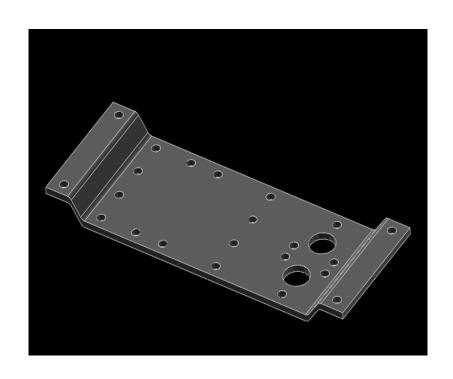
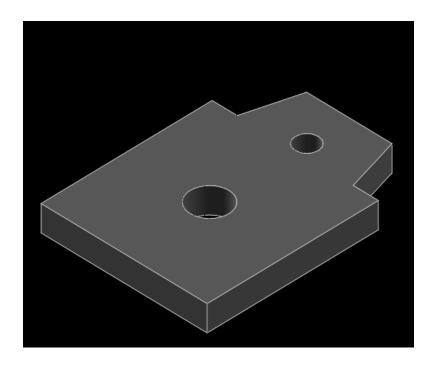


## 零件繪製分工

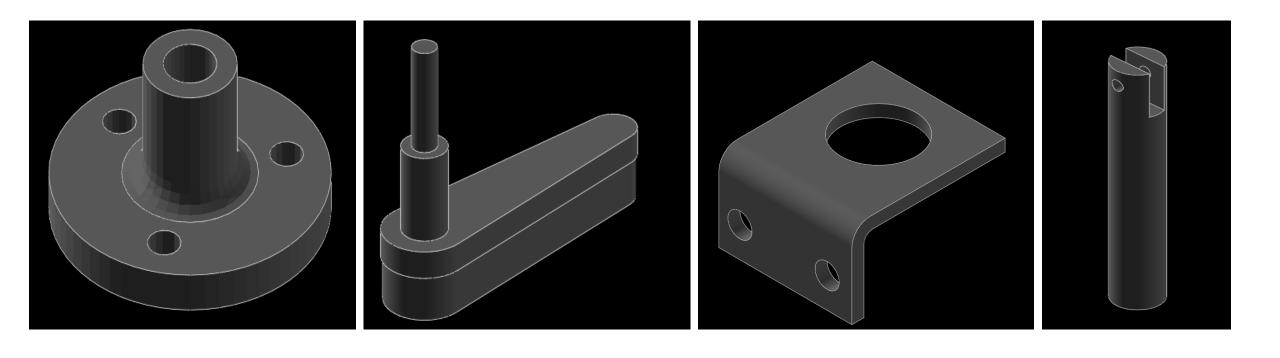
41223208-葉如意 負責繪製零件





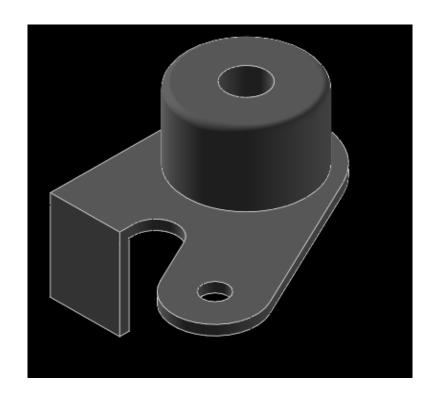
# 零件繪製分工

41223209-鄭佳青 負責繪製零件



## 零件繪製分工

41223234-陳奕廷 負責繪製零件

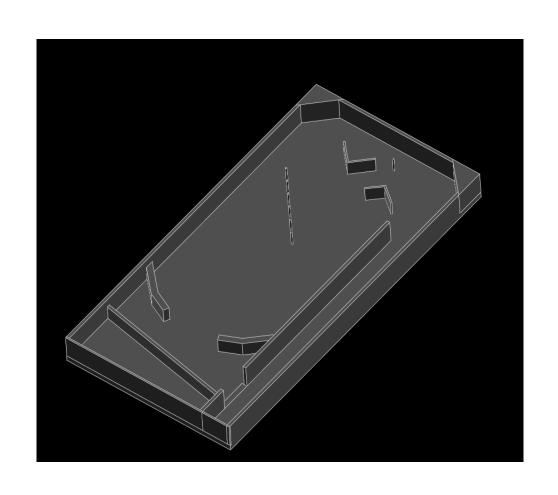


#### 組合-全員討論



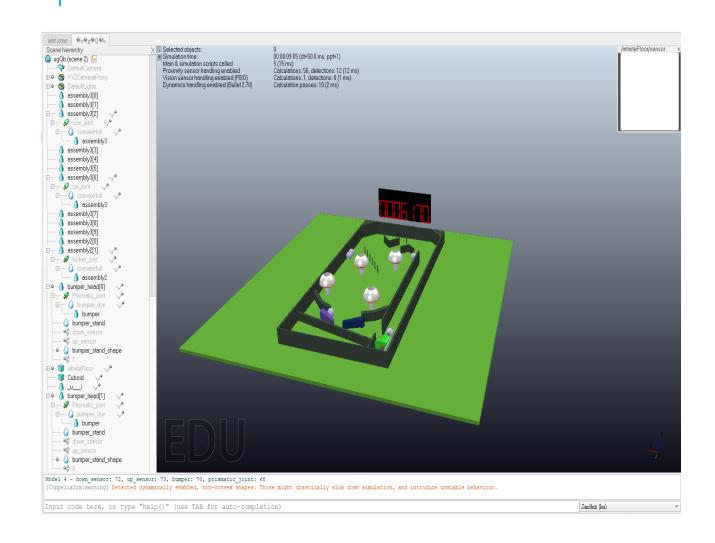
- 1.開啟solvespace
- 2.確認儲存的零件有開啟輪廓線
- 3.建立新檔,點選Link/Assemble,新增繪製好的零件。
- 4.組裝,給零件限制條件,平行/垂直/重和/共線等。
- 5.完成組合

## 彈珠台檯面設計



設計發想是參考夜市傳統彈珠台,在檯面內預留回彈計分器以及fipper、彈珠台拉桿擺放位置,預想球滾動之動向設計軌道,並利用SolveSpace繪製出來,底板:長120x寬60x高2mm,外側包圍板子:高8mm 厚度1mm,再繪製內部零件,轉成stl檔。

#### COPPELIASIM動態模擬



- 1.將檯面、擊球器、fipper等零件加入 Coppeliasim
- 2.調整位子
- 3.加入回彈裝置模型及記分板
- 4.更改操控程式

## 動態模擬過程中遇到的困難

1.擊球桿會亂跑

解決方法:要單獨新增動力模型,不然與地板接觸會導致桿件擊飛。

2.球無法依照重力滾動

解決方法:讓機構簡單化,像是彈珠台不要設計過於複雜,新增板子,作為新的彈珠台底部。

3.記分板無法正常顯示

解決方法:重新複製模組,因為程式有可能會卡機

#### 模擬程式

透過程式,讓動態模擬作動,點選 Tools go,程式就會開始執行,並透 過按鍵盤上的英文字母W、S操控左 邊Fipper, P、L操控右邊Fipper, K、 J操控擊球桿

```
■ 弾射利刃.py - SciTE

File Edit Search View Tools Options Language Buffers Help
 1 彈射利刃.py
    # pip install pyzmq cbor keyboard
    from coppeliasim_zmgremoteapi_client import RemoteAPIClient
    import keyboard
    # Connecting to the CoppeliaSim server
    client = RemoteAPIClient('localhost', 23000)
    print('Program started')
    sim = client.getObject('sim')
    # Get the handle for the slider (prismatic joint)
    cw= sim.getObject('/cw_joint')
    ccw= sim.getObject('/ccw_joint')
    slider = sim.getObject('/kicker_joint')
    # Starting the simulation
    sim.startSimulation()
    print('Simulation started')
    # Main control loop
  - def main():
       # Keep running until simulation is stopped
       while True:
          if keyboard.is_pressed('p'): # Move slider to -0.15 position
            print("p is pressed")
            sim.setJointTargetPosition(ccw, -0.5)
          if keyboard.is_pressed('1'): # Reset slider to the original position
             print("1 is pressed")
             sim.setJointTargetPosition(ccw, 0.0) # Reset to the initial position
          if keyboard.is_pressed('w'): # Move slider to -0.15 position
            print("w is pressed")
            sim.setJointTargetPosition(cw,0.5)
          if keyboard.is pressed('s'): # Reset slider to the original position
            print("s is pressed")
            sim.setJointTargetPosition(cw, 0.0) # Reset to the initial position
          if keyboard.is_pressed('j'): # Move slider to -0.15 position
            print("j is pressed")
            sim.setJointTargetPosition(slider, -0.15)
         if keyboard.is_pressed('k'): # Reset slider to the original position
            print("k is pressed")
            sim.setJointTargetPosition(slider, 0.0) # Reset to the initial position
          if keyboard.is_pressed('t'): # Stop the simulation when 'q' is pressed
            print("t is pressed - stopping simulation")
            sim.stopSimulation()
            break
    # Start the main control loop
    main()
```