

Lab 1 TUM 7

Task 2

a. Show $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right\}$ is basis for \mathbb{R}^3

$$\begin{aligned} \text{REF} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix} &\xrightarrow{R_2 - R_1, R_3 - R_1} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} \xrightarrow{R_2 \cdot \frac{1}{2}} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ &\xrightarrow{R_1 + R_2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

Since REF is identity matrix, the set of original vector is basis of \mathbb{R}^3

b. Why this is not ~~orthogonal~~ ^{orthonormal} basis for \mathbb{R}^3 ?

We calculate the dot product of every vector to check the orthogonal.

$$V_1 \cdot V_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = 0 \quad \left| \quad V_1 \cdot V_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} = 4 \quad \left| \quad V_2 \cdot V_3 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} = 1 \right.$$

Since not all of the vector are orthogonal so that are not orthonormal basis.

If we check the magnitude, we can get that all of the vector magnitude isn't equal to 1

$$\|V_1\| = \sqrt{1+1+1} = \sqrt{3}, \quad \|V_2\| = \sqrt{1+1+0} = \sqrt{2}, \quad \|V_3\| = \sqrt{1+4+1} = \sqrt{6}$$

c. Using Gram-Schmidt process, transform the basis to an orthonormal basis for \mathbb{R}^3

$$\begin{aligned} \vec{w}_1 &= \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}; \quad \vec{w}_2 = \vec{V}_2 - \frac{\vec{w}_1 \cdot \vec{V}_2}{\vec{w}_1 \cdot \vec{w}_1} \vec{w}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} - \frac{0}{3} \vec{w}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}; \quad \vec{w}_3 = \vec{V}_3 - \frac{\vec{w}_1 \cdot \vec{V}_3}{\vec{w}_1 \cdot \vec{w}_1} \vec{w}_1 - \frac{\vec{w}_2 \cdot \vec{V}_3}{\vec{w}_2 \cdot \vec{w}_2} \vec{w}_2 \\ &= \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} - \frac{4}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{6} \\ \frac{1}{6} \\ -\frac{1}{3} \end{bmatrix} \end{aligned}$$

$$\text{The orthogonal basis} \rightarrow \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{6} \\ \frac{1}{6} \\ -\frac{1}{3} \end{bmatrix} \right\}$$

$$\text{Normalizing and we find orthonormal basis} \rightarrow \left\{ \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \right\}$$

Goal 1

$$Ax = b \rightarrow \begin{pmatrix} 1 & 1 \\ 2 & 2 \\ 1 & 3 \end{pmatrix} x = \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix}$$

a. Is there a solution?

* If we eliminate A and B, we get

$$A^T x = b$$

$$\begin{pmatrix} 1 & 1 \\ 2 & 2 \\ 0 & 0 \end{pmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$$

Since the ~~row~~ third row of A equal to 0, the third row of vector B should be 0.
In that particular condition, the equation didn't have a solution.

b. Find $\hat{b} \in C(A)$, that minimize $\|b - \hat{b}\|$.

$$* \hat{b} = A\hat{x} = A(A^T A)^{-1} A^T b$$

$$A^T A = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 2 & 2 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} 6 & 8 \\ 8 & 14 \end{pmatrix}$$

$$(A^T A)^{-1} = \frac{1}{20} \begin{pmatrix} 14 & -8 \\ -8 & 6 \end{pmatrix}$$

$$\hat{b} = A(A^T A)^{-1} A^T b = A \frac{1}{20} \begin{pmatrix} 14 & -8 \\ -8 & 6 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix}$$

$$= \begin{pmatrix} 0,8 \\ 1,6 \\ 4,0 \end{pmatrix}$$

c. $\xi = b - \hat{b}$. Explain the relation between ξ and $C(A)$.

$$\xi = \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix} - \begin{pmatrix} 0,8 \\ 1,6 \\ 4,0 \end{pmatrix} = \begin{pmatrix} 1,2 \\ -0,6 \\ 0 \end{pmatrix}$$

Is the left nullspace matrix A. $\xi = (N(A^T)) \cdot \Sigma + C(A)$