

ME 311: Microprocessors and Automatic Control

FFs → Registers: Memory blocks, tri-state gate, addressing memory



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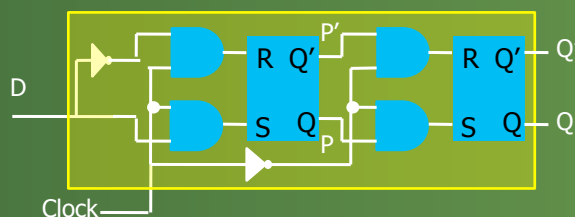
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Recall last class

Recap

- D-negative edge-triggered flip-flop
- Many other variants of flip-flop are available. Ex JK flip-flop
- Use of FF s for solving sequential logic problems





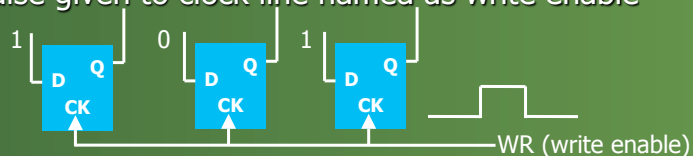
Building Memory

- Suppose we need to now construct memory using our D flip flops, how do we go about? What all we need.
- Lets start with putting 1 flip flop for storing one bit. Lets say for simplicity our one 'cell' or 'register' consist of 3 bit number
- Thus 3 flip flops for each cell would be needed and can be represented as the following



Building Memory

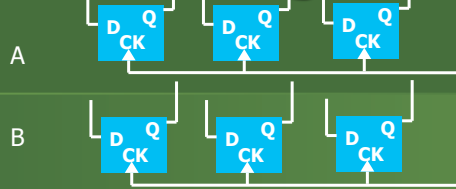
- Notice the same clock/enable signal
- Ok fine we have basic blocks in place but there are following questions?
- Q: How do we save the number say 101?
Have it ready on D lines as shown below and have signal pulse given to clock line named as write enable



- Q: Once saved how do we retrieve it back?
It will be always available on output Q lines as long as WR is low!
- Q: Will the number be lost if power is turned off? YES



Building Memory



Handling multiple such cells or registers:

- Q: How do I connect input lines and output lines so as to have desired data transfer between registers?

Consider examples of two registers A and B shown above.

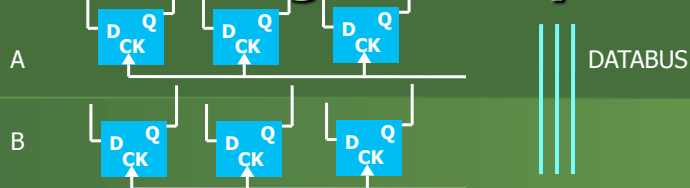
Suppose data from A is to be transferred to B: connect Q lines of FFs in A to D lines of FFs in B

- ➔ B gets permanently connected to A
- ➔ So if I want to perform operation of saving anything else to B without changing circuit, it is not possible
- ➔ So we would like to have flexibility

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Building Memory



Handling multiple such registers, we need a lot of flexibility:

- Q: how data can flow smoothly from one register to another in thousands of such registers at our will? Need a solution to scale up connections ➔ concept of using central 'databus' : hardware lines (equal to size of each register: 3 in this case) used for data transfer (As shown above). This will need additional features
 - We should be able to transfer stored data from any register to data bus without clash: the databus needs to be connected to respective Qs
 - We should be able store the data available on data bus to any register: the data bus needs to be connected to respective Ds
- ➔ We need additional circuit element called tri-state gate to control connection of either Q or D to the data bus. Discussed further...

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Fundamentals of

Tri-state gates

Z state is similar to
case of open switch

- Construct truth table:

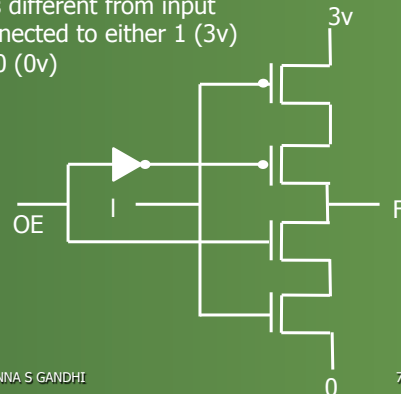
OE	I	F
0	1	Z
0	0	Z
1	0	1
1	1	0

Inverting Tristate gate
See that output F is inverted
Version of input I



OE: Output Enable

It is different from input
connected to either 1 (3v)
Or 0 (0v)



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CMOS implementation of a tri-state gate



Application example of

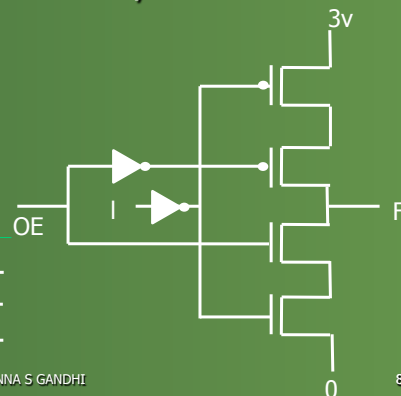
Tri-state gates

Non Inverting Tristate gate
See that output F is same
As input I

- High impedance state
denoted by Z



A	OE	F
X	0	Z
0	1	0
1	1	1



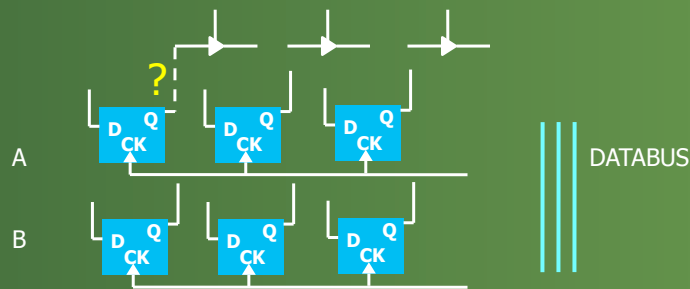
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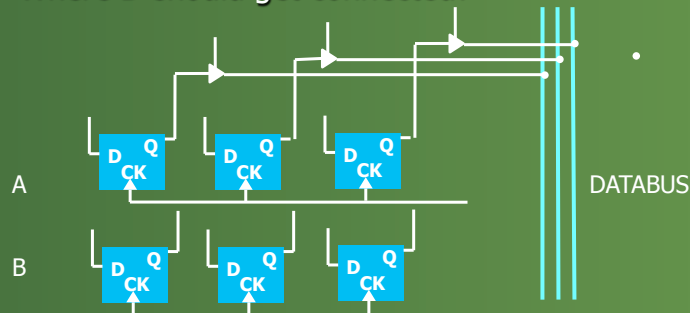
3-bit Register

- Q: Think how to use tri state gate such that there is no clash of data!!
- Where we should connect tri-state gate at D or Q?? How many tri-state gates we will need
- We will need 1 tri-state gate per flip-flop. Hence for 3 bit register we will need 3 of them
- Think What if we connect to D or Q?



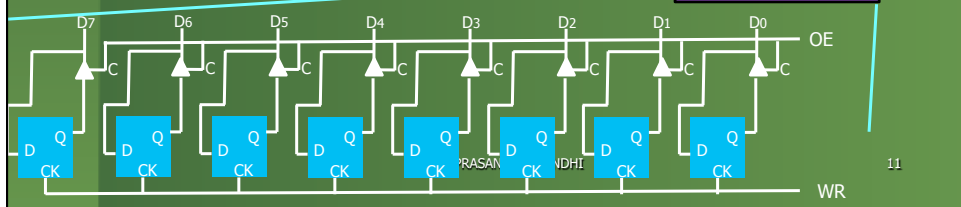
3-bit Register

- If we connect to D its of not much use since data on D can anyway be read only on clk edge
- If we connect to Q the data at Q will go on databus only on enabling the tristate gate
- So think if all registers are connected in similar way to databus can it work and how?
- Where D should get connected?

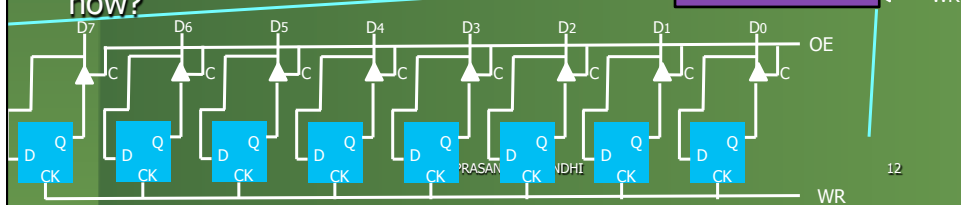




- D7-D0
- 8-Bit register
- OE
- WR



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- The diagram shows an 8-bit register (purple box) connected to a data bus (D7-D0, green line). The register has two control inputs: OE (Output Enable) and WR (Write Enable), both indicated by arrows pointing to the register.





8-bit Register

- Transfer of data from register A to B
 - OE of A should be high so that the data is available on data bus
 - During the same time (with OE_A high) WR of B should see a pulse (recall edge-triggered) at completion of which WR is again disabled
 - OE of A should go low
- Also when OE of one register is enabled OE of no Other register should be enabled.
- WR of several registers can be enabled at a time (storing same data in many registers)



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Addressing Memory Registers

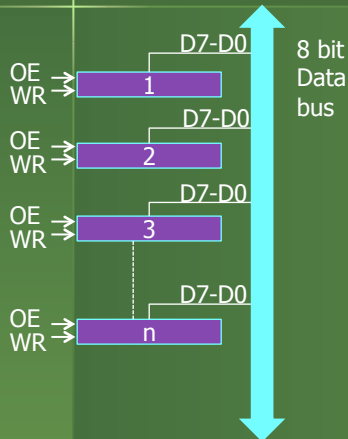
- Recall memory construction using registers
- Q: How do we select a particular designated register for read or write operations?
- Think of scaling memory!!!
- Its like you have many rooms available and need to have address to specify something to be fetched from some specific room or stored in another specific room.

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n 8-bit Registers



- A huge memory can be formed by putting together the elemental registers (this is RAM, why??)
- Q: How to address it? Meaning how to access data (read or write) in one of the locations?
- Ans: Assign address to each of the locations Then what?

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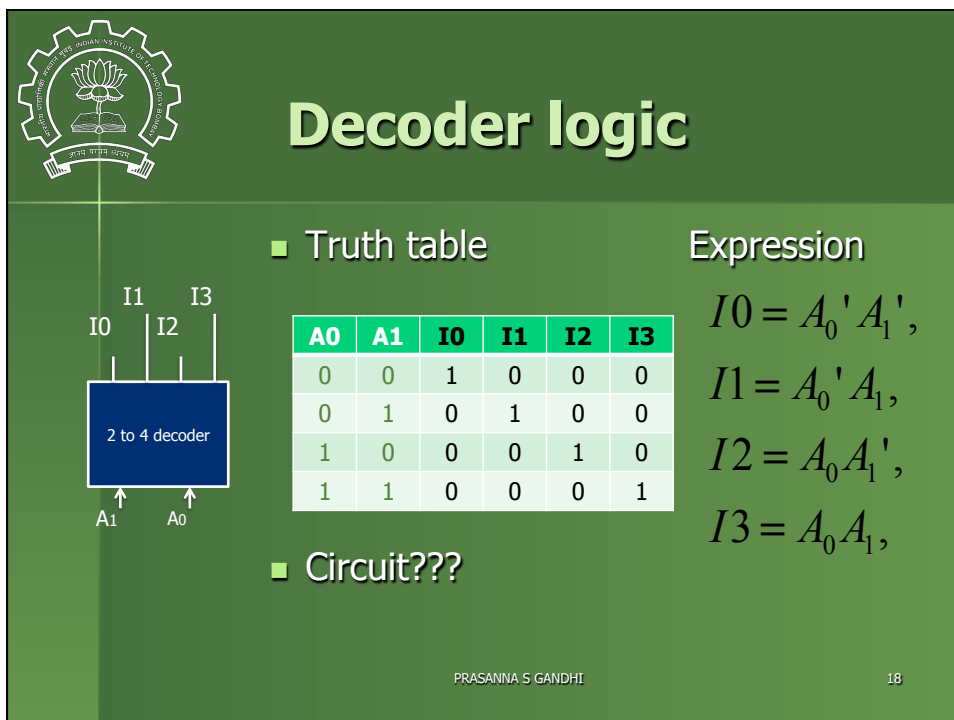
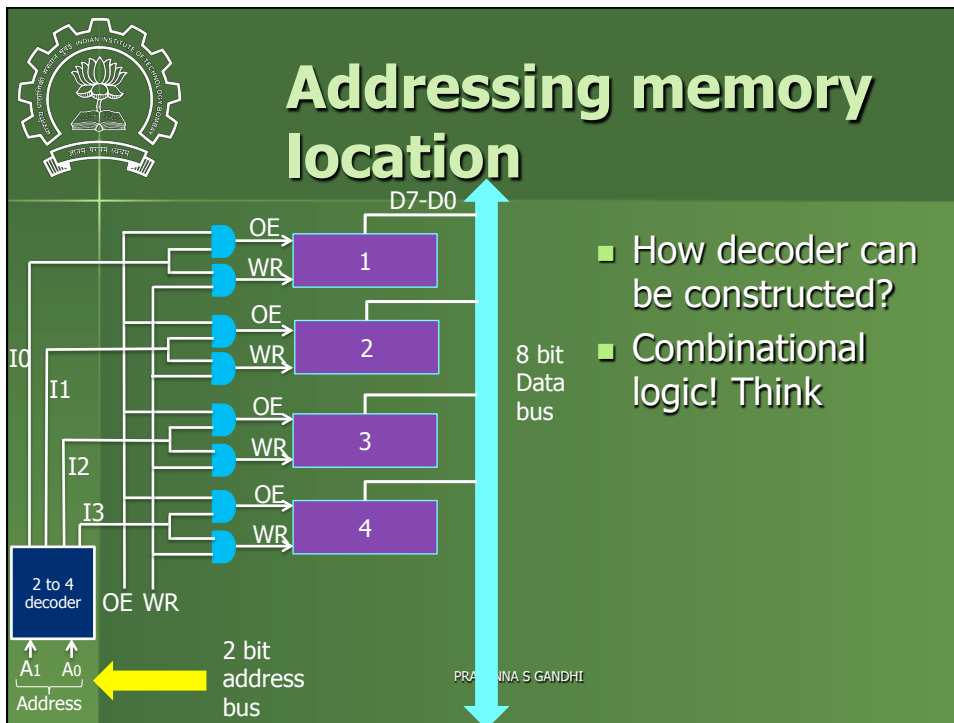
Addressing memory location



- Say we have 4 registers so the address can be from 00, 01, 10, and 11
- Now we need to select one of them at a time either for reading data (OE=1) onto data bus or writing data (WR=1) from data bus. How?
- Use decoder logic: given the address, the specified output line goes high
- Q: how do we connect outputs of decoder and respective OE and WR pins of registers??

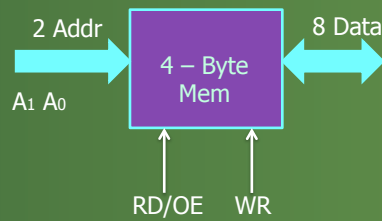
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■ Typical memory chip

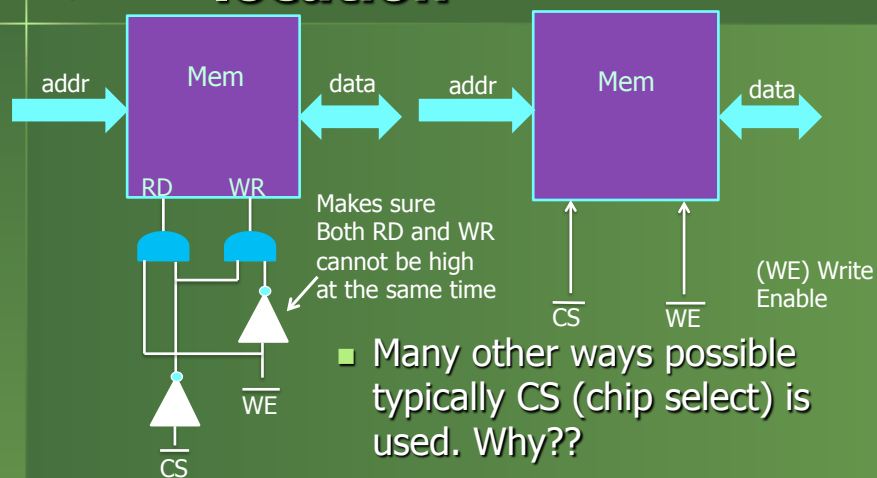


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Addressing memory location

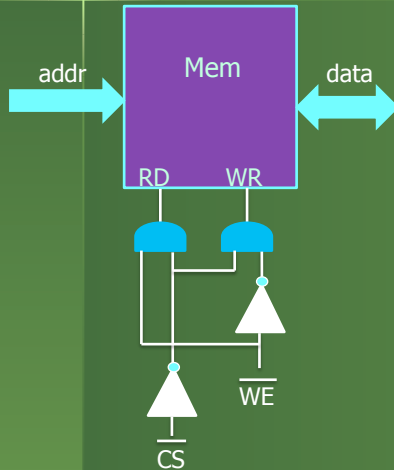


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Addressing memory location



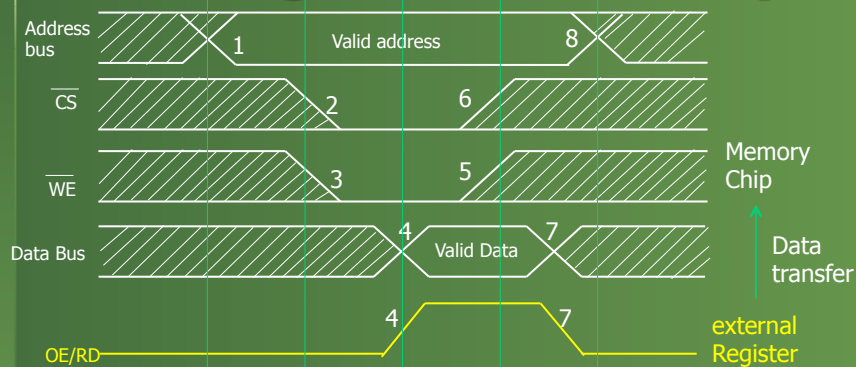
- Sequence of operations: say for writing data from external register to specified address location in memory Think!!
- 1. Place address on address bus
- 2. Bring CS' low
- 3. Bring WE' low
- 4. Place data from ext register on data bus (how?)
- 5. Bring WE' back to high
- 6. Reverse operations

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Timing diagram for write operation from ext register to memory



Notice the intervals 2-6 3-5 and 4-7 are same (about 1 clock cycle)
This is the reason any other sequence than what is given in previous Slide may not quite work. Do you see that!! Think about say why not To enable WE after the valid data gets on the data bus??

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Timing Methodologies

- Rules for interconnecting components and clocks
- Guarantee proper operation of system when strictly followed

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Timing Methodologies

- Basic rules for correct timing:
 - (1) Correct inputs, with respect to time, are provided to the flip-flops
 - (2) No flip-flop changes state more than once per clock cycle, the changes are synchronized with clock cycle

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THANK YOU

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