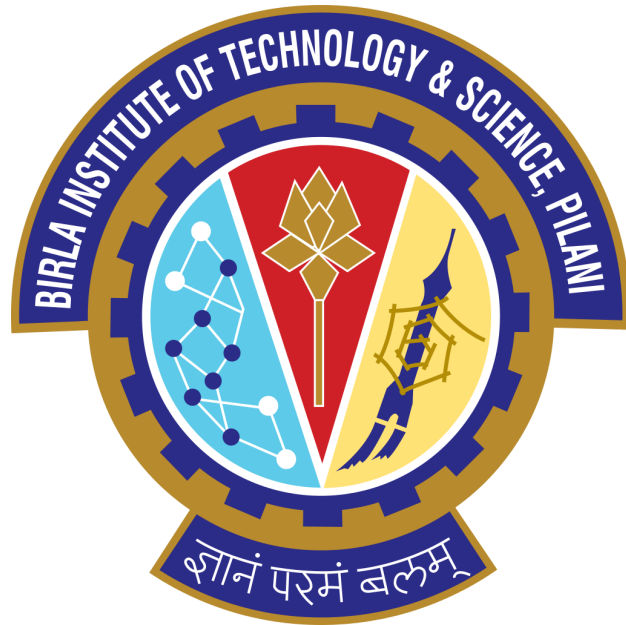


INSTR F241 : Microprocessor Programming and Interfacing



DESIGN ASSIGNMENT:
PROJECT-14

DOOR SECURITY CONTROL SYSTEM

GROUP NO : 98

MEET PARIKH	2015A8PS375P
MOHD INSHA KHAN	2015A8PS378P
ADITYA WAGH	2015A8PS382P
NIKHIL GOEL	2015A8PS385P

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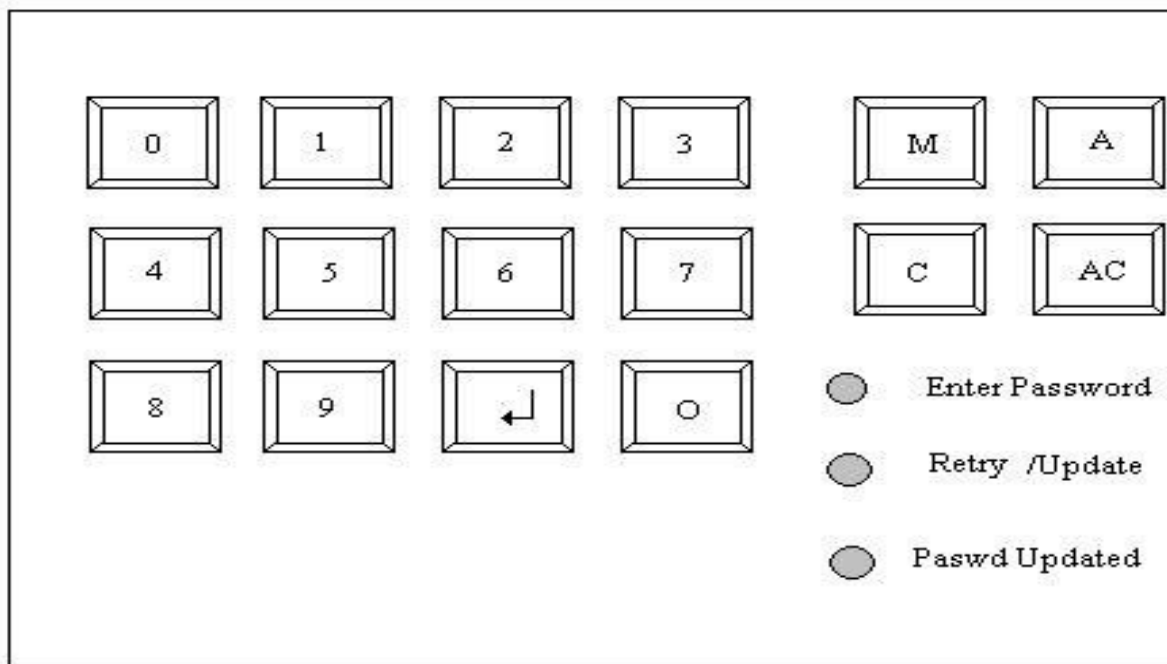
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PROBLEM STATEMENT

DESCRIPTION: This system controls the opening and closing of a door based on password entry. If the password is correct the person can enter. Each person is given two chances to enter the correct password. On failure an alarm is sounded. Inside the room a button is available when the button is pressed the door opens for 2 Min, so that the person can leave the room.

USER INTERFACE: There are three sets of passwords:

- (1) User
- (2) Master
- (3) Alarm off



- The Master password is used by the security Personnel for updating Password of the day. Pressing the M button activates this mode. The system glows Enter Password LED asking the personnel to enter the password. The master password is a 16-digit value. The master is given only a single chance to enter the password. If authenticated, the retry/Update LED glows. If there is a failure in authentication the alarm is sounded. When the retry/ Update LED glows the user has to enter password of the day. This is 12-digit value. Once this value has been accepted by the system the Passwd Updated LED glows.
- User has to press the O key when he wants to enter the room. The Enter Password LED prompts the user to enter the password. The user is given C/AC option as well. If the first attempt fails, the RETRY LED glows. The user is allowed to re-enter password, on authentication door opens for a period of 1 Min. On Failure an ALARM is sounded.
- To Turn-off the Alarm the A button has to be pressed. Enter Password LED glows prompting user to enter the 14-digit password for turning of alarm, no retries are allowed. If authentication is successful then the alarm is turned off.
- To leave the room a button is available inside the room, when the button is pressed the door opens for 1 Minute so that the person can leave the room.
- LCD show the entry as asterisk when the password characters are entered.

ASSUMPTIONS

- All operations are sequential and so, no two operations can be carried out at the same time.
- User cannot access the door lock system at the 24 hour mark. First, a user password needs to be set using the master mode and only then can the door lock be accessed.
- Once you have entered a mode, it is necessary to complete the entire procedure. Pressing any other mode buttons like M, O or A will not override the mode.
- In case of mistake in typing the password to turn down the alarm, the system will get locked in it's last state and to use it again, it is necessary to shutdown and restart the system.
- The 24 hour clock starts running as soon as we turn on the system.
- The Master Password and the Alarm Password have been hardcoded in the system.

Master Password: 9999999999999999

Alarm Password: 99999999999999

LIST OF COMPONENTS USED

Sr. No.	Hardware Device	Description	Quantity
1.	8086	16 bit Microprocessor	1
2.	74LS373	Octal Latch	3
3.	74LS245	Transceiver	2
4.	7432	OR gate	6
5.	NOT	NOT gate	6
6.	2732	ROM	2
7.	6116	RAM	2
8.	74LS138	3-to-8 Decoder	1
9.	8255A	Programmable Peripheral Interface	2
10.	8253A	Programmable Interval Timer	2
11.	KEYPAD-PROJECT	Hex-keypad	1
12.	BUTTON	Button	1
13.	LM016L	16x2 LCD display	1
14.	BUZZER	Alarm	1
15.	LED-BLUE	Blue LED	1
16.	LED-RED	Red LED	3
17.	MOTOR-STEPPER	Stepper Motor	1

18.	OMIH-SH-105D	Relay	1
-----	--------------	-------	---

19.	SW-SPDT-MOM	SPDT Switch	1
20.	ULN2003A	Darlington Transistor	1
21.	74LS241	Tri-state Buffer	1

Memory Mapping

Size of 2732 (ROM) : 4k

ROM(even) : 00000h - 01FFEnh (Ao = 0)

ROM (odd) : 00001h - 01FFFh (A0 = 1)

[illegible]

Size of 6116 (RAM) : 2k

RAM(even) : FF000h - FFFFEh (Ao = 0)

RAM(odd) : FF001h - FFFFh (A0 = 1)

[illegible]

I/O Mapping

Address of 8255-1 port-A : 00h
Address of 8255-1 port-B : 02h
Address of 8255-1 port-C : 04h
Address of 8255-1 control register : 06h
Control word of 8255-1 : 88h

Address of 8255-2 port-A : 08h
Address of 8255-2 port-B : 0Ah
Address of 8255-2 port-C : 0Ch
Address of 8255-2 control register : 0Eh
Control word of 8255-2 : 89h

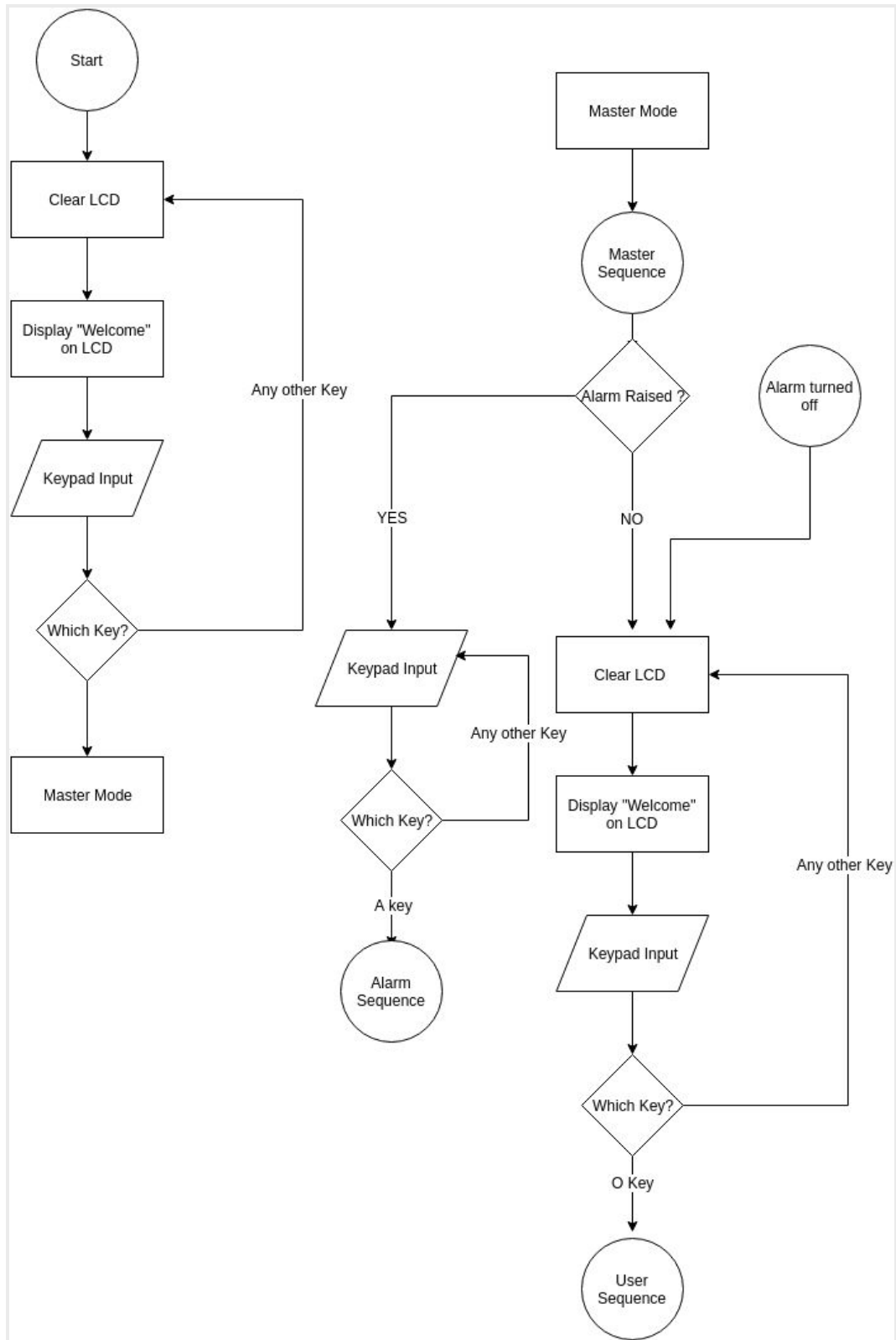
Address of 8253-1 count0 : 10h
Address of 8253-1 count1 : 12h
Address of 8253-1 count2 : 14h
Address of 8253-1 control register : 16h
Control word of 8253-1 count0 : 36h
Control word of 8253-1 count1 : 56h
Control word of 8253-1 count2 : 92h

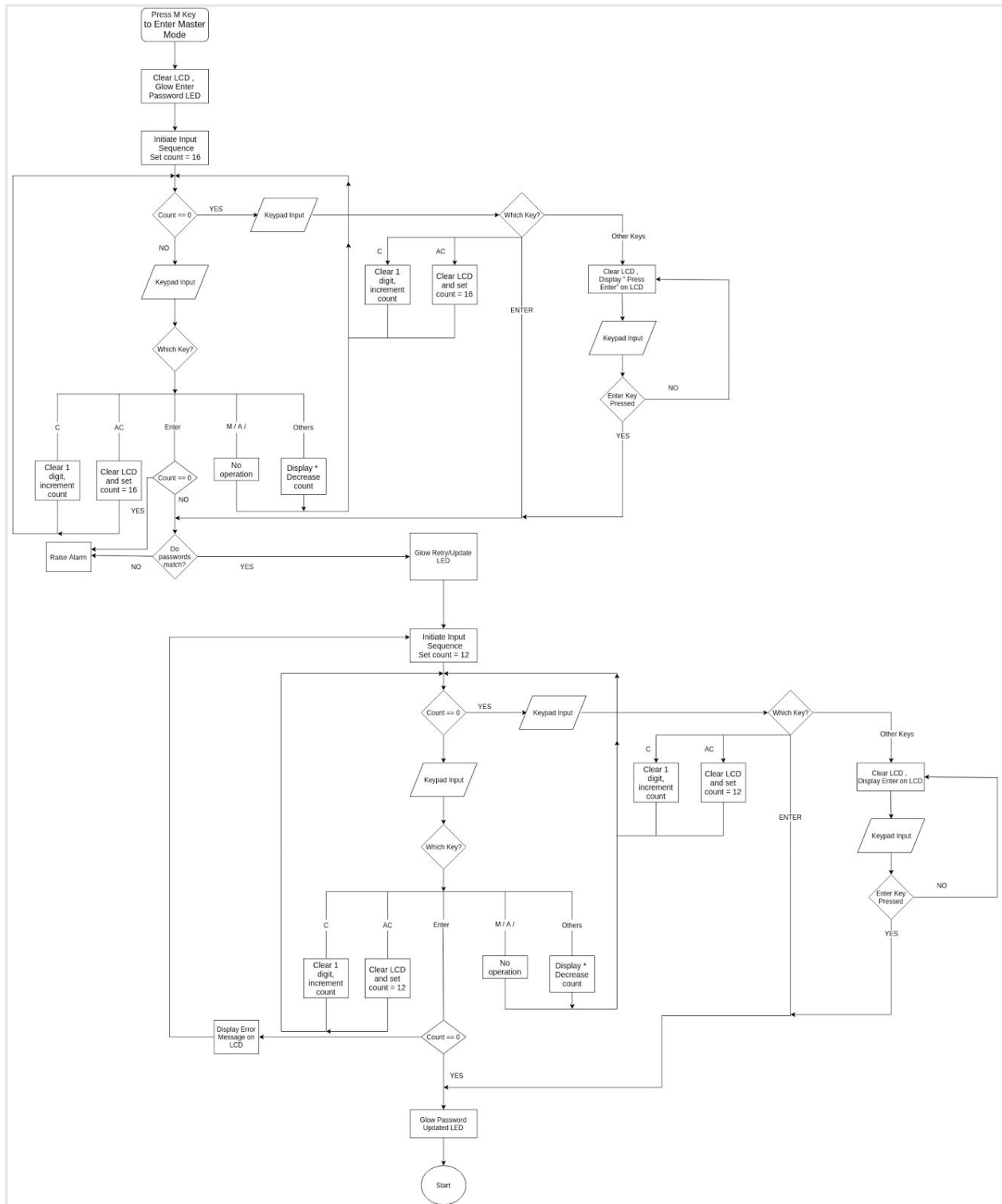
Address of 8253-2 count0 : 18h
Address of 8253-2 count1 : 1Ah
Address of 8253-2 count2 : 1Ch
Address of 8253-2 control register : 1Eh
Control word of 8253-2 count0 : 34h
Control word of 8253-2 count1 : 5Ah
Control word of 8253-2 count2 : 94h

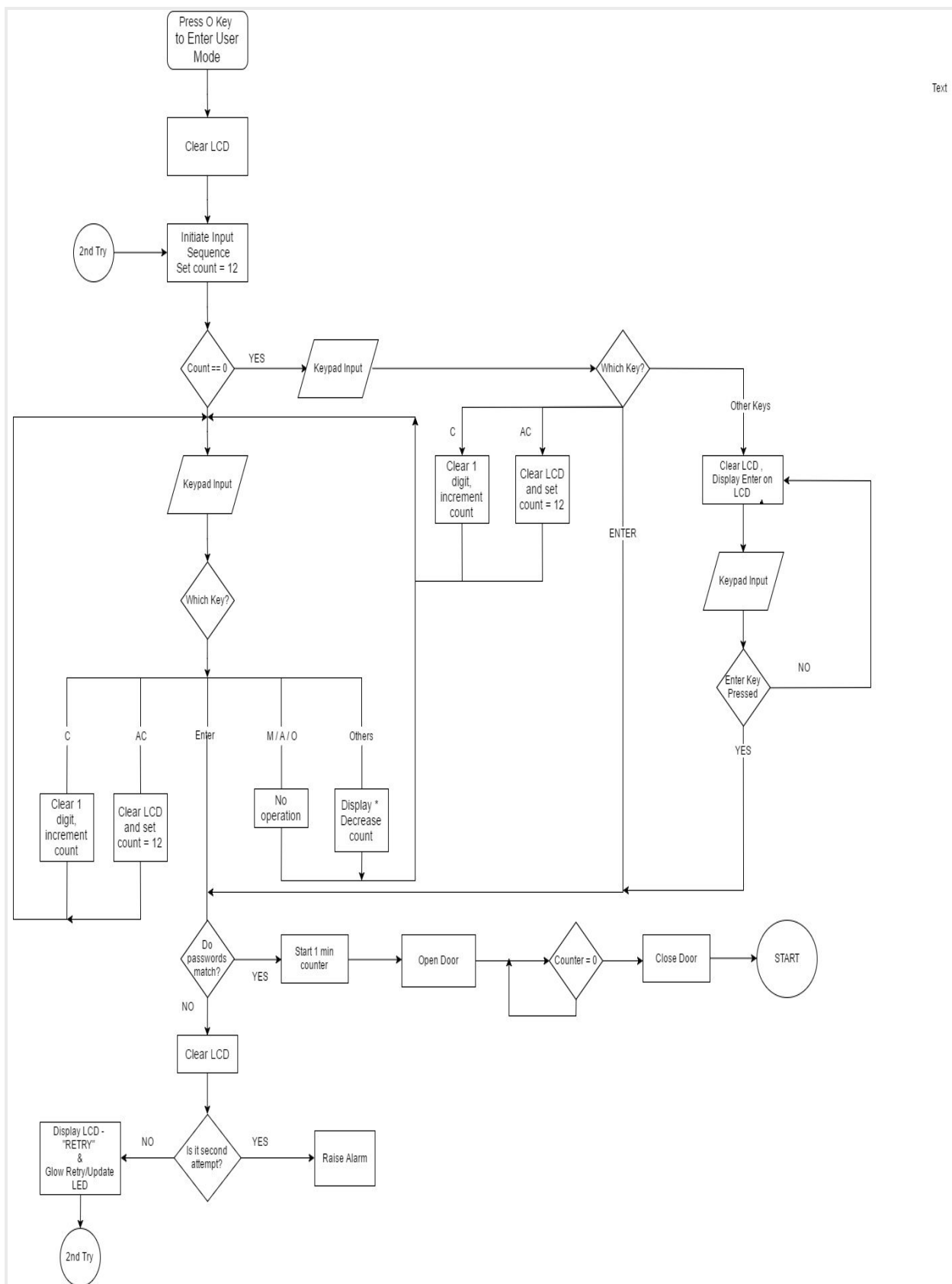
IVT

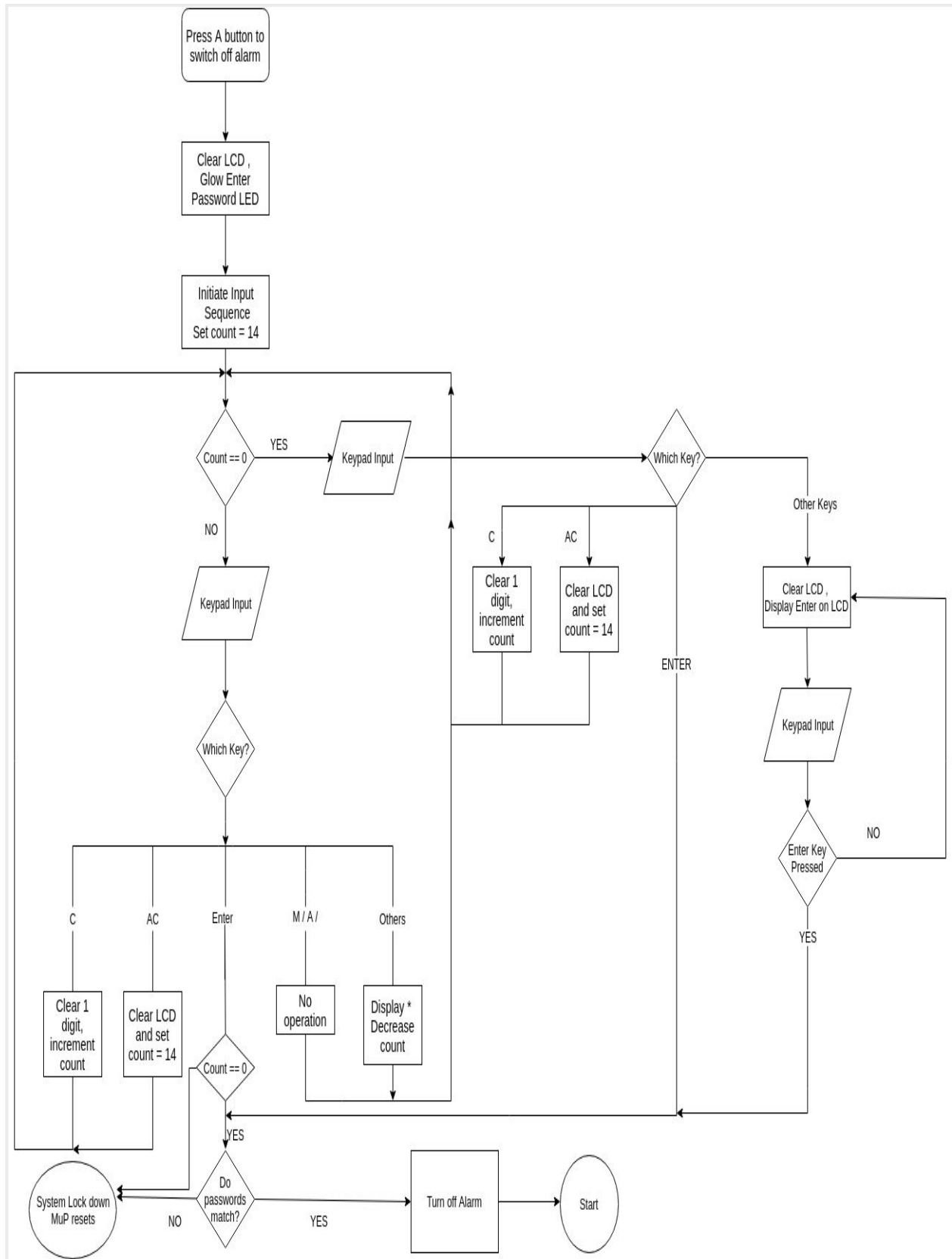
Interrupt Vector No.	Physical Address	Contains
INT 02h	00008h 0000Ah	IP2 CS2
INT 80h	00200h 00202h	IP128 CS128

Flow-Chart of the System









ALP Code

```
#make_bin#
```

```
#LOAD_SEGMENT=FFFFh#
```

```
#LOAD_OFFSET=0000h#
```

```
#CS=0000h#
```

```
#IP=0000h#
```

```
#DS=0000h#
```

```
#ES=0000h#
```

```
#SS=0000h#
```

```
#SP=FFFEh#
```

```
#AX=0000h#
```

```
#BX=0000h#
```

```
#CX=0000h#
```

```
#DX=0000h#
```

```
#SI=0000h#
```

```
#DI=0000h#
```

```
#BP=0000h#
```

```
    jmp    st1
```

```
    db     5 dup(0)
```

```
    ;IVT entry for NMI (INT 02h)
```

```
    dw     Nmi_24hrtimer
```

```
    dw     0000
```



```
db 500 dup(0)
```

```
;IVT entry for 80H
```

```
dw Switch_intR
```

```
dw 0000
```

```
db 508 dup(0)
```

```
sti: cli
```

```
;initialize ds, es,ss to start of RAM
```

```
mov ax,0200h
```

```
mov ds,ax
```

```
mov es,ax
```

```
mov ss,ax
```

```
mov sp,0FFFEH
```

```
; INITIALIZATION OF 8255,8253 BEGINS HERE
```

```
sti
```

```
mov al,89h ; control word for 8255-2
```

```
out 0Eh,al
```

```
mov al,88h ; control word for 8255-1
```

```
out 06h,al
```

```
mov al,36h ;control word for 8253-1 counter 0
```

```
out 16h,al
```

```
mov al,56h ;control word for 8253-1 counter 1
```

```
out 16h,al
```

```
mov al,92h ;control word for 8253-1 counter 2
```

```
out 16h,al
```

```
mov al,34h ;control word for 8253-2 counter 0
```

```
out 1eh,al
```

```
mov al,5ah ;control word for 8253-2 counter 1  
out 1eh,al
```

```
mov al,94h ;control word for 8253-2 counter 2  
out 1eh,al
```

```
mov al,50h ;load count lsb for 8253-1 counter 0  
out 10h,al
```

```
mov al,0C3h ;load count msb for 8253-1 counter 0  
out 10h,al
```

```
mov al,64h ;load count for 8253-1 counter 1  
out 12h,al
```

```
mov al,5h ;load count lsb for 8253-1 counter 2 (1 minute  
Timer)  
out 14h,al
```

```
mov al,40 ;load count for 8253-2 LSB counter 0 (24 hour  
counter)  
out 18h,al
```

```
mov al,0 ;load count for 8253-2 MSB counter 0 (24 hour  
counter)  
out 18h,al
```

```
mov al,3 ;load count for 8253-2 counter 1 (Switch trigger  
counter)  
out 1ah,al
```

```
mov al,2 ;load count for 8253-2 counter 2
out 1ch,al
;INITIALIZATION OF 8255,8253 ENDS HERE
```

```
mov al,00h ;default low output from 8255-2 upper port C
out 0ch,al
```

```
call DELAY_20ms ;LCD INITIALIZATION BEGINS
mov al,04h
out 02h,al
call DELAY_20ms
mov al,00h
out 02h,al
```

```
mov al,38h
out 00h,al
```

```
mov al,04h
out 02h,al
call DELAY_20ms
mov al,00h
out 02h,al
call DELAY_20ms
mov al,0Ch
out 00h,al
mov al,04h
out 02h,al
call DELAY_20ms
mov al,00h
out 02h,al
```

```
mov al,06h
out 00h,al
call DELAY_20ms
mov al,04h
out 02h,al
call DELAY_20ms
mov al,00h
out 02h,al
mov al,4ch
out 00h,al
call DELAY_20ms ;LCD INITIALIZATION ENDS
```

```
mov ax,0200h
mov ds,ax
```

```
mov si,0000h
mov al,0bdh ;hard coding pass-word
;9999999999999999
mov [si],al
```

```
mov al,0bdh
mov [si+1],al
```

```
mov al,0bdh
mov [si+2],al
```

```
mov al,0bdh
mov [si+3],al
```

```
mov al,0bdh
mov [si+4],al
```

```
mov al,0bdh
```

```
mov [si+5],al
```

```
mov al,obdh  
mov [si+6],al
```

```
mov al,obdh  
mov [si+7],al
```

```
mov al,obdh  
mov [si+8],al
```

```
mov al,obdh  
mov [si+9],al
```

```
mov al,obdh  
mov [si+0ah],al
```

```
mov al,obdh  
mov [si+0bh],al
```

```
mov al,obdh  
mov [si+0ch],al
```

```
mov al,obdh  
mov [si+0dh],al
```

```
mov al,obdh  
mov [si+0eh],al
```

```
mov al,obdh  
mov [si+0fh],al
```

```
add si,000fh
```

```
inc si
```

```
mov al,obdh ;hard coding alarm pass-word ;  
9999999999999999  
mov [si],al
```

```
mov al,obdh  
mov [si+1],al
```

```
mov al,obdh  
mov [si+2],al
```

```
mov al,obdh  
mov [si+3],al
```

```
mov al,obdh  
mov [si+4],al
```

```
mov al,obdh  
mov [si+5],al
```

```
mov al,obdh  
mov [si+6],al
```

```
mov al,obdh  
mov [si+7],al
```

```
mov al,obdh  
mov [si+8],al
```

```
mov al,obdh  
mov [si+9],al
```

```
mov al,obdh
mov [si+0ah],al
```

```
mov al,obdh
mov [si+0bh],al
```

```
mov al,obdh
mov [si+0ch],al
```

```
mov al,obdh
mov [si+0dh],al
```

```
add si,000dh
inc si
```

```
mov al,offh
out 08h,al
```

```
start:    call clear_LCD
          call welcome_msg
```

```
          mov bp,00h
          call keypad_input
          cmp al,0bbh
          jz master_mode
          jmp start
```

```
x6:    call clear_LCD
        call welcome_msg
        call keypad_input
        cmp al,0b7h
        jz User_mode
```

jmp x6 ;press valid key

master__mode:

call intm

mov bp,0abcdh

cmp ax,0abcdh

jnz x6

x8: call keypad__input

cmp al,7Dh

jz Alarm__mode

jnz x8

Alarm__mode:

call inta

cmp dh,6h

jz start

cmp dh,1h

jz x6

jmp x70

User__mode:

call intu

cmp ax,0abcdh

jz x8

jnz x6

x70:

stop: jmp stop

DELAY__20ms proc

MOV CH,5

X4: NOP


```
        NOP
        DEC CH
        JNZ X4
    RET
DELAY_20ms endp
DELAY_0.04s proc
```

```
        MOV cx,4fffh
X17:    NOP
        NOP
        DEC cx
        JNZ X17
    RET
DELAY_0.04s endp
DELAY_max proc
```

```
        MOV cx,0ffffh
X16:    NOP
        NOP
        DEC cx
        JNZ X16
    RET
DELAY_max endp
```

```
enter_LCD proc
    mov al,0A0h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h
    out 02h,al ;prints Space
```

```
mov al,0A0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,50h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints P
```

```
mov al,52h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints R
```

```
mov al,45h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
```

```
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
mov al,53h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints S
```

```
mov al,53h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints S
```

```
mov al,0A0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,45h
out 00h,al
```

```
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
mov al,4Eh
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints N
```

```
mov al,54h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints T
```

```
mov al,45h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
    mov al,52h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h
    out 02h,al ;prints R
RET
enter__LCD endp
```

intm proc

```
    call clear__LCD
    mov al,0feh
    out 08h,al ;turns on enter password LED
    mov cx,16
```

enter__16bit:

```
    call keypad__input
    cmp al,7eh
    jz pressc
    cmp al,7bh
    jz pressac
    cmp al,77h
    jz press__enter
    cmp al,0bbh
    jz nop__master
    cmp al,0b7h
    jz nop__master
    cmp al,7dh
```

```

        jz nop_master
        mov [si],al
        CALL Print_*
        inc si
        dec cx
        jnz enter_16bit
disp_entermaster:
        call keypad_input
        cmp al,7eh
        jz pressc
        cmp al,7bh
        jz pressac
        cmp al,77h
        jz press_enter
asd:    CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h
        jz press_enter
        jnz asd
nop_master:  nop
        jmp enter_16bit
pressc:    call clear_1digit_LCD
        dec si
        inc cx
        jmp enter_16bit
pressac:
        CALL clear_LCD
        mov cx,16
        mov si,1eh        ;start of pass segment
        jmp enter_16bit
press_enter:
        CALL clear_LCD

```

```
mov al,offh
out 08h,al
cmp cx,0
jz cmp_pass
jmp raise_alarm
```

day_pass:

```
mov si,002Eh
mov al,ofd
out 08h,al
call DELAY_max
call DELAY_max
call DELAY_max
call clear_LCD
mov cx,12
```

enter_12bit:

```
call keypad_input
cmp al,7eh
jz presscd
cmp al,0bbh
jz nop_day
cmp al,0b7h
jz nop_day
cmp al,7dh
jz nop_day
cmp al,7bh
jz pressacd
cmp al,77h
jz press_enterday
mov [si],al
CALL Print_*
inc si
```

```

        dec cx
        jnz enter_12bit
disp_enter:
        call keypad_input
        cmp al,7eh
        jz presscd day
        cmp al,7bh
        jz pressac day
        cmp al,77h
        jz press_enter day
asd1:   CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h
        jz press_enter day
        jnz asd1
nop_day: nop
        jmp enter_12bit

presscd day:
        call clear_1digit_LCD
        dec si
        inc cx
        jmp enter_12bit
pressac day:
        CALL clear_LCD
        jmp day_pass
press_enter day:
        CALL clear_LCD
        mov al,offh
        out 08h,al
        cmp cx,0
        jnz err_msg

```



```
mov al,0fbh
out 08h,al
```

```
call DELAY_max
call DELAY_max
```

```
mov al,offh
out 08h,al
jz end_69h
```

```
err_msg:
```

```
call error_msg
jmp day_pass
```

```
cmp_pass:
```

```
cld
mov si,0000h
mov di,001Eh
mov cx,17
```

```
x5:
```

```
mov al,[si]
mov bl,[di]
dec cx
jz day_pass
cmp al,bl
jnz raise_alarm
inc si
inc di
jmp x5
```

```
raise_alarm:
```

```
mov dh,5h
mov al,offh
out 08h,al
```

```
        mov ax,0abcdh
end_69h:
ret
intm endp
```

```
Print_* proc
        mov al,2Ah
        out 00h,al
        call DELAY_20ms
        mov al,05h
        out 02h,al
        call DELAY_20ms
        mov al,01h
        out 02h,al ;prints *
ret
Print_* endp
```

```
clear_LCD proc
        mov al,00h
        out 02h,al
        call DELAY_20ms
        mov al,01h                ;Clear Display
        out 00h,al
        call DELAY_20ms
        mov al,04h
        out 02h,al
        call DELAY_20ms
        mov al,00h
        out 02h,al
RET
clear_LCD endp
```

```

keypad_input proc                ;SubR for keypad entry,al has
unique key input value.
x0:    mov al,00h
        out 04h,al
x1:    in al,04h
        and al,0f0h
        cmp al,0f0h
        jnz x1
        CALL DELAY_20ms

        mov al,00h                ; Check for key press
        out 04,al
x2:    in al,04h
        and al,0F0h
        cmp al,0F0h
        jz x2
        CALL DELAY_20ms

        mov al,00h                ; Check for key press
        out 04,al
        in al,04h
        and al,0F0h
        cmp al,0F0h
        jz x2

        mov al,0Eh                ;Check for key press
column 1
        mov bl,al
        out 04h,al
        in al,04h
        and al,0f0h
        cmp al,0f0h

```

jnz x3

column 2 mov al,0Dh ;Check for key press

mov bl,al
out 04h,al
in al,04h
and al,0f0h
cmp al,0f0h
jnz x3

column 3 mov al,0Bh ;Check for key press

mov bl,al
out 04h,al
in al,04h
and al,0f0h
cmp al,0f0h
jnz x3

column 4 mov al,07h ;Check for key press

mov bl,al
out 04h,al
in al,04h
and al,0f0h
cmp al,0f0h
jz x2

x3: or al,bl

ret

keypad__input endp

inta proc

mov al,00eh

out 08h,al

mov cx,14

mov si,3ah

;store the 16-bit entered

pass after the hard coded pass word

enter_14bit:

call keypad_input

cmp al,7eh

jz pressc_alarm

cmp al,0bbh

jz nop_alarm

cmp al,0b7h

jz nop_alarm

cmp al,7dh

jz nop_alarm

cmp al,7bh

jz pressac_alarm

cmp al,77h

jz press_enter_alarm

mov [si],al

CALL Print_*

inc si

dec cx

jnz enter_14bit

disp_enteralarm:

call keypad_input

cmp al,7eh

jz pressc_alarm

cmp al,7bh

```

        jz pressac_alarm
        cmp al,77h
        jz press_enter_alarm
asd2:   CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h
        jz press_enter_alarm
        jnz asd2
nop_alarm: nop
        jmp enter_14bit
pressc_alarm:
        call clear_1digit_LCD
        dec si
        inc cx
        jmp enter_14bit
pressac_alarm:
        call clear_LCD
        mov cx,14
        mov si,3ah
        jmp enter_14bit
press_enter_alarm:
        CALL clear_LCD
        mov al,0fh
        out 08h,al
        cmp cx,0
        jz cmp_pass_alarm
        jnz x56
cmp_pass_alarm:
        cld
        mov si,10h
        mov di,3ah
        mov cx,14

```

;start of pass segment

```
repe cmpsb
cmp cx,00h
jnz x56
mov al,0ffh
out 08h,al
add dh,1h
```

```
x56:
ret
inta endp
```

```
intu proc
```

```
call clear_LCD
mov dl,1
```

;flag for checking two inputs

```
mov al,0feh
out 08h,al
mov cx,12
mov si,48h
```

;store the 12-bit entered

pass after the hard coded pass word

enter_12bitu:

```
call keypad_input
cmp al,7eh
jz pressc_user
cmp al,7bh
jz pressac_user
cmp al,0bbh
jz nop_user
cmp al,0b7h
jz nop_user
cmp al,7dh
jz nop_user
```

```

        cmp al,77h
        jz press__enter__user
        mov [si],al
        CALL Print_*
        inc si
        dec cx
        jnz enter_12bitu
disp__enter__user:
        call keypad__input
        cmp al,7eh
        jz pressc__user
        cmp al,7bh
        jz pressac__user
        cmp al,77h
        jz press__enter__user
asd3:    CALL clear__LCD
        CALL enter__LCD
        call keypad__input
        cmp al,77h
        jz press__enter__user
        jnz asd3
nop__user:
        nop
        jmp enter_12bitu
pressc__user:
        call clear_1digit__LCD
        dec si
        inc cx
        jmp enter_12bitu
pressac__user:
        call clear__LCD
        mov cx,12
        mov si,48h

```

;start of pass segment


```
        jmp enter_12bitu
press_enter_user:
        mov al,0ffh
        out 08h,al
        cmp cx,0
        jz cmp_pass_user
        jnz wrong_pass
```

```
cmp_pass_user:
        cld
        mov si,2eh
        mov di,48h
        mov cx,12
        repe cmpsb
        cmp cx,00h
        jnz wrong_pass
        jz open_door_user
```

```
wrong_pass :
        call clear_LCD
        mov si,48h
        mov cx,12
        cmp dl,0
        jz raise_alarm_user
        mov al,0fdh
        out 08h,al
        call retry_msg
        call DELAY_max
        call DELAY_max
        call clear_LCD
        mov cx,12
        dec dl
        jmp enter_12bitu
```

```
raise_alarm_user:
    mov dh,0
    mov al,0fh
    out 08h,al
    mov ax,0abcdh
    jmp end_70h
```

```
open_door_user:
    call open_door
```

```
end_70h:
```

```
ret
```

```
intu endp
```

```
ints proc
```

```
    call open_door
```

```
    ; CALL DELAY_0.04s
```

```
    ; mov al,00h
```

```
    ; out 0ch,al
```

```
ret
```

```
ints endp
```

```
open_door proc
```

```
    call clear_LCD
```

```
    mov al,8ah
```

```
    out 0Ah,al
```

```
    call DELAY_20ms
```

```
    mov al,0ah
```

```
    out 0Ah,al
```

```
x31:    in al,0ch
```



```
close_door endp
```

```
welcome_msg proc
```

```
    mov al,0A0h  
    out 00h,al  
    call DELAY_20ms  
    mov al,05h  
    out 02h,al  
    call DELAY_20ms  
    mov al,01h  
    out 02h,al ;prints Space
```

```
    mov al,0A0h  
    out 00h,al  
    call DELAY_20ms  
    mov al,05h  
    out 02h,al  
    call DELAY_20ms  
    mov al,01h  
    out 02h,al ;prints Space
```

```
    mov al,0A0h  
    out 00h,al  
    call DELAY_20ms  
    mov al,05h  
    out 02h,al  
    call DELAY_20ms  
    mov al,01h  
    out 02h,al ;prints Space
```

```
    mov al,0A0h  
    out 00h,al
```

```
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,0A0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,57h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints W
```

```
mov al,45h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
mov al,4Ch
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints L
```

```
mov al,43h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints C
```

```
mov al,4Fh
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints O
```

```
mov al,4dh
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
```

```
call DELAY_20ms
mov al,01h
out 02h,al ;prints M
```

```
mov al,45h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
ret
welcome__msg endp
```

```
update__msg proc
    mov al,55h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h
    out 02h,al ;prints U
```

```
    mov al,50h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h
```

```
out 02h,al ;prints P
```

```
mov al,44h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints D
```

```
mov al,41h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints A
```

```
mov al,54h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints T
```

```
mov al,45h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```



```
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
mov al,0A0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,50h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints P
```

```
mov al,41h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints A
```

```
mov al,53h
```

```
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints S
```

```
mov al,53h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints S
```

```
mov al,57h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints W
```

```
mov al,4Fh
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
```

```
out 02h,al ;prints O
```

```
mov al,52h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints R
```

```
mov al,44h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints D
```

```
ret
```

```
update_msg endp
```

```
clear_1digit_LCD proc
```

```
mov al,00h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,10h
```

```
;shift left by 1
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,04h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,00h  
out 02h,al
```

```
mov al,0A0h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al
```

```
;prints Space
```

```
call DELAY_20ms  
mov al,10h  
out 00h,al  
call DELAY_20ms  
mov al,04h  
out 02h,al  
call DELAY_20ms  
mov al,00h  
out 02h,al
```

```
;shift left by 1
```

```
RET  
clear_1digit_LCD endp
```

```
error_msg proc  
mov al,0A0h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h
```

```
out 02h,al ;prints Space
```

```
mov al,45h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints E
```

```
mov al,4Eh
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints N
```

```
mov al,54h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints T
```

```
mov al,45h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints E
```

```
mov al,52h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints R
```

```
mov al,0A0h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints Space
```

```
mov al,31h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints 1
```

```
mov al,32h
```

```
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints 2
```

```
mov al,0A0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,44h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints D
```

```
mov al,49h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
```

```
out 02h,al ;prints I
```

```
mov al,47h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints G
```

```
mov al,49h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints I
```

```
mov al,54h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints T
```

```
mov al,53h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```



```

    out 02h,al
    call DELAY_20ms
    mov al,01h
    out 02h,al ;prints S
RET
error_msg endp

retry_msg proc
    mov al,0A0h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h
    out 02h,al ;prints Space

    mov al,0A0h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h
    out 02h,al ;prints Space

    mov al,0A0h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
    call DELAY_20ms
    mov al,01h

```

```
out 02h,al ;prints Space
```

```
mov al,0A0h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints Space
```

```
mov al,52h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints R
```

```
mov al,45h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
```

```
call DELAY_20ms
```

```
mov al,01h
```

```
out 02h,al ;prints E
```

```
mov al,54h
```

```
out 00h,al
```

```
call DELAY_20ms
```

```
mov al,05h
```

```
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints T
```

```
mov al,52h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints R
```

```
mov al,59h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Y
```

```
ret
retry_msg endp
```

```
updateday_msg proc
    mov al,55h
    out 00h,al
    call DELAY_20ms
    mov al,05h
    out 02h,al
```

```
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints U
```

```
mov al,50h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints P
```

```
mov al,44h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints D
```

```
mov al,41h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints A
```

```
mov al,54h  
out 00h,al
```

```
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints T
```

```
mov al,45h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints E
```

```
mov al,0a0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,44h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints D
```

```
mov al,41h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints A
```

```
mov al,59h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Y
```

```
mov al,0a0h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
call DELAY_20ms
mov al,01h
out 02h,al ;prints Space
```

```
mov al,50h
out 00h,al
call DELAY_20ms
mov al,05h
out 02h,al
```

```
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints P
```

```
mov al,41h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints A
```

```
mov al,53h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints S
```

```
mov al,53h  
out 00h,al  
call DELAY_20ms  
mov al,05h  
out 02h,al  
call DELAY_20ms  
mov al,01h  
out 02h,al ;prints S
```

```
ret
```

```
updateday_msg endp
```

Nmi_24hrtimer:

```
call clear_LCD  
call clear_1digit_LCD  
call updateday_msg
```

startnmi:

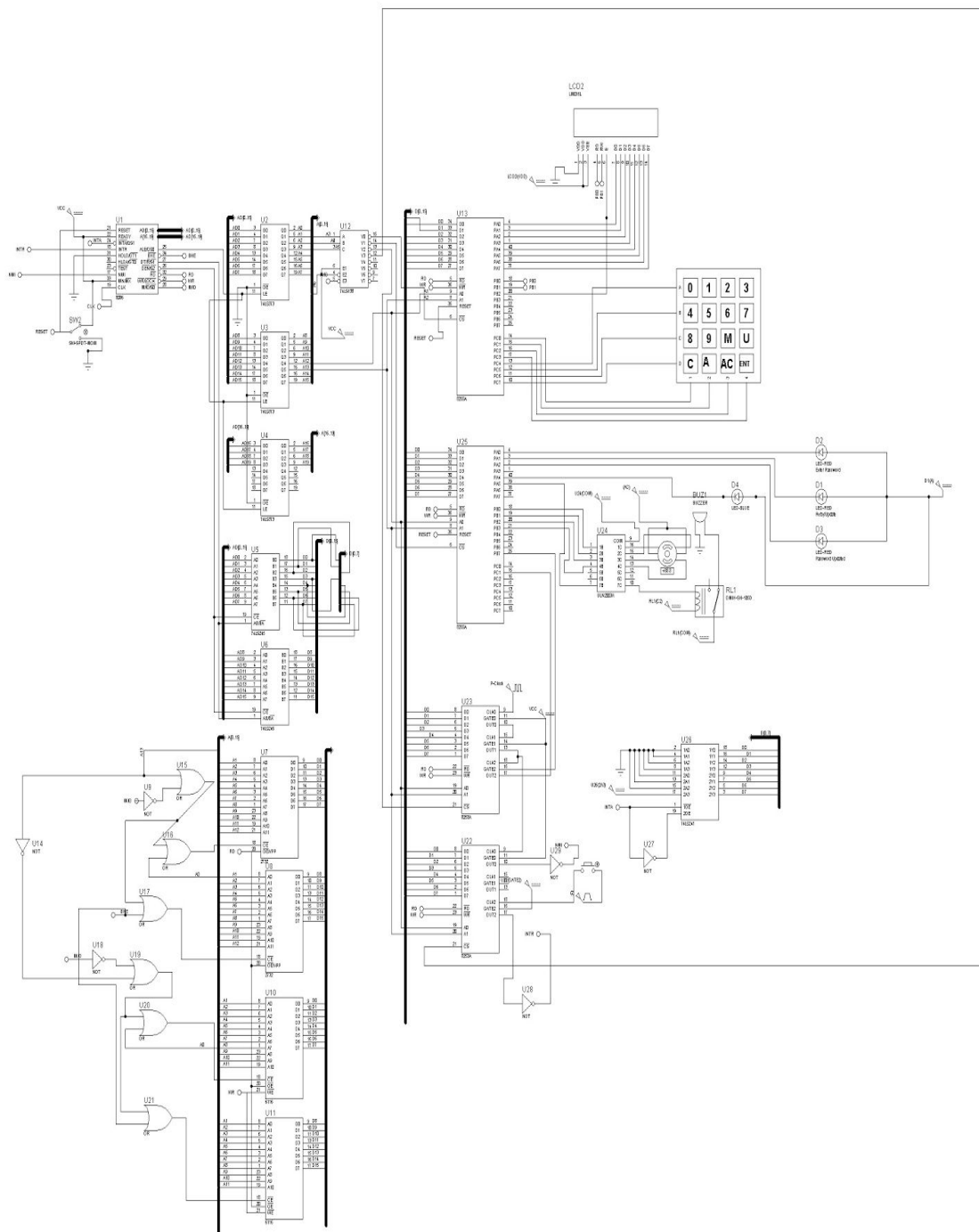
```
call keypad_input  
cmp al,0bbh  
jz master_mode  
jmp startnmi
```

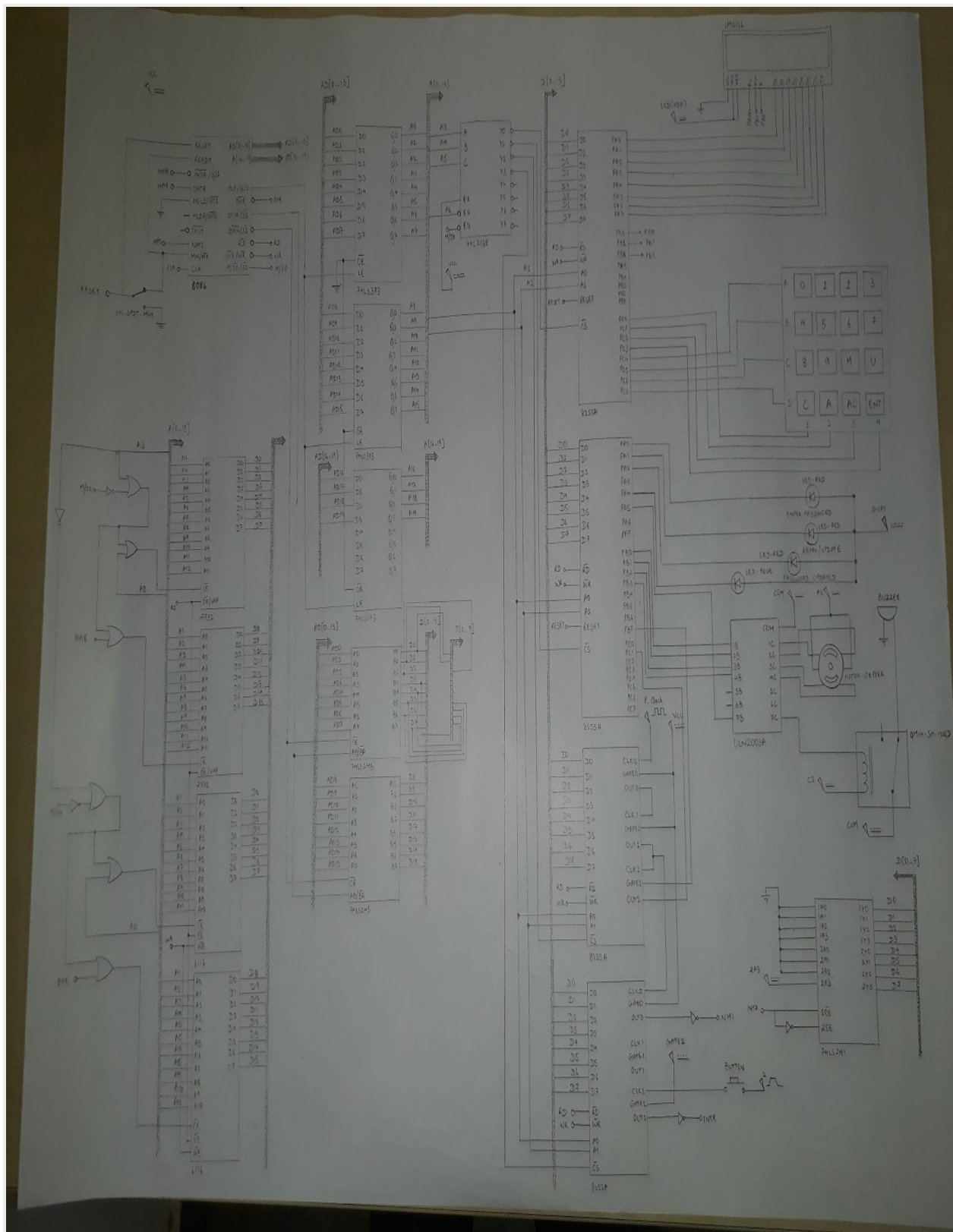
iret

Switch_intR:

```
call open_door  
sti  
cmp bp,0abcdh  
jz x6  
jnz start
```


Complete Circuit Diagram





References

- A 16x2 LCD display has been used. Following links were referred to understand its working:

<http://www.alldatasheet.com/view.jsp?Searchword=LMO16L>

<http://www.sakshieducation.com/Engineering/Story.aspx?cid=12&nid=96054>

- A 4x4 hex keypad has also been used.

<http://www.futurlec.com/Keypad4x4.shtml>

- A stepper motor and a Darlington transistor has been used.

<https://www.youtube.com/watch?v=8aLkXsh1O44>

<https://www.engineersgarage.com/electronic-components/uln2003-datasheet>