

Initial Proposed Thesis Timeline

Master Thesis Initial Timeline		Start date: 14/08/2023		August		September				October				November		December		January				February	
Milestones	Progress	w3	w4	w1	w2	w3	w4	w1	w2	w3	w4	w1	w2	w3	w4	w1	w2	w3	w4	w1	w2	w3	w4
Literature Review	In progress																						
Data Acquisition System																							
Familiarization/Setup and Pilot Testing	Not started																						
Design Data Synchronizorization System and Data Fusion	Not started																						
Finalize Stress Detection Algorithm																							
Experimental Phase																							
Experimental Design & Initial Trial	Not started																						
Subject Study and Data Collection	Not started																						
Data Analysis and Evaluation	Not started																						
Final Phase																							
Implement Robot Feedback	Not started																						
Initial Drafting of Results	Not started																						
Thesis Writing																							

Up-to-date Timeline: [Thesis Roadmap.xlsx](#)

Detailed Tasks

August W3&W4- Literature Review, Project Planning

- Deep dive into literature review and understand current state of the art.
- Refine project plane w.r.t to Literature review

Aug W4-Sept W1 -Familiarization/Setup and Pilot Testing

- Familiarize yourself and set up all sensor systems: wristband for physiological data, motion capture system for posture etc
- Develop the data acquisition system and Initial testing

Sep W2&W3- Design Data Synchronization System and Data Fusion

- Begin designing the data synchronization strategy.
- Develop the data fusion algorithms, combining physiological data, posture data, and potentially EEG data.

Sep W3&W4 Develop measure of stress Algorithm

- Extract features that can be indicators of stress.
- Finalize a working Algorithm

Oct W1&W2- Experimental Design & Initial Trial

- Plan the experiments(considering the procedure, subject selection, order of trials,), considering the different levels of robot-human interaction and the three types of robot controllers: Default, static collision avoidance, and predictive collision avoidance.
- Conduct initial trials to ensure the setup is working correctly and to refine any procedures.

Oct W3-Nov W2 Subject Study and Data Collection

- Recruit participants and begin the subject study, collecting both physiological and behavioral data.

Nov W3-Nov W4 : Data Analysis and Evaluation

- Begin data analysis and evaluation of human stress levels for different cooperation and control approaches.
- Refine Algorithm based on initial findings

Dec W1-Dec W2 : Buffer Period

- Finish any pending tasks.

Dec W3&Jan W2-

- Optionally, implement the feedback mechanism for the robot based on detected human stress levels.

Dec W4 & Jan W1 -Initial Drafting of Results

Jan W3-Feb W2- Thesis Results