

# *Lecture 07*

## *Linear Algebra*

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Mathematics Review Course, Summer 2023  
University of Minnesota  
*August 15th, 2023*

# LAST LECTURE REVIEW

- ▶ Matrices:
  - ▶ Matrix Operators
  - ▶ Rank Trace
  - ▶ The Determinant
  - ▶ Positive and Negative Definite Matrices
  - ▶ Linear Independence

# REVIEW ASSIGNMENT

1. Problem Set 06 solutions are available on Github.
2. Any issues or problems **You** would like to discuss?

# DAILY ICEBREAKER

- ▶ Attendance via prompt:
  - ▶ Name
  - ▶ Program and track
  - ▶ Daily icebreaker subject...



# *Topic: Linear Algebra*

# MOTIVATION

- ▶ General background
  - ▶ The algebra of manipulating matrices.
  - ▶ A compact, efficient method for working with systems of equations (e.g., a spreadsheet).
- ▶ Why do economists' care?
  - ▶ These is the foundation of how economists manipulate data.
- ▶ Application in this career
  - ▶ Important applications in econometrics.
  - ▶ Useful whenever you are creating or modifying an estimator.

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# OVERVIEW

1. Systems of Linear Equations
2. Gaussian Elimination
3. Linear Operators
4. Existence of a Solution
5. Cramer's Rule
6. Eigenvalues and the Characteristic Equation
7. Leading Principle Minors
8. Regression as a Matrix
9. Centering Matrix
10. Residual Maker

# 1. SYSTEMS OF LINEAR EQUATIONS

- ▶ Linear Functions:  $y = Ax$  with elements  $y_i$  of  $y$  such that  $y_i = a_i^T x$ .

$$a_i = \frac{\partial y_i}{\partial x} = \frac{\partial}{\partial x}(a_i^T x)$$

- ▶ Linear System:  $m$  equations for  $n$  unknown variables.

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= b_1 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n &= b_m \end{aligned}$$

## 2. GAUSSIAN ELIMINATION

► Augmented Matrix

$$\left( \begin{array}{ccc|c} a_{11} & a_{12} & \cdots & a_{1n}|b_1 \\ a_{21} & a_{22} & \cdots & a_{2n}|b_2 \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn}|b_m \end{array} \right)$$

## 2. GAUSSIAN ELIMINATION

- ▶ Row Echelon Form
  - ▶ Interchange any two rows.
  - ▶ Change row by adding a multiple of another row.
  - ▶ Multiply each element in a row by a non-zero scalar.

$$\begin{pmatrix} 1 & 0 & \cdots & 0 | b_1 \\ 0 & 1 & \cdots & 0 | b_2 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 | b_m \end{pmatrix}$$

### 3. LINEAR OPERATORS

- Product Rule:

$$\frac{\partial a^T b}{\partial x} = \frac{\partial a^T}{\partial x} b + \frac{\partial b^T}{\partial x} a$$

- Quadratic Form:

$$x^T A x = \sum_{i=1}^n \sum_{j=1}^n x_i x_j a_{ij}$$

## 4. EXISTENCE OF SOLUTION

- ▶ Important to know that a solution for a system exists.
- ▶ A system of linear equations with coefficient matrix  $A$  and an augmented matrix  $\hat{A}$  has a solution iff:

$$\text{rank}\hat{A} = \text{rank}A$$

- ▶ There are infinite solutions if  $\#rows(A) < \#cols(A)$ .
  - ▶ More unknown variables than observations.
- ▶ Non-singular Square Matrix: Ensure only one solutions exists iff

$$\#rows(A) = \#cols(A) = \text{rank}(A)$$

## 5. CRAMER'S RULE

- ▶ A unique solution  $x = (x_1, \dots, x_n)$  for  $n \times n$  system  $Ax = b$  is

$$x_i = \frac{\det B_i}{\det A} \forall i = 1, \dots, n$$

- ▶ Where  $B_i$  replaces the  $i$ 'th column of  $A$  with the  $b$  vector.

## 6. EIGENVALUES AND THE CHARACTERISTIC EQUATION

- ▶ Characteristic Equation

$$Ac = \lambda c$$

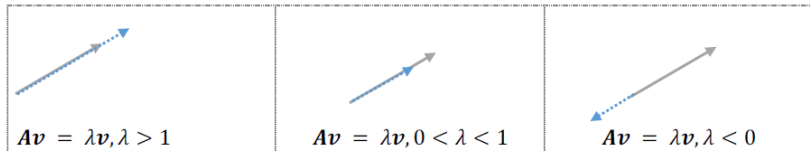
- ▶ Characteristic vectors:  $(c, \lambda)$
- ▶ Eigenvectors:  $c$
- ▶ Eigenvalues:  $\lambda$

$$Ac = \lambda Ic \iff (A - \lambda I)c = 0$$

- ▶ Homogeneous system has non-zero solution if it is singular and has zero determinant:  $\det(A - \lambda I) = 0$



# EIGENVECTORS SCALED BY EIGENVALUES



## 7. LEADING PRINCIPLE MINORS

- ▶ A way to test for matrix definiteness.
- ▶ Leading Principal Sub-matrix: Let  $A$  be a  $N \times N$  matrix. The  $K$ 'th order principal sub-matrix of  $A$  obtained by deleting the last  $N - K$  rows and the last  $N - K$  columns.
- ▶ Leading Principal Minor: The determinant of the  $K$ 'th order leading principal sub-matrix.
- ▶ Ex., for a  $3 \times 3$  matrix, the leading principal minors are:

$$|a_{11}|, \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}, \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

## 7. LEADING PRINCIPLE MINORS

- ▶ Positive Definite: Iff all  $N$  leading principal minors are  $\geq 0$ .
- ▶ Negative Definite: Iff the  $N$  leading principal minors alternate signs

$$\det(A_1) < 0, \det(A_2) > 0, \det(A_3) < 0, \text{ etc.}$$

- ▶ Indefinite: Leading principal minors follow any other order.

## 8. REGRESSION AS A MATRIX

- ▶ A linear OLS model:

$$Y_{N \times 1} = X_{N \times K} \beta_{K \times 1} + e_{N \times 1}$$

- ▶ With the goal of selecting  $\hat{\beta}$  that minimizes squared predicted errors.

$$\hat{e}^T \hat{e} = (Y - X\hat{\beta})^T (Y - X\hat{\beta})$$

## 8. REGRESSION AS A MATRIX

- So, taking the first derivative we can get:

$$\begin{aligned} X^T X \hat{\beta} - X^T Y &= 0 \\ \implies \\ -X^T (Y - X \hat{\beta}) &= -X^T \hat{e} = 0 \end{aligned}$$

- And the solution to OLS is:

$$\hat{\beta} = (X^T X)^{-1} X^T Y$$

## 9. CENTERING MATRIX

- ▶ It is common in statistics to transform data to be ‘deviations from the mean’.
- ▶ This can be done by creating the “centering matrix”.
- ▶ First, create a multiplier  $\frac{1}{N}ii^T$ .

$$\frac{1}{N}ii^T = \frac{1}{N} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix} (1 \quad 1 \quad \cdots \quad 1) = \begin{pmatrix} \frac{1}{N} & \frac{1}{N} & \cdots & \frac{1}{N} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{1}{N} & \frac{1}{N} & \cdots & \frac{1}{N} \end{pmatrix}$$

- ▶ Then define vectors of means.

$$i\bar{x} = \frac{1}{N}ii^T x = \begin{pmatrix} \frac{1}{N} & \frac{1}{N} & \cdots & \frac{1}{N} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{1}{N} & \frac{1}{N} & \cdots & \frac{1}{N} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} = \begin{pmatrix} \bar{x} \\ \bar{x} \\ \vdots \\ \bar{x} \end{pmatrix}$$

## 9. CENTERING MATRIX

- The vector of derivatives can be expressed as:

$$x - i\bar{x} = \begin{pmatrix} x_1 - \bar{x} \\ x_2 - \bar{x} \\ \vdots \\ x_N - \bar{x} \end{pmatrix} = x - \frac{1}{N}ii^Tx = (I - \frac{1}{N}ii^T)x = M^0x$$

- Summing these derivatives can be written as follows:

$$\sum_{i=1}^N (x_i - \bar{x})^2 = (x - i\bar{x})^T (x - i\bar{x}) = (M^0x)^T (M^0x) = x^T M^{0T} M^0 x$$

# 10. RESIDUAL MAKER

- Define

$$M = I - X(X^T X)^{-1} X^T$$

- Then

$$\hat{e} = Y - X\hat{\beta} = (I - X(X^T X)^{-1} X^T)Y = MY$$

- Residual Maker:  $M$



# PRACTICE: LINEAR ALGEBRA

1.

# REVIEW OF LINEAR ALGEBRA

1. Systems of Linear Equations
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# ASSIGNMENT

- ▶ Readings on Functions before Lecture 08:
  - ▶
- ▶ Assignment:
  - ▶ Problem Set 07 (PS07)
  - ▶ Solution set will be available following end of Lecture 08
- ▶ Struggling?
  1. Read the ‘Encouraged Reading’
  2. Review ‘Supplementary material’
  3. Reach out directly