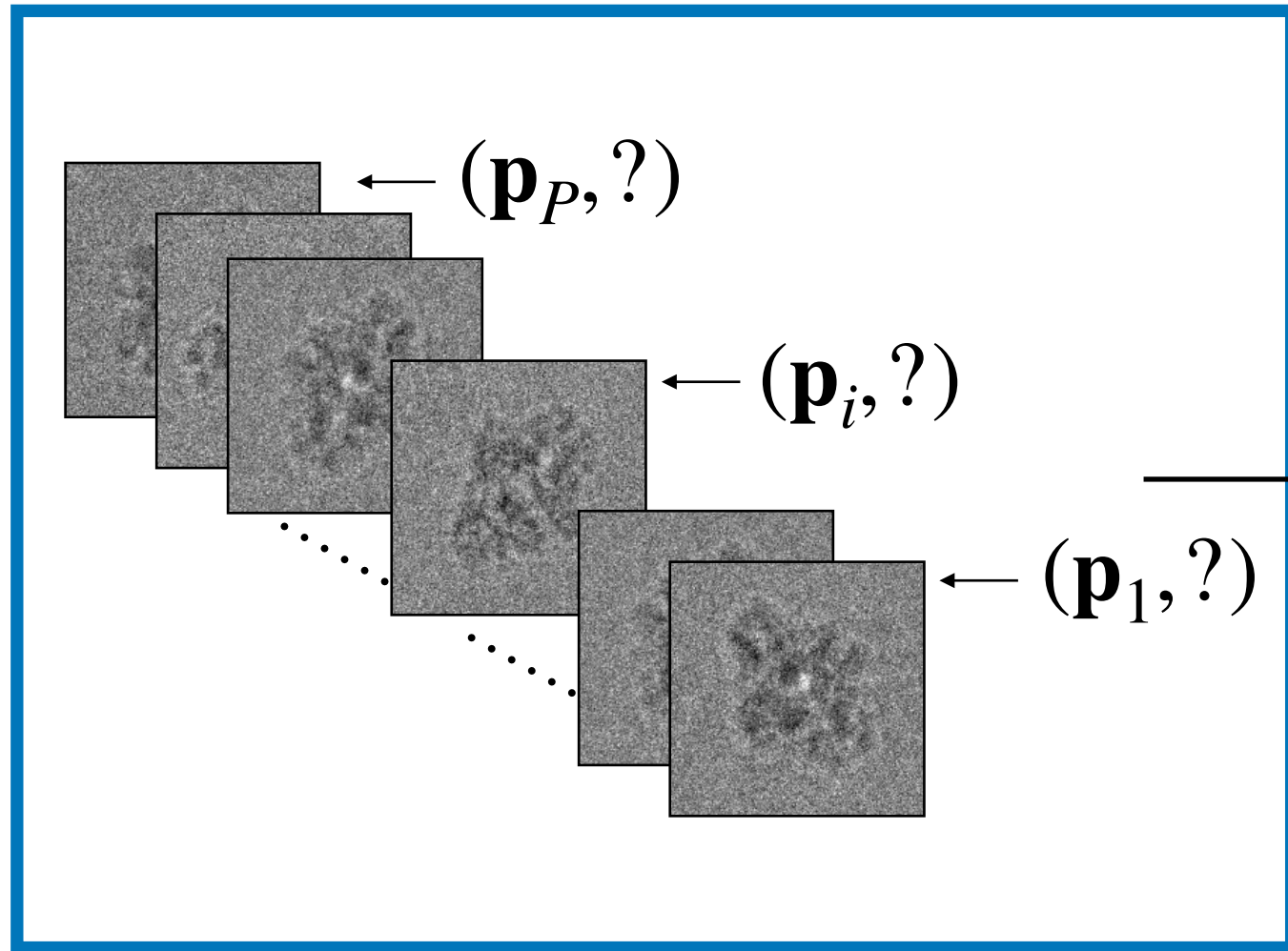
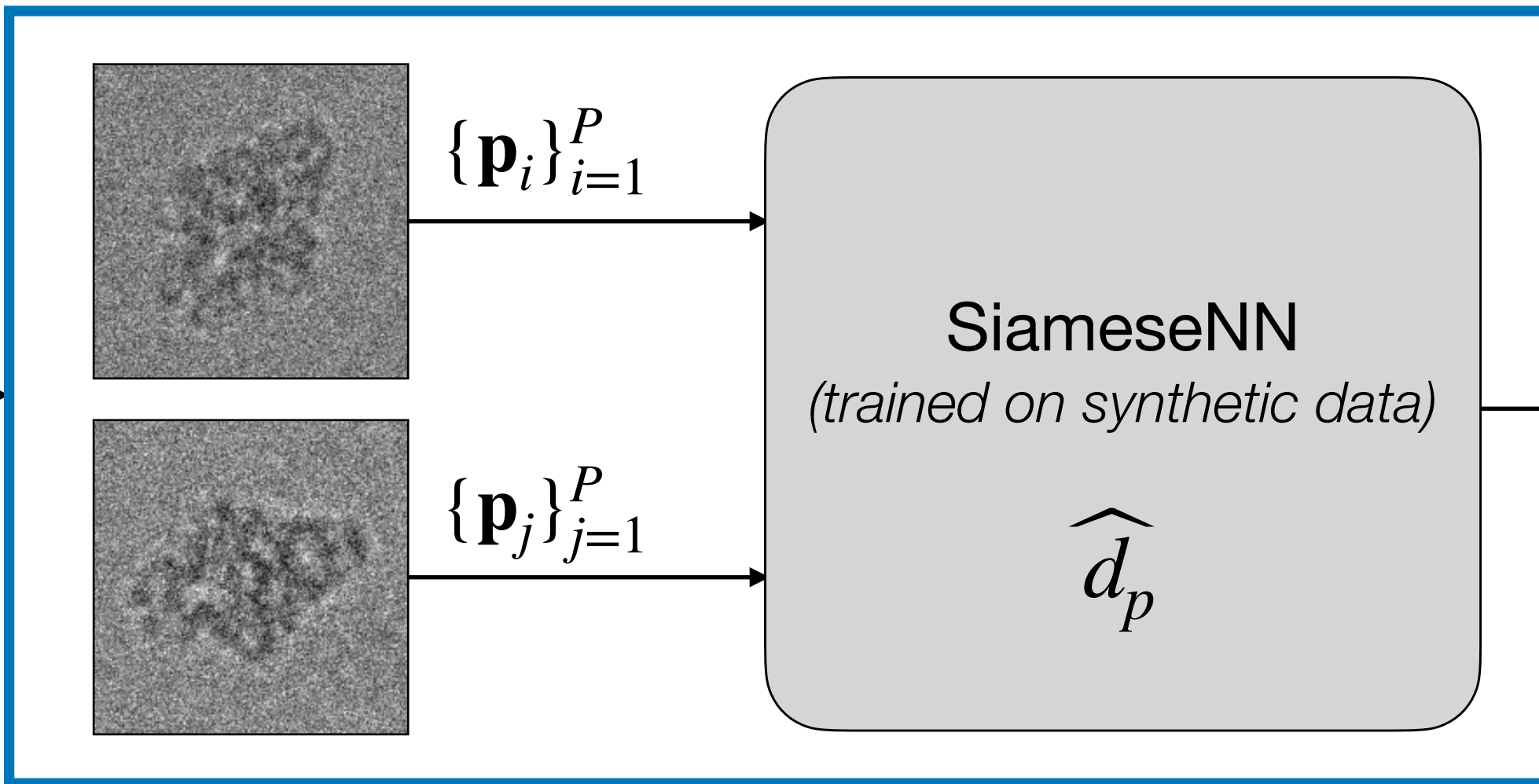


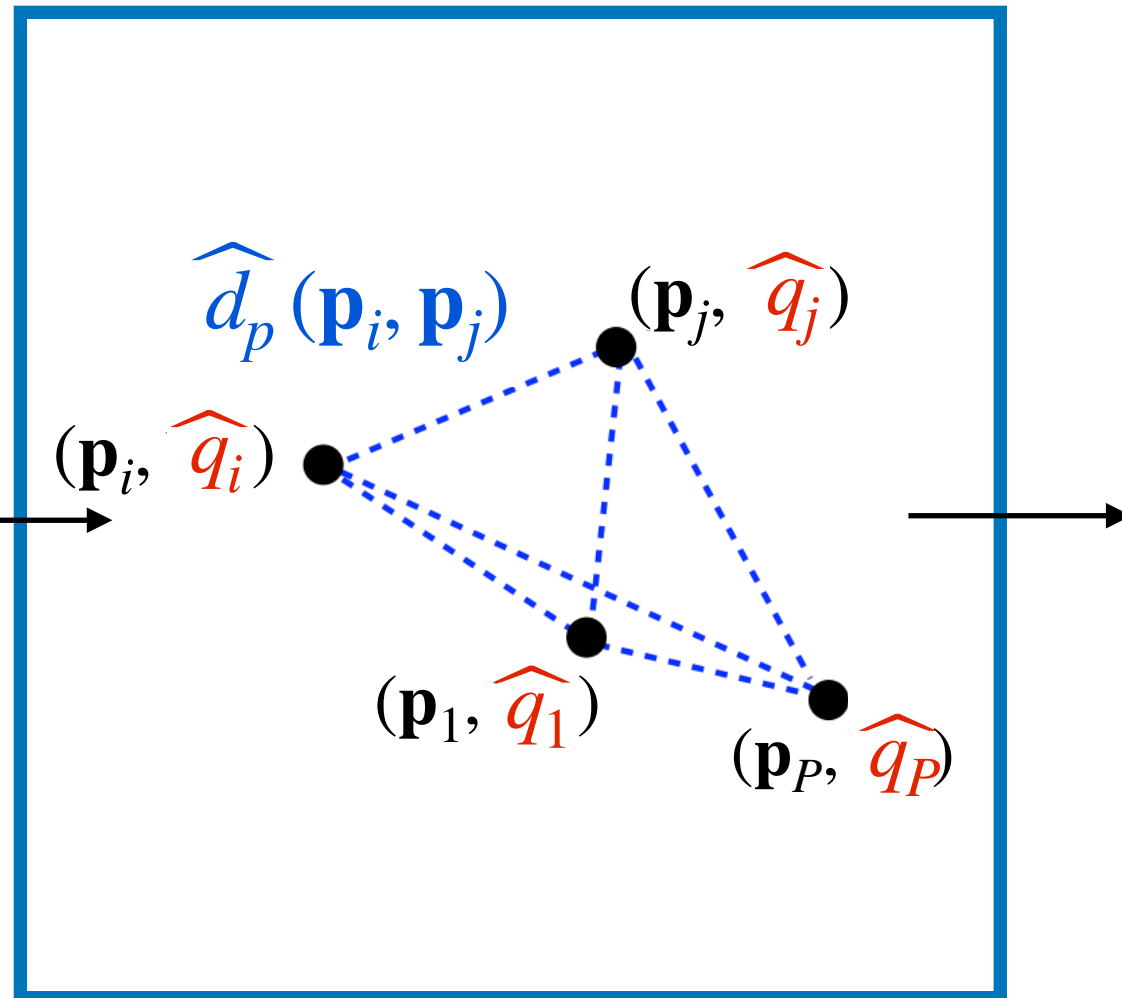
## Inputs: Acquired Projection Dataset



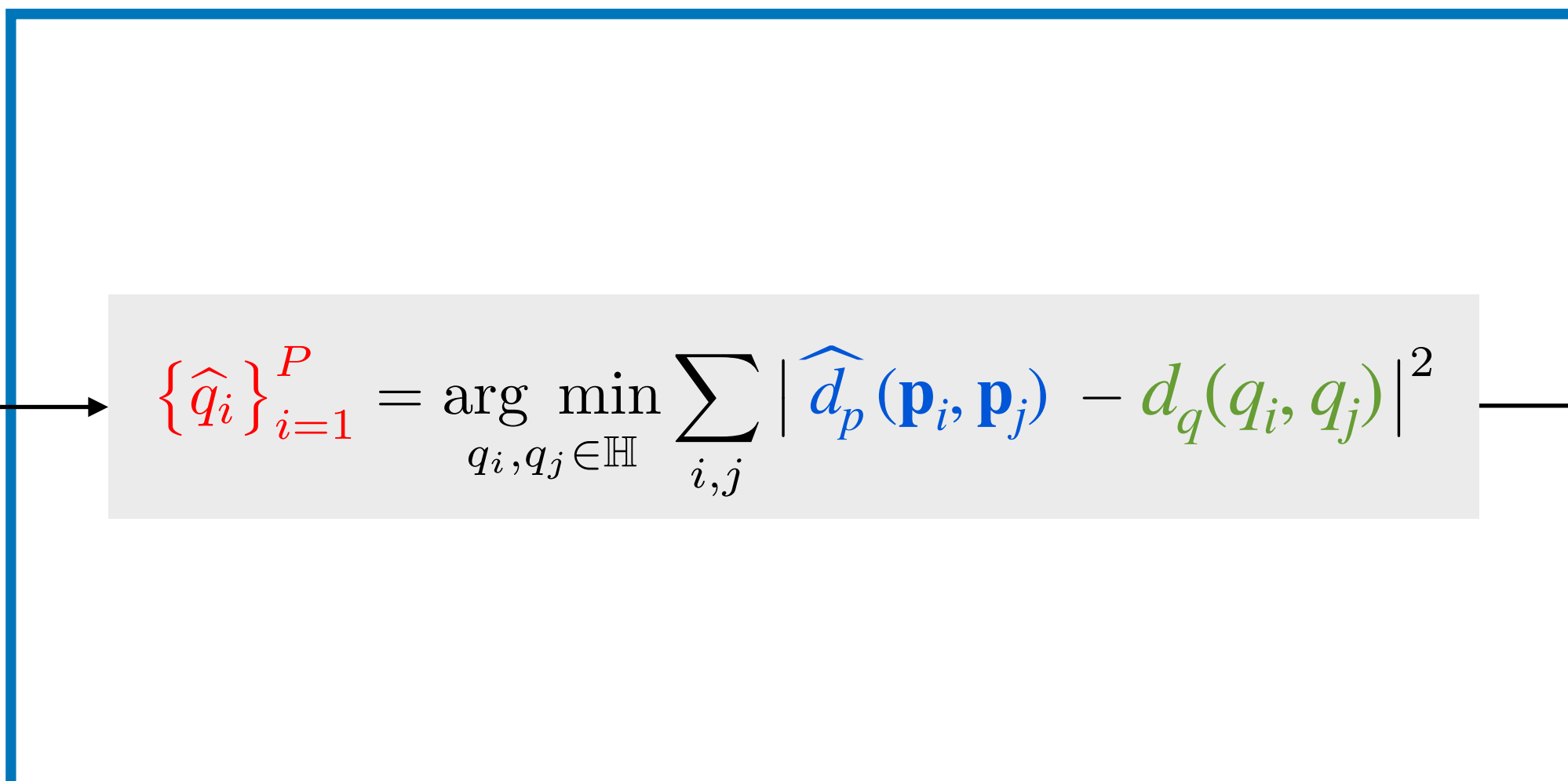
## Step 1: Estimate Distances



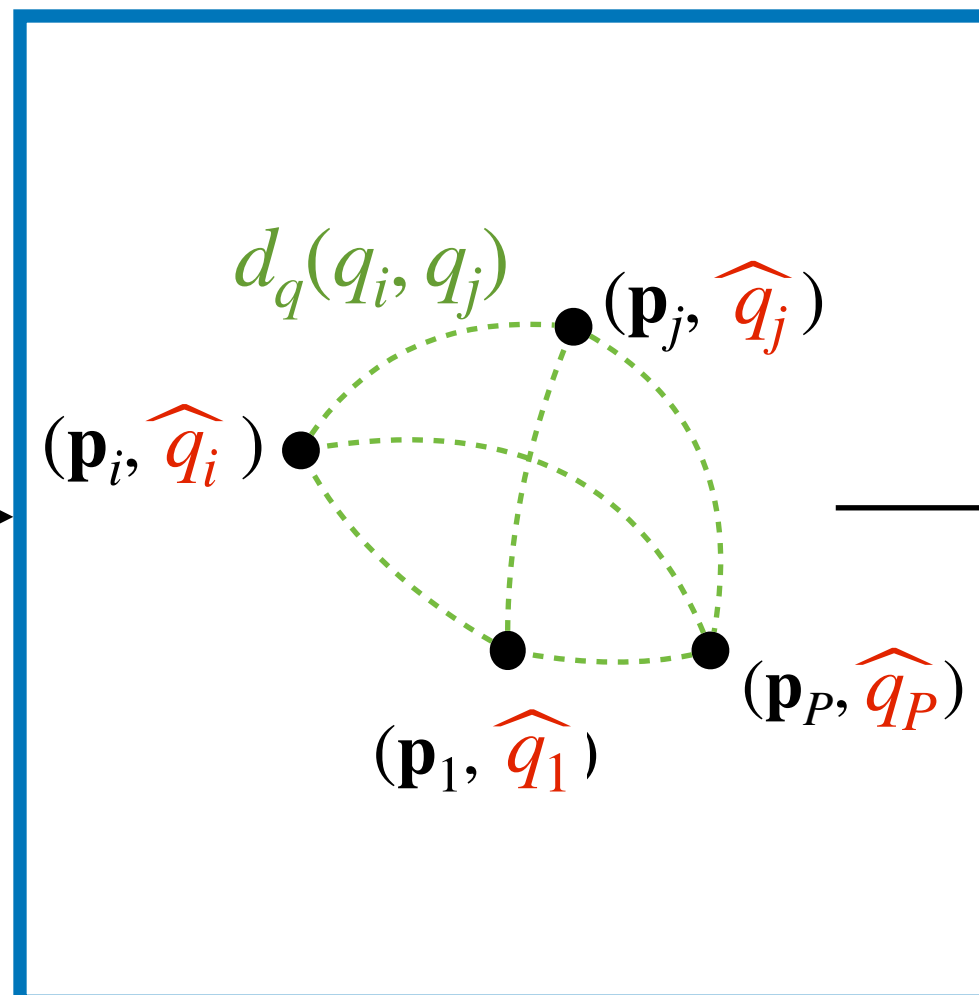
## Intermediate Representation



## Step 2: Recover Orientations



## Intermediate Representation



## Outputs: Recovered Orientations

