

Covariate Adjustment in Stratified Experiments

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Abstract

This paper studies covariate adjusted estimation of the average treatment effect in stratified experiments. We work in a general framework that includes matched tuples designs, coarse stratification, and complete randomization as special cases. Regression adjustment with treatment-covariate interactions is known to weakly improve efficiency for completely randomized designs. By contrast, we show that for stratified designs such regression estimators are generically inefficient, potentially even increasing estimator variance relative to the unadjusted benchmark. Motivated by this result, we derive the asymptotically optimal linear covariate adjustment for a given stratification. We construct several feasible estimators that implement this efficient adjustment in large samples. In the special case of matched pairs, for example, the regression including treatment, covariates, and pair fixed effects is asymptotically optimal. Conceptually, we show an equivalence between efficient linear adjustment of a stratified design and doubly-robust semiparametric adjustment of an independent design. We also provide novel asymptotically exact inference methods that allow researchers to report smaller confidence intervals, fully reflecting the efficiency gains from both stratification and adjustment. Simulations and an application to the Oregon Health Insurance Experiment data demonstrate the value of our proposed methods.

Keywords: Matched Pairs, Analysis of Covariance, Blocking, Robust Standard Error, Treatment Effects

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1 Introduction

This paper studies covariate adjusted estimation of the average treatment effect (ATE) in stratified experiments. Researchers often make use of both stratified treatment assignment and ex-post covariate adjustment to improve the precision of experimental estimates. Indeed, an influential paper by [Lin \(2013\)](#) showed in a design based setting that the regression estimator with full treatment-covariate interactions is always asymptotically weakly more efficient than difference of means estimation for completely randomized designs. [Negi and Wooldridge \(2021\)](#) extended these results to estimation of the ATE using data sampled from a super-population. However, questions remain about the interaction between stratification and regression adjustment and the implications of combining these methods for both estimator efficiency and the power and validity of inference methods. To study these questions, we work in the stratified randomization framework of [Cytrynbaum \(2022\)](#), which includes matched tuples designs (e.g. matched pairs), coarse stratification, and complete randomization as special cases.

We show that the [Lin \(2013\)](#) interacted regression adjustment is generically inefficient in the family of linearly adjusted estimators, with asymptotic efficiency only in the limiting case of complete randomization. Motivated by this finding, we characterize the efficient linear covariate adjustment for a given stratified design, providing several new estimators that achieve the optimal variance.

Our first result derives the optimal linear adjustment coefficient for a given stratification. We show that asymptotically the interacted regression estimator uses the wrong objective function, minimizing a marginal variance objective that is totally insensitive to the stratification. By contrast, the optimal adjustment coefficient minimizes a *mean-conditional* variance objective, conditional on the covariates used to stratify. Intuitively, the efficient covariate adjustment is tailored to the stratification, ignoring fluctuations of the estimator that are predictable by the stratification covariates. Section 3.2 draws an interesting connection with semiparametric regression, showing that efficient linear adjustment of a stratified design is asymptotically equivalent to doubly-robust semiparametric adjustment of an i.i.d. design. Intuitively, stratification contributes the nonparametric component of the semiparametric adjustment function.

Our second set of results provides feasible versions of the oracle linear adjustment derived in Section 3.1. First, we give a simple result showing that if the conditional expectation of the adjustment covariates is linear in a known set of transformations of the stratification variables, then adding the latter to the interacted regression restores optimality. Next we relax this assumption, providing four different regression estimators

that are asymptotically efficient under weak conditions. For matched pairs experiments or in settings with limited treatment effect heterogeneity, the non-interacted regression with a full set of pair fixed effects is asymptotically efficient. More generally, we show asymptotic optimality of within-stratum (inconsistently) partialled versions of the Lin and tyranny-of-the-minority estimators (Lin (2013)). We also define a “group OLS” estimator, extending a proposal of Imbens and Rubin (2015) for matched pairs experiments to a larger class of designs. We show that this estimator is also asymptotically optimal.

Our final contribution is to develop novel asymptotically exact inference methods for covariate adjusted estimation under stratified designs. Confidence intervals based on the usual heteroskedasticity robust variance estimator are known to be conservative in stratified experiments (Bai et al. (2021)). By contrast, the coverage probabilities of our proposed confidence intervals converge to the specified nominal level, without no over-coverage. Our approach applies to a generic family of linear covariate adjustments and randomization schemes, including as special cases non-interacted regression adjustment, the Lin (2013) interacted regression, and all of the other estimators considered in this paper. Simulations and an empirical application to the Oregon Health Insurance Experiment suggest that the usual Eicker-Huber-White confidence intervals can substantially overcover in stratified experiments, while our confidence intervals have close to nominal coverage.

There has been significant interest in treatment effect estimation under different experimental designs in the recent literature. Some papers studying covariate adjustment under stratified randomization include Bugni et al. (2018), Fogarty (2018), Liu and Yang (2020), Lu and Liu (2022), Ma et al. (2020), Reluga et al. (2022), Wang et al. (2021), Ye et al. (2022), Zhu et al. (2022), and Chang (2023). These works differ from our paper in at least one of the following ways: (1) studying inference on the sample average treatment effect (SATE) rather than the ATE in a super-population, (2) restricting to coarse stratification (stratum size going to infinity), or (3) proving weak efficiency gains but not optimality. In a finite population setting, Zhu et al. (2022) shows asymptotic efficiency of a projection-based estimator similar but not equivalent to the “partialled Lin” approach considered in Section 3.4.2. In the same setting, Lu and Liu (2022) prove efficiency of a tyranny-of-the-minority style regression similar to one the considered in Section 3.4.4. Both papers give conservative inference on the SATE, while we provide asymptotically exact inference on the ATE using a generalized pairs-of-pairs (Abadie and Imbens (2008)) style approach. See the remarks in Section 3.4 below for a more detailed comparison.

Relative to the above papers, the super-population framework considered here creates some new technical challenges. For example, as pointed out in Bai et al. (2021), match-

ing units into data-dependent strata post-sampling produces a complicated dependence structure between the treatment assignments and random covariates. We deal with this using a tight-matching condition (Equation 2.1) and martingale CLT analysis similar to Cytrynbaum (2022). This setting also has analytical advantages, which allow us to establish new conceptual results. For example, the population level characterization of the optimal adjustment coefficient in Section 3.1 allows us to give explicit necessary and sufficient conditions for the efficiency of several commonly used regression estimators. The efficiency of interacted regression under a “rich covariates” condition, as well as the equivalence between optimal linear adjustment of stratified designs and doubly-robust semiparametric adjustment appear to be new observations in this literature. To the best of our knowledge, we give the first asymptotically exact inference on the ATE for general covariate adjusted estimators under finely stratified randomization.

The rest of the paper is organized as follows. In Section 2 we define notation and introduce the family of stratified designs that we will consider throughout the paper. Section 3 gives our main results, characterizing optimal covariate adjustment and constructing efficient estimators. Section 4 provides asymptotically exact inference on the ATE for generic linearly adjusted estimators. In Sections 5 and 6, we study the finite sample properties of our method, including both simulations and an empirical application to the Oregon Health Insurance Experiment data (Finkelstein et al. (2012)). Section 7 concludes with some recommendations for practitioners.

2 Framework and Stratified Designs

For a binary treatment $d \in \{0, 1\}$, let $Y_i(1)$, $Y_i(0)$ denote the treated and control potential outcomes, respectively. For treatment assignment D_i , let $Y_i = Y_i(D_i) = D_i Y_i(1) + (1 - D_i) Y_i(0)$ be the observed outcome. Let X_i denote covariates. Consider data $(X_i, Y_i(1), Y_i(0))_{i=1}^n$ sampled i.i.d. from a super-population of interest. We are interested in estimating the average treatment effect in this population, $ATE = E[Y(1) - Y(0)]$. After sampling units $i = 1, \dots, n$, treatments $D_{1:n}$ are assigned by stratified randomization. In particular, we use the “local randomization” framework introduced in Cytrynbaum (2022).

Definition 2.1 (Local Randomization). Let treatment proportions $p = a/k$ with $\gcd(a, k) = 1$. Partition the experimental units into disjoint groups $g \subset [n]$ with $[n] = \bigsqcup_g \{i \in g\}$ and $|g| = k$, with n divisible by k for notational simplicity. Let $\psi(X) \in \mathbb{R}^{d_\psi}$ denote a vector of stratification variables. Suppose that the groups that satisfy a homogeneity condition

with respect to $\psi(X)$ such that

$$\frac{1}{n} \sum_g \sum_{\substack{i,j \in g \\ i < j}} |\psi(X_i) - \psi(X_j)|_2^2 = o_p(1). \quad (2.1)$$

Independently for each $|g| = k$, draw treatment variables $(D_i)_{i \in g}$ by setting $D_i = 1$ for exactly a out of k units, completely at random. For a stratification satisfying these conditions, we denote $D_{1:n} \sim \text{Loc}(\psi, p)$.

Remark 2.2 (Matched Tuples). Equation 2.1 requires units in a group to have similar $\psi(X_i)$ values and can be thought of as a tight-matching condition. Cytrynbaum (2022) gives a “block path” algorithm to match units into groups that provably satisfy this condition, generalizing and tightening the rates for a construction of Bai et al. (2021) in the case of matched pairs. Drawing treatments $D_{1:n} \sim \text{Loc}(\psi, p)$ produces a “matched k-tuples” design for $p = a/k$. Matched pairs corresponds to the case $p = 1/2$.

Remark 2.3 (Coarse Stratification). At first glance, Definition 2.1 produces n/k groups of units that are tightly matched in $\psi(X)$ space, suggesting fine stratification. In fact, complete randomization and coarse stratification are also included in this framework. For example, for complete randomization with $p = 2/3$, set $\psi_i = 1$ for all i and form groups g at random. This gives a “random matched triples” representation of complete randomization with $p = 2/3$. Similarly, coarse stratification with large fixed strata $S(X) \in \{1, \dots, m\}$ can be obtained by setting $\psi(X) = S(X)$ and matching units with identical $S(X)$ values into groups at random. Because of this, our framework enables a unified asymptotic analysis for a wide range of stratifications.

Experiment Timing: Suppose that the experimenter does the following

- (1) Samples units and observes their baseline covariates.
- (2) Partitions the units into data-dependent groups $g = g(\psi_{1:n})$ that satisfy Equation 2.1 for some stratification variables $\psi(X)$.
- (3) Draws treatment assignments $D_{1:n} \sim \text{Loc}(\psi, p)$, observes outcomes $Y_i(D_i)$, and forms an estimate of the ATE, potentially adjusting for covariates $h(X)$.

We are agnostic about the exact time at which the covariates are observed, subject to the constraints above. For example, it could be that only $\psi(X)$ is observed at the design stage, while the full vector X is collected later with the outcomes, and the experimenter chooses to adjust for $h(X) \subseteq X$. Alternatively, the full vector X could be observed at the design stage, but the experimenter chooses to only stratify on $\psi(X)$, and adjusts for $h(X) \subseteq X$ at step (3). We may or may not have $\psi(X) \subseteq h(X)$.

Consider the unadjusted estimator given by the coefficient $\hat{\theta}$ on D in the regression $Y \sim 1 + D$. Before discussing covariate adjustment, we first state a helpful variance decomposition for $\hat{\theta}$ that will be used extensively below. Let $c(X) = E[Y(1) - Y(0)|X]$ denote the conditional average treatment effect (CATE) and $\sigma_d^2(X) = \text{Var}(Y(d)|X)$ the heteroskedasticity function. Define the *balance function*

$$b(X; p) = E[Y(1)|X] \left(\frac{1-p}{p} \right)^{1/2} + E[Y(0)|X] \left(\frac{p}{1-p} \right)^{1/2}. \quad (2.2)$$

We often denote $b = b(X; p)$ in what follows. [Cytrynbaum \(2022\)](#) shows that if $D_{1:n} \sim \text{Loc}(\psi, p)$ then $\sqrt{n}(\hat{\theta} - \text{ATE}) \Rightarrow \mathcal{N}(0, V)$ with

$$V = \text{Var}(c(X)) + E[\text{Var}(b|\psi)] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right]. \quad (2.3)$$

The variance V is in fact the [Hahn \(1998\)](#) semiparametric variance bound¹ for the ATE (with covariates $\psi(X)$), giving a formal sense in which stratification does nonparametric regression adjustment “by design.” The middle term is the most important for our analysis below. For example, in this notation the difference in asymptotic efficiency between stratifications ψ_1 and ψ_2 (for fixed p) is simply $E[\text{Var}(b|\psi_1)] - E[\text{Var}(b|\psi_2)]$. Note also that $E[\text{Var}(b|\psi)] \leq \text{Var}(b)$ for any ψ , showing how stratification removes the variance due to fluctuations that are predictable by $\psi(X)$.

Moving beyond the difference of means estimator $\hat{\theta}$, suppose that at the analysis stage, the experimenter has access to covariates $h(X)$, which may strictly contain $\psi(X)$. One may try to further improve the efficiency of ATE estimation by regression adjustment using these covariates, either using standard the regression $Y \sim 1 + D + h$ or the regression $Y \sim 1 + D + h + Dh$ (with de-meaned covariates) studied in [Lin \(2013\)](#). We study the interaction between covariate adjustment and stratification in [Section 3.1](#) below, characterizing the optimal linear adjustment.

3 Main Results

3.1 Efficient Linear Adjustment in Stratified Experiments

In this section, we begin by studying the efficiency of commonly used covariate-adjusted estimators of the ATE under stratified randomization. [Lin \(2013\)](#) showed that in a completely randomized experiment, equivalent to $D_{1:n} \sim \text{Loc}(\psi, p)$ with $\psi = 1$, regression adjustment with full treatment-covariate interactions is asymptotically weakly more efficient than difference of means estimation. [Negi and Wooldridge \(2021\)](#) extended this

¹[Armstrong \(2022\)](#) shows that this variance bound also holds for stratified designs.

result to ATE estimation in the super-population framework that we use in this paper. Interestingly, we show that this result is atypical. For a general stratified experiment with $\psi \neq 1$, Lin (2013) style regression adjustment may be strictly inefficient relative to difference of means. The problem is that the interacted regression solves the wrong optimization problem, minimizing a marginal variance objective when, due to the stratification, it should instead minimize a mean-conditional variance objective, conditional on the stratification variables ψ . In fact, the Lin estimator is totally insensitive to the stratification, estimating the same adjustment coefficient for any stratified design $D_{1:n} \sim \text{Loc}(\psi, p)$. Because of this, interacted regression is generically sub-optimal and in some cases can even be strictly less efficient than difference of means.

Assumption 3.1 (Smoothness and Moment Conditions). *Assume the following:*

- (i) *The conditional expectations $E[h(X)|\psi]$ and $E[Y(d)|\psi]$ for $d \in \{0, 1\}$ are Lipschitz continuous in the stratification variables ψ or piecewise Lipschitz if $\dim(\psi) = 1$.*
- (ii) *The moments $E[Y(d)^4] < \infty$, $E[\text{Var}(Y(d)|X)^2] < \infty$ for $d \in \{0, 1\}$. $E[|h_t(X)|^4] < \infty$ for all $1 \leq t \leq \dim(h)$, $|\psi(X)|_2 < K < \infty$ a.s. and $\text{Var}(h) \succ 0$.*

Throughout the paper, we require that outcomes and covariates satisfy a weak smoothness condition with respect to the stratification variables, as well as the moment conditions given above. On a technical note, the piecewise Lipschitz assumption allows us to give a unified analysis, including coarse stratification $S(X) \in \{1, \dots, k\}$. To do this, we can formally extend the discrete functions $E[h_t|S = s]$ and $E[Y(d)|S = s]$ for $s \in \{1, \dots, k\}$ piecewise continuously to $[0, k + 1]$.

Now we are ready to define the Lin estimator and state our first result. Denote $h_i = h(X_i)$ and de-meaned covariates $\tilde{h}_i = h_i - E_n[h_i]$. The Lin estimator $\hat{\theta}_L$ is the coefficient on D_i in the interacted regression $Y_i \sim 1 + D_i + \tilde{h}_i + D_i \tilde{h}_i$. Define the within treatment arm covariate means $\bar{h}_1 = E_n[h_i D_i] / E_n[D_i]$ and $\bar{h}_0 = E_n[h_i (1 - D_i)] / E_n[1 - D_i]$. The Lin estimator $\hat{\theta}_L$ can be related to the difference of means estimator $\hat{\theta}$ as $\hat{\theta}_L = \hat{\theta} - \hat{\gamma}'_L (\bar{h}_1 - \bar{h}_0)$. Here, the *adjustment coefficient* $\hat{\gamma}_L$ is $\hat{\gamma}_L = (1 - p)(\hat{a}_1 + \hat{a}_0) + p\hat{a}_0$, where \hat{a}_0 and \hat{a}_1 are the coefficients on \tilde{h}_i and $D_i \tilde{h}_i$ respectively. The following theorem characterizes the asymptotic properties of this estimator under stratified designs.

Theorem 3.2. *Let Assumption 3.1 hold. If $D_{1:n} \sim \text{Loc}(\psi, p)$ then the Lin estimator $\sqrt{n}(\hat{\theta}_L - \text{ATE}) \Rightarrow \mathcal{N}(0, V)$ with*

$$V = \text{Var}(c(X)) + E \left[\text{Var}(b - \gamma'_L h | \psi) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1 - p} \right].$$

The adjustment coefficient $\hat{\gamma}_L \xrightarrow{p} \gamma_L$ with $\gamma_L = \underset{\gamma \in \mathbb{R}^{d_h}}{\text{argmin}} \text{Var}(b - \gamma' h)$.

The variance V differs from the variance of the unadjusted estimator only in the middle term, which changes from $E[\text{Var}(b|\psi)]$ in the unadjusted case to $E[\text{Var}(b - \gamma'_L h|\psi)]$ for the interacted regression. Crucially, the second statement of Theorem 3.2 shows that the adjustment coefficient γ_L attempts to minimize a marginal variance, instead of the mean-conditional variance that shows up in V above. Because of this, the estimator may be inefficient for general stratifications $\psi \neq 1$, since in general

$$\gamma_L = \underset{\gamma \in \mathbb{R}^{d_h}}{\text{argmin}} \text{Var}(b - \gamma' h) \neq \underset{\gamma \in \mathbb{R}^{d_h}}{\text{argmin}} E[\text{Var}(b - \gamma' h|\psi)] \equiv \gamma^*.$$

Observe that the Lin estimator is completely insensitive to the experimental design, estimating the same adjustment coefficient $\gamma_L = \underset{\gamma}{\text{argmin}} \text{Var}(b - \gamma' h)$ for any stratification variables $\psi(X)$. The following example shows that this can lead to strict inefficiency relative to difference of means estimation.

Example 3.3 (Random Assignment to Class Size). Suppose $Y(d)$ are student test scores under random assignment to one of two class sizes $d \in \{0, 1\}$. Let $h(X)$ be parent's wealth and $\psi(X)$ previous year (baseline) test scores. Suppose parent's wealth is predictive of future test scores marginally so that $\text{Cov}(h, Y(d)) > 0$. Then $\text{Cov}(h, b) > 0$ and the Lin coefficient $\gamma_L = \text{Var}(h)^{-1} \text{Cov}(h, b) > 0$. However, if on average parent's wealth has no predictive power for test scores *conditional* on a student's baseline scores (a proxy for ability) then $E[\text{Cov}(h, Y(d)|\psi)] = 0$. In this case, regression adjustment for parent's wealth $h(X)$ in an experiment stratified on the earlier scores $\psi(X)$ will be strictly less efficient than unadjusted estimation since

$$\begin{aligned} V_{lin} - V_{unadj} &= E[\text{Var}(b - \gamma'_L h|\psi)] - E[\text{Var}(b|\psi)] \\ &= -2\gamma_L E[\text{Cov}(h, b|\psi)] + \gamma_L^2 E[\text{Var}(h|\psi)] = \gamma_L^2 E[\text{Var}(h|\psi)] > 0 \end{aligned}$$

An important special case occurs when the design is completely randomized ($\psi = 1$) or if the covariates and stratification variables are independent $h(X) \perp\!\!\!\perp \psi(X)$. In this case, the Lin estimator is weakly more efficient than difference of means since we have

$$E[\text{Var}(b - \gamma'_L h|\psi)] = \text{Var}(b - \gamma'_L h) = \min_{\gamma} \text{Var}(b - \gamma' h) \leq \text{Var}(b).$$

An analogue of Theorem 3.2 also holds for the non-interacted regression estimator $Y_i \sim 1 + D_i + h_i$ under stratified designs $D_{1:n} \sim \text{Loc}(\psi, p)$. The non-interacted estimator is known to be inefficient relative to difference of means even for completely randomized experiments unless $p = 1/2$ or treatment effects are homogeneous. For completeness, we give asymptotic theory and optimality conditions for this estimator under stratified randomization in Section A.1 in the appendix. We noted above that the Lin estimator $\hat{\theta}_L$ can be written in the canonical form $\hat{\theta}_L = \hat{\theta} - \hat{\gamma}'_L (\bar{h}_1 - \bar{h}_0)$. In fact, most commonly used

adjusted estimators can be written in the standard form $\hat{\theta}_{adj} = \hat{\theta} - \hat{\gamma}(\bar{h}_1 - \bar{h}_0)$ for some $\hat{\gamma}$, up to lower order factors. The following theorem describes the asymptotic properties of general covariate-adjusted estimators $\hat{\theta}_{adj}$ of this form. To avoid carrying around factors of p in our variance expressions, in what follows we scale adjusted estimators by the normalization constant $c_p = \sqrt{p(1-p)}$.

Theorem 3.4. *Let Assumption 3.1 hold. Suppose $\hat{\gamma} \xrightarrow{p} \gamma$ and consider the adjusted estimator*

$$\hat{\theta}_{adj} = \hat{\theta} - \hat{\gamma}'(\bar{h}_1 - \bar{h}_0)c_p.$$

If $D_{1:n} \sim \text{Loc}(\psi, p)$ then $\sqrt{n}(\hat{\theta}_{adj} - \text{ATE}) \Rightarrow \mathcal{N}(0, V(\gamma))$ with

$$V(\gamma) = \text{Var}(c(X)) + E \left[\text{Var}(b - \gamma'h|\psi) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right]. \quad (3.1)$$

We define a linearly-adjusted estimator to be asymptotically efficient if it globally minimizes the asymptotic variance $V(\gamma)$ in the previous theorem.

Definition 3.5 (Optimal Linear Adjustment). The estimator $\hat{\theta}_{adj} = \hat{\theta} - \hat{\gamma}'(\bar{h}_1 - \bar{h}_0)c_p$ is *efficient* for the design $D_{1:n} \sim \text{Loc}(\psi, p)$ and covariates $h(X)$ if $\hat{\gamma} \xrightarrow{p} \gamma^*$ for an optimal adjustment coefficient

$$\gamma^* \in \underset{\gamma \in \mathbb{R}^{d_h}}{\text{argmin}} E \left[\text{Var}(b - \gamma'h|\psi) \right].$$

In particular, $V(\gamma^*) = \min_{\gamma \in \mathbb{R}^{d_h}} V(\gamma)$.

Note that efficiency is defined *relative* to a design $D_{1:n} \sim \text{Loc}(\psi, p)$ and covariates $h(X)$. Setting $\gamma = 0$ recovers unadjusted estimation, so any optimal estimator is in particular weakly more efficient than difference of means.

Remark 3.6 (Conditional Variance Minimization). Stratification reduces estimator variance by finely balancing the stratification variables $\psi(X)$ between treatment and control units. More precisely, under the design $D_{1:n} \sim \text{Loc}(\psi, p)$, imbalances in either the covariates $h(X_i)$ or the potential outcomes $Y_i(d)$ that are predictable by $\psi(X)$ do not contribute to first-order asymptotic variance. Because of this, the optimal covariate-adjusted estimator $\hat{\theta} - \gamma^*(\bar{h}_1 - \bar{h}_0)c_p$ ignores such fluctuations, minimizing the *mean-conditional* variance objective $E[\text{Var}(b - \gamma'h|\psi)]$, instead of the marginal variance $\text{Var}(b - \gamma'h)$ targeted by the Lin estimator.

Remark 3.7 (Non-Uniqueness). If $E[\text{Var}(h|\psi)] \succ 0$, then γ^* in Definition 3.5 is given uniquely by a mean-conditional OLS coefficient

$$\gamma^* = E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, b|\psi)].$$

In general, however, γ^* may not be unique. For example, if $h(x) = (z(\psi), w(x))$ with $z(\psi)$ a Lipschitz function of the stratification variables, then the variance objective

$$E[\text{Var}(b - \gamma'_z z - \gamma'_w w | \psi)] = E[\text{Var}(b - \gamma'_w w | \psi)] \quad \forall \gamma_z \in \mathbb{R}^{d_z}.$$

In fact, our analysis shows that the adjustment term $\gamma'_z(\bar{z}_1 - \bar{z}_0) = o_p(n^{-1/2})$ for any coefficient γ_z in this case. Intuitively, since the covariate $z(\psi)$ is already finely balanced by stratifying on $\psi(X)$, ex-post adjustment by $z(\psi)$ cannot improve first-order efficiency. However, there may still be finite sample efficiency gains from such adjustments, if the covariates $z(\psi)$ are not completely balanced by the stratification. Section 3.5 below provides methods to further adjust for covariates that are functions of the stratification variables.

3.2 Equivalence with Semiparametric Regression Adjustment

This section shows that optimal linear adjustment in stratified experiments is asymptotically as efficient as doubly-robust *semiparametric* adjustment in experiments with iid treatments. In particular, we show first-order asymptotic equivalence of the following (design, estimator) pairs

$$(D_{1:n} \sim \text{Loc}(\psi, p), \text{optimal linear}) \iff (D_i \overset{\text{iid}}{\sim} \text{Bernoulli}(p), \text{oracle semiparametric}).$$

To define the latter, let \mathcal{G} be a vector space of functions and suppose $E[Y(d)|\psi], E[h|\psi] \in \mathcal{G}$. For $d = 0, 1$, consider the population semiparametric regression model

$$(g_d, \gamma_d) = \underset{g \in \mathcal{G}, \gamma \in \mathbb{R}^{d_h}}{\text{argmin}} E[(Y(d) - g(\psi) - \gamma' h)^2].$$

Define the oracle semiparametric adjustment function $f_d(x) = g_d(\psi(x)) + \gamma'_d h(x)$ and consider a [Robins and Rotnitzky \(1995\)](#) style augmented inverse propensity weighting (AIPW) estimator

$$\hat{\theta}_{AIPW} = E_n[f_1(X_i) - f_0(X_i)] + E_n \left[\frac{D_i(Y_i - f_1(X_i))}{p} \right] - E_n \left[\frac{(1 - D_i)(Y_i - f_0(X_i))}{1 - p} \right].$$

The next theorem shows that optimal linear adjustment of the design $D_{1:n} \sim \text{Loc}(\psi, p)$ is asymptotically equivalent to oracle semiparametric adjustment, with non-parametric $\psi(X)$ component.

Theorem 3.8. *Let Assumption 3.1 hold and suppose $D_i \overset{\text{iid}}{\sim} \text{Bernoulli}(p)$. Then $\sqrt{n}(\hat{\theta}_{AIPW} -$*

ATE) $\Rightarrow \mathcal{N}(0, V^*)$ with

$$V^* = \text{Var}(c(X)) + \min_{\gamma \in \mathbb{R}^{d_h}} E \left[\text{Var}(b - \gamma' h | \psi) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right].$$

The limiting semiparametric variance V^* is the same as the efficient linearly adjusted variance $V(\gamma^*)$ from Definition 3.5. This shows that optimal linear adjustment of a stratified design is as efficient in large samples as semiparametric adjustment using the model $f_d(x) = g_d(\psi) + \gamma'_d h(x)$. Intuitively, stratification contributes the nonlinear component of the oracle model $f_d(x)$ above, while optimal adjustment contributes the linear component. The proof is given in Section A.2 of the appendix. The next two sections show how to construct linearly-adjusted estimators for the design $D_{1:n} \sim \text{Loc}(\psi, p)$ that achieve the optimal variance V^* .

3.3 Efficiency by Rich Strata Controls

This section provides a “rich covariates” style condition on the relationship between adjustment covariates and stratification variables under which a simple parametric correction of the Lin estimator is fully efficient. The basic idea is to include rich functions $z(\psi)$ of the stratification variables in the adjustment set alongside the additional covariates we would like to adjust for. The main result of this section shows that including these covariates $z(\psi)$ forces the Lin estimator to solve the mean-conditional variance minimization problem of Definition 3.5, restoring asymptotic optimality. An analogous result holds for the non-interacted regression estimator $Y \sim 1 + D + h$ if $p = 1/2$. As a simple application, Example 3.13 shows that the Lin estimator with leave-one-out strata indicators is efficient for coarsely stratified designs.

Consider adjusting for covariates $h(X) = (w(X), z(\psi))$. The main assumption of this section requires that the conditional mean $E[w|\psi]$ is well-approximated by known transformations $z(\psi)$ of the stratification variables.

Assumption 3.9. *There exist $c \in \mathbb{R}^{d_w}$ and $\Lambda \in \mathbb{R}^{d_w \times d_z}$ such that $E[w|\psi] = c + \Lambda z(\psi)$.*

Our next theorem shows that adding such transformations $z(\psi)$ to the adjustment set recovers full efficiency for the Lin estimator.

Theorem 3.10. *Suppose Assumptions 3.1 and 3.9 hold. Fix adjustment set $h(x) = (w(x), z(\psi))$. Then the Lin estimator $\hat{\theta}_L$ is fully efficient for the design $D_{1:n} \sim \text{Loc}(\psi, p)$. In particular, $\sqrt{n}(\hat{\theta}_L - \text{ATE}) \Rightarrow \mathcal{N}(0, V^*)$ with*

$$V^* = \text{Var}(c(X)) + \min_{\gamma \in \mathbb{R}^{d_h}} E \left[\text{Var}(b - \gamma' h | \psi) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right].$$

Moreover, the asymptotic variance has

$$\min_{\gamma \in \mathbb{R}^{d_h}} E[\text{Var}(b - \gamma' h | \psi)] = \min_{\alpha \in \mathbb{R}^{d_w}} E[\text{Var}(b - \alpha' w | \psi)].$$

In practice, Theorem 3.10 suggests including flexible functions $z(\psi)$ of the stratification variables in the adjustment set. The proof is given in Section A.3 of the supplement. The following corollary shows that if $p = 1/2$ (matched pairs) or if treatment effect heterogeneity is limited then the non-interacted regression $Y \sim 1 + D + w + z$ with rich strata controls $z(\psi)$ is also asymptotically efficient. The result is immediate from Theorem 3.10 and the work on non-interacted regression in Appendix A.1.

Corollary 3.11. *Suppose additionally that $p = 1/2$ or $\text{Cov}(Y(1) - Y(0), h) = 0$. Then the coefficient $\hat{\theta}_N$ on D_i in the regression $Y \sim 1 + D + w + z$ is asymptotically efficient.*

Remark 3.12 (Indirect Efficiency Gain). The second statement of the theorem shows that optimal adjustment for $h(X)$ is as efficient as optimal adjustment for the subvector $w(X) \subseteq h(X) = (w(X), z(\psi))$. In this sense, the efficiency improvement due to including $z(\psi)$ is indirect. Indeed, our analysis shows that $\hat{\theta} - \gamma'_z(\bar{z}_1 - \bar{z}_0) = \hat{\theta} + o_p(n^{-1/2})$ for any $\gamma_z \in \mathbb{R}^{d_z}$, so adjustment for $z(\psi)$ alone cannot affect the first-order asymptotic variance. Intuitively, we are just using the inclusion of $z(\psi)$ as a device to “tilt” the coefficient on $w(X)$, forcing the Lin estimator to solve the correct mean-conditional variance optimization problem.

As a corollary of the theorem, the next example shows that for coarsely stratified designs including leave-one-out strata indicators as covariates in the Lin estimator is sufficient for asymptotic efficiency.

Example 3.13 (Coarse Stratification). Consider stratified randomization $D_{1:n} \sim \text{Loc}(S, p)$ with fixed strata $S(x) \in \{1, \dots, m\}$. Let the adjustment covariates be $h(x) = (w(x), z(s))$ with leave-one-out strata indicators $z(S_i) = (\mathbb{1}(S_i = k))_{k=1}^{m-1}$. In this case, Assumption 3.9 is automatically satisfied since we can write $E[w|S] = c + \Lambda z$ with $c = E[w|S = m]$ and $\Lambda_{jk} = (E[w_j|S = k] - E[w_j|S = m])_{jk}$. Then by Theorem 3.10, the Lin estimator $\hat{\theta}_L$ with covariates $h_i = (w_i, z_i)$ is efficient. In particular, we have $\sqrt{n}(\hat{\theta}_L - \text{ATE}) \Rightarrow \mathcal{N}(0, V^*)$ with optimal variance

$$V^* = \text{Var}(c(X)) + \min_{\gamma} E \left[\text{Var}(b - \gamma' w | S) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right].$$

Similarly, by Corollary 3.11 if $p = 1/2$ then including leave-one-out strata fixed effects in the non-interacted regression restores efficiency.

Remark 3.14 (Fine Stratification). Note that the argument in Example 3.13 only applies to coarse stratification, where the strata $S(x) \in \{1, \dots, m\}$ are data-independent and

fixed as $n \rightarrow \infty$. For fine stratification $D_{1:n} \sim \text{Loc}(\psi, p)$ with continuous covariates $\psi(x)$, the strata are data-dependent and number of strata $m = \Omega(n)$, so Theorem 3.22 does not apply. Indeed, for matched pairs the Lin regression in Example 3.13 would have $n + 2\dim(h) > n$ covariates, producing collinearity. This collinearity problem occurs more generally - see Remark 3.19 below for further discussion.

Leaving behind the rich covariates Assumption 3.9, the next section provides new adjusted estimators that are fully efficient for any design in the class $D_{1:n} \sim \text{Loc}(\psi, p)$ under weak conditions.

3.4 Generic Efficient Adjustment

In this section, we study several adjusted estimators that are asymptotically efficient under weak conditions for any stratified design $D_{1:n} \sim \text{Loc}(\psi, p)$. For matched pairs designs, or in settings with limited treatment effect heterogeneity, the non-interacted regression including treatment, covariates, and pair fixed effects is efficient. More generally, we show that the following estimators are efficient under weak assumptions.

- (1) **PL** - A partialled Lin estimator with within-stratum (inconsistently) partialled covariates.
- (2) **GO** - A “Group OLS” estimator, generalizing a proposal of Imbens and Rubin (2015) for matched pairs designs.
- (3) **TM** - A tyranny-of-the-minority (ToM) estimator for stratified designs.

The main new condition we impose in this section is that the adjustment covariates are not collinear, conditionally on the stratification variables. This guarantees that the optimal adjustment coefficient γ^* is unique with $\gamma^* = E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, b|\psi)]$, as discussed in Remark 3.7.

Assumption 3.15. *Conditional variance* $E[\text{Var}(h|\psi)] \succ 0$.

Note that this assumption rules out adjustment for functions $h(\psi)$ of the stratification variables. To see why it is necessary, consider that, for example, in a regression with full strata fixed effects $Y \sim D + h + z^n$, covariates $h_i = h(\psi_i)$ would be asymptotically collinear with the strata fixed effects $z^n = (\mathbf{1}(i \in g))_{g=1}^{n/k}$. More intuitively, the problem is that $h(\psi)$ has too little residual variation within local regions of $\psi(X)$ space defining the fine strata. We noted earlier that $\hat{\theta} - \alpha'(\bar{h}_1 - \bar{h}_0) = \hat{\theta} - o_p(n^{-1/2})$ for any $\alpha \in \mathbb{R}^{d_h}$, so such adjustment cannot improve first-order efficiency. Nevertheless, one may still wish to adjust for $h(\psi)$ to correct finite sample imbalances not controlled by the design. Adjustment for such variables needs to be handled slightly differently, and we construct modified efficient estimators for this purpose in Section 3.5 below.

3.4.1 Strata Fixed Effects Estimator

Recall that for $p = a/k$, a finely stratified design $D_{1:n} \sim \text{Loc}(\psi, p)$ partitions the experimental units $\{1, \dots, n\}$ into n/k disjoint groups g . Define the fixed effects estimator $\hat{\theta}_{FE}$ by the least squares equation

$$Y_i = \hat{\theta}_{FE} D_i + \hat{\gamma}'_{FE} h_i + \sum_{g=1}^{n/k} \hat{a}_g \mathbf{1}(i \in g) + e_i. \quad (3.2)$$

The next theorem shows that $\hat{\theta}_{FE}$ is fully efficient in the case of matched pairs or if treatment effect heterogeneity is limited, but may be inefficient in general.

Theorem 3.16. *Suppose Assumptions 3.1 and 3.15 hold. The estimator has representation $\hat{\theta}_{FE} = \hat{\theta} - \hat{\gamma}'_{FE}(\bar{h}_1 - \bar{h}_0) + O_p(n^{-1})$. If $D_{1:n} \sim \text{Loc}(\psi, p)$ then $\sqrt{n}(\hat{\theta}_{FE} - \text{ATE}) \Rightarrow \mathcal{N}(0, V)$ with variance*

$$V = \text{Var}(c(X)) + E[\text{Var}(b - \gamma'_{FE} h | \psi)] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right].$$

and coefficient $\gamma_{FE} = \text{argmin}_{\gamma \in \mathbb{R}^{d_h}} E[\text{Var}(f - \gamma' h | \psi)]$ for target function

$$f(x) = m_1(x) \sqrt{\frac{p}{1-p}} + m_0(x) \sqrt{\frac{1-p}{p}}.$$

The function $f(x) \neq b(x)$ in general. If $p = 1/2$, the fixed effects estimator is efficient. If $p \neq 1/2$, it is efficient if and only if $E[\text{Cov}(h, Y(1) - Y(0) | \psi)] = 0$.

See Section A.4 for the proof. Asymptotically exact inference for the ATE using $\hat{\theta}_{FE}$ is available using the tools in Section 4.

Remark 3.17 (Conditions for Efficiency). If $p = 1/2$ then $f = b$ and $\hat{\theta}_{FE}$ is efficient. More generally, $f(x) \neq b(x)$ and $\hat{\theta}_{FE}$ solves the wrong variance minimization problem, effectively targeting the wrong linear combination of outcomes. The necessary and sufficient condition $E[\text{Cov}(h, Y(1) - Y(0) | \psi)] = 0$ requires that treatment effect heterogeneity is not explained by the covariates $h(X)$, conditional on the stratification variables.

In the rest of this section, we develop estimators that are fully efficient for any finely stratified design, without imposing any assumptions on treatment effect heterogeneity or treatment proportions.

3.4.2 Partialled Lin Estimator

First, we define a partialled version of the Lin estimator. Define the within-group partialled covariates

$$\check{h}_i = h_i - \frac{1}{k} \sum_{j \in g(i)} h_j.$$

For example, if $k = 2$ this is just the within-pair covariate difference $\check{h}_i = (1/2)(h_i - h_{m(i)})$, where i is matched to $m(i)$. We can think of \check{h}_i as an inconsistent but approximately unbiased signal for the non-parametrically residualized covariate $h_i - E[h_i|\psi_i]$. Next, we use these partialled covariates in the Lin regression

$$Y \sim 1 + D_i + \check{h}_i + D_i \check{h}_i \quad (3.3)$$

Define the *partialled* Lin estimator $\hat{\theta}_{PL}$ to be the coefficient on D_i in this regression. For reference, similarly to the Lin regression we may write this in the standard form $\hat{\theta}_{PL} = \hat{\theta} - \hat{\gamma}'_{PL}(\bar{h}_1 - \bar{h}_0)c_p$ with adjustment coefficient $\hat{\gamma}_{PL} = (\hat{a}_1 + \hat{a}_0)\sqrt{\frac{1-p}{p}} + \hat{a}_0\sqrt{\frac{p}{1-p}}$, where \hat{a}_0 and \hat{a}_1 are coefficients on \check{h}_i and $D_i \check{h}_i$.

Our main result in Theorem 3.22 below shows that the partialled Lin estimator $\hat{\theta}_{PL}$ is asymptotically efficient in the sense of Definition 3.5, with $\hat{\gamma}_{PL} \xrightarrow{p} \gamma^*$ for the optimal adjustment coefficient γ^* .

Remark 3.18 (Intuition for Optimality). Theorem 3.4 showed that an estimator $\hat{\theta} - \hat{\gamma}(\bar{h}_1 - \bar{h}_0)c_p$ is efficient if $\hat{\gamma} \xrightarrow{p} \gamma^*$ and γ^* solves the conditional-mean variance problem $\gamma^* \in \operatorname{argmin}_{\gamma} E[\operatorname{Var}(b - \gamma'h|\psi)]$. By using within-stratum partialled regressors \check{h}_i , we force the Lin estimator to only use covariate signal $h_i - E[h_i|\psi_i]$ that is mean-independent of the stratification variables.

Remark 3.19 (Treatment-Strata Interactions). As an alternative to $\hat{\theta}_{PL}$, one may attempt to use the Lin regression $Y_i \sim (1, h_i, g_i^n) + D_i(1, h_i, g_i^n)$ with leave-one-out strata fixed effects $g_i^n = (\mathbf{1}(i \in g))_{i=1}^{n/k-1}$. Unfortunately, this produces collinear regressors if either $a = 1$ or $a = k - 1$, which includes the case of matched pairs. To see the issue, one can show by Frisch-Waugh that in contrast to Equation 3.3 above, this estimator partials covariates h_i separately in each treatment arm, using $\check{h}_i = h_i - a^{-1} \sum_{j \in g(i)} h_j D_j$ if $D_i = 1$ and $\check{h}_i = h_i - (k - a)^{-1} \sum_{j \in g(i)} h_j (1 - D_j)$ if $D_i = 0$. For instance, if $a = 1$ then this is $\check{h}_i = h_i - h_i = 0$ for all i , showing collinearity. In the case $1 < a < k - 1$ where this estimator is feasible, it is asymptotically equivalent to the partialled Lin estimator. However, finite sample properties will be worse due to noisier within-arm partialling.

3.4.3 Group OLS Estimator

Next, we generalize an estimator proposed by [Imbens and Rubin \(2015\)](#) for covariate adjustment in matched pairs experiments to more general stratified designs. For each group of units $g = 1, \dots, n/k$ in the design $D_{1:n} \sim \text{Loc}(\psi, p)$, define the within-group difference of means of outcomes and covariates

$$y_g = \frac{1}{k} \sum_{i \in g} \frac{Y_i D_i}{p} - \frac{1}{k} \sum_{i \in g} \frac{Y_i (1 - D_i)}{1 - p} \quad \text{and} \quad h_g = \frac{1}{k} \sum_{i \in g} \frac{h_i D_i}{p} - \frac{1}{k} \sum_{i \in g} \frac{h_i (1 - D_i)}{1 - p}.$$

For any group-indexed array $(x_g)_g$, denote $E_g[x_g] = \frac{k}{n} \sum_g x_g$. Define the *Group OLS* estimator $\hat{\theta}_G$ by the regression $y_g = \hat{\theta}_G + \hat{\gamma}'_G h_g + e_g$ with $E_g[(1, h_g)e_g] = 0$. For motivation, note that if $h = 0$ then this becomes $y_g = \hat{\theta}_G + e_g$ and $\hat{\theta}_G$ is just the unadjusted estimator $\hat{\theta}_G = \bar{Y}_1 - \bar{Y}_0$. More generally, the adjusted version can be written $\hat{\theta}_G = E_g[y_g] - \hat{\gamma}'_G E_g[h_g] = \hat{\theta} - \hat{\gamma}'_G (\bar{h}_1 - \bar{h}_0)$ with adjustment coefficient $\hat{\gamma}_G = \text{Var}_g(h_g)^{-1} \text{Cov}_g(h_g, y_g)$. The main result of this section shows that $\hat{\theta}_G$ is asymptotically equivalent to the partialled Lin estimator $\hat{\theta}_{PL}$, and both are asymptotically optimal.

Remark 3.20 (Intuition for Efficiency). The estimator $\hat{\theta}_G$ uses within-group differences of covariates $\bar{h}_{g1} - \bar{h}_{g0}$ to predict within-group outcome differences $\bar{Y}_{1g} - \bar{Y}_{0g}$. Similar to the partialled Lin strategy, by doing this we only measure variation in covariates and potential outcomes that is orthogonal to the stratification variables. This forces least squares to compute a conditional variance-covariance tradeoff, solving the optimal adjustment problem in Definition 3.5. In particular, the proof of Theorem 3.22 shows that if $D_{1:n} \sim \text{Loc}(\psi, p)$ then the adjustment coefficient

$$\hat{\gamma}_G = \text{Var}_g(h_g)^{-1} \text{Cov}_g(h_g, y_g) \xrightarrow{p} \underset{\gamma}{c_p} \argmin E[\text{Var}(b - \gamma' h | \psi)].$$

Remark 3.21. [Imbens and Rubin \(2015\)](#) propose $\hat{\theta}_G$ in the case of matched pairs $k = 2$. Their analysis uses a toy sampling model where the pairs themselves are drawn “pre-matched” from a super-population. By contrast, we model the experimental units as being sampled from a super-population, with units matched into data-dependent strata post-sampling. This more realistic model complicates the analysis, producing different limiting variances and requiring different inference procedures. In a design-based setting, [Fogarty \(2018\)](#) shows that the [Imbens and Rubin \(2015\)](#) estimator is weakly more efficient than difference of means for matched pairs designs. By contrast, we extend this estimator to a larger family of fine stratifications strictly containing matched pairs, and show that it is asymptotically optimal among linearly adjusted estimators.

3.4.4 Tyranny-of-the-Minority (ToM) Regression

Finally, we define tyranny-of-the-minority (ToM) regression, extending Lin (2013). Let $\hat{\gamma}_{TM}$ be the coefficient in the regression $Y_i^{TM} = \hat{\gamma}_{TM}' \check{h}_i + e_i$ with partialled covariates \check{h}_i and weighted outcomes

$$Y_i^{TM} = D_i Y_i \frac{(1-p)^{1/2}}{p^{3/2}} + (1-D_i) Y_i \frac{p^{1/2}}{(1-p)^{3/2}}. \quad (3.4)$$

Define the ToM estimator $\hat{\theta}_{TM} = \hat{\theta} - \hat{\gamma}_{TM}'(\bar{h}_1 - \bar{h}_0)c_p$.

3.4.5 Main Result

The main result of this section shows that all three estimators above are asymptotically equivalent and efficient in the sense of Definition 3.5.

Theorem 3.22. *Suppose Assumptions 3.1 and 3.15 hold. If $D_{1:n} \sim \text{Loc}(\psi, p)$, then $\hat{\theta}_{PL} - \hat{\theta}_G = o_p(n^{-1/2})$ and $\hat{\theta}_{PL} - \hat{\theta}_{TM} = o_p(n^{-1/2})$. We have $\sqrt{n}(\hat{\theta}_{PL} - \text{ATE}) \Rightarrow \mathcal{N}(0, V^*)$ with the optimal variance*

$$V^* = \text{Var}(c(X)) + \min_{\gamma} E[\text{Var}(b - \gamma' h | \psi)] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right].$$

Methods for asymptotically exact inference on the ATE using these estimators are discussed in Section 4 below. The proof is given in Section A.4 of the appendix.

3.5 Further Adjustment for Stratification Variables

In this section, we give modified versions of the previous estimators that allow further adjustment for covariates $z(\psi)$ that are functions of the stratification variables. As discussed above, this cannot improve first-order efficiency but may improve finite sample performance by correcting for any remaining imbalances in ψ not controlled by the stratification.

Denote $z_i = z(\psi_i)$. Define a modified version of the fixed effects estimator $\hat{\tau}_{FE}$ by the coefficient on D_i in the regression $Y_i \sim (1, D_i, \check{h}_i, z_i)$. For the partialled Lin estimator, define a modified version $\hat{\tau}_{PL}$ to be the coefficient on D_i in the regression $Y_i \sim (1, \check{h}_i, z_i) + D_i(1, \check{h}_i, z_i)$. Define the modified group OLS estimator $\hat{\tau}_G = \hat{\theta}_G - \hat{\alpha}'_G(\bar{z}_1 - \bar{z}_0)c_p$, with $\hat{\alpha}_G$ the coefficient from the regression $c_p(Y_i^{TM} - \hat{\gamma}'_G h_i) = \hat{c} + \hat{\alpha}'_G z_i + e_i$ with $E_n[e_i(1, z_i)] = 0$.

For intuition about the modified group OLS estimator, we show in the appendix that $E[Y_i^{TM} | X_i] \propto b(X_i)$, so we may think of Y_i^{TM} as a noisy signal for $b(X_i)$. Then the OLS relation defining the coefficient $\hat{\alpha}_G$ behaves in large samples like the population

regression $b(X) - h(X)' \gamma^* \sim (1, z(\psi))$, where γ^* is the efficient adjustment coefficient for $h(X)$. Then we are effectively regressing the residuals $b(X) - h(X)' \gamma^*$ on the covariates $z(\psi)$. Our next theorem shows that these estimators are asymptotically equivalent to the original versions of each estimator that do not adjust for $z(\psi)$. However, the simulations in Sections 5 and 6 show that they may perform better in small experiments.

Theorem 3.23. *Suppose Assumptions 3.1 and 3.15 hold, as well as $\text{Var}(z) \succ 0$ and $E[|z|_2^2] < \infty$. Then if $D_{1:n} \sim \text{Loc}(\psi, p)$ we have $\hat{\tau}_k = \hat{\theta}_k + o_p(n^{-1/2})$ for $k \in \{FE, PL, G\}$. Each estimator has the form $\hat{\tau}_k = \hat{\theta}_k - \hat{\alpha}'_k(\bar{z}_1 - \bar{z}_0)c_p$ with $\hat{\alpha}_{FE} \xrightarrow{p} \text{argmin}_\alpha \text{Var}(f - \alpha'z)$, $\hat{\alpha}_{PL} \xrightarrow{p} \text{argmin}_\alpha \text{Var}(b - \alpha'z)$ and $\hat{\alpha}_G \xrightarrow{p} \text{argmin}_\alpha \text{Var}(b - h'\gamma^* - \alpha'z)$ and f as in 3.16.*

From the second statement of the theorem, we can interpret the modified estimators as taking a conservative approach that ignores stratification on ψ and adjusts for imbalances in $z(\psi)$ as if the experiment were completely randomized.

4 Inference

In this section, we provide asymptotically exact confidence intervals for the ATE in stratified experiments using generic linearly adjusted estimators. Overcoverage is known to be a problem for inference based on the usual Eicker-Huber-White (EHW) variance estimator in stratified experiments. For example, Bai et al. (2021) shows that the EHW variance estimators for $Y \sim 1 + D + h$ and the fixed effects regression $Y \sim D + h + z^n$ are asymptotically conservative for matched pairs designs if $h = 0$. To the best of our knowledge, we give the first asymptotically exact inference methods for covariate-adjusted ($h \neq 0$) ATE estimation under general stratified designs. Our main inference result applies to any estimator of the form $\hat{\theta} - \hat{\gamma}'(\bar{h}_1 - \bar{h}_0) + O_p(n^{-1})$, enabling asymptotically exact inference on the ATE using any of the estimators in this paper. Our confidence intervals are shorter than those produced by EHW in the simulations and empirical application below, taking full advantage of the efficiency gains from both stratification and covariate adjustment.

Before continuing, we review asymptotically exact inference for unadjusted estimation. The procedure introduced in Cytrynbaum (2022) extends the “pairs-of-pairs” idea from Abadie and Imbens (2008). In particular, we (1) form centroids $\frac{1}{k} \sum_{i \in g} \psi_i$ for each stratum, (2) match stratum centroids into pairs and (3) match treated units to treated units and control units to control units between paired strata. This results in a bijective matching function $\mu : [n] \rightarrow [n]$ with $D_i = D_{\mu(i)}$ for all i . Crucially, the centroid-pairing step (2) ensures a tight matching in the sense that provably $E_n[|\psi_i - \psi_{\mu(i)}|_2^2] = o_p(1)$ as $n \rightarrow \infty$. See the explicit construction in Cytrynbaum (2022) for details. We use the matching $\mu(\cdot)$ to define variance estimators in Definition 4.1 below.

Definition 4.1 (Unadjusted Variance Estimation). Define the following variance estimation components

$$\begin{aligned}\hat{v}_1 &= E_n \left[\frac{D_i(1-p)}{p^2} Y_i Y_{\mu(i)} \right] & \hat{v}_0 &= E_n \left[\frac{(1-D_i)p}{(1-p)^2} Y_i Y_{\mu(i)} \right] \\ \hat{v}_{10} &= 2n^{-1} \sum_{1 \leq i < j \leq n} \frac{\mathbb{1}(g(i) = g(j))}{k} \frac{D_i(1-D_j)Y_i Y_j}{p(1-p)}.\end{aligned}$$

Let the unadjusted variance estimator \hat{V} be given by

$$\hat{V} = \text{Var}_n \left(\frac{(D_i - p)Y_i}{p - p^2} \right) - \hat{v}_1 - \hat{v}_0 - 2\hat{v}_{10}.$$

Theorem 5.3 of [Cytrynbaum \(2022\)](#) shows that $\hat{V} = V + o_p(1)$, where V is the unadjusted asymptotic variance

$$V = \text{Var}(c(X)) + E[\text{Var}(b|\psi)] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right].$$

Next, we modify \hat{V} to account for the efficiency gains (or losses) of linear covariate adjustment. For propensity score $p = a/k$ define $\hat{V}_h = \frac{k}{k-1} E_n[\check{h}_i \check{h}_i']$ and $\hat{V}_b = \frac{k}{k-1} E_n[\check{h}_i Y_i^{TM}]$, with Y_i^{TM} the weighted outcomes defined in Equation 3.4. Our main result shows that the augmented variance estimator defined by $\hat{V}(\gamma) = \hat{V} - 2\hat{\gamma}'\hat{V}_b + \hat{\gamma}'\hat{V}_h\hat{\gamma}$ is consistent for the true asymptotic variance of the adjusted estimator with coefficient $\hat{\gamma}$.

Theorem 4.2. *Suppose Assumptions 3.1 and 3.15 hold. Let $D_{1:n} \sim \text{Loc}(\psi, p)$ and consider an estimator $\hat{\theta}(\hat{\gamma}) = \hat{\theta} - \hat{\gamma}'(\bar{h}_1 - \bar{h}_0)c_p$ with $\hat{\gamma} \xrightarrow{p} \gamma$ and asymptotic variance $V(\gamma)$ as in Theorem 3.4. Then $\hat{V}(\gamma) \xrightarrow{p} V(\gamma)$.*

See Section A.5 for the proof. Theorem 4.2 shows that the confidence interval

$$\hat{C} = \left[\hat{\theta}(\hat{\gamma}) - \frac{\hat{V}(\gamma)^{1/2}}{\sqrt{n}} c_{1-\alpha/2}, \hat{\theta}(\hat{\gamma}) + \frac{\hat{V}(\gamma)^{1/2}}{\sqrt{n}} c_{1-\alpha/2} \right] \quad (4.1)$$

with $c_a = \Phi^{-1}(a)$ is asymptotically exact in the sense that $P(\text{ATE} \in \hat{C}) = 1 - \alpha + o(1)$. The simulations in Section 5 and empirical application in Section 6 show that this interval has close to nominal coverage and good efficiency properties in finite samples. By comparison, the EHW variance based confidence intervals frequently overcover.

5 Simulations

In this section, we use simulations to test the finite sample performance of the estimators studied above. We consider quadratic outcome models of the form

$$Y_i(d) = \psi_i' Q_d \psi_i + \psi_i' L_d + c_d \cdot u(X_i) + \epsilon_i^d \quad E[\epsilon_i^d | X_i] = 0$$

for $d \in \{0, 1\}$. The component $u_i = u(X_i)$ represents covariate signal that is independent of the stratification variables $\psi(X_i)$. After implementing the design $D_{1:n} \sim \text{Loc}(\psi, p)$, we receive access to scalar covariates h_i that are correlated with both ψ_i and $Y_i(d)$. In particular, suppose that $h_i = \psi_i' Q_h \psi_i + \psi_i' L_h + u_i$ with $E[u_i | \psi_i] = 0$. In the following simulations, we let $\psi_i \sim N(0, I_m)$, $u_i \sim N(0, 1)$, and $\epsilon_i^d \sim N(0, 1/10)$ with $(\psi_i, u_i, \epsilon_i^d)$ jointly independent. We use treatment proportions $p = 2/3$ unless otherwise specified. With $m \equiv \dim(\psi)$, let $A \in \mathbb{R}^{m \times m}$ have $A_{ij} = 1$ for $i \neq j$ and $A_{ii} = 0$. We simulate the following DGP's:

Model 1: Quadratic coefficients $Q_h = (1/m^2)A$ and $Q_0 = Q_1 = (1/m)A$. Linear coefficients $L_0 = \mathbf{1}_m$, $L_1 = 2\mathbf{1}_m$, $L_h = \mathbf{1}_m$. Regressor signal $c_1 = c_0 = -3$.

Model 2: As in Model 1 but $c_0 = -4$ and $c_1 = -1$.

Model 3: As in Model 2 but $p = 1/2$.

Model 4: As in Model 1 but $c_0 = 2$ and $c_1 = 4$.

Model 5: As in Model 1 but $c_0 = 2$ and $c_1 = 4$ and $p = 1/2$.

Model 6: As in Model 1 but $Q_h = (1/100)A$.

We begin by comparing the efficiency properties of different linearly adjusted estimators. **Unadj** refers to simple difference of means (unadjusted). The **Lin** estimator is studied in Theorem 3.2. **Naive** refers to the non-interacted regression $Y \sim (1, D, h)$, (Theorem A.1). **FE** refers to the fixed effects estimator (Theorem 3.16) and **Plin** the partialled Lin estimator (Theorem 3.22). **GO** refers to Group OLS and **ToM** refers to Tyranny-of-the-Minority estimation (Theorem 3.22). **Strata Controls** refer to modified versions of each of the previous estimators that further adjust for parametric strata controls $z(\psi)$, as discussed in Section 3.3 and Section 3.5. In our simulations, we set $z(\psi) = \psi$. All results are calculated using 1000 Monte Carlo repetitions.

Table 1 studies estimator efficiency, showing the mean squared error (MSE) ratio, relative to difference of means, for each of the adjusted estimators above. In models 1, 2, and 3, both Naive and Lin style linear adjustment are strictly inefficient relative to unadjusted estimation. These models have marginal covariance $\text{Cov}(Y(d), h) > 0$ but conditional covariance $E[\text{Cov}(Y(d), h | \psi)] < 0$, conditional on the stratification variables.

Table 1: Ratio of MSE’s (%) for adjusted vs. unadjusted estimation.

| $(n, \dim(\psi))$ | Model | No Strata Controls | | | | | | | Strata Controls | | | | | |
|-------------------|-------|--------------------|-------|-------|------|------|------|-------|-----------------|------|------|------|------|------|
| | | Unadj | Naive | Lin | FE | Plin | GO | ToM | Naive | Lin | FE | Plin | GO | ToM |
| (600, 2) | 1 | 100 | 115.0 | 103.0 | 27.3 | 27.3 | 27.2 | 102.8 | 29.5 | 29.4 | 19.9 | 21.1 | 21.2 | 21.1 |
| | 2 | 100 | 126.8 | 102.3 | 48.4 | 39.7 | 39.7 | 101.8 | 58.4 | 41.6 | 42.1 | 34.4 | 34.7 | 34.6 |
| | 3 | 100 | 114.5 | 114.5 | 46.5 | 46.5 | 46.5 | 114.3 | 50.6 | 50.7 | 42.1 | 42.1 | 42.2 | 41.9 |
| | 4 | 100 | 21.2 | 27.8 | 21.8 | 18.1 | 18.1 | 27.9 | 17.6 | 20.3 | 25.7 | 20.8 | 20.9 | 21.0 |
| | 5 | 100 | 28.2 | 28.2 | 17.7 | 17.7 | 17.7 | 28.1 | 20.6 | 20.6 | 20.1 | 20.1 | 20.1 | 19.9 |
| | 6 | 100 | 100.1 | 100.2 | 16.4 | 16.4 | 16.4 | 99.8 | 6.9 | 6.8 | 11.1 | 11.0 | 11.2 | 11.0 |
| (1200, 2) | 1 | 100 | 114.7 | 102.9 | 20.8 | 20.5 | 20.7 | 102.7 | 28.5 | 28.5 | 16.2 | 16.7 | 16.8 | 16.7 |
| | 2 | 100 | 128.9 | 102.4 | 41.3 | 34.0 | 34.1 | 102.2 | 57.5 | 40.0 | 37.7 | 31.1 | 31.1 | 30.9 |
| | 3 | 100 | 115.9 | 116.0 | 41.3 | 41.3 | 41.3 | 115.8 | 49.7 | 49.7 | 38.9 | 38.9 | 38.9 | 38.8 |
| | 4 | 100 | 22.8 | 29.1 | 26.0 | 20.3 | 20.4 | 29.1 | 19.4 | 21.7 | 29.2 | 22.7 | 22.9 | 22.8 |
| | 5 | 100 | 27.0 | 26.9 | 16.1 | 16.1 | 16.1 | 26.9 | 19.1 | 19.0 | 17.6 | 17.7 | 17.7 | 17.6 |
| | 6 | 100 | 100.1 | 100.1 | 12.4 | 12.4 | 12.4 | 99.9 | 6.8 | 6.8 | 9.3 | 9.3 | 9.3 | 9.3 |
| (1200, 5) | 1 | 100 | 144.5 | 129.1 | 77.6 | 77.5 | 77.5 | 128.9 | 22.4 | 21.8 | 39.1 | 44.4 | 49.7 | 44.4 |
| | 2 | 100 | 146.0 | 124.0 | 86.9 | 79.1 | 79.0 | 124.0 | 45.9 | 33.7 | 55.4 | 51.6 | 56.6 | 51.3 |
| | 3 | 100 | 137.7 | 137.6 | 80.4 | 80.4 | 80.4 | 137.6 | 41.2 | 41.1 | 54.2 | 54.1 | 59.0 | 54.0 |
| | 4 | 100 | 28.2 | 32.6 | 33.3 | 28.0 | 28.0 | 32.6 | 27.3 | 21.4 | 57.6 | 45.8 | 48.8 | 46.0 |
| | 5 | 100 | 31.9 | 32.0 | 25.0 | 25.0 | 25.0 | 31.9 | 18.2 | 18.1 | 41.7 | 41.6 | 43.0 | 41.5 |
| | 6 | 100 | 135.5 | 135.5 | 74.5 | 74.5 | 74.5 | 135.4 | 17.3 | 17.3 | 40.8 | 40.9 | 43.5 | 40.7 |

Because of this, the optimal adjustment coefficient $\gamma^* < 0$, while the Naive and Lin regressions estimate positive adjustment coefficients $\gamma_N, \gamma_L > 0$, leading to even worse performance than difference of means in some cases. **Plin**, **GO**, and **FE** perform well across specifications for Models 1, 2, and 3. While asymptotically efficient, **ToM** performs poorly in finite samples when $p \neq 1/2$, since dividing by small propensity weights results in highly variable estimates of the optimal adjustment coefficient γ^* .

For Model 6, **Lin** with $z(\psi) = \psi$ controls is optimal. This is implied by our result on rich strata controls in Theorem 3.10. In particular, since $E[w|\psi]$ is (approximately) linear in ψ , including covariates $z(\psi) = \psi$ in the Lin estimator should give (approximate) efficiency. For Models 4 and 5, the (generally inefficient) **Naive** and **Lin** methods are competitive with the generic efficient methods from Section 3.4. This is because in these cases both $\text{Cov}(Y(d), h) \approx E[\text{Cov}(Y(d), h|\psi)]$, so that “by chance” the optimal adjustment coefficient γ^* is close to the Naive and Lin adjustment coefficients γ_N and γ_L . However, the Naive and Lin coefficients are estimated much more precisely than the optimal coefficient $\gamma^* = E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, b|\psi)]$. Summarizing our findings, the efficient methods perform well in finite samples when the gap $\gamma_L - \gamma^*$ between the sub-optimal Lin coefficient and optimal coefficient γ^* dominates the additional variability $\text{Var}(\hat{\gamma}^*) > \text{Var}(\hat{\gamma}_L)$ required to estimate γ^* .

Table 2 reports finite sample efficiency and coverage properties of the asymptotically exact inference methods developed in Section 4. We let $n = 1200$ and $\dim(\psi) = 5$.

Table 2: Inference Methods - Power and Coverage.

| | Model | No Strata Controls | | | | | | | Strata Controls | | | | | |
|-----------------------------------|-------|--------------------|-------|-------|-------|-------|-------|-------|-----------------|-------|-------|-------|-------|-------|
| | | Unadj | Naive | Lin | FE | Plin | GO | TOM | Naive | Lin | FE | Plin | GO | TOM |
| % Δ CI Length vs. Unadj | 1 | 0.0 | 19.3 | 12.9 | -11.1 | -11.3 | -11.1 | 12.9 | -48.8 | -49.4 | -35.1 | -31.4 | -28.0 | -31.5 |
| | 2 | 0.0 | 20.5 | 11.2 | -6.3 | -9.7 | -9.6 | 11.2 | -31.2 | -40.0 | -24.6 | -26.3 | -23.5 | -26.4 |
| | 3 | 0.0 | 16.0 | 16.0 | -8.6 | -8.6 | -8.6 | 16.0 | -33.8 | -33.8 | -24.5 | -24.4 | -22.3 | -24.5 |
| | 4 | 0.0 | -43.7 | -39.8 | -40.8 | -44.4 | -44.2 | -39.9 | -45.8 | -50.4 | -24.9 | -31.6 | -30.0 | -31.7 |
| | 5 | 0.0 | -41.4 | -41.3 | -47.2 | -47.2 | -47.2 | -41.4 | -52.7 | -52.6 | -34.5 | -34.5 | -33.1 | -34.5 |
| | 6 | 0.0 | 16.1 | 16.1 | -15.2 | -15.2 | -15.2 | 16.1 | -55.6 | -55.6 | -35.8 | -35.8 | -33.1 | -35.8 |
| Coverage (Exact) | 1 | 95.6 | 95 | 95.3 | 96 | 95.8 | 96 | 95.3 | 96.6 | 96.2 | 96.3 | 96.2 | 95.8 | 96.2 |
| | 2 | 96.3 | 95.6 | 96.1 | 96.5 | 96.1 | 96.1 | 96.1 | 95.5 | 96.2 | 95.7 | 96.2 | 95.7 | 96.1 |
| | 3 | 94.8 | 94 | 94.1 | 95.4 | 95.4 | 95.4 | 94 | 95.3 | 95.3 | 95 | 95.1 | 94.8 | 95 |
| | 4 | 96.5 | 97.5 | 98.1 | 95.9 | 96.4 | 96.9 | 97.9 | 96.8 | 96.9 | 95.1 | 96 | 95.4 | 96 |
| | 5 | 96.4 | 95.4 | 95.4 | 97 | 97 | 97 | 95.4 | 97.5 | 97.7 | 95.8 | 95.9 | 95.9 | 95.8 |
| | 6 | 95.7 | 95.4 | 95.4 | 96.1 | 96.1 | 96.1 | 95.4 | 96.7 | 96.6 | 96.3 | 96.3 | 96.1 | 96.4 |
| Coverage (HC2) | 1 | 98.6 | 95.5 | 95.8 | 99.1 | 99.1 | | | 99.9 | 98.4 | 99.3 | 98.5 | | |
| | 2 | 98.8 | 95.7 | 95.9 | 99.4 | 99.5 | | | 97.9 | 94.6 | 98.3 | 97.1 | | |
| | 3 | 99.1 | 95.8 | 93.7 | 99.5 | 99.5 | | | 97.6 | 91.2 | 97.8 | 96.3 | | |
| | 4 | 99.5 | 99.3 | 93.1 | 100 | 100 | | | 97.4 | 69.7 | 97.6 | 97.3 | | |
| | 5 | 99.2 | 96.5 | 90 | 100 | 100 | | | 96.7 | 65.4 | 98.9 | 98.1 | | |
| | 6 | 99.5 | 97.1 | 96.4 | 99.9 | 99.9 | | | 99 | 96.3 | 99.3 | 98.9 | | |

Inference results for varying n are given in Section 6. The first panel shows % reduction in confidence interval length relative to unadjusted estimation. All confidence intervals are computed using Equation 4.1. We see that the relative efficiency of different estimators are reflected by our inference methods. In particular, asymptotically exact inference allows researchers to report shorter confidence intervals when a more efficient adjustment method is used. In the second panel, we show coverage probabilities for our asymptotically exact confidence interval (Equation 4.1), across a range of linearly adjusted estimators. The final panel shows coverage probabilities for confidence intervals based on the usual HC2 variance estimator, where applicable. The HC2-based confidence intervals significantly overcover.

6 Empirical Results

This section applies our methods to the 2008 Oregon Health Insurance Experiment, a large-scale public health intervention that randomized medicaid eligibility to low-income, uninsured adults. Finkelstein et al. (2012) provide intent-to-treat and IV estimates of the effect of medicaid eligibility on a range of health and financial outcomes, including emergency department visits and welfare program (SNAP, TANF) enrollment in the followup period. We restrict our attention to single-member households participating in the March 2008 lottery drawing. The authors observe a number of baseline characteristics, including age, gender, previous emergency department visits, previous visits for a chronic condition, whether the individual participated in SNAP or TANF welfare programs and so on. Approximately 1/3 of the individuals in this wave were randomized to treatment,

without stratification.

We perform an intent-to-treat analysis of the effect of medicaid eligibility on number of emergency department (ED) visits in the follow-up period. We want to compare the performance of different covariate adjusted estimators under finely stratified treatment assignment. To do this, we first impute a full panel of potential outcomes $(\hat{Y}_i(0), \hat{Y}_i(1))_{i=1}^N$, letting $\hat{Y}_i(d) = Y_i(d)$ if $D_i = d$ and $\hat{Y}_i(d) = \max(0, \hat{f}_d(X_i) + \epsilon_i^d)$ if $D_i \neq d$. In particular, we fit $\hat{f}_d(x)$ with LASSO separately in each arm, using the baseline covariates above and all two-way interactions. We draw $\epsilon_i^d \sim \mathcal{N}(0, \hat{\sigma}_d^2)$, with $\hat{\sigma}_d^2$ a residual variance estimate. For each Monte Carlo iteration we do the following: (1) draw $(\hat{Y}_i(0), \hat{Y}_i(1))_{i=1}^n$ with replacement from $(\hat{Y}_i(0), \hat{Y}_i(1))_{i=1}^N$ (2) draw treatment assignments $D_{1:n} \sim \text{Loc}(\psi, 1/3)$, (3) reveal $\hat{Y}_i = \hat{Y}_i(D_i)$, (4) estimate the ATE using each of the covariate adjustment methods above, and (5) form confidence intervals using both Equation 4.1 and the usual HC2 robust variance estimator. We test the following stratifications and adjustment sets:

Model 1: $\psi = (\text{age, gender, any ED visit pre-lottery})$ and covariates $h(X) = (\text{number of ED visits pre-lottery})$.

Model 2: As in Model 1 but $h(X) = (\text{number of ED visits pre-lottery, ever on SNAP, any ED visit for chronic condition, })$.

Model 3: As in Model 1 but $h(X) = (\text{number of ED visits pre-lottery, ever on TANF, amount of pre-lottery SNAP benefits})$.

Table 3: Ratio of MSE's (%) for adjusted vs. unadjusted estimation.

| n | Model | No Strata Controls | | | | | | | Strata Controls | | | | | |
|------|-------|--------------------|-------|------|------|------|------|------|-----------------|------|------|------|------|------|
| | | Unadj | Naive | Lin | FE | Plin | GO | ToM | Naive | Lin | FE | Plin | GO | ToM |
| 600 | 1 | 100 | 85.0 | 85.9 | 84.8 | 85.5 | 85.5 | 84.8 | 84.9 | 86.9 | 85.1 | 86.2 | 85.8 | 86.4 |
| | 2 | 100 | 79.9 | 81.7 | 79.6 | 81.1 | 79.9 | 80.9 | 79.7 | 82.4 | 79.6 | 81.3 | 79.9 | 83.0 |
| | 3 | 100 | 81.7 | 82.8 | 81.9 | 83.4 | 82.9 | 82.1 | 81.8 | 83.6 | 82.3 | 83.9 | 83.3 | 85.7 |
| 900 | 1 | 100 | 85.0 | 85.9 | 84.8 | 85.5 | 85.5 | 84.8 | 84.9 | 86.9 | 85.1 | 86.2 | 85.8 | 86.4 |
| | 2 | 100 | 79.9 | 81.7 | 79.6 | 81.1 | 79.9 | 80.9 | 79.7 | 82.4 | 79.6 | 81.3 | 79.9 | 83.0 |
| | 3 | 100 | 81.7 | 82.8 | 81.9 | 83.4 | 82.9 | 82.1 | 81.8 | 83.6 | 82.3 | 83.9 | 83.3 | 85.7 |
| 1200 | 1 | 100 | 88.4 | 89.1 | 88.6 | 88.8 | 88.7 | 88.3 | 88.1 | 88.9 | 88.5 | 88.9 | 88.6 | 89.2 |
| | 2 | 100 | 82.0 | 82.8 | 81.6 | 82.4 | 81.9 | 82.5 | 82.0 | 83.2 | 81.4 | 82.3 | 81.7 | 83.9 |
| | 3 | 100 | 82.4 | 83.7 | 82.0 | 83.4 | 82.9 | 83.7 | 82.2 | 83.8 | 81.7 | 83.0 | 82.6 | 84.8 |

Table 3 shows the efficiency of various estimators (as in Section 5). The efficiency differences between adjustment strategies are minor. To see why, one can compute that for this DGP the optimal adjustment coefficient $\gamma^* \approx 2.2$, while the (sub-optimal) population Lin coefficient $\gamma_L \approx 2.4$. However, our estimate of the optimal coefficient² is less

²In particular, we have $\hat{\gamma}^* - \hat{\gamma} = O_p(n^{-2/(\dim(\psi)+1)})$, while $\hat{\gamma}_L - \gamma_L = O_p(n^{-1/2})$.

precise, $\text{Var}(\hat{\gamma}^*) > \text{Var}(\hat{\gamma}_L)$. Since the difference between optimal coefficients $\gamma^* - \gamma_L$ is small, in small enough samples a precise estimate of the sub-optimal coefficient can perform better than an imprecise estimate of the optimal coefficient.

Table 4: Inference Methods - Power and Coverage.

| | n | No Strata Controls | | | | | | | Strata Controls | | | | | |
|---------------------------|------|--------------------|-------|------|------|-------|------|-------|-----------------|------|------|-------|------|-------|
| | | Unadj | Naive | Lin | FE | Plin | GO | ToM | Naive | Lin | FE | Plin | GO | ToM |
| %Δ CI Length vs. Unadj | 300 | 0.0 | -8.9 | -9.2 | -9.3 | -11.1 | -9.4 | -11.1 | 0.3 | 0.1 | -9.2 | -10.6 | -9.4 | -12.2 |
| | 450 | 0.0 | -8.9 | -9.2 | -9.2 | -10.5 | -9.4 | -10.4 | 0.3 | -0.1 | -9.2 | -10.1 | -9.3 | -11.0 |
| | 600 | 0.0 | -8.3 | -8.5 | -8.6 | -9.5 | -8.7 | -9.4 | 0.0 | -0.5 | -8.5 | -9.3 | -8.7 | -9.9 |
| | 900 | 0.0 | -7.8 | -8.0 | -8.0 | -8.7 | -8.1 | -8.6 | -0.2 | -0.8 | -8.0 | -8.5 | -8.1 | -9.0 |
| | 1200 | 0.0 | -8.1 | -8.3 | -8.3 | -8.9 | -8.5 | -8.7 | -0.3 | -1.0 | -8.3 | -8.8 | -8.4 | -9.0 |
| Coverage (Exact) | 300 | 94.0 | 94.6 | 93.8 | 94.5 | 93.8 | 94.5 | 93.1 | 96.3 | 95.4 | 94.5 | 93.9 | 94.4 | 92.2 |
| | 450 | 94.7 | 94.7 | 94.1 | 94.1 | 93.3 | 93.3 | 93.4 | 96.2 | 95.6 | 94.3 | 93.5 | 93.4 | 92.4 |
| | 600 | 94.7 | 94.4 | 94.3 | 94.4 | 93.8 | 94.6 | 93.8 | 96.2 | 95.9 | 94.4 | 94.0 | 94.4 | 92.4 |
| | 900 | 94.4 | 94.5 | 93.9 | 94.6 | 94.3 | 94.6 | 94.9 | 96.7 | 96.4 | 94.6 | 94.3 | 94.5 | 94.1 |
| | 1200 | 95.7 | 95.7 | 95.5 | 95.5 | 95.4 | 95.3 | 95.5 | 97.0 | 96.9 | 95.6 | 95.5 | 95.4 | 94.9 |
| Coverage (HC2) | 300 | 95.4 | 94.9 | 94.4 | 99.1 | 97.0 | | | 94.7 | 94.1 | 98.9 | 95.1 | | |
| | 450 | 96.1 | 94.8 | 94.3 | 99.4 | 96.3 | | | 94.4 | 93.6 | 98.9 | 95.1 | | |
| | 600 | 96.7 | 95.2 | 94.7 | 98.8 | 97.0 | | | 95.1 | 94.8 | 98.5 | 95.3 | | |
| | 900 | 96.6 | 94.9 | 94.2 | 99.3 | 96.9 | | | 94.6 | 94.2 | 99.0 | 96.0 | | |
| | 1200 | 97.6 | 96.3 | 95.8 | 99.3 | 97.6 | | | 96.2 | 95.8 | 99.0 | 96.4 | | |

Table 4 shows power and coverage properties of the inference methods from Section 4. We fix the specification in Model 3, varying experiment size n . The asymptotically exact interval performs well for moderate and large experiment sizes, but has slight undercoverage for small n , likely due to the larger variance of the asymptotically exact variance estimator $\hat{V}(\gamma)$. In this example, the HC2 variance estimator performed well for Naive and Lin regressions, but significantly overcovers for the other estimators.

7 Discussion and Recommendations for Practice

Adjustment for covariates is common in the analysis of experimental data. This paper showed that for experiments with stratified treatment randomization, the usual regression estimators can be inefficient, providing feasible alternatives that are asymptotically optimal in the class of linearly adjusted estimators. We conclude by giving some recommendations for empirical practice based on the theory and simulations above. For coarsely stratified designs with $p \neq 1/2$, we recommend the Lin estimator with leave-one-out strata fixed effects, shown to be optimal in Example 3.13. If $p = 1/2$, the non-interacted regression with leave-one-out strata fixed effects suffices.

For finely stratified experiments, we give a more nuanced recommendation. As discussed in the previous section, estimates of the optimal coefficient γ^* are typically noisier than estimates of the Lin and non-interacted adjustment coefficients γ_L and γ_N . If $\gamma^* - \gamma_L$ is small, then a precise estimate of γ_L can perform better than an imprecise estimate of γ^* for small enough experiment sizes. On the other hand, $\gamma^* - \gamma_L$ may be large if the conditional covariance between covariates and outcomes is very different from the marginal covariance, in which case the Lin estimator can perform much worse than the optimal estimators in Section 3.4. Due to these findings, we recommend different estimators for “small” and “large” finely stratified experiments. For $p = 1/2$ and small n (e.g. $n < 600$), we recommend the non-interacted regression $Y \sim 1 + D + h + z$ with parametric strata controls $z(\psi)$. For large n , we recommend the pair fixed effects estimator, which is efficient in this case. For $p \neq 1/2$ and small n , we recommend the Lin estimator with parametric strata controls, as in Section 3.3. For $p \neq 1/2$ and large n , we recommend the partialled Lin estimator with additional parametric strata controls, as in Section 3.5.

Regardless of the adjustment strategy, we recommend using the asymptotically exact confidence intervals provided in Section 4. Our simulations showed close to nominal coverage for these confidence intervals across all considered estimators. By contrast, confidence intervals based on the HC2 robust variance estimator often had significant overcoverage.

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A Appendix

A.1 Non-Interacted Regression Adjustment

For completeness, before continuing we describe the asymptotic behavior of the commonly used non-interacted regression estimator under stratified designs. Let $\hat{\theta}_N$ be the coefficient on D_i in $Y \sim 1 + D + h$.

Theorem A.1. *Suppose Assumptions 3.1 and 3.15 hold. The estimator has representation $\hat{\theta}_N = \hat{\theta} - \hat{\gamma}'_N(\bar{h}_1 - \bar{h}_0) + O_p(n^{-1})$. If $D_{1:n} \sim \text{Loc}(\psi, p)$ then $\sqrt{n}(\hat{\theta}_N - \text{ATE}) \Rightarrow \mathcal{N}(0, V)$ with variance*

$$V = \text{Var}(c(X)) + E[\text{Var}(b - \gamma'_N h | \psi)] + E\left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p}\right].$$

The coefficient $\gamma_N = \text{argmin}_{\gamma \in \mathbb{R}^{d_h}} \text{Var}(f - \gamma' h)$ for target function

$$f(x) = m_1(x)\sqrt{\frac{p}{1-p}} + m_0(x)\sqrt{\frac{1-p}{p}}$$

with $f(x) \neq b(x)$ in general. The fixed effects estimator is efficient if either $p = 1/2$ or $\text{Cov}(h, Y(1) - Y(0)) = 0$.

Theorem A.1 shows that $\hat{\theta}_N$ is generally inefficient since it uses the wrong objective function. In particular, the target function $f(x) \neq b(x)$ unless $p = 1/2$. Also, the limiting coefficient γ_N minimizes marginal instead of conditional variance. The results in Section 4 show how to construct asymptotically exact confidence intervals for the ATE using $\hat{\theta}_N$.

A.2 Proofs for Section 3.1

Definition A.2 (Conditional Weak Convergence). For random variables $A_n \in \mathbb{R}^d$ and σ -algebras $(\mathcal{F}_n)_n$, define conditional weak convergence $A_n | \mathcal{F}_n \Rightarrow A \iff E[e^{it'A_n} | \mathcal{F}_n] = E[e^{it'A}] + o_p(1) \forall t \in \mathbb{R}^d$.

Proof of Theorem 3.4. First, note that we have

$$\begin{aligned} \hat{\gamma}'(\bar{h}_1 - \bar{h}_0)c_p &= \hat{\gamma}' E_n \left[\frac{(D_i - p)}{\sqrt{p - p^2}} h_i \right] = (\hat{\gamma} - \gamma)' E_n \left[\frac{(D_i - p)}{\sqrt{p - p^2}} h_i \right] + \gamma' E_n \left[\frac{(D_i - p)}{\sqrt{p - p^2}} h_i \right] \\ &= \gamma' E_n \left[\frac{(D_i - p)}{\sqrt{p - p^2}} h_i \right] + o_p(n^{-1/2}). \end{aligned}$$

Denote $b_i = b(X_i)$. Then, using the fundamental expansion of the difference of means

estimator from Theorem 3.17 of [Cytrynbaum \(2022\)](#), we have

$$\widehat{\theta}(\widehat{\gamma}) = E_n[c(X_i)] + E_n \left[\frac{D_i - p}{\sqrt{p - p^2}} (b_i - h'_i \gamma) \right] + E_n \left[\frac{D_i \epsilon_i^1}{p} - \frac{(1 - D_i) \epsilon_i^0}{1 - p} \right] + o_p(n^{-1/2}).$$

Consider the middle term and define the residual $v_i = b_i - \gamma' h_i - E[b_i - \gamma' h_i | \psi_i]$. By Lemma 9.4 of [Cytrynbaum \(2022\)](#) $E_n[(D_i - p)(b_i - \gamma' h_i)] = E_n[(D_i - p)v_i] + o_p(n^{-1/2})$. Let $\mathcal{F}_{x,n} = \sigma(X_{1:n}, \pi_n)$. By Theorem 9.5 of the same paper, we have the weak limit

$$\sqrt{n} E_n \left[\frac{D_i - p}{\sqrt{p - p^2}} v_i \right] \Big| \mathcal{F}_{x,n} \Rightarrow \mathcal{N}(0, \text{Var}(v))$$

in the sense of Definition A.2. Note that $\text{Var}(v) = E[v^2] = E[\text{Var}(b - \gamma' h | \psi)]$. Then we have shown the decomposition

$$\begin{aligned} \sqrt{n}(\widehat{\theta}(\widehat{\gamma}) - \text{ATE}) &= \sqrt{n} E_n[c(X_i) - \text{ATE}] + \sqrt{n} E_n \left[\frac{D_i - p}{\sqrt{p - p^2}} (b_i - h'_i \gamma) \right] \\ &\quad + \sqrt{n} E_n \left[\frac{D_i \epsilon_i^1}{p} - \frac{(1 - D_i) \epsilon_i^0}{1 - p} \right] + o_p(1). \end{aligned}$$

Then the argument used in Theorem 3.17 of [Cytrynbaum \(2022\)](#) shows that $\sqrt{n}(\widehat{\theta}(\widehat{\gamma}) - \text{ATE}) \Rightarrow \mathcal{N}(0, V(\gamma))$ with

$$V(\gamma) = \text{Var}(c(X)) + E \left[\text{Var}(b - \gamma' h | \psi) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1 - p} \right].$$

This finishes the proof. \square

Proof of Theorem 3.2. Define $W_i = (1, \tilde{h}_i)$. First consider the regression $Y_i \sim D_i W_i + (1 - D_i) W_i$, with coefficients $(\widehat{\gamma}_1, \widehat{\gamma}_0)$. By Frisch-Waugh and orthogonality of regressors, $\widehat{\gamma}_1$ is numerically equivalent to the regression coefficient $Y_i \sim D_i W_i$ and similarly for $\widehat{\gamma}_0$. Then consider $Y_i = D_i W_i' \widehat{\gamma}_1 + e_i$ with $E_n[e_i(D_i W_i)] = 0$. Then $D_i Y_i = D_i W_i' \widehat{\gamma}_1 + D_i e_i$ and $E_n[D_i e_i(D_i W_i)] = E_n[e_i(D_i W_i)] = 0$. Then $\widehat{\gamma}_1$ can be identified with the regression coefficient of $Y_i \sim W_i$ in the set $\{i : D_i = 1\}$. Let $\widehat{\gamma}_1 = (\widehat{c}_1, \widehat{\alpha}_1)$. By the usual OLS formula $\widehat{c}_1 = E_n[Y_i | D_i = 1] - \widehat{\alpha}_1' E_n[\tilde{h}_i | D_i = 1]$ and $\widehat{\alpha}_1 = \text{Var}_n(\tilde{h}_i | D_i = 1)^{-1} \text{Cov}_n(\tilde{h}_i, Y_i | D_i = 1)$. Similar formulas hold for $D_i = 0$ by symmetry. Next, note that for $m = d_h + 1$ the original regressors can be written as a linear transformation

$$\begin{pmatrix} D_i W_i \\ W_i \end{pmatrix} = \begin{pmatrix} I_m & 0 \\ I_m & I_m \end{pmatrix} \begin{pmatrix} D_i W_i \\ (1 - D_i) W_i \end{pmatrix}.$$

Then the OLS coefficients for the original regression $Y_i \sim D_i W_i + W_i$ are given by the

change of variables formula

$$\left(\begin{pmatrix} I_k & 0 \\ I_k & I_k \end{pmatrix}' \right)^{-1} \begin{pmatrix} \hat{\gamma}_1 \\ \hat{\gamma}_0 \end{pmatrix} = \begin{pmatrix} I_k & -I_k \\ 0 & I_k \end{pmatrix} \begin{pmatrix} \hat{\gamma}_1 \\ \hat{\gamma}_0 \end{pmatrix} = \begin{pmatrix} \hat{\gamma}_1 - \hat{\gamma}_0 \\ \hat{\gamma}_0 \end{pmatrix}.$$

In particular, the coefficient on D_i in the original regression is

$$\begin{aligned} \hat{\theta}_L &= \hat{c}_1 - \hat{c}_0 = E_n[Y_i - \hat{\alpha}'_1 \tilde{h}_i | D_i = 1] - E_n[Y_i - \hat{\alpha}'_0 \tilde{h}_i | D_i = 0] \\ &= \hat{\theta} - E_n \left[\frac{\hat{\alpha}'_1 \tilde{h}_i D_i}{p} \right] + E_n \left[\frac{\hat{\alpha}'_0 \tilde{h}_i (1 - D_i)}{1 - p} \right] \\ &= \hat{\theta} - E_n \left[\frac{\hat{\alpha}'_1 h_i (D_i - p)}{p} \right] - E_n \left[\frac{\hat{\alpha}'_0 h_i (D_i - p)}{1 - p} \right] \\ &= \hat{\theta} - (\hat{\alpha}_1 (1 - p) + \hat{\alpha}_0 p)' E_n \left[\frac{h_i (D_i - p)}{p(1 - p)} \right] \\ &= \hat{\theta} - \left(\hat{\alpha}_1 \sqrt{\frac{1 - p}{p}} + \hat{\alpha}_0 \sqrt{\frac{p}{1 - p}} \right)' (\bar{h}_1 - \bar{h}_0) c_p. \end{aligned}$$

The first equality since $E_n[D_i] = p$ identically. The second equality by expanding $D_i = D_i - p + p$ and using $E_n[\tilde{h}_i] = 0$ and $E_n[(D_i - p)E_n[h_i]] = 0$.

Next, consider the coefficient $\hat{\alpha}_1 = \text{Var}_n(\tilde{h}_i | D_i = 1)^{-1} \text{Cov}_n(\tilde{h}_i, Y_i | D_i = 1)$. We have $\text{Var}_n(\tilde{h}_i | D_i = 1) = p^{-1} E_n[D_i \tilde{h}_i \tilde{h}_i'] - p^{-2} E_n[D_i \tilde{h}_i] E_n[D_i \tilde{h}_i']$. Let $1 \leq t, t' \leq d_h$. Then we may compute $E_n[D_i \tilde{h}_{it} \tilde{h}_{it'}'] = E_n[(D_i - p) \tilde{h}_{it} \tilde{h}_{it'}'] + p E_n[\tilde{h}_{it} \tilde{h}_{it'}']$. For the first term, by Lemma 9.20 of [Cytrynbaum \(2022\)](#), Young's inequality, and Jensen's inequality

$$\begin{aligned} \text{Var}(\sqrt{n} E_n[(D_i - p) \tilde{h}_{it} \tilde{h}_{it'}'] | h_{1:n}) &\leq 2 E_n[\tilde{h}_{it}^2 \tilde{h}_{it'}'^2] \leq E_n[\tilde{h}_{it}^4 + \tilde{h}_{it'}'^4] \\ &\leq 8(E_n[h_{it}^4] + E_n[h_{it'}^4] + E_n[h_{it}]^4 + E_n[h_{it'}]^4) \leq 16(E_n[h_{it}^4] + E_n[h_{it'}^4]) = O_p(1). \end{aligned}$$

The final line is by Markov inequality and since $E[h_{it}^4] < \infty$ by assumption. Then $E_n[D_i \tilde{h}_{it} \tilde{h}_{it'}'] = p E_n[\tilde{h}_{it} \tilde{h}_{it'}'] + O_p(n^{-1/2})$. We also have $E_n[D_i \tilde{h}_i] = E_n[(D_i - p) \tilde{h}_i] + p E_n[\tilde{h}_i] = E_n[(D_i - p) h_i] = O_p(n^{-1/2})$. Then $\text{Var}_n(\tilde{h}_i | D_i = 1)^{-1} = \text{Var}(h)^{-1} + O_p(n^{-1/2})$. Similar reasoning shows that $\text{Cov}_n(\tilde{h}_i, Y_i | D_i = 1) = \text{Cov}(h_i, Y_i(1)) + O_p(n^{-1/2})$.

Then we have shown $\hat{\alpha}_1 = \text{Var}(h)^{-1} \text{Cov}(h, Y(1)) + O_p(n^{-1/2}) = \text{Var}(h)^{-1} \text{Cov}(h, m_1) + O_p(n^{-1/2})$. By symmetry, we also have $\hat{\alpha}_0 = \text{Var}(h)^{-1} \text{Cov}(h, m_0) + O_p(n^{-1/2})$. Putting this all together, we have $\hat{\alpha}_1 \sqrt{\frac{1-p}{p}} + \hat{\alpha}_0 \sqrt{\frac{p}{1-p}} = \text{Var}(h)^{-1} \text{Cov}(h, b) + o_p(1) = \gamma_L + o_p(1)$. Then by Theorem 3.4, $\sqrt{n}(\hat{\theta}_L - \text{ATE}) \Rightarrow \mathcal{N}(0, V)$ with

$$V = V(\gamma_L) = \text{Var}(c(X)) + E \left[\text{Var}(b - \gamma'_L h | \psi) \right] + E \left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p} \right]$$

as claimed. The claimed representation follows from the change of variables formula

above, since $\hat{\alpha}_1 = \hat{a}_1 + \hat{a}_0$ and $\hat{\alpha}_0 = \hat{a}_0$. This finishes the proof. \square

Proof of Theorem A.1. We have $Y_i = \hat{c} + \hat{\theta}_N D_i + \hat{\gamma}'_N h_i + e_i$ with $E_n[e_i(1, D_i, h_i)] = 0$. By applying Frisch-Waugh twice, we have $\tilde{Y}_i = \hat{\theta}_N(D_i - p) + \hat{\gamma}'_N \tilde{h}_i + e_i$ and $\hat{\theta}_N = E_n[(\tilde{D}_i)^2]^{-1} E_n[\tilde{D}_i Y_i]$ with partialled treatment $\tilde{D}_i = (D_i - p) - (E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i(D_i - p)])' \tilde{h}_i$. Squaring this expression gives

$$\begin{aligned} (\tilde{D}_i)^2 &= (D_i - p)^2 - 2(D_i - p)(E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i(D_i - p)])' \tilde{h}_i \\ &\quad + ((E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i(D_i - p)])' \tilde{h}_i)^2 \equiv \eta_{i1} + \eta_{i2} + \eta_{i3}. \end{aligned}$$

Using $E_n[\tilde{h}_i(D_i - p)] = O_p(n^{-1/2})$, we see that $E_n[\eta_{i2}] = O_p(n^{-1})$ and $E_n[\eta_{i3}] = O_p(n^{-1})$. Then we have $E_n[(\tilde{D}_i)^2] = E_n[(D_i - p)^2] + O_p(n^{-1}) = p - p^2 + O_p(n^{-1})$. Then apparently $\hat{\theta}_N = (p - p^2)^{-1} E_n[\tilde{D}_i Y_i] + O_p(n^{-1})$. Now note that

$$\begin{aligned} E_n[\tilde{D}_i Y_i] &= E_n[(D_i - p)Y_i] - E_n[(E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i(D_i - p)])' \tilde{h}_i Y_i] \\ &= E_n[(D_i - p)Y_i] - E_n[(D_i - p)\tilde{h}_i]' (E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i Y_i]). \end{aligned}$$

By using Frisch-Waugh to partial out $D_i - p$ from the original regression, we have $\hat{\gamma}_N = E_n[\bar{h}_i \bar{h}'_i]^{-1} E_n[\bar{h}_i Y_i]$ with $\bar{h}_i = \tilde{h}_i - (E_n[(D_i - p)^2]^{-1} E_n[\tilde{h}_i(D_i - p)])(D_i - p)$. Then using $E_n[\tilde{h}_i(D_i - p)] = O_p(n^{-1/2})$ again, we have $E_n[\bar{h}_i \bar{h}'_i] = E_n[\tilde{h}_i \tilde{h}'_i] + O_p(n^{-1})$. Similarly, $E_n[\bar{h}_i Y_i] = E_n[\tilde{h}_i Y_i] - \hat{\theta}_N E_n[\tilde{h}_i(D_i - p)] = E_n[\tilde{h}_i Y_i] + O_p(n^{-1/2})$. Then the coefficient $\hat{\gamma}_N = E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i Y_i] + O_p(n^{-1/2})$. Then we have shown that

$$\begin{aligned} \hat{\theta}_N &= \hat{\theta} - E_n \left[\frac{(D_i - p)\tilde{h}_i}{\sqrt{p - p^2}} \right]' (E_n[\tilde{h}_i \tilde{h}'_i]^{-1} E_n[\tilde{h}_i Y_i])(p - p^2)^{-1/2} + O_p(n^{-1}) \\ &= \hat{\theta} - E_n \left[\frac{(D_i - p)h_i}{\sqrt{p - p^2}} \right]' \hat{\gamma}_N (p - p^2)^{-1/2} + O_p(n^{-1}) \\ &= \hat{\theta} - (\hat{\gamma}_N / c_p)' (\bar{h}_1 - \bar{h}_0) c_p + O_p(n^{-1}). \end{aligned}$$

The second line uses that $E_n[(D_i - p)c] = 0$ for any constant. This shows the claimed representation. We have $E_n[\tilde{h}_i \tilde{h}'_i] = \text{Var}(h) + o_p(1)$. Note also that $E_n[\tilde{h}_i Y_i(1)D_i] = p \text{Cov}(h, Y(1)) + o_p(1)$ and $E_n[\tilde{h}_i Y_i(0)(1 - D_i)] = (1 - p) \text{Cov}(h, Y(0)) + o_p(1)$. Putting this together, we have shown that

$$\begin{aligned} \hat{\gamma}_N / c_p &= \text{Var}(h)^{-1} \text{Cov} \left(h, m_1 \sqrt{\frac{p}{1 - p}} + m_0 \sqrt{\frac{1 - p}{p}} \right) + o_p(1) \\ &= \underset{\gamma}{\text{argmin}} \text{Var}(f - \gamma' h) + o_p(1) = \gamma_N + o_p(1). \end{aligned}$$

Then the first claim follows from Theorem 3.4. For the efficiency claims, (a) if $p = 1/2$ and $\psi = 1$, then $f = b$ and $\gamma_N = \underset{\gamma}{\text{argmin}} \text{Var}(f - \gamma' h) = \underset{\gamma}{\text{argmin}} E[\text{Var}(b - \gamma' h | \psi)]$. For

(c), if $\psi = 1$ and $\text{Cov}(h, m_1 - m_0) = 0$, then we have

$$\text{Cov}(h, f) - \text{Cov}(h, b) = \text{Cov}\left(h, (m_1 - m_0) \frac{2p - 1}{\sqrt{p(1 - p)}}\right) = 0.$$

By expanding the variance, we have $\text{argmin}_\gamma \text{Var}(f - \gamma'h) = \text{argmin}_\gamma \text{Var}(b - \gamma'h)$. If (b) holds, then $m_1 - m_0 = 0$ and the same conclusion follows. This finishes the proof. \square

Proof of Theorem 3.8. For any $\gamma \in \mathbb{R}^{d_h}$, we have $\text{argmin}_{g \in \mathcal{G}} E[(Y(d) - g(\psi) - \gamma'h)^2] = E[Y(d) - \gamma'h|\psi]$ by standard arguments. Then the coefficients

$$\gamma_d = \text{argmin}_{\gamma \in \mathbb{R}^{d_h}} E[(Y(d) - \gamma'h - E[Y(d) - \gamma'h|\psi])^2] = \text{argmin}_{\gamma \in \mathbb{R}^{d_h}} E[\text{Var}(Y(d) - \gamma'h|\psi)]$$

and $g_d(\psi) = E[Y(d) - \gamma_d'h|\psi]$. Define $f_d(x) = g_d(\psi) + \gamma_d'h$. Then the AIPW estimator

$$\begin{aligned} \hat{\theta}_{AIPW} &= E_n[f_1(X_i) - f_0(X_i)] + E_n\left[\frac{D_i(Y_i - f_1(X_i))}{p}\right] - E_n\left[\frac{(1 - D_i)(Y_i - f_0(X_i))}{1 - p}\right] \\ &= \hat{\theta} - E_n\left[f_1(X_i) \frac{(D_i - p)}{p}\right] - E_n\left[f_0(X_i) \frac{(D_i - p)}{1 - p}\right] \\ &= \hat{\theta} - E_n\left[(D_i - p) \left(\frac{f_1(X_i)}{p} + \frac{f_0(X_i)}{1 - p}\right)\right] \\ &= E_n\left[\frac{D_i - p}{p - p^2} (Y_i - (1 - p)f_1(X_i) - pf_0(X_i))\right]. \end{aligned}$$

Let $F(x) = (1 + p)f_1(x) + pf_0(x)$. Then by vanilla CLT we have $\sqrt{n}(\hat{\theta}_{AIPW} - \text{ATE}) \Rightarrow \mathcal{N}(0, V)$ with $V = \text{Var}\left(\frac{D_i - p}{p - p^2} (Y_i - F(X_i))\right) \equiv \text{Var}(W_i)$. By fundamental expansion of the IPW estimator from [Cytrynbaum \(2022\)](#)

$$\begin{aligned} W_i &= \frac{D_i - p}{p - p^2} (Y_i - F(X_i)) - \text{ATE} = \left[\frac{D_i \epsilon_i^1}{p} - \frac{(1 - D_i) \epsilon_i^0}{1 - p}\right] \\ &\quad + [c(X_i) - \text{ATE}] + \left[\frac{D_i - p}{\sqrt{p - p^2}} \left((m_1 - f_1) \sqrt{\frac{1 - p}{p}} + (m_0 - f_0) \sqrt{\frac{p}{1 - p}}\right)\right]. \end{aligned}$$

By the law of total variance and tower law

$$\begin{aligned} \text{Var}(W) &= \text{Var}(E[W|X]) + E[\text{Var}(W|X)] \\ &= \text{Var}(E[W|X]) + E[\text{Var}(E[W|X, D]|X)] + E[\text{Var}(W|X, D)]. \end{aligned}$$

From the expansion above, $\text{Var}(E[W|X]) = \text{Var}(c(X) - \text{ATE}) = \text{Var}(c(X))$. Next

$$\begin{aligned} E[W|X, D] &= [c(X_i) - \text{ATE}] + \left[\frac{D_i - p}{\sqrt{p - p^2}} \left((m_1 - f_1) \sqrt{\frac{1-p}{p}} + (m_0 - f_0) \sqrt{\frac{p}{1-p}} \right) \right] \\ E[\text{Var}(E[W|X, D]|X)] &= E \left[\left((m_1 - f_1) \sqrt{\frac{1-p}{p}} + (m_0 - f_0) \sqrt{\frac{p}{1-p}} \right)^2 \right] \end{aligned}$$

Using the definition of $f_d(x)$ gives

$$\begin{aligned} &E \left[\left((m_1 - \gamma'_1 h - E[m_1 - \gamma'_1 h|\psi]) \sqrt{\frac{1-p}{p}} + (m_0 - \gamma'_0 h - E[Y(0) - \gamma'_0 h|\psi]) \sqrt{\frac{p}{1-p}} \right)^2 \right] \\ &= E \left[\text{Var} \left((m_1 - \gamma'_1 h) \sqrt{\frac{1-p}{p}} + (m_0 - \gamma'_0 h) \sqrt{\frac{p}{1-p}} \middle| \psi \right) \right] \\ &= E \left[\text{Var} \left(b - \left(\gamma_1 \sqrt{\frac{1-p}{p}} + \gamma_0 \sqrt{\frac{p}{1-p}} \right)' h \middle| \psi \right) \right] = \underset{\gamma \in \mathbb{R}^{d_h}}{\text{argmin}} E[\text{Var}(b - \gamma' h|\psi)]. \end{aligned}$$

The final line by characterization of γ_d above and linearity of $Z \rightarrow \underset{\gamma}{\text{argmin}} E[\text{Var}(Z - \gamma' h|\psi)]$. Finally note that

$$\begin{aligned} \text{Var}(W|X, D) &= E \left[\left(\frac{D_i \epsilon_i^1}{p} - \frac{(1 - D_i) \epsilon_i^0}{1-p} \right)^2 \middle| X, D \right] = E \left[\frac{D_i (\epsilon_i^1)^2}{p^2} + \frac{(1 - D_i) (\epsilon_i^0)^2}{(1-p)^2} \middle| X_i, D_i \right] \\ &= \frac{D_i \sigma_1^2(X_i)}{p^2} + \frac{(1 - D_i) \sigma_0^2(X_i)}{(1-p)^2}. \end{aligned}$$

Then $E[\text{Var}(W|X, D)] = E \left[\frac{\sigma_1^2(X_i)}{p} + \frac{\sigma_0^2(X_i)}{1-p} \right]$. Comparing with Equation 3.1 finishes the proof. \square

A.3 Proofs for Section 3.3

Proof of Theorem 3.10. By Theorem 3.2, the middle term of the asymptotic variance is $E[\text{Var}(b - \beta' h|\psi)]$ with $\beta = \text{Var}(h)^{-1} \text{Cov}(h, b)$. This is the OLS coefficient from the regression $b = a + \beta' h + e = a + \alpha' z + \gamma' w + e$ with $E[e(1, w, z)] = 0$ and $h = (w, z)$. Denote $\tilde{b} = b - E[b]$ and similarly for \tilde{w}, \tilde{z} . By Frisch-Waugh we have $\tilde{b} = \alpha' \tilde{z} + \gamma' \tilde{w} + e$. Let $\tilde{w} = \tilde{w} - (E[\tilde{z}\tilde{z}']^{-1} E[\tilde{z}\tilde{w}'])' \tilde{z}$. Then again by Frisch-Waugh the coefficient of interest is $\gamma = E[\tilde{w}\tilde{w}']^{-1} E[\tilde{w}\tilde{b}]$. Next, we characterize this coefficient.

By assumption, $E[w|\psi] = c + \Lambda z$. De-meaning both sides gives $E[\tilde{w}|\psi] = \Lambda \tilde{z}$. Write $\tilde{u} = \tilde{w} - E[\tilde{w}|\psi] = \tilde{w} - \Lambda \tilde{z}$ with $E[\tilde{u}|\psi] = 0$. Then we have

$$E[\tilde{z}\tilde{w}'] = E[\tilde{z}(\tilde{w} - E[\tilde{w}|\psi] + E[\tilde{w}|\psi])'] = E[\tilde{z}\tilde{u}'] + E[\tilde{z}\tilde{z}'\Lambda'] = E[\tilde{z}\tilde{z}']\Lambda'.$$

Then $\check{w} = \tilde{w} - (E[\tilde{z}\tilde{z}']^{-1}E[\tilde{z}\tilde{z}']\Lambda')'\tilde{z} = \tilde{w} - \Lambda\tilde{z} = \tilde{u}$. We have now shown that

$$\gamma = E[\tilde{u}\tilde{u}']^{-1}E[\tilde{u}b] = E[\text{Var}(\tilde{w}|\psi)]^{-1}E[\text{Cov}(\tilde{w}, b|\psi)] = E[\text{Var}(w|\psi)]^{-1}E[\text{Cov}(w, b|\psi)].$$

In particular, the coefficient $\beta = (\alpha, \gamma)$ is optimal

$$\begin{aligned} E[\text{Var}(b - \beta'h|\psi)] &= E[\text{Var}(b - \gamma'w|\psi)] = \min_{\tilde{\gamma}} E[\text{Var}(b - \tilde{\gamma}'w|\psi)] \\ &= \min_{\tilde{\alpha}, \tilde{\gamma}} E[\text{Var}(b - \tilde{\alpha}'z - \tilde{\gamma}'w|\psi)] = \min_{\beta} E[\text{Var}(b - \beta'h|\psi)]. \end{aligned}$$

The second equality since $z = z(\psi)$. This completes the proof. \square

A.4 Proofs for Section 3.4

Proof of Theorem 3.16. By Frisch-Waugh $\check{Y}_i = \hat{\theta}_{FE}\check{D}_i + \hat{\gamma}'_{FE}\check{h}_i + e_i$ with $\check{D}_i = D_i - k^{-1}\sum_{j \in g(i)} D_j = D_i - p$ and $\check{h}_i = h_i - k^{-1}\sum_{j \in g(i)} h_j$. Applying Frisch-Waugh again, the estimator is $\hat{\theta}_{FE} = E_n[(\bar{D}_i)^2]^{-1}E_n[\bar{D}_i Y_i]$ with $\bar{D}_i = (D_i - p) - (E_n[\check{h}_i\check{h}_i']^{-1}E_n[\check{h}_i(D_i - p)])'\check{h}_i$. By Lemma A.6 we have $E_n[\check{h}_i\check{h}_i'] \xrightarrow{p} \frac{k-1}{k}E[\text{Var}(h|\psi)] \succ 0$, so that $E_n[\check{h}_i\check{h}_i']^{-1} = O_p(1)$. By the definition of stratification, $E_n[(D_i - p)\mathbf{1}(g(i) = g)] = 0$ for all g . Then defining $\bar{h}_g \equiv k^{-1}\sum_{j \in g} h_j$ we may write

$$\begin{aligned} E_n[(D_i - p)\check{h}_i] &= E_n\left[(D_i - p)\left(h_i - \sum_g \mathbf{1}(g(i) = g)\bar{h}_g\right)\right] \\ &= E_n[(D_i - p)h_i] = O_p(n^{-1/2}). \end{aligned}$$

The final equality since $E[|h|_2^2] < \infty$ and by Lemma 9.20 of Cytrynbaum (2022). Then apparently $E_n[(\bar{D}_i)^2] = E_n[(D_i - p)^2] + O_p(n^{-1})$ so that $E_n[(\bar{D}_i)^2]^{-1} = (p - p^2)^{-1} + O_p(n^{-1})$. Then we have shown that

$$\begin{aligned} \hat{\theta}_{FE} &= \frac{E_n[(D_i - p)Y_i]}{p - p^2} - \frac{E_n[\check{h}_i(D_i - p)]'E_n[\check{h}_i\check{h}_i']^{-1}E_n[\check{h}_i Y_i]}{p - p^2} + O_p(n^{-1}) \\ &= \hat{\theta} - (\bar{h}_1 - \bar{h}_0)'E_n[\check{h}_i\check{h}_i']^{-1}E_n[\check{h}_i Y_i] + O_p(n^{-1}). \end{aligned}$$

By Lemma A.6 we have

$$\begin{aligned} E_n[\check{h}_i Y_i] &= E_n[\check{h}_i D_i Y_i(1)] + E_n[\check{h}_i(1 - D_i)Y_i(0)] \\ &= \frac{p(k-1)}{k}E[\text{Cov}(h, Y(1)|\psi)] + \frac{(1-p)(k-1)}{k}E[\text{Cov}(h, Y(0)|\psi)] + o_p(1) \\ &= \frac{(k-1)}{k}E[\text{Cov}(h, p \cdot m_1(X) + (1-p) \cdot m_0(X)|\psi)] + o_p(1). \end{aligned}$$

Putting this together, we have $c_p^{-1} E_n[\check{h}_i \check{h}_i']^{-1} E_n[\check{h}_i Y_i] \xrightarrow{p} E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, f|\psi)] = \arg\min_{\gamma} E[\text{Var}(f - \gamma' h|\psi)]$. Similar reasoning as above shows that $\hat{\gamma}_{FE} = E_n[\check{h}_i \check{h}_i']^{-1} E_n[\check{h}_i Y_i] + O_p(n^{-1/2})$. Then we have representation $\hat{\theta}_{FE} = \hat{\theta} - (c_p^{-1} \hat{\gamma}_{FE})'(\bar{h}_1 - \bar{h}_0)c_p + o_p(n^{-1/2})$. The efficiency claims follow identically to the reasoning in Theorem A.1. This finishes the proof. \square

Proof of Theorem 3.22 (Part I). Consider the regression $Y_i \sim D_i(1, \check{h}_i) + (1 - D_i)(1, \check{h}_i)$ with $\check{h}_i = h_i - k^{-1} \sum_{j \in g(i)} h_j$. Denote the OLS coefficients by $(\hat{c}_1, \hat{\alpha}_1)$ and $(\hat{c}_0, \hat{\alpha}_0)$ respectively. By Frisch-Waugh, the coefficient $(\hat{c}_1, \hat{\alpha}_1)$ is given by the equation $Y_i = \hat{c}_1 + \hat{\alpha}_1' \check{h}_i + e_i$ with $E_n[e_i(1, \check{h}_i)|D_i = 1] = 0$. By the usual OLS formula $\hat{\alpha}_1 = \text{Var}_n(\check{h}_i|D_i = 1)^{-1} \text{Cov}_n(\check{h}_i, Y_i|D_i = 1)$. Observe that by definition of stratification

$$P_n(g(i) = g|D_i = 1) = \frac{P_n(D_i = 1|g(i) = g)P_n(g(i) = g)}{P_n(D_i = 1)} = P_n(g(i) = g).$$

This shows that $E_n[E_n[h_i|g(i)]|D_i = 1] = E_n[E_n[h_i|g(i)]] = E_n[h_i]$, so that $E_n[\check{h}_i|D_i = 1] = E_n[h_i|D_i = 1] - E_n[h_i] = E_n[p^{-1}(D_i - p)h_i] = O_p(n^{-1/2})$ as above. Then we have

$$\begin{aligned} \text{Var}_n(\check{h}_i|D_i = 1) &= E_n[\check{h}_i \check{h}_i'|D_i = 1] - E_n[\check{h}_i|D_i = 1]E_n[\check{h}_i|D_i = 1]' \\ &= E_n[\check{h}_i \check{h}_i'|D_i = 1] + O_p(n^{-1}). \end{aligned}$$

Similarly, $\text{Cov}_n(\check{h}_i, Y_i|D_i = 1) = E_n[\check{h}_i Y_i|D_i = 1] + O_p(n^{-1/2})$. Then we have

$$\begin{aligned} \hat{\alpha}_1 &= E_n[\check{h}_i \check{h}_i'|D_i = 1]^{-1} E_n[\check{h}_i Y_i|D_i = 1] + O_p(n^{-1/2}) \\ &= \frac{k-1}{k} \frac{k}{k-1} E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, Y(1)|\psi)] + o_p(1) \end{aligned}$$

by Lemma A.6. Similarly, $\hat{\alpha}_0 = E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, Y(0)|\psi)] + o_p(1)$. By the usual OLS formula, the constant term \hat{c}_1 has form $\hat{c}_1 = E_n[Y_i|D_i = 1] - \hat{\alpha}_1' E_n[\check{h}_i|D_i = 1]$ and similarly for \hat{c}_0 . By change of variables used in the proof of Theorem 3.2, our estimator

$$\begin{aligned} \tilde{\theta} &= \hat{c}_1 - \hat{c}_0 = E_n[Y_i|D_i = 1] - E_n[Y_i|D_i = 0] - \left[\hat{\alpha}_1' E_n[\check{h}_i|D_i = 1] - \hat{\alpha}_0' E_n[\check{h}_i|D_i = 0] \right] \\ &= \hat{\theta} - E_n \left[\frac{\hat{\alpha}_1' h_i (D_i - p)}{p} + \frac{\hat{\alpha}_0' h_i (D_i - p)}{1 - p} \right] \\ &= \hat{\theta} - \left[\hat{\alpha}_1 \sqrt{\frac{1-p}{p}} + \hat{\alpha}_0 \sqrt{\frac{p}{1-p}} \right]' E_n \left[\frac{h_i (D_i - p)}{\sqrt{p - p^2}} \right]. \end{aligned}$$

Define $\hat{\gamma} = \hat{\alpha}_1 \sqrt{\frac{1-p}{p}} + \hat{\alpha}_0 \sqrt{\frac{p}{1-p}}$. Then by work above

$$\begin{aligned}\hat{\gamma} &= E[\text{Var}(h|\psi)]^{-1} E \left[\text{Cov} \left(h, \sqrt{\frac{1-p}{p}} Y(1) + \sqrt{\frac{p}{1-p}} Y(0) | \psi \right) \right] + o_p(1) \\ &= E[\text{Var}(h|\psi)]^{-1} E [\text{Cov}(h, b|\psi)] + o_p(1) = \underset{\gamma}{\text{argmin}} E[\text{Var}(b - \gamma' h|\psi)] + o_p(1).\end{aligned}$$

Then applying Theorem 3.4 completes the proof. As before, $\hat{\alpha}_1 = \hat{a}_1 + \hat{a}_0$ and $\hat{\alpha}_0 = \hat{a}_0$ by change of variables. \square

Proof of Theorem 3.22 (Part II). Next, we analyze the group OLS estimator. By Theorem 3.4, it suffices to show that $\hat{\gamma}_G = \text{Var}_g(h_g)^{-1} \text{Cov}_g(h_g, y_g) = c_p \cdot E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, b|\psi)] + o_p(1)$. For the first term, note that $E_g[h_g] = O_p(n^{-1/2})$ as above, so that $\text{Var}(h_g) = E_g[h_g h_g'] - E_g[h_g] E_g[h_g]' = E_g[h_g h_g'] + O_p(n^{-1})$. Similarly, $\text{Cov}_g(h_g, y_g) = E_g[h_g y_g] + O_p(n^{-1/2})$. Applying Lemma A.5 to each component of $h_i h_i'$ shows that

$$E_g[h_g h_g'] = \frac{k}{n} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} \frac{h_i'(D_i - p)}{p - p^2} \right) = \frac{k E[\text{Var}(h|\psi)]}{a(k - a)} + o_p(1).$$

Using the fundamental expansion of the IPW estimator, we have

$$\begin{aligned}E_g[y_g h_g] &= \frac{k}{n} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} \frac{Y_i(D_i - p)}{p - p^2} \right) \\ &= \frac{k}{n} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} c(X_i) + \frac{b_i(D_i - p)}{\sqrt{p - p^2}} + \frac{D_i \epsilon_i^1}{p} - \frac{(1 - D_i) \epsilon_i^0}{1 - p} \right) \\ &\equiv A_n + B_n + C_n.\end{aligned}$$

First, note that $A_n = O_p(n^{-1/2})$ and $C_n = O_p(n^{-1/2})$ by Lemma A.5. Moreover, we have

$$\begin{aligned}B_n &= \frac{k}{n} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} \frac{b_i(D_i - p)}{\sqrt{p - p^2}} \right) \\ &= \frac{k \sqrt{p - p^2}}{a(k - a)} E[\text{Cov}(h, b|\psi)] + o_p(1) = \frac{E[\text{Cov}(h, b|\psi)]}{\sqrt{a(k - a)}} + o_p(1).\end{aligned}$$

Putting this together, by continuous mapping we have

$$\begin{aligned}\hat{\gamma}_G &= \text{Var}_g(h_g)^{-1} \text{Cov}_g(h_g, y_g) = \frac{a(k - a)}{k} \frac{1}{\sqrt{a(k - a)}} E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, b|\psi)] + o_p(1) \\ &= \sqrt{p - p^2} E[\text{Var}(h|\psi)]^{-1} E[\text{Cov}(h, b|\psi)] + o_p(1).\end{aligned}$$

Applying Theorem 3.4 completes the proof. \square

Proof of Theorem 3.22 (Part III). Finally, we analyze the ToM estimator. Consider the sample moment $E_n[\check{h}_i Y_i^w]$. Applying Lemma A.6 gives

$$\begin{aligned} E_n[\check{h}_i Y_i^w] &= E_n[\check{h}_i D_i Y_i] \frac{(1-p)^{1/2}}{p^{3/2}} + E_n[\check{h}_i (1-D_i) Y_i] \frac{p^{1/2}}{(1-p)^{3/2}} \\ &= \frac{(1-p)^{1/2}}{p^{3/2}} \frac{p(k-1)}{k} E[\text{Cov}(h, m_1 | \psi)] \\ &\quad + \frac{p^{1/2}}{(1-p)^{3/2}} \frac{(1-p)(k-1)}{k} E[\text{Cov}(h, m_0 | \psi)] + o_p(1) \\ &= \frac{k-1}{k} \frac{(1-p)^{1/2}}{p^{1/2}} E[\text{Cov}(h, m_1 | \psi)] + \frac{p^{1/2}}{(1-p)^{1/2}} E[\text{Cov}(h, m_0 | \psi)] + o_p(1). \end{aligned}$$

The final line is $\frac{k-1}{k} E[\text{Cov}(h, b | \psi)] + o_p(1)$. Then again by Lemma A.6 and continuous mapping we obtain

$$\hat{\gamma}_{TM} = E_n[\check{h}_i \check{h}_i']^{-1} E_n[\check{h}_i Y_i^w] = \frac{k-1}{k} \frac{k}{k-1} E[\text{Var}(h | \psi)]^{-1} E[\text{Cov}(h, b | \psi)] + o_p(1).$$

Applying Theorem 3.4 completes the proof. \square

Proof of Theorem 3.23. First, consider the fixed effects estimator with

$$Y_i = \hat{c} + \hat{\tau}_{FE} D_i + \hat{\gamma}'_{FE} \check{h}_i + \hat{\gamma}'_z z_i + e_{i,1}.$$

Note that $\bar{D}_i = D_i - p$ and $\check{h}_i - E_n[\check{h}_i] = \check{h}_i - (E_n[h_i] - E_n[E_n[h_i | g_i = g]]) = \check{h}_i$. By Frisch-Waugh, we may instead study $Y_i = \hat{\tau}_{FE} (D_i - p) + \hat{\gamma}'_{FE} \check{h}_i + \hat{\gamma}'_z \tilde{z}_i + e_{i,2}$. Let $\check{w}_i = (\check{h}_i, \tilde{z}_i)$ and $w_i = (h_i, z_i)$. Then by work in Theorem 3.16, $\hat{\tau}_{FE} = E_n[(\bar{D}_i)^2]^{-1} E_n[\bar{D}_i Y_i]$ with

$$\bar{D}_i = (D_i - p) - (E_n[\check{w}_i \check{w}_i']^{-1} E_n[\check{w}_i (D_i - p)])' \check{w}_i.$$

Previous work suffices to show that $E_n[\check{w}_i (D_i - p)] = O_p(n^{-1/2})$. Then as before, $E_n[(\bar{D}_i)^2]^{-1} = (p - p^2)^{-1} + O_p(n^{-1})$. Then we have

$$\begin{aligned} \hat{\tau}_{FE} &= \hat{\theta} - (p - p^2)^{-1} (E_n[\check{w}_i \check{w}_i']^{-1} E_n[\check{w}_i (D_i - p)])' E_n[\check{w}_i Y_i] \\ &= \hat{\theta} - (\bar{w}_1 - \bar{w}_0)' E_n[\check{w}_i \check{w}_i']^{-1} E_n[\check{w}_i Y_i]. \end{aligned}$$

The second equality uses $E_n[\check{h}_i (D_i - p)] = E_n[h_i (D_i - p)]$ and $E_n[\tilde{z}_i (D_i - p)] = E_n[z_i (D_i - p)]$ as noted before. This shows the claim about estimator representation.

Next, consider $\hat{\gamma}_{FE}$. Define $g_i = (D_i - p, \tilde{z}_i)$. Let $\bar{h}_i = \check{h}_i - (E_n[g_i g_i']^{-1} E_n[g_i \check{h}_i])' g_i$. Then by Frisch-Waugh $\hat{\gamma}_{FE} = E_n[\bar{h}_i \bar{h}_i']^{-1} E_n[\bar{h}_i Y_i]$. Consider $E_n[\tilde{z}_i \check{h}_i] = E_n[z_i \check{h}_i]$ since $E_n[\check{h}_i] = 0$. We have $E_n[z_i \check{h}_i] = o_p(1)$ by Lemma A.6. Then by previous work $E_n[g_i \check{h}_i] = o_p(1)$. Then $E_n[\bar{h}_i \bar{h}_i'] = E_n[\check{h}_i \check{h}_i'] + o_p(1)$. Similarly, $E_n[\bar{h}_i Y_i] = E_n[\check{h}_i Y_i] + o_p(1)$. Then by continuous

mapping $\hat{\gamma}_{FE} = E_n[\bar{h}_i \bar{h}_i']^{-1} E_n[\bar{h}_i Y_i] = E_n[\check{h}_i \check{h}_i']^{-1} E_n[\check{h}_i Y_i] + o_p(1)$, the coefficient from the regression without strata variables z_i included shown in Theorem 3.16.

Consider $\hat{\gamma}_z$. Let $q_i = (D_i - p, \check{h}_i)$ and $\bar{z}_i = \tilde{z}_i - (E_n[q_i q_i']^{-1} E_n[q_i \tilde{z}_i])' q_i$. The last paragraph shows that $E_n[q_i \tilde{z}_i] = o_p(1)$. Then by similar reasoning as above and Frisch-Waugh

$$\begin{aligned} \hat{\gamma}_z &= E_n[\bar{z}_i \bar{z}_i']^{-1} E_n[\bar{z}_i Y_i] = E_n[\tilde{z}_i \tilde{z}_i']^{-1} E_n[\tilde{z}_i Y_i] + o_p(1) \\ &= \text{Var}(z)^{-1} \text{Cov}(z, pm_1 + (1-p)m_0) + o_p(1) = c_p \text{Var}(z)^{-1} \text{Cov}(z, f) + o_p(1). \end{aligned}$$

Our work so far also shows that $E_n[\check{w}_i \check{w}_i'] \xrightarrow{p} \text{Diag}(E_n[\check{h}_i \check{h}_i'], E_n[\tilde{z}_i \tilde{z}_i'])$. Then it's easy to see from our expression for $\hat{\tau}_{FE}$ that we may identify $\hat{\gamma}_z = \hat{\alpha}_1 + o_p(1)$. This finishes the proof for $\hat{\tau}_{FE}$. The proof for the stratification variable adjusted Lin estimator $\hat{\tau}_{PL}$ is similar and is omitted for brevity.

Next, consider the augmented group OLS estimator $\hat{\tau}_G$.

$$\begin{aligned} \text{Cov}_n(z_i, \eta_i) &= \text{Cov}\left(z_i, \frac{(1-p)D_i Y_i}{p} + \frac{p(1-D_i)Y_i}{1-p}\right) \\ &= \text{Cov}(z_i, (1-p)m_1 + pm_0) + o_p(1). \end{aligned}$$

Then $c_p^{-1} \text{Cov}_n(z_i, \eta_i - \hat{\gamma}_G' h_i) = \text{Cov}(z, b - c_p^{-1} h' \gamma_G) + o_p(1)$ by continuous mapping, so that $\hat{\alpha}_3 = \text{Var}(z)^{-1} \text{Cov}(z, b - c_p^{-1} h' \gamma_G) + o_p(1) = \arg\min_{\gamma} \text{Var}(b - c_p^{-1} h' \gamma - \gamma' z) + o_p(1)$. This completes the proof. \square

A.5 Proofs for Section 4

Proof of Theorem 4.2. By Theorem 3.4 we have

$$\begin{aligned} V(\gamma) &= \text{Var}(c(X)) + E\left[\text{Var}(b - \gamma' h | \psi)\right] + E\left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p}\right] \\ &= \text{Var}(c(X)) + E\left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p}\right] + E[\text{Var}(b | \psi)] \\ &\quad - 2\gamma' E[\text{Cov}(h, b | \psi)] + \gamma' E[\text{Var}(h | \psi)] \gamma. \end{aligned}$$

As mentioned in the text, Theorem 5.3 of [Cytrynbaum \(2022\)](#) shows that $\hat{V} \xrightarrow{p} \text{Var}(c(X)) + E[\text{Var}(b | \psi)] + E\left[\frac{\sigma_1^2(X)}{p} + \frac{\sigma_0^2(X)}{1-p}\right]$. Then it suffices to show that $\hat{V}_b \xrightarrow{p} E[\text{Cov}(h, b | \psi)]$ and

$\widehat{V}_h \xrightarrow{p} E[\text{Var}(h|\psi)]$. To see this, note that by Lemma A.6

$$\begin{aligned}
\widehat{V}_b &= \frac{k}{k-1} E_n[\check{h}_i Y_i^{TM}] = \frac{k}{k-1} \left[\frac{(1-p)^{1/2}}{p^{3/2}} E_n[D_i \check{h}_i Y_i] + \frac{p^{1/2}}{(1-p)^{3/2}} E_n[(1-D_i) \check{h}_i Y_i] \right] \\
&= \frac{k}{p(k-1)} \sqrt{\frac{1-p}{p}} E_n[D_i \check{h}_i Y_i] + \frac{k}{(1-p)(k-1)} \sqrt{\frac{p}{1-p}} E_n[(1-D_i) \check{h}_i Y_i] \\
&= \frac{k}{p(k-1)} \sqrt{\frac{1-p}{p}} E_n[D_i \check{h}_i Y_i] + \frac{k}{(1-p)(k-1)} \sqrt{\frac{p}{1-p}} E_n[(1-D_i) \check{h}_i Y_i] \\
&= E \left[\text{Cov} \left(h, \sqrt{\frac{1-p}{p}} m_1 + \sqrt{\frac{p}{1-p}} m_0 | \psi \right) \right] + o_p(1) = E[\text{Cov}(h, b | \psi)] + o_p(1).
\end{aligned}$$

By the same lemma, we have $\frac{k}{k-1} E_n[\check{h}_i \check{h}_i'] = E[\text{Var}(h|\psi)] + o_p(1)$. The conclusion then follows by continuous mapping, using $\widehat{\gamma} \xrightarrow{p} \gamma$.

Alternatively, consider defining $\widehat{V}_b = k c_p \cdot E_g[y_g h_g]$ and $\widehat{V}_h = k c_p^2 \cdot E_g[h_g h_g']$. In this case, by Lemma A.5 and the proof of Theorem 3.22 we have

$$\sqrt{a(k-a)} \cdot E_g[y_g h_g] \xrightarrow{p} E[\text{Cov}(h, b | \psi)] \quad \frac{a(k-a)}{k} \cdot E_g[h_g h_g'] \xrightarrow{p} E[\text{Var}(h | \psi)]$$

Since $\widehat{\gamma} \xrightarrow{p} \gamma$, the conclusion follows by continuous mapping. \square

A.6 Technical Lemmas

Lemma A.3 (Conditional Convergence). *Let $(\mathcal{G}_n)_{n \geq 1}$ and $(A_n)_{n \geq 1}$ a sequence of σ -algebras and RV's. Define conditional convergence*

$$\begin{aligned}
A_n = o_{p, \mathcal{G}_n}(1) &\iff P(|A_n| > \epsilon | \mathcal{G}_n) = o_p(1) \quad \forall \epsilon > 0. \\
A_n = O_{p, \mathcal{G}_n}(1) &\iff P(|A_n| > s_n | \mathcal{G}_n) = o_p(1) \quad \forall s_n \rightarrow \infty.
\end{aligned}$$

Then the following results hold

- (i) $A_n = o_p(1) \iff A_n = o_{p, \mathcal{G}_n}(1)$ and $A_n = O_p(1) \iff A_n = O_{p, \mathcal{G}_n}(1)$.
- (ii) $E[|A_n| | \mathcal{G}_n] = o_p(1)/O_p(1) \implies A_n = o_p(1)/O_p(1)$.
- (iii) $\text{Var}(A_n | \mathcal{G}_n) = o_p(c_n^2)/O_p(c_n^2) \implies A_n - E[A_n | \mathcal{G}_n] = o_p(c_n)/O_p(c_n)$ for all positive $(c_n)_n$.
- (iv) If $(A_n)_{n \geq 1}$ has $A_n \leq \bar{A} < \infty$ \mathcal{G}_n -a.s. $\forall n$ and $A_n = o_p(1) \implies E[|A_n| | \mathcal{G}_n] = o_p(1)$.

Proof. (i) Consider that for any $\epsilon > 0$

$$P(|A_n| > \epsilon) = E[\mathbf{1}(|A_n| > \epsilon)] = E[E[\mathbf{1}(|A_n| > \epsilon) | \mathcal{G}_n]] = E[P(|A_n| > \epsilon | \mathcal{G}_n)].$$

If $A_n = o_p(1)$, then $E[P(|A_n| > \epsilon | \mathcal{G}_n)] = o(1)$, so $P(|A_n| > \epsilon | \mathcal{G}_n) = o_p(1)$ by Markov inequality. Conversely, if $P(|A_n| > \epsilon | \mathcal{G}_n) = o_p(1)$, then $E[P(|A_n| > \epsilon | \mathcal{G}_n)] = o(1)$ since $(P(|A_n| > \epsilon | \mathcal{G}_n))_{n \geq 1}$ is uniformly bounded, hence UI. Then $P(|A_n| > \epsilon) = o(1)$. The second equivalence follows directly from the first. (ii) follows from (i) and conditional Markov inequality. (iii) is an application of (ii). For (iv), note that for any $\epsilon > 0$

$$E[|A_n| | \mathcal{G}_n] \leq \epsilon + E[|A_n| \mathbf{1}(|A_n| > \epsilon) | \mathcal{G}_n] \leq \epsilon + \bar{A} P(|A_n| > \epsilon | \mathcal{G}_n) = \epsilon + o_p(1).$$

The equality is by (i) and our assumption. Since $\epsilon > 0$ was arbitrary $E[|A_n| | \mathcal{G}_n] = o_p(1)$. \square

Lemma A.4. *Let $(a_i), (b_i), (c_i)$ be positive scalar arrays for $i \in [n]$. Then the inequality $\sum_{\substack{i,j,s \in g \\ i \neq j, j \neq s}} a_i b_j c_s \leq 3 \sum_i (a_i^3 + b_i^3 + c_i^3)$.*

Proof. Note that by AM-GM inequality and Jensen, for non-negative x, y, z we have $xyz \leq ((1/3)(x + y + z))^3 \leq (1/3)(x^3 + y^3 + z^3)$. Applying this gives

$$\begin{aligned} \sum_{\substack{i,j,s \in g \\ i \neq j, j \neq s}} a_i b_j c_s &\leq \left(\sum_i a_i \right) \left(\sum_j b_j \right) \left(\sum_s c_s \right) \\ &\leq (1/3) \left[\left(\sum_i a_i \right)^3 + \left(\sum_j b_j \right)^3 + \left(\sum_s c_s \right)^3 \right] \leq 3 \sum_i (a_i^3 + b_i^3 + c_i^3) \end{aligned}$$

\square

Lemma A.5 (Group OLS). *Let $h, w : \mathcal{X} \rightarrow \mathbb{R}$. Denote $h_i = h(X_i)$ and $w_i = w(X_i)$ and suppose $E[h_i | \psi_i = \psi]$ and $E[w_i | \psi_i = \psi]$ are Lipschitz continuous. Suppose $E[h_i^4] < \infty$ and $E[w_i^4] < \infty$. Let $\epsilon_i^d = Y_i(d) - m_d(X_i)$ for $d \in \{0, 1\}$. Then we have*

$$\begin{aligned} A_n &= n^{-1} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} \frac{w_i(D_i - p)}{p - p^2} \right) = \frac{E[\text{Cov}(h, w | \psi)]}{a(k - a)} + o_p(1). \\ B_n &= n^{-1} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} w_i \right) = O_p(n^{-1/2}). \\ C_n &= \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} \frac{D_i \epsilon_i^1}{p} - \frac{(1 - D_i) \epsilon_i^0}{1 - p} \right) = O_p(n^{-1/2}). \end{aligned}$$

Proof. Define $\bar{h}_{g1} = a^{-1} \sum_{i \in g} h_i \mathbf{1}(D_i = 1)$, $\bar{h}_{g0} = (k - a)^{-1} \sum_{i \in g} h_i \mathbf{1}(D_i = 0)$, and $\bar{w}_g = k^{-1} \sum_{i \in g} w_i$. Recall that $g \in \sigma(\psi_{1:n}, \pi_n)$ for each g and $D_{1:n} \in \sigma(\psi_{1:n}, \pi_n, \tau)$ with exogenous randomization variable $\tau \perp\!\!\!\perp (X_{1:n}, Y(d)_{1:n} : d = 0, 1)$. Notice that $k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} = \bar{h}_{g1} - \bar{h}_{g0}$. First consider B_n . By Lemma 9.19 of [Cytrynbaum \(2022\)](#),

we have $E[B_n|X_{1:n}, \pi_n] = 0$. Next, we have

$$\begin{aligned} E[B_n^2|X_{1:n}, \pi_n] &= E \left[n^{-2} \sum_{g, g'} \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g'} \frac{h_i(D_i - p)}{p - p^2} \right) \bar{w}_g \bar{w}_{g'} \middle| X_{1:n}, \pi_n \right] \\ &= E \left[n^{-2} \sum_g \left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right)^2 \bar{w}_g^2 \middle| X_{1:n}, \pi_n \right]. \end{aligned}$$

The second equality follows by Lemma 9.19 of [Cytrynbaum \(2022\)](#), since $\text{Cov}(D_i, D_j|X_{1:n}, \pi_n) = 0$ if i, j are in different groups. We may calculate

$$\begin{aligned} E \left[\left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right)^2 \middle| X_{1:n}, \pi_n \right] &= \frac{1}{k^2(p - p^2)^2} \sum_{i \in g} h_i^2 \text{Var}(D_i|X_{1:n}, \pi_n) \\ &+ \frac{1}{k^2(p - p^2)^2} \sum_{i \neq j \in g} h_i h_j \text{Cov}(D_i, D_j|X_{1:n}, \pi_n) = \frac{1}{k^2(p - p^2)^2} \left[\sum_{i \in g} h_i^2 - (k - 1)^{-1} \sum_{i \neq j \in g} h_i h_j \right]. \end{aligned}$$

Note that $\sum_{i \neq j \in g} |h_i h_j| \leq \left(\sum_{i \in g} |h_i| \right)^2 = k^2 \left(k^{-1} \sum_{i \in g} |h_i| \right)^2 \leq k \sum_{i \in g} |h_i|^2$. The final inequality by Jensen. Then by triangle inequality, a simple calculation gives

$$\frac{1}{k^2} \left| \sum_{i \in g} h_i^2 - (k - 1)^{-1} \sum_{i \neq j \in g} h_i h_j \right| \leq \frac{1}{k^2} \frac{2k - 1}{k - 1} \sum_{i \in g} h_i^2 \leq 3k^{-2} \sum_{i \in g} h_i^2.$$

Then continuing from above

$$\begin{aligned} E[B_n^2|X_{1:n}, \pi_n] &\lesssim k^{-2} n^{-2} \sum_g \left(\sum_{i \in g} h_i^2 \right) \left(\sum_{i \in g} w_i \right)^2 \leq \frac{1}{kn^2} \sum_g \left(\sum_{i \in g} h_i^2 \right) \left(\sum_{i \in g} w_i^2 \right) \\ &\leq \frac{1}{2kn^2} \sum_g \left[\left(\sum_{i \in g} h_i^2 \right)^2 + \left(\sum_{i \in g} w_i^2 \right)^2 \right] = (2n)^{-1} E_n[h_i^4 + w_i^4] = O_p(n^{-1}). \end{aligned}$$

The second inequality follows from Jensen, and the third by Young's inequality. The first equality by Jensen and final equality by our moment assumption. So by Lemma 9.16 in [Cytrynbaum \(2022\)](#), $B_n = O_p(n^{-1/2})$.

Next, consider A_n . Using the within-group covariances above, we compute

$$\begin{aligned}
E[A_n|X_{1:n}, \pi_n] &= \frac{1}{nk^2(p-p^2)^2} \sum_g \sum_{i,j \in g} \text{Cov}(D_i, D_j|X_{1:n}, \pi_n) h_i w_j \\
&= \frac{1}{nk^2(p-p^2)^2} \sum_g \left(\sum_{i \in g} (p-p^2) h_i w_i - \sum_{i \neq j \in g} \frac{a(k-a)}{k^2(k-1)} h_i w_j \right) \\
&= \frac{1}{k^2(p-p^2)} \left(E_n[h_i w_i] - \frac{1}{n(k-1)} \sum_g \sum_{i \neq j \in g} h_i w_j \right).
\end{aligned}$$

Define $u_i = w_i - E[w_i|\psi_i]$ and $v_i = h_i - E[h_i|\psi_i]$. Consider the second term. We have

$$n^{-1} \sum_g \sum_{i \neq j \in g} h_i w_j = n^{-1} \sum_g \sum_{i \neq j \in g} (E[h_i|\psi_i] + v_i)(E[w_j|\psi_j] + u_j) \equiv \sum_{l=1}^4 A_{n,l}.$$

First, note that for any scalars $a_i b_j + a_j b_i = a_i b_i + a_j b_j + (a_i - a_j)(b_j - b_i)$. Then we have

$$\begin{aligned}
A_{n,1} &\equiv n^{-1} \sum_g \sum_{i \neq j \in g} E[h_i|\psi_i] E[w_j|\psi_j] = n^{-1} \sum_g \sum_{i < j \in g} E[h_i|\psi_i] E[w_j|\psi_j] + E[h_j|\psi_j] E[w_i|\psi_i] \\
&= n^{-1} \sum_g \sum_{i < j \in g} E[h_i|\psi_i] E[w_i|\psi_i] + E[h_j|\psi_j] E[w_j|\psi_j] \\
&+ n^{-1} \sum_g \sum_{i < j \in g} (E[h_i|\psi_i] - E[h_j|\psi_j])(E[w_j|\psi_j] - E[w_i|\psi_i]) \equiv B_{n,1} + C_{n,1}.
\end{aligned}$$

By counting ordered tuples (i, j) , it's easy to see that

$$\begin{aligned}
B_{n,1} &= n^{-1} \sum_g \sum_{i \in g} (k-1) E[h_i|\psi_i] E[w_i|\psi_i] = (k-1) E_n[E[h_i|\psi_i] E[w_i|\psi_i]] \\
&= (k-1) E[E[h_i|\psi_i] E[w_i|\psi_i]] + o_p(1) = (k-1) (E[h_i w_i] - E[v_i u_i]) + o_p(1).
\end{aligned}$$

For the second term, by our Lipschitz assumptions we have $|C_{n,1}| \lesssim n^{-1} \sum_g \sum_{i < j \in g} |\psi_i - \psi_j|_2^2 = o_p(1)$. Next, claim that $A_{n,l} = o_p(1)$ for $l = 2, 3, 4$. For instance, we have

$$E[A_{n,2}|\psi_{1:n}, \pi_n] = n^{-1} \sum_g \sum_{i \neq j \in g} E[E[h_i|\psi_i] u_j|\psi_{1:n}, \pi_n] = 0.$$

Since $E[u_j|\psi_{1:n}, \pi_n] = E[u_j|\psi_j] = 0$ by Lemma 9.21 of [Cytrynbaum \(2022\)](#). Moreover, we have

$$E[A_{n,2}^2|\psi_{1:n}, \pi_n] = n^{-2} \sum_{g,g'} \sum_{i \neq j \in g} \sum_{s \neq t \in g'} E[h_i|\psi_i] E[h_s|\psi_s] E[u_j u_t|\psi_{1:n}, \pi_n].$$

For $j \neq t$, we have $E[u_j u_t|\psi_{1:n}, \pi_n] = E[u_j|\psi_j] E[u_t|\psi_t] = 0$ by Lemma 9.21 of the paper

above. Since the groups g are disjoint, and using $E[u_j^2|\psi_{1:n}, \pi_n] = E[u_j^2|\psi_j]$

$$\begin{aligned} E[A_{n,2}^2|\psi_{1:n}, \pi_n] &= n^{-2} \sum_g \sum_{\substack{i,j,s \in g \\ i \neq j, j \neq s}} E[h_i|\psi_i] E[h_s|\psi_s] E[u_j^2|\psi_j] \\ &\leq 3n^{-2} \sum_g \sum_{i \in g} 2E[h_i|\psi_i]^3 + E[u_i^2|\psi_i]^3 \\ &= 3n^{-1} E_n[2E[h_i|\psi_i]^3 + E[u_i^2|\psi_i]^3] = O_p(n^{-1}). \end{aligned}$$

Then we have shown $A_{n,2} = O_p(n^{-1/2})$ by Lemma 9.16 of [Cytrynbaum \(2022\)](#). The proof for $l = 3, 4$ is almost identical. Summarizing, the work above has shown that

$$\begin{aligned} E[A_n|X_{1:n}, \pi_n] &= \frac{1}{k^2(p-p^2)} \left(E_n[h_i w_i] - \frac{1}{k-1} (k-1)(E[h_i w_i] - E[v_i u_i]) \right) + o_p(1) \\ &= \frac{1}{k^2(p-p^2)} E[v_i u_i] + o_p(1) = \frac{E[\text{Cov}(h, w|\psi)]}{a(k-a)} + o_p(1). \end{aligned}$$

Next, we claim that $\text{Var}(A_n|X_{1:n}, \pi_n) = o_p(1)$. Define $\Delta_{h,g} = k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2}$, then

$$\text{Var}(A_n|X_{1:n}, \pi_n) = n^{-2} \sum_{g, g'} \text{Cov}(\Delta_{h,g} \Delta_{w,g}, \Delta_{h,g'} \Delta_{w,g'} | X_{1:n}, \pi_n).$$

Note that $\Delta_{h,g} \Delta_{w,g} \perp\!\!\!\perp \Delta_{h,g'} \Delta_{w,g'} | X_{1:n}, \pi_n$ for $g \neq g'$, since treatment assignments are (conditionally) independent between groups. Then the on-diagonal terms are

$$\begin{aligned} \text{Var}(A_n|X_{1:n}, \pi_n) &= n^{-2} \sum_g \text{Var} \left(\left(k^{-1} \sum_{i \in g} \frac{h_i(D_i - p)}{p - p^2} \right) \left(k^{-1} \sum_{i \in g} \frac{w_i(D_i - p)}{p - p^2} \right) \middle| X_{1:n}, \pi_n \right) \\ &= n^{-2} k^{-4} (p - p^2)^{-4} \sum_g \text{Var} \left(\sum_{i,j \in g} h_i w_j (D_i - p)(D_j - p) \middle| X_{1:n}, \pi_n \right). \end{aligned}$$

The inner variance term can be expanded as

$$\sum_{i,j \in g} \sum_{s,t \in g} h_i w_j h_s w_t \text{Cov} \left((D_i - p)(D_j - p), (D_s - p)(D_t - p) \middle| X_{1:n}, \pi_n \right).$$

We have $|\text{Cov}((D_i - p)(D_j - p), (D_s - p)(D_t - p) | X_{1:n}, \pi_n)| \leq 2$ since $|(D_i - p)| \leq 1$ for all $i \in [n]$. Using Lemma 9.17 in [Cytrynbaum \(2022\)](#), the previous display is bounded above by $\sum_{i,j \in g} \sum_{s,t \in g} |h_i w_j h_s w_t| \cdot 2 \leq 2k^3 \sum_{i \in g} (h_i^4 + w_i^4)$. Putting this all together,

$$\begin{aligned} \text{Var}(A_n|X_{1:n}, \pi_n) &\leq 2n^{-2} k^{-4} (p - p^2)^{-4} k^3 \sum_g \sum_{i \in g} (h_i^4 + w_i^4) \\ &= 2n^{-1} k^{-1} (p - p^2)^{-4} E_n[h_i^4 + w_i^4] = O_p(n^{-1}) \end{aligned}$$

By conditional Markov, this shows that $A_n - E[A_n|X_{1:n}, \pi_n] = O_p(n^{-1/2})$. Then we have shown that $A_n = \frac{E[\text{Cov}(h, w|\psi)]}{a(k-a)} + o_p(1)$.

Finally, we consider C_n . Note that $g, D_{1:n} \in \sigma(X_{1:n}, \pi_n, \tau)$ and $E[\epsilon_i^d|X_{1:n}, \pi_n, \tau] = E[\epsilon_i^d|X_i] = 0$ for $d = 0, 1$ by Lemma 9.21 of [Cytrynbaum \(2022\)](#), so we have $E[C_n|X_{1:n}, \pi_n, \tau] = 0$. Next, we claim that $E[C_n^2|X_{1:n}, \pi_n, \tau] = O_p(n^{-1})$. Note that C_n^2 can be written

$$\frac{1}{n^2 k^4} \sum_{g, g'} \left(\sum_{i, j \in g} \sum_{s, t \in g'} \frac{h_i(D_i - p)}{p - p^2} \left(\frac{D_j \epsilon_j^1}{p} - \frac{(1 - D_j) \epsilon_j^0}{1 - p} \right) \frac{h_s(D_s - p)}{p - p^2} \left(\frac{D_t \epsilon_t^1}{p} - \frac{(1 - D_t) \epsilon_t^0}{1 - p} \right) \right).$$

We have $E[\epsilon_j^d \epsilon_t^{d'}|X_{1:n}, \pi_n, \tau] = E[\epsilon_j^d|X_j] E[\epsilon_t^{d'}|X_t] = 0$ for any $j \neq t$ by Lemma 9.21 of [Cytrynbaum \(2022\)](#). By group disjointness, the term $E[C_n^2|X_{1:n}, \pi_n, \tau]$ simplifies to

$$\frac{1}{n^2 k^4} \sum_g \left(\sum_{i, j, s \in g} \frac{h_i(D_i - p)}{p - p^2} \frac{h_s(D_s - p)}{p - p^2} E \left[\left(\frac{D_j \epsilon_j^1}{p} - \frac{(1 - D_j) \epsilon_j^0}{1 - p} \right)^2 \middle| X_{1:n}, \pi_n, \tau \right] \right).$$

We have $E[(\epsilon_i^d)^2|X_{1:n}, \pi_n, \tau] = E[(\epsilon_i^d)^2|X_i] = \sigma_d^2(X_i)$. Then by Young's inequality and Lemma 9.21 of the paper above

$$E \left[\left(\frac{D_j \epsilon_j^1}{p} - \frac{(1 - D_j) \epsilon_j^0}{1 - p} \right)^2 \middle| X_{1:n}, \pi_n, \tau \right] \leq 2(p \wedge (1 - p))^{-1} (\sigma_1^2(X_j) + \sigma_0^2(X_j)).$$

Taking the absolute value of the second to last display and using triangle inequality gives the upper bound

$$\begin{aligned} & 2[n^2 k^4 (p - p^2)^2 (p \wedge (1 - p))]^{-1} \sum_g \left(\sum_{i, j, s \in g} |h_i h_s| (\sigma_1^2(X_j) + \sigma_0^2(X_j)) \right) \\ & \lesssim n^{-2} \sum_g \left(\sum_{i, j, s \in g} |h_i h_s|^2 + (\sigma_1^2(X_j) + \sigma_0^2(X_j))^2 \right) \\ & \leq n^{-1} k^2 E_n[(\sigma_1^2(X_i) + \sigma_0^2(X_i))^2] + n^{-2} k \sum_g \sum_{i, s \in g} |h_i h_s|^2. \end{aligned}$$

By Young's inequality and assumption $E[E_n[(\sigma_1^2(X_i) + \sigma_0^2(X_i))^2]] \leq 2E[\sigma_1^2(X_i)^2 + \sigma_0^2(X_i)^2] < \infty$. For the second term, using Jensen we have

$$n^{-1} \sum_g \sum_{i, s \in g} |h_i h_s|^2 = n^{-1} \sum_g \left(\sum_{i \in g} |h_i|^2 \right)^2 \leq k n^{-1} E_n[h_i^4] = O_p(1).$$

Then we have shown that $E[C_n^2|X_{1:n}, \pi_n, \tau] = O_p(n^{-1})$, so by conditional Markov inequality in Lemma A.3, $C_n = O_p(n^{-1/2})$. This finishes the proof. \square

Lemma A.6 (Partialled Lin). *Under assumptions, $E_n[\check{h}_i z_i] = o_p(1)$. Also, we have*

$$\begin{aligned} E_n[D_i \check{h}_i \check{h}'_i] &= \frac{p(k-1)}{k} E[\text{Var}(h|\psi)] + o_p(1) \quad E_n[\check{h}_i \check{h}'_i] = \frac{k-1}{k} E[\text{Var}(h|\psi)] + o_p(1) \\ E_n[D_i \check{h}_i Y_i] &= \frac{p(k-1)}{k} E[\text{Cov}(h, m_1|\psi)] + o_p(1) \\ E_n[(1-D_i) \check{h}_i Y_i] &= \frac{(1-p)(k-1)}{k} E[\text{Cov}(h, m_0|\psi)] + o_p(1). \end{aligned}$$

Proof. First, observe that

$$\check{h}_i = h_i - k^{-1} \sum_{j \in g(i)} h_j = \frac{k-1}{k} \cdot h_i - k^{-1} \sum_{j \in g(i) \setminus \{i\}} h_j = k^{-1} \sum_{j \in g(i) \setminus \{i\}} (h_i - h_j).$$

Note that $E_n[D_i \check{h}_i \check{h}_i] = E_n[(D_i - p) \check{h}_i \check{h}_i] + p E_n[\check{h}_i \check{h}_i]$. We claim that $E_n[(D_i - p) \check{h}_i \check{h}_i] = O_p(n^{-1/2})$. For $1 \leq t, t' \leq d_h$, by Lemma 9.20 of [Cytrynbaum \(2022\)](#) and Cauchy-Schwarz we have $\text{Var}(\sqrt{n} E_n[(D_i - p) \check{h}_{it} \check{h}_{it'}] | X_{1:n}, \pi_n) \leq 2 E_n[\check{h}_{it}^2 \check{h}_{it'}^2] \leq 2 E_n[\check{h}_{it}^4]^{1/2} E_n[\check{h}_{it'}^4]^{1/2}$. Next, note that by Jensen's followed by Young's inequality

$$\begin{aligned} \check{h}_{it}^4 &= \frac{(k-1)^4}{k^4} \left(\frac{1}{k-1} \sum_{j \in g(i) \setminus \{i\}} (h_{it} - h_{jt}) \right)^4 \leq \frac{(k-1)^3}{k^4} \sum_{j \in g(i) \setminus \{i\}} (h_{it} - h_{jt})^4 \\ &\leq 8 \frac{(k-1)^3}{k^4} \sum_{j \in g(i) \setminus \{i\}} (h_{it}^4 + h_{jt}^4) \leq 8 \frac{(k-1)^3}{k^4} \left((k-1) h_{it}^4 + \sum_{j \in g(i) \setminus \{i\}} h_{jt}^4 \right). \end{aligned}$$

By counting, we have $E_n \left[\sum_{j \in g(i) \setminus \{i\}} h_{jt}^4 \right] = (k-1) E_n[h_{it}^4]$. Putting this all together, $E_n[\check{h}_{it}^4] \lesssim E_n[h_{it}^4] = O_p(1)$. Then $\text{Var}(\sqrt{n} E_n[(D_i - p) \check{h}_{it} \check{h}_{it'}] | X_{1:n}, \pi_n) = O_p(1)$ so that $E_n[(D_i - p) \check{h}_{it} \check{h}_{it'}] = O_p(n^{-1/2})$ by Lemma A.3. Then it suffices to show the claim for $E_n[\check{h}_i \check{h}_i]$. Let $f_{it} = E[h_t(X_i) | \psi_i]$ and write $h_{it} = f_{it} + u_{it}$. Then we have

$$\begin{aligned} E_n[\check{h}_{it} \check{h}_{it'}] &= \frac{1}{nk^2} \sum_i \left(\sum_{j \in g(i) \setminus \{i\}} h_{it} - h_{jt} \right) \left(\sum_{l \in g(i) \setminus \{i\}} h_{it'} - h_{lt'} \right) \\ &= \frac{1}{nk^2} \sum_i D_i \sum_{j, l \in g(i) \setminus \{i\}} (h_{it} - h_{jt})(h_{it'} - h_{lt'}). \end{aligned}$$

We can expand the expression above as

$$\begin{aligned} &\frac{1}{nk^2} \sum_i \sum_{j, l \in g(i) \setminus \{i\}} \left[(f_{it} - f_{jt})(f_{it'} - f_{lt'}) + (f_{it} - f_{jt})(u_{it'} - u_{lt'}) \right. \\ &\quad \left. + (u_{it} - u_{jt})(f_{it'} - f_{lt'}) + (u_{it} - u_{jt})(u_{it'} - u_{lt'}) \right] \equiv A_n + B_n + C_n + D_n. \end{aligned}$$

First consider A_n . By the Lipschitz assumption in 3.1 and Young's inequality

$$\begin{aligned} |A_n| &\leq \frac{1}{nk^2} \sum_i \sum_{j,l \in g \setminus \{i\}} |f_{it} - f_{jt}| |f_{it'} - f_{lt'}| \lesssim \frac{1}{nk^2} \sum_i \sum_{j,l \in g \setminus \{i\}} |\psi_i - \psi_j|_2 |\psi_i - \psi_l|_2 \\ &\leq \frac{2}{nk^2} \sum_i \sum_{j,l \in g \setminus \{i\}} (|\psi_i - \psi_j|_2^2 + |\psi_i - \psi_l|_2^2) = \frac{4(k-1)}{nk^2} \sum_g \sum_{i,j \in g} |\psi_i - \psi_j|_2^2 = o_p(1). \end{aligned}$$

The second to last equality by counting and the final equality by Assumption 2.1. Next consider B_n . Note that each $g \in \sigma(\psi_{1:n}, \pi_n)$ and $E[u_{it}|\psi_{1:n}, \pi_n] = E[u_{it}|\psi_i] = 0$, so $E[B_n|\psi_{1:n}, \pi_n] = 0$. We can rewrite the sum

$$\sum_i \sum_{j,l \in g \setminus \{i\}} (f_{it} - f_{jt})(u_{it'} - u_{lt'}) = \sum_g \sum_{\substack{i,j,l \in g \\ j,l \neq i}} (f_{it} - f_{jt})(u_{it'} - u_{lt'}).$$

Then we may compute $\text{Var}(\sqrt{n}B_n|\psi_{1:n}, \pi_n) = E[nB_n^2|\psi_{1:n}, \pi_n]$ as follows. By Lemma 9.21 of Cytrynbaum (2022), $E[u_{it'}u_{jt'}|\psi_{1:n}, \pi_n] = 0$ for any $g(i) \neq g(j)$, so we only consider the diagonal

$$\begin{aligned} 0 &\leq \frac{1}{nk^4} \sum_g \sum_{\substack{i,j,l \in g \\ j,l \neq i}} \sum_{\substack{a,b,c \in g \\ b,c \neq a}} E[(f_{it} - f_{jt})(f_{at} - f_{bt})(u_{it'} - u_{lt'})(u_{at'} - u_{ct'})|\psi_{1:n}, \pi_n] \\ &\leq n^{-1} \sum_g \sum_{\substack{i,j,l \in g \\ j,l \neq i}} \sum_{\substack{a,b,c \in g \\ b,c \neq a}} |f_{it} - f_{jt}| |f_{at} - f_{bt}| |E[(u_{it'} - u_{lt'})(u_{at'} - u_{ct'})|\psi_{1:n}, \pi_n]| \\ &\lesssim n^{-1} \sum_g \max_{i,j \in g} |\psi_i - \psi_j|_2^2 \sum_{\substack{i,j,l \in g \\ j,l \neq i}} \sum_{\substack{a,b,c \in g \\ b,c \neq a}} |E[(u_{it'} - u_{lt'})(u_{at'} - u_{ct'})|\psi_{1:n}, \pi_n]|. \end{aligned}$$

Next, by Lemma 9.21 of Cytrynbaum (2022), $E[(u_{it'} - u_{lt'})(u_{at'} - u_{ct'})|\psi_{1:n}, \pi_n]$ is

$$\delta_{ai}E[u_{it'}^2|\psi_i] - \delta_{ia}E[u_{at'}^2|\psi_a] - \delta_{ci}E[u_{it'}^2|\psi_i] + \delta_{ic}E[u_{it'}^2|\psi_i].$$

Applying the triangle inequality and summing out using this relation, the above is

$$\begin{aligned} &\leq \frac{4k(k-1)^3}{n} \sum_g \max_{i,j \in g} |\psi_i - \psi_j|_2^2 \sum_{i \in g} E[u_{it'}^2|\psi_i] \\ &\lesssim n^{-1} \sum_g \left(\max_{i,j \in g} |\psi_i - \psi_j|_2^4 + \sum_{i \in g} E[u_{it'}^2|\psi_i]^2 \right) \\ &\leq n^{-1} \sum_g \text{Diam}(\text{Supp}(\psi))^2 \sum_{i,j \in g} |\psi_i - \psi_j|_2^2 + E_n[E[u_{it'}^2|\psi_i]^2]. \end{aligned}$$

We claim that $E[u_{it'}^4] < \infty$. Note that $E[u_{it'}^4] = E[(h_{it'} - f_{it'})^4] \leq 8E[h_{it'}^4] + 8E[f_{it'}^4]$ by Young's inequality. We have $E[h_{it'}^4] < \infty$ by assumption. Note that $E[f_{it'}^4] \leq C_f |\psi_i|^4 \leq$

$C_f \text{Diam}(\text{Supp}(\psi))^4 < \infty$ by Assumption 3.1, with Lipschitz constant C_f . Then $E[u_{it'}^4] < \infty$, so $E[E_n[E[u_{it'}^2|\psi_i]]] = E[E[u_{it'}^2|\psi_i]^2] \leq E[u_{it'}^4] < \infty$. The inequality follows by conditional Jensen and tower law. Then $E_n[E[u_{it'}^2|\psi_i]^2] = O_p(1)$ by Markov inequality. Then using Assumption 2.1 in the display above, we have shown $E[nB_n^2|\psi_{1:n}, \pi_n] = O_p(1)$ and by Lemma A.3 we have shown $B_n = O_p(n^{-1/2})$. We have $C_n = O_p(n^{-1/2})$ by symmetry. Finally, consider D_n . By Lemma 9.21 of Cytrynbaum (2022) compute $E[(u_{it} - u_{jt})(u_{it'} - u_{lt'})|\psi_{1:n}, \pi_n] = E[u_{it}u_{it'}|\psi_i] + E[u_{jt}u_{jt'}|\psi_j]\delta_{jl}$ for $j, l \neq i$. Then we calculate

$$\begin{aligned} E[D_n|\psi_{1:n}, \pi_n] &= \frac{1}{nk^2} \sum_i \sum_{j,l \in g(i) \setminus \{i\}} E[u_{it}u_{it'}|\psi_i] + E[u_{jt}u_{jt'}|\psi_j] \mathbf{1}(j=l) \\ &= \frac{1}{nk^2} \sum_i (k-1)^2 E[u_{it}u_{it'}|\psi_i] + \frac{1}{nk^2} \sum_i \sum_{j \in g(i) \setminus \{i\}} E[u_{jt}u_{jt'}|\psi_j] \\ &= \frac{(k-1)^2}{nk^2} \sum_i E[u_{it}u_{it'}|\psi_i] + \frac{k-1}{nk^2} \sum_i E[u_{it}u_{it'}|\psi_i] = \frac{k(k-1)}{nk^2} \sum_i E[u_{it}u_{it'}|\psi_i]. \end{aligned}$$

Now $E[E[u_{it}u_{it'}|\psi_i]^2] \leq E[u_{it}^2u_{it'}^2] \leq 2E[u_{it}^4] + 2E[u_{it'}^4] < \infty$ by Jensen, tower law, Young's, and work above. Then by Chebyshev $\frac{(k-1)}{nk} \sum_i E[u_{it}u_{it'}|\psi_i] = \frac{k-1}{k} E[u_{it}u_{it'}] + O_p(n^{-1/2}) = \frac{k-1}{k} E[\text{Cov}(h_{it}, h_{it'}|\psi_i)] + O_p(n^{-1/2})$. Then we have shown $E[D_n|\psi_{1:n}, \pi_n] = \frac{k-1}{k} E[\text{Cov}(h_{it}, h_{it'}|\psi_i)] + O_p(n^{-1/2})$. Next, we claim that $\text{Var}(\sqrt{n}D_n|\psi_{1:n}, \pi_n) = O_p(1)$. Following the steps above for B_n replacing terms shows that $\text{Var}(\sqrt{n}D_n|\psi_{1:n}, \pi_n)$ is

$$0 \leq \frac{1}{nk^4} \sum_g \sum_{\substack{i,j,l \in g \\ j,l \neq i}} \sum_{\substack{a,b,c \in g \\ b,c \neq a}} \text{Cov}((u_{it} - u_{jt})(u_{it'} - u_{lt'}), (u_{at} - u_{bt})(u_{at'} - u_{ct'})|\psi_{1:n}, \pi_n).$$

For any variables A, B , $|\text{Cov}(A, B)| \leq |E[AB]| + |E[A]E[B]| \leq 2|A|_2|B|_2$ by Cauchy-Schwarz and increasing $L_p(\mathbb{P})$ norms. By Young's inequality, $(a-b)^4 \leq 8(a^4 + b^4)$ for any $a, b \in \mathbb{R}$. Then using these facts

$$\begin{aligned} &|\text{Cov}((u_{it} - u_{jt})(u_{it'} - u_{lt'}), (u_{at} - u_{bt})(u_{at'} - u_{ct'})|\psi_{1:n}, \pi_n)| \\ &\leq 2E[(u_{it} - u_{jt})^2(u_{it'} - u_{lt'})^2|\psi_{1:n}, \pi_n]^{1/2} E[(u_{at} - u_{bt})^2(u_{at'} - u_{ct'})^2|\psi_{1:n}, \pi_n]^{1/2} \\ &\leq 4E[(u_{it} - u_{jt})^2(u_{it'} - u_{lt'})^2|\psi_{1:n}, \pi_n] + 4E[(u_{at} - u_{bt})^2(u_{at'} - u_{ct'})^2|\psi_{1:n}, \pi_n] \\ &\leq 2E[(u_{it} - u_{jt})^4 + (u_{it'} - u_{lt'})^4|\psi_{1:n}, \pi_n] + 2E[(u_{at} - u_{bt})^4 + (u_{at'} - u_{ct'})^4|\psi_{1:n}, \pi_n] \\ &\leq 16(E[u_{it}^4 + u_{jt}^4 + u_{it'}^4 + u_{lt'}^4|\psi_{1:n}, \pi_n] + E[u_{at}^4 + u_{bt}^4 + u_{at'}^4 + u_{ct'}^4|\psi_{1:n}, \pi_n]) \\ &= 16(2E[u_{it}^4|\psi_i] + E[u_{jt}^4|\psi_j] + E[u_{it'}^4|\psi_l] + 2E[u_{at}^4|\psi_a] + E[u_{bt}^4|\psi_b] + E[u_{ct'}^4|\psi_c]). \end{aligned}$$

Plugging this bound in above and summing out gives

$$\text{Var}(\sqrt{n}D_n|\psi_{1:n}, \pi_n) \leq \frac{32k^5}{nk^4} \sum_g \sum_{i \in g} E[u_{it}^4|\psi_i] \asymp E_n[E[u_{it}^4|\psi_i]] = O_p(1).$$

The final equality by Markov since $E[u_{it}^4] < \infty$. Then by conditional Markov [A.3](#) we have $D_n = \frac{k-1}{k}E[\text{Cov}(h_{it}, h_{it'}|\psi_i)] + O_p(n^{-1/2})$. Since t, t' were arbitrary, this shows $E_n[\check{h}_i \check{h}'_i] = E[\text{Var}(h|\psi)] + o_p(1)$.

Next, consider $E_n[D_i \check{h}_i Y_i] = E_n[(D_i - p)\check{h}_i Y_i(1)] + pE_n[\check{h}_i Y_i(1)]$. We claim that $E_n[(D_i - p)\check{h}_i Y_i(1)] = O_p(n^{-1/2})$. For $1 \leq t \leq d_h$, by Lemma 9.20 of [Cytrynbaum \(2022\)](#), and Cauchy-Schwarz

$$\text{Var}(\sqrt{n}E_n[(D_i - p)\check{h}_{it}Y_i(1)]|X_{1:n}, Y(1)_{1:n}, \pi_n) \leq 2E_n[\check{h}_{it}^2 Y_i(1)^2] \leq 2E_n[\check{h}_{it}^4]^{1/2} E_n[Y_i(1)^4]^{1/2}.$$

Note that $E_n[Y_i(1)^4] = O_p(1)$ by Markov inequality and Assumption [3.1](#) and $E_n[\check{h}_{it}^4] = O_p(1)$ was shown above. Then by Lemma [A.3](#) (conditional Markov), this shows the claim. Then it suffices to analyze $E_n[\check{h}_i Y_i(1)]$. Let $g_i = E[Y_i(1)|\psi_i]$ and $v_i = Y_i(1) - g_i$ with $E[v_i|\psi_i] = 0$. Then as above we may expand

$$\begin{aligned} E_n[\check{h}_i Y_i(1)] &= \frac{1}{nk} \sum_i \left(\sum_{j \in g(i) \setminus \{i\}} f_{it} - f_{jt} + u_{it} - u_{jt} \right) (g_i + v_i) \\ &= \frac{1}{nk} \sum_i \sum_{j \in g(i) \setminus \{i\}} (f_{it} - f_{jt})g_i + (f_{it} - f_{jt})v_i + (u_{it} - u_{jt})g_i + (u_{it} - u_{jt})v_i \\ &\equiv H_n + J_n + K_n + L_n. \end{aligned}$$

First consider H_n . By Assumption [3.1](#), $\psi \rightarrow g(\psi)$ is continuous and $\text{Supp}(\psi) \subseteq \bar{B}(0, K)$ compact, so $\sup_{\psi \in \bar{B}(0, K)} |g(\psi)| \equiv K' < \infty$ and $|g_i| \leq K'$ a.s. Then we have

$$|H_n| \lesssim n^{-1} \sum_i \sum_{j \in g(i) \setminus \{i\}} |\psi_i - \psi_j|_2 |g_i| \lesssim n^{-1} \sum_g \sum_{i, j \in g} |\psi_i - \psi_j|_2 = o_p(1).$$

For the final equality, note that here we have the unsquared norm, different from Assumption [2.1](#). The construction in Proposition 8.6 of [Cytrynbaum \(2022\)](#) gave showed that this quantity is also $o_p(1)$ (with rates). By substituting z_i for g_i , which satisfies the same conditions, this also shows that $E_n[z_i \check{h}'_i] = o_p(1)$. The proof that $J_n, K_n = O_p(n^{-1/2})$ are similar to the terms B_n, C_n above. Next, consider L_n . We have

$$\begin{aligned} E[L_n|\psi_{1:n}, \pi_n] &= \frac{1}{nk} \sum_i \sum_{j \in g(i) \setminus \{i\}} E[(u_{it} - u_{jt})v_i|\psi_{1:n}, \pi_n] \\ &= \frac{1}{nk} \sum_i \sum_{j \in g(i) \setminus \{i\}} E[u_{it}v_i|\psi_i] = \frac{k-1}{k} E_n[E[u_{it}v_i|\psi_i]] \\ &= \frac{k-1}{k} E[\text{Cov}(h_{it}, Y_i(1)|\psi_i)] + O_p(n^{-1/2}). \end{aligned}$$

The second equality follows since $j \neq i$ and by Lemma 9.21 of [Cytrynbaum \(2022\)](#).

The third equality by counting. For the last equality, note that by Jensen, tower law, Young's inequality $E[E[u_{it}v_i|\psi_i]^2] \leq E[u_{it}^2v_i^2] \leq (1/2)(E[u_{it}^4] + E[v_i^4])$. We showed $E[u_{it}^4] < \infty$ above and a similar proof applies to v_i . Then the final equality above follows by Chebyshev. The proof that $\text{Var}(L_n|\psi_{1:n}, \pi_n) = O_p(n^{-1/2})$ is similar to our analysis of D_n above. Then we have shown $E_n[D_i\check{h}_iY_i] = p^{\frac{k-1}{k}}E[\text{Cov}(h, Y(1)|\psi)] + o_p(1)$. The conclusion for $E_n[(1 - D_i)\check{h}_iY_i]$ follows by symmetry. This finishes the proof. \square