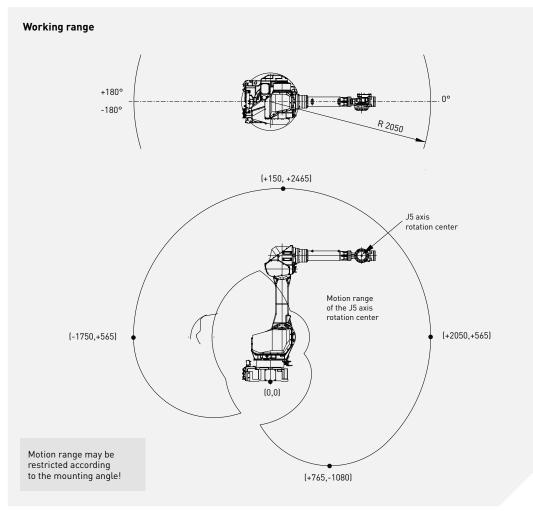
M-710*i*C/50



Max. load capacity at wrist: **50 kg**



					Motion r	ange (°)				Ма	ximum	speed (°	?/s)				
Controlled axes	Repeatability (mm)	Mechanical weight (kg)	J1	J2	73	J4	J5	J6	J1	J2	J3	J4	J5	J6	J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
6	± 0.03*	560	360	225	440	720	250	720	175	175	175	250	250	355	206/28	206/28	127/11



Ä Robot	M-710 <i>i</i> C/50
Robot footprint [mm]	535 X 550
Mounting position Floor	•
Mounting position Upside down	•
Mounting position Angle	•
Controller	R-30 <i>i</i> B Plus
Open air cabinet	-
Mate cabinet	0
A-cabinet	•
B-cabinet	0
iPendant Touch	•
Electrical connections	
Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	2.5
Integrated services	
Integrated signals on upper arm In/Out	8/8
Integrated air supply	1
Environment	
Acoustic noise level [dB]	71.3
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	IP54/IP67
Wrist & J3 arm standard/optional	IP67