

M378K Introduction to Mathematical Statistics

Problem Set #16

Consistency.

Definition 16.1. $\hat{\theta}_n$ is said to be a consistent estimator of θ if

$$\hat{\theta}_n \rightarrow \theta \text{ in probability as } n \rightarrow \infty,$$

i.e., if for any $\varepsilon > 0$,

$$\lim_{n \rightarrow \infty} \mathbb{P} \left[|\hat{\theta}_n - \theta| > \varepsilon \right] = 0.$$

Theorem 16.2. Let $\hat{\theta}_n$ be unbiased and such that

$$\text{Var} \left[\hat{\theta}_n \right] \xrightarrow{n \rightarrow \infty} 0.$$

Then, $\hat{\theta}_n$ is a consistent estimator.

Problem 16.1. Let Y_1, Y_2, \dots, Y_n be a random sample from any distribution with finite first and second moments. Propose a consistent estimator for the population mean μ and prove that it is, indeed, consistent.

→ :

$$\bar{Y} = \frac{1}{n} (Y_1 + Y_2 + \dots + Y_n)$$

unbiased ✓

$$\text{Var}[\bar{Y}] = \frac{\text{Var}[Y_1]}{n} \xrightarrow{n \rightarrow \infty} 0$$



Problem 16.2. Consider a random sample Y_1, Y_2, \dots, Y_n from a power distribution with the density of the form

$$f_Y(y) = \theta y^{\theta-1} \mathbf{1}_{(0,1)}(y).$$

What is a consistent estimator for $\frac{\theta}{\theta+1}$? **Prove** that your choice is indeed consistent.

→ :

$$\mathbb{E}[Y_1] = \int_0^1 y \cdot \theta y^{\theta-1} dy = \theta \int_0^1 y^{\theta} dy = \theta \cdot \frac{y^{\theta+1}}{\theta+1} \Big|_{y=0}^1 = \frac{\theta}{\theta+1}$$

We propose \bar{Y}_n :

- unbiased ✓

- $\text{Var}[\bar{Y}_n] \rightarrow 0$

- $\text{Var}[Y_1] = \mathbb{E}[Y_1^2] - (\mathbb{E}[Y_1])^2$

$$\parallel \int_0^1 y^2 \theta y^{\theta-1} dy$$

$$\parallel \theta \cdot \int_0^1 y^{\theta+1} dy$$

$$\parallel \frac{\theta}{\theta+2}$$



Maximum Likelihood Estimation.

Likelihood.

Def'n. Given a random sample Y_1, Y_2, \dots, Y_n from a discrete dist'n \mathcal{D} w/ an unknown parameter θ , the **likelihood function** is defined as

$$L(\theta; y_1, y_2, \dots, y_n) = P_{Y_1, \dots, Y_n}^{\theta}(y_1, \dots, y_n) = p^{\theta}(y_1) p^{\theta}(y_2) \dots p^{\theta}(y_n)$$

where p^{θ} is a pmf of \mathcal{D} .

If Y_1, \dots, Y_n come from a continuous dist'n \mathcal{D} w/ pdf f^{θ} , we have this definition:

$$L(\theta; y_1, \dots, y_n) = f_{Y_1, \dots, Y_n}^{\theta}(y_1, \dots, y_n) = f^{\theta}(y_1) \cdot f^{\theta}(y_2) \dots f^{\theta}(y_n)$$

Example.

Bernoulli. $Y_1, \dots, Y_n \sim B(p)$

$$p \leftrightarrow \theta$$

$$p(y) = \begin{cases} p & y=1 \\ 1-p & y=0 \end{cases}$$

$$= p^y (1-p)^{1-y} \quad \text{for } y=0,1$$

$$\begin{aligned} L(p; y_1, y_2, \dots, y_n) &= p^{y_1} (1-p)^{1-y_1} \cdot p^{y_2} (1-p)^{1-y_2} \cdot \dots \cdot p^{y_n} (1-p)^{1-y_n} \\ &= p^{\sum y_i} (1-p)^{n - \sum y_i} \end{aligned}$$