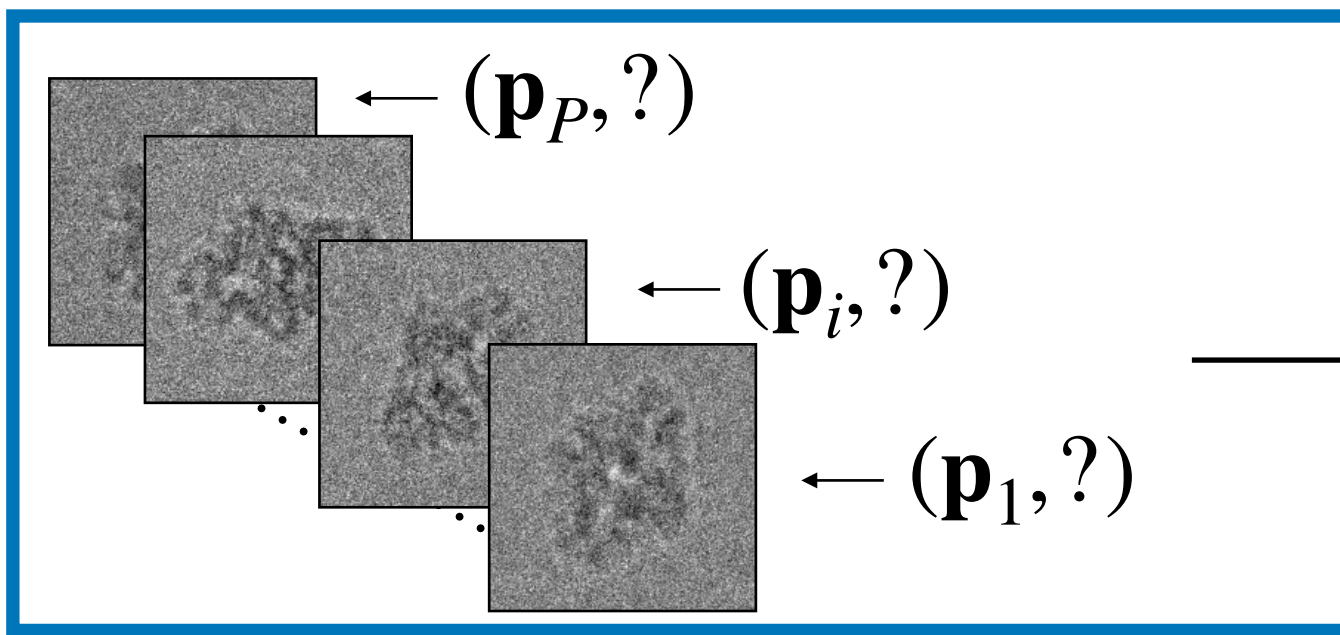
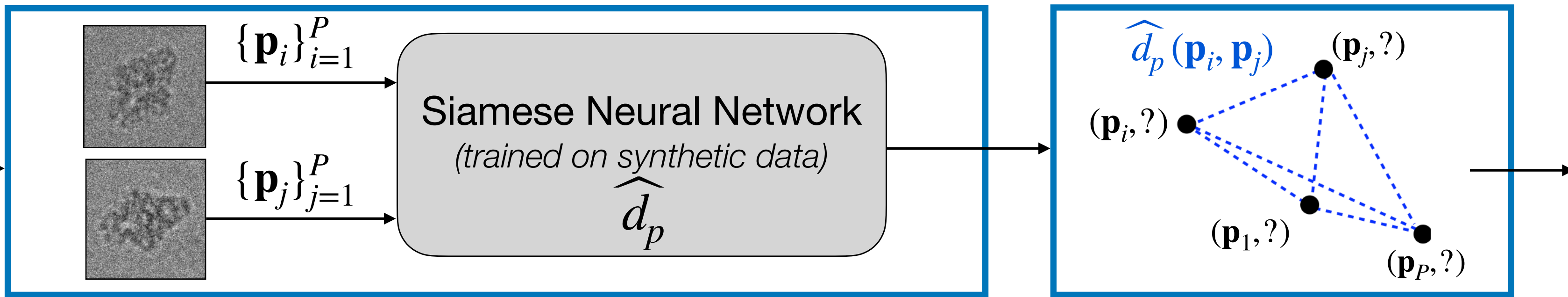


Inputs: Acquired Projection Dataset



Step 1: Estimate Distances



Step 2: Recover Orientations

