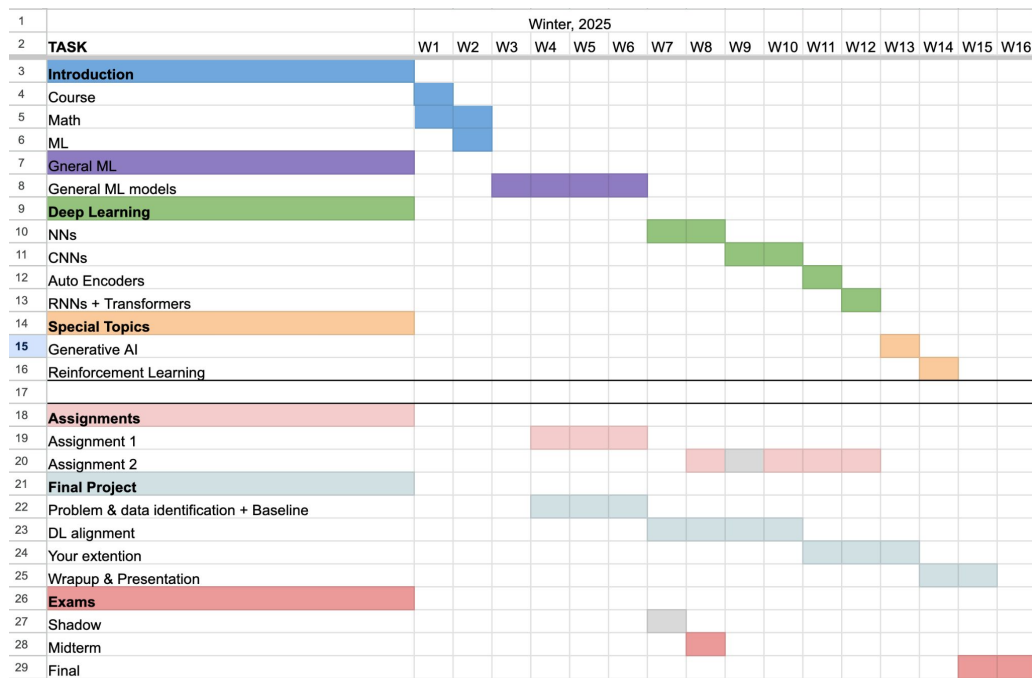




CIS 678 Machine Learning

Course Review Week

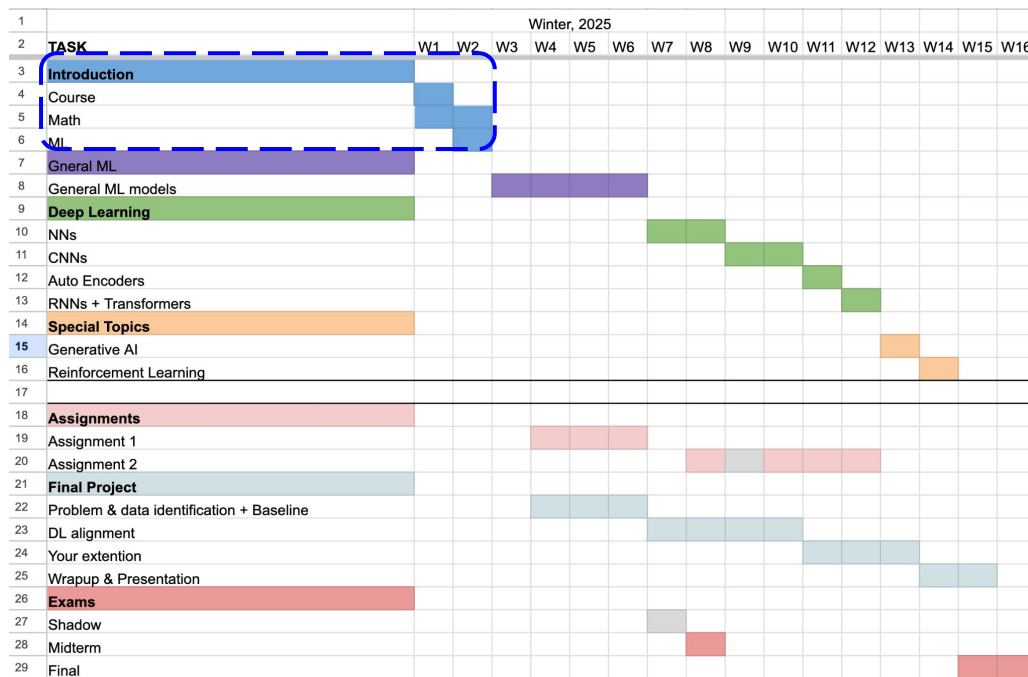


- L1/Manhattan distance
- L2/Euclidean distance,
- Cosine distances

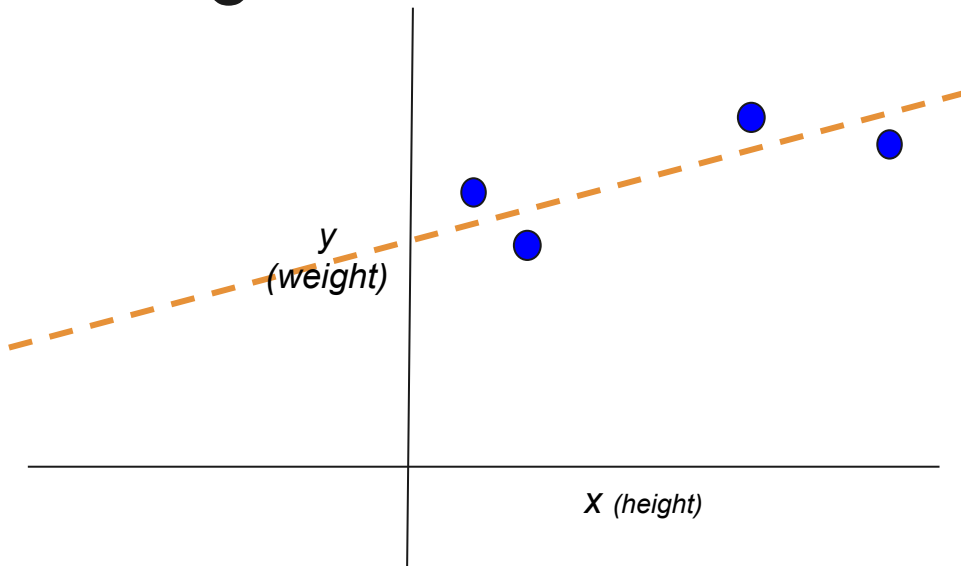
- Distance based
- Can be applied to both Regression and Classification tasks

Probability distributions

Linear to Polynomial Regression



Linear Regression



Model

$$\hat{y} = \beta_0 + \beta_1 x$$

$$\Theta = \{\beta_0, \beta_1\}$$

Fitting Error

$$\epsilon = |\hat{y} - y|$$

Optimization function

$$E_{\Theta} = \frac{1}{2} \sum_{i=1}^N (\hat{y}_i - y_i)^2$$

$$\Theta^* = \operatorname{argmin}_{\Theta} E\{(x_i, y_i)\}_{i=1, \dots, N}$$

Linear to Polynomial Regression

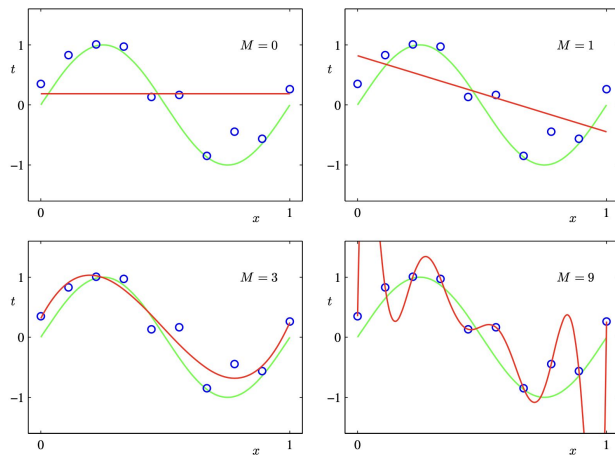


Table 1.1 Table of the coefficients w^* for polynomials of various order. Observe how the typical magnitude of the coefficients increases dramatically as the order of the polynomial increases.

	$M = 0$	$M = 1$	$M = 6$	$M = 9$
w_0^*	0.19	0.82	0.31	0.35
w_1^*		-1.27	7.99	232.37
w_2^*			-25.43	-5321.83
w_3^*			17.37	48568.31
w_4^*				-231639.30
w_5^*				640042.26
w_6^*				-1061800.52
w_7^*				1042400.18
w_8^*				-557682.99
w_9^*				125201.43

Model generalization

Linear to Polynomial Regression

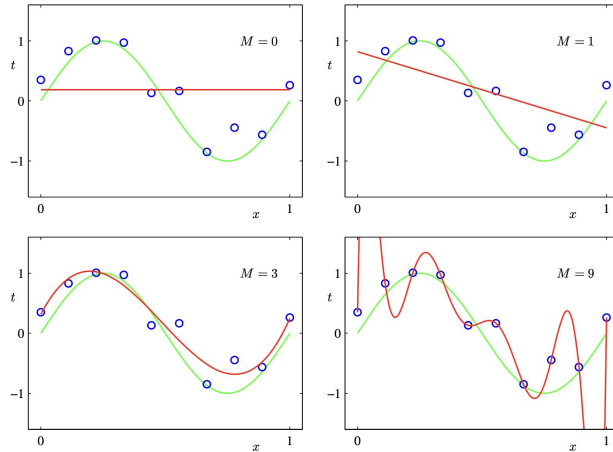


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Absolute values
are increasing

Model generalization

Linear to Polynomial Regression

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$

Essentially, the same formulation

Generally ML vs Math conventions

$$W^* = \operatorname{argmin}_W E\{(x_i, t_i)\}_{i=1, \dots, N}$$

Model

$$\hat{y} = \beta_0 + \beta_1 x$$

$$\Theta = \{\beta_0, \beta_1\}$$

$$\epsilon = |\hat{y} - y|$$

Optimization function

$$E_{\Theta} = \frac{1}{2} \sum_{i=1}^N (\hat{y}_i - y_i)^2$$

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Linear to Polynomial Regression

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$

Regularizer

$$\tilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2 + \frac{1}{2} \|\mathbf{w}\|^2$$

Model generalization: Regularization

Table 1.1 Table of the coefficients \mathbf{w}^* for polynomials of various order. Observe how the typical magnitude of the coefficients increases dramatically as the order of the polynomial increases.

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Abs values
Are increasing

Linear to Polynomial Regression

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decreasing

Model generalization: Regularization

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Abs values
Are increasing

Linear to Polynomial Regression

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decreasing

Model generalization: Regularization

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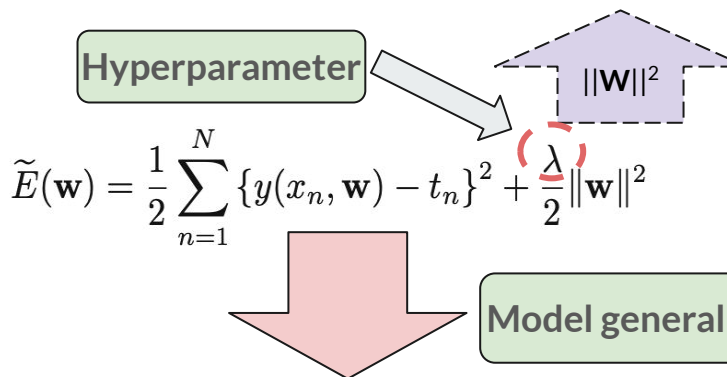
How to control this?

Linear to Polynomial Regression

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$

Table 1.1 Table of the coefficients \mathbf{w}^* for polynomials of various order. Observe how the typical magnitude of the coefficients increases dramatically as the order of the polynomial increases.

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Who to control this?

Model generalization: Regularization

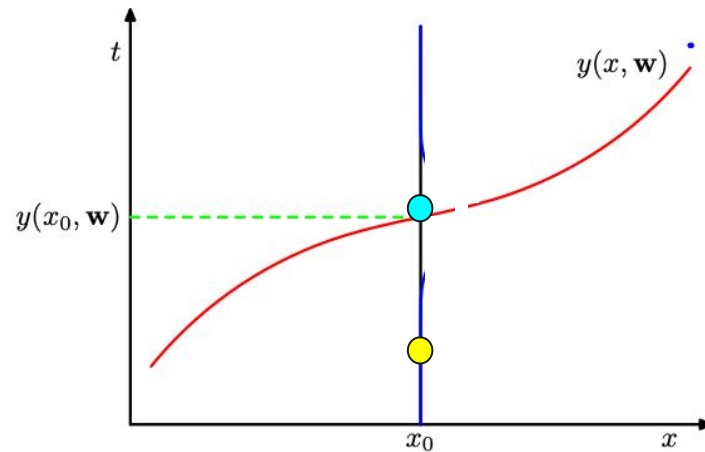


Probabilistic equivalent

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$

Probabilistic equivalent

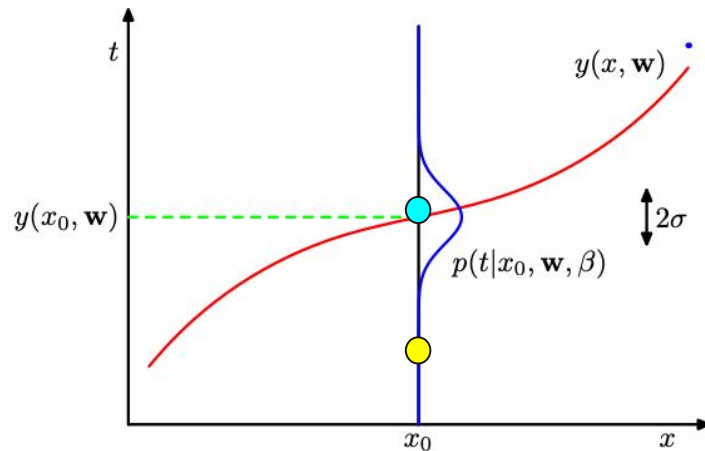
$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$



Probabilistic equivalent

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$

$$p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta) = \prod_{n=1}^N \mathcal{N}(t_n | y(x_n, \mathbf{w}), \beta^{-1})$$





General ML models

Supervised

- kNN
- Linear Regression
- Decision Tree
- Meta learners
 - Random Forest Regressor
 - Boosting Regressor
- Support Vector Regressor (SVRs)

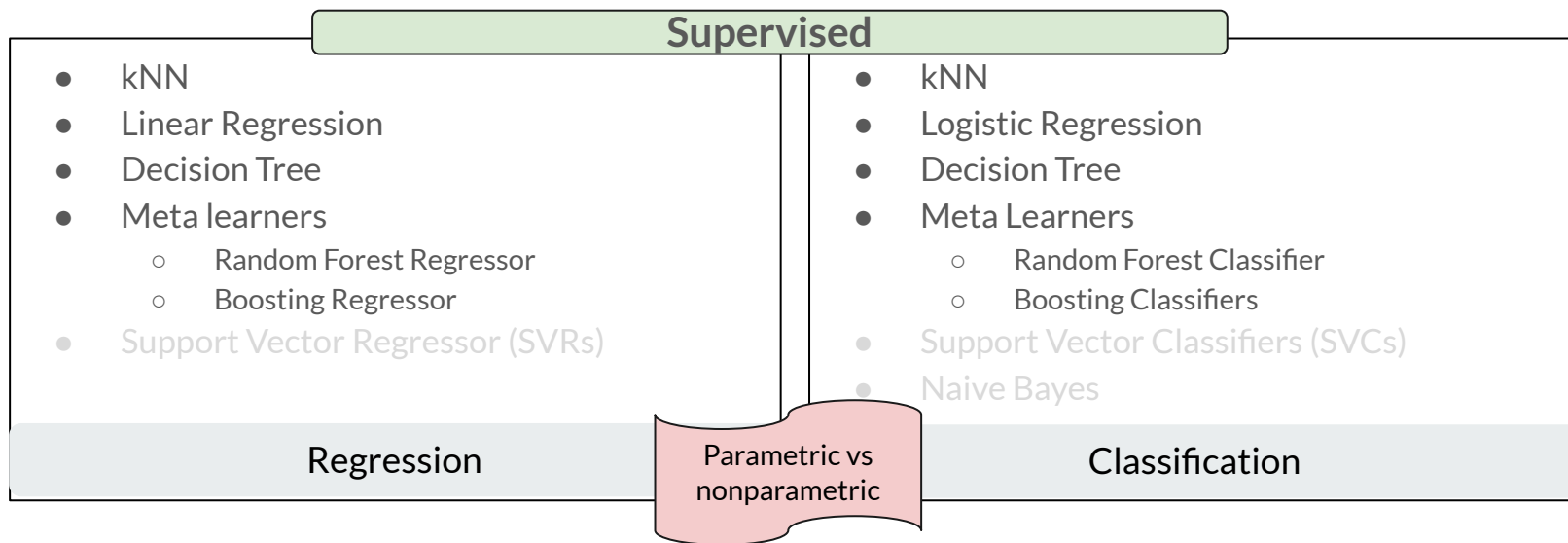
Regression

- kNN
- Logistic Regression
- Decision Tree
- Meta Learners
 - Random Forest Classifier
 - Boosting Classifiers
- Support Vector Classifiers (SVCs)
- Naive Bayes

Classification



General ML models





General ML models

Unsupervised

- Clustering algorithms
 - **k-means**: Centroid Based
 - k-modes: Mode Based (categorical)
 - **Hierarchical clustering**: Distance connectivity based
 - **GMM**: Distribution based
 - **DBSCAN**: Density Based
- How to choose the optimal number of clusters.

Clustering

- Principal Component Analysis (PCA)
- Singular Value Decomposition (SVD)

Linear Dimensionality Reduction



General ML models

Model generalization

- Universal concepts (applies to all models)
 - Cross validation
 - HP optimization

Universal concepts

- Overfitting
- Underfitting

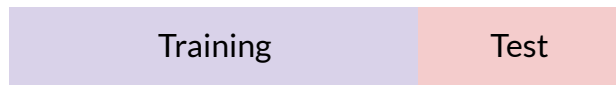
Overfitting vs Under fitting



General ML models

Model generalization

- Training set, Validation set, Test set
- iid data



Data splits

- Overfitting
- Underfitting

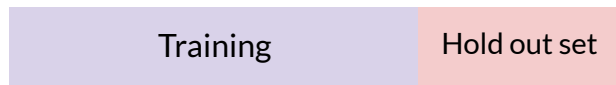
Overfitting vs Under fitting



General ML models

Model generalization

- Training set, Validation set, Test set
- iid data



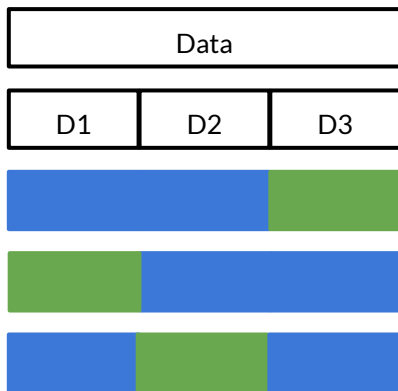
Data splits

- Overfitting
- Underfitting

Overfitting vs Under fitting



K-fold-cross validation



3-fold-cv

Train

validate

What HP gives the best validation score?

Assignment 1

Vector space

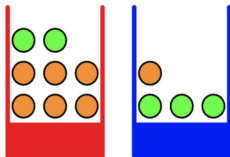


Figure 1: A red and a blue box containing a set of orange and green balls.

Probability & distribution

1. [2x2 points] For each dimension $d \in [2^1, 2^3, 2^5, \dots, 2^{11}]$, sample 100 random points from corresponding vector spaces (sample code to generate random samples is provided below), and

- Record the l_2 and the *cosine* distances between all pairs (of points); then
- Fit two normal/Gaussian distributions, one for each distance metric. Share the mean (μ) and the standard distribution (σ) parameters of each distribution that you have learned.
- Plot these normal/Gaussian distributions using your preferred visualization package(s).

normal/Gaussian distribution: $p(x) \sim \mathcal{N}(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$

Sample code (to generate $n = 100$ random samples from a $d = 4$ dimensional vector space):

```
import numpy as np
d, n = 4, 100
sample_data = np.random.randn(n, d)
```

2. [2x2 points]

There are some orange and green balls in a red and a blue box as illustrated in Figure 1. Someone (blinded by tying a piece of cloth around his/her eyes) is asked to pick up a ball twice (with replacement, i.e. the ball is placed back in the same box from where it was picked up).

- What is the **log-probability** of the first ball to be **orange** and second ball to be **green**?
- What is the **probability** that both the time the ball came from the **red** box?

Note: We assume, the selection of the red and the blue boxes follow an **uniform** distribution (given that the person is not able to see the color of those boxes).



Assignment 1

Loss function

Building your own model from scratch

3. [2 points] Given a Linear Regression model, $\Theta = \{\beta_0 = 0.1, \beta_1 = 0.9, \beta_2 = -3.5\}$ (where β_0 is the bias and β_1 and β_2 are the parameters associated with two input features/variables), the regularizer parameter $\lambda = 1.5$ and the following data set (with y being the target variable), estimate the

- Quadratic error or loss with l2 regularizer as defined below

$$E_{\Theta} = \frac{1}{2} \sum_{i=1}^{N-1} (y_i - \hat{y}_i)^2 + \frac{\lambda}{2} \|\beta\|^2$$

4. [4 points] You are asked to fit a **second order/degree** polynomial regression model, $y = \beta_0 + \beta_1 x + \beta_2 x^2$ with parameter $\Theta = \{\beta_0, \beta_1, \beta_2\}$ (where β_0 is the bias of your model) on the following dataset.
- data file:**
https://raw.githubusercontent.com/mdkamrulhasan/data-public/refs/heads/main/miscellaneous/second_degree_polynomial_regression_data.csv

For the setup below, we ask you to find out the updated version of Θ after two(2) iterations of any gradient descent algorithm (you can use the algorithm that we shared as a part of our linear regression model illustration in the class):

Setup details:

- Use the quadratic error/loss function
- Initialize, $\Theta_0 = \{\beta_0 = 0.0, \beta_1 = 0.0, \beta_2 = 1.0\}$
- Use learning rate (parameter), $L = 0.001$

Note: You have to define your error/loss function and also will need to estimate partial derivatives of your loss function.



Assignment 1

Regularization: model generalization

5. [3x2 points] For the given dataset below, we ask you develop, test and compare following models (follow the instructions under the **Detailed specification** section below).

- (a) Linear Regression
- (b) Linear Regression with l_1 regularizer
- (c) Linear Regression with l_2 regularizer

data file:

https://raw.githubusercontent.com/mdkamrulhasan/data_mining_kdd/main/data/medical-cost/insurance.csv

Detailed specification:

- Use a 50%-50% test/train setup.
- Use Mean Squared Error (MSE) as your evaluation metric.
- Visualize (using Bar charts) the model parameter **absolute** values (convert any negative values to positives before plotting).
- You can use python packages such as **sklearn** for your solution.



Shadow test followed by Mid-term!

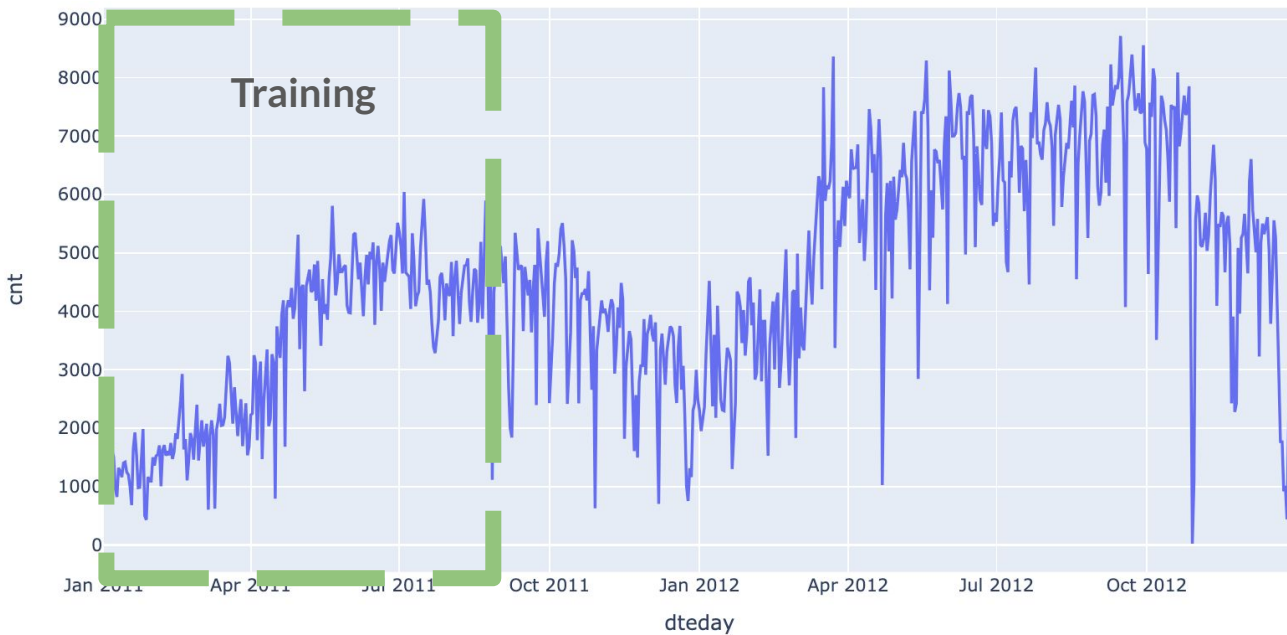
Sequential cross validation



*Invalid
configuration:*

*Training on the last
two and validation
on the **first fold**.*

Sequential cross validation



Always follow!

Sequential cross validation



Always follow!

Sequential cross validation



Always follow!

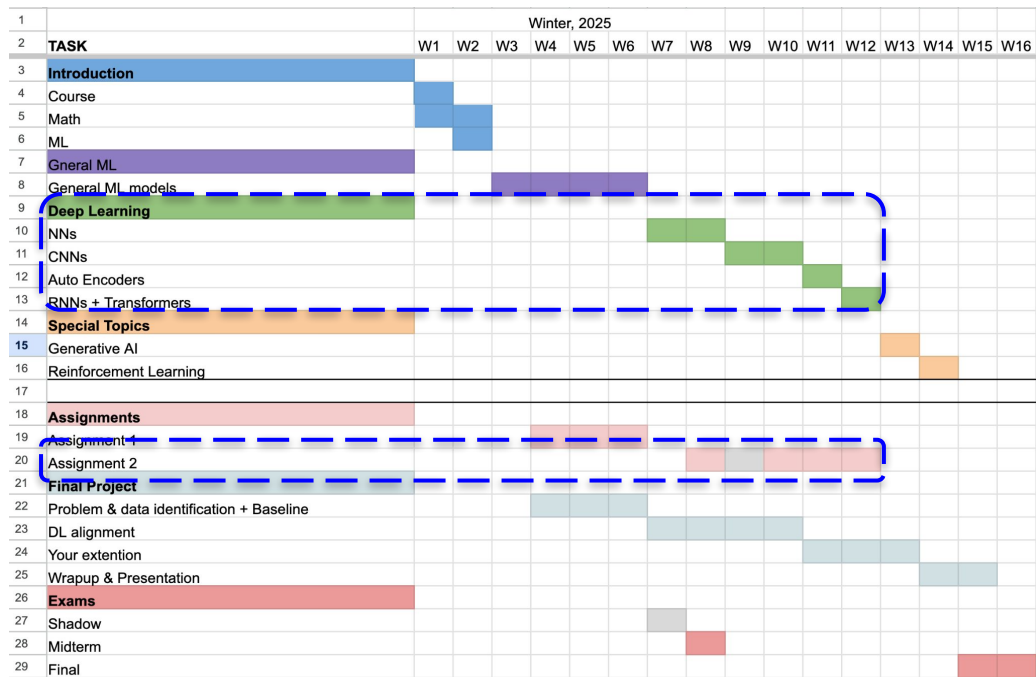
Sequential cross validation



Always follow!

[illegible]

Assignment 2

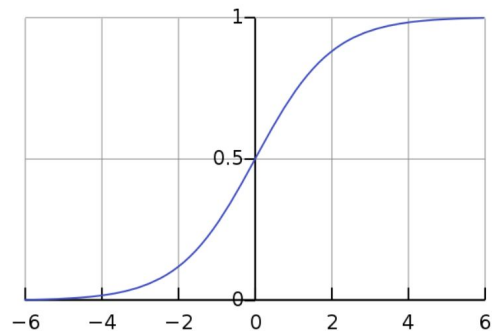


Logistic Regression

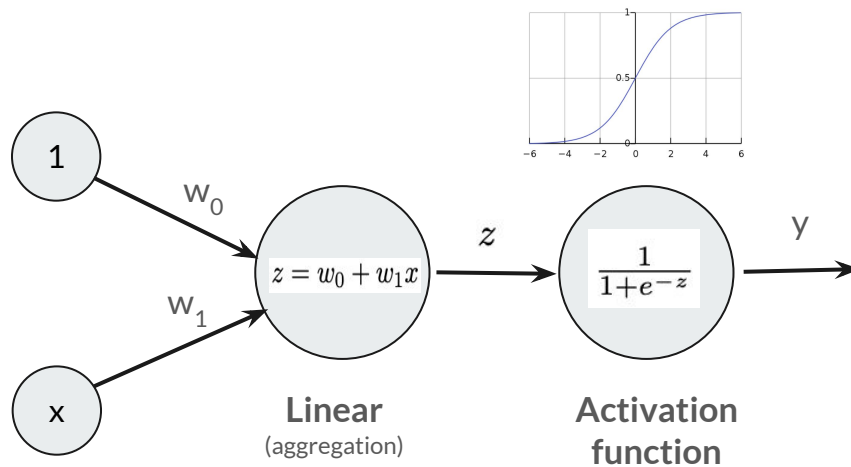
- Probabilistic classifier

$$p(x) = \frac{1}{1 + e^{-(w_0 + w_1 x)}}$$

- Sigmoid function

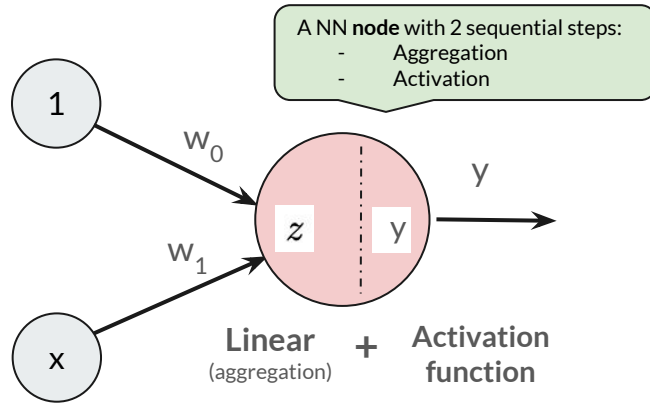


Neural Networks (Node)



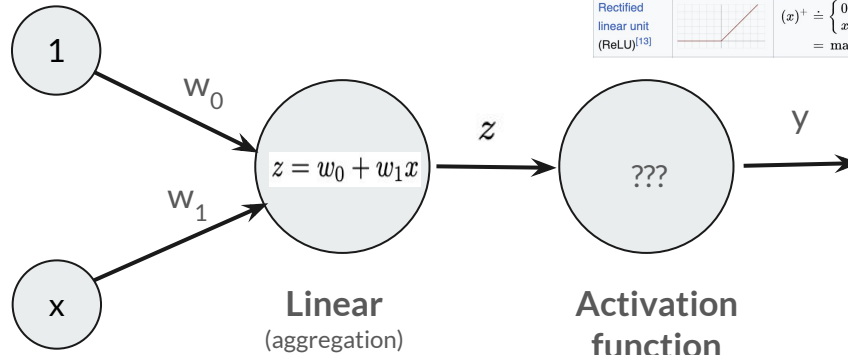
$y \in \{0, 1\}$
Logistic Regression

Neural Networks (Node)



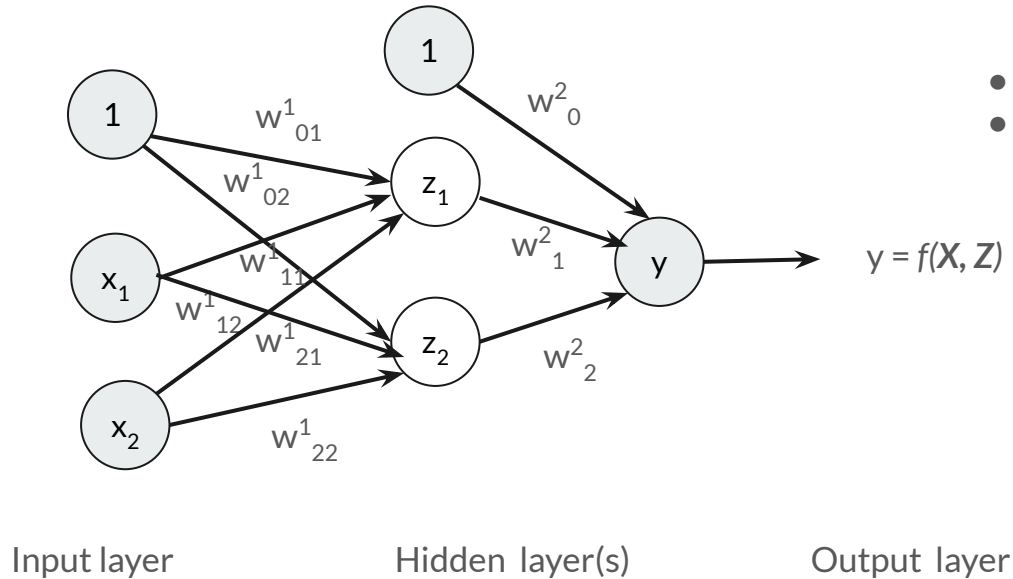
Neural Networks (Node)

Name	Plot	Function, $g(x)$
Identity		x
Binary step		$\begin{cases} 0 & \text{if } x < 0 \\ 1 & \text{if } x \geq 0 \end{cases}$
Logistic, sigmoid, or soft step		$\sigma(x) \doteq \frac{1}{1 + e^{-x}}$
Hyperbolic tangent (tanh)		$\tanh(x) \doteq \frac{e^x - e^{-x}}{e^x + e^{-x}}$
Soboleva modified hyperbolic tangent (smht)		$\text{smht}(x) \doteq \frac{e^{ax} - e^{-bx}}{e^{cx} + e^{-dx}}$
Rectified linear unit (ReLU) ^[13]		$(x)^+ \doteq \begin{cases} 0 & \text{if } x \leq 0 \\ x & \text{if } x > 0 \end{cases}$ $= \max(0, x) = x \mathbf{1}_{x>0}$



A NN with ???
Activation function

Feed-forward (FF) neural networks



- Feedforward NN
- Perceptron



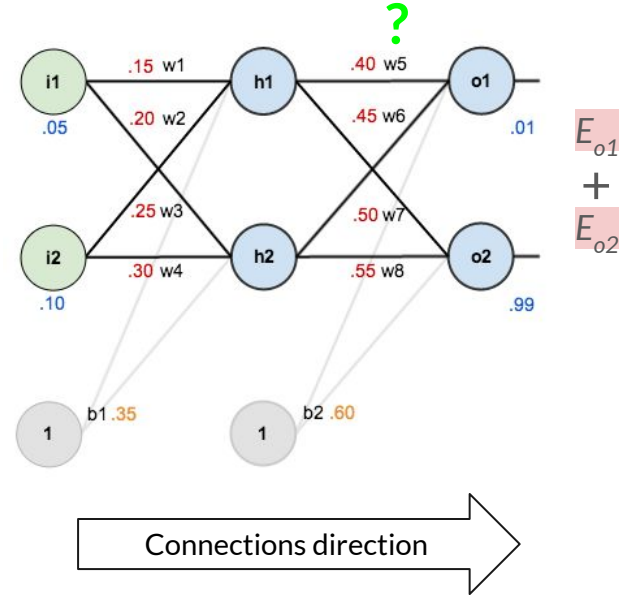
Error Back propagation

Gradient Descent (Error Back Propagation)

The Backwards Pass

Let's focus on $\frac{\partial E_{total}}{\partial w_5}$

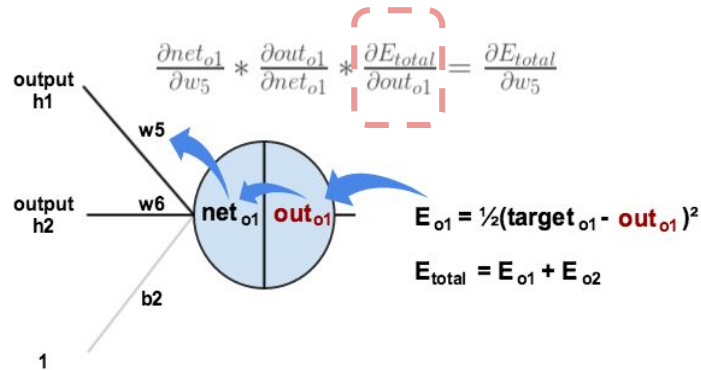
What would be the gradient update for w_5 ?



Adapted from

Gradient Descent (Error Back Propagation)

The Backwards Pass



$$E_{total} = \frac{1}{2}(\text{target}_{o1} - \text{out}_{o1})^2 + \frac{1}{2}(\text{target}_{o2} - \text{out}_{o2})^2$$

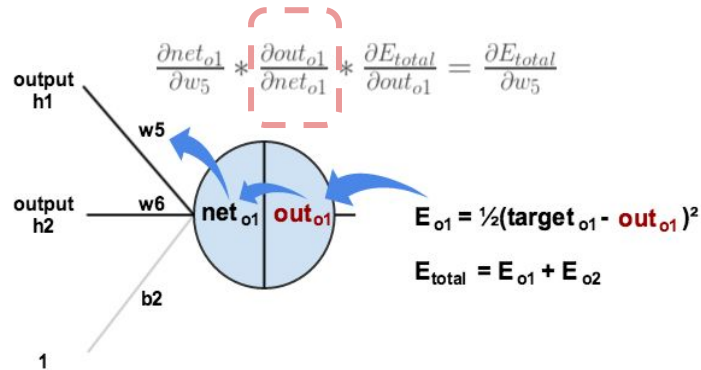
$$\frac{\partial E_{total}}{\partial out_{o1}} = 2 * \frac{1}{2}(\text{target}_{o1} - \text{out}_{o1})^{2-1} * -1 + 0$$

$$\frac{\partial E_{total}}{\partial out_{o1}} = -(\text{target}_{o1} - \text{out}_{o1}) = -(0.01 - 0.75136507) = 0.74136507$$

Adapted from

Gradient Descent (Error Back Propagation)

The Backwards Pass



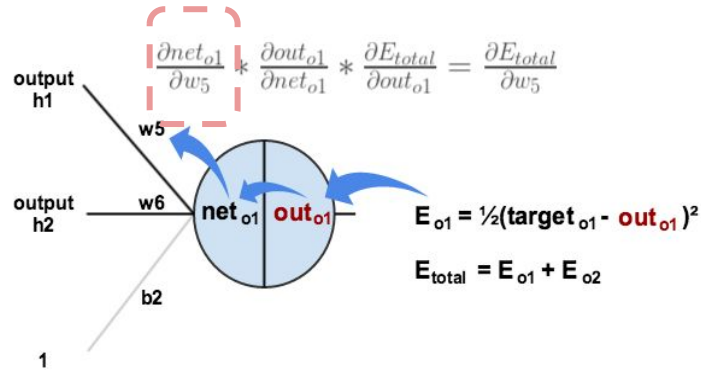
$$out_{o1} = \frac{1}{1 + e^{-net_{o1}}}$$

$$\begin{aligned} \frac{\partial out_{o1}}{\partial net_{o1}} &= out_{o1}(1 - out_{o1}) \\ &= 0.75136507(1 - 0.75136507) \\ &= 0.186815602 \end{aligned}$$

Adapted from

Gradient Descent (Error Back Propagation)

The Backwards Pass



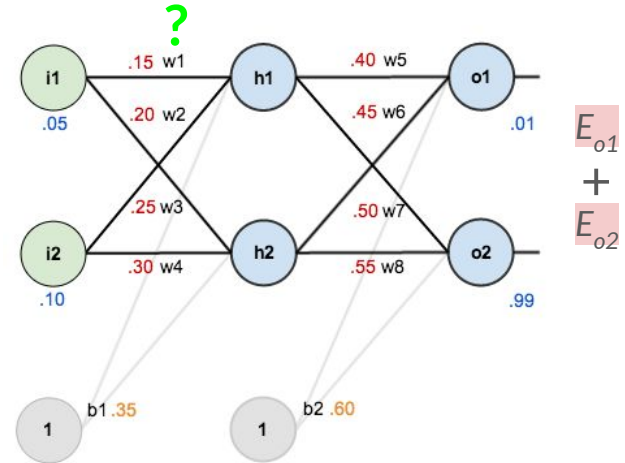
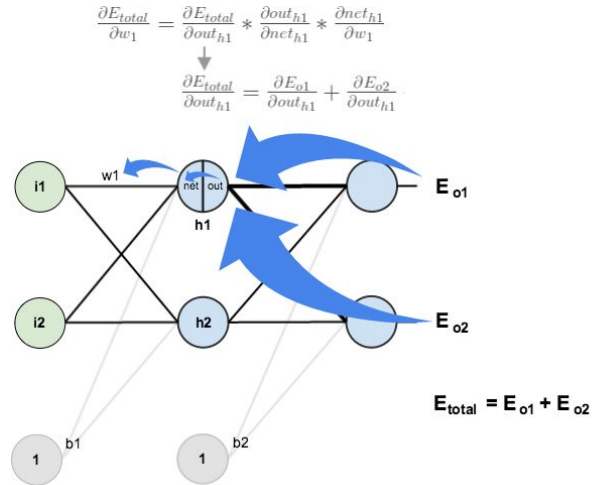
$$net_{o1} = w_5 * out_{h1} + w_6 * out_{h2} + b_2 * 1$$

$$\frac{\partial net_{o1}}{\partial w_5} = 1 * out_{h1} * w_5^{(1-1)} + 0 + 0 = out_{h1} = 0.593269992$$

Adapted from

Gradient Descent (Error Back Propagation)

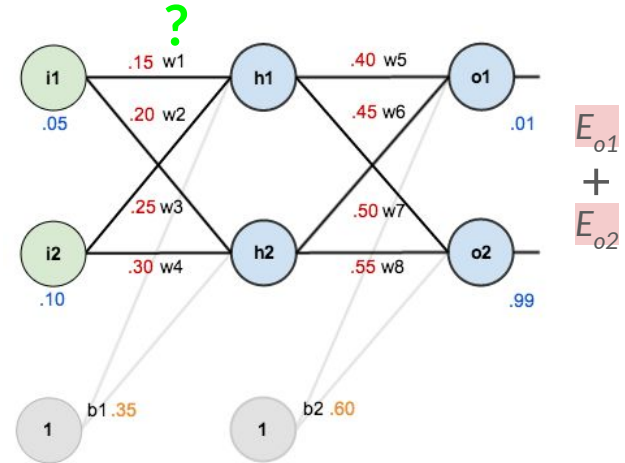
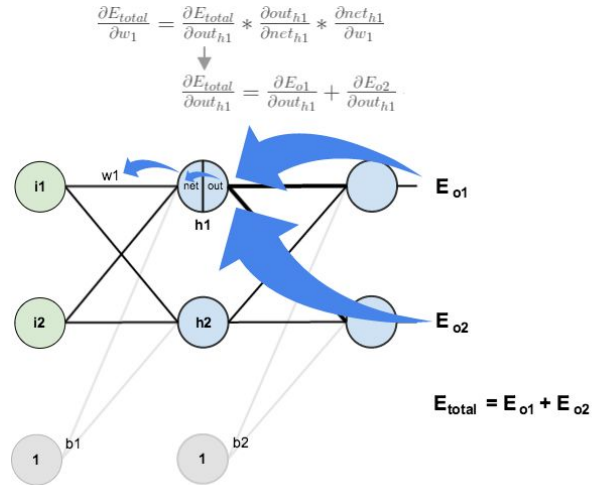
Hidden Layer



- While changing w_5 affects only O_1 , a change in w_1 will change both O_1 and O_2

Gradient Descent (Error Back Propagation)

Hidden Layer



- Can you think of an arbitrary node in a giant and complex NN? What challenges we may encounter?



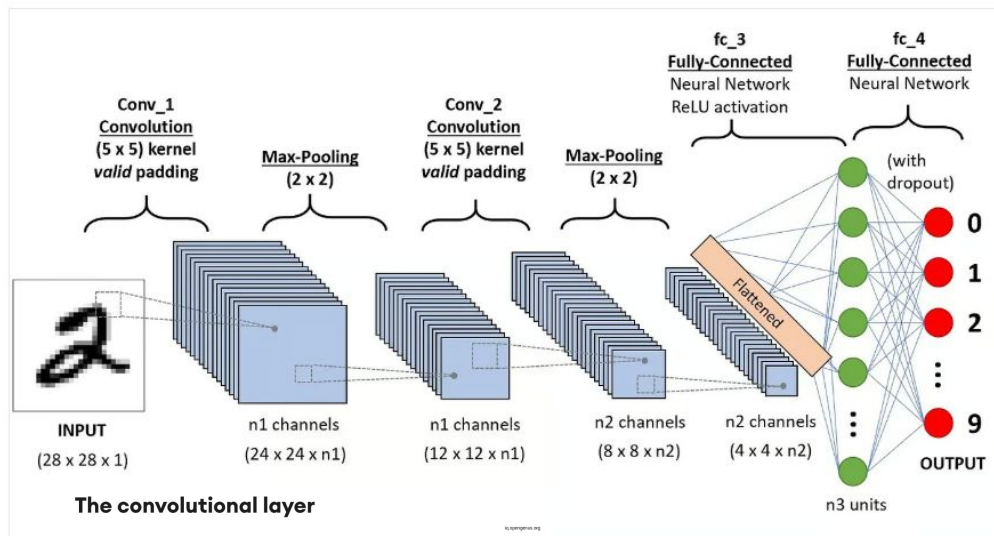
Convolutional NNs

- State of the Art for CV and some other problems
- Filters/Convolutional Kernels

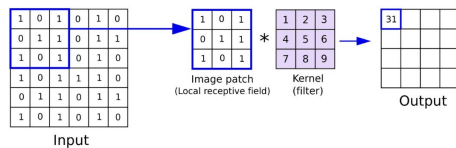
Examples:

- Alexnet
- VGG
- ResNet
- GoogLeNet
- ..

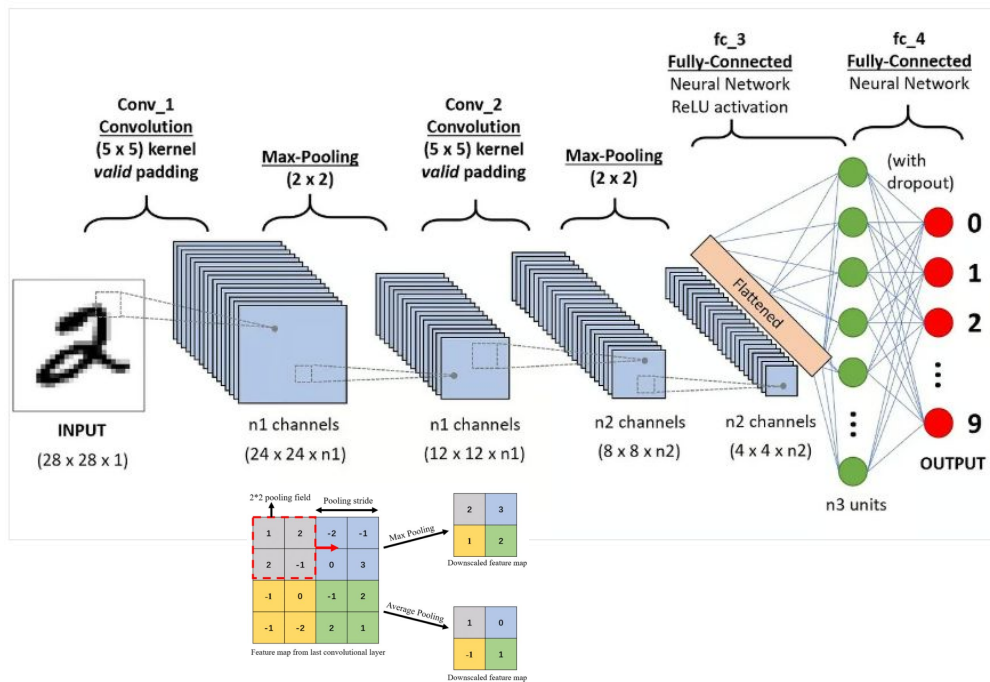
Convolutional NNs



The convolutional layer

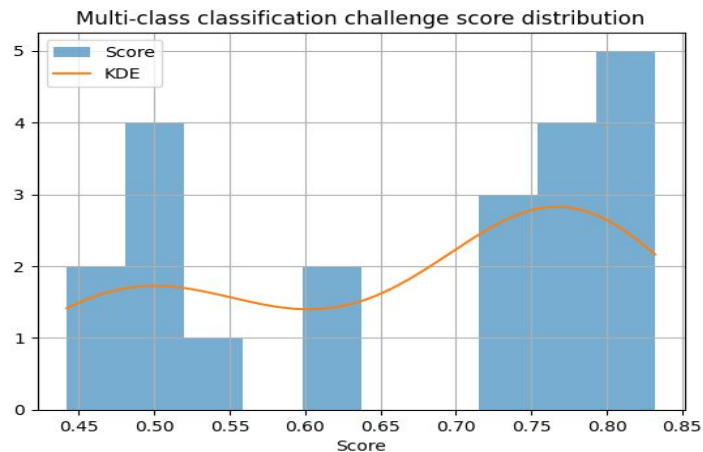


Convolutional NNs

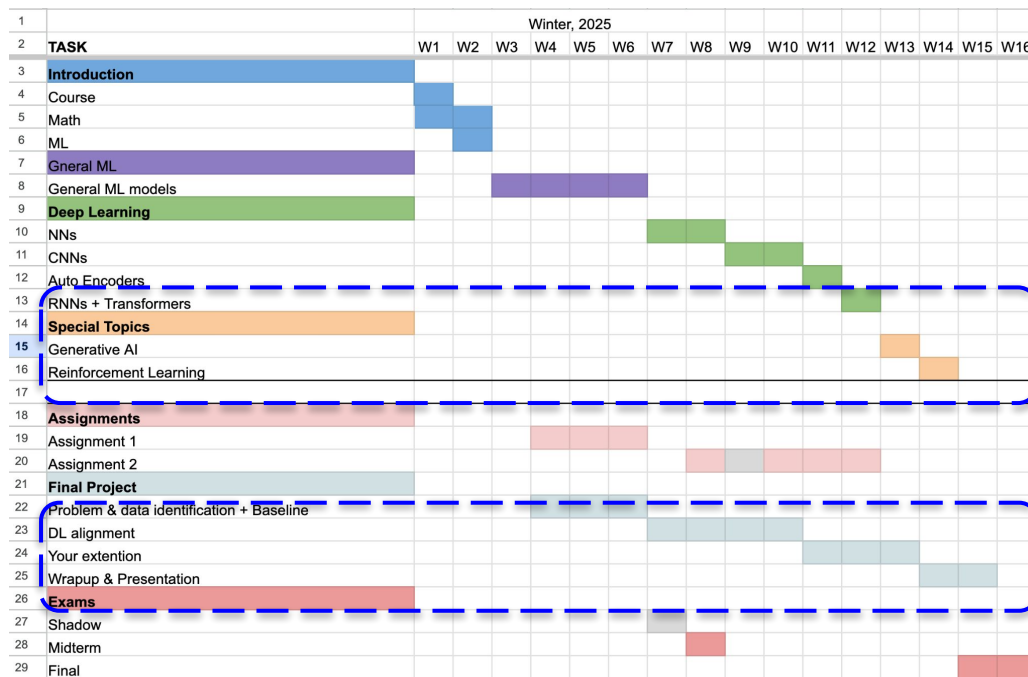


Assignment 1 (classification challenge)

- Deep learning models doubled the performance to general ML models



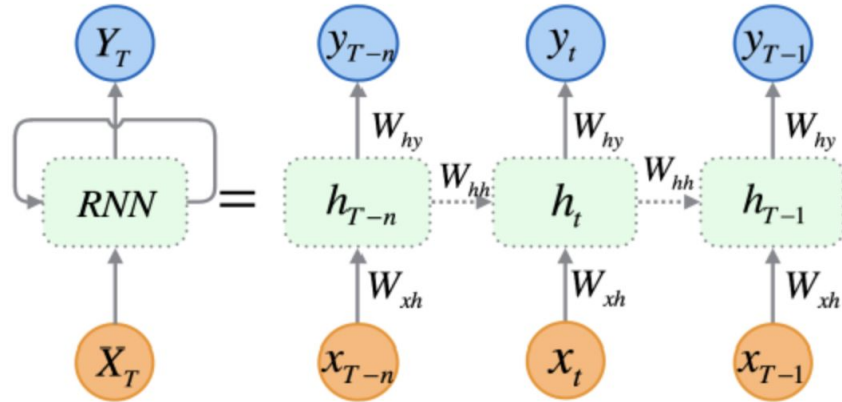
DL continuation + Project



Recurrent Neural Networks

Examples:

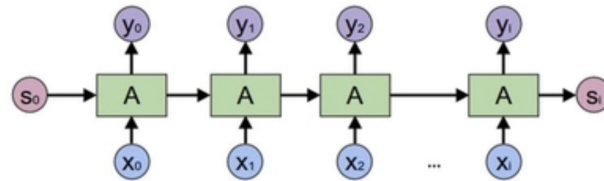
- LSTMs
- GRU



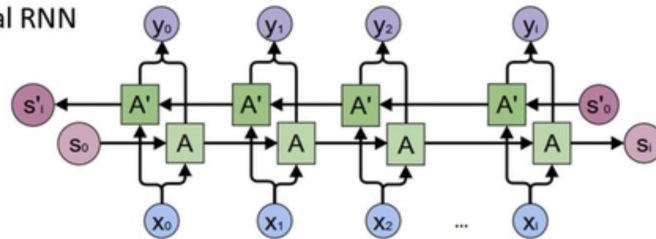
[ref](#)

RNNs

RNN

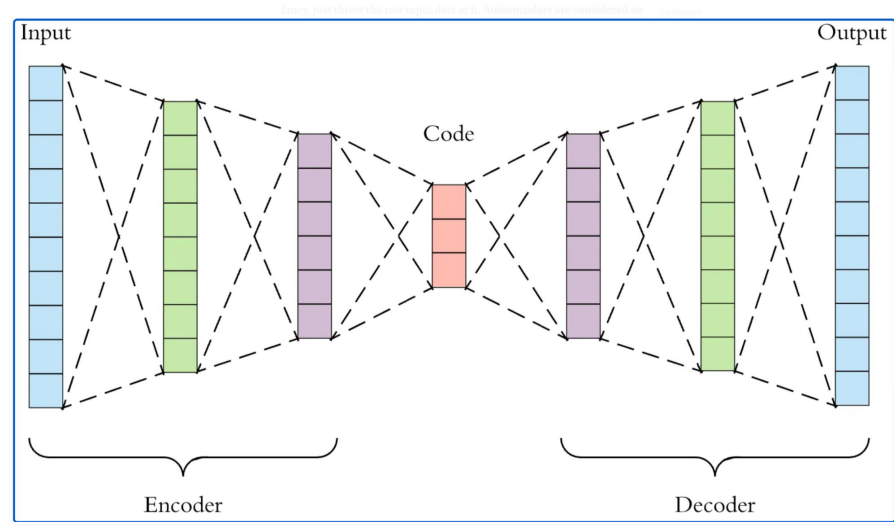


Bi-directional RNN



Unsupervised learning (nonlinear)

- Auto Encoders
- Restricted Boltzmann Machines (RBMs)



Transformers

Examples:

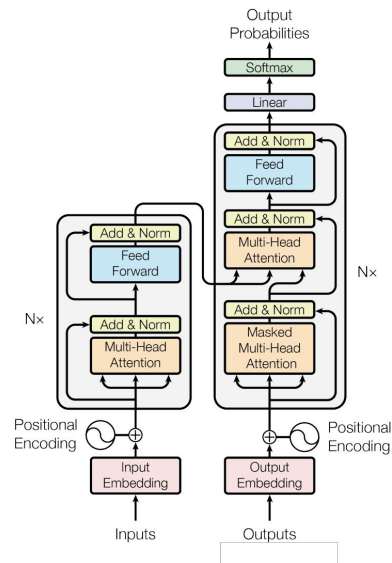
- Encoder decoder pair
- GPT
- BERT

BERT

Encoder

GPT

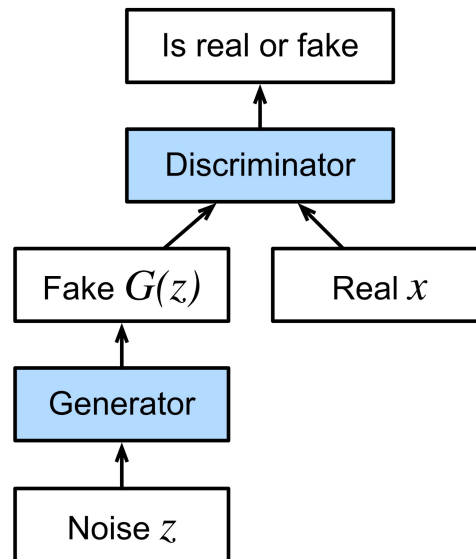
Decoder



Generative AI

Examples:

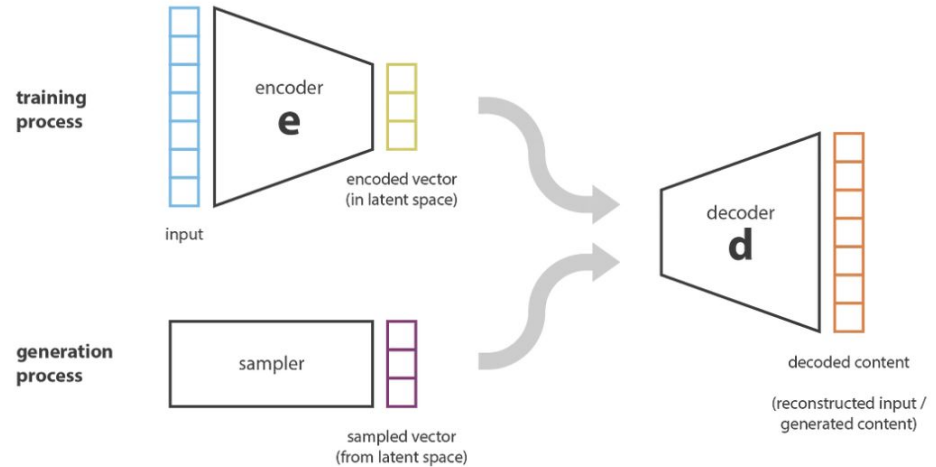
- Generative Adversarial Networks (GANs)



Generative AI

Examples:

- Generative Adversarial Networks (G
- **Variational Autoencoders (VAEs)**

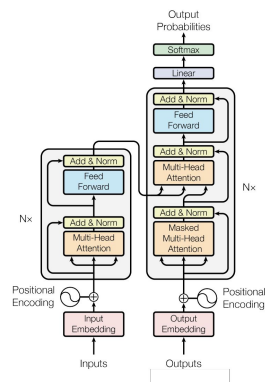


Foundational models

- We don't train independent models explicitly (say machine translation)

BERT

Encoder



GPT

Decoder

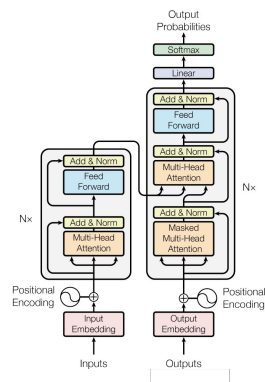
Machine translation

Foundational models

- We don't train independent models explicitly (say machine translation)
- Or document summarization

BERT

Encoder



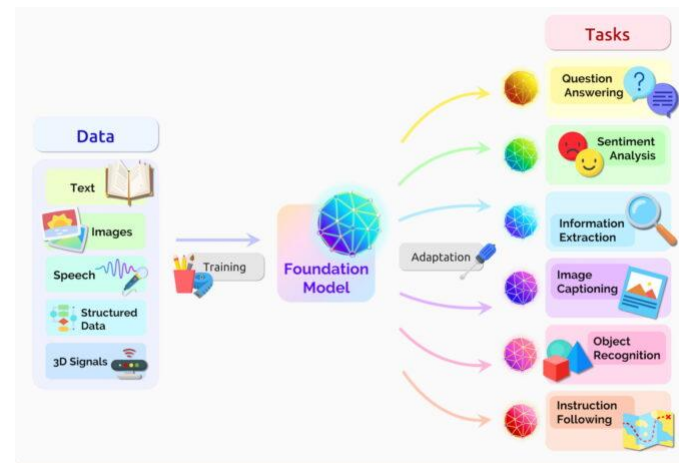
GPT

Decoder

Document summarization

Foundational models

- We don't train independent models explicitly (say machine translation)
- Or document summarization
- **We train a Base model for multiple tasks jointly, and then fine tune for specific tasks**



Foundational models

- We don't train independent models explicitly (say machine translation)
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- **We train a Base model for multiple tasks jointly, and then fine tune for specific tasks**

Training compute of notable machine learning models by domain, 2012–23
Source: Epoch, 2023 | Chart: 2024 AI Index report

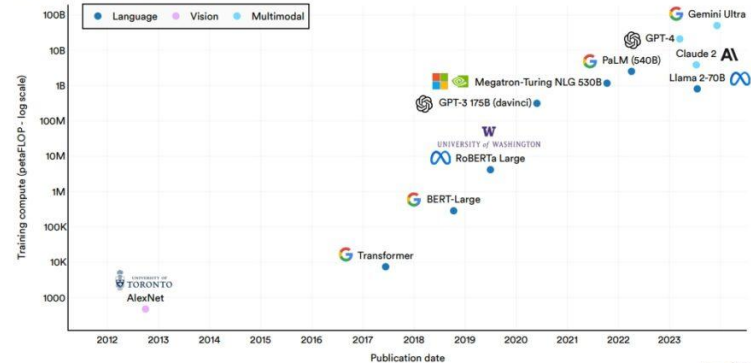


Figure 1.3.7



Training Neural Network Challenges

- Intractable gradients
 - Vanishing, and
 - Exploding gradients



Training Neural Network Challenges

- Intractable gradients
 - Vanishing, and
 - Exploding gradients
- Various normalizations
 - Input normalization (standard scalar)
 - Batch normalization
 - Layer normalization



Training Neural Network Challenges

- Intractable gradients
 - Vanishing, and
 - Exploding gradients
- Various normalizations
 - Input normalization (standard scalar)
 - Batch normalization
 - Layer normalization
- Controlling overfitting
 - Regularization
 - Early stopping
 - Drop out



QA