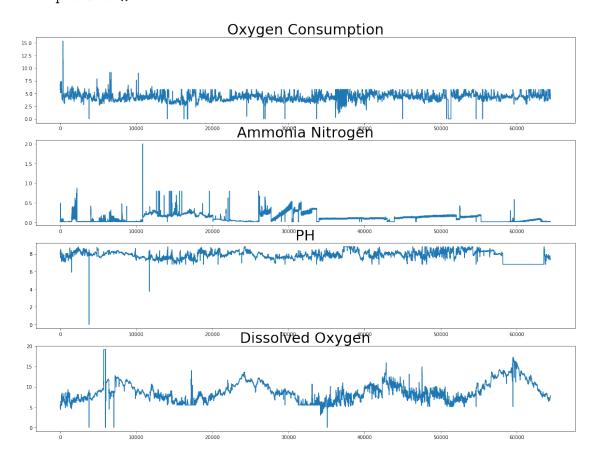
# Predict Dissolved Oxygen based on 60000+ data

#### August 27, 2019

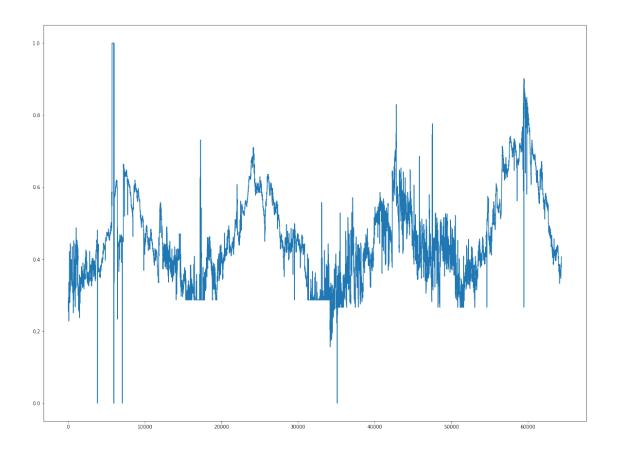
##The data are measured each 30 min in one location by online water quality monitor system

```
In [1]: import pandas as pd
        import seaborn as sns
        import numpy as np
        import matplotlib.pyplot as plt
        import datetime
        import warnings
        from sklearn import preprocessing
        from sklearn.preprocessing import StandardScaler
        from sklearn.preprocessing import LabelEncoder
        from sklearn.preprocessing import MinMaxScaler
        from livelossplot.keras import PlotLossesCallback
        from keras.models import Sequential
        from keras.layers import Dense
        from keras.layers import LSTM
        from keras.layers import GRU
        from keras import Input, Model
        from numpy import concatenate
        from sklearn.metrics import mean_squared_error
        from math import sqrt
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (40, 70) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
        plt.rcParams['image.cmap'] = 'gray'
Using TensorFlow backend.
In [28]: #
         dataset = pd.read_csv('HQQ.csv', header=0, index_col=None, parse_dates=True)
In [29]: values = dataset.values
         groups = [1, 2, 3, 4]
```

```
fig, axs = plt.subplots(1)
i = 1
for group in groups:
    plt.subplot(len(groups), 1, i)
    plt.plot(values[:, group])
    plt.title(dataset.columns[group], fontsize=30)
    i+=1
plt.show()
```



### 0.1 Data Preprocessing



```
In [7]: from tcn import TCN
In [8]: def data_split_TCN(data, train_len, lookback_window):
            train=data[:train_len]
            test=data[train_len:]
            X1, y1=[], []
            for i in range(lookback_window, len(train)):
                X1.append(train[i - lookback_window:i])
                y1.append(train[i])
                y_train = np.array(y1)
                X_train = np.array(X1)
            X2, y2=[], []
            for i in range(lookback_window, len(test)):
                X2.append(test[i - lookback_window:i])
                y2.append(test[i])
                y_{test} = np.array(y2)
                X_test = np.array(X2)
            return (X_train, y_train, X_test, y_test)
```

In [9]: def data\_split\_LSTM(X\_train,y\_train, X\_test, y\_test, lookback\_windows): #data split fo
# reshape the data to satisfy the input acquirement of LSTM

```
X_train = X_train.reshape(X_train.shape[0], X_train.shape[1], 1)
           X_test = X_test.reshape(X_test.shape[0], X_test.shape[1], 1)
           y_train = y_train.reshape(y_train.shape[0], 1)
            y_test = y_test.reshape(y_test.shape[0], 1)
            return (X_train, y_train, X_test, y_test)
In [10]: #Visualization
         def visualize(history):
             plt.rcParams['figure.figsize'] = (10.0, 6.0)
             # Plot training & validation loss values
            plt.plot(history.history['loss'])
             plt.plot(history.history['val_loss'])
            plt.title('Model loss')
            plt.ylabel('Loss')
            plt.xlabel('Epoch')
             plt.legend(['Train', 'Test'], loc='upper left')
             plt.show()
In [23]: def TCN_Model(X_train, y_train, lookback_window):
             i = Input(shape=(lookback_window, 1))
            m = TCN()(i)
            m = Dense(1, activation='linear')(m)
            model = Model(inputs=[i], outputs=[m])
             model.compile(optimizer='adam', loss='mse')
             model.fit(X_train, y_train, epochs=5, validation_split=0.2, shuffle=True, verbose
            return (model)
In [24]: def LSTM_Model(X_train, y_train):
            model = Sequential()
             model.add(LSTM(50, input_shape=(X_train.shape[1], X_train.shape[2])))
             model.add(Dense(1))
            model.compile(loss='mse', optimizer='adam')
             model.fit(X_train, y_train, epochs=5, batch_size=20, validation_split=0.2, verb
             return(model)
         #batch size=1 has the best result, but its disadvantage is it needs much longer time
In [25]: def GRU_Model(X_train, y_train):
            model = Sequential()
             model.add(GRU(50, input_shape=(X_train.shape[1], X_train.shape[2])))
             model.add(Dense(1))
             model.compile(loss='mse', optimizer='adam')
             model.fit(X_train, y_train, epochs=5, batch_size=20, validation_split=0.2, verb
             return(model)
In [26]: c=int(len(D0)*.8)
In [27]: X1_train, y1_train, X1_test, y1_test =data_split_TCN(D0, c, 20) #TCN
         X2_train, y2_train, X2_test, y2_test = data_split_LSTM(X1_train, y1_train, X1_test, y
         X3_train, y3_train, X3_test, y3_test = data_split_LSTM(X1_train, y1_train, X1_test, y
```

```
In [31]: model_DO_TCN=TCN_Model(X1_train, y1_train, 20)
WARNING:tensorflow:From /anaconda3/lib/python3.7/site-packages/tensorflow/python/ops/math_ops.
Instructions for updating:
Use tf.cast instead.
Train on 33003 samples, validate on 8251 samples
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
Epoch 5/5
In [32]: model_DO_LSTM=LSTM_Model(X2_train, y2_train)
Train on 33003 samples, validate on 8251 samples
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
In [33]: model_DO_GRU=GRU_Model(X3_train, y3_train)
Train on 33003 samples, validate on 8251 samples
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
Epoch 5/5
In [36]: #TCN original data
```

y1\_train\_hat=model\_DO\_TCN.predict(X1\_train)

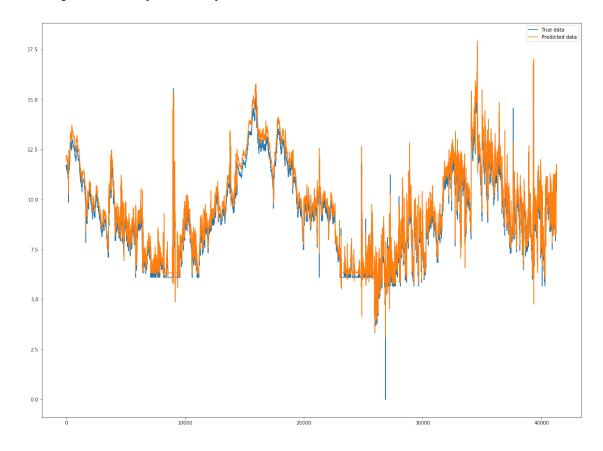
```
y1_train_hat=scaler_DO.inverse_transform(y1_train_hat)
y1_train=scaler_DO.inverse_transform(y1_train)

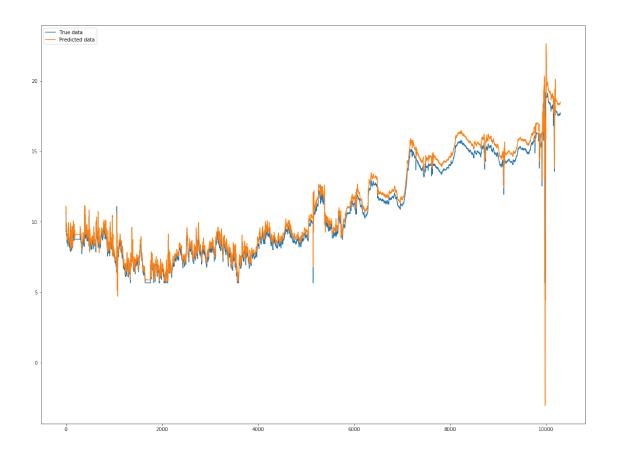
y1_test_hat=model_DO_TCN.predict(X1_test)
y1_test_hat=scaler_DO.inverse_transform(y1_test_hat)
y1_test=scaler_DO.inverse_transform(y1_test)

In [37]: def plot_curve(true_data, predicted):

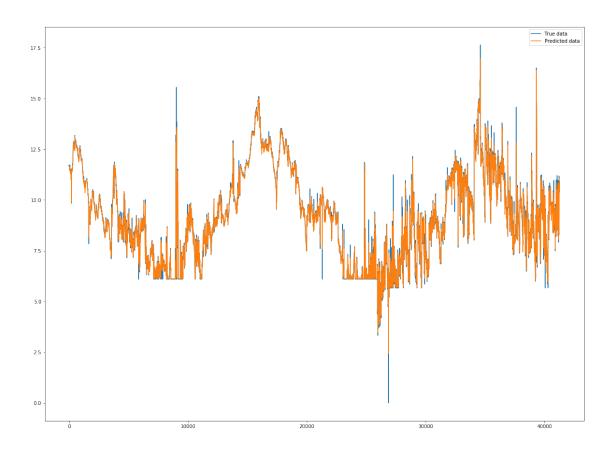
    plt.plot(true_data, label='True_data')
    plt.plot(predicted, label='Predicted_data')
    #plt.plot(predicted_LSTM, label='Predicted_data_by_LSTM')
    plt.legend()
    plt.savefig('result.png')
    plt.show()
```

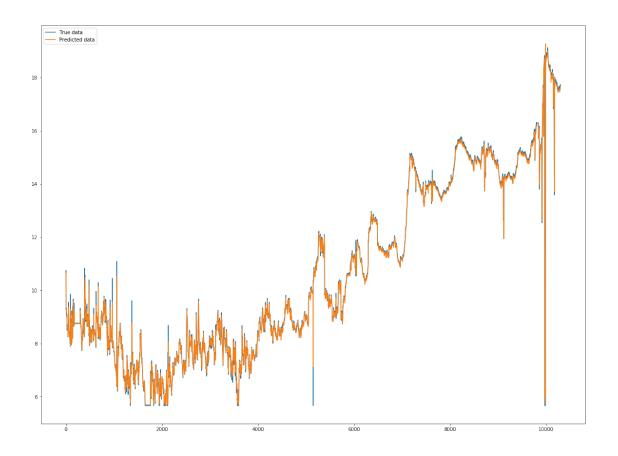
### 0.2 TCN





## 0.3 LSTM





### 0.4 **GRU**

