

tesseract\_environment  
::Command



```
graph BT; A[tesseract_environment::ChangeCollisionMarginsCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom represents the base class, `tesseract_environment::ChangeCollisionMarginsCommand`. A dark gray box at the top represents the derived class, `tesseract_environment::Command`. A blue arrow points from the base class box to the derived class box, indicating that `ChangeCollisionMarginsCommand` inherits from `Command`.

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