

Lesson 8

Trusses in 2D & 3D Space, Python codes

Minh-Chien Trinh, PhD

Division of Mechanical System Engineering
Jeonbuk National University

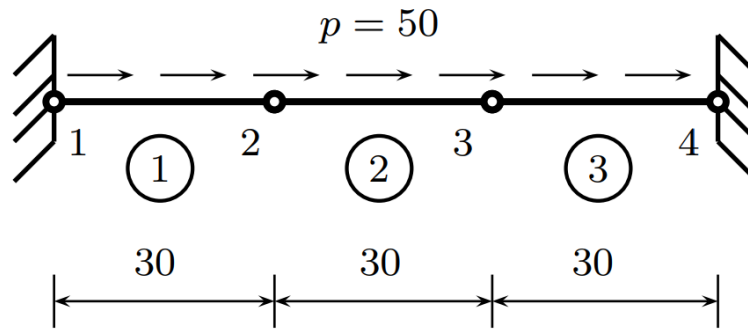
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1. Python Codes – Isoparametric Bar under Uniform Load

❖ Python code: <https://github.com/mctrinh/fem-class>



- An isotropic bar is clamped at two ends.
- Modulus of elasticity $E = 30 \cdot 10^6$
- Cross-section area $A = 1$
- Uniform axial load $p = 50$
- Exact solution
$$u = \frac{pLx}{2EA} \left(1 - \frac{x}{L} \right), \quad \sigma_x = \frac{pL}{A} \left(\frac{1}{2} - \frac{x}{L} \right)$$

2. Trusses in 2D Space – Formulation - DOFs

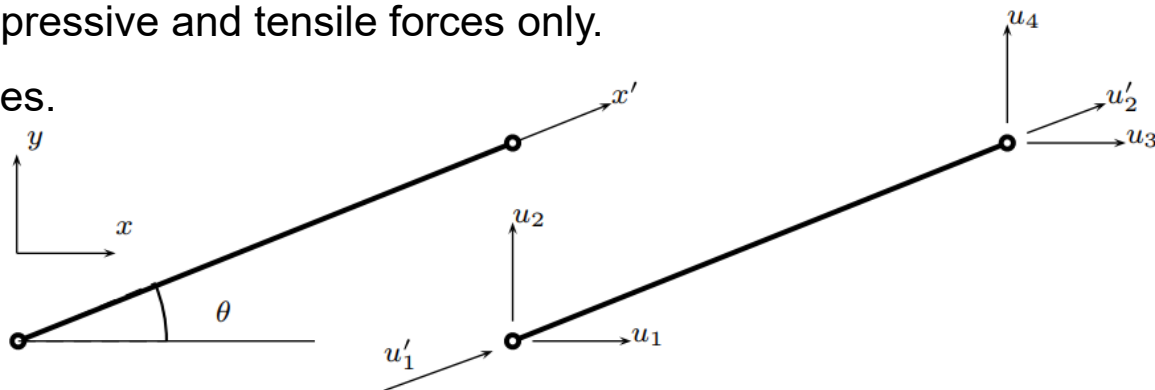
- ❖ A transformation of coordinate basis is necessary to translate the local element matrices into the structural coordinate system.
- ❖ Trusses and Bars supports compressive and tensile forces only.
- ❖ All forces are applied at the nodes.

- ❖ 2 DOFs in local coordinate

$$\mathbf{u}'^T = [u'_1 \quad u'_2]$$

- ❖ 4 DOFs in global coordinate

$$\mathbf{u}^T = [u_1 \quad u_2 \quad u_3 \quad u_4]$$



2D truss element: local and global DOFs

- ❖ Relation between local and global DOFs

$$\begin{cases} u'_1 = u_1 \cos \theta + u_2 \sin \theta \\ u'_2 = u_3 \cos \theta + u_4 \sin \theta \end{cases} \quad \Leftrightarrow \quad \mathbf{u}' = \mathbf{L} \mathbf{u}$$

$$\mathbf{L} = \begin{bmatrix} l & m & 0 & 0 \\ 0 & 0 & l & m \end{bmatrix} \quad \text{in which} \quad l = \cos \theta = \frac{x_2 - x_1}{L_e}; \quad m = \sin \theta = \frac{y_2 - y_1}{L_e}; \quad L_e = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

with θ is the angle between the local axis x' and global axis x .

2. Trusses in 2D Space – Formulation (Stiffness, Mass)

- ❖ The local stiffness matrix of 2D truss elements is like bar elements:

$$\mathbf{K}' = \frac{EA}{L_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

- ❖ The strain energy of this element is transformed from local to global coordinate system

$$U^e = \frac{1}{2} \mathbf{u}'^T \mathbf{K}' \mathbf{u}' = \frac{1}{2} \mathbf{u}^T [\mathbf{L}^T \mathbf{K}' \mathbf{L}] \mathbf{u} = \frac{1}{2} \mathbf{u}^T \mathbf{K} \mathbf{u}$$

with the global stiffness matrix

$$\mathbf{K} = \frac{EA}{L_e} \begin{bmatrix} l^2 & lm & -l^2 & -lm \\ lm & m^2 & -lm & -m^2 \\ -l^2 & -lm & l^2 & lm \\ -lm & -m^2 & lm & m^2 \end{bmatrix}$$

- ❖ The local mass matrix of 2D truss elements

The consistent mass matrix

$$\mathbf{M}'_C = \frac{\rho AL_e}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

The lumped mass matrix

$$\mathbf{M}'_L = \frac{\rho AL_e}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

2. Trusses in 2D Space – Formulation (Stiffness, Mass, Stress)

- ❖ The kinetic energy of this element is transformed from local to global coordinate system

$$K^e = \frac{1}{2} \dot{\mathbf{u}}'^T \mathbf{M}' \dot{\mathbf{u}}' = \frac{1}{2} \dot{\mathbf{u}}^T [\mathbf{L}^T \mathbf{M}' \mathbf{L}] \dot{\mathbf{u}} = \frac{1}{2} \dot{\mathbf{u}}^T \mathbf{M} \dot{\mathbf{u}}$$

$$\mathbf{M} = \frac{\rho A L_e}{6} \begin{bmatrix} 2l^2 & 2lm & l^2 & lm \\ 2lm & 2m^2 & lm & m^2 \\ l^2 & lm & 2l^2 & 2lm \\ lm & m^2 & 2lm & 2m^2 \end{bmatrix}$$

(the global consistent mass matrix)

$$\mathbf{M} = \frac{\rho A L_e}{2} \begin{bmatrix} l^2 & lm & 0 & 0 \\ lm & m^2 & 0 & 0 \\ 0 & 0 & l^2 & lm \\ 0 & 0 & lm & m^2 \end{bmatrix}$$

(the global lumped mass matrix)

- ❖ The translational masses never vanish and must be retained in the local mass matrix. Setting $lm = 0$ and other terms are set to 1.

$$\mathbf{M} = \frac{\rho A L_e}{6} \begin{bmatrix} 2 & 0 & 1 & 0 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 2 \end{bmatrix}$$

(the global consistent mass matrix)

$$\mathbf{M} = \frac{\rho A L_e}{2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

(the global lumped mass matrix)

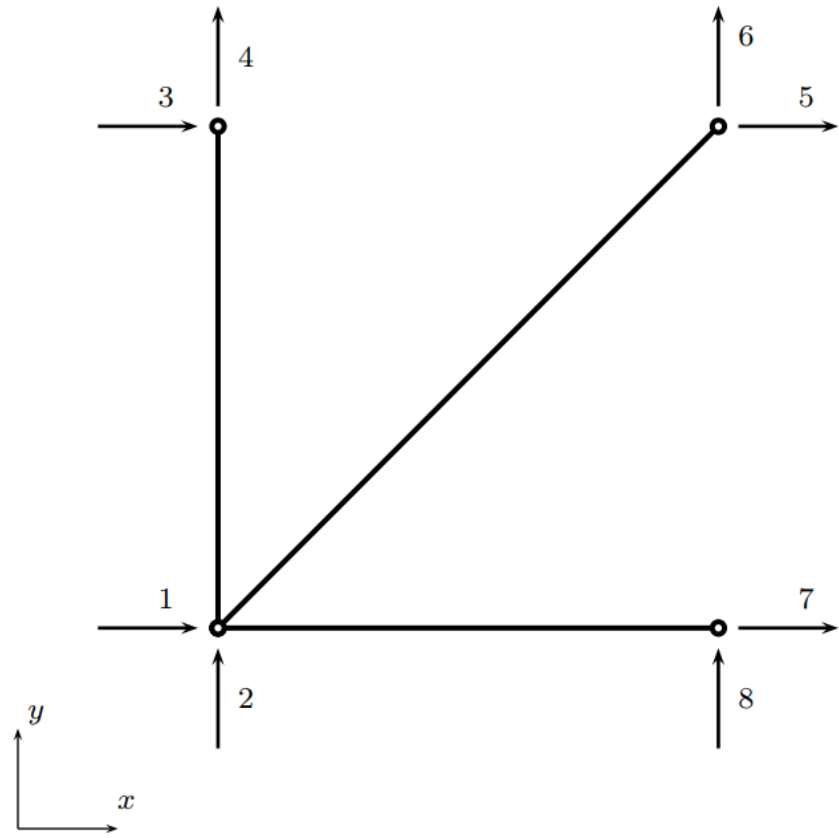
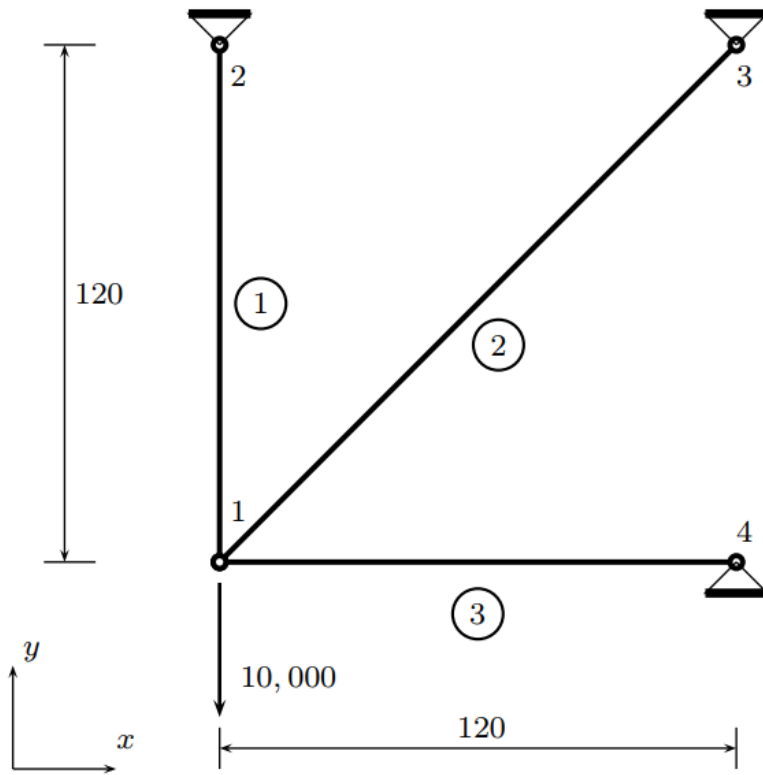
- ❖ The stress is transformed from local to global coordinate system

$$\sigma_x = E \varepsilon_x = E \frac{u'_2 - u'_1}{L_e} = \frac{E}{L_e} \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} u'_1 \\ u'_2 \end{bmatrix} = \frac{E}{L_e} \begin{bmatrix} -1 & 1 \end{bmatrix} \mathbf{u}' = \frac{E}{L_e} \begin{bmatrix} -1 & 1 \end{bmatrix} \mathbf{L} \mathbf{u} = \frac{E}{L_e} \begin{bmatrix} -l & -m & l & m \end{bmatrix} \mathbf{u}$$

2. Trusses in 2D Space – 2D Truss Problem - Python

❖ Python code: <https://github.com/mctrinh/fem-class>

- Modulus of elasticity $E = 30 \cdot 10^6$
- Cross-section area $A = 2$
- Applied load $P = 10000$



3. Trusses in 3D Space – Formulation

❖ Generalize the 2D truss model in 3D Cartesian space.

❖ The element has 2 DOFs in local coordinate

$$\mathbf{u}'^T = [u'_1 \quad u'_2 \quad u'_3 \quad u'_4 \quad u'_5 \quad u'_6]$$

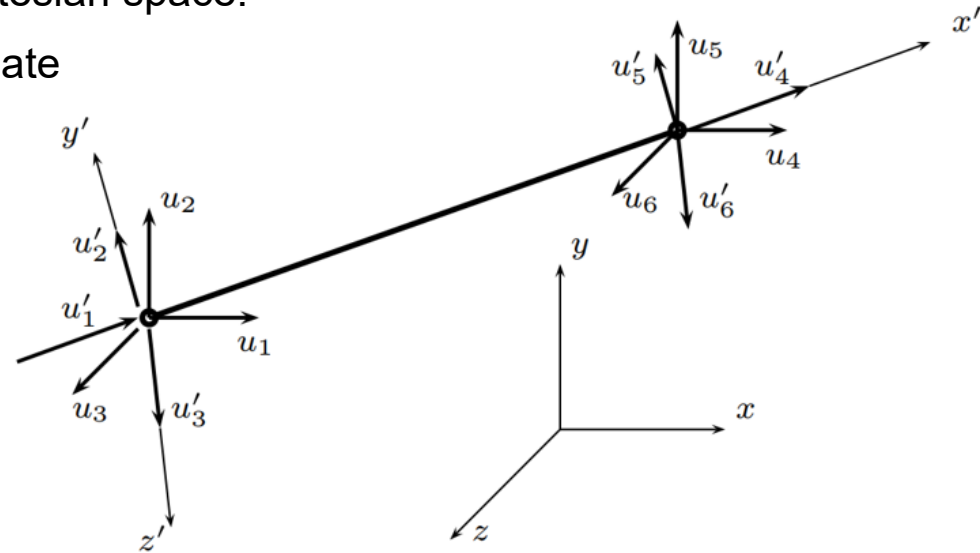
❖ Each node has 3 global DOFs.

❖ Totally, 6 DOFs in global coordinate

$$\mathbf{u}^T = [u_1 \quad u_2 \quad u_3 \quad u_4 \quad u_5 \quad u_6]$$

❖ Relation between local and global DOFs

$$\mathbf{u}' = \mathbf{L}\mathbf{u}$$



3D truss element: local and global DOFs

The direction cosines matrix

$$\mathbf{L} = \begin{bmatrix} l_x & l_y & l_z & 0 & 0 & 0 \\ 0 & 0 & 0 & l_x & l_y & l_z \end{bmatrix} \quad \text{with} \quad l_x = \frac{x_2 - x_1}{L_e}, \quad l_y = \frac{y_2 - y_1}{L_e}, \quad l_z = \frac{z_2 - z_1}{L_e}$$

❖ The local stiffness matrix of 3D truss elements is like before

$$\mathbf{K}^e = \frac{EA}{L_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

3. Trusses in 3D Space – Formulation

❖ The global stiffness matrix is

$$\mathbf{K} = \mathbf{L}^T \mathbf{K}^e \mathbf{L} = \frac{EA}{L_e} \begin{bmatrix} l_x^2 & l_x l_y & l_x l_z & -l_x^2 & -l_x l_y & -l_x l_z \\ & l_y^2 & l_y l_z & -l_x l_y & -l_y^2 & -l_y l_z \\ & & l_z^2 & -l_x l_z & -l_y l_z & -l_z^2 \\ & & & l_x^2 & l_x l_y & l_x l_z \\ & & & & l_y^2 & l_y l_z \\ & & & & & l_z^2 \end{bmatrix}$$

sym

❖ The global mass matrix is

$$\mathbf{M} = \mathbf{L}^T \mathbf{M}^e \mathbf{L} = \frac{\rho A L_e}{6} \begin{bmatrix} 2 & 0 & 0 & 1 & 0 & 0 \\ & 2 & 0 & 0 & 1 & 0 \\ & & 2 & 0 & 0 & 1 \\ & & & 2 & 0 & 0 \\ & & & & 2 & 0 \\ & & & & & 2 \end{bmatrix}$$

sym

The global consistent mass matrix

$$\mathbf{M} = \mathbf{L}^T \mathbf{M}^e \mathbf{L} = \frac{\rho A L_e}{2} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 & 0 \\ & & 1 & 0 & 0 & 0 \\ & & & 1 & 0 & 0 \\ & & & & 1 & 0 \\ & & & & & 1 \end{bmatrix}$$

sym

The global lumped mass matrix

3. Trusses in 3D Space – 3D Truss Problem - Python

❖ Python code: <https://github.com/mctrinh/fem-class>

- Given

$$E = 1.2 \cdot 10^6$$

$$P_1 = (72, 0, 0)$$

$$P_2 = (0, 36, 0)$$

$$P_3 = (0, 36, 72)$$

$$P_4 = (0, 0, -48)$$

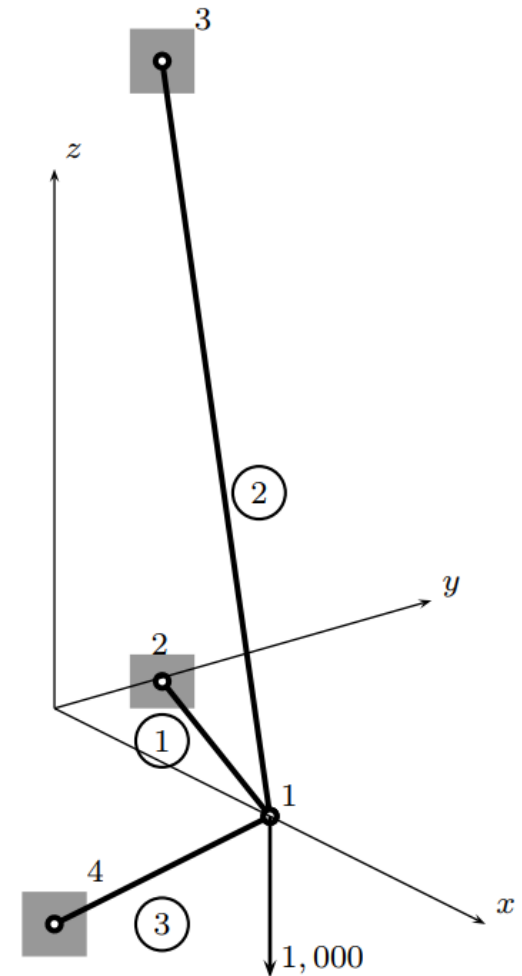
$$U_2 = U_3 = U_4 = (0, 0, 0)$$

$$v_1 = 0$$

$$A_1 = 0.302$$

$$A_2 = 0.729$$

$$A_3 = 0.187$$



- Evaluate displacements, reactions, stresses of elements.

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