

tesseract_environment
::Command



```
graph BT; A[tesseract_environment::ChangeCollisionMarginsCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates an inheritance relationship. A blue arrow points from the bottom box to the top box. The top box is white with a black border and contains the text 'tesseract_environment' and '::Command'. The bottom box is gray with a black border and contains the text 'tesseract_environment' and '::ChangeCollisionMarginsCommand'.

tesseract_environment
::ChangeCollisionMarginsCommand