Formulation of the optimization model in Owl

Martin-D. Lacasse

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1. Introduction

This document describes the mathematical model underlying the optimization algorithms implemented in Owl. This code is a Python application optimizing retirement planning using linear programming. The goal of these calculations is to optimize the financial aspects of retirement planning, considering the types of savings accounts, income tax, contributions, return rates, Roth conversions, and desired income amongst many other things.

The approach is described here mathematically and the implementation follows the structure and notation presented in this document. The intent of this document is to provide a guide to the Python code for any individual desiring to extend the model to other cases.

2. Indices, variables, and parameters

In the next sections, the indices, variables, and parameters are described in detail. Then the model constraints are introduced. For implementation in a linear programming solver, index mapping functions are proposed to map all variables into a single one-dimensional array that is optimized subject to inequality and equality constraints expressed in matrix form. Finally, the constraint matrices are built and so are some useful objective functions.

2.1 Indices

For all indices, we will follow the C array style (starting at 0), rather than the traditional mathematical standard starting at 1. This will facilitate the final sequential mapping of all the variables into a single one-dimensional array, and serve as a direct reference for better understanding the code implementation.

The indices used and their range are defined here, while we also introduce the characteristics and dimensions of the problem. Upper bounds on indices are indicated by the letter N, with the index name as a subscript, e.g., N_i for index i.

- Individual. i runs from 0 to $N_i 1$ where $N_i = 2$ for couples, or $N_i = 1$ for single individuals. The first individual to pass is denoted by i_d while the survivor is i_s .
- *j* Type of savings account. j goes from 0 to $N_j 1$, for taxable, tax-deferred, and tax-exempt accounts respectively. Therefore $N_j = 3$.
- k Type of asset class. k goes from 0 to $N_k 1$, for S&P 500, Baa corporate bonds, Treasury notes, and cash, respectively. $N_k = 4$. More asset classes could be considered at the cost of increasing the complexity of the problem while not generating much more insights.
- Year being modeled. n runs from 0 to $N_n 1$, and N_n is the first year following the passing of all individuals in the plan. The time period for all decision variables is annual. For spouses, $n_d 1$ is the year in which the first individual passes while the survivor will decease in year $N_n 1$ of the plan.
- Federal income tax bracket. t goes from 0 to $N_t 1$, from low to high. There are $N_t = 7$ federal income tax brackets.

2.2 Variables

We will use lowercase roman letters to represent variables. All variables are assumed to take only non-negative values (≥ 0 inequality).

Balance for individual i in savings account j at the beginning of year n. When we consider each asset class k, the variable b_{ijkn} is used instead.

 d_{in} Deposit of year-n net spending surplus in taxable account of individual i. Ideally, deposits would be made at the end of year n, but this creates spurious conditions that will be discussed below.

 f_{tn} Fraction of tax bracket t filled, so that taxable ordinary income G_n can be expressed as

$$G_n = \sum_t f_{tn} \bar{\Delta}_{tn}, \tag{2.1}$$

$$0 \le f_{tn} \le 1. \tag{2.2}$$

A definition of Δ can be found in the section describing the parameters below.

 g_n Net spending in year n.

 w_{ijn} Withdrawal from account j belonging to individual i at the beginning of year n. For the (j=1) tax-deferred savings account, w_{i1n} is referred to as a distribution for tax purposes as it is a taxable withdrawal, and will always satisfy required minimum distributions.

 x_{in} Roth conversion performed by individual *i* during year *n*. These events are taxable as ordinary income.

2.3 Parameters

For more easily distinguishing parameters from variables, all parameters will be expressed in Greek letters. Parameter values are either set by the user, historical data, or by the tax code.

 βij Initial balances in savings accounts. These amounts are used to initialize b_{ij0} .

Annual rate of return for asset class k in year n. A time series of annual return rates for each class of asset. Here, inflation and the rate of return of (k = 3) cash are assumed to be the same. In other words, investing in cash yields constant dollars (just inflation).

 γ_n Cumulative inflation at the beginning of year n computed as the product

$$\gamma_n = \prod_{n'=0}^{n-1} (1 + \tau_{3n'}), \tag{2.3}$$

with $\gamma_0 := 1$, and where n' is a dummy index. Parameters indexed for inflation will be indicated by a bar on top as in $\bar{\sigma}_n$.

 σ_n Standard deduction. It can be adjusted for inflation as follows

$$\bar{\sigma}_n = \sigma_n \gamma_n, \tag{2.4}$$

and can be modified for additional age exemptions after 65 of age, for example. It is a simple time series which can include any foreseeable changes in the tax code, or change in filing status due to the passing of one spouse for $n \ge n_d$.

 ξ_n Spending profile. This is a time series that multiplies the desired net spending amount. It is $\xi_n = 1$ for a flat profile, or can be a *smile* profile allowing for more money at the start of retirement. Parameter ξ_n can also contain spending adjustments typically made at the passing of one spouse. The *smile* can be implemented using a cosine superimposed over a gentle linear increase such as in

$$\xi_n = 1 + a_1 * \cos(2n\pi/(N_n - 1)) + a_2 n/(N_n - 1), \tag{2.5}$$

and then normalized by factor $N_n/(\sum_n \xi_n)$ to be sum-neutral with respect to a flat profile. Values of $a_1 = 15\%$ and $a_2 = 12\%$ provide curves that are similar to realistic spending profiles reported in the literature. See Fig. 2.1 for an example. At the passing of one spouse, both profiles are reduced by a factor χ for $n \geq n_d$, and the normalizing factor needs to be adjusted accordingly.

- χ Factor to reduce spending profile after the passing of one spouse. It is typically assumed to be 0.6.
- ρ_{in} Required minimum distribution for individual i in year n. Expressed in fractions which are determined from IRS tables. Simple if spouses are less than 10 years apart, a little more complex otherwise, as the age of both spouses need to be taken into account. Current implementation only supports spouses being less that 10 years apart. An error message is generated in these cases and the calculation is aborted.
- Γ_{tn} Bound for Federal income tax bracket. We define $\Gamma_{(-1)n} := 0$, so that Γ_{0n} is the upper bound for the 10% tax bracket in year n. As the filing status can change for couples, and so can the tax code, Γ_{tn} will be changing over n.
- Δ_{tn} Difference between upper bound Γ_t and lower bound Γ_{t-1} of a federal income tax bracket,

$$\Delta_{tn} = \Gamma_{tn} - \Gamma_{(t-1)n}. \tag{2.6}$$

Once adjusted for inflation, the taxable income can be expressed as in Eq. (2.1). These data are 7 time series. The filing status changes after the passing of one spouse $(n \ge n_d)$ and and these brackets are adjusted accordingly.

- θ_{tn} Tax rate for tax bracket t in year n. Using N_t time series allows to adjust income tax rates in foreseeable future. For example, in 2024 the rates (in decimal) are .10, .12, .22, .24, .32, .35, and .37. It is speculated that the rates will revert back to 2017 rates in 2026 with .10, .15, .25, .28, .33, .35, and .396. See Eq. (2.15) for its use.
- α_{ijkn} Desired asset allocation for savings account j of individual i in assets class k during year n. Allocation ratios come in many flavors as they could be specified globally between

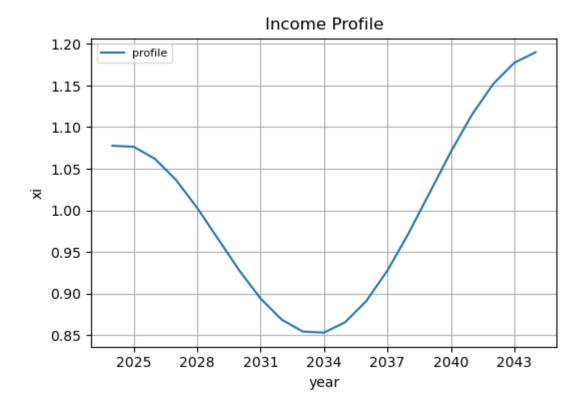


Figure 2.1: Example of a spending profile with 15% cosine factor and a 12% linear profile.

individuals and accounts as α_{kn} , for example. When specified by the user, allocation ratios typically involve two values, one at the beginning of the plan α_{ijk0} and the other at the end $\alpha_{ijkN_{n-1}}$. Then, intermediate values are interpolated either using a linear relation,

$$\alpha_{ijkn} = a + \frac{n}{N_n - 1}(b - a), \tag{2.7}$$

or an s-curve as in

$$\alpha_{ijkn} = a + \frac{(b-a)}{2} (\tanh((n-n_1)/n_2) + 1),$$
(2.8)

where n_1 is the number of years ahead when inflection point will occur, and n_2 is the width (in years) of the transition. Constants n_1 and n_2 are selected by the user. Using $a = \alpha_{ijk0}$ and $b = \alpha_{ijkN_n-1}$ is an approximation as values of ± 1 are only reached at $\pm \infty$. More precise bounds a' and b' can be determined by solving a 2×2 system of equations leading to

$$a' = (a - k_{12}b')/k_{11}$$

$$b' = ((b - (k_{21}/k_{11})a)/(k_{22} - (k_{21}/k_{11})k_{12}),$$
(2.9)

jack & jill - tutorial Assets Allocations (%) - taxable Jill C bonds / taxable Jill stocks / taxable Jill % year

Figure 2.2: Example of an allocation portfolio with 60/40% stocks/bonds transitioning to 70/30% using an s-curve.

where

$$k_{11} = \frac{1}{2}(1 + \tanh(n_1/n_2))$$

$$k_{12} = \frac{1}{2}(1 - \tanh(n_1/n_2))$$

$$k_{21} = \frac{1}{2}(1 - \tanh((N_n - 1 - n_1)/n_2))$$

$$k_{22} = \frac{1}{2}(1 + \tanh((N_n - 1 - n_1)/n_2)).$$
(2.10)

These interpolation functions allow the allocation ratios to gradually change or glide during retirement. Fig. (2.2) provides an example of an s-curve gliding allocation ratios.

It is also possible to have a coarser granularity on the portfolio by having an asset allocation scheme defined on a sum of accounts. For example, allocation can be coordinated between accounts leading to α_{ikn} , or even between spouses as α_{kn} . For any of these cases, it is

assumed that weights are always properly scaled so that

$$\sum_{k} \alpha_{ijkn} = 1,$$
or
$$\sum_{k} \alpha_{ikn} = 1,$$
or
$$\sum_{k} \alpha_{kn} = 1,$$
(2.11)

depending on the scheme selected.

- Λ_{in}^{\pm} Big-ticket item requested by individual i in year n. These are large expenses or influx of money that can be planned. Therefore, Λ^{\pm} can be positive (e.g., sell a house, inheritance) or negative (e.g., buy a house, large gifts).
- π_{in} Sum of pension benefits for individual i in year n. These amounts are typically specified along with the ages at which these benefits begin.
- ζ_{in} Social security benefits for individual i in year n. Starting age and the passing of one individual for spouses will determine the time series. $\bar{\zeta}_{in}$ is the same series adjusted for inflation.
- ϵ_{N_n} Desired amount to leave as a bequest at the end of the final year of the plan, $N_n 1$, which is the beginning of year N_n . This amount is the after-tax value of the estate for the heirs. See parameter ν .
- κ_{ijn} Sum of contributions to savings account j made by individual i during year n. We assume that contributions are made at half-year to balance regular contributions. In practice, a contribution amount κ_{ijn} is specified in which case the contribution to each asset class is

$$\kappa_{ijkn} = \alpha_{ijkn}\kappa_{ijn}. \tag{2.12}$$

- ω_{in} Sum of wages obtained by individual *i* during year *n*. Do not confuse wages ω with withdrawals w.
- μ Dividend return rate in taxable accounts. Average is little above 2% for S&P 500.
- ν Heirs income tax rate to be applied on the tax-deferred portion of the estate. This is not an estate tax but rather the federal income marginal tax rate for the heirs.
- ϕ_j Fraction of savings account j that is left to surviving spouse i_s as a beneficiary at the death of individual i_d , the first spouse to pass.
- ψ Income tax rate on long-term capital gain and qualified dividends, typically 15%.
- η Spousal ratio for withdrawals.

2.4 Intermediate variables

We use intermediate variables for conciseness or clarity, but they are ultimately replaced in the final formulation. All intermediate variables are in uppercase letters.

 G_n Taxable ordinary income in year n. Sum of wages, pension, social security benefits, all withdrawals from tax-deferred accounts, including Roth conversions, and gains from securities (i.e., all gains except those from the (k=0) equities) in the (j=0) taxable account, including contributions κ , minus the standard deduction,

$$G_{n} = \sum_{i} [\omega_{in} + .85\bar{\zeta}_{in} + \pi_{in}] - \bar{\sigma}_{n} +$$

$$\sum_{i} [w_{i1n} + x_{in}] +$$

$$\sum_{ik} [(1 - \delta(k, 0))(b_{i0n} - w_{i0n} + d_{in} + .5\kappa_{i0n})\alpha_{i0kn}\tau_{kn}]$$
(2.13)

Social security is indexed for inflation and is assumed to be taxed at 85%. We use a discrete Kronecker δ function for selecting gains from non-equity assets in taxable accounts. These gains are all taxed as ordinary income. Here, we assumed that deposits and withdrawals in the taxable account are taking place at the beginning of the year, while contributions are taking place in mid-year.

 Q_n Qualified dividends and long-term capital gains obtained in year n. They only involve gains occurring in taxable savings accounts (j=0) that were obtained from equities (k=0), or sales of stocks due to withdrawals from taxable savings accounts. For simplicity, we assume that all sales only generate long-term capital gains and that all dividends are qualified, resulting in

$$Q_n = \sum_{i} \alpha_{i00n} \left[(b_{i0n} - w_{i0n} + d_{in} + .5\kappa_{i0n})\mu + w_{i0n} \max(0, \tau_{0n-1}) \right].$$
 (2.14)

A formulation where only a fraction of dividends are qualified can easily be implemented with the addition of another parameter. Notice that we are using return rates from the previous year. The first terms on the right-hand side represent the amount of equities (k=0) in the (j=0) taxable savings account plus half the yearly contributions. The last terms account for withdrawals w of equities assumed to have been purchased a year ago. It does not account for losses, but a market drop would most likely result in stock purchase rather than sale. For withdrawals, we make the assumption of selling the most recent stocks which would not be accurate in situations where the taxable savings account is being depleted slowly.

 T_n Amount of income tax paid on taxable ordinary income G_n in year n. This is the taxes paid on ordinary income expressed as the sum of the amounts paid in each tax bracket as

$$T_n = \sum_t f_{tn} \bar{\Delta}_{tn} \theta_{tn}. \tag{2.15}$$

Notice that G_n is also defined by Eq. (2.1), and that optimal values of f_{tn} have to minimize T_n when either the bequest or the desired net spending are maximized. As the product

 $\Delta_{tn}\theta_{tn}$ does not guarantee to be ordered monotonically, a more practical choice is to use the combined variable $\bar{F}_{tn} = f_{tn}\bar{\Delta}_{tn}$ in the optimization. Given that the rates on tax brackets θ_{tn} are always increasing monotonically, we are then naturally filling in the lower brackets first when optimizing. In that case

$$T_n = \sum_t \bar{F}_t \theta_{tn}. \tag{2.16}$$

 U_n Amount of income tax paid on long-term capital gains and qualified dividends in year n,

$$U_n = \psi Q_n. \tag{2.17}$$

Although it is not always the case, we assume that qualified dividends and long-term capital gains are taxed at the same preferential rate ψ .

 M_n Medicare and Income Related Monthly Adjusted Adjustment for Medicare. As this additional adjustment is a step function, it has to be computed using binary variables and mixed-integer linear programming. The adjustment is computed from the modified adjusted gross income (MAGI) from 2 years earlier. For the MAGI, we will simply use $G_{n-2} + \bar{\sigma}_{n-2}$ and ignore the additional IRS rules around tax-free interests.

There are q=5 levels of step adjustments, $\bar{L}_{qn}=L_q\gamma_n$ and each of them introduce an annual additional Medicare cost of $\bar{C}_{qn}=C_q\gamma_n$. Both levels and costs are adjusted for inflation. Using binary variables z_{inq} and the following constraint

$$\bar{\sigma}_{n-2} - \bar{L}_{an} \le z_{ina}M - G_{n-2} \le bigM - \bar{L}_{an} + \bar{\sigma}_{n-2},$$
 (2.18)

the IRMAA adjustments can then computed as

$$I_n = \sum_{iq} z_{iqn} \bar{C}_{qn}. \tag{2.19}$$

If the plan does not have data from 2 years ago as Medicare starts, it will use last year's or this year's MAGI instead, in that order.

While this approach has been implemented and tested, the robustness of the bigM approach is not guaranteed and an easier approach is to implement a self-consistent loop that optimizes the spending or bequest, and updates the Medicare/IRMAA premiums accordingly. Therefore, the value will be computed from the MAGI as $M_n^s(G_n + \bar{\sigma}_n)$, where the value is at iteration s. After only a few iterations, the solution is converging to within a dollar over the sum of all variables in the plan. This approach, however, does not guarantee convergence as there can be cases where the premiums affect the solution which can oscillate between two solutions. Moreover, as the premiums are introduced as parameters in the constraints, there is no optimization taking place on Medicare costs.

3. Formulation with imposed asset allocation ratios

We first present the case where the sums of assets in each savings accounts b_{ijn} are known over which we assume a prescribed asset allocation ratios. The amount in each asset class k for b_{ijkn} is simply obtained from $\alpha_{ijkn}b_{ijn}$ in this case. This formulation assumes that the accounts are always balanced. This is a reasonable assumption given the auto-balancing feature offered by many financial service providers.

The benefit of this approach is that it has less variables and that only the sums of all asset classes in each savings account need to be known. The rate of return of the account is then simply the product of the account balance with the sum of the rates of return weighted according to the desired allocation ratio. This approach allows us to eliminate k by summing over it and rewrite

$$\sum_{k} b_{ijkn+1} = \sum_{k} b_{ijkn} (1 + \tau_{kn}) + \dots, \tag{3.1}$$

for the annual evolution of account balances from year n to year n+1 as the simpler expression

$$b_{ijn+1} = b_{ijn} \sum_{k} \alpha_{ijkn} (1 + \tau_{kn}) + \dots,$$

$$= b_{ijn} (1 + \mathcal{T}_{ijn}) + \dots,$$
 (3.2)

where

$$\mathcal{T}_{ijn} := \sum_{k} \alpha_{ijkn} \tau_{kn}. \tag{3.3}$$

In this formulation where the α_{ijkn} are prescribed, we will use \mathcal{T}_{ijn} to add the market returns to the savings balances.

3.1 Constraints

Required minimum distributions (RMDs) Withdrawals from the (j = 1) tax-deferred savings accounts must be larger or equal than the required minimum distributions, and therefore

$$\sum_{k} [w_{i1n} - \rho_{in}b_{i1n}] \ge 0. \tag{3.4}$$

As b_{ijn} are the balances at the beginning of year n, they are also the balances at December 31 of the previous year, which is the amount from which the IRS bases the RMDs. Eq. (3.4) has to hold for each year n and each individual i, and therefore, there are $i \times N_n$ such equations (even when $\rho_{in} = 0$). These constraints avoid paying the 50% penalty on amounts not withdrawn when RMDs are required. Note that aggregate rules need to be considered separately as this approach only considers the sum of assets in a class with similar tax treatment (e.g., IRA and 401k).

Income tax brackets Taxable ordinary income is divided in tax brackets as defined in Eq. (2.1), i.e.,

$$G_n = \sum_{t} f_{tn} \bar{\Delta}_{tn},$$

$$0 \le f_{tn} \le 1. \tag{3.5}$$

Given this definition, all bracket fractions f must be positive and smaller than or equal to 1, imposing an upper bound on f. Because $\theta_t > \theta_{t'}$ when t > t', we can exploit this monotonically increasing series of rates with t to have the minimization algorithm naturally fill the lower tax brackets. For that purpose, we need to introduce the combined variable

$$\bar{F}_{tn} = f_{tn}\bar{\Delta}_{tn},\tag{3.6}$$

implying that

$$G_n = \sum_t \bar{F}_{tn},\tag{3.7}$$

with

$$0 \le \bar{F}_{tn} \le \bar{\Delta}_{tn}. \tag{3.8}$$

Account balances Contributions are assumed to be made at half-year to better represent periodic contributions made throughout the year. As we already mentioned, the account balance at the end of a year is the same as the balance at the beginning of the following year. Changes include contributions κ , distributions and withdrawals w, conversions x, and growth τ on the account through the year. We track each savings account j separately, and the tax-deferred account is coupled to the tax-exempt account through Roth conversions.

The timing of Roth conversions, withdrawals, and deposits determines the coupling between these variables, and is worth a detailed discussion. First, the financial aspect, and then the algorithmic one. For the former, some financial advisors would recommend making conversions at the beginning of the year, while making withdrawals at the end. Obviously, simulators would always yield higher numbers for this scenario, as the moneys needed to pay the regular bills stayed in the bank until the end of the year. More realistically, however, it would be more accurate to assume the withdrawals at mid-year, to better represent evenly distributed withdrawals. So, financially, conversions at the beginning of the year, and withdrawals at mid-year make good sense. Conversions are also typically best when timed with a market downturn in the year.

Now, let's look at the optimization side of these transactions. During years of positive returns, a direct withdrawal from the tax-deferred account will always be unfavorable when compared to a Roth conversion at the beginning of the year, followed by a tax-exempt withdrawal later in the year. This is because the second scenario involves gains which are tax-free over the year, while the

first one does not. Moving account withdrawals at the beginning of the year, and the conversions in mid-year can solve this artificial bias. To favor tax-deferred withdrawals in most reasonable situations, it is desirable to make conversion and withdrawal events exclusive by introducing binary variables $z_{in} \in \{0,1\}$ with the following constraints:

$$0 \le z_{in}M - x_{in} \le M,$$

$$0 \le z_{in}M + w_{i1n} \le M.$$
(3.9)

Here, M is a large number such as 10^7 , just slightly larger than what x and w can possibly be.

Roth conversions are assumed to be made at mid-year, while withdrawals are made at the beginning of the year, and surplus deposits, if needed, could be made at the end of the year. Let's explore this approach in more detail.

Timing controls which terms get multiplied by the rate of return $(1 + \tau_{kn})$ for this particular asset k. Therefore, our current choice would yield

$$b_{ij(n+1)} = [b_{ijn} - w_{ijn} + .5\kappa_{ijn}](1 + \mathcal{T}_{ijn}) + (\delta(j,2) - \delta(j,1))x_{in}(1 + \mathcal{T}_{ijn}/2) + \delta(j,0)d_{in} + .5\kappa_{ijn},$$
(3.10)

where we use discrete Kronecker δ functions for selecting the specific accounts involved in Roth conversions. These conversions are made such that asset allocation ratios in the sending and receiving accounts are unchanged.

Bringing all variables to the left-hand side, this gets rewritten as

$$b_{ij(n+1)} - [b_{ijn} - w_{ijn}](1 + \mathcal{T}_{ijn}) - (\delta(j,2) - \delta(j,1))x_{in}(1 + \mathcal{T}_{ijn}/2) - \delta(j,0)d_{in} = \kappa_{ijn}(1 + \mathcal{T}_{ijn}/2).$$
(3.11)

When j = 0, this equation introduces a path to shelter negative returns by performing an over-withdrawal from the taxable account at the beginning of the year followed by a deposit in the same account at the end of the year. This can be removed by using another binary variable and make these events exclusive, using the same strategy as Eq. (3.9). Another approach, while not so natural, is to move all deposits at the beginning of the year so to be synchronous with withdrawals.

$$b_{ij(n+1)} - [b_{ijn} - w_{ijn} + \delta(j,0)d_{in}](1 + \mathcal{T}_{ijn}) - (\delta(j,2) - \delta(j,1))x_{in}(1 + \mathcal{T}_{ijn}/2) = \kappa_{ijn}(1 + \mathcal{T}_{ijn}/2).$$
(3.12)

This is the current approach used in Owl.

The initial balances β_{ij} are one of the main inputs of this model. The initial savings account balances are imposed through additional constraints as

$$b_{ij0} = \beta_{ij}. \tag{3.13}$$

At this point, we assume the the accounts are balanced according to the desired allocation ratios α_{ijkn} .

We also introduce another constraint that might look unnecessary, but helps convergence significantly. As the withdrawals are at the beginning of the year we impose that

$$w_{ijn} \le b_{ijn}. \tag{3.14}$$

Roth Conversions Roth conversions cannot be larger than the balance in the account:

$$x_{ijn} \le b_{i1n}. \tag{3.15}$$

This constraint, however, is naturally satisfied when $b_{ijn} \ge 0$ non-negativity is enforced. Additional constraints x_{max} can be imposed on conversions and then the previous equation becomes

$$x_{in} \le \min(b_{i1n}, x_{max}). \tag{3.16}$$

Net spending For calculating the net spending g_n , we consider the cash flow of all withdrawals, wages, social security and pension benefits, and big-ticket items. Then we subtract potential surplus deposits d_{in} made to the taxable savings account and all taxes paid:

$$g_n = \sum_{i} [\omega_{in} + \bar{\zeta}_{in} + \pi_{in}] + \sum_{ij} w_{ijn} + \sum_{i} \Lambda_{in}^{\pm} - \sum_{i} d_{in} - T_n - U_n - M_n.$$
 (3.17)

Notice how the big-ticket items Λ^{\pm} contribute directly to the cash flow. Replacing intermediate variables and bringing all variables to the left-hand side, we get

$$\begin{split} g_n - \sum_{ij} w_{ijn} + \sum_i d_{in} + \sum_t \bar{F}_{tn} \theta_{tn} \\ + \psi \alpha_{i00n} \sum_i \left[\mu(b_{i0n} - w_{i0n} + d_{in}) + w_{i0n} \max(0, \tau_{0n-1}) \right] &= \sum_i \left[\omega_{in} + \bar{\zeta}_{in} + \pi_{in} \right] + \\ & \sum_i \left[\Lambda_{in}^{\pm} - .5 \psi \mu \alpha_{i00n} \kappa_{i0n} \right] - N \beta_i^s 18) \end{split}$$

Notice that we do not consider market losses as we use $\max(0,\tau)$, and that rates from only the previous year are used. Tax-loss harvesting is beyond the scope of this model. For clarity, we did not express $M_n^s(G_n + sigma_n)$ in terms of the modified adjusted gross income (MAGI), but one to understand that there is a self-consistent loop solving for it and we are at iteration s.

We also want the net spending to be predictable and smooth. We will use

$$q_n/\bar{\xi}_n = q_0/\bar{\xi}_0,$$
 (3.19)

where the net spending is adjusted for inflation and where we introduced parameter ξ_n allowing for additional adjustments to the overall desired spending. Note that $\bar{\xi}_0 = \xi_0$ as $\gamma_0 = 1$. This spending profile can also be used to lower the desired income at the passing of one spouse and/or to allow for more realistic spending profiles. Eq. (3.19) can be rewritten as

$$g_n \xi_0 - g_0 \bar{\xi}_n = 0, \tag{3.20}$$

for the constraints to be enforced. Once g_0 is determined, the whole time series of net spending is determined.

Taxable ordinary income We connect the two definitions for G_n stated above in Eqs. (2.1) and (2.13),

$$\sum_{t} f_{tn} \bar{\Delta}_{tn} = \sum_{i} [\omega_{in} + .85 \bar{\zeta}_{in} + \pi_{in}]
+ \sum_{i} [w_{i1n} + x_{in}]
+ \sum_{i} [(1 - \delta(k, 0))(b_{i0n} - w_{i0n} + d_{in} + .5\kappa_{i0n})\alpha_{i0kn}\tau_{kn}] - \bar{\sigma}_{n}, \quad (3.21)$$

and re-arrange to move variables to the LHS as follows

$$\sum_{t} \bar{\Delta}_{tn} f_{tn} - \sum_{i} [w_{i1n} + x_{in}]$$

$$- \sum_{ik} [(1 - \delta(k, 0))(b_{i0n} - w_{i0n} + d_{in})\alpha_{i0kn}\tau_{kn}] = \sum_{i} [\omega_{in} + .85\bar{\zeta}_{in} + \pi_{in}] - \bar{\sigma}_{n}$$

$$+ .5 \sum_{ik} [(1 - \delta(k, 0))\alpha_{i0kn}\tau_{kn}\kappa_{i0n}]. (3.22)$$

4. Mapping of decision variables

At this point, one can use one of the many algebraic modeling languages such as AMPL, GAMS, Mosek, AIMMS, and Gurobi, and code the equations above using that language, but most of these applications are proprietary and require a license and additional software installation. These languages allow the problem to be stated at a high level and steps to cast the problem in a form suitable for solution are performed automatically. There are also object-oriented language extensions, such as Python's Pyomo and PuLP that ease the process of solving these problems. For completeness, however, we present here a simple index mapping approach that allows solving this problem using a generic linear programming solver.

To cast the problem in a form suitable for a linear programming solver, we will use a single block vector represented by the array y[q()] with index-mapping functions q(). While this process can be achieved using slicing and reshaping in some programming languages, we will present a generic approach suitable for most programming languages.

The detailed approach presented here also allows us to determine the size of the problem to solve. We proceed alphabetically for all variables, and continue to use the convention of having index 0 for representing the first element.

To bring all variables in a single block vector, we will simply use two generic index mapping functions defined as

$$q_*(C, \ell_1, \ell_2, \ell_3; N_1, N_2, N_3) := C + \ell_1 N_2 N_3 + \ell_2 N_3 + \ell_3,$$
 (4.1)

and

$$q_C(C, N_1, N_2, N_3) := C + N_1 N_2 N_3,$$

$$(4.2)$$

with the constraint that $0 < \ell_i < N_i$.

Account balances (b) For storing the savings account balances appropriately, variable b_{ijn} needs to have one more entry $(N_n + 1)$ to store the end-of-life estate value. Therefore, we use

$$y[q_b(i,j,n)] = b_{ijn}, \tag{4.3}$$

where

$$q_b(i,j,n) = q_*(C_b,i,j,n;N_i,N_j,N_n+1)$$
(4.4)

and where n exceptionally runs from 0 to N_n inclusively, and therefore q_b runs from $C_b = 0$ to $C_d - 1$, where

$$C_d = q_C(C_b, N_i, N_i, N_n + 1) = [N_i N_i (N_n + 1)].$$

Surplus deposits (d) For the surplus deposits in the taxable savings accounts d_{in} we will use

$$y[q_d(i,n)] = d_{in}, (4.5)$$

where

$$q_d(i,n) = q_*(C_d, i, n, 0; N_i, N_n)$$
(4.6)

with q_d running from C_d to $C_f - 1$, where

$$C_f = q_C(C_d, N_i, N_n, 1) = [N_i(N_i(N_n + 1) + N_n)].$$

Tax bracket fractions (f) For tax bracket fractions f_{tn} we will use

$$y[q_f(t,n)] = f_{tn}, (4.7)$$

where

$$q_f(t,n) = q_*(C_f, t, n, 0; N_t, N_n, 1)$$
(4.8)

with q_f running from C_f to $C_q - 1$, where

$$C_q = q_C(C_f, N_t, N_n, 1) = [N_i(N_j(N_n + 1) + N_n) + N_t N_n].$$

Net spending (g) For net spending g_n we will use

$$y[q_g(n)] = g_n, (4.9)$$

where

$$q_q(n) = q_*(C_q, n, 0, 0; N_n, 1, 1) = C_q + n, \tag{4.10}$$

with q_g running from C_g to $C_w - 1$, where

$$C_w = q_C(C_q, N_n, 1, 1) = [N_i(N_j(N_n + 1) + N_n) + (N_t + 1)N_n].$$

Withdrawals (w) For withdrawals w_{ijn} we will use

$$y[q_w(i,j,k,n)] = w_{ijn},$$
 (4.11)

where

$$q_w(i, j, n) = q_*(C_w, i, j, n; N_i, N_j, N_n)$$
(4.12)

with q_w running from C_w to $C_x - 1$, where

$$C_x = q_C(C_w, N_i, N_j, N_n) = [N_i(N_j(2N_n + 1) + (N_t + 1)N_n)].$$

Roth conversions (x) Finally, for Roth conversions x_{in} we will use

$$y[q_x(i,n)] = x_{in},$$
 (4.13)

where

$$q_x(i,n) = q_*(C_x, i, n, 0; N_i, N_n, 1)$$
(4.14)

with q_x running from C_x to $C_* - 1$, where

$$C_* = q_C(C_x, N_i, N_n, 1) = [N_i(N_i(2N_n + 1) + (N_t + N_i + 1)N_n].$$

Adding binary variables z_{in} adds N_iN_n more decision variables. With $N_i=2, N_j=3, N_k=4, N_t=7$ we have $24N_n+6$ variables. For a 30-year plan, this results in 726 variables. If the time resolution is increased to months, that would result in 7,992 variables which is still solvable by today's standards.

4.1 Reverse mapping of indices

The inverse functions for the index-mapping functions will be derived for the most complex case encountered in this paper. If we have

$$z = q_*(C, i, j, k, n; N_i, N_j, N_k, N_n) := C + iN_j N_k N_n + jN_k N_n + kN_n + n,$$
(4.15)

then $(i, j, k, n) = q_*^{-1}(z; N_i, N_j, N_k, N_n, C)$ is obtained from

$$\begin{array}{lll} n & = & \operatorname{mod}(\operatorname{mod}(\operatorname{mod}(z-C,N_{j}N_{k}N_{n}),N_{k}N_{n}),N_{n}), \\ k & = & \operatorname{mod}(\operatorname{mod}(z-C-n,N_{j}N_{k}N_{n}),N_{k}N_{n})/N_{n}, \\ j & = & \operatorname{mod}(z-C-n-kN_{n},N_{j}N_{k}N_{n})/(N_{k}N_{n}), \\ i & = & (z-C-n-kN_{n}-jN_{k}N_{n})/(N_{j}N_{k}N_{n}). \end{array} \tag{4.16}$$

While this holds for all cases presented in the previous section, this can be easily simplified for cases having fewer active indices. However, some modern languages can accomplish this mapping rather easily by providing reshape() functions.

5. Building constraint matrices

Let's first define generic index-mapping functions I and J as

$$I_{l}(n) = C_{l} + n,$$

$$I_{l}(i, n; N_{n}) = C_{l} + iN_{n} + n,$$

$$I_{l}(i, j, n; N_{j}, N_{n}) = C_{l} + iN_{j}N_{n} + jN_{n} + n,$$

$$\dots = \dots$$
(5.1)

and so on, which would cumulatively increase row count C_l at each new instance l, similar to how we proceeded in the previous section. This allows us to build rectangular matrices by iteratively adding rows. These constraint matrices have C_* columns but will have less rows, forming an underdetermined system to be optimized using linear programming.

5.1 Inequality constraints

Required minimum distributions (RMDs) We rewrite the inequality constraint on required minimum distributions Eq. (3.4) using matrix $A_u y \leq u$ starting with the following $N_i N_n$ rows,

$$A_{u}[I_{0}(i,n), q_{w}(i,1,n)] = -1$$

$$A_{u}[I_{0}(i,n), q_{b}(i,1,n)] = \rho_{in},$$

$$u[I_{0}(i,n)] = 0,$$

$$\forall i \in \{0, \dots, N_{i} - 1\},$$

$$\forall n \in \{0, \dots, N_{n} - 1\},$$

$$(5.2)$$

and all other elements in the same rows of A_u being 0. Notice that while b has $N_n + 1$ elements, the constraints for b go from 0 to $N_n - 1$ as there is no RMD required in the last year of the plan N_n . See Eq. (4.4).

Income tax brackets Similarly, we add N_tN_n more rows to matrix $A_uy \leq u$ to express the inequality constraint in Eq. (3.5) setting an upper limit on fractions $f_{tn} \leq 1$. Instead of using f, however, we will use $F_{tn} = f_{tn}\bar{\Delta}_{tn}$ of the same dimensions and therefore,

$$A_{u}[I_{1}(t,n), q_{F}(t,n)] = 1,$$

$$u[I_{1}(t,n)] = \bar{\Delta}_{tn},$$

$$\forall t \in \{0, \dots, N_{t} - 1\},$$

$$\forall n \in \{0, \dots, N_{n} - 1\},$$
(5.3)

and all other elements in the same rows of A_u being 0.

5.2 Equality constraints

Account balances For the equality constraint on account balances expressed in Eq. (3.11), we will define an equality constraint matrix $A_e y = v$ starting with $N_i N_j N_n$ rows as

$$A_{e}[J_{0}(i,j,n),q_{b}(i,j,n+1)] = 1,$$

$$A_{e}[J_{0}(i,j,n),q_{b}(i,j,n)] = -(1 + \mathcal{T}_{ijn}),$$

$$A_{e}[J_{0}(i,j,n),q_{x}(i,n)] = -(\delta(j,2) - \delta(j,1))(1 + \mathcal{T}_{ijn}),$$

$$A_{e}[J_{0}(i,j,n),q_{w}(i,j,n)] = (1 + \mathcal{T}_{ijn}),$$

$$A_{e}[J_{0}(i,j,n),q_{d}(i,n)] = -\delta(j,0)(1 + \mathcal{T}_{ijn}),$$

$$\forall i \in \{0,\ldots,N_{i}-1\},$$

$$\forall j \in \{0,\ldots,N_{j}-1\},$$

$$\forall n \in \{0,\ldots,N_{n}-1\},$$

where v is

$$v[J_0(i,j,n)] = \kappa_{ijn}(1 + \mathcal{T}_{ijn}/2).$$
 (5.5)

The initial account balances expressed in Eq. 3.13 are imposed through

$$A_{e}[J_{1}(i,j,k),q_{b}(i,j,0)] = 1,$$

$$v[J_{1}(i,j,k)] = \beta_{ijk},$$

$$\forall i \in \{0,\dots,N_{i}-1\},$$

$$\forall j \in \{0,\dots,N_{j}-1\},$$
(5.7)

leading to $N_i N_j$ additional rows to A_e .

Net spending For the equality constraint on net spending expressed in Eq. (3.18), we add N_n more rows to $A_e y = v$ as

$$A_{e}[J_{2}(n), q_{g}(n)] = 1,$$

$$A_{e}[J_{2}(n), q_{w}(i, j, n)] = -1 + \delta(j, 0)\psi\alpha_{i00n}(\max(0, \tau_{0n-1}) - \mu),$$

$$A_{e}[J_{2}(n), q_{d}(i, n)] = 1 + \psi\mu\alpha_{i00n},$$

$$A_{e}[J_{2}(n), q_{F}(t, n)] = \theta_{tn},$$

$$A_{e}[J_{2}(n), q_{b}(i, 0, n)] = \psi\mu\alpha_{i00n},$$

$$\forall t \in \{0, \dots, N_{t} - 1\},$$

$$\forall i \in \{0, \dots, N_{j} - 1\},$$

$$\forall n \in \{0, \dots, N_{n} - 1\},$$

where v is

$$v[J_2(n)] = \sum_{i} [\omega_{in} + \bar{\zeta}_{in} + \pi_{in} + \Lambda_{in}^{\pm} - .5\psi\mu\alpha_{i00n}\kappa_{i0n}] - M_n^s.$$
 (5.8)

The condition of having a predictable net spending expressed as an equality in Eq. (3.20) adds $N_n - 1$ more rows to $A_e y = v$ as

$$A_{e}[J_{3}(n), q_{g}(0)] = -\bar{\xi}_{n},$$

$$A_{e}[J_{3}(n), q_{g}(n)] = \xi_{0},$$

$$v[J_{3}(n)] = 0,$$

$$\forall n \in \{1, \dots, N_{n}\}.$$
(5.9)

Taxable ordinary income Finally, for the equality constraint in Eq. (3.22) establishing taxable ordinary income, we add N_n rows to $A_e y = v$ as follows

$$A_{e}[J_{4}(n), q_{F}(t, n)] = 1,$$

$$A_{e}[J_{4}(n), q_{w}(i, 1, n)] = -1,$$

$$A_{e}[J_{4}(n), q_{b}(i, 0, n)] = (1 - \delta(k, 0))\alpha_{i0kn}\tau_{kn},$$

$$A_{e}[J_{4}(n), q_{w}(i, 0, n)] = -(1 - \delta(k, 0))\alpha_{i0kn}\tau_{kn},$$

$$A_{e}[J_{4}(n), q_{d}(i, n)] = (1 - \delta(k, 0))\alpha_{i0kn}\tau_{kn},$$

$$A_{e}[J_{4}(n), q_{x}(i, n)] = -1,$$

$$\forall t \in \{0, \dots, N_{t} - 1\},$$

$$\forall k \in \{0, \dots, N_{k} - 1\},$$

$$\forall n \in \{0, \dots, N_{n} - 1\},$$

with

$$v[J_4(n)] = \sum_{i} [\omega_{in} + .85\bar{\zeta}_{in} + \pi_{in}] + .5\sum_{ik} [(1 - \delta(k, 0))\alpha_{i0kn}\tau_{kn}\kappa_{i0n}] - \bar{\sigma}_n.$$
 (5.11)

5.3 Other considerations

Beneficiaries Tax-exempt and tax-deferred accounts have special tax rules that allow giving part or the entire value of tax-exempt accounts to a spouse who can then consider it as his/her own. Let ϕ_j be the fraction of the account j that a spouse i_d wishes to leave to his/her surviving spouse i_s in the year $n_d < N_n - 1$ following the year of passing. To account for that event in year n_d , Eq. (3.12) needs to be rewritten as

$$b_{ij(n+1)} = (1 - \delta(n, n_d - 1)\delta(i, i_d))$$

$$\times \left\{ [b_{ijn} - w_{ijn} + \delta(j, 0)d_{ij}] (1 + \mathcal{T}_{ijn}) + [(\delta(j, 2) - \delta(j, 1))x_{in} + \kappa_{ijn}] (1 + \mathcal{T}_{ijn}/2) \right\}$$

$$+ (\phi_j \delta(n, n_d - 1)\delta(i, i_s))$$

$$\times \left\{ [b_{i_djn} - w_{i_djn} + \delta(j, 0)d_{i_dn}] (1 + \mathcal{T}_{i_djn}) + [(\delta(j, 2) - \delta(j, 1))x_{i_dn} + \kappa_{i_djkn}] (1 + \mathcal{T}_{i_djn}/2) \right\}.$$
(5.12)

The first multiplier () on the right-hand side will always be one except for i_d in year n_d-1 when it will be zero. This will result in emptying all accounts for i_d for years n_d and beyond. The second special multiplier () before the second set of brackets $\{\}$ will always be zero except for the surviving spouse i_s in year n_d-1 , who will then inherit a fraction ϕ_j of account j that was scheduled to go into i_d 's j account at the beginning of year n_d .

Rewriting the last equation as a constraint results in

$$b_{ij(n+1)} - (1 - \delta(n, n_d - 1)\delta(i, i_d))$$

$$\times \left\{ [b_{ijn} - w_{ijn} + \delta(j, 0)d_{in}] (1 + \mathcal{T}_{ijn}) + [(\delta(j, 2) - \delta(j, 1))x_{ikn}] (1 + \mathcal{T}_{ijn}/2) \right\}$$

$$- (\phi_j \delta(n, n_d - 1)\delta(i, i_s))$$

$$\times \left\{ [b_{i_djn}w_{ijn} + \delta(j, 0)d_{in}] (1 + \mathcal{T}_{i_djn}) + + [(\delta(j, 2) - \delta(j, 1))x_{i_dkn}] (1 + \mathcal{T}_{i_djn}/2) \right\}$$

$$= [(1 - \delta(n, n_d - 1)\delta(i, i_d))\kappa_{ijn} (1 + \mathcal{T}_{ijn}/2)$$

$$+ (\phi_j \delta(n, n_d - 1)\delta(i, i_s))\kappa_{i_djn}] (1 + \mathcal{T}_{i_djn}/2).$$

$$(5.13)$$

We are now ready to replace Eq. (5.4) for $A_e y = v$ by

$$\begin{split} A_{e}[J_{0}(i,j,n),q_{b}(i,j,n+1)] &= 1, \\ A_{e}[J_{0}(i,j,n),q_{b}(i,j,n)] &= -(1-\delta(n,n_{d}-1)\delta(i,i_{d}))(1+\mathcal{T}ijn), \\ A_{e}[J_{0}(i,j,n),q_{w}(i,j,n)] &= (1-\delta(n,n_{d}-1)\delta(i,i_{d}))(1+\mathcal{T}_{ijn}), \\ A_{e}[J_{0}(i,j,n),q_{d}(i,j,n)] &= -(1-\delta(n,n_{d}-1)\delta(i,i_{d}))\delta(j,0)(1+\mathcal{T}_{ijn}), \\ A_{e}[J_{0}(i,j,n),q_{x}(i,n)] &= -(1-\delta(n,n_{d}-1)\delta(i,i_{d}))(\delta(j,2)-\delta(j,1)), (1+\mathcal{T}_{ijn}/2), \\ \text{when } N_{i} = 2 \text{ and } i = i_{s} \\ A_{e}[J_{0}(i,j,n),q_{b}(i_{d},j,n)] &= -(\phi_{j}\delta(n,n_{d}-1)\delta(i,i_{s}))(1+\mathcal{T}_{ijn}), \\ A_{e}[J_{0}(i,j,n),q_{w}(i_{d},j,n)] &= (\phi_{j}\delta(n,n_{d}-1)\delta(i,i_{s}))\delta(j,0)(1+\mathcal{T}_{ijn}), \\ A_{e}[J_{0}(i,j,n),q_{d}(i_{d},n)] &= -(\phi_{j}\delta(n,n_{d}-1)\delta(i,i_{s}))\delta(j,0)(1+\mathcal{T}_{ijn}), \\ A_{e}[J_{0}(i,j,n),q_{x}(i_{d},n)] &= -(\phi_{j}\delta(n,n_{d}-1)\delta(i,i_{s}))(\delta(j,2)-\delta(j,1))(1+\mathcal{T}_{ijn}/2), \\ \forall i \in \{0,\ldots,N_{i}-1\}, \\ \forall j \in \{0,\ldots,N_{i}-1\}, \\ \forall n \in \{0,\ldots,N_{i}-1\}, \end{split}$$

where v is

$$v[J_0(i,j,n)] = (1 - \delta(n, n_d - 1)\delta(i, i_d))\kappa_{ijn}(1 + \mathcal{T}_{ijn}/2) + (\phi_j \delta(n, n_d - 1)\delta(i, i_s))\kappa_{idjn}(1 + \mathcal{T}_{idjn}/2).$$
 (5.14)

While the last two equations may look cumbersome, their net effect is only to include a few more terms when $n = n_d - 1$.

Assets allocation ratios When asset allocation ratios α are imposed, they should also be applied to how contributions amounts κ_{ijn} are invested, such that

$$\kappa_{ijkn} = \alpha_{ijkn}\kappa_{ijn}. (5.15)$$

For other allocation schemes, just substitute $\alpha_{ijkn} = \alpha_{ikn}$ or α_{kn} depending on the scheme selected. Assets allocation have been handled easily by assuming that the accounts are always rebalanced and only using a single multiplier \mathcal{T} , defined as

$$\mathcal{T}_{ijn} = \sum_{k} \alpha_{ijkn} \tau_{kn}, \tag{5.16}$$

to compute to return on the total balance of each savings account.

Spousal deposits and with drawals In order to keep the problem linear, a simple constraint that can be imposed on surplus deposits to be made in taxable savings accounts is to specify a spousal ratio η such as

$$d_{0n} = \eta d_{1n}. (5.17)$$

A similar spousal ratio can be imposed on withdrawals from tax-deferred accounts

$$w_{01n} = \eta w_{11n}, \tag{5.18}$$

but this can cause drawing from an account empty while the other spousal account is not.

6. Objective functions

The objective function is a simple scalar defined as $c \cdot y$ that will be minimized.

Maximum net spending There are a few ways by which a retirement plan can be optimized. For maximizing the net spending under the constraint of a desired bequest, we introduce the following relation

$$E_n = \sum_{ij} (1 - \nu \delta(j, 1)) b_{ijn}, \tag{6.1}$$

which is the value of the estate in nominal dollars at year n, taking into consideration the heir's marginal income tax rate on the (j = 1) tax-deferred account. In this situation, the concept of surplus deposit remains valid to handle surplus income.

For a desired bequest ϵ_{N_n} , expressed in today's dollars, the final amount in year N_n will need to be

$$E_{N_n} = \bar{\epsilon}_{N_n} = \epsilon_{N_n} \gamma_{N_n}. \tag{6.2}$$

Fixing a bequest value amounts to adding the following constraint

$$\sum_{ij} b_{ijN_n} (1 - \nu \delta(j, 1)) = \epsilon_{N_n} \gamma_{N_n}, \tag{6.3}$$

which would add one more row to $A_e y = v$ as

$$A_{e}[I(0), q_{b}(i, j, N_{n})] = (1 - \nu \delta(j, 1))$$

$$v[I(0)] = \epsilon_{N_{n}} \gamma_{N_{n}}$$

$$\forall i \in \{0, \dots, N_{i} - 1\},$$

$$\forall j \in \{0, \dots, N_{j} - 1\},$$

$$(6.5)$$

where I(0) is used only to provide the proper row offset C_l . See Eq. (5.1).

For maximizing the net spending under the constraint of a fixed bequest, one has simply to minimize the inner product $c \cdot y$, where c is

$$c[q_a(0)] = -1, (6.6)$$

and 0 otherwise. See Eq. 3.20.

Maximum bequest If, on the other hand, one would like to maximize the bequest under the constraint of a desired net spending g_o , one would add the following row to $A_e y = v$

$$A_e[I(0), q_g(0)] = 1,$$

 $v[I(0)] = g_o.$ (6.7)

The objective function would then be derived from Eq. (6.1) as minimizing the inner product $c \cdot y$, where c is

$$c[q_{b}(i, j, N_{n})] = -(1 - \nu \delta(j, 1)),$$

$$\forall i \in \{0, \dots, N_{i} - 1\},$$

$$\forall j \in \{0, \dots, N_{j} - 1\},$$

$$(6.8)$$

and 0 otherwise.