





The Simplest Version

E can be any one value from $\Theta_1, \Theta_2, ..., \Theta_k$ Then, we see one value y of the random variable Y. By the Bayes rule, we have for k=1,..., K,

This procedure is called Bayesian updating. When no prior information is available, we use the uninformed prior.

The Continuous Case.

Here, we assume that @ admits a pdf denoted by p(9) We denote the posterior density by

p(0 4, ..., 4n) As usual, L(O; y1,..., yn) is the likelihood fition.

So, the posterior density becomes
$$p(\Theta) \sqcup (\Theta; \, y_1, ..., y_n) = \frac{p(\Theta) \sqcup (\Theta; \, y_1, ..., y_n)}{\int \rho(\Theta) \sqcup (\Theta; \, y_1, ..., y_n) d\Theta}$$

Note: by default, the integral is from so to too.

• Θ is the "dummy" variable of integration.

Example. $Y_1, ..., Y_n$ is a random sample from $N(\mu, \sigma = 1)$ where the prior distribution for μ is $N(0, 1)$.

$$p(\mu) = \frac{1}{\sqrt{2\pi i}} e^{-\frac{M^2}{2}}$$
and $\lim_{n \to \infty} \frac{1}{\sqrt{2\pi i}} e^{-\frac{M^2}{2}} \exp\left(-\frac{1}{2} \sum_{i=1}^{N} (y_i - \mu)^2\right)$

$$p(\mu) y_1, ..., y_n) = \left(\frac{1}{\sqrt{2\pi i}}\right) \exp\left(-\frac{1}{2} \sum_{i=1}^{N} (y_i - \mu)^2\right) d\mu$$

$$p(\mu) y_1, ..., y_n) = C \exp\left(-\frac{1}{2} (\mu^2 + \sum_{i=1}^{N} (y_i - \mu)^2\right) d\mu$$

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$$= C \exp\left(-\frac{1}{2} (\mu^2 - 2 \cdot \mu \cdot \sum_{i=1}^{N} (y_i + \mu \cdot \mu^2)\right)$$

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$$= c' \exp \left(-\frac{1}{2(\frac{1}{n+1})} (\mu - (\frac{2y_i}{n+4}))^2\right)$$

$$C' = \frac{1}{SD\sqrt{2\pi}} = \frac{1}{\sqrt{2\pi}}$$