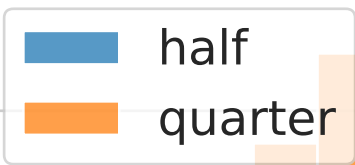


Number of orientations



750

500

250

0

0

1

2

3

$d_q(q_i, q_j)$

