## CSCI203 Algorithms and Data Structures

#### Graphs - Articulation Points

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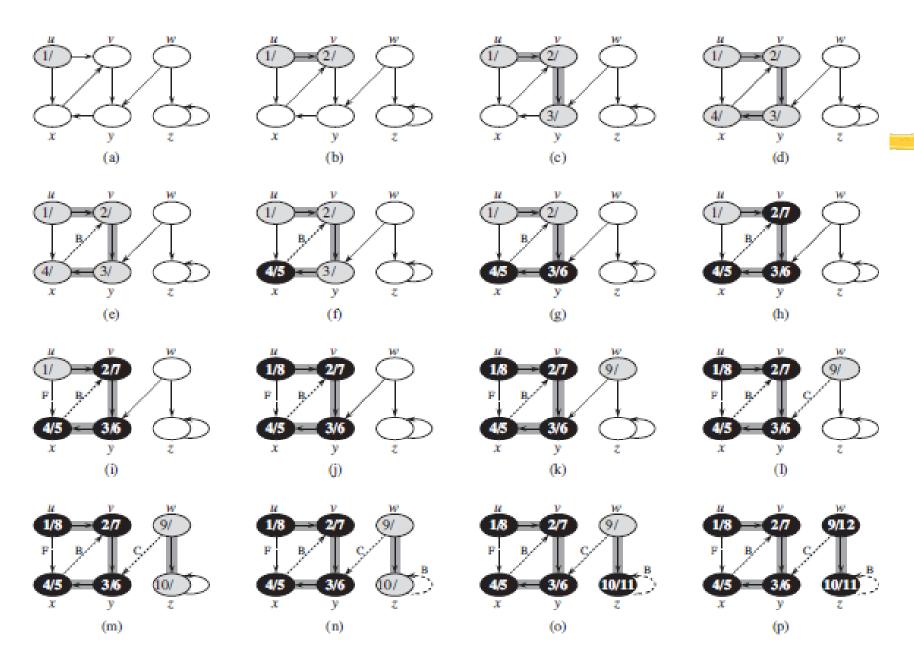
### Recall - DFS\_ALL(G)

Uses a global timestamp time.

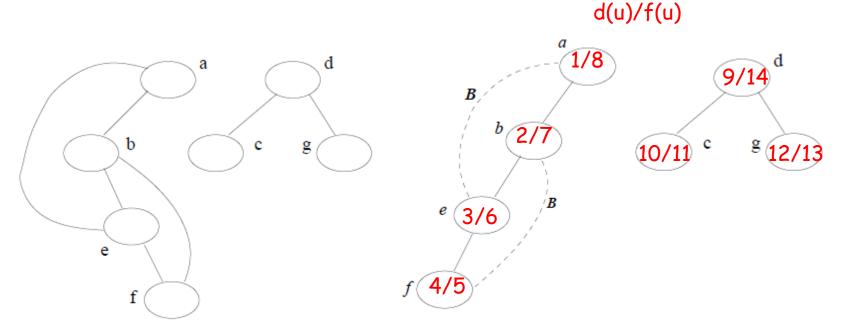
```
DFS ALL(G)
    for each u ∈ V
        do color[u] ← WHITE
time ← 0
for each u ∈ V
        do if color[u] = WHITE then DFS-VISIT(u)
DFS-VISIT (G, u)
color[u] ← GRAY // discover u
time ← time+1
d[u] ← time
for each v \in Adj[u] // explore (u, v)
    do if color[v] = WHITE then DFS-VISIT(v)
color[u] ← BLACK //
time ← time+1
                         //finish u
f[u] ← time
```

## Edge Classification

- If we perform a DFS on a graph we can classify the edges of a graph:
  - Tree edges: these form part of the search tree (or forest);
  - Forward edges: these lead from a vertex to a descendant;
  - Backward edges: these lead from a vertex to an ancestor;
  - Cross edges: these are all the edges that are left—they connect unrelated vertices.
- Vertex v is descendant of vertex u in depth first search iff v is discovered during the time which u is gray



• Given a graph G = (V, E), it traverses all vertices of G and constructs a forest (a collection of rooted trees), together with a set of source vertices (the roots).



## $DSF\_ALL(G)$ - a Simple Version

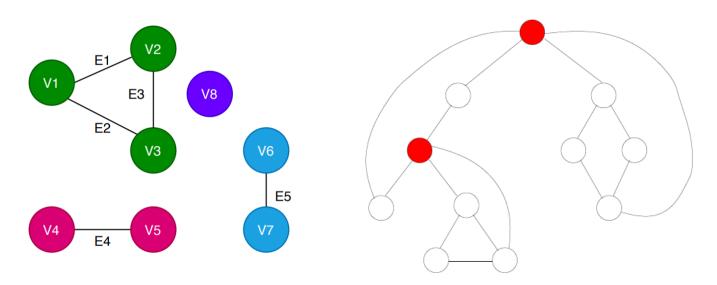
```
DFS{G} {
                                                d[u] - the discovery time,
   for each v in V do // Initialize
                                                a counter indicating when
        visit[v] = false;
                                                vertex u is discovered.
        p[v] = NULL;
                                             • p[u] - the predecessor of
        time=0;
                                                u, which discovered u.
   for each v in V do
        if (visit[v] == false) RDFS(v);
                                                        d(u)
RDFS(v) {
   visit[v]=true;
   d[v] = ++time;
   for each w in Adj(v) do {
        if (visit[w] == false) {
                                                          6
           p[w]=v;
           RDFS(w);
                                           3
                                                    p = [\phi, 1, 2, 3, \phi, 5, 5]
```

#### Edge Classification - Undirected Graphs

- For an undirected graph, it can only has tree edges or back edges.
- Tree edges
  - which are the edges  $\{p[v], v\}$  where DFS calls are made.
- Back edges
  - which are the edges  $\{u, v\}$  where v is an ancestor of u in the DFS tree.

## Connected Components in a Graph

- A connected component is a maximal connected subgraph of an undirected graph. Each vertex belongs to exactly one connected component, as does each edge.
- A graph is connected if and only if it has exactly one connected component.

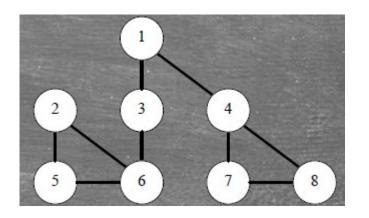


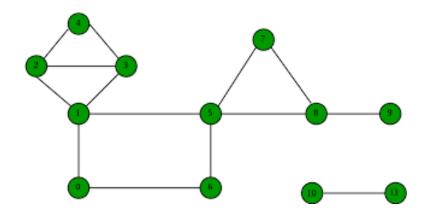
#### Articulation Points

- A vertex, v, in an undirected connected graph is an articulation point (or cut vertex) if removing it (and edges through it) disconnects the graph.
- Articulation points represent vulnerabilities in a connected network - single points whose failure would split the network into 2 or more disconnected components.
- They are useful for designing reliable networks.
- For a disconnected undirected graph, an articulation point is a vertex removing which increases number of connected components.

#### Articulation Points

Which vertices are articulation points?





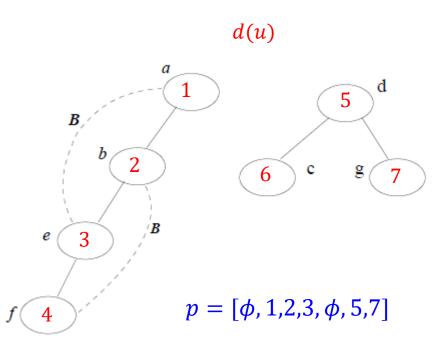
How can we find articulation points in a systematic manner?

## A Naive Approach

- A simple approach is to one by one remove all vertices and see if removal of a vertex causes disconnected graph. Following are steps of simple approach for connected graph.
- For every vertex v, do following
  - Remove v from graph.
  - See if the graph remains connected (We can either use BFS or DFS)
  - Add v back to the graph.
- ▶ Time complexity O(V \* (V + E))
- Can we do better?

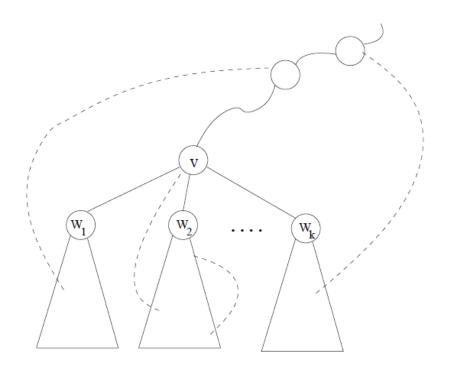
#### Observations

- The root of the DFS tree is an articulation if it has two or more children.
- 2. Any other internal vertex v in the DFS tree, if it has a subtree rooted at a child of v that does NOT have an edge which climbs 'higher' than v, then v is an articulation point.



## How to climb up

For an undirected graph, it can only has tree edges or back edges. A subtree can only climb to the upper part of the tree by a back edge, and a vertex can only climb up to its ancestor.



#### Observation 2

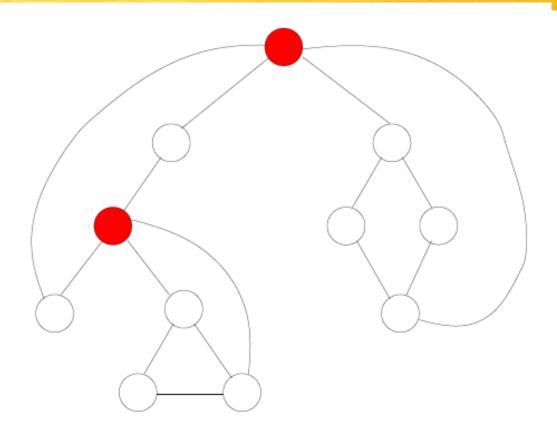
- We make use of the discovery time in the DFS tree to define 'low' and 'high'. Observe that if we follow a path from an ancestor (high) to a descendant (low), the discovery time is in increasing order.
- If there is a subtree rooted at a children of v which does not have a back edge connecting to a SMALLER discovery time than discover[v], then v is an articulation point.
- How do we know a subtree has a back edge climbing to an upper part of the tree?

#### Observation 2...

Define Low(v) be the smallest value of a subtree rooted at v to which it can climb up by a back edge.

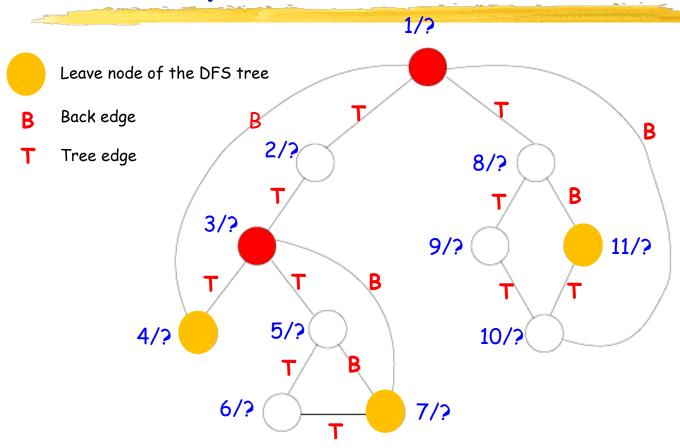
- $Low(v) = \\ \min\{discover(v); \ discover(w): (u, w) \ \text{is a back} \\ \text{edge for some descendant } u \ \text{of } v\}$
- w is a descendant of v
- u a descendant of w

d(v)/Low(v)



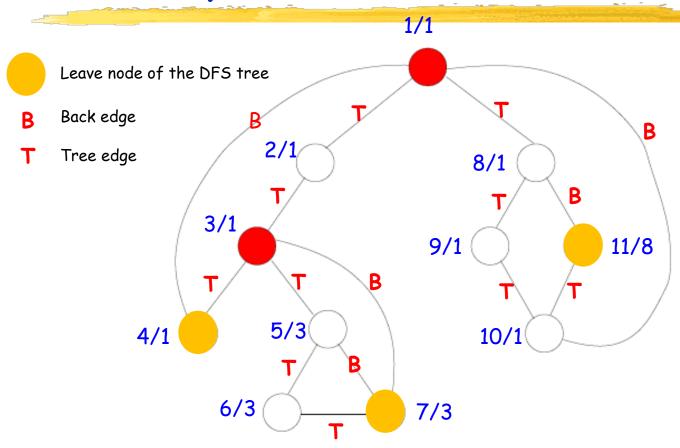
 $Low(v) = min\{discover(v); discover(w) : (u, w) \text{ is a back edge for some descendant } u \text{ of } v\}$ 

d(u)/Low(u)



 $Low[v] = min\{discover[v]; discover[w] : (u; w) \text{ is a back edge for some descendant } u \text{ of } v\}$ 

d(v)/Low(v)



 $Low(v) = min\{discover(v); discover(w): (u, w) \text{ is a back edge for some descendant } u \text{ of } v\}$ 

## Compute Low(v)

```
RDFS Compute Low(v) {
   visit[v]=true;
   Low[v]=discover[v] = ++time;
   for each w in Adj(v) do
       if (visit[w] == false) {
          p[w]=v;
          RDFS Compute Low(w);
          // When RDFS Compute Low(w) returns,
          // Low[w] stores the
          // lowest value it can climb up
          // for a subtree rooted at w.
          Low[v] = min(Low[v], Low[w]);
       \} else if (w != p[v]) {
          // {v, w} is a back edge
          Low[v] = min(Low[v], discover[w]);
```

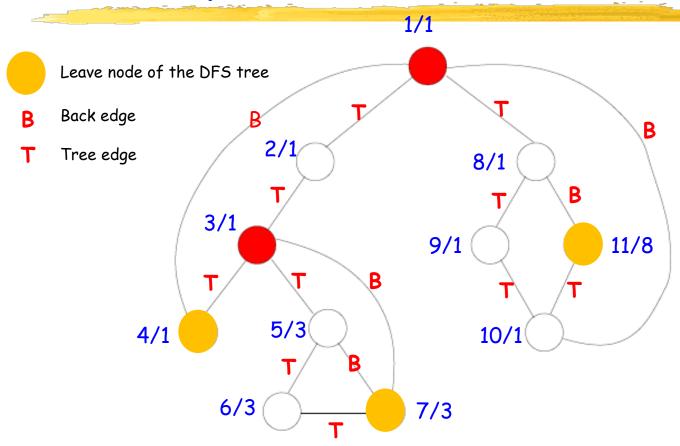
#### Articulation Points

- Conduct a depth first traversal of G, producing the spanning tree T with discovery[v] and Low[v] for each node v
- Consider each node v of the graph:
  - The root of the DFS tree, T, is an articulation point if it has two or more children.
  - If v has no children in T, it is not an articulation point;
  - Any other internal (non-leaf) vertex v in the DFS tree is an articulation point if v has a non-leave child w such that  $Low[w] \ge discover[v]$ .

#### Articulation Points...

```
// search for the DFS tree T
ArticulationPoints {
   for each v in V do {
        articulation point(v) = false;
        if (p[v] == NULL) \{ //v \text{ is a root }
           if (|Adj(v)|>1)
                articulation_point(v) = true;
           } else{
                for each w in Adj(v) and w is not a leaf in T do {
                   if (Low[w] >= discover[v])
                        articulation point(v)=true;
```

d(v)/Low(v)

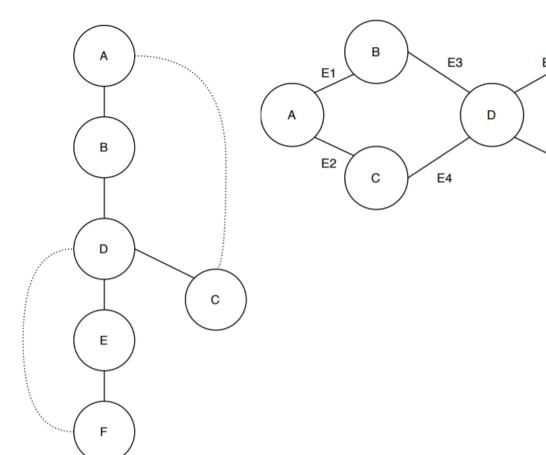


 $Low(v) = min\{discover(v); discover(w): (u, w) \text{ is a back edge for some descendant } u \text{ of } v\}$ 

We will run the algorithm to find out the articulation

points:

First, we convert the graph to a DFS tree (take Verte) A as the root).



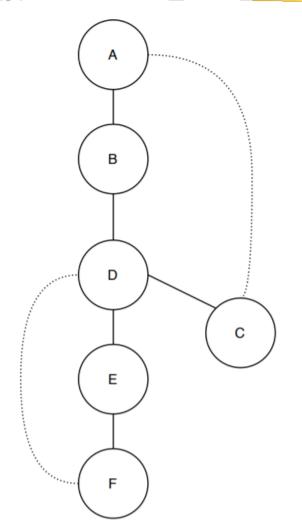
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# Second, we calculate the lowest discovery number of each vertex

Vertex	Depth Number	Lowest Discovery Number
A	1	1
В	2	1
С	6	1
D	3	1
Е	4	3
F	5	3



Third, find the articulation points. Let's start with a random pair of vertices (E, F) where E is the parent of F. Checking condition: low[F] >= depth[E]? but 3 < 4, so E is not an articulation point.

Now let's take another pair (D, E) where D is the parent of E. Checking condition: low[E] >= depth[D]? and 3=3= Checking condition D is not a leaf, so D is an articulation point. c

В			
D C C			
pth Number	Lowest Discovery Number		
1	1		
2	1		
6	1		
3	1		
4	3		
5	3		

В

D Е

## Why?

- The identification of articulation points is important in determining the critical components of networks.
- A component which corresponds to an articulation point is critical.
- If such a component fails, the network is compromised.