

tesseract_collision
/bullet/include/tesseract
_collision/bullet/tesseract
_gjk_pair_detector.h

```
graph BT; A["tesseract_collision  
/bullet/src/tesseract  
_convex_convex_algorithm.cpp"] --> C["tesseract_collision  
/bullet/include/tesseract  
_collision/bullet/tesseract  
_gjk_pair_detector.h"]; B["tesseract_collision  
/bullet/src/tesseract  
_gjk_pair_detector.cpp"] --> C;
```

The diagram illustrates a file dependency structure. At the top is a header file box (shaded gray) containing the path `tesseract_collision/bullet/include/tesseract_collision/bullet/tesseract_gjk_pair_detector.h`. Below it are two source file boxes (white). The left box contains `tesseract_collision/bullet/src/tesseract_convex_convex_algorithm.cpp` and the right box contains `tesseract_collision/bullet/src/tesseract_gjk_pair_detector.cpp`. Blue arrows point from each source file box up to the header file box, indicating that both source files include this header.

tesseract_collision
/bullet/src/tesseract
_convex_convex_algorithm.cpp

tesseract_collision
/bullet/src/tesseract
_gjk_pair_detector.cpp