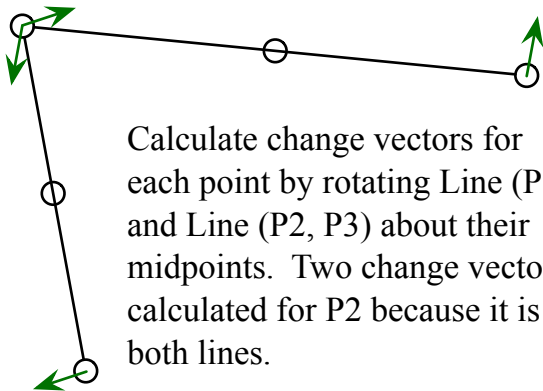


P2

Correct C1 (Right angle).



P3

Calculate change vectors for each point by rotating Line (P1, P2) and Line (P2, P3) about their midpoints. Two change vectors are calculated for P2 because it is in both lines.

P1