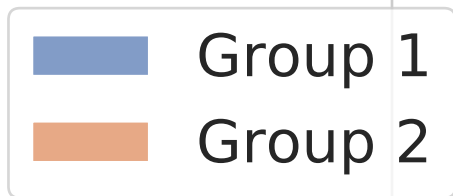


Number of orientations



500

0

0

1

2

3

$d_q(q_i, q_j)$