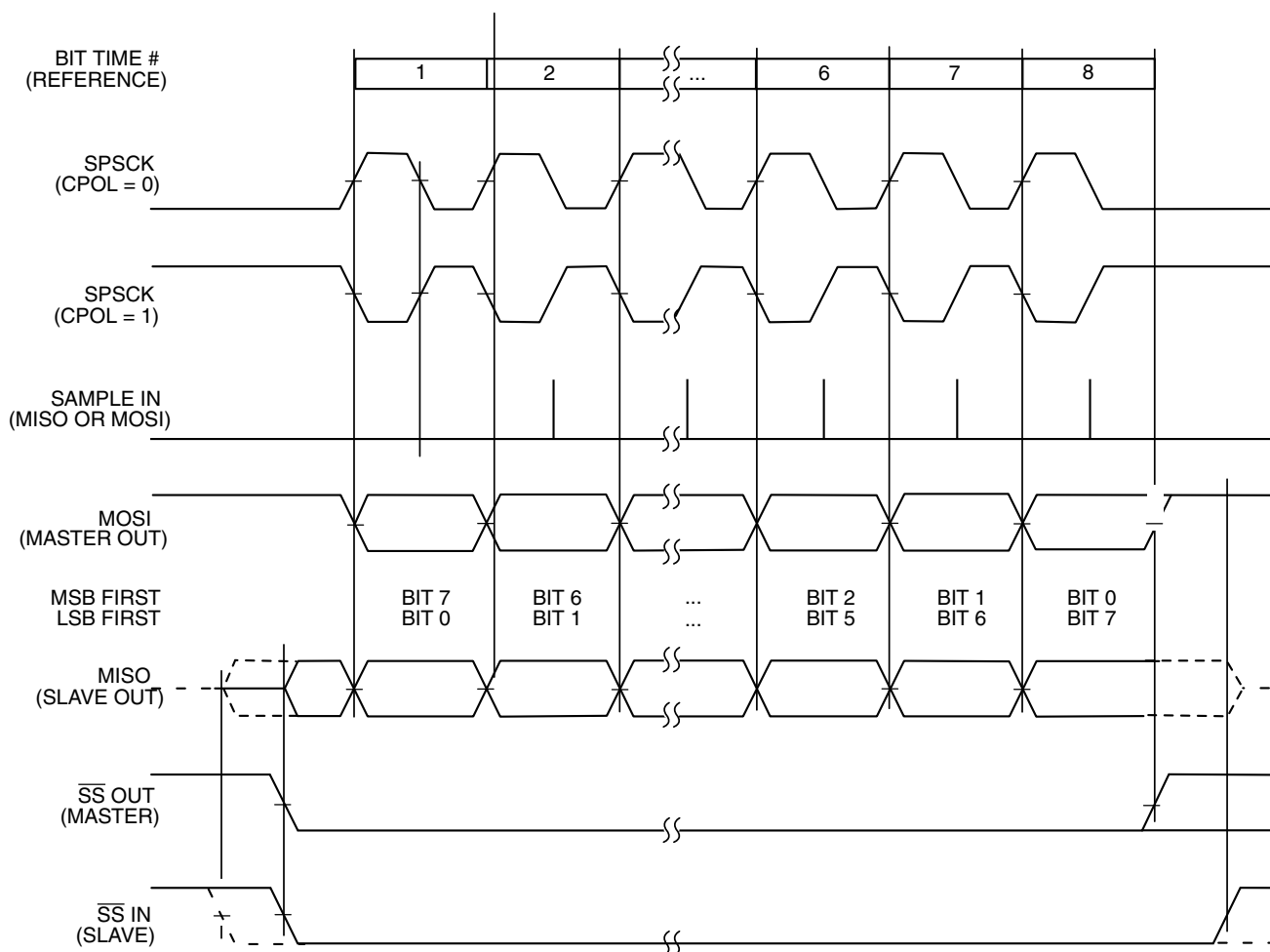


Figure 30-21. SPI clock formats (CPHA = 1)

When $C1[CPHA] = 1$, the slave begins to drive its MISO output when \overline{SS} goes to active low, but the data is not defined until the first SPSCCK edge. The first SPSCCK edge shifts the first bit of data from the shifter onto the MOSI output of the master and the MISO output of the slave. The next SPSCCK edge causes both the master and the slave to sample the data bit values on their MISO and MOSI inputs, respectively. At the third SPSCCK edge, the SPI shifter shifts one bit position which shifts in the bit value that was just sampled, and shifts the second data bit value out the other end of the shifter to the MOSI and MISO outputs of the master and slave, respectively.

When $C1[CPHA] = 1$, the slave's \overline{SS} input is not required to go to its inactive high level between transfers. In this clock format, a back-to-back transmission can occur, as follows:

1. A transmission is in progress.
2. A new data byte is written to the transmit buffer before the in-progress transmission is complete.
3. When the in-progress transmission is complete, the new, ready data byte is transmitted immediately.

Between these two successive transmissions, no pause is inserted; the $\overline{\text{SS}}$ pin remains low.

The following figure shows the clock formats when $\text{C1}[\text{CPHA}] = 0$. At the top of the figure, the eight bit times are shown for reference with bit 1 starting as the slave is selected ($\overline{\text{SS}}$ IN goes low), and bit 8 ends at the last SPSCCK edge. The MSB first and LSB first lines show the order of SPI data bits depending on the setting in LSBFE . Both variations of SPSCCK polarity are shown, but only one of these waveforms applies for a specific transfer, depending on the value in CPOL . The SAMPLE IN waveform applies to the MOSI input of a slave or the MISO input of a master. The MOSI waveform applies to the MOSI output pin from a master and the MISO waveform applies to the MISO output from a slave. The $\overline{\text{SS}}$ OUT waveform applies to the slave select output from a master (provided $\text{C2}[\text{MODFEN}]$ and $\text{C1}[\text{SSOE}] = 1$). The master $\overline{\text{SS}}$ output goes to active low at the start of the first bit time of the transfer and goes back high one-half SPSCCK cycle after the end of the eighth bit time of the transfer. The $\overline{\text{SS}}$ IN waveform applies to the slave select input of a slave.

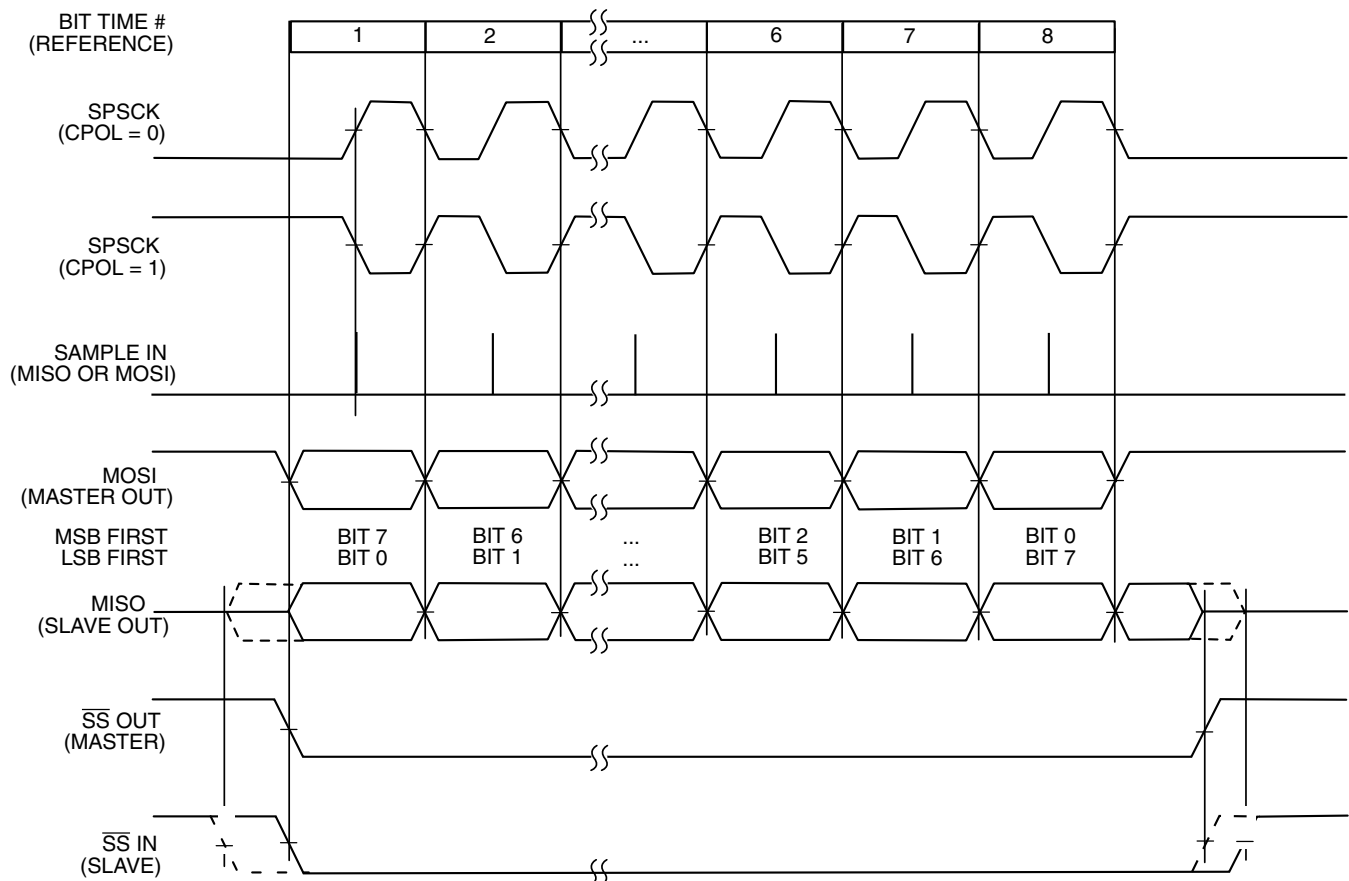


Figure 30-22. SPI clock formats (CPHA = 0)

When C1[CPHA] = 0, the slave begins to drive its MISO output with the first data bit value (MSB or LSB depending on LSBFE) when SS goes to active low. The first SPSCCK edge causes both the master and the slave to sample the data bit values on their MISO and MOSI inputs, respectively. At the second SPSCCK edge, the SPI shifter shifts one bit position which shifts in the bit value that was just sampled and shifts the second data bit value out the other end of the shifter to the MOSI and MISO outputs of the master and slave, respectively. When C1[CPHA] = 0, the slave's SS input must go to its inactive high level between transfers.

30.4.5 SPI baud rate generation

As shown in the following figure, the clock source for the SPI baud rate generator is the bus clock. The three prescale bits (SPPR2:SPPR1:SPPR0) choose a prescale divisor of 1, 2, 3, 4, 5, 6, 7, or 8. The three rate select bits (SPR3:SPR2:SPR1:SPR0) divide the output of the prescaler stage by 2, 4, 8, 16, 32, 64, 128, 256, or 512 to get the internal SPI master mode bit-rate clock.

The baud rate generator is activated only when the SPI is in the master mode and a serial transfer is taking place. In the other cases, the divider is disabled to decrease I_{DD} current.

The baud rate divisor equation is as follows (except those reserved combinations in the SPI Baud Rate Divisor table).

$$\text{BaudRateDivisor} = (\text{SPPR} + 1) \times 2^{(\text{SPR} + 1)}$$

The baud rate can be calculated with the following equation:

$$\text{BaudRate} = \text{BusClock} / \text{BaudRateDivisor}$$

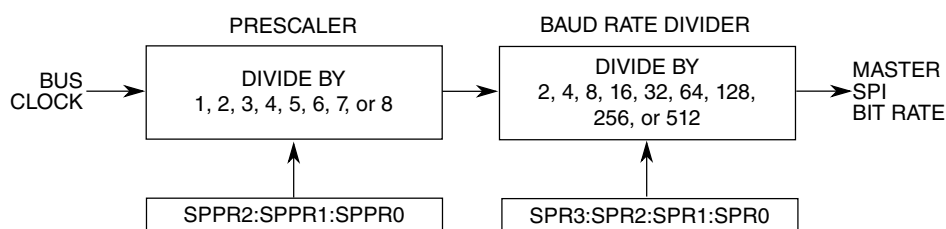


Figure 30-23. SPI baud rate generation

30.4.6 Special features

The following section describes the special features of SPI module.

30.4.6.1 \overline{SS} Output

The \overline{SS} output feature automatically drives the \overline{SS} pin low during transmission to select external devices and drives the \overline{SS} pin high during idle to deselect external devices. When the \overline{SS} output is selected, the \overline{SS} output pin is connected to the \overline{SS} input pin of the external device.

The \overline{SS} output is available only in master mode during normal SPI operation by asserting C1[SSOE] and C2[MODFEN] as shown in the description of C1[SSOE].

The mode fault feature is disabled while \overline{SS} output is enabled.

Note

Be careful when using the \overline{SS} output feature in a multimaster system because the mode fault feature is not available for detecting system errors between masters.

30.4.6.2 Bidirectional mode (MOMI or SISO)

The bidirectional mode is selected when the SPC0 bit is set in SPI Control Register 2 (see the following table). In this mode, the SPI uses only one serial data pin for the interface with one or more external devices. C1[MSTR] decides which pin to use. The MOSI pin becomes the serial data I/O (MOMI) pin for the master mode, and the MISO pin becomes serial data I/O (SISO) pin for the slave mode. The MISO pin in master mode and MOSI pin in slave mode are not used by the SPI.

Table 30-22. Normal Mode and Bidirectional Mode

| When SPE = 1 | Master Mode MSTR = 1 | Slave Mode MSTR = 0 |
|---------------------------------------|----------------------|---------------------|
| Normal Mode SPC0 = 0 | | |
| Bidirectional Mode SPC0 = 1 | | |

The direction of each serial I/O pin depends on C2[BIDIROE]. If the pin is configured as an output, serial data from the shift register is driven out on the pin. The same pin is also the serial input to the shift register.

The SPSCCK is an output for the master mode and an input for the slave mode.

\overline{SS} is the input or output for the master mode, and it is always the input for the slave mode.

The bidirectional mode does not affect SPSCCK and \overline{SS} functions.

Note

In bidirectional master mode, with the mode fault feature enabled, both data pins MISO and MOSI can be occupied by the SPI, though MOSI is normally used for transmissions in bidirectional mode and MISO is not used by the SPI. If a mode fault occurs, the SPI is automatically switched to slave mode. In this case, MISO becomes occupied by the SPI and MOSI is not used. Consider this scenario if the MISO pin is used for another purpose.

30.4.7 Error conditions

The SPI module has one error condition: the mode fault error.

30.4.7.1 Mode fault error

If the \overline{SS} input becomes low while the SPI is configured as a master, it indicates a system error where more than one master may be trying to drive the MOSI and SPSCCK lines simultaneously. This condition is not permitted in normal operation, and it sets the MODF bit in the SPI status register automatically provided that C2[MODFEN] is set.

In the special case where the SPI is in master mode and C2[MODFEN] is cleared, the \overline{SS} pin is not used by the SPI. In this special case, the mode fault error function is inhibited and MODF remains cleared. If the SPI system is configured as a slave, the \overline{SS} pin is a dedicated input pin. A mode fault error does not occur in slave mode.

If a mode fault error occurs, the SPI is switched to slave mode, with the exception that the slave output buffer is disabled. So the SPSCCK, MISO and MOSI pins are forced to be high impedance inputs to avoid any possibility of conflict with another output driver. A transmission in progress is aborted and the SPI is forced into idle state.

If the mode fault error occurs in the bidirectional mode for an SPI system configured in master mode, the output enable of MOMI (MOSI in bidirectional mode) is cleared if it was set. No mode fault error occurs in the bidirectional mode for the SPI system configured in slave mode.

The mode fault flag is cleared automatically by a read of the SPI Status Register (with MODF set) followed by a write to SPI Control Register 1. If the mode fault flag is cleared, the SPI becomes a normal master or slave again.

30.4.8 Low-power mode options

This section describes the low-power mode options.

30.4.8.1 SPI in Run mode

In Run mode, with the SPI system enable (SPE) bit in the SPI Control Register 1 clear, the SPI system is in a low-power, disabled state. SPI registers can still be accessed, but clocks to the core of this module are disabled.

30.4.8.2 SPI in Wait mode

SPI operation in Wait mode depends upon the state of the SPISWAI bit in SPI Control Register 2.

- If C2[SPISWAI] is clear, the SPI operates normally when the CPU is in Wait mode.
- If C2[SPISWAI] is set, SPI clock generation ceases and the SPI module enters a power conservation state when the CPU is in wait mode.
 - If C2[SPISWAI] is set and the SPI is configured for master, any transmission and reception in progress stops at Wait mode entry. The transmission and reception resumes when the SPI exits Wait mode.
 - If C2[SPISWAI] is set and the SPI is configured as a slave, any transmission and reception in progress continues if the SPSCCK continues to be driven from the master. This keeps the slave synchronized to the master and the SPSCCK.

If the master transmits data while the slave is in wait mode, the slave continues to send data consistent with the operation mode at the start of wait mode (that is, if the slave is currently sending its SPIx_D to the master, it continues to send the same byte. Otherwise, if the slave is currently sending the last data received byte from the master, it continues to send each previously received data from the master byte).

Note

Care must be taken when expecting data from a master while the slave is in a Wait mode or a Stop mode where the peripheral bus clock is stopped but internal logic states are retained. Even though the shift register continues to operate, the rest of the SPI is shut down (that is, an SPRF interrupt is not generated until an exit from Stop or Wait mode). Also, the data from the shift register is not copied into the SPIx_D registers until after the slave SPI has exited Wait or Stop mode. An SPRF flag and SPIx_D copy is only generated if Wait mode is entered or exited during a transmission. If the slave enters Wait mode in idle mode and exits Wait mode in idle mode, neither an SPRF nor a SPIx_D copy occurs.

30.4.8.3 SPI in Stop mode

Operation in a Stop mode where the peripheral bus clock is stopped but internal logic states are retained depends on the SPI system. The Stop mode does not depend on C2[SPISWAI]. Upon entry to this type of stop mode, the SPI module clock is disabled (held high or low).

- If the SPI is in master mode and exchanging data when the CPU enters the Stop mode, the transmission is frozen until the CPU exits stop mode. After the exit from stop mode, data to and from the external SPI is exchanged correctly.
- In slave mode, the SPI remains synchronized with the master.

The SPI is completely disabled in a stop mode where the peripheral bus clock is stopped and internal logic states are not retained. After an exit from this type of stop mode, all registers are reset to their default values, and the SPI module must be reinitialized.

30.4.9 Reset

The reset values of registers and signals are described in the Memory Map and Register Descriptions content, which details the registers and their bitfields.

- If a data transmission occurs in slave mode after a reset without a write to SPIx_D, the transmission consists of "garbage" or the data last received from the master before the reset.
- Reading from SPIx_D after reset always returns zeros.

30.4.10 Interrupts

The SPI originates interrupt requests only when the SPI is enabled (the SPE bit in the SPIx_C1 register is set). The following is a description of how the SPI makes a request and how the MCU should acknowledge that request. The interrupt vector offset and interrupt priority are chip dependent.

Four flag bits, three interrupt mask bits, and one interrupt vector are associated with the SPI system. The SPI interrupt enable mask (SPIE) enables interrupts from the SPI receiver full flag (SPRF) and mode fault flag (MODF). The SPI transmit interrupt enable mask (SPTIE) enables interrupts from the SPI transmit buffer empty flag (SPTEF). The SPI match interrupt enable mask bit (SPIMIE) enables interrupts from the SPI match flag (SPMF). When one of the flag bits is set, and the associated interrupt mask bit is set, a hardware interrupt request is sent to the CPU. If the interrupt mask bits are cleared, software can poll the associated flag bits instead of using interrupts. The SPI interrupt service routine (ISR) should check the flag bits to determine which event caused the interrupt. The service routine should also clear the flag bit(s) before returning from the ISR (usually near the beginning of the ISR).

30.4.10.1 MODF

MODF occurs when the master detects an error on the \overline{SS} pin. The master SPI must be configured for the MODF feature (see the description of the C1[SSOE] bit). Once MODF is set, the current transfer is aborted and the master (MSTR) bit in the SPIx_C1 register resets to 0.

The MODF interrupt is reflected in the status register's MODF flag. Clearing the flag also clears the interrupt. This interrupt stays active while the MODF flag is set. MODF has an automatic clearing process that is described in the SPI Status Register.

30.4.10.2 SPRF

SPRF occurs when new data has been received and copied to the SPI receive data buffer.

After SPRF is set, it does not clear until it is serviced. SPRF has an automatic clearing process that is described in the SPI Status Register details. If the SPRF is not serviced before the end of the next transfer (that is, SPRF remains active throughout another transfer), the subsequent transfers are ignored and no new data is copied into the Data register.

30.4.10.3 SPTEF

SPTEF occurs when the SPI transmit buffer is ready to accept new data.

After SPTEF is set, it does not clear until it is serviced. SPTEF has an automatic clearing process that is described in the SPI Status Register details.

30.4.10.4 SPMF

SPMF occurs when the data in the receive data buffer is equal to the data in the SPI Match Register.

30.4.10.5 Asynchronous interrupt in low-power modes

When the CPU is in Wait mode or Stop mode and the SPI module receives a transmission, the SPI module can generate an asynchronous interrupt to wake the CPU from the low power mode. The module generates the asynchronous interrupt only when all of the following conditions apply:

1. C1[SPIE] is set to 1.
2. The CPU is in Wait mode—in which case C2[SPISWAI] must be 1—or in Stop mode where the peripheral bus clock is stopped but internal logic states are retained.
3. The SPI module is in slave mode.
4. The received transmission ends.

After the interrupt wakes the CPU and the peripheral bus clock is active again, the SPI module copies the received data from the shifter into the Data register and generates flags signals. During the wakeup phase, a continuous transmission from a master would destroy the first received data.

30.5 Initialization/application information

This section discusses an example of how to initialize and use the SPI.

30.5.1 Initialization sequence

Before the SPI module can be used for communication, an initialization procedure must be carried out, as follows:

1. Update the Control Register 1 (SPIx_C1) to enable the SPI and to control interrupt enables. This register also sets the SPI as master or slave, determines clock phase and polarity, and configures the main SPI options.
2. Update the Control Register 2 (SPIx_C2) to enable additional SPI functions such as the SPI match interrupt feature, the master mode-fault function, and bidirectional mode output as well as to control and other optional features.
3. Update the Baud Rate Register (SPIx_BR) to set the prescaler and bit rate divisor for an SPI master.
4. Update the Hardware Match Register (SPIx_M) with the value to be compared to the receive data register for triggering an interrupt if hardware match interrupts are enabled.
5. In the master, read SPIx_S while S[SPTEF] = 1, and then write to the transmit data register (SPIx_D) to begin transfer.

30.5.2 Pseudo-Code Example

In this example, the SPI module is set up for master mode with only hardware match interrupts enabled. The SPI runs at a maximum baud rate of bus clock divided by 2. Clock phase and polarity are set for an active-high SPI clock where the first edge on SPSCCK occurs at the start of the first cycle of a data transfer.

| SPIx_C1=0x54(%01010100) | | | | |
|-------------------------|-------|---|---|--|
| Bit 7 | SPIE | = | 0 | Disables receive and mode fault interrupts |
| Bit 6 | SPE | = | 1 | Enables the SPI system |
| Bit 5 | SPTIE | = | 0 | Disables SPI transmit interrupts |
| Bit 4 | MSTR | = | 1 | Sets the SPI module as a master SPI device |
| Bit 3 | CPOL | = | 0 | Configures SPI clock as active-high |
| Bit 2 | CPHA | = | 1 | First edge on SPSCCK at start of first data transfer cycle |
| Bit 1 | SSOE | = | 0 | Determines SS pin function when mode fault enabled |
| Bit 0 | LSBFE | = | 0 | SPI serial data transfers start with most significant bit |

| SPIx_C2 = 0x80(%10000000) | | | | |
|---------------------------|---------|---|---|--------------------------------------|
| Bit 7 | SPMIE | = | 1 | SPI hardware match interrupt enabled |
| Bit 6 | | = | 0 | Unimplemented |
| Bit 5 | | = | 0 | Reserved |
| Bit 4 | MODFEN | = | 0 | Disables mode fault function |
| Bit 3 | BIDIROE | = | 0 | SPI data I/O pin acts as input |

Table continues on the next page...

Initialization/application information

| SPIx_C2 = 0x80(%10000000) | | | | |
|---------------------------|---------|---|---|--|
| Bit 2 | | = | 0 | Reserved |
| Bit 1 | SPISWAI | = | 0 | SPI clocks operate in wait mode |
| Bit 0 | SPC0 | = | 0 | uses separate pins for data input and output |

| SPIx_BR = 0x00(%00000000) | | | | |
|---------------------------|--|---|------|-----------------------------|
| Bit 7 | | = | 0 | Reserved |
| Bit 6:4 | | = | 000 | Sets prescale divisor to 1 |
| Bit 3:0 | | = | 0000 | Sets baud rate divisor to 2 |

| SPIx_S = 0x00(%00000000) | | | | |
|--------------------------|-------|---|---|--|
| Bit 7 | SPRF | = | 0 | Flag is set when receive data buffer is full |
| Bit 6 | SPMF | = | 0 | Flag is set when SPIx_M = receive data buffer |
| Bit 5 | SPTEF | = | 0 | Flag is set when transmit data buffer is empty |
| Bit 4 | MODF | = | 0 | Mode fault flag for master mode |
| Bit 3:0 | | = | 0 | Reserved |

| SPIx_M = 0xXX | |
|--|--|
| Holds bits 0–7 of the hardware match buffer. | |

| SPIx_D = 0xxx | |
|---|--|
| Holds bits 0–7 of the data to be transmitted by the transmit buffer and received by the receive buffer. | |

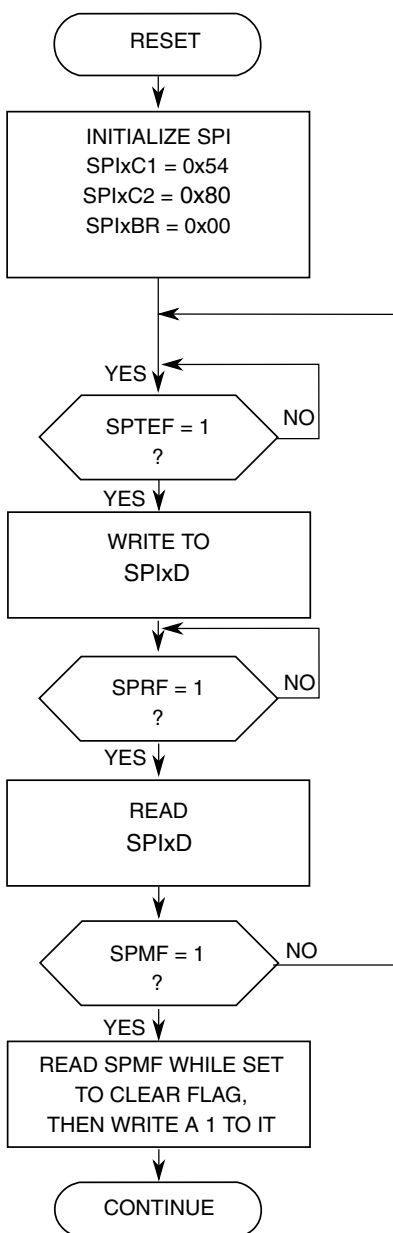


Figure 30-24. Initialization Flowchart Example for SPI Master Device

Chapter 31

Inter-Integrated Circuit (I2C)

31.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The inter-integrated circuit (I²C, I2C, or IIC) module provides a method of communication between a number of devices.

The interface is designed to operate up to 100 kbit/s with maximum bus loading and timing. The I2C device is capable of operating at higher baud rates, up to a maximum of clock/20, with reduced bus loading. The maximum communication length and the number of devices that can be connected are limited by a maximum bus capacitance of 400 pF. The I2C module also complies with the *System Management Bus (SMBus) Specification, version 2*.

31.1.1 Features

The I2C module has the following features:

- Compatible with *The I²C-Bus Specification*
- Multimaster operation
- Software programmable for one of 64 different serial clock frequencies
- Software-selectable acknowledge bit
- Interrupt-driven byte-by-byte data transfer
- Arbitration-lost interrupt with automatic mode switching from master to slave
- Calling address identification interrupt
- START and STOP signal generation and detection
- Repeated START signal generation and detection
- Acknowledge bit generation and detection

- Bus busy detection
- General call recognition
- 10-bit address extension
- Support for *System Management Bus (SMBus) Specification, version 2*
- Programmable input glitch filter
- Low power mode wakeup on slave address match
- Range slave address support

31.1.2 Modes of operation

The I2C module's operation in various low power modes is as follows:

- Run mode: This is the basic mode of operation. To conserve power in this mode, disable the module.
- Wait mode: The module continues to operate when the core is in Wait mode and can provide a wakeup interrupt.
- Stop mode: The module is inactive in Stop mode for reduced power consumption, except that address matching is enabled in Stop mode. The STOP instruction does not affect the I2C module's register states.

31.1.3 Block diagram

The following figure is a functional block diagram of the I2C module.

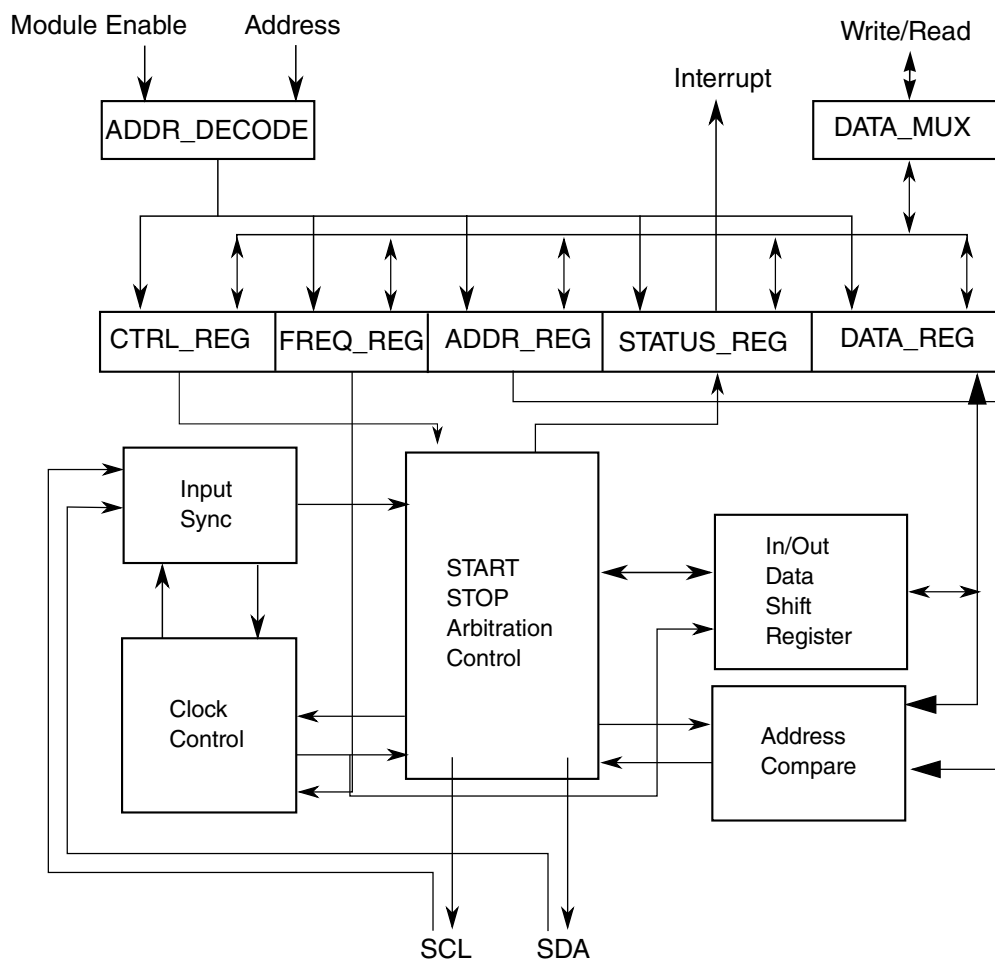


Figure 31-1. I2C Functional block diagram

31.2 I²C signal descriptions

The signal properties of I²C are shown in the table found here.

Table 31-1. I²C signal descriptions

| Signal | Description | I/O |
|--------|---|-----|
| SCL | Bidirectional serial clock line of the I ² C system. | I/O |
| SDA | Bidirectional serial data line of the I ² C system. | I/O |

31.3 Memory map/register definition

This section describes in detail all I2C registers accessible to the end user.

I2C memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|-----------------------------|
| 4006_6000 | I2C Address Register 1 (I2C0_A1) | 8 | R/W | 00h | 31.3.1/557 |
| 4006_6001 | I2C Frequency Divider register (I2C0_F) | 8 | R/W | 00h | 31.3.2/557 |
| 4006_6002 | I2C Control Register 1 (I2C0_C1) | 8 | R/W | 00h | 31.3.3/558 |
| 4006_6003 | I2C Status register (I2C0_S) | 8 | R/W | 80h | 31.3.4/560 |
| 4006_6004 | I2C Data I/O register (I2C0_D) | 8 | R/W | 00h | 31.3.5/561 |
| 4006_6005 | I2C Control Register 2 (I2C0_C2) | 8 | R/W | 00h | 31.3.6/562 |
| 4006_6006 | I2C Programmable Input Glitch Filter Register (I2C0_FLT) | 8 | R/W | 00h | 31.3.7/563 |
| 4006_6007 | I2C Range Address register (I2C0_RA) | 8 | R/W | 00h | 31.3.8/564 |
| 4006_6008 | I2C SMBus Control and Status register (I2C0_SMB) | 8 | R/W | 00h | 31.3.9/565 |
| 4006_6009 | I2C Address Register 2 (I2C0_A2) | 8 | R/W | C2h | 31.3.10/567 |
| 4006_600A | I2C SCL Low Timeout Register High (I2C0_SLTH) | 8 | R/W | 00h | 31.3.11/567 |
| 4006_600B | I2C SCL Low Timeout Register Low (I2C0_SLTL) | 8 | R/W | 00h | 31.3.12/567 |
| 4006_7000 | I2C Address Register 1 (I2C1_A1) | 8 | R/W | 00h | 31.3.1/557 |
| 4006_7001 | I2C Frequency Divider register (I2C1_F) | 8 | R/W | 00h | 31.3.2/557 |
| 4006_7002 | I2C Control Register 1 (I2C1_C1) | 8 | R/W | 00h | 31.3.3/558 |
| 4006_7003 | I2C Status register (I2C1_S) | 8 | R/W | 80h | 31.3.4/560 |
| 4006_7004 | I2C Data I/O register (I2C1_D) | 8 | R/W | 00h | 31.3.5/561 |
| 4006_7005 | I2C Control Register 2 (I2C1_C2) | 8 | R/W | 00h | 31.3.6/562 |
| 4006_7006 | I2C Programmable Input Glitch Filter Register (I2C1_FLT) | 8 | R/W | 00h | 31.3.7/563 |
| 4006_7007 | I2C Range Address register (I2C1_RA) | 8 | R/W | 00h | 31.3.8/564 |
| 4006_7008 | I2C SMBus Control and Status register (I2C1_SMB) | 8 | R/W | 00h | 31.3.9/565 |
| 4006_7009 | I2C Address Register 2 (I2C1_A2) | 8 | R/W | C2h | 31.3.10/567 |
| 4006_700A | I2C SCL Low Timeout Register High (I2C1_SLTH) | 8 | R/W | 00h | 31.3.11/567 |
| 4006_700B | I2C SCL Low Timeout Register Low (I2C1_SLTL) | 8 | R/W | 00h | 31.3.12/567 |

31.3.1 I2C Address Register 1 (I2Cx_A1)

This register contains the slave address to be used by the I2C module.

Address: Base address + 0h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---------|---|---|---|---|---|---|---|
| Read | AD[7:1] | | | | | | | 0 |
| Write | | | | | | | | 0 |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_A1 field descriptions

| Field | Description |
|----------------|---|
| 7–1 AD[7:1] | Address Contains the primary slave address used by the I2C module when it is addressed as a slave. This field is used in the 7-bit address scheme and the lower seven bits in the 10-bit address scheme. |
| 0 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

31.3.2 I2C Frequency Divider register (I2Cx_F)

Address: Base address + 1h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|---|-----|---|---|---|---|---|
| Read | MULT | | ICR | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_F field descriptions

| Field | Description |
|-------------|---|
| 7–6 MULT | Multiplier Factor Defines the multiplier factor (mul). This factor is used along with the SCL divider to generate the I2C baud rate. 00 mul = 1 01 mul = 2 10 mul = 4 11 Reserved |
| ICR | ClockRate Prescales the I2C module clock for bit rate selection. This field and the MULT field determine the I2C baud rate, the SDA hold time, the SCL start hold time, and the SCL stop hold time. For a list of values corresponding to each ICR setting, see I2C divider and hold values . The SCL divider multiplied by multiplier factor (mul) determines the I2C baud rate. $\text{I2C baud rate} = \text{I2C module clock speed (Hz)} / (\text{mul} \times \text{SCL divider})$ |

Table continues on the next page...

I2Cx_F field descriptions (continued)

| Field | Description | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|---|-------|-----------|-----------------|--|--|-----|-----------|----------|----|-----|-------|-------|-------|----|-----|-------|-------|-------|----|-----|-------|-------|-------|----|-----|-------|-------|-------|----|-----|-------|-------|-------|
| | <p>The SDA hold time is the delay from the falling edge of SCL (I2C clock) to the changing of SDA (I2C data).</p> <p>$\text{SDA hold time} = \text{I2C module clock period (s)} \times \text{mul} \times \text{SDA hold value}$</p> <p>The SCL start hold time is the delay from the falling edge of SDA (I2C data) while SCL is high (start condition) to the falling edge of SCL (I2C clock).</p> <p>$\text{SCL start hold time} = \text{I2C module clock period (s)} \times \text{mul} \times \text{SCL start hold value}$</p> <p>The SCL stop hold time is the delay from the rising edge of SCL (I2C clock) to the rising edge of SDA (I2C data) while SCL is high (stop condition).</p> <p>$\text{SCL stop hold time} = \text{I2C module clock period (s)} \times \text{mul} \times \text{SCL stop hold value}$</p> <p>For example, if the I2C module clock speed is 8 MHz, the following table shows the possible hold time values with different ICR and MULT selections to achieve an I²C baud rate of 100 kbit/s.</p> <table><tr><th rowspan="2">MULT</th><th rowspan="2">ICR</th><th colspan="3">Hold times (μs)</th></tr><tr><th>SDA</th><th>SCL Start</th><th>SCL Stop</th></tr><tr><td>2h</td><td>00h</td><td>3.500</td><td>3.000</td><td>5.500</td></tr><tr><td>1h</td><td>07h</td><td>2.500</td><td>4.000</td><td>5.250</td></tr><tr><td>1h</td><td>0Bh</td><td>2.250</td><td>4.000</td><td>5.250</td></tr><tr><td>0h</td><td>14h</td><td>2.125</td><td>4.250</td><td>5.125</td></tr><tr><td>0h</td><td>18h</td><td>1.125</td><td>4.750</td><td>5.125</td></tr></table> | MULT | ICR | Hold times (μs) | | | SDA | SCL Start | SCL Stop | 2h | 00h | 3.500 | 3.000 | 5.500 | 1h | 07h | 2.500 | 4.000 | 5.250 | 1h | 0Bh | 2.250 | 4.000 | 5.250 | 0h | 14h | 2.125 | 4.250 | 5.125 | 0h | 18h | 1.125 | 4.750 | 5.125 |
| MULT | ICR | | | Hold times (μs) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | SDA | SCL Start | SCL Stop | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2h | 00h | 3.500 | 3.000 | 5.500 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1h | 07h | 2.500 | 4.000 | 5.250 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1h | 0Bh | 2.250 | 4.000 | 5.250 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0h | 14h | 2.125 | 4.250 | 5.125 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0h | 18h | 1.125 | 4.750 | 5.125 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

31.3.3 I2C Control Register 1 (I2Cx_C1)

Address: Base address + 2h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|-----|----|------|------|------|---|
| Read | IICEN | IICIE | MST | TX | TXAK | 0 | WUEN | 0 |
| Write | | | | | | RSTA | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_C1 field descriptions

| Field | Description |
|------------|--|
| 7 IICEN | <p>I2C Enable</p> <p>Enables I2C module operation.</p> <p>0 Disabled 1 Enabled</p> |
| 6 IICIE | <p>I2C Interrupt Enable</p> <p>Enables I2C interrupt requests.</p> |

Table continues on the next page...

I2Cx_C1 field descriptions (continued)

| Field | Description |
|---------------|--|
| | 0 Disabled 1 Enabled |
| 5 MST | Master Mode Select When MST is changed from 0 to 1, a START signal is generated on the bus and master mode is selected. When this bit changes from 1 to 0, a STOP signal is generated and the mode of operation changes from master to slave. 0 Slave mode 1 Master mode |
| 4 TX | Transmit Mode Select Selects the direction of master and slave transfers. In master mode this bit must be set according to the type of transfer required. Therefore, for address cycles, this bit is always set. When addressed as a slave this bit must be set by software according to the SRW bit in the status register. 0 Receive 1 Transmit |
| 3 TXAK | Transmit Acknowledge Enable Specifies the value driven onto the SDA during data acknowledge cycles for both master and slave receivers. The value of SMB[FAK] affects NACK/ACK generation. NOTE: SCL is held low until TXAK is written. 0 An acknowledge signal is sent to the bus on the following receiving byte (if FACK is cleared) or the current receiving byte (if FACK is set). 1 No acknowledge signal is sent to the bus on the following receiving data byte (if FACK is cleared) or the current receiving data byte (if FACK is set). |
| 2 RSTA | Repeat START Writing 1 to this bit generates a repeated START condition provided it is the current master. This bit will always be read as 0. Attempting a repeat at the wrong time results in loss of arbitration. |
| 1 WUEN | Wakeup Enable The I2C module can wake the MCU from low power mode with no peripheral bus running when slave address matching occurs. 0 Normal operation. No interrupt generated when address matching in low power mode. 1 Enables the wakeup function in low power mode. |
| 0 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

31.3.4 I2C Status register (I2Cx_S)

Address: Base address + 3h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----|------|------|------|-----|-----|-------|------|
| Read | TCF | IAAS | BUSY | ARBL | RAM | SRW | IICIF | RXAK |
| Write | | | | w1c | | | w1c | |
| Reset | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_S field descriptions

| Field | Description |
|-----------|---|
| 7 TCF | <p>Transfer Complete Flag</p> <p>Acknowledges a byte transfer; TCF is set on the completion of a byte transfer. This bit is valid only during or immediately following a transfer to or from the I2C module. TCF is cleared by reading the I2C data register in receive mode or by writing to the I2C data register in transmit mode.</p> <p>0 Transfer in progress 1 Transfer complete</p> |
| 6 IAAS | <p>Addressed As A Slave</p> <p>This bit is set by one of the following conditions:</p> <ul style="list-style-type: none"> The calling address matches the programmed primary slave address in the A1 register, or matches the range address in the RA register (which must be set to a nonzero value and under the condition I2C_C2[RMEN] = 1). C2[GCAEN] is set and a general call is received. SMB[SIICAEN] is set and the calling address matches the second programmed slave address. ALERTEN is set and an SMBus alert response address is received RMEN is set and an address is received that is within the range between the values of the A1 and RA registers. <p>IAAS sets before the ACK bit. The CPU must check the SRW bit and set TX/RX accordingly. Writing the C1 register with any value clears this bit.</p> <p>0 Not addressed 1 Addressed as a slave</p> |
| 5 BUSY | <p>Bus Busy</p> <p>Indicates the status of the bus regardless of slave or master mode. This bit is set when a START signal is detected and cleared when a STOP signal is detected.</p> <p>0 Bus is idle 1 Bus is busy</p> |
| 4 ARBL | <p>Arbitration Lost</p> <p>This bit is set by hardware when the arbitration procedure is lost. The ARBL bit must be cleared by software, by writing 1 to it.</p> <p>0 Standard bus operation. 1 Loss of arbitration.</p> |
| 3 RAM | <p>Range Address Match</p> |

Table continues on the next page...

I2Cx_S field descriptions (continued)

| Field | Description |
|------------|--|
| | <p>This bit is set to 1 by any of the following conditions, if I2C_C2[RMEN] = 1:</p> <ul style="list-style-type: none"> Any nonzero calling address is received that matches the address in the RA register. The calling address is within the range of values of the A1 and RA registers. <p>Writing the C1 register with any value clears this bit to 0.</p> <p>0 Not addressed 1 Addressed as a slave</p> |
| 2 SRW | <p>Slave Read/Write</p> <p>When addressed as a slave, SRW indicates the value of the R/W command bit of the calling address sent to the master.</p> <p>0 Slave receive, master writing to slave 1 Slave transmit, master reading from slave</p> |
| 1 IICIF | <p>Interrupt Flag</p> <p>This bit sets when an interrupt is pending. This bit must be cleared by software by writing 1 to it, such as in the interrupt routine. One of the following events can set this bit:</p> <ul style="list-style-type: none"> One byte transfer, including ACK/NACK bit, completes if FACK is 0. An ACK or NACK is sent on the bus by writing 0 or 1 to TXAK after this bit is set in receive mode. One byte transfer, excluding ACK/NACK bit, completes if FACK is 1. Match of slave address to calling address including primary slave address, range slave address, alert response address, second slave address, or general call address. Arbitration lost In SMBus mode, any timeouts except SCL and SDA high timeouts I2C bus stop or start detection if the SSIE bit in the Input Glitch Filter register is 1 <p>NOTE: To clear the I2C bus stop or start detection interrupt: In the interrupt service routine, first clear the STOPF or STARTF bit in the Input Glitch Filter register by writing 1 to it, and then clear the IICIF bit. If this sequence is reversed, the IICIF bit is asserted again.</p> <p>0 No interrupt pending 1 Interrupt pending</p> |
| 0 RXAK | <p>Receive Acknowledge</p> <p>0 Acknowledge signal was received after the completion of one byte of data transmission on the bus 1 No acknowledge signal detected</p> |

31.3.5 I2C Data I/O register (I2Cx_D)

Address: Base address + 4h offset

| | | | | | | | | |
|-------|------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | DATA | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_D field descriptions

| Field | Description |
|-------|---|
| DATA | <p>Data</p> <p>In master transmit mode, when data is written to this register, a data transfer is initiated. The most significant bit is sent first. In master receive mode, reading this register initiates receiving of the next byte of data.</p> <p>NOTE: When making the transition out of master receive mode, switch the I2C mode before reading the Data register to prevent an inadvertent initiation of a master receive data transfer.</p> <p>In slave mode, the same functions are available after an address match occurs.</p> <p>The C1[TX] bit must correctly reflect the desired direction of transfer in master and slave modes for the transmission to begin. For example, if the I2C module is configured for master transmit but a master receive is desired, reading the Data register does not initiate the receive.</p> <p>Reading the Data register returns the last byte received while the I2C module is configured in master receive or slave receive mode. The Data register does not reflect every byte that is transmitted on the I2C bus, and neither can software verify that a byte has been written to the Data register correctly by reading it back.</p> <p>In master transmit mode, the first byte of data written to the Data register following assertion of MST (start bit) or assertion of RSTA (repeated start bit) is used for the address transfer and must consist of the calling address (in bits 7-1) concatenated with the required R/W bit (in position bit 0).</p> |

31.3.6 I2C Control Register 2 (I2Cx_C2)

Address: Base address + 5h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|---|------|------|----------|---|---|
| Read | GCAEN | ADEXT | 0 | SBRC | RMEN | AD[10:8] | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_C2 field descriptions

| Field | Description |
|---------------|---|
| 7 GCAEN | <p>General Call Address Enable</p> <p>Enables general call address.</p> <p>0 Disabled 1 Enabled</p> |
| 6 ADEXT | <p>Address Extension</p> <p>Controls the number of bits used for the slave address.</p> <p>0 7-bit address scheme 1 10-bit address scheme</p> |
| 5 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 4 SBRC | Slave Baud Rate Control |

Table continues on the next page...

I2Cx_C2 field descriptions (continued)

| Field | Description |
|-----------|---|
| | <p>Enables independent slave mode baud rate at maximum frequency, which forces clock stretching on SCL in very fast I2C modes. To a slave, an example of a "very fast" mode is when the master transfers at 40 kbit/s but the slave can capture the master's data at only 10 kbit/s.</p> <p>0 The slave baud rate follows the master baud rate and clock stretching may occur 1 Slave baud rate is independent of the master baud rate</p> |
| 3 RMEN | <p>Range Address Matching Enable</p> <p>This bit controls the slave address matching for addresses between the values of the A1 and RA registers. When this bit is set, a slave address matching occurs for any address greater than the value of the A1 register and less than or equal to the value of the RA register.</p> <p>0 Range mode disabled. No address matching occurs for an address within the range of values of the A1 and RA registers. 1 Range mode enabled. Address matching occurs when a slave receives an address within the range of values of the A1 and RA registers.</p> |
| AD[10:8] | <p>Slave Address</p> <p>Contains the upper three bits of the slave address in the 10-bit address scheme. This field is valid only while the ADEXT bit is set.</p> |

31.3.7 I2C Programmable Input Glitch Filter Register (I2Cx_FLT)

Address: Base address + 6h offset

| | | | | | | | | |
|-------|------|-------|------|--------|-----|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | SHEN | STOPF | SSIE | STARTF | FLT | | | |
| Write | | w1c | | w1c | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_FLT field descriptions

| Field | Description |
|-----------|--|
| 7 SHEN | <p>Stop Hold Enable</p> <p>Set this bit to hold off entry to stop mode when any data transmission or reception is occurring. The following scenario explains the holdoff functionality:</p> <ol style="list-style-type: none"> 1. The I2C module is configured for a basic transfer, and the SHEN bit is set to 1. 2. A transfer begins. 3. The MCU signals the I2C module to enter stop mode. 4. The byte currently being transferred, including both address and data, completes its transfer. 5. The I2C slave or master acknowledges that the in-transfer byte completed its transfer and acknowledges the request to enter stop mode. 6. After receiving the I2C module's acknowledgment of the request to enter stop mode, the MCU determines whether to shut off the I2C module's clock. <p>If the SHEN bit is set to 1 and the I2C module is in an idle or disabled state when the MCU signals to enter stop mode, the module immediately acknowledges the request to enter stop mode.</p> |

Table continues on the next page...

I2Cx_FLT field descriptions (continued)

| Field | Description |
|-------------|--|
| | <p>If SHEN is cleared to 0 and the overall data transmission or reception that was suspended by stop mode entry was incomplete: To resume the overall transmission or reception after the MCU exits stop mode, software must reinitialize the transfer by resending the address of the slave.</p> <p>If the I2C Control Register 1's IICIE bit was set to 1 before the MCU entered stop mode, system software will receive the interrupt triggered by the I2C Status Register's TCF bit after the MCU wakes from the stop mode.</p> <p>0 Stop holdoff is disabled. The MCU's entry to stop mode is not gated. 1 Stop holdoff is enabled.</p> |
| 6 STOPF | <p>I2C Bus Stop Detect Flag</p> <p>Hardware sets this bit when the I2C bus's stop status is detected. The STOPF bit must be cleared by writing 1 to it.</p> <p>0 No stop happens on I2C bus 1 Stop detected on I2C bus</p> |
| 5 SSIE | <p>I2C Bus Stop or Start Interrupt Enable</p> <p>This bit enables the interrupt for I2C bus stop or start detection.</p> <p>NOTE: To clear the I2C bus stop or start detection interrupt: In the interrupt service routine, first clear the STOPF or STARTF bit by writing 1 to it, and then clear the IICIF bit in the status register. If this sequence is reversed, the IICIF bit is asserted again.</p> <p>0 Stop or start detection interrupt is disabled 1 Stop or start detection interrupt is enabled</p> |
| 4 STARTF | <p>I2C Bus Start Detect Flag</p> <p>Hardware sets this bit when the I2C bus's start status is detected. The STARTF bit must be cleared by writing 1 to it.</p> <p>0 No start happens on I2C bus 1 Start detected on I2C bus</p> |
| FLT | <p>I2C Programmable Filter Factor</p> <p>Controls the width of the glitch, in terms of I2C module clock cycles, that the filter must absorb. For any glitch whose size is less than or equal to this width setting, the filter does not allow the glitch to pass.</p> <p>0h No filter/bypass 1-Fh Filter glitches up to width of n I2C module clock cycles, where $n=1-15d$</p> |

31.3.8 I2C Range Address register (I2Cx_RA)

Address: Base address + 7h offset

| | | | | | | | | |
|-------|-----|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | RAD | | | | | | | 0 |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_RA field descriptions

| Field | Description |
|---------------|---|
| 7–1 RAD | Range Slave Address This field contains the slave address to be used by the I2C module. The field is used in the 7-bit address scheme. If I2C_C2[RMEN] is set to 1, any nonzero value write enables this register. This register value can be considered as a maximum boundary in the range matching mode. |
| 0 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

31.3.9 I2C SMBus Control and Status register (I2Cx_SMB)**NOTE**

When the SCL and SDA signals are held high for a length of time greater than the high timeout period, the SHTF1 flag sets. Before reaching this threshold, while the system is detecting how long these signals are being held high, a master assumes that the bus is free. However, the SHTF1 bit is set to 1 in the bus transmission process with the idle bus state.

NOTE

When the TCKSEL bit is set, there is no need to monitor the SHTF1 bit because the bus speed is too high to match the protocol of SMBus.

Address: Base address + 8h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|---------|---------|--------|------|-------|-------|---------|
| Read | | | | | SLTF | SHTF1 | SHTF2 | |
| Write | FAACK | ALERTEN | SIICAEN | TCKSEL | w1c | | w1c | SHTF2IE |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_SMB field descriptions

| Field | Description |
|--------------|---|
| 7 FAACK | Fast NACK/ACK Enable For SMBus packet error checking, the CPU must be able to issue an ACK or NACK according to the result of receiving data byte. 0 An ACK or NACK is sent on the following receiving data byte 1 Writing 0 to TXAK after receiving a data byte generates an ACK. Writing 1 to TXAK after receiving a data byte generates a NACK. |
| 6 ALERTEN | SMBus Alert Response Address Enable Enables or disables SMBus alert response address matching. |

Table continues on the next page...

I2Cx_SMB field descriptions (continued)

| Field | Description |
|--------------|---|
| | <p>NOTE: After the host responds to a device that used the alert response address, you must use software to put the device's address on the bus. The alert protocol is described in the SMBus specification.</p> <p>0 SMBus alert response address matching is disabled 1 SMBus alert response address matching is enabled</p> |
| 5 SIICAEN | <p>Second I2C Address Enable</p> <p>Enables or disables SMBus device default address.</p> <p>0 I2C address register 2 matching is disabled 1 I2C address register 2 matching is enabled</p> |
| 4 TCKSEL | <p>Timeout Counter Clock Select</p> <p>Selects the clock source of the timeout counter.</p> <p>0 Timeout counter counts at the frequency of the I2C module clock / 64 1 Timeout counter counts at the frequency of the I2C module clock</p> |
| 3 SLTF | <p>SCL Low Timeout Flag</p> <p>This bit is set when the SLT register (consisting of the SLTH and SLTL registers) is loaded with a non-zero value (LoValue) and an SCL low timeout occurs. Software clears this bit by writing a logic 1 to it.</p> <p>NOTE: The low timeout function is disabled when the SLT register's value is 0.</p> <p>0 No low timeout occurs 1 Low timeout occurs</p> |
| 2 SHTF1 | <p>SCL High Timeout Flag 1</p> <p>This read-only bit sets when SCL and SDA are held high more than $\text{clock} \times \text{LoValue} / 512$, which indicates the bus is free. This bit is cleared automatically.</p> <p>0 No SCL high and SDA high timeout occurs 1 SCL high and SDA high timeout occurs</p> |
| 1 SHTF2 | <p>SCL High Timeout Flag 2</p> <p>This bit sets when SCL is held high and SDA is held low more than $\text{clock} \times \text{LoValue} / 512$. Software clears this bit by writing 1 to it.</p> <p>0 No SCL high and SDA low timeout occurs 1 SCL high and SDA low timeout occurs</p> |
| 0 SHTF2IE | <p>SHTF2 Interrupt Enable</p> <p>Enables SCL high and SDA low timeout interrupt.</p> <p>0 SHTF2 interrupt is disabled 1 SHTF2 interrupt is enabled</p> |

31.3.10 I2C Address Register 2 (I2Cx_A2)

Address: Base address + 9h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----|---|---|---|---|---|---|---|
| Read | SAD | | | | | | | 0 |
| Write | | | | | | | | 0 |
| Reset | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |

I2Cx_A2 field descriptions

| Field | Description |
|---------------|---|
| 7–1 SAD | SMBus Address Contains the slave address used by the SMBus. This field is used on the device default address or other related addresses. |
| 0 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |

31.3.11 I2C SCL Low Timeout Register High (I2Cx_SLTH)

Address: Base address + Ah offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------------|---|---|---|---|---|---|---|
| Read | SSLT[15:8] | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_SLTH field descriptions

| Field | Description |
|------------|---|
| SSLT[15:8] | SSLT[15:8] Most significant byte of SCL low timeout value that determines the timeout period of SCL low. |

31.3.12 I2C SCL Low Timeout Register Low (I2Cx_SLTL)

Address: Base address + Bh offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----------|---|---|---|---|---|---|---|
| Read | SSLT[7:0] | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

I2Cx_SLTL field descriptions

| Field | Description |
|-----------|-------------|
| SSLT[7:0] | SSLT[7:0] |

I2Cx_SLTL field descriptions (continued)

| Field | Description |
|-------|--|
| | Least significant byte of SCL low timeout value that determines the timeout period of SCL low. |

31.4 Functional description

This section provides a comprehensive functional description of the I2C module.

31.4.1 I2C protocol

The I2C bus system uses a serial data line (SDA) and a serial clock line (SCL) for data transfers.

All devices connected to it must have open drain or open collector outputs. A logic AND function is exercised on both lines with external pull-up resistors. The value of these resistors depends on the system.

Normally, a standard instance of communication is composed of four parts:

1. START signal
2. Slave address transmission
3. Data transfer
4. STOP signal

The STOP signal should not be confused with the CPU STOP instruction. The following figure illustrates I2C bus system communication.

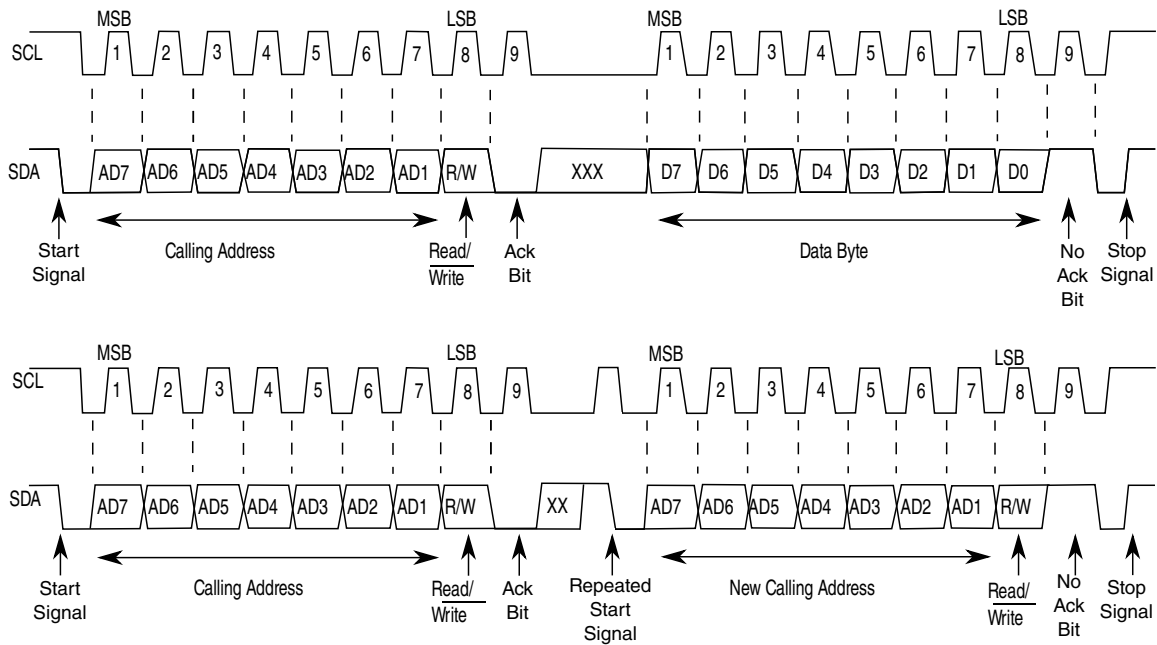


Figure 31-38. I2C bus transmission signals

31.4.1.1 START signal

The bus is free when no master device is engaging the bus (both SCL and SDA are high). When the bus is free, a master may initiate communication by sending a START signal. A START signal is defined as a high-to-low transition of SDA while SCL is high. This signal denotes the beginning of a new data transfer—each data transfer might contain several bytes of data—and brings all slaves out of their idle states.

31.4.1.2 Slave address transmission

Immediately after the START signal, the first byte of a data transfer is the slave address transmitted by the master. This address is a 7-bit calling address followed by an R/\overline{W} bit. The R/\overline{W} bit tells the slave the desired direction of data transfer.

- 1 = Read transfer: The slave transmits data to the master
- 0 = Write transfer: The master transmits data to the slave

Only the slave with a calling address that matches the one transmitted by the master responds by sending an acknowledge bit. The slave sends the acknowledge bit by pulling SDA low at the ninth clock.

No two slaves in the system can have the same address. If the I2C module is the master, it must not transmit an address that is equal to its own slave address. The I2C module cannot be master and slave at the same time. However, if arbitration is lost during an address cycle, the I2C module reverts to slave mode and operates correctly even if it is being addressed by another master.

31.4.1.3 Data transfers

When successful slave addressing is achieved, data transfer can proceed on a byte-by-byte basis in the direction specified by the $\overline{R/W}$ bit sent by the calling master.

All transfers that follow an address cycle are referred to as data transfers, even if they carry subaddress information for the slave device.

Each data byte is 8 bits long. Data may be changed only while SCL is low. Data must be held stable while SCL is high. There is one clock pulse on SCL for each data bit, and the MSB is transferred first. Each data byte is followed by a ninth (acknowledge) bit, which is signaled from the receiving device by pulling SDA low at the ninth clock. In summary, one complete data transfer needs nine clock pulses.

If the slave receiver does not acknowledge the master in the ninth bit, the slave must leave SDA high. The master interprets the failed acknowledgement as an unsuccessful data transfer.

If the master receiver does not acknowledge the slave transmitter after a data byte transmission, the slave interprets it as an end to data transfer and releases the SDA line.

In the case of a failed acknowledgement by either the slave or master, the data transfer is aborted and the master does one of two things:

- Relinquishes the bus by generating a STOP signal.
- Commences a new call by generating a repeated START signal.

31.4.1.4 STOP signal

The master can terminate the communication by generating a STOP signal to free the bus. A STOP signal is defined as a low-to-high transition of SDA while SCL is asserted.

The master can generate a STOP signal even if the slave has generated an acknowledgement, at which point the slave must release the bus.

31.4.1.5 Repeated START signal

The master may generate a START signal followed by a calling command without generating a STOP signal first. This action is called a repeated START. The master uses a repeated START to communicate with another slave or with the same slave in a different mode (transmit/receive mode) without releasing the bus.

31.4.1.6 Arbitration procedure

The I2C bus is a true multimaster bus that allows more than one master to be connected on it.

If two or more masters try to control the bus at the same time, a clock synchronization procedure determines the bus clock. The bus clock's low period is equal to the longest clock low period, and the high period is equal to the shortest one among the masters.

The relative priority of the contending masters is determined by a data arbitration procedure. A bus master loses arbitration if it transmits logic level 1 while another master transmits logic level 0. The losing masters immediately switch to slave receive mode and stop driving SDA output. In this case, the transition from master to slave mode does not generate a STOP condition. Meanwhile, hardware sets a status bit to indicate the loss of arbitration.

31.4.1.7 Clock synchronization

Because wire AND logic is performed on SCL, a high-to-low transition on SCL affects all devices connected on the bus. The devices start counting their low period and, after a device's clock has gone low, that device holds SCL low until the clock reaches its high state. However, the change of low to high in this device clock might not change the state of SCL if another device clock is still within its low period. Therefore, the synchronized clock SCL is held low by the device with the longest low period. Devices with shorter low periods enter a high wait state during this time; see the following diagram. When all applicable devices have counted off their low period, the synchronized clock SCL is released and pulled high. Afterward there is no difference between the device clocks and the state of SCL, and all devices start counting their high periods. The first device to complete its high period pulls SCL low again.

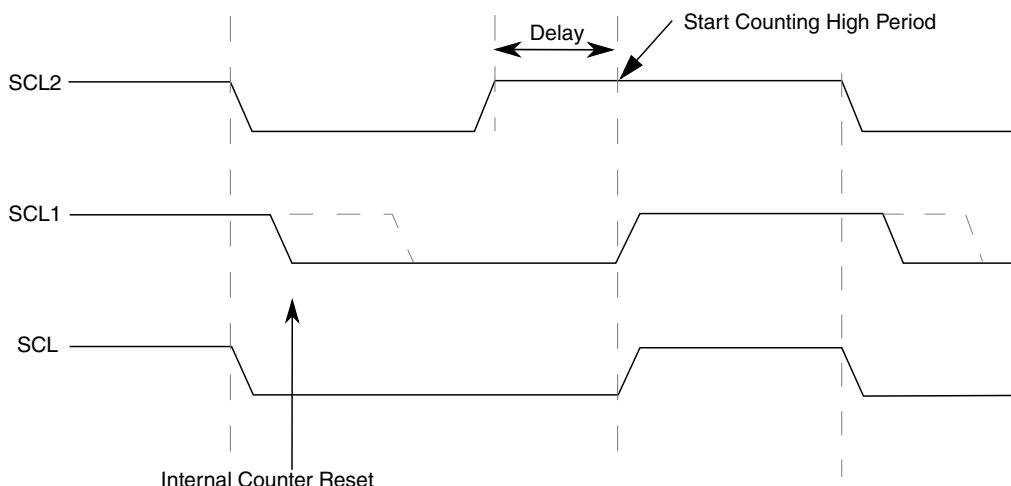


Figure 31-39. I2C clock synchronization

31.4.1.8 Handshaking

The clock synchronization mechanism can be used as a handshake in data transfers. A slave device may hold SCL low after completing a single byte transfer (9 bits). In this case, it halts the bus clock and forces the master clock into wait states until the slave releases SCL.

31.4.1.9 Clock stretching

The clock synchronization mechanism can be used by slaves to slow down the bit rate of a transfer. After the master drives SCL low, a slave can drive SCL low for the required period and then release it. If the slave's SCL low period is greater than the master's SCL low period, the resulting SCL bus signal's low period is stretched. In other words, the SCL bus signal's low period is increased to be the same length as the slave's SCL low period.

31.4.1.10 I2C divider and hold values

NOTE

For some cases on some devices, the SCL divider value may vary by ± 2 or ± 4 when ICR's value ranges from 00h to 0Fh. These potentially varying SCL divider values are highlighted in the following table. For the actual SCL divider values for your device, see the chip-specific details about the I2C module.

Table 31-41. I2C divider and hold values

| ICR (hex) | SCL divider | SDA hold value | SCL hold (start) value | SCL hold (stop) value | ICR (hex) | SCL divider (clocks) | SDA hold (clocks) | SCL hold (start) value | SCL hold (stop) value |
|-----------|-------------|----------------|------------------------|-----------------------|-----------|----------------------|-------------------|------------------------|-----------------------|
| 00 | 20 | 7 | 6 | 11 | 20 | 160 | 17 | 78 | 81 |
| 01 | 22 | 7 | 7 | 12 | 21 | 192 | 17 | 94 | 97 |
| 02 | 24 | 8 | 8 | 13 | 22 | 224 | 33 | 110 | 113 |
| 03 | 26 | 8 | 9 | 14 | 23 | 256 | 33 | 126 | 129 |
| 04 | 28 | 9 | 10 | 15 | 24 | 288 | 49 | 142 | 145 |
| 05 | 30 | 9 | 11 | 16 | 25 | 320 | 49 | 158 | 161 |
| 06 | 34 | 10 | 13 | 18 | 26 | 384 | 65 | 190 | 193 |
| 07 | 40 | 10 | 16 | 21 | 27 | 480 | 65 | 238 | 241 |
| 08 | 28 | 7 | 10 | 15 | 28 | 320 | 33 | 158 | 161 |
| 09 | 32 | 7 | 12 | 17 | 29 | 384 | 33 | 190 | 193 |
| 0A | 36 | 9 | 14 | 19 | 2A | 448 | 65 | 222 | 225 |
| 0B | 40 | 9 | 16 | 21 | 2B | 512 | 65 | 254 | 257 |
| 0C | 44 | 11 | 18 | 23 | 2C | 576 | 97 | 286 | 289 |
| 0D | 48 | 11 | 20 | 25 | 2D | 640 | 97 | 318 | 321 |
| 0E | 56 | 13 | 24 | 29 | 2E | 768 | 129 | 382 | 385 |
| 0F | 68 | 13 | 30 | 35 | 2F | 960 | 129 | 478 | 481 |
| 10 | 48 | 9 | 18 | 25 | 30 | 640 | 65 | 318 | 321 |
| 11 | 56 | 9 | 22 | 29 | 31 | 768 | 65 | 382 | 385 |
| 12 | 64 | 13 | 26 | 33 | 32 | 896 | 129 | 446 | 449 |
| 13 | 72 | 13 | 30 | 37 | 33 | 1024 | 129 | 510 | 513 |
| 14 | 80 | 17 | 34 | 41 | 34 | 1152 | 193 | 574 | 577 |
| 15 | 88 | 17 | 38 | 45 | 35 | 1280 | 193 | 638 | 641 |
| 16 | 104 | 21 | 46 | 53 | 36 | 1536 | 257 | 766 | 769 |
| 17 | 128 | 21 | 58 | 65 | 37 | 1920 | 257 | 958 | 961 |
| 18 | 80 | 9 | 38 | 41 | 38 | 1280 | 129 | 638 | 641 |
| 19 | 96 | 9 | 46 | 49 | 39 | 1536 | 129 | 766 | 769 |
| 1A | 112 | 17 | 54 | 57 | 3A | 1792 | 257 | 894 | 897 |
| 1B | 128 | 17 | 62 | 65 | 3B | 2048 | 257 | 1022 | 1025 |
| 1C | 144 | 25 | 70 | 73 | 3C | 2304 | 385 | 1150 | 1153 |
| 1D | 160 | 25 | 78 | 81 | 3D | 2560 | 385 | 1278 | 1281 |
| 1E | 192 | 33 | 94 | 97 | 3E | 3072 | 513 | 1534 | 1537 |
| 1F | 240 | 33 | 118 | 121 | 3F | 3840 | 513 | 1918 | 1921 |

31.4.2 10-bit address

For 10-bit addressing, 0x11110 is used for the first 5 bits of the first address byte. Various combinations of read/write formats are possible within a transfer that includes 10-bit addressing.

31.4.2.1 Master-transmitter addresses a slave-receiver

The transfer direction is not changed. When a 10-bit address follows a START condition, each slave compares the first 7 bits of the first byte of the slave address (11110XX) with its own address and tests whether the eighth bit (R/\overline{W} direction bit) is 0. It is possible that more than one device finds a match and generates an acknowledge (A1). Each slave that finds a match compares the 8 bits of the second byte of the slave address with its own address, but only one slave finds a match and generates an acknowledge (A2). The matching slave remains addressed by the master until it receives a STOP condition (P) or a repeated START condition (Sr) followed by a different slave address.

Table 31-42. Master-transmitter addresses slave-receiver with a 10-bit address

| | | | | | | | | | | | |
|---|---|---------------------|----|-----------------------------------|----|------|---|-----|------|-----|---|
| S | Slave address first 7 bits 11110 + AD10 + AD9 | R/ \overline{W} 0 | A1 | Slave address second byte AD[8:1] | A2 | Data | A | ... | Data | A/A | P |
|---|---|---------------------|----|-----------------------------------|----|------|---|-----|------|-----|---|

After the master-transmitter has sent the first byte of the 10-bit address, the slave-receiver sees an I2C interrupt. User software must ensure that for this interrupt, the contents of the Data register are ignored and not treated as valid data.

31.4.2.2 Master-receiver addresses a slave-transmitter

The transfer direction is changed after the second R/\overline{W} bit. Up to and including acknowledge bit A2, the procedure is the same as that described for a master-transmitter addressing a slave-receiver. After the repeated START condition (Sr), a matching slave remembers that it was addressed before. This slave then checks whether the first seven bits of the first byte of the slave address following Sr are the same as they were after the START condition (S), and it tests whether the eighth (R/\overline{W}) bit is 1. If there is a match, the slave considers that it has been addressed as a transmitter and generates acknowledge A3. The slave-transmitter remains addressed until it receives a STOP condition (P) or a repeated START condition (Sr) followed by a different slave address.

After a repeated START condition (Sr), all other slave devices also compare the first seven bits of the first byte of the slave address with their own addresses and test the eighth (R/\overline{W}) bit. However, none of them are addressed because $R/\overline{W} = 1$ (for 10-bit devices), or the 11110XX slave address (for 7-bit devices) does not match.

Table 31-43. Master-receiver addresses a slave-transmitter with a 10-bit address

| | | | | | | | | | | | | | | | |
|---|--|-----------------------|----|--------------------------------------|----|----|--|-----------------------|----|------|---|-----|------|---|---|
| S | Slave address first 7 bits 11110 + AD10 + AD9 | R/\overline{W} 0 | A1 | Slave address second byte AD[8:1] | A2 | Sr | Slave address first 7 bits 11110 + AD10 + AD9 | R/\overline{W} 1 | A3 | Data | A | ... | Data | A | P |
|---|--|-----------------------|----|--------------------------------------|----|----|--|-----------------------|----|------|---|-----|------|---|---|

After the master-receiver has sent the first byte of the 10-bit address, the slave-transmitter sees an I2C interrupt. User software must ensure that for this interrupt, the contents of the Data register are ignored and not treated as valid data.

31.4.3 Address matching

All received addresses can be requested in 7-bit or 10-bit address format.

- AD[7:1] in Address Register 1, which contains the I2C primary slave address, always participates in the address matching process. It provides a 7-bit address.
- If the ADEXT bit is set, AD[10:8] in Control Register 2 participates in the address matching process. It extends the I2C primary slave address to a 10-bit address.

Additional conditions that affect address matching include:

- If the GCAEN bit is set, general call participates the address matching process.
- If the ALERTEN bit is set, alert response participates the address matching process.
- If the SIICAEN bit is set, Address Register 2 participates in the address matching process.
- If the RMEN bit is set, when the Range Address register is programmed to a nonzero value, any address within the range of values of Address Register 1 (excluded) and the Range Address register (included) participates in the address matching process. The Range Address register must be programmed to a value greater than the value of Address Register 1.

When the I2C module responds to one of these addresses, it acts as a slave-receiver and the IAAS bit is set after the address cycle. Software must read the Data register after the first byte transfer to determine that the address is matched.

31.4.4 System management bus specification

SMBus provides a control bus for system and power management related tasks. A system can use SMBus to pass messages to and from devices instead of tripping individual control lines.

Removing the individual control lines reduces pin count. Accepting messages ensures future expandability. With the system management bus, a device can provide manufacturer information, tell the system what its model/part number is, save its state for a suspend event, report different types of errors, accept control parameters, and return its status.

31.4.4.1 Timeouts

The $T_{\text{TIMEOUT},\text{MIN}}$ parameter allows a master or slave to conclude that a defective device is holding the clock low indefinitely or a master is intentionally trying to drive devices off the bus. The slave device must release the bus (stop driving the bus and let SCL and SDA float high) when it detects any single clock held low longer than $T_{\text{TIMEOUT},\text{MIN}}$. Devices that have detected this condition must reset their communication and be able to receive a new START condition within the timeframe of $T_{\text{TIMEOUT},\text{MAX}}$.

SMBus defines a clock low timeout, T_{TIMEOUT} , of 35 ms, specifies $T_{\text{LOW}:\text{SEXT}}$ as the cumulative clock low extend time for a slave device, and specifies $T_{\text{LOW}:\text{MEXT}}$ as the cumulative clock low extend time for a master device.

31.4.4.1.1 SCL low timeout

If the SCL line is held low by a slave device on the bus, no further communication is possible. Furthermore, the master cannot force the SCL line high to correct the error condition. To solve this problem, the SMBus protocol specifies that devices participating in a transfer must detect any clock cycle held low longer than a timeout value condition. Devices that have detected the timeout condition must reset the communication. When the I2C module is an active master, if it detects that SMBCLK low has exceeded the value of $T_{\text{TIMEOUT},\text{MIN}}$, it must generate a stop condition within or after the current data byte in the transfer process. When the I2C module is a slave, if it detects the $T_{\text{TIMEOUT},\text{MIN}}$ condition, it resets its communication and is then able to receive a new START condition.

31.4.4.1.2 SCL high timeout

When the I2C module has determined that the SMBCLK and SMBDAT signals have been high for at least $T_{\text{HIGH:MAX}}$, it assumes that the bus is idle.

A HIGH timeout occurs after a START condition appears on the bus but before a STOP condition appears on the bus. Any master detecting this scenario can assume the bus is free when either of the following occurs:

- SHTF1 rises.
- The BUSY bit is high and SHTF1 is high.

When the SMBDAT signal is low and the SMBCLK signal is high for a period of time, another kind of timeout occurs. The time period must be defined in software. SHTF2 is used as the flag when the time limit is reached. This flag is also an interrupt resource, so it triggers IICIF.

31.4.4.1.3 CSMBCLK TIMEOUT MEXT and CSMBCLK TIMEOUT SEXT

The following figure illustrates the definition of the timeout intervals $T_{\text{LOW:SEXT}}$ and $T_{\text{LOW:MEXT}}$. When in master mode, the I2C module must not cumulatively extend its clock cycles for a period greater than $T_{\text{LOW:MEXT}}$ within a byte, where each byte is defined as START-to-ACK, ACK-to-ACK, or ACK-to-STOP. When CSMBCLK TIMEOUT MEXT occurs, SMBus MEXT rises and also triggers the SLTF.

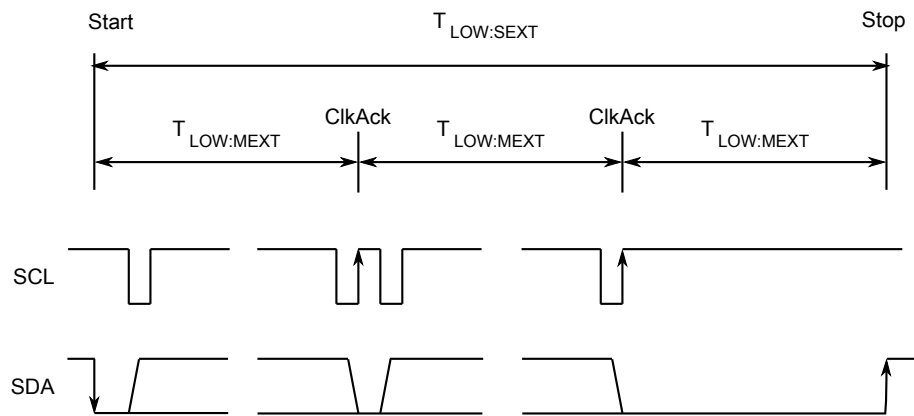


Figure 31-40. Timeout measurement intervals

A master is allowed to abort the transaction in progress to any slave that violates the $T_{\text{LOW:SEXT}}$ or $T_{\text{TIMEOUT,MIN}}$ specifications. To abort the transaction, the master issues a STOP condition at the conclusion of the byte transfer in progress. When a slave, the I2C module must not cumulatively extend its clock cycles for a period greater than $T_{\text{LOW:SEXT}}$ during any message from the initial START to the STOP. When CSMBCLK TIMEOUT SEXT occurs, SEXT rises and also triggers SLTF.

NOTE

CSMBCLK TIMEOUT SEXT and CSMBCLK TIMEOUT MEXT are optional functions that are implemented in the second step.

31.4.4.2 FAST ACK and NACK

To improve reliability and communication robustness, implementation of packet error checking (PEC) by SMBus devices is optional for SMBus devices but required for devices participating in and only during the address resolution protocol (ARP) process. The PEC is a CRC-8 error checking byte, calculated on all the message bytes. The PEC is appended to the message by the device that supplied the last data byte. If the PEC is present but not correct, a NACK is issued by the receiver. Otherwise an ACK is issued. To calculate the CRC-8 by software, this module can hold the SCL line low after receiving the eighth SCL (8th bit) if this byte is a data byte. So software can determine whether an ACK or NACK should be sent to the bus by setting or clearing the TXAK bit if the FACK (fast ACK/NACK enable) bit is enabled.

SMBus requires a device always to acknowledge its own address, as a mechanism to detect the presence of a removable device (such as a battery or docking station) on the bus. In addition to indicating a slave device busy condition, SMBus uses the NACK mechanism to indicate the reception of an invalid command or invalid data. Because such a condition may occur on the last byte of the transfer, SMBus devices are required to have the ability to generate the not acknowledge after the transfer of each byte and before the completion of the transaction. This requirement is important because SMBus does not provide any other resend signaling. This difference in the use of the NACK signaling has implications on the specific implementation of the SMBus port, especially in devices that handle critical system data such as the SMBus host and the SBS components.

NOTE

In the last byte of master receive slave transmit mode, the master must send a NACK to the bus, so FACK must be switched off before the last byte transmits.

31.4.5 Resets

The I2C module is disabled after a reset. The I2C module cannot cause a core reset.

31.4.6 Interrupts

The I2C module generates an interrupt when any of the events in the table found here occur, provided that the IICIE bit is set.

The interrupt is driven by the IICIF bit (of the I2C Status Register) and masked with the IICIE bit (of the I2C Control Register 1). The IICIF bit must be cleared (by software) by writing 1 to it in the interrupt routine. The SMBus timeouts interrupt is driven by SLTF and masked with the IICIE bit. The SLTF bit must be cleared by software by writing 1 to it in the interrupt routine. You can determine the interrupt type by reading the Status Register.

NOTE

In master receive mode, the FACK bit must be set to zero before the last byte transfer.

Table 31-44. Interrupt summary

| Interrupt source | Status | Flag | Local enable |
|--------------------------------------|--------|-------|-----------------|
| Complete 1-byte transfer | TCF | IICIF | IICIE |
| Match of received calling address | IAAS | IICIF | IICIE |
| Arbitration lost | ARBL | IICIF | IICIE |
| I ² C bus stop detection | STOPF | IICIF | IICIE & SSIE |
| I ² C bus start detection | STARTF | IICIF | IICIE & SSIE |
| SMBus SCL low timeout | SLTF | IICIF | IICIE |
| SMBus SCL high SDA low timeout | SHTF2 | IICIF | IICIE & SHTF2IE |
| Wakeup from stop or wait mode | IAAS | IICIF | IICIE & WUEN |

31.4.6.1 Byte transfer interrupt

The Transfer Complete Flag (TCF) bit is set at the falling edge of the ninth clock to indicate the completion of a byte and acknowledgement transfer. When FACK is enabled, TCF is then set at the falling edge of eighth clock to indicate the completion of byte.

31.4.6.2 Address detect interrupt

When the calling address matches the programmed slave address (I2C Address Register) or when the GCAEN bit is set and a general call is received, the IAAS bit in the Status Register is set. The CPU is interrupted, provided the IICIE bit is set. The CPU must check the SRW bit and set its Tx mode accordingly.

31.4.6.3 Stop Detect Interrupt

When the stop status is detected on the I²C bus, the SSIE bit is set to 1. The CPU is interrupted, provided the IICIE and SSIE bits are both set to 1.

31.4.6.4 Exit from low-power/stop modes

The slave receive input detect circuit and address matching feature are still active on low power modes (wait and stop). An asynchronous input matching slave address or general call address brings the CPU out of low power/stop mode if the interrupt is not masked. Therefore, TCF and IAAS both can trigger this interrupt.

31.4.6.5 Arbitration lost interrupt

The I2C is a true multimaster bus that allows more than one master to be connected on it. If two or more masters try to control the bus at the same time, the relative priority of the contending masters is determined by a data arbitration procedure. The I2C module asserts the arbitration-lost interrupt when it loses the data arbitration process and the ARBL bit in the Status Register is set.

Arbitration is lost in the following circumstances:

1. SDA is sampled as low when the master drives high during an address or data transmit cycle.
2. SDA is sampled as low when the master drives high during the acknowledge bit of a data receive cycle.
3. A START cycle is attempted when the bus is busy.
4. A repeated START cycle is requested in slave mode.
5. A STOP condition is detected when the master did not request it.

The ARBL bit must be cleared (by software) by writing 1 to it.

31.4.6.6 Timeout interrupt in SMBus

When the IICIE bit is set, the I2C module asserts a timeout interrupt (outputs SLTF and SHTF2) upon detection of any of the mentioned timeout conditions, with one exception. The SCL high and SDA high TIMEOUT mechanism must not be used to influence the timeout interrupt output, because this timeout indicates an idle condition on the bus. SHTF1 rises when it matches the SCL high and SDA high TIMEOUT and falls automatically just to indicate the bus status. The SHTF2's timeout period is the same as that of SHTF1, which is short compared to that of SLTF, so another control bit, SHTF2IE, is added to enable or disable it.

31.4.7 Programmable input glitch filter

An I2C glitch filter has been added outside legacy I2C modules but within the I2C package. This filter can absorb glitches on the I2C clock and data lines for the I2C module.

The width of the glitch to absorb can be specified in terms of the number of (half) I2C module clock cycles. A single Programmable Input Glitch Filter control register is provided. Effectively, any down-up-down or up-down-up transition on the data line that occurs within the number of clock cycles programmed in this register is ignored by the I2C module. The programmer must specify the size of the glitch (in terms of I2C module clock cycles) for the filter to absorb and not pass.

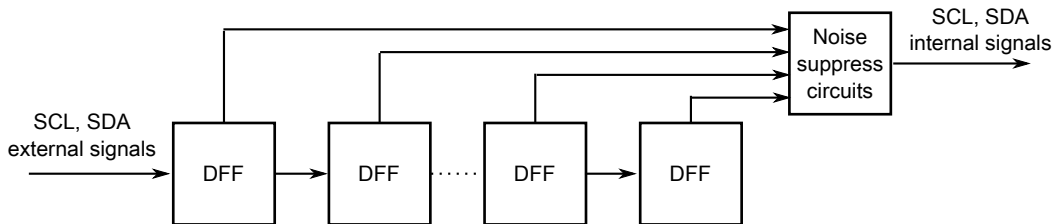


Figure 31-41. Programmable input glitch filter diagram

31.4.8 Address matching wake-up

When a primary, range, or general call address match occurs when the I2C module is in slave receive mode, the MCU wakes from a low power mode where no peripheral bus is running.

After the address matching IAAS bit is set, an interrupt is sent at the end of address matching to wake the core.

NOTE

During the wake-up process, if an external master continues to send data to the slave, the baud rate under Stop mode must be less than 50 kbit/s. To avoid the slower baud rate under Stop mode, the master can add a short delay in firmware to wait until the wake-up process is complete and then send data.

NOTE

Wake-up caused by an address match is not supported for SMBus mode.

31.5 Initialization/application information

Module Initialization (Slave)

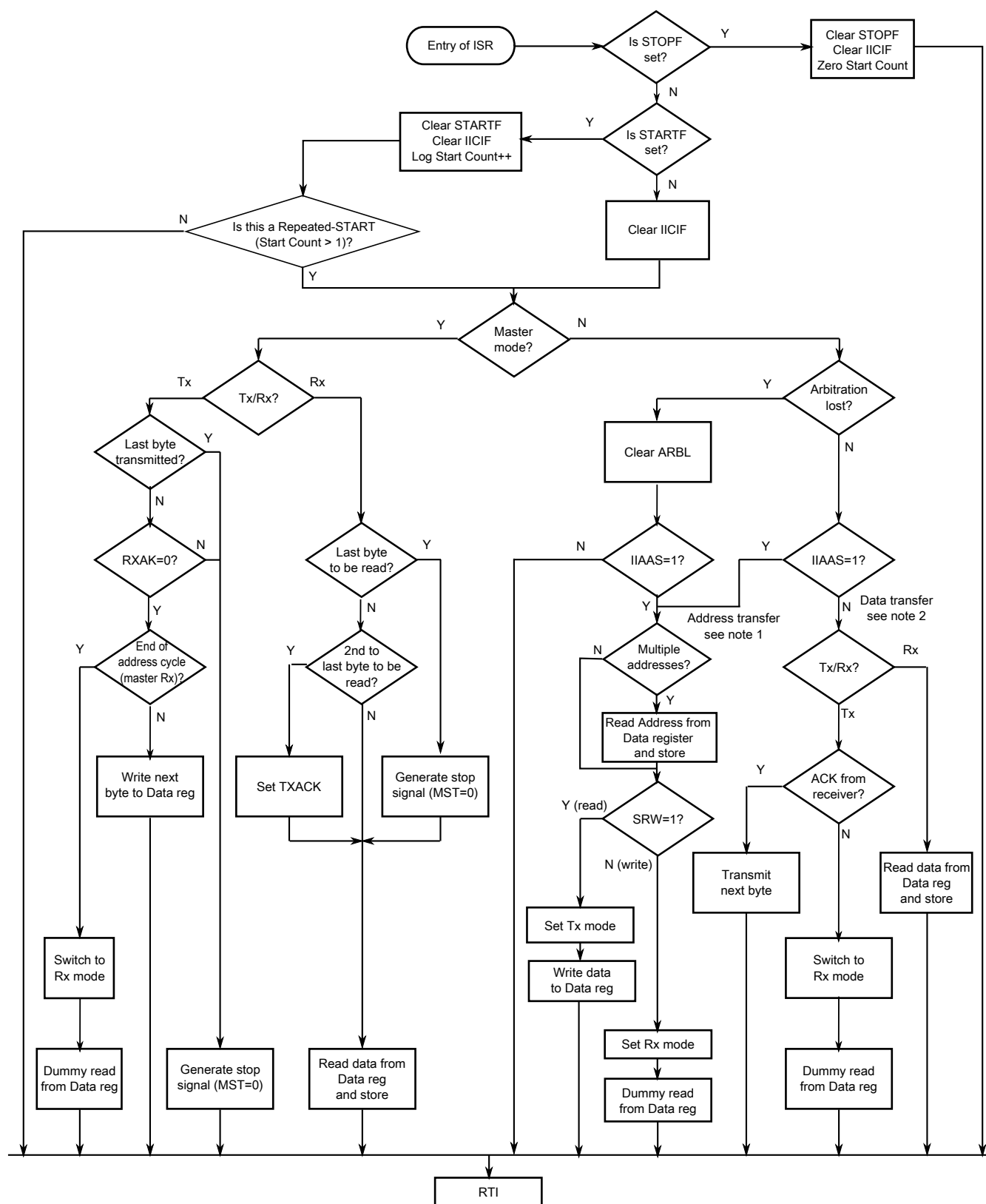
1. Write: Control Register 2
 - to enable or disable general call
 - to select 10-bit or 7-bit addressing mode
2. Write: Address Register 1 to set the slave address
3. Write: Control Register 1 to enable the I2C module and interrupts
4. Initialize RAM variables (IICEN = 1 and IICIE = 1) for transmit data
5. Initialize RAM variables used to achieve the routine shown in the following figure

Module Initialization (Master)

1. Write: Frequency Divider register to set the I2C baud rate (see example in description of [ICR](#))
2. Write: Control Register 1 to enable the I2C module and interrupts
3. Initialize RAM variables (IICEN = 1 and IICIE = 1) for transmit data
4. Initialize RAM variables used to achieve the routine shown in the following figure
5. Write: Control Register 1 to enable TX
6. Write: Control Register 1 to enable MST (master mode)
7. Write: Data register with the address of the target slave (the LSB of this byte determines whether the communication is master receive or transmit)

The routine shown in the following figure encompasses both master and slave I2C operations. For slave operation, an incoming I2C message that contains the proper address begins I2C communication. For master operation, communication must be

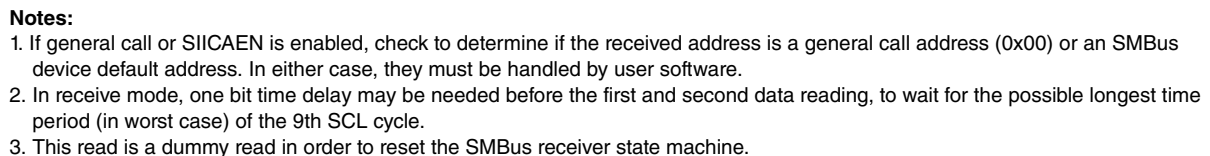
initiated by writing the Data register. An example of an I2C driver which implements many of the steps described here is available in [AN4342: Using the Inter-Integrated Circuit on ColdFire+ and Kinetis](#) .



Notes:

1. If general call is enabled, check to determine if the received address is a general call address (0x00).
If the received address is a general call address, the general call must be handled by user software.
2. When 10-bit addressing addresses a slave, the slave sees an interrupt following the first byte of the extended address.
Ensure that for this interrupt, the contents of the Data register are ignored and not treated as a valid data transfer.

Figure 31-42. Typical I2C interrupt routine



KEA128 Sub-Family Reference Manual, Rev. 2, July 2014

Chapter 32

Freescall's Scalable Controller Area Network (MSCAN)

32.1 Introduction

Freescall's scalable controller area network (MSCAN) is a communication controller implementing the CAN 2.0A/B protocol as defined in the Bosch specification dated September 1991. For users to fully understand the MSCAN specification, it is recommended that the Bosch specification be read first to familiarize the reader with the terms and concepts contained within this document.

Though not exclusively intended for automotive applications, CAN protocol is designed to meet the specific requirements of a vehicle serial data bus: real-time processing, reliable operation in the EMI environment of a vehicle, cost-effectiveness, and required bandwidth.

MSCAN uses an advanced buffer arrangement resulting in predictable real-time behavior and simplified application software.

32.1.1 Glossary

Table 32-1. Terminology

| Term | Description |
|---------|---------------------------------|
| ACK | Acknowledge of CAN message |
| CAN | Controller area network |
| CRC | Cyclic redundancy code |
| EOF | End of frame |
| FIFO | First-In-First-Out memory |
| IFS | Inter-Frame sequence |
| SOF | Start of Frame |
| CPU bus | CPU related read/write data bus |

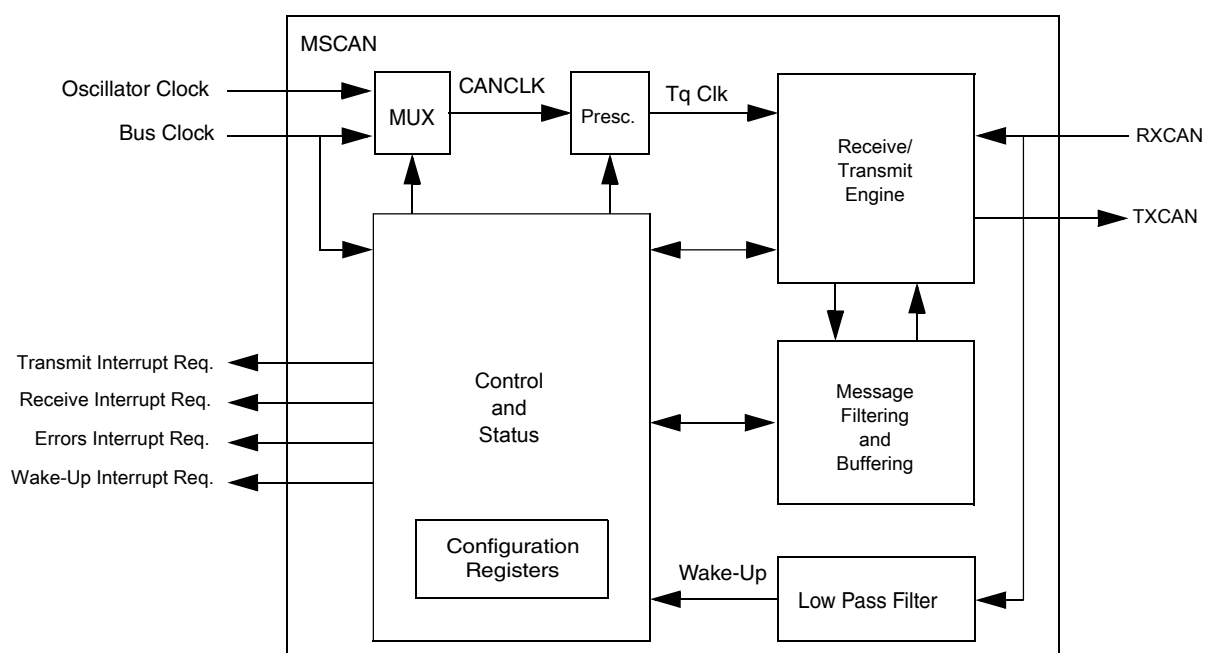
Table continues on the next page...

Table 32-1. Terminology (continued)

| Term | Description |
|------------------|---------------------------------------|
| CAN bus | CAN protocol related serial bus |
| oscillator clock | Direct clock from external oscillator |
| bus clock | CPU bus related clock |
| CAN clock | CAN protocol related clock |

32.1.2 Block diagram

The following figure is the block diagram of the MSCAN

**Figure 32-1. MSCAN Block Diagram**

32.1.3 Features

The basic features of the MSCAN are as follows:

- Implementation of the CAN protocol - Version 2.0A/B
 - Standard and extended data frames
 - Zero to eight bytes data length
 - Programmable bit rate up to 1 Mbps¹
 - Support for remote frames
- Five receive buffers with FIFO storage scheme

1. Depending on the actual bit timing and the clock jitter of the PLL.

- Three transmit buffers with internal prioritization using a "local priority" concept
- Flexible maskable identifier filter supports two full-size (32-bit) extended identifier filters, or four 16-bit filters, or eight 8-bit filters
- Programmable wake-up functionality with integrated low-pass filter
- Programmable loopback mode supports self-test operation
- Programmable listen-only mode for monitoring of CAN bus
- Programmable bus-off recovery functionality
- Separate signalling and interrupt capabilities for all CAN receiver and transmitter error states (warning, error passive, bus-off)
- Programmable MSCAN clock source either bus clock or oscillator clock
- Internal timer for time-stamping of received and transmitted messages
- Three low-power modes: sleep, power down, and MSCAN enable
- Global initialization of configuration registers

32.1.4 Modes of operation

32.1.4.1 Normal system operating modes

The MSCAN module behaves as described within this specification in all normal system operating modes. Write restrictions exist for some registers.

32.1.4.2 Special system operating modes

The MSCAN module behaves as described within this specification in all special system operating modes. Write restrictions which exist on specific registers in normal modes are lifted for test purposes in special modes.

32.1.4.3 Emulation modes

In all emulation modes, the MSCAN module behaves just like in normal system operating modes as described within this specification.

32.1.4.4 Listen-only mode

In an optional CAN bus monitoring mode (listen-only), the CAN node is able to receive valid data frames and valid remote frames, but it sends only "recessive" bits on the CAN bus. In addition, it cannot start a transmission.

If the MAC sub-layer is required to send a "dominant" bit (ACK bit, overload flag, or active error flag), the bit is rerouted internally so that the MAC sub-layer monitors this "dominant" bit, although the CAN bus may remain in recessive state externally.

32.1.4.5 MSCAN initialization mode

MSCAN Initialization Mode The MSCAN enters initialization mode when it is enabled (CANE=1).

When entering initialization mode during operation, any on-going transmission or reception is immediately aborted and synchronization to the CAN bus is lost, potentially causing CAN protocol violations. To protect the CAN bus system from fatal consequences of violations, the MSCAN immediately drives TXCAN into a recessive state.

NOTE

The user is responsible for ensuring that the MSCAN is not active when initialization mode is entered. The recommended procedure is to bring the MSCAN into sleep mode (SLPRQ = 1 and SLPK = 1) before setting the INITRQ bit in the CANCTL0 register. Otherwise, the abort of an on-going message can cause an error condition and can impact other CAN bus devices.

In initialization mode, the MSCAN is stopped. However, interface registers remain accessible. This mode is used to reset the CANCTL0, CANRFLG, CANRIER, CANTFLG, CANTIER, CANTARQ, CANTAACK, and CANTBSEL registers to their default values. In addition, the MSCAN enables the configuration of the CANBTR0, CANBTR1 bit timing registers; CANIDAC; and the CANIDAR, CANIDMR message filters.

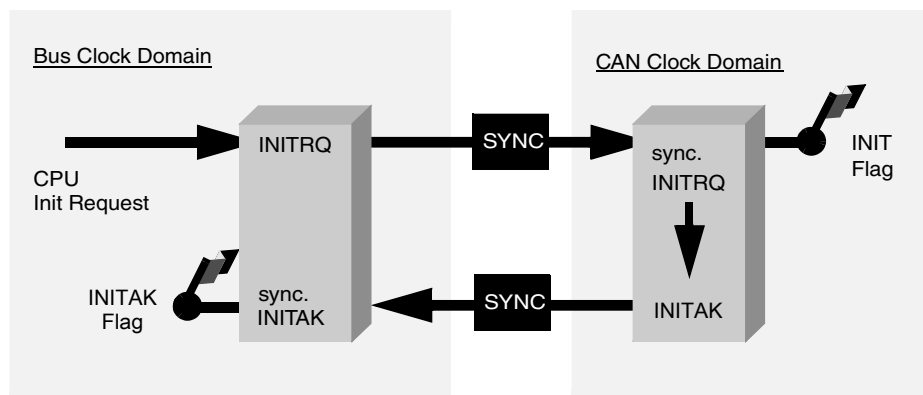


Figure 32-2. Initialization request/acknowledge cycle

Due to independent clock domains within the MSCAN, INITRQ must be synchronized to all domains by using a special handshake mechanism. This handshake causes additional synchronization delay (see [Figure 32-2](#)).

If there is no message transfer ongoing on the CAN bus, the minimum delay will be two additional bus clocks and three additional CAN clocks. When all parts of the MSCAN are in initialization mode, the INITAK flag is set. The application software must use INITAK as a handshake indication for the request (INITRQ) to go into initialization mode.

NOTE

The CPU cannot clear INITRQ before initialization mode (INITRQ = 1 and INITAK = 1) is active.

32.2 External signal description

The MSCAN uses two external pins.

NOTE

On MCUs with an integrated CAN physical interface (transceiver) the MSCAN interface is connected internally to the transceiver interface. In these cases the external availability of signals TXCAN and RXCAN is optional.

Table 32-2. MSCAN signal descriptions

| Signal | Description | I/O | Function |
|--------|----------------------------|-----|---|
| RXCAN | CAN receiver input pin | I | - |
| TXCAN | CAN transmitter output pin | O | The TXCAN output pin represents the logic level on the CAN bus: <ul style="list-style-type: none"> • 0 = Dominant state • 1 = Recessive state |

32.2.1 CAN system

A typical CAN system with MSCAN is shown in the following figure. Each CAN station is connected physically to the CAN bus lines through a transceiver device. The transceiver is capable of driving the large current needed for the CAN bus and has current protection against defective CAN or defective stations.

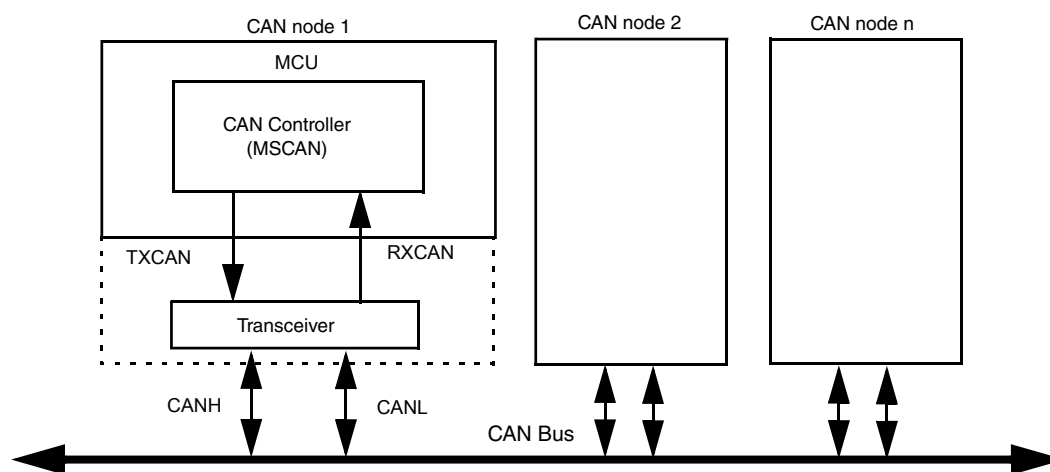


Figure 32-3. CAN system

32.3 Memory map and register definition

32.3.1 Programmer's model of message storage

Each of the receive and transmit message buffers allocates 16 bytes in the memory map containing a 13 byte data structure.

An additional transmit buffer priority register (TBPR) is defined for the transmit buffers. Within the last two bytes of this memory map, the MSCAN stores a special 16-bit time stamp, which is sampled from an internal timer after successful transmission or reception of a message. This feature is only available for transmit and receiver buffers, if the CANCTL0[TIME] is set.

The time stamp register is written by the MSCAN. The CPU can only read these registers.

The following table shows the registers that the data structure of receive and transmit buffers for extended identifiers and standard identifiers mapping to.

Table 32-3. Message buffer organization

| Offset address | Extended identifiers | Standard identifiers |
|----------------|----------------------|----------------------|
| 0x0020 | REIDR0 | RSIDR0 |
| 0x0021 | REIDR1 | RSIDR1 |
| 0x0022 | REIDR2 | |
| 0x0023 | REIDR3 | |

Table continues on the next page...

Table 32-3. Message buffer organization (continued)

| Offset address | Extended identifiers | Standard identifiers |
|----------------|----------------------|----------------------|
| 0x0024 | REDSR0 | |
| 0x0025 | REDSR1 | |
| 0x0026 | REDSR2 | |
| 0x0027 | REDSR3 | |
| 0x0028 | REDSR4 | |
| 0x0029 | REDSR5 | |
| 0x002A | REDSR6 | |
| 0x002B | REDSR7 | |
| 0x002C | RDLR | |
| 0x0030 | TEIDR0 | TSIDR0 |
| 0x0031 | TEIDR1 | TSIDR1 |
| 0x0032 | TEIDR2 | |
| 0x0033 | TEIDR3 | |
| 0x0034 | TEDSR0 | |
| 0x0035 | TEDSR1 | |
| 0x0036 | TEDSR2 | |
| 0x0037 | TEDSR3 | |
| 0x0038 | TEDSR4 | |
| 0x0039 | TEDSR5 | |
| 0x003A | TEDSR6 | |
| 0x003B | TEDSR7 | |
| 0x003C | TDLR | |

NOTE

Read:

- For transmit buffers, anytime when CANTFLG[TXE] flag is set and the corresponding transmit buffer is selected in CANTBSEL
- For receive buffers, only when CANRFLG[RXF] flag is set

Write:

- For transmit buffers, anytime when CANTFLG[TXE] flag is set and the corresponding transmit buffer is selected in CANTBSEL.
- Unimplemented for receive buffers.

Reset: Undefined because of RAM-based implementation

MSCAN memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|--|-----------------|--------|-------------|-----------------------------|
| 4002_4000 | MSCAN Control Register 0 (MSCAN_CANCTL0) | 8 | R/W | 01h | 32.3.2/596 |
| 4002_4001 | MSCAN Control Register 1 (MSCAN_CANCTL1) | 8 | R/W | 11h | 32.3.3/599 |
| 4002_4002 | MSCAN Bus Timing Register 0 (MSCAN_CANBTR0) | 8 | R/W | 00h | 32.3.4/601 |
| 4002_4003 | MSCAN Bus Timing Register 1 (MSCAN_CANBTR1) | 8 | R/W | 00h | 32.3.5/601 |
| 4002_4004 | MSCAN Receiver Flag Register (MSCAN_CANRFLG) | 8 | R/W | 00h | 32.3.6/603 |
| 4002_4005 | MSCAN Receiver Interrupt Enable Register (MSCAN_CANRIER) | 8 | R/W | 00h | 32.3.7/605 |
| 4002_4006 | MSCAN Transmitter Flag Register (MSCAN_CANTFLG) | 8 | R/W | 07h | 32.3.8/606 |
| 4002_4007 | MSCAN Transmitter Interrupt Enable Register (MSCAN_CANTIER) | 8 | R/W | 00h | 32.3.9/607 |
| 4002_4008 | MSCAN Transmitter Message Abort Request Register (MSCAN_CANTARQ) | 8 | R/W | 00h | 32.3.10/608 |
| 4002_4009 | MSCAN Transmitter Message Abort Acknowledge Register (MSCAN_CANTAACK) | 8 | R | 00h | 32.3.11/609 |
| 4002_400A | MSCAN Transmit Buffer Selection Register (MSCAN_CANTBSEL) | 8 | R/W | 00h | 32.3.12/609 |
| 4002_400B | MSCAN Identifier Acceptance Control Register (MSCAN_CANIDAC) | 8 | R/W | 00h | 32.3.13/610 |
| 4002_400D | MSCAN Miscellaneous Register (MSCAN_CANMISC) | 8 | R/W | 00h | 32.3.14/611 |
| 4002_400E | MSCAN Receive Error Counter (MSCAN_CANRXERR) | 8 | R | 00h | 32.3.15/612 |
| 4002_400F | MSCAN Transmit Error Counter (MSCAN_CANTXERR) | 8 | R | 00h | 32.3.16/613 |
| 4002_4010 | MSCAN Identifier Acceptance Register n of First Bank (MSCAN_CANIDAR0) | 8 | R/W | 00h | 32.3.17/613 |
| 4002_4011 | MSCAN Identifier Acceptance Register n of First Bank (MSCAN_CANIDAR1) | 8 | R/W | 00h | 32.3.17/613 |
| 4002_4012 | MSCAN Identifier Acceptance Register n of First Bank (MSCAN_CANIDAR2) | 8 | R/W | 00h | 32.3.17/613 |
| 4002_4013 | MSCAN Identifier Acceptance Register n of First Bank (MSCAN_CANIDAR3) | 8 | R/W | 00h | 32.3.17/613 |
| 4002_4014 | MSCAN Identifier Mask Register n of First Bank (MSCAN_CANIDMR0) | 8 | R/W | 00h | 32.3.18/614 |
| 4002_4015 | MSCAN Identifier Mask Register n of First Bank (MSCAN_CANIDMR1) | 8 | R/W | 00h | 32.3.18/614 |
| 4002_4016 | MSCAN Identifier Mask Register n of First Bank (MSCAN_CANIDMR2) | 8 | R/W | 00h | 32.3.18/614 |
| 4002_4017 | MSCAN Identifier Mask Register n of First Bank (MSCAN_CANIDMR3) | 8 | R/W | 00h | 32.3.18/614 |
| 4002_4018 | MSCAN Identifier Acceptance Register n of Second Bank (MSCAN_CANIDAR4) | 8 | R/W | 00h | 32.3.19/615 |

Table continues on the next page...

MSCAN memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|-------------------------------|--|------------------------|---------------|--------------------|------------------------------|
| 4002_4019 | MSCAN Identifier Acceptance Register n of Second Bank (MSCAN_CANIDAR5) | 8 | R/W | 00h | 32.3.19/ 615 |
| 4002_401A | MSCAN Identifier Acceptance Register n of Second Bank (MSCAN_CANIDAR6) | 8 | R/W | 00h | 32.3.19/ 615 |
| 4002_401B | MSCAN Identifier Acceptance Register n of Second Bank (MSCAN_CANIDAR7) | 8 | R/W | 00h | 32.3.19/ 615 |
| 4002_401C | MSCAN Identifier Mask Register n of Second Bank (MSCAN_CANIDMR4) | 8 | R/W | 00h | 32.3.20/ 616 |
| 4002_401D | MSCAN Identifier Mask Register n of Second Bank (MSCAN_CANIDMR5) | 8 | R/W | 00h | 32.3.20/ 616 |
| 4002_401E | MSCAN Identifier Mask Register n of Second Bank (MSCAN_CANIDMR6) | 8 | R/W | 00h | 32.3.20/ 616 |
| 4002_401F | MSCAN Identifier Mask Register n of Second Bank (MSCAN_CANIDMR7) | 8 | R/W | 00h | 32.3.20/ 616 |
| 4002_4020 | Receive Extended Identifier Register 0 (MSCAN_REIDR0) | 8 | R/W | Undefined | 32.3.21/ 616 |
| 4002_4020 | Receive Standard Identifier Register 0 (MSCAN_RSIDR0) | 8 | R/W | Undefined | 32.3.22/ 617 |
| 4002_4021 | Receive Extended Identifier Register 1 (MSCAN_REIDR1) | 8 | R/W | Undefined | 32.3.23/ 617 |
| 4002_4021 | Receive Standard Identifier Register 1 (MSCAN_RSIDR1) | 8 | R/W | Undefined | 32.3.24/ 618 |
| 4002_4022 | Receive Extended Identifier Register 2 (MSCAN_REIDR2) | 8 | R/W | Undefined | 32.3.25/ 619 |
| 4002_4023 | Receive Extended Identifier Register 3 (MSCAN_REIDR3) | 8 | R/W | Undefined | 32.3.26/ 620 |
| 4002_4024 | Receive Extended Data Segment Register N (MSCAN_REDSR0) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_4025 | Receive Extended Data Segment Register N (MSCAN_REDSR1) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_4026 | Receive Extended Data Segment Register N (MSCAN_REDSR2) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_4027 | Receive Extended Data Segment Register N (MSCAN_REDSR3) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_4028 | Receive Extended Data Segment Register N (MSCAN_REDSR4) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_4029 | Receive Extended Data Segment Register N (MSCAN_REDSR5) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_402A | Receive Extended Data Segment Register N (MSCAN_REDSR6) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_402B | Receive Extended Data Segment Register N (MSCAN_REDSR7) | 8 | R/W | Undefined | 32.3.27/ 620 |
| 4002_402C | Receive Data Length Register (MSCAN_RDLR) | 8 | R/W | Undefined | 32.3.28/ 621 |

Table continues on the next page...

MSCAN memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|-------------------------------|--|------------------------|---------------|--------------------|-----------------------------|
| 4002_402E | Receive Time Stamp Register High (MSCAN_RTSH) | 8 | R | Undefined | 32.3.29/621 |
| 4002_402F | Receive Time Stamp Register Low (MSCAN_RTSL) | 8 | R | Undefined | 32.3.30/622 |
| 4002_4030 | Transmit Extended Identifier Register 0 (MSCAN_TEIDR0) | 8 | R/W | Undefined | 32.3.31/623 |
| 4002_4030 | Transmit Standard Identifier Register 0 (MSCAN_TSIDR0) | 8 | R/W | Undefined | 32.3.32/623 |
| 4002_4031 | Transmit Extended Identifier Register 1 (MSCAN_TEIDR1) | 8 | R/W | Undefined | 32.3.33/624 |
| 4002_4031 | Transmit Standard Identifier Register 1 (MSCAN_TSIDR1) | 8 | R/W | Undefined | 32.3.34/625 |
| 4002_4032 | Transmit Extended Identifier Register 2 (MSCAN_TEIDR2) | 8 | R/W | Undefined | 32.3.35/626 |
| 4002_4033 | Transmit Extended Identifier Register 3 (MSCAN_TEIDR3) | 8 | R/W | Undefined | 32.3.36/626 |
| 4002_4034 | Transmit Extended Data Segment Register N (MSCAN_TEDSR0) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_4035 | Transmit Extended Data Segment Register N (MSCAN_TEDSR1) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_4036 | Transmit Extended Data Segment Register N (MSCAN_TEDSR2) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_4037 | Transmit Extended Data Segment Register N (MSCAN_TEDSR3) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_4038 | Transmit Extended Data Segment Register N (MSCAN_TEDSR4) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_4039 | Transmit Extended Data Segment Register N (MSCAN_TEDSR5) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_403A | Transmit Extended Data Segment Register N (MSCAN_TEDSR6) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_403B | Transmit Extended Data Segment Register N (MSCAN_TEDSR7) | 8 | R/W | Undefined | 32.3.37/627 |
| 4002_403C | Transmit Data Length Register (MSCAN_TDLR) | 8 | R/W | Undefined | 32.3.38/627 |
| 4002_403D | Transmit Buffer Priority Register (MSCAN_TBPR) | 8 | R/W | Undefined | 32.3.39/628 |
| 4002_403E | Transmit Time Stamp Register High (MSCAN_TTSH) | 8 | R | Undefined | 32.3.40/629 |
| 4002_403F | Transmit Time Stamp Register Low (MSCAN_TTSL) | 8 | R | Undefined | 32.3.41/630 |

32.3.2 MSCAN Control Register 0 (MSCAN_CANCTL0)

The CANCTL0 register provides various control bits of the MSCAN module.

NOTE

Write: Anytime when out of initialization mode; exceptions are read-only RXACT and SYNCH, RXFRM (which is set by the module only), and INTRQ (which is also writable in initialization mode)

The CANCTL0 register, except WUPE, INTRQ, and SLPRQ, is held in the reset state when the initialization mode is active (INTRQ = 1 and INITAK = 1). This register is writable again as soon as the initialization mode is exited (INTRQ = 0 and INITAK = 0).

Address: 4002_4000h base + 0h offset = 4002_4000h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|-------|-------|------|------|-------|-------|
| Read | RXFRM | RXACT | CSWAI | SYNCH | TIME | WUPE | SLPRQ | INTRQ |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

MSCAN_CANCTL0 field descriptions

| Field | Description |
|------------|---|
| 7 RXFRM | <p>Received Frame Flag</p> <p>This bit is read and clear only. It is set when a receiver has received a valid message correctly, independently of the filter configuration. After it is set, it remains set until cleared by software or reset. Clearing is done by writing a 1. Writing a 0 is ignored. This bit is not valid in loopback mode.</p> <p>0 No valid message was received since last clearing this flag. 1 A valid message was received since last clearing of this flag.</p> |
| 6 RXACT | <p>Receiver Active Status</p> <p>This read-only flag indicates the MSCAN is receiving a message. The flag is controlled by the receiver front end. This bit is not valid in loopback mode.</p> <p>NOTE: See the Bosch CAN 2.0A/B specification for a detailed definition of transmitter and receiver states.</p> <p>0 MSCAN is transmitting or idle. 1 MSCAN is receiving a message, including when arbitration is lost.</p> |
| 5 CSWAI | <p>CAN Stops in Wait Mode</p> <p>Enabling this bit allows for lower power consumption in wait mode by disabling all the clocks at the CPU bus interface to the MSCAN module.</p> <p>NOTE: In order to protect from accidentally violating the CAN protocol, TXCAN is immediately forced to a recessive state when the CPU enters wait (CSWAI = 1) or stop mode</p> <p>0 The module is not affected during wait mode. 1 The module ceases to be clocked during wait mode.</p> |

Table continues on the next page...

MSCAN_CANCTL0 field descriptions (continued)

| Field | Description |
|-------------|--|
| 4 SYNCH | <p>Synchronized Status</p> <p>This read-only flag indicates whether the MSCAN is synchronized to the CAN bus and able to participate in the communication process. It is set and cleared by the MSCAN.</p> <p>0 MSCAN is not synchronized to the CAN bus. 1 MSCAN is synchronized to the CAN bus.</p> |
| 3 TIME | <p>Timer Enable</p> <p>This bit activates an internal 16-bit wide free running timer which is clocked by the bit clock rate. If the timer is enabled, a 16-bit time stamp will be assigned to each transmitted/received message within the active TX/RX buffer. Right after the EOF of a valid message on the CAN bus, the time stamp is written to the highest bytes (0x000E, 0x000F) in the appropriate buffer. In loopback mode no receive timestamp is generated. The internal timer is reset (all bits set to 0) when disabled. This bit is held low in initialization mode.</p> <p>0 Disable internal MSCAN timer. 1 Enable internal MSCAN timer.</p> |
| 2 WUPE | <p>WakeUp Enable</p> <p>This configuration bit allows the MSCAN to restart from sleep mode or from power down mode (entered from sleep) when traffic on CAN is detected. This bit must be configured before sleep mode entry for the selected function to take effect.</p> <p>NOTE: The CPU has to make sure that the WUPE register and the WUPIE wakeup interrupt enable register is enabled, if the recovery mechanism from stop or wait is required.</p> <p>0 Wakeup disabled - The MSCAN ignores traffic on CAN. 1 Wakeup enabled - The MSCAN is able to restart.</p> |
| 1 SLPRQ | <p>Sleep Mode Request</p> <p>This bit requests the MSCAN to enter sleep mode, which is an internal power saving mode. The sleep mode request is serviced when the CAN bus is idle, i.e., the module is not receiving a message and all transmit buffers are empty. The module indicates entry to sleep mode by setting SLPK = 1. SLPRQ cannot be set while the WUPIF flag is set. Sleep mode will be active until SLPRQ is cleared by the CPU or, depending on the setting of WUPE, the MSCAN detects activity on the CAN bus and clears SLPRQ itself.</p> <p>NOTE: The CPU cannot clear SLPRQ before the MSCAN has entered sleep mode (SLPRQ = 1 and SLPK = 1).</p> <p>0 Running - The MSCAN functions normally. 1 Sleep mode request - The MSCAN enters sleep mode when CAN bus idle.</p> |
| 0 INITRQ | <p>Initialization Mode Request</p> <p>When this bit is set by the CPU, the MSCAN skips to initialization mode. Any ongoing transmission or reception is aborted and synchronization to the CAN bus is lost. The module indicates entry to initialization mode by setting INITAK = 1.</p> <p>The following registers enter their hard reset state and restore their default values: CANCTL0 (Not including WUPE, INITRQ, and SLPRQ), CANRFLG (TSTAT1 and TSTAT0 are not affected by initialization mode), CANRIER (RSTAT1 and RSTAT0 are not affected by initialization mode), CANTFLG, CANTIER, CANTARQ, CANTAACK, and CANTBSEL. The registers CANCTL1, CANBTR0, CANBTR1, CANIDAC, CANIDAR0-7, and CANIDMR0-7 can only be written by the CPU when the MSCAN is in initialization mode (INITRQ = 1 and INITAK = 1). The values of the error counters are not affected by initialization mode.</p> |

Table continues on the next page...

MSCAN_CANCTL0 field descriptions (continued)

| Field | Description |
|-------|--|
| | <p>When this bit is cleared by the CPU, the MSCAN restarts and then tries to synchronize to the CAN bus. If the MSCAN is not in bus-off state, it synchronizes after 11 consecutive recessive bits on the CAN bus; if the MSCAN is in bus-off state, it continues to wait for 128 occurrences of 11 consecutive recessive bits.</p> <p>Writing to other bits in CANCTL0, CANRFLG, CANRIER, CANTFLG, or CANTIER must be done only after initialization mode is exited, which is INITRQ = 0 and INITAK = 0.</p> <p>NOTE: The CPU cannot clear INITRQ before the MSCAN has entered initialization mode (INITRQ = 1 and INITAK = 1).</p> <p>In order to protect from accidentally violating the CAN protocol, TXCAN is immediately forced to a recessive state when the initialization mode is requested by the CPU. Thus, the recommended procedure is to bring the MSCAN into sleep mode (SLPRQ = 1 and SLPK = 1) before requesting initialization mode.</p> <p>0 Normal operation. 1 MSCAN in initialization mode.</p> |

32.3.3 MSCAN Control Register 1 (MSCAN_CANCTL1)

The CANCTL1 register provides various control bits and handshake status information of the MSCAN module.

NOTE

Write: Anytime in initialization mode (INITRQ = 1 and INITAK = 1), except CANE which is write once in normal and anytime in special system operation modes when the MSCAN is in initialization mode (INITRQ = 1 and INITAK = 1)

Address: 4002_4000h base + 1h offset = 4002_4001h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|--------|-------|--------|------|------|-------|--------|
| Read | CANE | CLKSRC | LOOPB | LISTEN | BORM | WUPM | SLPAK | INITAK |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |

MSCAN_CANCTL1 field descriptions

| Field | Description |
|-------------|--|
| 7 CANE | <p>MSCAN Enable</p> <p>0 MSCAN module is disabled. 1 MSCAN module is enabled.</p> |
| 6 CLKSRC | <p>MSCAN Clock Source</p> <p>This bit defines the clock source for the MSCAN module (only for systems with a clock generation module).</p> |

Table continues on the next page...

MSCAN_CANCTL1 field descriptions (continued)

| Field | Description |
|-------------|--|
| | <p>0 MSCAN clock source is the oscillator clock.</p> <p>1 MSCAN clock source is the bus clock.</p> |
| 5 LOOPB | <p>Loopback Self Test Mode</p> <p>When this bit is set, the MSCAN performs an internal loopback which can be used for self test operation. The bit stream output of the transmitter is fed back to the receiver internally. The RXCAN input is ignored and the TXCAN output goes to the recessive state (logic 1). The MSCAN behaves as it does normally when transmitting and treats its own transmitted message as a message received from a remote node. In this state, the MSCAN ignores the bit sent during the ACK slot in the CAN frame acknowledge field to ensure proper reception of its own message. Both transmit and receive interrupts are generated.</p> <p>0 Loopback self test disabled.</p> <p>1 Loopback self test enabled.</p> |
| 4 LISTEN | <p>Listen Only Mode</p> <p>This bit configures the MSCAN as a CAN bus monitor. When LISTEN is set, all valid CAN messages with matching ID are received, but no acknowledgement or error frames are sent out. In addition, the error counters are frozen. Listen only mode supports applications which require "hot plugging" or throughput analysis. The MSCAN is unable to transmit any messages when listen only mode is active.</p> <p>0 Normal operation.</p> <p>1 Listen only mode activated.</p> |
| 3 BORM | <p>Bus-Off Recovery Mode</p> <p>This bit configures the bus-off state recovery mode of the MSCAN.</p> <p>0 Automatic bus-off recovery (see Bosch CAN 2.0A/B protocol specification).</p> <p>1 Bus-off recovery upon user request.</p> |
| 2 WUPM | <p>WakeUp Mode</p> <p>If WUPE in CANCTL0 is enabled, this bit defines whether the integrated low-pass filter is applied to protect the MSCAN from spurious wakeup.</p> <p>0 MSCAN wakes on any dominant level on the CAN bus.</p> <p>1 MSCAN wakes only in case of a dominant pulse on the CAN bus that has a length of T_{wup}.</p> |
| 1 SLPAK | <p>Sleep Mode Acknowledge</p> <p>This flag indicates whether the MSCAN module has entered sleep mode. It is used as a handshake flag for the SLPRQ sleep mode request. Sleep mode is active when SLPRQ = 1 and SLPK = 1. Depending on the setting of WUPE, the MSCAN will clear the flag if it detects activity on the CAN bus while in sleep mode.</p> <p>0 Running - The MSCAN operates normally.</p> <p>1 Sleep mode active - The MSCAN has entered sleep mode.</p> |
| 0 INITAK | <p>Initialization Mode Acknowledge</p> <p>This flag indicates whether the MSCAN module is in initialization mode. It is used as a handshake flag for the INTRQ initialization mode request. Initialization mode is active when INTRQ = 1 and INITAK = 1. The registers CANCTL1, CANBTR0, CANBTR1, CANIDAC, CANIDAR0-CANIDAR7, and CANIDMR0-CANIDMR7 can be written only by the CPU when the MSCAN is in initialization mode.</p> <p>0 Running - The MSCAN operates normally.</p> <p>1 Initialization mode active - The MSCAN has entered initialization mode.</p> |

32.3.4 MSCAN Bus Timing Register 0 (MSCAN_CANBTR0)

The CANBTR0 register configures various CAN bus timing parameters of the MSCAN module.

NOTE

Write: Anytime in initialization mode (INITRQ = 1 and INITAK = 1)

Address: 4002_4000h base + 2h offset = 4002_4002h

| | | | | | | | | |
|-------|-----|---|-----|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | SJW | | BRP | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANBTR0 field descriptions

| Field | Description |
|------------|---|
| 7–6 SJW | <p>Synchronization Jump Width</p> <p>The synchronization jump width defines the maximum number of time quanta (Tq) clock cycles a bit can be shortened or lengthened to achieve resynchronization to data transitions on the CAN bus.</p> <p>00 1 Tq clock cycle. 01 2 Tq clock cycles. 10 3 Tq clock cycle. 11 4 Tq clock cycles.</p> |
| BRP | <p>Baud Rate Prescaler</p> <p>These bits determine the time quanta (Tq) clock which is used to build up the bit timing.</p> <p>000000 1 000001 2 000010 000011 111110 63 111111 64</p> |

32.3.5 MSCAN Bus Timing Register 1 (MSCAN_CANBTR1)

The CANBTR1 register configures various CAN bus timing parameters of the MSCAN module.

NOTE

Write: Anytime in initialization mode (INITRQ = 1 and INITAK = 1)

Memory map and register definition

Address: 4002_4000h base + 3h offset = 4002_4003h

| | | | | | | | | |
|-------|------|-------|---|---|-------|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | SAMP | TSEG2 | | | TSEG1 | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANBTR1 field descriptions

| Field | Description |
|--------------|--|
| 7 SAMP | <p>Sampling</p> <p>This bit determines the number of CAN bus samples taken per bit time.</p> <p>If SAMP = 0, the resulting bit value is equal to the value of the single bit positioned at the sample point. If SAMP = 1, the resulting bit value is determined by using majority rule on the three total samples. For higher bit rates, it is recommended that only one sample is taken per bit time (SAMP = 0).</p> <p>0 One sample per bit. 1 Three samples per bit. In this case, PHASE_SEG1 must be at least 2 time quanta (Tq).</p> |
| 6–4 TSEG2 | <p>Time Segment 2</p> <p>Time segments within the bit time fix the number of clock cycles per bit time and the location of the sample point.</p> <p>000 1 Tq clock cycle (not valid) 001 2 Tq clock cycles 010 3 Tq clock cycles 011 4 Tq clock cycles 100 5 Tq clock cycles 101 6 Tq clock cycles 110 7 Tq clock cycles 111 8 Tq clock cycles</p> |
| TSEG1 | <p>Time Segment 1</p> <p>Time segments within the bit time fix the number of clock cycles per bit time and the location of the sample point.</p> <p>The bit time is determined by the oscillator frequency, the baud rate prescaler, and the number of time quanta (Tq) clock cycles per bit.</p> <p>Bit time = (1 + timesegment1 + timesegment2) * (Prescaler value) / f_{CANCLK}</p> <p>0000 1 Tq clock cycle (not valid) 0001 2 Tq clock cycles (not valid) 0010 3 Tq clock cycles (not valid) 0011 4 Tq clock cycles 1110 15 Tq clock cycles 1111 16 Tq clock cycles</p> |

32.3.6 MSCAN Receiver Flag Register (MSCAN_CANRFLG)

A flag can be cleared only by software (writing a 1 to the corresponding bit position) when the condition which caused the setting is no longer valid. Every flag has an associated interrupt enable bit in the CANRIER register.

NOTE

Write: Anytime when not in initialization mode, except RSTAT[1:0] and TSTAT[1:0] flags which are read-only; write of 1 clears flag; write of 0 is ignored.

The CANRFLG register is held in the reset state when the initialization mode is active (INITRQ = 1 and INITAK = 1). This register is writable again as soon as the initialization mode is exited (INITRQ = 0 and INITAK = 0).

Address: 4002_4000h base + 4h offset = 4002_4004h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|-------|---|-------|---|-------|-----|
| Read | WUPIF | CSCIF | RSTAT | | TSTAT | | OVRIF | RXF |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANRFLG field descriptions

| Field | Description |
|--------------|---|
| 7 WUPIF | <p>Wake-Up Interrupt Flag</p> <p>If the MSCAN detects CAN bus activity while in sleep mode and CANTCTL0[WUPE] = 1, the module will set WUPIF. If not masked, a wake-up interrupt is pending while this flag is set.</p> <p>0 No wakeup activity observed while in sleep mode. 1 MSCAN detected activity on the CAN bus and requested wakeup.</p> |
| 6 CSCIF | <p>CAN Status Change Interrupt Flag</p> <p>This flag is set when the MSCAN changes its current CAN bus status due to the actual value of the transmit error counter (TEC) and the receive error counter (REC). An additional 4-bit (RSTAT[1:0], TSTAT[1:0]) status register, which is split into separate sections for TEC/REC, informs the system on the actual CAN bus status. If not masked, an error interrupt is pending while this flag is set. CSCIF provides a blocking interrupt. That guarantees that the receiver/transmitter status bits (RSTAT/TSTAT) are only updated when no CAN status change interrupt is pending. If the TECs/RECs change their current value after the CSCIF is asserted, which would cause an additional state change in the RSTAT/TSTAT bits, these bits keep their status until the current CSCIF interrupt is cleared again.</p> <p>0 No change in CAN bus status occurred since last interrupt. 1 MSCAN changed current CAN bus status.</p> |
| 5-4 RSTAT | Receiver Status |

Table continues on the next page...

MSCAN_CANRFLG field descriptions (continued)

| Field | Description |
|--------------|--|
| | <p>The values of the error counters control the actual CAN bus status of the MSCAN. As soon as the status change interrupt flag (CSCIF) is set, these bits indicate the appropriate receiver related CAN bus status of the MSCAN.</p> <p>NOTE: This field is not affected by initialization mode.</p> <p>00 RxOK: $0 \leq \text{receive error counter} < 96$ 01 RxWRN: $96 \leq \text{receive error counter} < 128$ 10 RxERR: $128 \leq \text{receive error counter}$ 11 Bus-off: $256 \leq \text{transmit error counter}$ (Redundant Information for the most critical CAN bus status which is "bus-off". This only occurs if the Tx error counter exceeds a number of 255 errors. Bus-off affects the receiver state. As soon as the transmitter leaves its bus-off state the receiver state skips to RxOK too. Refer also to TSTAT[1:0] coding in this register.)</p> |
| 3–2 TSTAT | <p>Transmitter Status</p> <p>The values of the error counters control the actual CAN bus status of the MSCAN. As soon as the status change interrupt flag (CSCIF) is set, these bits indicate the appropriate transmitter related CAN bus status of the MSCAN.</p> <p>NOTE: This field is not affected by initialization mode.</p> <p>00 TxOK: $0 \leq \text{transmit error counter} < 96$ 01 TxWRN: $96 \leq \text{transmit error counter} < 128$ 10 TxERR: $128 \leq \text{transmit error counter} < 256$ 11 Bus-off: $256 \leq \text{transmit error counter}$</p> |
| 1 OVRIF | <p>Overrun Interrupt Flag</p> <p>This flag is set when a data overrun condition occurs. If not masked, an error interrupt is pending while this flag is set.</p> <p>0 No data overrun condition. 1 A data overrun detected.</p> |
| 0 RXF | <p>Receive Buffer Full Flag</p> <p>RXF is set by the MSCAN when a new message is shifted in the receiver FIFO. This flag indicates whether the shifted buffer is loaded with a correctly received message (matching identifier, matching cyclic redundancy code (CRC) and no other errors detected). After the CPU has read that message from the RxFG buffer in the receiver FIFO, the RXF flag must be cleared to release the buffer. A set RXF flag prohibits the shifting of the next FIFO entry into the foreground buffer (RxFG). If not masked, a receive interrupt is pending while this flag is set.</p> <p>NOTE: To ensure data integrity, do not read the receive buffer registers while the RXF flag is cleared. For MCUs with dual CPUs, reading the receive buffer registers while the RXF flag is cleared may result in a CPU fault condition.</p> <p>0 No new message available within the RxFG. 1 The receiver FIFO is not empty. A new message is available in the RxFG.</p> |

32.3.7 MSCAN Receiver Interrupt Enable Register (MSCAN_CANRIER)

This register contains the interrupt enable bits for the interrupt flags described in the CANRFLG register.

NOTE

The CANRIER register is held in the reset state when the initialization mode is active (INITRQ=1 and INITAK=1). This register is writable when not in initialization mode (INITRQ=0 and INITAK=0).

The RSTATE[1:0], TSTATE[1:0] bits are not affected by initialization mode.

Address: 4002_4000h base + 5h offset = 4002_4005h

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|--------|---|--------|---|-------|-------|
| Read | WUPIE | CSCIE | RSTATE | | TSTATE | | OVRIE | RXFIE |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANRIER field descriptions

| Field | Description |
|---------------|--|
| 7 WUPIE | <p>WakeUp Interrupt Enable</p> <p>WUPIE and WUPE must both be enabled if the recovery mechanism from stop or wait is required.</p> <p>0 No interrupt request is generated from this event. 1 A wake-up event causes a Wake-Up interrupt request.</p> |
| 6 CSCIE | <p>CAN Status Change Interrupt Enable</p> <p>0 No interrupt request is generated from this event. 1 A CAN Status Change event causes an error interrupt request.</p> |
| 5-4 RSTATE | <p>Receiver Status Change Enable</p> <p>These RSTAT enable bits control the sensitivity level in which receiver state changes are causing CSCIF interrupts. Independent of the chosen sensitivity level the RSTAT flags continue to indicate the actual receiver state and are only updated if no CSCIF interrupt is pending.</p> <p>00 Do not generate any CSCIF interrupt caused by receiver state changes. 01 Generate CSCIF interrupt only if the receiver enters or leaves "bus-off" state. Discard other receiver state changes for generating CSCIF interrupt. 10 Generate CSCIF interrupt only if the receiver enters or leaves "RxErr" or "bus-off"¹ state. Discard other receiver state changes for generating CSCIF interrupt. 11 Generate CSCIF interrupt on all state changes.</p> |
| 3-2 TSTATE | <p>Transmitter Status Change Enable</p> |

Table continues on the next page...

MSCAN_CANRIER field descriptions (continued)

| Field | Description |
|------------|--|
| | These TSTAT enable bits control the sensitivity level in which transmitter state changes are causing CSCIF interrupts. Independent of the chosen sensitivity level, the TSTAT flags continue to indicate the actual transmitter state and are only updated if no CSCIF interrupt is pending. |
| | 00 Do not generate any CSCIF interrupt caused by transmitter state changes. |
| | 01 Generate CSCIF interrupt only if the transmitter enters or leaves "bus-off" state. Discard other transmitter state changes for generating CSCIF interrupt. |
| | 10 Generate CSCIF interrupt only if the transmitter enters or leaves "TxErr" or "bus-off" state. Discard other transmitter state changes for generating CSCIF interrupt. |
| | 11 Generate CSCIF interrupt on all state changes. |
| 1 OVRIE | Overrun Interrupt Enable 0 No interrupt request is generated from this event. 1 An overrun event causes an error interrupt request. |
| 0 RXFIE | Receiver Full Interrupt Enable 0 No interrupt request is generated from this event. 1 A receive buffer full (successful message reception) event causes a receiver interrupt request. |

1. Bus-off state is only defined for transmitters by the CAN standard (see Bosch CAN 2.0A/B protocol specification). Because the only possible state change for the transmitter from bus-off to TxOK also forces the receiver to skip its current state to RxOK, the coding of the RXSTAT[1:0] flags define an additional bus-off state for the receiver

32.3.8 MSCAN Transmitter Flag Register (MSCAN_CANTFLG)

The transmit buffer empty flags each have an associated interrupt enable bit in the CANTIER register.

NOTE

Write: Anytime when not in initialization mode; write of 1 clears flag, write of 0 is ignored.

The CANTFLG register is held in the reset state when the initialization mode is active (INITRQ = 1 and INITAK = 1). This register is writable when not in initialization mode (INITRQ = 0 and INITAK = 0).

Address: 4002_4000h base + 6h offset = 4002_4006h

| | | | | | | | | |
|-------|---|---|---|---|---|-----|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | TXE | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 |

MSCAN_CANTFLG field descriptions

| Field | Description |
|-----------------|--|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| TXE | <p>Transmitter Buffer Empty</p> <p>This flag indicates that the associated transmit message buffer is empty, and thus not scheduled for transmission. The CPU must clear the flag after a message is set up in the transmit buffer and is due for transmission. The MSCAN sets the flag after the message is sent successfully. The flag is also set by the MSCAN when the transmission request is successfully aborted due to a pending abort request. If not masked, a transmit interrupt is pending while this flag is set.</p> <p>Clearing a TXEx flag also clears the corresponding ABTAKx. When a TXEx flag is set, the corresponding ABTRQx bit is cleared.</p> <p>When listen-mode is active, the TXEx flags cannot be cleared and no transmission is started.</p> <p>Read and write accesses to the transmit buffer will be blocked, if the corresponding TXEx bit is cleared (TXEx = 0) and the buffer is scheduled for transmission.</p> <p>0 The associated message buffer is full (loaded with a message due for transmission). 1 The associated message buffer is empty (not scheduled).</p> |

32.3.9 MSCAN Transmitter Interrupt Enable Register (MSCAN_CANTIER)

This register contains the interrupt enable bits for the transmit buffer empty interrupt flags.

NOTE

The CANTIER register is held in the reset state when the initialization mode is active (INITRQ = 1 and INITAK = 1).
This register is writable when not in initialization mode (INITRQ = 0 and INITAK = 0).

Write at anytime when not in initialization mode.

Address: 4002_4000h base + 7h offset = 4002_4007h

| | | | | | | | | |
|-------|---|---|---|---|---|-------|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | TXEIE | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANTIER field descriptions

| Field | Description |
|-----------------|---|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| TXEIE | Transmitter Empty Interrupt Enable |

Table continues on the next page...

MSCAN_CANTIER field descriptions (continued)

| Field | Description |
|-------|--|
| 0 | No interrupt request is generated from this event. |
| 1 | A transmitter empty (transmit buffer available for transmission) event causes a transmitter empty interrupt request. |

32.3.10 MSCAN Transmitter Message Abort Request Register (MSCAN_CANTARQ)

The CANTARQ register allows abort request of queued messages.

NOTE

Write: Anytime when not in initialization mode

The CANTARQ register is held in the reset state when the initialization mode is active (INITRQ = 1 and INITAK = 1).

This register is writable when not in initialization mode (INITRQ = 0 and INITAK = 0).

Address: 4002_4000h base + 8h offset = 4002_4008h

| | | | | | | | | |
|-------|---|---|---|---|-------|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | ABTRQ | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANTARQ field descriptions

| Field | Description |
|-----------------|--|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ABTRQ | <p>Abort Request</p> <p>The CPU sets the ABTRQx bit to request that a scheduled message buffer (TXEx = 0) be aborted. The MSCAN grants the request if the message has not already started transmission, or if the transmission is not successful (lost arbitration or error). When a message is aborted, the associated TXE and abort acknowledge flags ABTAK, are set and a transmit interrupt occurs if enabled. The CPU cannot reset ABTRQx. ABTRQx is reset whenever the associated TXE flag is set.</p> <p>0 No abort request. 1 Abort request pending.</p> |

32.3.11 MSCAN Transmitter Message Abort Acknowledge Register (MSCAN_CANTAACK)

The CANTAACK register indicates the successful abort of a queued message, if requested by the appropriate bits in the CANTARQ register.

NOTE

The CANTAACK register is held in the reset state when the initialization mode is active (INITRQ = 1 and INITAK = 1).

Address: 4002_4000h base + 9h offset = 4002_4009h

| | | | | | | | | |
|-------|---|---|---|---|---|-------|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | ABTAK | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANTAACK field descriptions

| Field | Description |
|-----------------|---|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| ABTAK | Abort Acknowledge This flag acknowledges that a message was aborted due to a pending abort request from the CPU. After a particular message buffer is flagged empty, this flag can be used by the application software to identify whether the message was aborted successfully or was sent anyway. The ABTAKx flag is cleared whenever the corresponding TXE flag is cleared. 0 The message was not aborted. 1 The message was aborted. |

32.3.12 MSCAN Transmit Buffer Selection Register (MSCAN_CANTBSEL)

The CANTBSEL register allows the selection of the actual transmit message buffer, which then will be accessible in the CANTXFG register space.

NOTE

Read: Find the lowest ordered bit set to 1, all other bits will be read as 0.

Write: Anytime when not in initialization mode

The CANTBSEL register is held in the reset state when the initialization mode is active (INITRQ = 1 and INITAK=1). This register is writable when not in initialization mode (INITRQ = 0 and INITAK = 0).

The following gives a short programming example of the usage of the CANTBSEL register:

To get the next available transmit buffer, application software must read the CANTFLG register and write this value back into the CANTBSEL register. In this example Tx buffers TX1 and TX2 are available. The value read from CANTFLG is therefore 0b0000_0110. When writing this value back to CANTBSEL, the Tx buffer TX1 is selected in the CANTXFG because the lowest numbered bit set to 1 is at bit position 1. Reading back this value out of CANTBSEL results in 0b0000_0010, because only the lowest numbered bit position set to 1 is presented. This mechanism eases the application software's selection of the next available Tx buffer.

If all transmit message buffers are deselected, no accesses are allowed to the CANTXFG registers.

Address: 4002_4000h base + Ah offset = 4002_400Ah

| | | | | | | | | |
|-------|---|---|---|---|---|---|----|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | | TX | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANTBSEL field descriptions

| Field | Description |
|-----------------|--|
| 7–3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| TX | <p>Transmit Buffer Select</p> <p>The lowest numbered bit places the respective transmit buffer in the CANTXFG register space (e.g., TX1 = 1 and TX0 = 1 selects transmit buffer TX0; TX1 = 1 and TX0 = 0 selects transmit buffer TX1). Read and write accesses to the selected transmit buffer will be blocked, if the corresponding TXEx bit is cleared and the buffer is scheduled for transmission.</p> <p>0 The associated message buffer is deselected.</p> <p>1 The associated message buffer is selected, if lowest numbered bit.</p> |

32.3.13 MSCAN Identifier Acceptance Control Register (MSCAN_CANIDAC)

The CANIDAC register is used for identifier acceptance control as described below.

NOTE

Write: Anytime in initialization mode (INITRQ = 1 and INITAK = 1), except bits IDHITx, which are read-only

Address: 4002_4000h base + Bh offset = 4002_400Bh

| | | | | | | | | |
|-------|---|---|------|---|---|-------|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | IDAM | | 0 | IDHIT | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANIDAC field descriptions

| Field | Description |
|-----------------|---|
| 7–6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5–4 IDAM | Identifier Acceptance Mode The CPU sets these flags to define the identifier acceptance filter organization. In filter closed mode, no message is accepted such that the foreground buffer is never reloaded. 00 Two 32-bit acceptance filters. 01 Four 16-bit acceptance filters. 10 Eight 8-bit acceptance filters. 11 Filter closed. |
| 3 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| IDHIT | Identifier Acceptance Hit Indicator The MSCAN sets these flags to indicate an identifier acceptance hit. The IDHIT indicators are always related to the message in the foreground buffer (RxFG). When a message gets shifted into the foreground buffer of the receiver FIFO the indicators are updated as well. 000 Filter 0 hit. 001 Filter 1 hit. 010 Filter 2 hit. 011 Filter 3 hit. 100 Filter 4 hit. 101 Filter 5 hit. 110 Filter 6 hit. 111 Filter 7 hit. |

32.3.14 MSCAN Miscellaneous Register (MSCAN_CANMISC)

This register provides additional features.

NOTE

Write: Anytime; write of '1' clears flag; write of '0' ignored.

Memory map and register definition

Address: 4002_4000h base + Dh offset = 4002_400Dh

| | | | | | | | | |
|-------|---|---|---|---|---|---|---|--------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | 0 | | | | | | | BOHOLD |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANMISC field descriptions

| Field | Description |
|-----------------|---|
| 7–1 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 0 BOHOLD | Bus-off State Hold Until User Request If BORM is set in MSCAN Control Register 1 (CANCTL1), this bit indicates whether the module has entered the bus-off state. Clearing this bit requests the recovery from bus-off. 0 Module is not bus-off or recovery has been requested by user in bus-off state. 1 Module is bus-off and holds this state until user request. |

32.3.15 MSCAN Receive Error Counter (MSCAN_CANRXERR)

This register reflects the status of the MSCAN receive error counter.

NOTE

Read: Only when in sleep mode (SLPRQ = 1 and SLPK = 1) or initialization mode (INITRQ = 1 and INITAK = 1).

Reading this register when in any other mode other than sleep or initialization mode may return an incorrect value. For MCUs with dual CPUs, this may result in a CPU fault condition.

Address: 4002_4000h base + Eh offset = 4002_400Eh

| | | | | | | | | |
|-------|-------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | RXERR | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANRXERR field descriptions

| Field | Description |
|-------|--|
| RXERR | Receive Error Counter This field is read only in sleep mode (SLPRQ = 1 and SLPK = 1) or initialization mode (INITRQ = 1 and INITAK = 1) |

32.3.16 MSCAN Transmit Error Counter (MSCAN_CANTXERR)

This register reflects the status of the MSCAN transmit error counter.

NOTE

Reading this register when in any other mode other than sleep or initialization mode may return an incorrect value. For MCUs with dual CPUs, this may result in a CPU fault condition.

Address: 4002_4000h base + Fh offset = 4002_400Fh

| | | | | | | | | |
|-------|-------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TXERR | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANTXERR field descriptions

| Field | Description |
|-------|---|
| TXERR | Transmit Error Counter This field is read only in sleep mode (SLPRQ = 1 and SLPK = 1) or initialization mode (INITRQ = 1 and INITAK = 1) |

32.3.17 MSCAN Identifier Acceptance Register n of First Bank (MSCAN_CANIDAR_n)

On reception, each message is written into the background receive buffer. The CPU is only signalled to read the message if it passes the criteria in the identifier acceptance and identifier mask registers (accepted); otherwise, the message is overwritten by the next message (dropped).

The acceptance registers of the MSCAN are applied on the REIDR0-REIDR3 registers for the extendard identifiers and RSIDR0-RSIDR1 registers for the standard identifiers of incoming messages in a bit by bit manner.

For extended identifiers, all four acceptance and mask registers are applied. For standard identifiers, only the first two (CANIDAR0/1, CANIDMR0/1) are applied.

Address: 4002_4000h base + 10h offset + (1d × i), where i=0d to 3d

| | | | | | | | | |
|-------|----|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | AC | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANIDAR_n field descriptions

| Field | Description |
|-------|---|
| AC | <p>Acceptance Code Bits</p> <p>AC[7:0] comprise a user-defined sequence of bits with which the corresponding bits of the related identifier register (RSIDR_n or REIDR_n) of the receive message buffer are compared. The result of this comparison is then masked with the corresponding identifier mask register.</p> |

32.3.18 MSCAN Identifier Mask Register n of First Bank (MSCAN_CANIDMR_n)

The identifier mask register specifies which of the corresponding bits in the identifier acceptance register are relevant for acceptance filtering. To receive standard identifiers in 32-bit filter mode, it is required to program the last three bits (AM[2:0]) in the mask registers CANIDMR1 and CANIDMR5 to "don't care." To receive standard identifiers in 16 bit filter mode, it is required to program the last three bits (AM[2:0]) in the mask registers CANIDMR1, CANIDMR3, CANIDMR5, and CANIDMR7 to "don't care."

Address: 4002_4000h base + 14h offset + (1d × i), where i=0d to 3d

| | | | | | | | | |
|-------|----|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | AM | | | | | | | |
| Write | | | | | | | | |
| Reset | | | | | | | | |
| | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANIDMR_n field descriptions

| Field | Description |
|-------|---|
| AM | <p>Acceptance Mask Bits</p> <p>If a particular bit in this register is cleared, this indicates that the corresponding bit in the identifier acceptance register must be the same as its identifier bit before a match is detected. The message is accepted if all such bits match. If a bit is set, it indicates that the state of the corresponding bit in the identifier acceptance register does not affect whether or not the message is accepted.</p> <p>0 Match corresponding acceptance code register and identifier bits. 1 Ignore corresponding acceptance code register bit.</p> |

32.3.19 MSCAN Identifier Acceptance Register n of Second Bank (MSCAN_CANIDAR_n)

On reception, each message is written into the background receive buffer. The CPU is only signalled to read the message if it passes the criteria in the identifier acceptance and identifier mask registers (accepted); otherwise, the message is overwritten by the next message (dropped).

The acceptance registers of the MSCAN are applied on the REIDR0-REIDR3 registers for the extendard identifiers and RSIDR0-RSIDR1 registers for the standard identifiers of incoming messages in a bit by bit manner.

For extended identifiers, all four acceptance and mask registers are applied. For standard identifiers, only the first two (CANIDAR4/5, CANIDMR4/5) are applied.

Address: 4002_4000h base + 18h offset + (1d × i), where i=0d to 3d

| | | | | | | | | |
|-------|----|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | AC | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANIDAR_n field descriptions

| Field | Description |
|-------|---|
| AC | <p>Acceptance Code Bits</p> <p>AC[7:0] comprise a user-defined sequence of bits with which the corresponding bits of the related identifier register (RSIDR_n or REIDR_n) of the receive message buffer are compared. The result of this comparison is then masked with the corresponding identifier mask register.</p> |

32.3.20 MSCAN Identifier Mask Register n of Second Bank (MSCAN_CANIDMRn)

The identifier mask register specifies which of the corresponding bits in the identifier acceptance register are relevant for acceptance filtering. To receive standard identifiers in 32 bit filter mode, it is required to program the last three bits (AM[2:0]) in the mask registers CANIDMR1 and CANIDMR5 to "don't care." To receive standard identifiers in 16 bit filter mode, it is required to program the last three bits (AM[2:0]) in the mask registers CANIDMR1, CANIDMR3, CANIDMR5, and CANIDMR7 to "don't care."

Address: 4002_4000h base + 1Ch offset + (1d × i), where i=0d to 3d

| | | | | | | | | |
|-------|----|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | AM | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

MSCAN_CANIDMRn field descriptions

| Field | Description |
|-------|---|
| AM | <p>Acceptance Mask Bits</p> <p>If a particular bit in this register is cleared, this indicates that the corresponding bit in the identifier acceptance register must be the same as its identifier bit before a match is detected. The message is accepted if all such bits match. If a bit is set, it indicates that the state of the corresponding bit in the identifier acceptance register does not affect whether or not the message is accepted.</p> <p>0 Match corresponding acceptance code register and identifier bits. 1 Ignore corresponding acceptance code register bit.</p> |

32.3.21 Receive Extended Identifier Register 0 (MSCAN_REIDR0)

The identifier registers for an extended format identifier consist of a total of 32 bits: REID[28:0], RSRR, RIDE, and RRTR.

Address: 4002_4000h base + 20h offset = 4002_4020h

| | | | | | | | | |
|-------|---------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | REID28_REID21 | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_REIDR0 field descriptions

| Field | Description |
|---------------|---|
| REID28_REID21 | Extended Format Identifier The extended identifiers consist of 29 bits (REID[28:0]) for the extended format. REID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.22 Receive Standard Identifier Register 0 (MSCAN_RSIDR0)

The identifier registers for a standard format identifier consist of a total of 13 bits: RID[10:0], RRTR, and RSIDE.

Address: 4002_4000h base + 20h offset = 4002_4020h

| | | | | | | | | |
|-------|--------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | RSID10_RSID3 | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_RSIDR0 field descriptions

| Field | Description |
|--------------|--|
| RSID10_RSID3 | Standard Format Identifier The identifiers consist of 11 bits (RSID[10:0]) for the standard format. RSID10 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.23 Receive Extended Identifier Register 1 (MSCAN_REIDR1)

The identifier registers for an extended format identifier consist of a total of 32 bits: REID[28:0], RSRR, REIDE, and RRTR.

Address: 4002_4000h base + 21h offset = 4002_4021h

| | | | | | | | | |
|-------|---------------|----|----|----|------|-------|---------------|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | REID20_REID18 | | | | RSRR | REIDE | REID17_REID15 | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_REIDR1 field descriptions

| Field | Description |
|----------------------|---|
| 7-5 REID20_REID18 | Extended Format Identifier 20-18 The identifiers consist of 29 bits (REID[28:0]) for the extended format. EID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |
| 4 RSRR | Substitute Remote Request This fixed recessive bit is used only in extended format. It must be set to 1 by the user for transmission buffers and is stored as received on the CAN bus for receive buffers. |
| 3 REIDE | ID Extended This flag indicates whether the extended or standard identifier format is applied in this buffer. In the case of a receive buffer, the flag is set as received and indicates to the CPU how to process the buffer identifier registers. In the case of a transmit buffer, the flag indicates to the MSCAN what type of identifier to send. 0 Standard format (11 bit). 1 Extended format (29 bit). |
| REID17_REID15 | Extended Format Identifier 17-15 The identifiers consist of 29 bits (REID[28:0]) for the extended format. RID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.24 Receive Standard Identifier Register 1 (MSCAN_RSIDR1)

The identifier registers for a standard format identifier consist of a total of 13 bits: RSID[10:0], RRTR, and REIDE.

Address: 4002_4000h base + 21h offset = 4002_4021h

| | | | | | | | | |
|-------|-------------|----|----|-------|-------|----------|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | RSID2_RSID0 | | | RSRTR | RSIDE | Reserved | | |
| Write | | | | | | Reserved | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_RSIDR1 field descriptions

| Field | Description |
|--------------------|--|
| 7-5 RSID2_RSID0 | Standard Format Identifier 2-0 The identifiers consist of 11 bits (RID[10:0]) for the standard format. RID10 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |
| 4 RSRTR | Remote Transmission Request |

Table continues on the next page...

MSCAN_RSIDR1 field descriptions (continued)

| Field | Description |
|------------|---|
| | <p>This flag reflects the status of the Remote Transmission Request bit in the CAN frame. In the case of a receive buffer, it indicates the status of the received frame and supports the transmission of an answering frame in software. In the case of a transmit buffer, this flag defines the setting of the RRTR bit to be sent.</p> <p>0 Data frame. 1 Remote frame.</p> |
| 3 RSIDE | <p>ID Extended</p> <p>This flag indicates whether the extended or standard identifier format is applied in this buffer. In the case of a receive buffer, the flag is set as received and indicates to the CPU how to process the buffer identifier registers. In the case of a transmit buffer, the flag indicates to the MSCAN what type of identifier to send.</p> <p>0 Standard format (11 bit). 1 Extended format (29 bit).</p> |
| Reserved | This field is reserved. |

32.3.25 Receive Extended Identifier Register 2 (MSCAN_REIDR2)

The identifier registers for an extended format identifier consist of a total of 32 bits: REID[28:0], RSRR, REIDE, and RRTR.

Address: 4002_4000h base + 22h offset = 4002_4022h

| | | | | | | | | |
|-------|--------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | REID14_REID7 | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_REIDR2 field descriptions

| Field | Description |
|--------------|--|
| REID14_REID7 | <p>Extended Format Identifier 14-7</p> <p>The identifiers consist of 29 bits (REID[28:0]) for the extended format. REID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number.</p> |

32.3.26 Receive Extended Identifier Register 3 (MSCAN_REIDR3)

The identifier registers for an extended format identifier consist of a total of 32 bits: REID[28:0], RSRR, REIDE, and RRTR.

Address: 4002_4000h base + 23h offset = 4002_4023h

| | | | | | | | | |
|-------|-------------|----|----|----|----|----|----|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | REID6_REID0 | | | | | | | RERTR |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_REIDR3 field descriptions

| Field | Description |
|--------------------|--|
| 7–1 REID6_REID0 | Extended Format Identifier 6-0 The identifiers consist of 29 bits (REID[28:0]) for the extended format. REID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |
| 0 RERTR | Remote Transmission Request This flag reflects the status of the remote transmission request bit in the CAN frame. In the case of a receive buffer, it indicates the status of the received frame and supports the transmission of an answering frame in software. In the case of a transmit buffer, this flag defines the setting of the RTR bit to be sent. 0 Data frame. 1 Remote frame. |

32.3.27 Receive Extended Data Segment Register N (MSCAN_REDSRn)

The eight data segment registers, each with bits RDB[7:0], contain the data to be received. The number of bytes to be received is determined by the data length code in the corresponding RDLR register.

Address: 4002_4000h base + 24h offset + (1d × i), where i=0d to 7d

| | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | RDB | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_REDSRn field descriptions

| Field | Description |
|-------|----------------------------------|
| RDB | Data Bits Data to be received |

32.3.28 Receive Data Length Register (MSCAN_RDLR)

This register keeps the data length field of the CAN frame.

Address: 4002_4000h base + 2Ch offset = 4002_402Ch

| | | | | | | | | |
|-------|----------|----|----|----|------|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | Reserved | | | | RDLC | | | |
| Write | Reserved | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_RDLR field descriptions

| Field | Description | | | | | | | | | | | | | | | | | | | | |
|-----------------|--|------|---|------|---|------|---|------|---|------|---|------|---|------|---|------|---|------|---|--------|----------|
| 7–4 Reserved | This field is reserved. | | | | | | | | | | | | | | | | | | | | |
| RDLC | <p>Data Length Code Bits</p> <p>The data length code contains the number of bytes (data byte count) of the respective message. During the transmission of a remote frame, the data length code is transmitted as programmed while the number of transmitted data bytes is always 0. The data byte count ranges from 0 to 8 for a data frame.</p> <table> <tr><td>0000</td><td>0</td></tr> <tr><td>0001</td><td>1</td></tr> <tr><td>0010</td><td>2</td></tr> <tr><td>0011</td><td>3</td></tr> <tr><td>0100</td><td>4</td></tr> <tr><td>0101</td><td>5</td></tr> <tr><td>0110</td><td>6</td></tr> <tr><td>0111</td><td>7</td></tr> <tr><td>1000</td><td>8</td></tr> <tr><td>others</td><td>Reserved</td></tr> </table> | 0000 | 0 | 0001 | 1 | 0010 | 2 | 0011 | 3 | 0100 | 4 | 0101 | 5 | 0110 | 6 | 0111 | 7 | 1000 | 8 | others | Reserved |
| 0000 | 0 | | | | | | | | | | | | | | | | | | | | |
| 0001 | 1 | | | | | | | | | | | | | | | | | | | | |
| 0010 | 2 | | | | | | | | | | | | | | | | | | | | |
| 0011 | 3 | | | | | | | | | | | | | | | | | | | | |
| 0100 | 4 | | | | | | | | | | | | | | | | | | | | |
| 0101 | 5 | | | | | | | | | | | | | | | | | | | | |
| 0110 | 6 | | | | | | | | | | | | | | | | | | | | |
| 0111 | 7 | | | | | | | | | | | | | | | | | | | | |
| 1000 | 8 | | | | | | | | | | | | | | | | | | | | |
| others | Reserved | | | | | | | | | | | | | | | | | | | | |

32.3.29 Receive Time Stamp Register High (MSCAN_RTSH)

If the TIME bit is enabled, the MSCAN will write a time stamp to the respective registers in the active receive buffer right after the EOF of a valid message on the CAN bus.

Memory map and register definition

The timer value, which is used for stamping, is taken from a free running internal CAN bit clock. A timer overrun is not indicated by the MSCAN. The timer is reset (all bits set to 0) during initialization mode. The CPU can only read the time stamp registers.

Address: 4002_4000h base + 2Eh offset = 4002_402Eh

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----|----|----|----|----|----|----|----|
| Read | RTS | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_RTSRH field descriptions

| Field | Description |
|-------|----------------------------------|
| RTS | Time Stamp Time stamp 7 to 0. |

32.3.30 Receive Time Stamp Register Low (MSCAN_RTSRL)

If the TIME bit is enabled, the MSCAN will write a time stamp to the respective registers in the active receive buffer right after the EOF of a valid message on the CAN bus.

The timer value, which is used for stamping, is taken from a free running internal CAN bit clock. A timer overrun is not indicated by the MSCAN. The timer is reset (all bits set to 0) during initialization mode. The CPU can only read the time stamp registers.

NOTE

This register can be read or write at anytime when TXEx flag is set and the corresponding transmit buffer is selected in CANTBSEL.

Address: 4002_4000h base + 2Fh offset = 4002_402Fh

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----|----|----|----|----|----|----|----|
| Read | RTS | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_RTSRL field descriptions

| Field | Description |
|-------|-------------|
| RTS | Time Stamp |

MSCAN_RTSRL field descriptions (continued)

| Field | Description |
|-------|---------------------|
| | Time stamp 15 to 8. |

32.3.31 Transmit Extended Identifier Register 0 (MSCAN_TEIDR0)

The identifier registers for an extended format identifier consist of a total of 32 bits: TEID[28:0], TSRR, TIDE, and TRTR.

Address: 4002_4000h base + 30h offset = 4002_4030h

| | | | | | | | | |
|-------|---------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TEID28_TEID21 | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TEIDR0 field descriptions

| Field | Description |
|---------------|---|
| TEID28_TEID21 | Extended Format Identifier The extended identifiers consist of 29 bits (TEID[28:0]) for the extended format. TEID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.32 Transmit Standard Identifier Register 0 (MSCAN_TSIDR0)

The identifier registers for a standard format identifier consist of a total of 13 bits: TID[10:0], TRTR, and TSIDE.

Address: 4002_4000h base + 30h offset = 4002_4030h

| | | | | | | | | |
|-------|--------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TSID10_TSID3 | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TSIDR0 field descriptions

| Field | Description |
|--------------|----------------------------|
| TSID10_TSID3 | Standard Format Identifier |

MSCAN_TSIDR0 field descriptions (continued)

| Field | Description |
|-------|--|
| | The identifiers consist of 11 bits (TSID[10:0]) for the standard format. TSID10 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.33 Transmit Extended Identifier Register 1 (MSCAN_TEIDR1)

The identifier registers for an extended format identifier consist of a total of 32 bits: TEID[28:0], TSRR, TEIDE, and TRTR.

Address: 4002_4000h base + 31h offset = 4002_4031h

| | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TEIDR1 field descriptions

| Field | Description |
|----------------------|---|
| 7–5 TEID20_TEID18 | Extended Format Identifier 20-18 The identifiers consist of 29 bits (TEID[28:0]) for the extended format. TEID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |
| 4 TSRR | Substitute Remote Request This fixed recessive bit is used only in extended format. It must be set to 1 by the user for transmission buffers and is stored as received on the CAN bus for receive buffers. |
| 3 TEIDE | ID Extended This flag indicates whether the extended or standard identifier format is applied in this buffer. In the case of a receive buffer, the flag is set as received and indicates to the CPU how to process the buffer identifier registers. In the case of a transmit buffer, the flag indicates to the MSCAN what type of identifier to send. 0 Standard format (11 bit). 1 Extended format (29 bit). |
| TEID17_TEID15 | Extended Format Identifier 17-15 The identifiers consist of 29 bits (TEID[28:0]) for the extended format. TID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.34 Transmit Standard Identifier Register 1 (MSCAN_TSIDR1)

The identifier registers for a standard format identifier consist of a total of 13 bits: TEID[10:0], TRTR, and TEIDE.

Address: 4002_4000h base + 31h offset = 4002_4031h

| | | | | | | | | |
|-------|-------------|----|----|-------|-------|----------|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TSID2_TSID0 | | | TSRTR | TSIDE | Reserved | | |
| Write | | | | | | Reserved | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TSIDR1 field descriptions

| Field | Description |
|--------------------|---|
| 7-5 TSID2_TSID0 | Standard Format Identifier 2-0 The identifiers consist of 11 bits (TID[10:0]) for the standard format. ID10 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |
| 4 TSRTR | Remote Transmission Request This flag reflects the status of the Remote Transmission Request bit in the CAN frame. In the case of a receive buffer, it indicates the status of the received frame and supports the transmission of an answering frame in software. In the case of a transmit buffer, this flag defines the setting of the TRTR bit to be sent. 0 Data frame. 1 Remote frame. |
| 3 TSIDE | ID Extended This flag indicates whether the extended or standard identifier format is applied in this buffer. In the case of a receive buffer, the flag is set as received and indicates to the CPU how to process the buffer identifier registers. In the case of a transmit buffer, the flag indicates to the MSCAN what type of identifier to send. 0 Standard format (11 bit). 1 Extended format (29 bit). |
| Reserved | This field is reserved. |

32.3.35 Transmit Extended Identifier Register 2 (MSCAN_TEIDR2)

The identifier registers for an extended format identifier consist of a total of 32 bits: TEID[28:0], TSRR, TEIDE, and TRTR.

Address: 4002_4000h base + 32h offset = 4002_4032h

| | | | | | | | | |
|-------|--------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TEID14_TEID7 | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TEIDR2 field descriptions

| Field | Description |
|--------------|---|
| TEID14_TEID7 | Extended Format Identifier 14-7 The identifiers consist of 29 bits (TEID[28:0]) for the extended format. TEID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

32.3.36 Transmit Extended Identifier Register 3 (MSCAN_TEIDR3)

The identifier registers for an extended format identifier consist of a total of 32 bits: TEID[28:0], TSRR, TEIDE, and TRTR.

Address: 4002_4000h base + 33h offset = 4002_4033h

| | | | | | | | | |
|-------|-------------|----|----|----|----|----|----|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TEID6_TEID0 | | | | | | | TERTR |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TEIDR3 field descriptions

| Field | Description |
|--------------------|--|
| 7-1 TEID6_TEID0 | Extended Format Identifier 6-0 The identifiers consist of 29 bits (TEID[28:0]) for the extended format. TEID28 is the most significant bit and is transmitted first on the CAN bus during the arbitration procedure. The priority of an identifier is defined to be highest for the smallest binary number. |

Table continues on the next page...

MSCAN_TEIDR3 field descriptions (continued)

| Field | Description |
|------------|---|
| 0 TERTR | Remote Transmission Request This flag reflects the status of the remote transmission request bit in the CAN frame. In the case of a receive buffer, it indicates the status of the received frame and supports the transmission of an answering frame in software. In the case of a transmit buffer, this flag defines the setting of the TRTR bit to be sent. 0 Data frame. 1 Remote frame. |

32.3.37 Transmit Extended Data Segment Register N (MSCAN_TEDSR_n)

The eight data segment registers, each with bits TDB[7:0], contain the data to be transmitted. The number of bytes to be transmitted is determined by the data length code in the corresponding TDLR register.

Address: 4002_4000h base + 34h offset + (1d × i), where i=0d to 7d

| | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TDB | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TEDSR_n field descriptions

| Field | Description |
|-------|--------------------------------------|
| TDB | Data Bits Data to be received |

32.3.38 Transmit Data Length Register (MSCAN_TDLR)

This register keeps the data length field of the CAN frame.

Address: 4002_4000h base + 3Ch offset = 4002_403Ch

| | | | | | | | | |
|-------|----------|----|----|----|------|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | Reserved | | | | TDLR | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TDLR field descriptions

| Field | Description | | | | | | | | | | | | | | | | | | | | |
|-----------------|--|------|---|------|---|------|---|------|---|------|---|------|---|------|---|------|---|------|---|--------|----------|
| 7–4 Reserved | This field is reserved. | | | | | | | | | | | | | | | | | | | | |
| TDLC | <p>Data Length Code Bits</p> <p>The data length code contains the number of bytes (data byte count) of the respective message. During the transmission of a remote frame, the data length code is transmitted as programmed while the number of transmitted data bytes is always 0. The data byte count ranges from 0 to 8 for a data frame.</p> <table> <tr><td>0000</td><td>0</td></tr> <tr><td>0001</td><td>1</td></tr> <tr><td>0010</td><td>2</td></tr> <tr><td>0011</td><td>3</td></tr> <tr><td>0100</td><td>4</td></tr> <tr><td>0101</td><td>5</td></tr> <tr><td>0110</td><td>6</td></tr> <tr><td>0111</td><td>7</td></tr> <tr><td>1000</td><td>8</td></tr> <tr><td>others</td><td>Reserved</td></tr> </table> | 0000 | 0 | 0001 | 1 | 0010 | 2 | 0011 | 3 | 0100 | 4 | 0101 | 5 | 0110 | 6 | 0111 | 7 | 1000 | 8 | others | Reserved |
| 0000 | 0 | | | | | | | | | | | | | | | | | | | | |
| 0001 | 1 | | | | | | | | | | | | | | | | | | | | |
| 0010 | 2 | | | | | | | | | | | | | | | | | | | | |
| 0011 | 3 | | | | | | | | | | | | | | | | | | | | |
| 0100 | 4 | | | | | | | | | | | | | | | | | | | | |
| 0101 | 5 | | | | | | | | | | | | | | | | | | | | |
| 0110 | 6 | | | | | | | | | | | | | | | | | | | | |
| 0111 | 7 | | | | | | | | | | | | | | | | | | | | |
| 1000 | 8 | | | | | | | | | | | | | | | | | | | | |
| others | Reserved | | | | | | | | | | | | | | | | | | | | |

32.3.39 Transmit Buffer Priority Register (MSCAN_TBPR)

This register defines the local priority of the associated message buffer. The local priority is used for the internal prioritization process of the MSCAN and is defined to be highest for the smallest binary number. The MSCAN implements the following internal prioritization mechanisms:

- All transmission buffers with a cleared TXEx flag participate in the prioritization immediately before the SOF (start of frame) is sent.
- The transmission buffer with the lowest local priority field wins the prioritization.

In cases of more than one buffer having the same lowest priority, the message buffer with the lower index number wins.

NOTE

This register can be read or write at anytime when TXEx flag is set and the corresponding transmit buffer is selected in CANTBSEL.

Address: 4002_4000h base + 3Dh offset = 4002_403Dh

| | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | PRIO | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TBPR field descriptions

| Field | Description |
|-------|--|
| PRI0 | Priority Local priority of the associated message buffer. |

32.3.40 Transmit Time Stamp Register High (MSCAN_TTSRH)

If the TIME bit is enabled, the MSCAN will write a time stamp to the respective registers in the active transmit buffer right after the EOF of a valid message on the CAN bus. In case of a transmission, the CPU can only read the time stamp after the respective transmit buffer has been flagged empty.

The timer value, which is used for stamping, is taken from a free running internal CAN bit clock. A timer overrun is not indicated by the MSCAN. The timer is reset (all bits set to 0) during initialization mode. The CPU can only read the time stamp registers.

NOTE

For transmit buffers, this register is read at anytime when TXEx flag is set and the corresponding transmit buffer is selected in CANTBSEL

Address: 4002_4000h base + 3Eh offset = 4002_403Eh

| | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TTS | | | | | | | |
| Write | | | | | | | | |
| Reset | x* | x* | x* | x* | x* | x* | x* | x* |

* Notes:

- x = Undefined at reset.

MSCAN_TTSRH field descriptions

| Field | Description |
|-------|----------------------------------|
| TTS | Time Stamp Time stamp 7 to 0. |

32.3.41 Transmit Time Stamp Register Low (MSCAN_TTSRL)

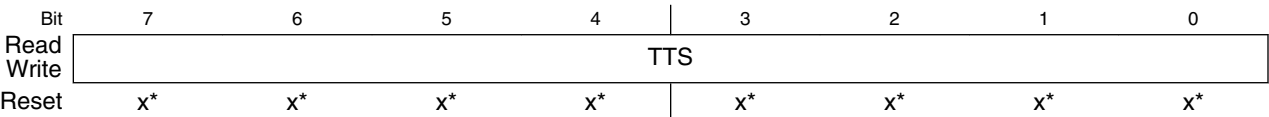
If the TIME bit is enabled, the MSCAN will write a time stamp to the respective registers in the active transmit buffer right after the EOF of a valid message on the CAN bus. In case of a transmission, the CPU can only read the time stamp after the respective transmit buffer has been flagged empty.

The timer value, which is used for stamping, is taken from a free running internal CAN bit clock. A timer overrun is not indicated by the MSCAN. The timer is reset (all bits set to 0) during initialization mode. The CPU can only read the time stamp registers.

NOTE

This register can be read or write at anytime when TXEx flag is set and the corresponding transmit buffer is selected in CANTBSEL.

Address: 4002_4000h base + 3Fh offset = 4002_403Fh



- * Notes:
- x = Undefined at reset.

MSCAN_TTSRL field descriptions

| Field | Description |
|-------|-----------------------------------|
| TTS | Time Stamp Time stamp 15 to 8. |

32.4 Functional description

32.4.1 Message storage

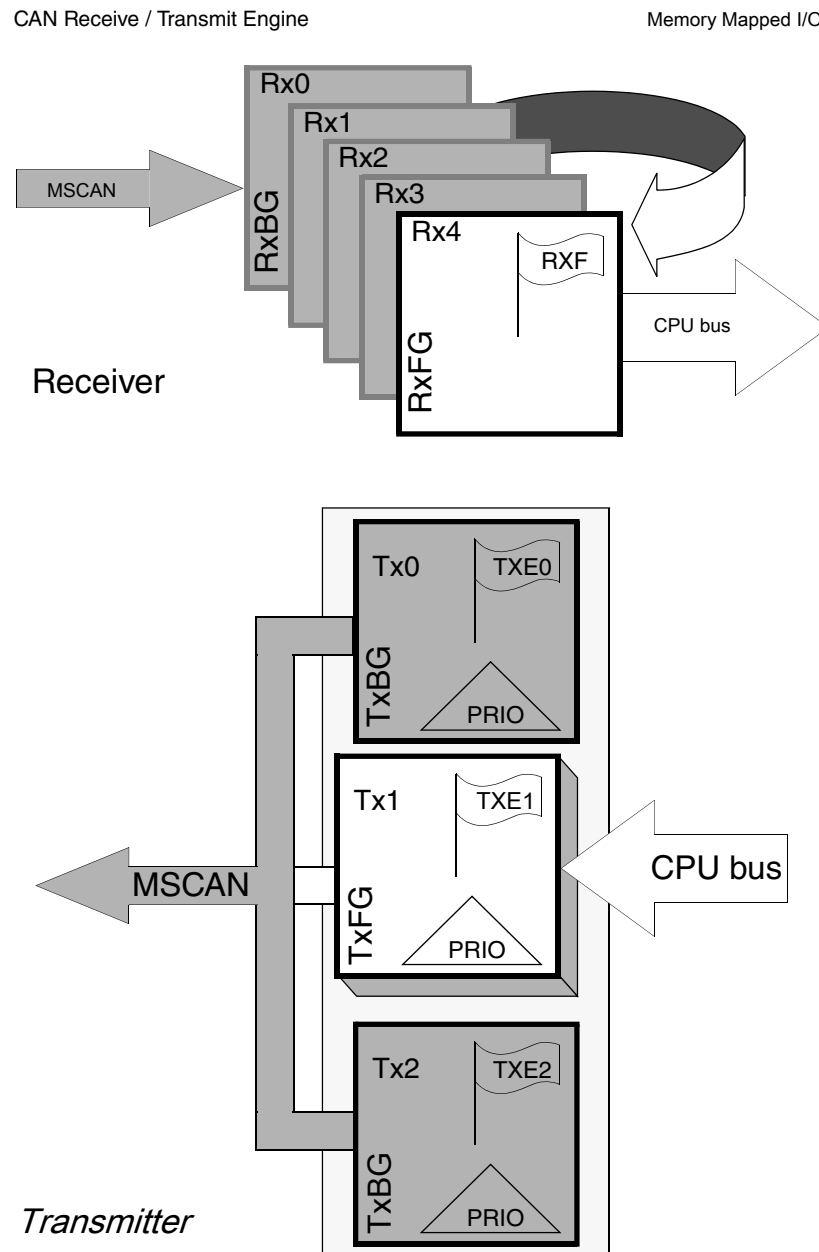


Figure 32-76. User model for message buffer organization

The MSCAN facilitates a sophisticated message storage system which addresses the requirements of a broad range of network applications.

32.4.2 Message transmit background

Modern application layer software is built upon two fundamental assumptions:

- Any CAN node is able to send out a stream of scheduled messages without releasing the CAN bus between the two messages. Such nodes arbitrate for the CAN bus immediately after sending the previous message and only release the CAN bus in case of lost arbitration.
- The internal message queue within any CAN node is organized such that the highest priority message is sent out first, if more than one message is ready to be sent.

The behavior described in the bullets above cannot be achieved with a single transmit buffer. That buffer must be reloaded immediately after the previous message is sent. This loading process lasts a finite amount of time and must be completed within the inter-frame sequence (IFS) to be able to send an uninterrupted stream of messages. Even if this is feasible for limited CAN bus speeds, it requires that the CPU reacts with short latencies to the transmit interrupt.

A double buffer scheme de-couples the reloading of the transmit buffer from the actual message sending and, therefore, reduces the reactivity requirements of the CPU. Problems can arise if the sending of a message is finished while the CPU re-loads the second buffer. No buffer would then be ready for transmission, and the CAN bus would be released.

At least three transmit buffers are required to meet the first of the above requirements under all circumstances. The MSCAN has three transmit buffers.

The second requirement calls for some sort of internal prioritization which the MSCAN implements with the "local priority" concept described in .

32.4.3 Transmit structures

The MSCAN triple transmit buffer scheme optimizes real-time performance by allowing multiple messages to be set up in advance. The three buffers are arranged as shown in [Figure 32-76](#).

All three buffers have a 13-byte data structure similar to the outline of the receive buffers. An additional Transmit Buffer Priority Register (TBPR) contains an 8-bit local priority field (PRIO). The remaining two bytes are used for time stamping of a message, if required.

To transmit a message, the CPU must identify an available transmit buffer, which is indicated by a set transmitter buffer empty (TXEx) flag. If a transmit buffer is available, the CPU must set a pointer to this buffer by writing to the CANTBSEL register. This makes the respective buffer accessible within the CANTXFG address space. The algorithmic feature associated with the CANTBSEL register simplifies the transmit buffer selection. In addition, this scheme makes the handler software simpler because only one address area is applicable for the transmit process, and the required address space is minimized.

The CPU then stores the identifier, the control bits, and the data content into one of the transmit buffers. Finally, the buffer is flagged as ready for transmission by clearing the associated TXE flag.

The MSCAN then schedules the message for transmission and signals the successful transmission of the buffer by setting the associated TXE flag. A transmit interrupt is generated³ when TXEx is set and can be used to drive the application software to re-load the buffer.

If more than one buffer is scheduled for transmission when the CAN bus becomes available for arbitration, the MSCAN uses the local priority setting of the three buffers to determine the prioritization. For this purpose, every transmit buffer has an 8-bit local priority field (PRIO). The application software programs this field when the message is set up. The local priority reflects the priority of this particular message relative to the set of messages being transmitted from this node. The lowest binary value of the PRIO field is defined to be the highest priority. The internal scheduling process takes place whenever the MSCAN arbitrates for the CAN bus. This is also the case after the occurrence of a transmission error.

When a high priority message is scheduled by the application software, it may become necessary to abort a lower priority message in one of the three transmit buffers. Because messages that are already in transmission cannot be aborted, the user must request the abort by setting the corresponding abort request bit (ABTRQ). The MSCAN then grants the request, if possible, by:

1. Setting the corresponding abort acknowledge flag (ABTAK) in the CANTAACK register.
2. Setting the associated TXE flag to release the buffer.
3. Generating a transmit interrupt. The transmit interrupt handler software can determine from the setting of the ABTAK flag whether the message was aborted (ABTAK = 1) or sent (ABTAK = 0).

3. The transmit interrupt occurs only if not masked. A polling scheme can be applied on TXEx also.

32.4.4 Receive structures

The received messages are stored in a five stage input FIFO. The five message buffers are alternately mapped into a single memory area. The background receive buffer (RxBG) is exclusively associated with the MSCAN, but the foreground receive buffer (RxFG) is addressable by the CPU. This scheme simplifies the handler software because only one address area is applicable for the receive process.

All receive buffers have a size of 15 bytes to store the CAN control bits, the identifier (standard or extended), the data contents, and a time stamp, if enabled.

The receiver full flag (RXF) signals the status of the foreground receive buffer. When the buffer contains a correctly received message with a matching identifier, this flag is set.

On reception, each message is checked to see whether it passes the filter and simultaneously is written into the active RxBG. After successful reception of a valid message, the MSCAN shifts the content of RxBG into the receiver FIFO, sets the RXF flag, and generates a receive interrupt⁴ to the CPU. The user's receive handler must read the received message from the RxFG and then reset the RXF flag to acknowledge the interrupt and to release the foreground buffer. A new message, which can follow immediately after the IFS field of the CAN frame, is received into the next available RxBG. If the MSCAN receives an invalid message in its RxBG (wrong identifier, transmission errors, etc.) the actual contents of the buffer will be over-written by the next message. The buffer will then not be shifted into the FIFO.

When the MSCAN module is transmitting, the MSCAN receives its own transmitted messages into the background receive buffer, RxBG, but does not shift it into the receiver FIFO, generate a receive interrupt, or acknowledge its own messages on the CAN bus. The exception to this rule is in loopback mode where the MSCAN treats its own messages exactly like all other incoming messages. The MSCAN receives its own transmitted messages in the event that it loses arbitration. If arbitration is lost, the MSCAN must be prepared to become a receiver.

An overrun condition occurs when all receive message buffers in the FIFO are filled with correctly received messages with accepted identifiers and another message is correctly received from the CAN bus with an accepted identifier. The latter message is discarded and an error interrupt with overrun indication is generated if enabled. The MSCAN remains able to transmit messages while the receiver FIFO is being filled, but all incoming messages are discarded. As soon as a receive buffer in the FIFO is available again, new valid messages will be accepted.

4. The receive interrupt occurs only if not masked. A polling scheme can be applied on RXF also.

32.4.5 Identifier acceptance filter

The MSCAN identifier acceptance registers define the acceptable patterns of the standard or extended identifier (ID[10:0] or ID[28:0]). Any of these bits can be marked 'don't care' in the MSCAN identifier mask registers.

A filter hit is indicated to the application software by a set receive buffer full flag (RXF = 1) and three bits in the CANIDAC register. These identifier hit flags (IDHIT[2:0]) clearly identify the filter section that caused the acceptance. They simplify the application software's task to identify the cause of the receiver interrupt. If more than one hit occurs (two or more filters match), the lower hit has priority.

A very flexible programmable generic identifier acceptance filter has been introduced to reduce the CPU interrupt loading. The filter is programmable to operate in four different modes:

- Two identifier acceptance filters, each to be applied to:
 - The full 29 bits of the extended identifier and to the following bits of the CAN 2.0B frame:
 - Remote transmission request (RTR)
 - Identifier extension (IDE)
 - Substitute remote request (SRR)
 - The 11 bits of the standard identifier plus the RTR and IDE bits of the CAN 2.0A/B messages. This mode implements two filters for a full length CAN 2.0B compliant extended identifier. Although this mode can be used for standard identifiers, it is recommended to use the four or eight identifier acceptance filters.

[Figure 32-77](#) shows how the first 32-bit filter bank (CANIDAR0-CANIDAR3, CANIDMR0-CANIDMR3) produces a filter 0 hit. Similarly, the second filter bank (CANIDAR4-CANIDAR7, CANIDMR4-CANIDMR7) produces a filter 1 hit.

- Four identifier acceptance filters, each to be applied to:
 - The 14 most significant bits of the extended identifier plus the SRR and IDE bits of CAN 2.0B messages.
 - The 11 bits of the standard identifier, the RTR and IDE bits of CAN 2.0A/B messages. [Figure 32-78](#) shows how the first 32-bit filter bank (CANIDAR0-CANIDAR3, CANIDMR0-CANIDMR3) produces filter 0 and 1 hits. Similarly, the second filter bank (CANIDAR4-CANIDAR7, CANIDMR4-CANIDMR7) produces filter 2 and 3 hits.

Functional description

- Eight identifier acceptance filters, each to be applied to the first 8 bits of the identifier. This mode implements eight independent filters for the first 8 bits of a CAN 2.0A/B compliant standard identifier or a CAN 2.0B compliant extended identifier. [Figure 32-79](#) shows how the first 32-bit filter bank (CANIDAR0-CANIDAR3, CANIDMR0-CANIDMR3) produces filter 0 to 3 hits. Similarly, the second filter bank (CANIDAR4-CANIDAR7, CANIDMR4-CANIDMR7) produces filter 4 to 7 hits.
- Closed filter. No CAN message is copied into the foreground buffer RxFG, and the RXF flag is never set.

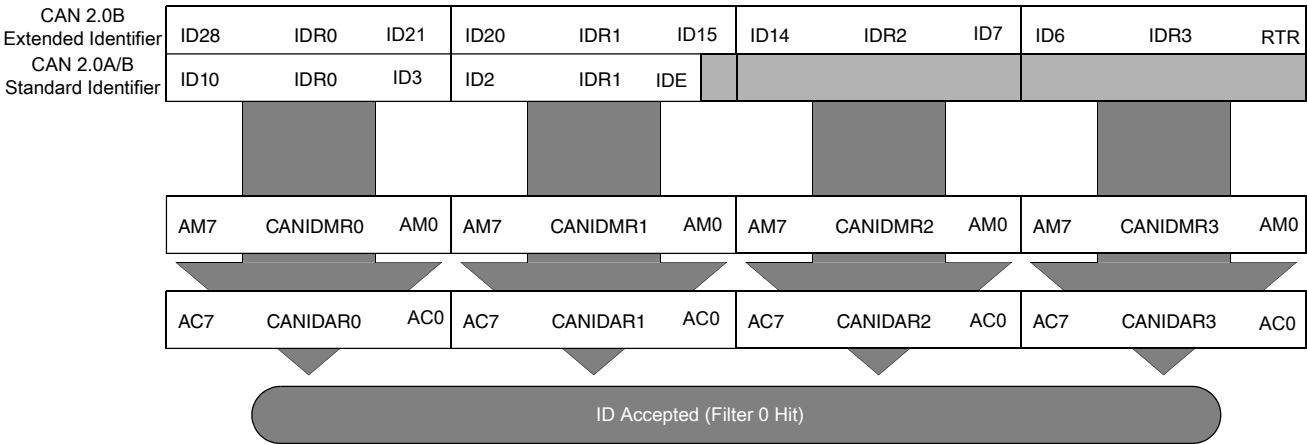


Figure 32-77. 32-bit maskable identifier acceptance filter

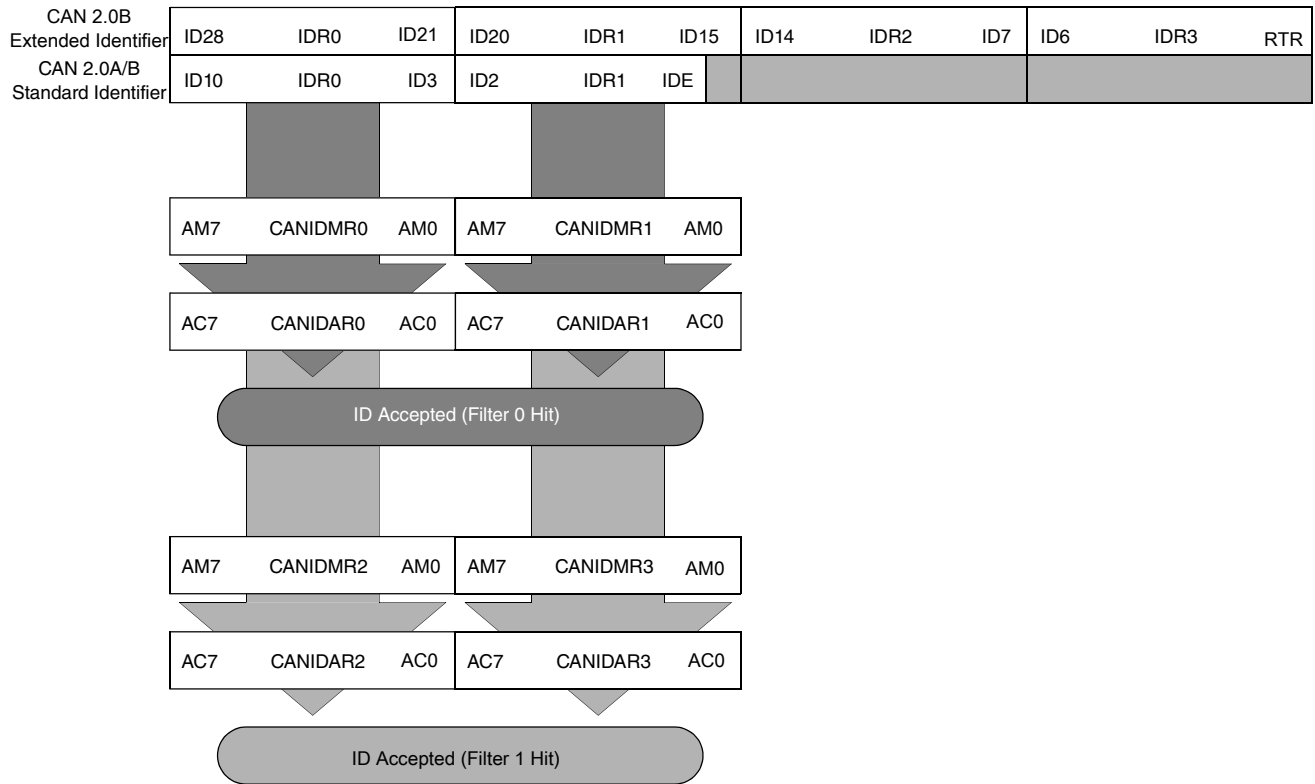


Figure 32-78. 16-bit maskable identifier acceptance filter

Functional description

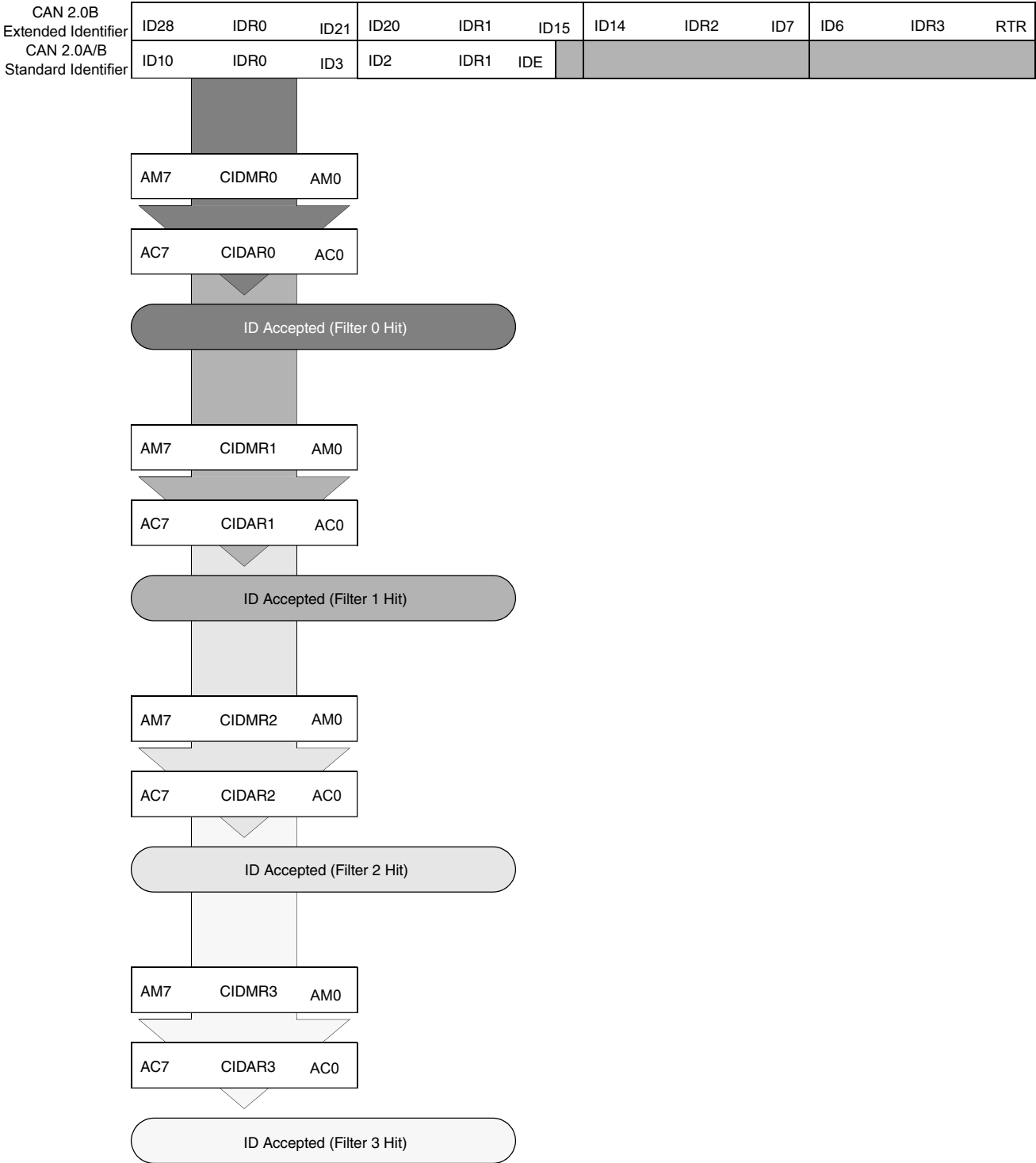


Figure 32-79. 8-bit maskable identifier acceptance filter

32.4.5.1 Protocol violation protection

The MSCAN protects the user from accidentally violating the CAN protocol through programming errors. The protection logic implements the following features:

- The receive and transmit error counters cannot be written or otherwise manipulated.
- All registers which control the configuration of the MSCAN cannot be modified while the MSCAN is on-line. The MSCAN has to be in Initialization Mode. The corresponding INTRQ/INITAK handshake bits in the CANCTL0/CANCTL1 registers serve as a lock to protect the following registers:
 - MSCAN control 1 register (CANCTL1)
 - MSCAN bus timing registers 0 and 1 (CANBTR0, CANBTR1)
 - MSCAN identifier acceptance control register (CANIDAC)
 - MSCAN identifier acceptance registers (CANIDAR0-CANIDAR7)
 - MSCAN identifier mask registers (CANIDMR0-CANIDMR7)
- The TXCAN is immediately forced to a recessive state when the MSCAN goes into the power down mode or initialization mode.
- The MSCAN enable bit (CANE) is writable only once in normal system operation modes, which provides further protection against inadvertently disabling the MSCAN.

32.4.5.2 Clock system

shows the structure of the MSCAN clock generation circuitry.

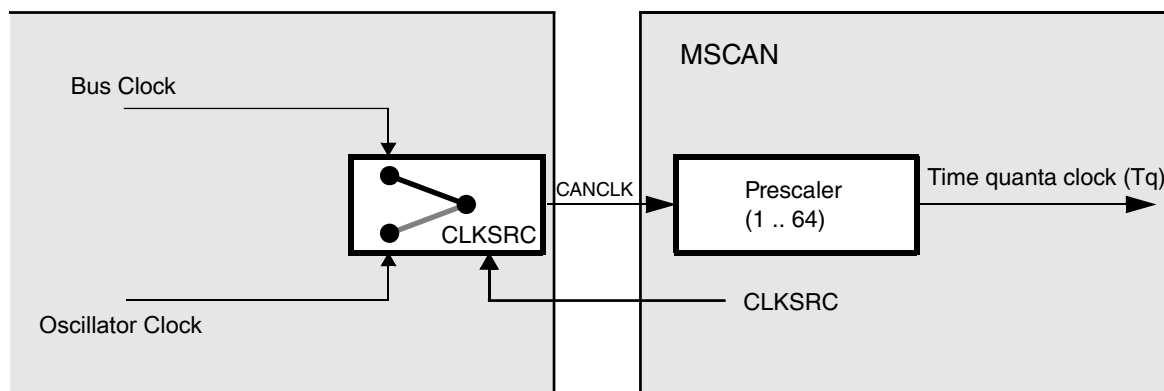


Figure 32-80. MSCAN clocking scheme

The clock source bit (CLKSRC) in the CANCTL1 register defines whether the internal CANCLK is connected to the output of a crystal oscillator (oscillator clock) or to the bus clock.

The clock source has to be chosen such that the tight oscillator tolerance requirements (up to 0.4%) of the CAN protocol are met. Additionally, for high CAN bus rates (1 Mbps), a 45% to 55% duty cycle of the clock is required.

Functional description

If the bus clock is generated from a PLL, it is recommended to select the oscillator clock rather than the bus clock due to jitter considerations, especially at the faster CAN bus rates.

For microcontrollers without a clock and reset generator (CRG), CANCLK is driven from the crystal oscillator (oscillator clock).

A programmable prescaler generates the time quanta (Tq) clock from CANCLK. A time quantum is the atomic unit of time handled by the MSCAN.

$$\Gamma_q = f_{CANCLK} / (\text{Prescaler value})$$

A bit time is subdivided into three segments as described in the Bosch CAN 2.0A/B specification. (see [Figure 32-81](#)):

- SYNC_SEG: This segment has a fixed length of one time quantum. Signal edges are expected to happen within this section.
- Time Segment 1: This segment includes the PROP_SEG and the PHASE_SEG1 of the CAN standard. It can be programmed by setting the parameter TSEG1 to consist of 4 to 16 time quanta.
- Time Segment 2: This segment represents the PHASE_SEG2 of the CAN standard. It can be programmed by setting the TSEG2 parameter to be 2 to 8 time quanta long.

$$\text{Bit rate} = f_{\Gamma_q} / (\text{Number of time quanta})$$

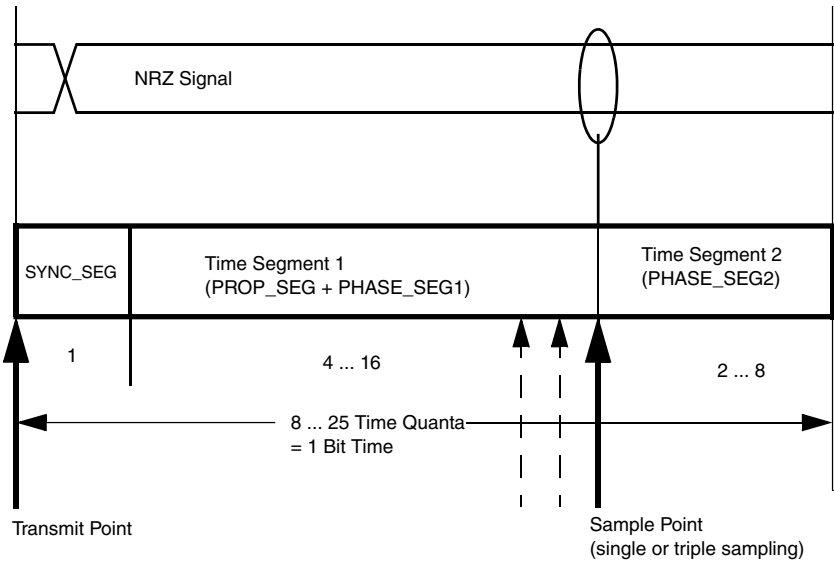


Figure 32-81. Segments within the bit time

Table 32-77. Time segment syntax

| Syntax | Description |
|----------|--|
| SYNC_SEG | System expects transitions to occur on the CAN bus during this period. |

Table continues on the next page...

Table 32-77. Time segment syntax (continued)

| Syntax | Description |
|----------------|--|
| Transmit Point | A node in transmit mode transfers a new value to the CAN bus at this point. |
| Sample Point | A node in receive mode samples the CAN bus at this point. If the three samples per bit option is selected, then this point marks the position of the third sample. |

The synchronization jump width (see the Bosch CAN 2.0A/B specification for details) can be programmed in a range of 1 to 4 time quanta by setting the SJW parameter.

The SYNC_SEG, TSEG1, TSEG2, and SJW parameters are set by programming the MSCAN bus timing registers (CANBTR0, CANBTR1).

[Table 32-78](#) gives an overview of the Bosch CAN 2.0A/B specification compliant segment settings and the related parameter values.

Table 32-78. Bosch CAN 2.0A/B compliant bit time segment settings

| Time Segment 1 | TSEG1 | Time Segment 2 | TSEG2 | Synchronization Jump Width | SJW |
|----------------|---------|----------------|-------|----------------------------|--------|
| 5 .. 10 | 4 .. 9 | 2 | 1 | 1 .. 2 | 0 .. 1 |
| 4 .. 11 | 3 .. 10 | 3 | 2 | 1 .. 3 | 0 .. 2 |
| 5 .. 12 | 4 .. 11 | 4 | 3 | 1 .. 4 | 0 .. 3 |
| 6 .. 13 | 5 .. 12 | 5 | 4 | 1 .. 4 | 0 .. 3 |
| 7 .. 14 | 6 .. 13 | 6 | 5 | 1 .. 4 | 0 .. 3 |
| 8 .. 15 | 7 .. 14 | 7 | 6 | 1 .. 4 | 0 .. 3 |
| 9 .. 16 | 8 .. 15 | 8 | 7 | 1 .. 4 | 0 .. 3 |

32.4.6 Low-power options

If the MSCAN is disabled (CANE = 0), the MSCAN clocks are stopped for power saving.

If the MSCAN is enabled (CANE = 1), the MSCAN has two additional modes with reduced power consumption, compared to normal mode: sleep and power down mode. In sleep mode, power consumption is reduced by stopping all clocks except those to access the registers from the CPU side. In power down mode, all clocks are stopped and no power is consumed.

[Table 32-79](#) summarizes the combinations of MSCAN and CPU modes. A particular combination of modes is entered by the given settings on the CSWAI and SLPRQ/SLPAK bits.

Table 32-79. CPU vs. MSCAN operating modes

| CPU Mode | MSCAN Mode | | | |
|----------|--|--|--|--|
| | Normal | Reduced power consumption | | |
| | | Sleep | Power down | Disabled (CANE=0) |
| RUN | <ul style="list-style-type: none"> • CSWAI = X¹ • SLPRQ = 0 • SLPK = 0 | <ul style="list-style-type: none"> • CSWAI = X • SLPRQ = 1 • SLPK = 1 | | <ul style="list-style-type: none"> • CSWAI = X • SLPRQ = X • SLPK = X |
| WAIT | <ul style="list-style-type: none"> • CSWAI = 0 • SLPRQ = 0 • SLPK = 0 | <ul style="list-style-type: none"> • CSWAI = 0 • SLPRQ = 1 • SLPK = 1 | <ul style="list-style-type: none"> • CSWAI = 1 • SLPRQ = X • SLPK = X | <ul style="list-style-type: none"> • CSWAI = X • SLPRQ = X • SLPK = X |
| STOP | | | <ul style="list-style-type: none"> • CSWAI = X • SLPRQ = X • SLPK = X | <ul style="list-style-type: none"> • CSWAI = X • SLPRQ = X • SLPK = X |

1. X means don't care.

32.4.6.1 Operation in run mode

As shown in [Table 32-79](#), only MSCAN sleep mode is available as low power option when the CPU is in run mode.

32.4.6.2 Operation in wait mode

The WAI instruction puts the MCU in a low power consumption stand-by mode. If the CSWAI bit is set, additional power can be saved in power down mode because the CPU clocks are stopped. After leaving this power down mode, the MSCAN restarts and enters normal mode again.

While the CPU is in wait mode, the MSCAN can be operated in normal mode and generate interrupts (registers can be accessed via background debug mode).

32.4.6.3 Operation in stop mode

The STOP instruction puts the MCU in a low power consumption stand-by mode. In stop mode, the MSCAN is set in power down mode regardless of the value of the SLPRQ/SLPAK and CSWAI bits ([Table 32-79](#)).

32.4.6.4 MSCAN normal mode

This is a non-power-saving mode. Enabling the MSCAN puts the module from disabled mode into normal mode. In this mode the module can either be in initialization mode or out of initialization mode. See [MSCAN initialization mode](#).

32.4.6.5 MSCAN sleep mode

The CPU can request the MSCAN to enter this low power mode by asserting the SLPRQ bit in the CANCTL0 register. The time when the MSCAN enters sleep mode depends on a fixed synchronization delay and its current activity:

- If there are one or more message buffers scheduled for transmission (TXEx = 0), the MSCAN will continue to transmit until all transmit message buffers are empty (TXEx = 1, transmitted successfully or aborted) and then goes into sleep mode.
- If the MSCAN is receiving, it continues to receive and goes into sleep mode as soon as the CAN bus next becomes idle.
- If the MSCAN is neither transmitting nor receiving, it immediately goes into sleep mode.

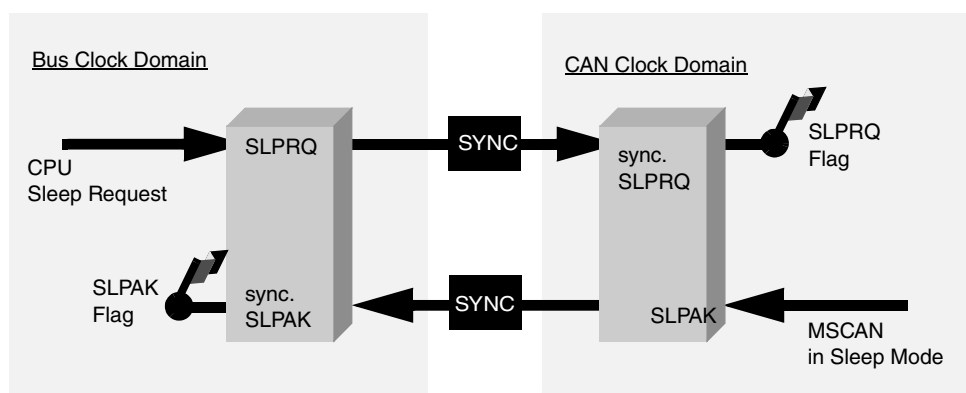


Figure 32-82. Sleep request / acknowledge cycle

NOTE

The application software must avoid setting up a transmission (by clearing one or more TXEx flag(s)) and immediately request sleep mode (by setting SLPRQ). Whether the MSCAN starts transmitting or goes into sleep mode directly depends on the exact sequence of operations.

If sleep mode is active, the SLPRQ and SLPK bits are set ([Figure 32-82](#)). The application software must use SLPK as a handshake indication for the request (SLPRQ) to go into sleep mode.

When in sleep mode (SLPRQ = 1 and SLPK = 1), the MSCAN stops its internal clocks. However, clocks that allow register accesses from the CPU side continue to run.

If the MSCAN is in bus-off state, it stops counting the 128 occurrences of 11 consecutive recessive bits due to the stopped clocks. TXCAN remains in a recessive state. If RXF = 1, the message can be read and RXF can be cleared. Shifting a new message into the foreground buffer of the receiver FIFO (RxFG) does not take place while in sleep mode.

It is possible to access the transmit buffers and to clear the associated TXE flags. No message abort takes place while in sleep mode.

If the WUPE bit in CANCTL0 is not asserted, the MSCAN will mask any activity it detects on CAN. RXCAN is therefore held internally in a recessive state. This locks the MSCAN in sleep mode. WUPE must be set before entering sleep mode to take effect.

The MSCAN is able to leave sleep mode (wake up) only when:

- CAN bus activity occurs and WUPE = 1 or
- the CPU clears the SLPRQ bit

NOTE

The CPU cannot clear the SLPRQ bit before sleep mode (SLPRQ = 1 and SLPK = 1) is active.

After wake-up, the MSCAN waits for 11 consecutive recessive bits to synchronize to the CAN bus. As a consequence, if the MSCAN is woken-up by a CAN frame, this frame is not received.

The receive message buffers (RxFG and RxBG) contain messages if they were received before sleep mode was entered. All pending actions will be executed upon wake-up; copying of RxBG into RxFG, message aborts and message transmissions. If the MSCAN remains in bus-off state after sleep mode was exited, it continues counting the 128 occurrences of 11 consecutive recessive bits.

32.4.6.6 MSCAN power down mode

The MSCAN is in power down mode ([Table 32-79](#)) when

- CPU is in stop mode or
- CPU is in wait mode and the CSWAI bit is set

When entering the power down mode, the MSCAN immediately stops all ongoing transmissions and receptions, potentially causing CAN protocol violations. To protect the CAN bus system from fatal consequences of violations to the above rule, the MSCAN immediately drives TXCAN into a recessive state.

NOTE

The user is responsible for ensuring that the MSCAN is not active when power down mode is entered. The recommended procedure is to bring the MSCAN into Sleep mode before the STOP or WAI instruction (if CSWAI is set) is executed. Otherwise, the abort of an ongoing message can cause an error condition and impact other CAN bus devices.

In power down mode, all clocks are stopped and no registers can be accessed. If the MSCAN was not in sleep mode before power down mode became active, the module performs an internal recovery cycle after powering up. This causes some fixed delay before the module enters normal mode again.

32.4.6.7 Disabled mode

The MSCAN is in disabled mode out of reset (CANE=0). All module clocks are stopped for power saving, however the register map can still be accessed as specified.

32.4.6.8 Programmable wake-Up function

The MSCAN can be programmed to wake up from sleep or power down mode as soon as CAN bus activity is detected (see control bit WUPE in MSCAN Control Register 0 (CANCTL0)). The sensitivity to existing CAN bus action can be modified by applying a low-pass filter function to the RXCAN input line.

This feature can be used to protect the MSCAN from wake-up due to short glitches on the CAN bus lines. Such glitches can result from-for example-electromagnetic interference within noisy environments

32.4.7 Reset initialization

The reset state of each individual bit is listed in [Memory map and register definition](#) which details all the registers and their bit-fields.

32.4.8 Interrupts

This section describes all interrupts originated by the MSCAN. It documents the enable bits and generated flags. Each interrupt is listed and described separately.

32.4.8.1 Description of interrupt operation

The MSCAN supports four interrupt vectors (see [Table 32-80](#)), any of which can be individually masked.

Refer to the device overview section to determine the dedicated interrupt vector addresses.

Table 32-80. Interrupt vectors

| Interrupt source | CCR mask | Local enable |
|---|----------|------------------------|
| Wake-up interrupt (WUPIF) | 1 bit | CANRIER (WUPIE) |
| Error Interrupts interrupt (CSCIF, OVRIF) | 1 bit | CANRIER (CSCIE, OVRIE) |
| Receive interrupt (RXF) | 1 bit | CANRIER (RXFIE) |
| Transmit interrupts (TXE[2:0]) | 1 bit | CANTIER (TXEIE[2:0]) |

32.4.8.2 Transmit interrupt

At least one of the three transmit buffers is empty (not scheduled) and can be loaded to schedule a message for transmission. The TXEx flag of the empty message buffer is set.

32.4.8.3 Receive interrupt

A message is successfully received and shifted into the foreground buffer (RxFG) of the receiver FIFO. This interrupt is generated immediately after receiving the EOF symbol. The RXF flag is set. If there are multiple messages in the receiver FIFO, the RXF flag is set as soon as the next message is shifted to the foreground buffer.

32.4.8.4 Wake-up interrupt

A wake-up interrupt is generated if activity on the CAN bus occurs during MSCAN sleep or power-down mode.

NOTE

This interrupt can only occur if the MSCAN was in sleep mode (SLPRQ = 1 and SLPK = 1) before entering power down mode, the wake-up option is enabled (WUPE = 1), and the wake-up interrupt is enabled (WUPIE = 1).

32.4.8.5 Error interrupt

An error interrupt is generated if an overrun of the receiver FIFO, error, warning, or bus-off condition occurs. MSCAN Receiver Flag Register (CANRFLG) indicates one of the following conditions:

- Overrun - An overrun condition of the receiver FIFO as described in [Receive structures](#) occurred.
- CAN Status Change - The actual value of the transmit and receive error counters control the CAN bus state of the MSCAN. As soon as the error counters skip into a critical range (Tx/Rx-warning, Tx/Rx-error, bus-off) the MSCAN flags an error condition. The status change, which caused the error condition, is indicated by the TSTAT and RSTAT flags.

32.4.8.6 Interrupt acknowledge

Interrupts are directly associated with one or more status flags in either the MSCAN Receiver Flag Register (CANRFLG) or the MSCAN Transmitter Flag Register (CANTFLG). Interrupts are pending as long as one of the corresponding flags is set. The flags in CANRFLG and CANTFLG must be reset within the interrupt handler to handshake the interrupt. The flags are reset by writing a 1 to the corresponding bit position. A flag cannot be cleared if the respective condition prevails.

NOTE

It must be guaranteed that the CPU clears only the bit causing the current interrupt. For this reason, bit manipulation instructions (BSET) must not be used to clear interrupt flags. These instructions may cause accidental clearing of interrupt flags which are set after entering the current interrupt service routine.

32.4.9 Initialization/Application information

32.4.9.1 MSCAN initialization

The procedure to initially start up the MSCAN module out of reset is as follows:

1. Assert CANE
2. Write to the configuration registers in initialization mode
3. Clear INITRQ to leave initialization mode

If the configuration of registers which are only writable in initialization mode shall be changed:

1. Bring the module into sleep mode by setting SLPRQ and awaiting SLPK to assert after the CAN bus becomes idle.
2. Enter initialization mode: assert INITRQ and await INITAK
3. Write to the configuration registers in initialization mode
4. Clear INITRQ to leave initialization mode and continue

32.4.9.2 Bus-off recovery

The bus-off recovery is user configurable. The bus-off state can either be left automatically or on user request.

For reasons of backwards compatibility, the MSCAN defaults to automatic recovery after reset. In this case, the MSCAN will become error active again after counting 128 occurrences of 11 consecutive recessive bits on the CAN bus (see the Bosch CAN 2.0 A/B specification for details).

If the MSCAN is configured for user request (BORM set in MSCAN Control Register 1 (CANCTL1)), the recovery from bus-off starts after both independent events have become true:

- 128 occurrences of 11 consecutive recessive bits on the CAN bus have been monitored
- BOHOLD in MSCAN Miscellaneous Register (CANMISC) has been cleared by the user

These two events may occur in any order.

Chapter 33

Universal Asynchronous Receiver/Transmitter (UART)

33.1 Introduction

33.1.1 Features

Features of UART module include:

- Full-duplex, standard non-return-to-zero (NRZ) format
- Double-buffered transmitter and receiver with separate enables
- Programmable baud rates (13-bit modulo divider)
- Interrupt-driven or polled operation:
 - Transmit data register empty and transmission complete
 - Receive data register full
 - Receive overrun, parity error, framing error, and noise error
 - Idle receiver detect
 - Active edge on receive pin
 - Break detect supporting LIN
- Hardware parity generation and checking
- Programmable 8-bit or 9-bit character length
- Programmable 1-bit or 2-bit stop bits
- Receiver wakeup by idle-line or address-mark
- Optional 13-bit break character generation / 11-bit break character detection
- Selectable transmitter output polarity

33.1.2 Modes of operation

See Section [Functional description](#) for details concerning UART operation in these modes:

- 8- and 9-bit data modes
- Stop mode operation
- Loop mode
- Single-wire mode

33.1.3 Block diagram

The following figure shows the transmitter portion of the UART.

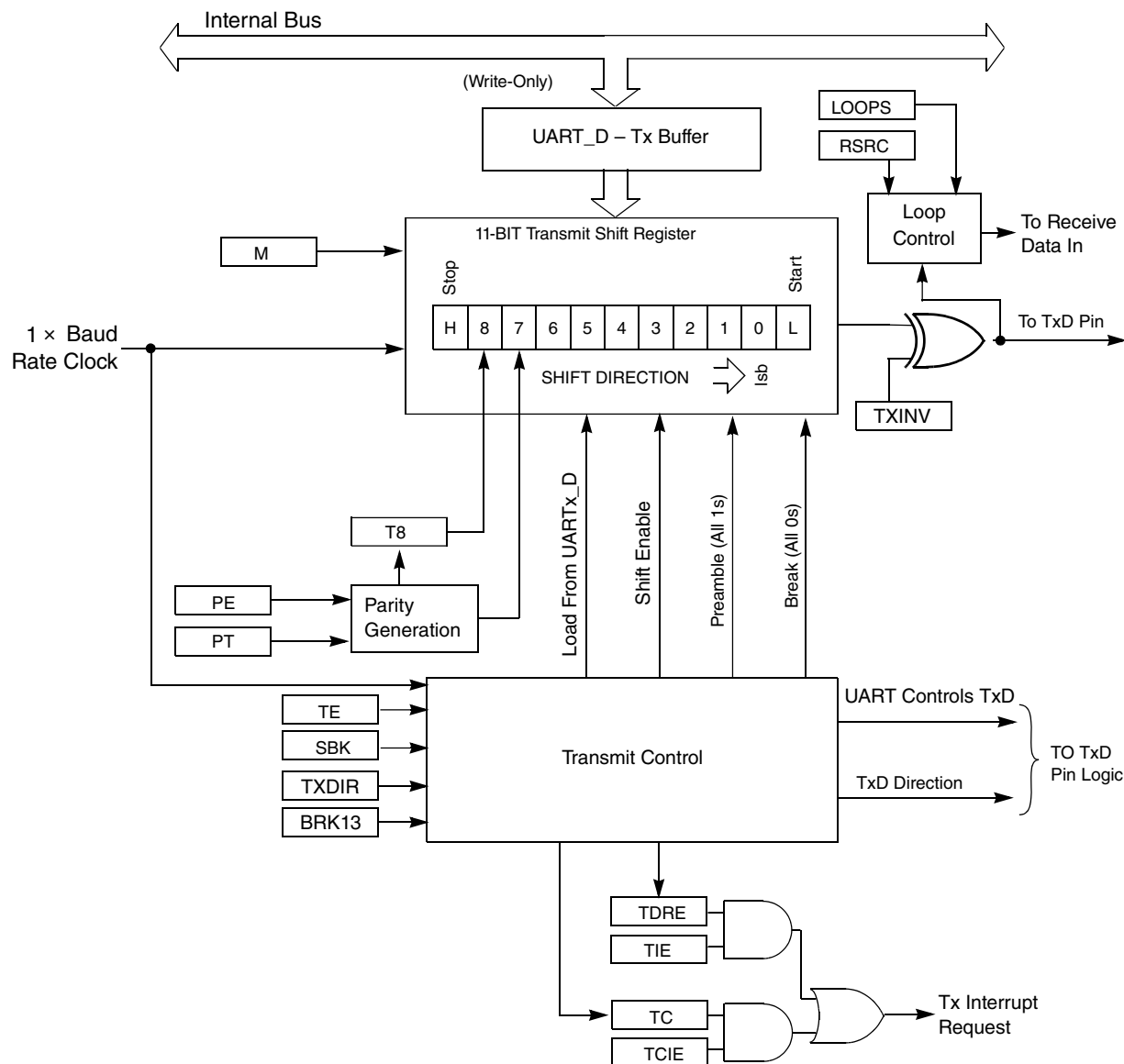


Figure 33-1. UART transmitter block diagram

The following figure shows the receiver portion of the UART.

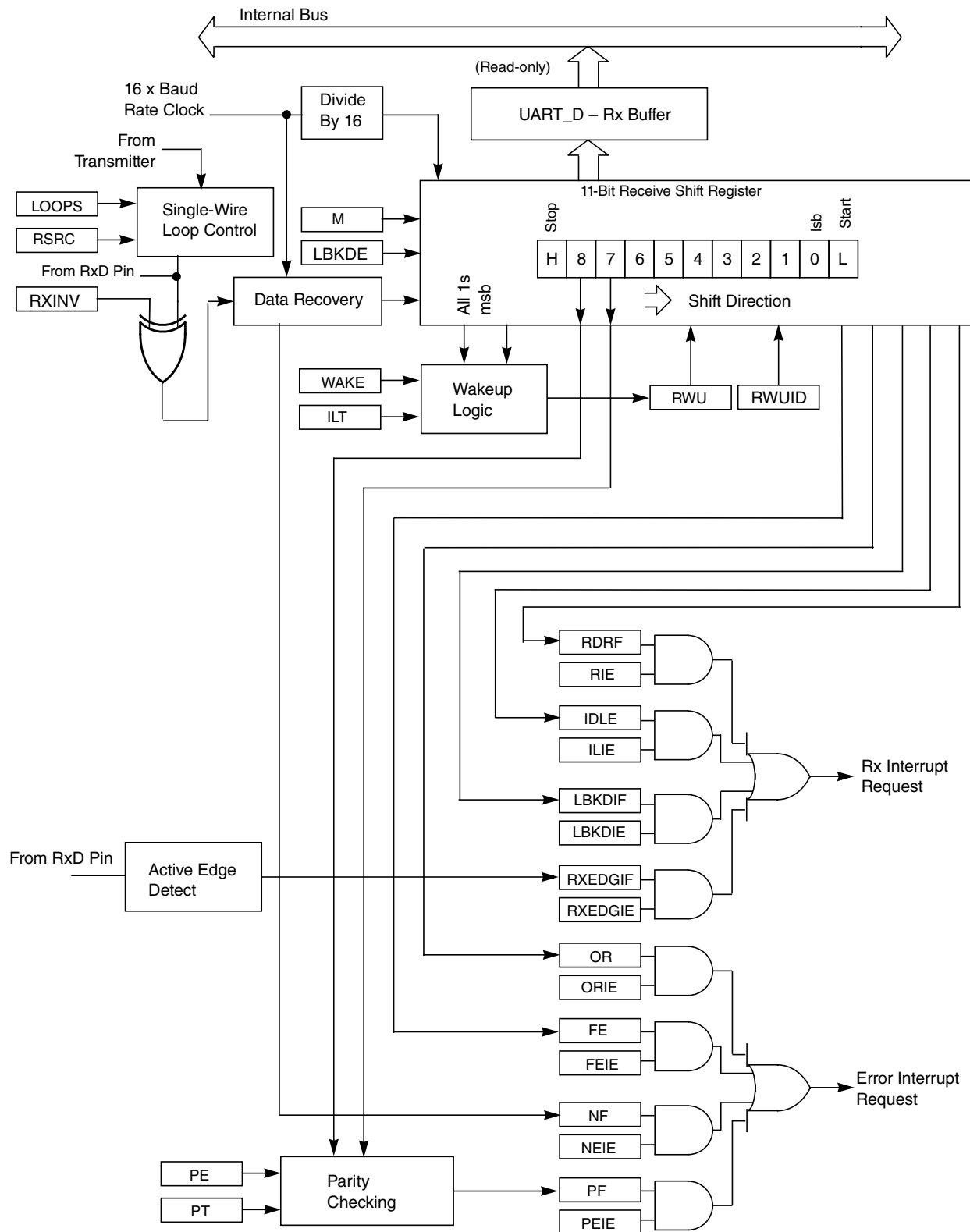


Figure 33-2. UART receiver block diagram

33.2 UART signal descriptions

The UART signals are shown in the table found here.

Table 33-1. UART signal descriptions

| Signal | Description | I/O |
|--------|---------------|-----|
| RxD | Receive data | I |
| TxD | Transmit data | I/O |

33.2.1 Detailed signal descriptions

The detailed signal descriptions of the UART are shown in the following table.

Table 33-2. UART—Detailed signal descriptions

| Signal | I/O | Description | |
|--------|-----|---|--|
| RxD | I | Receive data. Serial data input to receiver. | |
| | | State meaning | Whether RxD is interpreted as a 1 or 0 depends on the bit encoding method along with other configuration settings. |
| | | Timing | Sampled at a frequency determined by the module clock divided by the baud rate. |
| TxD | I/O | Transmit data. Serial data output from transmitter. | |
| | | State meaning | Whether TxD is interpreted as a 1 or 0 depends on the bit encoding method along with other configuration settings. |
| | | Timing | Driven at the beginning or within a bit time according to the bit encoding method along with other configuration settings. Otherwise, transmissions are independent of reception timing. |

33.3 Register definition

The UART has 8-bit registers to control baud rate, select UART options, report UART status, and for transmit/receive data.

Refer to the direct-page register summary in the memory chapter of this document or the absolute address assignments for all UART registers. This section refers to registers and control bits only by their names. A Freescale-provided equate or header file is used to translate these names into the appropriate absolute addresses.

UART memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-------------|----------------------------|
| 4006_A000 | UART Baud Rate Register: High (UART0_BDH) | 8 | R/W | 00h | 33.3.1/653 |
| 4006_A001 | UART Baud Rate Register: Low (UART0_BDL) | 8 | R/W | 04h | 33.3.2/654 |
| 4006_A002 | UART Control Register 1 (UART0_C1) | 8 | R/W | 00h | 33.3.3/655 |
| 4006_A003 | UART Control Register 2 (UART0_C2) | 8 | R/W | 00h | 33.3.4/656 |
| 4006_A004 | UART Status Register 1 (UART0_S1) | 8 | R | C0h | 33.3.5/658 |
| 4006_A005 | UART Status Register 2 (UART0_S2) | 8 | R/W | 00h | 33.3.6/659 |
| 4006_A006 | UART Control Register 3 (UART0_C3) | 8 | R/W | 00h | 33.3.7/661 |
| 4006_A007 | UART Data Register (UART0_D) | 8 | R/W | 00h | 33.3.8/662 |
| 4006_B000 | UART Baud Rate Register: High (UART1_BDH) | 8 | R/W | 00h | 33.3.1/653 |
| 4006_B001 | UART Baud Rate Register: Low (UART1_BDL) | 8 | R/W | 04h | 33.3.2/654 |
| 4006_B002 | UART Control Register 1 (UART1_C1) | 8 | R/W | 00h | 33.3.3/655 |
| 4006_B003 | UART Control Register 2 (UART1_C2) | 8 | R/W | 00h | 33.3.4/656 |
| 4006_B004 | UART Status Register 1 (UART1_S1) | 8 | R | C0h | 33.3.5/658 |
| 4006_B005 | UART Status Register 2 (UART1_S2) | 8 | R/W | 00h | 33.3.6/659 |
| 4006_B006 | UART Control Register 3 (UART1_C3) | 8 | R/W | 00h | 33.3.7/661 |
| 4006_B007 | UART Data Register (UART1_D) | 8 | R/W | 00h | 33.3.8/662 |
| 4006_C000 | UART Baud Rate Register: High (UART2_BDH) | 8 | R/W | 00h | 33.3.1/653 |
| 4006_C001 | UART Baud Rate Register: Low (UART2_BDL) | 8 | R/W | 04h | 33.3.2/654 |
| 4006_C002 | UART Control Register 1 (UART2_C1) | 8 | R/W | 00h | 33.3.3/655 |
| 4006_C003 | UART Control Register 2 (UART2_C2) | 8 | R/W | 00h | 33.3.4/656 |
| 4006_C004 | UART Status Register 1 (UART2_S1) | 8 | R | C0h | 33.3.5/658 |
| 4006_C005 | UART Status Register 2 (UART2_S2) | 8 | R/W | 00h | 33.3.6/659 |
| 4006_C006 | UART Control Register 3 (UART2_C3) | 8 | R/W | 00h | 33.3.7/661 |
| 4006_C007 | UART Data Register (UART2_D) | 8 | R/W | 00h | 33.3.8/662 |

33.3.1 UART Baud Rate Register: High (UARTx_BDH)

This register, along with UART_BDL, controls the prescale divisor for UART baud rate generation. To update the 13-bit baud rate setting SBR[12:0], first write to UART_BDH to buffer the high half of the new value and then write to UART_BDL. The working value in UART_BDH does not change until UART_BDL is written.

Address: Base address + 0h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|--------|---------|------|-----|---|---|---|---|
| Read | LBKDIE | RXEDGIE | SBNS | SBR | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_BDH field descriptions

| Field | Description |
|--------------|---|
| 7 LBKDIE | LIN Break Detect Interrupt Enable (for LBKDIF) 0 Hardware interrupts from UART_S2[LBKDIF] disabled (use polling). 1 Hardware interrupt requested when UART_S2[LBKDIF] flag is 1. |
| 6 RXEDGIE | RxD Input Active Edge Interrupt Enable (for RXEDGIF) 0 Hardware interrupts from UART_S2[RXEDGIF] disabled (use polling). 1 Hardware interrupt requested when UART_S2[RXEDGIF] flag is 1. |
| 5 SBNS | Stop Bit Number Select SBNS determines whether data characters are one or two stop bits. 0 One stop bit. 1 Two stop bit. |
| SBR | Baud Rate Modulo Divisor. The 13 bits in SBR[12:0] are referred to collectively as BR, and they set the modulo divide rate for the UART baud rate generator. When BR is cleared, the UART baud rate generator is disabled to reduce supply current. When BR is 1 - 8191, the UART baud rate equals $BUSCLK/(16 \times BR)$. |

33.3.2 UART Baud Rate Register: Low (UARTx_BDL)

This register, along with UART_BDH, control the prescale divisor for UART baud rate generation. To update the 13-bit baud rate setting [SBR12:SBR0], first write to UART_BDH to buffer the high half of the new value and then write to UART_BDL. The working value in UART_BDH does not change until UART_BDL is written.

UART_BDL is reset to a non-zero value, so after reset, the baud rate generator remains disabled until the first time the receiver or transmitter is enabled; that is, 1 is written to UART_C2[RE] or UART_C2[TE].

Address: Base address + 1h offset

| | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | | | | | | | | |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

UARTx_BDL field descriptions

| Field | Description |
|-------|---|
| SBR | Baud Rate Modulo Divisor These 13 bits in SBR[12:0] are referred to collectively as BR, which set the modulo divide rate for the UART baud rate generator. When BR is cleared, the UART baud rate generator is disabled to reduce supply current. When BR is 1 - 8191, the UART baud rate equals $BUSCLK/(16 \times BR)$. |

33.3.3 UART Control Register 1 (UARTx_C1)

This read/write register controls various optional features of the UART system.

Address: Base address + 2h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|----------|------|---|------|-----|----|----|
| Read | LOOPS | UARTSWAI | RSRC | M | WAKE | ILT | PE | PT |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_C1 field descriptions

| Field | Description |
|---------------|---|
| 7 LOOPS | <p>Loop Mode Select</p> <p>Selects between loop mode and normal 2-pin full-duplex modes. When LOOPS is set, the transmitter output is internally connected to the receiver input.</p> <p>0 Normal operation - RxD and TxD use separate pins.</p> <p>1 Loop mode or single-wire mode where transmitter outputs are internally connected to receiver input. (See RSRC bit.) RxD pin is not used by UART.</p> |
| 6 UARTSWAI | <p>UART Stops in Wait Mode</p> <p>0 UART clocks continue to run in Wait mode so the UART can be the source of an interrupt that wakes up the CPU.</p> <p>1 UART clocks freeze while CPU is in Wait mode.</p> |
| 5 RSRC | <p>Receiver Source Select</p> <p>This field has no meaning or effect unless LOOPS is set to 1. When LOOPS is set, the receiver input is internally connected to the TxD pin and RSRC determines whether this connection is also connected to the transmitter output.</p> <p>0 Provided LOOPS is set, RSRC is cleared, selects internal loop back mode and the UART does not use the RxD pins.</p> <p>1 Single-wire UART mode where the TxD pin is connected to the transmitter output and receiver input.</p> |
| 4 M | <p>9-Bit or 8-Bit Mode Select</p> <p>This field configures the UART to be operated in 9-bit or 8-bit data mode.</p> <p>0 Normal - start + 8 data bits (lsb first) + stop.</p> <p>1 Receiver and transmitter use 9-bit data characters start + 8 data bits (lsb first) + 9th data bit + stop.</p> |
| 3 WAKE | <p>Receiver Wakeup Method Select</p> <p>This field selects the receiver wakeup method.</p> <p>0 Idle-line wake-up.</p> <p>1 Address-mark wake-up.</p> |
| 2 ILT | <p>Idle Line Type Select</p> |

Table continues on the next page...

UARTx_C1 field descriptions (continued)

| Field | Description |
|---------|---|
| | Setting this field to 1 ensures that the stop bits and logic 1 bits at the end of a character do not count toward the 10 or 11 bit times of logic high level needed by the idle line detection logic. 0 Idle character bit count starts after start bit. 1 Idle character bit count starts after stop bit. |
| 1 PE | Parity Enable Enables hardware parity generation and checking. When parity is enabled, the most significant bit (msb) of the data character, eighth or ninth data bit, is treated as the parity bit. 0 No hardware parity generation or checking. 1 Parity enabled. |
| 0 PT | Parity Type Provided parity is enabled (PE = 1), this field selects even or odd parity. Odd parity means the total number of 1s in the data character, including the parity bit, is odd. Even parity means the total number of 1s in the data character, including the parity bit, is even. 0 Even parity. 1 Odd parity. |

33.3.4 UART Control Register 2 (UARTx_C2)

This register can be read or written at any time.

Address: Base address + 3h offset

| | | | | | | | | |
|-------|-----|------|-----|------|----|----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | TIE | TCIE | RIE | ILIE | TE | RE | RWU | SBK |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_C2 field descriptions

| Field | Description |
|-----------|---|
| 7 TIE | Transmit Interrupt Enable for TDRE 0 Hardware interrupts from TDRE disabled; use polling. 1 Hardware interrupt requested when TDRE flag is 1. |
| 6 TCIE | Transmission Complete Interrupt Enable for TC 0 Hardware interrupts from TC disabled; use polling. 1 Hardware interrupt requested when TC flag is 1. |
| 5 RIE | Receiver Interrupt Enable for RDRF 0 Hardware interrupts from S1[RDRF] disabled; use polling. 1 Hardware interrupt requested when S1[RDRF] flag is 1. |
| 4 ILIE | Idle Line Interrupt Enable for IDLE |

Table continues on the next page...

UARTx_C2 field descriptions (continued)

| Field | Description |
|----------|--|
| | <p>0 Hardware interrupts from S1[IDLE] disabled; use polling.</p> <p>1 Hardware interrupt requested when S1[IDLE] flag is 1.</p> |
| 3 TE | <p>Transmitter Enable</p> <p>TE must be 1 to use the UART transmitter. When TE is set, the UART forces the TxD pin to act as an output for the UART system.</p> <p>When the UART is configured for single-wire operation (LOOPS = RSRC = 1), TXDIR controls the direction of traffic on the single UART communication line (TxD pin).</p> <p>TE can also queue an idle character by clearing TE and then setting TE while a transmission is in progress.</p> <p>When 0 is written to TE, the transmitter keeps control of the port TxD pin until any data, queued idle, or queued break character finishes transmitting before allowing the pin to revert to a general-purpose I/O pin.</p> <p>0 Transmitter off.</p> <p>1 Transmitter on.</p> |
| 2 RE | <p>Receiver Enable</p> <p>When the UART receiver is off, the RxD pin reverts to being a general-purpose port I/O pin. If C1[LOOPS] is set, the RxD pin reverts to being a general-purpose I/O pin even if RE is set.</p> <p>0 Receiver off.</p> <p>1 Receiver on.</p> |
| 1 RWU | <p>Receiver Wakeup Control</p> <p>A 1 can be written to this field to place the UART receiver in a standby state where it waits for automatic hardware detection of a selected wake-up condition. The wake-up condition is an idle line between messages, WAKE = 0, idle-line wake-up, or a logic 1 in the most significant data bit in a character, WAKE = 1, address-mark wake-up. Application software sets RWU and, normally, a selected hardware condition automatically clears RWU.</p> <p>0 Normal UART receiver operation.</p> <p>1 UART receiver in standby waiting for wake-up condition.</p> |
| 0 SBK | <p>Send Break</p> <p>Writing a 1 and then a 0 to SBK queues a break character in the transmit data stream. Additional break characters of 10 or 11 or 12, 13 or 14 or 15 if BRK13 = 1, bit times of logic 0 are queued as long as SBK is set. Depending on the timing of the set and clear of SBK relative to the information currently being transmitted, a second break character may be queued before software clears SBK.</p> <p>0 Normal transmitter operation.</p> <p>1 Queue break character(s) to be sent.</p> |

33.3.5 UART Status Register 1 (UARTx_S1)

This register has eight read-only status flags. Writes have no effect. Special software sequences, which do not involve writing to this register, clear these status flags.

Address: Base address + 4h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|----|------|------|----|----|----|----|
| Read | TDRE | TC | RDRF | IDLE | OR | NF | FE | PF |
| Write | | | | | | | | |
| Reset | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_S1 field descriptions

| Field | Description |
|-----------|---|
| 7 TDRE | <p>Transmit Data Register Empty Flag</p> <p>TDRE is set out of reset and when a transmit data value transfers from the transmit data buffer to the transmit shifter, leaving room for a new character in the buffer. To clear TDRE, read UART_S1 with TDRE set and then write to the UART data register (UART_D).</p> <p>0 Transmit data register (buffer) full. 1 Transmit data register (buffer) empty.</p> |
| 6 TC | <p>Transmission Complete Flag</p> <p>TC is set out of reset and when TDRE is set and no data, preamble, or break character is being transmitted.</p> <p>TC is cleared automatically by reading UART_S1 with TC set and then executing one of the following operations:</p> <ul style="list-style-type: none"> • Write to the UART data register (UART_D) to transmit new data • Queue a preamble by changing TE from 0 to 1 • Queue a break character by writing 1 to UART_C2[SBK] <p>0 Transmitter active (sending data, a preamble, or a break). 1 Transmitter idle (transmission activity complete).</p> |
| 5 RDRF | <p>Receive Data Register Full Flag</p> <p>RDRF becomes set when a character transfers from the receive shifter into the receive data register (UART_D). To clear RDRF, read UART_S1 with RDRF set and then read the UART data register (UART_D).</p> <p>0 Receive data register empty. 1 Receive data register full.</p> |
| 4 IDLE | <p>Idle Line Flag</p> <p>IDLE is set when the UART receive line becomes idle for a full character time after a period of activity. When C1[ILT] is cleared, the receiver starts counting idle bit times after the start bit. If the receive character is all 1s, these bit times and the stop bits time count toward the full character time of logic high, 10 or 11 bit times depending on the M control bit, needed for the receiver to detect an idle line. When ILT is set, the receiver doesn't start counting idle bit times until the stop bits. The stop bits and any logic high bit times at the end of the previous character do not count toward the full character time of logic high needed for the receiver to detect an idle line.</p> |

Table continues on the next page...

UARTx_S1 field descriptions (continued)

| Field | Description |
|---------|--|
| | <p>To clear IDLE, read UART_S1 with IDLE set and then read the UART data register (UART_D). After IDLE has been cleared, it cannot become set again until after a new character has been received and RDRF has been set. IDLE is set only once even if the receive line remains idle for an extended period.</p> <p>0 No idle line detected. 1 Idle line was detected.</p> |
| 3 OR | <p>Receiver Overrun Flag</p> <p>OR is set when a new serial character is ready to be transferred to the receive data register (buffer), but the previously received character has not been read from UART_D yet. In this case, the new character, and all associated error information, is lost because there is no room to move it into UART_D. To clear OR, read UART_S1 with OR set and then read the UART data register (UART_D).</p> <p>0 No overrun. 1 Receive overrun (new UART data lost).</p> |
| 2 NF | <p>Noise Flag</p> <p>The advanced sampling technique used in the receiver takes seven samples during the start bit and three samples in each data bit and the stop bits. If any of these samples disagrees with the rest of the samples within any bit time in the frame, the flag NF is set at the same time as RDRF is set for the character. To clear NF, read UART_S1 and then read the UART data register (UART_D).</p> <p>0 No noise detected. 1 Noise detected in the received character in UART_D.</p> |
| 1 FE | <p>Framing Error Flag</p> <p>FE is set at the same time as RDRF when the receiver detects a logic 0 where the stop bits were expected. This suggests the receiver was not properly aligned to a character frame. To clear FE, read UART_S1 with FE set and then read the UART data register (UART_D).</p> <p>0 No framing error detected. This does not guarantee the framing is correct. 1 Framing error.</p> |
| 0 PF | <p>Parity Error Flag</p> <p>PF is set at the same time as RDRF when parity is enabled (PE = 1) and the parity bit in the received character does not agree with the expected parity value. To clear PF, read UART_S1 and then read the UART data register (UART_D).</p> <p>0 No parity error. 1 Parity error.</p> |

33.3.6 UART Status Register 2 (UARTx_S2)

This register contains one read-only status flag.

When using an internal oscillator in a LIN system, it is necessary to raise the break detection threshold one bit time. Under the worst case timing conditions allowed in LIN, it is possible that a 0x00 data character can appear to be 10.26 bit times long at a slave running 14% faster than the master. This would trigger normal break detection circuitry

Register definition

designed to detect a 10-bit break symbol. When the LBKDE bit is set, framing errors are inhibited and the break detection threshold changes from 10 bits to 11 bits, preventing false detection of a 0x00 data character as a LIN break symbol.

Address: Base address + 5h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|--------|---------|---|-------|-------|-------|-------|-----|
| Read | LBKDIF | RXEDGIF | 0 | RXINV | RWUID | BRK13 | LBKDE | RAF |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_S2 field descriptions

| Field | Description |
|---------------|--|
| 7 LBKDIF | <p>LIN Break Detect Interrupt Flag</p> <p>LBKDIF is set when the LIN break detect circuitry is enabled and a LIN break character is detected. LBKDIF is cleared by writing a 1 to it.</p> <p>0 No LIN break character has been detected. 1 LIN break character has been detected.</p> |
| 6 RXEDGIF | <p>RxD Pin Active Edge Interrupt Flag</p> <p>RXEDGIF is set when an active edge, falling if RXINV = 0, rising if RXINV=1, on the RxD pin occurs. RXEDGIF is cleared by writing a 1 to it.</p> <p>0 No active edge on the receive pin has occurred. 1 An active edge on the receive pin has occurred.</p> |
| 5 Reserved | <p>This field is reserved.</p> <p>This read-only field is reserved and always has the value 0.</p> |
| 4 RXINV | <p>Receive Data Inversion</p> <p>Setting this field reverses the polarity of the received data input.</p> <p>NOTE: Setting RXINV inverts the RxD input for all cases: data bits, start and stop bits, break, and idle.</p> <p>0 Receive data not inverted. 1 Receive data inverted.</p> |
| 3 RWUID | <p>Receive Wake Up Idle Detect</p> <p>RWUID controls whether the idle character that wakes up the receiver sets S1[IDLE].</p> <p>0 During receive standby state (RWU = 1), S1[IDLE] does not get set upon detection of an idle character. 1 During receive standby state (RWU = 1), S1[IDLE] gets set upon detection of an idle character.</p> |
| 2 BRK13 | <p>Break Character Generation Length</p> <p>BRK13 selects a longer transmitted break character length. Detection of a framing error is not affected by the state of this field.</p> <p>0 Break character is transmitted with length of 10 bit times (if M = 0, SBNS = 0) or 11 (if M = 1, SBNS = 0 or M = 0, SBNS = 1) or 12 (if M = 1, SBNS = 1). 1 Break character is transmitted with length of 13 bit times (if M = 0, SBNS = 0) or 14 (if M = 1, SBNS = 0 or M = 0, SBNS = 1) or 15 (if M = 1, SBNS = 1).</p> |

Table continues on the next page...

UARTx_S2 field descriptions (continued)

| Field | Description |
|------------|---|
| 1 LBKDE | <p>LIN Break Detection Enable</p> <p>LBKDE enables the break detection. While LBKDE is set, S1[FE] and S1[RDRF] flags are prevented from setting.</p> <p>0 Break detection is disabled.</p> <p>1 Break detection is enabled (Break character is detected at length 11 bit times (if C1[M] = 0, BDH[SBNS] = 0) or 12 (if C1[M] = 1, BDH[SBNS] = 0 or C1[M] = 0, BDH[SBNS] = 1) or 13 (if C1[M] = 1, BDH[SBNS] = 1)).</p> |
| 0 RAF | <p>Receiver Active Flag</p> <p>RAF is set when the UART receiver detects the beginning of a valid start bit, and RAF is cleared automatically when the receiver detects an idle line. This status flag can be used to check whether an UART character is being received before instructing the MCU to go to stop mode.</p> <p>0 UART receiver idle waiting for a start bit.</p> <p>1 UART receiver active (RxD input not idle).</p> |

33.3.7 UART Control Register 3 (UARTx_C3)

Address: Base address + 6h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|----|----|-------|-------|------|------|------|------|
| Read | R8 | T8 | TXDIR | TXINV | ORIE | NEIE | FEIE | PEIE |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_C3 field descriptions

| Field | Description |
|------------|---|
| 7 R8 | <p>Ninth Data Bit for Receiver</p> <p>When the UART is configured for 9-bit data (C1[M] = 1), R8 can be thought of as a ninth receive data bit to the left of the msb of the buffered data in the UART_D register. When reading 9-bit data, read R8 before reading UART_D because reading UART_D completes automatic flag clearing sequences that could allow R8 and UART_D to be overwritten with new data.</p> |
| 6 T8 | <p>Ninth Data Bit for Transmitter</p> <p>When the UART is configured for 9-bit data (C1[M] = 1), T8 may be thought of as a ninth transmit data bit to the left of the msb of the data in the UART_D register. When writing 9-bit data, the entire 9-bit value is transferred to the UART shift register after UART_D is written so T8 should be written, if it needs to change from its previous value, before UART_D is written. If T8 does not need to change in the new value, such as when it is used to generate mark or space parity, it need not be written each time UART_D is written.</p> |
| 5 TXDIR | <p>TxD Pin Direction in Single-Wire Mode</p> <p>When the UART is configured for single-wire half-duplex operation (LOOPS = RSRC = 1), this field determines the direction of data at the TxD pin.</p> |

Table continues on the next page...

UARTx_C3 field descriptions (continued)

| Field | Description |
|------------|--|
| | 0 TxD pin is an input in single-wire mode. 1 TxD pin is an output in single-wire mode. |
| 4 TXINV | Transmit Data Inversion Setting this field reverses the polarity of the transmitted data output. NOTE: Setting TXINV inverts the TxD output for all cases: data bits, start and stop bits, break, and idle. 0 Transmit data not inverted. 1 Transmit data inverted. |
| 3 ORIE | Overrun Interrupt Enable Enables the overrun flag (OR) to generate hardware interrupt requests. 0 OR interrupts disabled; use polling. 1 Hardware interrupt requested when OR is set. |
| 2 NEIE | Noise Error Interrupt Enable Enables the noise flag (NF) to generate hardware interrupt requests. 0 NF interrupts disabled; use polling). 1 Hardware interrupt requested when NF is set. |
| 1 FEIE | Framing Error Interrupt Enable Enables the framing error flag (FE) to generate hardware interrupt requests. 0 FE interrupts disabled; use polling). 1 Hardware interrupt requested when FE is set. |
| 0 PEIE | Parity Error Interrupt Enable Enables the parity error flag (PF) to generate hardware interrupt requests. 0 PF interrupts disabled; use polling). 1 Hardware interrupt requested when PF is set. |

33.3.8 UART Data Register (UARTx_D)

This register is actually two separate registers. Reads return the contents of the read-only receive data buffer and writes go to the write-only transmit data buffer. Reads and writes of this register are also involved in the automatic flag clearing mechanisms for the UART status flags.

Address: Base address + 7h offset

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|------|------|------|------|------|------|------|
| Read | R7T7 | R6T6 | R5T5 | R4T4 | R3T3 | R2T2 | R1T1 | R0T0 |
| Write | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

UARTx_D field descriptions

| Field | Description |
|-----------|---|
| 7 R7T7 | Read receive data buffer 7 or write transmit data buffer 7. |
| 6 R6T6 | Read receive data buffer 6 or write transmit data buffer 6. |
| 5 R5T5 | Read receive data buffer 5 or write transmit data buffer 5. |
| 4 R4T4 | Read receive data buffer 4 or write transmit data buffer 4. |
| 3 R3T3 | Read receive data buffer 3 or write transmit data buffer 3. |
| 2 R2T2 | Read receive data buffer 2 or write transmit data buffer 2. |
| 1 R1T1 | Read receive data buffer 1 or write transmit data buffer 1. |
| 0 R0T0 | Read receive data buffer 0 or write transmit data buffer 0. |

33.4 Functional description

The UART allows full-duplex, asynchronous, NRZ serial communication among the MCU and remote devices, including other MCUs.

The UART comprises a baud rate generator, transmitter, and receiver block. The transmitter and receiver operate independently, although they use the same baud rate generator. During normal operation, the MCU monitors the status of the UART, writes the data to be transmitted, and processes received data. The following describes each of the blocks of the UART.

33.4.1 Baud rate generation

As shown in the figure found [here](#), the clock source for the UART baud rate generator is the bus-rate clock.

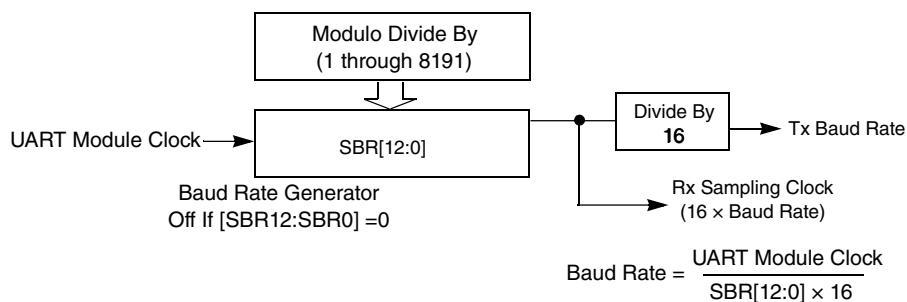


Figure 33-35. UART baud rate generation

UART communications require the transmitter and receiver, which typically derive baud rates from independent clock sources, to use the same baud rate. Allowed tolerance on this baud frequency depends on the details of how the receiver synchronizes to the leading edge of the start bit and how bit sampling is performed.

The MCU resynchronizes to bit boundaries on every high-to-low transition. In the worst case, there are no such transitions in the full 10- or 11-bit or 12-bit time character frame so any mismatch in baud rate is accumulated for the whole character time. For a Freescale UART system whose bus frequency is driven by a crystal, the allowed baud rate mismatch is about ± 4.5 percent for 8-bit data format and about ± 4 percent for 9-bit data format. Although baud rate modulo divider settings do not always produce baud rates that exactly match standard rates, it is normally possible to get within a few percent, which is acceptable for reliable communications.

33.4.2 Transmitter functional description

This section describes the overall block diagram for the UART transmitter, as well as specialized functions for sending break and idle characters.

The transmitter output (TxD) idle state defaults to logic high, UART_C3[TXINV] is cleared following reset. The transmitter output is inverted by setting UART_C3[TXINV]. The transmitter is enabled by setting the TE bit in UART_C2. This queues a preamble character that is one full character frame of the idle state. The transmitter then remains idle until data is available in the transmit data buffer. Programs store data into the transmit data buffer by writing to the UART data register (UART_D).

The central element of the UART transmitter is the transmit shift register that is 10 or 11 or 12 bits long depending on the setting in the UART_C1[M] control bit and UART_BDH[SBNS] bit. For the remainder of this section, assume UART_C1[M] is cleared, UART_BDH[SBNS] is also cleared, selecting the normal 8-bit data mode. In 8-bit data mode, the shift register holds a start bit, eight data bits, and a stop bit. When the transmit shift register is available for a new UART character, the value waiting in the

transmit data register is transferred to the shift register, synchronized with the baud rate clock, and the transmit data register empty (UART_S1[TDRE]) status flag is set to indicate another character may be written to the transmit data buffer at UART_D.

NOTE

Always read UART_S1 before writing to UART_D to allow data to be transmitted.

If no new character is waiting in the transmit data buffer after a stop bit is shifted out the TxD pin, the transmitter sets the transmit complete flag and enters an idle mode, with TxD high, waiting for more characters to transmit.

Writing 0 to UART_C2[TE] does not immediately release the pin to be a general-purpose I/O pin. Any transmit activity in progress must first be completed. This includes data characters in progress, queued idle characters, and queued break characters.

33.4.2.1 Send break and queued idle

UART_C2[SBK] sends break characters originally used to gain the attention of old teletype receivers. Break characters are a full character time of logic 0, 10 bit times including the start and stop bits. A longer break of 13 bit times can be enabled by setting UART_S2[BRK13]. Normally, a program would wait for UART_S1[TDRE] to become set to indicate the last character of a message has moved to the transmit shifter, write 1, and then write 0 to UART_C2[SBK]. This action queues a break character to be sent as soon as the shifter is available. If UART_C2[SBK] remains 1 when the queued break moves into the shifter, synchronized to the baud rate clock, an additional break character is queued. If the receiving device is another Freescale Semiconductor UART, the break characters are received as 0s in all eight data bits and a framing error (UART_S1[FE] = 1) occurs.

When idle-line wake-up is used, a full character time of idle (logic 1) is needed between messages to wake up any sleeping receivers. Normally, a program would wait for UART_S1[TDRE] to become set to indicate the last character of a message has moved to the transmit shifter, then write 0 and then write 1 to the UART_C2[TE] bit. This action queues an idle character to be sent as soon as the shifter is available. As long as the character in the shifter does not finish while UART_C2[TE] is cleared, the UART transmitter never actually releases control of the TxD pin. If there is a possibility of the shifter finishing while UART_C2[TE] is cleared, set the general-purpose I/O controls so the pin shared with TxD is an output driving a logic 1. This ensures that the TxD line looks like a normal idle line even if the UART loses control of the port pin between writing 0 and then 1 to UART_C2[TE].

The length of the break character is affected by the UART_S2[BRK13] and UART_C1[M] as shown below.

Table 33-39. Break character length

| BRK13 | M | SBNS | Break character length |
|-------|---|------|------------------------|
| 0 | 0 | 0 | 10 bit times |
| 0 | 0 | 1 | 11 bit times |
| 0 | 1 | 0 | 11 bit times |
| 0 | 1 | 1 | 12 bit times |
| 1 | 0 | 0 | 13 bit times |
| 1 | 0 | 1 | 14 bit times |
| 1 | 1 | 0 | 14 bit times |
| 1 | 1 | 1 | 15 bit times |

33.4.3 Receiver functional description

In this section, the receiver block diagram is a guide for the overall receiver functional description.

Next, the data sampling technique used to reconstruct receiver data is described in more detail. Finally, two variations of the receiver wakeup function are explained.

The receiver input is inverted by setting UART_S2[RXINV]. The receiver is enabled by setting the UART_C2[RE] bit. Character frames consist of a start bit of logic 0, eight (or nine) data bits (lsb first), and one (or two) stop bits of logic 1. For information about 9-bit data mode, refer to [8- and 9-bit data modes](#). For the remainder of this discussion, assume the UART is configured for normal 8-bit data mode.

After receiving the stop bit into the receive shifter, and provided the receive data register is not already full, the data character is transferred to the receive data register and the receive data register full (UART_S1[RDRF]) status flag is set. If UART_S1[RDRF] was already set indicating the receive data register (buffer) was already full, the overrun (OR) status flag is set and the new data is lost. Because the UART receiver is double-buffered, the program has one full character time after UART_S1[RDRF] is set before the data in the receive data buffer must be read to avoid a receiver overrun.

When a program detects that the receive data register is full (UART_S1[RDRF] = 1), it gets the data from the receive data register by reading UART_D. The UART_S1[RDRF] flag is cleared automatically by a two-step sequence normally satisfied in the course of the user's program that manages receive data. Refer to [Interrupts and status flags](#) for more details about flag clearing.

33.4.3.1 Data sampling technique

The UART receiver uses a 16× baud rate clock for sampling. The oversampling ratio is fixed at 16. The receiver starts by taking logic level samples at 16 times the baud rate to search for a falling edge on the RxD serial data input pin. A falling edge is defined as a logic 0 sample after three consecutive logic 1 samples. The 16× baud rate clock divides the bit time into 16 segments labeled UART_D[RT1] through UART_D[RT16]. When a falling edge is located, three more samples are taken at UART_D[RT3], UART_D[RT5], and UART_D[RT7] to make sure this was a real start bit and not merely noise. If at least two of these three samples are 0, the receiver assumes it is synchronized to a receive character.

The receiver then samples each bit time, including the start and stop bits, at UART_D[RT8], UART_D[RT9], and UART_D[RT10] to determine the logic level for that bit. The logic level is interpreted to be that of the majority of the samples taken during the bit time. In the case of the start bit, the bit is assumed to be 0 if at least two of the samples at UART_D[RT3], UART_D[RT5], and UART_D[RT7] are 0 even if one or all of the samples taken at UART_D[RT8], UART_D[RT9], and UART_D[RT10] are 1s. If any sample in any bit time, including the start and stop bits, in a character frame fails to agree with the logic level for that bit, the noise flag (UART_S1[NF]) is set when the received character is transferred to the receive data buffer.

The falling edge detection logic continuously looks for falling edges. If an edge is detected, the sample clock is resynchronized to bit times. This improves the reliability of the receiver in the presence of noise or mismatched baud rates. It does not improve worst case analysis because some characters do not have any extra falling edges anywhere in the character frame.

In the case of a framing error, provided the received character was not a break character, the sampling logic that searches for a falling edge is filled with three logic 1 samples so that a new start bit can be detected almost immediately.

In the case of a framing error, the receiver is inhibited from receiving any new characters until the framing error flag is cleared. The receive shift register continues to function, but a complete character cannot transfer to the receive data buffer if UART_S1[FE] remains set.

33.4.3.2 Receiver wake-up operation

Receiver wake-up is a hardware mechanism that allows an UART receiver to ignore the characters in a message intended for a different UART receiver. In such a system, all receivers evaluate the first character(s) of each message, and as soon as they determine the message is intended for a different receiver, they write logic 1 to the receiver wake up control field (UART_C2[RWU]). When UART_C2[RWU] is set, the status flags associated with the receiver, (with the exception of the idle bit, IDLE, when UART_S2[RWUID] is set), are inhibited from setting, thus eliminating the software overhead for handling the unimportant message characters. At the end of a message, or at the beginning of the next message, all receivers automatically force UART_C2[RWU] to 0, so all receivers wake up in time to look at the first character(s) of the next message.

33.4.3.2.1 Idle-line wakeup

When wake is cleared, the receiver is configured for idle-line wakeup. In this mode, UART_C2[RWU] is cleared automatically when the receiver detects a full character time of the idle-line level. The UART_C1[M] control field selects 8-bit or 9-bit data mode and UART_BDH[SBNS] selects 1-bit or 2-bit stop bit number that determines how many bit times of idle are needed to constitute a full character time, 10 or 11 or 12 bit times because of the start and stop bits.

When UART_C2[RWU] is 1 and UART_S2[RWUID] is 0, the idle condition that wakes up the receiver does not set UART_S1[IDLE]. The receiver wakes up and waits for the first data character of the next message that sets UART_S1[RDRF] and generates an interrupt, if enabled. When UART_S2[RWUID] is 1, any idle condition sets UART_S1[IDLE] flag and generates an interrupt if enabled, regardless of whether UART_C2[RWU] is 0 or 1.

The idle-line type (UART_C1[ILT]) control bit selects one of two ways to detect an idle line. When UART_C1[ILT] is cleared, the idle bit counter starts after the start bit so the stop bit and any logic 1s at the end of a character count toward the full character time of idle. When UART_C1[ILT] is set, the idle bit counter does not start until after a stop bit time, so the idle detection is not affected by the data in the last character of the previous message.

33.4.3.2.2 Address-mark wakeup

When wake is set, the receiver is configured for address-mark wakeup. In this mode, UART_C2[RWU] is cleared automatically when the receiver detects a, or two, if UART_BDH[SBNS] = 1, logic 1 in the most significant bits of a received character, eighth bit when UART_C1[M] is cleared and ninth bit when UART_C1[M] is set.

Address-mark wakeup allows messages to contain idle characters, but requires the msb be reserved for use in address frames. The one, or two, if `UART_BDH[SBNS] = 1`, logic 1s msb of an address frame clears the `UART_C2[RWU]` bit before the stop bits are received and sets the `UART_S1[RDRF]` flag. In this case, the character with the msb set is received even though the receiver was sleeping during most of this character time.

33.4.4 Interrupts and status flags

The UART system has one interrupt vector which has three separate interrupt types. One interrupt type is associated with the transmitter for `UART_S1[TDRE]` and `UART_S1[TC]` events. Another interrupt type is associated with the receiver for `RDRF`, `IDLE`, `RXEDGIF`, and `LBKDIF` events. A third type is used for `OR`, `NF`, `FE`, and `PF` error conditions. Each of these ten interrupt sources can be separately masked by local interrupt enable masks. The flags can be polled by software when the local masks are cleared to disable generation of hardware interrupt requests.

The UART transmitter has two status flags that can optionally generate hardware interrupt requests. Transmit data register empty (`UART_S1[TDRE]`) indicates when there is room in the transmit data buffer to write another transmit character to `UART_D`. If the transmit interrupt enable (`UART_C2[TIE]`) bit is set, a hardware interrupt is requested when `UART_S1[TDRE]` is set. Transmit complete (`UART_S1[TC]`) indicates that the transmitter is finished transmitting all data, preamble, and break characters and is idle with `TxD` at the inactive level. This flag is often used in systems with modems to determine when it is safe to turn off the modem. If the transmit complete interrupt enable (`UART_C2[TCIE]`) bit is set, a hardware interrupt is requested when `UART_S1[TC]` is set. Instead of hardware interrupts, software polling may be used to monitor the `UART_S1[TDRE]` and `UART_S1[TC]` status flags if the corresponding `UART_C2[TIE]` or `UART_C2[TCIE]` local interrupt masks are cleared.

When a program detects that the receive data register is full (`UART_S1[RDRF] = 1`), it gets the data from the receive data register by reading `UART_D`. The `UART_S1[RDRF]` flag is cleared by reading `UART_S1` while `UART_S1[RDRF]` is set and then reading `UART_D`.

When polling is used, this sequence is naturally satisfied in the normal course of the user program. If hardware interrupts are used, `UART_S1` must be read in the interrupt service routine (ISR). Normally, this is done in the ISR anyway to check for receive errors, so the sequence is automatically satisfied.

The IDLE status flag includes logic that prevents it from getting set repeatedly when the RxD line remains idle for an extended period of time. IDLE is cleared by reading UART_S1 while UART_S1[IDLE] is set and then reading UART_D. After UART_S1[IDLE] has been cleared, it cannot become set again until the receiver has received at least one new character and has set UART_S1[RDRF].

If the associated error was detected in the received character that caused UART_S1[RDRF] to be set, the error flags - noise flag (UART_S1[NF]), framing error (UART_S1[FE]), and parity error flag (UART_S1[PF]) - are set at the same time as UART_S1[RDRF]. These flags are not set in overrun cases.

If UART_S1[RDRF] was already set when a new character is ready to be transferred from the receive shifter to the receive data buffer, the overrun (UART_S1[OR]) flag is set instead of the data along with any associated NF, FE, or PF condition is lost.

At any time, an active edge on the RxD serial data input pin causes the UART_S2[RXEDGIF] flag to set. The UART_S2[RXEDGIF] flag is cleared by writing a 1 to it. This function depends on the receiver being enabled (UART_C2[RE] = 1).

33.4.5 Baud rate tolerance

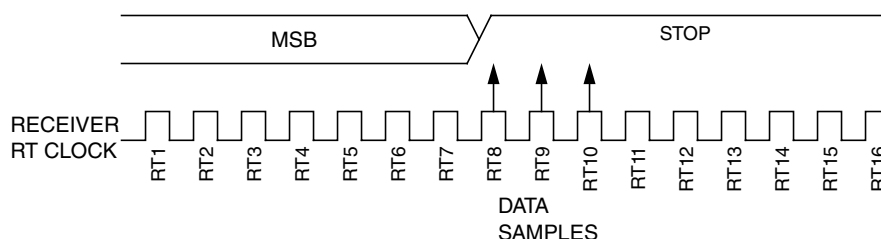
A transmitting device may operate at a baud rate below or above that of the receiver.

Accumulated bit time misalignment can cause one of the three stop bit data samples (RT8, RT9, and RT10) to fall outside the actual stop bit. A noise error will occur if the RT8, RT9, and RT10 samples are not all the same logical values. A framing error will occur if the receiver clock is misaligned in such a way that the majority of the RT8, RT9, and RT10 stop bit samples are a logic zero.

As the receiver samples an incoming frame, it re-synchronizes the RT clock on any valid falling edge within the frame. Resynchronization within frames will correct a misalignment between transmitter bit times and receiver bit times.

33.4.5.1 Slow data tolerance

Figure 33-36 shows how much a slow received frame can be misaligned without causing a noise error or a framing error. The slow stop bit begins at RT8 instead of RT1 but arrives in time for the stop bit data samples at RT8, RT9, and RT10.

**Figure 33-36. Slow data**

For an 8-bit data and 1 stop bit character, data sampling of the stop bit takes the receiver 9 bit times x 16 RT cycles + 10 RT cycles = 154 RT cycles.

With the misaligned character shown in [Figure 33-36](#), the receiver counts 154 RT cycles at the point when the count of the transmitting device is 9 bit times x 16 RT cycles + 3 RT cycles = 147 RT cycles.

The maximum percent difference between the receiver count and the transmitter count of a slow 8-bit data and 1 stop bit character with no errors is:

$$((154 - 147) / 154) \times 100 = 4.54\%$$

For a 9-bit data or 2 stop bits character, data sampling of the stop bit takes the receiver 10 bit times x 16 RT cycles + 10 RT cycles = 170 RT cycles.

With the misaligned character shown in [Figure 33-36](#), the receiver counts 170 RT cycles at the point when the count of the transmitting device is 10 bit times x 16 RT cycles + 3 RT cycles = 163 RT cycles.

The maximum percent difference between the receiver count and the transmitter count of a slow 9-bit or 2 stop bits character with no errors is:

$$((170 - 163) / 170) \times 100 = 4.12\%$$

For a 9-bit data and 2 stop bit character, data sampling of the stop bit takes the receiver 11 bit times x 16 RT cycles + 10 RT cycles = 186 RT cycles.

With the misaligned character shown in [Figure 33-36](#), the receiver counts 186 RT cycles at the point when the count of the transmitting device is 11 bit times x 16 RT cycles + 3 RT cycles = 179 RT cycles.

The maximum percent difference between the receiver count and the transmitter count of a slow 9-bit and 2 stop bits character with no errors is: $((186 - 179) / 186) \times 100 = 3.76\%$

33.4.5.2 Fast data tolerance

[Figure 33-37](#) shows how much a fast received frame can be misaligned. The fast stop bit ends at RT10 instead of RT16 but is still sampled at RT8, RT9, and RT10.

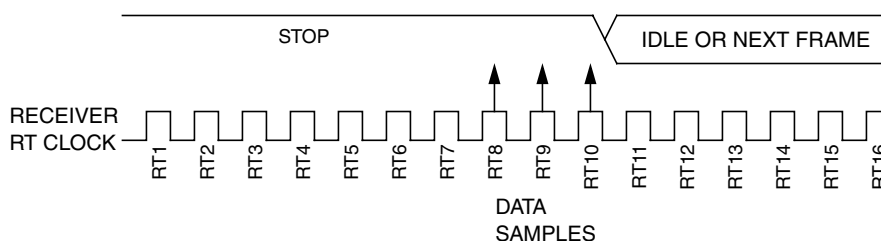


Figure 33-37. Fast data

For an 8-bit data and 1 stop bit character, data sampling of the stop bit takes the receiver 9 bit times x 16 RT cycles + 10 RT cycles = 154 RT cycles.

With the misaligned character shown in [Figure 33-37](#), the receiver counts 154 RT cycles at the point when the count of the transmitting device is 10 bit times x 16 RT cycles = 160 RT cycles.

The maximum percent difference between the receiver count and the transmitter count of a fast 8-bit and 1 stop bit character with no errors is:

$$((154 - 160) / 154) \times 100 = 3.90\%$$

For a 9-bit data or 2 stop bits character, data sampling of the stop bit takes the receiver 10 bit times x 16 RT cycles + 10 RT cycles = 170 RT cycles.

With the misaligned character shown in, the receiver counts 170 RT cycles at the point when the count of the transmitting device is 11 bit times x 16 RT cycles = 176 RT cycles.

The maximum percent difference between the receiver count and the transmitter count of a fast 9-bit or 2 stop bits character with no errors is:

$$((170 - 176) / 170) \times 100 = 3.53\%$$

For a 9-bit data and 2 stop bits character, data sampling of the stop bit takes the receiver 11 bit times x 16 RT cycles + 10 RT cycles = 186 RT cycles.

With the misaligned character shown in, the receiver counts 186 RT cycles at the point when the count of the transmitting device is 12 bit times x 16 RT cycles = 192 RT cycles.

The maximum percent difference between the receiver count and the transmitter count of a fast 9-bit and 2 stop bits character with no errors is:

$$((186 - 192) / 186) \times 100 = 3.23\%$$

33.4.6 Additional UART functions

The following sections describe additional UART functions.

33.4.6.1 8- and 9-bit data modes

The UART system, transmitter and receiver, can be configured to operate in 9-bit data mode by setting UART_C1[M]. In 9-bit mode, there is a ninth data bit to the left of the most significant bit of the UART data register. For the transmit data buffer, this bit is stored in T8 in UART_C3. For the receiver, the ninth bit is held in UART_C3[R8].

For coherent writes to the transmit data buffer, write to UART_C3[T8] before writing to UART_D.

If the bit value to be transmitted as the ninth bit of a new character is the same as for the previous character, it is not necessary to write to UART_C3[T8] again. When data is transferred from the transmit data buffer to the transmit shifter, the value in UART_C3[T8] is copied at the same time data is transferred from UART_D to the shifter.

The 9-bit data mode is typically used with parity to allow eight bits of data plus the parity in the ninth bit, or it is used with address-mark wake-up so the ninth data bit can serve as the wakeup bit. In custom protocols, the ninth bit can also serve as a software-controlled marker.

33.4.6.2 Stop mode operation

During all stop modes, clocks to the UART module are halted.

No UART module registers are affected in Stop mode.

The receive input active edge detect circuit remains active in Stop mode. An active edge on the receive input brings the CPU out of Stop mode if the interrupt is not masked (UART_BDH[RXEDGIE] = 1).

Because the clocks are halted, the UART module resumes operation upon exit from stop, only in Stop mode. Software must ensure stop mode is not entered while there is a character (including preamble, break and normal data) being transmitted out of or received into the UART module, that means UART_S1[TC] = 1, UART_S1[TDRE] = 1, and UART_S2[RAF] = 0 must all meet before entering stop mode.

33.4.6.3 Loop mode

When UART_C1[LOOPS] is set, the UART_C1[RSRC] bit in the same register chooses between loop mode (UART_C1[RSRC] = 0) or single-wire mode (UART_C1[RSRC] = 1). Loop mode is sometimes used to check software, independent of connections in the external system, to help isolate system problems. In this mode, the internal loop back connection from the transmitter to the receiver causes the receiver to receive characters that are sent out by the transmitter.

33.4.6.4 Single-wire operation

When UART_C1[LOOPS] is set, UART_C1[RSRC] chooses between loop mode (UART_C1[RSRC] = 0) or single-wire mode (UART_C1[RSRC] = 1). Single-wire mode implements a half-duplex serial connection. The receiver is internally connected to the transmitter output and to the TxD pin. The RxD pin is not used and reverts to a general-purpose port I/O pin.

In single-wire mode, the UART_C3[TXDIR] bit controls the direction of serial data on the TxD pin. When UART_C3[TXDIR] is cleared, the TxD pin is an input to the UART receiver and the transmitter is temporarily disconnected from the TxD pin so an external device can send serial data to the receiver. When UART_C3[TXDIR] is set, the TxD pin is an output driven by the transmitter. In single-wire mode, the transmitter output is internally connected to the receiver input and the RxD pin is not used by the UART, so it reverts to a general-purpose port I/O pin.

Chapter 34

General-Purpose Input/Output (GPIO)

34.1 Introduction

NOTE

For the chip-specific implementation details of this module's instances, see the chip configuration information.

The general-purpose input and output (GPIO) module is accessible via the peripheral bus and also communicates to the processor core via a zero wait state interface (IOPORT) for maximum pin performance. The GPIO registers support 8-bit, 16-bit or 32-bit accesses.

The GPIO data direction and output data registers control the direction and output data of each pin when the pin is configured for the GPIO function. The GPIO input data register displays the logic value on each pin when the pin is configured for any digital function, provided the corresponding Port Control and Interrupt module for that pin is enabled.

Efficient bit manipulation of the general-purpose outputs is supported through the addition of set, clear, and toggle write-only registers for each port output data register.

34.1.1 Features

- Features of the GPIO module include:
 - Port Data Input register visible in all digital pin-multiplexing modes
 - Port Data Output register with corresponding set/clear/toggle registers
 - Port Data Direction register
 - Zero wait state access to GPIO registers through IOPORT

NOTE

The GPIO module is clocked by system clock.

34.1.2 Modes of operation

The following table depicts different modes of operation and the behavior of the GPIO module in these modes.

Table 34-1. Modes of operation

| Modes of operation | Description |
|--------------------|------------------------------------|
| Run | The GPIO module operates normally. |
| Wait | The GPIO module operates normally. |
| Stop | The GPIO module is disabled. |
| Debug | The GPIO module operates normally. |

34.1.3 GPIO signal descriptions

Table 34-2. GPIO signal descriptions

| GPIO signal descriptions | Description | I/O |
|--------------------------|------------------------------|-----|
| PTA7–PTA0 | General-purpose input/output | I/O |
| PTB7–PTB0 | General-purpose input/output | I/O |
| PTC7–PTC0 | General-purpose input/output | I/O |
| PTD7–PTD0 | General-purpose input/output | I/O |
| PTE7–PTE0 | General-purpose input/output | I/O |
| PTF7–PTF0 | General-purpose input/output | I/O |
| PTG7–PTG0 | General-purpose input/output | I/O |
| PTH7–PTH0 | General-purpose input/output | I/O |
| PTI7–PTI0 ¹ | General-purpose input/output | I/O |

1. This device has only PTI6–PTI0.

NOTE

Not all pins within each port are implemented on each device. See the chapter on signal multiplexing for the number of GPIO ports available in the device.

34.1.3.1 Detailed signal description

Table 34-3. GPIO interface-detailed signal descriptions

| Signal | I/O | Description | |
|-----------|-----|------------------------------|---------------------------------|
| PTA7–PTA0 | I/O | General-purpose input/output | |
| PTB7–PTB0 | | State meaning | Asserted: The pin is logic 1. |
| PTC7–PTC0 | | | Deasserted: The pin is logic 0. |

Table continues on the next page...

Table 34-3. GPIO interface-detailed signal descriptions (continued)

| Signal | I/O | Description | |
|---|-----|-------------|---|
| PTD7–PTD0 PTE7–PTE0 PTF7–PTF0 PTG7–PTG0 PTH7–PTH0 PTI7–PTI0 ¹ | | Timing | <p>Assertion: When output, this signal occurs on the rising-edge of the system clock. For input, it may occur at any time and input may be asserted asynchronously to the system clock.</p> <p>Deassertion: When output, this signal occurs on the rising-edge of the system clock. For input, it may occur at any time and input may be asserted asynchronously to the system clock.</p> |

1. This device has only PTI6–PTI0.

NOTE

Not all pins within each port are implemented on each device.
See the chapter on signal multiplexing for the number of GPIO ports available in the device.

34.2 Memory map and register definition

The GPIO module has two address slots on AIPS-Lite peripheral bridge to keep software compatibility between Freescale product portfolios. All of the GPIO registers could be accessed either by using base address of 0x400F_F000 or 0x4000_F000. It is recommended to use 0x400F_F000 as the base address of GPIO module, and the register memory map of this chapter is also based on the base address of 0x400F_F000.

Any read or write access to the GPIO memory space that is outside the valid memory map results in a bus error.

34.2.1 GPIO/FGPIO register bits assignment

In this device, each 8-bit port pin is mapped to the 32-bit GPIO/FGPIO registers as described in the table.

Table 34-4. GPIOA/FGPIOA register bits assignment

| Port pin | Register bit |
|----------|--------------|
| PTD7 | 31 |
| PTD6 | 30 |
| PTD5 | 29 |
| PTD4 | 28 |
| PTD3 | 27 |
| PTD2 | 26 |
| PTD1 | 25 |
| PTD0 | 24 |
| PTC7 | 23 |
| PTC6 | 22 |
| PTC5 | 21 |
| PTC4 | 20 |
| PTC3 | 19 |
| PTC2 | 18 |
| PTC1 | 17 |
| PTC0 | 16 |
| PTB7 | 15 |
| PTB6 | 14 |
| PTB5 | 13 |
| PTB4 | 12 |
| PTB3 | 11 |
| PTB2 | 10 |
| PTB1 | 9 |
| PTB0 | 8 |
| PTA7 | 7 |
| PTA6 | 6 |
| PTA5 | 5 |
| PTA4 | 4 |
| PTA3 | 3 |
| PTA2 | 2 |
| PTA1 | 1 |
| PTA0 | 0 |

Table 34-5. GPIOB/FGPIOB register bits assignment

| Port pin | Register bit |
|----------|--------------|
| PTH7 | 31 |
| PTH6 | 30 |
| PTH5 | 29 |
| PTH4 | 28 |
| PTH3 | 27 |
| PTH2 | 26 |
| PTH1 | 25 |
| PTH0 | 24 |
| PTG7 | 23 |
| PTG6 | 22 |
| PTG5 | 21 |
| PTG4 | 20 |
| PTG3 | 19 |
| PTG2 | 18 |
| PTG1 | 17 |
| PTG0 | 16 |
| PTF7 | 15 |
| PTF6 | 14 |
| PTF5 | 13 |
| PTF4 | 12 |
| PTF3 | 11 |
| PTF2 | 10 |
| PTF1 | 9 |
| PTF0 | 8 |
| PTE7 | 7 |
| PTE6 | 6 |
| PTE5 | 5 |
| PTE4 | 4 |
| PTE3 | 3 |
| PTE2 | 2 |
| PTE1 | 1 |
| PTE0 | 0 |

Table 34-6. GPIOC/FGPIOC register bits assignment

| Port pin | Register bit |
|----------|--------------|
| Reserved | 31 |
| Reserved | 30 |
| Reserved | 29 |
| Reserved | 28 |
| Reserved | 27 |
| Reserved | 26 |
| Reserved | 25 |
| Reserved | 24 |
| Reserved | 23 |
| Reserved | 22 |
| Reserved | 21 |
| Reserved | 20 |
| Reserved | 19 |
| Reserved | 18 |
| Reserved | 17 |
| Reserved | 16 |
| Reserved | 15 |
| Reserved | 14 |
| Reserved | 13 |
| Reserved | 12 |
| Reserved | 11 |
| Reserved | 10 |
| Reserved | 9 |
| Reserved | 8 |
| Reserved | 7 |
| PTI6 | 6 |
| PTI5 | 5 |
| PTI4 | 4 |
| PTI3 | 3 |
| PTI2 | 2 |
| PTI1 | 1 |
| PTI0 | 0 |

GPIO memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|-----------------------|-------------|----------------------------|
| 400F_F000 | Port Data Output Register (GPIOA_PDOR) | 32 | R/W | 0000_0000h | 34.2.2/679 |
| 400F_F004 | Port Set Output Register (GPIOA_PSOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.3/680 |
| 400F_F008 | Port Clear Output Register (GPIOA_PCOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.4/680 |
| 400F_F00C | Port Toggle Output Register (GPIOA_PTOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.5/681 |

Table continues on the next page...

GPIO memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|-------------------------------|---|------------------------|-----------------------|--------------------|----------------------------|
| 400F_F010 | Port Data Input Register (GPIOA_PDIR) | 32 | R | 0000_0000h | 34.2.6/681 |
| 400F_F014 | Port Data Direction Register (GPIOA_PDDR) | 32 | R/W | 0000_0000h | 34.2.7/682 |
| 400F_F018 | Port Input Disable Register (GPIOA_PIDR) | 32 | R/W | FFFF_FFFFh | 34.2.8/682 |
| 400F_F040 | Port Data Output Register (GPIOB_PDOR) | 32 | R/W | 0000_0000h | 34.2.2/679 |
| 400F_F044 | Port Set Output Register (GPIOB_PSOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.3/680 |
| 400F_F048 | Port Clear Output Register (GPIOB_PCOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.4/680 |
| 400F_F04C | Port Toggle Output Register (GPIOB_PTOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.5/681 |
| 400F_F050 | Port Data Input Register (GPIOB_PDIR) | 32 | R | 0000_0000h | 34.2.6/681 |
| 400F_F054 | Port Data Direction Register (GPIOB_PDDR) | 32 | R/W | 0000_0000h | 34.2.7/682 |
| 400F_F058 | Port Input Disable Register (GPIOB_PIDR) | 32 | R/W | FFFF_FFFFh | 34.2.8/682 |
| 400F_F080 | Port Data Output Register (GPIOC_PDOR) | 32 | R/W | 0000_0000h | 34.2.2/679 |
| 400F_F084 | Port Set Output Register (GPIOC_PSOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.3/680 |
| 400F_F088 | Port Clear Output Register (GPIOC_PCOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.4/680 |
| 400F_F08C | Port Toggle Output Register (GPIOC_PTOR) | 32 | W (always reads 0) | 0000_0000h | 34.2.5/681 |
| 400F_F090 | Port Data Input Register (GPIOC_PDIR) | 32 | R | 0000_0000h | 34.2.6/681 |
| 400F_F094 | Port Data Direction Register (GPIOC_PDDR) | 32 | R/W | 0000_0000h | 34.2.7/682 |
| 400F_F098 | Port Input Disable Register (GPIOC_PIDR) | 32 | R/W | FFFF_FFFFh | 34.2.8/682 |

34.2.2 Port Data Output Register (GPIOx_PDOR)

This register configures the logic levels that are driven on each general-purpose output pins.

NOTE

Do not modify pin configuration registers associated with pins not available in your selected package. All unbonded pins not available in your package will default to DISABLE state for lowest power consumption.

Memory map and register definition

Address: Base address + 0h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PDO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | PDO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

GPIOx_PDOR field descriptions

| Field | Description |
|-------|--|
| PDO | <p>Port Data Output</p> <p>Register bits for unbonded pins return a undefined value when read.</p> <p>0 Logic level 0 is driven on pin, provided pin is configured for general-purpose output.</p> <p>1 Logic level 1 is driven on pin, provided pin is configured for general-purpose output.</p> |

34.2.3 Port Set Output Register (GPIOx_PSOR)

This register configures whether to set the fields of the PDOR.

Address: Base address + 4h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | PTSO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

GPIOx_PSOR field descriptions

| Field | Description |
|-------|--|
| PTSO | <p>Port Set Output</p> <p>Writing to this register will update the contents of the corresponding bit in the PDOR as follows:</p> <p>0 Corresponding bit in PDORn does not change.</p> <p>1 Corresponding bit in PDORn is set to logic 1.</p> |

34.2.4 Port Clear Output Register (GPIOx_PCOR)

This register configures whether to clear the fields of PDOR.

Address: Base address + 8h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | PTCO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

GPIOx_PCOR field descriptions

| Field | Description |
|-------|---|
| PTCO | Port Clear Output Writing to this register will update the contents of the corresponding bit in the Port Data Output Register (PDOR) as follows: 0 Corresponding bit in PDORn does not change. 1 Corresponding bit in PDORn is cleared to logic 0. |

34.2.5 Port Toggle Output Register (GPIOx_PTOR)

Address: Base address + Ch offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | PTTO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

GPIOx_PTOR field descriptions

| Field | Description |
|-------|--|
| PTTO | Port Toggle Output Writing to this register will update the contents of the corresponding bit in the PDOR as follows: 0 Corresponding bit in PDORn does not change. 1 Corresponding bit in PDORn is set to the inverse of its existing logic state. |

34.2.6 Port Data Input Register (GPIOx_PDIR)**NOTE**

Do not modify pin configuration registers associated with pins not available in your selected package. All unbonded pins not available in your package will default to DISABLE state for lowest power consumption.

Address: Base address + 10h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PDI | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

GPIOx_PDIR field descriptions

| Field | Description |
|-------|--|
| PDI | <p>Port Data Input</p> <p>Reads 0 at the unimplemented pins for a particular device. Pins that are not configured for a digital function read 0. If the Port Control and Interrupt module is disabled, then the corresponding bit in PDIR does not update.</p> <p>0 Pin logic level is logic 0, or is not configured for use by digital function.</p> <p>1 Pin logic level is logic 1.</p> |

34.2.7 Port Data Direction Register (GPIOx_PDDR)

The PDDR configures the individual port pins for input or output.

Address: Base address + 14h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

GPIOx_PDDR field descriptions

| Field | Description |
|-------|--|
| PDD | <p>Port Data Direction</p> <p>Configures individual port pins for input or output.</p> <p>0 Pin is configured as general-purpose input, for the GPIO function. The pin will be high-Z if the port input is disabled in GPIOx_PIDR register.</p> <p>1 Pin is configured as general-purpose output, for the GPIO function.</p> |

34.2.8 Port Input Disable Register (GPIOx_PIDR)

Address: Base address + 18h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | PID | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | |

GPIOx_PIDR field descriptions

| Field | Description |
|-------|--|
| PID | <p>Port Input Disable</p> <p>0 Pin is configured for General Purpose Input, provided the pin is configured for any digital function.</p> <p>1 Pin is not configured as General Purpose Input. Corresponding Port Data Input Register bit will read zero.</p> |

34.3 FGPIO memory map and register definition

The GPIO registers are also aliased to the IOPORT interface on the Cortex-M0+ from address 0xF800_0000.

Accesses via the IOPORT interface occur in parallel with any instruction fetches and will therefore complete in a single cycle. This aliased Fast GPIO memory map is called FGPIO.

Any read or write access to the FGPIO memory space that is outside the valid memory map results in a bus error. All register accesses complete with zero wait states, except error accesses which complete with one wait state.

34.3.1 GPIO/FGPIO register bits assignment

In this device, each 8-bit port pin is mapped to the 32-bit GPIO/FGPIO registers as described in the table.

Table 34-39. GPIOA/FGPIOA register bits assignment

| Port pin | Register bit |
|----------|--------------|
| PTD7 | 31 |
| PTD6 | 30 |
| PTD5 | 29 |
| PTD4 | 28 |
| PTD3 | 27 |
| PTD2 | 26 |
| PTD1 | 25 |
| PTD0 | 24 |
| PTC7 | 23 |
| PTC6 | 22 |
| PTC5 | 21 |
| PTC4 | 20 |
| PTC3 | 19 |
| PTC2 | 18 |
| PTC1 | 17 |
| PTC0 | 16 |
| PTB7 | 15 |
| PTB6 | 14 |
| PTB5 | 13 |
| PTB4 | 12 |
| PTB3 | 11 |
| PTB2 | 10 |
| PTB1 | 9 |
| PTB0 | 8 |
| PTA7 | 7 |
| PTA6 | 6 |
| PTA5 | 5 |
| PTA4 | 4 |
| PTA3 | 3 |
| PTA2 | 2 |
| PTA1 | 1 |
| PTA0 | 0 |

Table 34-40. GPIOB/FGPIOB register bits assignment

| Port pin | Register bit |
|----------|--------------|
| PTH7 | 31 |
| PTH6 | 30 |
| PTH5 | 29 |
| PTH4 | 28 |
| PTH3 | 27 |
| PTH2 | 26 |
| PTH1 | 25 |
| PTH0 | 24 |
| PTG7 | 23 |
| PTG6 | 22 |
| PTG5 | 21 |
| PTG4 | 20 |
| PTG3 | 19 |
| PTG2 | 18 |
| PTG1 | 17 |
| PTG0 | 16 |
| PTF7 | 15 |
| PTF6 | 14 |
| PTF5 | 13 |
| PTF4 | 12 |
| PTF3 | 11 |
| PTF2 | 10 |
| PTF1 | 9 |
| PTF0 | 8 |
| PTE7 | 7 |
| PTE6 | 6 |
| PTE5 | 5 |
| PTE4 | 4 |
| PTE3 | 3 |
| PTE2 | 2 |
| PTE1 | 1 |
| PTE0 | 0 |

Table 34-41. GPIOC/FGPIOC register bits assignment

| Register bit | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|------|------|------|------|------|------|------|
| Port pin | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved | PTI6 | PTI5 | PTI4 | PTI3 | PTI2 | PTI1 | PTI0 |

FGPIO memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|-----------------------|-------------|----------------------------|
| F800_0000 | Port Data Output Register (FGPIOA_PDOR) | 32 | R/W | 0000_0000h | 34.3.2/685 |
| F800_0004 | Port Set Output Register (FGPIOA_PSOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.3/685 |
| F800_0008 | Port Clear Output Register (FGPIOA_PCOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.4/686 |
| F800_000C | Port Toggle Output Register (FGPIOA_PTOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.5/686 |
| F800_0010 | Port Data Input Register (FGPIOA_PDIR) | 32 | R | 0000_0000h | 34.3.6/687 |
| F800_0014 | Port Data Direction Register (FGPIOA_PDDR) | 32 | R/W | 0000_0000h | 34.3.7/687 |
| F800_0018 | Port Input Disable Register (FGPIOA_PIDR) | 32 | R/W | FFFF_FFFFh | 34.3.8/688 |
| F800_0040 | Port Data Output Register (FGPIOB_PDOR) | 32 | R/W | 0000_0000h | 34.3.2/685 |
| F800_0044 | Port Set Output Register (FGPIOB_PSOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.3/685 |
| F800_0048 | Port Clear Output Register (FGPIOB_PCOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.4/686 |
| F800_004C | Port Toggle Output Register (FGPIOB_PTOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.5/686 |
| F800_0050 | Port Data Input Register (FGPIOB_PDIR) | 32 | R | 0000_0000h | 34.3.6/687 |
| F800_0054 | Port Data Direction Register (FGPIOB_PDDR) | 32 | R/W | 0000_0000h | 34.3.7/687 |
| F800_0058 | Port Input Disable Register (FGPIOB_PIDR) | 32 | R/W | FFFF_FFFFh | 34.3.8/688 |
| F800_0080 | Port Data Output Register (FGPIOC_PDOR) | 32 | R/W | 0000_0000h | 34.3.2/685 |
| F800_0084 | Port Set Output Register (FGPIOC_PSOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.3/685 |

Table continues on the next page...

FGPIO memory map (continued)

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/page |
|------------------------|--|-----------------|-----------------------|-------------|----------------------------|
| F800_0088 | Port Clear Output Register (FGPIOC_PCOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.4/686 |
| F800_008C | Port Toggle Output Register (FGPIOC_PTOR) | 32 | W (always reads 0) | 0000_0000h | 34.3.5/686 |
| F800_0090 | Port Data Input Register (FGPIOC_PDIR) | 32 | R | 0000_0000h | 34.3.6/687 |
| F800_0094 | Port Data Direction Register (FGPIOC_PDDR) | 32 | R/W | 0000_0000h | 34.3.7/687 |
| F800_0098 | Port Input Disable Register (FGPIOC_PIDR) | 32 | R/W | FFFF_FFFFh | 34.3.8/688 |

34.3.2 Port Data Output Register (FGPIOx_PDOR)

This register configures the logic levels that are driven on each general-purpose output pins.

Address: Base address + 0h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PDO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

FGPIOx_PDOR field descriptions

| Field | Description |
|-------|---|
| PDO | <p>Port Data Output</p> <p>Unimplemented pins for a particular device read as zero.</p> <p>0 Logic level 0 is driven on pin, provided pin is configured for general-purpose output.</p> <p>1 Logic level 1 is driven on pin, provided pin is configured for general-purpose output.</p> |

34.3.3 Port Set Output Register (FGPIOx_PSOR)

This register configures whether to set the fields of the PDOR.

Address: Base address + 4h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | PTSO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

FGPIOx_PSOR field descriptions

| Field | Description |
|-------|--|
| PTSO | <p>Port Set Output</p> <p>Writing to this register will update the contents of the corresponding bit in the PDOR as follows:</p> <p>0 Corresponding bit in PDORn does not change.</p> <p>1 Corresponding bit in PDORn is set to logic 1.</p> |

34.3.4 Port Clear Output Register (FGPIOx_PCOR)

This register configures whether to clear the fields of PDOR.

Address: Base address + 8h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | PTCO | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

FGPIOx_PCOR field descriptions

| Field | Description |
|-------|--|
| PTCO | <p>Port Clear Output</p> <p>Writing to this register will update the contents of the corresponding bit in the Port Data Output Register (PDOR) as follows:</p> <p>0 Corresponding bit in PDORn does not change.</p> <p>1 Corresponding bit in PDORn is cleared to logic 0.</p> |

34.3.5 Port Toggle Output Register (FGPIOx_PTOR)

Address: Base address + Ch offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | | | | | | | | | | | | | | | | | 0 | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | PTTO | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

FGPIOx_PTOR field descriptions

| Field | Description |
|-------|---|
| PTTO | <p>Port Toggle Output</p> <p>Writing to this register will update the contents of the corresponding bit in the PDOR as follows:</p> |

FGPIOx_PTOR field descriptions (continued)

| Field | Description |
|-------|---|
| 0 | Corresponding bit in PDORn does not change. |
| 1 | Corresponding bit in PDORn is set to the inverse of its existing logic state. |

34.3.6 Port Data Input Register (FGPIOx_PDIR)

Address: Base address + 10h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PDI | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FGPIOx_PDIR field descriptions

| Field | Description |
|-------|--|
| PDI | <p>Port Data Input</p> <p>Reads 0 at the unimplemented pins for a particular device. Pins that are not configured for a digital function read 0. If the Port Control and Interrupt module is disabled, then the corresponding bit in PDIR does not update.</p> <p>0 Pin logic level is logic 0, or is not configured for use by digital function.</p> <p>1 Pin logic level is logic 1.</p> |

34.3.7 Port Data Direction Register (FGPIOx_PDDR)

The PDDR configures the individual port pins for input or output.

Address: Base address + 14h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | PDD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

FGPIOx_PDDR field descriptions

| Field | Description |
|-------|---|
| PDD | <p>Port Data Direction</p> <p>Configures individual port pins for input or output.</p> <p>0 Pin is configured as general-purpose input, for the GPIO function. The pin will be high-Z if the port input is disabled in FGPIOx_PDIR register.</p> <p>1 Pin is configured as general-purpose output, for the GPIO function.</p> |

34.3.8 Port Input Disable Register (FGPIOx_PIDR)

Address: Base address + 18h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

FGPIOx_PIDR field descriptions

| Field | Description |
|-------|--|
| PID | <p>Port Input Disable</p> <p>0 Pin is configured for General Purpose Input, provided the pin is configured for any digital function.</p> <p>1 Pin is not configured as General Purpose Input. Corresponding Port Data Input Register bit will read zero.</p> |

34.4 Functional description

34.4.1 General-purpose input

The logic state of each pin is available via the Port Data Input registers, provided the pin is configured for a digital function and the corresponding Port Control and Interrupt module is enabled.

34.4.2 General-purpose output

The logic state of each pin can be controlled via the port data output registers and port data direction registers, provided the pin is configured for the GPIO function. The following table depicts the conditions for a pin to be configured as input/output.

| If | Then |
|--|--|
| A pin is configured for the GPIO function and the corresponding port data direction register bit is clear. | The pin is configured as an input. |
| A pin is configured for the GPIO function and the corresponding port data direction register bit is set. | The pin is configured as an output and the logic state of the pin is equal to the corresponding port data output register. |

To facilitate efficient bit manipulation on the general-purpose outputs, pin data set, pin data clear, and pin data toggle registers exist to allow one or more outputs within one port to be set, cleared, or toggled from a single register write.

The corresponding Port Control and Interrupt module does not need to be enabled to update the state of the port data direction registers and port data output registers including the set/clear/toggle registers.

34.4.3 IOPORT

The GPIO registers are also aliased to the IOPORT interface on the Cortex-M0+ from address 0xF800_0000. Accesses via the IOPORT interface occur in parallel with any instruction fetches and will therefore complete in a single cycle.

Chapter 35

Keyboard interrupts (KBI)

35.1 Introduction

35.1.1 Features

The KBI features include:

- Up to 32 keyboard interrupt pins with individual pin enable bits
- Each keyboard interrupt pin is programmable as:
 - falling-edge sensitivity only
 - rising-edge sensitivity only
 - both falling-edge and low-level sensitivity
 - both rising-edge and high-level sensitivity
- One software-enabled keyboard interrupt
- Exit from low-power modes

35.1.2 Modes of Operation

This section defines the KBI operation in:

- Wait mode
- Stop mode
- Background debug mode

35.1.2.1 KBI in Wait mode

Executing the Wait instruction places the MCU into Wait mode. The KBI interrupt should be enabled ($\text{KBI_SC}[\text{KBIE}] = 1$), if desired, before executing the Wait instruction, allowing the KBI to continue to operate while the MCU is in Wait mode. An enabled KBI pin ($\text{KBI_PE}[\text{KBIPEn}] = 1$) can be used to bring the MCU out of Wait mode if the KBI interrupt is enabled ($\text{KBI_SC}[\text{KBIE}] = 1$).

35.1.2.2 KBI in Stop modes

Executing the Stop instruction places the MCU into Stop mode (when Stop is selected), where the KBI can operate asynchronously. If this is the desired behavior, the KBI interrupt must be enabled ($\text{KBI_SC}[\text{KBIE}] = 1$) before executing the Stop instruction, allowing the KBI to continue to operate while the MCU is in Stop mode. An enabled KBI pin ($\text{KBI_PE}[\text{KBIPEn}] = 1$) can be used to bring the MCU out of Stop mode if the KBI interrupt is enabled ($\text{KBI_SC}[\text{KBIE}] = 1$).

35.1.3 Block Diagram

The block diagram for the keyboard interrupt module is shown below..

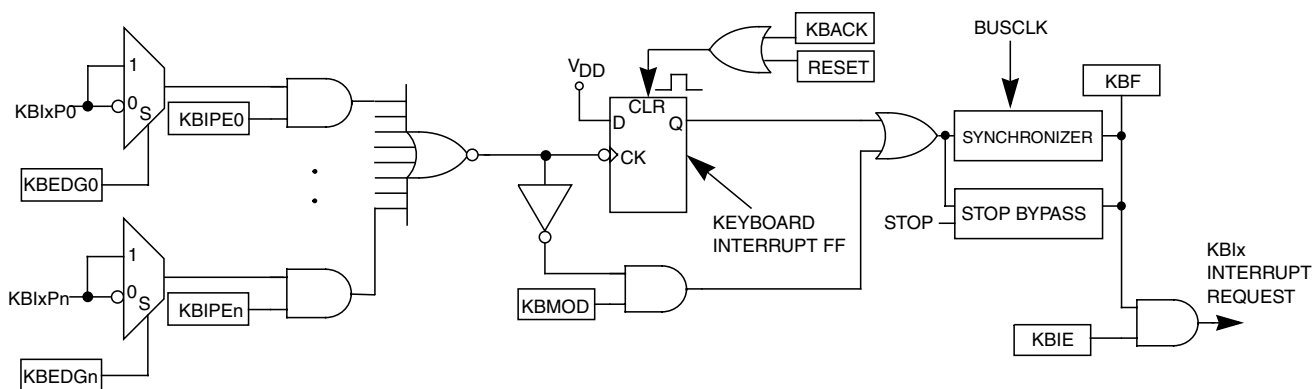


Figure 35-1. KBI block diagram

35.2 External signals description

The KBI input pins can be used to detect either falling edges, or both falling edge and low-level interrupt requests. The KBI input pins can also be used to detect either rising edges, or both rising edge and high-level interrupt requests.

The signal properties of KBI are shown in the following table:

Table 35-1. External signals description

| Signal | Function | I/O |
|--------|-------------------------|-----|
| KBIxPn | Keyboard interrupt pins | I |

35.3 Register definition

The KBI includes following registers:

- A pin status and control register, KBIx_SC
- A pin enable register, KBIx_PE
- An edge select register, KBIx_ES
- A source pin register, KBIx_SP

See the direct-page register summary in the Memory chapter for the absolute address assignments for all KBI registers. This section refers to registers and control bits only by their names.

Some MCUs may have more than one KBI, so register names include placeholder characters to identify which KBI is being referenced.

35.4 Memory Map and Registers

KBI memory map

| Absolute address (hex) | Register name | Width (in bits) | Access | Reset value | Section/ page |
|------------------------|---|-----------------|--------|-------------|----------------------------|
| 4007_9000 | KBI Pin Enable Register (KBI0_PE) | 32 | R/W | 0000_0000h | 35.4.1/694 |
| 4007_9004 | KBI Edge Select Register (KBI0_ES) | 32 | R/W | 0000_0000h | 35.4.2/694 |
| 4007_9008 | KBI Status and Control Register (KBI0_SC) | 32 | R/W | 0000_0000h | 35.4.3/695 |
| 4007_900C | KBI Source Pin Register (KBI0_SP) | 32 | R | 0000_0000h | 35.4.4/696 |
| 4007_A000 | KBI Pin Enable Register (KBI1_PE) | 32 | R/W | 0000_0000h | 35.4.1/694 |
| 4007_A004 | KBI Edge Select Register (KBI1_ES) | 32 | R/W | 0000_0000h | 35.4.2/694 |
| 4007_A008 | KBI Status and Control Register (KBI1_SC) | 32 | R/W | 0000_0000h | 35.4.3/695 |
| 4007_A00C | KBI Source Pin Register (KBI1_SP) | 32 | R | 0000_0000h | 35.4.4/696 |

35.4.1 KBI Pin Enable Register (KBIX_PE)

KBIX_PE contains the pin enable control bits.

Address: Base address + 0h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | KBIPE | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

KBIX_PE field descriptions

| Field | Description |
|-------|---|
| KBIPE | <p>KBI Pin Enables</p> <p>Each of the KBIPE_n bits enable the corresponding KBI interrupt pin.</p> <p>0 Pin is not enabled as KBI interrupt. 1 Pin is enabled as KBI interrupt.</p> |

35.4.2 KBI Edge Select Register (KBIX_ES)

KBIX_ES contains the edge select control bits.

Address: Base address + 4h offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | KBEDG | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

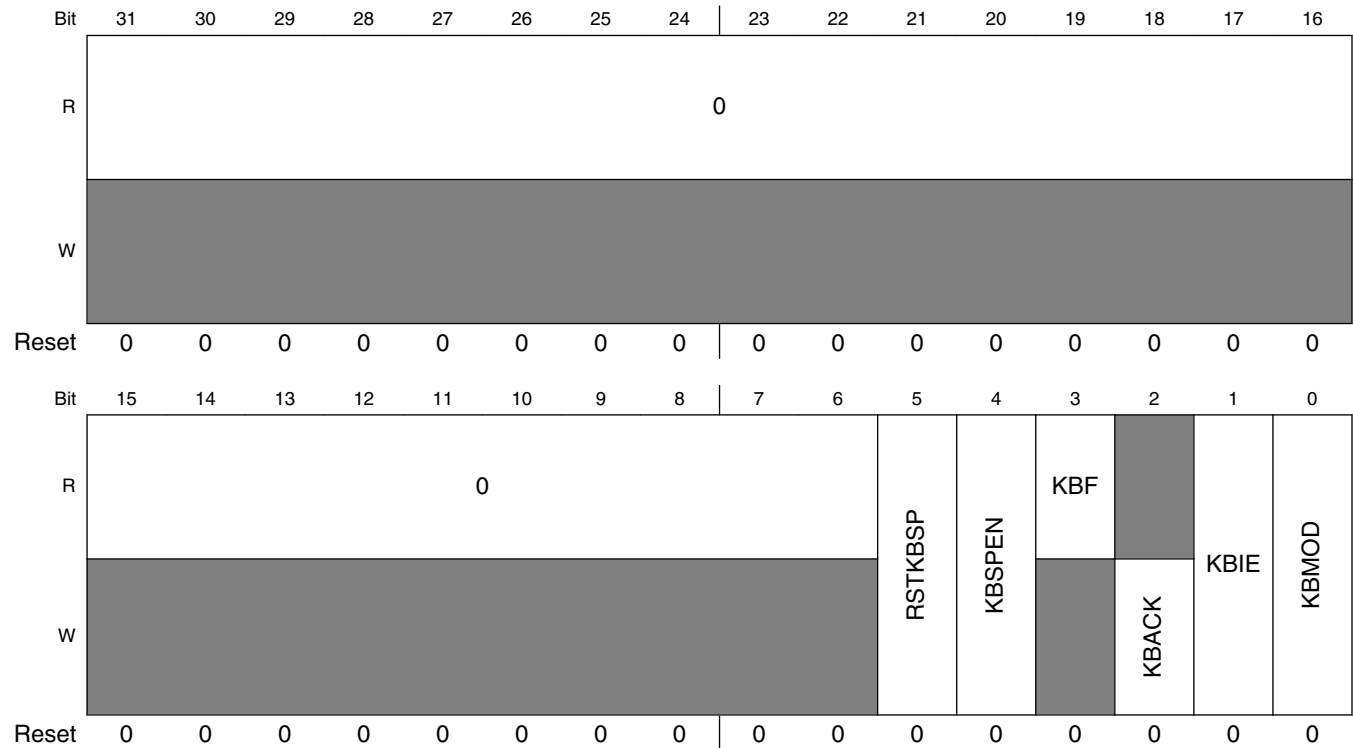
KBIX_ES field descriptions

| Field | Description |
|-------|--|
| KBEDG | <p>KBI Edge Selects</p> <p>Each of the KBEDG_n bits selects the falling edge/low-level or rising edge/high-level function of the corresponding pin.</p> <p>0 Falling edge/low level. 1 Rising edge/high level.</p> |

35.4.3 KBI Status and Control Register (KBIX_SC)

KBIX_SC contains the status flag and control bits, which are used to configure the KBI.

Address: Base address + 8h offset



KBIX_SC field descriptions

| Field | Description |
|------------------|---|
| 31–6 Reserved | This field is reserved. This read-only field is reserved and always has the value 0. |
| 5 RSTKBSP | Reset KBI_SP registe Writing a 1 to RSTKBSP is to clear the KBIXSP Register. This bit always reads as 0. |
| 4 KBSPEN | Real KBI_SP register enable 0 The real time value of Keyboard source pin to be read. 1 The latched value in KBxSP register while interrupt flag occur to be read. |
| 3 KBF | KBI Interrupt Flag Indicates when a KBI interrupt request is detected. Writes have no effect on KBF. 0 KBI interrupt request not detected. 1 KBI interrupt request detected. |
| 2 KBACK | KBI Acknowledge Writing a 1 to KBACK is part of the flag clearing mechanism. |

Table continues on the next page...

KBIx_SC field descriptions (continued)

| Field | Description |
|------------|--|
| 1 KBIE | KBI Interrupt Enable Determines whether a KBI interrupt is enabled or not. 0 KBI interrupt not enabled. 1 KBI interrupt enabled. |
| 0 KBMOD | KBI Detection Mode KBMOD (along with ES[KBEDG]) controls the detection mode of the KBI interrupt pins. 0 Keyboard detects edges only. 1 Keyboard detects both edges and levels. |

35.4.4 KBI Source Pin Register (KBIx_SP)

KBIx Source Pin register indicate the source pin of KBI. Its reset value is from system reset.

Address: Base address + Ch offset

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R | SP | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |

KBIx_SP field descriptions

| Field | Description |
|-------|---|
| SP | KBI Source Pin This field is read only, it indicates the active pin defined as keyboard interrupt which is pushed, the individual bit is set to 1 when corresponding keyboard pin is effective pushed, only system reset or writing 1 to RSTKBP bit can clear this register. |

35.5 Functional Description

This on-chip peripheral module is called a keyboard interrupt module because originally it was designed to simplify the connection and use of row-column matrices of keyboard switches. However, these inputs are also useful as extra external interrupt inputs and as an external means of waking the MCU from stop or wait low-power modes.

The KBI module allows up to eight pins to act as additional interrupt sources. Writing to the KBIx_PE[KBIPEn] bits independently enables or disables each KBI pin. Each KBI pin can be configured as edge sensitive or edge and level sensitive based on the

KBIx_SC[KBMOD] bit. Edge sensitive can be software programmed to be either falling or rising; the level can be either low or high. The polarity of the edge or edge and level sensitivity is selected using the KBIx_ES[KBEDGn] bits.

35.5.1 Edge-only sensitivity

Synchronous logic is used to detect edges. A falling edge is detected when an enabled keyboard interrupt (KBIx_PE[KBIPEn]=1) input signal is seen as a logic 1 (the deasserted level) during one bus cycle and then a logic 0 (the asserted level) during the next cycle. A rising edge is detected when the input signal is seen as a logic 0 (the deasserted level) during one bus cycle and then a logic 1 (the asserted level) during the next cycle.

Before the first edge is detected, all enabled keyboard interrupt input signals must be at the deasserted logic levels. After any edge is detected, all enabled keyboard interrupt input signals must return to the deasserted level before any new edge can be detected.

A valid edge on an enabled KBI pin will set KBIx_SC[KBF]. If KBIx_SC[KBIE] is set, an interrupt request will be presented to the MPU. Clearing of KBIx_SC[KBF] is accomplished by writing a 1 to KBIx_SC[KBACK].

35.5.2 Edge and level sensitivity

A valid edge or level on an enabled KBI pin will set KBIx_SC[KBF]. If KBIx_SC[KBIE] is set, an interrupt request will be presented to the MCU. Clearing of KBIx_SC[KBF] is accomplished by writing a 1 to KBIx_SC[KBACK], provided all enabled keyboard inputs are at their deasserted levels. KBIx_SC[KBF] will remain set if any enabled KBI pin is asserted while attempting to clear KBIx_SC[KBF] by writing a 1 to KBIx_SC[KBACK].

35.5.3 KBI Pullup Resistor

Each KBI pin, if enabled by KBIx_PE, can be configured via the associated I/O port pull enable register, see [Port Control \(PORT\)](#) chapter, to use:

- an internal pullup resistor, or
- no resistor

If an internal pullup resistor is enabled for an enabled KBI pin, the associated I/O port pull select register (see [I/O Port](#) chapter) can be used to select an internal pullup resistor.

35.5.4 KBI initialization

When a keyboard interrupt pin is first enabled, it is possible to get a false keyboard interrupt flag. To prevent a false interrupt request during keyboard initialization, the user should do the following:

1. Mask keyboard interrupts by clearing KBIx_SC[KBIE].
2. Enable the KBI polarity by setting the appropriate KBIx_ES[KBEDGn] bits.
3. Before using internal pullup resistors, configure the associated bits in PORT_PUE0 and PORT_PUE1.
4. Enable the KBI pins by setting the appropriate KBIx_PE[KBIPEn] bits.
5. Write to KBIx_SC[KBACK] to clear any false interrupts.
6. Write to KBIx_SC[RSTKBSP] to clear KBIx_SP for any false.
7. Set KBIx_SC[KBIE] to enable interrupts.

Chapter 36

Release Notes for Rev 2

Table 36-1. Generic changes

- Updated supported parts.

Table 36-2. About this document chapter changes

No substantial content changes.

Table 36-3. Introduction chapter changes

- Editorial changes.
- [Memories and memory interfaces](#) is updated to show 64/128 KB flash memory.
- [Orderable part numbers](#) section is updated.

Table 36-4. Chip configuration chapter changes

- [Alternate Non-Volatile IRC User Trim Description](#) section is added.
- Following sections are updated to show all supported parts:
 - [Flash memory sizes](#) section updated.
 - [SRAM sizes](#) section updated
 - [ADC instantiation information](#) section updated.

Table 36-5. Memory map chapter changes

- Updated note at [Peripheral ID Register \(ROM_PERIPHID_n\)](#) and [Component ID Register \(ROM_COMPID_n\)](#) registers.

Table 36-6. Clock distribution chapter changes

- Note updated in [FTM and PWT clocking](#) section.

Table 36-7. Reset and boot chapter changes

No substantial content changes.

Table 36-8. Power management chapter changes

No substantial content changes.

Table 36-9. Security chapter changes

- Note updated in [Flash security](#) section.

Table 36-10. Debug chapter changes

No substantial content changes.

Table 36-11. Signal multiplexing and signal descriptions chapter changes

No substantial content changes.

Table 36-12. Port control (PORT) chapter changes

No substantial content changes.

Table 36-13. SIM chapter changes

No substantial content changes.

Table 36-14. Power Management Controller chapter changes

No substantial content changes.

Table 36-15. Miscellaneous Control Module chapter changes

No substantial content changes.

Table 36-16. Peripheral Bridge chapter changes

No substantial content changes.

Table 36-17. Watchdog Timer chapter changes

- [Features](#) section is updated.

Table 36-18. Bit Manipulation Engine chapter changes

No substantial content changes.

Table 36-19. Flash Memory Module chapter changes

- Updated features list in section: [Flash memory features](#) section.
- Updated [Flash memory map](#) section.
- Updated [Flash initialization after system reset](#) section.
- Added figure [Figure 18-3](#).
- Added text "It will also trigger an illegal access exception" in [Flash command summary](#)
- Updated bit description of bit "SEC" in the register: FTMRE_FSEC

Table 36-20. Flash Memory Controller chapter changes

No substantial content changes.

Table 36-21. Internal Clock Source chapter changes

- Updated [Features](#)
- Updated bit description of bit "RDIV" in the register: ICS_C1
- Updated bit description of bit "SCTRIM" in the register: ICS_C3
- Updated bit description of bit "SCFTRIM" in the register: ICS_C4
- Changed TRIM[7:0] to SCTRIM[7:] in LOCK bit of register: ICS_S
- Updated code segments in following section:
 - [Initializing FEI mode](#)
 - [Initializing FBI mode](#)
 - [Initializing FEE mode](#)
 - [Initializing FBE mode](#)

Table 36-22. Oscillator chapter changes

- Updated bit description of bit "RANGE" in the register: OSC_CR

Table 36-23. Cyclic Redundancy Check chapter changes

- Updated [CRC initialization/reinitialization](#) section.

Table 36-24. Interrupt chapter changes

No substantial content changes.

Table 36-25. Analog-to-digital converter chapter changes

- Updated [FIFO operation](#) section.
- Minor editorial updates in [Figure 24-11](#)

Table 36-26. Analog comparator chapter changes

No substantial content changes.

Table 36-27. FlexTimer Module chapter changes

- Updated [FlexTimer philosophy](#) section.
- Minor editorial updates in table "Mode, edge, and level selection" under FTMx_CnSC register.
- Minor editorial updates in [FlexTimer philosophy](#) section.
- Updated note under [Up-down counting](#) section.
- Deleted note under [Input Capture mode](#) section.
- Deleted note under [Output Compare mode](#) section.
- Updated note under [Edge-Aligned PWM \(EPWM\) mode](#) section.
- Deleted note under [Center-Aligned PWM \(CPWM\) mode](#) section.
- Removed list item "FTMEN = 1" in section: [Combine mode](#)
- Updated section [Complementary mode](#)
- Deleted note under section [PWM synchronization](#)
- Removed list items "FTMEN = 1" "COMBINE = 1" and "CPWMS = 0" and updated note in section: [Inverting](#)
- Deleted note under section [Software output control](#)
- Updated note under section [Deadtime insertion](#)
- Changed "The fault control is enabled if (FTMEN = 1) and (FAULTM[1:0] ≠ 0:0)." to "The fault control is enabled if (FAULTM[1:0] ≠ 0:0)." in [Fault control](#) section.
- Updated note under section [Initialization](#)
- Deleted note under section [Channel trigger output](#)
- Deleted note under section [Initialization trigger](#)
- Removed 'FTMEN=1' from "The Dual Edge Capture mode is selected if FTMEN = 1 and DECAPEN = 1." in section: [Dual Edge Capture mode](#)
- Removed 'FTMEN=1' from "The One-Shot Capture mode is selected when (FTMEN = 1), (DECAPEN = 1), and (MS(n)A = 0)." in section: [One-Shot Capture mode](#) and [Continuous Capture mode](#).
- Added note under section [Debug mode](#).
- Deleted note under section [Intermediate load](#)
- Minor editorial updates in section [Global time base \(GTB\)](#)
- Added section [Initialization Procedure](#)
- Note removed in [STATUS](#) register.
- Updated bit field description of FTMEN in [MODE](#) register.
- Updated bit field descriptions in [COMBINE](#) register.
- Note deleted in [FlexTimer philosophy](#) section.

Table 36-28. Pulse Width Timer chapter changes

- Minor update in [Block diagram](#)
- Added note below the [Block diagram](#)
- Updated bit field description of PCLKS bit in [PWT_R1](#) register.
- Updated [Figure 27-4](#)

Table 36-29. Periodic Interrupt Timer chapter changes

- Minor editorial update in section [Introduction](#).
- [Example configuration for chained timers](#) section is updated.

Table 36-30. Real -Time Counter chapter changes

No substantial content changes.

Table 36-31. Serial Peripheral Interface chapter changes

No substantial content changes.

Table 36-32. Inter-Integrated Circuit chapter changes

- Minor editorial update in section [Features](#).

Table 36-33. MSCAN chapter changes

- Updated "MSCAN Transmit Buffer Selection Register" register.
- Added crossreference to figure "User model for message buffer organization" in section: [Transmit structures](#)

Table 36-34. UART chapter changes

- Minor editorial update in section [Fast data tolerance](#)

Table 36-35. General-Purpose Input/Output (GPIO) chapter changes

- Updated section [Features](#).
- Added note in section [Detailed signal description](#).

Table 36-36. Keyboard interrupts chapter changes

No substantial content changes.



How to Reach Us:**Home Page:**freescale.com**Web Support:**freescale.com/support

Information in this document is provided solely to enable system and software implementers to use Freescale products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits based on the information in this document.

Freescale reserves the right to make changes without further notice to any products herein.

Freescale makes no warranty, representation, or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages.

“Typical” parameters that may be provided in Freescale data sheets and/or specifications can and do vary in different applications, and actual performance may vary over time. All operating parameters, including “typicals,” must be validated for each customer application by customer's technical experts. Freescale does not convey any license under its patent rights nor the rights of others. Freescale sells products pursuant to standard terms and conditions of sale, which can be found at the following address: freescale.com/SalesTermsandConditions.

Freescale, the Freescale logo, and Kinetis are trademarks of Freescale Semiconductor, Inc., Reg. U.S. Pat. & Tm. Off. All other product or service names are the property of their respective owners. ARM and Cortex-M0+ are the registered trademarks of ARM Limited.

©2014 Freescale Semiconductor, Inc.

