

M339G: April 21st, 2025.

Example. Find a point \vec{p} on the plane $x+y-2z=6$ which lies closest to the origin.

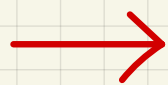
→:

Q: Why is this a constrained optimization problem?

→: Function we're trying to minimize

$$\tilde{D}(x,y,z) = x^2 + y^2 + z^2$$

subject to: $x+y-2z=6$.



In general, $f(x,y,z) \rightarrow \min/\max$

subject to the constraint $F(x,y,z) = 0$

First, we construct the "Lagrangian function"

$$L(x,y,z,\lambda) = f(x,y,z) + \lambda F(x,y,z)$$

Then, we optimize the function L as a f'tion of four variables (x,y,z,λ) .

Back to our example:

$$\tilde{D}(x,y,z) = x^2 + y^2 + z^2 \rightarrow \min$$

$$\text{subject to } F(x,y,z) = x+y-2z-6=0$$

$$\Rightarrow L(x,y,z,\lambda) = x^2 + y^2 + z^2 + \lambda(x+y-2z-6)$$

$$\frac{\partial L}{\partial x} = 2x + \lambda = 0$$

$$\frac{\partial L}{\partial y} = 2y + \lambda = 0$$

$$\frac{\partial L}{\partial z} = 2z - 2\lambda = 0$$

$$\frac{\partial L}{\partial \lambda} = x + y - 2z - 6 = 0$$

$$\Rightarrow x = -\frac{\lambda}{2}$$

$$\Rightarrow y = -\frac{\lambda}{2}$$

$$\Rightarrow z = \lambda$$

$$\Rightarrow x + y - 2z - 6 = 0$$

$$-\frac{\lambda}{2} - \frac{\lambda}{2} - 2\lambda = 6$$

$$\lambda = -2$$

$$\vec{p} = (x,y,z) = (1,1,-2)$$



Margins & Separating Hyperplanes.

Linear classifiers can be described geometrically as separating hyperplanes.

Any affine function $x \mapsto \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_p x_p$ determines a hyperplane in \mathbb{R}^p our predictor space

More precisely, $\{x : \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p = 0\}$ is a hyperplane splitting the space \mathbb{R}^p into two "half spaces":

$$\beta_0 + \beta_1 x_1 + \dots + \beta_p x_p > 0$$

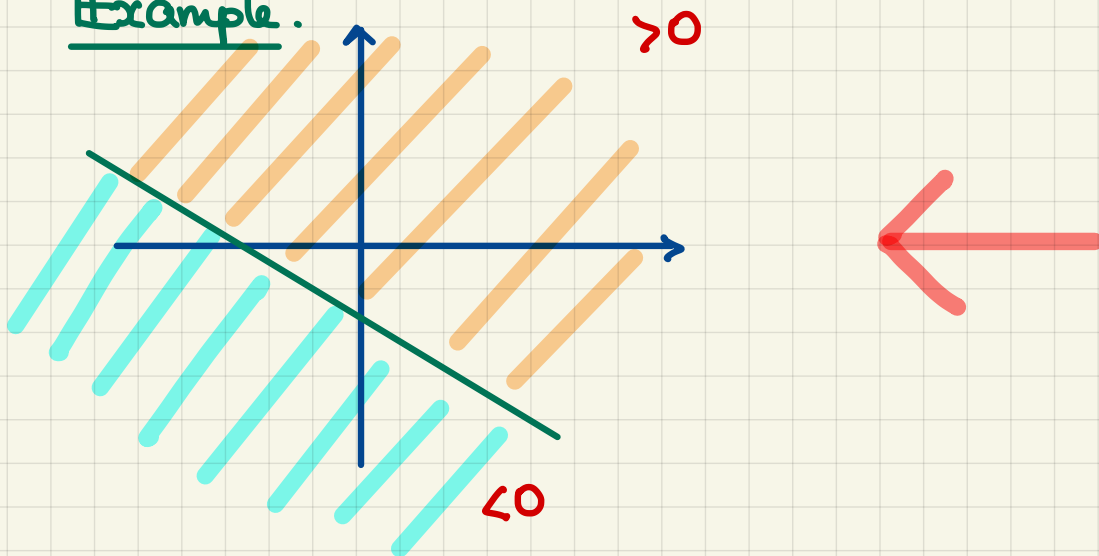
and

$$\beta_0 + \beta_1 x_1 + \dots + \beta_p x_p < 0.$$

The vector $\vec{n} = (\beta_1, \beta_2, \dots, \beta_p)$ is the **normal vector** of our hyperplane. For a given hyperplane, we can always choose \vec{n} so that $\|\vec{n}\| = 1$

Of course, the coefficient β_0 must also be scaled accordingly.

Example.



Note: • If the hyperplane goes through the origin,
then $\beta_0 = 0$

For any point x in the space, the deviation between it and the hyperplane is equal to

$$\beta \cdot x = \beta_1 x_1 + \dots + \beta_p x_p$$

- If $\beta_0 \neq 0$, the hyperplane does not go through the origin. The deviation becomes

$$\beta_0 + \beta \cdot x$$

The sign tells us which side of the hyperplane the point x is.

Maximal Margin Classifier.

Suppose that we have a classification problem w/ two classes. We choose to encode these classes as $Y = -1$ and $Y = +1$.

Our criterion for the best among all the separating hyperplanes (if such exist) is to find the one w/ the largest possible margin around the hyperplane.

OPTIMIZATION PROBLEM.

We formulate the above task as

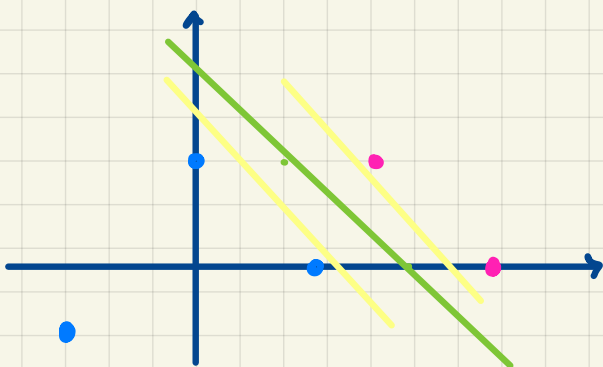
$$\max_{\beta_0, \beta_1, \dots, \beta_p} M$$

subject to
and

$$\sum_{i=1}^p \beta_i^2 = 1$$

$$y_i (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip}) \geq M$$

for all $i = 1, \dots, n$




maximal margin classifier

Reformulation of the Optimization Problem.

Define the vector

$$w = (w_1, \dots, w_p) = \frac{\beta}{M}$$

$$\min_{\beta_0, w} \frac{1}{2} \|w\|^2$$

subject to $y_i(\beta_0 + w_1 x_{i1} + \dots + w_p x_{ip}) \geq 1$ 
for all $i = 1, \dots, n$

This is a quadratic optimization problem.

We introduce Karush-Kuhn-Tucker (KKT) multipliers

$$\lambda = (\lambda_1, \dots, \lambda_n)$$

Now, we have an optimization problem which is equivalent to

$$\max_{\lambda} \min_{\beta_0, w} \left(\frac{1}{2} \|w\|^2 - \sum_{i=1}^n \lambda_i \cdot (y_i(\beta_0 + w_1 x_{i1} + \dots + w_p x_{ip}) - 1) \right)$$

subject to $\lambda_i \geq 0$ for all $i = 1 \dots n$

We differentiate partially the above w.r.t. β_0, w_1, \dots, w_p

We get

$$w_k - \sum_{i=1}^n \lambda_i \cdot y_i x_{ik} = 0 \quad \text{for all } k = 1 \dots p$$

$$\text{and} \quad - \sum_{i=1}^n \lambda_i y_i = 0,$$

i.e.,

$$w_k = \sum_{i=1}^n \lambda_i y_i x_{ik} \quad \text{and} \quad \sum_{i=1}^n \lambda_i y_i = 0.$$

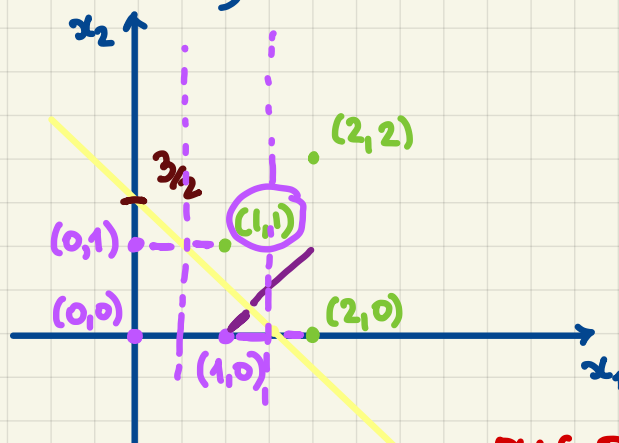
Moreover, by the KKT procedure, we know that

$$\lambda_i > 0 \iff y_i(\beta_0 + w_1 x_{i1} + \dots + w_p x_{ip}) = 1,$$

i.e., the point x_i falls on the margin

Problem. Consider these training data.

	x_1	x_2	y
$i=1$	1	1	+1
$i=2$	2	2	+1
$i=3$	2	0	+1
$i=4$	0	0	-1
$i=5$	1	0	-1
$i=6$	0	1	-1



w_1 and w_2 and $\beta_0 = ?$

$$(0,1): \beta_0 + w_1 \cdot 0 + w_2 \cdot 1 = -1$$

$$(1,0): \beta_0 + w_1 \cdot 1 + w_2 \cdot 0 = -1$$

$$w_1 = w_2$$

$$\beta_0 = -1 - w_1$$

$$(1,1): \beta_0 + w_1 \cdot 1 + w_2 \cdot 1 = 1 \rightarrow -1 - w_1 + w_1 + w_1 = 1 \Rightarrow w_1 = 2$$

$$(2,0): \beta_0 + w_1 \cdot 2 + w_2 \cdot 0 = 1$$

$$\Rightarrow w_2 = 2$$

$$\Rightarrow \beta_0 = -3$$

\Rightarrow Our eq'n for the hyperplane:

$$-3 + 2x_1 + 2x_2 = 0$$

$$2x_1 + 2x_2 = 3$$

$$x_1 + x_2 = \frac{3}{2}$$

$$x_2 = -x_1 + \frac{3}{2}$$

$$\|w\|^2 = 2^2 + 2^2 = 8 \Rightarrow \|w\| = 2\sqrt{2} \Rightarrow M = \frac{1}{2\sqrt{2}} = \frac{\sqrt{2}}{4}$$

Task: Convince yourselves that the optimal margin does not increase if we discard (0,1) or (2,0).