## The Supervised Learning Problem

#### Starting point:

- Outcome measurement Y (also called dependent variable, response, target).
- Vector of p predictor measurements X (also called inputs, regressors, covariates, features, independent variables).
- In the regression problem, Y is quantitative (e.g price, blood pressure).
- In the *classification problem*, Y takes values in a finite, unordered set (survived/died, digit 0-9, cancer class of tissue sample).
- We have training data  $(x_1, y_1), \ldots, (x_N, y_N)$ . These are observations (examples, instances) of these measurements.

## Objectives

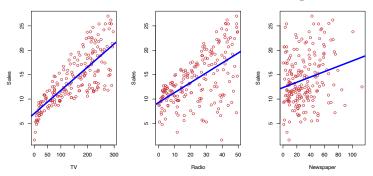
On the basis of the training data we would like to:

- Accurately predict unseen test cases.
- Understand which inputs affect the outcome, and how.
- Assess the quality of our predictions and inferences.

### Philosophy

- It is important to understand the ideas behind the various techniques, in order to know how and when to use them.
- One has to understand the simpler methods first, in order to grasp the more sophisticated ones.
- It is important to accurately assess the performance of a method, to know how well or how badly it is working [simpler methods often perform as well as fancier ones!]
- This is an exciting research area, having important applications in science, industry and finance.
- Statistical learning is a fundamental ingredient in the training of a modern *data scientist*.

# What is Statistical Learning?



Shown are Sales vs TV, Radio and Newspaper, with a blue linear-regression line fit separately to each. Can we predict Sales using these three?

Perhaps we can do better using a model

 $\mathtt{Sales} pprox f(\mathtt{TV},\mathtt{Radio},\mathtt{Newspaper})$ 

#### Notation

Here Sales is a response or target that we wish to predict. We generically refer to the response as Y.

TV is a feature, or input, or predictor; we name it  $X_1$ .

Likewise name Radio as  $X_2$ , and so on.

We can refer to the *input vector* collectively as

$$X = \begin{pmatrix} X_1 \\ X_2 \\ X_3 \end{pmatrix}$$

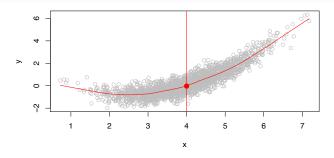
Now we write our model as

$$Y = f(X) + \epsilon$$

where  $\epsilon$  captures measurement errors and other discrepancies.

# What is f(X) good for?

- With a good f we can make predictions of Y at new points X = x.
- We can understand which components of  $X = (X_1, X_2, \ldots, X_p)$  are important in explaining Y, and which are irrelevant. e.g. Seniority and Years of Education have a big impact on Income, but Marital Status typically does not.
- Depending on the complexity of f, we may be able to understand how each component  $X_i$  of X affects Y.



Is there an ideal f(X)? In particular, what is a good value for f(X) at any selected value of X, say X=4? There can be many Y values at X=4. A good value is

$$f(4) = E(Y|X=4)$$

E(Y|X=4) means expected value (average) of Y given X=4.

This ideal f(x) = E(Y|X = x) is called the regression function.

• Is also defined for vector X; e.g.

$$f(x) = f(x_1, x_2, x_3) = E(Y|X_1 = x_1, X_2 = x_2, X_3 = x_3)$$

- Is also defined for vector X; e.g.  $f(x) = f(x_1, x_2, x_3) = E(Y|X_1 = x_1, X_2 = x_2, X_3 = x_3)$
- Is the *ideal* or *optimal* predictor of Y with regard to mean-squared prediction error: f(x) = E(Y|X=x) is the function that minimizes  $E[(Y-g(X))^2|X=x]$  over all functions g at all points X=x.

- Is also defined for vector X; e.g.  $f(x) = f(x_1, x_2, x_3) = E(Y|X_1 = x_1, X_2 = x_2, X_3 = x_3)$
- Is the *ideal* or *optimal* predictor of Y with regard to mean-squared prediction error: f(x) = E(Y|X=x) is the function that minimizes  $E[(Y-g(X))^2|X=x]$  over all functions g at all points X=x.
- $\epsilon = Y f(x)$  is the *irreducible* error i.e. even if we knew f(x), we would still make errors in prediction, since at each X = x there is typically a distribution of possible Y values.

- Is also defined for vector X; e.g.  $f(x) = f(x_1, x_2, x_3) = E(Y|X_1 = x_1, X_2 = x_2, X_3 = x_3)$
- Is the *ideal* or *optimal* predictor of Y with regard to mean-squared prediction error: f(x) = E(Y|X=x) is the function that minimizes  $E[(Y-g(X))^2|X=x]$  over all functions g at all points X=x.
- $\epsilon = Y f(x)$  is the *irreducible* error i.e. even if we knew f(x), we would still make errors in prediction, since at each X = x there is typically a distribution of possible Y values.
- For any estimate  $\hat{f}(x)$  of f(x), we have

$$E[(Y - \hat{f}(X))^{2} | X = x] = \underbrace{[f(x) - \hat{f}(x)]^{2}}_{Reducible} + \underbrace{\operatorname{Var}(\epsilon)}_{Irreducible}$$