

Alpine Linux Init System

From Alpine Linux

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Quick-Start Information

Alpine Linux uses OpenRC (<https://wiki.gentoo.org/wiki/OpenRC>) for its init system.

The following commands are available to manage the init system:

- `rc-update add service <runlevel>`
- `rc-update del service <runlevel>`
- `rc-service <service> <start stop restart>`

Equivalent to `/etc/init.d/service <start stop restart>`

- `rc-status`

To check services and their set runlevels

- `rc <runlevel>`

To change to a different runlevel

- `reboot`

Equivalent to `shutdown -r now` from traditional GNU/Linux systems

- `halt`

Equivalent to `shutdown -h now` from traditional GNU/Linux systems

- `poweroff`

To turn off the machine

Tip: Prior to Alpine Linux 2.0.0, you might need to use the following commands instead: `rc_add`, `rc_delete`, and `rc_status`.

Available Runlevels

The available runlevels are:

- **default** - Used if no runlevel is specified. (This is generally the runlevel you want to add services to.)
- **hotplugged**
- **needed**
- **manual**

The special runlevels are:

- **sysinit** - Brings up any system specific stuff such as `/dev`, `/proc` and optionally `/sys` for Linux based systems. It also mounts `/lib/rc/init.d` as a ramdisk using `tmpfs` where available unless `/` is mounted `rw` at boot. `rc` uses `/lib/rc/init.d` to hold state information about the services it runs. `sysinit` always runs when the host first starts and should not be run again.
- **boot** - Generally the only services you should add to the boot runlevel are those which deal with the mounting of filesystems, set the initial state of attached peripherals and logging. Hotplugged services are added to the boot runlevel by the system. All services in the boot and `sysinit` runlevels are automatically included in all other runlevels except for those listed here.
- **single** - Stops all services except for those in the `sysinit` runlevel.
- **reboot** - Changes to the shutdown runlevel and then reboots the host.
- **shutdown** - Changes to the shutdown runlevel and then halts the host.

rc-update usage

```
Usage: rc-update [options] add service <runlevel>
       rc-update [options] del service <runlevel>
       rc-update [options] show
```

Options: [suChqv]

-s, --stack	Stack a runlevel instead of a service
-u, --update	Force an update of the dependency tree
-h, --help	Display this help output
-C, --nocolor	Disable color output
-v, --verbose	Run verbosely
-q, --quiet	Run quietly

rc-status usage

```
Usage: rc-status [options] [runlevel1] [runlevel2] ...
```

Options: [aclrsuChqv]

-a, --all	Show services from all run levels
-c, --crashed	Show crashed services
-l, --list	Show list of run levels
-r, --runlevel	Show the name of the current runlevel
-s, --servicelist	Show service list
-u, --unused	Show services not assigned to any runlevel
-h, --help	Display this help output
-C, --nocolor	Disable color output
-v, --verbose	Run verbosely
-q, --quiet	Run quietly

rc-service usage

```
Usage: rc-service [options]
```

Options: [e:ilr:ChqVv]

-e, --exists <arg>	tests if the service exists or not
-i, --ifexists	if the service exists then run the command
-l, --list	list all available services
-r, --resolve <arg>	resolve the service name to an init script
-h, --help	Display this help output
-C, --nocolor	Disable color output
-V, --version	Display software version
-v, --verbose	Run verbosely
-q, --quiet	Run quietly

rc usage

```
Usage: rc [options]
```

Options: [a:o:s:SchqVv]

-a, --applet <arg>	runs the applet specified by the next argument
-o, --override <arg>	override the next runlevel to change into when leaving single user or boot runlevels
-s, --service <arg>	runs the service specified with the rest

```
of the arguments
-S, --sys      output the RC system type, if any
-h, --help     Display this help output
-C, --nocolor  Disable color output
-V, --version  Display software version
-v, --verbose  Run verbosely
-q, --quiet    Run quietly
```

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Category: Booting

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