

Day 6 Notes

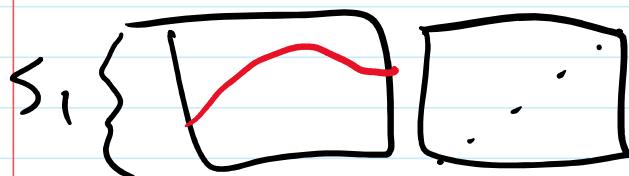
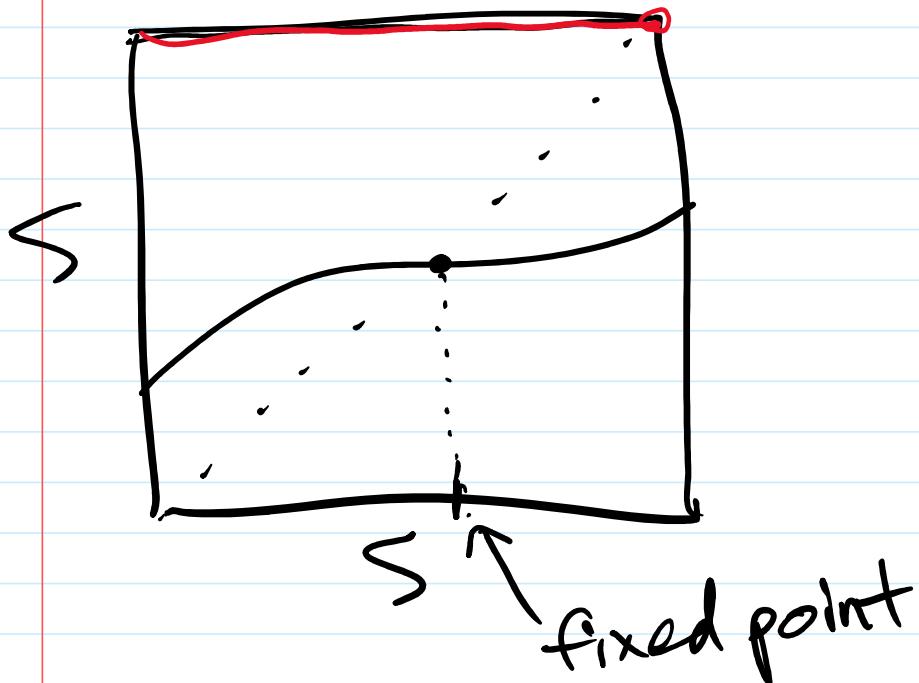
Monday, August 16, 2021

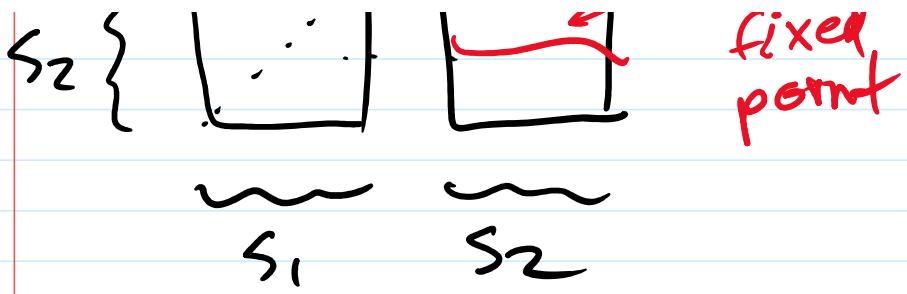
9:05 AM

Brouwer's F.P.T.

$$f: S \rightarrow S \quad S \subseteq \mathbb{R}^n$$

S compact and convex
and f continuous.





$$S = S_1 \cup S_2$$

$$\boxed{\quad} \subset \boxed{\quad}$$

$$f(x,y) = (e^{x^2} + \ln y) y^2$$

$$f_x = y^2 e^{x^2} \cdot 2x$$

$$f_y = e^{x^2} \cdot 2y + \frac{1}{y} y^2 + 2y \ln y$$

$$f_{xx} = y^2 \left(2x e^{x^2} \cdot 2x + 2e^{x^2} \right)$$

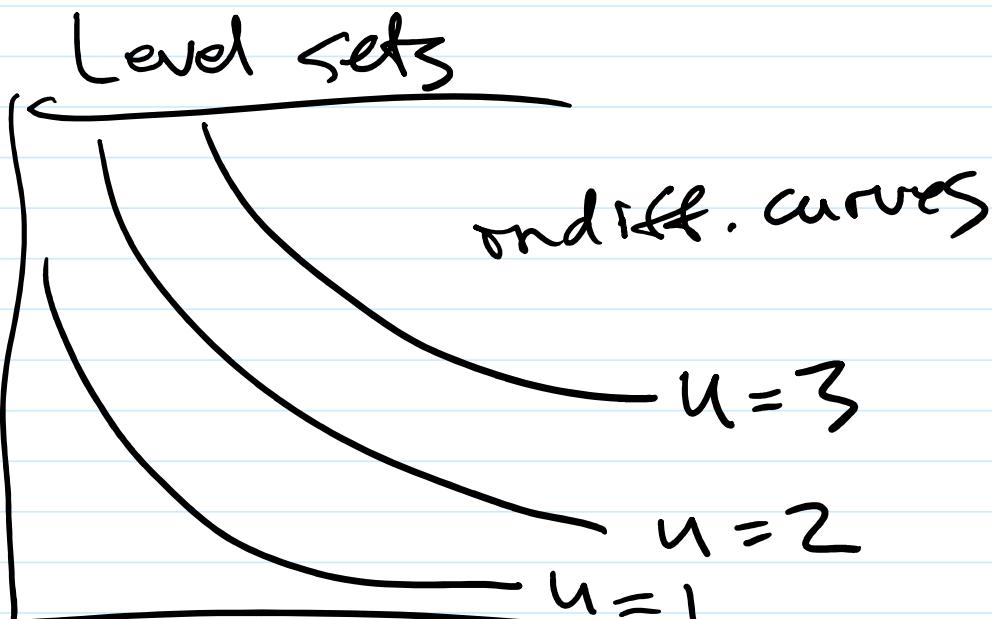
$$f_{yy} = e^{x^2} \cdot 2 + 1 + 2 \ln y + \frac{2y}{y}$$

$$f_{xy} = 2ye^{x^2} \cdot 2x$$

$$f_{yx} = e^{x^2} \cdot 2y \cdot 2x$$

$$\text{so } H = \begin{bmatrix} y^2(4x^2 e^{x^2} + 2e^{x^2}) & 4xye^{x^2} \\ 4xye^{x^2} & \end{bmatrix}$$

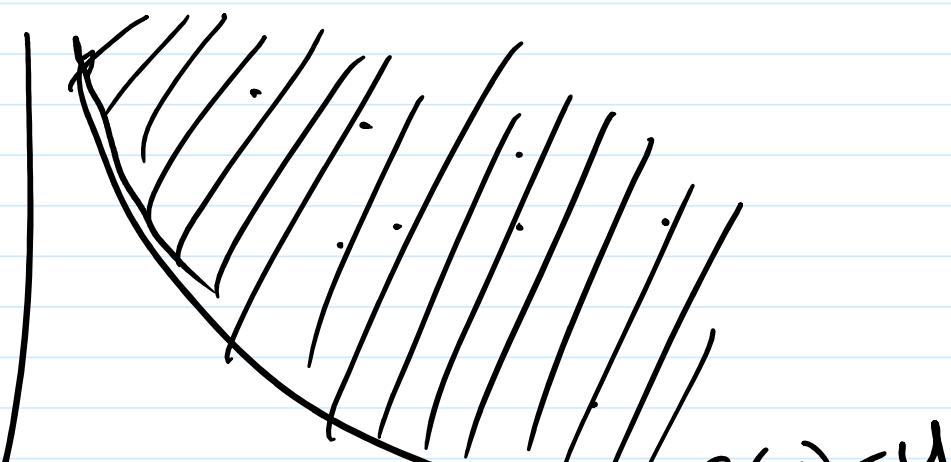
$$\text{so } H = \begin{bmatrix} y^2(4x^2e^{x^2} + 2e^{x^2}) & 4xye^{x^2} \\ 4xye^{x^2} & 2e^{x^2} + 2\ln y + 3 \end{bmatrix}$$

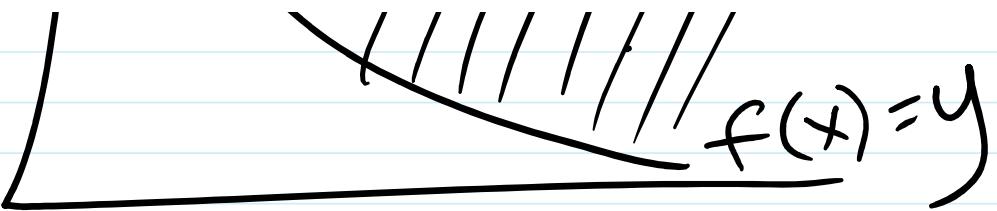


$$\{x : f(x) = y\}$$

Upper contour set

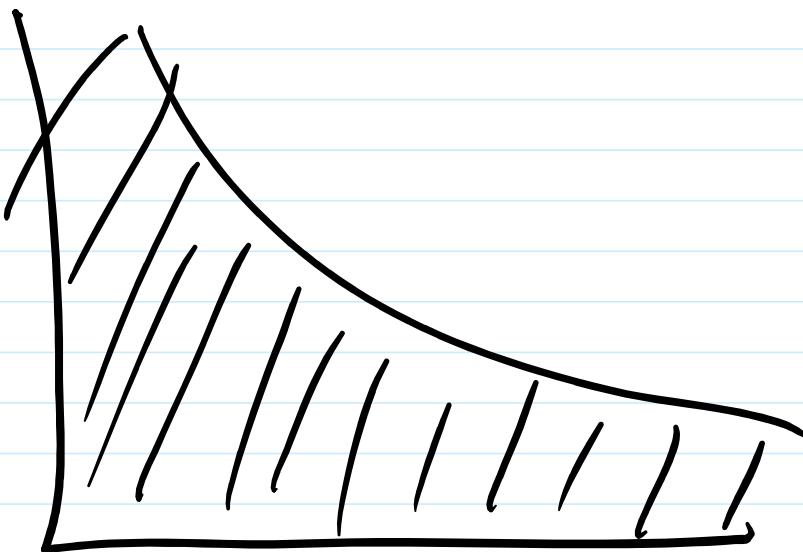
$$\{x : f(x) \geq y\}$$





Lower contour set

$$\{x : f(x) \leq y\}$$



Homogeneous fn

$HD(K)$: homogeneous of degree K

A fn is $HD(K)$ if for any constant a :

$$f(ax) = a^k f(x)$$

Constant Returns to Scale

A CRS prod. fn is HD(1)
in all inputs.

$$F(K, L) = K + L$$

$$F(2K, 2L) = 2K + 2L = 2F(K, L)$$

so F is HD(1).

Ex $y = bx^K$

$$y(x) = bx^K$$

$$y(\alpha x) = b(\alpha x)^K = b\alpha^K x^K$$

$$= \alpha^K \cdot bx^K = \alpha^K y(x)$$

Ex $y = a x_1^{K_1} x_2^{K_2} x_3^{K_3}$

$$\boxed{\text{Ex] } Y = \underline{a X_1^{K_1} X_2^{K_2} X_3^{K_3}}}$$

what is the HD()?

Cobb Douglas

HD(K) where

K is the sum of exponents.

$Y = AK^\alpha L^{1-\alpha}$ is always
HD(1) or CRS

$$C(\lambda r_1 g) = \lambda C(r_1 g)$$

$$C(r, g) = (r_1^\alpha + r_2^\alpha)^{1/\alpha} (g_1^{3/4} + g_2^{3/4})^{1/2}$$

$$C(t r, g) = ((t r_1)^\alpha + (t r_2)^\alpha)^{1/\alpha} \cdot (g_1^{3/4} + g_2^{3/4})^{1/2}$$

$$= (t^\alpha [r_1^\alpha + r_2^\alpha])^{1/\alpha} \cdot g(g)$$

$$\begin{aligned}
 &= -\left(t^\alpha [r_1^\alpha + r_2^\alpha]\right) \cdot g(g) \\
 &= (t^\alpha)^{\frac{1}{\alpha}} \cdot (r_1^\alpha + r_2^\alpha)^{\frac{1}{\alpha}} \cdot g(g) \\
 &= t(r_1^\alpha + r_2^\alpha)^{\frac{1}{\alpha}} \cdot g(g) \\
 &= tC(r_1 g)
 \end{aligned}$$

So this is HD(1) in r .

Demand functions

$$x_2^*(p, \omega) = \frac{\omega}{p^2} \cdot \frac{\alpha_2}{\alpha_1 + \alpha_2}$$

$$x_2(\lambda p, \lambda \omega) = \frac{\lambda \omega}{\lambda p^2} \cdot \frac{\alpha_2}{\alpha_1 + \alpha_2}$$

$$= \frac{\omega}{p^2} \cdot \frac{\alpha_2}{\alpha_1 + \alpha_2}$$

$$= \lambda^0 \cdot x_2(p, \omega)$$

\rightarrow So firs \exists HD(α) in
 p, w .

All demand fns are HD(α)

Ex | $\frac{\partial w}{\partial p_r}$ $\frac{\partial p_m}{\partial p_r}$
→ HD(α)

Euler's Theorem

If $f \in HD(\mathbb{R})$ then

$$Kf(x) = \sum_{i=1}^n x_i \frac{\partial f}{\partial x_i}(x)$$

$$= x \cdot \nabla f$$

dot product

gradient vector

Suppose $f \in HD(K)$.

Then $F(tx) = t^K F(x)$

Differentiate both sides wrt t.

$$\frac{\partial F}{\partial x_1} \cdot \boxed{\frac{\partial}{\partial t}(tx_1)} + \frac{\partial F}{\partial x_2} \cdot \frac{\partial}{\partial t}(tx_2) + \dots$$

evaluate at t = 1

$$= \boxed{K t^{K-1} F(x)}$$

$$\Rightarrow \frac{\partial F}{\partial x_1} \cdot x_1 + \frac{\partial F}{\partial x_2} \cdot x_2 + \dots = K F(x)$$



Ex 1 Demand fn

$$x_2 = \frac{\omega}{p_2} \cdot \frac{\alpha_2}{\alpha_1 + \alpha_2}$$

$$\cancel{\frac{\partial x_2}{\partial p_1} \cdot p_1 + \frac{\partial x_2}{\partial p_2} \cdot p_2 + \frac{\partial x_2}{\partial \omega} \cdot \omega = 0}$$

0

$$\begin{aligned}
 & \text{O } \quad \curvearrowleft \\
 & \frac{\omega \alpha_2}{\alpha_1 + \alpha_2} \cdot -1 \cdot p_2^2 \cdot p_2 \\
 & = -\omega \cdot \frac{\alpha_2}{\alpha_1 + \alpha_2} \cdot \frac{1}{p_2} \\
 & \qquad \qquad \qquad \curvearrowright \\
 & \frac{1}{p_2} \cdot \frac{\alpha_2}{\alpha_1 + \alpha_2} \cdot \omega
 \end{aligned}$$

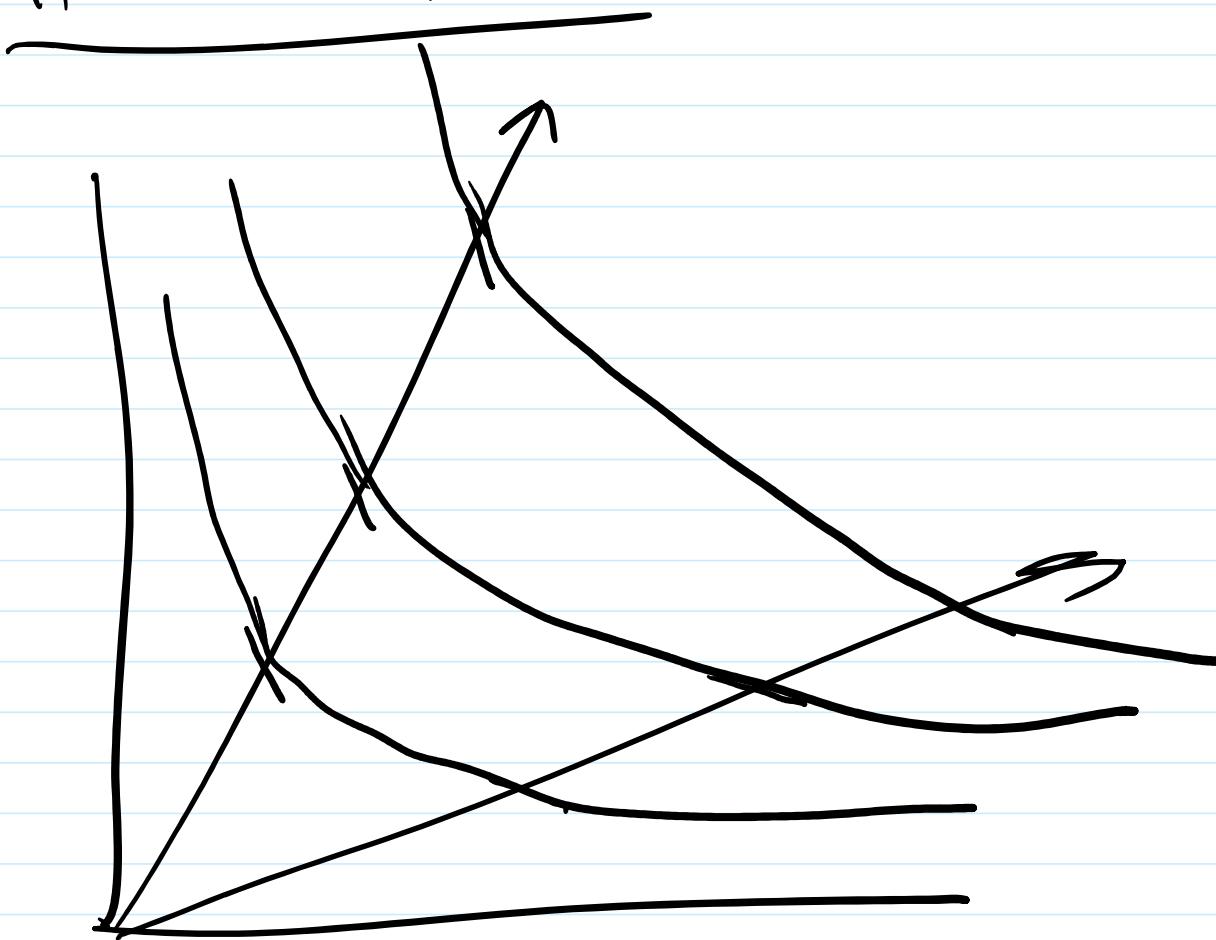
$$\text{So } \frac{2 \times z}{2p_2} \cdot p_2 = -\frac{2 \times z}{2w} \cdot w$$

So their sum is 0.

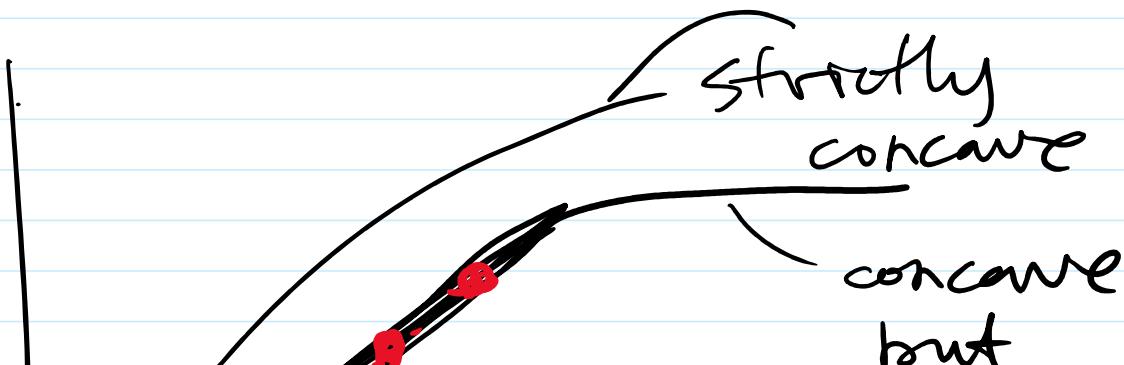
Recording was
Paused for the

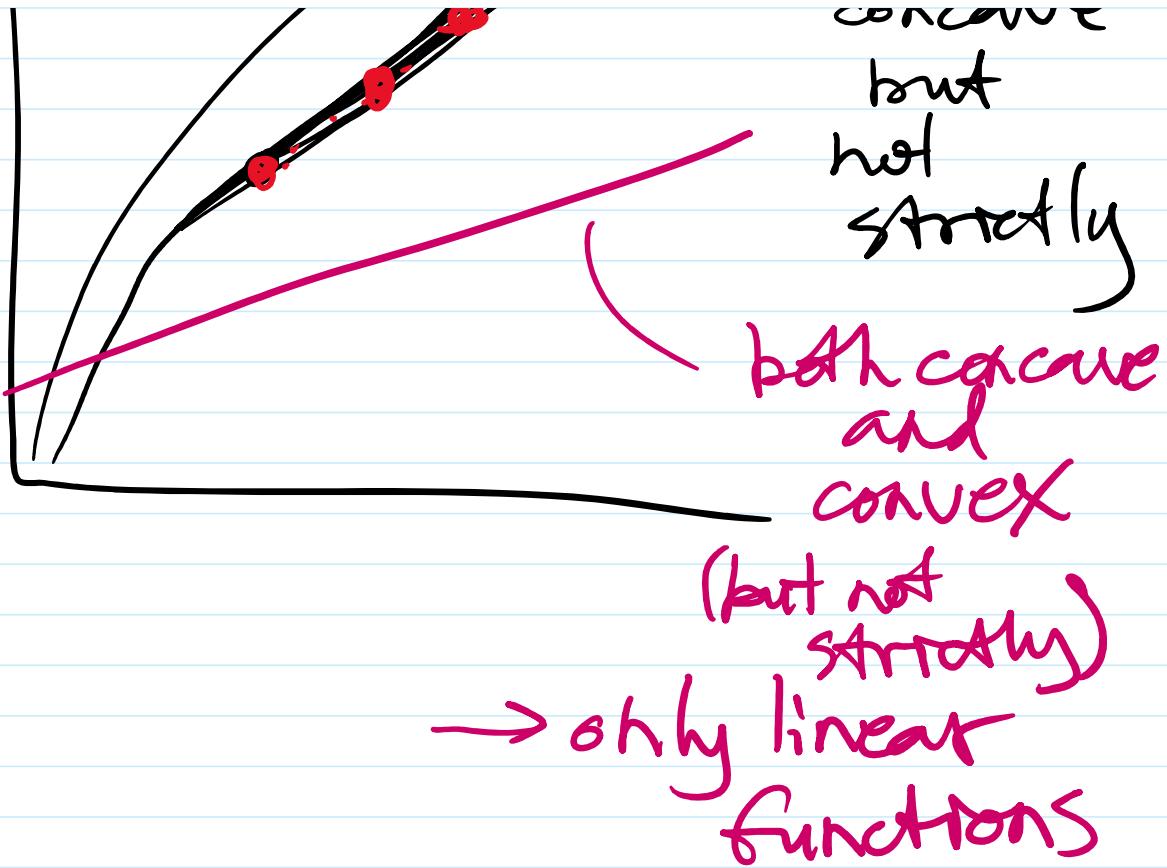
next section

Homothetic

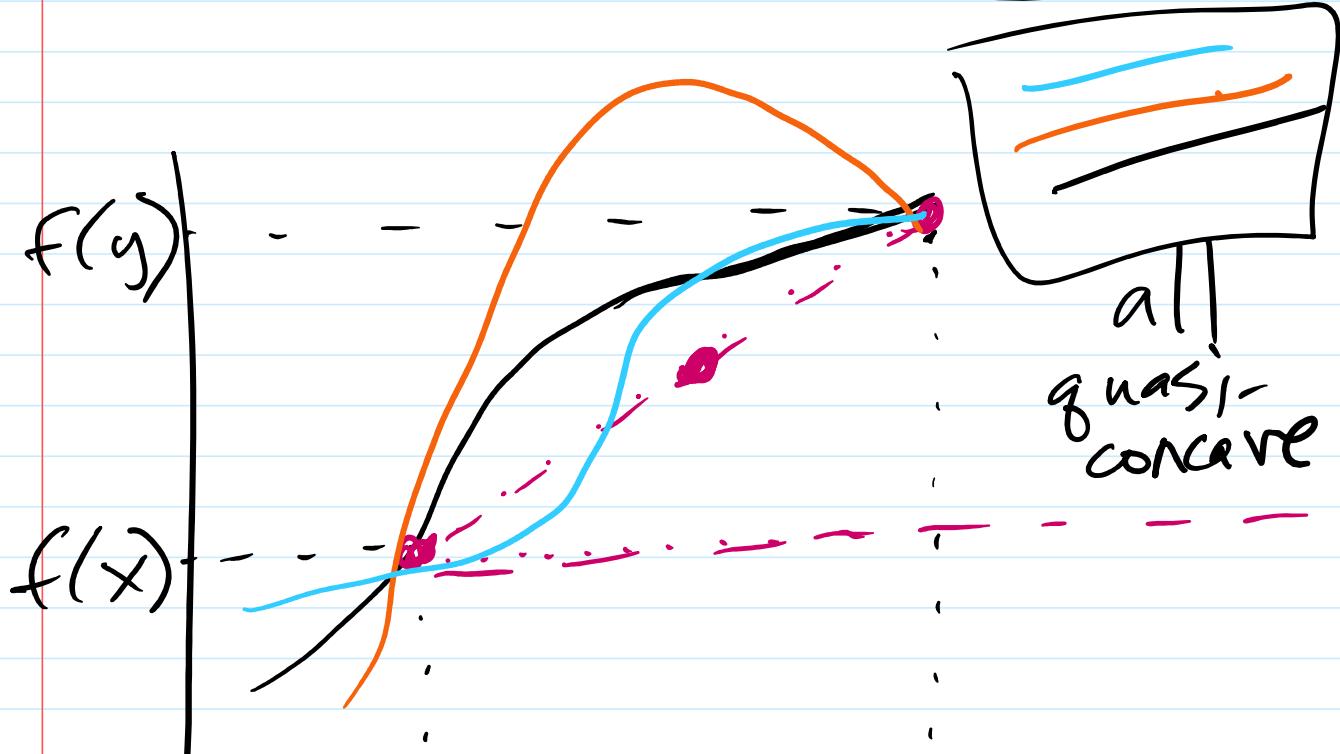


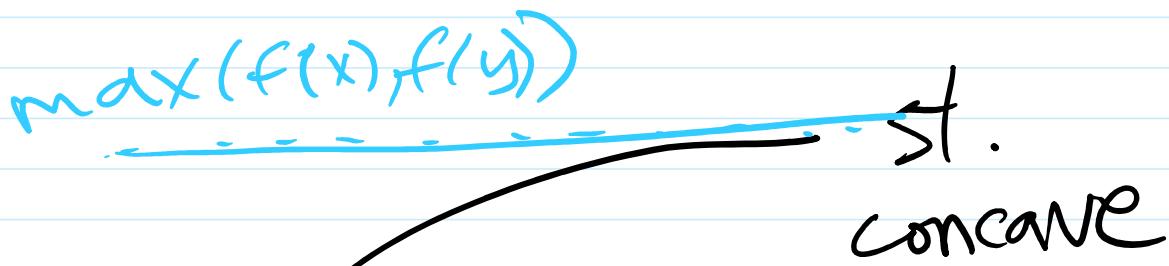
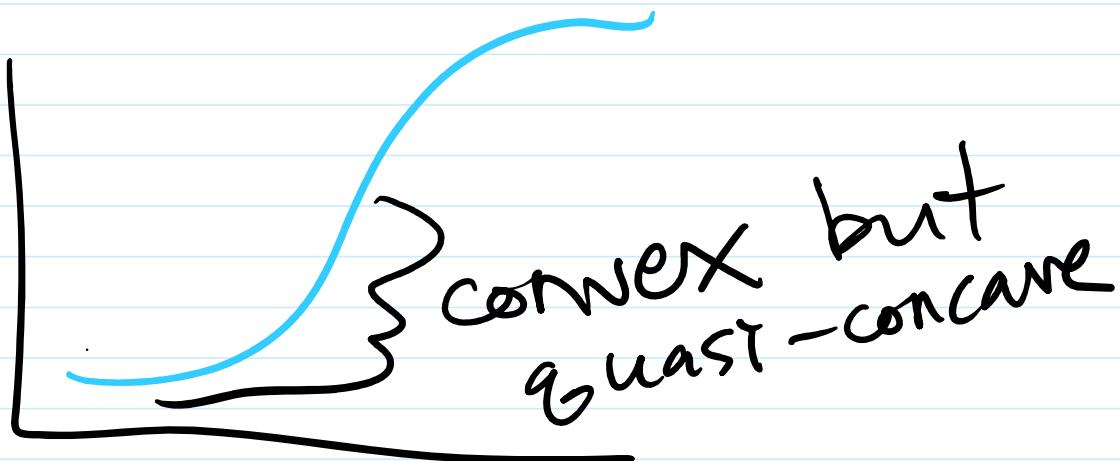
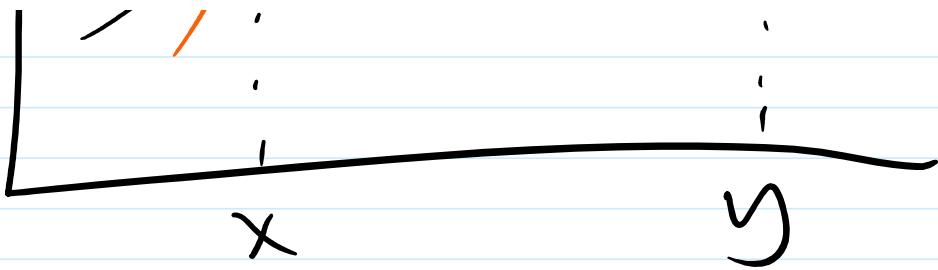
Level sets are parallel.





Quasi-concave





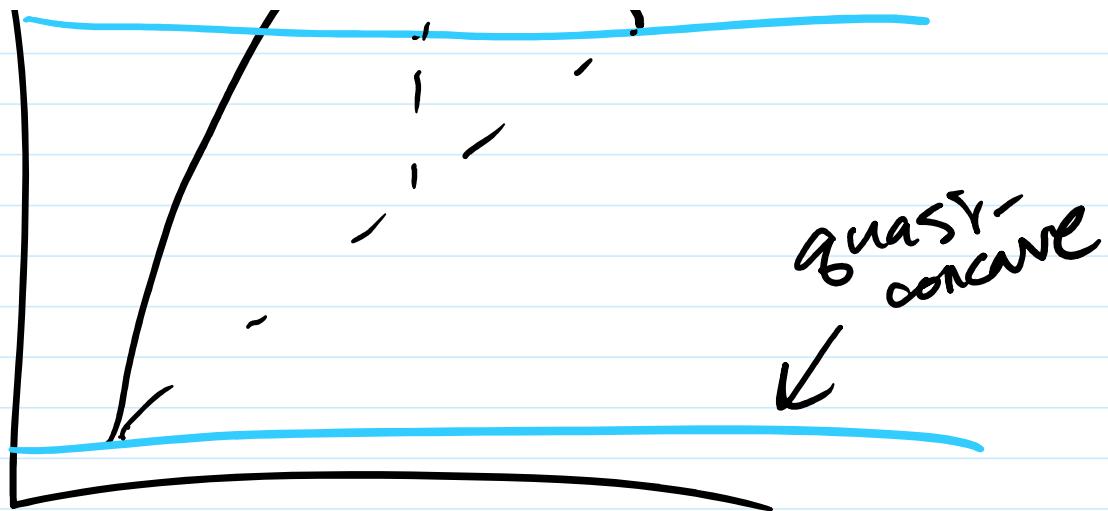
quasi-concave
and quasi convex

$$\min(f(x), f(y))$$

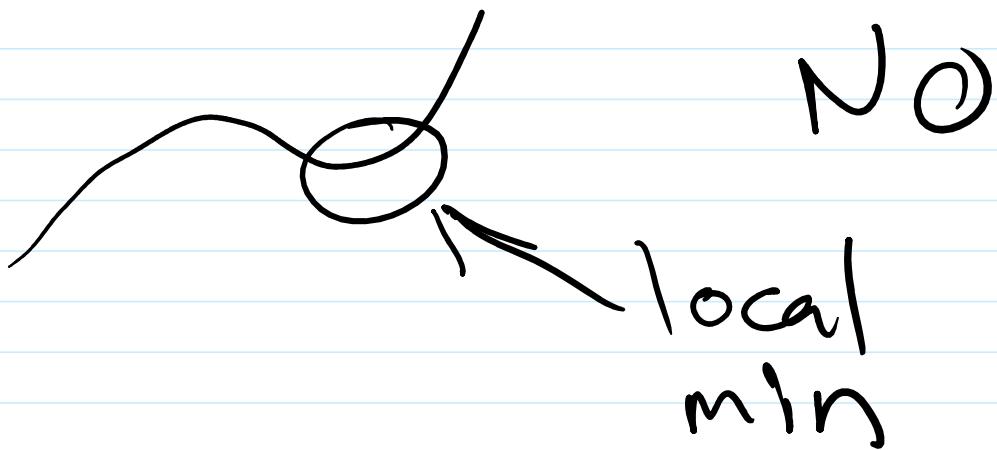
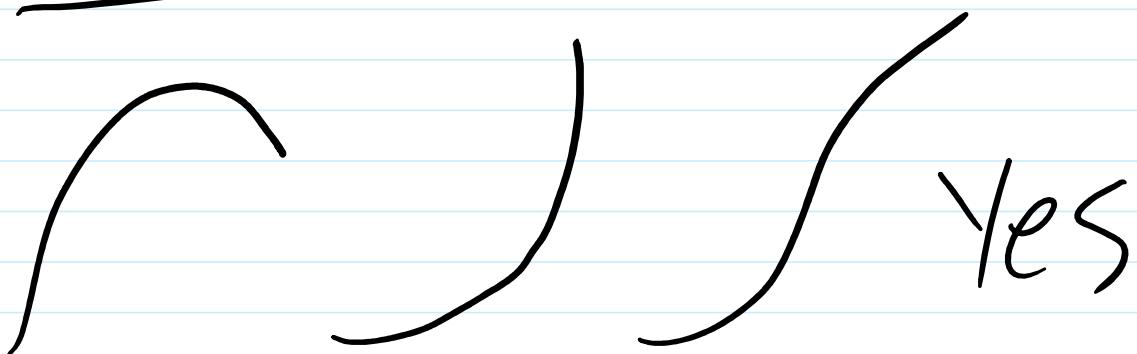
$$((\alpha x + (1-\alpha)y)) \geq \max(f(x), f(y))$$

not quasi convex

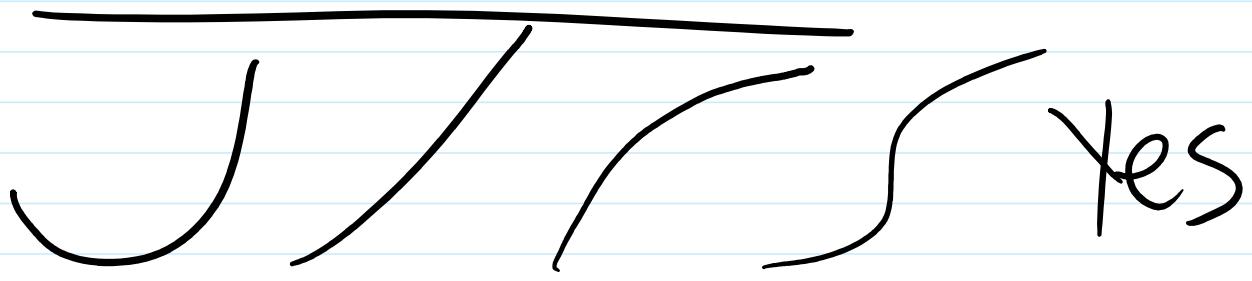




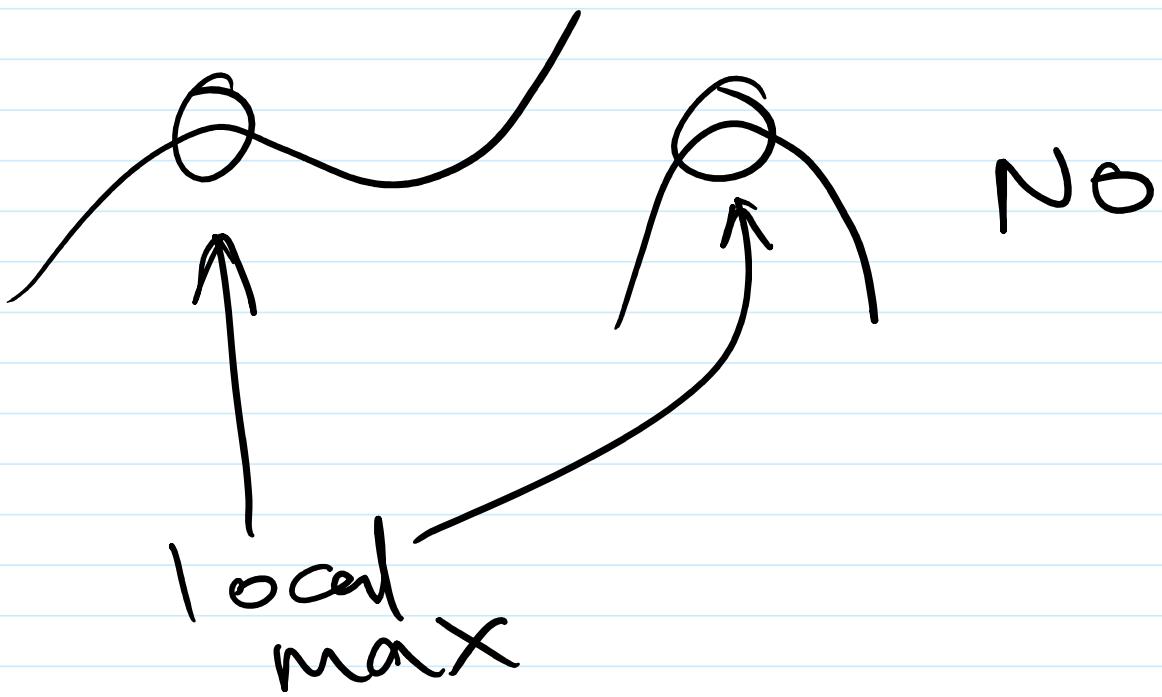
Quasiconcave



Quasiconvex



Yes



Interior local min/max
⇒ not quasi-concave/
convex

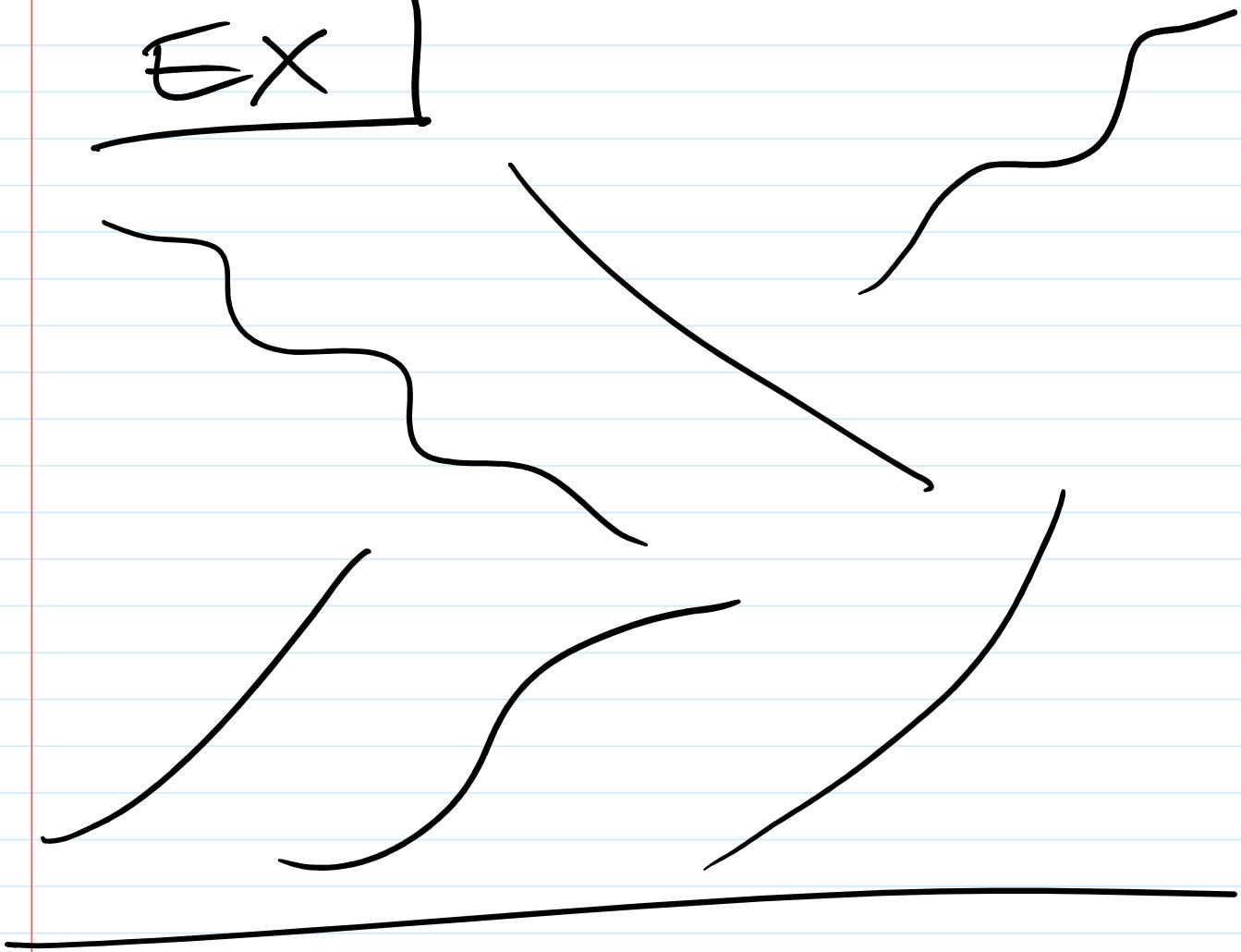
One implication :

A fn is quasi-concave

and quasi-convex ~~FFR~~

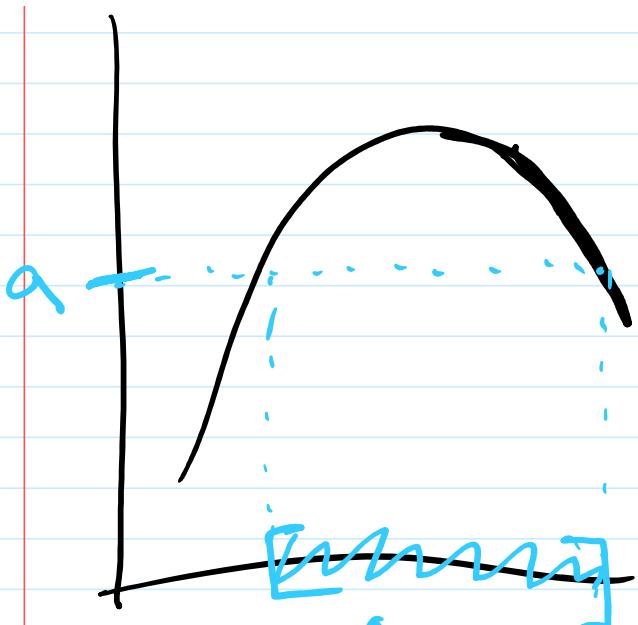
f is monotonic.

Ex]

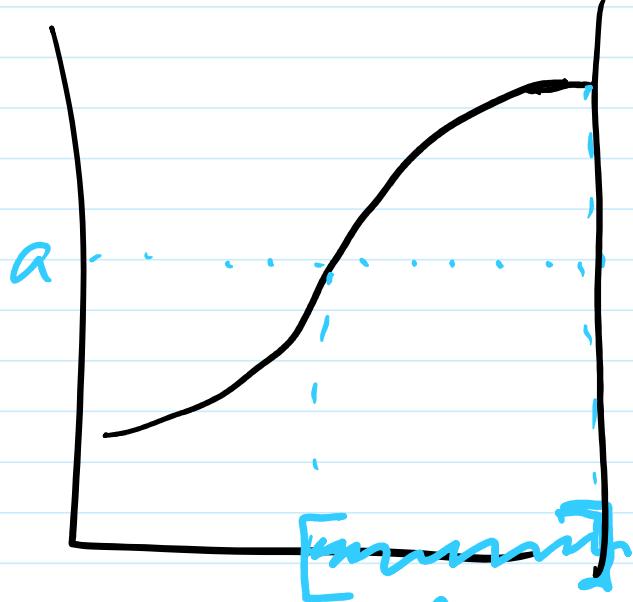


A fn \Rightarrow quasi concave

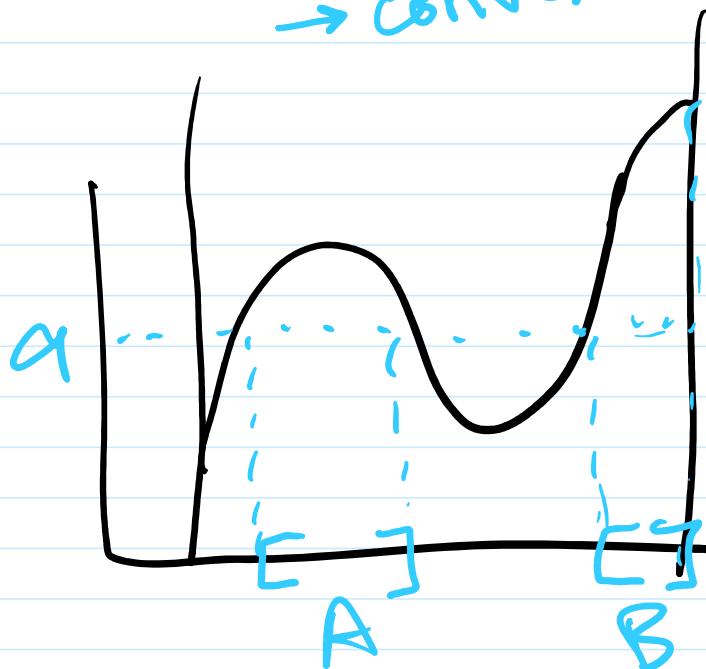
iff all of its upper
contour sets are convex.



↑
upper
contour
set
→ convex



↑
U.C.S
→ convex



upper. cont. set
 $= A \cup B$

= AUS

→ not convex

→ not quasiconcave

Consumer has a quasiconcave utility function.

⇒ All the upper contour sets are convex

⇒ The consumer's preferences are convex.

Concavity in \mathbb{R}^n

Recall:

A fn $f: \mathbb{R} \rightarrow \mathbb{R}$ is convex

If $f''(x) > 0$.

In \mathbb{R}^n :

A fn $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is ^{strictly} convex

If $\nabla^2 f$ Hessian is positive definite.

A symmetric matrix
(e.g. the Hessian) is positive definite if

$$Hx \neq 0, x^T H x > 0$$

$$x \in \mathbb{R}^n$$

$$\begin{matrix} x^T H x > 0 \\ \text{row vector} \\ \text{col vector} \end{matrix}$$

quadratic form

$$x^T H x = \sum_i \sum_j x_i x_j H_{ij}$$

*i, jth
element
of H*

Ex: $H = \begin{bmatrix} 2 & 3 \\ 3 & 4 \end{bmatrix}$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$x^T H x = 2x_1^2 + 6x_1 x_2 + 4x_2^2$$

$$2 \cdot (3x_1 x_2)$$

$x^T H x > 0$ pos. definite \iff strictly convex

≥ 0 pos. semidef. — convex

< 0 neg. def. — st. concave
 ≤ 0 neg. semidef — concave

Recording resumes here

$$f(x_1, x_2, \dots, x_n, y) = C$$

Ex 1 $u(x_1, x_2, x_3)$

Want to know MRS_{23} .

= slope of the indiff.
(in \mathbb{R}^2).

Hold u constant at π ,
to define a level set
of u .

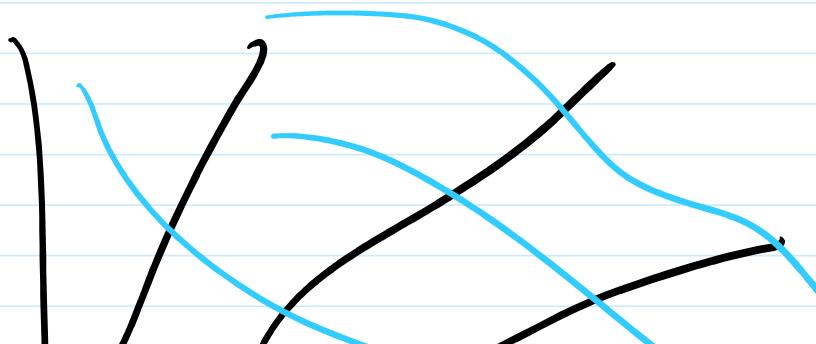
Let's use $u(x_1, x_2, x_3)$
 $= x_1^{1/4} x_2^{1/3} x_3^{1/6}$.

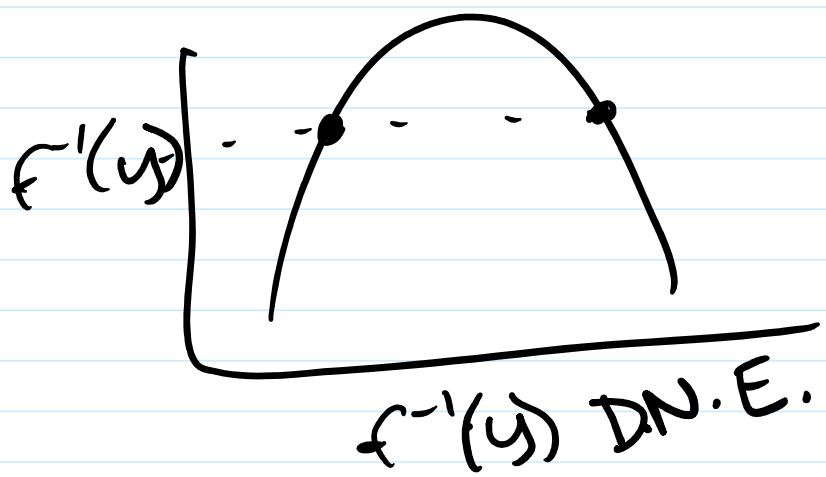
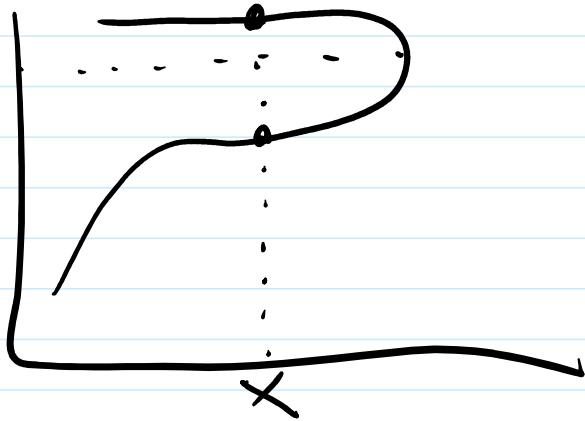
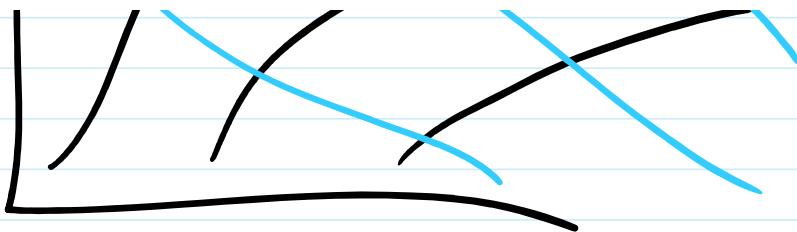
Find $\frac{dx_2}{dx_3} = MRS_{23}$ holding
 utility constant.

$$\begin{aligned}\frac{dx_2}{dx_3} &= -\frac{\frac{\partial u}{\partial x_3}}{\frac{\partial u}{\partial x_2}} \\ &= -\frac{\frac{1}{6}x_1^{1/4}x_2^{1/3}x_3^{-5/6}}{\frac{1}{3}x_1^{1/4}x_2^{-2/3}x_3^{1/6}} \\ &= -\frac{1}{2} \cdot \frac{x_2}{x_3}\end{aligned}$$

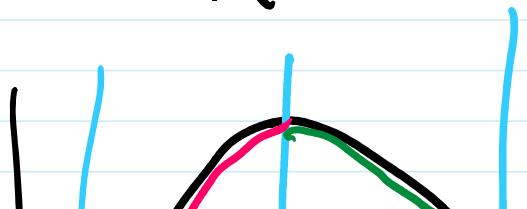
Inverse fn

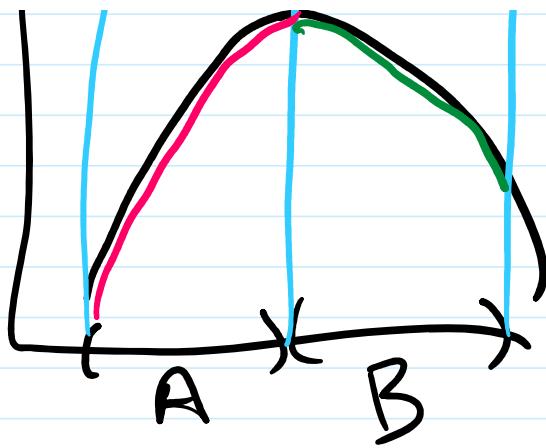
→ strictly monotonic





But the inverse of a non-monotonic fn may exist if you restrict the domain





$$f_A(x) \quad f_B(x)$$

$$f_A : A \rightarrow \mathbb{R} \quad f_B : B \rightarrow \mathbb{R}$$

f_A^{-1} exists f_B^{-1} exists

Correspondences

$$f(x) = y$$

a set ^{not}
 a vector

$$F(x) = \{y_1, y_2, y_3\}$$

Not a multi-valued
fn or vector field.

$$F(x_1) = \{1, 2, 3\}$$

$$F(x_2) = \{0, 0, 1, 5, 10\}$$

$$F(x_3) = \emptyset$$

$$\boxed{F: X \Rightarrow R}$$

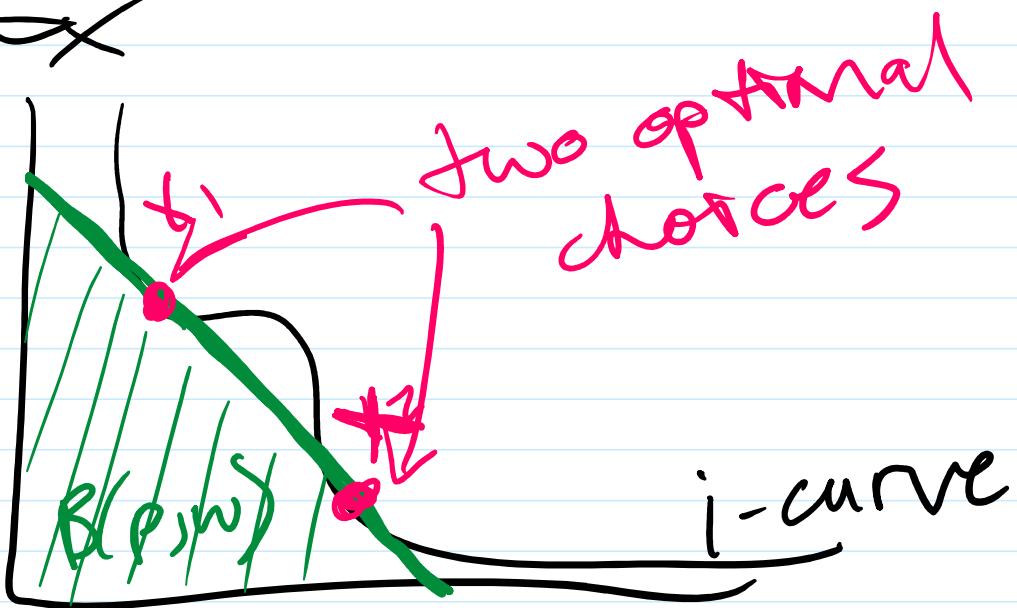
$\mathcal{P}(X)$ powerset: set of
all subsets of X .

$$F: X \Rightarrow R$$

\equiv

$$F: X \rightarrow \underline{\mathcal{P}(R)}$$

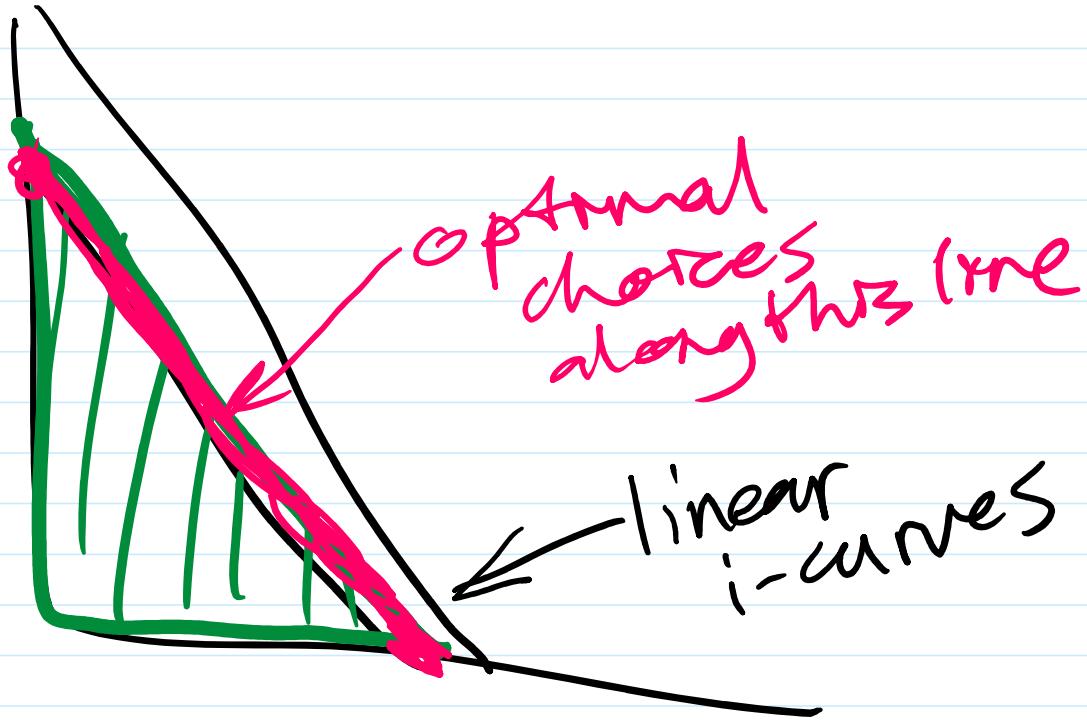
Ex



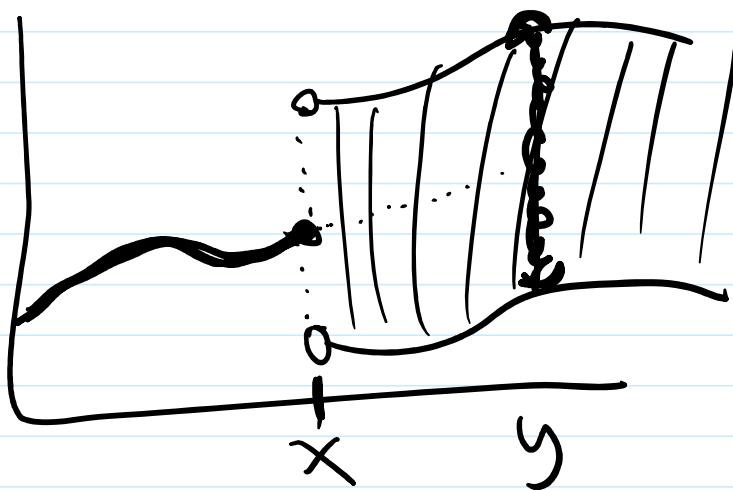
Demand correspondence

$$X^*(p, w) = \{x_1, x_2\}$$

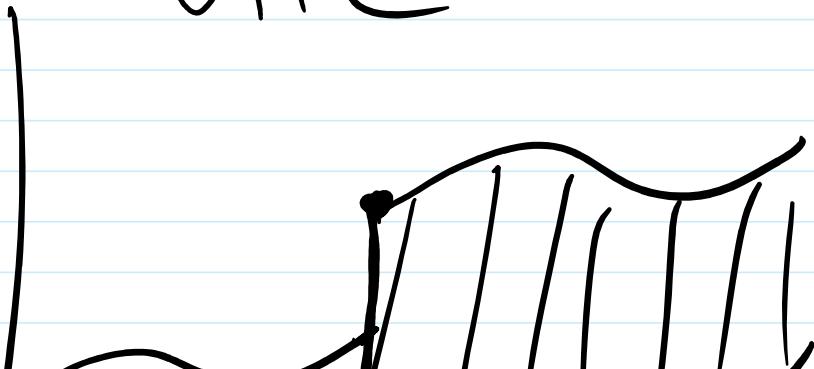
$\underbrace{\phantom{X^*(p, w) = \{x_1, x_2\}}}_{\text{maximizer}}$

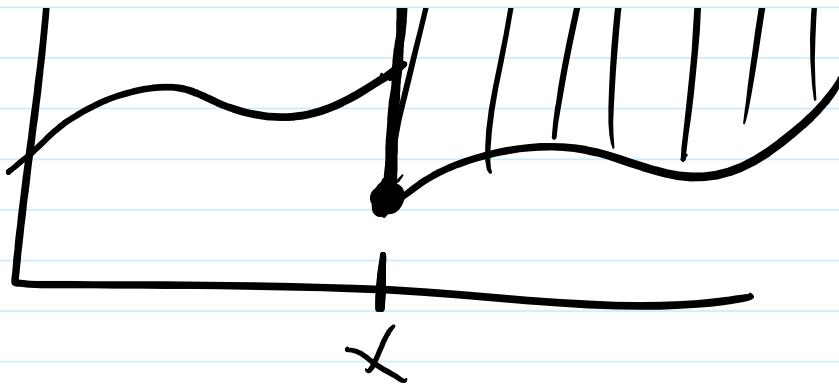


LHC



VHC





- 1) There are multiple equivalent definitions, using diff. characterizations of open and closed sets.
- 2) A correspondence is called continuous if it is both LHC and UHC.
- 3) Both LHC and UHC are equivalent to continuity for single-valued functions.

Kakutani's F.P.T.

\hat{x} is a fixed point of
 ϕ if $\hat{x} \in \phi(\hat{x})$

