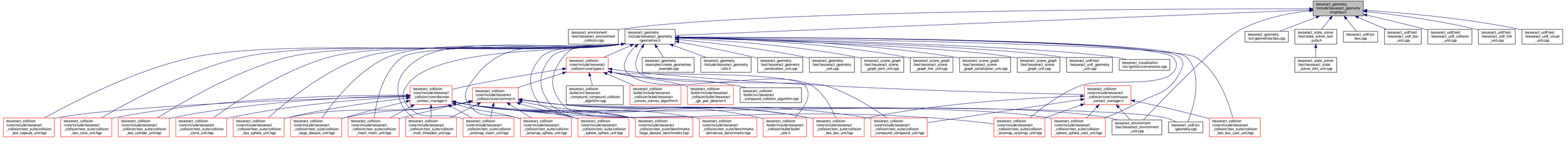
tesseract_geometry /include/tesseract_geometry /impl/bvh.h
tesseract_geometry /src/geometries/box.cpp
tesseract_state_solver /test/tesseract_state_solver_test suite.h
tesseract_state_solver /test/tesseract_state_solver_ofkt_unit.cpp
tesseract_urdf/src /box.cpp
tesseract_urdf/test /tesseract_urdf_box _unit.cpp
tesseract_urdf/test /tesseract_urdf_collision _unit.cpp
tesseract_urdf/test /tesseract_urdf_link _unit.cpp
tesseract_urdf/test /tesseract_urdf_visual _unit.cpp
tesseract_environment /test/tesseract_environment _collision.cpp
tesseract_geometry /include/tesseract_geometry /geometries.h
tesseract_geometry /examples/create_geometries _example.cpp
tesseract_geometry /include/tesseract_geometry /utils.h
tesseract_geometry /test/tesseract_geometry _serialization_unit.cpp
tesseract_geometry /test/tesseract_geometry _unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_joint_unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_link_unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_serialization_unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_unit.cpp
tesseract_urdf/test /tesseract_urdf_geometry _unit.cpp
tesseract_visualization /src/ignition/conversions.cpp
tesseract_collision /core/include/tesseract _collision/core/types.h
tesseract_collision /core/include/tesseract _collision/core/discrete _contact_manager.h
tesseract_collision /core/include/tesseract _collision/core/common.h
tesseract_collision /bullet/src/tesseract _compound_compound_collision _algorithm.cpp
tesseract_collision /bullet/include/tesseract _collision/bullet/tesseract _convex_convex_algorithm.h
tesseract_collision /bullet/include/tesseract _collision/bullet/tesseract _gjk_pair_detector.h
tesseract_collision /bullet/src/tesseract _compound_collision_algorithm.cpp
tesseract_collision /core/include/tesseract _collision/core/continuous _contact_manager.h
tesseract_collision /core/include/tesseract _collision/test_suite/collision _box_capsule_unit.hpp
tesseract_collision /core/include/tesseract _collision/test_suite/collision _box_cone_unit.hpp
tesseract_collision /core/include/tesseract _collision/test_suite/collision _box_cylinder_unit.hpp
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tesseract_environment /test/tesseract_environment _unit.cpp
tesseract_urdf/src /geometry.cpp
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