

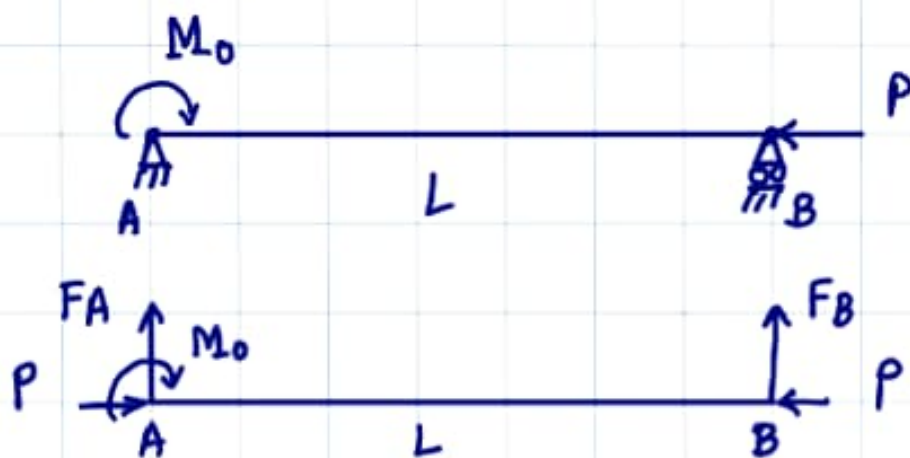
ME 202
LECTURE 33
TUE 05 APR 2022

Approaches to buckling,

- ☑ Non-trivial deformations of a perfect (perfectly symmetrical) system
Eigenvalue problem. Equilibrium.
- ☑ Uncontrollably large (theoretically ∞) deformations of an imperfect (asymmetric) system. Equilibrium.
- ☐ Stability switching in potential energy

Energy approach useful in obtaining approximate solutions to buckling problems.

Imperfect Column



$$F_A + F_B = 0, \quad M_0 = F_B L, \quad F_B = \frac{M_0}{L}$$

$F_A = -\frac{M_0}{L}$
 $V(z) = \frac{M_0}{L}$
 $F_A = -\frac{M_0}{L}$
 $\Sigma M_A = 0$

$$M(z) + \frac{M_0}{L} z + P u(z) - M_0 = 0$$

$$M(z) = EI u''(z)$$

$$EI u''(z) + P u(z) = M_0 \left(1 - \frac{z}{L}\right)$$

$$u'' + \underbrace{\frac{P}{EI}}_{\lambda^2} u = \frac{M_0}{EI} \left(1 - \frac{z}{L}\right)$$

$$u = A \cos \lambda z + B \sin \lambda z + \frac{M_0}{P} \left(1 - \frac{z}{L}\right)$$

$$BC \quad u(0) = 0, \quad \frac{M_0}{P} + A = 0, \quad A = -\frac{M_0}{P}$$

$$u(L) = 0, \quad -\frac{M_0}{P} \cos \lambda L + B \sin \lambda L = 0$$

$$B = \frac{M_0}{P} \frac{\cos \lambda L}{\sin \lambda L}$$

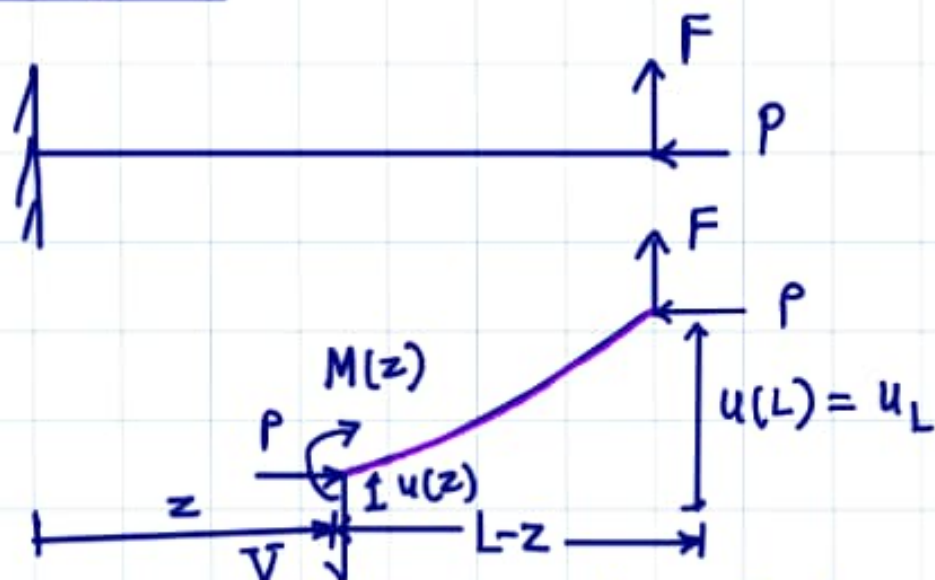
$$u(z) = \frac{M_0}{P} \left[1 - \frac{z}{L} - \cos \lambda z + \frac{\cos \lambda L}{\sin \lambda L} \sin \lambda z \right]$$

As $\lambda L \rightarrow \pi$, $u \rightarrow \infty$

$$\sqrt{\frac{P}{EI}} L \rightarrow \pi, \quad \text{As } P \rightarrow \frac{\pi^2 EI}{L^2}$$

$$\lambda L \rightarrow n\pi, \quad P \rightarrow \frac{n^2 \pi^2 EI}{L^2}$$

Example 2



$$M(z) = F(L-z) + P(u_L - u(z)) = EI u''$$

$$u'' + \frac{P}{EI} u = P u_L + FL - Fz$$

$$u = A \cos \lambda z + B \sin \lambda z + u_L + \frac{FL}{P} - \frac{Fz}{P}$$

$$\lambda^2 = \frac{P}{EI}$$

Cantilever BCs $u(0) = 0, u'(0) = 0$
 $u(L) = u_L$

$$u_L + \frac{FL}{P} + A = 0$$

$$-\frac{F}{P} + B\lambda = 0$$

$$u_L + A \cos \lambda L + B \sin \lambda L = u_L$$

$$A = -\frac{F}{P\lambda} \tan \lambda L, \quad B = \frac{F}{P\lambda}$$

$$u_L = \frac{F}{P\lambda} \tan \lambda L - \frac{FL}{P}$$

$$\text{As } P \rightarrow 0, \quad u_L \rightarrow \frac{FL^3}{3EI} \quad ?$$

$$\tan \theta = \theta + \frac{\theta^3}{3} + \frac{2}{15} \theta^5 + \dots \quad |\theta| < \pi/2$$

$$u_L = \frac{F}{P\lambda} \left(\cancel{\lambda L} + \frac{(\cancel{\lambda L})^3}{3} \right) - \frac{\cancel{FL}}{\cancel{P}}$$

$$= \frac{FL^3}{3EI} \quad \begin{matrix} \lambda L \rightarrow 0 \\ P \rightarrow 0 \end{matrix}$$

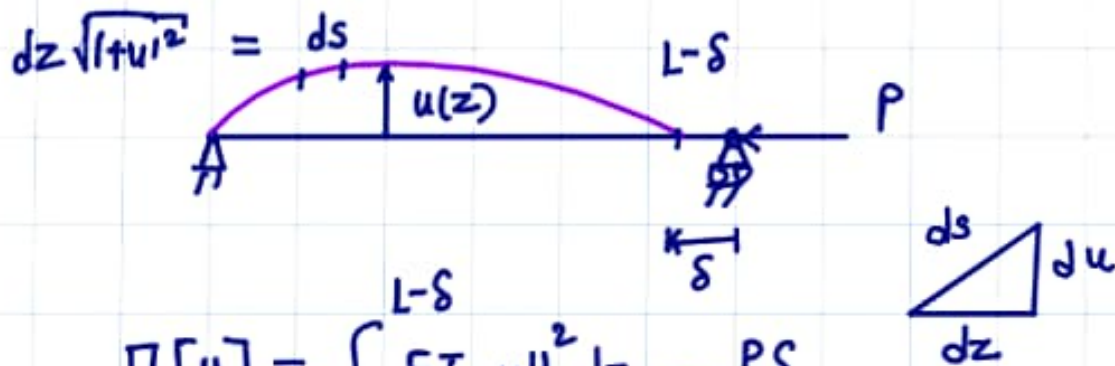
$$u(z) = \frac{F}{P} \tan \lambda L (1 - \cos \lambda z) - \frac{F}{P\lambda} (\lambda z - \sin \lambda z)$$

As $\lambda L \rightarrow \frac{\pi}{2}$, as $L \sqrt{\frac{P}{EI}} \rightarrow \frac{\pi}{2}$

$$P \rightarrow \frac{\pi^2 EI}{4L^2} \quad \text{for cantilever}$$

$$\underbrace{4L^2}_{P^*, P_{cr}}$$

Potential Energy Method



$$\Pi[u] = \int_0^{L-\delta} \frac{EI}{2} u''^2 dz - P\delta$$

Assume incompressibility N.A.

$$L = \int_0^{L-\delta} \sqrt{1+u'^2} dz, \quad |u'| \ll 1$$

$$\approx \int_0^{L-\delta} \left(1 + \frac{1}{2}u'^2\right) dz$$

$$L = \int_0^{L-\delta} \left(1 + \frac{1}{2}u'^2\right) dz = L - \delta + \int_0^{L-\delta} \frac{1}{2}u'^2 dz$$

$$\delta = \int_0^{L-\delta} \frac{1}{2}u'^2 dz, \quad \delta \ll L$$

$$\delta = \int_0^L \frac{1}{2} u'^2 dz$$

$$\Pi = \int_0^L \left(\frac{EI}{2} u''^2 - \frac{P}{2} u'^2 \right) dz$$

Approx solutions.

Pinned-pinned $u(0)=0, u(L)=0$

$$u = Az(L-z) \quad \text{approx.}$$

$$u' = AL - 2Az$$

$$u'' = -2A$$

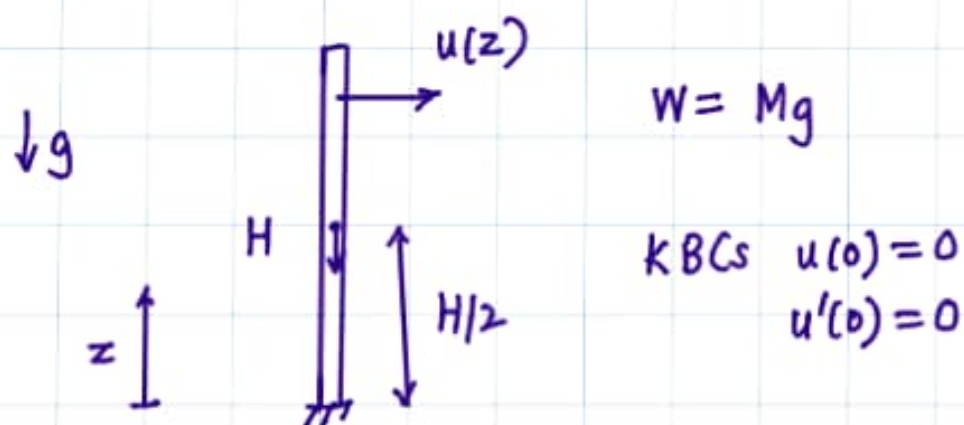
$$\Pi = 2EI A^2 L - \frac{P}{6} A^2 L^3$$

$$\text{Equilibrium } \frac{\partial \Pi}{\partial A} = 0, \quad \frac{2AL^3}{6} \left(\frac{12EI}{L^2} - P \right) = 0$$

$$\text{for nontrivial } A, \quad P = \frac{12EI}{L^2} \quad \text{approx. buckling load}$$

$$P_{\text{exact}} = \frac{\pi^2 EI}{L^2}, \quad \pi^2 \approx 9.8696 \dots$$

Max Height of a Tall Column/Tower



$$\text{Quick } \Pi = \int_0^H \frac{EI}{2} u''^2 dz - \int_0^{H/2} \frac{Mg}{2} u'^2 dz$$

$$\text{Assume } u = A_0 + A_1 z + A_2 z^2$$

Correct Way

$$\int_0^H \frac{EI}{2} u''^2 dz - \int_0^H \frac{P}{2} u'^2 dz$$
$$P = mg(H-z)$$

$$m = \frac{\text{Mass}}{\text{height}}$$

$$= \rho A$$