

tesseract_environment
::Command



```
graph BT; A[tesseract_environment::AddAllowedCollisionCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates a class hierarchy. At the bottom is a gray-shaded box containing the text 'tesseract_environment::AddAllowedCollisionCommand'. A blue arrow points vertically upwards from this box to a white box above it. The white box contains the text 'tesseract_environment::Command'.

tesseract_environment
::AddAllowedCollisionCommand