

Lecture 22: Linear Programming

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601.433/633 Introduction to Algorithms

Introduction

Today: What, why, and just ~~how~~ a taste of how

- ▶ Entire course on linear programming over in AMS. Super important topic!
- ▶ Fast algorithms in theory and in practice.

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- ▶ Entire course on linear programming over in AMS. Super important topic!
- ▶ Fast algorithms in theory and in practice.

Why: Even more general than max-flow, can still be solved in polynomial time!

- ▶ Max flow important in its own right, but also because it can be used to solve many other things (max bipartite matching)
- ▶ Linear programming: important in its own right, but also even more general than max-flow.
- ▶ Can model many, many problems!

Example: Planning Your Week

168 hours in a week. How much time to spend:

- ▶ Studying (***S***)
- ▶ Partying (***P***)
- ▶ Everything else (***E***)

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- ▶ Studying (S)
 - ▶ Partying (P)
 - ▶ Everything else (E)
- ▶ $E \geq 56$ (at least 8 hours/day sleep, shower, etc.)
 - ▶ $P + E \geq 70$ (need to stay sane)
 - ▶ $S \geq 60$ (to pass your classes)
 - ▶ $2S + E - 3P \geq 150$ (too much partying requires studying or sleep)

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- ▶ Yes! $S = 80$, $P = 20$, $E = 68$

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Question: Suppose “happiness” is $2P + 3E$. Can we find a feasible solution maximizing this?

Linear Programming

$$\left[\begin{array}{c} \text{L} \\ \text{C} \\ \text{J} \end{array} \right] \left[\begin{array}{c} x \\ \leq \\ \geq \end{array} \right] \geq S$$

Input (a “linear program”):

- ▶ n variables x_1, \dots, x_n (take values in \mathbb{R})
- ▶ m *non-strict linear inequalities* in these variables (constraints)
 - ▶ E.g.: $3x_1 + 4x_2 \leq 6$, $0 \leq x_1 \leq 3$, $x_2 - 3x_3 + 2x_7 \leq 17$
 - ▶ Not allowed (examples): $x_2 x_3 \geq 5$, $x_4 < 2$, $x_5 + \log x_2 \geq 4$
- ▶ Possibly a *linear* objective function
 - ▶ $\max 2x_3 - 4x_5$, $\min \frac{5}{2}x_4 + x_2$, ...

$$\begin{aligned} & \max && S_{f_1} + 2x_2 - 7x_7 \\ \text{s.t.} & && x_1 - 110x_2 + 100x_7 \leq -S \\ & && \vdots \end{aligned}$$

Goals:

- ▶ Feasibility: Find values for x 's that satisfy all constraints
- ▶ Optimization: Find feasible solutions maximizing/minimizing objective function

Both achievable in polynomial time, reasonably fast!

Planning your week as an LP

Variables: P, E, S

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Planning your week as an LP

Variables: P, E, S

$$\max \quad 2P + E$$

subject to $E \geq 56$

$$S \geq 60$$

$$2S + E - 3P \geq 150$$

$$P + E \geq 70$$

$$P + S + E = 168$$

$$P \geq 0$$

$$S \geq 0$$

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When using an LP to model your problem, need to be sure that *all* aspects of your problem included!

Operations Research-style Example

Four different manufacturing plants for making cars:

	labor	materials	pollution
Plant 1	2	3	15
Plant 2	3	4	10
Plant 3	4	5	9
Plant 4	5	6	7

Operations Research-style Example

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- ▶ Need to produce at least **400** cars at plant 3 (labor agreement)
- ▶ Have **3300** total hours of labor, **4000** units of material
- ▶ Environmental law: produce at most **12000** pollution
- ▶ Make as many cars as possible

OR example as an LP

Four different manufacturing plants for making cars **Variables:**

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OR example as an LP

Four different manufacturing plants for making cars:

Variables: $x_i = \#$ cars produced at plant i , for $i \in \{1, 2, 3, 4\}$

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Four different manufacturing plants for making cars:

Variables: $x_i = \# \text{ cars produced at plant } i$, for $i \in \{1, 2, 3, 4\}$

Objective: $\max x_1 + x_2 + x_3 + x_4$

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$$x_3 \geq 400$$

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$$2x_1 + 3x_2 + 4x_3 + 5x_4 \leq 3300$$

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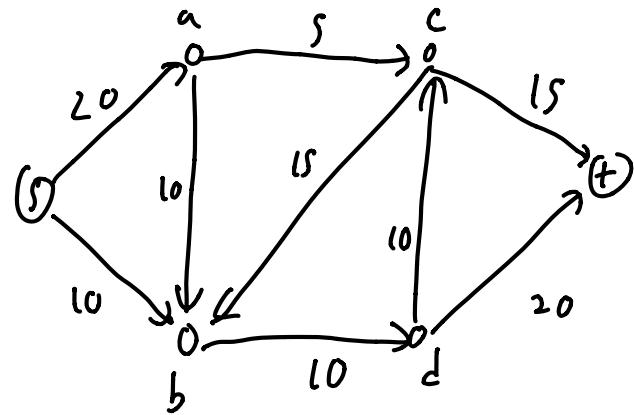
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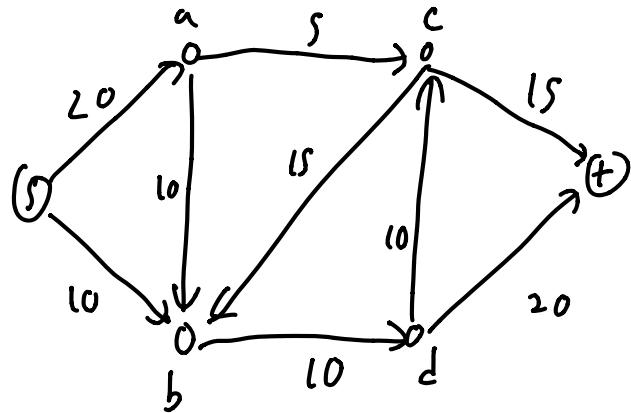
$$x_i \geq 0 \quad \forall i \in \{1, 2, 3, 4\}$$

Max Flow as LP



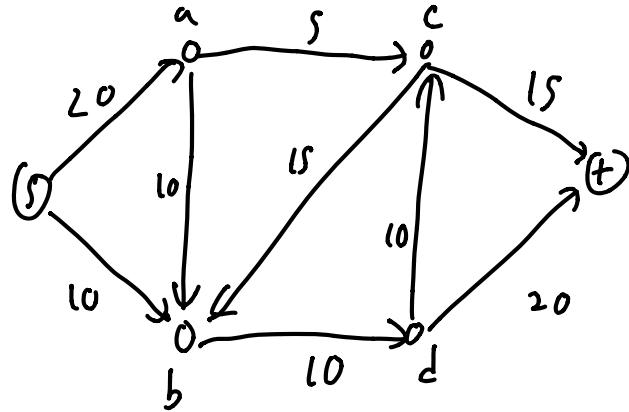
Max Flow as LP

Variables:

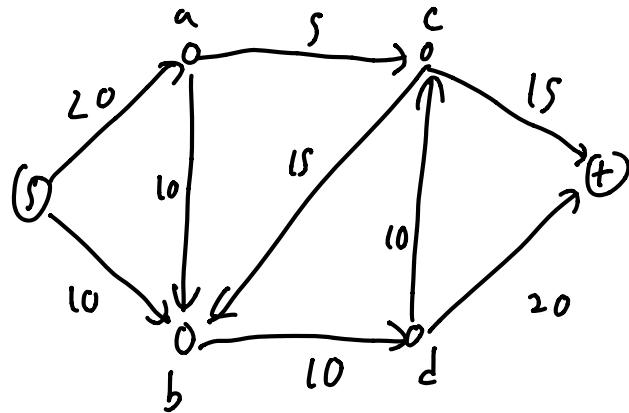


Max Flow as LP

Variables: $f(e)$ for all $e \in E$



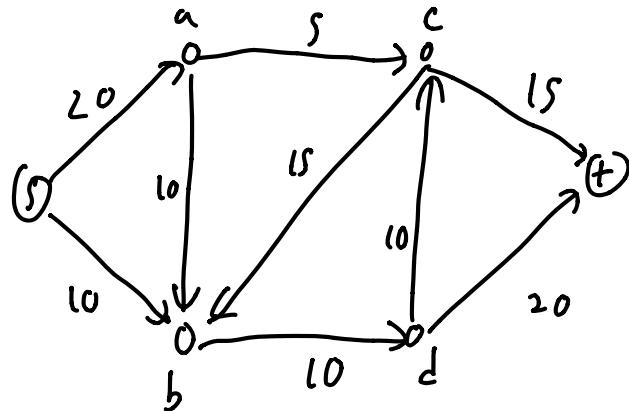
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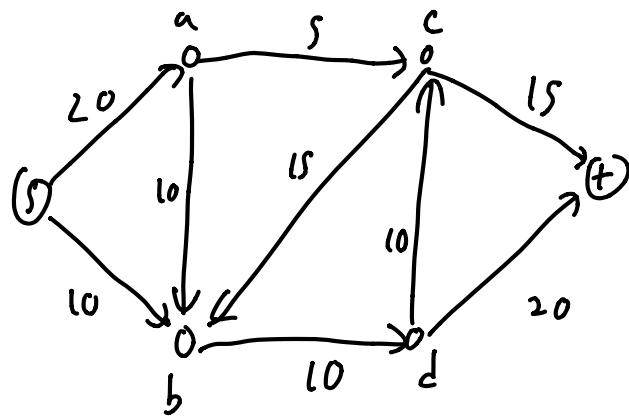
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Variables: $f(e)$ for all $e \in E$

Objective: $\max \sum_v f(s, v) - \sum_v f(v, s)$

Max Flow as LP

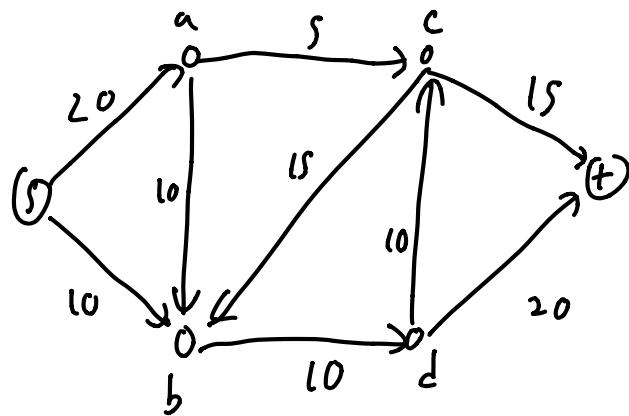


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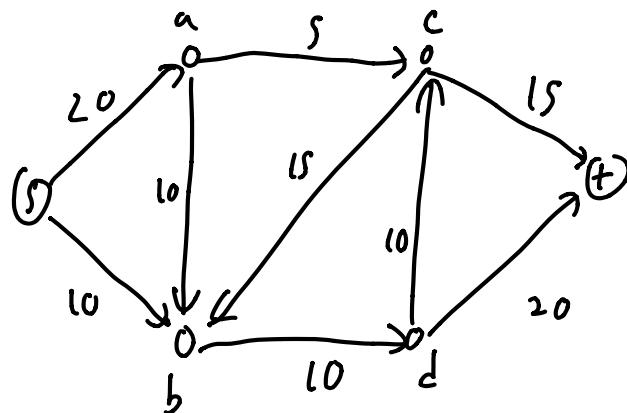
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Objective: $\max \sum_v f(s, v) - \sum_v f(v, s)$

Constraints:

$$\sum_v f(v, u) - \sum_v f(u, v) \stackrel{<}{\geq} 0 \quad \forall u \in V \setminus \{s, t\}$$

Max Flow as LP



Variables: $f(e)$ for all $e \in E$

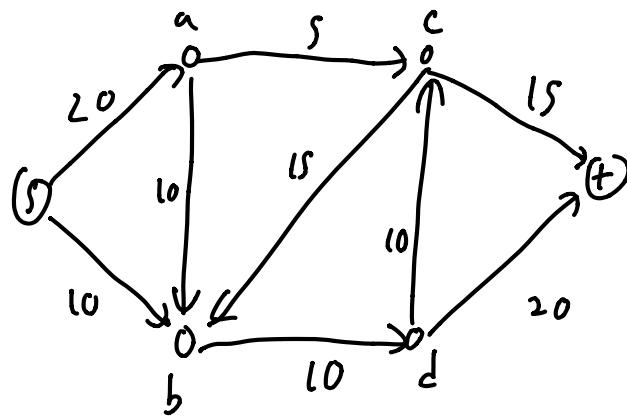
Objective: $\max \sum_v f(s, v) - \sum_v f(v, s)$

Constraints:

$$\sum_v f(v, u) - \sum_v f(u, v) = 0 \quad \forall u \in V \setminus \{s, t\}$$

$$f(e) \leq c(e) \quad \forall e \in E$$

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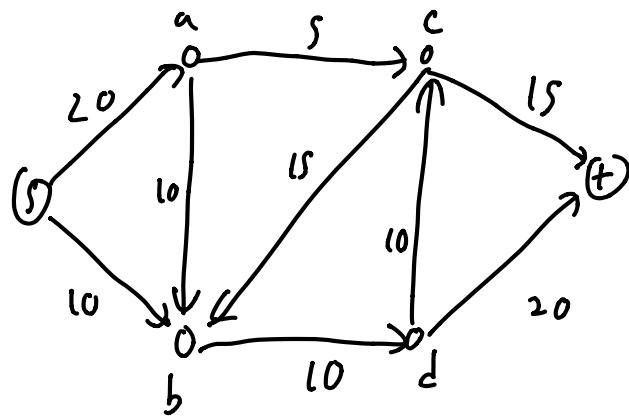
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So can solve max-flow and min-cut (slower) by using generic LP solver

Multicommodity Flow

Generalization of max-flow with
multiple commodities that can't mix,
but use up same capacity

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Generalization of max-flow with multiple commodities that can't mix, but use up same capacity

Setup:

- ▶ Directed graph $\mathbf{G} = (\mathcal{V}, \mathcal{E})$
- ▶ Capacities $c : \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$
- ▶ k source-sink pairs $\{(s_i, t_i)\}_{i \in [k]}$

Goal: send flow of commodity i from s_i to t_i , max total flow sent across all commodities

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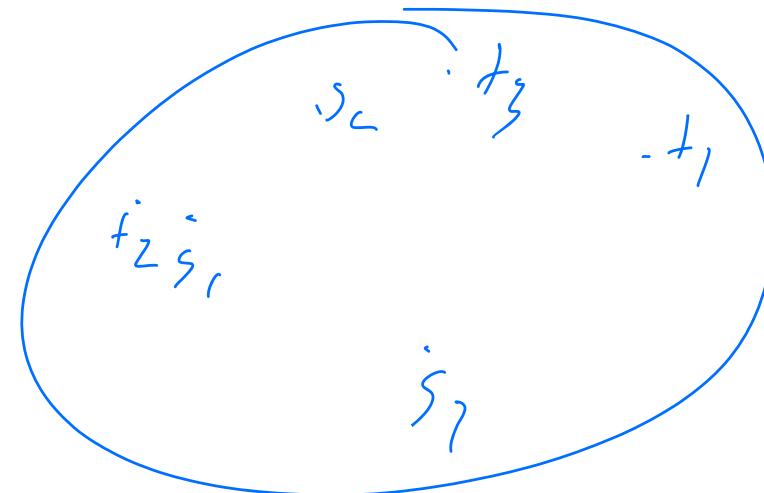
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Variables: $f_i(e)$ for all $e \in E$ and for all $i \in [k]$.
Flow of commodity i on edge e

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Concurrent Flow

Multicommodity flow, but:

- ▶ Also given *demands*
 $d : [k] \rightarrow \mathbb{R}_{\geq 0}$
- ▶ Question: Is there a multicommodity flow that sends at least $d(i)$ commodity- i flow from s_i to t_i for all $i \in [k]$?

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$$f_i(e) \geq 0 \quad \forall e \in E, \forall i \in [k]$$

$$\sum_v f_i(s_i, v) - \sum_v f_i(v, s_i) \geq d(i) \quad \forall i \in [k]$$

Maximum Concurrent Flow

If answer is no: how much
do we need to scale down
demands so that there is a
multicommodity flow?

Maximum Concurrent Flow

Variables:

- ▶ $f_i(e)$ for all $e \in E$ and for all $i \in [k]$.
- ▶ λ

Objective: $\max \lambda$

If answer is no: how much do we need to scale down demands so that there is a multicommodity flow?

Constraints:

$$\sum_v f_i(v, u) - \sum_v f_i(u, v) = 0 \quad \forall i \in [k], \forall u \in V \setminus \{s_i, t_i\}$$

$$\sum_{i=1}^k f_i(e) \leq c(e) \quad \forall e \in E$$

$$f_i(e) \geq 0 \quad \forall e \in E, \forall i \in [k]$$

$$\sum_v f_i(s_i, v) - \sum_v f_i(v, s_i) \geq \lambda d(i) \quad \forall i \in [k]$$

Shortest $s - t$ path

Very surprising LP!

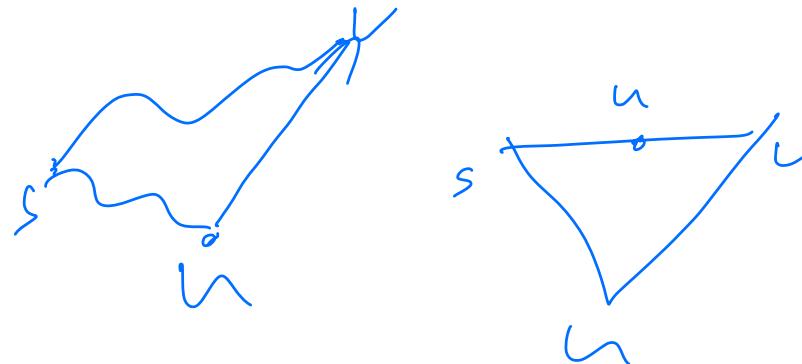
Variables: d_v for all $v \in V$: shortest-path distance from s to v

$$\max d_t$$

$$\text{subject to } d_s = 0$$

$$d_v \leq d_u + \ell(u, v)$$

$$\forall (u, v) \in E$$



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Correctness Theorem: Let \vec{d}^* denote the optimal LP solution. Then $d_t^* = d(s, t)$

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\leq : Let $P = (s = v_0, v_1, \dots, v_k = t)$ be shortest $s \rightarrow t$ path.

Prove by induction: $d_{v_i}^* \leq d(s, v_i)$ for all i

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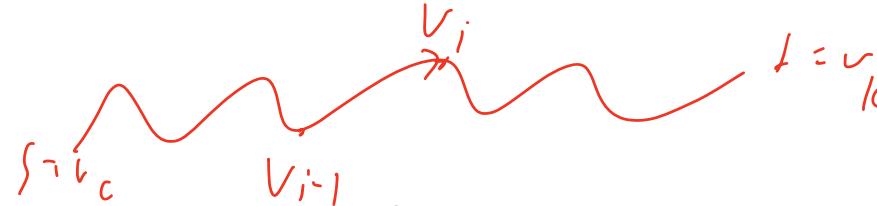
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in L-die step

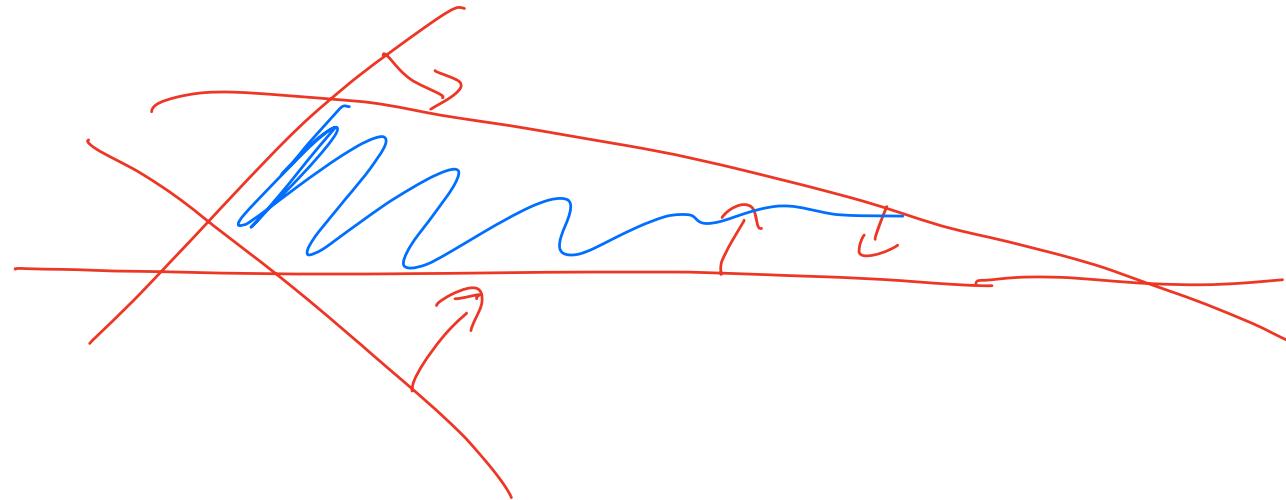
Inductive step: $d_{v_i}^* \leq d_{v_{i-1}}^* + \ell(v_{i-1}, v_i) \leq d(s, v_{i-1}) + \ell(v_{i-1}, v_i) = d(s, v_i)$

Algorithms for LPs

Geometry

To get intuition: think of LPs *geometrically*

- ▶ Space: \mathbb{R}^n (one dimension per variable)
- ▶ Linear constraint: halfspace (one side of a hyperplane)
- ▶ Feasible region: intersection of halfspaces. *Convex Polytope* (usually just called a *Polytope*)



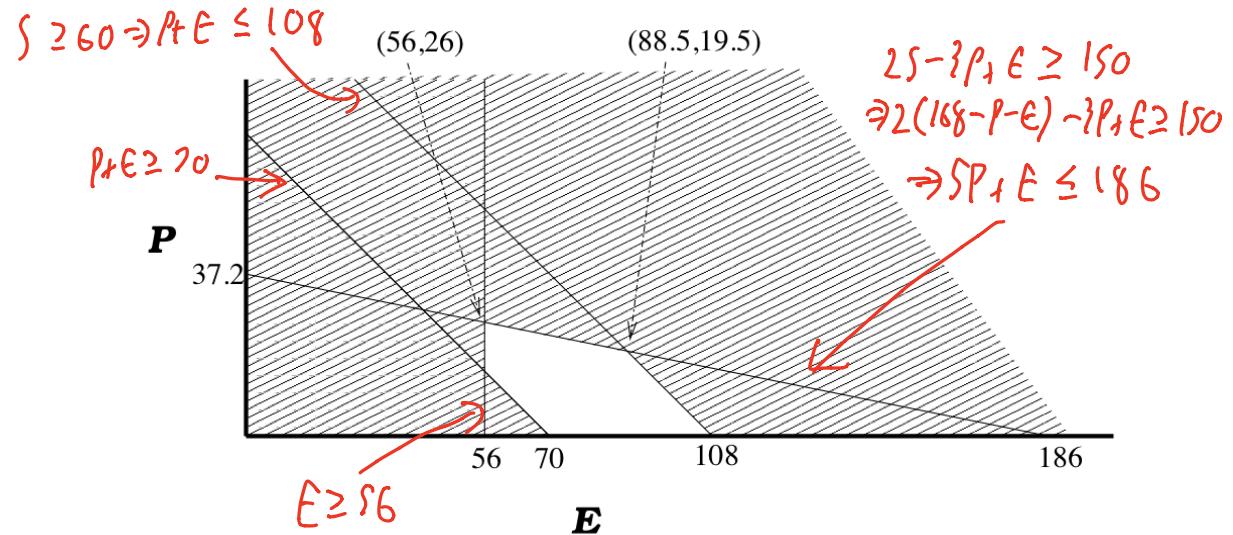
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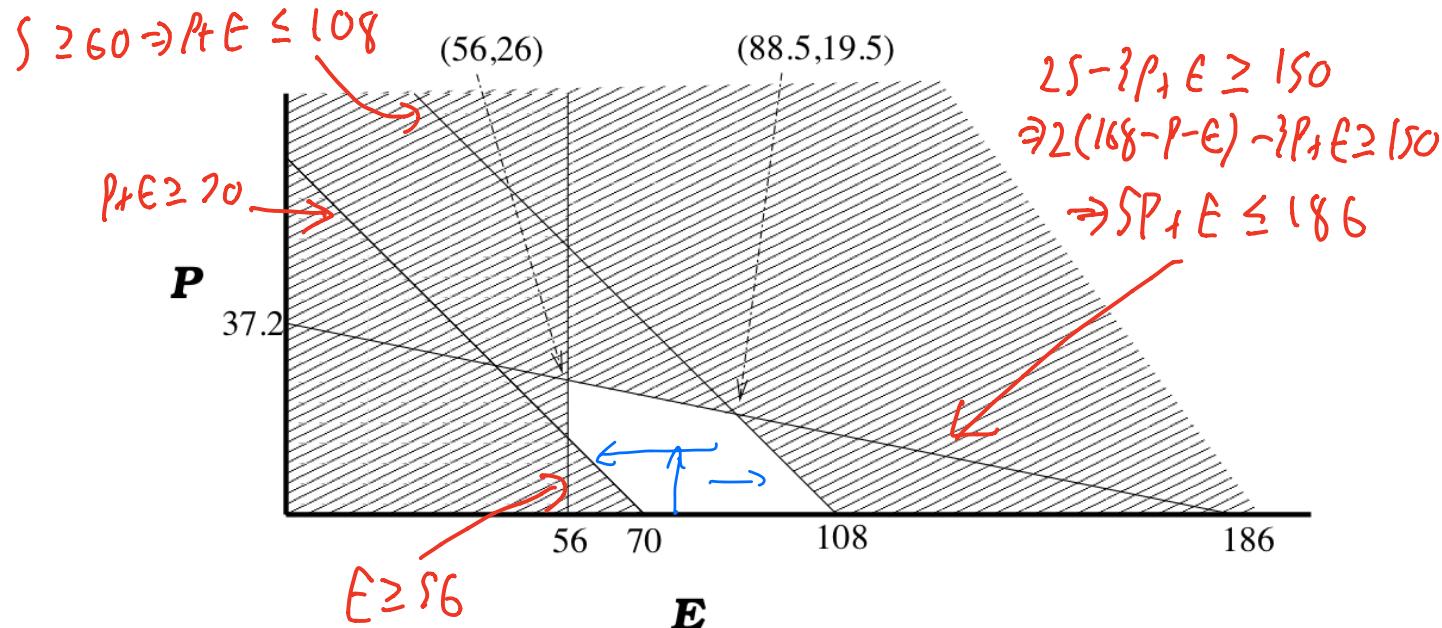
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Example: planning your week

- ▶ 3 variables S, P, E so \mathbb{R}^3
- ▶ But $S + P + E = 168 \implies S = 168 - P - E$
- ▶ Make this substitution, get \mathbb{R}^2



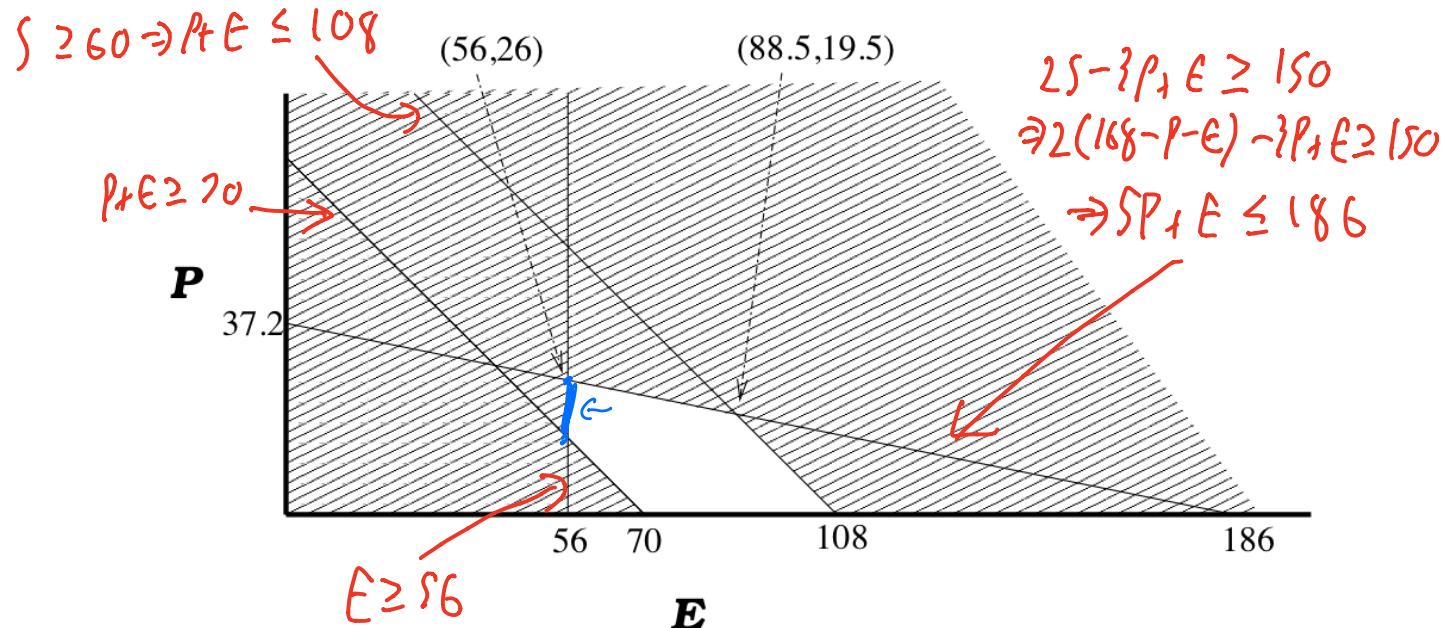
Geometry (cont'd)



Objective: feasible solution “furthest” along specified direction

- ▶ **max P :** (56, 26)
- ▶ **max $2P + E$:** (88.5, 19.5)

Geometry (cont'd)



Objective: feasible solution “furthest” along specified direction

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Main theorem: optimal solution is always at a “corner” (also called a “vertex”)

Simplex Algorithm [Dantzig 1940's]

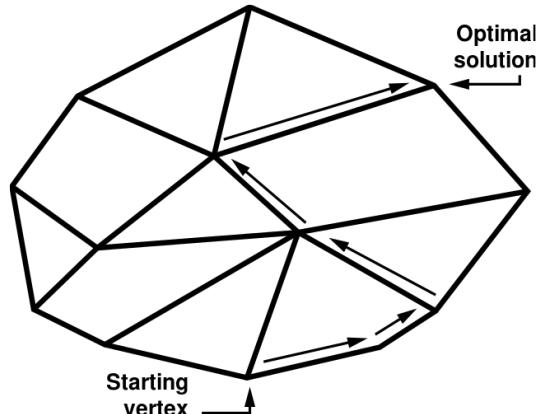
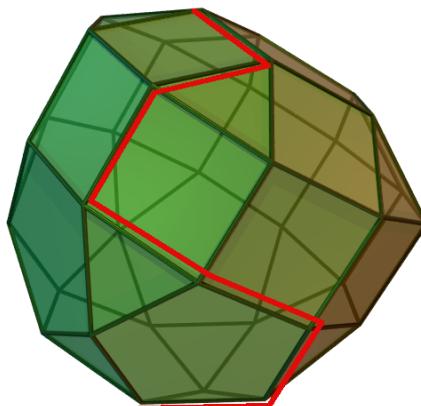
Initialize \vec{x} to an arbitrary corner

while(a neighboring corner \vec{x}' of \vec{x} has better objective value) {

$\vec{x} \leftarrow \vec{x}'$

}

return \vec{x}



Simplex Analysis

Theorem: Simplex returns the optimal solution.

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- ▶ Slow in theory
- ▶ Fast in practice!
 - ▶ Much of AMS LP course really about simplex: traditionally favorite algorithm of people who want to actually solve LPs
- ▶ Some theory to explain discrepancy (“smoothed analysis”)

Ellipsoid Algorithm [Khachiyan 1980]

First polytime algorithm!

Designed to just solve feasibility question \implies can also solve optimization

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First polytime algorithm!

Designed to just solve feasibility question \implies can also solve optimization

- ▶ Start with ellipsoid E containing feasible region P (if it exists)
- ▶ Let x be center of E
- ▶ While(x not feasible)
 - ▶ Find a hyperplane H through x such that all of P on one side
 - ▶ Let E' be the half-ellipsoid of E defined by H
 - ▶ Find a new ellipsoid \hat{E} containing E' so that $\text{vol}(\hat{E}) \leq (1 - \frac{1}{n}) \text{vol}(E)$
 - ▶ Let $E = \hat{E}$ and let x be center of \hat{E}

Analysis

Extremely complicated!

Geometry of ellipsoids: can always find an ellipsoid containing a half-ellipsoid with at most $(1 - 1/n)$ of the volume of the original

- ▶ Using inequality from last time: after n iterations, volume drops by $(1 - \frac{1}{n})^n \leq 1/e$ factor
 - ▶ Crucial fact: if volume “too small”, P must be empty
- ➡ Polynomial time!

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- ➡ Polynomial time!

In practice: horrible.

Interior Point Methods (Karmarkar's Algorithm)

Fast in both theory and practice!

