

Scenario	Trial	Robot	Initial Position	Connected To	Time to Connect (s)
Scenario 1	1	Robot_0	(2.0, -0.4)	robot_1	1,08
Scenario 1	1	Robot_1	(-2.2, -0.4)	robot_2	0,88
Scenario 1	1	Robot_2	(0.0, 2.8)	robot_1	1,99
Scenario 1	2	Robot_0	(2.0, -0.4)	robot_1	0,75
Scenario 1	2	Robot_1	(-2.2, -0.4)	robot_2	2,30
Scenario 1	2	Robot_2	(0.0, 2.8)	robot_1	1,44
Scenario 1	3	Robot_0	(2.0, -0.4)	robot_1	0,89
Scenario 1	3	Robot_1	(-2.2, -0.4)	robot_2	0,79
Scenario 1	3	Robot_2	(0.0, 2.8)	robot_1	0,97
Scenario 1	4	Robot_0	(2.0, -0.4)	robot_1	0,80
Scenario 1	4	Robot_1	(-2.2, -0.4)	robot_2	0,88
Scenario 1	4	Robot_2	(0.0, 2.8)	robot_1	1,26
Scenario 1	5	Robot_0	(2.0, -0.4)	robot_1	0,78
Scenario 1	5	Robot_1	(-2.2, -0.4)	robot_2	1,57
Scenario 1	5	Robot_2	(0.0, 2.8)	robot_1	0,79

Scenario	Trial	Robot	Initial Position	Connected To	Time to Connect (s)
Scenario 2		1 Robot_0	(0.0, -3.1)	robot_1	1,48
Scenario 2		1 Robot_1	(-2.2, -0.4)	robot_2	0,84
Scenario 2		1 Robot_2	(0.0, 2.8)	robot_1	0,84
Scenario 2		2 Robot_0	(0.0, -3.1)	robot_1	0,77
Scenario 2		2 Robot_1	(-2.2, -0.4)	robot_2	2,18
Scenario 2		2 Robot_2	(0.0, 2.8)	robot_1	0,77
Scenario 2		3 Robot_0	(0.0, -3.1)	robot_1	1,50
Scenario 2		3 Robot_1	(-2.2, -0.4)	robot_2	0,89
Scenario 2		3 Robot_2	(0.0, 2.8)	robot_1	0,99
Scenario 2		4 Robot_0	(0.0, -3.1)	robot_1	1,80
Scenario 2		4 Robot_1	(-2.2, -0.4)	robot_2	0,79
Scenario 2		4 Robot_2	(0.0, 2.8)	robot_1	1,07
Scenario 2		5 Robot_0	(0.0, -3.1)	robot_1	0,88
Scenario 2		5 Robot_1	(-2.2, -0.4)	robot_2	0,78
Scenario 2		5 Robot_2	(0.0, 2.8)	robot_1	0,86

Scenario	Trial	Robot	Initial Position	Connected To	Time to Connect (s)
Scenario 3	1	Robot_0	(0.0, -3.1)	robot_1	1,12
Scenario 3	1	Robot_1	(2.4, -3.2)	robot_2	0,84
Scenario 3	1	Robot_2	(0.0, 2.8)	robot_0	0,84
Scenario 3	2	Robot_0	(0.0, -3.1)	robot_1	1,02
Scenario 3	2	Robot_1	(2.4, -3.2)	robot_2	0,82
Scenario 3	2	Robot_2	(0.0, 2.8)	robot_0	1,32
Scenario 3	3	Robot_0	(0.0, -3.1)	robot_1	0,77
Scenario 3	3	Robot_1	(2.4, -3.2)	robot_2	0,84
Scenario 3	3	Robot_2	(0.0, 2.8)	robot_0	1,72
Scenario 3	4	Robot_0	(0.0, -3.1)	robot_1	0,64
Scenario 3	4	Robot_1	(2.4, -3.2)	robot_2	1,84
Scenario 3	4	Robot_2	(0.0, 2.8)	robot_0	0,74
Scenario 3	5	Robot_0	(0.0, -3.1)	robot_1	0,73
Scenario 3	5	Robot_1	(2.4, -3.2)	robot_2	1,13
Scenario 3	5	Robot_2	(0.0, 2.8)	robot_0	1,53

Scenario	Trial	Robot	Initial Position	Connected To	Time to Connect (s)
Scenario 4	1	Robot_0	(0.0, -3.1)	robot_1	1,12
Scenario 4	1	Robot_1	(2.4, -3.2)	robot_2	0,84
Scenario 4	1	Robot_2	(1.6, -0.44)	robot_0	0,84
Scenario 4	2	Robot_0	(0.0, -3.1)	robot_1	0,86
Scenario 4	2	Robot_1	(2.4, -3.2)	robot_2	0,76
Scenario 4	2	Robot_2	(1.6, -0.44)	robot_0	0,96
Scenario 4	3	Robot_0	(0.0, -3.1)	robot_1	1,43
Scenario 4	3	Robot_1	(2.4, -3.2)	robot_2	0,82
Scenario 4	3	Robot_2	(1.6, -0.44)	robot_0	0,82
Scenario 4	4	Robot_0	(0.0, -3.1)	robot_1	1,99
Scenario 4	4	Robot_1	(2.4, -3.2)	robot_2	0,80
Scenario 4	4	Robot_2	(1.6, -0.44)	robot_0	0,80
Scenario 4	5	Robot_0	(0.0, -3.1)	robot_1	1,92
Scenario 4	5	Robot_1	(2.4, -3.2)	robot_2	0,94
Scenario 4	5	Robot_2	(1.6, -0.44)	robot_0	1,94

Scenario	Trial	Robot	Initial Position	Connected To	Time to Connect (s)
Scenario 5		1 Robot_0	(4.5, -5.8)	robot_2	0,79
Scenario 5		1 Robot_1	(2.4, -3.2)	robot_2	0,90
Scenario 5		1 Robot_2	(6.5, -3.1)	robot_0	0,70
Scenario 5		2 Robot_0	(4.5, -5.8)	robot_2	0,87
Scenario 5		2 Robot_1	(2.4, -3.2)	robot_2	0,78
Scenario 5		2 Robot_2	(6.5, -3.1)	robot_0	0,77
Scenario 5		3 Robot_0	(4.5, -5.8)	robot_2	0,78
Scenario 5		3 Robot_1	(2.4, -3.2)	robot_2	0,82
Scenario 5		3 Robot_2	(6.5, -3.1)	robot_0	0,66
Scenario 5		4 Robot_0	(4.5, -5.8)	robot_2	1,36
Scenario 5		4 Robot_1	(2.4, -3.2)	robot_2	1,18
Scenario 5		4 Robot_2	(6.5, -3.1)	robot_0	0,78
Scenario 5		5 Robot_0	(4.5, -5.8)	robot_2	1,08
Scenario 5		5 Robot_1	(2.4, -3.2)	robot_2	0,87
Scenario 5		5 Robot_2	(6.5, -3.1)	robot_0	0,69

Scenario	Robot	N	Mean (s)
Scenario 1	Robot_0	5,00	0,86
Scenario 1	Robot_1	5,00	1,28
Scenario 1	Robot_2	5,00	1,29
Scenario 2	Robot_0	5,00	1,29
Scenario 2	Robot_1	5,00	1,10
Scenario 2	Robot_2	5,00	0,91
Scenario 3	Robot_0	5,00	0,86
Scenario 3	Robot_1	5,00	1,09
Scenario 3	Robot_2	5,00	1,23
Scenario 4	Robot_0	5,00	1,46
Scenario 4	Robot_1	5,00	0,83
Scenario 4	Robot_2	5,00	1,07
Scenario 5	Robot_0	5,00	0,98
Scenario 5	Robot_1	5,00	0,91
Scenario 5	Robot_2	5,00	0,72