



# Master in Computer Vision Barcelona

Project  
Module 4  
Coordination

**Week 4: Tasks Description**

Video Surveillance for Road  
Traffic Monitoring

J. Ruiz-Hidalgo / X. Giró

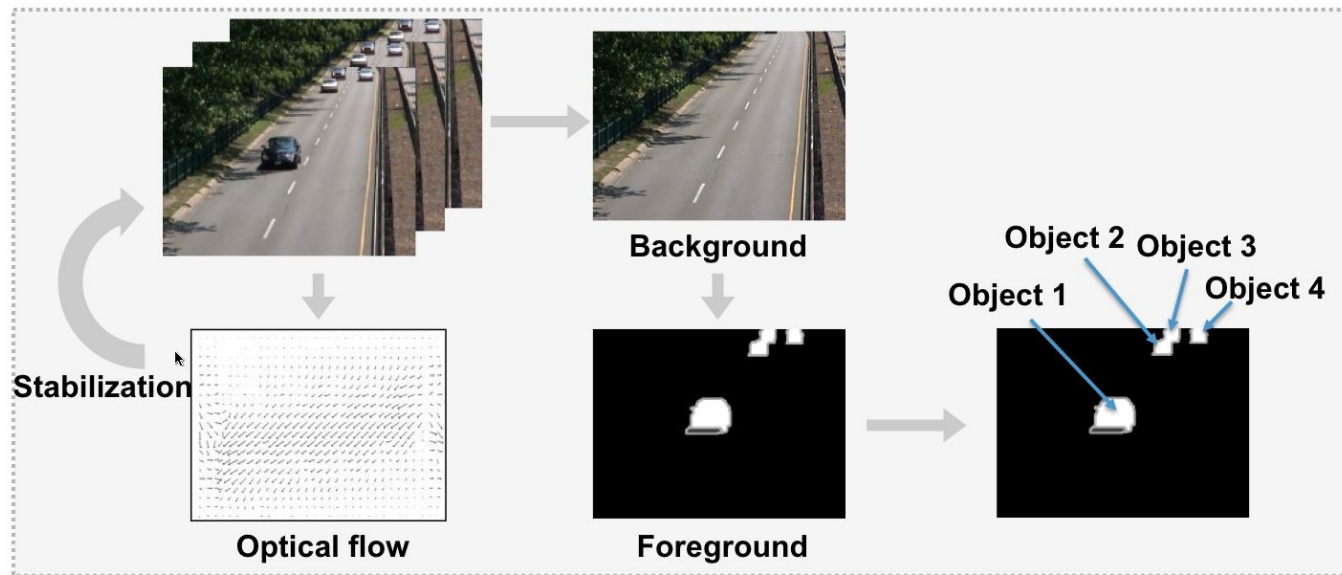
[j.ruiz@upc.edu](mailto:j.ruiz@upc.edu) / [xavier.giro@upc.edu](mailto:xavier.giro@upc.edu)




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# Project Schedule

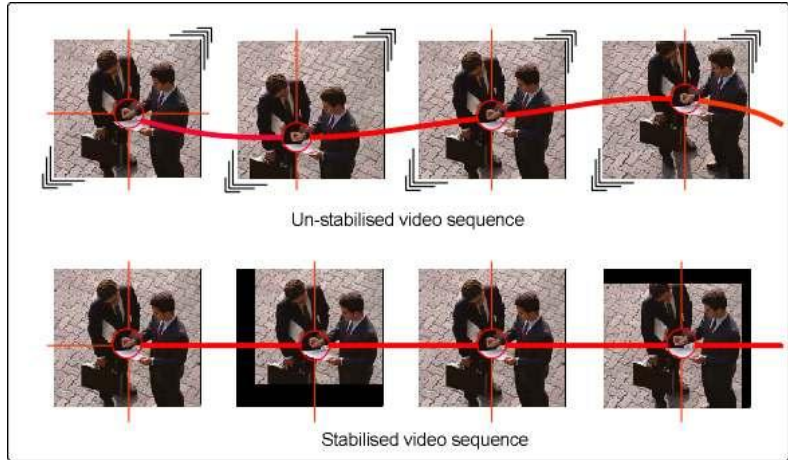
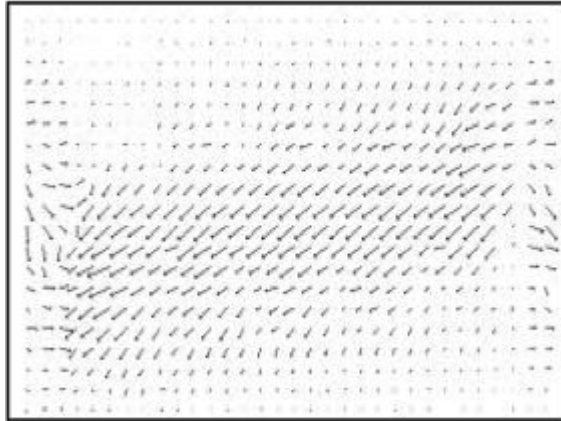


Week 1	Week 2	Week 3	Week 4	Week 5	Week 6
<ul style="list-style-type: none"><li>• Introduction</li><li>• DB</li><li>• Evaluation metrics</li></ul>	<ul style="list-style-type: none"><li>• Background estimation</li><li>• Stauffer &amp; Grimson</li></ul>	<ul style="list-style-type: none"><li>• Foreground segmentation</li><li>• Area filter</li><li>• Hole filling</li><li>• Shadow removal</li></ul>	<ul style="list-style-type: none"><li>• Optical flow</li><li>• Video stabilization</li></ul>	<ul style="list-style-type: none"><li>• Region tracking</li><li>• Kalman filter</li></ul>	<ul style="list-style-type: none"><li>• <b>Presentation</b></li></ul>

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# Goals Week 4

- Estimate the optical flow of a video sequence.
- Use the optical flow to correct any potential camera jitter.



Source: <http://www.ovation.co.uk/video-stabilization.html>

# Sequences

- Same as in week 1.
- Sequences 45 and 157 (image\_0) from the KITTI dataset.



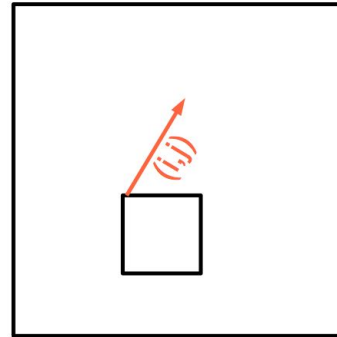
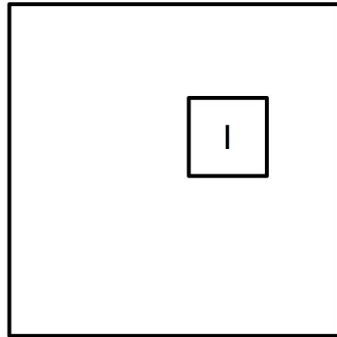
- Same as in weeks 2 and 3.
- TRAFFIC: frames 950 to 1050.



# Task 1

- Implement a block matching solution for optical flow estimation.
- Your decisions:
  - Forward or Backward compensation.
  - Area of Search.
  - Size of the blocks.

$$E(i, j) = \sum_{(m,n) \in I} (q_c[m, n] - q_r[m-i, n-j])^2$$



## Task 2: Comparison with Lucas-Kanade

- Compare the generated optical flows with the results obtained with Lucas-Kanade

	Mean Magnitude Error (MMEN)	Percentage of Erroneous Pixels (PEPN)
Your block matching		
Lucas-Kanade		

# Task 3

- Use the estimated flow between two frames to align them.
- Apply it to stabilize the camera on the TRAFFIC sequence.
- Assess the foreground extraction algorithm after camera stabilization with your best configuration of previous weeks
  - Provide a PR curve for both (video stabilization and not)
  - Compute AUC and compare both results
  - Provide F1-score for best configuration for both results

[https://upload.wikimedia.org/wikipedia/commons/d/d7/Video\\_image\\_stabilization.ogv](https://upload.wikimedia.org/wikipedia/commons/d/d7/Video_image_stabilization.ogv)

## Task 4 (optional)

- Search online for implementations of optical flow estimations and run them on the provided sequences ([middlebury](#))
- Provide the source code and references in your submission.

	Mean Magnitude Error (MMEN)	Percentage of Erroneous Pixels (PEPN)
Optical Flow 1		
Optical Flow 2		



## Task 5 (optional): Additional stabilization

- Search online for up to 2 other implementations of video stabilizations and test them (run them) on the provided sequences.
- Provide the source code and references in your submission
- Use PR curves, AUC and F1-score to compare results



Source : [Mercalli V3 SAL](#)

## Task 6 (optional)

- Record a short (maximum 5 seconds) video with a handheld camera.
- Stabilize it with any technique you choose.
- Submit the non-stabilised and stabilised versions of the same sequence.
- If using an external source code, provide a reference and code.
- Example: <http://youtu.be/0MiY-PNy-GU> and [research paper](#).



Source : <http://thenextweb.com/apps/2013/02/25/luma-improves-its-super-smooth-image-stabilization-for-shooting-video-on-ios/#!r9ZFj>

# Deliverables

- Short presentation
  - Code used for the week assignment.
  - Link your stabilized videos from youtube
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- **Wednesday 20th January 2016**
    - **Upload presentation link to github**
    - **Fill the intra-group evaluation**