Linear Regression-3

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Multiple Linear Regression assumes

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_p X_p + \epsilon_1$$

The model can be expressed as

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x_1 + \hat{\beta}_2 x_2 + \dots + \hat{\beta}_p x_p$$

with its coefficients being derived by minimizing

RSS =
$$\sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$
 $\sum_{i=1}^{n} (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_{i1} - \hat{\beta}_2 x_{i2} - \dots - \hat{\beta}_p x_{ip})^2$

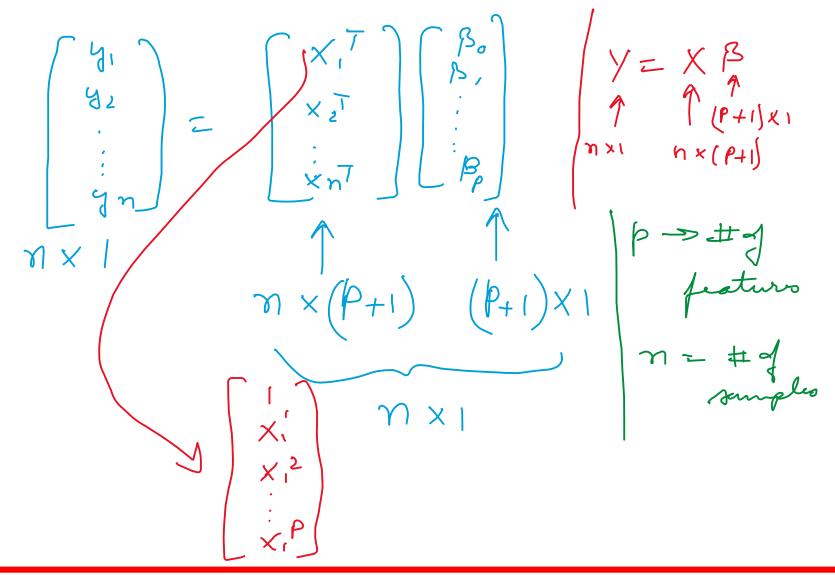
RSS

If X is a vector
$$\begin{bmatrix} x' \\ x^2 \end{bmatrix}$$

Data:
$$n$$
-deta pointo
$$\begin{pmatrix} \chi_1^T, y_1 \end{pmatrix}, \begin{pmatrix} \chi_2^T, y_2 \end{pmatrix} \dots \begin{pmatrix} \chi_n^T, y_n \end{pmatrix}$$

$$\begin{pmatrix} \chi_1^1 \\ \chi_2 \\ \chi_3^2 \\ \vdots \end{pmatrix}$$

Dota:
$$(x_1, y_1)$$
, ... (x_n, y_n)
 $x_1 = (x_1, x_2, \dots, x_n)$
 $\beta = (\beta_0, \beta_1, \beta_2, \dots, \beta_p)$
 $(\beta_1) \times 1$
 $(\beta_1) \times 1$
 $(\beta_1) \times 1$



RSS =
$$\|XB-Y\|^2$$
, B^* is the valle of B which min RSS : $(M>P+1)$

RSS (B)

Lord min B^* would be solf

 $\nabla RSS(B^*) = 0$

$$RSS(\beta) = \| \times \beta - y \|^{2}$$

$$= (\times \beta - y)^{T} (\times \beta - y)$$

$$= (\times \beta)^{T} \times \beta - (\times \beta)^{T} y - y^{T} \times \beta + y^{T} y$$

$$= \beta^{T} \times x^{T} \times \beta - 2 \beta^{T} \times x^{T} y + y^{T} y$$

$$\nabla_{x} (a^{T}x) = a \quad \text{and} \quad \nabla_{x} (x^{T}Ax) = (A + A^{T})x$$

$$\nabla_{x} (a^{T}x) = a$$

$$\nabla_{x} (x^{T}Ax) = (A + A^{T})x$$

$$\nabla_{x} (x^{$$

$$\nabla_{\beta} RSS(\beta) = 2 \times T \times \beta - 2 \times T y$$

$$Find \nabla_{\beta} RSS(\beta^*) = 0$$

$$2 \times T \times \beta^* - 2 \times T y = 0$$

$$\times T \times \beta^* = X T y$$

$$(\times T \times)^{-1} (\times T \times) \beta^* = (\times T \times)^{-1} \times T y$$

$$I \beta^* = (\times T \times)^{-1} \times T y$$

min
$$RSS(B)$$

$$\Rightarrow B^* = (X^T X)^{-1} X^T Y$$

$$\Rightarrow min (global min)$$

$$Y = XB$$

$$\forall RSS(B) = Z X^T X B - 2 X^T Y$$

$$\forall^2 RSS(B) = Z X^T X$$

$$\Rightarrow n \times (P+1)$$

$$(P+1) \times n$$

$$(P+1) (P+1)$$

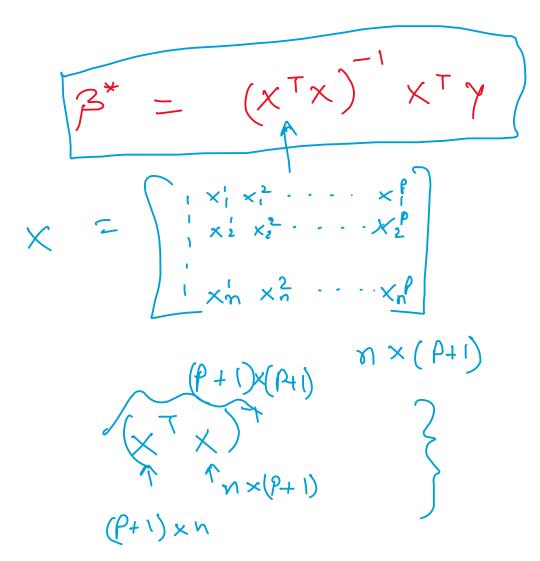
$$\nabla^{2} RSS(B) = 2 \times T \times 1$$

$$1 \times (P+1)$$
Heroian of RSS
$$(P+1) \times N$$

$$(P+1) (P+1)$$

$$\forall \beta$$
 $\beta T \left(2 \times T \times\right) \beta = 2 \left(\times \beta\right)^T \times \beta$

$$= 2 \left\|X^{\beta}\right\|^2 > 0$$
 β^* is now global minima.



Gauss-Markov Theorem

• The Gauss–Markov theorem states that if we have any other linear estimator $\tilde{\theta} = \mathbf{c}^T \mathbf{y}$ that is unbiased for $\mathbf{\alpha}^T \mathbf{\beta}$, that is, $\mathbf{E}(\mathbf{c}^T \mathbf{y}) = \mathbf{\alpha}^T \mathbf{\beta}$, then

$$Var(a^T \hat{\beta}) \leq Var(\mathbf{c}^T \mathbf{y}).$$

Gauss-Markov Theorem

• The least squares estimate of $\alpha^T\beta$ is

$$\hat{\theta} = a^T \hat{\beta} = a^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}.$$

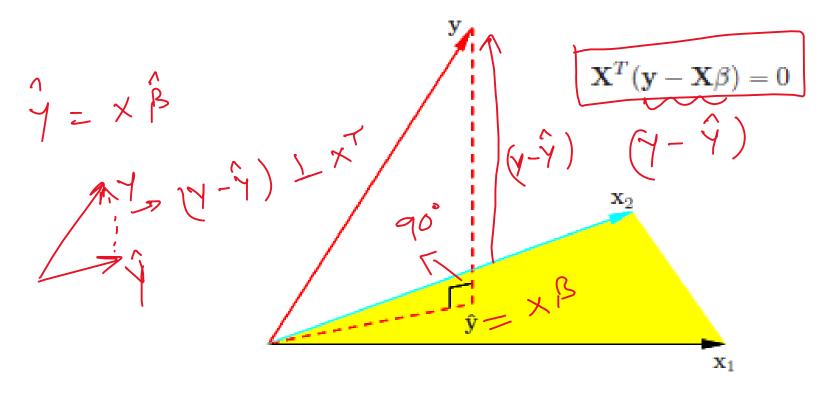
- Considering X to be fixed, this is a linear function $c_0^T y$ of the response vector y.
- If we assume that the linear model is correct, $\alpha^T\beta$ is unbiased since

$$E(a^{T}\hat{\beta}) = E(a^{T}(\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{X}^{T}\mathbf{y})$$

$$= a^{T}(\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{X}^{T}\mathbf{X}\beta$$

$$= a^{T}\beta.$$

Linear Regression



The N-dimensional geometry of least squares regression with two predictors. The outcome vector y is orthogonally projected onto the hyperplane spanned by the input vectors \mathbf{x}_1 and \mathbf{x}_2 . The projection $\mathbf{\hat{y}}$ represents the vector of the least squares predictions

In multiple linear regression, we usually are interested in answering a few important questions.

- 1. Is at least one of the predictors X1,X2, . . . , Xp useful in predicting the response?
- 2. Do all the predictors help to explain Y, or is only a subset of the predictors useful?
- 3. How well does the model fit the data?
- 4. Given a set of predictor values, what response value should we predict, and how accurate is our prediction?

Extensions of Linear Models

Removing the Additive Assumption
 Introduce the interactive term

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_1 X_2 + \epsilon.$$

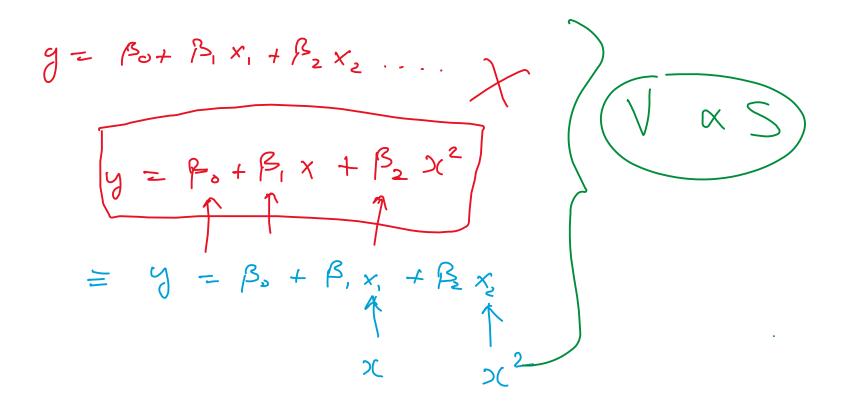
$$Y = \beta_0 + (\beta_1 + \beta_3 X_2) X_1 + \beta_2 X_2 + \epsilon.$$

$$= \beta_0 + \tilde{\beta}_1 X_1 + \beta_2 X_2 + \epsilon.$$

- Where $\tilde{\beta}_1 = \beta_1 + \beta_3 X_2$
- Non-linear Relationships

$$mpg = \beta_0 + \beta_1 \times horsepower + \beta_2 \times horsepower^2 + \epsilon$$

Nonlinear regression



Basis function regression

Hypothesis testing in multi linear regression

$$y = f(x) + \varepsilon \qquad f(x)$$

$$y = \beta + \beta_1 \times_1 + \beta_2 \times_2 + \cdots + \varepsilon$$

$$+ \text{ statistic} \implies \beta - \text{ Volue}$$

$$y = \beta_1 + \beta_2 \times_2 + \cdots + \varepsilon$$

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F-Statistic

F-Statistic

Is There a Relationship Between the Response and **Predictors?**

We test the null hypothesis,

versus the alternative

 H_a : at least one β_i is non-zero.

This hypothesis test is performed by computing the F-statistic,

$$F = \frac{(TSS - RSS)/p}{RSS/(n-p-1)}, \quad Linear model is correctly for the production of the production$$

Value of F-statistic close to 1 when null hypothesis true ← Value of F-statistic greater than 1 when alternative hypothesis true

Hypothesis testing in multi linear regression

- F is very close to one we cannot reject the null hypothesis (thus, in a sense we accepted the null hypothesis)
- If F is **very large** we reject the null hypothesis (thus, in a sense we accepted the **alternate hypothesis**)

How large is large enough?

- This depends upon the values of n and p.
- If n is very large a small value above 1 is also a compelling evidence against the null hypothesis; however if n is a small then F has to be very large for us to reject the null hypothesis.
- When the null hypothesis is true and the error follows a Gaussian distribution, then it can be shown that F-statistic follows Fdistribution

Hypothesis testing in multi linear regression

Why do we need F-statistic when t-statistic already exists?

(Given these individual p-values for each variable, why do we need to look at the overall F-statistic? After all, it seems likely that if any one of the p-values for the individual variables is very small, then at least one of the predictors is related to the response.)

- However, the above logic is flawed, especially when the number of predictors p is large.
- For instance, consider an example in which p = 100 and $H0: \beta 1 = \beta 2 = \ldots = \beta p = 0$ is true, so no variable is truly associated with the response. In this situation, about 5% of the p-values associated with each variable will be below 0.05 by chance. In other words, we expect to see approximately five small p-values even in the absence of any true association between the predictors and the response.

- Predictors with Only Two Levels
- Define new variables

$$x_i = \begin{cases} 1 & \text{if } i \text{th person is female} \\ 0 & \text{if } i \text{th person is male,} \end{cases}$$

The model then takes the form

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i = \begin{cases} \beta_0 + \beta_1 + \epsilon_i & \text{if } i \text{th person is female} \\ \beta_0 + \epsilon_i & \text{if } i \text{th person is male.} \end{cases}$$

- Predictors with more than Two Levels
- Define new variables

$$x_{i1} = \begin{cases} 1 & \text{if } i \text{th person is Asian} \\ 0 & \text{if } i \text{th person is not Asian,} \end{cases}$$

$$x_{i2} = \begin{cases} 1 & \text{if } i \text{th person is Caucasian} \\ 0 & \text{if } i \text{th person is not Caucasian.} \end{cases}$$

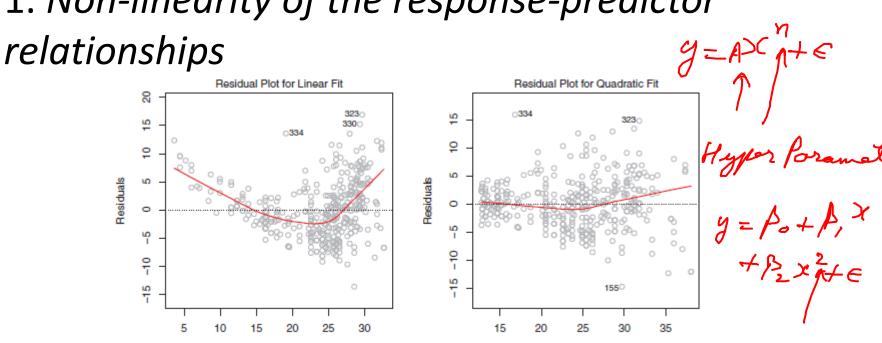
The model then takes the form

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i = \begin{cases} \beta_0 + \beta_1 + \epsilon_i & \text{if ith person is Asian} \\ \beta_0 + \beta_2 + \epsilon_i & \text{if ith person is Caucasian} \\ \beta_0 + \epsilon_i & \text{if ith person is African American.} \end{cases}$$

- 1. Non-linearity of the response-predictor relationships.
- 2. Correlation of error terms.
- 3. Non-constant variance of error terms.
- 4. Outliers.
- 5. High-leverage points.
- 6. Collinearity.

1. Non-linearity of the response-predictor

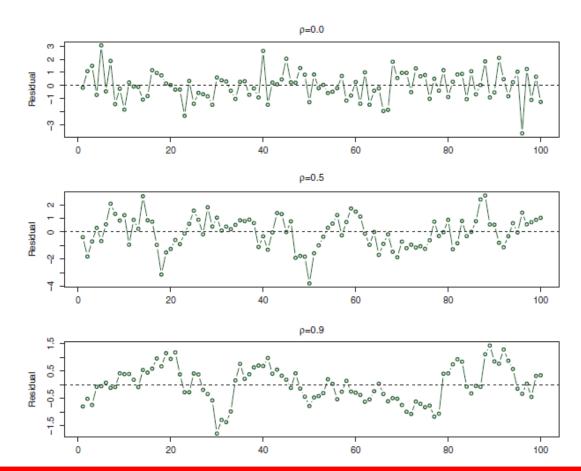
Fitted values



Plots of residuals versus predicted (or fitted) values for the Auto data set. In each plot, the red line is a smooth fit to the residuals, intended to make it easier to identify a trend. Left: A linear regression of mpg on horsepower. A strong pattern in the residuals indicates non-linearity in the data. Right: A linear regression of mpg on horsepower and horsepower². There is little pattern in the residuals.

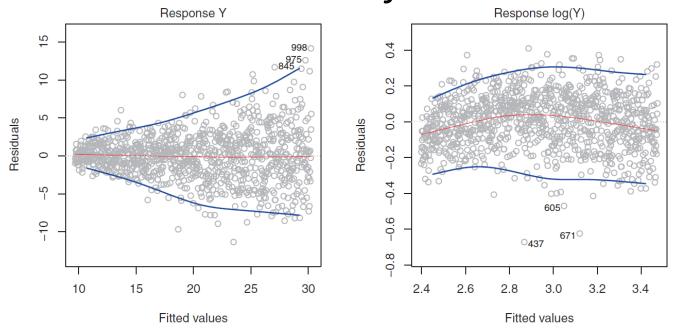
Fitted values

2. Correlation of error terms



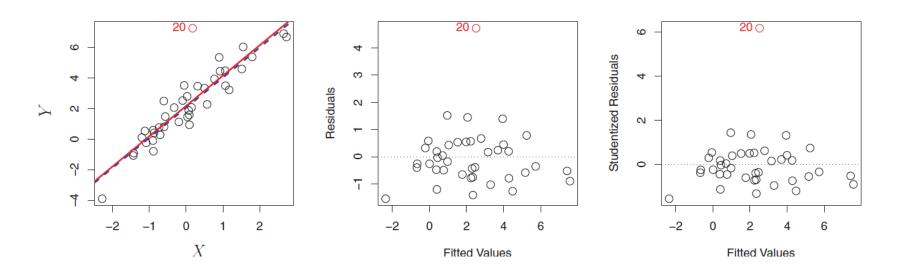
Plots of residuals from simulated time series data sets generated with differing levels of correlation ρ between error terms for adjacent time points.

3. Non-constant variance of error terms.



Residual plots. In each plot, the red line is a smooth fit to the residuals, intended to make it easier to identify a trend. The blue lines track the outer quantiles of the residuals, and emphasize patterns. Left: The funnel shape indicates heteroscedasticity. Right: The response has been log transformed, and there is now no evidence of heteroscedasticity

4. Outliers.



Left: The least squares regression line is shown in red, and the regression line after removing the outlier is shown in blue. Center: The residual plot clearly identifies the outlier. Right: The outlier has a studentized residual of 6; typically we expect values between –3 and 3.

Robust Regression

- The average quadratic error functional (RSS) is very sensitive to outliers
- Robust error functionals aim to reduce the influence of outliers.
- Linear regression with robust error functionals is called robust linear regression.

Robust Regression

• One example of a robust error functional is the Huber function where the errors are only squared if they are smaller than a threshold $\varepsilon > 0$, otherwise they have only a linear impact

$$E_{H} = \sum_{k=1}^{n} \begin{cases} e_{k}^{2} & \text{if } |e_{k}| < \epsilon \\ 2\epsilon \cdot |e_{k}| - \epsilon^{2} & \text{otherwise} \end{cases}$$

Robust Regression

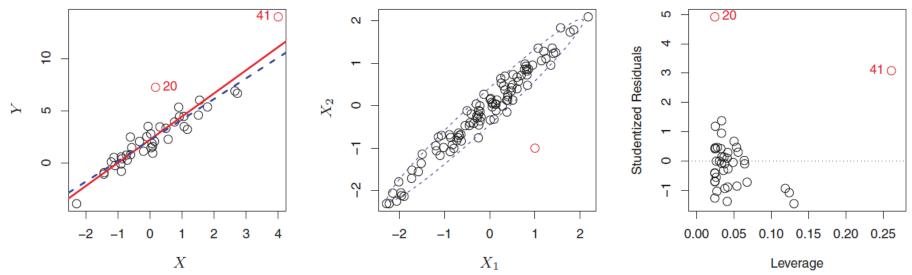
 Another example of a robust error functional is least trimmed squares which sorts the errors so that

$$e_1' \leq e_2' \leq \ldots \leq e_n'$$

and only considers the m smallest errors, $1 \le m \le n$.

$$E_{LTS} = \sum_{k=1}^{m} e_k^{\prime 2}$$

5. High-leverage points



Left: Observation 41 is a high leverage point, while 20 is not. The red line is the fit to all the data, and the blue line is the fit with observation 41 removed. Center: The red observation is not unusual in terms of its X1 value or its X2 value, but still falls outside the bulk of the data, and hence has high leverage. Right: Observation 41 has a high leverage and a high residual

High-leverage points

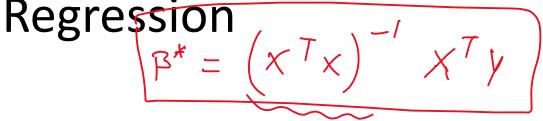
- In order to quantify an observation's leverage, we compute the *leverage statistic*.
- A large value of this statistic indicates an observation with high leverage.
- For a simple linear regression.

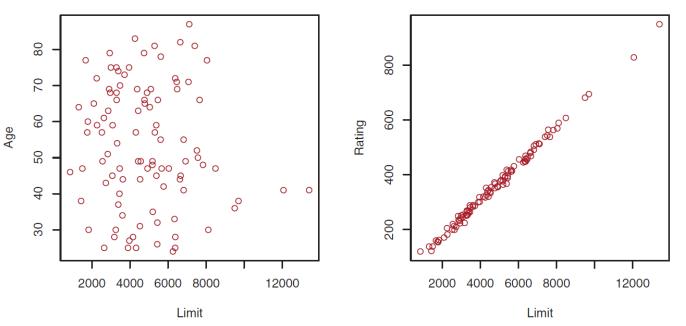
$$h_i = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{\sum_{i'=1}^n (x_{i'} - \bar{x})^2}.$$

- The leverage statistic h_i is always between 1/n and 1.
- The average leverage for all the observations is always equal to (p+1)/n.

Potential problems of Linear

 $g = f(x) + \epsilon$ 6. Collinearity





Scatterplots of the observations from the Credit data set. Left: A plot of age versus limit. These two variables are not collinear. Right: A plot of rating versus limit. There is high collinearity.

Singular value decomposition is a generalization of the eigen- decomposition of a square Matrix to a non-square matrix.

$$M = U\Sigma V^*$$

Where,

M is a real of complex m x n matrix

U is an m x m, real or complex unitary matrix (conjugate transpose, U^{\ast} is also its inverse)

 Σ is an m x n rectangular diagonal matrix with non-negative real numbers

 V^* is an n x n, real or complex unitary matrix

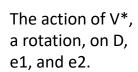
If M is real then U and V are real orthogonal matrices

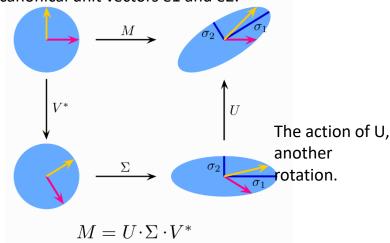
The diagonal values of Σ are known as the singular values. By convention they are written in descending order. In this case Σ (but not always U and V^*) is uniquely determined by M.

$$M = U\Sigma V^*$$

Illustration of the singular value decomposition $U\Sigma V^*$ of a real 2×2 matrix M.

The action of M, indicated by its effect on the unit disc D and the two canonical unit vectors e1 and e2.





The action of Σ , a scaling by the singular values $\sigma 1$ horizontally and $\sigma 2$ vertically.

Compact Singular Value Decomposition

Compact singular value decomposition is similar to SVD with a square diagonal matrix $\boldsymbol{\Sigma}_d$.

$$M = U_c \Sigma_d V_c^*$$

Where,

M is a real of complex m x n matrix

 U_c is an m x r, semi-unitary matrix ($U_c^*U_c = I_{rxr}$)

 Σ_d is an r x r square diagonal matrix with positive real numbers

 V_c is an n x r , semi-unitary matrix ($V_c^*V_c = I_{rxr}$)

 $r \leq \min\{n, m\}$ is the rank of M matrix, and $\Sigma_{\rm d}$ has only the non-zero singular values of M.

Thus,
$$\Sigma = \begin{bmatrix} \Sigma_d & 0 \\ 0 & 0 \end{bmatrix}$$

 Compact Singular Value Decomposition

Semi- unitary medric & U*U mxz A 9xn 1 xr 2 < min (m,n) is the rank of M E is a non-zered diagonal mother, 9×1 is a non-zered diagonal mother,

G = f(x) + E

Random Error with mean => Singular

values will

never be zero

if for volumes points

but will be close to

zero.

If singular values are neal zero then (x^Tx)⁻¹ will exist.

X=UEVT=U[Ex]VT sliggand matriceville Ridge Regression simples values

regrenion

min $\|X\beta - Y\|_{2}^{2} = \sum (x^{T}x)^{T}X^{T}y$ Ridge min || XB_Y||² + \ ||\B||² A le fittglarit.

$$RSS(\beta) = \|X\beta - Y\|_{2}^{2} + \lambda \|\beta\|_{2}^{2}$$

$$= \beta^{T} X^{T} X^{\beta} - 2 \beta^{T} X^{T} Y$$

$$+ Y^{T} Y + \lambda \beta T \beta$$

$$\nabla RSS(\beta) = 2 X^{T} X^{\beta} - 2 X^{T} Y + 2 \lambda \beta$$

$$\nabla RSS(\beta) = 0$$

$$\nabla_{\beta} RSS(\beta) = 2 \times^{T} \times \beta - 2 \times^{T} y + 2 \lambda \beta$$

$$\forall RSS = 0$$

$$= > 2 \times^{T} \times \beta - 2 \times^{T} y + 2 \lambda \beta^{S} = 0$$

$$(2 \times^{T} \times + 2 \times^{T} y + 2 \times^{T} y) = 2 \times^{T} y$$

$$\beta = (x^{T} \times + \lambda T)^{T} \times^{T} y$$