

# Lecture 13: Dynamic Programming II

Michael Dinitz

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601.433/633 Introduction to Algorithms

# Introduction

Today: two more examples of dynamic programming

- ▶ *Longest Common Subsequence* (strings)
- ▶ *Optimal Binary Search Tree* (trees)

Important problems, but really: more examples of dynamic programming

Both in CLRS (unlike Weighted Interval Scheduling)

# Longest Common Subsequence

# Definitions

**String:** Sequence of elements of some *alphabet* ( $\{0, 1\}$ , or  $\{\mathbf{A} - \mathbf{Z}\} \cup \{\mathbf{a} - \mathbf{z}\}$ , etc.)

**Definition:** A sequence  $\mathbf{Z} = (z_1, \dots, z_k)$  is a *subsequence* of  $\mathbf{X} = (x_1, \dots, x_m)$  if there exists a strictly increasing sequence  $(i_1, i_2, \dots, i_k)$  such that  $x_{i_j} = z_j$  for all  $j \in \{1, 2, \dots, k\}$ .

**Example:**  $(B, C, D, B)$  is a subsequence of  $(A, B, C, B, D, A, B)$

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**Definition:** In *Longest Common Subsequence* problem (LCS) we are given two strings  $X = (x_1, \dots, x_m)$  and  $Y = (y_1, \dots, y_n)$ . Need to find the longest  $Z$  which is a subsequence of both  $X$  and  $Y$ .

# Subproblems

First and most important step of dynamic programming: define subproblems!

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- ▶  $\mathbf{Y}_j = (y_1, y_2, \dots, y_j)$  (so  $\mathbf{Y} = \mathbf{Y}_n$ )

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Two-dimensional table!

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Second step of dynamic programming: prove optimal substructure

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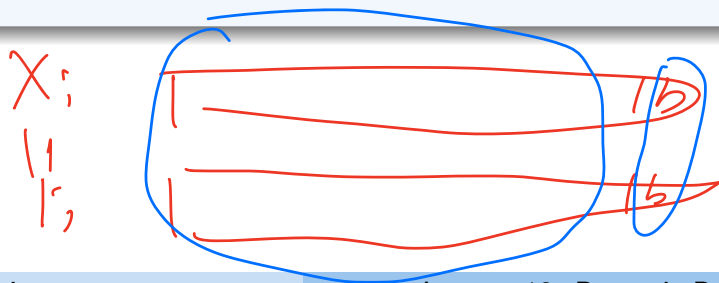
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# Optimal Substructure: Proof (I)

**Case 1:** If  $x_i = y_j$ , then  $z_k = x_i = y_j$  and  $Z_{k-1} = OPT(i-1, j-1)$

Proof Sketch.

Contradiction.

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**Part 2:** Suppose  $Z_{k-1} \neq \text{OPT}(i-1, j-1)$ .

$\Rightarrow \exists W$  LCS of  $X_{i-1}, Y_{j-1}$  of length  $> k-1 \Rightarrow \geq k$

$\Rightarrow (W, a)$  common subsequence of  $X_i, Y_j$  of length  $> k$

▶ Contradiction to  $Z$  being LCS of  $X_i$  and  $Y_j$



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## Optimal Substructure: Proof (III)

**Case 3:** If  $x_i \neq y_j$  and  $z_k \neq y_j$  then  $Z = OPT(i, j - 1)$

Proof.

Symmetric to Case 2. □

# Structure Corollary

Corollary

$(OPT(i-1, j-1), x_i)$

$$OPT(i, j) = \begin{cases} \emptyset & \text{if } i = 0 \text{ or } j = 0, \\ OPT(i-1, j-1) \circ x_i & \text{if } i, j > 0 \text{ and } x_i = y_j \\ \max(OPT(i, j-1), OPT(i-1, j)) & \text{if } i, j > 0 \text{ and } x_i \neq y_j \end{cases}$$

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Gives obvious recursive algorithm

- ▶ Can take exponential time (good exercise at home!)

Dynamic Programming!

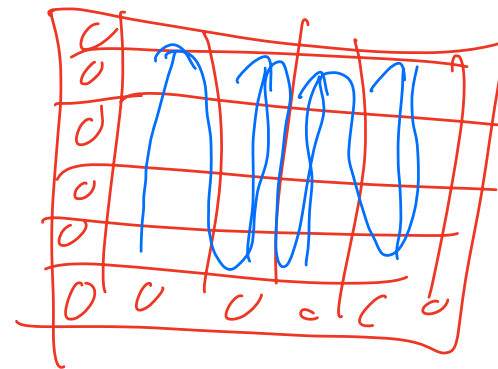
- ▶ Top-Down: are problems getting “smaller”? What does “smaller” mean?
- ▶ Bottom-Up: two-dimensional table! What order to fill it in?

# Dynamic Programming Algorithm

```
LCS(X,Y) {  
  for( $i = 0$  to  $m$ )  $M[i, 0] = 0$ ;  
  for( $j = 0$  to  $n$ )  $M[0, j] = 0$ ;  
  for( $i = 1$  to  $m$ ) {  
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Running Time:  $O(mn)$

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*align*

*induction*

*S T*

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3. If  $x_i \neq y_j$ , then

$$\begin{aligned} M[i, j] &= \max(M[i, j - 1], M[i - 1, j]) && \text{(def of algorithm)} \\ &= \max(|OPT(i, j - 1)|, |OPT(i - 1, j)|) && \text{(induction)} \\ &= |OPT(i, j)| && \text{(structure thm/corollary)} \end{aligned}$$

# Computing a Solution

Like we talked about last lecture: backtrack through dynamic programming table.

Details in CLRS 14.4

# Optimal Binary Search Trees

# Problem Definition

Input: probability distribution / search frequency of keys

- ▶  $n$  distinct keys  $k_1 < k_2 < \dots < k_n$
- ▶ For each  $i \in [n]$ , probability  $p_i$  that we search for  $k_i$  (so  $\sum_{i=1}^n p_i = 1$ )

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Cost of searching for  $k_i$  in tree  $T$  is  $\text{depth}_T(k_i) + 1$  (say depth of root = 0)

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**Definition:**  $c(T) = \sum_{i=1}^n p_i (\text{depth}_T(k_i) + 1)$

Problem: Find search tree  $T$  minimizing cost.

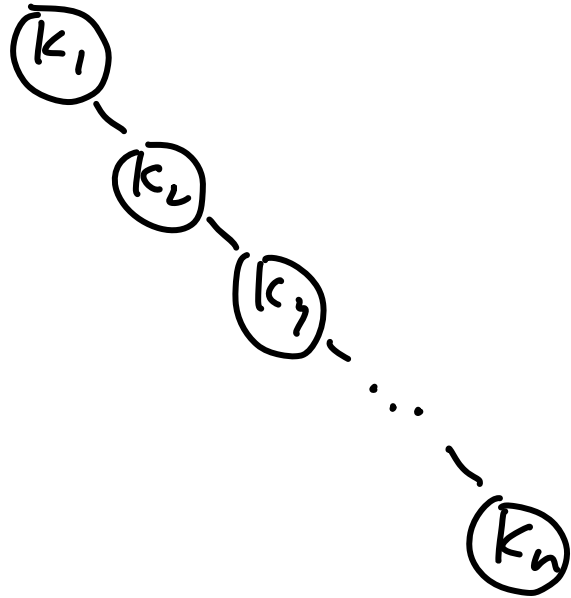
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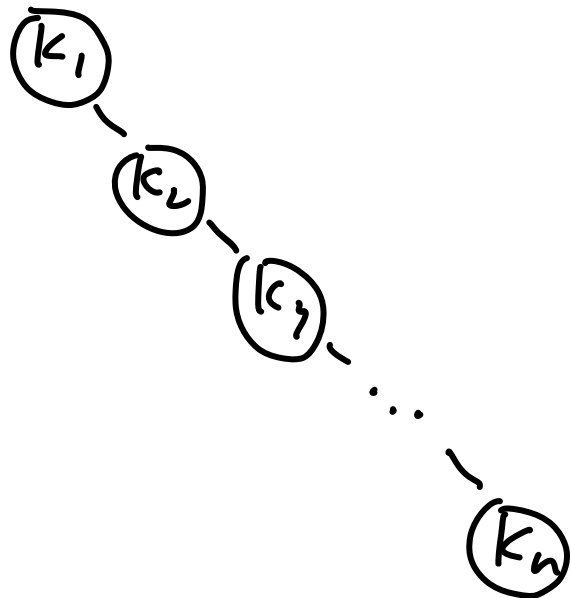
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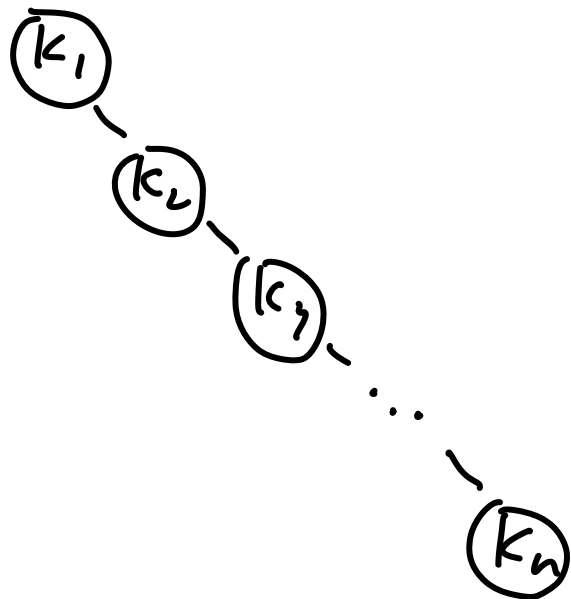


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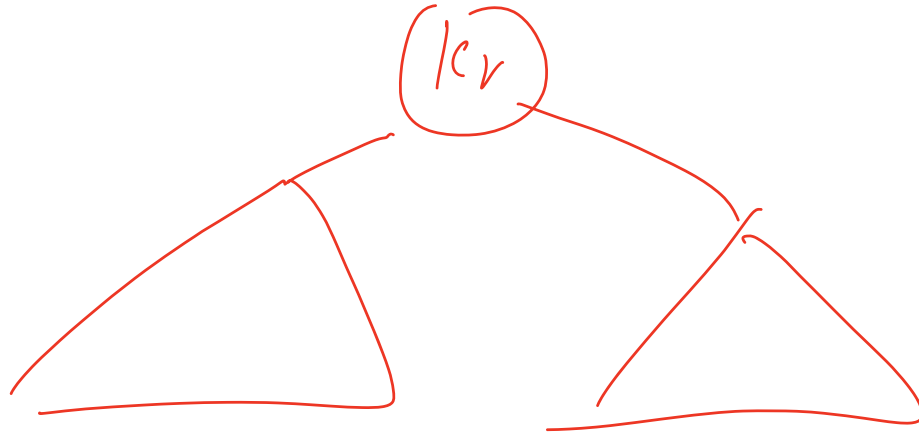


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$$\text{Balanced search tree: } E[\text{cost}] \leq O(\log n)$$

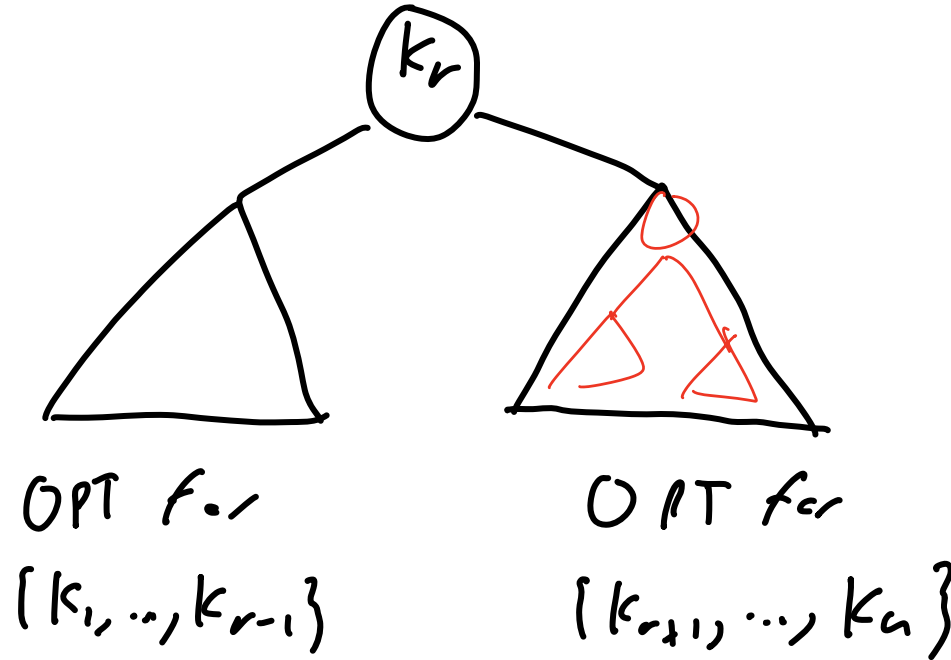
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By convention, if  $i > j$  then  $OPT(i, j)$  empty  
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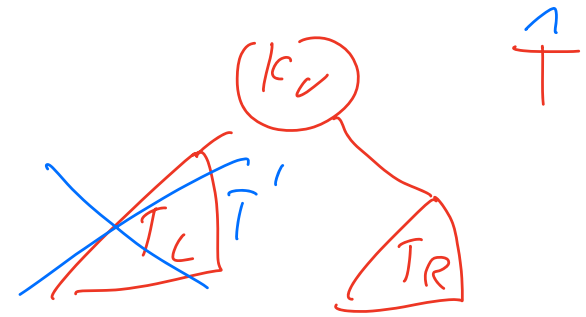
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## Theorem (Optimal Substructure)

*Let  $k_r$  be the root of  $\mathbf{OPT}(i, j)$ . Then the left subtree of  $\mathbf{OPT}(i, j)$  is  $\mathbf{OPT}(i, r - 1)$ , and the right subtree of  $\mathbf{OPT}(i, j)$  is  $\mathbf{OPT}(r + 1, j)$ .*

# Proof Sketch of Optimal Substructure



Definitions:

- ▶ Let  $T = \text{OPT}(i, j)$ ,  $T_L$  its left subtree,  $T_R$  its right subtree.
- ▶ Suppose for contradiction  $T_L \neq \text{OPT}(i, r-1)$ , let  $T' = \text{OPT}(i, r-1)$   
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Whole bunch of math (see lecture notes): get that  $c(\hat{T}) < c(T)$

Contradicts  $T = \text{OPT}(i, j)$

# Proof Sketch of Optimal Substructure

Definitions:

- ▶ Let  $T = \text{OPT}(i, j)$ ,  $T_L$  its left subtree,  $T_R$  its right subtree.
- ▶ Suppose for contradiction  $T_L \neq \text{OPT}(i, r - 1)$ , let  $T' = \text{OPT}(i, r - 1)$   
 $\implies c(T') < c(T_L)$  (def of  $\text{OPT}(i, r - 1)$ )
- ▶ Let  $\hat{T}$  be tree get by replacing  $T_L$  with  $T'$

Whole bunch of math (see lecture notes): get that  $c(\hat{T}) < c(T)$

Contradicts  $T = \text{OPT}(i, j)$

Symmetric argument works for  $T_R = \text{OPT}(r + 1, j)$

# Cost Corollary

## Corollary

$$c(OPT(i, j)) = \sum_{a=i}^j p_a + \min_{i \leq r \leq j} (c(OPT(i, r-1)) + c(OPT(r+1, j)))$$

Let  $k_r$  be root of  $OPT(i, j)$

$$c(OPT(i, j)) = \sum_{a=i}^j p_a (\text{depth}_{OPT(i, j)}(k_a) + 1) \quad \text{def}$$

ST  $\rightarrow$

$$= \sum_{a=i}^{r-1} (p_a (\text{depth}_{OPT(i, r-1)}(k_a) + 2)) + p_r + \sum_{a=r+1}^j p_a (\text{depth}_{OPT(r+1, j)}(k_a) + 2)$$

algebra  $\rightarrow$

$$= \sum_{a=i}^j p_a + \sum_{a=i}^{r-1} (p_a (\text{depth}_{OPT(i, r-1)}(k_a) + 1)) + \sum_{a=r+1}^j p_a (\text{depth}_{OPT(r+1, j)}(k_a) + 1)$$

def cost  $\rightarrow$

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$$\begin{aligned} c(\text{OPT}(i, j)) &= \sum_{a=i}^j p_a (\text{depth}_{\text{OPT}(i, j)}(k_a) + 1) \\ &= \sum_{a=i}^{r-1} (p_a (\text{depth}_{\text{OPT}(i, r-1)}(k_a) + 2)) + p_r + \sum_{a=r+1}^j p_a (\text{depth}_{\text{OPT}(r+1, j)}(k_a) + 2) \\ &= \sum_{a=i}^j p_a + \sum_{a=i}^{r-1} (p_a (\text{depth}_{\text{OPT}(i, r-1)}(k_a) + 1)) + \sum_{a=r+1}^j p_a (\text{depth}_{\text{OPT}(r+1, j)}(k_a) + 1) \\ &= \sum_{a=i}^j p_a + c(\text{OPT}(i, r-1)) + c(\text{OPT}(r+1, j)). \end{aligned}$$

Same logic holds for any possible root  $\implies$  take min

# Algorithm

Fill in table  $M$ :

$$M[i, j] = \begin{cases} 0 & \text{if } i > j \\ \min_{i \leq r \leq j} \left( \sum_{a=i}^j p_a + M[i, r-1] + M[r+1, j] \right) & \text{if } i \leq j \end{cases}$$

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- ▶ Base case: if  $j - i < 0$  then  $M[i, j] = OPT(i, j) = 0$
- ▶ Inductive step:

$$M[i, j] = \min_{i \leq r \leq j} \left( \sum_{a=i}^j p_a + M[i, r-1] + M[r+1, j] \right) \quad (\text{alg def})$$

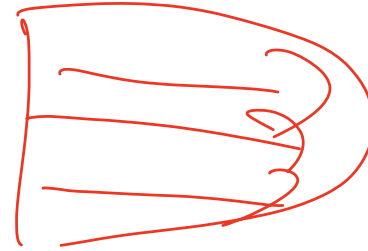
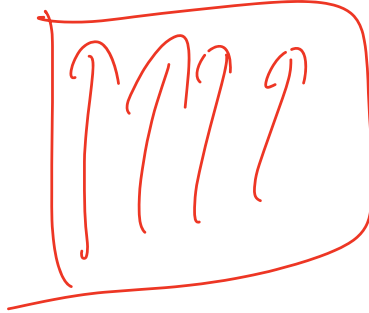
$$= \min_{i \leq r \leq j} \left( \sum_{a=i}^j p_a + c(OPT(i, r-1)) + c(OPT(r+1, j)) \right) \quad (\text{induction})$$

$$= c(OPT(i, j)) \quad (\text{cost corollary})$$

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What order to fill the table in?

- ▶ Obvious approach: for( $i = 1$  to  $n - 1$ ) for( $j = i + 1$  to  $n$ ) Doesn't work!

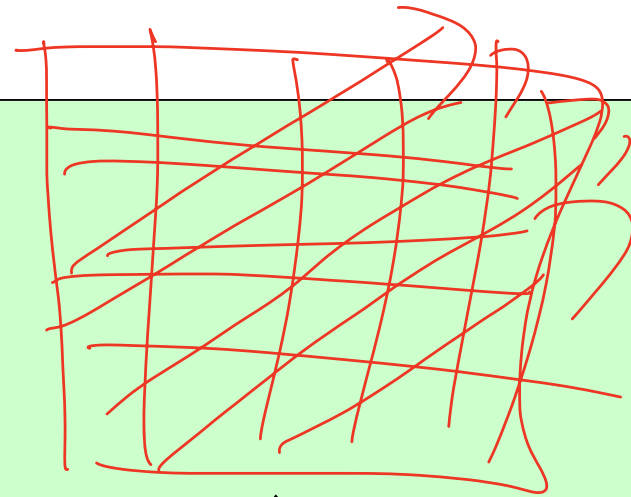


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- ▶ Take hint from induction:  $j - i$

```
OBST {  
  Set  $M[i, j] = 0$  for all  $j > i$ ;  
  Set  $M[i, i] = p_i$  for all  $i$   
  for( $\ell = 1$  to  $n - 1$ ) {  
    for( $i = 1$  to  $n - \ell$ ) {  
       $j = i + \ell$   
       $M[i, j] = \min_{i \leq r \leq j} \left( \sum_{a=i}^j p_a + M[i, r - 1] + M[r + 1, j] \right)$ ;  
    }  
  }  
  return  $M[1, n]$ ;  
}
```



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**Correctness:** same as top-down

**Running Time:**

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Total running time:  $O(n^3)$

# Bonus Content

**Obvious Question:** Robustness.

- ▶ What if given distribution is *wrong*?

Want algorithm that gives a solution with cost a function of true optimal cost, “distance” between given distribution and true distribution.

Dinitz, Im, Lavastida, Moseley, Niaparast, Vassilvitskii. *Binary Search Trees with Distributional Predictions*. NeurIPS '24