Key Features

* SPI interface used in probe
* Three AA batteries used with two LDOs to obtain correct power for the separate rails

Movement system

* Components
  + Motor Controller
    - 7.5 Amps Continuous Per Channel
    - 15 Amps Peak Per Channel
    - Dual Encoders Supported
    - Position Control
    - Autotuning PID
    - Multimode Control Interface
    - USB, Serial, R/C, Analog Inputs
    - Limit, Home and E-Stops
    - Up to 34VDC Operation
  + Motor with encoder and controller
    - This motor controller is capable of controlling two brushed DC motors as shown in the figure taken from the datasheet above. This system also has a setting for running them in sync with each other as a part of the compatible software (Motion Studio) shown below.
    - This motor controller is designed to control two motors up to 34V 7.5 Amps continuous and 34V 15 Amps peak per channel which is well above the 12V 1.8 Amp stall current of each motor. These values were taken from the datasheets of both the motor and motor controller.
    - This controller can be controlled via USB (from the data sheet shown above) which eliminates the need for an Arduino or Rasberry Pi for easy velocity control, and is compatible with quadrature encoders as stated in the datasheet which will allow for accurate velocity control regardless of load changes

Fig.1 Motor Velocity Deviation Table

| Run Number | Set Velocity(ft/sec) | Maximum Velocity Deviation(ft/sec) |
| --- | --- | --- |
| 1 | 1.39 | 0.016 |
| 2 | 1.36 | 0.060 |
| 3 | 1.34 | 0.038 |
| 4 | 1.41 | 0.019 |
| 5 | 1.27 | 0.052 |

Probe Systems

* Memory
  + Memory chip (AT25SL128A-MHE-T)
    - Single 1.7 V - 2.0 V Supply
    - 128 Mbit Flash Memory
    - Serial Peripheral Interface (SPI)
    - Supports SPI Modes 0 and 3
    - Supports Dual Output Read and Quad I/O Program and Read
    - 133 MHz Maximum Operating Frequency
    - Clock-to-Output (tV1) of 6 ns
    - Up to 65 Mbytes/s continuous data transfer rate
    - Full Chip Erase

Fig.2 Memory Testing

| Run Time (minutes) | Bytes Stored (bytes) | Bytes Retreived  (bytes) | Remaining Bytes (bytes) |
| --- | --- | --- | --- |
| 1 | 32,760 | 32,760 | 16,744,456 |
| 5 | 163,800 | 163,800 | 16,613,416 |
| 10 | 327,600 | 327,600 | 16,449,616 |
| 15 | 491,400 | 491,400 | 16,285,816 |
| 20 | 655,200 | 655,200 | 16,122,016 |

* Power
  + Batteries
    - AA batteries
  + LDOs
    - 1.8 V LDO
      * Operating Input Voltage Range: 2.2 V to 5.5 V
      * Available in Fixed Voltage Option: 1.2 V to 5.3 V
      * ±2% Accuracy Over Load/Temperature
      * Ultra Low Quiescent Current Typ. 12 A
      * Standby Current: Typ. 0.1 A
      * Very Low Dropout: 80 mV at 250 mA
      * Ultra High PSRR: Typ. 92 dB at 20 mA, f = 1 kHz
      * Ultra Low Noise: 6.5 VRMS
    - 3.3 V LDO
      * Operating Input Voltage Range: 2.7 V to 18 V
      * Output Voltage: 1.2 V to 17 V
      * Capable of Sourcing 140 mA Peak Output Current
      * Low Shutdown Current: 100 nA typ.
      * Very Low Quiescent Current: 1 A typ.
      * Low Dropout: 215 mV typ. at 100 mA
      * Output Voltage Accuracy ±1%
      * Power Good Output (Version B)
      * Built−in Soft Start Circuit to Suppress Inrush Current
      * Over−Current and Thermal Shutdown Protections

Fig.3 Battery testing

| Run Time (minutes) | Initial Voltage (V) | Post-test Voltage (V) | Load Current (mA) |
| --- | --- | --- | --- |
| 20 | 5.08 | 5.03 | 15-18 |
| 20 | 5.03 | 4.98 | 15-18 |
| 20 | 4.98 | 4.92 | 15-18 |

* Microcontroller
  + SPI and I2C capabilities
* IMU (ISM330DHCXTR)
  + 3D accelerometer with selectable full scale: ±2/±4/±8/±16 g
  + 3D gyroscope with extended selectable full scale
  + Embedded compensation for high stability over temperature
  + SPI/I²C serial interface
  + Auxiliary SPI serial interface for data output of gyroscope and accelerometer
  + (OIS and other stabilization applications)
  + Six-channel synchronized output
  + Sensor hub feature to efficiently collect data from additional external sensors
  + Embedded smart FIFO up to 9 kbytes
  + Programmable Finite State Machine to process data from accelerometer, gyroscope, and external sensors
  + Smart embedded functions and interrupts: tilt detection, free-fall, wakeup, 6D/4D orientation, click and double-click
  + Analog supply voltage: 1.71 V to 3.6 V
  + Embedded self-test both for gyroscope and accelerometer
* Software
  + Probe software
    - Utilizes C
  + Mapping software
    - Utilizes Python

Citations and Datasheets

* [NCP163 - LDO Regulator - Ultra-Low Noise, High PSRR, RF and Analog Circuits, 250 mA](https://www.mouser.com/datasheet/2/308/NCP163_D-1101311.pdf)
* <https://www.mouser.com/datasheet/2/308/NCP711_D-1879967.pdf>
* [AT25SL128A-MHE-T Adesto Technologies | Integrated Circuits (ICs) | DigiKey](https://www.digikey.com/en/products/detail/adesto-technologies/AT25SL128A-MHE-T/6827494)
* <https://www.basicmicro.com/Roboclaw-2x7A-Motor-Controller_p_55.html>
* <https://www.pololu.com/product/4865>