

Lecture 06

Matrices

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- ▶ Multi-variate Calculus:
 - ▶ Partial Derivatives
 - ▶ Total Differentiation
 - ▶ Gradients
 - ▶ Implicit Partial Derivatives

REVIEW ASSIGNMENT

1. Problem Set 05 solutions are available on Github.
2. Any issues or problems **You** would like to discuss?

OVERVIEW

1. Foundations of Matrices
2. Matrix Operators
3. Rank
4. Special Matrices
5. The Determinant
6. Trace
7. Matrix Decomposition
8. Positive and Negative Definite Matrices
9. Linear Independence
10. Chain Rule for Vectors

VECTORS ARE BOTH DIRECTION AND MAGNITUDE



1. FOUNDATIONS OF MATRICES

- ▶ In a matrix, a row is denoted i and the column j and is written as such in a cell: c_{ij} .
- ▶ To use linear operators on two or more matrices, you must be sure that the result will be a **conformable** matrix.
- ▶ For multiplication, it must be that $n = s$ (e.g., the columns of A must match the rows of B):

If $A_{m \times n} \times B_{s \times p} = AB_{m \times p}$

$$\begin{array}{cc} \text{A} & \text{B} \\ (2 \times 2) & (2 \times 3) \\ \begin{bmatrix} 7 & 1 \\ 3 & 4 \end{bmatrix} & \begin{bmatrix} 7 & 1 & 0 \\ 3 & 4 & -1 \end{bmatrix} \end{array}$$

2. MATRIX OPERATORS

- Partition: Divide a matrix into column or row vectors or into smaller matrices.

$$A = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_k \end{bmatrix} = [a_1 \quad a_2 \quad \cdots \quad a_r]$$

$$A = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{k1} \end{bmatrix} \cdots \begin{bmatrix} a_{1r} \\ a_{2r} \\ \vdots \\ a_{kr} \end{bmatrix}$$

2. MATRIX OPERATORS

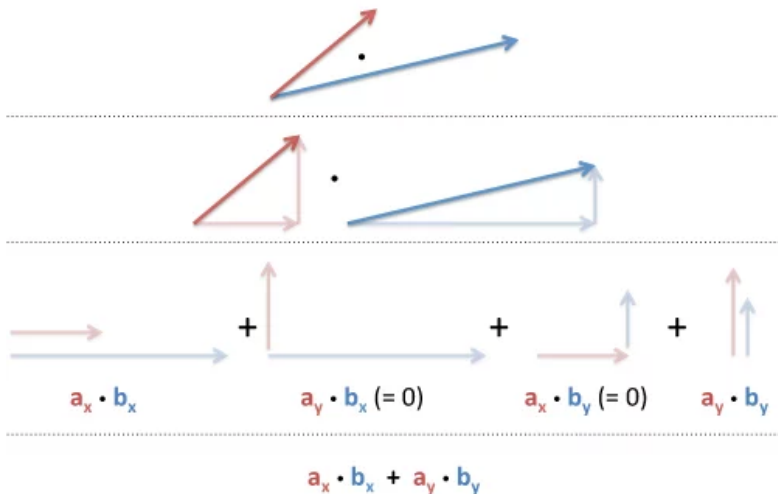
- Multiplication by constant

$$A \cdot c = \begin{bmatrix} a_{11}c & a_{12}c & \cdots & a_{1r}c \\ a_{21}c & a_{22}c & \cdots & a_{2r}c \\ \vdots & \vdots & \ddots & \vdots \\ a_{k1}c & a_{k2}c & \cdots & a_{kr}c \end{bmatrix}$$

- Inner product of two $k \times 1$ vectors

$$a^T \cdot b = a_1 \cdot b_1 + a_2 \cdot b_2 + \dots + a_k \cdot b_k = \sum_{j=1}^k a_j b_j$$

2. MATRIX OPERATORS



PRACTICE: DOT PRODUCT

1. Find dot product $a \cdot b$ for $a = [9 \ 5 \ -4 \ 2]$ and $b = [-3 \ -2 \ 7 \ -1]$.
2. Find dot product $a \cdot b$ for $a = [2 \ -3 \ 4 \ 15 \ -3]$ and $b = [8 \ 8 \ 2 \ -10 \ 0]$.

PRACTICE: DOT PRODUCT

1. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 9 & 5 & -4 & 2 \end{bmatrix}$ and $b = \begin{bmatrix} -3 & -2 & 7 & -1 \end{bmatrix}$.
2. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 2 & -3 & 4 & 15 & -3 \end{bmatrix}$ and $b = \begin{bmatrix} 8 & 8 & 2 & -10 & 0 \end{bmatrix}$.

Answer: [◀ Show Work](#)

$$a \cdot b = -150$$

PRACTICE: DOT PRODUCT

1. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 9 & 5 & -4 & 2 \end{bmatrix}$ and $b = \begin{bmatrix} -3 & -2 & 7 & -1 \end{bmatrix}$
2. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 2 & -3 & 4 & 15 & -3 \end{bmatrix}$ and $b = \begin{bmatrix} 8 & 8 & 2 & -10 & 0 \end{bmatrix}$.
3. Find dot product $a \cdot b$ for $a = \begin{bmatrix} 2x & 2xy & 4z \end{bmatrix}$ and $b = \begin{bmatrix} x & 3y & xz \end{bmatrix}$.

PRACTICE: DOT PRODUCT

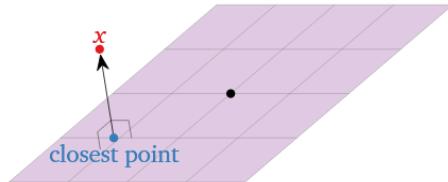
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Answer: [◀ Show Work](#)

$$a \cdot b = 2x^2 + 6xy^2 + 4xz^2$$

2. MATRIX OPERATORS

- Orthogonality: A perpendicular (i.e., right angle) in n dimensions.
- Orthogonal vectors are $a^T \cdot b = 0$

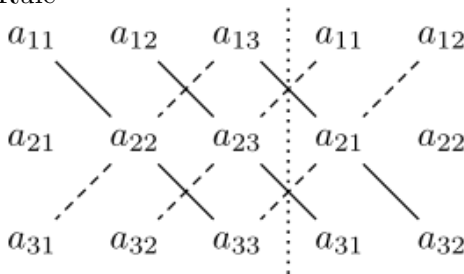


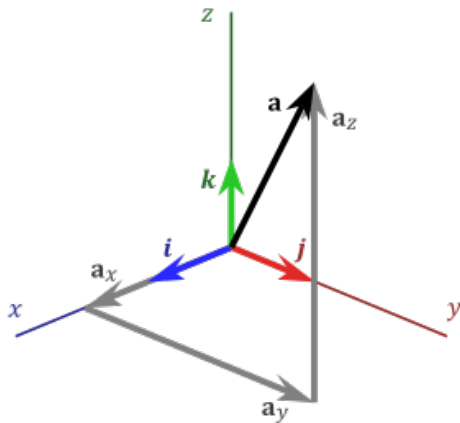
2. MATRIX OPERATORS

- **Cross Product:** Vector product (or outer product) is a new vector perpendicular to both input vectors $a = (a_1 \ a_2 \ a_3)$ and $b = (b_1 \ b_2 \ b_3)$.

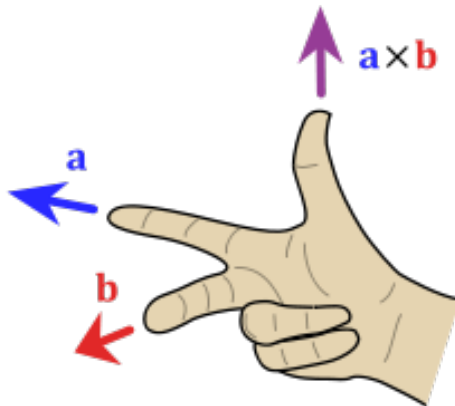
$$\begin{aligned} a \times b &= (a_1\vec{i} + a_2\vec{j} + a_3\vec{k}) \times (b_1\vec{i} + b_2\vec{j} + b_3\vec{k}) \\ &= (a_2b_3 - a_3b_2)\vec{i} + (a_3b_1 - a_1b_3)\vec{j} + (a_1b_2 - a_2b_1)\vec{k} \end{aligned}$$

- Sarrus's Rule





RIGHT HAND RULE



ALTERNATIVES TO THE
RIGHT-HAND RULE IN
VECTOR MULTIPLICATION:

BOOK RULE:

OPEN THE FRONT COVER ALONG
THE FIRST VECTOR AND THE
BACK COVER ALONG THE SECOND.
THE RESULT VECTOR IS ALONG
THE SPINE, OUT THE TOP.

HANDGUN RULE:

POINT THE GRIP ALONG THE FIRST
VECTOR AND ROTATE IT SO THE
SECOND VECTOR IS ON THE SAFETY
LATCH SIDE. FIRE. THE RESULT VECTOR
IS TOWARD THE BULLET HOLES.

BODY RULE (MALES ONLY):

POINT YOUR RIGHT ARM ALONG THE
FIRST VECTOR AND YOUR LEGS ALONG
THE SECOND; THEN WATCH SOME PORN.

PRACTICE: CROSS PRODUCT

1. Find cross product $w \times v$ for $w = \begin{bmatrix} 1 & 6 & -8 \end{bmatrix}$ and $v = \begin{bmatrix} 4 & -2 & -1 \end{bmatrix}$.
2. Find cross product $a \times b$ for $a = \begin{bmatrix} 2 & 1 & -1 \end{bmatrix}$ and $b = \begin{bmatrix} -3 & 4 & 1 \end{bmatrix}$.

PRACTICE: CROSS PRODUCT

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3. Find cross product $a \times b$ for $a = \begin{bmatrix} 3 & -2 & -1 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 5 & 1 & -2 & 3 \end{bmatrix}$.

PRACTICE: CROSS PRODUCT

1. Find cross product $w \times v$ for $w = \begin{bmatrix} 1 & 6 & -8 \end{bmatrix}$ and $v = \begin{bmatrix} 4 & -2 & -1 \end{bmatrix}$.
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3. Find cross product $a \times b$ for $a = \begin{bmatrix} 3 & -2 & -1 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 5 & 1 & -2 & 3 \end{bmatrix}$.

Answer: [◀ Show Work](#)

$$a \times b = 12\vec{i} - 12\vec{j} + 30\vec{k} + 4\vec{l}$$

2. MATRIX OPERATORS

- ▶ Matrix Multiplication is summing the multiplication of the columns and the rows into a new matrix.
- ▶ Conformable: $[k \times r] \times [r \times s] = [k \times s]$
- ▶ Multiplication is not commutative $A \times B \neq B \times A$

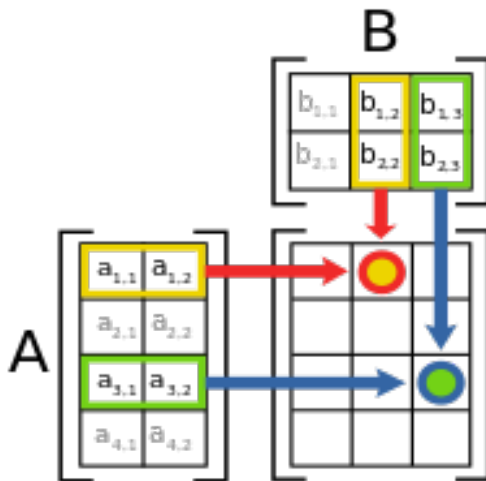
$$A \times B = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_k^T \end{bmatrix} \times \begin{bmatrix} b_1 & b_2 & \cdots & b_s \end{bmatrix} \\ = \begin{bmatrix} a_1^T b_1 & a_1^T b_2 & \cdots & a_1^T b_s \\ a_2^T b_1 & a_2^T b_2 & \cdots & a_2^T b_s \\ \vdots & \vdots & \ddots & \vdots \\ a_k^T b_1 & a_k^T b_2 & \cdots & a_k^T b_s \end{bmatrix}$$

2. MATRIX OPERATORS

- Matrix multiplication: $A_{m \times n} B_{n \times p} = C_{m \times p}$

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}, B = \begin{bmatrix} b_{11} & \cdots & b_{1p} \\ \vdots & \ddots & \vdots \\ b_{n1} & \cdots & b_{np} \end{bmatrix}$$

$$C = \begin{bmatrix} a_{11}b_{11} + \cdots + a_{1n}b_{n1} & \cdots & a_{11}b_{1p} + \cdots + a_{1n}b_{np} \\ \vdots & \ddots & \vdots \\ a_{m1}b_{11} + \cdots + a_{mn}b_{n1} & \cdots & a_{m1}b_{1p} + \cdots + a_{mn}b_{np} \end{bmatrix}$$



PRACTICE: MATRIX MULTIPLICATION

1. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.

PRACTICE: MATRIX MULTIPLICATION

1. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.

Answer: [◀ Show Work](#)

$$AB = \begin{bmatrix} -1 & 6 \\ 4 & 9 \end{bmatrix}$$

PRACTICE: MATRIX MULTIPLICATION

1. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.
2. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.

PRACTICE: MATRIX MULTIPLICATION

1. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.
2. Find AB given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.

Answer: ◀ Show Work

$$|2 \times 2| \times |3 \times 2| = \text{Does not conform}$$

PRACTICE: MATRIX MULTIPLICATION

- Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.
- Find AB given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.
- Find AB given $A = \begin{bmatrix} 3 & -6 & 9 \\ 10 & 1 & 0 \\ -8 & 2 & -2 \end{bmatrix}$ and $B = \begin{bmatrix} 9 & 1 & 7 & -5 \\ 3 & 5 & 0 & 6 \\ 4 & 1 & 2 & 2 \end{bmatrix}$.

PRACTICE: MATRIX MULTIPLICATION

- Find AB given $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 4 \\ -2 & 1 \end{bmatrix}$.
- Find AB given $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 3 & 8 \\ 2 & 9 \\ 1 & 7 \end{bmatrix}$.
- Find AB given $A = \begin{bmatrix} 3 & -6 & 9 \\ 10 & 1 & 0 \\ -8 & 2 & -2 \end{bmatrix}$ and $B = \begin{bmatrix} 9 & 1 & 7 & -5 \\ 3 & 5 & 0 & 6 \\ 4 & 1 & 2 & 2 \end{bmatrix}$.

Answer: [◀ Show Work](#)

$$AB = \begin{bmatrix} 45 & -18 & 39 & -33 \\ 93 & 15 & 70 & -44 \\ -74 & 0 & -60 & 48 \end{bmatrix}$$

2. MATRIX OPERATORS

- Inversion: Solve when matrix is square and non-singular ($\#rows(A) = \#cols(A)$).
- Let $B = A^{-1}$ be the inverse of full-rank $k \times k$ matrix A .
- This satisfies $AB = I_k$.
- Suppose $n \times n$ matrix A is invertible. Then it is non-singular and has a unique solution:

$$Ax=b$$

$$x = A^{-1}b$$

- This is important for determining coefficients in OLS.

3. RANK

- ▶ Rank: Number of non-zero rows in the row echelon form.
- ▶ $\text{rank} = \min(m, n)$
 - ▶ Full Rank: # of rows = # of columns
 - ▶ $\text{rank}A \leq \# \text{rows}(A)$
 - ▶ $\text{rank}A \leq \# \text{cols}(A)$

5. SPECIAL MATRICES

- ▶ Square Matrix: $k = r$
 - ▶ Square matrices are symmetric $A = A^T$
 - ▶ Called a **diagonal** if all off diagonal elements are zero.
 - ▶ Called an **upper diagonal** (or lower) if all elements below (above) the diagonal are zero.
 - ▶ Idempotent: $B^2 = BB = B$
- ▶ Identity Matrix: Diagonal matrix with only 1's as values in diagonal.

$$I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

- ▶ Zero Matrix: A null matrix with only zeros.
 - ▶ E.g., $[0]$, $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

6. THE DETERMINANT

- A matrix A is non-singular iff its determinant is non-zero.

$$\det \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} \\ - a_{13}a_{22}a_{31} - a_{21}a_{12}a_{33} - a_{11}a_{23}a_{32}$$

- $\det A^T = \det A$
- $\det(A \cdot B) = \det A \cdot \det B$
- $\det(A + B) \neq \det A + \det B$

6. THE DETERMINANT

- **Minor of Matrix:** A determinant of a smaller square matrix cut from A by removing one or more rows and columns.

$$\begin{aligned} |A| &= a_{11}|M_{11}| - a_{12}|M_{12}| + a_{13}|M_{13}| \\ &= a_{11} \begin{vmatrix} \cancel{a_{11}} & \cancel{a_{12}} & \cancel{a_{13}} \\ a_{21} & a_{22} & a_{23} \\ \cancel{a_{31}} & \cancel{a_{32}} & \cancel{a_{33}} \end{vmatrix} - a_{12} \begin{vmatrix} \cancel{a_{11}} & \cancel{a_{12}} & \cancel{a_{13}} \\ a_{21} & \cancel{a_{22}} & a_{23} \\ a_{31} & \cancel{a_{32}} & \cancel{a_{33}} \end{vmatrix} + a_{13} \begin{vmatrix} \cancel{a_{11}} & \cancel{a_{12}} & \cancel{a_{13}} \\ a_{21} & a_{22} & \cancel{a_{23}} \\ a_{31} & \cancel{a_{32}} & \cancel{a_{33}} \end{vmatrix} \\ &= a_{11} \cdot \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \cdot \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \cdot \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} \end{aligned}$$

- Adjacent of Matrix: $adjA = (-1)^{i+j} \times \det(\text{minor of } i, j)$.
- A non-singular matrix has the inversion:

$$A^{-1} = \frac{1}{\det A} \cdot adj A$$

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

DEMONSTRATION: DETERMINANT

Question:

$$\det \begin{pmatrix} 7 & 2 & 1 \\ 0 & 3 & -1 \\ -3 & 4 & -2 \end{pmatrix}$$

DEMONSTRATION: DETERMINANT

Question:

$$\det \begin{pmatrix} 7 & 2 & 1 \\ 0 & 3 & -1 \\ -3 & 4 & -2 \end{pmatrix}$$

Answer:

$$\begin{aligned} \det(\cdot) &= 7(-6 - (-4)) - 2(0 - (3)) + 1(0 - (-9)) \\ &= 7(-2) - 2(3) + 1(9) \\ &= -11 \end{aligned}$$

PRACTICE: DETERMINANTS

$$1. \det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$$

PRACTICE: DETERMINANTS

1. $\det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$

Answer: [◀ Show Work](#)

$$\det(\cdot) = -1$$

PRACTICE: DETERMINANTS

1. $\det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$.

2. $\det \begin{pmatrix} 1 & 2 & 4 \\ 2 & 7 & 3 \\ 3 & 1 & -5 \end{pmatrix}$.

Answer: [◀ Show Work](#)

$$\det(\cdot) = -76$$

PRACTICE: DETERMINANTS

1. $\det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$.

2. $\det \begin{pmatrix} 1 & 2 & 4 \\ 2 & 7 & 3 \\ 3 & 1 & -5 \end{pmatrix}$.

3. $\det \begin{pmatrix} 1 & 1 & 2 \\ 2 & 3 & 1 \\ 3 & 4 & -5 \end{pmatrix}$.

PRACTICE: DETERMINANTS

1. $\det \begin{pmatrix} 1 & -1 \\ -2 & 1 \end{pmatrix}$.

2. $\det \begin{pmatrix} 1 & 2 & 4 \\ 2 & 7 & 3 \\ 3 & 1 & -5 \end{pmatrix}$.

3. $\det \begin{pmatrix} 1 & 1 & 2 \\ 2 & 3 & 1 \\ 3 & 4 & -5 \end{pmatrix}$.

Answer: [◀ Show Work](#)

$$\det(\cdot) = -8$$

7. MATRIX DECOMPOSITION

- ▶ A matrix can be decomposed into its eigenvector.
- ▶ Eigenvector is the vector which transforms (e.g., rotates, stretches) another vector by a constant factor.
- ▶ Eigenvectors = c_i .
- ▶ Eigenvalues = λ_i

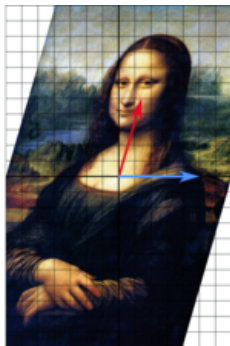
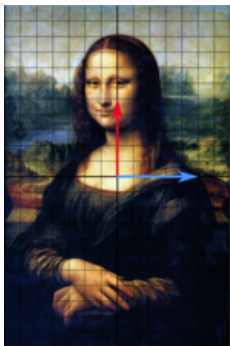
$$C = (c_1 \quad c_2 \quad \cdots \quad c_k)$$

$$\Lambda = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_k \end{pmatrix}$$

$$Ac_k = \lambda_k c_k$$

$$AC = C\Lambda$$

LINEAR TRANSFORMATION

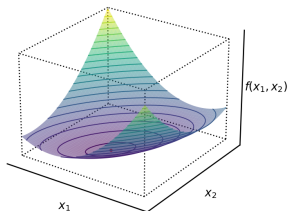


8. POSITIVE AND NEGATIVE DEFINITE MATRICES

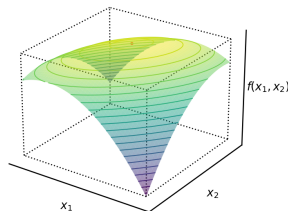
- ▶ Positive Definite: Iff for $k \times k$ real symmetric matrix A ,
 $\forall c \neq 0 \in \mathbb{R}^k$, $c^T A c > 0$.
- ▶ Negative Definite: Iff for $k \times k$ real symmetric matrix A ,
 $\forall c \neq 0 \in \mathbb{R}^k$, $c^T A c < 0$.
- ▶ Semi-definite: A weak inequality \geq, \leq in either case.
- ▶ Negative Semi-definite: All diagonal elements must be ≤ 0 .

8. POSITIVE AND NEGATIVE DEFINITE MATRICES

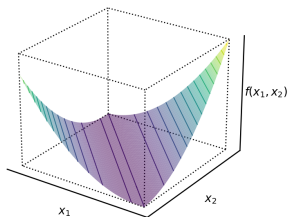
Positive definite



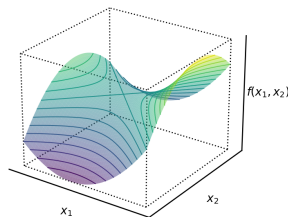
Negative definite



Singular & positive semi-definite



Indefinite



9. LINEAR INDEPENDENCE

- **Homogeneous System:** Guaranteed to have at least one solution $x_i = 0 \forall i$ when $b_i = 0 \forall i$

$$A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = 0$$

- ▶ **Linearly Dependent:** Iff there is a non-zero solution.
 - ▶ Means one of the column vectors a_n can be written as a linear combination of the other vectors.
 - ▶ Implies infinite solutions.
 - ▶ Short Rank ($\#rows(A) < \#cols(A)$) must be linearly dependent.
- ▶ **Linearly Independent:** Iff the only solution is the zero solution.
- ▶ **Singular:** When a square matrix has a non-zero solution.

10. CHAIN RULE FOR VECTORS

- ▶ Let x, y, z be vectors such that z is a function of y , and y is a function of x .
- ▶ We can apply the chain rule noting that with vectors we must chain the results **from the left**:

$$\frac{\partial z}{\partial x} = \frac{\partial y}{\partial x} \frac{\partial z}{\partial y} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x}$$

REVIEW OF MATRICES

1. Foundations of Matrices
2. Matrix Operators
3. Rank
4. Special Matrices
5. The Determinant
6. Trace
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8. Positive and Negative Definite Matrices
9. Linear Independence
10. Chain Rule for Vectors

DOT PRODUCT QUESTION 2 ANSWER:

◀ QUESTION

$$\begin{aligned}a \cdot b &= 2(8) + (-3)(8) + 4(2) + 15(-10) + (-3)0 \\ &= -150\end{aligned}$$

DOT PRODUCT QUESTION 3 ANSWER:

[◀ QUESTION](#)

$$a \cdot b = 2x^2 + 6xy^2 + 4xz^2$$

CROSS PRODUCT QUESTION 1 ANSWER:

◀ QUESTION

$$\begin{aligned}w \times v &= -6\vec{i} - 32\vec{j} - 2\vec{k} + 1\vec{j} - 16\vec{i} - 24\vec{k} \\ &= -22\vec{i} - 31\vec{j} - 26\vec{k}\end{aligned}$$

CROSS PRODUCT QUESTION 2 ANSWER:

◀ QUESTION

$$\begin{aligned}a \times b &= (1)(1)\vec{i} + (-1)(-3)\vec{j} + 2(1)\vec{k} \\ &\quad - 2(1)\vec{j} - (-1)4\vec{i} - (1)(-3)\vec{k} \\ &= 5\vec{i} + \vec{j} + 11\vec{k}\end{aligned}$$

CROSS PRODUCT QUESTION 3 ANSWER:

◀ QUESTION

$$\begin{aligned}a \times b &= 4\vec{i} - 3\vec{j} + 20\vec{k} + 3\vec{l} \\ &\quad + 10\vec{k} - 9\vec{j} + 8\vec{i} + 1\vec{l} \\ &= 12\vec{i} - 12\vec{j} + 30\vec{k} + 4\vec{l}\end{aligned}$$

MATRIX MULT. QUESTION 1 ANSWER:

◀ QUESTION

$$\begin{aligned} AB &= \begin{bmatrix} 3 - 4 & 4 + 2 \\ 6 - 2 & 8 + 1 \end{bmatrix} \\ &= \begin{bmatrix} -1 & 6 \\ 4 & 9 \end{bmatrix} \end{aligned}$$

MATRIX MULT. QUESTION 2 ANSWER:

◀ QUESTION

$|2 \times 2| \times |3 \times 2| =$ Does not conform

MATRIX MULT. QUESTION 3 ANSWER:

◀ QUESTION

$$\begin{aligned}
 AB &= \begin{bmatrix} 27 - 18 + 36 & 3 - 30 + 9 & 21 + 0 + 18 & -15 - 36 + 18 \\ 90 + 3 + 0 & 10 + 5 + 0 & 70 + 0 + 0 & -50 + 6 + 0 \\ -72 + 6 - 8 & -8 + 10 - 2 & -56 + 0 - 4 & 40 + 12 - 4 \end{bmatrix} \\
 &= \begin{bmatrix} 45 & -18 & 39 & -33 \\ 93 & 15 & 70 & -44 \\ -74 & 0 & -60 & 48 \end{bmatrix}
 \end{aligned}$$

DETERMINANTS QUESTION 1 ANSWER:

[◀ QUESTION](#)

$$\begin{aligned} \det(\cdot) &= 1 - 2 \\ &= -1 \end{aligned}$$

DETERMINANTS QUESTION 2 ANSWER:

◀ QUESTION

$$\begin{aligned} \det(\cdot) &= 1(-35 - 3) - 2(-10 - 9) + 4(2 - 21) \\ &= -76 \end{aligned}$$

DETERMINANTS QUESTION 3 ANSWER:

◀ QUESTION

$$\begin{aligned} \det(\cdot) &= 1(-15 - 4) - 1(-10 - 3) + 2(8 - 9) \\ &= -8 \end{aligned}$$