

Matthew D. Kvalheim

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Citizenship: USA

Research Interests

Nonlinear systems in general, and in particular: dynamics, control theory, stochastic processes, robotics.

Employment

- 2022– **Postdoctoral Assistant Professor**, *University of Michigan*, Department of Mathematics.
Mentor: Anthony M. Bloch
- 2019–2022 **Postdoctoral Researcher**, *University of Pennsylvania*, Department of Electrical and Systems Engineering.
Mentors: Yuliy Baryshnikov, Daniel E. Koditschek
- 2018–2019 **Postdoctoral Research Fellow**, *University of Michigan*, Department of Electrical Engineering and Computer Science.
Mentors: Anthony M. Bloch, Shai Revzen

Education

- 2013–2018 **Ph.D.**, *University of Michigan*, Electrical Engineering.
- 2013–2017 **M.S.**, *University of Michigan*, Mathematics.
- 2013–2017 **M.S.**, *University of Michigan*, Electrical Engineering.
- 2009–2013 **B.S.**, *Ohio University*, Electrical Engineering, first in EECS graduating class.

Doctoral Thesis

Title Aspects of invariant manifold theory and applications
Adviser Shai Revzen

Published or Accepted Journal Papers

- 8 **A generalization of the Hopf degree theorem.**
Matthew D. Kvalheim
Proceedings of the American Mathematical Society, Accepted (2022). ([arXiv](#))
- 7 **Planning of obstacle-aided navigation for multi-legged robots using a sampling-based method over directed graphs.**
Kaustav Chakraborty, Haodi Hu, Matthew D. Kvalheim, and Feifei Qian
IEEE Robotics and Automation Letters, Accepted (2022). ([article](#))
- 6 **Necessary conditions for feedback stabilization and safety.**
Matthew D. Kvalheim and Daniel E. Koditschek
J. Geometric Mechanics, Accepted (2022). ([article](#), [arXiv](#))
- 5 **Families of periodic orbits: closed 1-forms and global continuability.**
Matthew D. Kvalheim and Anthony M. Bloch
J. Differential Equations, 285 (2021), pp. 211–257. ([article](#), [arXiv](#))

- 4 **Conley's fundamental theorem for a class of hybrid systems.**
Matthew D. Kvalheim, Paul Gustafson, and Daniel E. Koditschek
 SIAM J. Applied Dynamical Systems (SIADS), 20.2 (2021), pp. 784–825. ([article](#), [arXiv](#))
- 3 **Existence and uniqueness of global Koopman eigenfunctions for stable fixed points and periodic orbits.**
Matthew D. Kvalheim and Shai Revzen
 Physica D, 425 (2021), pp. 132959. ([article](#), [arXiv](#))
- 2 **Gait modeling and optimization for the perturbed Stokes regime.**
Matthew D. Kvalheim, Brian Bittner, and Shai Revzen
 Nonlinear Dynamics, 97.4 (2019), pp. 2249–2270. ([article](#), [arXiv](#))
- 1 **Global linearization and fiber bundle structure of invariant manifolds.**
Jaap Eldering, Matthew D. Kvalheim, and Shai Revzen
 Nonlinearity, 31.9 (2018), pp. 4202–4245. ([article](#), [arXiv](#))

Submitted Journal Papers and other Preprints

- 7 **Obstructions to asymptotic stabilization.**
Matthew D. Kvalheim
 SIAM J. Control and Optimization (SICON), Under Review (2022). ([arXiv](#))
- 6 **Estimating phase from observed trajectories using the temporal 1-form.**
Simon Wilshin, Matthew D. Kvalheim, Clayton Scott, and Shai Revzen
 Physical Review E, Under Review (2022). ([arXiv](#))
- 5 **Flux in tilted potential systems: negative resistance and persistence.**
Yuliy Baryshnikov and Matthew D. Kvalheim
 Communications in Mathematical Physics, Under Review (2021). ([arXiv](#))
- 4 **A pasting lemma for Lipschitz functions.**
Matthew D. Kvalheim, Paul Gustafson, and Samuel A. Burden
 (2021). ([arXiv](#))
- 3 **Phase response curves and the role of coordinates.**
Simon Wilshin, Matthew D. Kvalheim, and Shai Revzen
 (2021). ([arXiv](#))
- 2 **Poincaré-Hopf theorem for hybrid systems.**
Matthew D. Kvalheim
 (2021). ([arXiv](#))
- 1 **Reverse-engineering invariant manifolds with asymptotic phase.**
Matthew D. Kvalheim and Shai Revzen
 (2016). ([arXiv](#))

Peer-reviewed Conference Papers

- 2 **Generic properties of Koopman eigenfunctions for stable fixed points and periodic orbits.**
Matthew D. Kvalheim, David A. Hong, and Shai Revzen
 IFAC-PapersOnline, 54.9 (2021), pp. 267–272. ([article](#), [arXiv](#))
- 1 **Data-driven models of legged locomotion.**
Shai Revzen and Matthew D. Kvalheim
 SPIE Defense + Security. International Society for Optics and Photonics (2015). ([article](#))

Book Chapters

- 2 **Bioinspired legged locomotion, chapter 3.2: Templates and anchors.**
Matthew D. Kvalheim and Shai Revzen
Butterworth-Heinemann, Elsevier, Oxford (2017)
- 1 **Bioinspired legged locomotion, chapter 3.5: Locomotion as an oscillator.**
Shai Revzen and Matthew D. Kvalheim
Butterworth-Heinemann, Elsevier, Oxford (2017)

Teaching Experience

- 2022 **Course Instructor**, *University of Michigan*, Ann Arbor, MI.
Instructor of record for two course sections of Calculus I (Math 115) in Fall 2022
- 2015–2022 **Private Tutor**, *WyzAnt, Inc.*
Independent contractor; mathematics, electrical engineering;
perfect score on student evaluations (out of 19 total); 160+ hours experience
- 2019 **Guest Lecturer**, *University of Pennsylvania*, Philadelphia, PA.
Graduate course: Dynamical Systems for Engineering and Biological Applications (ESE 512)
Course instructor: Daniel E. Koditschek
- 2014 **Graduate Student Instructor**, *University of Michigan*, Ann Arbor, MI.
Senior-level course: Discrete-Time Signal Processing (EECS 451)
Course instructor: Laura Balzano
- 2011–2012 **Supplemental Instruction Leader**, **Academic Achievement Center**, *Ohio University*, Athens, OH.
Sophomore-level course: Statics (CE 220)

Mentoring and Outreach

- 2019–present **Mentor of graduate students**, *University of Pennsylvania*.
Mentored 2 graduate students in research
- 2019 **Volunteer, demonstrations to visiting K-12 students, Philly Robotics Expo (PRX)**, *University of Pennsylvania*, Philadelphia, PA.
Representing GRASP Laboratory, University of Pennsylvania; robotics outreach
- 2019 **Volunteer, demonstrations to members of the National Society of Black Engineers, 45th Annual Convention of the National Society of Black Engineers (NSBE)**, Detroit, MI.
Representing BIRDS Laboratory, University of Michigan; robotics outreach
- 2013–2018 **Mentor of undergraduate and graduate students, BIRDS Laboratory**, *University of Michigan*.
Mentored 2 undergraduate and 3 graduate students
- 2015 **Volunteer, demonstrations to visiting Chinese dignitaries**, *University of Michigan*, Ann Arbor, MI.
Representing University of Michigan; robotics outreach
- 2015 **Volunteer, demonstrations to alumni and industry**, *Engineering Graduate Symposium*, Ann Arbor, MI.
Representing BIRDS Laboratory, University of Michigan; robotics outreach
- 2015 **Volunteer, panel participant**, *Graduate Student Council*, Ann Arbor, MI.
Member of panel of University of Michigan graduate students; answering questions from prospective graduate students

- 2014 **Volunteer, demonstrations to elementary schoolers**, *Bryant Elementary School*, Ann Arbor, MI.
Representing BIRDS Laboratory, University of Michigan; robotics outreach

Talks

- 2022 **Large deviations, persistent homology, and Brownian conductors with negative resistance**, *Invited talk, Cornell University*, online.
Probability Seminar
- 2022 **When can hybrid systems operate safely?**, *Invited talk, University of Michigan*, online.
Control Seminar
- 2022 **Flux in small noise dynamics: persistence and negative resistance**, *Invited talk, Brown University, Division of Applied Mathematics*, online.
- 2021 **Flux in small noise dynamics: negative resistance and persistence**, *Invited talk, University of Illinois Urbana-Champaign*, online.
Mathematical Biology Seminar
- 2021 **When and how are hybrid dynamical systems conjugate to their classical quotients?**, *Invited talk, SIAM Conference on Control and its Applications*, online.
with Samuel A. Burden
Minisymposium: Physically grounded semantics for programming hybrid dynamical systems
- 2021 **Toward a physically grounded type theory for robot task composition.**, *Invited talk, IEEE International Conference on Robotics and Automation (ICRA)*, online.
with Daniel E. Koditschek and Paul Gustafson
Workshop: Compositional robotics: mathematics and tools
- 2021 **Toward a physically grounded type theory for robot task composition**, *Invited talk, IEEE International Conference on Robotics and Automation (ICRA)*, online.
with Daniel E. Koditschek and Paul Gustafson
Workshop: Compositional robotics: mathematics and tools
- 2021 **Small noise dynamics, persistence, and negative resistance**, *Invited talk, SIAM Conference on Applications of Dynamical Systems*, online.
with Yuliy Baryshnikov
Minisymposium: Stochastic oscillators
- 2021 **Flux in tilted potential systems: negative resistance and persistence**, *Invited talk, Army Research Office SLICE MURI W911NF-18-1-032 Group Meeting*, online.
- 2021 **Towards a Conley theory for hybrid dynamical systems**, *Invited talk, Rutgers University*, online.
TRIPODS/DATA-INSPIRE Workshop: Dynamics, Topology, and Robotic Control
- 2021 **Hierarchical composition via collapse of dimension in dynamical systems**, *Invited talk, ETH Zürich*, online.
Series: Autonomy Talks
- 2021 **Existence and uniqueness of global linearizing coordinates**, *Invited talk, Army Research Lab*, online.
Representing the MURI group funded by Army Research Office MURI 911NF-17-1-0306
- 2021 **Safety and stabilization: necessary conditions**, *Invited talk, Army Research Office SLICE MURI W911NF-18-1-032 Group Meeting*, online.
- 2021 **Necessary conditions for feedback stabilization and safety**, *Invited talk, University of Pennsylvania*, online.
Kod*Lab Research Seminar

- 2020 **Proving periodic orbits exist: global continuation and Lyapunov 1-forms**, *Invited Talk, University of Pennsylvania*, online.
Graduate Research Seminar in Applied Topology (GRST)
- 2020 **Proving periodic orbits exist: Lyapunov 1-forms and global continuation**, *Invited talk, University of Pennsylvania*, online.
Kod*Lab Research Seminar
- 2020 **Geometry and dynamics of circulant systems**, *Invited talk, AMS sectional meeting*, online.
with Anthony M. Bloch (speaker)
Special session: Geometric dynamics
- 2020 **Conley's fundamental theorem for a class of hybrid systems**, *Invited talk, Army Research Office SLICE MURI W911NF-18-1-032 Group Meeting*, online.
- 2020 **Conley's fundamental theorem for a class of hybrid systems**, *Invited talk, University of Pennsylvania*, online.
Kod*Lab Research Seminar
- 2020 **Toward a task planning theory for robot hybrid dynamics**, *Invited talk, BIRS-CMO*, online.
with Daniel E. Koditschek and Paul Gustafson
Workshop: Topological complexity and motion planning
- 2020 **Isochrons from short, noisy data**, *Invited talk, Dynamics Days Europe*, online.
with Simon Wilshin, Clayton Scott, and Shai Revzen
Minisymposium: Stochastic oscillators
- 2019 **Invariant manifolds, locomotion, and the Koopman operator**, *Invited Talk, University of Pennsylvania*, Philadelphia, PA.
Chaudhari Research Group Seminar
- 2019 **Templates, anchors, and normally hyperbolic invariant manifolds**, *Invited Talk, University of Pennsylvania*, Philadelphia, PA.
DAIR Lab Research Seminar
- 2019 **Templates, anchors, and normally hyperbolic invariant manifolds**, *Invited Talk, University of Pennsylvania*, Philadelphia, PA.
ScalAR Lab Research Seminar
- 2019 **Existence and uniqueness of linearizing semiconjugacies for stable fixed points and periodic orbits**, *Invited talk, California Institute of Technology*, Pasadena, CA.
Army Research Office MURI 911NF-17-1-0306 Group Meeting
- 2019 **Is legged locomotion almost smooth?**, *Dynamic Walking*, Calgary, AB, Canada.
with Shai Revzen (speaker) and George Council
- 2019 **Dynamics of circulant systems of ODEs**, *Invited talk, SIAM Conference on Applications of Dynamical Systems*, Snowbird, UT.
with Anthony M. Bloch (speaker)
- 2019 **Reduced-order models for locomotion in the perturbed Stokes regime**, *Invited talk, SIAM Conference on Applications of Dynamical Systems*, Snowbird, UT.
with Shai Revzen
- 2019 **Hybrid oscillators: phase and amplitude in a class of non-smooth systems**, *Invited talk, SIAM Conference on Applications of Dynamical Systems*, Snowbird, UT.
with Shai Revzen

- 2018 **Aspects of invariant manifold theory and applications**, *Invited talk*, University of California Santa Barbara, Santa Barbara, CA.
Army Research Office MURI 911NF-17-1-0306 Group Meeting
- 2018 **Oscillators, asymptotic phase, and reduction of dynamical systems**, *Invited talk*, University of Michigan, Ann Arbor, MI.
Applied and Interdisciplinary Mathematics Student Seminar
- 2018 **Testing an extended ‘Posture Principle’**, *Annual meeting of the Society for Integrative and Comparative Biology (SICB)*, San Francisco, CA.
with Shai Revzen
- 2018 **Invariant manifolds, asymptotic phase, and data-driven algorithms**, *Invited talk*, University of Pennsylvania, Philadelphia, PA.
Kod*Lab Research Seminar
- 2016 **A recipe for embedding templates in anchors**, *Invited talk*, University of Michigan, Ann Arbor, MI.
Legged Robotics Seminar
- 2015 **Introduction to homology: towards topological data analysis, pt. II/II**, *Invited talk*, University of Michigan, Ann Arbor, MI.
Signal Processing Student Seminar
- 2015 **Introduction to homology: towards topological data analysis, pt. I/II**, *Invited talk*, University of Michigan, Ann Arbor, MI.
Signal Processing Student Seminar
- 2015 **Phase-based models of rhythmic systems**, *Dynamic Walking*, Columbus, OH.
with Shai Revzen
- 2015 **Better models of rhythmic systems: predicting locomotion from phase alone**, *Annual meeting of the Society for Integrative and Comparative Biology (SICB)*, West Palm Beach, FL.
with Shai Revzen
- 2014 **Why the trot?**, *Annual meeting of the Society for Integrative and Comparative Biology (SICB)*, Austin, TX.
with Shai Revzen and Sam Burden (speakers)

Posters

- 2020 **A mode map representation to predict steady states and attraction basins for legged locomotion on obstacle terrains**, *International Conference on Intelligent Robotics and Systems (IROS)*, online.
with Haodi Hu (presenter), Michelle Joyce, Simon Wilshin, Andrew Spence, and Feifei Qian
Workshop: Robotics-inspired biology
- 2019 **Principal Koopman eigenfunctions for nonlinear and nonsmooth systems**, University of California, Los Angeles, Los Angeles, CA.
with Shai Revzen
Workshop: Operator theoretic methods in dynamic data analysis and control
- 2019 **Principal Koopman eigenfunctions for nonlinear and nonsmooth systems**, University of California, Los Angeles, Los Angeles, CA.
with Shai Revzen
Workshop: Operator theoretic methods in dynamic data analysis and control

- 2018 **Global linearization and fiber bundle structure of invariant manifolds**, *AIMS Conference Series on Dynamical Systems and Differential Equations*, Taipei, Taiwan.
with Jaap Eldering and Shai Revzen
- 2018 **Templates and Anchors: a review of notions of model reduction**, *Dynamic Walking*, Pensicola, FL.
with Shai Revzen
- 2017 **Asymptotic phase, model reduction, and control of Templates & Anchors**, *Ohio State University, Mathematical Biosciences Institute*, Columbus, OH.
with Shai Revzen
Workshop: Sensorimotor control of animals and robots
- 2017 **A dynamical systems perspective on Templates & Anchors: some general methods for anchoring templates**, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, BC.
with Shai Revzen
Workshop: Robotics-inspired Biology
- 2014 **Phase-based algorithm for modeling time-rescaling distortion of rhythmic data**, *University of Michigan*, Ann Arbor, MI.
with Shai Revzen
Engineering Graduate Symposium
- 2013 **A hybrid system provides a robust alternative to a linear regulator**, *University of Michigan*, Ann Arbor, MI.
with Shai Revzen
Engineering Graduate Symposium
- 2013 **An indoor navigation device for use in GPS-denied environments**, *University of Michigan*, Ann Arbor, MI, Award: 1st place, EECS division.
with Ryan Kollar, Christopher Moore, Jessica Belzer, and Matthew Miltner
Ohio University Student Expo

Honors and Awards

- 2013 **Rackham Engineering Award**, *University of Michigan*.
Graduate fellowship awarded by Rackham Graduate School
- 2013 **Outstanding Senior in Electrical Engineering**, *Ohio University*.
Awarded by a faculty panel
- 2013 **First place, Undergraduate Student Expo**, *Ohio University*.
Senior design team awarded first place in the EECS division
- 2012 **Undergraduate Research Award, College of Engineering**, *Ohio University*.
My proposal was funded for a semester of undergraduate research
- 2012 **Outstanding Junior in Electrical Engineering**, *Ohio University*.
Awarded by a faculty panel
- 2009–2013 **Gateway Excellence Scholarship**, *Ohio University*.
Academic merit-based scholarship (full tuition)
- 2011 **Dean's Scholarship**, *Ohio University*.
Academic merit-based scholarship
- 2011 **Fritz/Dolores Russ Scholarship**, *Ohio University*.
Academic merit-based scholarship

Academic Service

Reviewer for

SIAM J. Control and Optimization, Stochastic Models, Biological Cybernetics, Annual Reviews in Control, IEEE Conference on Decision and Control (CDC), ASME J. Biomechanical Engineering, Robotics: Science and Systems (RSS), International Symposium on Nonlinear Theory and Its Applications (NOLTA), and others.

Co-organizer

2022 **IEEE International Conference on Robotics and Automation (ICRA).**

Workshop: Compositional Robotics: Mathematics and Tools

2022 **Festschrift in honor of Daniel E. Koditschek.**

Professional Memberships

American Mathematical Society (AMS), Institute of Electrical and Electronics Engineers (IEEE), Society for Industrial and Applied Mathematics (SIAM), SIAM Activity Group on Dynamical Systems (SIAG/DS), and others.

Other work experience

2012 **Undergraduate Student Researcher,** *Ohio University*, Athens, OH.

Funded undergraduate research; sensor fusion and navigation for drones

Adviser: Maarten Uijt de Haag

2012 **Co-Op,** *GE Aviation Systems*, Vandalia, OH.

2011 **Engineering Intern,** *Lakeshore Cryotronics*, Westerville, OH.

References

Yuliy Baryshnikov

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Anthony M. Bloch

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Shai Revzen

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