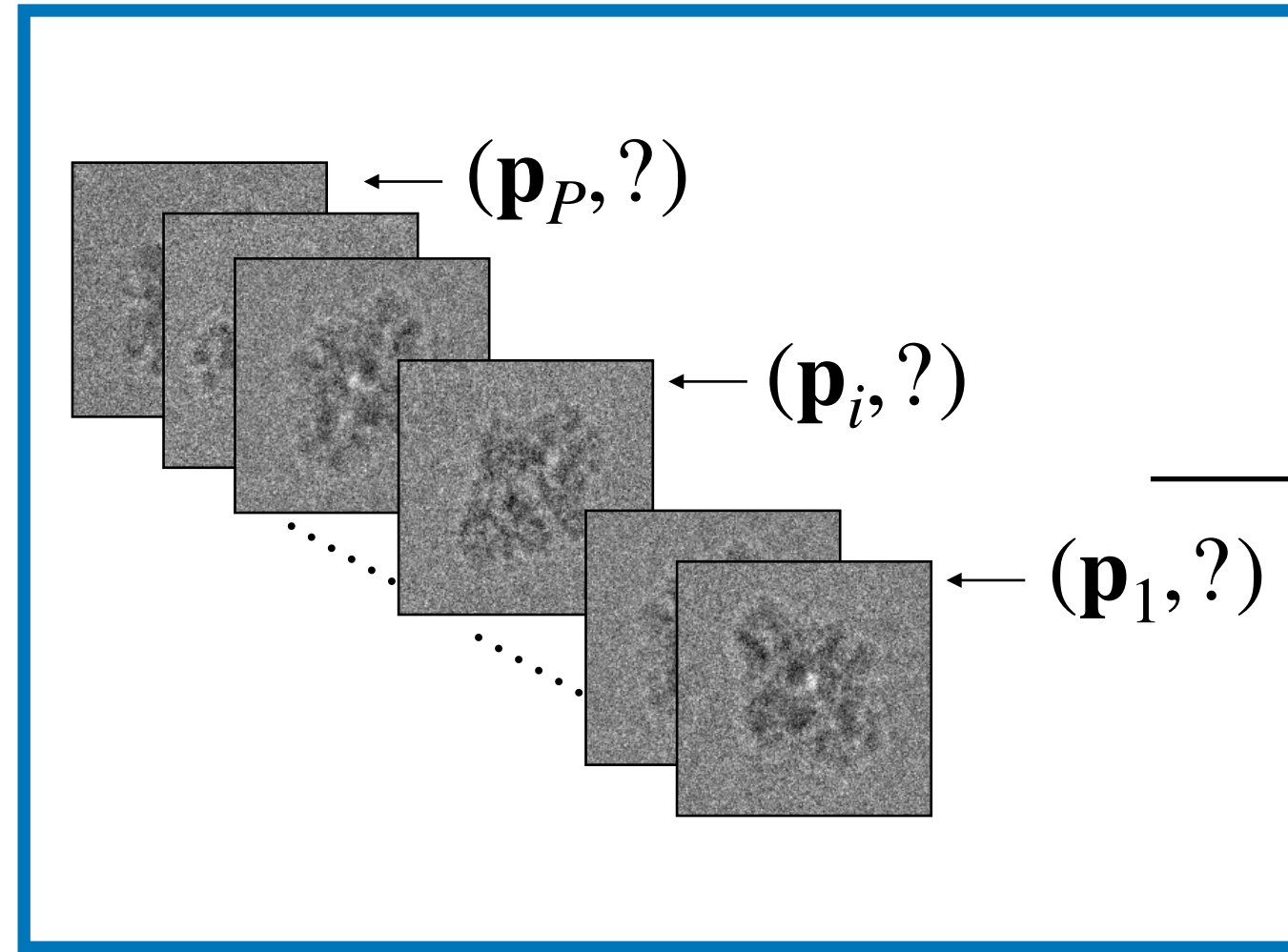
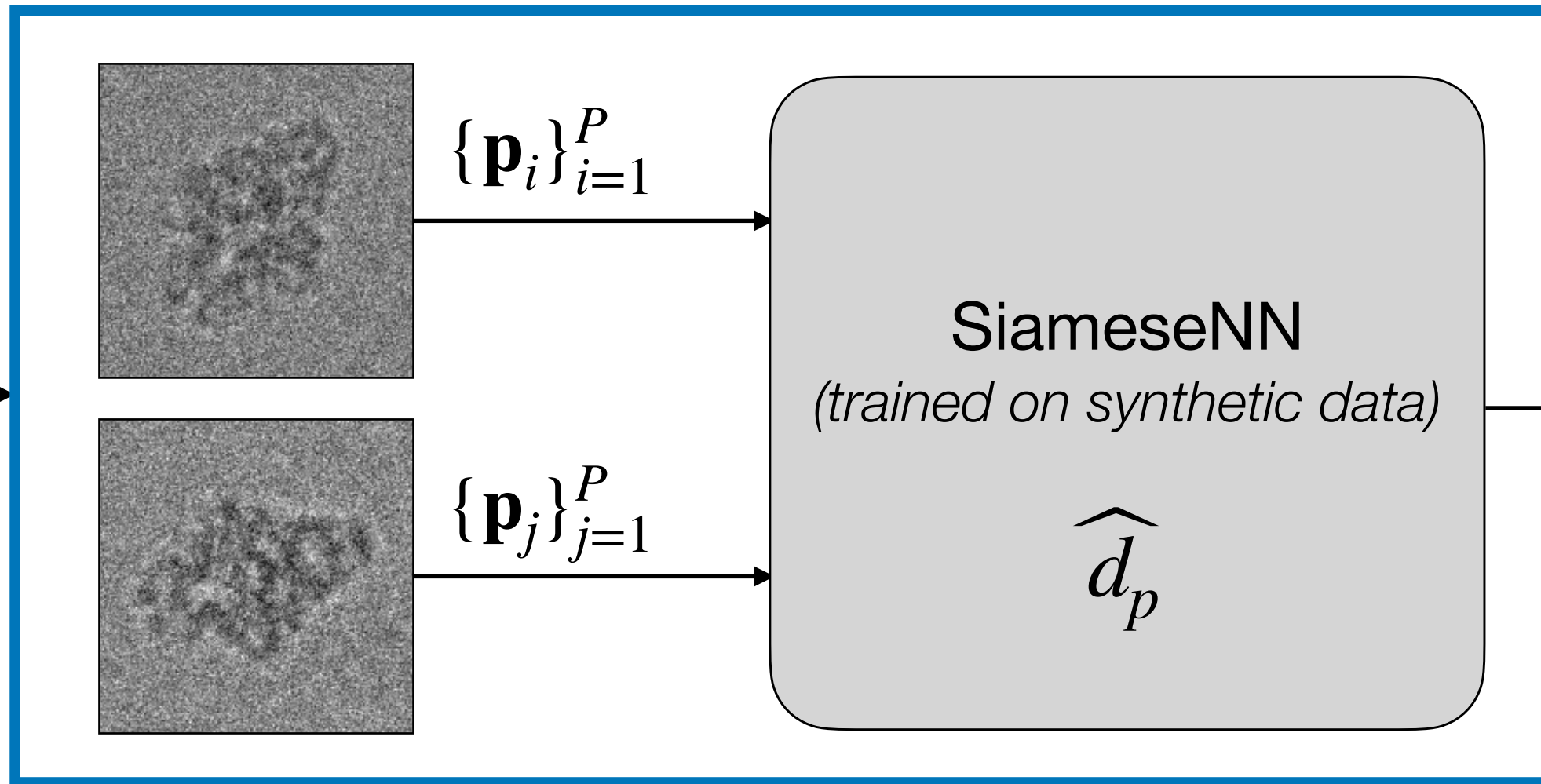


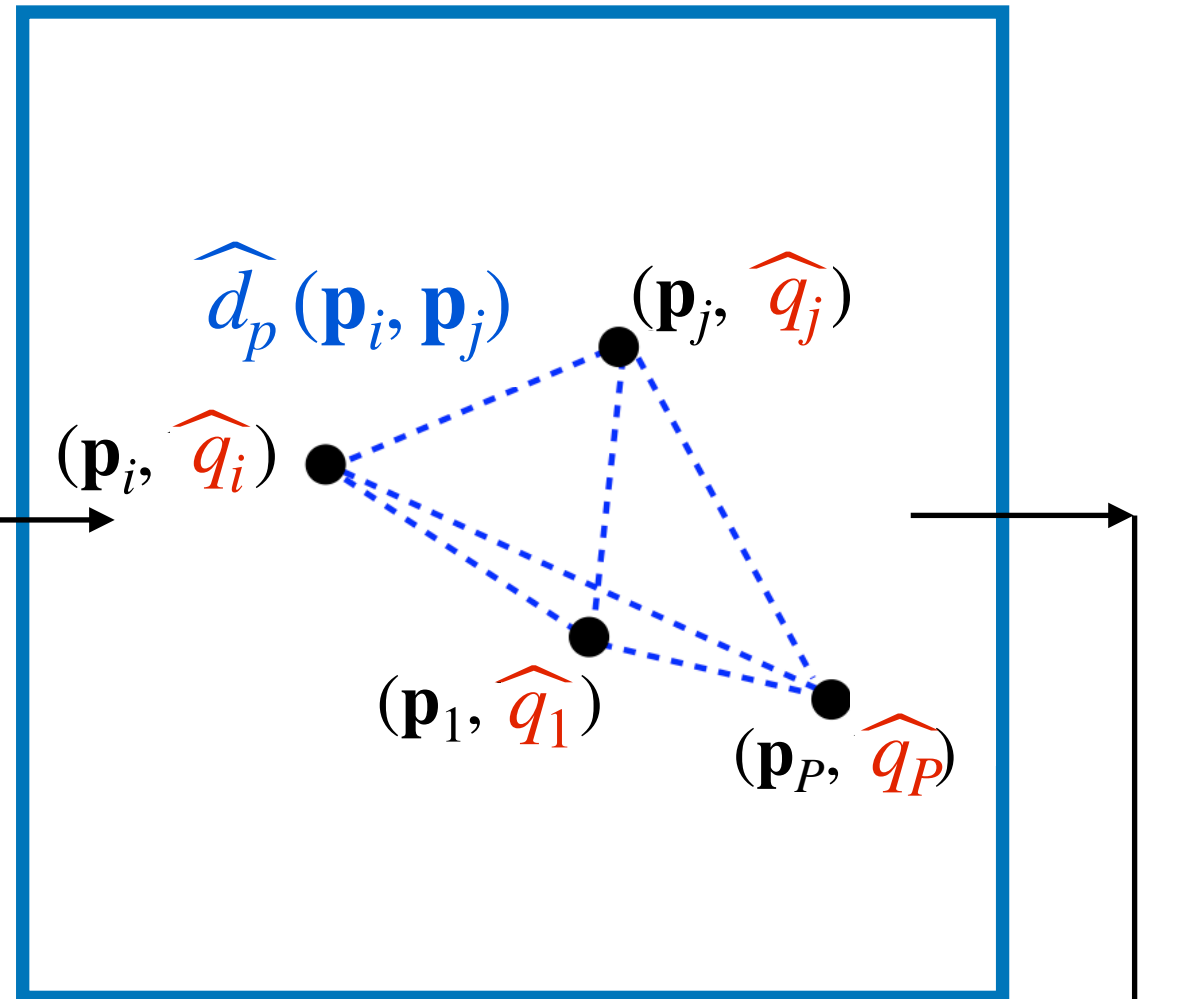
Inputs: Acquired Projection Dataset



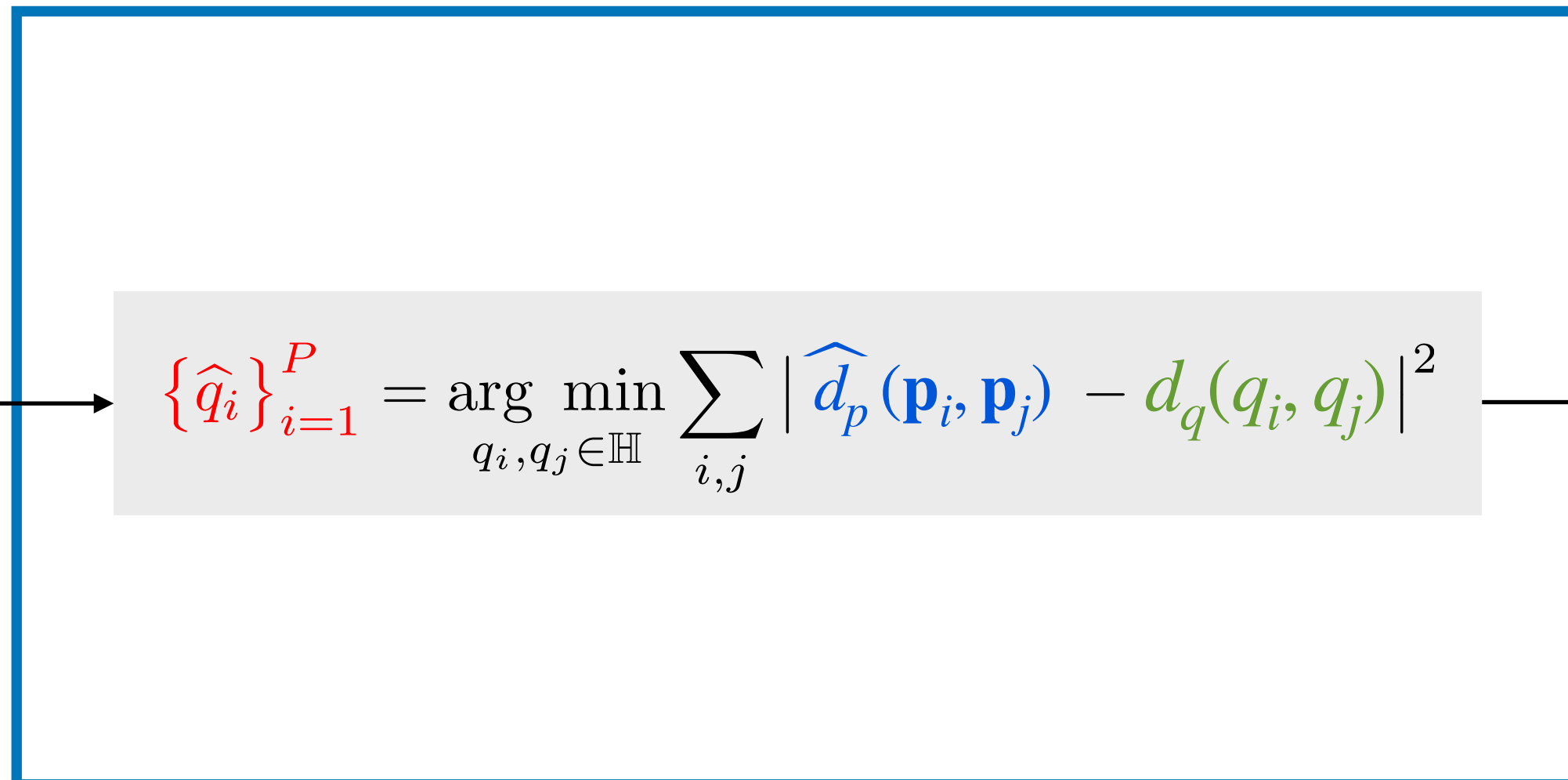
Step 1: Estimate Distances



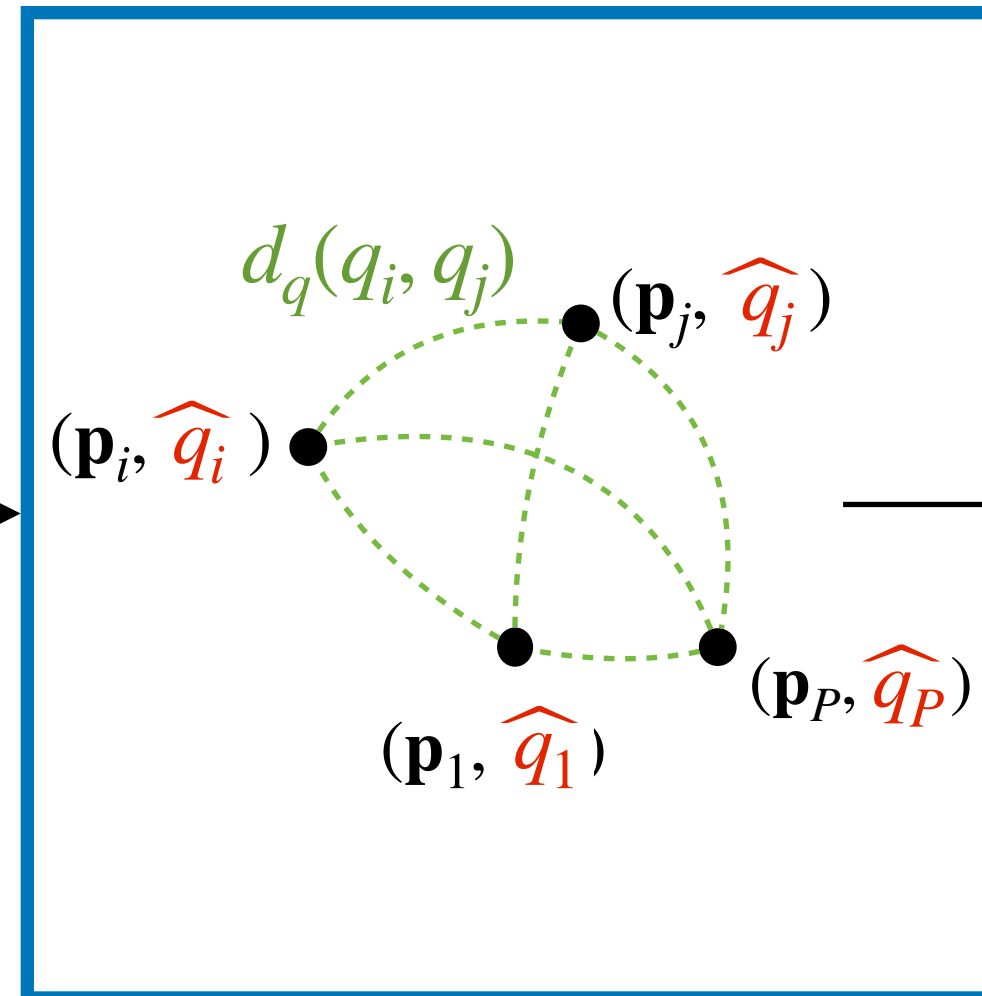
Intermediate Representation



Step 2: Recover Orientations



Intermediate Representation



Outputs: Recovered Orientations

