Assignment 1.3 Exercises: 1, 2, 3, 4, 6, 7, 11, 13, 14

Exercise 1.3.1 Using row reduction, we can arrive at the system of equations

$$\begin{cases} x + 4z - 3w = 5 \\ y - 3x + 2w = -3. \end{cases}$$

From here, we let z = t, w = u where t and u are arbitrary parameters, and get the parametrization

$$\begin{cases} x = 5 - 4t + 3u \\ y = -3 + 3t - 2u \\ z = t \\ w = u. \end{cases}$$

Exercise 1.3.2 Using the trigonometric identity $\cos(2t) = 2\cos^2(t) - 1$, we have that $x = \cos(t)$, $y = \cos(2t) = 2\cos^2(t) - 1$. Substituting x for $\cos(t)$ into y yields the parabola $y = 2x^2 - 1$. This parametrization covers the parabola contained in the square $-1 \le x, y \le 1$ since $-1 \le \cos(\theta) \le 1$.

Exercise 1.3.3 This parametrization can be given by x = t, y = f(t).

Exercise 1.3.4

(1.3.4a) We begin by solving $x = \frac{t}{1+t}$ for t, which yields $t = \frac{x}{1-x}$. Next, we substitute this value into $y = 1 - \frac{1}{t^2}$ so

$$y = 1 - \frac{1}{t^2} = 1 - \frac{(1-x)^2}{x^2} = \frac{2x-1}{x^2}.$$

Thus we have that $x^2y = 2x - 1$, which implies that the parametrization is contained in $V(x^2y - 2x + 1)$.

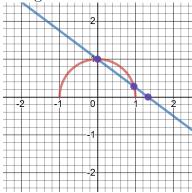
(1.3.4b) First, note that $(1,1) \in V(x^2y-2x+1)$ and that $1 \neq \frac{t}{1+t}$ for all $t \in \mathbb{R}$. Thus, the parametrization excludes (1,1). To see all other points are covered by the parametrization, suppose (x,y) satisfies $x^2y-2x+1=0$ with $x \neq 1$. Observe now that $x \neq 0$, since 0*y-2*0+1=0 is impossible. We therefore set $t=\frac{x}{1-x} \in \mathbb{R}$ and observe that $t \neq 0$ due to our constraints on x. Then $x=\frac{t}{1+t}$ by our definition of t and

$$1 - \frac{1}{t^2} = 1 - \frac{(1-x)^2}{x^2} = \frac{2x-1}{x^2} = y.$$

Note that the last equality follows from $x^2y - 2x + 1 = 0$. Therefore, (x, y) comes from the parametrization.

Exercise 1.3.6

(1.3.6a) The following is a second-dimensional representation of the concept. Note that the only point not reached by constructing lines this way is the "north pole", since that point cannot be represented by a line that intersects the sphere at two places using our current modeling.



(1.3.6b) The line from (0,0,1) to (u,v,0) can be parametrized by (1-t)(0,0,1) + t(u,v,0) = (tu,tv,1-t).

(1.3.6c) Substituing x = tu, y = tv, z = 1 - t into $x^2 + y^2 + z^2 - 1 = 0$ yields

$$0 = (tu)^{2} + (tv)^{2} + (1-t)^{2} - 1 = (u^{2} + v^{2} + 1)t^{2} - 2t = t((u^{2} + v^{2} + 1)t - 2).$$

Note that, since t=0 corresponds to the point (0,0,1), the other point of intersection must be given by $t=\frac{2}{u^2+v^2+1}$. Thus we have that

$$x = tu = \frac{2u}{u^2 + v^2 + 1}, y = tv = \frac{2v}{u^2 + v^2 + 1}, z = 1 - t = \frac{u^2 + v^2 - 1}{u^2 + v^2 + 1}.$$

Exercise 1.3.7 Working in \mathbb{R}^n means that the "north pole" is given by $(0, \ldots, 0, 1)$. Next, we need to define the line through the north pole and a point $(u_1, \ldots, u_{n-1}, 0)$ in the hyperplane $x_n = 0$. This can be defined by

$$(x_1,\ldots,x_n)=(1-t)(0,\ldots,0,1)+t(u_1,\ldots,u_{n-1},0)=(tu_1,\ldots,tu_{n-1},1-t).$$

We can observe that this line meets $x_1^2 + \ldots + x_n^2 - 1 = 0$ where

$$0 = (tu_1)^2 + \ldots + (tu_{n-1}^2) + (1-t)^2 - 1 = (u_1^2 + \ldots + u_{n-1}^2 + 1)t^2 - 2t = t((u_1^2 + \ldots + u_{n-1}^2 + 1)t - 2).$$

We already know that t = 0 is the north pole, so the other point of intersection must be given by

$$t = \frac{2}{u_1^2 + \ldots + u_{n-1}^2 + 1}$$

which gives the parametrization

$$x_i = tu_i = \frac{2u_i}{u_1^2 + \ldots + u_{n-1}^2 + 1}$$

for all $1 \le i \le n$.

Exercise 1.3.11

(1.3.11a) Using 1.3.8, we can change the variables $y \to x, x \to z$ to see that $x^2 = cz^2 - z^3$ is parametrized by $z = c - t^2, x = t(c - t^2)$.

(1.3.11b) Using $c = y^2$ for some fixed y, it follows that $x^2 = y^2z^2 - z^3$ is parametrized by $z = y^2 - t^2$, $x = t(y^2 - t^2)$. Finally, we replace y with a parameter u to get the parametrization $x = t(u^2 - t^2)$, y = u, $z = u^2 - t^2$ of $x^2 = y^2z^2 - z^3$, which is the surface $V(x^2 - y^2z^2 + z^3)$ in \mathbb{R}^3 .

(1.3.11c) Let $(x, y, z) \in V(x^2 - y^2z^2 + z^3)$, and define $c = y^2$. We then have that $(x, z) \in V(x^2 - cz^2 - z^3)$. Using (1.3.8c) with the change of variables $y \to x, x \to z$, there exists a t such that $z = c - t^2, x = t(c - t^2)$. Now, let u = y so that $c = y^2 = u^2$. Then $x = t(u^2 - t^2), y = u, z = u^2 - t^2$ as desired.

Exercise 1.3.13 Using method 1, we have that x = 1 + u - v, y = u + 2v, z = -1 - u + v satisfies ax + by + cz = d if and only if

$$d = a(1+u-v) + b(u+2v) + c(-1-u+v) = (a+b-c)u + (-a+2b+c)v + (a-c).$$

We can rewrite this as the following system of equations

$$\begin{cases} a+b-c=0\\ -a+2b+c=0\\ a-c=d. \end{cases}$$

When solved, this system yields a = c = 1, b = d = 0, so the equation is x + z = 0.

Exercise 1.3.14

(1.3.14a) Let $P, Q \in \mathbb{R}^2$. Then the line connecting P and Q is parametrized by

$$P + t(Q - P) = (1 - t)P + tQ$$

for $t \in \mathbb{R}$. Note that t = 0 yields P, t = 1 yields Q, and $0 \le t \le 1$ yields the line segment joining the two. Thus we have that

$$(1-t)P + tQ \in C$$

for $0 \le t \le 1$.

(1.3.14b) We wish to show that, for a convex set C containing P_1, \ldots, P_n , we have $\sum_{i=1}^n t_i P_i \in C$ when $t_1, \ldots, t_n \geq 0$ and that $\sum_{i=1}^n t_i = 1$. We proceed by induction on n. The base case of n=1 is true by observation, so we assume that the assertion is true for n. Next, we consider $P_1, \ldots, P_{n+1} \in C$ with $t_1, \ldots, t_{n+1} \geq 0$ and $\sum_{i=1}^{n+1} t_i = 1$. This implies that $t_{n+1} \leq 1$ and yields two possible cases:

Case 1: $t_{n+1} = 1$. Then $t_1 = \ldots = t_n = 0$, so $\sum_{i=1}^{n+1} t_i P_i = P_{n+1} \in C$. Case 2: $t_{n+1} < 1$. Then $1 - t_{n+1} > 0$ and we fix $u = \frac{t_i}{1 - t_{n+1}}$ for $1 \le i \le n$. Then $u_i \ge 0$. Thus $\sum_{i=1}^n t_i = 1 - t_{n+1}$ implies $\sum_{i=1}^{nu} u_i = 1$. Using the inductive hypothesis, $P = \sum_{i=1}^{n} t_i P_i \in C$. We can then use (1, 2, 14) by (1, 2, 14) $P = \sum_{i=1}^{n} u_i P_i \in C$. We can then use (1.3.14a) to show that C contains the point as follows:

$$(1 - t_{n+1})P + t_{n+1}P_{n+1} = (1 - t_{n+1})\sum_{i=1}^{n} u_i P_i + t_{n+1}P_{n+1}$$

$$= (1 - t_{n+1})\sum_{i=1}^{n} \frac{t_i}{1 - t_{n+1}}P_i + t_{n+1}P_{n+1}$$

$$= \sum_{i=1}^{n} t_i P_i + t_{n+1}P_{n+1}$$

$$= \sum_{i=1}^{n+1} t_i P_i$$

as desired.