

**AFTER A MATH TEST...**

# Discrete Mathematics

#5 Induction and Recursion

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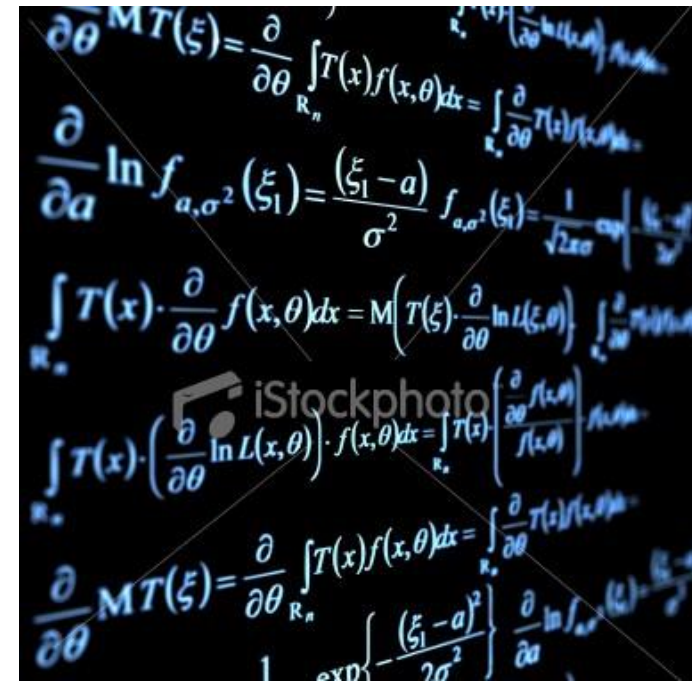
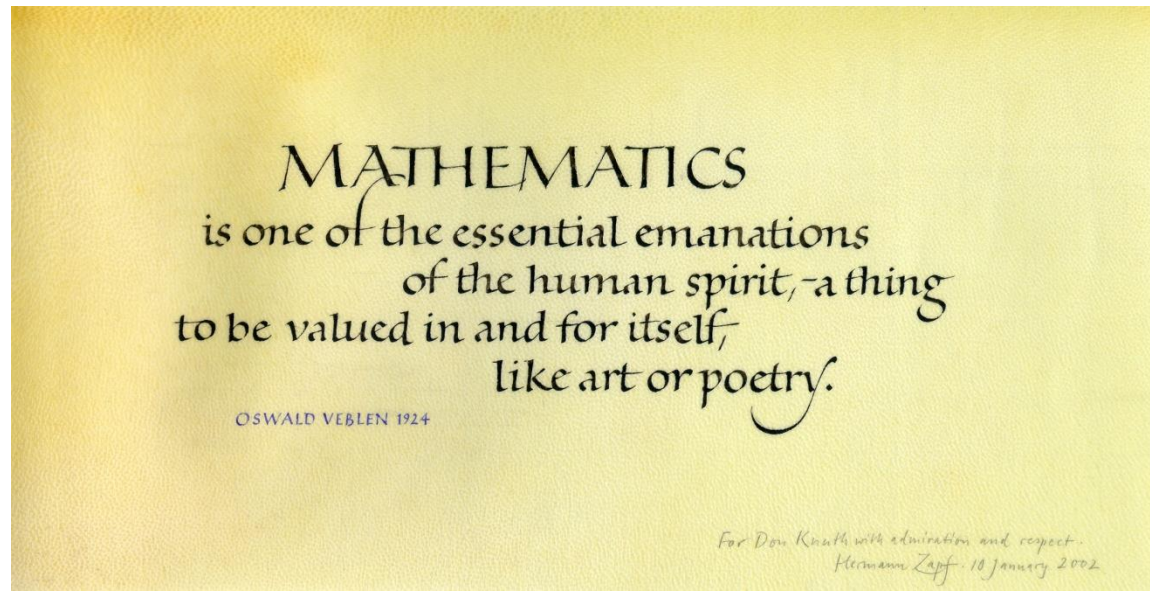
When I was young ...





# Why study mathematics?

- It is foundation of science
- It has been used in so many areas: economics, engineering, life science, social science, modern physics etc
- Example?



# simple drill: read aloud!

- On Thomas Calculus we have this

**THEOREM 4—The Sandwich Theorem** Suppose that  $g(x) \leq f(x) \leq h(x)$  for all  $x$  in some open interval containing  $c$ , except possibly at  $x = c$  itself. Suppose also that

$$\lim_{x \rightarrow c} g(x) = \lim_{x \rightarrow c} h(x) = L.$$

Then  $\lim_{x \rightarrow c} f(x) = L$ .

# Another drillA

- On a technical book there is a passage like this

**5.1. Theorem.** Suppose that  $f \in \mathcal{F}$  is bounded below by some constant  $c$ , and  $f_\alpha$  is defined as above with  $\alpha > 0$ . Then  $f_\alpha$  is bounded below by  $c$ , and is Lipschitz on each bounded subset of  $X$  (and in particular is finite-valued). Furthermore, suppose  $x \in X$  is such that  $\partial_P f_\alpha(x)$  is nonempty. Then there exists a point  $\bar{y} \in X$  satisfying the following:

- (a) If  $\{y_i\} \subset X$  is a minimizing sequence for the infimum in (1), then  $\lim_{i \rightarrow \infty} y_i = \bar{y}$ .
- (b) The infimum in (1) is attained uniquely at  $\bar{y}$ .
- (c) The Fréchet derivative  $f'_\alpha(x)$  exists and equals  $2\alpha(x - \bar{y})$ . Thus the proximal subgradient  $\partial_P f_\alpha(x)$  is the singleton  $\{2\alpha(x - \bar{y})\}$ .
- (d)  $2\alpha(x - \bar{y}) \in \partial_P f(\bar{y})$ .

*Proof.* Suppose we are given  $f$  and  $\alpha > 0$  as above. It is clear from the definition that  $f_\alpha$  is bounded below by  $c$ . We now show that  $f_\alpha$  is Lipschitz on any bounded set  $S \subset X$ .

For any fixed  $x_0 \in \text{dom } f \neq \emptyset$ , note that  $f_\alpha(x) \leq f(x_0) + \alpha\|x - x_0\|^2$  for all  $x \in X$ , and thus in particular  $m := \sup\{f_\alpha(x) : x \in S\} < \infty$ . Since  $\alpha > 0$ , and  $f$  is bounded below, we have that for any  $\varepsilon > 0$  the set

$$C := \{z : \exists y \in S \text{ so that } f(z) + \alpha\|y - z\|^2 \leq m + \varepsilon\}$$

is bounded in  $X$ .

# One more

**Theorem 4.1** Let  $x = 0$  be an equilibrium point for (4.1) and  $D \subset R^n$  be a domain containing  $x = 0$ . Let  $V : D \rightarrow R$  be a continuously differentiable function such that

$$V(0) = 0 \text{ and } V(x) > 0 \text{ in } D - \{0\} \quad (4.2)$$

$$\dot{V}(x) \leq 0 \text{ in } D \quad (4.3)$$

Then,  $x = 0$  is stable. Moreover, if

$$\dot{V}(x) < 0 \text{ in } D - \{0\} \quad (4.4)$$

then  $x = 0$  is asymptotically stable.

- A very famous theorem called Lyapunov Theorem

**Proof:** Given  $\varepsilon > 0$ , choose  $r \in (0, \varepsilon]$  such that

$$B_r = \{x \in R^n \mid \|x\| \leq r\} \subset D$$

Let  $\alpha = \min_{\|x\|=r} V(x)$ . Then,  $\alpha > 0$  by (4.2). Take  $\beta \in (0, \alpha)$  and let

$$\Omega_\beta = \{x \in B_r \mid V(x) \leq \beta\}$$

Then,  $\Omega_\beta$  is in the interior of  $B_r$ .<sup>2</sup> (See Figure 4.1.) The set  $\Omega_\beta$  has the property that any trajectory starting in  $\Omega_\beta$  at  $t = 0$  stays in  $\Omega_\beta$  for all  $t \geq 0$ . This follows from (4.3) since

$$\dot{V}(x(t)) \leq 0 \Rightarrow V(x(t)) \leq V(x(0)) \leq \beta, \forall t \geq 0$$

Because  $\Omega_\beta$  is a compact set,<sup>3</sup> we conclude from Theorem 3.3 that (4.1) has a unique solution defined for all  $t \geq 0$  whenever  $x(0) \in \Omega_\beta$ . As  $V(x)$  is continuous and  $V(0) = 0$ , there is  $\delta > 0$  such that

$$\|x\| \leq \delta \Rightarrow V(x) < \beta$$

Then,

$$B_\delta \subset \Omega_\beta \subset B_r$$

and

$$x(0) \in B_\delta \Rightarrow x(0) \in \Omega_\beta \Rightarrow x(t) \in \Omega_\beta \Rightarrow x(t) \in B_r$$

Therefore,

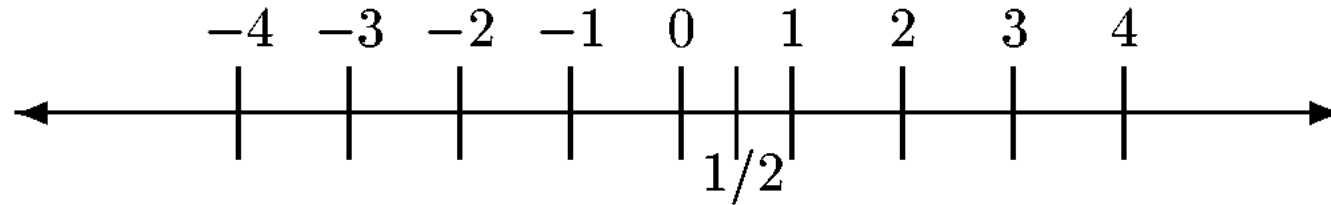
$$\|x(0)\| < \delta \Rightarrow \|x(t)\| < r \leq \varepsilon, \forall t \geq 0$$

# What can you conclude?

- It is indeed important to open many doors!

# Refresher (set and number)

- Number



- Set of number
  - $\mathbf{Z}$ =the set of integers= $\{0,1,-1,2,-1,3,-3,\dots\}$
  - $\mathbf{N}$ =the set of nonnegative integers or natural numbers
  - $\mathbf{Z}^+$ =the set of positive integers
  - $\mathbf{Q}$ =the set of rational numbers= $\{a/b \mid a,b \text{ is integer, } b \text{ not zero}\}$
  - $\mathbf{Q}^+$ =the set of positive rational numbers
  - $\mathbf{Q}^*$ =the set of nonzero rational numbers
  - $\mathbf{R}$ =the set of real numbers
  - $\mathbf{R}^+$ =the set of positive real numbers
  - $\mathbf{R}^*$ =the set of nonzero real numbers
  - $\mathbf{C}$ =the set of complex numbers
- Infinite sets come in different sizes!



# Induction and Recursion

## Chapter 4

Take a look at this video, today we are going to talk about this!

