

tesseract_collision
::ConvexDecomposition

```
graph RL; A["tesseract_collision::ConvexDecompositionHACD"] --> C["tesseract_collision::ConvexDecomposition"]; B["tesseract_collision::ConvexDecompositionVHACD"] --> C;
```

The diagram illustrates inheritance or specialization relationships between three C++ namespaces. On the left is a gray-shaded box representing the base namespace: `tesseract_collision::ConvexDecomposition`. On the right are two white boxes representing derived namespaces: `tesseract_collision::ConvexDecompositionHACD` (top) and `tesseract_collision::ConvexDecompositionVHACD` (bottom). Blue arrows point from each of the right-hand boxes to the left-hand box, indicating that both derived namespaces inherit from or specialize the base namespace.

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::ConvexDecompositionHACD

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::ConvexDecompositionVHACD