

Day 8 Notes

Wednesday, August 18, 2021 9:04 AM

Math tricks

sum of geometric series

$$\sum_{i=0}^{\infty} r^i \quad \text{where } |r| < 1$$

$$1 + r + r^2 + r^3 + \dots$$

$$\text{Sum} = \frac{1}{1-r}$$

$$S_0 = \sum_{i=0}^{\infty} r^i = 1 + r + r^2 + \dots$$

$$S_1 = \sum_{i=1}^{\infty} r^i = r + r^2 + r^3 + \dots$$

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Two facts 1) $S_0 = S_1 + 1$

2) $S_1 = rS_0$

$$S_0 - S_1 = 1$$

$$\overline{r} \downarrow S_0$$

$$\Rightarrow S_0(1-r) = 1$$

$$\Rightarrow S_0 = \frac{1}{1-r}$$

Systems

$$AX = b$$

Solve for X .

A : coefficient matrix

or a linear transformation

→ a function mapping

X to b . It must

satisfy:

$$f: X \rightarrow Y$$

where $f(\alpha x + \beta z)$

$$= \alpha f(x) + \beta f(z)$$

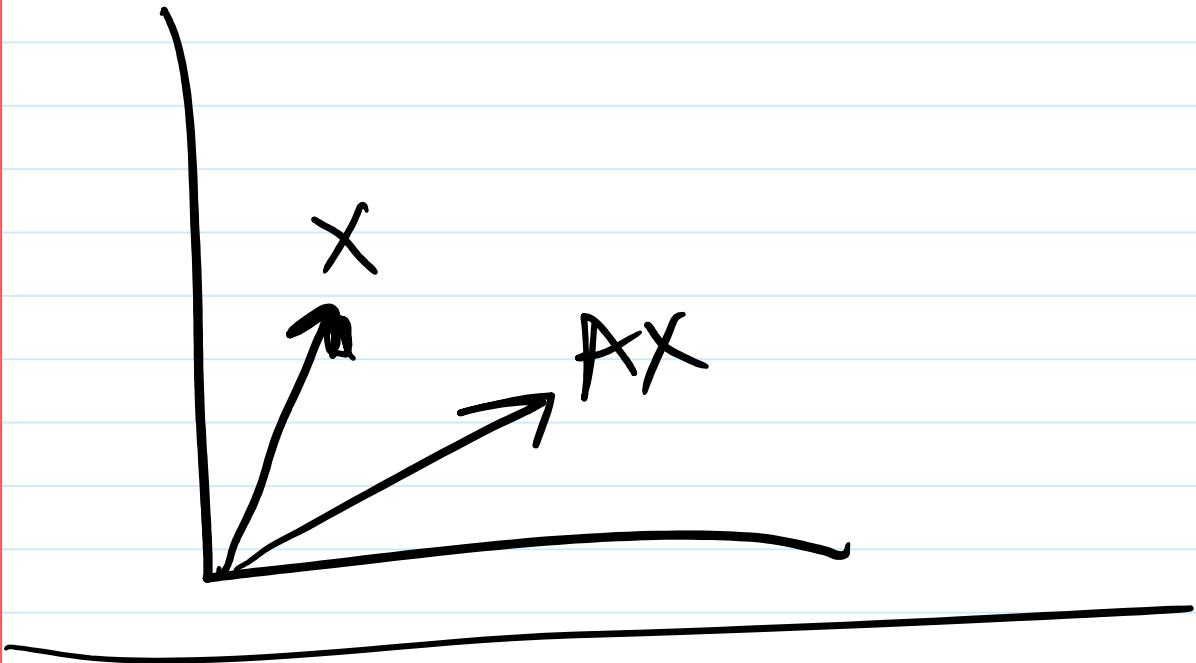
If A is square then

it is called a linear operator and it maps a space into itself,
e.g. $A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$A x = b$$

$$3 \times 3 \quad 3 \times 1 \quad 3 \times 1$$

$$x \in \mathbb{R}^3 \rightarrow b \in \mathbb{R}^3$$



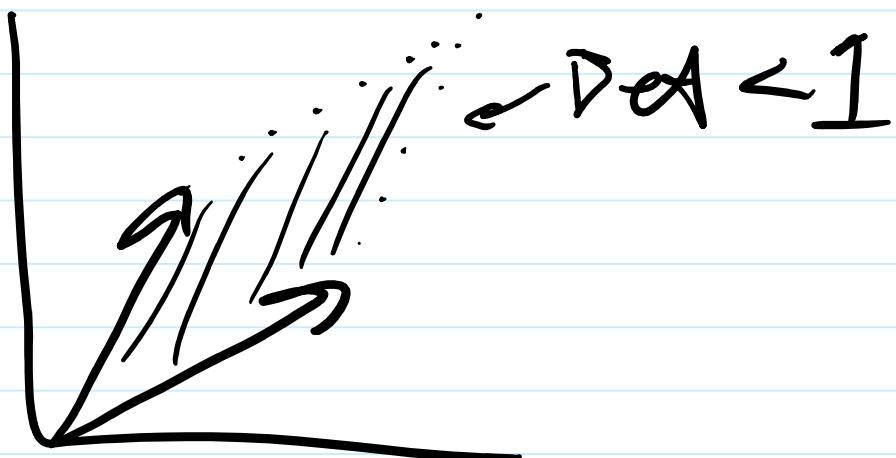
Correlation matrix

$$R = \begin{bmatrix} 1 & \rho_{12} & \rho_{13} & \rho_{14} \\ \rho_{12} & 1 & & \\ \rho_{13} & & 1 & \\ \rho_{14} & & & 1 \end{bmatrix}$$

If all vars are uncorrelated
 then $\text{Det}(R) = 1$. In
 that case $R = I$.
 otherwise $|R| < 1$.

$\uparrow \rightarrow$ uncorrelated = orthogonal

Det is a unit cube



Then $|R| = 0$.

The corr matrix is singular,
so R^{-1} DNE.

$$\underline{\underline{(X'X)}}$$

$X'X$ is a rescaling
of correlation
matrix

$\frac{X'X}{n}$ is the sample covariance
($\because X$ is in deviations
from means)

Determinant of an $n \times n$ matrix
is $HDC(n)$.

$$\text{So } \text{Det}(\alpha A) = \alpha^n \text{Det}(A)$$

which comes from:

$$\text{Det } B = \alpha \text{Det } A \quad \text{if } B$$

is just A with one
column or row multiplied
by α .

by α .

Systems

$$Ax = b$$

Gaussian elimination

$$\left[\begin{matrix} A & : & b \\ \vdots & & \vdots \end{matrix} \right]$$

Perform elementary row operations until A is in row echelon form.

Row-echelon form

$$\left[\begin{array}{cccc|c} 1 & 2 & 3 & 4 & 5 \\ 0 & 2 & 6 & 6 & 8 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \quad \text{pivots}$$

Reduced R-E form

- 1) Pivots are 1
- 2) all other entries in a pivot column are 0

$$\left[\begin{array}{ccccc} 1 & 0 & 3 & 0 & 5 \\ 0 & 1 & 6 & 0 & 8 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

zeros
pivots = 1

A

B

C

D

E

A — Red. REF.

B — REF

C — REF

D — Red. REF

E — REF

Gauss-Jordan

$[A : b]$

Step 3: STOP

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 1 \end{array} \right]$$



No solution

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 5 \end{array} \right]$$

- 1) $a_1x + b_1y + c_1z = d_1$
- 2) $a_2x + b_2y + c_2z = d_2$
- 3) $a_3x + b_3y + c_3z = d_3$

$$1 \cdot z = 5$$

$$\text{so } z = 5$$

$$y = 4$$

$$x = 3$$

Mult (1) by 5

$$5a_1x + 5b_1y - 5c_1z = 5d_1$$

Add (1) & (2)

$$\begin{aligned} a_1x + a_2x + b_1y + b_2y + c_1z + c_2z \\ \hline = d_1 + d_2 \end{aligned}$$

Ex | solve:

$$4y + z = 2$$

$$2x + 6y - 2z = 3$$

$$4x + 8y - 5z = 4$$

$$\left[\begin{array}{ccc|c} A & & & b \\ 0 & 4 & 1 & 2 \\ 2 & 6 & -2 & 3 \\ 4 & 8 & -5 & 4 \end{array} \right]$$

$$R_1 \leftrightarrow R_2 \left[\begin{array}{ccc|c} 2 & 6 & -2 & 3 \\ 0 & 4 & 1 & 2 \\ 4 & 8 & -5 & 4 \end{array} \right]$$

$$-2 \cdot R_1 + R_3 \left[\begin{array}{ccc|c} 2 & 6 & -2 & 3 \\ 0 & 4 & 1 & 2 \\ 0 & -4 & -1 & -2 \end{array} \right]$$

$$1 \cdot R_2 + R_3 \left[\begin{array}{ccc|c} 2 & 6 & -2 & 3 \\ 0 & 4 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Row echelon form

$$\frac{-3}{2}R_2 + R_1 \left[\begin{array}{ccc|c} 2 & 0 & -3.5 & 0 \\ 0 & 4 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\left[\begin{matrix} 0 & 0 & 0 & : & 0 \end{matrix} \right]$$

$\frac{1}{2}R_1$

$$\left[\begin{matrix} 1 & 0 & -\frac{1}{4} & : & 0 \\ 0 & 4 & 1 & : & 2 \\ 0 & 0 & 0 & : & 0 \end{matrix} \right]$$

$\frac{1}{4}R_2$

$$\left[\begin{matrix} 1 & 0 & -\frac{1}{4} & : & 0 \\ 0 & 1 & \frac{1}{4} & : & \frac{1}{2} \\ 0 & 0 & 0 & : & 0 \end{matrix} \right]$$

Reduced REF.

$$x - \frac{1}{4}z = 0$$

$$y + \frac{1}{4}z = \frac{1}{2}$$

$$x = \frac{1}{4}z$$

$$y = \frac{1}{2} - \frac{1}{4}z$$

choose z .

→ infinitely many solutions.

Cramer's Rule

Let $AX=b$ be a system
of n equations in n
unknowns. Then

$$x_i = \frac{\det A^i}{\det A}$$

A^i has the i th column of
 A replaced by b .

\hat{x} replaced by v .

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 3 & 3 \end{pmatrix} \quad b = \begin{pmatrix} 9 \\ 9 \\ 9 \end{pmatrix}$$

$$A' = \begin{pmatrix} 9 & 2 & 3 \\ 9 & 1 & 0 \\ 9 & 3 & 3 \end{pmatrix}$$

$$A'' = \begin{pmatrix} 1 & 9 & 3 \\ 0 & 9 & 0 \\ 0 & 9 & 3 \end{pmatrix}$$

$$x' = \det \begin{pmatrix} 9 & 2 & 3 \\ 9 & 1 & 0 \\ 9 & 3 & 3 \end{pmatrix}$$

$$\det \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 3 & 3 \end{pmatrix}$$

$$\begin{array}{c} \diagup \quad \diagdown \\ \text{Cramer's Rule} \end{array} \quad \left| \begin{array}{c} \dots \\ 1033 \end{array} \right.$$

Ex]

$$A = \begin{pmatrix} 7 & -2 \\ 3 & 1 \end{pmatrix} \quad b = \begin{pmatrix} 3 \\ 5 \end{pmatrix}$$

$$A' = \begin{pmatrix} 3 & -2 \\ 5 & 1 \end{pmatrix} \quad A^2 = \begin{pmatrix} 7 & 3 \\ 3 & 5 \end{pmatrix}$$

$$\begin{aligned} \det A &= 7 \cdot 1 - (-2) \cdot 3 \\ &= 7 + 6 = 13 \end{aligned}$$

$$\begin{aligned} \det A' &= 3 \cdot 1 - (-2) \cdot 5 \\ &= 13 \end{aligned}$$

$$\begin{aligned} \det A^2 &= 7 \cdot 5 - 3 \cdot 3 \\ &= 26 \end{aligned}$$

$$= 26$$

$$X_1 = \frac{\det A^1}{\det A} = \frac{13}{13} = 1$$

$$X_2 = \frac{\det A^2}{\det A} = \frac{26}{13} = 2$$

check:

$$7 \cdot 1 - 2 \cdot 2 = 3 \quad \checkmark$$

$$3 \cdot 1 + 2 = 5 \quad \checkmark$$

Homogeneous systems

$Ax = 0$ the set of all solutions \mathbb{R}
called the nullspace

Trivial solution: $x = 0$.

If $Ax=0$ has only the trivial solution, the columns of A are called linearly independent. Otherwise if $\text{nullsp}(A) \neq \{0\}$, the columns are linearly dependent. Then at least column β is a linear combo. of the others.

$$c_1v_1 + c_2v_2 + \dots + c_nv_n = 0$$

Suppose not all v_1, \dots, v_n are zero.

Then $c_1v_1 + c_2v_2 + \dots + c_{n-1}v_{n-1}$

$$= -c_n v_n$$

$$\Rightarrow v_n = \underbrace{-\frac{c_1}{c_n} v_1 - \frac{c_2}{c_n} v_2 - \dots}_{-\frac{c_{n-1}}{c_n} v_{n-1}}$$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ lin ind.

$$0x_1 + 1x_2 = b_1$$

$$1x_1 + 0x_2 = b_2$$

homogeneous:

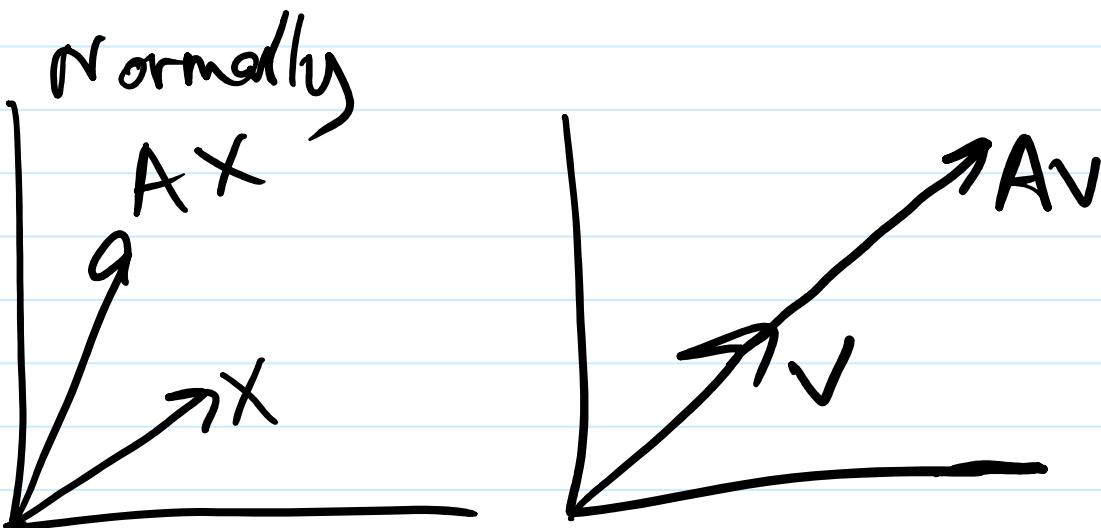
$$\left. \begin{array}{l} x_2 = 0 \\ x_1 = 0 \end{array} \right\} \text{only trivial solution}$$

Eigenvalues and Eigenvectors

Let A be $n \times n$.

Then $\lambda \in \mathbb{C}$ is an eigenvalue of A if $\exists v \neq 0$ such that $Av = \lambda v$

And v is called an eigenvector corresponding to λ .



$$AX = \lambda X$$

$$\Leftrightarrow AX = \lambda I X$$

$$\iff Ax - \lambda Ix = 0$$

$$\iff (A - \lambda I)x = 0$$

This has nontrivial solutions

If $(A - \lambda I)$ is singular.

$$\text{So } \text{Det}(A - \lambda I) = 0$$

That leads to the
characteristic equation

$\text{Det}(A - \lambda I) = 0$. We
want to solve it for λ .

Ex $2x_1 + 3x_2 = \lambda x_1$

$$4x_1 + 3x_2 = \lambda x_2$$

$$\text{or } \begin{pmatrix} 2 & 3 \\ 4 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

char equation:

$$\det \begin{pmatrix} 2-\lambda & 3 \\ 4 & 3-\lambda \end{pmatrix} = 0$$

$$(2-\lambda)(3-\lambda) - 3 \cdot 4 = 0$$

$$6 - 2\lambda - 3\lambda + \lambda^2 - 12 = 0$$

$$\boxed{\lambda^2 - 5\lambda - 6 = 0}$$

quadratic equation

The 2 solutions are
the eigenvalues of A.

In general the char. eq'n

In general the char. eqn will be an n^{th} order polynomial in λ , and will have n roots.

The roots can be repeated, or 0, or complex.

$$\lambda = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\begin{aligned}a &= 1 \\b &= -5 \\c &= -6\end{aligned}$$

$$\lambda_1 = \frac{5 + \sqrt{25 + 24}}{2}$$

$$= \frac{5 + \sqrt{49}}{2}$$

$$= \frac{5+7}{2} = 6$$

$$\lambda_2 = \frac{5 - \sqrt{49}}{2}$$

$$= \frac{5-7}{2} = -1$$

Eigenvectors

$$\lambda = 6$$

$$\begin{pmatrix} 2-6 & 3 \\ 4 & 3-6 \end{pmatrix} x = 0$$

$$-4x_1 + x_2 = 0$$

$$4x_1 - 3x_2 = 0$$

$$\left(\begin{array}{cc|c} -4 & 3 & 0 \\ 4 & -3 & 0 \end{array} \right)$$

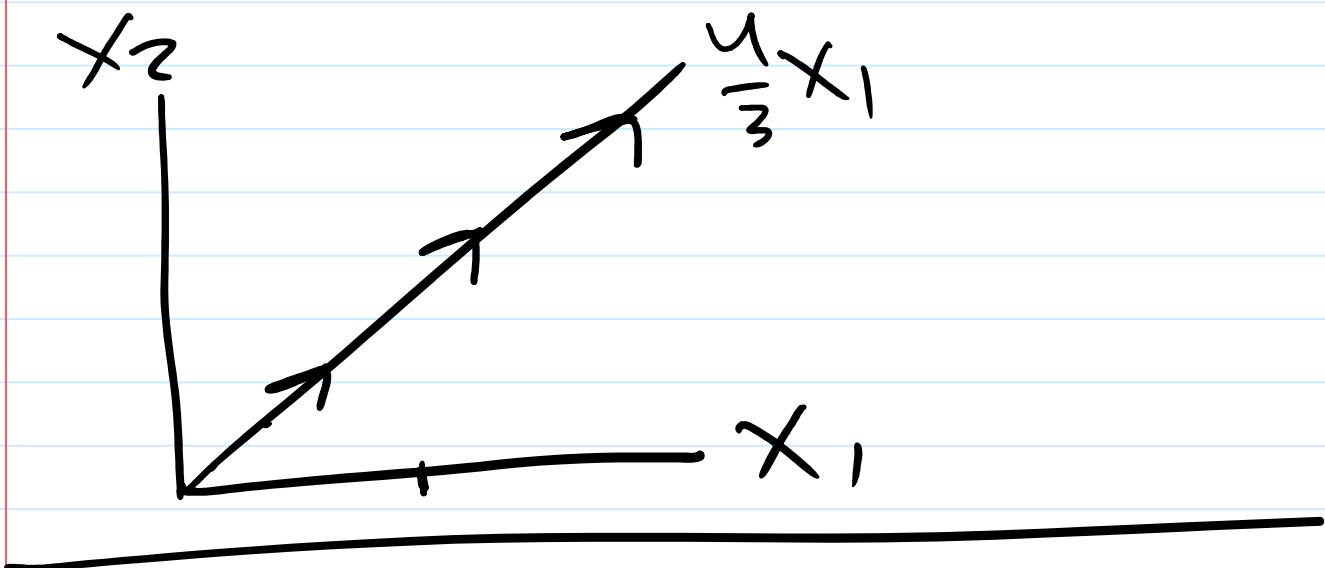
$$\underbrace{R_1 + R_2}_{\sim} \left(\begin{array}{cc|c} -4 & 3 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$-4x_1 + 3x_2 = 0$$

$$3x_2 = 4x_1$$

$$x_2 = \frac{4}{3}x_1$$

any $\begin{pmatrix} x_1 \\ \frac{4}{3}x_1 \end{pmatrix}$ will be a solution
for $\lambda=6$.



Eigenvalue decomposition
or "spectral decomposition"

A square matrix is called
"diagonalizable" if there

"diagonalizable" $\Leftrightarrow \exists$ a
invertible matrix C and
a diagonal matrix Λ such
that $\Lambda = C^{-1}AC$.

$$\Rightarrow C\Lambda C^{-1} = A$$

The columns of C are
the eigenvectors (scaled
to have length 1) and
the diagonal elements
of Λ are corresponding
eigenvalues.

$$AC = C\Lambda$$

$$\begin{bmatrix} Ac_1 & Ac_2 & \cdots & Ac_n \end{bmatrix} = \begin{bmatrix} \lambda_1 c_1 & \lambda_2 c_2 & \cdots & \lambda_n c_n \end{bmatrix}$$

This says:

$$Ac_1 = \lambda c_1 \quad \leftarrow \text{def'n of eigenvalues/vectors}$$

$$Ac_2 = \lambda c_2$$

$$Ac_3 = \lambda c_3$$

:

A matrix is diagonalizable iff its eigen vectors are linearly independent.

Positive and negative definite matrices

^{symmetric}
A matrix is positive definite

A , matrix \Rightarrow positive definite
if $\forall x \neq 0, x^T A x > 0$.

If A is positive definite:

- all eigenvalues are positive.

- \exists a matrix W such that
 $A = W^T W$. W is $m \times n$.
(necessary and sufficient)

If A pos def then $A = W^T W$
for some W .

If we have a matrix $X^T X$,
then it is positive semidef.
and positive definite if
the columns of X are

The columns of X are linearly independent.

Let A be pos. def. Then

$$A = W'W \text{ so}$$

$$\begin{aligned} X'AX &= X'W'WX \\ &= (WX)'WX \end{aligned}$$

= a sum of squares

$$= (WX)_1^2 + (WX)_2^2 + (WX)_3^2 + \dots$$

$$> 0$$

Vector Spaces

Scalar mult : \odot

Vector addition: \oplus

$w, u, v \in S, a, b \in F$ (e.g. \mathbb{R})

1) $a \odot u \oplus b \odot v \in S$

2) $u \oplus v = v \oplus u$

3) $u \oplus (v \oplus w) = (u \oplus v) \oplus w$

4) $\exists 0 \in S$ s.t. $u \oplus 0 = u$

$\forall u \in S$

5) $\forall u \in S, \exists -u$ s.t. $u \oplus -u = 0$

6) $(ab) \odot u = a \odot (b \odot u)$

7) $(a+b) \odot u = (a \odot u) \oplus (b \odot u)$

8) $a \odot (u \oplus v) = (a \odot u) \oplus (a \odot v)$

9) $\exists u = u \ \forall u \in S$

Examples: \mathbb{R}^n is a vector space where

\odot is just multiplying a vector by a constant and

\oplus is just adding vectors.

The set of $m \times n$ matrices is a vector space.

The set of random variables is a vector space.

The set of continuous fns on a closed interval.

$f(x) = 0 \rightsquigarrow$ the zero vector.

$$-f = -1 \cdot f$$

