

## Section 3.4. Discrete Distributions

So far: Usually, we focused on  $\Omega$ s that were finite and we had  $X$ s that had finite supports.

Now: We want to model, e.g., the time until some event of interest happens.  
 ↑  
 In some integer units.

We would have an outcome space such as:

$$\Omega = \{0, 1, 2, \dots, n, \dots\}$$

An infinite  $\Omega$ !

More generally: Want to talk about COUNTABLE outcome spaces, i.e.,  $\Omega$ s whose elements can be arranged in a sequence, i.e.,

$$\Omega = \{\omega_1, \omega_2, \omega_3, \dots, \omega_n, \dots\}$$

$$\Omega = \{1, 2, 3, \dots, n, \dots\}$$

$$\Omega = \{T, HT, HHT, \dots, H^{(n)}T, \dots\}$$

$$\Omega = \{0, 1, -1, 2, -2, 3, -3, \dots, n, -n, \dots\}$$

(for difference in times, toss a coin, ...)

Q: What was our first example of a probability dist'n on a finite  $\Omega$ ?

→: **EQUALLY LIKELY OUTCOMES** w/  $PP[\omega] = \frac{1}{|\Omega|}$



Q: Is this type of a uniform distribution possible on an infinitely countable  $\Omega$ ?

→:  $\Omega = \{\omega_1, \omega_2, \dots, \omega_n, \dots\}$

Assume that there exists a probability  $p > 0$  such that

$$p = PP[\omega_i] \text{ for all } i \in \mathbb{N}$$

By the Law of Total One ,

$$1 = \sum_{i=1}^{+\infty} \text{TP}[w_i] = \sum_{i=1}^{+\infty} p = "p \cdot \infty"$$

Uniform probabilities on infinitely countable  $\Omega$  are impossible.

□

Example. Consider a coin w/ probability of Hs equal to  $p$ .  
Toss this coin repeatedly (and independently).  
The first time the H appears (success!) is recorded.

$$\Omega = \mathbb{N} = \{1, 2, \dots, n, \dots\}$$

We can be forced to wait arbitrarily long.

What is the probability dist'n  $\text{TP}$ ?

$$\text{TP}[\{1\}] = p$$

$$\text{TP}[\{2\}] = (1-p) \cdot p$$

$$\text{TP}[\{3\}] = (1-p)^2 \cdot p$$

⋮

$$\text{TP}[\{n\}] = (1-p)^{n-1} \cdot p$$

⋮

We might be interested in something like:

$$\text{TP}[\{\text{it takes a prime number of trials}\}]$$

Def'n. A function  $T: \Omega \rightarrow \mathbb{R}$  is a random variable on  $\Omega$ .

e.g.,  $T$ ... a r.v. representing the number of trials until the first success (inclusive)

$$T(\omega) = \omega \quad \text{for all } \omega \in \Omega$$

$$\text{Support}(T) = \mathbb{N} = \{1, 2, \dots\}$$

Def'n. Any r.v. whose support is @ most countable (i.e., finite or infinitely countable) is called a **DISCRETE RANDOM VARIABLE**.

If  $\text{Support}(T) = \mathbb{N}$ , we say that  $T$  is **N-valued**.

If  $\text{Support}(T) = \mathbb{N}_0 = \{0, 1, 2, \dots\}$ , we say that  $T$  is  **$\mathbb{N}_0$ -valued**.

Def'n. Let  $T$  be a r.v. w/ support  $\{t_1, t_2, \dots, t_n, \dots\}$ .  
The function

$$p_T(t_i) = \mathbb{P}[T=t_i] \text{ for all } i \in \mathbb{N}$$

is the **probability mass function** of  $T$ .

Convention. If  $T$  is  $\mathbb{N}_0$ -valued, then the pmf is usually written as

$$p_k = p_T(k) \text{ for all } k \in \mathbb{N}_0$$

Example [cont'd].

$$\text{Tng}(p)$$

$$p_n = (1-p)^{n-1} \cdot p \text{ for all } n \in \mathbb{N}$$

Problem. In modeling the number of claims filed by an individual under an auto policy during a 3-year period, an actuary makes a simplifying assumption that for all  $n \geq 0$ :

$$p_{n+1} = \frac{1}{5} p_n$$

w/  $p_n$  representing the probability that exactly  $n$  claims were filed.

Under this assumption, what is the probability that a **policyholder files more than one claim?**

→:

$$p_{n+1} = \left(\frac{1}{5}\right)p_n = \left(\frac{1}{5}\right)\left(\frac{1}{5}\right)p_{n-1} = \dots = \left(\frac{1}{5}\right)^{n+1} \cdot p_0$$

Similar to our geometric, but "shifted".

By the **Law of Total One**,

$$1 = \sum_{n=0}^{+\infty} p_n = \sum_{n=0}^{+\infty} \left( \left(\frac{1}{5}\right)^n \circledcirc p_0 \right) = p_0$$

$$\sum_{n=0}^{+\infty} \left(\frac{1}{5}\right)^n = p_0$$

$$\frac{1}{1 - \left(\frac{1}{5}\right)} = p_0$$

$$P_0 \cdot \frac{5}{4} = 1 \Rightarrow P_0 = \frac{4}{5}$$

in the problem

$$P_1 = \frac{1}{5} P_0 = \frac{1}{5} \cdot \frac{4}{5} = \frac{4}{25}$$

$N$ ... a r.v. denoting the # of claims

$$TP[N > 1] = 1 - TP[N=0] - \boxed{TP[N=1]}$$

$$= 1 - \frac{4}{5} - \frac{4}{25} = \frac{25-20-4}{25} = \frac{1}{25} = 0.04$$

□

Example. Imagine that you toss a coin w/ probab. of Hs equal to  $P$ , until you get Heads.

Assume that you already tossed the coin,  $m$  times @ least not getting Hs. What's the probability that you have to toss the coin more than  $n$  more times?

→:  $N$ ... # of tosses

$$N \sim g(p)$$

Given that  $\{N \geq m\} = \{N > m-1\}$

The probability we're looking for is

$$TP[N > n+m-1 \mid N > m-1] = ? \quad \text{Hint:} \begin{array}{l} \bullet \text{Def'n of conditional probab.} \\ \bullet \text{pmf of the geometric} \\ \bullet \text{algebra} \end{array}$$

$$\begin{aligned} TP[N > n+m-1 \mid N > m-1] &= \cancel{\frac{TP[N > n+m-1, N > m-1]}{TP[N > m-1]}} \\ &= \frac{TP[N > n+m-1]}{TP[N > m-1]} = \frac{(1-p)^{n+m-1}}{(1-p)^{m-1}} = (1-p)^n \\ &= \boxed{TP[N > n]} \end{aligned}$$

This is called the memoryless property.