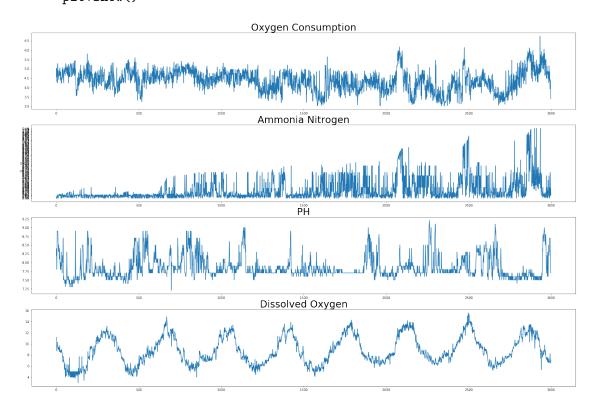
# Predict Dissolved Oxygen

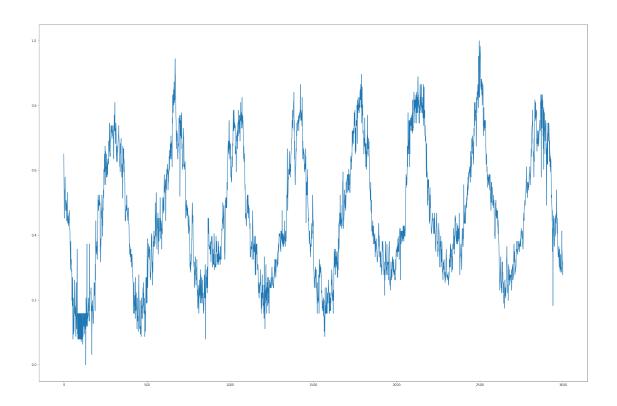
#### August 26, 2019

```
In [107]: import numpy as np
          import pandas as pd
          from pandas import read_csv
          from pandas import DataFrame
          from datetime import datetime
          from matplotlib import pyplot
          from sklearn.preprocessing import MinMaxScaler
          from sklearn.preprocessing import LabelEncoder
          from pandas import concat
          from keras.models import Sequential
          from keras.layers import Dense
          from keras.layers import LSTM
          from keras.layers import GRU
          from keras.layers import Dropout
          from numpy import concatenate
          from sklearn.metrics import mean_squared_error
          from math import sqrt
          from scipy import interpolate
          import matplotlib.pyplot as plt
          import matplotlib as mpl
          from keras import Input, Model
          from keras.layers import Dense
          %matplotlib inline
          plt.rcParams['figure.figsize'] = (30.0, 20.0) # set default size of plots
          plt.rcParams['image.interpolation'] = 'nearest'
          plt.rcParams['image.cmap'] = 'gray'
In [108]: #
          dataset = pd.read_csv('Water Quality Record.csv', header=0, index_col=0, parse_dates=
          values = dataset.values
          groups = [0, 1, 2, 3]
          fig, axs = plt.subplots(1)
          i = 1
```

```
for group in groups:
    plt.subplot(len(groups), 1, i)
    plt.plot(values[:, group])
    plt.title(dataset.columns[group], fontsize=30)
    i+=1
plt.show()
```



## 1 Data preprocessing



Out[111]: [<matplotlib.lines.Line2D at 0x1ab601a7b8>]

In [112]: from tcn import TCN

```
In [113]: def data_split_TCN(data, train_len, lookback_window):
              train=data[:train_len]
              test=data[train_len:]
              X1, y1=[], []
              for i in range(lookback_window, len(train)):
                  X1.append(train[i - lookback_window:i])
                  y1.append(train[i])
                  y_train = np.array(y1)
                  X_train = np.array(X1)
              X2, y2=[], []
              for i in range(lookback_window, len(test)):
                  X2.append(test[i - lookback_window:i])
                  y2.append(test[i])
                  y_test = np.array(y2)
                  X_test = np.array(X2)
              return (X_train, y_train, X_test, y_test)
In [114]: def data_split_LSTM(X_train,y_train, X_test, y_test, lookback_windows): #data split
              # reshape the data to satisfy the input acquirement of LSTM
             X_train = X_train.reshape(X_train.shape[0], X_train.shape[1], 1)
```

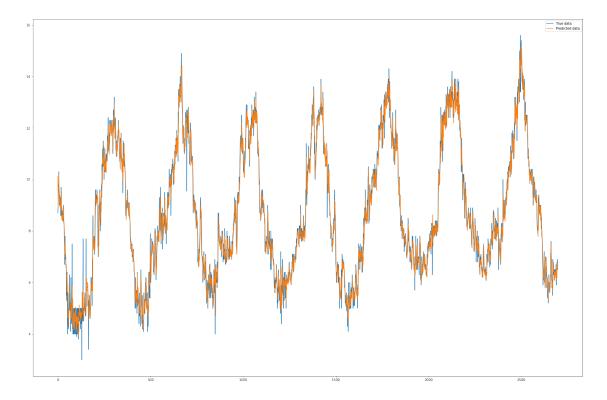
```
X_test = X_test.reshape(X_test.shape[0], X_test.shape[1], 1)
              y_train = y_train.reshape(y_train.shape[0], 1)
              y_test = y_test.reshape(y_test.shape[0], 1)
              return (X train, y train, X test, y test)
In [115]: #Visualization
          def visualize(history):
              plt.rcParams['figure.figsize'] = (10.0, 6.0)
              # Plot training & validation loss values
              plt.plot(history.history['loss'])
              plt.plot(history.history['val_loss'])
              plt.title('Model loss')
              plt.ylabel('Loss')
             plt.xlabel('Epoch')
              plt.legend(['Train', 'Test'], loc='upper left')
              plt.show()
In [139]: def TCN_Model(X_train, y_train, lookback_window):
              i = Input(shape=(lookback_window, 1))
              m = TCN()(i)
              m = Dense(1, activation='linear')(m)
              model = Model(inputs=[i], outputs=[m])
              model.compile(optimizer='adam', loss='mse')
              model.fit(X_train, y_train, epochs=5, validation_split=0.1, shuffle=True, verbose
              return (model)
In [140]: def LSTM_Model(X_train, y_train):
              model = Sequential()
              model.add(LSTM(50, input_shape=(X_train.shape[1], X_train.shape[2])))
              model.add(Dense(1))
              model.compile(loss='mse', optimizer='adam')
              model.fit(X_train, y_train, epochs=5, batch_size=1, validation_split=0.1, verb
              return(model)
In [141]: def GRU_Model(X_train, y_train):
              model = Sequential()
              model.add(GRU(50, input_shape=(X_train.shape[1], X_train.shape[2])))
              model.add(Dense(1))
              model.compile(loss='mse', optimizer='adam')
              model.fit(X_train, y_train, epochs=5, batch_size=1, validation_split=0.1, verb
              return(model)
In [142]: c=int(len(df)*.9)
```

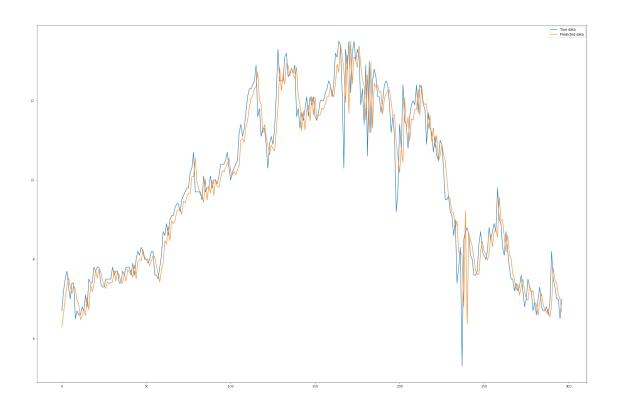
#### 2 DO

#x1\_train ,x1\_test for TCN; x2\_train,x2\_test for LSTM

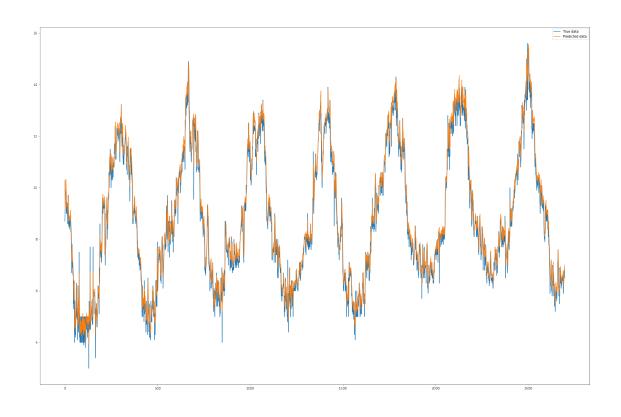
```
In [154]: X1_train, y1_train, X1_test, y1_test =data_split_TCN(D0, c, 1) #D0, TCN
   X2_train, y2_train, X2_test, y2_test = data_split_LSTM(X1_train, y1_train, X1_test, y2_train, X2_test, y2_train, X2_test, y2_train, X2_test, y2_train, X2_test, y2_train, X2_test
   X3_train, y3_train, X3_test, y3_test = data_split_LSTM(X1_train, y1_train, X1_test,
In [155]: model_DO_TCN=TCN_Model(X1_train, y1_train, 1)
Train on 2429 samples, validate on 270 samples
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
Epoch 5/5
In [156]: model_DO_LSTM=LSTM_Model(X2_train, y2_train)
Train on 2429 samples, validate on 270 samples
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
Epoch 5/5
In [157]: model_DO_GRU=GRU_Model(X3_train, y3_train)
Train on 2429 samples, validate on 270 samples
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
Epoch 5/5
```

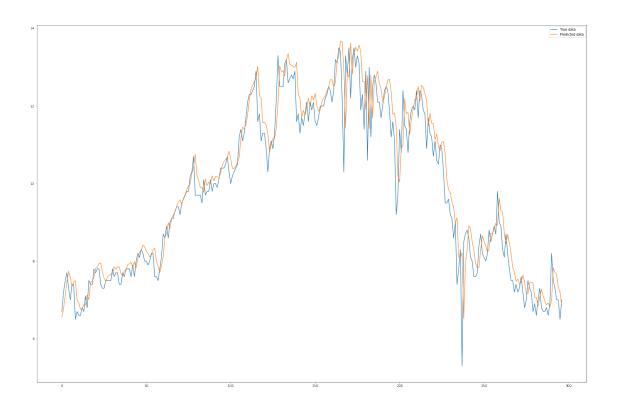
#### 2.0.1 TCN





### **LSTM**





#### 2.0.2 GRU

