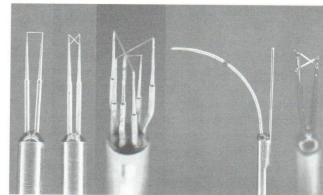


Introduction to Hotwire Anemometry

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Introduction

- Basic principle – amount of cooling experienced by a heated wire can be related to the local flow velocity



Hot-wire and hot-film probes. (Photographs provided by and used with permission of TSI, Inc.)

- A small diameter metal wire sensor (made of tungsten, platinum or platinum alloy) is heated over flow temperature using an electric current
- Typically, diameter of wire = $0.5\text{--}5\text{ }\mu\text{m}$, length = $0.15\text{--}1.5\text{ mm}$, resistance $\sim 4\text{ ohms}$
- Similar to hot-wire, we can also have hot-film – consists of a thin metal film deposited over a quartz core
- Hot-wire mostly used with gases and hot-film with flow of liquids

Principle of Hot-wire Anemometry

Resistance of a wire depends linearly on its temperature.

$$R_s = R_f[1 + \alpha(T_s - T_f)] \quad \dots \quad (1)$$

where R_s is electrical resistance at temperature T_s , R_f is resistance at T_f and α is temperature-resistance coefficient ($= 0.004 \text{ K}^{-1}$ for tungsten and platinum)

From energy balance we have,

$$dQ/dt = P - F \quad \dots \quad (2)$$

where Q is internal energy of sensor, P is electrical input power to sensor, and F is total rate of heat transferred from the sensor

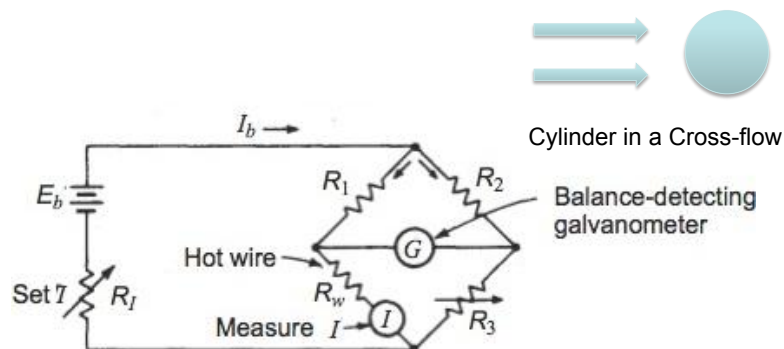
Now, $F = q_c + q_p + q_r + q_s$

where q_c is heat transfer rate due to convection from sensor to flow

q_p is heat transfer due to conduction to supporting prongs

q_r is heat transfer due to radiation from sensor to surrounding

q_s is heat transfer to quartz substrate (relevant only in hot-film) 3



$q_{\text{convection}} = h$ (heat transfer coefficient) * A (surface area) * ΔT (temperature difference between surface and fluid)

Heat transfer coefficient = f (geometry of surface, flow velocity, fluid properties)

For a fixed geometry: Heat transfer coefficient = h (flow velocity, fluid properties)

$hd/k = g((\rho u d / \mu), (\mu Cp / k))$

Nu (Nusselt number) = $g(Re, Pr)$

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Principle of Hot-wire Anemometry (contd.)

Analyzing the factors contributing to heat loss, we get –

- Heat loss to the prong supports can be neglected if the aspect ratio (l/d) of the wire is large (> 200)
- Radiation heat transfer can usually be neglected with respect to convective heat transfer
- Note, heat transfer by convection be either be forced or free – their relative magnitudes will depend on the local flow velocity
- We want forced convection to dominate – for this $Re_d > Gr^{1/3}$ where Re_d is Reynolds no. based on wire diameter and Gr is Grashof number
- For a circular cylinder in cross-flow, the average Nusselt number (Nu_d) is given by (Incropera and DeWitt, p 411) provided $Re_d Pr > 0.2$

$$Nu_d = 0.3 + \frac{0.62 Re_d^{1/2} Pr^{1/3}}{[1 + (0.4/Pr)^{2/3}]^{1/4}} \left[1 + \left(\frac{Re_d}{282000} \right)^{5/8} \right]^{4/5} \quad \text{where } Nu_d = \frac{hd}{k}$$

$$Re_d = \frac{\rho U d}{\mu}$$

- For air (with Pr close to unity) and Re_d small (< 120), we get

$$h = C_0 + C_1 \sqrt{U} \quad \dots \quad (3)$$
 where h is heat transfer coefficient, C_0 , C_1 are constants, U is local flow velocity, and Pr is Prandtl number

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Principle of Hot-wire Anemometry (contd.)

- Electrical power input to sensor

$$P = E^2/R_s = I^2 R_s$$

where E is voltage across wire

- Note that R_s can be related to T_s (using Eq (1))

- Therefore, Eq (2) can be written as

$$m C_p dT_s/dt = P(I, T_s) - F(U, T_s) \quad \dots \quad (4)$$

where m is mass of wire, C_p is specific heat of wire material, T_s is wire (surface) temperature, U is component of velocity vector normal to the wire, and I is current supplied to the wire

- Want either I or T_s to be a constant, then U can be related to the other variable – called constant current and constant temperature modes of operation

- Constant temperature mode is preferred so that the thermal inertia ($m C_p dT_s/dt$ term) does not come into picture

Zero order instrument: No derivative with respect to time is involved

First-order instrument: First order derivative

Second-order instrument: Second order derivative

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Principle of Hot-wire Anemometry (*contd.*)

- For constant temperature mode, Eq. (4) reduces to
$$E^2/R_s = hS(T_s - T_o) \quad \dots \quad (5)$$
where S is surface area of wire and T_o is flow temperature

- Substituting Eq. (3) in Eq. (5), we get
$$E^2/R_s = (C_0 + C_1 \sqrt{U}) S (T_s - T_o)$$

which is usually rewritten as

$$E^2 = A + B U^{1/n} \quad \dots \quad (6)$$

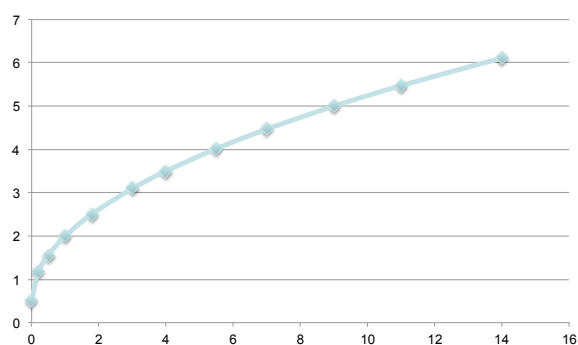
A , B and $1/n$ are calibration constants.

$1/n$ is expected to be close to 0.5 – comes in the range of 0.4-0.5

Eq (6) is referred to as the Kings law

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Typical calibration curve



Voltage (V) versus velocity (m/s)

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