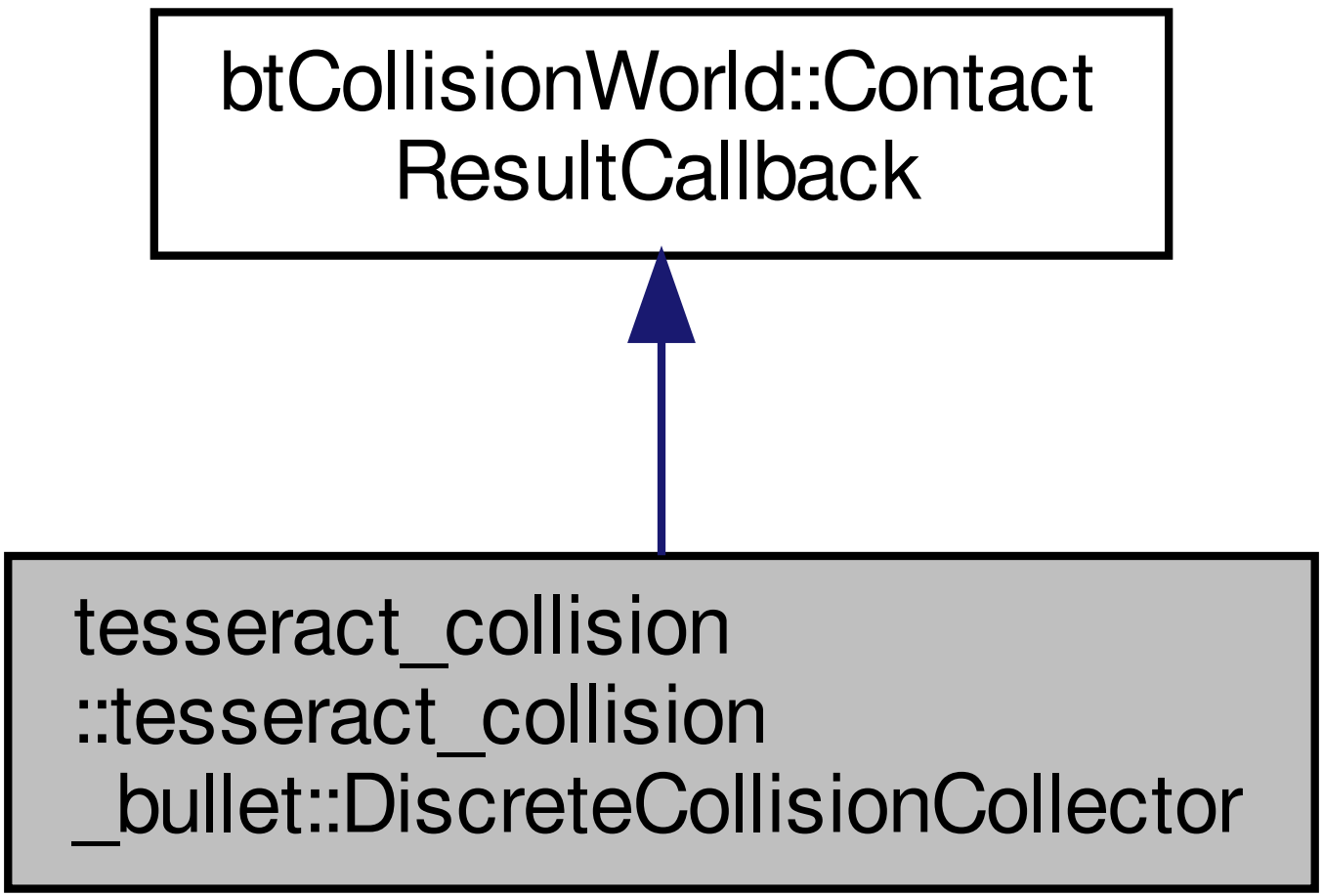
btCollisionWorld::Contact
ResultCallback
tesseract_collision
::tesseract_collision
_bullet::DiscreteCollisionCollector