COMPARISON FILTERING vs NON-FILTERING								
		IDF1 (SEQ 3)						
Detector	Tracker	c010	c011	c012	c013	c014	c015	Average
Mask RCNN (FT)	Overlap	0,2868	0,1971	0,0303	0,2194	0,241	0,0027	0,1629
	Kalman	0,4334	0,2731	0,0321	0,4252	0,3691	0,00279	0,2559
Mask RCNN (FT) + filtering	Overlap	0,5974	0,5173	0,4137	0,3635	0,5487	0,0540	0,4158
	Kalman	0,7661	0,7020	0,6022	0,8291	0,7408	0,0562	0,6161