Lecture 06 Matrices

Ryan McWay[†]

 $^{\dagger}Applied\ Economics,$ University of Minnesota

Mathematics Review Course, Summer 2023 University of Minnesota August 14th, 2023

LAST LECTURE REVIEW

- ► Multi-variate Calculus:
 - ► Partial Derivatives
 - ► Total Differentiation
 - ▶ Gradients
 - ► Implicit Partial Derivatives

REVIEW ASSIGNMENT

- 1. Problem Set 05 solutions are available on Github.
- 2. Any issues or problems **You** would like to discuss?

DAILY ICEBREAKER

- ► Attendance via prompt:
 - ► Name
 - ▶ Daily Icebreaker: Magic is real and you can crossover into the world of TV. What TV show would you want to live in?



Topic: Matrices

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MOTIVATION

- ► General background
 - ► A structured way to capture a series of related numbers.
 - ► Condense a system of equations.
 - ► This is the original conception of a 'spreadsheet' like you might find in Excel.
- ▶ Why do economists' care?
 - ▶ We primarily work with tabular datsets.
 - This is the main way with conceptualize information and manipulate it in practice.
- ► Application in this career
 - ▶ Matrices are throughout applied work as they are the foundation of both data storage, as well as how statistical software performs operations.

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OVERVIEW

- 1. Foundations of Matrices
- 2. Matrix Operators
- 3. Rank
- 4. Special Matrices
- 5. The Determinant
- 6. Trace
- 7. Matrix Decomposition
- 8. Positive and Negative Definite Matrices
- 9. Linear Independence
- 10. Chain Rule for Vectors

1. FOUNDATIONS OF MATRICES

- ► Scalar: Single number. e.g., [5]
- ▶ Vector: Either a $k \times 1$ column or $1 \times k$ row.

$$a = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_k \end{pmatrix}$$

ightharpoonup Matrix: A $k \times r$ rectangular array.

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1r} \\ a_{21} & a_{22} & \cdots & a_{2r} \\ \vdots & \vdots & \ddots & \vdots \\ a_{k1} & a_{k2} & \cdots & a_{kr} \end{bmatrix}$$

VECTORS ARE BOTH DIRECTION AND MAGNITUDE



1. FOUNDATIONS OF MATRICES

- ▶ In a matrix, a row is denoted i and the column j and is written as such in a cell: c_{ij} .
- ► To use linear operators on two or more matrices, you must be sure that the result will be a **conformable** matrix.
- For multiplication, it must be that n = s (e.g., the columns of A must match the rows of B):

If
$$A_{m \times n} \times B_{s \times p} = AB_{m \times p}$$

$$\begin{array}{ccc} A & B \\ (2 \times 2) & (2 \times 3) \\ \begin{bmatrix} 7 & 1 \\ 3 & 4 \end{bmatrix} & \begin{bmatrix} 7 & 1 & 0 \\ 3 & 4 & -1 \end{bmatrix} \\ \end{array}$$

- ► Transpose: Flip a matrix about the diagonal.
- \triangleright Ex., given the a and A previously defined.

$$A^{T} = \begin{pmatrix} a_{1} & a_{2} & \cdots & a_{k} \end{pmatrix}$$

$$A^{T} = \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{k1} \\ a_{12} & a_{22} & \cdots & a_{k2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1r} & a_{2r} & \cdots & a_{kr} \end{bmatrix}$$

▶ Partition: Divide a matrix into column or row vectors or into smaller matrices.

$$A = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_k \end{bmatrix} = \begin{bmatrix} a_1 & a_2 & \cdots & a_r \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{k1} \end{bmatrix} \cdots \begin{bmatrix} a_{1r} \\ a_{2r} \\ \vdots \\ a_{kr} \end{bmatrix}$$

► Addition:

- ightharpoonup Commutes: A + B = B + A
- ightharpoonup Associate: A + (B + C) = (A + B) + C
- ► Distributive: $(A + B)^T = A^T + B^T$

$$A + B = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \cdots & a_{1r} + b_{1r} \\ a_{21} + b_{21} & a_{22} + b_{22} & \cdots & a_{2r} + b_{2r} \\ \vdots & \vdots & \ddots & \vdots \\ a_{k1} + b_{k1} & a_{k2} + b_{k2} & \cdots & a_{kr} + b_{kr} \end{bmatrix}$$

► Multiplication by constant

$$A \cdot c = \begin{bmatrix} a_{11}c & a_{12}c & \cdots & a_{1r}c \\ a_{21}c & a_{22}c & \cdots & a_{2r}c \\ \vdots & \vdots & \ddots & \vdots \\ a_{k1}c & a_{k2}c & \cdots & a_{kr}c \end{bmatrix}$$

▶ Inner product of two $k \times 1$ vectors

$$a^{T} \cdot b = a_{1} \cdot b_{1} + a_{2} \cdot b_{2} + \dots + a_{k} \cdot b_{k} = \sum_{i=1}^{k} a_{i} b_{i}$$

2. Matrix Operators

▶ Dot Product: For two vectors *a* and *b* the **inner product** (or scalar product) is defined as:

$$a \cdot b = \sum_{i=1}^{n} a_i b_i = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$$

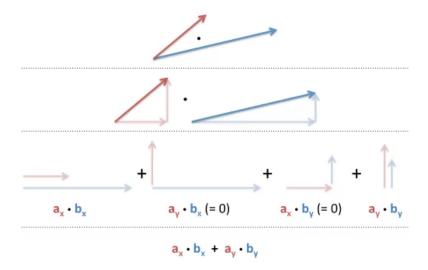
▶ A useful identity is to consider the dot product of Euclidean vectors when they are orthogonal (i.e., right angles, or 90° or $\theta = \frac{\pi}{2}$.

$$a \cdot b = ||a|| \cdot ||b|| \cos(\theta)$$

$$a \cdot b = ||a|| \cdot ||b|| \cos(\frac{\pi}{2})$$

$$a \cdot b = ||a|| \cdot ||b|| 0$$

$$a \cdot b = 0$$



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Math Review 2023: Matrices

Aug. 14th, 2023

DEMONSTRATION: DOT PRODUCT

Question:

Find dot product of
$$a = \begin{bmatrix} 0 & 4 & -2 \end{bmatrix} \cdot b = \begin{bmatrix} 2 \\ -1 \\ 7 \end{bmatrix}$$

Answer:

$$a \cdot b = (0)(2) + 4(-1) + (-2)(7)$$

= -18

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= -18

1. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 9 & 5 & -4 & 2 \end{bmatrix}$ and $b = \begin{bmatrix} -3 & -2 & 7 & -1 \end{bmatrix}$.

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Math Review 2023: Matrices

1. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 9 & 5 & -4 & 2 \end{bmatrix}$ and $b = \begin{bmatrix} -3 & -2 & 7 & -1 \end{bmatrix}.$

Answer: Show Work

$$a \cdot b = -67$$

- 1. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 9 & 5 & -4 & 2 \end{bmatrix}$ and $b = \begin{bmatrix} -3 & -2 & 7 & -1 \end{bmatrix}$.
- 2. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 2 & -3 & 4 & 15 & -3 \end{bmatrix}$ and $b = \begin{bmatrix} 8 & 8 & 2 & -10 & 0 \end{bmatrix}$.

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Answer: Show Work

$$a \cdot b = -150$$

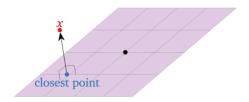
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- 3. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 2x & 2xy & 4z \end{bmatrix}$ and $b = \begin{bmatrix} x & 3y & xz \end{bmatrix}$.

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Answer: \ Show Work

$$a \cdot b = 2x^2 + 6xy^2 + 4xz^2$$

- ightharpoonup Orthogonality: A perpendicular (i.e., right angle) in n dimensions.
- ▶ Orthogonal vectors are $a^T \cdot b = 0$

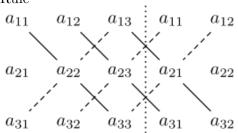


▶ Cross Product: Vector product (or outer product) is a new vector perpendicular to both input vectors $a = \begin{pmatrix} a_1 & a_2 & a_3 \end{pmatrix}$ and $b = \begin{pmatrix} b_1 & b_2 & b_3 \end{pmatrix}$.

$$a \times b = (a_1 \vec{i} + a_2 \vec{j} + a_3 \vec{k}) \times (b_1 \vec{i} + b_2 \vec{j} + b_3 \vec{k})$$

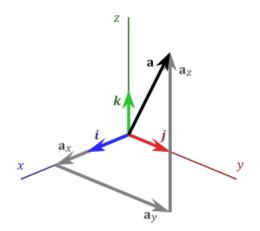
= $(a_2 b_3 - a_3 b_2) \vec{i} + (a_3 b_1 - a_1 b_3) \vec{j} + (a_1 b_2 - a_2 b_1) \vec{k}$

► Sarrus's Rule



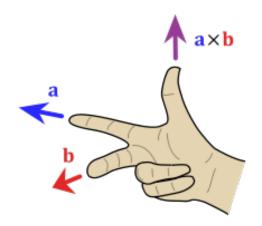
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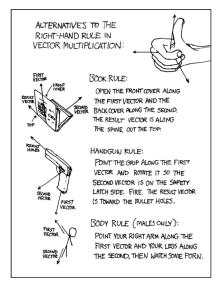


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RIGHT HAND RULE



RIGHT HAND RULE



DEMONSTRATION: CROSS PRODUCT

Question:

Find the cross product of
$$v = \begin{bmatrix} 0 & 4 & -2 \end{bmatrix} \times w = \begin{bmatrix} 3 & -1 & 5 \end{bmatrix}$$

$$v \times w = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} & | \vec{i} & \vec{j} \\ 0 & 4 & -2 & 0 & 4 \\ 3 & -1 & 5 & | 3 & -1 \end{vmatrix}$$
$$= 20\vec{i} - 6\vec{j} + 0\vec{k} - 0\vec{j} - 2\vec{i} - 12\vec{k}$$
$$= 18\vec{i} - 6\vec{j} - 12\vec{k}$$
$$= (18 - 6 - 12)$$

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PRACTICE: CROSS PRODUCT

1. Find cross product $w \times v$ for $w = \begin{bmatrix} 1 & 6 & -8 \end{bmatrix}$ and $v = \begin{bmatrix} 4 & -2 & -1 \end{bmatrix}$.

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Answer: \ Show Work

$$w \times v = -22\vec{i} - 31\vec{j} - 26\vec{k}$$

PRACTICE: CROSS PRODUCT

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$$a \times b = 5\vec{i} + \vec{j} + 11\vec{k}$$

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- 3. Find cross product $a \times b$ for $a = \begin{bmatrix} 3 & -2 & -1 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 5 & 1 & -2 & 3 \end{bmatrix}$.

$$a \times b = 12\vec{i} - 12\vec{j} + 30\vec{k} + 4\vec{l}$$

- ► Matrix Multiplication is summing the multiplication of the columns and the rows into a new matrix.
- ► Conformable: $[k \times r] \times [r \times s] = [k \times s]$
- ▶ Multiplication is not commutative $A \times B \neq B \times A$

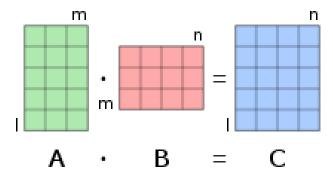
$$A \times B = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_k^T \end{bmatrix} \times \begin{bmatrix} b_1 & b_2 & \cdots & b_s \end{bmatrix}$$

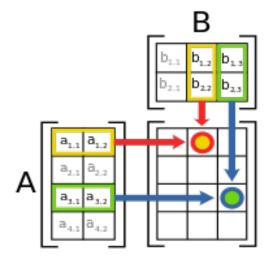
$$= \begin{bmatrix} a_1^T b_1 & a_1^T b_2 & \cdots & a_1^T b_s \\ a_2^T b_1 & a_2^T b_2 & \cdots & a_2^T b_s \\ \vdots & \vdots & \ddots & \vdots \\ a_k^T b_1 & a_k^T b_2 & \cdots & a_k^T b_s \end{bmatrix}$$

▶ Matrix multiplication: $A_{m \times n} B_{n \times p} = C_{m \times p}$

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} , B = \begin{bmatrix} b_{11} & \cdots & b_{1p} \\ \vdots & \ddots & \vdots \\ b_{n1} & \cdots & b_{np} \end{bmatrix}$$

$$C = \begin{bmatrix} a_{11}b_{11} + \cdots + a_{1n}b_{n1} & \cdots & a_{11}b_{1p} + \cdots + a_{1n}b_{np} \\ \vdots & \ddots & \vdots \\ a_{m1}b_{11} + \cdots + a_{mn}b_{n1} & \cdots & a_{m1}b_{1p} + \cdots + a_{mn}b_{np} \end{bmatrix}$$





DEMONSTRATION: MATRIX MULTIPLICATION

Question:

Determine *CD* given
$$C = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
 and $D = \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix}$

Answer:

$$CD = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \times \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix}$$

$$= \begin{bmatrix} 1(5) + (2)(7) & 1(6) + (2)(8) \\ (3)(5) + (4)(7) & (3)(6) + (4)(8) \end{bmatrix}$$

$$= \begin{bmatrix} 19 & 22 \\ 43 & 50 \end{bmatrix}$$

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$$= \begin{bmatrix} 19 & 22 \\ 43 & 50 \end{bmatrix}$$

1. Find
$$AB$$
 given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.

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1. Find
$$AB$$
 given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.

Answer: Show Work

$$AB = \begin{bmatrix} -1 & 6 \\ 4 & 9 \end{bmatrix}$$

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- 1. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.
- 2. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.

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 given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.

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$$AB$$
 given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.

$$|2 \times 2| \times |3 \times 2| = \text{Does not conform}$$

- 1. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.
- 2. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.
- 3. Find AB given $A = \begin{bmatrix} 3 & -6 & 9 \\ 10 & 1 & 0 \\ -8 & 2 & -2 \end{bmatrix}$ and $B = \begin{bmatrix} 9 & 1 & 7 & -5 \\ 3 & 5 & 0 & 6 \\ 4 & 1 & 2 & 2 \end{bmatrix}$.

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$$AB = \begin{bmatrix} 45 & -18 & 39 & -33 \\ 93 & 15 & 70 & -44 \\ -74 & 0 & -60 & 48 \end{bmatrix}$$

2. Matrix Operators

- ▶ Inversion: Solve when when matrix is square and non-singular (#rows(A) = #cols(A)).
- ▶ Let $B = A^{-1}$ be the inverse of full-rank $k \times k$ matrix A.
- ▶ This satisfies $AB = I_k$.
- ▶ Suppose $n \times n$ matrix A is invertible. Then it is non-singular and has a unique solution:

$$Ax = b$$
$$x = A^{-1}b$$

▶ This is important for determining coefficients in OLS.

3. Rank

- ▶ Rank: Number of non-zero rows in the row echelon form.
- $ightharpoonup rank = \min(m, n)$
 - ▶ Full Rank: # of rows = # of columns
 - $ightharpoonup rank A \leq \#rows(A)$
 - $ightharpoonup rank A \leq \#cols(A)$

4. TRACE

- ▶ Trace: Sum of the diagonal elements of $k \times k$ matrix A
 - ightharpoonup tr(cA) = ctr(A)
 - $ightharpoonup tr(A^T) = tr(A)$
 - ightharpoonup tr(A+B) = tr(A) + tr(B)
 - $ightharpoonup tr(I_k) = k$
 - ▶ If conformable, tr(AB) = tr(BA)

$$tr(A) = \sum_{i=1}^{k} a_{ii}$$

5. Special Matrices

- ▶ Square Matrix: k = r
 - ightharpoonup Square matrices are symmetric $A = A^T$
 - ► Called a **diagonal** if all off diagonal elements are zero.
 - ► Called an **upper diagonal** (or lower) if all elements below (above) the diagonal are zero.
 - ▶ Idempotent: $B^2 = BB = B$
- ► Identity Matrix: Diagonal matrix with only 1's as values in diagonal.

$$I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

► Zero Matrix: A null matrix with only zeros.

$$\blacktriangleright \text{ E.g., } [0], \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

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6. THE DETERMINANT

Matrices

ightharpoonup A matrix A is non-singular iff its determinant is non-zero.

$$det \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

$$det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32}$$

$$- a_{13}a_{22}a_{31} - a_{21}a_{12}a_{33} - a_{11}a_{23}a_{32}$$

- $ightharpoonup det A^T = det A$
- $ightharpoonup det(A \cdot B) = detA \cdot detB$
- \blacktriangleright $det(A+B) \neq detA + detB$

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6. The Determinant

▶ Minor of Matrix: A determinant of a smaller square matrix cut from *A* by removing one or more rows and columns.

$$\begin{aligned} |A| &= a_{11}|M_{11}| - a_{12}|M_{12}| + a_{13}|M_{13}| \\ &= a_{11}\begin{bmatrix} -a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} - a_{12}\begin{bmatrix} -a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} + a_{13}\begin{bmatrix} -a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \\ &= a_{11} \cdot \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \cdot \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \cdot \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} \end{aligned}$$

- ▶ Adjacent of Matrix: $adjA = (-1)^{i+j} \times det(\text{minor of } i, j)$.
- ► A non-singular matrix has the inversion:

$$A^{-1} = \frac{1}{detA} \cdot adjA$$
$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

DEMONSTRATION: DETERMINANT

Question:

$$det \begin{pmatrix} 7 & 2 & 1 \\ 0 & 3 & -1 \\ -3 & 4 & -2 \end{pmatrix}$$

Answer.

$$det(\cdot) = 7(-6 - (-4)) - 2(0 - (3)) + 1(0 - (-9))$$
$$= 7(-2) - 2(3) + 1(9)$$
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1.
$$det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$

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1.
$$det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$

$$det(\cdot) = -1$$

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$$det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$
.

$$2. \det \begin{pmatrix} 1 & 2 & 4 \\ 2 & 7 & 3 \\ 3 & 1 & -5 \end{pmatrix}.$$

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$$det(\cdot) = -76$$

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$$det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$
.

$$2. \det \begin{pmatrix} 1 & 2 & 4 \\ 2 & 7 & 3 \\ 3 & 1 & -5 \end{pmatrix}.$$

3.
$$det \begin{pmatrix} 1 & 1 & 2 \\ 2 & 3 & 1 \\ 3 & 4 & -5 \end{pmatrix}$$
.

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$$det\begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$
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3.
$$det \begin{pmatrix} 1 & 1 & 2 \\ 2 & 3 & 1 \\ 3 & 4 & -5 \end{pmatrix}$$
.

$$det(\cdot) = -8$$

7. Matrix Decomposition

- ► A matrix can be decomposed into its eigenvector.
- ► Eignevector is the vector which transforms (e.g., rotates, stretches) another vector by a constant factor.
- ightharpoonup Eigenvectors = c_i .
- ightharpoonup Eigenvalues = λ_i

$$\Lambda = \begin{pmatrix}
c_1 & c_2 & \cdots & c_k \\
\lambda_1 & 0 & \cdots & 0 \\
0 & \lambda_2 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & \lambda_k
\end{pmatrix}$$

$$Ac_k = \lambda_k c_k$$
$$AC = C\Lambda$$

LINEAR TRANSFORMATION





$$\begin{bmatrix} \cos 90^{\circ} & \sin 90^{\circ} \\ -\sin 90^{\circ} & \cos 90^{\circ} \end{bmatrix} \begin{bmatrix} \alpha_{1} \\ \alpha_{2} \end{bmatrix} = \begin{bmatrix} \Omega & \Omega \\ \Omega_{2} \end{bmatrix}$$

7. MATRIX DECOMPOSITION

- ► The vectors are orthogonal.
- $ightharpoonup c_i^T c_i = 1 \implies C^T C = I \implies CC^T = CC^{-1} = I.$
- ightharpoonup The diagonalization of A is

$$C^T A C = C^T C \Lambda = I \Lambda = \Lambda$$

► The spectral decomposition

$$A = C\Lambda C^{T} = \sum_{i=1}^{k} \lambda_{i} c_{i} c_{i}^{T}$$

8. Positive and Negative Definite Matrices

- ▶ Positive Definite: Iff for $k \times k$ real symmetric matrix A, $\forall c \neq 0 \in \mathbb{R}^k$, $c^T A c > 0$.
- ▶ Negative Definite: Iff for $k \times k$ real symmetric matrix A, $\forall c \neq 0 \in \mathbb{R}^k$, $c^T A c < 0$.
- \triangleright Semi-definite: A weak inequality \geq , \leq in either case.
- \blacktriangleright Negative Semi-definite: All diagonal elements must be ≤ 0 .

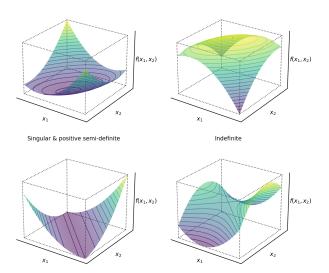
How to determine if you have a **positive** definite matrix?

- 1. All eigenvalues > 0.
- 2. Sylvester's Criterion: All upper left determinants (e.g., sub-matrices) must be > 0.
- 3. Every pivot must be > 0.
- 4. A has independent columns (e.g., $S = A^{T}A$)
- 5. $x^T S x > 0 \forall x : x \neq 0$

8. Positive and Negative Definite Matrices

Positive definite

Negative definite



9. LINEAR INDEPENDENCE

▶ Homogeneous System: Guaranteed to have at least one solution $x_i = 0 \forall i$ when $b_i = 0 \forall i$

$$A\begin{pmatrix} x_1 \\ \cdots \\ x_n \end{pmatrix} = 0$$

- ▶ Linearly Dependent: Iff there is a non-zero solution.
 - ▶ Means one of the column vectors a_n can be written as a linear combination of the other vectors.
 - ► Implies infinite solutions.
 - ▶ Short Rank (#rows(A) < #cols(A) must be linearly dependent.
- ► Linearly Independent: Iff the only solution is the zero solution.
- ▶ Singular: When a square matrix has a non-zero solution.

- Let x, y, z be vectors such that z is a function of y, and y is a function of x.
- ► We can apply the chain rule noting that with vectors we must chain the results **from the left**:

$$\frac{\partial z}{\partial x} = \frac{\partial y}{\partial x} \frac{\partial z}{\partial y} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x}$$

10. CHAIN RULE FOR VECTORS

$$\frac{\partial z}{\partial x} = \begin{bmatrix} \sum_{q=1}^{r} \frac{\partial z_1}{\partial y_q} \frac{\partial y_q}{\partial x_1} & \cdots & \sum_{q=1}^{r} \frac{\partial z_1}{\partial y_q} \frac{\partial y_q}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \sum_{q=1}^{r} \frac{\partial z_m}{\partial y_q} \frac{\partial y_q}{\partial x_1} & \cdots & \sum_{q=1}^{r} \frac{\partial z_m}{\partial y_q} \frac{\partial y_q}{\partial x_n} \end{bmatrix}$$

Lecture Review

Review

REVIEW OF MATRICES

- 1. Foundations of Matrices
- 2. Matrix Operators
- 3. Rank
- 4. Special Matrices
- 5. The Determinant
- 6. Trace
- 7. Matrix Decomposition
- 8. Positive and Negative Definite Matrices
- 9. Linear Independence
- 10. Chain Rule for Vectors

ASSIGNMENT

- ▶ Readings on Linear Algebra before Lecture 07:
 - ► S&B Ch. 7, 8, & 9
- ► Assignment:
 - ► Problem Set 06 (PS06)
 - ► Solution set will be available following end of Lecture 07
- ► Struggling?
 - 1. Read the 'Encouraged Reading'
 - 2. Review 'Supplementary material'
 - 3. Reach out directly

DOT PRODUCT QUESTION 1 ANSWER:

$$a \cdot b = 9(-3) + 5(-2) + (-4)7 + 2(-1)$$

= -67

DOT PRODUCT QUESTION 2 ANSWER:

$$a \cdot b = 2(8) + (-3)(8) + 4(2) + 15(-10) + (-3)0$$

= -150

DOT PRODUCT QUESTION 3 ANSWER:

$$a \cdot b = 2x^2 + 6xy^2 + 4xz^2$$

CROSS PRODUCT QUESTION 1 ANSWER:

$$w \times v = -6\vec{i} - 32\vec{j} - 2\vec{k} + 1\vec{j} - 16\vec{i} - 24\vec{k}$$
$$= -22\vec{i} - 31\vec{j} - 26\vec{k}$$

CROSS PRODUCT QUESTION 2 ANSWER:

$$\begin{aligned} a \times b = & (1)(1)\vec{i} + (-1)(-3)\vec{j} + 2(1)\vec{k} \\ -& 2(1)\vec{j} - (-1)4\vec{i} - (1)(-3)\vec{k} \\ =& 5\vec{i} + \vec{j} + 11\vec{k} \end{aligned}$$

CROSS PRODUCT QUESTION 3 ANSWER:

$$a \times b = 4\vec{i} - 3\vec{j} + 20\vec{k} + 3\vec{l} + 10\vec{k} - 9\vec{j} + 8\vec{i} + 1\vec{l}$$
$$= 12\vec{i} - 12\vec{j} + 30\vec{k} + 4\vec{l}$$

MATRIX MULT. QUESTION 1 ANSWER:

$$AB = \begin{bmatrix} 3-4 & 4+2 \\ 6-2 & 8+1 \end{bmatrix}$$
$$= \begin{bmatrix} -1 & 6 \\ 4 & 9 \end{bmatrix}$$

MATRIX MULT. QUESTION 2 ANSWER:

◆ QUESTION

 $|2 \times 2| \times |3 \times 2| = \text{Does not conform}$

MATRIX MULT. QUESTION 3 ANSWER:

$$AB = \begin{bmatrix} 27 - 18 + 36 & 3 - 30 + 9 & 21 + 0 + 18 & -15 - 36 + 18 \\ 90 + 3 + 0 & 10 + 5 + 0 & 70 + 0 + 0 & -50 + 6 + 0 \\ -72 + 6 - 8 & -8 + 10 - 2 & -56 + 0 - 4 & 40 + 12 - 4 \end{bmatrix}$$

$$= \begin{bmatrix} 45 & -18 & 39 & -33 \\ 93 & 15 & 70 & -44 \\ -74 & 0 & -60 & 48 \end{bmatrix}$$

DETERMINANTS QUESTION 1 ANSWER:

$$det(\cdot) = 1 - 2$$
$$= -1$$

DETERMINANTS QUESTION 2 ANSWER:

$$det(\cdot) = 1(-35 - 3) - 2(-10 - 9) + 4(2 - 21)$$

= -76

DETERMINANTS QUESTION 3 ANSWER:

$$det(\cdot) = 1(-15 - 4) - 1(-10 - 3) + 2(8 - 9)$$

= -8